

Hydrological model parameter instability: A source of additional uncertainty in estimating the hydrological impacts of climate change?

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5	Pierre Brigode ¹ , Ludovic Oudin ¹ , Charles Perrin ²								
6	¹ UPMC Univ. Paris 06, UMR 7619 Sisyphe, Case 105, 4 Place Jussieu, F-75005 Paris,								
7	France								
8	² Hydrosystems Research Unit (HBAN), Irstea, 1, rue Pierre-Gilles de Gennes, CS								
9	10030, 92761 Antony Cedex, France								
10 11	Company and in a systhese Empile pieze bries de Quemo fr								
11	Corresponding author. Email. pierre.origode@upinc.n								
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38 Abstract

39 This paper investigates the uncertainty of hydrological predictions due to rainfall-runoff 40 model parameters in the context of climate change impact studies. Two sources of 41 uncertainty were considered: (i) the dependence of the optimal parameter set on the 42 climate characteristics of the calibration period and (ii) the use of several posterior 43 parameter sets over a given calibration period. The first source of uncertainty often refers 44 to the lack of model robustness, while the second one refers to parameter uncertainty 45 estimation based on Bayesian inference. Two rainfall-runoff models were tested on 89 46 catchments in northern and central France. The two sources of uncertainty were assessed 47 in the past observed period and in future climate conditions. The results show that, given 48 the evaluation approach followed here, the lack of robustness was the major source of 49 variability in streamflow projections in future climate conditions for the two models 50 tested. The hydrological projections generated by an ensemble of posterior parameter sets 51 are close to those associated with the optimal set. Therefore, it seems that greater effort 52 should be invested in improving the robustness of models for climate change impact 53 studies, especially by developing more suitable model structures and proposing 54 calibration procedures that increase their robustness.

55

56 Keywords: Climate change, rainfall-runoff modelling, hydrological model calibration,
57 uncertainty, robustness.

58

59 **1** INTRODUCTION

60 1.1 Hydrological projections under climate change and their associated uncertainties

61 The impacts of climate change on catchment behaviour have been extensively investigated 62 over the last few decades (see e.g. for Europe Arnell, 1999a, Arnell, 1999b; for Australia 63 Vaze et al., 2011 and Vaze and Teng, 2011). Quantitatively assessing the uncertainties associated with hydrological projections is a difficult task, even if qualitatively it is now 64 65 recognised that these uncertainties are considerable. They stem from the methods used to generate climate projections as well as from hydrological modelling. Moreover, the relative 66 67 importance of the various uncertainty sources is not easy to assess. Wilby and Harris (2006) proposed a framework to assess the relative weights of the sources of uncertainty in future 68 69 low flows for the River Thames. They consider that uncertainty sources should be ranked in 70 decreasing order as follows: Global Circulation Models (GCMs) > (empirical) downscaling 71 method > hydrological model structure > hydrological model parameters > emission scenario. 72 However, this conclusion was obtained using only two rainfall-runoff models applied to a 73 single catchment. Wilby (2005) noted that depending on the rainfall-runoff model used (and 74 possibly the catchment studied), the uncertainties associated with hydrological modelling may 75 predominate. More recently, Chen et al. (2011) showed on a Canadian catchment that the 76 choices of GCMs and downscaling techniques are the greatest uncertainty sources in 77 hydrological projection estimations, followed by emission scenarios and hydrological model 78 structures, and last hydrological model parameter estimation. On several southeastern 79 Australian catchments, Teng et al. (2012) also showed that uncertainties stemming from 80 fifteen GCM outputs are much greater than the uncertainties stemming from five hydrological 81 models. Focusing on future hydrological trends in the UK, Arnell (2011) showed that 82 "uncertainty in response between climate model patterns is considerably greater than the 83 range due to uncertainty in hydrological model parameterization." These results show that the 84 uncertainties generated by the hydrological modelling step, though generally lower than that 85 generated by the climate modelling step, can be significant in some cases and should not be 86 ignored in climate change impact studies.

87 The common sources of uncertainty in hydrological modelling in stationary conditions (in 88 terms of climate conditions and/or physical characteristics) include errors in model structure, 89 problems in the calibration procedure, and errors in the data used for calibration. In non-90 stationary conditions, as in climate change studies, additional uncertainties may come from 91 parameter instability due to the possible changes in the physical catchment characteristics and 92 in the dominant processes. In both cases, model structure errors and the identification of 93 model parameters can generally be considered as the two main sources of uncertainty in the 94 hydrological modelling step. Several methods exist for studying uncertainties due to model 95 structure (see e.g. Refsgaard et al., 2006). In climate change impact studies, the errors 96 stemming from the model structure are usually assessed using several rainfall-runoff models 97 and quantifying the range of their outputs (Booij, 2005; Wilby, 2005; Wilby and Harris, 2006; 98 Jiang et al., 2007). The problem of parameter identification has been widely investigated and 99 many methods to quantify the associated uncertainty have been proposed (see e.g. Matott et 100 al., 2009, for a review). In a recent study, Bastola et al. (2011) attempted to quantify these two 101 hydrological uncertainty sources (model structure and parameter sets) in a climate change 102 context using a multi-model approach combining multiple emission scenarios and GCMs, 103 four conceptual rainfall-runoff models and two parameter uncertainty evaluation methods 104 (Generalized Likelihood Uncertainty Estimation and Bayesian Model Averaging). The 105 authors concluded that "the role of hydrological model uncertainty is remarkably high and 106 should therefore be routinely considered in impact studies." Note that the type of hydrological 107 model used (physically-based or conceptual, lumped or distributed, etc.) may also be 108 considered as an uncertain choice, in both stationary and non-stationary conditions. It is often

109 considered that the physical basis of process descriptions is indispensable to maintain the 110 predictive power of hydrological models in a changing climate (see e.g. Ludwig et al., 2009). 111 A few studies have covered this issue by considering both conceptual and physically-based 112 models (see e.g. Poulin et al., 2011). The RExHySS project (Ducharne et al., 2009; Ducharne 113 et al., 2011) addressed this issue on the Seine River basin (France) by considering seven 114 hydrological models, including distributed (predominantly) physically-based models, semi-115 distributed physically-based models and lumped conceptual models. Interestingly, the results 116 showed that the conceptualisation of the models was not the main source of variability in 117 hydrological projections among the model simulations since large differences were found 118 between models with similar conceptualisations.

119 1.2 Can model parameter instability be a major source of uncertainty?

120 Other studies have investigated the dependence of the model parameters on the characteristics 121 of the record period used for calibration. In climate change impact studies, the record period 122 used to calibrate the model differs from the projected period. Since rainfall-runoff model 123 parameters must be calibrated using the available data sets, they will partially account for the 124 errors contained in these data (see e.g. Yapo et al., 1996; Oudin et al., 2006a) and/or their 125 specific climate characteristics (see e.g. Gan and Burges, 1990). This is a well-known issue 126 for conceptual rainfall-runoff models but physically-based models are also affected by this 127 problem (see e.g. Rosero et al., 2010). Model parameters are the integrators of the data's 128 information content. Different time periods used for calibration may provide quite different 129 optimum parameter sets, depending on whether the period is dry or wet, for example, thus 130 providing an estimation of parameter uncertainty with respect to their lack of robustness. Here 131 Beven (1993) states that "it is easy to show that if the same model is 'optimised' on two 132 different periods of record, two different optimum parameter sets will be produced. Extension 133 to multiple calibration periods, if the data were available, would yield multiple optimum

134 parameter sets. The resulting parameter distributions would reflect the uncertainty in the 135 parameter estimates and the interaction between the individual parameters." As stressed by 136 Gan and Burges (1990), this obviously "should be heeded by modelers who use calibrated 137 conceptual models to explore hydrologic consequences of climate change." As a consequence, 138 and without clear guidelines on how the model should be calibrated for climate change impact 139 studies, most hydrologists calibrate their models with all the available data (e.g. Vaze and 140 Teng, 2011) or with the longest observed period they consider representative of the current 141 hydro-climatology conditions (e.g. Poulin et al., 2011), generally considering a priori that "the 142 longer the calibration period, the more robust the parameter set."

143 One way to evaluate the capacity of models to represent the hydrological behaviour of a 144 catchment in a changing climate is to apply the differential split-sample test, introduced by 145 Klemeš (1986). In this testing scheme, two contrasted periods are identified in the available 146 record and the split-sample test is performed using these two periods. If the model is intended 147 to simulate streamflow under wetter climate conditions, then it should be calibrated on a dry 148 period selected in the available record and validated on a wet period. Conversely, if it is 149 intended to simulate flows under drier climatic conditions, the reverse should be done. The 150 model should demonstrate its ability to perform well in these contrasted conditions. Despite 151 the simplicity of the test, relatively few authors have followed the differential split-sample test 152 in the past (see e.g. Jakeman et al., 1993; Refsgaard and Knudsen, 1996; Donnelly-153 Makowecki and Moore, 1999; Seibert, 2003; Wilby, 2005). More recently, Merz et al. (2011) 154 applied the test to a large set of 273 catchments in Austria and found that the parameters of 155 the hydrological model controlling snow and soil moisture processes were significantly 156 related to the climatic conditions of the calibration period. Consequently, the performance of 157 the model was particularly affected if the calibration and the validation periods differed 158 substantially. Vaze et al. (2010) also applied the differential split-sample test to 61 catchments

159 in southeast Australia with four conceptual hydrological models. They found that the 160 performance of these models was relatively dependent on the climatic conditions of the 161 calibration period. On 216 southeastern Australian catchments, Coron et al. (2012) 162 highlighted the same lack of robustness of three hydrological models tested in climatic 163 conditions different from those used for parameter calibration. Vaze et al. (2010) therefore 164 suggest that it would be wiser to calibrate model parameters on a portion of the record with 165 conditions similar to those of the future period to simulate. This idea was also put forward by 166 de Vos et al. (2010), who proposed dynamically re-calibrating model parameters for each 167 temporal cluster by finding analogous periods in the historical record. Following similar 168 motivations, Luo et al. (2011) showed that more consistent model predictions on specific 169 hydrological years are obtained if a selection of calibration periods is performed, and Singh et al. (2011) used adjusted parameter values depending on the aridity of the catchment 170 171 considered for improving model prediction. These methodologies could be applied for 172 simulating future hydrological conditions, but unfortunately, as stated by Prudhomme and 173 Davies (2009), long records that include climatic conditions similar to what could be expected 174 in the future are lacking. This makes it difficult to identify a set of parameters specific to such 175 future conditions. Note that in some regions, climate changes have occurred in the past and it 176 is therefore possible to objectively assess the potential of hydrological models to cope with 177 changing climate. This is the case for Central and Western Africa, affected by a marked 178 reduction in rainfall and runoff from the year 1970 onwards. Using different models on 179 different catchments in this region, Niel et al. (2003) and Le Lay et al. (2007) showed no 180 evidence that non-stationarity in climate would incur model parameter instability.

181 *1.3* Scope of the paper

182 This paper intends to investigate the uncertainty of hydrological predictions for the future 183 climate. To this aim, we followed Klemeš's differential split-sample test and assessed the

184 corresponding variability of the simulated hydrological impacts of projected climate when 185 considering alternatively (i) the dependence of the optimal parameter set on the calibration 186 period characteristics and (ii) an ensemble of posterior parameter sets obtained on a given 187 calibration period. Each source of uncertainty was already studied in the context of changing 188 climate, but their relative importance has not been assessed so far. Besides, most studies 189 focusing on the parameter's dependency on climate conditions did not assess the 190 consequences of choosing various calibration strategies on future hydrological projections. 191 Here we will attempt to assess the long-term effects of these two sources of uncertainty in 192 future conditions.

193

194 **2 DATA AND MODELS**

195 2.1 Catchment set

196 A set of 89 catchments located in northern and central France was used, namely the Somme 197 River at Abbeville, 22 sub-catchments of the Loire River basin and 66 sub-catchments of the 198 Seine River basin (see Figure 1). Catchment area ranges from 32 to 109,930 km², runoff yield 199 ranges from 0.11 to 0.69 and the aridity index (here defined as the ratio of mean annual 200 Penman (1948) potential evapotranspiration to mean annual rainfall) ranges from 0.64 to 1.39. 201 Compared to the Seine basin sub-catchments, the sub-catchments of the Loire River basin add 202 diversity in terms of physiographic characteristics (with generally larger areas, higher 203 elevations, and a different geological context), and hydro-climatic characteristics (with 204 generally higher runoff yields). None of the catchments studied is strongly influenced by 205 upstream dams.

206

FIGURE 1: Location and distribution of various characteristics of the 89 catchments used.
The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles (67 is the number of catchments in the Seine and Somme basins, 22 in the Loire basin).

210

211 2.2 Hydro-meteorological data

The hydrological models tested here require only daily time series of potential evapotranspiration (PE) and rainfall (P) as input data. We used climate data from the SAFRAN meteorological reanalysis (Quintana-Segui et al., 2008; Vidal et al., 2010), which provides daily series of Penman PE and P from 1970 to 2007 at a mesoscale (on an 8×8 km grid). These data were aggregated for each catchment in order to estimate mean areal inputs. Besides daily streamflow (Q), time series were used to calibrate the models and assess their performance.

Since it is not within the scope of this paper to discuss the uncertainties related to climate projections, the outputs of a single general circulation model (GFDL CM2.1) driven by the A1B emissions scenario (IPCC, 2007) were chosen as climate projections. These outputs were regionalised using a statistical downscaling method based on weather types (Boé et al., 2006), producing a database at the same spatial resolution as the SAFRAN database (8 \times 8 km). Three time slices with continuous daily series of PE and P were used in this study:

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• 1980–2000, referred to as "present time" and noted PT hereafter;

226

• 2045–2065, referred to as "mid-century" and noted MC hereafter;

• 2080–2100, referred to as "end-of-century" and noted EC hereafter.

This scenario was tested on the Seine and the Somme basins within the RExHySS project (Ducharne et al., 2009, Ducharne et al., 2011) and on the Loire River basin within the ICC-Hydroqual project (Moatar et al., 2010). For the Seine and the Somme basins, the downscaled projection simulates an increase in mean annual air temperature of 1.8°C by MC and 3.1°C by EC, a decrease in mean annual precipitation of 5% by MC and 10% by EC (with an increase of winter precipitation and a decrease of summer precipitation) and an increase in potential evapotranspiration of 16% by MC and 26% by EC. These predictions are close to the mean trends estimated with up to 14 climate projections used in the RExHySS and ICC-Hydroqual projects, making the scenario used in this study an in-between scenario.

237 2.3 Rainfall-runoff models

Two daily continuous lumped rainfall-runoff models were used to avoid providing model-specific conclusions:

- The GR4J rainfall-runoff model, an efficient and parsimonious (four free parameters)
 model described in detail by Perrin et al. (2003);
- The TOPMO model (six free parameters), inspired by TOPMODEL (Beven and Kirkby, 1979; Michel et al., 2003), already tested on large data sets. This lumped model is quite different from GR4J but has comparable performance (see e.g. Oudin et al., 2006b). Here the distribution of the topographic index is parameterised and optimised, and not calculated from a digital elevation model. This was found to have only a limited impact on model efficiency, as shown by Franchini et al. (1996) and this eases the application of the model when it is tested on a large set of catchments.

Note that we did not explicitly investigate the uncertainties stemming from hydrological model structures. This was analysed e.g. by Seiller et al. (2012) using a multi-model approach in a climate change perspective.

252 2.4 Model parameterisation

The optimisation algorithm used to calibrate parameter values is the Differential Evolution Adaptive Metropolis (DREAM) algorithm (Vrugt et al., 2009). DREAM optimises model

parameters on a given period and additionally infers the posterior probability distribution of
model parameter values through Markov Chain Monte Carlo (MCMC) sampling.

As an objective function, we used the formal Generalized Likelihood function described by Schoups and Vrugt (2010), which considers correlated, heteroscedastic, and non-Gaussian errors (noted GL hereafter). The results in validation are analysed with the Nash and Sutcliffe (1970) efficiency criterion, which is still widely used in modelling studies. It was computed on root square transformed flows (noted NSEsq hereafter), which makes it possible to assess model efficiency for both high and low flows (Oudin et al. 2006b).

263

264 3 METHODOLOGY FOR INVESTIGATING PARAMETER UNCERTAINTY IN A CHANGING 265 CLIMATE

266 3.1 General methodology

The building blocks of the method originate from the differential split-sample test recommended by Klemeš (1986) and the methodology followed by Wilby (2005). The parameter uncertainty associated with the changing climate is characterised by the variability of the parameters across calibration sub-periods with varying hydroclimatic characteristics. The methodology is carried out in three steps (see Figure 2):

- Step 1: identification of test periods.
- Step 2: model parameter calibration and identification of posterior parameter sets.
- Step 3: model validation and simulation, and parameter uncertainty quantification.

275 These three steps are further detailed hereafter.

276

FIGURE 2: Illustration of the three-step methodology used for investigating parameter
uncertainty in a changing climate.

Note that a similar methodology was used in the RheinBlick project (Görgen et al., 2010) for
quantifying uncertainties due to the parameters of hydrological models in a climate change
perspective on the Rhine basin.

283

3.2 Step 1: Identification of climatically contrasted sub-periods

284 For each catchment, four climatically contrasted 3-year sub-periods were identified in the 285 available record: a wet sub-period, two dry ones and an intermediate one. The driest sub-286 period will be used as the validation period (hereafter noted dry validation sub-periods) and 287 the three others will be used as calibration sub-periods. This choice was made because the 288 selected climate projection indicates that future conditions will be drier and warmer on the 289 test basins. The aridity index (here defined as the ratio of mean Penman potential 290 evapotranspiration to mean precipitation) was used to characterise the climatic specificity of 291 each sub-period: the wet sub-period corresponds to the three contiguous hydrological years 292 with the lowest aridity index (here a hydrological year starts on September 1 and ends on 293 August 31). The choice of this index is rather arbitrary and may influence the results obtained 294 hereafter. However, since it is solely based on climate characteristics, this makes it possible to 295 assess the climatic specificity of the chosen sub-periods compared to the projected future 296 climate. Obviously, it was not possible to use a criterion based on observed streamflows, as 297 done by Seibert (2003) on observed data, since future flow observations by definition do not 298 exist.

The choice of the length of the record sub-period to consider is not straightforward since it is based on a trade-off between two opposite expectations: (i) the longer the sub-periods, the more robust the set of parameters should be and (ii) the shorter the sub-periods, the more climatically contrasted sub-periods can be found in the record period. A review of the literature (see e.g. the review proposed by Perrin et al. (2007)) shows that there is no clear 304 consensus on the minimum length of calibration period for rainfall-runoff models, which is 305 probably attributable to the specificity of the catchments and models used in those studies. 306 Specifically for the two parsimonious models used in this paper, Anctil et al. (2004) obtained 307 good GR4J performance with 3- to 5-year calibration periods and Perrin et al. (2007) showed 308 that the calibration of the GR4J and TOPMO models with the equivalent of only 1 year of 309 data can provide acceptable performance. Thus, it seems that 3-year periods can yield 310 acceptable parameter sets. Those relatively short sub-periods allow representing significantly 311 contrasted climatic conditions. Interestingly, Figure 3 shows that the contrast between the 312 aridity indexes of the different calibration sub-periods is similar to the contrast between the 313 aridity indexes of the observed record and future climate projection. However, it should be 314 noted here that the climate projection simulates systematically drier conditions than the dry 315 validation sub-periods. This means that whatever the selected calibration sub-period, the 316 model is applied in extrapolation in future climate conditions. Note that the aridity index does 317 not reflect seasonal variability of precipitation and potential evapotranspiration: two sub-318 periods with similar values of the aridity index may be quite different in terms of climate 319 seasonality. This means that seasonal indexes would be useful to consider as additional 320 criteria for period selection if seasonal contrasts were under study.

321

322 FIGURE 3: Comparison of Aridity Index (AI) values for the different calibration and 323 validation sub-periods considered and for the three time slices (PT, MC, EC) for the 89 324 catchments.

325

326 3.3 Step 2: Model calibrations on the specific periods

For each catchment, the two hydrological models were calibrated using the three climaticallycontrasted sub-periods (i.e. the wet, mean and dry sub-periods) and the whole record period

(except the dry validation sub-periods, which are used for model validation in step 3). A 1-year warm-up period was considered for each simulation.

The DREAM algorithm was used to infer the most likely parameter set and its underlying posterior probability distribution. We selected for each calibration run (i) the optimal parameter set defined as the parameter set maximising the GL objective function and (ii) an ensemble of 2000 posterior parameter sets representing the posterior probability distribution of parameter sets. For each catchment and each calibration period, we checked that the DREAM algorithm converged to the stationary distribution representing the model's posterior distribution by analysing the Gelman-Rubin convergence statistics.

338 Note that additional model calibrations were also performed on the dry validation sub-periods.
339 The corresponding calibration performance was used as a reference to evaluate the
340 performance of models validated on these dry validation sub-periods after calibration on other
341 periods.

342 3.4 Step 3: Model simulations with different parameter sets

At this stage of the methodology, four optimal parameter sets corresponding to the four calibration periods and an ensemble of 2000 posterior parameter sets identified throughout the record period (except the dry validation sub-periods) are available for each catchment.

All these parameter sets were used for each catchment to simulate the streamflow time series over the dry validation sub-periods (illustrated as grey hydrographs in the first line of the third step of Figure 2) and on the three time slices (PT, MC and EC) (illustrated as grey envelops on the flow duration curves plotted in the second line of the third step of Figure 2). Three typical streamflow characteristics were analysed:

- 351352
- The 95th flow exceedance percentile of the flow duration curve, Q₉₅ (mm/day), describing low flows;
- 353
- The mean annual streamflow, Q_{MA} (mm/y), indicating the overall water availability;

• The 5th flow percentile, Q_{05} (mm/day), describing high flows.

355 For each catchment and each model, the four ensembles of parameter sets were tested first on 356 the dry validation sub-periods. We analysed the dependence of model performance on the 357 climatic specificity of the calibration period. Furthermore, the biases between the observed 358 and the simulated streamflow characteristics were assessed. Second, the variability of the 359 future streamflow simulations obtained using various calibration conditions was analysed for 360 each future time slice. To differentiate the impacts stemming from the specificity of the 361 calibration period from those associated with the "classical" parameter uncertainty approach 362 based on Bayesian inference on the whole record period, the results are presented step by step 363 hereafter.

364 4 Results

365 4.1 Calibration performance results

366 In this section, the general calibration performance of the two models are analysed. Figure 4 367 presents the distributions of the GL function evaluations and the distributions of the Nash-368 Sutcliffe efficiencies computed on root square transformed flows (NSEsq) obtained by the 369 GR4J and TOPMO models on the catchment set. The distributions were obtained with (i) the 370 calibration efficiencies over the whole record without the dry validation sub-periods obtained 371 with optimal parameter sets, i.e. 89 values for each model (white boxplots, noted OPT) and 372 (ii) calibration performance over the same record periods obtained with the 2000 posterior 373 parameter sets identified for each of the 89 catchments, i.e. 178,000 values for each model 374 (grey boxplots, noted POS). The distributions of the GL objective function values highlight 375 that optimal parameter sets present similar general calibration efficiency to the calibration 376 efficiency obtained using the populations of posterior parameter sets. Considering populations 377 of posterior parameter sets thus adds a limited variability in terms of calibration performance 378 over the whole record periods (without dry validation sub-periods) for the two models. For 379 GR4J, the distributions of the NSEsq efficiencies similarly show that the optimal parameter 380 identified with the DREAM algorithm and with the GL objective function have similar 381 general performance as the posterior parameter sets. The performance losses when 382 considering populations of posterior parameter sets instead of optimal parameter sets are more 383 significant for TOPMO than for GR4J, with median NSEsq moving from 0.86 with optimal 384 parameter sets to 0.84 with posterior parameter sets. Calibration performance results for the 385 other calibration sub-periods (wet, mean and dry 3-year calibration sub-periods) show the 386 same general tendencies (not shown here). The difference between the two models might stem 387 from the number of free parameters, higher for TOPMO (six free parameters) than for GR4J 388 (four free parameters). Thus, the calibrated parameter values of TOPMO may show greater 389 sensitivity to the choice of the objective function. Finally, note that the general performance 390 of both models is quite reasonable, with half of the catchments studied presenting calibration 391 performance obtained with optimal parameter sets on the whole record periods (without the 392 dry validation sub-periods) greater than 0.85 for the two models.

393

FIGURE 4: Distributions of the GL objective function values (top) and of the NSEsq values (bottom) of the two models illustrating (i) calibration performance over the whole record periods without the dry validation sub-periods obtained with optimal parameter sets (white boxplots, noted OPT) and (ii) calibration performance over the whole record periods obtained with posterior parameter sets (grey boxplots, noted POS). Results are shown for GR4J (left) and TOPMO (right). The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.

402 **4.2** Sensitivity to the climate characteristics of the calibration period

In this section, the model outputs are analysed considering different calibration periods. First the efficiency of the model on the dry validation sub-periods is discussed in terms of NSEsq and simulation of standard streamflow characteristics. Second, we analyse the resulting spread of the simulated streamflows for the future time slices.

407

• Efficiency on dry validation sub-periods:

408 Figure 5 shows the distributions of the NSEsq values on the catchment set obtained by the 409 two models in (i) calibration over the dry validation sub-periods and (ii) validation over the 410 dry validation sub-periods using the other four calibration sub-periods considered (wet, mean, 411 dry, and whole record periods). Models calibrated over different sub-periods generally 412 encountered similar difficulties simulating flows on the dry validation sub-periods since the 413 validation efficiencies are clearly reduced compared to the calibration efficiencies on this sub-414 period. The differences between the four calibration strategies (over a wet, a mean, a dry sub-415 period or a long period) are limited but, for both models, using the wettest sub-periods for 416 calibration appears particularly detrimental to simulating the dry validation sub-periods. GR4J 417 and TOPMO obtained marginally better validation results using dry and mean conditions for 418 calibration, respectively. Interestingly, calibrating the models on the whole record period 419 (except the dry validation sub-periods, resulting in 20 years of record on average) does not 420 warrant a particularly robust estimation of optimal parameter sets, since the validation 421 efficiencies are generally similar to those obtained with 3-year calibration periods. This is not 422 consistent with the wide-spread idea that the longer the calibration period, the more robust the 423 parameter set.

424 These results corroborate the previous findings of Vaze et al. (2010), Merz et al. (2011) and 425 Coron et al. (2012) obtained with different catchments and models, emphasising the lack of robustness of conceptual rainfall-runoff models when the climatic settings between calibrationand validation periods are different.

428

FIGURE 5: Distributions of the NSEsq values obtained by the two models illustrating (i) calibration performance over the dry validation sub-periods (black boxplots) and (ii) validation performance over the dry validation sub-periods using the other four calibration sub-periods considered (wet, mean, dry, and whole record without the dry validation subperiod illustrated, respectively, with blue, green, red and white boxplots). Results are shown for GR4J (left) and TOPMO (right). The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.

436

437 Figure 6 summarises the results of the models' sensitivity to the climatic specificity of the 438 calibration period on the observed dry validation sub-periods. This figure is organised as a 439 table with two columns and three rows: each column represents a hydrological model (left: 440 GR4J; right: TOPMO) and each row represents a specific characteristic of the simulated flow 441 series (from top to bottom: Q_{95} , Q_{MA} and Q_{05}). For each model and for each streamflow 442 characteristic, the plot on the left shows the observed versus simulated value for each 443 catchment, each dot representing the mean of simulated values obtained with the four optimal 444 parameter sets and each bar representing the range of simulated values when using the four 445 optimal parameter sets. Ideally, all range bars should be centred on the 1:1 line, meaning that 446 streamflow simulated by parameter sets originating from different calibration sub-periods are 447 all equal to the observed streamflow. The boxplots on the right represent the distributions of 448 the relative errors on the flow characteristic on the dry validation sub-periods over the 89 449 catchments when considering the four calibration sub-periods. These relative errors were 450 estimated as the ratio of the difference between simulated and observed flow characteristics to the observed flow characteristics. Ideally, all the boxplots should be centred on a null value ofthe bias between the observed and the simulated streamflow.

453 The first main result is that the two rainfall-runoff models present similar overall efficiency in 454 simulating the flow characteristics on the dry validation sub-periods (graphs on the left). This 455 efficiency is rather limited since the median absolute bias is greater than 0.1 for both models. 456 Even for the estimation of mean annual flow (Q_{MA}), none of the four calibration strategies 457 yields a median absolute bias lower than 0.1. The second main result is that the impact of the 458 climatic specificity of the calibration sub-periods on the modelled flow characteristics is not straightforward (graphs on the right). For GR4J, it seems that the 3-year dry calibration sub-459 460 periods provide the least biased estimations of the three streamflow characteristics of the dry 461 validation sub-periods. Using wet and mean 3-year calibration sub-periods tends to yield 462 overestimated flow simulations on the dry validation sub-periods. Conversely, TOPMO tends 463 to underestimate flows of the dry validation sub-periods. The mean 3-year calibration sub-464 periods seems to provide less biased estimation of the streamflow characteristics on the dry validation sub-periods. Finally, using 3-year calibration sub-periods (dry ones for GR4J and 465 466 mean ones for TOPMO) yields less biased predictions than when considering the whole 467 available records for calibration for both hydrological models and for the three streamflow 468 characteristics studied here, which corroborates the validation performance illustrated in 469 Figure 5. Note, however, that all calibration periods produce highly biased predictions and 470 that the differences between the calibration strategies are relatively limited compared to these 471 biases.

472

473 FIGURE 6: Sensitivity of the simulated flow characteristics (from top to bottom: Q_{95} , Q_{MA} 474 and Q_{05}) on the dry validation sub-periods after calibration on climatically specific periods 475 (wet, mean, dry, total record) (left column: GR4J; right column: TOPMO). The Q-Q plots 476 show the observed versus simulated value for each catchment, each dot representing the mean 477 of values simulated with the four optimal parameter sets and each bar representing the range 478 of simulated values when using the four optimal parameter sets. The boxplots on the right 479 represent the distributions of the relative errors on the flow characteristic on the dry 480 validation sub-periods over the 89 catchments when considering the four calibration periods. 481 The boxplots are constructed with the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.

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483

• Impacts on simulated flow evolutions:

484 Then we assessed the change in future simulated streamflow characteristics when considering 485 the variability stemming from the climatic specificity of the calibration periods. Figure 7 486 shows the models' outputs on future time slices when using the sets of model parameters 487 obtained on the four different calibration periods considered so far. The range of streamflow 488 characteristics simulated for future time slices (mid-century (MC) and end-of-century (EC)) 489 with the four parameter sets are plotted against those simulated for the present time slice (PT). 490 In the following, we assume that a model simulates a significant hydrological change on a 491 catchment if the range bar is completely above or below the 1:1 line, meaning that the change 492 can be considered beyond the variability generated by the climate specificity of the calibration 493 periods considered. For example, a decreasing trend of Q₀₅ between PT and MC is assumed 494 for a particular catchment if a model calibrated over the four different sub-periods simulates 495 four Q_{05} values lower in MC than in PT.

496 Considering the range across centres, the two models suggest a rather similar decreasing trend 497 for the values of the three streamflow characteristics from PT to EC. This trend is not 498 observed for the MC time slice. The Q_{05} streamflow characteristic (high flows) increases for 499 this time slice, before decreasing more sharply by the end of the century. Some catchments 500 show particularly large range bars. An analysis of these catchments (not shown here) indicates 501 that the calibration performance is particularly poor for at least one calibration sub-period. 502 This shows that a model with poor performance in current conditions will add substantial 503 uncertainty to future predictions.

504

505 FIGURE 7: Comparison of the simulations of three streamflow characteristics (from top to 506 bottom: Q_{95} , Q_{MA} and Q_{05}) obtained on the present time slice (PT) and future time slices (MC 507 and EC) under projected climate conditions with the two hydrological models (left: GR4J; 508 right: TOPMO). The range bars represent, for each catchment, the range of estimated values 509 with the four optimal parameter sets corresponding to the four calibration periods.

510

511 The sensitivity of the two models to the climatic specificity of the calibration periods is of the 512 same magnitude for all three time slices considered, meaning that the sensitivity to the 513 calibration periods is relatively stable in the future time slices. Figure 8 synthesises the results 514 of these trends (e.g. a decreasing trend of Q₀₅ between PT and MC is assumed for a particular 515 catchment when a model calibrated over the four different sub-periods simulates four Q_{05} 516 values lower in MC than in PT), showing the proportion of catchments where hydrological 517 trends between present (PT) and future (MC and EC) time slices have been simulated 518 considering different calibration sub-periods for the two hydrological models. It also 519 compares the information given by a hydrological model calibrated over a long period (here 520 the entire available record without the dry validation sub-periods) and the information given 521 using the four different calibration periods. These results confirm the previously obtained 522 general trend of a decrease in the three streamflow characteristic values from PT to EC, with a 523 particular increasing trend for high flows (Q05) from PT to MC. Nevertheless, when 524 considering the four different calibration periods, a number of catchments show no clear 525 trends for the MC time slice, which attenuates the general trends highlighted when using the whole record periods as the only calibration periods. Last, differences between the two models can be observed: when considering only the whole record for calibration, GR4J seems to simulate a more regionally homogeneous decrease in low- to medium-flow characteristics $(Q_{95} \text{ and } Q_{MA})$, since the percentage of catchments with a decrease in flow is larger than for TOPMO. Considering the four calibration periods, the two models yield more homogeneous simulations for the catchment set.

532

FIGURE 8: Proportions of catchments showing (or not) hydrological trends between present
(PT) and future (MC and EC) time slices considering different calibration sub-periods for the
two hydrological models: white highlights a clear decrease, black highlights a clear increase
and grey highlights no clear trend.

537

538 4.3 Sensitivity to the use of a posterior ensemble of parameter sets

In this section, the model outputs are analysed considering 2000 posterior parameter sets obtained on the whole record period for each catchment and for each model. First, we discuss the efficiency of these ensembles of posterior parameter sets on the dry validation sub-periods in terms of NSEsq and simulation of the three streamflow characteristics (Q₉₅, Q_{MA} and Q₀₅). Second, we analyse the resulting variability of the simulated streamflow characteristics for the future climate conditions.

545

• Efficiency on dry validation sub-periods:

Figure 9 shows the distribution of NSEsq values obtained by the two models illustrating (i) the calibration performance of the optimal parameter sets over the dry validation sub-periods (i.e. 89 NSEsq values for each model) and (ii) the validation performance over the dry validation sub-periods using optimal parameter sets (i.e. 89 NSEsq values for each model) and posterior parameter sets (i.e. 178,000 NSEsq values for each model) identified on the whole 551 record periods without the dry validation sub-periods. For GR4J, the validation performance 552 obtained by posterior parameter sets is very similar to that produced by the individual optimal 553 parameter sets presented in Figure 5, meaning that for the catchments studied, the DREAM 554 algorithm produces posterior parameter sets yielding efficiency close to the value obtained by 555 optimal parameter sets over the dry validation sub-periods. The NSEsq performance 556 distributions obtained with optimal and posterior parameter sets are not similar for TOPMO: 557 the optimal parameter sets appear to be less efficient than the posterior parameter sets in terms 558 of NSEsq validation performance. This means that rather different optima exist when using 559 the GL function and a likelihood function based on a standard least squares errors scheme 560 (NSEsq here). Nevertheless, differences between optimal parameter set performance and 561 posterior parameter set performance are less significant in the validation step than in the 562 calibration step, as shown in Figure 4. It should be remembered that the NSEsq was not used 563 as an objective function.

564

FIGURE 9: Distribution of NSEsq values obtained by the two models illustrating (i) calibration performance of the optimal parameter sets over the dry-validation sub-periods (black "OPT" boxplots) and (ii) validation performance over the dry validation sub-periods using optimal (white "OPT" boxplots) and posterior (grey "POS" boxplots) parameter sets identified on the whole record periods without the dry validation sub-periods. Results are shown for GR4J (left) and TOPMO (right). The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90.

572

573 Figure 10 shows the variability of the models' outputs on the dry validation sub-periods when 574 considering the ensembles of posterior parameter sets instead of the single optimal parameter 575 set. This figure is organised like Figure 6. The dots represent the means of flow characteristics 576 on a catchment simulated with the 2000 posterior parameter sets and the bars represent the 577 range of simulated flow characteristics on a catchment when considering its 2000 posterior 578 parameter sets. The boxplots synthesise the distributions of the relative errors on the flow 579 characteristics simulated by the models with the posterior parameter sets identified.

580 The first major result is that considering posterior parameter sets does not significantly 581 increase the variability of the simulated flows. The biases between observed flows and flows 582 simulated by the ensembles of posterior parameter sets (grey boxplots) are close to those 583 obtained with the ensembles of optimal parameter sets (white boxplots). Moreover, this 584 variability is very limited compared to the variability observed when considering the four 585 climate-specific parameter sets (see Figure 6). Here, the hydrological responses associated 586 with 2000 posterior parameter sets are similar to those associated with optimal parameter sets. 587 The flow characteristics obtained by TOPMO present generally greater uncertainty than those 588 obtained by GR4J. These predictive uncertainty values are again probably due to the larger 589 number of free parameters for TOPMO. Note, however, that the predictive uncertainty for 590 TOPMO is often consistent with the observed biases for the validation sub-periods since the 591 estimation range often encompasses the observed flow value.

592

593 FIGURE 10: Sensitivity of the simulated flow characteristics (from top to bottom: Q_{95} , Q_{MA} 594 and Q_{05}) on the dry validation sub-periods using the 2000 posterior parameter sets 595 determined on the whole record periods without the dry validation sub-periods for the two 596 hydrological models (left: GR4J; right: TOPMO). The Q-Q plots show the observed versus 597 simulated value for each catchment, each dot representing the mean of simulated values when 598 using the 2000 posterior parameter sets and each bar representing the range of simulated 599 values when using the 2000 posterior parameter sets. The boxplots on the right represent the 600 distributions of the relative errors on the flow characteristic on the dry validation sub-periods

- 601 over the 89 catchments when considering the 2000 posterior parameter sets. The boxplots are
 602 constructed with the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.
- 603

• Impacts on simulated flow evolutions:

605 Figure 11 synthesises the results on the evolution of flows when considering the posterior 606 parameter sets obtained throughout the whole record periods. This figure is organised like 607 Figure 7: for each catchment, a range cross quantifies the variability in the estimation of flow 608 characteristics for a time slice simulated by the posterior parameter sets obtained on the whole 609 record periods. The results are very different from those obtained when considering only the 610 individual optimal parameter sets for each of the four calibration periods (Figure 7). The 611 variability of simulated flows considering 2000 posterior parameter sets for each catchment is 612 much lower than the variability considering four climate-specific parameter sets for each 613 catchment. Nevertheless, the variability in TOPMO outputs considering posterior parameter 614 sets is higher than GR4J's variability.

615

616 FIGURE 11: Comparison of the simulations of three streamflow characteristics (from top to 617 bottom: Q_{95} , Q_{MA} and Q_{05}) obtained on the present time slice (PT) and future time slices (MC 618 and EC) under projected climate conditions with the two hydrological models (left: GR4J; 619 right: TOPMO). For each catchment, the range bars represent the range of estimated values 620 with the 2000 posterior parameter sets obtained over the whole record period.

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Figure 12 illustrates the proportion of catchments showing (or not showing) clear changes when considering the ensemble simulations obtained with the posterior parameter sets. The additional consideration of the ensembles of 2000 posterior parameter sets yields a slight increase in the number of catchments for which no clear trend is observed, particularly between the MC and the PT. Nevertheless, the future trends are similar to those observed without taking into account the ensembles of posterior parameter sets, i.e. when using only the optimal parameter sets. There is a sharp decrease in all streamflow characteristics by the EC and a slight but significant increase in the high-flow characteristic for the MC.

630

FIGURE 12: Proportion of catchments showing (or not showing) hydrological trends
between present (PT) and future (MC and EC) time slices considering (or not considering)
posterior parameter sets for the two hydrological models: white highlights a clear decrease,
black highlights a clear increase and grey highlights no clear trend.

635

636 5 DISCUSSION AND CONCLUSION

This paper attempted to investigate the uncertainty of hydrological predictions for the future climate when considering either (i) the dependence of the optimal parameter set on calibration period specificity or (ii) the use of several posterior parameter sets over a given calibration period. The first aspect often refers to the robustness of model parameters, while the second often refers to parameter uncertainty estimation based on Bayesian inference.

642 The two conceptual hydrological models tested here were sensitive to the use of climatically 643 contrasted calibration sub-periods. This sensitivity was highlighted by a wide range of possible simulated streamflows for both the dry observed validation sub-periods and the 644 645 future climate time slices. Even if general future changes can be observed when considering 646 four optimal parameter sets (obtained with the calibration on three sub-periods and the whole 647 record periods except the dry validation sub-periods) for each catchment, the proportion of 648 catchments showing clear changes is much lower than when considering a unique parameter 649 set (obtained by calibration on the whole record periods except the dry validation sub-650 periods). However, the impact of the calibration period climate specificity on the simulated 651 streamflows is not straightforward since for a majority of the catchments studied, using a wet 652 calibration sub-period for a dry validation sub-period does not systematically generate a larger 653 bias between observed and simulated flows than when using a dry calibration sub-period. 654 Moreover, considering long periods for model calibration does not generate more robust 655 simulation than using 3-year sub-periods, which is not consistent with the common belief that 656 "the longer the calibration period, the more robust the parameter set". Since the use of two 657 different hydrological models did not provide equivalent results, the relation between the 658 model considered and the impact of the climatic specificity of the calibration period on 659 calibration and validation performance should be further investigated.

660 Concerning the "classical" parameter uncertainty assessment followed in this study, it seems 661 that the prediction bounds obtained from the ensembles of posterior parameter sets are 662 considerably thinner than what would be expected, especially for the GR4J model. 663 Nevertheless, it is important to note that these results are dependent to some extent on the 664 method used (the DREAM algorithm (Vrugt et al., 2009) and the GL objective function 665 (Schoups and Vrugt, 2010)), the catchments studied and the models considered. It appeared 666 that DREAM provided posterior parameter sets that were close to the optimal ones in terms of Nash-Sutcliffe validation efficiency over the dry validation sub-periods. Other methods to 667 668 quantify parameter uncertainty could produce posterior parameter sets with greater 669 differences than the optimal ones and thus yield larger uncertainty bounds. Considering the 670 ensembles of 2000 posterior parameter sets yields a slight increase in the number of 671 catchments for which no clear trend is observed, especially for TOPMO. The results obtained 672 by the two conceptual models were found to be relatively consistent. The main differences 673 were the larger uncertainty bounds observed for TOPMO. This is probably attributable to the 674 larger number of degrees of freedom of TOPMO, which has six free parameters, compared to 675 the four free parameters of GR4J. TOPMO's calibrated parameters are thus likely to depend

676 more on the choice of the calibration period and the objective function used during the 677 optimisation process. Still, further research is needed to confirm these hypotheses.

Our results show that, given the evaluation approach followed here, model robustness was the 678 679 major source of variability in streamflow projections in future climate conditions. They 680 corroborate the previous findings of Vaze et al. (2010), Merz et al. (2011) and Coron et al. 681 (2012) obtained with different catchment sets and models, emphasising the lack of robustness 682 of conceptual rainfall-runoff models when the climatic context between calibration and 683 validation periods are different. Note that for these three studies, long-term regional non-684 stationarities were observed on the catchments studied: southeastern Australian catchments 685 suffered from long drought periods while Austrian catchments experienced a significant 686 increase in temperature over the last few decades, generating a shift in the hydrological 687 regimes, particularly for snow-affected catchments. These situations allow testing the 688 hydrological models on long as well as significantly different sub-periods in terms of climatic 689 conditions. Even if these actual non-stationarities were not observed everywhere, it seems 690 possible to test the sensitivity of models' calibration on climatically contrasted sub-periods.

Thus, from these results, it seems difficult to provide general guidelines for calibrating hydrological models for climate change studies. The robustness issue should be investigated more thoroughly, by proposing and testing calibration procedures that increase this robustness. For example, Coron et al. (2012) proposed the Generalized Split Sample Test procedure, which aims at testing all possible combinations of calibration-validation periods and thus studying the capability of the tested model to be used in different climatic contexts. Other tests could be performed, inspired by the methodology defined in this work.

This study also stresses that hydrological models do not efficiently reproduce streamflow characteristics, even if the NSEsq coefficient estimated after calibration is quite high. The median bias obtained for mean annual flow was generally greater than 10%. This is a

considerable limitation for the use of hydrological models to simulate extreme high or low
flows in a changing climate. To cope with this notable failure, one could suggest using multiobjective calibration procedures and/or adapting the objective function to the estimated flow
characteristic.

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FIGURES



900 Fig. 1. Location and distribution of various characteristics of the 89 catchments used. The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles (67 is the number of catchments in the Seine and Somme basins, 22 in the Loire basin).



Fig. 2. Illustration of the three-step methodology used for investigating parameter uncertaintyin a changing climate.



Fig. 3. Comparison of Aridity Index (AI) values for the different calibration and validation
sub-periods considered and for the three time slices (PT, MC, EC) for the 89 catchments.





Fig. 4. Distributions of the GL objective function values (top) and of the NSEsq values (bottom) of the two models illustrating (i) calibration performance over the whole record periods without the dry validation sub-periods obtained with optimal parameter sets (white boxplots, noted OPT) and (ii) calibration performance over the whole record periods obtained with posterior parameter sets (grey boxplots, noted POS). Results are shown for GR4J (left) and TOPMO (right). The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.



920

Calibration period

921 Fig. 5. Distributions of the NSEsq values obtained by the two models illustrating (i) 922 calibration performance over the dry validation sub-periods (black boxplots) and (ii) 923 validation performance over the dry validation sub-periods using the other four calibration 924 sub-periods considered (wet, mean, dry, and whole record without the dry validation sub-925 period illustrated, respectively, with blue, green, red and white boxplots). Results are shown 926 for GR4J (left) and TOPMO (right). The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90 927 percentiles.



929

930 Fig. 6. Sensitivity of the simulated flow characteristics (from top to bottom: Q95, QMA and 931 Q05) on the dry validation sub-periods after calibration on climatically specific periods (wet, 932 mean, dry, total record) (left column: GR4J; right column: TOPMO). The Q-Q plots show the 933 observed versus simulated value for each catchment, each dot representing the mean of values 934 simulated with the four optimal parameter sets and each bar representing the range of 935 simulated values when using the four optimal parameter sets. The boxplots on the right 936 represent the distributions of the relative errors on the flow characteristic on the dry validation 937 sub-periods over the 89 catchments when considering the four calibration periods. The 938 boxplots are constructed with the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.



Fig. 7. Comparison of the simulations of three streamflow characteristics (from top to bottom:
Q95, QMA and Q05) obtained on the present time slice (PT) and future time slices (MC and
EC) under projected climate conditions with the two hydrological models (left: GR4J; right:
TOPMO). The range bars represent, for each catchment, the range of estimated values with
the four optimal parameter sets corresponding to the four calibration periods.

		GR4J		тормо	
	Calibration period		PT to EC	PT to MC	PT to EC
	Whole record period (1 parameter set)	Θ	\bigcirc		\bigcirc
Q ₉₅	4 sub-periods (4 parameter sets)	Θ	\bigcirc		\bigcirc
Q _{MA}	Whole record period (1 parameter set)		\bigcirc		\bigcirc
	4 sub-periods (4 parameter sets)	G	\bigcirc		
Q ₀₅	Whole record period (1 parameter set)				$\overline{\mathbf{O}}$
	4 sub-periods (4 parameter sets)		\bigcirc		\bigcirc

948 Fig. 8. Proportions of catchments showing (or not) hydrological trends between present (PT)

949 and future (MC and EC) time slices considering different calibration sub-periods for the two

950 hydrological models: white highlights a clear decrease, black highlights a clear increase and

951 grey highlights no clear trend.



Parameter sets

Parameter sets

Fig. 9. Distribution of NSEsq values obtained by the two models illustrating (i) calibration performance of the optimal parameter sets over the dry-validation subperiods (black "OPT" boxplots) and (ii) validation performance over the dry validation sub-periods using optimal (white "OPT" boxplots) and posterior (grey "POS" boxplots) parameter sets identified on the whole record periods without the dry validation sub-periods. Results are shown for GR4J (left) and TOPMO (right). The boxplots show the 0.10, 0.25, 0.50, 0.75 and 0.90.

960





962 Fig. 10. Sensitivity of the simulated flow characteristics (from top to bottom: Q95, QMA and 963 Q05) on the dry validation sub-periods using the 2000 posterior parameter sets determined on 964 the whole record periods without the dry validation sub-periods for the two hydrological models (left: GR4J; right: TOPMO). The Q-Q plots show the observed versus simulated 965 966 value for each catchment, each dot representing the mean of simulated values when using the 967 2000 posterior parameter sets and each bar representing the range of simulated values when 968 using the 2000 posterior parameter sets. The boxplots on the right represent the distributions 969 of the relative errors on the flow characteristic on the dry validation sub-periods over the 89 970 catchments when considering the 2000 posterior parameter sets. The boxplots are constructed 971 with the 0.10, 0.25, 0.50, 0.75 and 0.90 percentiles.



Fig. 11. Comparison of the simulations of three streamflow characteristics (from top to
bottom: Q95, QMA and Q05) obtained on the present time slice (PT) and future time slices
(MC and EC) under projected climate conditions with the two hydrological models (left:
GR4J; right: TOPMO). For each catchment, the range bars represent the range of estimated
values with the 2000 posterior parameter sets obtained over the whole record period.

		GR4J		тормо	
	Calibration period	PT to MC	PT to EC	PT to MC	PT to EC
_	Whole record period (1 parameter set)	Θ	\bigcirc		\bigcirc
Q ₉₅	Whole period record (2000 equifinal parameter sets)	Θ	\bigcirc	Θ	\bigcirc
Q _{MA}	Whole record period (1 parameter set)		\bigcirc		\bigcirc
	Whole period record (2000 equifinal parameter sets)		\bigcirc	\bigcirc	\bigcirc
Q ₀₅	Whole record period (1 parameter set)				Θ
	Whole period record (2000 equifinal parameter sets)	C			\bigcirc

Fig. 12. Proportion of catchments showing (or not showing) hydrological trends between present (PT) and future (MC and EC) time slices considering (or not considering) posterior parameter sets for the two hydrological models: white highlights a clear decrease, black

984 highlights a clear increase and grey highlights no clear trend.