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Controllability of quantum systems with a polarizability term

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Quantum systems

Outline of the talk



2 Controllability results



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Bilinear quantum systems

• The system is described by the Schrödinger equation:

$$\mathrm{i}rac{\partial\psi}{\partial t} = (-\Delta + V(x))\psi(x,t)$$
 , $x \in \Omega$

- Ω : real manifold (**R**^{*d*}, Euclidean sphere,...);
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Different models:

- Usually, dipolar approximation $\mu(x, u) = u(t)W(x)$ is enough.
- For better accuracy, we have to consider second order terms $\mu(x, u) = u(t)W_1(x) + u^2(t)W_2(x)$.

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Finite dimensional space: Coron, Rouchon, Beauchard,.. Infinite dimensional space: Morancey (Lyapunov methods with W_1 and W_2 bounded, Ω compact subset of \mathbf{R}^d)

Semi-linear quantum systems: abstract form

- The state is described by the *wave function*, a point in some Hilbert space.
- Dynamics given by the Schrödinger equation

$$\frac{d}{dt}\psi = A\psi + u(t)B\psi(+u^2(t)C\psi)$$

A, *B* and *C* are skew-adjoint operators (not necesseraly bounded).

Some standard assumptions

- A has purely discrete spectrum (−iλ_k)_k, λ_k → +∞;
- (φ_k)_k, Hilebrt basis of *H* made of eigenvectors of *A*,
 *A*φ_k = -iλ_kφ_k;
- for every k, ϕ_k belongs to the domains of B and C;
- for every u in \mathbf{R}^+ , $A + uB + u^2C$ is skew-adjoint.

Quantum systems

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Controllability of bilinear quantum systems

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Controllability of bilinear quantum systems

$$\frac{d}{dt}\psi = A\psi + u(t)B\psi$$

Non-degenerate transition

A couple (j, k) in **N**² is a non degenerate transition of (A, B) if $\langle \phi_j, B\phi_k \rangle \neq 0$ and $|\lambda_j - \lambda_k| = |\lambda_m - \lambda_n|$ implies $\{j, k\} = \{m, n\}$ or $\langle \phi_m, B\phi_n \rangle = 0$.

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Periodic excitations of bilinear systems

Let (j, k) be a non-degenerate transition of (A, B). If u is $2\pi/|\lambda_j - \lambda_k|$ periodic with non zero first Fourier coefficient and zero Fourier coefficient for every frequency associated with a transition (m, n), $|\lambda_m - \lambda_n| \in \mathbf{N} \setminus \{1\} |\lambda_j - \lambda_n|$. Then, there exists T such that $|\langle \phi_j, \Upsilon_{nT}^{u/n} \phi_k \rangle| \rightarrow 1$ as n tends to infinity.

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Weakly-coupled systems

Definition

A pair (*A*, *B*) of linear operators if weakly-coupled if there exists $\alpha < 1$ such that $||B\psi|| \le |||A|^{\alpha}\psi||$ for every ψ in $D(|A|^{\alpha})$ and there exists $c_{A,B}$ such that $|\Im\langle A\psi, B\psi\rangle| \le c_{A,B}|\langle A\psi, B\psi\rangle|$ for every ψ in D(A).

Good Galerkin approximations

Let (A, B) be weakly-coupled. Then for every ψ in H, ε , K > 0, there exists N in **N** such that $||u||_{L^1} < K \implies ||X^u_{(N)}(t)\psi - \Upsilon^u_T\psi|| < \varepsilon$

All the systems presented in the physics litterature are weakly-coupled.

Quantum	systems

Result

$$\frac{\mathrm{d}\psi}{\mathrm{d}t} = \mathbf{A}\psi + \mathbf{u}(t)\mathbf{B}\psi + \mathbf{u}^{2}(t)\mathbf{C}\psi$$

Good Galerkin approximation

If (A, B) and (A, C) are weakly-coupled, then for every ψ in H, $\varepsilon, K > 0$, there exists N in **N** such that $\|u\|_{L^1} + \|u^2\|_{L^1} < K \implies \|X^u_{(N)}(t)\psi - \Upsilon^u_T\psi\| < \varepsilon$

Result with general C (possibly unbounded)

Let (A, B) and (A, C) be weakly-coupled. Let (j, k) be a non-degenerate transition of (A, B). For allmost every α in **R**, for every $\varepsilon > 0$, there exists $u_{\varepsilon} : [0, T_{\varepsilon}] \to \{0, \alpha\}$ such that $\|\Upsilon_{(A,B,C)}^{u_{\varepsilon}}(T_{\varepsilon})\phi_{j} - \phi_{k}\| < \varepsilon$.

Idea of the proof

$$\frac{\mathrm{d}\psi}{\mathrm{d}t} = A\psi + u(t)B\psi + u^2(t)C\psi$$

A bilinear result

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Proof of the semi-linear controllability result: For allmost every α in **R**, (j,k) is a non-degenerate transition of $(A, B + \alpha C)$. Apply the preceeding (bilinear) result to $(A, B + \alpha C)$ and notice that

$$u(t)(B + \alpha C) = \begin{cases} \alpha B + \alpha^2 C & \text{if } u(t) = \alpha \\ 0 & \text{if } u(t) = 0 \end{cases}$$

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Particular case: *C* bounded

$$\begin{array}{ll} \Upsilon^n, \mbox{ propagator of } & \frac{d\psi}{dt} = A\psi + u(t)/nB\psi + u^2(t)/n^2C\psi \\ Y_n, \mbox{ propagator of } & \frac{d\psi}{dt} = A\psi + u(t)/nB\psi \end{array}$$

Since Y_n and Υ^n are unitary propagators and u is $2\pi/|\lambda_2 - \lambda_1|$ periodic, one gets

$$\left|\Upsilon_{nt,0}^{u/n}\phi_{1}-Y_{n}(nt,0)\phi_{1}\right|\leq \underbrace{\frac{\|C\|}{n}}_{\rightarrow 0}\underbrace{\left(\frac{t|\lambda_{2}-\lambda_{1}|}{2\pi}+1\right)\int_{0}^{\frac{2\pi}{|\lambda_{1}-\lambda_{2}|}}|u(s)|^{2}\mathrm{d}s}_{\text{bounded}}$$

Numerically: it converges faster with the semi-linear example than with the bilinear system!

Outline of the talk







Conclusion

Take home message

- Semi-linear conservative quantum systems can be treated with tools of geometric control theory.
- Results are obvious when the quadratic term C is bounded.
- Proof for general quadratic terms relies on precise time estimates for the finite dimensional Galerkin approximations.

Future works and open question

- Generalization to systems that are not weakly-coupled.
- Generalization to semi-linear systems (not only quadratic).
- What about controllability time?