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1 Imaging the dynamics of magma propagation using
2 radiated seismic intensity

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3 At shallow depth beneath Earth's surface, magma propagates through strongly
4 heterogeneous volcanic material. Inversion of buoyancy and/or solidification
5 have strong impacts on the dynamics of propagation without any change of
6 magma supply. In this paper, we study the spatial and time evolution of magma
7 intrusions using induced seismicity. We propose a new method based on es-
8 timates of radiated seismic intensities recorded at different stations during
9 seismic swarms at Piton de la Fournaise volcano. By applying this method
10 to the January 2010 Piton de la Fournaise volcano eruption, we image com-
11 plex dike propagation dynamics which strongly differ from a model of con-
12 stant velocity dike propagation. We provide a new and fully automatic method
13 to image in real time the dynamics of dike propagation and to infer the po-
14 sition of eruptive fissures.

1. Introduction

15 Eruption precursory activity associated to volcanic unrest is currently recorded at many
16 volcanological observatories around the world and mainly consists of seismicity and ground
17 deformation monitoring. During magma propagation to the near-surface, the vicinity of
18 the associated dike or sill is subjected to a large stress field perturbation [*Rubin and*
19 *Gillard, 1998*], that will concentrate most of the induced seismicity (seismic swarms).
20 Monitoring these seismic swarms is thus a potentially powerful technique to track magma
21 movements but is not used to its full potential for several reasons. During seismic swarms,
22 seismic events are difficult to separate, so that one may not use the efficient localization
23 methods that have been devised for single earthquakes. Only those events that are well
24 identified can be treated with current methods and a large part of the seismic signal is left
25 unused. Consequently, the interpretation of the data in term of the dynamics of magma
26 migration is difficult. Previously, few examples of migration of seismicity associated with
27 magma movement have been imaged by geophysical means [*Aoki et al., 1999; Hayashi and*
28 *Morita, 2003; Battaglia et al., 2005*]. However, precise analysis of seismicity (localization,
29 magnitude) requires post-processing and is therefore difficult to perform in real time.

30 Here, we propose a simple but robust method to track magma movements using the
31 ratio at different seismic stations of the seismic intensities radiated by the surroundings of
32 the dike's tip. We apply this method to the January 2010 eruption of Piton de la Fournaise
33 volcano (La Réunion island). As a result, we observe a complex dike propagation dynamic
34 which strongly differs from a model of constant velocity dike propagation. We thus provide

35 a fully automatic and simple method to image in near-real time the dynamics of dike
 36 propagation and to infer the position of eruptive fissures.

2. Method

Traditionally, seismic events are located using P or S wave travel time delays measured at different receivers. This approach finds its limits when it becomes difficult to measure accurate arrival times such as for example, during seismic swarms or in cases of low signal to noise ratio micro-seismicity. Here, we propose a method to automatically estimate the position at depth of a seismic source by using the differences in seismic amplitudes recorded at difference sensors. This approach relies on the attenuation of seismic waves along the source-receiver travel path. In order to avoid the detection of single P or S wave arrivals, we use an estimate of the average recorded seismic intensity over a time window much longer than the seismic wave travel time delays at different sensors (see section 3 for details). Following *Battaglia and Aki* [2003], we use a simple attenuation law that takes into account geometrical and intrinsic but not scattering attenuation (equation 1).

$$I_i = A_o \frac{e^{-Br_i}}{r_i^n}, \quad (1)$$

with,

$$B = \frac{\pi f}{Q\beta}, \quad (2)$$

37 where I_i is the seismic intensity recorded at receiver i , r_i is the distance from the source,
 38 I_o is the source radiated seismic intensity, f is frequency, β is shear wave velocity and Q is
 39 the quality factor for attenuation. The index $n = 1$ for body waves and $n = 0.5$ for surface
 40 waves. For simplification we consider an isotropic medium with constant B . Because we

41 don't know which type of wave (body or surface) dominates the intensity estimates, we
 42 make no approximation about the value of n . In the next section we will investigate the
 43 effect of n and Q .

To avoid the estimate of the seismic intensity at the source (I_o), we choose to analyse the ratios of seismic intensities between all sensors (equation 3) rather than the true seismic intensities at different sensors.

$$\frac{I_i}{I_j} \Big| ^t = \left(\frac{r_j^t}{r_i^t} \right)^n \exp \left[-B(r_i^t - r_j^t) \right] . \quad (3)$$

Assuming a migration such that $r_i^{t+\delta t} = r_i^t + \delta_i$ and $r_j^{t+\delta t} = r_j^t + \delta_j$, with δ_i and δ_j that can be defined either positively or negatively depending on the relative direction of the source to the station:

$$\frac{I_i}{I_j} \Big| ^{t+\delta t} = \left(\frac{r_j^t + \delta_j}{r_i^t + \delta_i} \right)^n \exp \left[-B(r_i^t + \delta_i - r_j^t - \delta_j) \right] , \quad (4)$$

by first order linearisation we obtain :

$$\frac{I_i}{I_j} \Big| ^{t+\delta t} = \frac{A_i}{A_j} \Big| ^t \left[1 + \delta_j \left(\frac{n}{r_j^t} + B \right) - \delta_i \left(\frac{n}{r_i^t} + B \right) \right] . \quad (5)$$

44 Equation 5 shows that only the migration of seismicity will affect the intensity ratio and
 45 not the change of radiated seismic intensity at the source which does not appear in the
 46 final equation. The only exception is if the motion occurs within the plane perpendicular
 47 to the middle of the line defined by the two stations. In this particular case the intensity
 48 ratio will remain unchanged. For the present purpose, and using the fact that we use
 49 different stations, we will consider any temporal changes as a result of the migration of
 50 the seismic source and therefore to the migration of the magma.

3. Example of data processing

51 As an application of the proposed method, we focus on Piton de la Fournaise (PdF)
 52 volcano located on La Réunion island in the Indian ocean (Figure 1). It is a basaltic shield
 53 volcano which erupted more than 30 times between 2000 and 2010. Since 2009-2010, 15
 54 broad-band seismic stations have been installed on the volcano as part of the UnderVolc
 55 project, in addition to the existing seismic array. We analyse data from the 2010 January
 56 eruption. The selected eruption presents a seismic swarm that can be divided into two
 57 phases (figure 2 a and b). During the first phase, which lasted for about an hour, a high
 58 level of seismicity was recorded followed by a relatively quiet phase that directly precede
 59 the onset of the eruption (seismic tremor).

60 As a first stage of data processing we correct the signal from the sensor and acquisition
 61 sensitivity to retrieve accurate values of ground motion velocity. Seismic signal amplitudes
 62 have also been corrected from site effects using the coda amplification factor method
 63 [*Battaglia and Aki, 2003*].

64 Seismicity induced by magma migration presents a relatively high frequency content
 65 compared to the permanent back-ground noise. For this study we will only consider a
 66 frequency range between 5Hz and 15Hz.

67 We calculate the envelope of the signal, E , using the norm between the filtered data,
 68 x , and their Hilbert transform, H :

$$E = \sqrt{(H(x) - x)^2}. \quad (6)$$

69 To eliminate spikes or glitches we decimate the data by keeping the median of 1000 con-
 70 secutive points, corresponding to 10 seconds. This leads to the seismic intensity estimate,
 71 I , that we will use from now.

72 The last step of the analysis is a median filter applied on I using a sliding window of
 73 given duration Δt .

The nomenclature used is :

$$I_{Sta}^{\Delta t}, \quad (7)$$

74 with Sta corresponding to the name of the station. Figure 2 c and d represents the results
 75 of this data processing for $\Delta t = 5min$.

76 To highlight relative changes of intensity between different stations we plot the ratio
 77 $I_{Sta_1}^{\Delta t} / I_{Sta_2}^{\Delta t}$ (one example is shown figure 2 e).

4. Results

78 Ratios for different pairs of stations are shown figure 3 a. It is important to note that
 79 since this method relies on the seismo-acoustic emissions from the dike's tip, we only
 80 show results corresponding to periods when signal intensities $I_{Sta}^{\Delta t}$ are at least twice the
 81 background seismic noise intensity level.

82 We also compare observations of intensity ratios to synthetic intensity ratios at station
 83 UV05 and FLR (figure 3 b and c) using a theoretical vertical pathway beneath the eruptive
 84 vent and a constant propagation velocity from sea level (0 meters a.s.l at 07:54 AM) to
 85 the surface (2500 m at 10:25 AM). The intensity ratios are calculated using equation 3
 86 for different value for the quality factor (Q) and both volumetric and surface attenuation
 87 (respectively $n = 1$ and $n = 0.5$). An interesting point is the behaviour of the theoretical

88 curve that presents an apparent acceleration since the migration is set to be at constant
89 speed.

90 Interestingly the beginning of the seismic swarm (07:54 to 09:00 AM) shows a high level
91 of seismicity with intensity ratios close to unity and with no significant variations which
92 can be interpreted as a slow migration of the magma. In the later part of the seismic
93 swarm (09:00 AM to 10:25 AM) seismic activity strongly decreases and intensity ratios
94 show strong variations. This can be interpreted as a fast migration of the magma in the
95 shallow part of the edifice. This migration presents some heterogeneity with a phase of
96 arrest around 10:00 AM.

97 Simple modelling does not explain the temporal change of the intensity ratio and shows
98 that simple migration is not likely to occur in natural systems. Nevertheless, the intensity
99 ratio during the tremor can be explained using $n = 1$ and $Q \sim 200$, which does not seem
100 a reasonable value for the quality factor, or using $n = 0.5$ and $Q \sim 50$, which implies
101 that the computed seismic intensities are dominated by surface waves. This Q value is in
102 agreement with previous studies [*Battaglia and Aki, 2003; Battaglia et al., 2005*].

103 Regarding the ratio presented figure 3 a, the change at 10:09 AM could be due to
104 a change in the direction of the propagation from vertical to horizontal toward station
105 UV05. This highlights the need to develop an inverse problem to extract the position of
106 the propagating front from all the possible intensity ratios.

5. Inverse problem

107 In order to image magma propagation at depth, we seek the best position within a grid
108 that best explains the intensity ratios from all possible pairs of stations. We process a

109 simple inverse problem in which we compute all the theoretical intensity ratios on each
 110 point of the grid defined as follows: Easting from 362 km to 370 km every 100m, Northing
 111 from 7647 km to 7653 km every 100 m and depth from -0.5 km to 2.5 km above sea level
 112 every 50 m. The limitation in depth comes from the localisation of individual events at
 113 the beginning of the seismic swarm. Parameters used for the attenuation law are $n = 0.5$
 114 and $Q = 50$.

115 The 3-dimensional misfit used is the following :

$$\chi = \sqrt{\sum_i \sum_{j>i} \left(\frac{I_{\text{Sta}_i}^{\Delta t} \Big|_{\text{calculated}}}{I_{\text{Sta}_j}^{\Delta t}} - \frac{I_{\text{Sta}_i}^{\Delta t} \Big|_{\text{measured}}}{I_{\text{Sta}_j}^{\Delta t}} \right)^2}. \quad (8)$$

116 The results are shown figure 4. During the period of high seismic activity, locations
 117 are saturated at sea level which is consistent with commonly observed seismicity on PdF
 118 volcano and the location of single events at the beginning of seismic swarms. As already
 119 observed in figure 3, the inversion results show a phase of arrest around 10:00 AM.

6. Discussions and Conclusions

120 The proposed analysis will find a limitation when the source of the seismicity is far
 121 from all the stations. In that case, the relative difference in the source-receiver paths are
 122 negligible and all the possible intensity ratios will be close to one. This also implies, for
 123 future inversion of the migration using intensity ratios, that the error on the position will
 124 be a function of the position itself: the greater the source-receiver distance, the greater
 125 the error will be.

126 In term of the dynamics of magma propagation, the results clearly show that the upward
127 migration started between 9:00 AM and 9:30 AM. Combining intensity ratios (figure 3)
128 and the results of the inversion (figure 4) we can infer that the migration initiates at 9:00
129 AM with clear migration toward the surface at 9:25 AM which corresponds to about one
130 hour after the beginning of the seismic swarm. At smaller scale the upward propagation
131 does not occur at constant velocity but presents phases of rapid propagation and phases
132 of arrest or with a strong decrease of velocity.

133 This simple analysis can be easily applied to the real time monitoring of magma migra-
134 tion and gives an opportunity to extract information on the dynamics of magma propa-
135 gation.

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145 ber XXXX.

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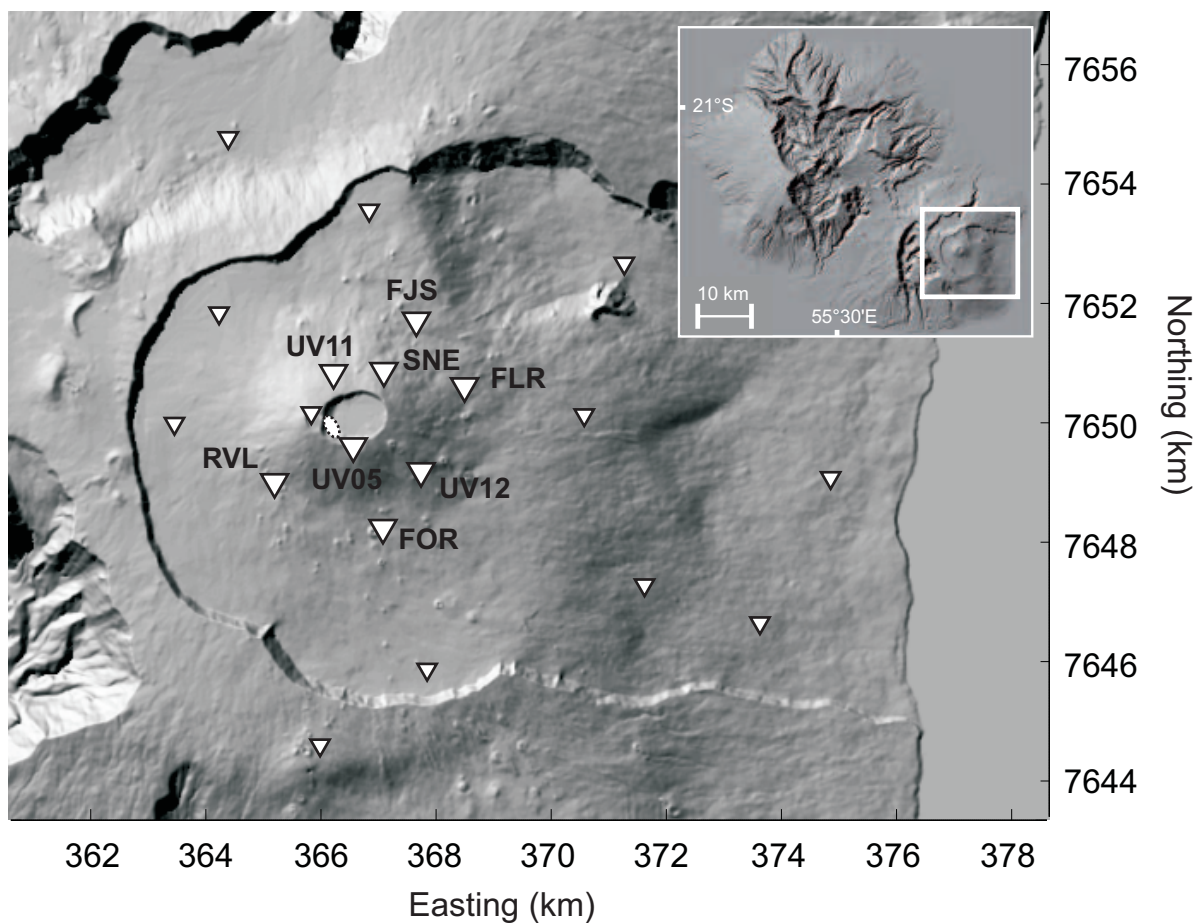


Figure 1. Location of Piton de la Fournaise volcano on La Réunion island (inset) and seismic station distribution (inverted triangles). Those used in this study are referred by their names on the map. The position of the January 2010 eruptive fissure is shown as a dashed circle.

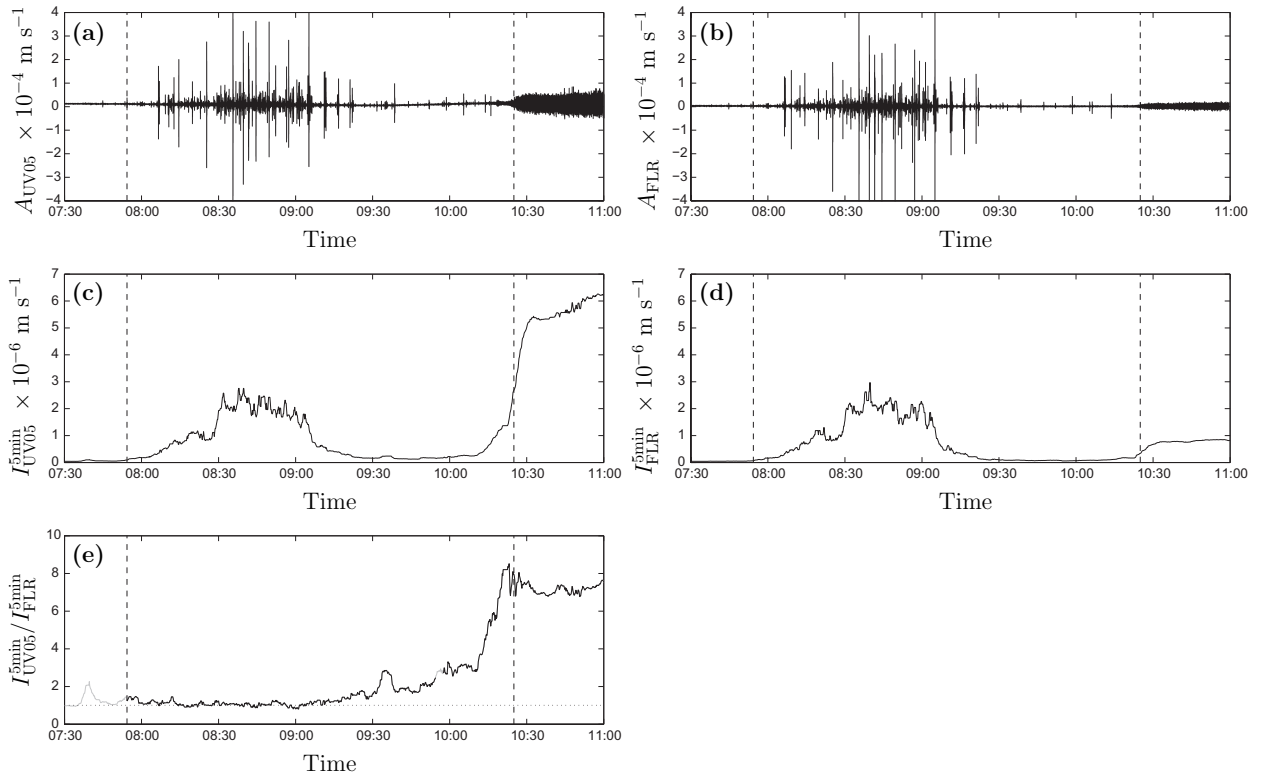


Figure 2. Example of data processing. **a** and **b** represent the raw ground velocity at stations UV05 and FLR respectively. **c** and **d** represent the seismic intensities, see section 3 for further details. **e** represents the ratio between I_{UV05}^{5min} and I_{FLR}^{5min} . Vertical dashed lines represent the beginning of the seismic swarm (07:54 AM) and the onset of the eruption (10:25 AM).

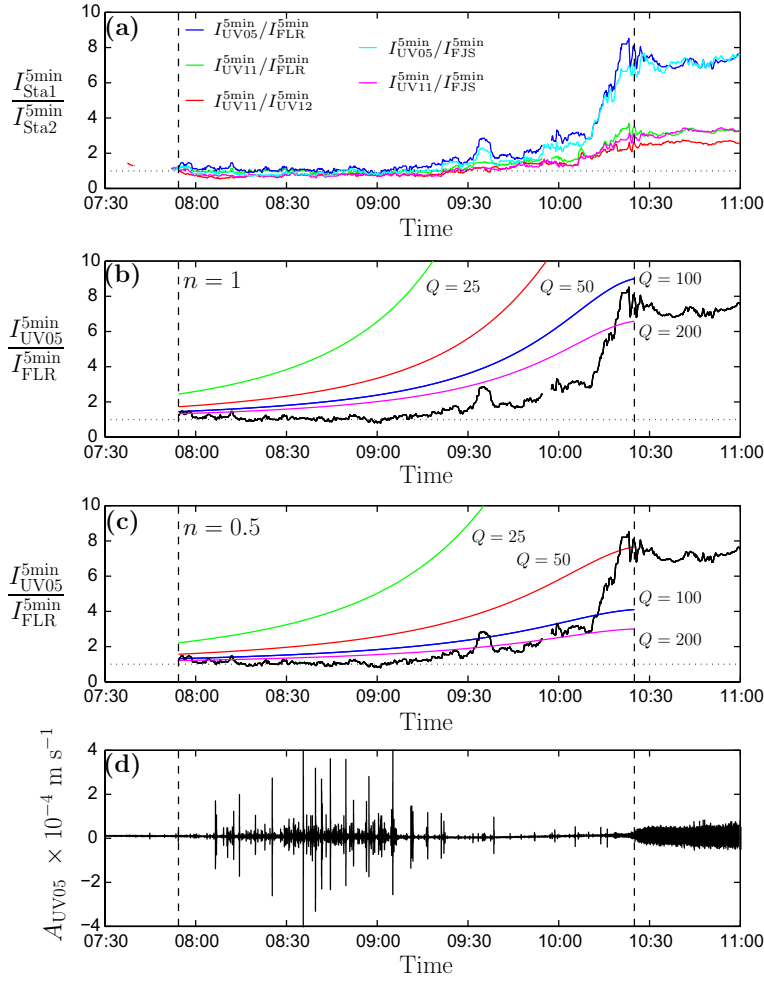


Figure 3. a, Seismic intensity ratio for five different station pairs ($\Delta t = 5\text{min}$). Comparison of real and synthetic ratios for station pair UV05, FLR using different quality factors and considering body wave (b) or surface wave (c) attenuation (respectively, $n = 1$ and $n = 0.5$). The synthetic curves are calculated for a source migrating at constant vertical velocity from sea level at 07:54 AM to the vent at 10:25 AM. d represents the raw seismic signal at station UV05 for timing comparison. Vertical dashed lines represent the beginning of the seismic swarm (07:54 AM) and the onset of the eruption (10:25 AM).

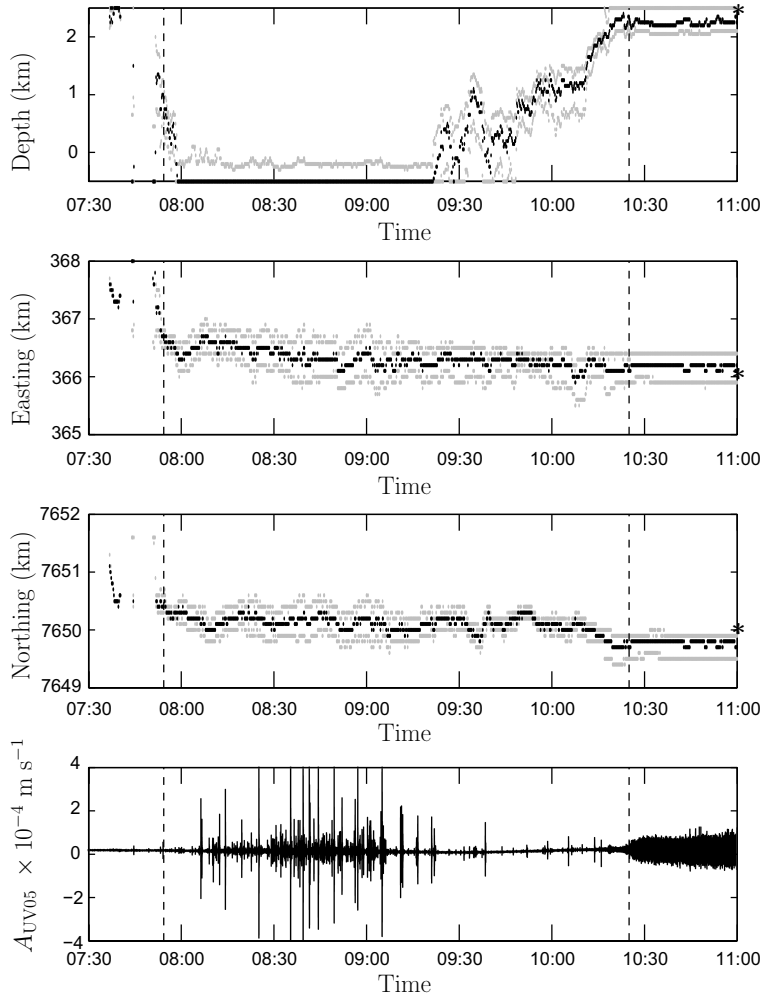


Figure 4. Inversion results. The top three panels show the results of the inversion in terms of depth (above sea level), Easting and Northing. For each component, the black curve represents the best position of the minimum misfit and both grey curve represent the minimum and maximum extension of a volume including misfit values inferior to 10% of the minimum misfit. The bottom panel represents the seismic signal at station UV05 for timing comparison. Vertical dashed lines represent the beginning of the seismic swarm (07:54 AM) and the onset of the eruption (10:25 AM). The black stars show the location of the eruptive fissure.