# Notes on the analytic solution for the Dahl's friction model 

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#### Abstract

This document provides the analytical solution of the friction model for different changes in the sign of the vehicle speed.


## I. Analytic solution of the DAHL'S FRICTION MODEL

The load torque $\tau_{a}$ is described by the Dahl's model and is given by the following differential equation:

$$
\begin{equation*}
\frac{\mathrm{d} F}{\mathrm{~d} \theta}=\sigma_{0}\left(1-\frac{F}{F_{c}} \operatorname{sgn}(\dot{\theta})\right) \tag{1}
\end{equation*}
$$

Let make the hypothesis to have a positive speed signal during the time interval $t \in\left[0, t_{1}\right]$. At the time $t=0$, we have the corresponding value for the angle $\theta(0)=\theta_{0}$. This hypothesis implies that we have $\operatorname{sgn}(\dot{\theta})=+1$ in Eq. (1) for $\theta \in\left[\theta_{0}, \theta\right]$. We make also the hypothesis to start from null initial conditions, this implies that we need to solve the following differential equation:

$$
\begin{equation*}
\frac{\mathrm{d} F}{\mathrm{~d} \theta}=\sigma_{0}\left(1-\frac{F}{F_{c}}\right) \tag{2}
\end{equation*}
$$

with the following initial condition:

$$
\begin{equation*}
F\left(\theta_{0}\right)=0 \tag{3}
\end{equation*}
$$

We divide both terms of Eq. (2) by $\left(1-\frac{F}{F_{c}}\right)$ and $F_{c}$, in order to obtain a suited primitive:

$$
\begin{equation*}
\frac{-\frac{1}{F_{c}}\left(\frac{\mathrm{~d} F}{\mathrm{~d} \theta}\right)}{\left(1-\frac{F}{F_{c}}\right)}=-\frac{\sigma_{0}}{F_{c}} \tag{4}
\end{equation*}
$$

To obtain the analytic solution of Eq. (4) for positive speeds, we integrate both terms during the interval $\left(\theta_{0}, \theta(t)\right)$ :

$$
\begin{equation*}
\int_{\theta_{0}}^{\theta(t)} \frac{-\frac{1}{F_{c}} \frac{\mathrm{~d} F}{\left(1-\frac{F}{F_{c}}\right)} \mathrm{d} \theta=-\frac{\sigma_{0}}{F_{c}} \int_{\theta_{0}}^{\theta(t)} \mathrm{d} \theta, 0 \text {. }{ }^{\theta(1)}}{(1)} \tag{5}
\end{equation*}
$$

The result of this integral is:

$$
\begin{equation*}
\ln \left|1-\frac{F(\theta(t))}{F_{c}}\right|-\ln \left|1-\frac{F\left(\theta_{0}\right)}{F_{c}}\right|=-\frac{\sigma_{0}}{F_{c}}\left(\theta(t)-\theta_{0}\right) \tag{6}
\end{equation*}
$$

By substituting the initial condition (3), it is easily to obtain the solution for positive speeds:

$$
\begin{equation*}
F(\theta(t))=F_{c}\left[1-e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta(t)-\theta_{0}\right)}\right] \tag{7}
\end{equation*}
$$

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At the time instant $t=t_{1}$, the speed changes in sign and becomes negative $(\operatorname{sgn}(\dot{\theta})=-1$ in Eq. (1)) during the time interval $t \in\left[t_{1}, t_{2}\right]$. To guarantee the continuity of the function, we require that the initial condition corresponds to the last values assumed from $F(\theta(t))$ during the interval $t \in\left[0, t_{1}\right]$, i.e. $F\left(\boldsymbol{\theta}\left(t_{1}^{-}\right)\right)=F\left(\boldsymbol{\theta}\left(t_{1}^{+}\right)\right)$. Under these hypothesis, the new Cauchy problem to solve is:

$$
\begin{align*}
\frac{\mathrm{d} F}{\mathrm{~d} \theta} & =\sigma_{0}\left(1+\frac{F}{F_{c}}\right)  \tag{8}\\
F\left(\theta\left(t_{1}^{-}\right)\right) & =F\left(\theta\left(t_{1}^{+}\right)\right) \tag{9}
\end{align*}
$$

To solve this problem, we proceed as for Eqs. (4) and (5), then we integrate between $\theta\left(t_{1}\right)$ and $\theta(t)$, as follows:

$$
\begin{equation*}
\int_{\theta\left(t_{1}\right)}^{\theta(t)} \frac{\frac{1}{F_{c}} \frac{\mathrm{~d} F}{\left(1+\frac{F}{F_{c}}\right)}}{\left(\theta \theta=\int_{\theta\left(t_{1}\right)}^{\theta(t)} \frac{\sigma_{0}}{F_{c}} \mathrm{~d} \theta, ~\right.} \tag{10}
\end{equation*}
$$

The solution of this integral is:

$$
\begin{equation*}
\ln \left|1+\frac{F(\theta(t))}{F_{c}}\right|-k_{1}=\frac{\sigma_{0}}{F_{c}}\left(\theta(t)-\theta\left(t_{1}\right)\right) \tag{11}
\end{equation*}
$$

Where $k_{1}$ is a constant, depending from the initial conditions. By inverting this equation, we obtain:

$$
\begin{equation*}
F(\theta(t))=F_{c}\left[-1+e^{\frac{\sigma_{0}}{T_{c}}\left(\theta(t)-\theta\left(t_{1}\right)\right)} \cdot e^{k_{1}}\right] \tag{12}
\end{equation*}
$$

To determine the constant $k_{1}$, we introduce the initial condition $F\left(\theta\left(t_{1}^{-}\right)\right)=F\left(\theta\left(t_{1}^{+}\right)\right)$:

$$
\begin{gather*}
F\left(\theta\left(t_{1}^{-}\right)\right)=F_{c}\left[1-e^{-\frac{\sigma_{0}}{T_{c}} \theta\left(t_{1}\right)}\right]  \tag{13}\\
F\left(\theta\left(t_{1}^{+}\right)\right)=F_{c}\left[-1+e^{\frac{\sigma_{0}}{F_{c}}\left(\theta\left(t_{1}\right)-\theta\left(t_{1}\right)\right)} \cdot e^{k_{1}}\right] \tag{14}
\end{gather*}
$$

It follows:

$$
\begin{equation*}
F_{c}\left[1-e^{-\frac{\sigma_{0}}{T_{c}} \theta\left(t_{1}\right)}\right]=F_{c}\left[-1+e^{k_{1}}\right] \tag{15}
\end{equation*}
$$

By solving for $k_{1}$, we obtain:

$$
\begin{equation*}
k_{1}=\ln \left[2-e^{-\frac{\sigma_{0}}{T_{c}} \theta\left(t_{1}\right)}\right] \tag{16}
\end{equation*}
$$

So the solution for negative speeds is:

$$
\begin{equation*}
F(\theta(t))=F_{C}\left[-1+e^{\frac{\sigma_{0}}{F_{C}}\left(\theta(t)-\theta\left(t_{1}\right)\right)} \cdot e^{\ln \left[2-e^{-\frac{\sigma_{0}}{F_{C}} \theta\left(t_{1}\right)}\right]}\right] \tag{17}
\end{equation*}
$$

By rearranging all terms, this expression can be simplified as follows:

$$
\begin{equation*}
F(\theta(t))=F_{c}\left[-1+2 e^{\frac{\sigma_{0}}{T_{c}}\left(\theta(t)-\theta\left(t_{1}\right)\right)}-e^{\frac{\sigma_{0}}{T_{c}}\left(\theta(t)-2 \theta\left(t_{1}\right)\right)}\right] \tag{18}
\end{equation*}
$$

If we make the hypothesis that the speed changes in sign and becomes positive during the time interval $t \in\left[t_{2}, t_{f}\right]$, we
can find the analytic solution $F(\theta)$ for this last interval, by repeating the same steps as for the previous cases. In this case, the boundary condition is $F\left(\theta\left(t_{2}^{-}\right)\right)=F\left(\theta\left(t_{2}^{+}\right)\right)$, so we need to solve:

$$
\begin{align*}
\frac{\mathrm{d} F}{\mathrm{~d} \theta} & =\sigma_{0}\left(1-\frac{F}{F_{c}}\right)  \tag{19}\\
F\left(\theta\left(t_{2}^{-}\right)\right) & =F\left(\theta\left(t_{2}^{+}\right)\right) \tag{20}
\end{align*}
$$

We proceed as in the previous cases and we integrate the primitive between $\left[\theta_{2}, \theta(t)\right]$ :

We obtain the following analytic solution:

$$
\begin{equation*}
F(\theta(t))=F_{c}\left[1-e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta(t)-\theta\left(t_{2}\right)\right)} \cdot e^{k_{2}}\right] \tag{22}
\end{equation*}
$$

We can determine the constant $k_{2}$ by introducing the boundary condition $F\left(\theta\left(t_{2}^{-}\right)\right)=F\left(\theta\left(t_{2}^{+}\right)\right)$:

$$
\begin{gather*}
F\left(\theta\left(t_{2}^{-}\right)\right)=F_{c}\left[-1+2 e^{\frac{\sigma_{0}}{T_{c}}}\left(\theta\left(t_{2}\right)-\theta\left(t_{1}\right)\right)\right.  \tag{23}\\
F\left(e^{\frac{\sigma_{0}}{T_{c}}\left(\theta\left(t_{2}\right)-2 \theta\left(t_{1}\right)\right)}\right]  \tag{24}\\
\left.F\left(t_{2}^{+}\right)\right)=F_{c}\left[1-e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta\left(t_{2}\right)-\theta\left(t_{2}\right)\right)} \cdot e^{k_{2}}\right]
\end{gather*}
$$

It follows:

$$
\begin{equation*}
F_{c}\left[1-e^{k_{2}}\right]=F_{c}\left[-1+2 e^{\frac{\sigma_{0}}{F_{c}}\left(\theta\left(t_{2}\right)-\theta\left(t_{1}\right)\right)}-e^{\frac{\sigma_{0}}{F_{c}}\left(\theta\left(t_{2}\right)-2 \theta\left(t_{1}\right)\right)}\right] \tag{25}
\end{equation*}
$$

From Eq. (25) we get the following expression for the constant $k_{2}$ :

$$
\begin{equation*}
k_{2}=\ln \left[2-2 e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta\left(t_{2}\right)-\theta\left(t_{1}\right)\right)}+e^{\frac{\sigma_{0}}{T_{c}}\left(\theta\left(t_{2}\right)-2 \theta\left(t_{1}\right)\right)}\right] \tag{26}
\end{equation*}
$$

If we substitute Eq. (26) in Eq. (22) and we simplify, we get the solution for the friction torque when the speed is positive and the initial condition is different from zero:

$$
\begin{aligned}
& F(\theta(t))=F_{c}\left[1-2 e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta(t)-\theta\left(t_{2}\right)\right)}+\right. \\
& \left.2 e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta(t)+\theta\left(t_{1}\right)-2 \theta\left(t_{2}\right)\right)}-e^{-\frac{\sigma_{0}}{F_{c}}\left(\theta(t)+2 \theta\left(t_{1}\right)-2 \theta\left(t_{2}\right)\right)}\right]^{27)}
\end{aligned}
$$

