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Subproblem *h*-Conform Magnetodynamic Finite Element Formulation for Accurate Model of Multiply Connected Thin Regions

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Abstract — A subproblem *h*-conform eddy current finite element method is proposed for correcting the inaccuracies inherent to thin shell models. Such models replace thin volume regions by surfaces but neglect border effects in the vicinity of their edges and corners. The developed surface-to-volume correction problem is defined as a step of the multiple subproblems applied to a complete problem, consisting of inductors and magnetic or conducting regions, some of these being thin regions. The general case of multiply connected thin regions is considered.

I. INTRODUCTION

Thin shell (TS) finite element (FE) models [1], [2] [3], assume that the fields in the thin regions are approximated by a *priori* 1-D analytical distributions along the shell thickness. In the frame of the FE method, their interior is thus not meshed and is rather extracted from the studied domain, being reduced to a zero-thickness double layer with interface conditions (ICs) linked to the inner analytical distributions. This means that corner and edge effects are neglected.

To overcome these drawbacks, the subproblem method (SPM) for the h-conform FE formulation has been already developed by authors [5] for simply connected TS regions, proposing a surface-to-volume local correction. The method is herein extended to multiply connected TS regions, i.e. regions with holes, for both the associated surface model (alternative to the method in [3]) and its volume correction. The global currents flowing around the holes and their associated voltages are naturally coupled to the local quatities, via some cuts for magnetic scalar potential discontinuities at both TS and correction steps.

A reduced model (SP q) with the inductors alone is first considered before adding the TS (SP p), followed by the volumic correction SP (SP k). From SP q to SP p, the solution q contributes to the surface sources (SSs) for the added TS, with TS ICs. From SP p to SP k, SSs and volume sources (VSs) allow to suppress the TS and cut discontinuities and simultaneously add the actual volume of the thin region. Each SP requires a proper adapted mesh of its regions. The method is illustrated and validated on a practical problem.

II. FROM THIN SHELL TO VOLUME MODEL

A. h-formulation with source and reaction magnetic fields

The magnetic field h_i at step *i* of the SPM, is defined in a domain Ω_i , with boundary $\partial \Omega_i = \Gamma_i = \Gamma_{h,i} \cup \Gamma_{b,i}$, as

$$h_i = h_{s,i} + h_{r,i} - \operatorname{grad} \phi_i$$
, curl $h_{s,i} = j_{s,i}$, (1a-b)

where $h_{s,i}$ is a source magnetic field due to the fixed current density $j_{s,i}$, $h_{r,i}$ is the reaction field in conducting regions $\Omega_{c,i}$ and ϕ_i is the reaction magnetic scalar potential in non-conducting regions $\Omega_{c,i}^c$. Potential ϕ_i in $\Omega_{c,i}^c$ is multivalued (Fig. 1) and made singlevalued via the definition of cuts through each hole of $\Omega_{c,i}$ [6]. The h_i - ϕ_i magnetodynamic formulation of the SPs i = q, p and k is obtained from the weak form of Faraday's equation [5], i.e.,

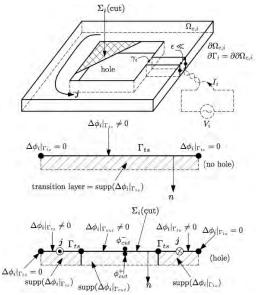


Fig. 1. 3D plate and its section without and with a hole, with the associated cut and transition layer for $\Delta\phi_i.$

$$\partial_t(\mu_i \boldsymbol{h}_i, \boldsymbol{h}'_i)_{\Omega_i} + (\sigma_i^{-1} \operatorname{curl} \boldsymbol{h}_i, \operatorname{curl} \boldsymbol{h}'_i)_{\Omega_{c,i}} + \langle [\boldsymbol{n} \times \boldsymbol{e}_i]_{\Gamma_i}, \boldsymbol{h}'_i \rangle_{\Gamma} \\ + (\sigma_i^{-1} \boldsymbol{j}_{s,i}, \operatorname{curl} \boldsymbol{h}'_i)_{\Omega_{s,i}} = 0, \ \forall \boldsymbol{h}'_i \in F_i^1(\Omega_i),$$
(2)

where μ_i is the magnetic permeability, σ_i is the conductivity and $F_i^1(\Omega_i)$ is a curl-conform function space (built with edge FEs at the discrete level) defined on Ω_i and containing the basis functions for h_i (coupled to ϕ_i) as well as for the test function h'_i . The notation $[\cdot]_{\gamma_i}=\cdot|_{\gamma_i^+}-\cdot|_{\gamma_i^-}$ refers to the discontinuity of a quantity through an interface γ_i (with sides γ_i^+ and γ_i^-) in Ω_i , defining ICs. The term $\langle [\mathbf{n} \times \mathbf{e}_i]_{\Gamma_i}, h'_i \rangle_{\Gamma_i}$ is used to weakly express the electric field TS IC proper to the TS model [2]. It can be extended to a global condition defining a voltage V_i [4], with $h'_i = \mathbf{c}_i = -\text{grad } q_i$ in $\Omega_{c,i}^C$ is fixed to 1 on one side of the associated cut and to 0 on the other side. One gets [4]

$$\langle \boldsymbol{n} \times \boldsymbol{e}_i, \boldsymbol{c}_i \rangle_{\partial \Omega_{c,i}} = \oint_{\partial \Gamma_i} q_i \boldsymbol{e}_i . dl = \int_{\gamma_i} \boldsymbol{e}_i . dl = V_i,$$
 (3)

B. Field Discontinuities for Multiply Connected TS Regions

A volume shell initially in $\Omega_{c,i}$ is extracted from Ω_i and then considered with the double layer TS surface $\Gamma_{ts,i}$ [2]. In addition to the electric field IC weakly defined in (2), the TS model requires a magnetic field discontinuity $[h_i]_{\Gamma_{ts,i}} = h_{d,i}$ strongly defined in $F_i^1(\Omega_i)$ via an IC on both sides of

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the TS via $\mathbf{h}_i|_{\Gamma_{ts,i}^+} = \mathbf{h}_{c,i}|_{\Gamma_{ts,i}} + \mathbf{h}_{d,i}|_{\Gamma_{ts,i}}$ and $\mathbf{h}_i|_{\Gamma_{ts,i}^-} = \mathbf{h}_{c,i}|_{\Gamma_{ts,i}}$ [2]. This can be also formulated via a discontinuity $[\phi_i]_{\Gamma_{ts,i}} = \Delta \phi_i|_{\Gamma_{ts,i}} = \phi_{d,i}|_{\Gamma_{ts,i}}$ (Fig. 1), with $\phi_i|_{\Gamma_{ts,i}^+} = \phi_{c,i}|_{\Gamma_{ts,i}} + \phi_{d,i}|_{\Gamma_{ts,i}}$ and $\phi_i|_{\Gamma_{ts,i}^-} = \phi_{c,i}|_{\Gamma_{ts,i}}$. The discontinuities $\phi_{d,i}$ of ϕ_i are constant on each cut and can be written as

$$[\phi_i]_{cut,i} = \phi_i|_{\Gamma^+_{cut,i}} - \phi_i|_{\Gamma^-_{cut,i}} = \phi_{d,i}|_{\Gamma_{cut,i}} = I_i, \quad (4)$$

where I_i is the global current flowing around the cut [4]. Discontinuities $\phi_{d,i}|_{\Gamma_{ts,i}}$ and $\phi_{d,i}|_{\Gamma_{cut,i}}$ have to be matched at the TS-cuts intersections.

C. Volume Correction

The obtained TS solution in SP p is then corrected by SP k solution that overcomes the TS assumptions [2]. The SPM provides the tools to implement such a model refinement, thanks to simultaneous SSs and VSs. A fine volume mesh of the shell is now required and is extended to its neighborhood without including the other regions of previous SPs. This allows to focus on the fineness of the mesh only in the shell. SSs related to ICs [2], [5] compensate the TS and cut discontinuities, i.e. $\phi_{d,p}|_{\Gamma_{ts,p}}$ and $\phi_{d,p}|_{\Gamma_{cut,p}}$, and $[n \times e_p]_{\Gamma_{ts,p}}$ to suppress the TS representation via SSs opposed to ICs, i.e. $h_{d,k} = -h_{d,p}$ and $\phi_{d,k} = -\phi_{d,p}$, and $[n \times e_k]_{\Gamma_{ts,k}} = -[n \times e_p]_{\Gamma_{ts,p}}$ in parallel to VSs [5] in the added volume shell that account for volume change of μ_p and σ_p in SP p to μ_k and σ_k in SP k (with $\mu_p = \mu_0$, $\mu_k = \mu_{r,plate}, \sigma_p = 0$ and $\sigma_k = \sigma_{plate}$).

III. APPLICATION

The 3D test problem is based on TEAM problem 7: an inductor placed above a thin plate with a hole (Fig. 2) $(\mu_{r,plate} = 1, \sigma_{plate} = 35.26 \text{ MS/m})$. A SP scheme considers the TS model followed by its volume correction.

Distributions of eddy current densities j_i on the TS SP pand volume correction SP k are shown in Fig. 2, with plate thickness d = 19 mm and frequency f = 200 Hz (skin depth $\delta = 6$ mm). The TS error on j_p locally reaches 43%. The inacuracy on the Joule power loss densities of TS SP p is pointed out by the importance of the correction SP k (Fig. 3). It reaches several tens of percents along the borders for some critical parameters: e.g., 53% (Fig. 3, *top*) or 61% (Fig. 3, *bottom*), for $\delta = 6$ mm in both cases. Significant errors on the Joule losses for TS SP p are shown in Table I. They increase with both the thickness of the plate and the frequency.

The SPM allows to accurately correct any TS solution. In particular, accurate correction of eddy current and power loss density are obtained at the edges and corners of multiply connected thin regions. Details on the efficiency of the proposed method and the simplification of SP meshes will be given in the extended paper.

TABLE I. JOULE LOSSES IN THE PLATE

Thickness d (mm)	Frequency f (Hz)	Thin Shell P _{thin} (W)	Volume P _{vol} (W)	Error (%)
2	50	14.45	13.82	4.36
19	50	5.86	7.95	26.18
2	200	50.44	47.33	6.44
19	200	8.88	15.19	41.51

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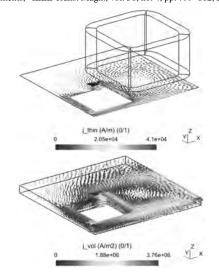


Fig. 2. TEAM problem 7; eddy current density on TS model (*top*) and volume correction (*bottom*) (d = 19 mm, f = 200 Hz).

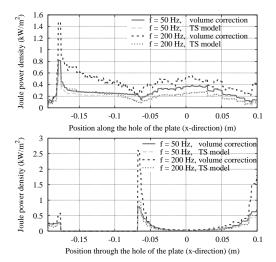


Fig. 3. Joule power loss density for TS model and volume correction along hole and plate border (top) and through the hole (d = 19 mm).

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