## Notes on the analytic solution for the Dahl's friction model

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*Abstract*— This document provides the analytical solution of the friction model for different changes in the sign of the vehicle speed.

## I. ANALYTIC SOLUTION OF THE DAHL'S FRICTION MODEL

The load torque  $\tau_a$  is described by the Dahl's model and is given by the following differential equation:

$$\frac{\mathrm{d}F}{\mathrm{d}\theta} = \sigma_0 \left( 1 - \frac{F}{F_c} \operatorname{sgn}\left(\dot{\theta}\right) \right) \tag{1}$$

Let make the hypothesis to have a positive speed signal during the time interval  $t \in [0, t_1]$ . At the time t = 0, we have the corresponding value for the angle  $\theta(0) = \theta_0$ . This hypothesis implies that we have  $sgn(\dot{\theta}) = +1$  in Eq. (1) for  $\theta \in [\theta_0, \theta]$ . We make also the hypothesis to start from null initial conditions, this implies that we need to solve the following differential equation:

$$\frac{\mathrm{d}F}{\mathrm{d}\theta} = \sigma_0 \left( 1 - \frac{F}{F_c} \right) \tag{2}$$

with the following initial condition:

$$F(\theta_0) = 0 \tag{3}$$

We divide both terms of Eq. (2) by  $\left(1 - \frac{F}{F_c}\right)$  and  $F_c$ , in order to obtain a suited primitive:

$$\frac{-\frac{1}{F_c} \left(\frac{\mathrm{d}F}{\mathrm{d}\theta}\right)}{\left(1 - \frac{F}{F_c}\right)} = -\frac{\sigma_0}{F_c} \tag{4}$$

To obtain the analytic solution of Eq. (4) for positive speeds, we integrate both terms during the interval  $(\theta_0, \theta(t))$ :

$$\int_{\theta_0}^{\theta(t)} \frac{-\frac{1}{F_c} \frac{\mathrm{d}F}{\mathrm{d}\theta}}{\left(1 - \frac{F}{F_c}\right)} \mathrm{d}\theta = -\frac{\sigma_0}{F_c} \int_{\theta_0}^{\theta(t)} \mathrm{d}\theta \tag{5}$$

The result of this integral is:

$$\ln\left|1 - \frac{F(\theta(t))}{F_c}\right| - \ln\left|1 - \frac{F(\theta_0)}{F_c}\right| = -\frac{\sigma_0}{F_c}(\theta(t) - \theta_0) \quad (6)$$

By substituting the initial condition (3), it is easily to obtain the solution for positive speeds:

$$F(\theta(t)) = F_c \left[ 1 - e^{-\frac{\sigma_0}{F_c}(\theta(t) - \theta_0)} \right]$$
(7)

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$$\frac{\mathrm{d}F}{\mathrm{d}\theta} = \sigma_0 \left(1 + \frac{F}{F_c}\right) \tag{8}$$

$$F(\theta(t_1^-)) = F(\theta(t_1^+))$$
(9)

To solve this problem, we proceed as for Eqs. (4) and (5), then we integrate between  $\theta(t_1)$  and  $\theta(t)$ , as follows:

$$\int_{\theta(t_1)}^{\theta(t)} \frac{\frac{1}{F_c} \frac{\mathrm{d}F}{\mathrm{d}\theta}}{\left(1 + \frac{F}{F_c}\right)} \mathrm{d}\theta = \int_{\theta(t_1)}^{\theta(t)} \frac{\sigma_0}{F_c} \mathrm{d}\theta \tag{10}$$

The solution of this integral is:

$$\ln\left|1 + \frac{F(\theta(t))}{F_c}\right| - k_1 = \frac{\sigma_0}{F_c}(\theta(t) - \theta(t_1))$$
(11)

Where  $k_1$  is a constant, depending from the initial conditions. By inverting this equation, we obtain:

$$F(\theta(t)) = F_c \left[ -1 + e^{\frac{\Theta_0}{F_c}(\theta(t) - \theta(t_1))} \cdot e^{k_1} \right]$$
(12)

To determine the constant  $k_1$ , we introduce the initial condition  $F(\theta(t_1^-)) = F(\theta(t_1^+))$ :

$$F(\theta(t_1^-)) = F_c \left[ 1 - e^{-\frac{\sigma_0}{F_c}\theta(t_1)} \right]$$
(13)

$$F(\theta(t_1^+)) = F_c\left[-1 + e^{\frac{\sigma_0}{F_c}(\theta(t_1) - \theta(t_1))} \cdot e^{k_1}\right]$$
(14)

It follows:

$$F_c\left[1 - e^{-\frac{\sigma_0}{T_c}\theta(t_1)}\right] = F_c\left[-1 + e^{k_1}\right]$$
(15)

By solving for  $k_1$ , we obtain:

$$k_1 = \ln\left[2 - e^{-\frac{\sigma_0}{T_c}\theta(t_1)}\right] \tag{16}$$

So the solution for negative speeds is:

$$F(\boldsymbol{\theta}(t)) = F_c \left[ -1 + e^{\frac{\sigma_0}{F_c}(\boldsymbol{\theta}(t) - \boldsymbol{\theta}(t_1))} \cdot e^{\ln\left[2 - e^{-\frac{\sigma_0}{F_c}\boldsymbol{\theta}(t_1)}\right]} \right]$$
(17)

By rearranging all terms, this expression can be simplified as follows:

$$F(\theta(t)) = F_c \left[ -1 + 2e^{\frac{\sigma_0}{F_c}(\theta(t) - \theta(t_1))} - e^{\frac{\sigma_0}{F_c}(\theta(t) - 2\theta(t_1))} \right]$$
(18)

If we make the hypothesis that the speed changes in sign and becomes positive during the time interval  $t \in [t_2, t_f]$ , we can find the analytic solution  $F(\theta)$  for this last interval, by repeating the same steps as for the previous cases. In this case, the boundary condition is  $F(\theta(t_2^-)) = F(\theta(t_2^+))$ , so we need to solve:

$$\frac{\mathrm{d}F}{\mathrm{d}\theta} = \sigma_0 \left(1 - \frac{F}{F_c}\right) \tag{19}$$

$$F(\theta(t_2^-)) = F(\theta(t_2^+))$$
(20)

We proceed as in the previous cases and we integrate the primitive between  $[\theta_2, \theta(t)]$ :

$$\int_{\theta_2}^{\theta(t)} \frac{-\frac{1}{F_c} \frac{\mathrm{d}F}{\mathrm{d}\theta}}{\left(1 - \frac{F}{F_c}\right)} \mathrm{d}\theta = -\frac{\sigma_0}{F_c} \int_{\theta_2}^{\theta(t)} \mathrm{d}\theta \tag{21}$$

We obtain the following analytic solution:

$$F(\theta(t)) = F_c \left[ 1 - e^{-\frac{\sigma_0}{F_c}(\theta(t) - \theta(t_2))} \cdot e^{k_2} \right]$$
(22)

We can determine the constant  $k_2$  by introducing the boundary condition  $F(\theta(t_2^-)) = F(\theta(t_2^+))$ :

$$F(\theta(t_{2}^{-})) = F_{c} \left[ -1 + 2e^{\frac{\sigma_{0}}{F_{c}}(\theta(t_{2}) - \theta(t_{1}))} - e^{\frac{\sigma_{0}}{F_{c}}(\theta(t_{2}) - 2\theta(t_{1}))} \right]$$
(23)  
$$F(\theta(t_{2}^{+})) = F_{c} \left[ 1 - e^{-\frac{\sigma_{0}}{F_{c}}(\theta(t_{2}) - \theta(t_{2}))} \cdot e^{k_{2}} \right]$$
(24)

It follows:

$$F_{c}\left[1-e^{k_{2}}\right] = F_{c}\left[-1+2e^{\frac{\sigma_{0}}{F_{c}}(\theta(t_{2})-\theta(t_{1}))}-e^{\frac{\sigma_{0}}{F_{c}}(\theta(t_{2})-2\theta(t_{1}))}\right]$$
(25)

From Eq. (25) we get the following expression for the constant  $k_2$ :

$$k_{2} = \ln \left[ 2 - 2e^{-\frac{\sigma_{0}}{F_{c}}(\theta(t_{2}) - \theta(t_{1}))} + e^{\frac{\sigma_{0}}{F_{c}}(\theta(t_{2}) - 2\theta(t_{1}))} \right]$$
(26)

If we substitute Eq. (26) in Eq. (22) and we simplify, we get the solution for the friction torque when the speed is positive and the initial condition is different from zero:

$$F(\theta(t)) = F_{c} \left[ 1 - 2e^{-\frac{\sigma_{0}}{F_{c}}(\theta(t) - \theta(t_{2}))} + 2e^{-\frac{\sigma_{0}}{F_{c}}(\theta(t) + \theta(t_{1}) - 2\theta(t_{2}))} - e^{-\frac{\sigma_{0}}{F_{c}}(\theta(t) + 2\theta(t_{1}) - 2\theta(t_{2}))} \right]$$
(27)