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Artificial compliance inherent to the intrinsic cohesive zone models: criteria and application to planar meshes

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Abstract

In this study, criteria on the artificial compliance due to intrinsic cohesive zone models are presented. The approach is based on a micromechanical model for a collection of cohesive zone models embedded between each mesh of a finite element-type discretization. The overall elastic behaviour of this cohesive volumetric medium is obtained using homogenization techniques and is given in a closed-form as function of bulk properties of the relevant material and mesh parameters (the mesh type and size). Practical criteria are obtained for the calibration of the cohesive stiffnesses bounding the additional compliance inherent to intrinsic cohesive zone models by lower value. For isotropic planar discretizations (e.g. Delaunay mesh), a rigorous bound is derived whereas convenient estimates are given for non-isotropic discretizations (e.g. regular mesh).

Keywords: Micromechanics; Damage; Cohesive Zone Models; Homogenization; Planar meshes

1 Introduction

Since the pioneering works of [Dugdale \(1960\)](#) and [Barenblatt \(1962\)](#), cohesive approaches had emerged as one of the most efficient methods used for numerical fracture mechanics. Their numerical simplicity as their capacity to simulate numerical fracture processes from crack initiation to overall failure without any ad hoc criteria are the most appealing features of these models. However, their numerical implementation exhibits a strong mesh sensitivity which is still an issue of concern: as shown in [Tijssens et al. \(2000\)](#), the fracture paths depend on the mesh geometry and size. Despite this path sensitivity, the authors show therein that the overall force-displacement response is not very sensitive to the mesh size and can be predicted with reasonable accuracy. Another aspect of this mesh sensitivity concerns the intrinsic Cohesive Zone Models (CZM), i.e. traction-separation laws with initial slope: incorporating cohesive zones between each couple of adjacent elements of a finite element-type discretization leads to an additional compliance since the density of the cohesive interfaces increases as the mesh is refined. This aspect can be illustrated on a simple 1D case (see [Figure 1](#)), where a linear elastic intrinsic CZM is inserted between two bulk elements. In that case, the equilibrium condition reads:

$$\frac{F}{S} = E^M \varepsilon = C_N [\mathbf{u}], \quad (1)$$

where F is the applied force, ε the strain in the bulk elements (mesh size L_{mesh} , cross section S), E^M the Young's modulus used in the bulk element constitutive behaviour, C_N the initial cohesive stiffness of the intrinsic model and $[\mathbf{u}]$ is the displacement jump across the cohesive zone. The overall strain of this

composite is:

$$\tilde{\varepsilon} = \frac{F/S}{E^M} + \frac{F/S}{C_N L_{\text{mesh}}}. \quad (2)$$

Since the equilibrium condition requires $F/S = \tilde{E}\tilde{\varepsilon}$, where \tilde{E} denotes the apparent Young's modulus of the assemblage, one can deduce the normalized apparent Young's modulus:

$$\frac{\tilde{E}}{E^M} = \frac{F/S}{E^M \tilde{\varepsilon}} = \frac{\xi}{1 + \xi} \quad \text{with} \quad \xi = \frac{C_N L_{\text{mesh}}}{E^M}. \quad (3)$$

According to this last equation, the ratio ξ appears as the key adimensional parameter in controlling the mesh sensitivity of intrinsic CZMs. More precisely, the added compliance vanishes ($\tilde{E} \rightarrow E^M$) when $\xi \rightarrow +\infty$, see Figure 1 (b). In other words, the overall elastic behaviour is not affected by the introduction of intrinsic CZMs between bulk elements and therefore the mesh sensitivity effect vanishes.

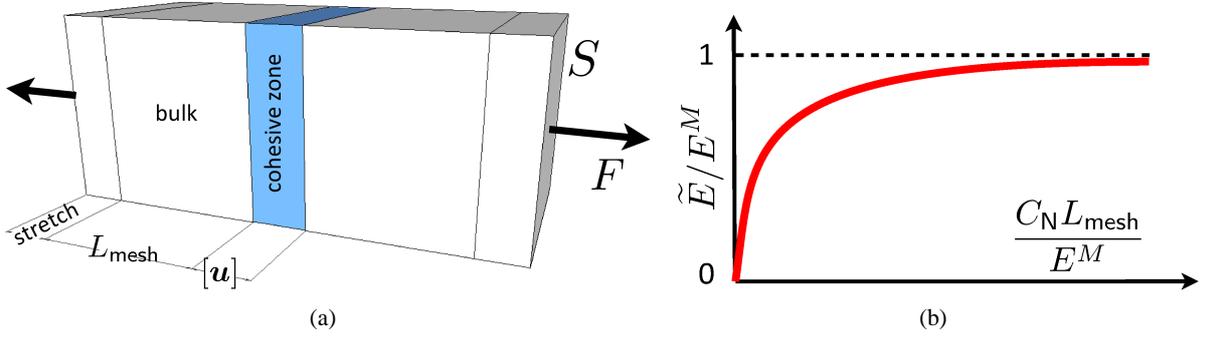


Figure 1: Illustration of the relationship between apparent Young's modulus and mesh size in 1D-case: (a) a representative part of 1D finite element mesh with embedded cohesive zone model, (b) overall Young's modulus normalized by bulk modulus vs mesh size.

Following the same type of ideas, various authors have proposed semi-empirical bound for the ratio ξ in order to define 'invisible' CZMs at the scale of a structure. Equation (3) results from similar mechanical considerations in the work of Turon et al. (2007) concerning the numerical simulation of delamination: taking ξ larger than 50 ($\xi > 50$) ensures that the apparent loss of stiffness is less than 2%, hence the composite is not affected by the presence of cohesive interfaces. Performing numerical tension and shear tests, Espinosa and Zavattieri (2003) have noticed that the elastic wave speeds remain unchanged across a cohesive line between two elastic and isotropic media when $\xi \geq 10$. Estimating the added compliance for cross-triangle elements arranged in quadrilateral pattern submitted to uniaxial tension, biaxial uniform tension and pure shear, Tomar et al. (2004) obtain (ν^M being the Poisson ratio of the bulk material):

$$\xi \gg \alpha \frac{\sqrt{2} + 1}{1 - \nu^M}. \quad (4)$$

with $\alpha = 1$ for plane stress and $\alpha = 1/(1 - (\nu^M)^2)$ for plane strain. The aim of this work is to forth fully generalize these criteria to three dimensional situations and to any type of loadings.

2 Micromechanical model

We focus in the sequel on *cohesive-volumetric* finite element approach with *intrinsic* cohesive zone model: each volumetric element of a standard finite element discretization is connected to each couple of adjacent elements using intrinsic CZMs as boundary conditions. Recent developments suggest to replace the cohesive-volumetric approach with the coupling between CZMs and X-FEM, e.g. Benvenuti (2008), but this cumbersome technic is not widely spread in commercial codes. Moreover, the

cohesive-volumetric approach can be used with extrinsic cohesive models, i.e. initially rigid or 'shifted' models (Hille et al., 2004). But most of the time, loading-unloading situations lead to elastic reload of the cohesive zones and the intrinsic case should anyway be considered. Intrinsic cohesive zone models embedded within a standard finite element discretization is thus investigated in the following as a reference case.

2.1 Cohesive discretization as a "matrix-inclusion" composite

Following Blal et al. (2011), the main idea is to replace a cohesive-volumetric finite element discretization by a continuous *matrix* containing penny-shaped cohesive *inclusions* (Figure 2). The matrix has

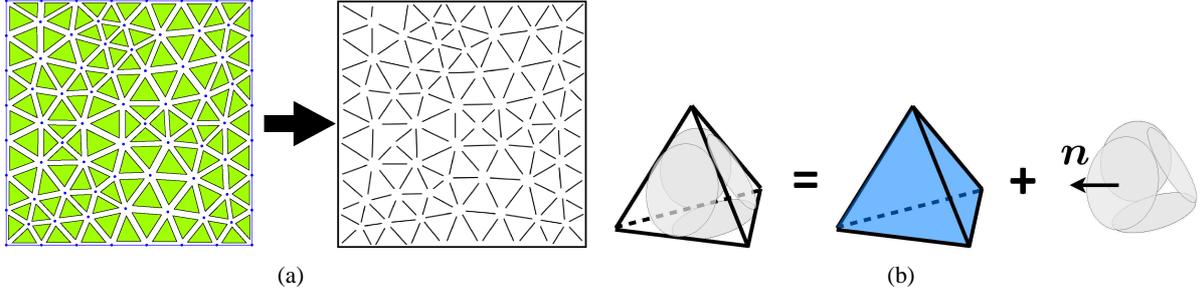


Figure 2: Principle of the approach: a cohesive-volumetric finite element mesh is replaced by a continuous matrix corresponding to bulk elements and a collection of penny-shaped cohesive inclusions corresponding to the edges of the underlying mesh; (a) 2-D illustration, (b) 3-D illustration.

the same behaviour as the bulk finite element behaviour whereas the penny-shaped inclusions have a cohesive behaviour defined by a traction-separation law. The spatial distribution of the cohesive inclusions corresponds to those of the edges of the underlying mesh and has the same density, denoted by Z . In particular, in the case of a statistical isotropic mesh, e.g. a Delaunay-type mesh, the inclusions are randomly distributed in space and in orientation. The density Z corresponds to the specific 'surface' of the interface between the meshes: in two dimensions, Z is equal to the ratio of the total length of the edges to the area of the meshed surface; in three dimensions, Z is equal to the ratio of the total area of the edges to the volume of the meshed body. Moreover, the next assumption is made concerning the shape of the inclusions:

Hypothesis 1. The inclusions are assumed to be penny-shaped (Figure 2). In two dimensions, the straight edges of the mesh are thus replaced by zero thickness whiskers and this assumption has no consequence. In three dimensions, the polygonal edges are replaced by disks (with the same spatial density): the two situations are admittedly close to each other but are different when considered rigorously.

2.2 Phases properties

In the sequel, we restrict our attention to linear elastic behaviours. Moreover, the matrix phase is considered as isotropic and its constitutive relation reads:

$$\boldsymbol{\sigma} = \mathbb{C}^M : \boldsymbol{\varepsilon} \quad \text{with} \quad \mathbb{C}^M = 3k^M \mathbb{J} + 2\mu^M \mathbb{K}, \quad (5)$$

where $\boldsymbol{\sigma}$ (resp. $\boldsymbol{\varepsilon}$) is the stress field (resp. strain), \mathbb{C}^M is a fourth order stiffness tensor, k^M and μ^M are the bulk and the shear modulus respectively. The symmetric tensors \mathbb{J} and \mathbb{K} define the generic basis of the fourth order isotropic symmetric tensors:

$$\mathbb{J} = \frac{1}{3} \mathbf{i} \otimes \mathbf{i} \quad \text{and} \quad \mathbb{K} = \mathbb{I} - \mathbb{J} \quad \text{with} \quad 2\mathbb{I}_{ijkl} = (\mathbf{i}_{ik} \mathbf{i}_{jl} + \mathbf{i}_{il} \mathbf{i}_{jk}) \quad (6)$$

where \mathbf{i} is the second order identity tensor. The previous constitutive law (5) can be written in a matrix form as follows:

$$\begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \sqrt{2}\sigma_{xy} \\ \sqrt{2}\sigma_{xz} \\ \sqrt{2}\sigma_{yz} \end{bmatrix} = \begin{bmatrix} \left(k^M + \frac{4\mu^M}{3}\right) & \left(k^M - \frac{2\mu^M}{3}\right) & \left(k^M - \frac{2\mu^M}{3}\right) & 0 & 0 & 0 \\ \left(k^M - \frac{2\mu^M}{3}\right) & \left(k^M + \frac{4\mu^M}{3}\right) & \left(k^M - \frac{2\mu^M}{3}\right) & 0 & 0 & 0 \\ \left(k^M - \frac{2\mu^M}{3}\right) & \left(k^M - \frac{2\mu^M}{3}\right) & \left(k^M + \frac{4\mu^M}{3}\right) & 0 & 0 & 0 \\ 0 & 0 & 0 & 2\mu^M & 0 & 0 \\ 0 & 0 & 0 & 0 & 2\mu^M & 0 \\ 0 & 0 & 0 & 0 & 0 & 2\mu^M \end{bmatrix} \begin{bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} \\ \sqrt{2}\varepsilon_{xy} \\ \sqrt{2}\varepsilon_{xz} \\ \sqrt{2}\varepsilon_{yz} \end{bmatrix} \quad (7)$$

The cohesive traction-separation law corresponds to a linear relation between the cohesive stress vector \mathbf{R}^{coh} and the opening displacement vector $[\mathbf{u}] = \mathbf{u}^+ - \mathbf{u}^-$ where \mathbf{u}^+ (resp. \mathbf{u}^-) is the displacement of the points located on the top (resp. bottom) side of the interface. In the local normal-tangent basis oriented by the normal vector \mathbf{n} , the jump displacement vector can be decomposed to a normal, u_N , and a tangential, \mathbf{u}_T , component, so that: $[\mathbf{u}] = u_N \mathbf{n} + \mathbf{u}_T$. The cohesive constitutive relation reads:

$$\mathbf{R}^{\text{coh}} = \mathbf{K} \cdot [\mathbf{u}] \quad \text{with} \quad \mathbf{K} = C_N \mathbf{n} \otimes \mathbf{n} + C_T (\mathbf{i} - \mathbf{n} \otimes \mathbf{n}), \quad (8)$$

where C_N (resp. C_T) is the normal (resp. tangential) initial 'stiffness' of the cohesive law. The cohesive stress tensor is given thus combining (8) and the relationship $\mathbf{R}^{\text{coh}} = \boldsymbol{\sigma}^{\text{coh}} \cdot \mathbf{n}$ as proposed in [Acary and Monerie \(2006\)](#):

$$\boldsymbol{\sigma}^{\text{coh}} = (C_N \mathbb{E}_l + C_T \mathbb{K}_l) : ([\mathbf{u}] \otimes_s \mathbf{n}), \quad (9)$$

where \otimes_s is the symmetric dyadic product ($2\mathbf{a} \otimes_s \mathbf{b} = a_i b_j + a_j b_i$ for any vector \mathbf{a} and \mathbf{b}) and $\mathbb{E}_l, \mathbb{K}_l$ are two components of the fourth order transversely isotropic and symmetric tensors frame:

$$\mathbb{E}_l = \mathbf{n} \otimes \mathbf{n} \otimes \mathbf{n} \otimes \mathbf{n} \quad \text{and} \quad \mathbb{K}_l = 2(\mathbf{j}_s \otimes \mathbf{j}_s + \mathbf{j}_t \otimes \mathbf{j}_t) \quad (10)$$

with $\mathbf{j}_s = \mathbf{n} \otimes_s \mathbf{s}$ and $\mathbf{j}_t = \mathbf{n} \otimes_s \mathbf{t}$, where \mathbf{s} and \mathbf{t} are two orthogonal vectors defining the transversal plane ($\mathbf{n}, \mathbf{t}, \mathbf{s}$ define the local orthogonal basis of the cohesive inclusion). Defining the cohesive 'strain' with the help of a small length e ([Michel et al., 1994](#)):

$$\boldsymbol{\varepsilon}^{\text{coh}} = \frac{[\mathbf{u}] \otimes_s \mathbf{n}}{e}, \quad (11)$$

a fourth order stiffness tensor \mathbb{C}^{coh} can be deduced for the cohesive phase. The constitutive relation thus reads for the inclusions:

$$\boldsymbol{\sigma}^{\text{coh}} = \mathbb{C}^{\text{coh}} : \boldsymbol{\varepsilon}^{\text{coh}} \quad \text{with} \quad \mathbb{C}^{\text{coh}} = e (C_N \mathbb{E}_l + C_T \mathbb{K}_l). \quad (12)$$

According to the local frame $(\mathbf{n}, \mathbf{t}, \mathbf{s})$, the cohesive governing equation (12) reads in a reduced form:

$$\begin{bmatrix} \sigma_{nn} \\ \sigma_{tt} \\ \sigma_{ss} \\ \sqrt{2}\sigma_{nt} \\ \sqrt{2}\sigma_{ns} \\ \sqrt{2}\sigma_{st} \end{bmatrix} = e \begin{bmatrix} C_N & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & C_T & 0 & 0 \\ 0 & 0 & 0 & 0 & C_T & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_{nn} \\ \varepsilon_{tt} \\ \varepsilon_{ss} \\ \sqrt{2}\varepsilon_{nt} \\ \sqrt{2}\varepsilon_{ns} \\ \sqrt{2}\varepsilon_{st} \end{bmatrix} \quad (13)$$

The small length e , that should tend to zero, is a fictitious thickness associated to the cohesive zone. Since oblate ellipsoids tend to penny-shaped inclusions when their thickness tends to zero, the cohesive inclusions are now considered as oblate ellipsoids and their volume fraction f is the product of the density Z (inversely proportional to a length, namely the mesh size L_{mesh}) and of the fictitious thickness e :

$$f = eZ$$

where the cylindrical hypothesis of inclusions instead of oblate one has no consequence when $e \rightarrow 0$.

2.3 The overall homogeneous behaviour: Hashin-Shtrickman estimate

A Hashin-Shtrickman estimate (Hashin and Shtrickman, 1963) is used in order to establish an analytical expression of the overall elastic stiffness, denoted by \mathbb{C}^{hom} . The considered matrix-inclusion composite (Figure 2) is composed of an isotropic elastic matrix (volume fraction $1 - f$) following the constitutive relation (5) and of a collection of transversely isotropic oblate ellipsoids (volume fraction f) with the largest semi-axis a varying from A^- to A^+ , with the same aspect ratio $w = b/a \ll 1$ (b is the smallest semi-axis, i.e. along the dimension of the ellipsoids along the symmetry axis) and following the constitutive relation (8). The orientation of these ellipsoids is characterized by the direction of their symmetry axis, i.e. a vector \mathbf{n} of the unit sphere S of \mathbb{R}^3 (measure 4π). This collection of inclusions is splitted into $N - 1$ families r ($r = 2, \dots, N$), the r -th family being defined by a radius included in $(a, a + da)$ and an orientation lying within the elementary solid angle ds centered on \mathbf{n} . Defining the inclusion density $\phi(a, \mathbf{n})$ such that $\phi(a, \mathbf{n})dad\mathbf{n}$ is the number of inclusions of the r -th family in a unit volume, the volume fraction by unit volume c_r of the r -th family reads:

$$c_r = \phi(a, \mathbf{n}) \frac{4\pi}{3} a^2 b da d\mathbf{n} = \phi(a, \mathbf{n}) \frac{4\pi}{3} a^3 w da d\mathbf{n} \quad (r = 2, \dots, N),$$

$$\text{with } f = \sum_{r=2}^N c_r = \int_S \int_{A^-}^{A^+} \phi(a, \mathbf{n}) \frac{4\pi}{3} a^3 w da d\mathbf{n}. \quad (14)$$

For this situation, the following generalization of the Hashin-Shtrickman's result is considered (Willis, 1977):

$$\begin{aligned} \mathbb{C}^{\text{HS}}(\mathbb{C}^0) = & \\ & \left[(1 - f) \mathbb{C}^{\text{M}} : \left(\mathbb{I} + \mathbb{P} : (\mathbb{C}^{\text{M}} - \mathbb{C}^0) \right)^{-1} + \sum_{r=2}^N c_r \mathbb{C}_r^{\text{coh}} : \left(\mathbb{I} + \mathbb{P} : (\mathbb{C}_r^{\text{coh}} - \mathbb{C}^0) \right)^{-1} \right] \\ & : \left[(1 - f) \left(\mathbb{I} + \mathbb{P} : (\mathbb{C}^{\text{M}} - \mathbb{C}^0) \right)^{-1} + \sum_{r=2}^N c_r \left(\mathbb{I} + \mathbb{P} : (\mathbb{C}_r^{\text{coh}} - \mathbb{C}^0) \right)^{-1} \right]^{-1} \end{aligned} \quad (15)$$

where \mathbb{C}^0 (resp. $\mathbb{C}_r^{\text{coh}}$) is the fourth order stiffness tensor of a reference medium (resp. of the r -th family of inclusions) and \mathbb{P} is the Hill polarization tensor which characterizes the stress that the infinite surrounding reference medium applies on a single ellipsoid having a homogeneous eigenstrain. The Hill tensor \mathbb{P} depends on the shape of the inclusion w , on its orientation \mathbf{n} and on the stiffness tensor of the reference medium \mathbb{C}^0 . Following Willis (1977), this reference medium is a homogeneous material such that the constitutive relations (5) and (12) are replaced respectively with $\boldsymbol{\sigma} = \mathbb{C}^0 : \boldsymbol{\varepsilon} + \boldsymbol{\tau}$ and $\boldsymbol{\sigma}^{\text{coh}} = \mathbb{C}^0 : \boldsymbol{\varepsilon}^{\text{coh}} + \boldsymbol{\tau}^{\text{coh}}$ where the polarizations $\boldsymbol{\tau}$ and $\boldsymbol{\tau}^{\text{coh}}$ reads: $\boldsymbol{\tau} = (\mathbb{C} - \mathbb{C}^0) : \boldsymbol{\varepsilon}$ and $\boldsymbol{\tau}^{\text{coh}} = (\mathbb{C}^{\text{coh}} - \mathbb{C}^0) : \boldsymbol{\varepsilon}^{\text{coh}}$. Using the Hill influence tensor $\mathbb{C}^* = \mathbb{P}^{-1} - \mathbb{C}^0$, and introducing the two fourth order tensors $\mathbb{V}_1 = (\mathbb{C}^* + \mathbb{C}^{\text{M}})^{-1}$ and $\mathbb{V}_r = (\mathbb{C}^* + \mathbb{C}_r^{\text{coh}})^{-1}$, one obtains:

$$\begin{aligned} \mathbb{I} + \mathbb{P} : (\mathbb{C}^{\text{M}} - \mathbb{C}^0) &= \mathbb{I} + (\mathbb{C}^* + \mathbb{C}^0)^{-1} : (\mathbb{C}^{\text{M}} - \mathbb{C}^0) \\ &= (\mathbb{C}^* + \mathbb{C}^0)^{-1} : (\mathbb{C}^* + \mathbb{C}^{\text{M}}) \\ &= (\mathbb{C}^* + \mathbb{C}^0)^{-1} : \mathbb{V}_1^{-1} \end{aligned}$$

and the same relation holds for

$$\mathbb{I} + \mathbb{P} : (\mathbb{C}_r^{\text{coh}} - \mathbb{C}^0) = (\mathbb{C}^* + \mathbb{C}^0)^{-1} : \mathbb{V}_r^{-1}.$$

Combining these two last relations and simplifying by $(\mathbb{C}^* + \mathbb{C}^0)$, equation (15) is rearranged as:

$$\mathbb{C}^{\text{HS}}(\mathbb{C}^0) = \left[(1 - f) \mathbb{C}^{\text{M}} : \mathbb{V}_1 + \sum_{r=2}^N c_r \mathbb{C}_r^{\text{coh}} : \mathbb{V}_r \right] : \left[(1 - f) \mathbb{V}_1 + \sum_{r=2}^N c_r \mathbb{V}_r \right]^{-1} \quad (16)$$

Introducing $\mathbb{T}_r = \mathbb{V}_r : \mathbb{V}_1^{-1}$ and remarking that the cohesive stiffness depends only on the orientation \mathbf{n} , i.e. $\mathbb{C}_r^{\text{coh}} = \mathbb{C}^{\text{coh}}(\mathbf{n})$, and that tensor \mathbb{T}_r depends only on the aspect ratio w and the direction \mathbf{n} , i.e.

$$\mathbb{T}_r = \mathbb{T}(w, \mathbf{n}) = (\mathbb{C}^*(w, \mathbf{n}) + \mathbb{C}^{\text{coh}}(\mathbf{n}))^{-1} : (\mathbb{C}^*(w, \mathbf{n}) + \mathbb{C}^{\text{M}}) \quad (17)$$

the estimate (16) is rewritten with the help of the density $\phi(a, \mathbf{n})$, equation (14) and an integration over the radius and the orientation:

$$\begin{aligned} \mathbb{C}^{\text{HS}}(\mathbb{C}^0) &= \left[(1-f)\mathbb{C}^{\text{M}} + \int_S \int_{A^-}^{A^+} \phi(a, \mathbf{n}) \frac{4\pi}{3} a^3 w \mathbb{C}^{\text{coh}}(\mathbf{n}) : \mathbb{T}(w, \mathbf{n}) da ds \right] \\ &: \left[(1-f)\mathbb{I} + \int_S \int_{A^-}^{A^+} \phi(a, \mathbf{n}) \frac{4\pi}{3} a^3 w \mathbb{T}(w, \mathbf{n}) da ds \right]^{-1}. \end{aligned} \quad (18)$$

Since w is assumed to be constant and $\mathbb{C}^{\text{coh}}(\mathbf{n})$ and $\mathbb{T}(w, \mathbf{n})$ do not depend on the radius a , integrating over a leads to:

$$\begin{aligned} \mathbb{C}^{\text{HS}}(\mathbb{C}^0) &= \left[(1-f)\mathbb{C}^{\text{M}} + w \int_S \psi(\mathbf{n}) \mathbb{C}^{\text{coh}}(\mathbf{n}) : \mathbb{T}(w, \mathbf{n}) ds \right] : \\ &\left[(1-f)\mathbb{I} + w \int_S \psi(\mathbf{n}) \mathbb{T}(w, \mathbf{n}) ds \right]^{-1} \end{aligned} \quad (19)$$

where

$$\psi(\mathbf{n}) = \int_{A^-}^{A^+} \frac{4}{3} \pi a^3 \phi(a, \mathbf{n}) da.$$

If the underlying mesh contains specific orientations (e.g. anisotropic meshes), they have to be taken into account through the density $\psi(\mathbf{n})$. For simplicity, isotropic meshes (e.g. Delaunay-type meshes) are considered in the next section.

2.4 Lower bound for isotropic meshes

We now specialize (19) for the case of an isotropic microstructure: both matrix and the mesh distribution are isotropic. Hence, the orientations of inclusions are assumed to have an equi-probability property (randomly oriented inclusions corresponding to isotropic overall meshes), the density $\psi(\mathbf{n})$ is reduced to $f/(4\pi w)$ and the estimate (19) becomes ($f = eZ$):

$$\begin{aligned} \mathbb{C}^{\text{HS}}(\mathbb{C}^0) &= \left[\frac{f}{4\pi} \int_S \mathbb{C}^{\text{coh}} : \mathbb{T}(w, \mathbf{n}) ds + (1-f)\mathbb{C}^{\text{M}} \right] : \left[\frac{f}{4\pi} \int_S \mathbb{T}(w, \mathbf{n}) ds + (1-f)\mathbb{I} \right]^{-1} \\ &= \left[eZ \langle \mathbb{C}^{\text{coh}} : \mathbb{T} \rangle_{\circ} + (1-eZ)\mathbb{C}^{\text{M}} \right] : \left[eZ \langle \mathbb{T} \rangle_{\circ} + (1-eZ)\mathbb{I} \right]^{-1} \end{aligned} \quad (20)$$

where $\langle \cdot \rangle_{\circ}$ indicates the average over all orientations. Following [Gatt et al. \(2005\)](#), this orientational average is equivalent to a projection over the isotropic frame for the fourth order symmetric tensors:

$$\langle \mathbb{D} \rangle_{\circ} = \frac{\mathbb{J} :: \mathbb{D}}{\mathbb{J} :: \mathbb{J}} \mathbb{J} + \frac{\mathbb{K} :: \mathbb{D}}{\mathbb{K} :: \mathbb{K}} \mathbb{K} \quad \text{for any fourth order tensor } \mathbb{D}, \quad (21)$$

and the overall stiffness tensor is obtained after the passage to the limit: $\mathbb{C}^{\text{hom}} = \lim_{e \rightarrow 0} \mathbb{C}^{\text{HS}}(\mathbb{C}^0)$. At this stage, according to the choice of the reference medium \mathbb{C}^0 , different bounds and estimates can be derived. Since, the normal and the tangential cohesive stiffnesses C_{N} and C_{T} have bounded values, the cohesive stiffness tensor \mathbb{C}^{coh} tends to zero when the small length e tends to zero (see equation (12)). At the limit $e \rightarrow 0$, \mathbb{C}^{coh} is thus always smaller in a quadratic sense than the matrix elastic tensor \mathbb{C}^{M} . The choice of the reference medium $\mathbb{C}^0 = \mathbb{C}^{\text{M}}$ corresponds to the Hashin-shtrickman upper bound (or the Mori-Tanaka estimate) and gives the trivial result $\mathbb{C}^{\text{hom}} = \mathbb{C}^{\text{M}}$ at the limit $e \rightarrow 0$. The same trivial result

is obtained for the self-constituent scheme ($\mathbb{C}^0 = \mathbb{C}^{\text{hom}}$). Thus, by focusing on the case $\mathbb{C}^0 = \mathbb{C}^{\text{coh}}$, i.e. using the most compliant phase as a reference medium the Hashin-Shtrickman lower bound is defined $\mathbb{C}^{\text{HS-}} = \mathbb{C}^{\text{HS}}(\mathbb{C}^{\text{coh}})$:

$$\begin{aligned}\mathbb{C}^{\text{hom}} &= \lim_{e \rightarrow 0} \mathbb{C}^{\text{HS-}} \\ &= \lim_{e \rightarrow 0} \left[eZ \langle \mathbb{C}^{\text{coh}} : \mathbb{T} \rangle_{\circ} + (1 - eZ)\mathbb{C}^{\text{M}} \right] : [eZ \langle \mathbb{T} \rangle_{\circ} + (1 - eZ)\mathbb{I}]^{-1}.\end{aligned}\quad (22)$$

where the tensor \mathbb{T} is reduced in this case to:

$$\mathbb{T} = \mathbb{T}(\mathbb{C}^{\text{coh}}) = \mathbb{I} + \mathbb{P}(\mathbb{C}^{\text{coh}}) : (\mathbb{C}^{\text{M}} - \mathbb{C}^{\text{coh}}).\quad (23)$$

The explicit analytical expression of the fourth order tensor \mathbb{C}^{hom} can be conveniently obtained by representing the different tensors in terms of the components of the generic basis of transversely isotropic symmetric and fourth order tensors. Any transversely isotropic symmetric and fourth order tensors \mathbb{C} can be linearly decomposed as follows (see [Bornert et al. \(2001\)](#) for example):

$$\mathbb{C} = C_1 \mathbb{E}_l + C_2 \mathbb{J}_t + C_3 (\mathbb{F} + {}^{\text{T}}\mathbb{F}) + C_5 \mathbb{K}_t + C_6 \mathbb{K}_l,\quad (24)$$

where \mathbb{E}_l and \mathbb{K}_l are previously introduced in (10) and the other components of the transversely isotropic tensor frame are given by:

$$\begin{aligned}\mathbf{i}_t &= \mathbf{i} - \mathbf{n} \otimes \mathbf{n} & \mathbb{J}_t &= \frac{1}{2} \mathbf{i}_t \otimes \mathbf{i}_t, \\ \mathbb{F} &= \frac{1}{\sqrt{2}} \mathbf{i}_t \otimes \mathbf{n} \otimes \mathbf{n} & \mathbb{K}_t &= \mathbb{I}_t - \mathbb{J}_t.\end{aligned}\quad (25)$$

with \mathbb{I}_t being the fourth order transversal identity and \mathbf{n} the main axis of the transversely isotropic medium (here \mathbf{n} coincides with the outward normal of the penny-shaped cohesive inclusions). It follows that the sum and the product of two tensors \mathbb{C} and \mathbb{Q} are immediately given by:

$$\begin{aligned}\mathbb{C} + \mathbb{Q} &= (C_1 + Q_1) \mathbb{E}_l + (C_2 + Q_2) \mathbb{J}_t + (C_3 + Q_3) (\mathbb{F} + {}^{\text{T}}\mathbb{F}) + (C_5 + Q_5) \mathbb{K}_t \\ &\quad + (C_6 + Q_6) \mathbb{K}_l, \\ \mathbb{C} : \mathbb{Q} &= (C_1 Q_1 + C_3 Q_3) \mathbb{E}_l + (C_2 Q_2 + C_3 Q_3) \mathbb{J}_t + (C_1 Q_3 + C_3 Q_2) \mathbb{F} \\ &\quad + (C_3 Q_1 + C_2 Q_3) {}^{\text{T}}\mathbb{F} + C_5 Q_5 \mathbb{K}_t + C_6 Q_6 \mathbb{K}_l.\end{aligned}\quad (26)$$

Moreover, the inverse of a tensor \mathbb{C} can be obtained using simple algebraic manipulations:

$$\mathbb{C}^{-1} = \frac{C_1}{\Delta} \mathbb{E}_l + \frac{C_2}{\Delta} \mathbb{J}_t + \frac{-C_3}{\Delta} (\mathbb{F} + {}^{\text{T}}\mathbb{F}) + \frac{1}{C_5} \mathbb{K}_t + \frac{1}{C_6} \mathbb{K}_l\quad (27)$$

where $\Delta = C_1 C_2 - C_3^2$.

As first step, the cohesive stiffness tensor is re-written in the transversely isotropic frame:

$$\mathbb{C}^{\text{coh}} = e \left(C_{\text{N}} \mathbb{E}_l + C_{\text{A}} \mathbb{J}_t + C_{\text{B}} (\mathbb{F} + {}^{\text{T}}\mathbb{F}) + C_{\text{C}} \mathbb{K}_t + C_{\text{T}} \mathbb{K}_l \right),\quad (28)$$

where the coefficients, C_{A} , C_{B} and C_{C} do not have any physical sense and are introduced in order to calculate the inverse tensors occurring in the expression of the Hashin-Shtrickman estimate; indeed, these coefficients will naturally disappear when e tends to zero. The expression of the polarization tensor \mathbb{P} is then derived for penny-shaped inclusions (radius R) with the cohesive inclusions (28) as the reference medium using the method proposed in [Sevostianov et al. \(2005\)](#):

$$\begin{aligned}\mathbb{P}(e, \mathbf{n}) &= \frac{1}{C_{\text{N}}} e \mathbb{E}_l + \frac{3\pi}{4\sqrt{2} C_{\text{N}} R} (\mathbb{F} + {}^{\text{T}}\mathbb{F}) - \frac{\pi}{C_{\text{T}} R} (\mathbb{J}_t + \mathbb{K}_t) \\ &\quad + \frac{1}{C_{\text{T}} e} \mathbb{K}_t + \frac{C_{\text{A}} + 2C_{\text{C}}}{4C_{\text{T}}^2 R} \pi \mathbb{K}_l.\end{aligned}\quad (29)$$

The Projection of the matrix stiffness tensor \mathbb{C}^M in the transversely isotropic frame:

$$\begin{aligned}\mathbb{C}^M &= \left[k^M + \frac{4\mu^M}{3} \right] \mathbb{E}_l + \left[\sqrt{2} \left(k^M - \frac{2\mu^M}{3} \right) \right] (\mathbb{F} + {}^T\mathbb{F}) \\ &+ \left[2k^M + \frac{2\mu^M}{3} \right] \mathbb{J}_t + 2\mu^M (\mathbb{K}_t + \mathbb{K}_l),\end{aligned}\quad (30)$$

and the substitution of equations (5), (28) and (29) into (23) leads to:

$$\begin{aligned}\mathbb{T} &= \left[\frac{9e\pi + 12R}{12C_N e R} k^M + \left(\frac{4}{3C_N e} - \frac{\pi}{2C_N R} \right) \mu^M \right] \mathbb{E}_l \\ &+ \left[-\frac{3C_A e \pi}{4\sqrt{2}C_N R} + \frac{(18e\pi + 24R)}{12\sqrt{2}C_N e R} k^M + \left(-\frac{2\sqrt{2}}{3C_N e} + \frac{\pi}{2\sqrt{2}C_N R} \right) \mu^M \right] (\mathbb{F} + {}^T\mathbb{F}) \\ &+ \left[1 + \frac{C_A e \pi}{C_T R} + \frac{(-24C_N \pi + 9C_T \pi)}{12C_N C_T R} k^M + \left(-\frac{\pi}{2C_N R} - \frac{2\pi}{3C_T R} \right) \mu^M \right] \mathbb{J}_t \\ &+ \left[\frac{C_C e \pi + C_T R}{C_T R} - \frac{2\pi \mu^M}{C_T R} \right] \mathbb{K}_t \\ &+ \left[1 - \frac{C_A e \pi + 2C_C e \pi + 4C_T R}{4C_T R} + \frac{(C_A e \pi + 2C_C e \pi + 4C_T R) \mu^M}{2C_T^2 e R} \right] \mathbb{K}_l.\end{aligned}\quad (31)$$

The Hashin-Shtrikman lower bound (22) involves the quantity $\mathbb{C}^{\text{coh}} : \mathbb{T}$ which can be obtained using the formulas (12), (31) and the elementary operations introduced in (26):

$$\begin{aligned}\mathbb{C}^{\text{coh}} : \mathbb{T} &= \left[k^M + \frac{4\mu^M}{3} + \frac{3k^M - 2\mu^M}{4R} \pi e \right] \mathbb{E}_l \\ &+ \sqrt{2} \left[k^M - \frac{2\mu^M}{3} + \frac{3k^M + \mu^M}{4R} \pi e \right] \mathbb{F} \\ &+ \left[\frac{C_A(-24k + 16\mu^M)}{12\sqrt{2}C_T R} \pi e + \frac{C_A(9C_T k^M + 12C_T \mu^M)}{12\sqrt{2}C_N C_T R} \pi e \right] {}^T\mathbb{F} \\ &+ \left[\frac{C_A \pi (3k^M - 2\mu^M)}{4C_N R} e - \frac{C_A(6k^M \pi - 3C_T R + 2\pi \mu^M)}{3C_T R} e \right] \mathbb{J}_t \\ &+ \left[\left(C_C - \frac{2C_C \pi \mu^M}{C_T R} \right) e \right] \mathbb{K}_t + \left[2\mu^M + \frac{(C_A + 2C_C) \mu^M}{2C_T R} \pi e \right] \mathbb{K}_l \\ &+ o(e)\end{aligned}\quad (32)$$

Then, to calculate the expression

$$\mathbb{C}^{\text{HS}^-} = \left[eZ \langle \mathbb{C}^{\text{coh}} : \mathbb{T} \rangle_{\odot} + (1 - eZ) \mathbb{C}^M \right] : \left[eZ \langle \mathbb{T} \rangle_{\odot} + (1 - eZ) \mathbb{I} \right]^{-1},$$

use is made of the average over all spatial orientations (see (21)) and the inversion relationship (27). Noting that

$$\begin{cases} \mathbb{E}_l :: \mathbb{J} = \frac{1}{3}, & \mathbb{J}_t :: \mathbb{J} = \frac{2}{3}, \\ \mathbb{F} :: \mathbb{J} = {}^T\mathbb{F} :: \mathbb{J} = \frac{\sqrt{2}}{3}, & \mathbb{K}_t :: \mathbb{J} = \mathbb{K}_l :: \mathbb{J} = 0, \\ \mathbb{E}_l :: \mathbb{K} = \frac{2}{3}, & \mathbb{J}_t :: \mathbb{K} = \frac{1}{3}, \\ \mathbb{F} :: \mathbb{K} = {}^T\mathbb{F} :: \mathbb{K} = \frac{-\sqrt{2}}{3}, & \mathbb{K}_t :: \mathbb{K} = \mathbb{K}_l :: \mathbb{K} = 2, \end{cases}\quad (33)$$

the power series expansion of \mathbb{C}^{HS^-} around the point $e = 0$ at the first order reads:

$$\begin{aligned}\mathbb{C}^{\text{HS}^-} &= \left(\left[3k^M - 2Zk^M e \right] \mathbb{J} + \left[2\mu^M - \frac{14}{15} Z \mu^M e \right] \mathbb{K} + o(e) \right) : \\ &\left(\left[\frac{C_N}{C_N + k^M Z} + g(e) \right] \mathbb{J} + \left[\frac{15C_N C_T \mu^M}{15C_N C_T + 12C_N Z \mu^M + 4C_T Z \mu^M} + h(e) \right] \mathbb{K} + o(e) \right)\end{aligned}\quad (34)$$

where

$$g(e) = \frac{2C_N^2 k^M \pi Z}{C_T R (C_N + Z k^M)^2} e + \frac{-9k^M \pi + 2C_N R}{6R (C_N + Z k^M)^2} C_N Z e$$

and

$$h(e) = \frac{15 (3C_T^2 \pi \mu^M + C_N (8C_T^2 R - 3(C_A + 2C_C) \pi \mu^M + 14C_T \pi \mu^M))}{R(4C_T Z \mu^M + 3C_N(5C_T + 4Z \mu^M))^2} C_N Z e.$$

Finally, the passage to the limit $e \rightarrow 0$ allows to derive the analytical expression of the homogeneous Hashin-Shtrikman lower bound:

$$\mathbb{C}^{\text{hom}} = 3 \frac{C_N k^M}{C_N + k^M Z} \mathbb{J} + 2 \frac{15 C_N C_T \mu^M}{15 C_N C_T + 12 C_N Z \mu^M + 4 C_T Z \mu^M} \mathbb{K}. \quad (35)$$

Hence, the expression of the bulk and shear homogeneous moduli k^{hom} and μ^{hom} are:

$$\begin{cases} \frac{k^{\text{hom}}}{k^M} = \frac{\xi_k}{1 + \xi_k} & \text{with } \xi_k = \frac{C_N}{Z k^M}, \\ \frac{\mu^{\text{hom}}}{\mu^M} = \frac{\xi_\mu}{1 + \xi_\mu} & \text{with } \xi_\mu = \frac{15}{4(1 + 3C_N/C_T)} \frac{C_N}{Z \mu^M}. \end{cases} \quad (36)$$

It is worth noting that equations (36) show that a cohesive-volumetric formulation with vanishing tangential cohesive stiffness ($C_T \rightarrow 0$) leads to a macroscopic no shear material ($\mu^{\text{hom}} \rightarrow 0$). Moreover, the lower bounds (36) allow to define *criteria* on the overall loss of stiffnesses, e.g. assuming that a reduction of 5% on the apparent bulk and shear moduli is admissible:

$$\begin{cases} \frac{k^{\text{hom}}}{k^M} \geq 0.95 \text{ is ensured for } \xi_k \geq 20 \\ \frac{\mu^{\text{hom}}}{\mu^M} \geq 0.95 \text{ is ensured for } \xi_\mu \geq 20. \end{cases} \quad (37)$$

Since the geometric *hypothesis* 1 has no influence for the case of 2-D discretization, it should be mentioned that, for planar isotropic meshes, (36) is a lower bound and (37) is a '*rigorous*' *criteria*. For regular meshes, (36) is an estimate. The accuracy of the obtained results is illustrated in the next section and practical criteria are derived in the section 4.

3 Numerical experiments

All calculation presented hereafter were done using the software XPER (Perales et al., 2008, 2010). The analysis is based on embedded linear elastic cohesive-volumetric elements and isotropic medium under plane strain conditions. In Figure 4, the dependency of the overall elastic moduli on the normal-to-tangential cohesive stiffness ratio is studied for regular meshes (see Figure 3, left). Bulk material properties are as follows: Young's modulus $E^M = 117.5$ GPa and Poisson coefficient $\nu^M = 0.3$. The evolution of the overall elastic properties as function of the normal cohesive stiffness is illustrated for different normal-to-tangential cohesive stiffness ratios C_N/C_T . Numerical experiments show clearly that the overall bulk modulus k^{hom} is not sensitive to the ratio C_N/C_T , as predicted by the theoretical bounds (36). The overall shear modulus μ^{hom} decreases with the ratio C_N/C_T , and again these results are compatible with the bounds (36). It should be noticed that these bounds are sharper when the normal-to-tangential cohesive stiffness ratio decreases. Numerically speaking, the bounds (36) are thus not very accurate for large values of the ratio C_N/C_T as expected.

The results presented in Figure 5 show that the apparent reduction associated to the Young's modulus E^{hom}/E^M depends on the normal-to-tangential cohesive stiffness ratio as expected by (39). Moreover, we observe that the ratio C_N/C_T leading to an apparent Young's modulus reduction E^{hom}/E^M increases with the Poisson ratio: the dashed lines show that for a material with $\nu^M = 0.3$, the Young's modulus

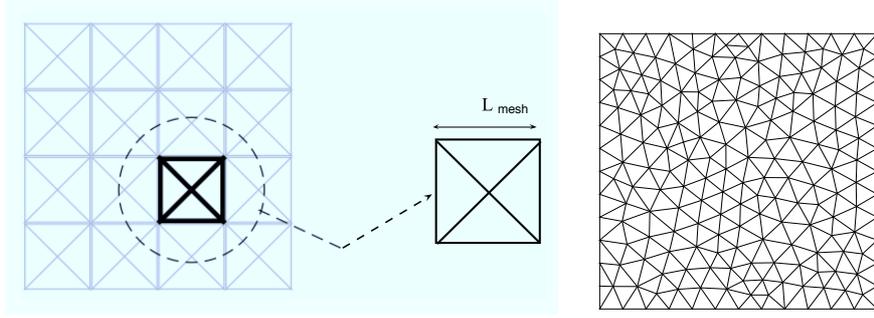


Figure 3: Examples of Regular (left) and Delaunay-type (right) meshes.

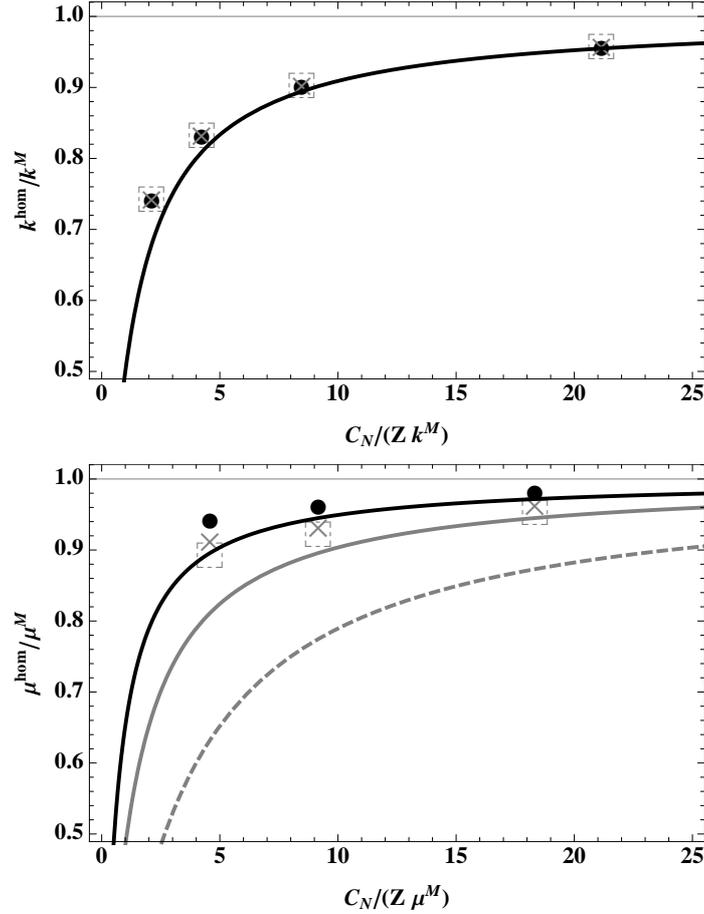


Figure 4: Normalized overall elastic moduli for different cases of the normal-to-tangential cohesive stiffness ratio: bulk modulus (top) and shear modulus (bottom). Numerical results: $C_N/C_T = 1/3$ black bullets, $C_N/C_T = 1$ gray crosses, $C_N/C_T = 3$ gray dashed squares. Theoretical bounds (36): $C_N/C_T = 1/3$ black curve, $C_N/C_T = 1$ gray curve, $C_N/C_T = 3$ gray dashed curve.

reduction reaches 0.77 when the ratio $C_N/C_T = 1$, whereas a material with $\nu^M = 0$ needs a ratio $C_N/C_T = 1/3$ to reach the same reduction; this result is consistent with the proposed criterion (42).

In Figure 6 and Figure 7, the numerical experiments concern both planar Delaunay (closed symbols with variance) and 'cross-triangle quadrilateral' meshes (open symbols) for the case $C_N = C_T$: as antecedently expected in the previous section, Figure 6 and Figure 7 show that relations (36) are rigorous lower bounds for *isotropic* meshes (Delaunay) and convenient estimates for *regular* meshes. Note that these regular meshes exhibit a higher added compliance than isotropic ones. Moreover, these numerical results clearly show that the criteria (37), $\xi_k \geq 20$ and $\xi_\mu \geq 20$, ensure that the overall added compliance

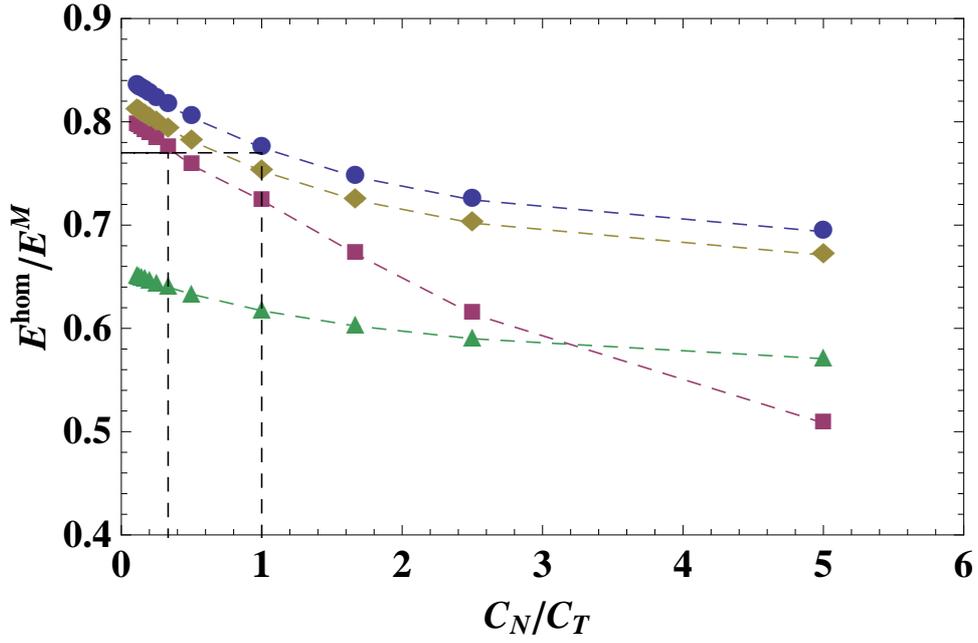


Figure 5: Effect of the tangential-to-normal cohesive stiffness ratio on the overall behaviour: Young apparent reduction vs the ratio C_N/C_T using a square regular mesh ($L_{\text{mesh}} = 0.05\text{mm}$). $\nu^M = 0.3$ (circular symbols), $\nu^M = 0.14$ (diamond symbol), $\nu^M = 0$ (square symbols) and $\nu^M = -0.7$ (triangular symbols).

do not exceed 5% (dashed lines in Figure 6 and Figure 7).

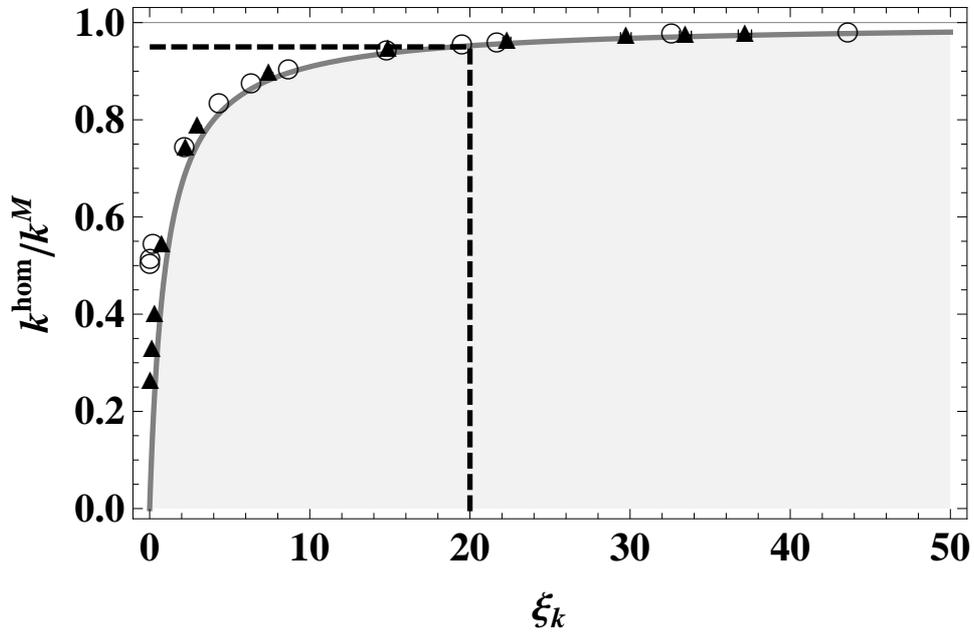


Figure 6: Normalized overall bulk modulus of a cohesive-volumetric formulation with intrinsic CZMs (case $C_N = C_T$): lower bounds (36) (thick gray line), criteria (37) (dashed line), numerical results for Delaunay meshes (closed symbols with variance) and for cross-triangle quadrilateral meshes (open symbols).

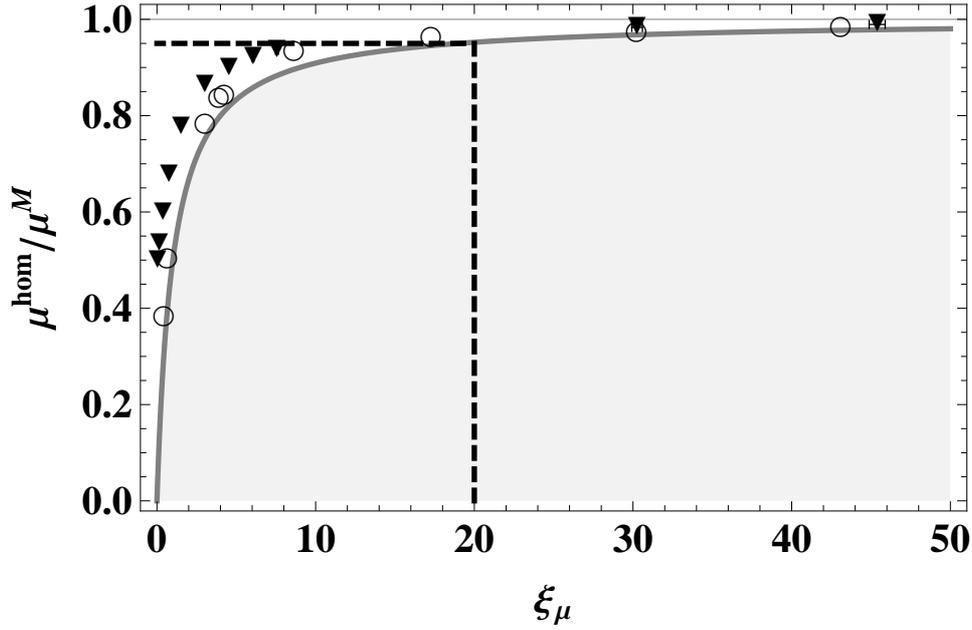


Figure 7: Normalized overall shear modulus of a cohesive-volumetric formulation with intrinsic CZMs (case $C_N = C_T$): lower bounds (36) (thick gray line), criteria (37) (dashed line), numerical results for Delaunay meshes (closed symbols with variance) and for cross-triangle quadrilateral meshes (open symbols).

4 Practical criteria on cohesive stiffnesses

Criteria on cohesive stiffnesses obtained from micromechanical models have been firstly discussed by [Acary and Monerie \(2006\)](#). Hereafter, use will be made of engineer's moduli (Young moduli and Poisson ratio):

$$\begin{aligned} E^M &= \frac{9k^M\mu^M}{3k^M + \mu^M} \quad \text{and} \quad \nu^M = \frac{3k^M - 2\mu^M}{6k^M + 2\mu^M}, \\ E^{\text{hom}} &= \frac{9k^{\text{hom}}\mu^{\text{hom}}}{3k^{\text{hom}} + \mu^{\text{hom}}} \quad \text{and} \quad \nu^{\text{hom}} = \frac{3k^{\text{hom}} - 2\mu^{\text{hom}}}{6k^{\text{hom}} + 2\mu^{\text{hom}}}. \end{aligned} \quad (38)$$

The additional compliance due to the presence of intrinsic CZMs is measured by two relative apparent reductions $R = E^{\text{hom}}/E^M$ and $r = \nu^{\text{hom}}/\nu^M$, so that cohesive zones do not affect the overall behaviour if, ideally, $R = 1$ and $r = 1$. Combining (36) and (38) gives for the proposed micromechanical model:

$$R = \frac{E^{\text{hom}}}{E^M} = \frac{\xi_E}{1 + \xi_E} \quad \text{where} \quad \xi_E = \frac{5}{1 + (4/3)(C_N/C_T)} \times \frac{C_N}{E^M Z}, \quad (39)$$

and

$$r = \frac{\nu^{\text{hom}}}{\nu^M} = \frac{15C_N\nu^M + (-1 + 2C_N/C_T)E^M Z}{15C_N\nu^M + (3 + 4C_N/C_T)E^M Z\nu^M}. \quad (40)$$

The equation (39) extends the 1D-equation (3) with a prefactor on ξ and the use of the density Z instead of the mesh size L_{mesh} . This equation shows again that without tangential cohesive stiffness ($C_T \rightarrow 0$) an overall no tension material is expected ($E^{\text{hom}} \rightarrow 0$). Moreover, the situation $R = 1$ can not be reached (the overall Young's modulus is always disturbed by the presence of CZMs using a Hashin Shtrikman estimate). However, for a given value of $R \in [0, 1[$, equation (39) leads to an implicit lower bound on the key parameter $C_N/(E^M Z)$ involving the normal-to-tangential cohesive stiffness ratio C_N/C_T :

$$\frac{C_N}{E^M Z} \geq \frac{1}{5} \frac{R}{1 - R} \left(1 + \frac{4}{3} \frac{C_N}{C_T} \right). \quad (41)$$

Fortunately, reduction $r = 1$, i.e. $\nu^{\text{hom}} = \nu^{\text{M}}$, can be reached in (40) fixing the ratio $C_{\text{N}}/C_{\text{T}}$ and thus defining 'invisible' intrinsic CZMs for the Poisson ratio:

$$\nu^{\text{hom}} = \nu^{\text{M}} \Rightarrow \frac{C_{\text{N}}}{C_{\text{T}}} = \frac{1}{2} \frac{1 + 3\nu^{\text{M}}}{1 - 2\nu^{\text{M}}}. \quad (42)$$

It is worth noting that the condition (42) ensures same elastic reduction for bulk, shear and Young moduli:

$$\frac{k^{\text{hom}}}{k^{\text{M}}} = \frac{\mu^{\text{hom}}}{\mu^{\text{M}}} = \frac{E^{\text{hom}}}{E^{\text{M}}}. \quad (43)$$

We underline that relationships (43) were proposed by [Li and Wang \(2004\)](#) as a closure condition in their self-consistent estimate for pure hydrostatic loadings. The present approach can thus be seen as an improvement of the results of [Li and Wang \(2004\)](#) to arbitrary type of loadings.

As before mentioned, the cohesive interface density Z corresponds to the 'specific' interface surface: $Z = \mathcal{A}/\mathcal{S}$ where \mathcal{A} is the total edge length (resp. area) in 2-D (resp. in 3-D) and \mathcal{S} is the total area (resp. volume) of the 2-D (resp. 3-D) meshed body. For any discretization characterized by a mesh size L_{mesh} , \mathcal{A} is proportional to L_{mesh}^{q-1} of the mesh and \mathcal{S} is proportional to L_{mesh}^q where q is the considered dimension; density Z is thus inversely proportional to the mesh size and can be expressed as:

$$Z = \frac{\gamma}{L_{\text{mesh}}}, \quad (44)$$

where the real γ depends on the spatial distribution of the considered mesh. Hence, relations (41), (42) and (44) allow to define a practical criterion on the ratio $C_{\text{N}}L_{\text{mesh}}/E^{\text{M}}$ extending semi-empirical criteria previously proposed in the literature ([Espinosa and Zavattieri, 2003](#); [Tomar et al., 2004](#); [Turon et al., 2007](#)):

$$\frac{C_{\text{N}}L_{\text{mesh}}}{E^{\text{M}}} \geq \gamma \frac{R}{1-R} \frac{1}{3(1-2\nu^{\text{M}})}. \quad (45)$$

Moreover, the intermediate criteria (41) and (42) together with the apparent reductions $R < 1$ and $r = 1$ allow to ensure accurate estimates of the elastic wave speeds, in fact better than of the apparent compliance. The apparent dilatational and shear wave speeds are given by $c_d^{\text{hom}} = \sqrt{(\lambda^{\text{hom}} + 2\mu^{\text{hom}})/\rho^{\text{hom}}}$ and $c_s^{\text{hom}} = \sqrt{\mu^{\text{hom}}/\rho^{\text{hom}}}$ respectively, where λ^{hom} is the effective Lamé's coefficient and ρ^{hom} is the effective density of the cohesive-volumetric medium. Assuming that the finite element discretization does not affect the density $\rho^{\text{hom}} = \rho^{\text{M}}$ (ρ^{M} being the density of the matrix phase) and since the criterion (42) ensures that the reduction $r = 1$ is reached for the Poisson ratio, the apparent reductions of the elastic wave speeds read:

$$\frac{c_d^{\text{hom}}}{c_d^{\text{M}}} = \sqrt{\frac{\lambda^{\text{hom}} + 2\mu^{\text{hom}}}{\lambda^{\text{M}} + 2\mu^{\text{M}}}} = \sqrt{\frac{E^{\text{hom}}}{E^{\text{M}}}} = \sqrt{R}, \quad (46)$$

$$\frac{c_s^{\text{hom}}}{c_s^{\text{M}}} = \sqrt{\frac{\mu^{\text{hom}}}{\mu^{\text{M}}}} = \sqrt{\frac{E^{\text{hom}}}{E^{\text{M}}}} = \sqrt{R}. \quad (47)$$

Thus, tolerating for example a reduction of 5% for the Young's modulus, i.e. $R = 0.95$, leads to a reduction lower than 3% for the elastic wave speeds ($\sqrt{R} \simeq 0.97$).

The application of the previous criterion (45) to the case of planar meshes is studied hereafter where the influence of the discretization morphology is illustrated.

5 Application to planar meshes

5.1 Regular meshes

We consider the case of a '2-D cross-triangle quadrilateral' meshes: each element square is divided into four isosceles triangles as shown in Figure 3 (a). Note that for such case of mesh geometry, the property

of the orientational equi-probability of inclusions is not respected since the mesh is not really isotropic. The obtained criterion (36) should be thus understood as an estimate and not as a lower bound. The parameter γ is equal in that case to $\gamma = 2(1 + \sqrt{2}) = 4.83$ (see Appendix A), this result combined with the relation (42) and the inequality (45) provides a '2-D practical 5% criteria' ($R = 0.95$) for regular meshes:

$$\boxed{\frac{C_N L_{\text{mesh}}}{E^M} \geq \frac{30}{1 - 2\nu^M} \quad \text{and} \quad \frac{C_T}{C_N} = 2 \frac{1 - 2\nu^M}{1 + 3\nu^M}} \quad (48)$$

For a bulk material with $\nu^M = 0.2$, these criteria give $C_T = 0.75C_N$ and $C_N \geq 50E^M/L_{\text{mesh}}$, which corresponds to the numerical criterion proposed by Turon et al. (2007). Conversely, combining (42) and (45) shows that, for a bulk material with $\nu^M = 0.2$, the criterion proposed by Espinosa and Zavattieri (2003), $\frac{C_N L_{\text{mesh}}}{E^M} \geq 10$, corresponds to a reduction $R = 0.78$, which guaranties only that the loss in apparent Young's modulus is less than about 22%.

5.2 Delaunay meshes

In Delaunay-type discretizations (see Figure 3 (b)), the length of an edge has a probability density function depending on the density of the underlying node-point process (Stoyan et al., 1995; Muche, 1996). The parameter γ is thus a stochastical parameter given by a mean and a variance. For a chosen mesh generation, a node-point density is obtained and the variance of Z can be computed. The mean value of Z can be estimated using statistical results of Muche (1996) and introducing a reference edge length (corresponding to an equivalent equilateral triangle):

$$Z = \frac{\gamma}{L_{\text{mesh}}} \quad \text{where} \quad \gamma = 2.97 \quad (49)$$

This result combined with the relation (42) and the inequality (45) provides a '2-D practical 5% criteria' ($R = 0.95$) for Delaunay meshes:

$$\boxed{\frac{C_N L_{\text{mesh}}}{E^M} \geq \frac{19}{1 - 2\nu^M} \quad \text{and} \quad \frac{C_T}{C_N} = 2 \frac{1 - 2\nu^M}{1 + 3\nu^M}} \quad (50)$$

The result obtained by application of the criteria (48) and (50) is plotted in Figure 8 where the elastic energy of a medium containing embedded CZMs is compared to the elastic energy of a medium without CZMs (standard finite element method). The obtained results show that both regular and Delaunay meshes induce a global loss of elastic energy that does not exceed 5% when the cohesive stiffnesses are suitably calibrated following (48) and (50). When the density Z is fixed at the same value, the difference between the two types of meshes is not significant as shown in Figure 8. This result validates the fact that the overall behaviour obtained with the Hashin-Shtrikman scheme (36) is a convenient estimate even if the property of isotropic meshes is not respected.

6 Concluding remarks

The overall constitutive behaviour of an elastic medium with embedded cohesive inclusions has been studied. An equivalent 'matrix-inclusions' composite is considered as a representation of a cohesive-volumetric finite element modelling. As result of this micromechanical model, the following points can be highlighted:

- Rigorous lower bounds on the normal, C_N , and the tangential, C_T , cohesive stiffness have been obtained for isotropic planar meshes as well as convenient criteria for regular meshes. The practical criteria are given as function of bulk material properties (E^M, ν^M) for a given mesh density Z (mesh size L_{mesh} and mesh morphology parameter γ).

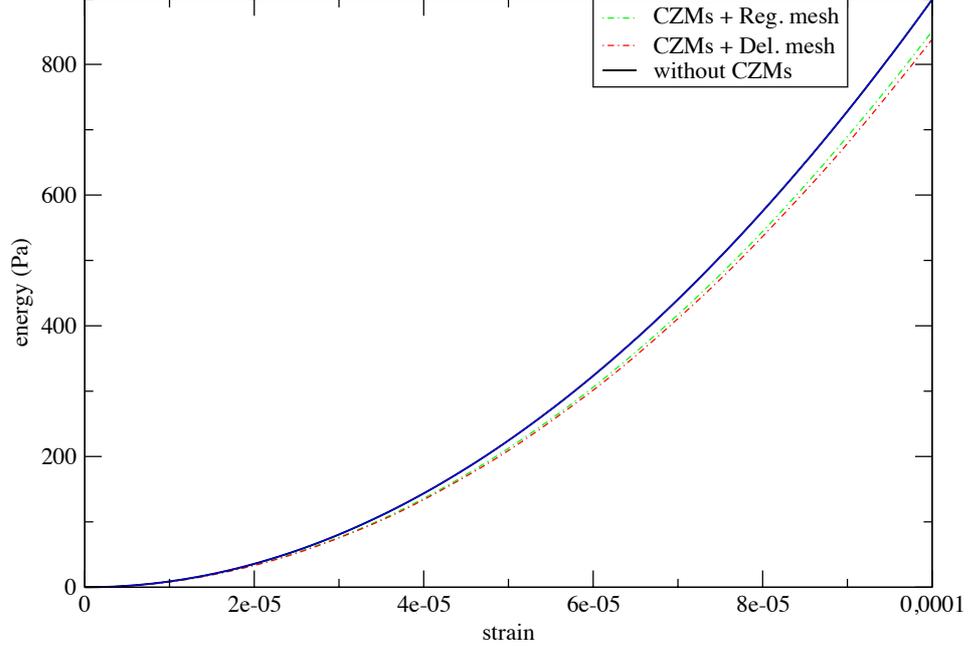


Figure 8: Overall elastic energy (area under the stress-strain curve) of a square cell during a shear test: standard finite element modeling without CZMs (continuous line), cohesive-volumetric finite element modeling using a Delaunay mesh (lower dot-dashed curve) or using a Regular mesh (upper dot-dashed curve).

- Intermediate results of this study show that a cohesive-volumetric approach with a vanishing tangential cohesive stiffness ($C_T \rightarrow 0$) leads to an overall no shear material.
- The accuracy of these results has been numerically tested for both Delaunay and regular meshes. The numerical part shows a consistence between numerical results and analytical analysis.

Acknowledgements

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A Expression of the cohesive density for the case of 2-D regular meshes

We consider a square cell meshed with regular squares divided into four isosceles triangles. We denote by N_t the number of the triangular elements, L_{mesh} the length of the larger side of each triangle and L_{tot} the total length of the boundaries between the underlying meshes (total length of the cohesive interfaces). Associating to the cohesive zones a fictitious thickness e , the volume fraction $f = eZ$ of cohesive interfaces reads:

$$f = \frac{eL_{\text{tot}}}{eL_{\text{tot}} + N_t(L_{\text{mesh}}^2/4)}, \quad (51)$$

hence, the expression of the density parameter Z is asymptotically obtained ($e \rightarrow 0$):

$$Z = \frac{L_{\text{tot}}}{N_t(L_{\text{mesh}}^2/4)}. \quad (52)$$

The total cohesive length L_{tot} is linked to the mesh length L_{mesh} and the triangles number N_t by the relationship:

$$L_{\text{tot}} = 2 \left(\sqrt{2} + 1 \right) \frac{N_t}{4} L_{\text{mesh}} + \sqrt{N_t} L_{\text{mesh}}, \quad (53)$$

which allows deriving an approximation of Z for large number of mesh elements ($N_t \rightarrow \infty$):

$$Z = \frac{\gamma}{L_{\text{mesh}}} \quad \text{with} \quad \gamma = 2 \left(1 + \sqrt{2}\right). \quad (54)$$

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