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Computation of open Gromov-Witten invariants for toric Calabi-Yau 3-folds by topological recursion, a proof of the BKMP conjecture

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Abstract

The BKMP conjecture (2006-2008), proposed a new method to compute closed and open Gromov-Witten invariants for every toric Calabi-Yau 3-folds, through a topological recursion based on mirror symmetry. So far, this conjecture had been verified to low genus for several toric CY3folds, and proved to all genus only for \mathbb{C}^3 .

In this article we prove the general case. Our proof is based on the fact that both sides of the conjecture can be naturally written in terms of combinatorial sums of weighted graphs: on the A-model side this is the localization formula, and on the B-model side the graphs encode the recursive algorithm of the topological recursion.

One can slightly reorganize the set of graphs obtained in the B-side, so that it coincides with the one obtained by localization in the A-model. Then it suffices to compare the weights of vertices and edges of graphs on each side, which is done in 2 steps: the weights coincide in the large radius limit, due to the fact that the toric graph is the tropical limit of the mirror curve. Then the derivatives with respect to Kähler radius coincide due to special geometry property implied by the topological recursion.

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1 Introduction

Topological string theory has raised a lot of interest, because it is a limit of string theory which is mathematically well defined and where computations can be entirely performed. Topological A-model string theory is mathematically formulated as Gromov–Witten theory.

For applications in physics, one is often concerned by topological string theories in target spaces which are Calabi–Yau 3-folds. Not so many examples of Calabi–Yau spaces are known explicitly, but there is a family which is particularly well understood, this is the family of "toric" Calabi–Yau 3-folds. These are particularly well studied thanks to their toric symmetry, which allows to go even deeper in the computations.

There are mainly two types of topological string theories: A-model and B-model, and it was conjectured (and proved in some cases) that the A-model and B-model are dual to each other, through **mirror symmetry** which exchanges the complex and Kähler structures of the target spaces. For both A and B theories, the "string amplitudes" enumerate in some appropriate way, maps from a Riemann surface of given topology, into the target space (the Calabi–Yau 3-fold \mathfrak{X} or its mirror $\hat{\mathfrak{X}}$). The string amplitudes for the A-model are called "Gromov–Witten" invariants and are well defined and extensively studied mathematical objects.

So, string amplitudes depend on a target space and on the topology (genus and possibly number of boundaries) of a Riemann surface. Closed amplitudes $F_g(\mathfrak{X})$ enumerate surfaces without boundaries, they depend only on a genus g . They are encoded into generating functions by making formal series:

$$F(\mathfrak{X}, g_s) = \sum_{g=\text{genus}} g_s^{2g-2} F_g(\mathfrak{X})$$

where \mathfrak{X} is our target space (the toric CY 3-folds) and where the formal parameter g_s is traditionally called the "string coupling constant". The goal is eventually to compute $F_g = F_g(\mathfrak{X})$, i.e. amplitudes corresponding to enumeration of Riemann surfaces of given genus. For example $F_0(\mathfrak{X})$ computes planar amplitudes, i.e. rational maps from \mathbb{P}^1 into \mathfrak{X} .

Topological vertex. In principle, topological string amplitudes for toric CY 3-folds are entirely known, through the "topological vertex" method [2, 36, 44, 42, 43]. In that method, one introduces

$$q = e^{-g_s}$$

and string amplitudes are given in terms of a series in powers of q :

$$Z = e^{F(g_s)} = e^{\sum_g g_s^{2g-2} F_g} = \sum_k q^k C_k$$

where the coefficients C_k are of combinatoric nature (typically they enumerate 2d or 3d partitions, this is often called a "crystal model"), they are known rather explicitly, or at least they are given by explicit combinatoric sums over partitions.

The problem is to extract from this q -series, which is defined as an expansion near $q = 0$, the asymptotic behavior and expansion near $q = 1$ in powers of $g_s = -\ln q$. Indeed, the coefficients of this expansion are the ones of physical interest for precision computations in high energy physics. Even computing the leading order i.e. F_0 , requires an infinite combinatoric sum, and is not straightforward, and going beyond leading order directly from the combinatoric sum is a very difficult challenge.

Methods for computing Gromov–Witten invariants of fixed genus. Many methods have been introduced to compute directly the g_s expansion, most of them are based on solving a differential equation:

- one is the famous "**holomorphic anomaly equations**" [5, 1]. It is based on the observation that topological string amplitudes should be "modular" invariant. This implies a relationship between their holomorphic and anti-holomorphic parts with respect to the parameters of the target space, which can be translated into a set of EDP satisfied by the string amplitudes. A drawback of the method is that one can compute the amplitudes only up to an unknown holomorphic function, which can be fixed by knowing the answer in some limiting cases. When applicable, the holomorphic anomaly equation method is extremely efficient for actual computations of Gromov-Witten invariants.

- Another is **Givental's** method [26, 25]. This method translates some geometric relations (like gluing surfaces) into a set of EDP. Those EDP can be formally solved, and the solution can be written as a linear operator acting on a product of Kontsevich integrals (depending on an infinite number of times), i.e. one has to compute derivatives of Kontsevich integrals and at the end set the times to some special values. This method shows that the generating function of Gromov-Witten invariants is a Tau-function for some integrable hierarchy.

In both methods one has to find the Gromov-Witten invariants of a whole family of Calabi-Yau 3-folds, one can't find the invariants of one manifold directly.

The remodeling method

- In 2006 [40] M. Mariño suggested a new method, and then with Bouchard, Klemm and Pasquetti further formalized the statement under the name "**remodeling the B–**

model” in 2008 [9]. That method is based on the ”topological recursion” of [13, 18] and on mirror symmetry (this will be described in more details in section 4 below). This method proposes to compute the amplitudes by recursion on the Euler characteristics, without having to solve a differential equation, and in particular allows to compute the amplitudes of one given manifold without having to study a family of manifolds. Also, they give a recipe to compute ”open Gromov-Witten invariants”, as well as invariants for orbifold geometries, which were not known before. This claim of [9] is often called the **”BKMP conjecture”**, and can be seen as an explicit example of mirror symmetry to all genus. We write it explicitly as conjecture 4.1 in section 4.3.

The authors of [9] and many others afterwards checked this conjecture for many examples of target space manifolds, and for low genus Gromov–Witten invariants, but the statement was so far proved to all genus only for the simplest toric Calabi–Yau 3-fold, namely $\mathfrak{X} = \mathbb{C}^3$ [11, 53].

It was also noticed that the topological recursion implies the holomorphic anomaly equations [19] as well as some properties very similar to Givental’s formalism [48], but the converse has not been proved.

In [53], the proof for $\mathfrak{X} = \mathbb{C}^3$ was mostly combinatorial, and used the ”cut and join” equations of Goulden–Jackson [27]. Unfortunately the tools involved in the combinatorics were very specific to the \mathbb{C}^3 geometry, and not easy to generalize, and has prevented the authors of [11, 53] to extend their proof to other toric Calabi-Yau spaces.

The goal of the present article is to present a **general proof** for every toric Calabi-Yau 3-fold, mostly combinatorial although not based on cut and join, but more based on special properties of the topological recursion as well as localization.

Sketch of the proof:

- on the A-model side, it is known [36, 12] how to write the Gromov-Witten invariants through a **localization** formula, as a combinatorial sum over **graphs**, with weights associated to edges and vertices. Vertices are labeled by a ”genus” and valency (g, n) . Weights of vertices are Gromov-Witten invariants of \mathbb{C}^3 (i.e. the topological vertex) and are given by the Mariño–Vafa formula, i.e. they are triple Hodge integrals in $\overline{\mathcal{M}}_{g,n}$.

- on the B-model side, the topological recursion can be naturally written as a combinatorial sum over **graphs**, with weights associated to edges and vertices (but not the same graphs and weights as the A-model side). Vertices are also labeled by a genus and valency (g, n) . Weights of vertices are combinations of residues of meromorphic forms computed at the branchpoint of the mirror curve.

- contrarily to the A-model side, the graphs of the B-model side have no $(0, 1)$ or $(0, 2)$ vertices (genus zero, valency 1 or 2). There is a standard graph combinatorial

toolkit which allows to relate sums of graphs with or without vertices of valency 1 or 2. In other words we can add $(0, 1)$ and $(0, 2)$ vertices to the B-model sum of graphs, at the price of changing ("renormalizing") the weights of edges and vertices.

- after this graph manipulation, so that we have the same graphs on both sides, it remains to check whether the weights of edges and vertices in the A-model and in the B-model coincide. This is done in two steps:

- In the large radius limit, where all Kähler parameters are large $t_j \rightarrow +\infty$, i.e. the **tropical limit**, the fact that the tropical limit of the spectral curve is the toric graph of the A-model side, implies that the weights coincide at all $t_j = \infty$.

- For finite Kähler radius t_j , thanks to the topological recursion, the weights of the B-model side satisfy the "**special geometry** property" (similar to Seiberg–Witten relations), i.e. a differential equation with $\partial/\partial t_j$, which allows to compute their derivatives with respect to t_j , and thus show that the weights of the A-model and B-model side, coincide for all t_j 's (large enough).

This concludes the proof of the BKMP conjecture.

This article is organised as follows:

- Section 2 is a reminder on Toric Calabi-Yau 3-folds geometry and mirror symmetry.
- Section 3 is devoted to the description of the A-model side reminding the topological vertex formalism through localization.
- In section 4, we present the BKMP conjecture and prove it by reorganising the graphs involved by the topological recursion into a set of graphs matching the ones rising for the localisation analysis of section 3.
- Section 5 is a conclusion.
- The first two appendices are reminder of the topological recursion formalism and its relation to intersection numbers. The other ones present some of the technical proofs of theorems requested for proving the BKMP conjecture.

2 Reminder: geometry of Toric Calabi–Yau 3-folds

The geometry of toric Calabi-Yau 3-folds is well known and described in many works and review articles [49, 8, 23, 36, 51], it is mostly combinatorial. The goal of this section is to give a brief description of the geometry and combinatorics of those spaces and introduce notations, which will be useful for the rest of the article. Since these are

classical results of toric geometry, we only provide sketches of proofs here and we refer the reader to the aforementioned literature for more details.

2.1 Construction of toric Calabi–Yau 3-folds

Every toric Calabi-Yau 3-fold \mathfrak{X} can be constructed as follows. Let r be a non negative integer, and let $\vec{q}_1, \dots, \vec{q}_r$ be independent integer vectors called charges $\vec{q}_i = (q_{i,1}, \dots, q_{i,r+3}) \in \mathbb{Z}^{r+3}$ for $i = 1, \dots, r$ such that

$$\forall i = 1, \dots, r \quad , \quad \sum_{j=1}^{r+3} q_{i,j} = 0. \quad (2.1)$$

In addition, these charges will be asked to fulfill additional conditions called "smoothness condition" which are described later in section 2.1.2.

Let t_1, \dots, t_r be r positive real numbers $t_i > 0$, called Kähler parameters, or radii and X_1, \dots, X_{r+3} be the canonical coordinates of \mathbb{C}^{r+3} . We write

$$X_i = |X_i| e^{i\theta_i}. \quad (2.2)$$

Definition 2.1 For charges $\{\vec{q}_i\}_{i=1}^r$, Kähler parameters $\{t_i\}_{i=1}^r$ and $\{X_i\}_{i=1}^{r+3}$ as above, one defines the 6-dimensional real manifold \mathfrak{X} as follows. \mathfrak{X} is the submanifold of \mathbb{C}^{r+3} defined by the r relations

$$\forall i = 1, \dots, r \quad , \quad \sum_{j=1}^{r+3} q_{i,j} |X_j|^2 = t_i, \quad (2.3)$$

and quotiented by the equivalence relations:

$$\forall i = 1, \dots, r, \forall \alpha \in \mathbb{R} \quad , \quad (\theta_1, \dots, \theta_{r+3}) \equiv (\theta_1, \dots, \theta_{r+3}) + \alpha (q_{i,1}, \dots, q_{i,r+3}). \quad (2.4)$$

Under a suitable choice of charges \vec{q}_i 's, \mathfrak{X} is a smooth 6 dimensional manifold. It turns out that \mathfrak{X} has a complex structure inherited from that of \mathbb{C}^{r+3} and it has the Calabi-Yau property which is equivalent to $\sum_{j=1}^{r+3} q_{i,j} = 0$. One can check that the following symplectic form:

$$\omega = \frac{1}{2} \sum_{i=1}^{r+3} d|X_i|^2 \wedge d\theta_i \quad (2.5)$$

is a well defined symplectic form on \mathfrak{X} (it is the reduction of the canonical symplectic form on \mathbb{C}^{r+3} , and it descends to the equivalence classes).

Let us consider 2 examples which we will develop in the following:

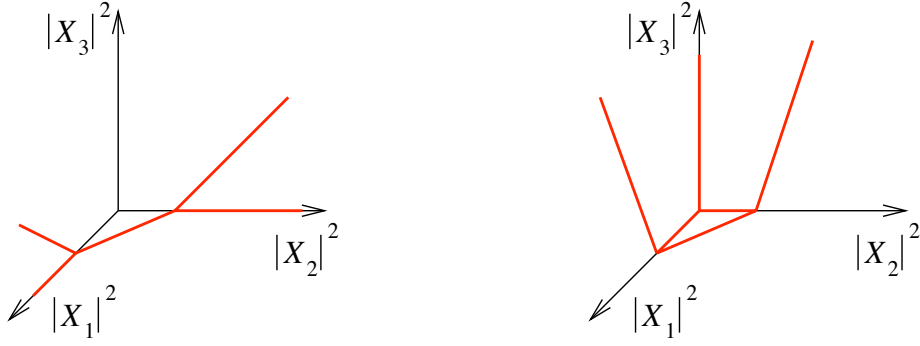


Figure 1: The polyhedra of the resolved connifold $q = (1, 1, -1, -1)$ and of local \mathbb{P}^2 $q = (1, 1, -3, 1)$.

- The resolved connifold is defined with $r = 1$ and $q = (1, 1, -1, -1)$, i.e.

$$|X_1|^2 + |X_2|^2 - |X_3|^2 - |X_4|^2 = t \quad , \quad (\theta_1, \theta_2, \theta_3, \theta_4) \equiv (\theta_1 + \alpha, \theta_2 + \alpha, \theta_3 - \alpha, \theta_4 - \alpha). \quad (2.6)$$

- The local \mathbb{P}^2 is defined with $r = 1$ and $q = (1, 1, -3, 1)$, i.e.

$$|X_1|^2 + |X_2|^2 - 3|X_3|^2 + |X_4|^2 = t \quad , \quad (\theta_1, \theta_2, \theta_3, \theta_4) \equiv (\theta_1 + \alpha, \theta_2 + \alpha, \theta_3 - 3\alpha, \theta_4 + \alpha). \quad (2.7)$$

2.1.1 The toric graph

Let π be the moment map

$$\begin{aligned} \pi : \mathfrak{X} &\rightarrow \mathbb{R}^3 \\ &\mapsto (|X_1|^2, |X_2|^2, |X_3|^2) \end{aligned} \quad (2.8)$$

The image $\pi(\mathfrak{X})$ is a convex polyhedral subdomain of \mathbb{R}^3 . Its faces are given by $|X_i|^2 = 0$ for some $i = 1, \dots, 3 + r$. Its edges are the loci where a pair of $|X_i|^2$ vanish and its vertices are reached when 3 of the $|X_i|^2$ vanish. See fig.1 for our 2 examples.

Let us define the three vectors

$$\alpha = (1, 0, 0, \alpha_4, \dots, \alpha_{r+3}) \quad , \quad \beta = (0, 1, 0, \beta_4, \dots, \beta_{r+3}) \quad , \quad \gamma = (0, 0, 1, \gamma_4, \dots, \gamma_{r+3}) \quad (2.9)$$

satisfying

$$\sum_{j=1}^{r+3} q_{i,j} \alpha_j = 0 \quad , \quad \sum_{j=1}^{r+3} q_{i,j} \beta_j = 0 \quad , \quad \sum_{j=1}^{r+3} q_{i,j} \gamma_j = 0 \quad (2.10)$$

for all $i = 1, \dots, r$. Notice that this definition implies that

$$\forall j = 1, \dots, r + 3 \quad , \quad \alpha_j + \beta_j + \gamma_j = 1. \quad (2.11)$$

Thus, the 3-dimensional vector $(\alpha_j, \beta_j, \gamma_j)$ is the normal to the j^{th} face ($|X_j|^2 = 0$).

We define the graph in \mathbb{R}^3 whose $r+3$ vertices are the points

$$(\alpha_j, \beta_j, \gamma_j) \quad (2.12)$$

and we draw an edge between $(\alpha_i, \beta_i, \gamma_i)$ and $(\alpha_j, \beta_j, \gamma_j)$ iff the face $|X_i|^2 = 0$ and $|X_j|^2 = 0$ have a common edge.

This graph is in \mathbb{R}^3 , but since it lies on the hyperplane $\alpha + \beta + \gamma = 1$ (thanks to the Calabi-Yau condition $\sum_{j=1}^{r+3} q_{i,j} = 0$), we can actually view it as a graph in \mathbb{R}^2 .

We thus define:

Definition 2.2 *The dual toric graph $\hat{\Upsilon}_{\mathfrak{X}}$ of \mathfrak{X} , is the graph in \mathbb{R}^2 whose $r+3$ vertices are the points*

$$v_j = (\alpha_j, \beta_j) \quad (2.13)$$

such that two vertices v_i and v_j are linked by an edge if and only if the faces $|X_i|^2 = 0$ and $|X_j|^2 = 0$ have a common edge. $\hat{\Upsilon}_{\mathfrak{X}}$ is thus the graph whose vertices are the normal vectors to the faces of the polyhedra of \mathfrak{X} .

Definition 2.3 *The toric graph $\Upsilon_{\mathfrak{X}}$ of \mathfrak{X} , is the dual of $\hat{\Upsilon}_{\mathfrak{X}}$, i.e. a graph whose edges are orthogonal to those of $\hat{\Upsilon}_{\mathfrak{X}}$, and such that the length of the α -projection of the compact edges are equal to the $|X_1|^2$ projection of the corresponding edges in the polyhedra. The lengths of compact edges of the toric graph, are thus linear combinations of the t_j 's.*

The coordinates of a vertex σ of $\Upsilon_{\mathfrak{X}}$ in the \mathbb{R}^2 plane are denoted:

$$\sigma = (\overset{\circ}{a}_{\sigma}, \overset{\circ}{b}_{\sigma}). \quad (2.14)$$

Thus $\overset{\circ}{a}_{\sigma} - \overset{\circ}{a}_{\sigma'}$ (resp. $\overset{\circ}{b}_{\sigma} - \overset{\circ}{b}_{\sigma'}$) is a linear combination of t_j 's.

See fig.2 for examples.

2.1.2 Smoothness condition

The polyhedra $\pi(\mathfrak{X})$ is not smooth at its vertices. Thus \mathfrak{X} might not be smooth at these vertices. It can be shown that the invertibility of the matrix $[q_{i,j}]_{i=1,\dots,r; j=1,\dots,r+3, j \neq i_1, i_2, i_3}$ with integer coefficients, i.e. that:

$$\forall (i_1, i_2, i_3) = \text{vertex} \quad , \quad \det (q_{i,j})_{i=1,\dots,r; j=1,\dots,r+3, j \neq i_1, i_2, i_3} = \pm 1 \quad (2.15)$$

ensures the smoothness of \mathfrak{X} near the vertex $|X_{i_1}|^2 = |X_{i_2}|^2 = |X_{i_3}|^2 = 0$. We refer to it as the smoothness condition of \mathfrak{X} near (i_1, i_2, i_3) .

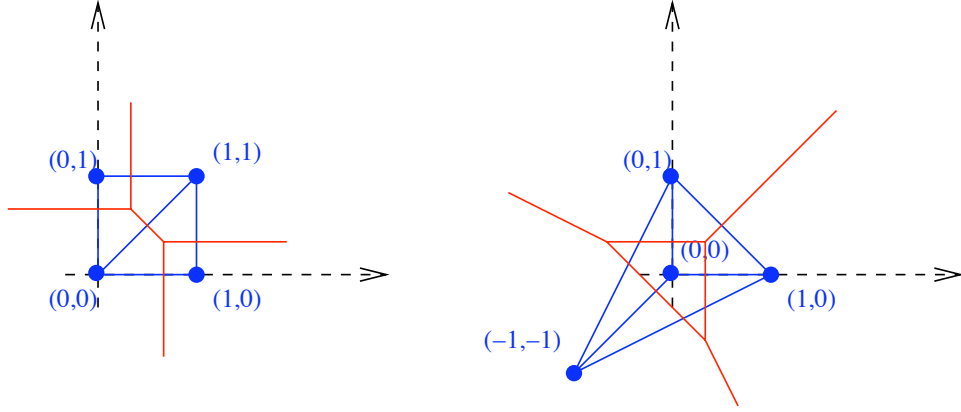


Figure 2: The toric graphs (red) and their duals (blue) for the resolved conifold $q = (1, 1, -1, -1)$ and of local \mathbb{P}^2 $q = (1, 1, -3, 1)$. All the blue triangles have area $1/2$.

Near (i_1, i_2, i_3) , \mathfrak{X} is locally \mathbb{C}^3 , and the condition above is related to the fact that we can define the 3 canonical angles of \mathbb{C}^3 , and the angles must have periodicities 2π (so we need integer coefficients). Once again, we refer the reader to the literature cited at the beginning of this section for further insights on this topic.

In terms of the toric graph, a vertex of the polyhedra is a triangular face of the dual graph $\hat{\Upsilon}_{\mathfrak{X}}$, and the condition 2.15 is equivalent to saying that:

$$\text{area of triangle } (i_1, i_2, i_3) = \frac{1}{2} \quad (2.16)$$

i.e.

$$\alpha_{i_1}\beta_{i_2} - \alpha_{i_2}\beta_{i_1} + \alpha_{i_2}\beta_{i_3} - \alpha_{i_3}\beta_{i_2} + \alpha_{i_3}\beta_{i_1} - \alpha_{i_1}\beta_{i_3} = \pm 1. \quad (2.17)$$

If we relabel the points i_1, i_2, i_3 so that the triangle (i_1, i_2, i_3) has trigonometric orientation in \mathbb{R}^2 , then the expression above is $+1$:

$$\alpha_{i_1}\beta_{i_2} - \alpha_{i_2}\beta_{i_1} + \alpha_{i_2}\beta_{i_3} - \alpha_{i_3}\beta_{i_2} + \alpha_{i_3}\beta_{i_1} - \alpha_{i_1}\beta_{i_3} = +1. \quad (2.18)$$

Proposition 2.1 *The dual toric graph $\hat{\Upsilon}_{\mathfrak{X}}$ is a triangulated polygon with vertices in \mathbb{Z}^2 , made of triangles of area $1/2$.*

2.1.3 Local framings

The previous smoothness condition can be readily rewritten as a determinant, by introducing the following matrix:

Definition 2.4 To every vertex σ of $\Upsilon_{\mathfrak{X}}$, (i.e. to a positively oriented triangle (i_1, i_2, i_3) of the dual $\hat{\Upsilon}_{\mathfrak{X}}$) we associate the 2×2 matrix \mathfrak{f}_{σ} (called local framing matrix at vertex σ):

$$\mathfrak{f}_{\sigma} = \begin{pmatrix} \mathfrak{f}_{a,\sigma} & \mathfrak{f}_{b,\sigma} \\ \mathfrak{f}_{c,\sigma} & \mathfrak{f}_{d,\sigma} \end{pmatrix} = \begin{pmatrix} \beta_{i_3} - \beta_{i_1} & \beta_{i_1} - \beta_{i_2} \\ \alpha_{i_1} - \alpha_{i_3} & \alpha_{i_2} - \alpha_{i_1} \end{pmatrix} \quad (2.19)$$

The smoothness condition is that $\det \mathfrak{f}_{\sigma} = 1$, i.e. $\mathfrak{f}_{\sigma} \in Sl_2(\mathbb{Z})$.

Observe that a rotation of the triangle $(i_1, i_2, i_3) \rightarrow (i_2, i_3, i_1)$ amounts to

$$\mathfrak{f}_{\sigma} \rightarrow \mathfrak{f}_{\sigma} \times \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix}, \quad (2.20)$$

and a change of orientation of the triangle $(i_1, i_2, i_3) \rightarrow (i_2, i_1, i_3)$ amounts to

$$\mathfrak{f}_{\sigma} \rightarrow \mathfrak{f}_{\sigma} \times \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix}. \quad (2.21)$$

Definition 2.5 Let $e = (\sigma, \sigma')$ be an edge of $\Upsilon_{\mathfrak{X}}$, we denote $\epsilon = (\sigma, e)$ (resp. $\epsilon' = (\sigma', e)$) the half edge of e starting from σ (resp. σ'), and let σ be dual to the positively oriented triangle (i_1, i_2, i_3) in $\hat{\Upsilon}_{\mathfrak{X}}$ and σ' be dual to the positively oriented triangle (i_2, i_1, i_4) . We define the framing of the half-edge (σ, e) as:

$$\mathfrak{f}_{\epsilon} = -\mathfrak{f}_{\epsilon'} = \beta_{i_1} - \beta_{i_2} = \mathfrak{f}_{b,\sigma} = -\mathfrak{f}_{b,\sigma'}. \quad (2.22)$$

Notice that the framings of the 3 half-edges emanating from a vertex σ are respectively:

$$\mathfrak{f}_{b,\sigma} \quad , \quad -\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma} \quad , \quad \mathfrak{f}_{a,\sigma}, \quad (2.23)$$

and their sum is zero:

$$\forall \sigma = \text{vertex of } \Upsilon_{\mathfrak{X}}, \quad \sum_{\epsilon \text{ adjacent to } \sigma} f_{\epsilon} = 0. \quad (2.24)$$

2.1.4 Lagrangian submanifolds

For a toric Calabi-Yau 3-fold \mathfrak{X} , we define a set of special Lagrangian submanifolds as follows:

Definition 2.6 Consider a 1-dimensional affine subspace V of \mathbb{R}^3 , given by relations

$$V : \quad \forall i = 1, 2, \quad \sum_{j=1}^{r+3} r_{i,j} |X_j|^2 = c_i \quad (2.25)$$

where $\{r_{i,j}\}_{i=1,\dots,2,j=1,\dots,r+3}$ are integers such that $\sum_j r_{i,j} = 0$, and c_1, c_2 are two real numbers chosen such that V intersects an edge of the polyhedra of \mathfrak{X} . Then define a

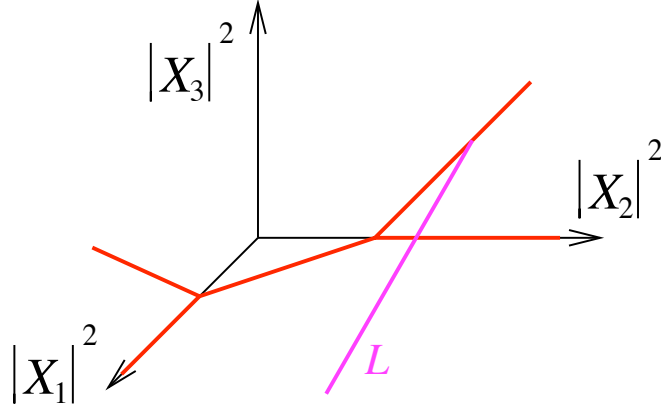


Figure 3: Example of a brane L for \mathfrak{X} =resolved conifold. $\pi(L)$ is a line $V \subset \mathbb{R}^3$, ending on an edge of the polyhedra of \mathfrak{X} .

special Lagrangian submanifold L , as the 3 dimensional submanifold of \mathfrak{X} given by the following relationships:

$$\forall i = 1, 2, \quad \sum_{j=1}^{r+3} r_{i,j} |X_j|^2 = c_i \quad (2.26)$$

and the realtionships between $\theta_1, \dots, \theta_{r+3}$:

$$0 = \det \begin{pmatrix} q_{1,1} & \cdots & q_{1,r+3} \\ \vdots & & \vdots \\ q_{r,1} & \cdots & q_{r,r+3} \\ r_{1,1} & \cdots & r_{1,r+3} \\ r_{2,1} & \cdots & r_{2,r+3} \\ \theta_1 & \cdots & \theta_{r+3} \end{pmatrix}. \quad (2.27)$$

This condition implies that L is Lagrangian, i.e. the symplectic form $\omega = \frac{1}{2} \sum_{j=1}^{r+3} d|X_j|^2 \wedge d\theta_j = 0$ vanishes on L .

In addition, we shall require that the plane orthogonal to V in \mathbb{R}^3 be not parallel to any edge of the polyhedra of \mathfrak{X} .

L (in fact V) can be pictorially represented as a half-line on the polyhedra of \mathfrak{X} , ending on an edge, or also L can be represented as a line attached to an edge of the toric graph, see fig.3.

The fact that L ends on an edge of the toric graph, implies that L is topologically

$$L \sim \mathbb{C} \times S^1, \quad (2.28)$$

and it has Betti number

$$b_1(L) = \dim H_1(L, \mathbb{Z}) = 1 \quad , \quad H_1(L, \mathbb{Z}) \sim \mathbb{Z}. \quad (2.29)$$

From now on, we shall always assume that L ends on a non-compact edge.

2.2 The mirror

For a set of r complex parameters $\{\tilde{t}_i\}_{i=1}^r$, and a set of charges $\{\vec{q}_i\}_{i=1}^r$ as before, one defines the projective curve embedded in $\mathbb{P}^2 = (Y_1, Y_2, Y_3)$ by the homogeneous degree 1 polynomial:

$$H(Y_1, Y_2, Y_3; \tilde{t}_1, \dots, \tilde{t}_r) = \sum_{i=1}^{r+3} Y_i = 0 \quad (2.30)$$

where $Y_i = e^{-x_i}$, and

$$\forall i = 1, \dots, r \quad , \quad \sum_{j=1}^{r+3} q_{i,j} x_j = \tilde{t}_i. \quad (2.31)$$

Thanks to the Calabi-Yau condition $\sum_j q_{i,j} = 0$, it is homogeneous of degree 1. If we choose the patch $Y_3 = 1$, this defines an algebraic curve embedded into $(\mathbb{C}^*)^2$:

$$H(Y_1, Y_2, 1; \tilde{t}_1, \dots, \tilde{t}_r) = 0. \quad (2.32)$$

Remark 2.1 The polynomial $H(Y_1, Y_2, Y_3)$ depends on the complex parameters \tilde{t}_i and charges \vec{q}_i but, as long as there is no ambiguity, we omit to write down this dependence explicitly in the following.

Let us consider our two examples:

- For the resolved conifold $q = (1, 1, -1, -1)$, we have $x_4 = x_1 + x_2 - x_3 - \tilde{t}$, i.e.

$$Y_4 = e^{\tilde{t}} \frac{Y_1 Y_2}{Y_3} \quad (2.33)$$

and thus

$$H(Y_1, Y_2, Y_3) = Y_1 + Y_2 + Y_3 + e^{\tilde{t}} \frac{Y_1 Y_2}{Y_3}. \quad (2.34)$$

The corresponding algebraic curve is:

$$Y_1 + Y_2 + 1 + e^{\tilde{t}} Y_1 Y_2 = 0 \quad (2.35)$$

which is parameterized by a unique parameter \tilde{t} .

- For local \mathbb{P}^2 $q = (1, 1, -3, 1)$, we have $x_4 = 3x_3 - x_1 - x_2 - \tilde{t}$, i.e.

$$Y_4 = e^{\tilde{t}} \frac{Y_3^3}{Y_1 Y_2} \quad (2.36)$$

and thus

$$H(Y_1, Y_2, Y_3) = Y_1 + Y_2 + Y_3 + e^{\tilde{t}} \frac{Y_3^3}{Y_1 Y_2}. \quad (2.37)$$

The algebraic curve is:

$$Y_1 + Y_2 + 1 + \frac{e^{\tilde{t}}}{Y_1 Y_2} = 0. \quad (2.38)$$

2.2.1 Newton's polygon

Notice that the equation of this projective curve is always of the form:

$$H(Y_1, Y_2, Y_3) = \sum_{(\alpha, \beta) = \text{vertex of } \hat{\Upsilon}_{\mathfrak{X}}} H_{\alpha, \beta} Y_1^\alpha Y_2^\beta Y_3^{1-\alpha-\beta}. \quad (2.39)$$

In the patch $Y_3 = 1$, it gives the plane curve

$$H(Y_1, Y_2, 1) = \sum_{(\alpha, \beta) = \text{vertex of } \hat{\Upsilon}_{\mathfrak{X}}} H_{\alpha, \beta} Y_1^\alpha Y_2^\beta = 0. \quad (2.40)$$

Newton's polygon is defined as the set of points $(\alpha, \beta) \in \mathbb{Z}^2$ such that $H_{\alpha, \beta} \neq 0$. Therefore:

Proposition 2.2 *the Newton's polygon of the plane curve $H(Y_1, Y_2, 1) = 0$ is the dual toric graph.*

2.2.2 Topology of the mirror curve

Let \mathcal{C} be the Riemann surface of polynomial equation $0 = H(X, Y) = \sum_{i,j} H_{i,j} X^i Y^j$ with generic coefficients $H_{i,j}$.

It is a classical result in algebraic geometry, that the genus \mathfrak{g} of \mathcal{C} is the number of integer points strictly contained in the convex envelope of the Newton's polygon.

Since the Newton's polygon is the dual toric graph $\hat{\Upsilon}_{\mathfrak{X}}$ and since $\hat{\Upsilon}_{\mathfrak{X}}$ is triangulated with triangles of area $1/2$, each triangle contains no integer point in its interior, integer points are only at vertices, and thus the number \mathfrak{g} of integer points is the number of vertices of $\hat{\Upsilon}_{\mathfrak{X}}$ which are strictly inside the polygon, i.e. in terms of the dual, this is the number of compact faces of $\Upsilon_{\mathfrak{X}}$, that is to say the number "loops" of $\Upsilon_{\mathfrak{X}}$. Since the number of faces of $\Upsilon_{\mathfrak{X}}$ is $r + 3^3$, the number of non-compact faces is $r + 3 - \mathfrak{g}$. This means that:

³Remember that each face corresponds to some $|X_i|^2 = 0$, $i = 1, \dots, r + 3$.

Proposition 2.3 *The genus \mathfrak{g} of the algebraic curve \mathcal{C} is the number of loops in the toric graph $\Upsilon_{\mathfrak{x}}$. The number of punctures of $H(X, Y) = 0$ is $r + 3 - \mathfrak{g}$.*

$\hat{\Upsilon}_{\mathfrak{x}}$ is a triangulated polygon in \mathbb{Z}^2 , with $r + 3$ vertices, $\mathfrak{g} + 2r + 3$ edges, $\mathfrak{g} + r + 1$ triangular faces (each triangle having area $1/2$).

The toric graph $\Upsilon_{\mathfrak{x}}$ is a planar trivalent graph with $2\mathfrak{g} + r$ compact edges, $r + 3 - \mathfrak{g}$ non-compact edges, $\mathfrak{g} + r + 1$ vertices, \mathfrak{g} compact faces and $r + 3 - \mathfrak{g}$ non-compact faces.

For our two examples, this gives:

- The mirror of the resolved conifold has genus $\mathfrak{g} = 0$. The toric graph has $r = 1$, it has 5 edges, 1 compact and 4 non-compact, and it has 2 vertices, and no internal face. See fig.1.
- The mirror of local \mathbb{P}^2 has genus $\mathfrak{g} = 1$. Its toric graph has $r = 1$, it has 3 vertices, 6 edges, 3 compact and 3 non-compact, and one internal face. See fig.1.

2.2.3 Branchpoints

The branchpoints are the zeroes of the meromorphic differential form $dx = -dX/X$ on \mathcal{C} . The number of branchpoints is given by the Hurwitz formula:

$$\#\text{zeroes of } dx = 2\mathfrak{g} - 2 - \deg(dx) \quad (2.41)$$

where $-\deg(dx)$ is the number of poles of dx , i.e. the number of punctures, which is equal to $r + 3 - \mathfrak{g}$. This shows that the number of branchpoints is equal to the number of vertices of $\Upsilon_{\mathfrak{x}}$:

$$\#\text{zeroes of } dx = 2\mathfrak{g} - 2 - \deg(dx) = \mathfrak{g} + r + 1. \quad (2.42)$$

To each vertex σ of $\Upsilon_{\mathfrak{x}}$, we can associate a branchpoint a_{σ} . This labeling of branchpoints by vertices of the $\Upsilon_{\mathfrak{x}}$ is made explicit in the next section.

2.2.4 Framing

For $f \in \mathbb{Z}$, we shall consider the plane curve $H_f(X, Y) = 0$ defined by

$$H_f(X, Y) = H(XY^f, Y, 1) \quad (2.43)$$

i.e. we have replaced $Y_1 = XY^f$ and $Y_2 = Y$ and $Y_3 = 1$. Such an integer $f \in \mathbb{Z}$ is called the "framing".

The framed curve has an equation of the form:

$$H_f(X, Y) = \sum_{(\alpha, \beta) = \text{vertex of } \hat{\Upsilon}_{\mathfrak{x}}} H_{\alpha, \beta} X^{\alpha} Y^{\beta + f\alpha}. \quad (2.44)$$

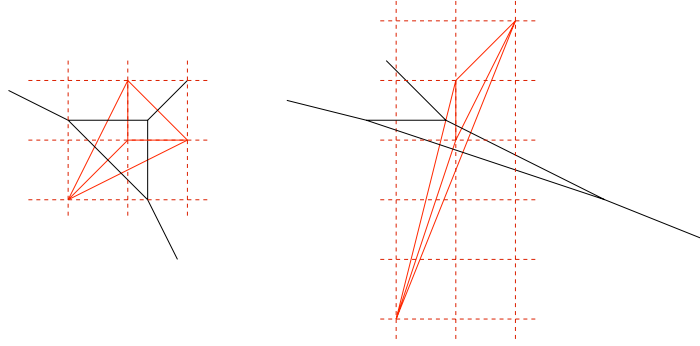


Figure 4: The toric graph of local \mathbb{P}^2 and its dual, and the same graph after a framing transformation $X \rightarrow XY^f$ such that there is no more vertical edge (no horizontal edge in the dual). Here the framing is $f = 2$.

Its Newton's polygon is an affine transformation of the dual toric graph $\hat{\Upsilon}_{\mathbf{x}}$. See fig.4 for the example of local \mathbb{P}^2 .

In all what follows we shall always assume that we have chosen a framing such that the framed toric graph has no vertical edge.

2.3 Atlas of the mirror curve with cylinders and pants

2.3.1 Amoeba and tropical limit

For describing the geometry of the mirror curve, it is very useful to introduce some basic results of tropical geometry.

First of all, given a sub-manifold of \mathbb{C}^n , one defines its Amoeba as follows:

Definition 2.7 For $n \in \mathbb{N}$ and a polynomial $P(Y_1, \dots, Y_n)$, we define the Amoeba of the submanifold $\mathcal{V} := \{(Y_1, \dots, Y_n) \in \mathbb{C}^n | P(Y_1, \dots, Y_n) = 0\}$ by

$$\mathcal{A}(P) := \{(\operatorname{Re} x_1, \dots, \operatorname{Re} x_n) | P(e^{-x_1}, \dots, e^{-x_n}) = 0\}. \quad (2.45)$$

Another way to define this Amoeba is the image of \mathcal{V} under the so-called *Log* map which we shall now define.

Definition 2.8 For $\lambda \in \mathbb{R}^+$, let us define the "Log" map

$$\begin{aligned} \operatorname{Log}_\lambda : (\mathbb{C}^*)^n &\rightarrow \mathbb{R}^n \\ (Y_1, \dots, Y_n) &\rightarrow \left(-\frac{\log|Y_1|}{\log \lambda}, \dots, -\frac{\log|Y_n|}{\log \lambda} \right). \end{aligned} \quad (2.46)$$

With this definition, one sees that

$$\mathcal{A}(P) = \operatorname{Log}_e(\mathcal{V}), \quad (2.47)$$

while changing the value of λ amounts to applying a rescaling to the Amoeba.

In particular, the limit $\lambda \rightarrow \infty$ is known as the tropical limit, following a result of Mikhalkin [45] and Rullgård [50]:

Theorem 2.1 *When $\lambda \rightarrow +\infty$, the λ rescaled Amoeba of $P(X, Y) = \sum_{i,j} \alpha_{i,j} \lambda^{-a_{i,j}} X^i Y^j$ converges to a tropical curve:*

$$\text{Log}_\lambda(\mathcal{V}) \rightarrow_{\lambda \rightarrow \infty} P_\infty(x, y) \quad (2.48)$$

where the tropical curve

$$P_\infty(X, Y) := \sum_{i,j} a_{i,j} X^i Y^j \quad (2.49)$$

is defined by

$$\begin{aligned} \sum_{i,j} a_{i,j} X^i Y^j &= \{ (x_0, y_0) \in \mathbb{R}^2 \mid \exists (i, j) \neq (k, l), \forall (m, n) \notin \{(i, j), (k, l)\}, \\ &\quad a_{i,j} + ix_0 + jy_0 = a_{k,l} + kx_0 + ly_0 \leq a_{m,n} + mx_0 + ny_0 \}. \end{aligned} \quad (2.50)$$

A tropical curve is thus a union of straight segments in \mathbb{R}^2 , forming a graph with trivalent vertices drawn in \mathbb{R}^2 whose faces are associated to the monomials defining polynomial, edges to pairs of such monomials and vertices to triple of them. In particular, the λ rescaled Amoeba of $P(x, y) = \sum_{i,j} \alpha_{i,j} \lambda^{-a_{i,j}} X^i Y^j$ converges in the tropical limit to a graph whose faces correspond to sectors where the log of one of the monomials $\alpha_{i,j} \lambda^{-a_{i,j}} X^i Y^j$ has a modulus larger than the other monomials. The edges and vertices of the limiting Amoeba are thus the locus where two, respectively three, of these monomial are of equal magnitude, and larger than the other ones. Let us remark that the pairs $(i, j) \in \mathbb{Z}^2$ for which $\alpha_{i,j} \neq 0$ fix the slope of the possible edges of the tropical curve whereas the position of the vertices as well as the connectivity of the graph representing this tropical curve depend on the exponents $a_{i,j}$'s.

Let us apply the rescaling technic to the study of the geometry of the mirror curve.

Proposition 2.4 *The tropical limit of the plane curve $H_f(X, Y) = 0$ with complex parameters $\tilde{t}_j = \tilde{T}_j \log \lambda$, is the framed toric graph rescaled by $\log \lambda$ of \mathfrak{X} with Kähler parameters $t_j = \tilde{t}_j + O(1)$.*

proof:

We are interested in the large complex parameter limit $\tilde{t}_k \rightarrow \infty$. For reaching this limit, let us define

$$\tilde{T}_k := \frac{\tilde{t}_k}{\log \lambda} \quad (2.51)$$

where we assume $\tilde{T}_k = O(1)$ when $\lambda \rightarrow +\infty$.

Let us first remark that the coefficient of $X^\alpha Y^\beta$ in the polynomial $H_f(X, Y)$ read

$$H_{\alpha, \beta - f\alpha} = e^{\tilde{t}_{\alpha, \beta}} \quad (2.52)$$

where the times $\tilde{t}_{\alpha, \beta}$ are linear combinations of the complex parameters:

$$\tilde{t}_{\alpha, \beta} = \sum_k C_{\alpha, \beta; k} \tilde{t}_k. \quad (2.53)$$

With these notations, the framed mirror curve can be written

$$H_f(X, Y) = \sum_{(\alpha, \beta - f\alpha) = \text{vertex of } \hat{\Upsilon}_{\mathfrak{X}}} \sum_k C_{\alpha, \beta; k} \tilde{T}_k X^\alpha Y^\beta. \quad (2.54)$$

We can now study the tropical limit of the plane curve $H_f(X, Y) = 0$. When $\lambda \rightarrow \infty$, its rescaled Amoeba converges to

$$H_f^{[\infty]}(X, Y) = \sum_{(\alpha, \beta - f\alpha) = \text{vertex of } \hat{\Upsilon}_{\mathfrak{X}}} \left(- \sum_k C_{\alpha, \beta; k} \tilde{T}_k \right) X^\alpha Y^\beta. \quad (2.55)$$

It is supported by the lines of equation:

$$- \sum_k C_{\alpha, \beta; k} \tilde{T}_k + \alpha x + \beta y = - \sum_k C_{\alpha', \beta'; k} \tilde{T}_k + \alpha' x + \beta' y \quad (2.56)$$

for $(\alpha, \beta - f\alpha)$ and $(\alpha', \beta' - f\alpha')$ two vertices of $\hat{\Upsilon}_{\mathfrak{X}}$. It is easy to see that these lines are parallel to the edges of the framed toric graph of \mathfrak{X}^4 .

More precisely, the tropical curve $H_f^{[\infty]}(X, Y)$ is a graph whose faces are sectors of \mathbb{R}^2 where the logarithm of the modulus of one of the monomials in $H_f(X, Y)$ is larger than all the other ones. It is now important to remember that such a monomial is just the expression of one of the Y_i/Y_3 in terms of X and Y . If $i = 3$ we have that $|Y_i/Y_3| = 1$ and $|Y_j/Y_3| \ll 1$ for $j \neq 3$. If $i \neq 3$, we have that $|Y_j/Y_i| \ll 1$ for $j \neq i$. Let us write

$$|X_j|^2 = -\log |Y_j/Y_i|.$$

Hence, a face of the graph defining the tropical limit, corresponds to

$$|X_i|^2 = 0 \quad , \quad \forall j \neq i \quad |X_j|^2 > 0$$

and by definition $\sum_j q_{k,j} |X_j|^2 = \tilde{t}_k$. In other words a face of the tropical curve corresponds to the vanishing of one of the $|X_i|^2$, i.e. to a face of the toric graph.

⁴Remark that this property does not depend on the value of the parameters $C_{\alpha, \beta; k}$ and \tilde{T}_k .

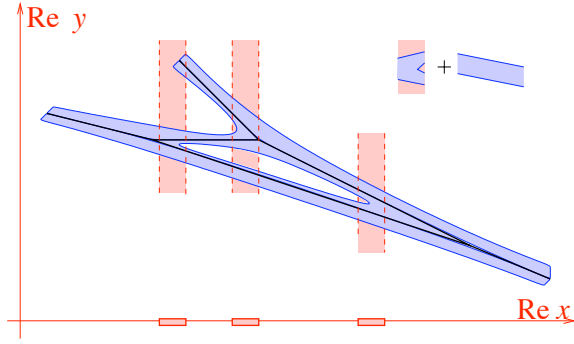


Figure 5: For \tilde{t}_i 's large enough, the Amoeba surrounds the toric graph. Since we have chosen the framing so that the toric graph has no vertical edge, it is possible to cut the amoeba by vertical strips of width $O(1)$ (when $\tilde{t}_i \rightarrow \infty$), such that the amoeba is a union of 3-legs amoebas of fixed width R , and 2 legs amoebas of arbitrary width.

In this way, we can associate a face of the Toric graph to each face of the graph defined by the tropical curve. The adjacency of these latter faces is thus given by the Toric graph. Combining this result with the fact that the edges of the tropical curve are parallel to the ones of the framed toric graph proves the proposition (up to a translation of the edges which does not change the graph and is of no interest in the following).

□

2.3.2 Large radius

When the parameters \tilde{t}_j are large enough, the amoeba of the mirror curve is a small region which surrounds its tropical limit (cf. fig. 5), that is to say, it is a fattening of the framed toric graph.

Thus, when the \tilde{t}_j 's are large enough, it is possible to cut the amoeba by vertical strips of fixed width $R = O(1)$, such that the amoeba is a union of 3-legs amoeba pieces of fixed width, and 2 legs amoeba pieces of arbitrary width. See fig 5.

• Cylinders

Regions of the amoeba which are close to edges (i.e. 2-legs amoeba pieces) correspond to two of the $|Y_i|$'s of the same magnitude and all the others much smaller, i.e. they are approximated by:

$$e^{\tilde{t}_{\alpha,\beta}} X^\alpha Y^\beta + e^{\tilde{t}_{\alpha',\beta'}} X^{\alpha'} Y^{\beta'} = o(1) \quad (2.57)$$

with (α, β) and (α', β') two adjacent vertices of the dual toric graph.

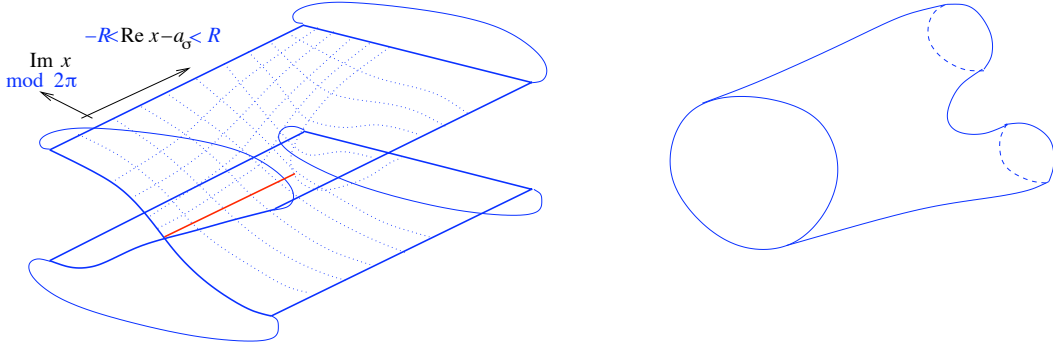


Figure 6: Each \mathcal{C}_σ is topologically a "pair of pants" i.e. a Riemann sphere with 3 holes, $\partial\mathcal{C}_\sigma$ is the union of 3 circles. C_σ is realized by gluing 2 copies of the x -complex plane, with a cut $]\infty, a_\sigma]$, glued together along the cut. Moreover, since the curve is algebraic in the variable $X = e^{-x}$, this means that x has to be identified with $x \equiv x + 2\pi i \mathfrak{f}$. Also, we have defined C_σ by restricting $-\frac{R}{2} < \text{Re}(x - a_\sigma) < \frac{R}{2}$ for large enough \tilde{t}_j 's.

The curve $e^{\tilde{t}_{\alpha,\beta}} X^\alpha Y^\beta + e^{\tilde{t}_{\alpha',\beta'}} X^{\alpha'} Y^{\beta'} = 0$, is a rational curve with 2 punctures, it is topologically a cylinder. It can be parametrized by a complex parameter $z \in \mathbb{C}^*$:

$$\begin{cases} X = e^{-x} = z^{\beta-\beta'} (1 + o(1)) \\ Y = e^{-y} = -e^{\frac{t_{\alpha,\beta} - t_{\alpha',\beta'}}{\beta' - \beta}} z^{\alpha' - \alpha} (1 + o(1)) \end{cases} \quad (2.58)$$

The differential $dx = (\beta' - \beta)dz$ never vanishes, so this curve contains no branchpoints.

• **Pairs of pants** Regions of the amoeba which are close to vertices (i.e. 3-legs amoeba pieces) correspond to three of the $|Y_i|$'s of the same magnitude and all the others much smaller, i.e. they are approximated by:

$$e^{\tilde{t}_{\alpha,\beta}} X^\alpha Y^\beta + e^{\tilde{t}_{\alpha',\beta'}} X^{\alpha'} Y^{\beta'} + e^{\tilde{t}_{\alpha'',\beta''}} X^{\alpha''} Y^{\beta''} = o(1) \quad (2.59)$$

where $(\alpha, \beta), (\alpha', \beta'), (\alpha'', \beta'')$ is an oriented triangle of $\hat{\Upsilon}_{\mathfrak{x}}$, i.e. a vertex σ of $\Upsilon_{\mathfrak{x}}$. This curve can be parametrized by a complex parameter $z \in \mathbb{C} \setminus \{0, 1, \infty\}$:

$$\begin{cases} x = -\ln X = -\mathfrak{f}_b \ln z - \mathfrak{f}_a \ln(1-z) + \mathfrak{f}_b \ln \frac{\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b} + \mathfrak{f}_a \ln \frac{\mathfrak{f}_a}{\mathfrak{f}_a + \mathfrak{f}_b} + \overset{\circ}{a}_\sigma + o(1) \\ y = -\ln Y = -\mathfrak{f}_d \ln z - \mathfrak{f}_c \ln(1-z) + \mathfrak{f}_d \ln \frac{\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b} + \mathfrak{f}_c \ln \frac{\mathfrak{f}_a}{\mathfrak{f}_a + \mathfrak{f}_b} + \overset{\circ}{b}_\sigma + o(1) \end{cases} \quad (2.60)$$

where \mathfrak{f} is the framing matrix defined in def. 2.4.

It is easy to see that this curve is topologically a pair of pants see fig.6.

The differential

$$dx = \left(\frac{-\mathfrak{f}_b}{z} + \frac{\mathfrak{f}_a}{1-z} \right) dz \quad (2.61)$$

vanishes at exactly one point $z = \mathfrak{f}_b/(\mathfrak{f}_a + \mathfrak{f}_b)$, so this pair of pants contains exactly one branchpoint (here we use that we have chosen the framing so that the framed toric graph has no vertical edge, i.e. $\mathfrak{f}_a, \mathfrak{f}_b$ and $\mathfrak{f}_a + \mathfrak{f}_b$ are all non-vanishing).

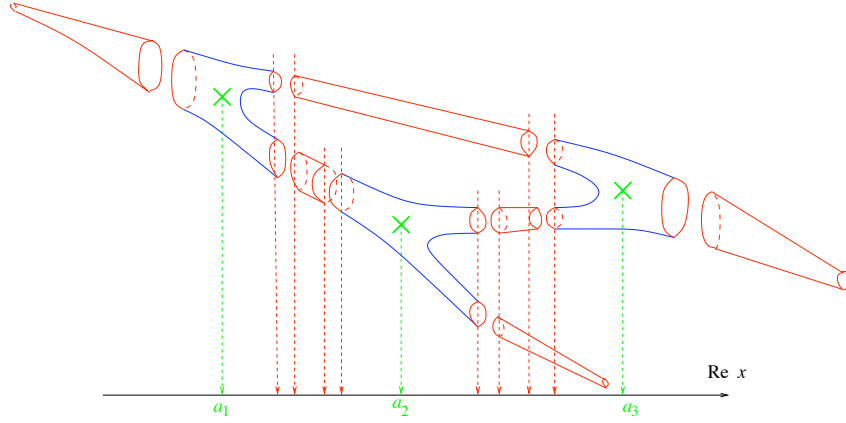


Figure 7: For \tilde{t}_j 's large enough, and if we have chosen an appropriate framing (such that the toric graph has no vertical edge), then we can cut the curve by planes $\text{Re } x = \text{constant}$, such that the curve is a union of pairs of pants and cylinders. Each pair of pants contains exactly one branchpoint a_σ , and we chose the cutting planes such that the domain $\{\text{Re}(x - a_\sigma)\}$ remains finite in the limit $\tilde{t}_j \rightarrow +\infty$. The cylinders become of infinite length in the limit $\tilde{t}_j \rightarrow +\infty$, their length is of the order $|\text{Re}(a_\sigma - a_{\sigma'})|$ i.e. of the order of \tilde{t}_j . The example here is local \mathbb{P}^2 , of equation $1 + XY^2 + Y + \frac{e^{\tilde{t}}}{XY^3} = 0$, i.e. the curve $1 + X + Y + \frac{e^{\tilde{t}}}{XY} = 0$ framed by $X \rightarrow XY^2$.

2.3.3 Atlas of the mirror curve

This gives an explicit atlas of charts to describe the plane curve $H_f(X, Y) = 0$.

In other words, an atlas of \mathcal{C} is obtained as follows:

Proposition 2.5 *The curve \mathcal{C} is covered by a union of cylinders \mathcal{C}_e (with $e \in \text{edges}$) and spheres with 3 holes \mathcal{C}_σ (with $\sigma \in \text{vertices}$).*

$$\mathcal{C} = \bigcup_{\sigma=\text{vertices of } \Upsilon_{\mathfrak{X}}} \mathcal{C}_\sigma \quad \bigcup_{e=\text{edges of } \Upsilon_{\mathfrak{X}}} \mathcal{C}_e. \quad (2.62)$$

The transition maps are given by identifying the coordinate e^{-x} . Indeed, if σ is a vertex and e is an adjacent edge, then the map $\mathcal{C} \rightarrow \mathbb{C}^*$, $\mapsto e^{-x}$ is analytical and invertible on $\mathcal{C}_\sigma \cap \mathcal{C}_e$ (this intersection has the topology of a cylinder).

Each pair of pants \mathcal{C}_σ contains exactly one branchpoint, and thus we label the branchpoints by vertices $\sigma \in \Upsilon_{\mathfrak{X}}$.

2.3.4 The Harnack property

Notice that the map $\mathcal{C} \rightarrow \mathcal{A} : (e^{-x}, e^{-y}) \mapsto (\text{Re } x, \text{Re } y)$ is $2 \rightarrow 1$ in each cylinder and each pair of pants, and our assumption that \tilde{t}_j 's are large enough implies that

the amoeba pieces of distinct cylinders and pairs of pants don't overlap, so the map $\mathcal{C} \rightarrow \mathcal{A} : (e^{-x}, e^{-y}) \mapsto (\operatorname{Re} x, \operatorname{Re} y)$ is globally $2 \rightarrow 1$. This is called the "Harnack property", and this means that $H(e^{-x}, e^{-y}) = 0$ is a Harnack curve.

It was shown by [32, 29] that a Harnack curve can always be realized as the limit shape of a crystal model, which makes the link with combinatorics, but we shall not use that here.

2.4 The mirror map

Our mirror curve is of the form:

$$H(X, Y) = \sum_{(i,j) \in \hat{\Upsilon}_{\mathfrak{X}}} e^{\tilde{t}_{i,j}} X^i Y^j \quad (2.63)$$

where each coefficient $\tilde{t}_{i,j}$ is a linear combination of \tilde{t}_i 's:

$$\tilde{t}_{i,j} = \sum_{k=1}^r C_{i,j;k} \tilde{t}_k. \quad (2.64)$$

Notice that each $I = (i, j)$ is a vertex of the dual toric graph $\hat{\Upsilon}_{\mathfrak{X}}$, and thus corresponds to a face of the toric graph $\Upsilon_{\mathfrak{X}}$.

Our toric graph has \mathfrak{g} loops, i.e. \mathfrak{g} compact faces. To each loop we associate a cycle \mathcal{B}_I on \mathcal{C} by taking the preimage of the corresponding loop at the boundary of the amoeba (see fig.8).

Then, let us choose \mathfrak{g} compact-edges in such a way that after removing those edges the graph remains connected (and thus is a tree).

On each of those edges e_I , define \mathcal{A}_I to be a circle of constant $\operatorname{Re} x$ wrapping the cylinder \mathcal{C}_{e_I} .

We can choose the edges in such a way that

$$\mathcal{A}_I \cap \mathcal{B}_J = \delta_{I,J}. \quad (2.65)$$

Since the non-compact edges of $\Upsilon_{\mathfrak{X}}$ correspond to punctures (i.e. places where $X = 0$ or $X = \infty$, and $Y = 0$ or $Y = \infty$), we can choose on $\mathcal{C} \setminus \cup_I \mathcal{A}_I$ a tree T whose vertices are the punctures.

This ensures that the function $\ln Y$ is well defined on $\mathcal{C} \setminus T$.

Definition 2.9 *The mirror map $\{\tilde{t}_k\}_{k=1,\dots,r+3} \mapsto \{t_k\}_{k=1,\dots,r+3}$ is defined by:*

If (i, j) is a non-compact face:

$$t_{i,j} = \tilde{t}_{i,j}, \quad (2.66)$$

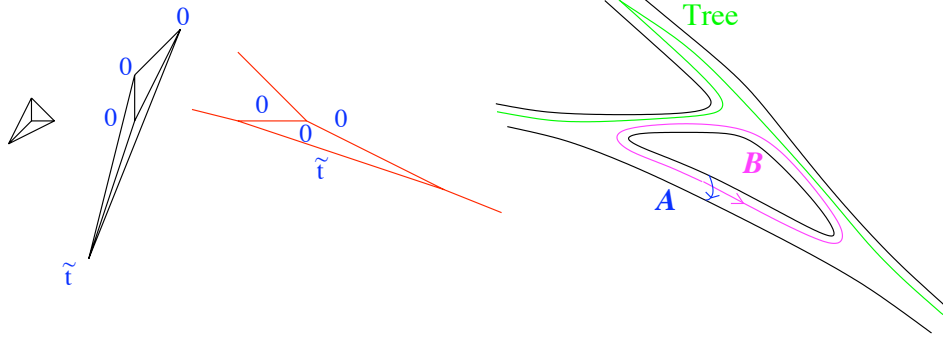


Figure 8: For each vertex $I = (i, j)$ of $\hat{\Upsilon}_{\mathfrak{X}}$, i.e. for each loop I of the toric graph, we draw a \mathcal{B} -cycle \mathcal{B}_I , and then, we choose dual \mathcal{A} -cycles \mathcal{A}_J such that \mathcal{A}_J is a circle with constant $\text{Re } x$ around a cylinder corresponding to an edge surrounding the loop, and such that $\mathcal{A}_J \cap \mathcal{B}_I = \delta_{I,J}$. Then we draw a tree on \mathcal{C} whose vertices are the punctures (the points where $X \rightarrow 0$ or $X \rightarrow \infty$), and which doesn't intersect the \mathcal{A} -cycles and \mathcal{B} -cycles.

and if $I = (i, j)$ is a compact face:

$$t_{i,j} = \frac{1}{2i\pi} \oint_{\mathcal{A}_I} y dx = \frac{1}{2i\pi} \oint_{\mathcal{A}_I} \ln Y \frac{dX}{X}. \quad (2.67)$$

The times t_k 's with $k = 1, \dots, r$, are defined by inverting the system:

$$t_{i,j} = \sum_{k=1}^r C_{i,j;k} t_k \quad (2.68)$$

where the coefficients $C_{i,j;k}$ are defined in eq. (2.64):

$$\tilde{t}_{i,j} = \sum_{k=1}^r C_{i,j;k} \tilde{t}_k. \quad (2.69)$$

If the Kähler parameters t_j 's defining the manifold \mathfrak{X} , and the complex parameters \tilde{t}_j defining the plane curve $H(X, Y; \{\tilde{t}_j\})$ are related by those relations, then we say that $H(X, Y; \{\tilde{t}_j\}) = 0$ is the mirror curve of \mathfrak{X} ⁵.

One can see that in the large parameter limit, when all \tilde{t}_i 's are large, one has:

$$t_i \sim \tilde{t}_i + O(e^{-\tilde{t}_1}, \dots, e^{-\tilde{t}_r}). \quad (2.70)$$

The relationships eq. (2.67) are called "mirror map".

⁵ The mirror curve defined in this way is not the image of \mathfrak{X} under mirror symmetry. This image is indeed a 3-fold defined by the equation $H(X, Y; \{\tilde{t}_j\}) = uv$.

Remark 2.2 These relationship can be rephrased in terms of Picard-Fuchs equations.

$$dx \frac{\partial y(x)}{\partial t_I} = \int_{x' \in \mathcal{B}_I} B(x, x'). \quad (2.71)$$

and thus

$$\frac{\partial t_I}{\partial t_J} = \delta_{I,J} = \frac{1}{2i\pi} \int_{x \in \mathcal{A}_I} \int_{x' \in \mathcal{B}_J} B(x, x'), \quad (2.72)$$

where B is the Bergman kernel on \mathcal{C} . We shall not use this property.

3 A-model side

3.1 Closed Gromov-Witten invariants

3.1.1 Definition

Consider \mathfrak{X} a toric Calabi–Yau manifold of dimension 3, with some toric symmetry T_3 .

Definition 3.1 Let $\beta \in H_2(\mathfrak{X}, \mathbb{Z})$. We define the moduli space of "stable maps"

$$\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta) = \{(\Sigma, f)\} \quad (3.1)$$

where Σ is a (possibly nodal) connected oriented Riemann surface of genus g , and $f : \Sigma \rightarrow \mathfrak{X}$ is holomorphic in the interior of Σ , $f(\Sigma) \in \beta$, and f is a stable map. Stability means that if Σ is a nodal surface, any sphere component with at most 2 nodal points cannot be collapsed to a point by f , and any torus component with no nodal point cannot be collapsed to a point by f . $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)$ is the set of equivalence classes of stable maps modulo isomorphisms. It is an orbifold, meaning that stable maps with symmetries are quotiented by their automorphism group.

It is a classic result of algebraic geometry that $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)$ is a compact moduli space (see for example [24] for a review on the subject).

It has been shown that it has a fundamental class 1 and a virtual cycle $[\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)]^{\text{vir}}$ [35], and thus we can define the Gromov–Witten invariants as:

Definition 3.2 We define the Gromov–Witten invariants as a formal power series (the formal parameter being $\mathbf{Q} = e^{-\mathbf{t}}$):

$$\mathcal{W}_{g,0}(\mathfrak{X}, \mathbf{t}) = \sum_{\beta \in H_2(\mathfrak{X}, \mathbb{Z})} e^{-\mathbf{t} \cdot \beta} \int_{[\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)]^{\text{vir}}} 1. \quad (3.2)$$

where $\mathbf{t} = (t_1, \dots, t_{b_2(\mathfrak{X})})$ is a vector of dimension $b_2(\mathfrak{X}) = \dim H_2(\mathfrak{X}, \mathbb{Z})$, of complex formal parameters t_i .

We emphasize that this defines a formal series in the parameters $\mathbf{Q} = e^{-\mathbf{t}}$, and every equality we are going to consider, will be an equality of formal series, meaning equality of the coefficients of the series.

We won't study the construction of the virtual cycle in this article, as we won't need it, and we refer the reader who wants to know more details to the literature [49].

3.1.2 Localization

The toric symmetry of \mathfrak{X} allows to use Atiyah-Bott localization and thus

$$\mathcal{W}_{g,0}(\mathfrak{X}, \mathbf{t}) = \sum_{\beta \in H_2(\mathfrak{X}, \mathbb{Z})} e^{-\mathbf{t} \cdot \beta} \sum_{\Xi \in \overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}} \int_{[\Xi]^{\text{vir}}} \frac{1}{e_T(N_{\Xi}^{\text{vir}})} \quad (3.3)$$

where $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}$ is the subset of $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)$ of maps invariant under the toric action of \mathfrak{X} . For $\Xi \in \overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}$, the virtual cycle of $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)$ descends to a virtual cycle $[\Xi]^{\text{vir}}$, and to a normal bundle N_{Ξ}^{vir} , and e_T is the equivariant Euler class.

This construction is well studied in the literature, and we shall now briefly describe the fixed locus to motivate the definition of the relative Gromov-Witten invariants given in section 3.3.

3.1.3 Torus orbits in \mathfrak{X}

Before describing the contribution to the localization formula, it is useful to recall the torus action on \mathfrak{X} . Remember that we have defined the moment map

$$\pi : \mathfrak{X} \rightarrow \mathbb{R}^3 \quad , \quad \mapsto (|X_1|^2, |X_2|^2, |X_3|^2). \quad (3.4)$$

It sends \mathfrak{X} to the polyhedra.

The torus action consists in shifting the 3 independent angles, it doesn't change the radius. Hence, it keeps the polyhedra fixed. Let us now study the orbits of the points of \mathfrak{X} under this action:

- For a generic point $p \in \mathfrak{X}$, $\pi(p)$ is in the bulk of the polyhedra, so the 3 independent radius are non-vanishing, and the orbit of p under the torus action is a 3-dimensional torus.
- For a point p such that $\pi(p)$ is on a face of the polyhedra, there are only 2 non-vanishing radius, and thus an orbit of the torus action is a 2-dimensional torus.
- For a point p such that $\pi(p)$ is on an edge of the polyhedra, there is only 1 non-vanishing radius, and thus an orbit of the torus action is a circle.
- For a point p such that $\pi(p)$ is a vertex of the polyhedra, there is no non-vanishing radius, and thus an orbit of the torus action is a point, i.e. vertices of the torus graph correspond to fixed points of the torus action.

Notice that:

- a fixed point i.e. $\pi^{-1}(\text{vertex})$ is a 0-dimensional manifold. For a vertex σ of $\Upsilon_{\mathfrak{X}}$, we denote $\sigma = \pi^{-1}(\sigma)$ the corresponding fixed point of \mathfrak{X} ;
- $\pi^{-1}(\text{edge})$ is a 2-dimensional manifold (a 1-dimensional family of circles). If the edge is a closed edge, this is a sphere with 2 punctures (the 2 punctures being the 2 fixed points), and if the edge is open, this is a half-sphere with one puncture. For a closed edge $e = (\sigma, \sigma')$ (resp. an open edge $\epsilon = (\sigma, e)$), we denote $\tau_{(\sigma, \sigma')} = \pi^{-1}(e)$ (resp. $\tau_{(\sigma, e)} = \pi^{-1}(\epsilon)$) the corresponding sphere (resp. half-sphere).
- $\pi^{-1}(\text{face})$ is a 4-dimensional manifold (a 2-dimensional family of 2-dimensional tori).
- $\pi^{-1}(\text{bulk})$ is a 6-dimensional manifold (a 3-dimensional family of 3-dimensional tori).

In other words, the only fixed locus of \mathfrak{X} which are manifolds of dimension at most 2, correspond to either edges or vertices of the toric graph.

Definition 3.3 *Let $\mathfrak{X}^{\text{fixed}}$ be the subset of \mathfrak{X} :*

$$\mathfrak{X}^{\text{fixed}} = \pi^{-1}(\text{edges} \cup \text{vertices}). \quad (3.5)$$

$\mathfrak{X}^{\text{fixed}}$ is a circle bundle over the toric graph.

- To each vertex σ of the toric graph corresponds a circle σ of vanishing radius (a point);
- to each compact edge $e = (\sigma, \sigma')$ corresponds a sphere $\tau_{(\sigma, \sigma')}$;
- to each non-compact edge $\epsilon = (\sigma, e)$ corresponds a half-sphere $\tau_{(\sigma, e)}$.

See fig.9 for the resolved conifold example.

3.1.4 Framing

There are several possible torus actions in \mathfrak{X} , obtained by changing the canonical basis of \mathbb{C}^3 by an $U(3)$ change of coordinate. So far we have chosen the basis X_1, X_2, X_3 , but we can take $(X'_1, X'_2, X'_3) = U(X_1, X_2, X_3)$ where $U \in U(3)$, so that the symplectic form is conserved:

$$\omega = \sum_{i=1}^3 dX_i \wedge d\bar{X}_i = \sum_{i=1}^3 dX'_i \wedge d\bar{X}'_i. \quad (3.6)$$

The torus action shifts the angles $\theta_1, \theta_2, \theta_3$ where $X_i = |X_i| e^{i\theta_i}$, but we could also shift the θ'_i 's where $X'_i = |X'_i| e^{i\theta'_i}$.

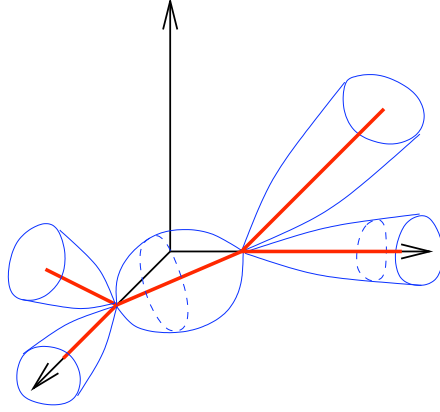


Figure 9: The fixed locus $\mathfrak{X}^{\text{fixed}} = \pi^{-1}(\text{edges} \cup \text{vertices})$ is a circle bundle over the toric graph. Vertices correspond to points, compact edges correspond to spheres, and non compact edges correspond to half-spheres.

Here, we shall choose a basis of X_i 's such that the torus action leaves the S^1 circle $L \cap \{\text{toric graph}\}$ invariant. It depends on our choice of L . Therefore, up to a change of the variables $\{X_i\}_{i=1, \dots, r+3}$ we shall assume that L corresponds to $|X_i|^2 = 0$ for $i \neq 1$. In other words L is the line along the coordinate X_1 . This can always be achieved by a linear transformation of the type:

$$|X_1|^2 \rightarrow |X_1|^2 + f|X_2|^2 + f'|X_3|^2. \quad (3.7)$$

Notice that for the mirror, it corresponds to

$$Y_1 \rightarrow Y_1 Y_2^f Y_3^{f'} \quad (3.8)$$

and if we choose the patch $Y_3 = 1$ that means

$$X \rightarrow X Y^f, \quad (3.9)$$

i.e. it is a framing transformation.

3.1.5 Fixed loci

For a map $[f : \Sigma \rightarrow \mathfrak{X}]$ to belong to $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}$, it has to map Σ to $f(\Sigma) \subset \mathfrak{X}^{\text{fixed}}$.

Let \mathcal{O}_i be an irreducible component of Σ . It's image under f enters one of these three cases⁶:

⁶The interested reader can find proofs and references in [37]. We only want to motivate some of the forthcoming definition in this part.

- Either it is collapsed, i.e. it is mapped to a 0-dimensional component of $\mathfrak{X}^{\text{fixed}}$. This means that $f|_{\mathcal{O}_i}$ is constant and maps all the points of \mathcal{O}_i to a vertex $\sigma(\mathcal{O}_i)$ of the polyhedra. This component can have an arbitrary topology as long as it satisfies the stability condition: its genus $g(\mathcal{O}_i)$ and the number of nodal points $n(\mathcal{O}_i)$ that it contains must satisfy

$$2 - 2g(\mathcal{O}_i) - n(\mathcal{O}_i) < 0. \quad (3.10)$$

- Either it is a sphere with two nodal points and is mapped to a compact 2-dimensional fixed submanifold of \mathfrak{X} , that is to say, to an inner edge e of the polyhedra. The map $f|_{\mathcal{O}_i}$ is then a map between two spheres mapping the nodal points to the two vertices to which $e(\mathcal{O}_i)$ is incident. This map can be of arbitrary degree $d(\mathcal{O}_i) \in \mathbb{N}^*$ and is totally ramified at the two nodal points.
- Either it is a sphere with only one nodal point and is mapped to a compact 2-dimensional fixed submanifold of \mathfrak{X} , that is to say, to an inner edge e of the polyhedra. The nodal point is mapped to one of the two vertices adjacent to the inner edge, therefore there exists a smooth point on \mathcal{O}_i which is mapped to the other vertex. The map $f|_{\mathcal{O}_i}$ is then a map between two spheres mapping the nodal point to a vertex, and the other smooth point to the other vertex. This map can be of arbitrary degree $d(\mathcal{O}_i) \in \mathbb{N}^*$ and is totally ramified at the two fixed points.

A map $(\Sigma, f) \in \overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}$ is thus the union of such irreducible components $\Sigma = \bigcup_i \mathcal{O}_i$ of respective genus $g(\mathcal{O}_i)$ with respectively $n(\mathcal{O}_i)$ nodal points and a map f such that its restrictions $f_i = f|_{\mathcal{O}_i}$ of degree d_i satisfy the constraints:

- If \mathcal{O}_i is stable, i.e. if $2 - 2g(\mathcal{O}_i) - n(\mathcal{O}_i) < 0$, then $d_i = 0$ and f_i is the constant map mapping all the points of \mathcal{O}_i to a vertex $\sigma(\mathcal{O}_i) = \sigma_{l(i)}$ of the Toric graph. The label $l(i)$ tells which fixed point of \mathfrak{X} , \mathcal{O}_i is mapped to.
- If \mathcal{O}_i is unstable, i.e. if $g(\mathcal{O}_i) = 0$ and $n(\mathcal{O}_i) \in \{1, 2\}$, then f_i has an arbitrary degree $d_i = d(\mathcal{O}_i) > 0$ mapping the sphere $\mathcal{O}_i \simeq \mathbb{P}^1$ to one of the 1-dimensional fixed submanifolds of \mathfrak{X} , $f_i(\mathcal{O}_i) = \tau_{e_{l(i)}}$. The label $l(i)$ tells to which 1-dimensional fixed locus of \mathfrak{X} , \mathcal{O}_i is mapped to.
- The intersection of two irreducible components is a nodal point which is mapped to a fixed point of \mathfrak{X} , i.e. to a vertex of the toric graph;
- The genus of Σ is equal to g ;

- The image of Σ belongs to the class β , which translates into

$$\sum_{\mathcal{O}_i \text{ unstable}} d_i \left[\tau_{e_{l(i)}} \right] = \beta. \quad (3.11)$$

3.2 Graphs for the fixed locus

A good way to encode such a fixed map is through a map between $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}$ and a set of graphs. For later convenience, we now introduce a set of graphs which is slightly larger than the one requested for describing $\overline{\mathcal{M}}_{g,0}(\mathfrak{X}, \beta)^{\text{fixed}}$.

3.2.1 Graphs

This leads us to define the following set of graphs $\mathcal{G}_{g,n}$ as:

Definition 3.4 *Let g, n be non-negative integers. $\mathcal{G}_{g,n}$ is the set of graphs defined as follows: $G \in \mathcal{G}_{g,n}$ if G is a connected graph, made of vertices and half-edges, each closed edge is a pair of half-edges, and:*

- *each vertex v has a "color" σ_v which is a vertex of $\Upsilon_{\mathfrak{X}}$, a "genus" $g_v \in \mathbb{N}$, and a "valence" $n_v = \#$ of half-edges incident to v . We denote*

$$E_v = \{h \mid h = \text{half-edge incident to } v\} \quad , \quad \#E_v = n_v. \quad (3.12)$$

- *each half-edge $h \in E_v$ carries a "degree" $d_h \in \mathbb{N}$ and a "color" ϵ_h which is an half-edge of $\Upsilon_{\mathfrak{X}}$, incident to σ_v .*

$$\epsilon_h \in \{\text{half-edges of } \Upsilon_{\mathfrak{X}} \text{ incident to } \sigma_{v(h)}\} \quad \text{where } v(h) \text{ is the vertex adjacent to } h, \quad (3.13)$$

which implies that for a given h , ϵ_h can take only 3 values (there are 3 half-edges incident to a vertex in $\Upsilon_{\mathfrak{X}}$).

- *There are exactly n open half-edges, they are labeled h_1, \dots, h_n .*
- *each closed edge $e = (h_+, h_-)$ is made of two half-edges.*
- *we impose to have*

$$2 - 2g - n = \sum_v (2 - 2g_v - n_v). \quad (3.14)$$

- *We define $\mathcal{G}_{g,n}^{\text{stable}} \subset \mathcal{G}_{g,n}$ the subset of $\mathcal{G}_{g,n}$ with the additional condition that $G \in \mathcal{G}_{g,n}^{\text{stable}}$ iff*

$$\forall v, \quad 2 - 2g_v - n_v < 0, \quad (3.15)$$

in other words $(g_v, n_v) \neq (0, 1)$ and $(g_v, n_v) \neq (0, 2)$.

- *We also define $\tilde{\mathcal{G}}_{g,n}$ (resp. $\tilde{\mathcal{G}}_{g,n}^{\text{stable}}$) as the same set of graphs, but without degree labels d_h attached to half-edges.*

3.2.2 Fixed map and graphs

Let $\Xi = (\Sigma, f)$ be a fixed stable map. Notice that only the irreducible components of Σ which are spheres with 1 or 2 nodal points, are not mapped to a fixed point of $\mathfrak{X}^{\text{fixed}}$, and they are mapped to spheres of $\mathfrak{X}^{\text{fixed}}$.

Therefore we define:

Definition 3.5 *Let $\Xi = (\Sigma, f) \in \overline{\mathcal{M}}_{g,0}(X, \beta)^{\text{fixed}}$ be a fixed stable map. Let us define:*

$$\Sigma_{\text{vertices}} = f^{-1}(\text{fixed points in } \mathfrak{X}^{\text{fixed}}) \quad , \quad \Sigma_{\text{edges}} = \Sigma \setminus \Sigma_{\text{vertices}}. \quad (3.16)$$

Let us write Σ_{vertices} and Σ_{edges} as the disjoint union of their connected components:

$$\Sigma_{\text{vertices}} = \uplus_i \hat{\mathcal{O}}_i \quad , \quad \Sigma_{\text{edges}} = \uplus_i \mathcal{O}_i. \quad (3.17)$$

Each \mathcal{O}_i is a sphere with 2 point removed, i.e. it is a cylinder homeomorphic to \mathbb{C}^ , and each $\hat{\mathcal{O}}_i$ is either a nodal surface, or it is an isolated nodal point, or an isolated smooth point on a sphere with only one other nodal point.*

To $\Xi = (\Sigma, f)$, we associate a graph of $\mathcal{G}_{g,0}$ as follows:

- *to each $\mathcal{O}_i \subset \Sigma_{\text{edges}}$ we associate an edge e_i . The edge e_i is made of two half-edges h_{i+} and h_{i-} corresponding to the two nodal points of \mathcal{O}_i . The edge e_i , and thus the two half-edges $h_{i\pm}$ carry the degree d_{e_i} of the map $f : \mathcal{O}_i \rightarrow \mathfrak{X}^{\text{fixed}}$. Each half-edge $h_{i\pm}$ carries a label $\epsilon_{h_{i\pm}}$ equal to the label of the corresponding half-edge in the toric graph $\Upsilon_{\mathfrak{X}}$.*

- *to each $\hat{\mathcal{O}}_i \subset \Sigma_{\text{vertices}}$ we associate a vertex v_i . The vertex carries a label σ_{v_i} which is the vertex of the toric graph corresponding to the fixed point $f(\hat{\mathcal{O}}_i)$. It carries a genus $g_{v_i} = \text{genus of } \hat{\mathcal{O}}_i$ (and we set $g_{v_i} = 0$ if $\hat{\mathcal{O}}_i$ is a point). It carries a valence $n_{v_i} = \#(\overline{\Sigma}_{\text{edges}} \cap \hat{\mathcal{O}}_i)$.*

- *the incidence relations are determined as follows: an edge e_i is adjacent to a vertex v_j iff $\overline{\mathcal{O}}_i \cap \hat{\mathcal{O}}_j \neq \emptyset$. For each vertex v we define $E_v = \{\text{half-edges adjacent to } v\}$.*

See fig.10 for an example.

We have defined those graphs so that it defines an injective orbifold morphism⁷:

$$\begin{aligned} \overline{\mathcal{M}}_{g,0}(X, \beta)^{\text{fixed}} &\rightarrow \bigoplus_{G \in \mathcal{G}_{g,0}} \prod_{v=\text{vertices}(G)} \overline{\mathcal{M}}_{g_v, n_v} \times \mathbb{N}^{\# \text{half-edges}(G)} \\ (\Sigma, f) &\mapsto \bigoplus_{i=\text{vertices}} \hat{\mathcal{O}}_i \quad \bigoplus_{h=\text{half-edges}} d_h. \end{aligned} \quad (3.18)$$

Remark 3.1 Notice that this application is not surjective. Indeed not all graphs $G \in \mathcal{G}_{g,0}$ satisfy that the degrees of closed half-edges $d_{(v,e)}$ be such that they combine to be the

⁷For a precise definition as well as the description of the image of this morphism see [37].

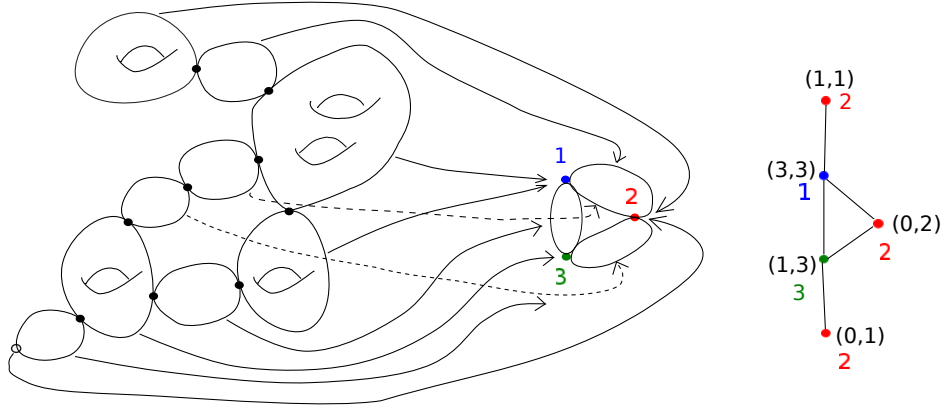


Figure 10: In this example, \mathfrak{X} is local \mathbb{P}^2 , whose toric graph has 3 vertices, labeled (1), (2), (3). $(\Sigma, f) \in \overline{\mathcal{M}}_{g,0}(X, \beta)^{\text{fixed}}$ is a stable nodal map, invariant under the torus action. Each sphere component \mathcal{O}_i with 1 or 2 nodal point is mapped by f to an invariant sphere of $\mathfrak{X}^{\text{fixed}}$. Each higher genus component $\hat{\mathcal{O}}_i$ or each sphere with at least 3 nodal points is mapped to a fixed point of \mathfrak{X} , with label 1, 2 or 3. Each nodal point is also mapped to a fixed point of \mathfrak{X} . For sphere components with only one nodal point (see the bottom left sphere in this example) there is also a smooth point mapped to a fixed point. To each sphere component \mathcal{O}_i of Σ with 1 or 2 nodal point we associate an edge. To each connected component $\hat{\mathcal{O}}_i$ of the preimage of a fixed point (this can be either a stable nodal surface, or an isolated nodal point, or an isolated smooth point) we associate a vertex, to which we associate the label of the fixed point and the pair (g, n) corresponding to the total genus g of $\hat{\mathcal{O}}_i$ (and we set $g = 0$ if $\hat{\mathcal{O}}_i$ is a point), and where n is the number of edges adjacent to it.

homology class β . Moreover, the image $f(\Sigma) \subset \mathfrak{X}^{\text{fixed}}$ must be such that neighboring vertices v, v' can only have labels $\sigma_v, \sigma_{v'}$ which are adjacent in the toric graph, and if h and h' are the two half edges of an edge $e = (h, h')$ we should have that $(\epsilon_h, \epsilon_{h'})$ be an edge of $\Upsilon_{\mathfrak{X}}$, and we should have $d_h = d_{h'}$. As we have defined them, not all graphs in $\mathcal{G}_{g,n}$ satisfy those conditions. In [36] the authors prefer to define a smaller set of graphs containing only the graphs which can be images of fixed stable maps.

Here, we prefer to define a larger set of graphs $\mathcal{G}_{g,n}$ in order to make the link with the topological recursion formalism in the B-model side, later in section 4.4.

Our strategy will be to assign weights to graphs, in order that unwanted graphs receive a vanishing weight.

3.2.3 Gromov-Witten invariants and weighted sum over graphs

Since this morphism is injective, the sum over fixed stable maps can be translated into a sum over $\bigoplus_{G \in \mathcal{G}_{g,0}} \prod_{v=\text{vertices}(G)} \overline{\mathcal{M}}_{g_v, n_v} \times \mathbb{N}^{\# \text{half-edges}(G)}$, i.e. over decorated graphs.

It can be shown that the measure on this set of graphs factorises, up to a symmetry factor, into a product of measures on the vertices and edges forming the graph [37]:

Theorem 3.1 (Localization formula [36, 12]) *The Gromov–Witten invariants of a calabi–Yau \mathfrak{X} can be written as a sum over graphs, weighted by products of weights $H_{g,n;\sigma}(\{k_1, \dots, k_n\})$ associated to vertices and weights $F_{\epsilon,\epsilon'}(k, k')$ associated to edges:*

$$\begin{aligned} \mathcal{W}_{g,0}(\mathfrak{X}, \mathbf{t}) &= \sum_{G \in \mathcal{G}_{g,0}} \frac{(-1)^n}{\#\text{Aut}(G)} \prod_v H_{g_v, n_v; \sigma_v}(\{d_h / \mathfrak{f}_{\epsilon_h}\}_{h \in E_v}) \\ &\quad \prod_{\text{edges } e=(h_+(e), h_-(e))} F_{\epsilon_{h_+(e)}, \epsilon_{h_-(e)}}(d_{h_+(e)}, d_{h_-(e)}). \end{aligned} \quad (3.19)$$

where

- if $2 - 2g - n < 0$:

$$\begin{aligned} H_{g,n,\sigma}(k_1, \dots, k_n) &= 2^{g-1} \left(\frac{1}{2} \prod_{\epsilon=\text{half-edges of } \sigma} \mathfrak{f}_{\epsilon} \right)^{g-1+\frac{n}{2}} \\ &\quad \int_{\bar{\mathcal{M}}_{g,n}} \prod_{\epsilon=\text{half-edges of } \sigma} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{\epsilon}) \prod_{i=1}^n \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_i)}{1 - k_i \psi_i} \end{aligned} \quad (3.20)$$

$$\text{where} \quad \gamma_{\mathfrak{f}}(k) = \frac{1}{\sqrt{\pi k}} \frac{\hat{\Gamma}(k(\mathfrak{f}_a + \mathfrak{f}_b))}{\hat{\Gamma}(k \mathfrak{f}_a) \hat{\Gamma}(k \mathfrak{f}_b)} \quad (3.21)$$

and where $\hat{\Gamma}$ is the "regularized" Γ function defined as

$$\hat{\Gamma}(u) = \frac{e^u \sqrt{u}}{u^u \sqrt{2\pi}} \Gamma(u) = e^{\sum_{k=1}^{\infty} \frac{\mathcal{B}_{2k}}{2k(2k-1)} u^{1-2k}} \quad (3.22)$$

($\Gamma(u)$ is the Gamma function and \mathcal{B}_k is the k^{th} Bernoulli number), and $\hat{\Lambda}_{\text{Hodge}}(f)$ is the Hodge class in $\bar{\mathcal{M}}_{g,n}$ and ψ_i is the first Chern class of the cotangent bundle at the i^{th} marked point.

The same formula applies to $(g, n) = (0, 1)$ and $(0, 2)$ if we define

- if $(g, n) = (0, 1)$:

$$\int_{\bar{\mathcal{M}}_{0,1}} \prod_{\epsilon=\text{half-edges of } \sigma} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{\epsilon}) \frac{1}{1 - k \psi} \stackrel{\text{def}}{=} \frac{1}{k^2} \quad (3.23)$$

- if $(g, n) = (0, 2)$:

$$\int_{\bar{\mathcal{M}}_{0,2}} \prod_{\epsilon=\text{half-edges of } \sigma} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{\epsilon}) \frac{1}{1 - k_1 \psi_1} \frac{1}{1 - k_2 \psi_2} \stackrel{\text{def}}{=} \frac{1}{k_1 + k_2}. \quad (3.24)$$

- and

$$F_{\epsilon_+, \epsilon_-}(d, d') = A_{\epsilon_+, \epsilon_-} \delta_{d, d'} \frac{d}{f_{\epsilon_+}^2} e^{-d \frac{\mathring{\sigma}_{\sigma(\epsilon_+)} - \mathring{\sigma}_{\sigma(\epsilon_-)}}{\mathfrak{f}_{\epsilon_+}}} \quad (3.25)$$

where $A_{\epsilon_+, \epsilon_-} = 1$ if there exists an edge $e = (\epsilon_+, \epsilon_-)$ in the toric graph and zero otherwise, and \mathring{a}_σ is the projection along the axis $|X_1|^2$ of the vertex σ of the toric graph, defined in def. 2.3 (it is a linear combination of the t_i 's). Notice that if $A_{\epsilon_+, \epsilon_-} = 1$, we have $\mathfrak{f}_{\epsilon_+} = -\mathfrak{f}_{\epsilon_-}$, and thus

$$F_{\epsilon_+, \epsilon_-}(d, d') = F_{\epsilon_-, \epsilon_+}(d', d). \quad (3.26)$$

Sketch of a proof:

Intuitively, this decomposition comes from the fact that, once a graph is fixed, the enumeration of corresponding fixed maps can be performed independently for each irreducible component of Σ .

The functions $H_{g,n;\sigma}(\{k_1, \dots, k_n\})$ correspond to vertices, i.e. to constant maps $f : \hat{\mathcal{O}}_i \rightarrow$ fixed point in \mathfrak{X} , and can thus be computed only with the knowledge of a vicinity of a fixed point of \mathfrak{X} , and in the vicinity of a fixed point, \mathfrak{X} can be replaced by \mathbb{C}^3 , thus $H_{g,n;\sigma}(\{k_1, \dots, k_n\})$ are related to the Gromov-Witten invariants of \mathbb{C}^3 , i.e. to the topological vertex, and are computed by the Mariño–Vafa formula [41, 38] as triple Hodge integrals, and result in eq. (3.20).

For edges, we already mentioned that graphs in $\mathcal{G}_{g,n}$ which are not images of fixed stable maps, should receive a vanishing weight, so in particular $F_{\epsilon_-, \epsilon_+}(d', d)$ must vanish if ϵ_\pm are not the two half-edges forming an edge of $\Upsilon_{\mathfrak{X}}$, and also it must vanish if $d \neq d'$, so it must be proportional to $A_{\epsilon_+, \epsilon_-} \delta_{d,d'}$. The weight $e^{-d \frac{\mathring{a}_{\sigma(\epsilon_+)} - \mathring{a}_{\sigma(\epsilon_-)}}{\mathfrak{f}_{\epsilon_+}}}$ is such that thanks to (3.11)

$$\prod_{\text{edges } e=(h_+, h_-)} e^{-d_e \frac{\mathring{a}_{\sigma(\epsilon_{h_+})} - \mathring{a}_{\sigma(\epsilon_{h_-})}}{\mathfrak{f}_{\epsilon_{h_+}}}} = e^{-t, \beta}. \quad (3.27)$$

The factor $\prod_{\text{edges } e} d_e / \mathfrak{f}_e^2$ is a symmetry factor.

All those factors are encoded by $F_{\epsilon, \epsilon'}(k, k')$ defined in eq. (3.25). \square

3.3 Open Gromov-Witten invariants

We wish to generalize this definition of Gromov-Witten invariants to the enumeration of open surfaces whose boundaries are mapped to Lagrangian sub-manifolds. For this purpose, we define:

Definition 3.6 For $\beta \in H_2(\mathfrak{X}, L, \mathbb{Z})$ (relative homology class of 2-chains in \mathfrak{X} whose boundaries lie on L) and $\vec{w} = (w_1, \dots, w_n)$ with $w_i \in H_1(L, \mathbb{Z})$, and such that $\sum_i w_i = \partial\beta$, we define the moduli space

$$\overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, \vec{w}) = \{(\Sigma, f)\} \quad (3.28)$$

where Σ is a (possibly nodal) connected oriented Riemann surface of genus g with n circle boundaries labeled $\partial_1\Sigma, \dots, \partial_n\Sigma$, and $f : \Sigma \rightarrow \mathfrak{X}$ is a holomorphic stable map, such that $f(\partial_i\Sigma) \subset L$, and f is a stable map. Stability means that if Σ is a nodal surface, any sphere component with at most 2 nodal or marked points or boundaries cannot be collapsed to a point by f , and any torus component with no nodal point or boundary cannot be collapsed to a point by f . And $f(\Sigma) \in \beta$ and $f(\partial_i\Sigma) \in w_i$. Again, $\overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, \vec{w})$ is the set of equivalence classes of stable maps modulo isomorphisms. It is an orbifold, meaning that stable maps with symmetries are quotiented by their automorphism group.

When $n > 0$, Katz and Liu [30] have constructed a virtual class and virtual cycle in $\overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, \vec{w})$. Their method is based on the fact that L is the fixed locus of an antiholomorphic involution in \mathfrak{X} , and thus by "doubling" Σ (i.e. extending Σ to a larger closed Riemann surface by Schwarz principle across the boundaries), they embed $\overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, \vec{w})$ in a closed moduli space $\overline{\mathcal{M}}_{g',0}(\mathfrak{X}, \beta')$, where the virtual cycle and class are well known, and they take the restriction to the part invariant under the antiholomorphic involution. This allows them to show that there is a localization formula, which we use below.

For our purpose here, we shall start directly from the localization formula of [38], and which is the straightforward generalization of theorem 3.1:

Definition 3.7 For $n \geq 0$ we define the open Gromov–Witten invariants as

$$\begin{aligned}
\mathcal{W}_{g,n}(\mathfrak{X}, L, \mathbf{t}; x_1, \dots, x_n) &= \sum_{G \in \mathcal{G}_{g,n}} \frac{(-1)^n}{\#\text{Aut}(G)} \prod_v H_{g_v, n_v; \sigma_v}(\{d_h / \mathfrak{f}_{\epsilon_h}\}_{h \in E_v}) \\
&\quad \prod_{\text{closed edges } e=(h_+(e), h_-(e))} F_{\epsilon_{h_+(e)}, \epsilon_{h_-(e)}}(d_{h_+(e)}, d_{h_-(e)}) \\
&\quad \prod_{\text{open half edges } h_i, i=1, \dots, n} \frac{\delta_{\epsilon_{h_i}, \epsilon_i} d_{h_i}}{\mathfrak{f}_{\epsilon_{h_i}}^2} e^{-\frac{d_{h_i}}{\mathfrak{f}_{\epsilon_i}} (x_i - \mathring{a}_{\sigma(\epsilon_i)})},
\end{aligned}
\tag{3.29}$$

where we recall that ϵ_i is the half-edge of $\Upsilon_{\mathfrak{X}}$ on which L ends, $\mathfrak{f}_{\epsilon_i}$ is its framing, and $\mathring{a}_{\sigma(\epsilon_i)}$ is the position of the vertex of $\Upsilon_{\mathfrak{X}}$ adjacent to the half-edge ϵ_i on which L ends. The factors $H_{g,n,\sigma}(k_1, \dots, k_n)$ and $F_{\epsilon_+, \epsilon_-}(d, d')$ are defined in eq. (3.20) and eq. (3.25).

3.3.1 Heuristic origin of this definition

One would like to define the Open Gromov–Witten invariants as formal power series (the formal parameters being $\mathbf{Q} = e^{-\mathbf{t}}$ and $X_i = e^{-x_i}$) computing the integral of the

fundamental class 1 over the virtual fundamental cycle of $[\mathcal{M}_{g,n}(\mathfrak{X}, L, \beta, \vec{w})]^{\text{vir}}$:

$$\mathcal{W}_{g,n}(\mathfrak{X}, L, \mathbf{t}; x_1, \dots, x_n) \quad " = " \quad \sum_{\beta, w_1, \dots, w_n} e^{-\mathbf{t} \cdot \beta} \prod_{i=1}^n e^{-\frac{w_i}{f_{\epsilon_i}} x_i} \int_{[\overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, \vec{w})]^{\text{vir}}} 1 \quad (3.30)$$

where f_{ϵ_i} is the framing of the half-edge of $\Upsilon_{\mathfrak{X}}$ on which L ends (see def. 2.5).

Since this virtual cycle is not so well understood, we prefer to attempt to define the Open Gromov–Witten invariants through the localization formula:

$$\mathcal{W}_{g,n}(\mathfrak{X}, L, \mathbf{t}; x_1, \dots, x_n) \quad " = " \quad \sum_{\beta \in H_2(\mathfrak{X}, L, \mathbb{Z})} \sum_{w_i \in H_1(L, \mathbb{Z})} e^{-\mathbf{t} \cdot \beta} e^{-\sum_{i=1}^n \frac{w_i}{f_{\epsilon_i}} x_i} \sum_{\Xi \in \overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, w)^{\text{fixed}}} \int_{[\Xi]^{\text{vir}}} \frac{1}{e_T(N_{\Xi}^{\text{vir}})} \quad (3.31)$$

where $\overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, w)^{\text{fixed}}$ is the fixed locus of the moduli space of stable maps under the torus action under study. In order to give a meaning to that definition, we need to describe the fixed locus in more details.

3.3.2 Fixed maps

The fixed locus $\overline{\mathcal{M}}_{g,n}^{\text{fixed}}(\mathfrak{X}, L, \beta, \omega)$ is well studied and well known [37, 2, 49]. Let us describe it briefly. It is just a generalization of the $n = 0$ case studied in the preceding section 3.1.5 obtained by including maps from half-spheres components of Σ to fixed half-spheres $\tau_{(\sigma, e)}$ of \mathfrak{X} .

Let $\Xi = (\Sigma, f) \in \overline{\mathcal{M}}_{g,n}(\mathfrak{X}, L, \beta, w)^{\text{fixed}}$ be a fixed stable map.

Since the boundaries of Σ have to be sent to L , this means that they must be sent to $L \cap \mathfrak{X}^{\text{fixed}}$ which is a circle of fixed radius, and

$$\pi(f(\partial_i \Sigma)) = \text{point on the toric graph} = L \cap \text{toric graph}. \quad (3.32)$$

Also, we see that the image of any irreducible component of Σ must be either a point or a sphere with 2 fixed points, or a half-sphere (a disc bounded by the circle $L \cap \mathfrak{X}^{\text{fixed}}$) with 1-fixed point (this last case only if the component contains a boundary).

In particular this implies that a component of Σ containing a boundary is never collapsed to a point, and therefore it can be only a disc with only 1 nodal point and one boundary. Therefore, each boundary is on a disc component.

Appart from those disc components, which are necessarily sent to the half-edge of the toric graph on which L ends, all the other components are mapped by f in the same way as described in section 3.1.5.

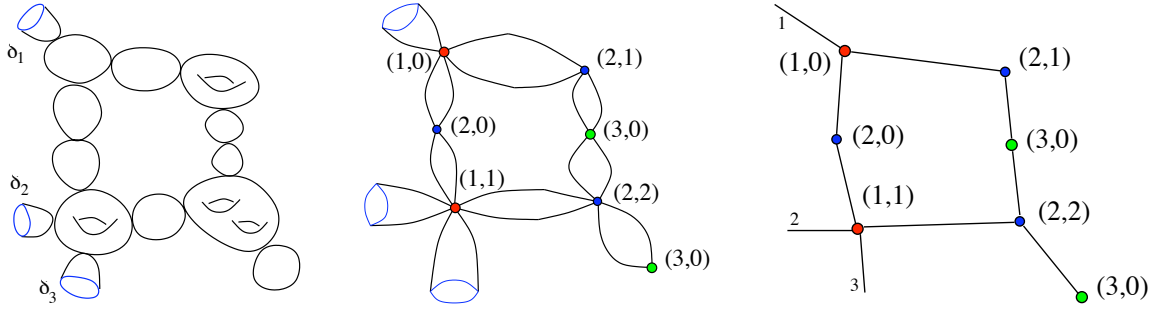


Figure 11: Example of a fixed map of a (nodal) curve Σ of genus 5 and 3 boundaries into \mathfrak{X} . The image $f(\Sigma) \subset \mathfrak{X}$ is made of fixed points in \mathfrak{X} , and of spheres and half spheres invariant under the torus action. All components of a topology with $\chi < 0$ are necessarily collapsed to fixed points. Only components which are spheres with 1 or 2 nodal points can be mapped to invariant curves. Nodal points are mapped to fixed points, and it may also happen that some smooth point gets mapped to a fixed point. The fixed map can be represented by a diagram whose vertices are labeled by (fixed points, genus of the component), and edges correspond to invariant curves. Each vertex carries 2 indices: the label of the fixed point and the genus of the component which was mapped to it.

3.3.3 Fixed maps and graphs

Using the sets of graphs defined in definition 3.4, the study of the fixed locus of the torus action allows to introduce the following morphism.

Definition 3.8 *We define an injective orbifold morphism:*

$$\overline{\mathcal{M}}_{g,n}(X, L, \beta, w)^{\text{fixed}} \rightarrow \bigoplus_{G \in \mathcal{G}_{g,n}} \prod_{v=\text{vertices}(G)} \overline{\mathcal{M}}_{g_v, n_v} \times \mathbb{N}^{\# \text{ half-edges}(G)} \quad (3.33)$$

where each fixed map $\Xi = (\Sigma, f)$ is mapped to a graph G as follows:

1) to each sphere component of Σ with 1 or 2 nodal points is associated a closed edge e of the graph, i.e. two half-edges.

2) to each half-sphere component whose boundary is the circle $\partial_i \Sigma$, is associated the open half-edge h_i with label i , and we have $\epsilon_{h_i} = \epsilon_i$ the open half-edge of $\Upsilon_{\mathfrak{X}}$ on which the brane L ends, and the degree $d_{h_i} = w_i$ the degree of the map $f : \partial_i \Sigma \rightarrow S^1 = L \cap \mathfrak{X}^{\text{fixed}}$.

$$\epsilon_{h_i} = \epsilon_i \quad , \quad d_{h_i} = w_i. \quad (3.34)$$

3) to each connected component of $\Sigma_{\text{vertices}} = f^{-1}(\text{fixed points})$, we associate a vertex v whose labels (g_v, n_v, σ_v) are such that σ_v is the label of the fixed point to which that component is sent by f , g_v is the genus of that component (if the component is an isolated point we set $g_v = 0$), and n_v is the number of adjacent spheres or half-spheres.

5) the incidence relations between vertices and half-edges are obviously the incidence relations of components of Σ .

6) to each half-edge $h = (v, e)$ is associated the degree $d_h \in \mathbb{N}$ of the map f from the sphere of Σ corresponding to edge e to the sphere of $\mathfrak{X}^{\text{fixed}}$ at the nodal or possibly smooth point of that sphere sent to the vertex v .

7) to each vertex v corresponding to a connected component of Σ as described in 3), we associate the corresponding nodal Riemann surface in $\overline{\mathcal{M}}_{g_v, n_v}$. If $(g_v, n_v) = (0, 1)$ we define $\overline{\mathcal{M}}_{0,1}$ = "point", and if $(g_v, n_v) = (0, 2)$ we define $\overline{\mathcal{M}}_{0,2}$ = "point".

From that definition, it is easy to see how the localization formula eq. (3.31) should give eq. (3.29) in def.3.7. The only difference between eq. (3.29) and eq. (3.19), is that we now have a factor counting the half-spheres.

4 B-model side

The B-model side is also a "counting" of embeddings of Riemann surfaces into a Calabi-Yau 3-fold $\hat{\mathfrak{X}}$, but with a weight different from the Gromov-Witten side. Mirror symmetry, and here more precisely the BKMP conjecture, claim that "amplitudes" computed in the B-model with $\hat{\mathfrak{X}}$ = mirror of \mathfrak{X} , equal the (open or closed) Gromov-Witten invariants of \mathfrak{X} of the A-model side.

We refer the reader to the literature [49] for a precise definition of the B-model. Here we shall use the "remodeled" B-model (as named in [9]), which defines the B-model amplitudes as some "topological recursion invariants" which we explain below.

4.1 Mirror

Mirror symmetry assigns another Calabi-Yau manifold to \mathfrak{X} , namely:

$$\hat{\mathfrak{X}} = \{w_+ w_- = H(X, Y)\} \subset \mathbb{C}^2 \times (\mathbb{C}^*)^2 \quad (4.1)$$

i.e. $\hat{\mathfrak{X}}$ is a 3-dimensional complex submanifold of $\mathbb{C}^2 \times (\mathbb{C}^*)^2$, defined in coordinates $(w_+, w_-) \in \mathbb{C}^2$ and $(X, Y) \in (\mathbb{C}^*)^2$ by the relationship:

$$w_+ w_- = H(X, Y) \quad (4.2)$$

where H is the mirror curve defined in section 2.2.

It has the Calabi-Yau property, and the nowhere vanishing holomorphic 3-form is:

$$\Omega = \frac{dw_+ \wedge dX \wedge dY}{w_+ X Y} = - \frac{dw_- \wedge dX \wedge dY}{w_- X Y}. \quad (4.3)$$

Definition 4.1 *The plane curve*

$$H(e^{-x} e^{-fy}, e^{-y}) = 0 \quad (4.4)$$

is called the framed "spectral curve" of $\hat{\mathfrak{X}}$, by abuse of notation, we shall also call it $\hat{\mathfrak{X}}$. It is also often called the "mirror curve" of \mathfrak{X} .

It is the singular locus in $\hat{\mathfrak{X}}$ at which $w_+ = 0$ or $w_- = 0$. In general, the Calabi–Yau 3-fold $\hat{\mathfrak{X}}$ is an hyperbolic bundle over $(\mathbb{C}^*)^2$, whose fiber degenerates on the spectral curve.

4.2 Spectral curves

A spectral curve is in fact the data of a plane curve with some additional structure.

Definition 4.2 (Spectral curve) *A spectral curve $\mathcal{S} = (\mathcal{C}, x, y, B)$, is the data of:*

- *a Riemann surface \mathcal{C} , not necessarily compact,*
- *two analytical functions $x : \mathcal{C} \rightarrow \mathbb{C}$, $y : \mathcal{C} \rightarrow \mathbb{C}$,*
- *a Bergman kernel $B : \mathcal{C} \times \mathcal{C} \rightarrow T^*(\mathcal{C}) \otimes T^*(\mathcal{C})$, i.e. a symmetric 2nd kind bilinear meromorphic differential, having a double pole on the diagonal and no other pole, and normalized (in any local coordinate z) as:*

$$B(z_1, z_2) \underset{z_2 \rightarrow z_1}{\sim} \frac{dz_1 \otimes dz_2}{(z_1 - z_2)^2} + \text{analytical}. \quad (4.5)$$

Moreover, the spectral curve \mathcal{S} is called regular if the meromorphic form dx has a finite number of zeroes on \mathcal{C} , denoted $\{\alpha_1, \dots, \alpha_b\}$ which are all simple zeroes, and dy doesn't vanish at the zeroes of dx . In other words, locally near a branchpoint α_i , y behaves like a square root of x :

$$y(z) \underset{z \rightarrow \alpha_i}{\sim} y(\alpha_i) + y'(\alpha_i) \sqrt{x(z) - a_i} + O(x(z) - a_i) \quad , \quad y'(\alpha_i) \neq 0 \quad (4.6)$$

and where $a_i = x(\alpha_i)$ is the x -projection of the branchpoint α_i :

$$x(\alpha_i) = a_i. \quad (4.7)$$

From now on, all spectral curves considered shall be mirrors of toric CY 3folds:

$$\mathcal{S} = (\mathcal{C}, x, y, B) \quad (4.8)$$

where:

- \mathcal{C} is the Riemann surface described in section 2.2.2, and whose atlas of charts (obtained by gluing pairs of pants and cylinders) $\mathcal{C} = \cup_{\sigma} \mathcal{C}_{\sigma} \cup_{(\sigma, \sigma')} \mathcal{C}_{\sigma, \sigma'}$ was described in section 2.3.3, cf fig.7. \mathcal{C} is a compact Riemann surface of some genus \mathbf{g} equal to the number of loops of the toric graph $\Upsilon_{\mathfrak{x}}$.

- the analytical functions x and y are:

$$x = -\ln X \quad , \quad y = -\ln Y. \quad (4.9)$$

Notice that $X : \mathcal{C} \rightarrow \mathbb{C}$, $z \mapsto X(z)$ (resp. Y) is a meromorphic function on \mathcal{C} , its number of poles = its number of zeroes = the degree in Y (resp, in X) of the polynomial $H(X, Y)$.

This shows that x and y have logarithmic singularities, but their differentials $dx = -dX/X$ and $dy = -dY/Y$ are meromorphic forms on \mathcal{C} , having only simple poles, and their residues are rational numbers (related to the degrees of X and Y at their poles or zeroes).

The poles of dx and dy are the punctures, i.e. the zeroes or poles of X and/or of Y .

- The Bergman kernel B is the unique fundamental form of the 2nd kind on \mathcal{C} (i.e. having a double pole on the diagonal and no other pole, see [22]), normalized on \mathcal{A}_I -cycles (the cycles were defined in def 2.9 section 2.4, they are the ones which compute the mirror map, in particular \mathcal{A} -cycles wrap around cylinders and \mathcal{B} -cycles wrap around loops of the toric graph):

$$\oint_{z_2 \in \mathcal{A}_j} B(z_1, z_2) = 0. \quad (4.10)$$

B can be obtained as the second logarithmic derivative of the prime form on \mathcal{C} (cf [22]):

$$B(z_1, z_2) = d_1 \otimes d_2 \ln E(z_1, z_2). \quad (4.11)$$

B is also related to the "heat kernel" on \mathcal{C} , or to the "Green function" on \mathcal{C} , see [28, 22]. Its "physical meaning" is that it gives the electric field measured at z_2 created by a unit dipole located at z_1 (the log of the prime form $\ln E(z_1, z_2)$ would be the electric potential measured at z_2 created by a unit charge located at z_1).

4.3 Invariants of spectral curves and the BKMP conjecture

To any spectral curve \mathcal{S} is associated a set of "invariants" $\omega_{g,n}(\mathcal{S}; z_1, \dots, z_n)$ first defined in [18]. We emphasize that those invariants are defined for any spectral curve, there is no need to be related to the mirror of a CY manifold.

For completeness, we recall the definition of invariants $\omega_{g,n}(\mathcal{S})$ of a spectral curve \mathcal{S} in appendix A, however we emphasize that it shall not be needed in this article. Instead we shall need only a few of their properties, and in particular the fact that they can be written in terms of graphs, in section 4.4 below, and can be written in terms of intersection numbers in the moduli space of curves $\overline{\mathcal{M}}_{g,n}$ in theorem 4.2 below.

For our purpose we just need:

Definition 4.3 *To a spectral curve \mathcal{S} , we associate the family of its invariants $\omega_{g,n}$ ($g, n \in \mathbb{N}$) : $\mathcal{C}^n \rightarrow T^*(\mathcal{C})^{\otimes n}$, defined by the topological recursion of [18] (see full definition in appendix A.2).*

$$\omega_{g,n}(\mathcal{S}; z_1, \dots, z_n) \in \overbrace{T^*(\mathcal{C}) \otimes \dots \otimes T^*(\mathcal{C})}^{n \text{ times}}. \quad (4.12)$$

It is a symmetric multilinear meromorphic differential. If $2 - 2g - n < 0$, it has poles only at $z_i = \text{branchpoints of the spectral curve (zeroes of } dx)$, of order at most $6g + 2n - 4$, and have no residues. In particular for $n = 0$ we denote $F_g = \omega_{g,0}$:

$$F_g(\mathcal{S}) = \omega_{g,0}(\mathcal{S}) \in \mathbb{C}. \quad (4.13)$$

As special cases, for the lowest values of g and n we mention that:

$$\omega_{0,1}(\mathcal{S}; z) = y(z) dx(z) \quad , \quad \omega_{0,2}(\mathcal{S}; z_1, z_2) = B(z_1, z_2), \quad (4.14)$$

$$\omega_{0,3}(\mathcal{S}; z_1, z_2, z_3) = \sum_{\sigma=\text{branch point}} \text{Res}_{z \rightarrow \sigma} \frac{B(z, z_1) B(z, z_2) B(z, z_3)}{dx(z) dy(z)}. \quad (4.15)$$

$F_0 = \omega_{0,0}$ is the "prepotential", and $F_1 = \omega_{1,0}$ is related to the log determinant of a Laplacian on \mathcal{C} , and for other values of (g, n) we refer to appendix A or to the literature [18].

Those invariants have many fascinating properties (modularity, integrability, special geometry) [18, 20], and can be expressed in terms of intersection numbers [14, 15].

The invariants $\omega_{g,n}(\mathcal{S}; z_1, \dots, z_n)$ depend on n points $(z_1, \dots, z_n) \in \mathcal{C}^n$, however, it is convenient to use a local coordinate on \mathcal{C} , and use the variable $x_i = x(z_i) \in \mathbb{C}$ instead of $z_i \in \mathcal{C}$, we thus write:

Definition 4.4

$$W_{g,n}(\mathcal{S}; x_1, \dots, x_n) = \omega_{g,n}(\mathcal{S}; z_1, \dots, z_n) \quad , \quad x_i = x(z_i) \in \mathbb{C}. \quad (4.16)$$

Remark 4.1 $\omega_{g,n}$ is an analytical (meromorphic) function of each $z_i \in \mathcal{C}$, but since the map $z_i \mapsto x(z_i)$ might be non-invertible (it is not invertible at the branchpoints), the $W_{g,n}$ are not analytical functions of their variables $x_i \in \mathbb{C}$, they are typically multivalued, and they have branchcuts starting and ending at the branchpoints and at the punctures.

In [40, 9], Mariño, Bouchard, Klemm and Pasquetti, conjectured that Gromov–Witten invariants of toric Calabi–Yau 3-folds, coincide with the invariants of their mirror’s spectral curve $\mathcal{S} = \hat{\mathfrak{X}}$.

This conjecture was checked by [9] for many manifolds \mathfrak{X} to low genus, and it was proved to all genus only for the simplest case, namely $\mathfrak{X} = \mathbb{C}^3$ (=framed topological vertex), independently by Chen [11] and Zhou [53] in 2009, by extending the existing proof for the Hurwitz numbers (which is the infinite framing limit of the BKMP conjecture for the topological vertex, known as Bouchard–Mariño conjecture [10], proved in [7, 17]).

Conjecture 4.1 (BKMP conjecture 2006-2008 [40, 9]) *If \mathfrak{X} is a toric Calabi–Yau 3-fold, we have*

$$\mathcal{W}_{g,n}(\mathfrak{X}, L, \mathbf{t}; x_1, \dots, x_n) dx_1 \otimes \dots \otimes dx_n = W_{g,n}(\hat{\mathfrak{X}}; x_1, \dots, x_n) \quad (4.17)$$

where $\hat{\mathfrak{X}}$ is the framed mirror curve of \mathfrak{X} .

As we mentioned, this conjecture was already proved for $\mathfrak{X} = \mathbb{C}^3$, and was proved to low genus in a many examples. We prove the general case below.

4.4 Invariants as graphs and intersection numbers

We shall not need the explicit definition of the invariants $W_{g,n}$, instead we give a combinatoric algorithm to compute them, following [14], we write the invariants as the following two theorems (valid for any spectral curves):

Theorem 4.1 (E. 2011 [14]) *Let $\mathcal{S}_\sigma = (\mathcal{C}_\sigma, x, y, B_\sigma)$ be a spectral curve with only one branchpoint located at $x = a_\sigma$. The invariants $W_{g,n}(\mathcal{S}_\sigma)$ with $2 - 2g - n < 0$, can be expressed as integrals of combinations of ψ and Mumford’s κ classes in $\overline{\mathcal{M}}_{g,n}$ as:*

$$W_{g,n}(\mathcal{S}_\sigma; x_1, \dots, x_n) = \frac{2^{3g-3+n}}{e^{-\hat{t}_{\sigma,0}(2g-2+n)}} \sum_{d_1+\dots+d_n \leq 3g-3+n} \left(\int_{\overline{\mathcal{M}}_{g,n}} \hat{\Lambda}_{\mathcal{S}_\sigma} \prod_{i=1}^n \tau_{d_i} \right) \prod_{i=1}^n d\xi_{\sigma,d_i}(x_i) \quad (4.18)$$

where we have defined:

•

$$e^{-\hat{t}_{\sigma,0}} = 4y'(a_\sigma) = 2 \lim_{z \rightarrow a_\sigma} \frac{y(z) - y(\bar{z})}{\sqrt{x(z) - a_\sigma}} \quad (4.19)$$

where $y'(a_\sigma)$ was defined in eq. (4.6).

• the times $\hat{t}_{\sigma,k}$, or more precisely their generating function $g_\sigma(u)$

$$g_\sigma(u) = \sum_{k=1}^{\infty} \hat{t}_{\sigma,k} u^{-k} \quad (4.20)$$

is defined by the Laplace transform of the 1-form ydx along a "steepest descent" path $\gamma_\sigma \subset \mathcal{C}_\sigma$ such that $x(\gamma_\sigma) - x(a_\sigma) = \mathbb{R}_+$ and $a_\sigma \in \gamma_\sigma$ (i.e. γ_σ is the horizontal trajectory of x going through the branchpoint a_σ):

$$e^{-\hat{t}_{\sigma,0}} e^{-g_\sigma(u)} = \frac{2u^{3/2} e^{u a_\sigma}}{\sqrt{\pi}} \int_{\gamma_\sigma} e^{-ux} y dx \quad (4.21)$$

- the coefficients $\hat{B}_{\sigma,k,l}$, or more precisely their generating function $\hat{B}_\sigma(u, v)$ is defined by the double Laplace transform of B_σ along γ_σ :

$$\hat{B}_\sigma(u, v) = \sum_{k,l=0}^{\infty} \hat{B}_{\sigma,k,l} u^{-k} v^{-l} = \frac{uv}{u+v} + \frac{\sqrt{uv} e^{(u+v)a_\sigma}}{2\pi} \int_{\gamma_\sigma \times \gamma_\sigma} e^{-ux} e^{-vx'} B_\sigma(x, x') \quad (4.22)$$

where the double integral is properly regularized so that the result has a large u, v expansion, see [14].

- The one forms $d\xi_{\sigma,d}(x)$ are defined as

$$d\xi_{\sigma,d}(x) = - \frac{(2d-1)!!}{2^d} \text{Res}_{x' \rightarrow a_\sigma} B_\sigma(x, x') (x' - a_\sigma)^{-d-1/2} \quad (4.23)$$

- the tautological class $\hat{\Lambda}_{\mathcal{S}_\sigma}$ is a combination of $\tau_d = \psi^d$ and Mumford's κ classes in $\overline{\mathcal{M}}_{g,n}$ (see appendix B), defined as

$$\hat{\Lambda}_{\mathcal{S}_\sigma} = e^{\sum_{k \geq 1} \hat{t}_{\sigma,k} \kappa_k} e^{\frac{1}{2} \sum_{\delta \in \partial \mathcal{M}_{g,n}} \sum_{k,l} \hat{B}_{\sigma,k,l} l_{\delta*} \tau_k \tau_l} \quad (4.24)$$

$l_{\delta*}$ is the natural inclusion of $\partial \mathcal{M}_{g,n}$ into $\mathcal{M}_{g-1,n+2} \cup \sum_{h+h'=g, m+m'=n} \mathcal{M}_{h,m+1} \times \mathcal{M}_{h',m'+1}$,

proof:

The proof is done in [14]. Let us just sketch the main steps.

The prototype of a spectral curve with only one branchpoint is $y = \sum_{k \in \mathbb{N}} t_{k+2} (x - a)^{k/2}$.

This is the spectral curve of Kontsevich's matrix Airy integral with times $\{t_k\}$ [33], whose invariants $\omega_{g,n}$ are (almost by definition of Kontsevich's integral, see [16, 33]), generating functions for intersection numbers of ψ classes in $\overline{\mathcal{M}}_{g,n}$ (see appendix B). Finding a Kontsevich spectral curve (i.e. finding the Kontsevich times t_k) which has the same Taylor expansion near the branchpoint as \mathcal{S}_σ , allows to express the invariants of any spectral curve with one branchpoint in terms of intersection of classes in $\overline{\mathcal{M}}_{g,n}$. Moreover, the result looks even better if we rewrite, using Arbarello and Cornalba's relations [4], the combinations of ψ classes in terms of Mumford κ classes. All this was done in [14] and results into theorem 4.1.

□

Remark 4.2 Formula eq. (4.18) looks very similar to the ELSV formula, and indeed it reduces to the ELSV formula for the spectral curve $(\mathbb{C}, x(z) = z - \ln z, y(z) = z, B(z_1, z_2) = dz_1 \otimes dz_2 / (z_1 - z_2)^2)$ which appears in the study of simple Hurwitz numbers [10, 7, 17, 14]. In that case the combination of κ and ψ classes in eq. (4.24) reduces to the Hodge class through Mumford's formula [47]. See [14] for the detailed proof.

Once we know how to compute the invariants of spectral curves having only 1 branch-point, the following theorem (proved in [15]) gives invariants of spectral curves with an arbitrary number of branchpoints:

Theorem 4.2 (corollary of the theorem in [15, 3, 48, 34]) *Let $\mathcal{S} = (\mathcal{C}, x, y, B)$ be a spectral curve with branchpoints $\{a_1, \dots, a_b\}$. Let $\mathcal{S}_\sigma = (\mathcal{C}_\sigma, x, y, B_\sigma)$ be the local spectral curve near the branchpoint a_σ , with $\mathcal{C}_\sigma \subset \mathcal{C}$ containing only the branchpoint a_σ , and x and y are the restrictions of x and y to \mathcal{C}_σ , and B_σ a Bergman kernel⁸ on \mathcal{C}_σ .*

When $2 - 2g - n < 0$, the invariants of \mathcal{S} can be computed in terms of graphs and invariants of local curves near branchpoints, as

$$\begin{aligned}
W_{g,n}(\mathcal{S}; x_1, \dots, x_n) = & \sum_{G \in \tilde{\mathcal{G}}_{g,n}^{\text{stable}}} \frac{1}{\#\text{Aut}(G)} \prod_{h=\text{half-edges}} \text{Res}_{x_h \rightarrow a_{\sigma_v(h)}} \\
& \prod_{v=\text{vertices}} W_{g_v, n_v}(\mathcal{S}_{\sigma_v}; \{x_h\}_{h \in E_v}) \\
& \prod_{(h_+, h_-)=\text{closed edges}} \left[\ln(E(\mathcal{S}; x_{h_+}, x_{h_-})) \right. \\
& \quad \left. - \delta_{\sigma_v(h_+), \sigma_v(h_-)} \ln(E(\mathcal{S}_{\sigma_v(h_+)}; x_{h_+}, x_{h_-})) \right] \\
& \prod_{h_i=\text{open half-edges}} dS(\mathcal{S}; x_i, x_{h_i})
\end{aligned} \tag{4.25}$$

where $E(\mathcal{S}; x_1, x_2)$ denotes the prime form associated to the Bergman kernel on \mathcal{S} , i.e.

$$d_1 \otimes d_2 \ln E(\mathcal{S}; x_1, x_2) = B(\mathcal{S}; x_1, x_2). \tag{4.26}$$

and $dS(\mathcal{S}; x_1, x_2)$ is the Cauchy kernel associated to the Bergman kernel on \mathcal{S}

$$d_1 \ln E(\mathcal{S}; x_1, x_2) = dS(\mathcal{S}; x_1, x_2) = \int_{x'_2=o}^{x_2} B(\mathcal{S}; x_1, x'_2). \tag{4.27}$$

And $\tilde{\mathcal{G}}_{g,n}^{\text{stable}}$ is the same set of graphs as in $\mathcal{G}_{g,n}^{\text{stable}}$ defined in def.3.4, but without degree labels d_h on half-edges.

⁸ B_σ needs not be the restriction of B to \mathcal{C}_σ , neither needs to be the normalized Bergman kernel on \mathcal{C}_σ . For this theorem it just needs to be any symmetric bilinear differential having a normalized double pole on the diagonal.

For example $W_{0,4}$: since $\sum_v (2 - 2g_v - n_v) = -2$ and $2 - 2g_v - n_v < 0$ and $\sum_v n_v \geq 4$, $\tilde{\mathcal{G}}_{0,4}^{\text{stable}}$ contains graphs with at most 2 vertices. More precisely, $\tilde{\mathcal{G}}_{0,4}^{\text{stable}}$ contains either graphs with one 4-valent vertex, or graphs with two 3-valent vertices:

$$\begin{aligned}
& W_{0,4}(\mathcal{S}; x_1, x_2, x_3, x_4) \\
&= \sum_{\sigma} \text{Res}_{x'_1, x'_2, x'_3, x'_4 \rightarrow a_{\sigma}} W_{0,4}(\mathcal{S}_{\sigma}; x'_1, x'_2, x'_3, x'_4) \prod_{i=1}^4 dS(\mathcal{S}; x_i, x'_i) \\
&+ \sum_{\sigma_1} \sum_{\sigma_2} \text{Res}_{x'_1, x'_2, x'_5 \rightarrow a_{\sigma_1}} \text{Res}_{x'_3, x'_4, x'_6 \rightarrow a_{\sigma_2}} W_{0,3}(\mathcal{S}_{\sigma_1}; x'_1, x'_2, x'_5) W_{0,3}(\mathcal{S}_{\sigma_2}; x'_3, x'_4, x'_6) \\
&\quad (\ln E(\mathcal{S}; x'_5, x'_6) - \delta_{\sigma_1, \sigma_2} \ln E(\mathcal{S}_{\sigma_1}; x'_5, x'_6)) \prod_{i=1}^4 dS(\mathcal{S}; x_i, x'_i) \\
&+ \text{permutations of } \{x_1, x_2, x_3, x_4\} \tag{4.28}
\end{aligned}$$

$$W_{(0,4)} = \begin{array}{c} x_1 \quad x_2 \\ \diagdown \quad \diagup \\ (0,4,1) \bullet \\ \diagup \quad \diagdown \\ x_3 \quad x_4 \end{array} + \begin{array}{c} x_1 \quad x_2 \\ \diagdown \quad \diagup \\ (0,4,2) \bullet \\ \diagup \quad \diagdown \\ x_3 \quad x_4 \end{array} + \begin{array}{c} x_1 \quad x_2 \\ \diagdown \quad \diagup \\ (0,3,1) \bullet \text{---} \bullet (0,3,2) \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ x_3 \quad x_5' \quad x_6' \quad x_4 \end{array} + \text{perm. } (x_1, x_2, x_3, x_4)$$

proof:

This is a mere rewriting of [15], and it is a consequence of [48, 34], the graphs are a way of encoding the order in which residues are computed, i.e. it is only a combinatorial way of summing over σ the residues at the branchpoints a_{σ} . A detailed proof is written in [15]. We emphasize that this theorem applies to any spectral curve \mathcal{S} , it doesn't need to be related to any Calabi–Yau mirror geometry.

□

4.5 Geometry of the local spectral curve

In prop 2.5, we have defined an atlas for the curve \mathcal{C} , in terms of pairs of pants \mathcal{C}_{σ} and cylinders $\mathcal{C}_{\sigma, \sigma'}$, labeled by vertices and edges of the toric graph $\Upsilon_{\mathfrak{X}}$. Each \mathcal{C}_{σ} contains exactly one branchpoint a_{σ} .

Since \mathcal{C}_{σ} is topologically a pair of pants, it can be realized as the projective complex plane with 3 holes, and we can choose the 3 holes to be connected domains respectively containing $z = 0, 1, \infty$, i.e.

$$\mathcal{C}_{\sigma} \subset \mathbb{P}^1 \setminus \{0, 1, \infty\}. \tag{4.29}$$

The functions $X = e^{-x}$ and $Y = e^{-y}$ are holomorphic functions on \mathcal{C}_{σ} , and thus the functions x and y are holomorphic functions on $\mathcal{C}_{\sigma} \setminus T$ where the tree T was introduced in section 2.4 as a cut for the log.

4.5.1 Large radius limit (tropica limit)

Let $(\overset{\circ}{a}_\sigma, \overset{\circ}{b}_\sigma)$ be the vertices of the toric graph (see def. 2.3). \mathcal{C}_σ was defined in section 2.3.3 so that $x - \overset{\circ}{a}_\sigma$ and $y - \overset{\circ}{b}_\sigma$ have a non-trivial limit when all $t_j \rightarrow +\infty$, i.e. we define:

Definition 4.5 *The functions $\overset{\circ}{x}_\sigma : \mathcal{C}_\sigma \rightarrow \mathbb{C}$ and $\overset{\circ}{y}_\sigma : \mathcal{C}_\sigma \rightarrow \mathbb{C}$ are the large radius limits of x and y in $\mathcal{C} \cap \mathcal{C}_\sigma$:*

$$\overset{\circ}{x}_\sigma = \lim_{\tilde{t}_j \rightarrow +\infty} x - \overset{\circ}{a}_\sigma \quad , \quad \overset{\circ}{y}_\sigma = \lim_{\tilde{t}_j \rightarrow +\infty} y - \overset{\circ}{b}_\sigma. \quad (4.30)$$

A vertex σ of the toric graph is a triangle $\sigma = (i_1, i_2, i_3)$ of the dual $\hat{\Upsilon}_{\mathfrak{X}}$. Since we are very close to a vertex of the toric graph, in the tropical limit only three of the Y_i 's don't tend to 0, i.e. the large radius limit of the mirror curve is:

$$Y_{i_1} + Y_{i_2} + Y_{i_3} = 0, \quad (4.31)$$

or alternatively, only 3 monomials in $H(X, Y) = 0 = \sum_{i,j} e^{-\tilde{t}_{i,j}} X^i Y^j$ survive in that limit $H(X, Y) \rightarrow \overset{\circ}{H}_\sigma(\overset{\circ}{X}_\sigma, \overset{\circ}{Y}_\sigma)$:

$$H \rightarrow \overset{\circ}{H}_\sigma \quad , \quad \overset{\circ}{H}_\sigma(\overset{\circ}{X}, \overset{\circ}{Y}) = 1 + C_\sigma \overset{\circ}{X}^{\overset{\circ}{f}_{d,\sigma}} \overset{\circ}{Y}^{-\overset{\circ}{f}_{b,\sigma}} + \tilde{C}_\sigma \overset{\circ}{X}^{-\overset{\circ}{f}_{c,\sigma}} \overset{\circ}{Y}^{\overset{\circ}{f}_{a,\sigma}}. \quad (4.32)$$

The exponents $(\mathfrak{f}_{a,\sigma}, \mathfrak{f}_{b,\sigma}, \mathfrak{f}_{c,\sigma}, \mathfrak{f}_{d,\sigma}) \in \mathbb{Z}^4$ are integers corresponding to the vertices of the dual toric graph around the vertex σ . They form the local framing matrix at vertex σ defined in def.2.4:

$$\mathfrak{f}_\sigma = \begin{pmatrix} \mathfrak{f}_{a,\sigma} & \mathfrak{f}_{b,\sigma} \\ \mathfrak{f}_{c,\sigma} & \mathfrak{f}_{d,\sigma} \end{pmatrix} \quad , \quad \det \mathfrak{f}_\sigma = 1. \quad (4.33)$$

The coefficients C_σ and \tilde{C}_σ are the limits of:

$$-\ln C_\sigma = \lim_{\tilde{t}_j \rightarrow +\infty} -\mathfrak{f}_{d,\sigma} a_\sigma + \mathfrak{f}_{b,\sigma} y(a_\sigma) + \tilde{t}_{i-\mathfrak{f}_{d,\sigma}, j+\mathfrak{f}_{b,\sigma}} - \tilde{t}_{i,j} \quad (4.34)$$

$$-\ln \tilde{C}_\sigma = \lim_{\tilde{t}_j \rightarrow +\infty} \mathfrak{f}_{c,\sigma} a_\sigma - \mathfrak{f}_{a,\sigma} y(a_\sigma) + \tilde{t}_{i+\mathfrak{f}_{c,\sigma}, j-\mathfrak{f}_{a,\sigma}} - \tilde{t}_{i,j} \quad (4.35)$$

where $(i, j) \in \mathbb{Z}^2$ is any vertex of the dual graph $\hat{\Upsilon}_{\mathfrak{X}}$ adjacent to the vertex σ .

We can parametrize our curve eq. (4.32) by a complex variable $z \in \mathbb{C} \setminus \{0, 1, \infty\}$, and here explicitly:

$$\begin{aligned} \overset{\circ}{X}_\sigma(z) &= e^{-\overset{\circ}{x}_\sigma(z)} = (-C_\sigma)^{-\mathfrak{f}_{a,\sigma}} (-\tilde{C}_\sigma)^{-\mathfrak{f}_{b,\sigma}} z^{\mathfrak{f}_{b,\sigma}} (1-z)^{\mathfrak{f}_{a,\sigma}} \\ \overset{\circ}{Y}_\sigma(z) &= e^{-\overset{\circ}{y}_\sigma(z)} = (-C_\sigma)^{-\mathfrak{f}_{c,\sigma}} (-\tilde{C}_\sigma)^{-\mathfrak{f}_{d,\sigma}} z^{\mathfrak{f}_{d,\sigma}} (1-z)^{\mathfrak{f}_{c,\sigma}} \end{aligned} \quad (4.36)$$

i.e.

$$\begin{aligned}\overset{\circ}{x}_\sigma(z) &= \mathfrak{f}_{a,\sigma} \ln(-C_\sigma) + \mathfrak{f}_{b,\sigma} \ln(-\tilde{C}_\sigma) - \mathfrak{f}_{b,\sigma} \ln z - \mathfrak{f}_{a,\sigma} \ln(1-z) \\ \overset{\circ}{y}_\sigma(z) &= \mathfrak{f}_{c,\sigma} \ln(-C_\sigma) + \mathfrak{f}_{d,\sigma} \ln(-\tilde{C}_\sigma) - \mathfrak{f}_{d,\sigma} \ln z - \mathfrak{f}_{c,\sigma} \ln(1-z)\end{aligned}\quad (4.37)$$

taking the differentials gives:

$$d\overset{\circ}{x}_\sigma = - \left(\frac{\mathfrak{f}_{b,\sigma}}{z} + \frac{\mathfrak{f}_{a,\sigma}}{z-1} \right) dz \quad , \quad d\overset{\circ}{y}_\sigma = - \left(\frac{\mathfrak{f}_{d,\sigma}}{z} + \frac{\mathfrak{f}_{c,\sigma}}{z-1} \right) dz. \quad (4.38)$$

Notice that $d\overset{\circ}{x}_\sigma$ and $d\overset{\circ}{y}_\sigma$ are meromorphic forms on \mathbb{P}^1 having only simple poles at $0, 1, \infty$, and the entries of \mathfrak{f} are the residues of those poles.

We have realized \mathcal{C}_σ as an open domain of $\mathbb{P}^1 \setminus \{0, 1, \infty\}$.

Notice that $d\overset{\circ}{x}_\sigma$ vanishes at

$$z = \frac{\mathfrak{f}_{b,\sigma}}{\mathfrak{f}_{a,\sigma} + \mathfrak{f}_{b,\sigma}}, \quad (4.39)$$

therefore the branchpoint is located at (by definition it was at $\overset{\circ}{x}_\sigma = 0, \overset{\circ}{y}_\sigma = 0$):

$$0 = \mathfrak{f}_{a,\sigma} \ln(-C_\sigma) + \mathfrak{f}_{b,\sigma} \ln(-\tilde{C}_\sigma) - \mathfrak{f}_{b,\sigma} \ln \frac{\mathfrak{f}_{b,\sigma}}{\mathfrak{f}_{a,\sigma} + \mathfrak{f}_{b,\sigma}} - \mathfrak{f}_{a,\sigma} \ln \frac{\mathfrak{f}_{a,\sigma}}{\mathfrak{f}_{a,\sigma} + \mathfrak{f}_{b,\sigma}} \quad (4.40)$$

and similarly $\overset{\circ}{y}_\sigma$ must vanish at the branchpoint. This determines the coefficients C_σ and \tilde{C}_σ .

We thus define:

Definition 4.6 *Let*

$$\mathfrak{f} = \begin{pmatrix} \mathfrak{f}_a & \mathfrak{f}_b \\ \mathfrak{f}_c & \mathfrak{f}_d \end{pmatrix} \in Sl_2(\mathbb{Z}) \quad , \quad \mathfrak{f}_a \mathfrak{f}_d - \mathfrak{f}_b \mathfrak{f}_c = 1 \quad (4.41)$$

be a local framing matrix, then we define the "vertex" spectral curve $\overset{\circ}{\mathcal{S}}_\mathfrak{f}$ as:

$$\overset{\circ}{\mathcal{S}}_\mathfrak{f} = (\mathbb{P}^1 \setminus \{0, 1, \infty\}, \overset{\circ}{x}_\mathfrak{f}, \overset{\circ}{y}_\mathfrak{f}, \overset{\circ}{B}_\mathfrak{f}) \quad (4.42)$$

where

$$\begin{cases} \overset{\circ}{x}_\mathfrak{f}(z) = -\mathfrak{f}_b \ln z - \mathfrak{f}_a \ln(1-z) + \mathfrak{f}_b \ln \frac{\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b} + \mathfrak{f}_a \ln \frac{\mathfrak{f}_a}{\mathfrak{f}_a + \mathfrak{f}_b} \\ \overset{\circ}{y}_\mathfrak{f}(z) = -\mathfrak{f}_d \ln z - \mathfrak{f}_c \ln(1-z) + \mathfrak{f}_d \ln \frac{\mathfrak{f}_d}{\mathfrak{f}_c + \mathfrak{f}_d} + \mathfrak{f}_c \ln \frac{\mathfrak{f}_c}{\mathfrak{f}_c + \mathfrak{f}_d} \\ \overset{\circ}{B}_\mathfrak{f}(x_1, x_2) = \frac{dz_1 \otimes dz_2}{(z_1 - z_2)^2} \quad \text{where } x_1 = \overset{\circ}{x}_\mathfrak{f}(z_1), x_2 = \overset{\circ}{x}_\mathfrak{f}(z_2). \end{cases} \quad (4.43)$$

This curve is the spectral curve of a toric Calabi-Yau whose toric graph has only one vertex, and thus it is $\mathfrak{X} = \mathbb{C}^3$, together with a framing matrix \mathfrak{f} . In other words, the large radius limit of the mirror curve near a vertex σ , is the mirror curve of the toric Calabi-Yau 3-fold $\mathfrak{X} = \mathbb{C}^3$ with framing \mathfrak{f}_σ .

4.5.2 Local spectral curve at a vertex

Now, we can consider the spectral curve on its whole without considering the large radius limit. We define

Definition 4.7 *Let \mathcal{S}_σ be the spectral curve obtained by restriction of the full spectral curve \mathcal{S} , to the vicinity \mathcal{C}_σ of a_σ :*

$$\mathcal{S}_\sigma = (\mathcal{C}_\sigma, x - \overset{\circ}{a}_\sigma, y - \overset{\circ}{b}_\sigma, B_\sigma) \quad (4.44)$$

where x, y are simply the restrictions to \mathcal{C}_σ of x, y on \mathcal{C} , and B_σ is the Bergman kernel of the Riemann sphere \mathbb{P}^1 (remember that \mathcal{C}_σ is a sphere with 3 holes, i.e. $\mathcal{C}_\sigma \subset \mathbb{P}^1$), i.e. it is the same $\overset{\circ}{B}_{\mathfrak{f}_\sigma}$ introduced in def.4.6, shifted by $a_\sigma - \overset{\circ}{a}_\sigma$

$$B(\mathcal{S}_\sigma; x_1, x_2) = B_\sigma(x_1, x_2) = \overset{\circ}{B}_{\mathfrak{f}_\sigma}(x_1 - a_\sigma + \overset{\circ}{a}_\sigma, x_2 - a_\sigma + \overset{\circ}{a}_\sigma). \quad (4.45)$$

By definition, the spectral curve \mathcal{S}_σ has only one branchpoint, located at $x = a_\sigma - \overset{\circ}{a}_\sigma$. Its invariants are computed by theorem 4.1, and can thus be written in terms of integrals of some classes in $\overline{\mathcal{M}}_{g,n}$.

4.6 Large radius limit: the topological vertex

Almost by definition def 4.6, the large radius limit of the spectral curve \mathcal{S}_σ is $\overset{\circ}{\mathcal{S}}_{\mathfrak{f}_\sigma}$:

$$\overset{\circ}{\mathcal{S}}_{\mathfrak{f}} = (\mathbb{P}^1, \overset{\circ}{x}_{\mathfrak{f}}, \overset{\circ}{y}_{\mathfrak{f}}, \overset{\circ}{B}_{\mathfrak{f}}) \quad (4.46)$$

where

$$\begin{cases} \overset{\circ}{x}_{\mathfrak{f}}(z) = -\mathfrak{f}_b \ln z - \mathfrak{f}_a \ln(1-z) + \mathfrak{f}_b \ln \frac{\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b} + \mathfrak{f}_a \ln \frac{\mathfrak{f}_a}{\mathfrak{f}_a + \mathfrak{f}_b} \\ \overset{\circ}{y}_{\mathfrak{f}}(z) = -\mathfrak{f}_d \ln z - \mathfrak{f}_c \ln(1-z) + \mathfrak{f}_d \ln \frac{\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b} + \mathfrak{f}_c \ln \frac{\mathfrak{f}_a}{\mathfrak{f}_a + \mathfrak{f}_b} \\ \overset{\circ}{B}_{\mathfrak{f}}(x_1, x_2) = \frac{dz_1 \otimes dz_2}{(z_1 - z_2)^2} \quad \text{where } x_1 = \overset{\circ}{x}_{\mathfrak{f}}(z_1), x_2 = \overset{\circ}{x}_{\mathfrak{f}}(z_2). \end{cases} \quad (4.47)$$

It has a unique branchpoint ($d\overset{\circ}{x}_{\mathfrak{f}}(z) = 0$) at

$$z = \frac{\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b}. \quad (4.48)$$

Let us then apply theorem 4.1 to $\overset{\circ}{\mathcal{S}}_{\mathfrak{f}}$ (this was done in [14]):

Theorem 4.3 ("Mariño–Vafa formula") *We have:*

$$\begin{aligned} & W_{g,n}(\overset{\circ}{\mathcal{S}}_{\mathfrak{f}}; x_1, \dots, x_n) \\ = & \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f},0}(2-2g-n)}} \sum_{\{d_i\}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_a) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_b) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_a - \mathfrak{f}_b) \prod_{i=1}^n \tau_{d_i} \right\rangle_{g,n} \prod_{i=1}^n d\overset{\circ}{\xi}_{\mathfrak{f},d_i}(x_i) \end{aligned}$$

(4.49)

where

$$e^{-\hat{t}_{\mathfrak{f},0}} = \frac{2\sqrt{2}}{\sqrt{\mathfrak{f}_a \mathfrak{f}_b (\mathfrak{f}_a + \mathfrak{f}_b)}} \quad (4.50)$$

and where, if x lies near the puncture of $\mathbb{P}^1 \setminus \{0, 1, \infty\}$ (i.e. $z = 0, 1$ or ∞) corresponding to the half-edge ϵ , (whose framing is $\mathfrak{f}_\epsilon = \mathfrak{f}_b, \mathfrak{f}_a$ or $-\mathfrak{f}_a - \mathfrak{f}_b$ respectively):

$$\tilde{\xi}_{\mathfrak{f}_\epsilon, d}(x) = (-1)^d \left(\frac{d}{dx} \right)^d \overset{\circ}{\xi}_{\mathfrak{f}_\epsilon, 0}(x) = \sum_k \frac{k^d}{\mathfrak{f}_{\epsilon_i}^{d+1}} \gamma_{\mathfrak{f}}(k/\mathfrak{f}_\epsilon) e^{-\frac{k}{\mathfrak{f}_\epsilon} x}. \quad (4.51)$$

Thus, if x_i lies near the puncture corresponding to the half-edge ϵ_i , (whose framing is $\mathfrak{f}_{\epsilon_i}$):

$$\begin{aligned} & W_{g,n}(\overset{\circ}{\mathcal{S}}_{\mathfrak{f}}; x_1, \dots, x_n) \\ = & \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f},0}(2-2g-n)}} \sum_{\{k_i\}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_a) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_b) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_a - \mathfrak{f}_b) \prod_{i=1}^n \frac{1}{1 - \frac{k_i}{\mathfrak{f}_{\epsilon_i}}} \psi_i \right\rangle_{g,n} \\ & \prod_{i=1}^n \frac{k_i}{\mathfrak{f}_{\epsilon_i}^2} \gamma_{\mathfrak{f}}(k_i/\mathfrak{f}_{\epsilon_i}) e^{-\frac{k_i}{\mathfrak{f}_{\epsilon_i}} x_i} dx_i \end{aligned} \quad (4.52)$$

where the sum carries over positive integers $(k_1, \dots, k_n) \in \mathbb{Z}_+^n$.

proof:

This theorem is a mere application of theorem 4.1, and is fully proved in [14], or alternatively, it can be seen as a consequence of the proof of BKMP for the framed vertex [11, 53]. For completeness, we redo it in appendix E, as an application of theorem 4.1. \square

Remark 4.3 One can recognize that the right hand side of eq. (4.49) is the Mariño–Vafa formula for the topological vertex [41, 39, 38], i.e. the Gromov–Witten invariants of $\mathfrak{X} = \mathbb{C}^3$ with framing matrix \mathfrak{f} , and thus, theorem 4.3 (proved in [14]) can be viewed as another proof of the BKMP conjecture for the topological vertex $\mathfrak{X} = \mathbb{C}^3$ with framing matrix \mathfrak{f} . The first proof of the BKMP conjecture for $\mathfrak{X} = \mathbb{C}^3$, are those of Chen [11] and Zhou [53].

4.7 Invariants of the local spectral curve

We know that in the tropical limit when all $t_j \rightarrow +\infty$, we have $\mathcal{S}_\sigma \rightarrow \overset{\circ}{\mathcal{S}}_{\mathfrak{f}_\sigma}$, and we have expressed the invariants of $\overset{\circ}{\mathcal{S}}_{\mathfrak{f}_\sigma}$ in terms of Hodge classes integrals in $\overline{\mathcal{M}}_{g,n}$. Moreover, it is shown in [18], that the invariants $\omega_{g,n}$ of any spectral curve satisfy ”special geometry relations” (similar to Seiberg–Witten for $\omega_{0,0}$), which allows to compute the derivatives $\partial/\partial t_j$, and thus allow to compute the Taylor expansion of the invariants in a vicinity of the tropical limit. This gives the following lemma:

Lemma 4.1 *If $2 - 2g - n < 0$*

$$\begin{aligned}
& W_{g,n}(\mathcal{S}_\sigma; x_1, \dots, x_n) \\
&= \frac{2^{3g-3+n}}{e^{\hat{t}_{f_\sigma,0}(2-2g-n)}} \sum_{k=0}^{\infty} \frac{1}{k!} \sum_{d_1, \dots, d_{n+k}} \prod_{i=1}^k R_{\sigma, d_{n+i}} \\
&\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \prod_{j=1}^{n+k} \tau_{d_j} \right\rangle_{g,n+k} \prod_{j=1}^n d\tilde{\xi}_{\mathfrak{f}_\sigma, d_j}(x_j) \\
&= \frac{2^{3g-3+n}}{e^{\hat{t}_{f_\sigma,0}(2-2g-n)}} \sum_{d_1, \dots, d_n} \prod_{j=1}^n d\tilde{\xi}_{\mathfrak{f}_\sigma, d_j}(x_j) \\
&\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) e^{l_1^* \sum_d R_{\sigma,d} \tau_d} \prod_{j=1}^n \tau_{d_j} \right\rangle_{g,n}
\end{aligned} \tag{4.53}$$

where

$$R_{\sigma,d} = \frac{-2e^{\hat{t}_{f_\sigma,0}}}{2\pi i} \oint_{\partial \mathcal{C}_\sigma} \tilde{\xi}_{\mathfrak{f}_\sigma, d}(x) (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x)) dx, \tag{4.54}$$

where $\partial \mathcal{C}_\sigma$ is the boundary of \mathcal{C}_σ , i.e. the union of three circles, oriented so that \mathcal{C}_σ lies on the left of $\partial \mathcal{C}_\sigma$. In the second equality, l_1^* denotes the natural inclusion of $\mathcal{M}_{g,n} \subset \mathcal{M}_{g,n+1}$, so that $e^{l_1^* \sum_d R_{\sigma,d} \tau_d}$ is just a short hand notation for the formula above.

And similarly for $(g, n) = (0, 2)$:

$$\begin{aligned}
W_{0,2}(\mathcal{S}_\sigma; x_1, x_2) &= B_\sigma(x_1, x_2) = \mathring{B}_{\mathfrak{f}_\sigma}(x_1 - a_\sigma + \mathring{a}_\sigma, x_2 - a_\sigma + \mathring{a}_\sigma) \\
&= \mathring{B}_{\mathfrak{f}_\sigma}(x_1, x_2) + \frac{1}{2} \sum_{k=1}^{\infty} \frac{1}{k!} \sum_{d_1, \dots, d_{k+2}} d\tilde{\xi}_{\mathfrak{f}_\sigma, d_1}(x_1) d\tilde{\xi}_{\mathfrak{f}_\sigma, d_2}(x_2) \prod_{i=3}^{k+2} R_{\sigma, d_i} \\
&\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \prod_{j=1}^{k+2} \tau_{d_j} \right\rangle_{0,k+2}
\end{aligned} \tag{4.55}$$

and for $(g, n) = (0, 1)$:

$$\begin{aligned}
W_{0,1}(\mathcal{S}_\sigma; x_1) &= (y(x_1 + \mathring{a}_\sigma) - \mathring{b}_\sigma) dx_1 \\
&= \mathring{y}_{\mathfrak{f}_\sigma}(x_1) dx_1 + \frac{1}{2\pi i} \oint_{\partial \mathcal{C}_\sigma} \mathring{B}_{\mathfrak{f}_\sigma}(x_1, x') \Phi(x') \\
&\quad + \frac{e^{-\hat{t}_{f_\sigma,0}}}{4} \sum_{k=2}^{\infty} \frac{1}{k!} \sum_{d_1, \dots, d_{k+1}} d\tilde{\xi}_{\mathfrak{f}_\sigma, d_1}(x_1) \prod_{i=2}^{k+1} R_{\sigma, d_i} \\
&\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \tau_{d_1} \prod_{j=2}^{k+1} \tau_{d_j} \right\rangle_{0,k+1}
\end{aligned} \tag{4.56}$$

proof:

Since the proof is quite technical and long, we do it in appendix F.

Let us just mention that it is proved using the "special geometry" property of the topological recursion. This property says that the derivative of $W_{g,n}$ with respect to a parameter t on which the spectral curve depends, is the integral of $W_{g,n+1}$ on the dual cycle of $\partial y dx / \partial t$. The dual cycle t^* is a cycle such that:

$$\frac{\partial}{\partial t} y(x) dx = \int_{x' \in t^*} B(x, x'). \quad (4.57)$$

The special geometry property of the topological recursion is that:

Theorem 4.4 (Special geometry, proved in [18]) *For any spectral curve we have:*

$$\frac{\partial}{\partial t} W_{g,n}(\mathcal{S}; x_1, \dots, x_n) = \int_{x' \in t^*} W_{g,n+1}(\mathcal{S}; x_1, \dots, x_n, x'). \quad (4.58)$$

The proof of lemma 4.1 uses that property to show that both sides of lemma 4.1 satisfy the same differential equations with respect to the variables t_j 's. Moreover thanks to the large radius limit (tropical limit), the two sides obviously coincide when all $t_j = +\infty$, which concludes the proof.

□

As a corollary of lemma 4.1 as well as the expression of $\overset{\circ}{\xi}(x)$ eq. (4.51), we get:

Corollary 4.1 *Let σ be a vertex of $\Upsilon_{\mathfrak{X}}$, and assume that x_j , $j = 1, \dots, n$ are such that x_j belongs to a cylinder \mathcal{C}_{ϵ_j} where ϵ_j is an half-edge of $\Upsilon_{\mathfrak{X}}$ adjacent to σ , we have for $2 - 2g - n < 0$:*

$$\begin{aligned} & W_{g,n}(\mathcal{S}_{\sigma}; x_1, \dots, x_n) \\ = & \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f}_{\sigma},0}(2-2g-n)}} \sum_{k_1, \dots, k_n} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) e^{l_1^* \sum_d R_{\sigma,d} \tau_d} \right. \\ & \left. \prod_{j=1}^n \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_j / \mathfrak{f}_{\epsilon_j})}{1 - \frac{k_j}{\mathfrak{f}_{\epsilon_j}} \psi_j} \right\rangle_{g,n} \prod_{j=1}^n \frac{k_j}{(\mathfrak{f}_{\epsilon_j})^2} e^{-\frac{k_j}{\mathfrak{f}_{\epsilon_j}} x_j} dx_j, \end{aligned} \quad (4.59)$$

$$\begin{aligned} W_{0,2}(\mathcal{S}_{\sigma}; x_1, x_2) &= B_{\sigma}(x_1, x_2) = \overset{\circ}{B}_{\mathfrak{f}_{\sigma}}(x_1 + \overset{\circ}{a}_{\sigma} - a_{\sigma}, x_2 + \overset{\circ}{a}_{\sigma} - a_{\sigma}) \\ &= \overset{\circ}{B}_{\mathfrak{f}_{\sigma}}(x_1, x_2) + \frac{1}{2} \sum_{k_1, k_2} \sum_{k=1}^{\infty} \frac{1}{k!} \\ &\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \right. \\ &\quad \left. \left(\sum_d R_{\sigma,d} \tau_d \right)^k \prod_{j=1}^2 \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_j / \mathfrak{f}_{\epsilon_j})}{1 - \frac{k_j}{\mathfrak{f}_{\epsilon_j}} \psi_j} \right\rangle_{0,k+2} \end{aligned}$$

$$(4.60) \quad \prod_{j=1}^2 \frac{k_j}{(\mathfrak{f}_{\epsilon_j})^2} e^{-\frac{k_j}{\mathfrak{f}_{\epsilon_j}} x_j} dx_j$$

and

$$(4.61) \quad \begin{aligned} W_{0,1}(\mathcal{S}_\sigma; x_1) &= (y(x_1 + \mathring{a}_\sigma) - \mathring{b}_\sigma) dx_1 \\ &= \mathring{y}_{\mathfrak{f}_\sigma}(x_1) dx_1 + \frac{2}{2\pi i} \oint_{x' \in \partial \mathcal{C}_\sigma} \mathring{B}_{\mathfrak{f}_\sigma}(x_1, x') \Phi(x') + \frac{e^{-\hat{t}_{\mathfrak{f}_\sigma, 0}}}{4} \sum_{k_1} \sum_{k=2}^{\infty} \frac{1}{k!} \\ &\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \right. \\ &\quad \left. \left(\sum_d R_{\sigma,d} \tau_d \right)^k \frac{\gamma_{\mathfrak{f}_\sigma}(k_1/\mathfrak{f}_{\epsilon_1})}{1 - \frac{k_1}{\mathfrak{f}_{\epsilon_1}} \psi_1} \right\rangle_{0,k+1} \frac{k_1}{(\mathfrak{f}_{\epsilon_1})^2} e^{-\frac{k_1}{\mathfrak{f}_{\epsilon_1}} x_1} dx_1. \end{aligned}$$

4.8 Invariants of the mirror curve as graphs

This allows to rewrite theorem 4.2 as:

Corollary 4.2

$$(4.62) \quad \begin{aligned} &W_{g,n}(\mathcal{S}; x_1, \dots, x_n) \\ &= \sum_{G \in \mathcal{G}_{g,n}^{\text{stable}}} \frac{1}{\#\text{Aut}(G)} \prod_{v=\text{vertices}} 2^{3g_v-3+n_v} e^{\hat{t}_{\sigma_v, 0}(2g_v-2+n_v)} \\ &\quad \left(\int_{\overline{\mathcal{M}}_{g_v, n_v}} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma_v}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma_v}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma_v} - \mathfrak{f}_{b,\sigma_v}) e^{l_1^* \sum_d R_{\sigma_v, d} \tau_d} \prod_{h \in E_v} \tau_{d_h} \right) \\ &\quad \prod_{(h_+, h_-) = \text{closed edges}} \hat{E}_{\sigma_v(h_+), d_{h_+}; \sigma_v(h_-), d_{h_-}} \\ &\quad \prod_{j=1, h_j = \text{open half-edges}}^n \frac{-1}{2\pi i} \oint_{x'_j \in \partial \mathcal{C}_{\sigma_v(h_j)}} \tilde{\xi}_{\sigma_v(h_j), d_{h_j}}(x'_j - \mathring{a}_{\sigma_v(h_j)}) B(\mathcal{S}; x'_j, x_j) \end{aligned}$$

where the sum is only over stable graphs (every vertex v is such that $2 - 2g_v - n_v < 0$), and where

$$(4.63) \quad \begin{aligned} \hat{E}_{\sigma, d; \sigma', d'} &= \frac{1}{(2\pi i)^2} \oint_{x \in \partial \mathcal{C}_\sigma} \oint_{x' \in \partial \mathcal{C}_{\sigma'}} \tilde{\xi}_{\sigma, d}(x - \mathring{a}_\sigma) \left(B(\mathcal{S}; x, x') \right. \\ &\quad \left. - \delta_{\sigma, \sigma'} B(\mathcal{S}; x - \mathring{a}_\sigma, x' - \mathring{a}_{\sigma'}) \right) \tilde{\xi}_{\sigma', d'}(x' - \mathring{a}_{\sigma'}). \end{aligned}$$

If x_j lies on a cylinder \mathcal{C}_{ϵ_j} where ϵ_j is any half-edge (not necessarily corresponding the non-compact half-edge of $\Upsilon_{\mathfrak{X}}$ where the special Lagrangian brane L is ending), we have the expansion

$$(4.64) \quad \tilde{\xi}_{\sigma(\epsilon_j), d}(x_j) = - \sum_{k=1}^{\infty} \frac{\gamma_{\mathfrak{f}_{\sigma(\epsilon_j)}}(k/\mathfrak{f}_{\epsilon_j})}{\mathfrak{f}_{\epsilon_j}} e^{-\frac{k}{\mathfrak{f}_{\epsilon_j}} x_j} \frac{k^d}{(\mathfrak{f}_{\epsilon_j})^d}.$$

Using this expansion of $\tilde{\xi}$, we easily arrive at:

Theorem 4.5 *If $x_j \in \mathcal{C}_{\epsilon_j}$ where ϵ_j is an half edge of $\Upsilon_{\mathfrak{X}}$ (not necessarily corresponding to a non-compact edge, neither the one on which the brane L ends), we have*

$$\begin{aligned}
& W_{g,n}(\mathcal{S}; x_1, \dots, x_n) \\
&= \sum_{G \in \mathcal{G}_{g,n}^{\text{stable}}} \frac{1}{\#\text{Aut}(G)} \prod_{v=\text{vertices}} \tilde{\mathcal{H}}_{g_v, n_v, \sigma_v}(\{d_h/\mathfrak{f}_{\epsilon_h}\}_{h \in E_v}) \\
& \quad \prod_{e=(h_+, h_-)=\text{closed edges}} \tilde{\mathcal{F}}_{\epsilon_{h_+}, d_{h_+}; \epsilon_{h_-}, d_{h_-}} \prod_{j=1, h_j=\text{open half-edges}}^n d\tilde{J}_{\epsilon_{h_j}, d_{h_j}}(x_j)
\end{aligned} \tag{4.65}$$

where the sum is only over stable graphs (every vertex v is such that $2 - 2g_v - n_v < 0$), and where

$$\begin{aligned}
\tilde{\mathcal{H}}_{g,n,\sigma}(k_1, \dots, k_n) &= \frac{2^{3g-3+n}}{e^{-\hat{t}_{\sigma,0}(2g-2+n)}} \int_{\mathcal{M}_{g,n}} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \\
& \quad e^{l_1^* \sum_d R_{\sigma,d} \tau_d} \prod_{i=1}^n \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_i)}{1 - k_i \psi_i},
\end{aligned} \tag{4.66}$$

$$\begin{aligned}
\tilde{\mathcal{F}}_{\epsilon, d; \epsilon', d'} &= \frac{1}{\mathfrak{f}_{\epsilon} \mathfrak{f}_{\epsilon'} (2\pi i)^2} \oint_{x \in \partial_{\epsilon} \mathcal{C}_{\sigma(\epsilon)}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{-\frac{d}{\mathfrak{f}_{\epsilon}} (x - \mathring{a}_{\sigma(\epsilon)})} \left(B(\mathcal{S}; x, x') \right. \\
& \quad \left. - \delta_{\sigma(\epsilon), \sigma(\epsilon')} B(\mathcal{S}_{\sigma(\epsilon)}; x - \mathring{a}_{\sigma(\epsilon)}, x' - \mathring{a}_{\sigma(\epsilon')}) \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} (x' - \mathring{a}_{\sigma(\epsilon')})}
\end{aligned} \tag{4.67}$$

and

$$d\tilde{J}_{\epsilon, d}(x) = \frac{1}{\mathfrak{f}_{\epsilon} 2\pi i} \oint_{x' \in \partial_{\epsilon} \mathcal{C}_{\sigma(\epsilon)}} e^{-\frac{d}{\mathfrak{f}_{\epsilon}} x'} B(\mathcal{S}; x' + \mathring{a}_{\sigma(\epsilon)}, x). \tag{4.68}$$

4.9 Weight of edges

In the graph sum, the weight of edges is given by formula eq. (4.67), it involves the double Fourier transform of the Bergman kernel.

4.9.1 More geometry: the Bergman kernel

Recall that the curve \mathcal{C} is a union of cylinders $\mathcal{C}_{\sigma, \sigma'}$ and of pairs of pants \mathcal{C}_{σ} , cf fig.7 and fig 12.

The following lemma allows to express the Bergman kernel of the full curve \mathcal{C} in terms of Bergman kernels of its pieces \mathcal{C}_{σ} and $\mathcal{C}_{\sigma, \sigma'}$. Recall that we write (for any curve \mathcal{S}) that the Bergman kernel is the double derivative of the log of the prime form E :

$$B(\mathcal{S}; x_1, x_2) = d_{x_1} \otimes d_{x_2} \ln E(\mathcal{S}; x_1, x_2). \tag{4.69}$$

We have:

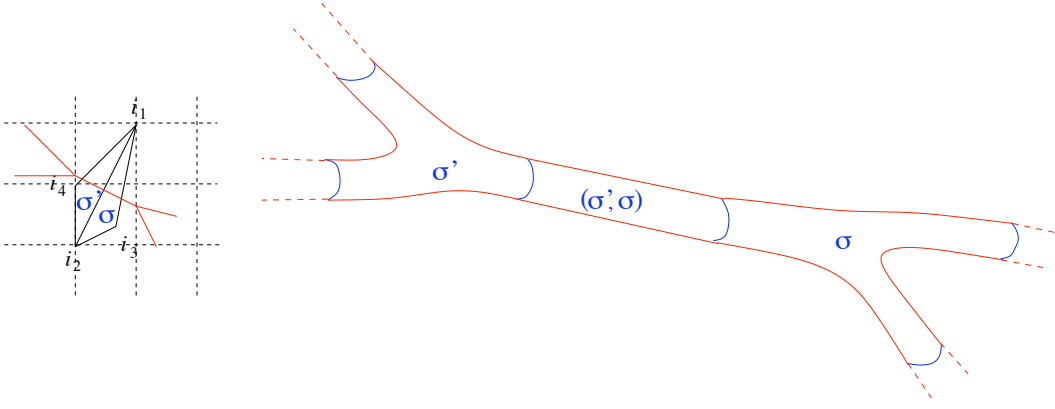


Figure 12: The curve \mathcal{C} is a union of cylinders $\mathcal{C}_{\sigma, \sigma'}$ corresponding to edges of the toric graph $\Upsilon_{\mathfrak{X}}$ and of pairs of pants \mathcal{C}_{σ} corresponding to vertices of $\Upsilon_{\mathfrak{X}}$. Its Bergman kernel can be obtained as a combination of the Bergman kernels of each pieces. Notice that the framing of the edge σ, σ' is $\mathfrak{f}_{\sigma, \sigma'} = -\mathfrak{f}_{\sigma', \sigma} = \mathfrak{f}_{b, \sigma'} = -\mathfrak{f}_{b, \sigma} = \beta_{i_2} - \beta_{i_1}$.

Lemma 4.2 *Let σ, σ' be two vertices. Let $x \in \mathcal{C}_{\sigma}$ and $x' \in \mathcal{C}_{\sigma'}$, then we have*

$$\begin{aligned}
& \ln E(\mathcal{S}; \mathring{a}_{\sigma} + x, \mathring{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} \ln E(\mathcal{S}_{\sigma}; x, x') \\
= & \frac{1}{(2\pi i)^2} \oint_{x_2 \in \partial_{\sigma} \mathcal{C}_{\sigma'}} \oint_{x_1 \in \partial_{\sigma'} \mathcal{C}_{\sigma}} \ln E(\mathcal{S}_{\sigma}; x, x_1) \times \\
& \times B(\mathcal{S}_{\sigma, \sigma'}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_{\sigma}) \ln E(\mathcal{S}_{\sigma'}; x_2, x') \\
& + \sum_{\sigma_1} \frac{1}{(2\pi i)^2} \oint_{x_2 \in \partial_{\sigma} \mathcal{C}_{\sigma_1}} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_{\sigma}} \ln E(\mathcal{S}_{\sigma}; x, x_1) B(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_{\sigma}) \\
& \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma'} + x') - \delta_{\sigma_1, \sigma'} \ln E(\mathcal{S}_{\sigma'}; x_2, x') \right)
\end{aligned} \tag{4.70}$$

where

$$B(\mathcal{S}_{\sigma, \sigma'}; x_1, x_2) = A_{\sigma, \sigma'} \frac{1}{(\mathfrak{f}_{\sigma, \sigma'})^2} \frac{e^{-\frac{x_1}{\mathfrak{f}_{\sigma, \sigma'}}} e^{-\frac{x_2}{\mathfrak{f}_{\sigma, \sigma'}}}}{\left(e^{-\frac{x_1}{\mathfrak{f}_{\sigma, \sigma'}}} - e^{-\frac{x_2}{\mathfrak{f}_{\sigma, \sigma'}}} \right)^2} dx_1 \otimes dx_2 \tag{4.71}$$

is the Bergman kernel on the cylinder $\mathcal{C}_{\sigma, \sigma'}$, $A_{\sigma, \sigma'}$ is the adjacency matrix of the toric graph, i.e. $A_{\sigma, \sigma'} = 1$ if σ and σ' are neighbors and 0 otherwise, and $\mathfrak{f}_{\sigma, \sigma'}$ is the framing of the edge (σ, σ') as defined in def 2.5.

This lemma is illustrated in fig. 13.

proof:

This lemma is proved in appendix C. The proof is only complex analysis on \mathcal{C} , it consists in writing Cauchy residue formula and moving the integration contours. \square

$$B(x, x') = \delta_{\sigma\sigma'} B_{\text{pant}}(x, x') + B_{\text{cylinder}} \cdot B_{\text{total}}$$

Figure 13: Lemma 4.2 shows that the Bergman kernel of the full curve \mathcal{C} , can be constructed by combining Bergman kernels of the pairs of pants \mathcal{C}_σ and Bergman kernels of cylinders $\mathcal{C}_{\sigma,\sigma'}$. In some sense $B_{\text{total}} = B_{\text{pant}} + B_{\text{pant}} B_{\text{cylinder}} B_{\text{total}}$.

4.9.2 Renormalizing edges

Now, it remains to compute the weights eq. (4.67) attached to edges of the graph decomposition of $W_{g,n}(\mathcal{S})$ through corollary 4.2, i.e. the integrals

$$\begin{aligned} \tilde{\mathcal{F}}_{\epsilon,d;\epsilon',d'} &= \frac{1}{\mathfrak{f}_\epsilon \mathfrak{f}_{\epsilon'} (2\pi i)^2} \oint_{x \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{-\frac{d}{\mathfrak{f}_\epsilon} x} \left(B(\mathcal{S}; x + \mathring{a}_{\sigma(\epsilon)}, x' + \mathring{a}_{\sigma(\epsilon')}) \right. \\ &\quad \left. - \delta_{\sigma(\epsilon), \sigma(\epsilon')} B(\mathcal{S}_{\sigma(\epsilon)}; x, x') \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'}. \end{aligned} \quad (4.72)$$

From lemma 4.2 above, we prove that:

Proposition 4.1 *The edge weight $\tilde{F}_{\epsilon,d;\epsilon',d'}$ satisfies:*

$$\tilde{\mathcal{F}}_{\epsilon,d;\epsilon',d'} = \mathcal{F}_{\epsilon,d;\epsilon',d'} + \sum_{\epsilon_1, d_1} \sum_{\epsilon_2, d_2} \mathcal{F}_{\epsilon,d;\epsilon_1, d_1} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon_1)}(d_1/\mathfrak{f}_{\epsilon_1}; d_2/\mathfrak{f}_{\epsilon_2}) \tilde{\mathcal{F}}_{\epsilon_2, d_2; \epsilon', d'} \quad (4.73)$$

where

$$\mathcal{F}_{\epsilon,d;\epsilon',d'} = \frac{d}{\mathfrak{f}_\epsilon^2} e^{-\frac{d}{\mathfrak{f}_\epsilon} (\mathring{a}_{\sigma(\epsilon')} - \mathring{a}_{\sigma(\epsilon)})} A_{\epsilon, \epsilon'} \delta_{d, d'} \quad (4.74)$$

and

$$\begin{aligned} \tilde{\mathcal{H}}_{0,2,\sigma}(k; k') &= \mathcal{H}_{0,2,\sigma}(k; k') \\ &\quad + \frac{1}{2} \sum_{n=1}^{\infty} \frac{1}{n!} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \right. \\ &\quad \left. \left(\sum_d R_{\sigma,d} \tau_d \right)^n \frac{\gamma_{\mathfrak{f}_\sigma}(k)}{1-k\psi} \frac{\gamma_{\mathfrak{f}_{\sigma'}}(k')}{1-k'\psi'} \right\rangle_{0,n+2} \end{aligned} \quad (4.75)$$

and

$$\mathcal{H}_{0,2,\sigma}(k; k') = \frac{1}{k+k'} \gamma_{\mathfrak{f}_\sigma}(k) \gamma_{\mathfrak{f}_{\sigma'}}(k'). \quad (4.76)$$

This lemma means that:

$$\tilde{\mathcal{F}} = \mathcal{F} + \mathcal{F} \tilde{\mathcal{H}}_{0,2} \mathcal{F} + \mathcal{F} \tilde{\mathcal{H}}_{0,2} \mathcal{F} \tilde{\mathcal{H}}_{0,2} \mathcal{F} + \mathcal{F} \tilde{\mathcal{H}}_{0,2} \mathcal{F} \tilde{\mathcal{H}}_{0,2} \mathcal{F} \tilde{\mathcal{H}}_{0,2} \mathcal{F} + \dots \quad (4.77)$$

which is illustrated as:

$$\text{---} = \text{---} + \text{---} \bullet \text{---} + \text{---} \bullet \text{---} \bullet \text{---} + \dots$$

i.e. $\mathcal{H}_{0,2,\sigma}$ can be viewed as the $(0,2)$ vertex, and \mathcal{F} as an edge weight.

proof:

From lemma 4.2 in appendix C, we see that we first have to compute:

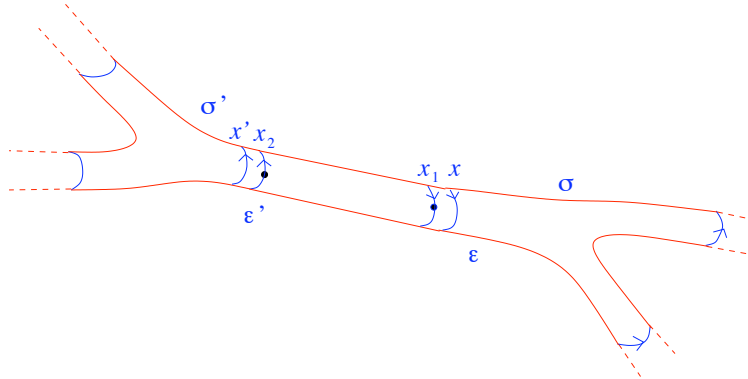
$$\begin{aligned} \mathcal{F}_{\epsilon,d;\epsilon',d'} &= \frac{1}{\mathfrak{f}_\epsilon \mathfrak{f}_{\epsilon'} (2\pi i)^4} \oint_{x_1 \in \partial_{\sigma(\epsilon')} \mathcal{C}_{\sigma(\epsilon)}} \oint_{x \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x_2 \in \partial_{\sigma(\epsilon)} \mathcal{C}_{\sigma(\epsilon')}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d}{\mathfrak{f}_\epsilon} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx dx' \\ &\quad e^{-\frac{d}{\mathfrak{f}_\epsilon} x} \ln E(\mathcal{S}_{\sigma(\epsilon)}; x, x_1) B(\mathcal{S}_{(\sigma(\epsilon), \sigma(\epsilon'))}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma) \\ &\quad \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_2, x') e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} \end{aligned} \quad (4.78)$$

which is non-vanishing only if $\sigma(\epsilon)$ and $\sigma(\epsilon')$ are adjacent vertices in $\Upsilon_{\mathfrak{x}}$.

Moreover, if ϵ (resp. ϵ') is not the half-edge linking $\sigma(\epsilon)$ to $\sigma(\epsilon')$ (resp. $\sigma(\epsilon')$ to $\sigma(\epsilon)$), we may push the integration contour for x (resp. x') towards the puncture of $\mathcal{C}_{\sigma(\epsilon)}$ (resp. $\mathcal{C}_{\sigma(\epsilon')}$) in the direction of the half-edge ϵ (resp. ϵ') without meeting any singularity, and thus the result vanishes. $\mathcal{F}_{\epsilon,d;\epsilon',d'}$ is thus proportional to the adjacency matrix $A_{\epsilon,\epsilon'}$ which is 1 if the half-edges ϵ and ϵ' form an edge of $\Upsilon_{\mathfrak{x}}$, and 0 otherwise:

$$\begin{aligned} \mathcal{F}_{\epsilon,d;\epsilon',d'} &= \frac{A_{\epsilon,\epsilon'}}{\mathfrak{f}_\epsilon \mathfrak{f}_{\epsilon'} (2\pi i)^4} \oint_{x_1 \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x_2 \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d}{\mathfrak{f}_\epsilon} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx dx' \\ &\quad e^{-\frac{d}{\mathfrak{f}_\epsilon} x} \ln E(\mathcal{S}_{\sigma(\epsilon)}; x, x_1) B(\mathcal{S}_{(\sigma(\epsilon), \sigma(\epsilon'))}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma) \\ &\quad \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_2, x') e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'}. \end{aligned} \quad (4.79)$$

So, from now on, we assume that (ϵ, ϵ') is the edge linking $\sigma(\epsilon)$ to $\sigma(\epsilon')$.



We can push the integration contour of x through that of x_1 and send it to the puncture of $\mathcal{C}_{\sigma(\epsilon)}$ where it vanishes, we only pick a residue at $x = x_1$, and similarly for x' and x_2 , and we get:

$$\mathcal{F}_{\epsilon,d;\epsilon',d'} = \frac{A_{\epsilon,\epsilon'}}{\mathfrak{f}_\epsilon \mathfrak{f}_{\epsilon'} (2\pi i)^2} \oint_{x_1 \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x_2 \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d}{\mathfrak{f}_\epsilon} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx dx'$$

$$e^{-\frac{d}{f_\epsilon} x_1} B(\mathcal{S}_{(\epsilon, \epsilon')}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma) e^{-\frac{d'}{f_{\epsilon'}} x_2}. \quad (4.80)$$

Similarly, on the cylinder $\mathcal{C}_{(\epsilon, \epsilon')}$, we can push the integration contour of x_1 through that of x_2 and send it to the puncture where it vanishes, we only pick a residue at $x_1 = x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma$, and we get:

$$\mathcal{F}_{\epsilon, d; \epsilon', d'} = \frac{d}{f_\epsilon} \frac{A_{\epsilon, \epsilon'}}{f_\epsilon f_{\epsilon'} 2\pi i} \oint_{x_2 \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{-\frac{d}{f_\epsilon} (x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma)} e^{-\frac{d'}{f_{\epsilon'}} x_2} dx_2. \quad (4.81)$$

Then, notice that if $A_{\epsilon, \epsilon'} \neq 0$, this means that (ϵ, ϵ') is an edge of the toric graph and thus $f_{\epsilon'} = -f_\epsilon$. Consider the variable $z = e^{-x_2/f_\epsilon} = e^{x_2/f_{\epsilon'}}$, we thus have

$$\begin{aligned} \mathcal{F}_{\epsilon, d; \epsilon', d'} &= \frac{-d}{f_\epsilon^3} e^{-\frac{d}{f_\epsilon} (\mathring{a}_{\sigma'} - \mathring{a}_\sigma)} \frac{A_{\epsilon, \epsilon'}}{2\pi i} \oint_{x_2 \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{-\frac{d-d'}{f_\epsilon} x_2} dx_2 \\ &= \frac{d}{f_\epsilon^3} e^{-\frac{d}{f_\epsilon} (\mathring{a}_{\sigma'} - \mathring{a}_\sigma)} A_{\epsilon, \epsilon'} \operatorname{Res}_{z \rightarrow 0} z^{d-d'} f_\epsilon \frac{dz}{z} \\ &= \frac{d}{f_\epsilon^2} e^{-\frac{d}{f_\epsilon} (\mathring{a}_{\sigma'} - \mathring{a}_\sigma)} A_{\epsilon, \epsilon'} \delta_{d, d'}. \end{aligned} \quad (4.82)$$

Then, using lemma 4.2, we have:

$$\begin{aligned} &\tilde{\mathcal{F}}_{\epsilon, d; \epsilon', d'} - \mathcal{F}_{\epsilon, d; \epsilon', d'} \\ &= \frac{1}{f_\epsilon f_{\epsilon'} (2\pi i)^4} \sum_{\sigma_1} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_{\sigma(\epsilon)}} \oint_{x \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x_2 \in \partial_{\sigma(\epsilon)} \mathcal{C}_{\sigma_1}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d}{f_\epsilon} \frac{d'}{f_{\epsilon'}} dx dx' \\ &\quad e^{-\frac{d}{f_\epsilon} x} \ln E(\mathcal{S}_{\sigma(\epsilon)}; x, x_1) B(\mathcal{S}_{(\sigma(\epsilon), \sigma_1)}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_{\sigma(\epsilon)}) \\ &\quad \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma(\epsilon')} + x') - \delta_{\sigma_1, \sigma(\epsilon')} \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_2, x') \right) e^{-\frac{d'}{f_{\epsilon'}} x'} \end{aligned} \quad (4.83)$$

where the sum vanishes if σ_1 is not a neighbor of $\sigma(\epsilon)$.

Again, if ϵ is not the half-edge linking $\sigma(\epsilon)$ to σ_1 , we can push the integration contour of x towards the puncture of $\mathcal{C}_{\sigma(\epsilon)}$ without meeting any singularity and the result vanishes. In other words, σ_1 has to be chosen as the vertex on the other side of the half-edge ϵ .

We can then push the integration contour of x through that of x_1 and send it to the puncture of $\mathcal{C}_{\sigma(\epsilon)}$ where it vanishes, we only pick a residue at $x = x_1$

$$\begin{aligned} &\tilde{\mathcal{F}}_{\epsilon, d; \epsilon', d'} - \mathcal{F}_{\epsilon, d; \epsilon', d'} \\ &= \frac{1}{f_\epsilon f_{\epsilon'} (2\pi i)^3} \oint_{x_1 \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x_2 \in \partial_{\sigma(\epsilon)} \mathcal{C}_{\sigma_1}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d'}{f_{\epsilon'}} dx' \\ &\quad e^{-\frac{d}{f_\epsilon} x_1} B(\mathcal{S}_{(\sigma(\epsilon), \sigma_1)}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_{\sigma(\epsilon)}) \end{aligned}$$

$$(4.84) \quad \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma(\epsilon')} + x') - \delta_{\sigma_1, \sigma(\epsilon')} \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_2, x') \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'}$$

then we can push the integration contour of x_1 through that of x_2 and send it to the puncture where it vanishes, we only pick a residue at $x_1 = x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_{\sigma(\epsilon)}$

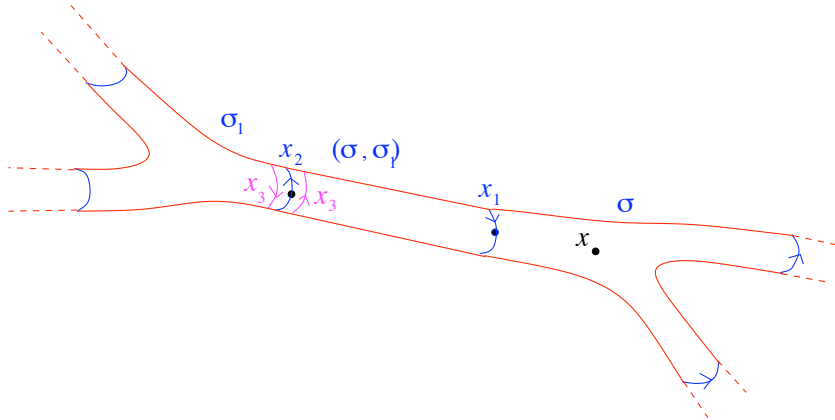
$$(4.85) \quad \begin{aligned} & \tilde{\mathcal{F}}_{\epsilon, d; \epsilon', d'} - \mathcal{F}_{\epsilon, d; \epsilon', d'} \\ &= \frac{1}{\mathfrak{f}_{\epsilon} \mathfrak{f}_{\epsilon'} (2\pi i)^2} \oint_{x_2 \in \partial_{\sigma(\epsilon)} \mathcal{C}_{\sigma_1}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d}{\mathfrak{f}_{\epsilon}} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx_2 dx' e^{-\frac{d}{\mathfrak{f}_{\epsilon}} (x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_{\sigma(\epsilon)})} \\ & \quad \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma(\epsilon')} + x') - \delta_{\sigma_1, \sigma(\epsilon')} \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_2, x') \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} \\ &= \sum_{\epsilon_1, d_1} F_{\epsilon, d; \epsilon_1, d_1} \frac{1}{\mathfrak{f}_{\epsilon'} (2\pi i)^2} \oint_{x_2 \in \partial_{\epsilon_1} \mathcal{C}_{\sigma(\epsilon_1)}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx_2 dx' e^{\frac{d_1}{\mathfrak{f}_{\epsilon_1}} x_2} \\ & \quad \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma(\epsilon_1)} + x_2, \mathring{a}_{\sigma(\epsilon')} + x') - \delta_{\sigma(\epsilon_1), \sigma(\epsilon')} \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_2, x') \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} \end{aligned}$$

where we have used that $\mathcal{F}_{\epsilon, d; \epsilon_1, d_1}$ is non-vanishing only if ϵ_1 is the half edge linking σ_1 to $\sigma(\epsilon)$, and thus $\mathfrak{f}_{\epsilon_1} = -\mathfrak{f}_{\epsilon}$. One would be tempted to identify this last integral with $\tilde{\mathcal{F}}_{\epsilon_1, -d_1; \epsilon', d'}$, but it is not possible because of the wrong sign of d_1 in the exponential.

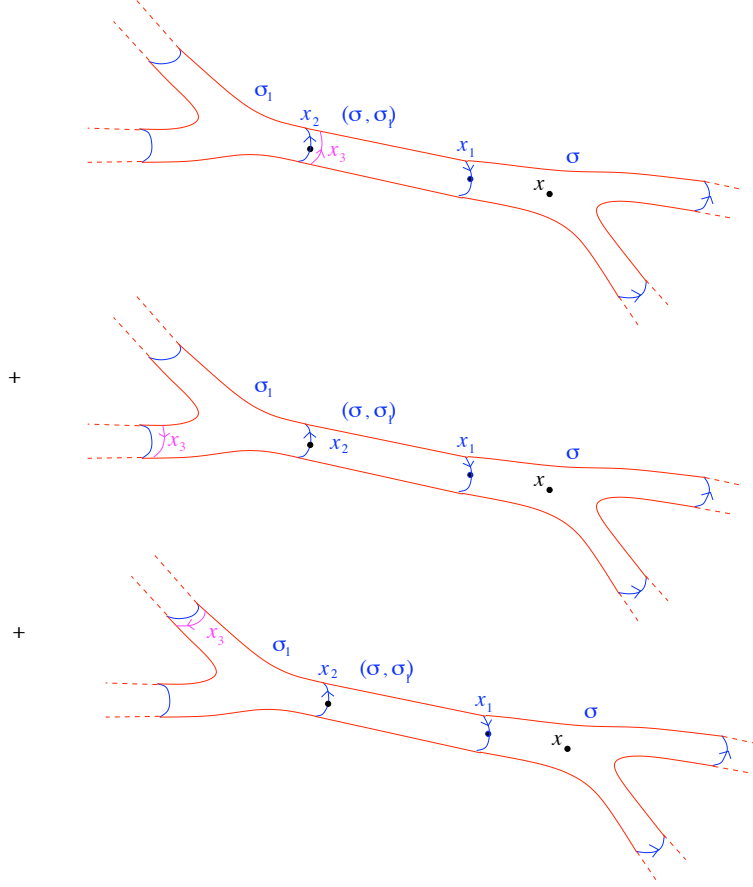
Instead, we insert another integral:

$$(4.86) \quad \begin{aligned} & \tilde{\mathcal{F}}_{\epsilon, d; \epsilon', d'} - \mathcal{F}_{\epsilon, d; \epsilon', d'} \\ &= - \sum_{\epsilon_1, d_1} F_{\epsilon, d; \epsilon_1, d_1} \frac{\mathfrak{f}_{\epsilon_1}}{d_1 \mathfrak{f}_{\epsilon'} (2\pi i)^2} \oint_{x_2 \in \partial_{\epsilon_1} \mathcal{C}_{\sigma(\epsilon_1)}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \text{Res}_{x_3 \rightarrow x_2} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx' \\ & \quad e^{\frac{d_1}{\mathfrak{f}_{\epsilon_1}} x_2} B(\mathcal{S}_{\sigma(\epsilon_1)}; x_2, x_3) \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma(\epsilon_1)} + x_3, \mathring{a}_{\sigma(\epsilon')} + x') \right. \\ & \quad \left. - \delta_{\sigma(\epsilon_1), \sigma(\epsilon')} \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_3, x') \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} \end{aligned}$$

and we deform the integration contour of x_3 (i.e. a small circle around x_2) into a pair of circles around the cylinder, one on each side of the integration contour of x_2 .



Then, we push the x_3 circle which is inside \mathcal{C}_{σ_1} through the pair of pants, and thus we deform the integration contour for x_3 into $\partial\mathcal{C}_{\sigma_1}$:



Eventually we have

$$\begin{aligned}
& \tilde{\mathcal{F}}_{\epsilon, d; \epsilon', d'} - \mathcal{F}_{\epsilon, d; \epsilon', d'} \\
= & - \sum_{\epsilon_1, d_1} F_{\epsilon, d; \epsilon_1, d_1} \sum_{\epsilon''} \frac{\mathfrak{f}_{\epsilon_1}}{d_1 \mathfrak{f}_{\epsilon'} (2\pi i)^3} \oint_{x_3 \in \partial_{\epsilon''} \mathcal{C}_{\sigma(\epsilon_1)}} \oint_{x_2 \in \partial_{\epsilon_1} \mathcal{C}_{\sigma(\epsilon_1)}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \frac{d'}{\mathfrak{f}_{\epsilon'}} dx' \\
& e^{\frac{d_1}{\mathfrak{f}_{\epsilon_1}} x_2} B(\mathcal{S}_{\sigma(\epsilon_1)}; x_2, x_3) \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma(\epsilon_1)} + x_3, \mathring{a}_{\sigma(\epsilon')} + x') \right. \\
& \left. - \delta_{\sigma(\epsilon_1), \sigma(\epsilon')} \ln E(\mathcal{S}_{\sigma(\epsilon')}; x_3, x') \right) e^{-\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} \\
(4.87)
\end{aligned}$$

where $\sum_{\epsilon''}$ means the sum over the 3 boundaries of \mathcal{C}_{σ_1} , and where x_2 is integrated in the interior of \mathcal{C}_{σ_1} .

Then, notice that the following integral (whose integration contour leaves x_3 near one of the punctures):

$$\oint_{x_2 \in \partial_{\epsilon_1} \mathcal{C}_{\sigma(\epsilon_1)}} e^{\frac{d_1}{\mathfrak{f}_{\epsilon_1}} x_2} B(\mathcal{S}_{\sigma(\epsilon_1)}; x_2, x_3) \quad (4.88)$$

is an analytic function of $e^{-x_3/\mathfrak{f}_{\epsilon''}}$ when x_3 approaches the puncture ϵ'' . Therefore we may expand it as:

$$\begin{aligned} & -\frac{\mathfrak{f}_{\epsilon_1} \mathfrak{f}_{\epsilon''}}{d_1} \frac{1}{2i\pi} \oint_{x_2 \in \partial_{\epsilon_1} \mathcal{C}_{\sigma(\epsilon_1)}} e^{\frac{d_1}{\mathfrak{f}_{\epsilon_1}} x_2} B(\mathcal{S}_{\sigma(\epsilon_1)}; x_2, x_3) \\ & \sim \sum_{d''=0}^{\infty} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon_1)}(d_1/\mathfrak{f}_{\epsilon_1}; d''/\mathfrak{f}_{\epsilon''}) e^{-\frac{d''}{\mathfrak{f}_{\epsilon''}} x_3} \frac{d''}{\mathfrak{f}_{\epsilon''}} dx_3, \end{aligned} \quad (4.89)$$

whose coefficients $\tilde{\mathcal{H}}_{0,2,\sigma}(d/\mathfrak{f}_{\epsilon}; d'/\mathfrak{f}_{\epsilon'})$ can be determined by computing a residue at the puncture ϵ' , i.e. a contour integral around $\partial_{\epsilon'} \mathcal{C}_{\sigma}$:

$$\tilde{\mathcal{H}}_{0,2,\sigma}(d/\mathfrak{f}_{\epsilon}; d'/\mathfrak{f}_{\epsilon'}) = -\frac{\mathfrak{f}_{\epsilon} \mathfrak{f}_{\epsilon'}}{d d'} \frac{1}{(2i\pi)^2} \oint_{x \in \partial_{\epsilon} \mathcal{C}_{\sigma}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma}} e^{\frac{d}{\mathfrak{f}_{\epsilon}} x} B(\mathcal{S}_{\sigma}; x, x') e^{\frac{d'}{\mathfrak{f}_{\epsilon'}} x'}. \quad (4.90)$$

According to corollary 4.1, we have

$$\begin{aligned} -\tilde{\mathcal{H}}_{0,2,\sigma}(k; k') &= \mathcal{H}_{0,2,\sigma}(k; k') \\ &+ \frac{1}{2} \sum_{n=1}^{\infty} \frac{1}{n!} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \right. \\ &\quad \left. \left(\sum_d R_{\sigma,d} \tau_d \right)^n \frac{\gamma_{\mathfrak{f}_{\sigma}}(k)}{1-k\psi} \frac{\gamma_{\mathfrak{f}_{\sigma'}}(k')}{1-k'\psi'} \right\rangle_{0,n+2} \end{aligned} \quad (4.91)$$

where

$$\mathcal{H}_{0,2,\sigma}(d/\mathfrak{f}_{\epsilon}; d'/\mathfrak{f}_{\epsilon'}) = \frac{\mathfrak{f}_{\epsilon} \mathfrak{f}_{\epsilon'}}{d d'} \frac{1}{(2i\pi)^2} \oint_{x \in \partial_{\epsilon} \mathcal{C}_{\sigma}} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma}} e^{\frac{d}{\mathfrak{f}_{\epsilon}} x} \mathring{B}_{\mathfrak{f}_{\sigma}}(x, x') e^{\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} \quad (4.92)$$

can be computed explicitly:

$$\mathcal{H}_{0,2,\sigma}(k; k') = \frac{1}{k+k'} \gamma_{\mathfrak{f}_{\sigma}}(k) \gamma_{\mathfrak{f}_{\sigma}}(k') \quad (4.93)$$

and can be included into the sum by formally writing:

$$\left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \frac{1}{1-k\psi} \frac{1}{1-k'\psi'} \right\rangle_{0,2} = \frac{2}{k+k'}. \quad (4.94)$$

Finally we have:

$$\tilde{\mathcal{F}}_{\epsilon,d;\epsilon',d'} = \mathcal{F}_{\epsilon,d;\epsilon',d'} + \sum_{\epsilon_1,d_1} \sum_{\epsilon_2,d_2} \mathcal{F}_{\epsilon,d;\epsilon_1,d_1} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon_1)}(\epsilon_1, d_1; \epsilon_2, d_2) \tilde{\mathcal{F}}_{\epsilon_2,d_2;\epsilon',d'} \quad (4.95)$$

which proves the proposition. \square

4.9.3 External legs

Then, we need to compute the weight of external legs given by eq. (4.68):

Proposition 4.2 *If $x \in \mathcal{C}_{\epsilon_i}$ is on an open edge, we have*

$$d\tilde{J}_{\epsilon,d}(x) = dJ_{\epsilon,d}(x) + \sum_{\epsilon',d',\epsilon'',d''} \mathcal{F}_{\epsilon,d;\epsilon',d'} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon')}(d'/\mathfrak{f}_{\epsilon'}; d''/\mathfrak{f}_{\epsilon''}) d\tilde{J}_{\epsilon'',d''}(x) \quad (4.96)$$

where

$$dJ_{\epsilon,d}(x) = \delta_{\epsilon,\epsilon_i} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(x-\mathring{a}_{\sigma(\epsilon)})} \frac{d}{\mathfrak{f}_{\epsilon}^2} dx. \quad (4.97)$$

proof:

Assume that $x \in \mathcal{C}_{\epsilon_i}$. We have from eq. (4.68)

$$d\tilde{J}_{\epsilon,d}(x) = \frac{1}{\mathfrak{f}_{\epsilon}} \frac{1}{2\pi i} \oint_{x' \in \partial_{\epsilon} \mathcal{C}_{\sigma(\epsilon)}} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(x'-\mathring{a}_{\sigma(\epsilon)})} B(\mathcal{S}; x', x). \quad (4.98)$$

Let ϵ' be the other side of the edge of ϵ (i.e. such that $A_{\epsilon,\epsilon'} = 1$, and then we have $\mathfrak{f}_{\epsilon'} = -\mathfrak{f}_{\epsilon}$). Let us move the integration contour to the other end of the cylinder, by doing so, we may pick a residue at $x = x'$ in the case where x' lies on the cylinder. We thus have

$$\begin{aligned} d\tilde{J}_{\epsilon,d}(x) &= \delta_{\epsilon,\epsilon_i} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(x-\mathring{a}_{\sigma(\epsilon)})} \frac{d}{\mathfrak{f}_{\epsilon}^2} dx \\ &+ \sum_{\epsilon'} \frac{A_{\epsilon,\epsilon'}}{\mathfrak{f}_{\epsilon'}} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(\mathring{a}_{\sigma(\epsilon')} - \mathring{a}_{\sigma(\epsilon)})} \frac{1}{2\pi i} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{+\frac{d}{\mathfrak{f}_{\epsilon'}}(x'-\mathring{a}_{\sigma(\epsilon')})} B(\mathcal{S}; x', x). \end{aligned} \quad (4.99)$$

Since we have the wrong sign for the exponential, we insert another integral like in (4.86):

$$\begin{aligned} d\tilde{J}_{\epsilon,d}(x) &= \delta_{\epsilon,\epsilon_i} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(x-\mathring{a}_{\sigma(\epsilon)})} \frac{d}{\mathfrak{f}_{\epsilon}^2} dx \\ &- \sum_{\epsilon',d'} \mathcal{F}_{\epsilon,d;\epsilon',d'} \frac{\mathfrak{f}_{\epsilon'}}{d'} \frac{1}{2\pi i} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \text{Res}_{x'' \rightarrow x'} \\ &e^{+\frac{d}{\mathfrak{f}_{\epsilon'}}(x'-\mathring{a}_{\sigma(\epsilon')})} dS(\mathcal{S}_{\sigma(\epsilon')}, x' - \mathring{a}_{\sigma(\epsilon')}, x'' - \mathring{a}_{\sigma(\epsilon')}) B(\mathcal{S}; x'', x) \\ &= \delta_{\epsilon,\epsilon_i} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(x-\mathring{a}_{\sigma(\epsilon)})} \frac{d}{\mathfrak{f}_{\epsilon}^2} dx \\ &+ \sum_{\epsilon',d',\epsilon''} \mathcal{F}_{\epsilon,d;\epsilon',d'} \frac{\mathfrak{f}_{\epsilon'}}{d'} \frac{1}{(2\pi i)^2} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} \oint_{x'' \in \partial_{\epsilon''} \mathcal{C}_{\sigma(\epsilon')}} \\ &e^{+\frac{d'}{\mathfrak{f}_{\epsilon'}}(x'-\mathring{a}_{\sigma(\epsilon')})} dS(\mathcal{S}_{\sigma(\epsilon')}, x' - \mathring{a}_{\sigma(\epsilon')}, x'' - \mathring{a}_{\sigma(\epsilon')}) B(\mathcal{S}; x'', x). \end{aligned} \quad (4.100)$$

Then we use

$$-\frac{\mathfrak{f}_{\epsilon'} \mathfrak{f}_{\epsilon''}}{d' 2i\pi} \oint_{x' \in \partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{\frac{d'}{\mathfrak{f}_{\epsilon'}} x'} dS(\mathcal{S}_{\sigma(\epsilon')}; x', x'') = - \sum_{d''=0}^{\infty} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon')}(d'/\mathfrak{f}_{\epsilon'}; d''/\mathfrak{f}_{\epsilon''}) e^{-\frac{d''}{\mathfrak{f}_{\epsilon''}} x''}. \quad (4.101)$$

That gives

$$\begin{aligned} d\tilde{J}_{\epsilon,d}(x) &= \delta_{\epsilon,\epsilon_i} e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(x-\mathring{a}_{\sigma(\epsilon)})} \frac{d}{\mathfrak{f}_{\epsilon}^2} dx \\ &\quad - \sum_{\epsilon',d',\epsilon'',d''} \mathcal{F}_{\epsilon,d;\epsilon',d'} \tilde{H}_{0,2,\sigma(\epsilon')}(d'/\mathfrak{f}_{\epsilon'}; d''/\mathfrak{f}_{\epsilon''}) d\tilde{J}_{\epsilon'',d''}(x). \end{aligned} \quad (4.102)$$

□

In other words, we may replace the edge weight $\tilde{\mathcal{F}}$ by \mathcal{F} , by introducing a 2-valent vertex $\tilde{\mathcal{H}}_{0,2}$.

We thus have:

Theorem 4.6 *If $x_j \in \mathcal{C}_{\epsilon_j}$ where ϵ_j is an half edge of $\Upsilon_{\mathfrak{X}}$ (not necessarily corresponding to a non-compact edge, neither necessarily the one on which the brane L ends), we have*

$$\begin{aligned} &W_{g,n}(\mathcal{S}; x_1, \dots, x_n) \\ &= 2^{3g-3+n} \sum_{G \in \mathcal{G}_{g,n}^{\text{stable}+(0,2)}} \frac{1}{\#\text{Aut}(G)} \prod_{v=\text{vertices}} \frac{\tilde{\mathcal{H}}_{g_v, n_v, \sigma_v}(\{d_h/\mathfrak{f}_{\epsilon_h}\}_{h \in E_v})}{\prod_{h \in E_v} \mathfrak{f}_{\epsilon_h}} \\ &\quad \prod_{e=(h_+, h_-)=\text{closed edges}} \mathcal{F}_{\epsilon_{h_+}, d_{h_+}; \epsilon_{h_-}, d_{h_-}} \prod_{j=1}^n e^{-\frac{d_j}{\mathfrak{f}_{\epsilon_j}}(x_j - \mathring{a}_{\sigma(\epsilon_j)})} \frac{d_j}{\mathfrak{f}_{\epsilon_j}} dx_j \end{aligned} \quad (4.103)$$

where the sum is over stable graphs with possibly $(0, 2)$ vertices (every vertex v is such that $2 - 2g_v - n_v < 1$), with

$$\begin{aligned} \tilde{\mathcal{H}}_{g,n,\sigma}(k_1, \dots, k_n) &= e^{\hat{t}_{\sigma,0}(2g-2+n)} \int_{\mathcal{M}_{g,n}} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \\ &\quad e^{l_1^* \sum_d \tilde{R}_{\sigma_v, d} \tau_d} \prod_{i=1}^n \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_i)}{1 - k_i \psi_i}, \end{aligned} \quad (4.104)$$

$$\begin{aligned} \tilde{\mathcal{H}}_{0,2,\sigma}(k_1, k_2) &= \mathcal{H}_{0,2,\sigma}(k_1, k_2) \\ &\quad + \sum_{k=1}^{\infty} \frac{1}{k!} \int_{\mathcal{M}_{0,k+2}} \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \\ &\quad \left(\sum_d \tilde{R}_{\sigma_v, d} \tau_d \right)^k \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_1)}{1 - k_1 \psi_1} \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_2)}{1 - k_2 \psi_2} \end{aligned} \quad (4.105)$$

and

$$\mathcal{F}_{\epsilon,d;\epsilon',d'} = d e^{-\frac{d}{\mathfrak{f}_{\epsilon}}(\mathring{a}_{\sigma'} - \mathring{a}_{\sigma})} A_{\epsilon,\epsilon'} \delta_{d,d'}. \quad (4.106)$$

proof:

The sum over all $(0, 2)$ vertices can be performed due to

$$\tilde{\mathcal{F}} = \mathcal{F} + \mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F} + \mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F} + \mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F} + \dots$$

which is illustrated as:

$$\text{————} = \text{-----} + \text{-----} \bullet \text{-----} + \text{-----} \bullet \text{-----} \bullet \text{-----} + \dots$$

and it exactly reproduces the left hand side. This is a usual trick used in combinatorics of graphs. \square

4.9.4 Renormalized disc amplitude $R_{\sigma,d}$

Proposition 4.3 *The vertex weights can be renormalized by*

$$\begin{aligned} & \tilde{\mathcal{H}}_{g,n,\sigma}(d_1, \dots, d_n) \\ = & \mathcal{H}_{g,n,\sigma}(d_1, \dots, d_n) \\ & + \sum_{k=1}^{\infty} \frac{1}{k!} \sum_{\epsilon_{n+1}, \dots, \epsilon_{n+k}} \sum_{d_{n+1}, \dots, d_{n+k}} \mathcal{H}_{g,n+k,\sigma}(d_1, \dots, d_{n+k}) \prod_{i=n+1}^{n+k} \mathcal{F}_{\epsilon, d_i; \epsilon_i, d_i} C_{\sigma(\epsilon'_i)}(d_i) \end{aligned} \quad (4.107)$$

and

$$\begin{aligned} C_{\sigma}(d) &= \mathcal{H}_{0,1,\sigma}(d) \\ &+ \sum_{k=1}^{\infty} \frac{1}{k!} \sum_{\epsilon_2, \dots, \epsilon_{k+1}} \sum_{d_2, \dots, d_{k+1}} \mathcal{H}_{0,k+1,\sigma}(d_1, d_2, \dots, d_{k+1}) \prod_{i=2}^{k+1} \mathcal{F}_{\epsilon, d_i; \epsilon_i, d_i} C_{\sigma(\epsilon'_i)}(d_i) \end{aligned} \quad (4.108)$$

where

$$\mathcal{H}_{0,1,\sigma}(k) = \frac{e^{-\hat{t}_{\mathfrak{f}\sigma,0}}}{4k^2} \gamma_{\mathfrak{f}\sigma}(k) \quad (4.109)$$

and, for $2 - 2g - n < 0$:

$$\begin{aligned} \mathcal{H}_{g,n,\sigma}(k_1, \dots, k_n) &= \frac{2^{3g-3+n}}{e^{(2-2g-n)\hat{t}_{\mathfrak{f}\sigma,0}}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \right. \\ &\quad \left. \prod_{i=1}^n \frac{\gamma_{\mathfrak{f}\sigma}(k_i)}{1 - k_i \psi_i} \right\rangle_{g,n}. \end{aligned} \quad (4.110)$$

proof:

From lemma 4.1, we have

$$R_{\sigma,d} = \frac{-2e^{\hat{t}_{\mathfrak{f}\sigma,0}}}{2\pi i} \oint_{\partial \mathcal{C}_{\sigma}} \tilde{\xi}_{\mathfrak{f}\sigma,d}^{\circ}(x) (y(x + \mathring{a}_{\sigma}) - \mathring{b}_{\sigma} - \mathring{y}_{\mathfrak{f}\sigma}(x)) dx. \quad (4.111)$$

We first decompose $\partial\mathcal{C}_\sigma$ into its 3 circles $\cup_\epsilon \partial_\epsilon \mathcal{C}_\sigma$, and on each $\partial_\epsilon \mathcal{C}_\sigma$ we use the expansion (E.15) for $\xi_{\mathfrak{f}_\sigma, d}(x)$. This implies

$$\sum_d \psi^d R_{\sigma, d} = 2 e^{\hat{t}_{\mathfrak{f}_\sigma(\epsilon), 0}} \sum_\epsilon \sum_k \frac{\gamma_\sigma(k/\mathfrak{f}_\epsilon)}{1 - \frac{k}{\mathfrak{f}_\epsilon} \psi} \hat{R}_\epsilon(k/\mathfrak{f}_\epsilon) \quad (4.112)$$

where

$$\hat{R}_\epsilon(k/\mathfrak{f}_\epsilon) = \frac{1}{\mathfrak{f}_\epsilon 2\pi i} \oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{-\frac{k}{\mathfrak{f}_\epsilon} (x - \mathring{a}_{\sigma(\epsilon)})} (y(x) - \mathring{b}_{\sigma(\epsilon)} - \mathring{y}_{\mathfrak{f}_{\sigma(\epsilon)}}(x - \mathring{a}_{\sigma(\epsilon)})) dx. \quad (4.113)$$

When $k = 0$, we have to compute

$$\oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} (y(x) - \mathring{b}_{\sigma(\epsilon)} - \mathring{y}_{\mathfrak{f}_{\sigma(\epsilon)}}(x - \mathring{a}_{\sigma(\epsilon)})) dx = 0 \quad (4.114)$$

which vanishes (order by order in the Q expansion) due to (F.7). So, let us assume $k \neq 0$ and integrate by parts:

$$\hat{R}_\epsilon(k/\mathfrak{f}_\epsilon) = \frac{1}{k} \frac{1}{2\pi i} \oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{-\frac{k}{\mathfrak{f}_\epsilon} (x - \mathring{a}_{\sigma(\epsilon)})} (dy(x) - d\mathring{y}_{\mathfrak{f}_{\sigma(\epsilon)}}(x - \mathring{a}_{\sigma(\epsilon)})). \quad (4.115)$$

Using the parametrization of def. 4.6 one can compute explicitly

$$\oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{-\frac{k}{\mathfrak{f}_\epsilon} x} d\mathring{y}_{\mathfrak{f}_{\sigma(\epsilon)}}(x) = 0, \quad (4.116)$$

and thus

$$\hat{R}_\epsilon(k/\mathfrak{f}_\epsilon) = \frac{1}{k} \frac{1}{2\pi i} \oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{-\frac{k}{\mathfrak{f}_\epsilon} (x - \mathring{a}_{\sigma(\epsilon)})} dy(x). \quad (4.117)$$

Then, let us move the integration contour through the cylinder \mathcal{C}_ϵ . Let us call ϵ' the other half-edge of the cylinder (i.e. $A_{\epsilon, \epsilon'} = 1$, and in that case $\mathfrak{f}_{\epsilon'} = -\mathfrak{f}_\epsilon$):

$$\hat{R}_\epsilon(k/\mathfrak{f}_\epsilon) = -\frac{1}{k} \frac{1}{2\pi i} \sum_{\epsilon'} A_{\epsilon, \epsilon'} e^{-\frac{k}{\mathfrak{f}_\epsilon} (\mathring{a}_{\sigma(\epsilon')} - \mathring{a}_{\sigma(\epsilon)})} \oint_{\partial_{\epsilon'} \mathcal{C}_{\sigma(\epsilon')}} e^{+\frac{k}{\mathfrak{f}_{\epsilon'}} (x - \mathring{a}_{\sigma(\epsilon')})} dy(x) \quad (4.118)$$

which we can write

$$\hat{R}_\epsilon(k/\mathfrak{f}_\epsilon) = \sum_{\epsilon', k'} F_{\epsilon, k; \epsilon', k'} C_{\epsilon'}(k'/\mathfrak{f}_{\epsilon'}) \quad (4.119)$$

with

$$\begin{aligned} C_\epsilon(k/\mathfrak{f}_\epsilon) &= -\frac{\mathfrak{f}_\epsilon^2}{k^2} \frac{1}{2\pi i} \oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{+\frac{k}{\mathfrak{f}_\epsilon} (x - \mathring{a}_{\sigma(\epsilon)})} dy(x) \\ &= -\frac{\mathfrak{f}_\epsilon^2}{k^2} \frac{1}{2\pi i} \oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{+\frac{k}{\mathfrak{f}_\epsilon} x} d\Phi(x) - \frac{\mathfrak{f}_\epsilon^2}{k^2} \frac{1}{2\pi i} \oint_{\partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} e^{+\frac{k}{\mathfrak{f}_\epsilon} x} d\mathring{y}_{\mathfrak{f}_{\sigma(\epsilon)}}(x) \end{aligned} \quad (4.120)$$

where we have introduced $\Phi(x)$ such that

$$d\Phi(x) = (y(x) - \overset{\circ}{b}_\sigma - \overset{\circ}{y}_{\mathfrak{f}_\sigma}(x - \overset{\circ}{a}_\sigma)) dx. \quad (4.121)$$

Then, let us use eq. (4.61) of corollary 4.1:

$$\begin{aligned} d\Phi(x) &= \frac{1}{2\pi i} \oint_{x' \in \partial \mathcal{C}_\sigma} \overset{\circ}{B}_{\mathfrak{f}_\sigma}(x, x') \Phi(x') - \frac{e^{-\hat{t}_{\mathfrak{f}_\sigma, 0}}}{4} \sum_{k_1} \sum_{n=2}^{\infty} \frac{1}{n!} \\ &\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a, \sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b, \sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a, \sigma} - \mathfrak{f}_{b, \sigma}) \right. \\ &\quad \left. \left(\sum_d R_{\sigma, d} \tau_d \right)^n \frac{\gamma_{\mathfrak{f}_\sigma}(k_1/\mathfrak{f}_\epsilon)}{1 - \frac{k_1}{\mathfrak{f}_\epsilon} \psi_1} \right\rangle_{0, n+1} \frac{k_1}{(\mathfrak{f}_\epsilon)^2} e^{-\frac{k_1}{\mathfrak{f}_\epsilon} x} dx. \end{aligned} \quad (4.122)$$

We thus get that:

$$\begin{aligned} C_\epsilon(k/\mathfrak{f}_\epsilon) &= -\frac{\mathfrak{f}_\epsilon}{k} \frac{1}{(2\pi i)^2} \oint_{x \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x' \in \partial \mathcal{C}_\sigma} e^{+\frac{k}{\mathfrak{f}_\epsilon} x} \overset{\circ}{B}_{\mathfrak{f}_\sigma}(x, x') \Phi(x') \\ &\quad + \frac{e^{-\hat{t}_{\mathfrak{f}_\sigma, 0}}}{4} \sum_{n=2}^{\infty} \frac{1}{n!} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a, \sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b, \sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a, \sigma} - \mathfrak{f}_{b, \sigma}) \right. \\ &\quad \left. \left(\sum_d R_{\sigma, d} \tau_d \right)^n \frac{\gamma_{\mathfrak{f}_\sigma}(k/\mathfrak{f}_\epsilon)}{1 - \frac{k}{\mathfrak{f}_\epsilon} \psi_1} \right\rangle_{0, n+1}. \end{aligned} \quad (4.123)$$

For $2 - 2g - n < 0$ we define:

$$\begin{aligned} \mathcal{H}_{g, n, \sigma}(k_1, \dots, k_n) &= \frac{2^{3g-3+n}}{e^{(2-2g-n)\hat{t}_{\mathfrak{f}_\sigma, 0}}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a, \sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b, \sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a, \sigma} - \mathfrak{f}_{b, \sigma}) \right. \\ &\quad \left. \prod_{i=1}^n \frac{\gamma_{\mathfrak{f}_\sigma}(k_i)}{1 - k_i \psi_i} \right\rangle_{g, n} \end{aligned} \quad (4.124)$$

and

$$\mathcal{H}_{0, 2, \sigma}(k/\mathfrak{f}_\epsilon, k'/\mathfrak{f}_{\epsilon'}) = -\frac{\mathfrak{f}_\epsilon \mathfrak{f}_{\epsilon'}}{k k'} \frac{1}{(2\pi i)^2} \oint_{x \in \partial_\epsilon \mathcal{C}_{\sigma(\epsilon)}} \oint_{x' \in \partial \mathcal{C}_\sigma} e^{+\frac{k}{\mathfrak{f}_\epsilon} x} \overset{\circ}{B}_{\mathfrak{f}_\sigma}(x, x') e^{+\frac{k'}{\mathfrak{f}_{\epsilon'}} x'} \quad (4.125)$$

and

$$H_{0, 1, \sigma}(k) = \frac{e^{-\hat{t}_{\mathfrak{f}_\sigma, 0}}}{4 k^2} \gamma_{\mathfrak{f}_\sigma}(k). \quad (4.126)$$

This amounts to write virtually:

$$\left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a, \sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b, \sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a, \sigma} - \mathfrak{f}_{b, \sigma}) \frac{1}{1 - k \psi} \right\rangle_{0, 1} = \frac{1}{k^2}. \quad (4.127)$$

This gives that

$$C_\sigma(k/\mathfrak{f}_\epsilon) = \mathcal{H}_{0, 1, \sigma}(k/\mathfrak{f}_\epsilon) + \sum_{n=1}^{\infty} \frac{1}{n!} \sum_{\epsilon'_i, i=1, \dots, n} \sum_{d'_i, i=1, \dots, n}$$

$$\mathcal{H}_{0,n+1,\sigma}(k/\epsilon, k_1/\epsilon_1, \dots, k_n/\epsilon_n) \prod_{i=1}^n \mathcal{F}_{\epsilon_i, k_i; \epsilon'_i, k'_i} C_{\sigma(\epsilon'_i)}(k'_i/\epsilon'_i). \quad (4.128)$$

□

4.10 Finishing the proof

So far we had from theorem 4.5 that, if $x_j \in \mathcal{C}_{\epsilon_j}$ where ϵ_j is an half edge of $\Upsilon_{\mathfrak{x}}$ (not necessarily corresponding to a non-compact edge, neither necessarily the one on which the brane L ends), we have

$$\begin{aligned} & W_{g,n}(\mathcal{S}; x_1, \dots, x_n) \\ = & \sum_{G \in \mathcal{G}_{g,n}^{\text{stable}}} \frac{1}{\#\text{Aut}(G)} \prod_{v=\text{vertices}} \tilde{\mathcal{H}}_{g_v, n_v, \sigma_v}(\{d_h/\mathfrak{f}_{\epsilon_h}\}_{h \in E_v}) \\ & \prod_{e=(h_+, h_-)=\text{closed edges}} \tilde{\mathcal{F}}_{\epsilon_{h_+}, d_{h_+}; \epsilon_{h_-}, d_{h_-}} \prod_{j=1, h_j=\text{open half-edges}}^n d\tilde{\mathcal{J}}_{\epsilon_{h_j}, d_{h_j}}(x_j) \end{aligned} \quad (4.129)$$

where the quantities $\tilde{\mathcal{H}}_{g,n,\sigma}$ and $\tilde{\mathcal{F}}_{\epsilon,d;\epsilon',d'}$ are directly computed from the spectral curve, and where the sum is only over stable graphs (every vertex v is such that $2 - 2g_v - n_v < 0$).

However, we have just found that we have for $(g, n) \neq (0, 1)$:

$$\begin{aligned} & \tilde{\mathcal{H}}_{g,n,\sigma}(k_1/\mathfrak{f}_{\epsilon_1}, \dots, k_n/\mathfrak{f}_{\epsilon_n}) \\ = & \mathcal{H}_{g,n,\sigma}(k_1/\mathfrak{f}_{\epsilon_1}, \dots, k_n/\mathfrak{f}_{\epsilon_n}) \\ & + \sum_{m=1}^{\infty} \frac{1}{m!} \sum_{\epsilon'_i, i=n+1, \dots, n+m} \sum_{d'_i, i=n+1, \dots, n+m} \mathcal{H}_{g,n+m,\sigma}(k_1/\epsilon_1, \dots, k_{n+m}/\epsilon_{n+m}) \prod_{i=n+1}^{n+m} \mathcal{F}_{\epsilon_i, k_i; \epsilon'_i, k'_i} C_{\sigma(\epsilon'_i)}(k'_i/\epsilon'_i) \end{aligned} \quad (4.130)$$

and for $(g, n) = (0, 1)$

$$\begin{aligned} C_{\sigma}(k/\mathfrak{f}_{\epsilon}) &= \mathcal{H}_{0,1,\sigma}(k/\mathfrak{f}_{\epsilon}) + \sum_{n=1}^{\infty} \frac{1}{n!} \sum_{\epsilon'_i, i=1, \dots, n} \sum_{d'_i, i=1, \dots, n} \mathcal{H}_{0,n+1,\sigma}(k/\epsilon, k_1/\epsilon_1, \dots, k_n/\epsilon_n) \prod_{i=1}^n \mathcal{F}_{\epsilon_i, k_i; \epsilon'_i, k'_i} C_{\sigma(\epsilon'_i)}(k'_i/\epsilon'_i) \end{aligned} \quad (4.131)$$

and we have

$$\tilde{\mathcal{F}}_{\epsilon, k; \epsilon', k'} = \mathcal{F}_{\epsilon, k; \epsilon', k'} + \sum_{\epsilon'', \epsilon''', k'', k'''} \mathcal{F}_{\epsilon, k; \epsilon'', k''} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon'')}(k''/\mathfrak{f}_{\epsilon''}, k'''/\mathfrak{f}_{\epsilon'''}) \tilde{\mathcal{F}}_{\epsilon''', k'''; \epsilon', k'} \quad (4.132)$$

$$\begin{aligned} \tilde{H}_{g,n} &= H_{g,n} + H_{g,n+1} + \frac{1}{2} H_{g,n+2} + \frac{1}{6} H_{g,n+3} + \dots \\ \text{black vertex with 1 half-edge} &= H_{0,1} + H_{0,2} + \frac{1}{2} H_{0,3} + \frac{1}{6} H_{0,4} + \dots \\ \text{solid line} &= \text{dashed line} + \text{dashed line with 1 dot} + \text{dashed line with 2 dots} + \text{dashed line with 3 dots} + \dots \end{aligned}$$

Figure 14: The vertices weights $\tilde{\mathcal{H}}_{g,n}$ are obtained by gluing C in all possible ways, and C must be chosen such that $\mathcal{H}_{0,1} = C$. The weight for the propagator is $\tilde{\mathcal{F}} = \mathcal{F} + \mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F} + \mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F}\tilde{\mathcal{H}}_{0,2}\mathcal{F} + \dots = \mathcal{F} + \mathcal{F}\tilde{\mathcal{H}}_{0,2}\tilde{\mathcal{F}}$

and

$$d\tilde{J}_{\epsilon,k}(x) = dJ_{\epsilon,k}(x) + \sum_{\epsilon', \epsilon'', k', k''} \tilde{\mathcal{F}}_{\epsilon,k;\epsilon,k'} \tilde{\mathcal{H}}_{0,2,\sigma(\epsilon')}(k'/\mathfrak{f}_{\epsilon'}, k''/\mathfrak{f}_{\epsilon''}) dJ_{\epsilon'',k''}(x) \quad (4.133)$$

All this is sufficient to prove that:

Theorem 4.7

$$\begin{aligned} & W_{g,n}(\mathcal{S}; x_1, \dots, x_n) \\ &= \sum_{G \in \mathcal{G}_{g,n}} \frac{1}{\#\text{Aut}(G)} \prod_{v=\text{vertices}} \mathcal{H}_{g_v, n_v, \sigma_v}(\{d_h/\mathfrak{f}_{\epsilon_h}\}_{h \in E_v}) \\ & \quad \prod_{e=(h_+, h_-)=\text{closed edges}} \mathcal{F}_{\epsilon_{h_+}, d_{h_+}; \epsilon_{h_-}, d_{h_-}} \prod_{j=1, h_j=\text{open half-edges}}^n dJ_{\epsilon_{h_j}, d_{h_j}}(x_j) \end{aligned} \quad (4.134)$$

where now the sum is over all graphs (not only stable ones). Moreover we have:

$$\begin{aligned} \mathcal{H}_{g,n,\sigma}(k_1, \dots, k_n) &= \frac{2^{3g-3+n}}{e^{(2-2g-n)\hat{t}_{\mathfrak{f}_{\sigma},0}}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \right. \\ & \quad \left. \prod_{i=1}^n \frac{\gamma_{\mathfrak{f}_{\sigma}}(k_i)}{1 - k_i \psi_i} \right\rangle_{g,n} \end{aligned} \quad (4.135)$$

where for $(g, n) = (0, 2)$ and $(0, 1)$ we have defined

$$\left\langle \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathbf{f}_{a,\sigma} - \mathbf{f}_{b,\sigma}) \frac{1}{1 - k\psi} \right\rangle_{0,1} \stackrel{\text{def}}{=} \frac{1}{k^2} \quad (4.136)$$

$$\left\langle \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathbf{f}_{a,\sigma} - \mathbf{f}_{b,\sigma}) \frac{1}{1 - k\psi_1} \frac{1}{1 - k'\psi_2} \right\rangle_{0,2} \stackrel{\text{def}}{=} \frac{2}{k + k'} \quad (4.137)$$

and

$$\mathcal{F}_{\epsilon, d; \epsilon', d'} = A_{\epsilon, \epsilon'} \delta_{d, d'} \frac{d}{\mathfrak{f}_{\epsilon}^2} e^{-\frac{d}{\mathfrak{f}_{\epsilon}} (\hat{a}_{\sigma'} - \hat{a}_{\sigma})} \quad (4.138)$$

$$dJ_{\epsilon, k}(x) = e^{-\frac{k}{\mathfrak{f}_{\epsilon}} (x - \hat{a}_{\sigma(\epsilon)})} \frac{k}{\mathfrak{f}_{\epsilon}^2} dx \quad (4.139)$$

proof:

The proof is best represented graphically, this is fig. 14. \square

One can check that this expression coincides with the localization formula for Gromov–Witten invariants. This concludes the proof of the BKMP conjecture:

Theorem 4.8 *The BKMP conjecture holds true. In other words the invariants $W_{g,n}$ of the mirror curve \mathcal{S} do coincide with the Gromov–Witten invariants:*

$$W_{g,n}(\mathcal{S}; x_1, \dots, x_n) = \mathcal{W}_{g,n}(\mathfrak{X}, x_1, \dots, x_n) dx_1 \otimes \dots \otimes dx_n. \quad (4.140)$$

5 Conclusion

We have obtained theorem 4.7 using only properties of the topological recursion (mostly combinatorics of graphs and complex analysis on the spectral curve), and it is remarkable that what we obtain is exactly the localization formula of Gromov–Witten invariants.

Our proof is thus a proof which works mostly on the B-model side. The main ingredients are localization, tropical limit, special geometry, graph combinatorics and complex analysis on \mathcal{C} .

En route we have seen that the B-model formula continues to make sense when the boundaries are not all on the same brane, each boundary can be chosen on a different brane, and also the brane needs not be on a non-compact edge of the toric graph, it can be on any half-edge.

We hope that the present proof may shed some new light on the A-model side geometry.

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Appendix A

A Invariants of spectral curves and topological recursion

A.1 Spectral curves

A spectral curve is in fact the data of a plane curve with some additional structure. We set:

Definition A.1 (Spectral curve) *a spectral curve $\mathcal{S} = (\mathcal{C}, x, y, B)$, is the data of:*

- *a Riemann surface \mathcal{C} , not necessarily compact,*
- *two analytical functions $x : \mathcal{C} \rightarrow \mathbb{C}$, $y : \mathcal{C} \rightarrow \mathbb{C}$,*
- *a Bergman kernel B , i.e. a symmetric 2nd kind bilinear meromorphic differential, having a double pole on the diagonal and no other pole, and normalized (in any local coordinate z) as:*

$$B(z_1, z_2) \underset{z_2 \rightarrow z_1}{\sim} \frac{dz_1 \otimes dz_2}{(z_1 - z_2)^2} + \text{analytical.} \quad (\text{A.1})$$

Moreover, the spectral curve \mathcal{S} is called regular if the 1-form dx has a finite number of zeroes on \mathcal{C} , denoted $\{\alpha_1, \dots, \alpha_b\}$, and they are simple zeroes, and dy doesn't vanish at the zeroes of dx . In other words, locally near a branchpoint α , y behaves like a square root of x :

$$y(z) \underset{z \rightarrow \alpha}{\sim} y(\alpha) + y'(a) \sqrt{x(z) - a} + O(x(z) - a) \quad , \quad y'(a) \neq 0 \quad (\text{A.2})$$

and where $a = x(\alpha)$ is the x -projection of the branchpoint α :

$$x(\alpha) = a. \quad (\text{A.3})$$

A.2 Invariants

In [18], it was defined how to associate to a regular spectral curve \mathcal{S} , an infinite sequence of symmetric multilinear meromorphic forms $\omega_n^{(g)} \in T^*(\mathcal{C}) \otimes \cdots \otimes T^*(\mathcal{C})$, and a sequence of complex numbers $F_g(\mathcal{S}) \in \mathbb{C}$. The definition is given by a recursion, often called ”topological recursion”, which we recall:

Definition A.2 (Invariants $\omega_{g,n}(\mathcal{S})$) *Let $\mathcal{S} = (\mathcal{C}, x, y, B)$ be a regular spectral curve. Let $\alpha_1, \dots, \alpha_b$ be its branchpoints (zeroes of dx in \mathcal{C}), and $a_i = x(\alpha_i)$. We define*

$$\omega_{0,1}(\mathcal{S}; z) = y(z) dx(z), \quad (\text{A.4})$$

$$\omega_{0,2}(\mathcal{S}; z_1, z_2) = B(z_1, z_2), \quad (\text{A.5})$$

and for $2g - 2 + (n + 1) > 0$:

$$\begin{aligned} \omega_{g,n+1}(\mathcal{S}; z_1, \dots, z_n, z_{n+1}) &= \sum_{i=1}^b \text{Res}_{z \rightarrow \alpha_i} K(z_{n+1}, z) \left[\omega_{g-1,n+2}(z, \bar{z}, z_1, \dots, z_n) \right. \\ &\quad \left. + \sum_{h=0}^g \sum'_{I \sqcup J = \{z_1, \dots, z_n\}} \omega_{h,1+\#I}(z, I) \omega_{g-h,1+\#J}(z, J) \right] \end{aligned} \quad (\text{A.6})$$

where the prime in $\sum_h \sum'_{I \sqcup J}$ means that we exclude from the sum the terms ($h = 0, I = \emptyset$) and ($h = g, J = \emptyset$), and where \bar{z} means the other branch of the square-root in (4.6) near a branchpoint α_i , i.e. if z is in the vicinity of α_i , $\bar{z} \neq z$ is the other point in the vicinity of α_i such that

$$x(\bar{z}) = x(z), \quad (\text{A.7})$$

and thus $y(\bar{z}) \sim y(\alpha) - y'(a)\sqrt{x(z) - a}$. The recursion kernel $K(z_{n+1}, z)$ is defined as

$$K(z_{n+1}, z) = \frac{\int_{z'=\bar{z}}^z B(z_{n+1}, z')}{2(y(z) - y(\bar{z})) dx(z)} \quad (\text{A.8})$$

K is a 1-form in z_{n+1} defined on \mathcal{C} with a simple pole at $z_{n+1} = z$ and at $z_{n+1} = \bar{z}$, and in z it is the inverse of a 1-form, defined only locally near branchpoints, and it has a simple pole at $z = \alpha_i$.

Using the $x(z)$ coordinate instead of z , we define

$$W_{g,n}(\mathcal{S}; x(z_1), \dots, x(z_n)) = \omega_{g,n}(z_1, \dots, z_n). \quad (\text{A.9})$$

We also define for $g \geq 2$:

$$F_g(\mathcal{S}) = \omega_{g,0}(\mathcal{S}) = \frac{1}{2-2g} \sum_{i=1}^b \text{Res}_{z \rightarrow \alpha_i} \omega_{g,1}(\mathcal{S}; z) \left(\int_{z'=\alpha_i}^z y(z') dx(z') \right). \quad (\text{A.10})$$

With this definition, $F_g(\mathcal{S}) \in \mathbb{C}$ is a complex number associated to \mathcal{S} , sometimes called the g^{th} symplectic invariant of \mathcal{S} , and $\omega_{g,n}(\mathcal{S}; z_1, \dots, z_n)$ is a symmetric multilinear differential $\in T^*(\mathcal{C}) \otimes \dots \otimes T^*(\mathcal{C})$, sometimes called the n^{th} descendant of F_g . Very often we denote $F_g = \omega_{g,0}$. If $2 - 2g - n < 0$, $\omega_{g,n}$ is called stable, and otherwise unstable, the only unstable cases are $F_0, F_1, \omega_{0,1}, \omega_{0,2}$. For $2 - 2g - n < 0$, $\omega_{g,n}$ has poles only at branchpoints (when some z_k tends to a branchpoint a_i), without residues, and the degrees of the poles are $\leq 6g + 2n - 4$. In the x variables, $W_{g,n}$ are multivalued functions of the x_i 's and their singular behavior near $x_i \rightarrow a_j$ are half integer power singularities:

$$W_{g,n}(\mathcal{S}; x_1, \dots, x_n) \sim O\left((x_i - a_j)^{-d_{i,j} - \frac{1}{2}}\right) dx_i \quad (\text{A.11})$$

where

$$d_{i,j} \leq 3g - 3 + n \quad (\text{A.12})$$

We shall not write here the definition of F_0 and F_1 , see [18], since we shall not use them here.

Those invariants F_g and $\omega_{g,n}$'s have many fascinating properties, in particular related to integrability, to modular forms, and to special geometry, and we refer the reader to [18, 20].

B Intersection numbers

Since many of our formula involve intersection numbers in moduli spaces of curves, let us introduce basic concepts. We refer the reader to [] for deeper description.

B.1 Definitions

Let $\mathcal{M}_{g,n}$ be the moduli space of complex curves of genus g with n marked points. It is a complex orbifold (manifold quotiented by a group of symmetries), of dimension

$$\dim \mathcal{M}_{g,n} = d_{g,n} = 3g - 3 + n. \quad (\text{B.1})$$

Each element $(\Sigma, p_1, \dots, p_n) \in \mathcal{M}_{g,n}$ is a smooth complex curve Σ of genus g with n smooth distinct marked points p_1, \dots, p_n . $\mathcal{M}_{g,n}$ is not compact because the limit of a family of smooth curves may be non-smooth, some cycles may shrink, or some marked points may collapse in the limit. The Deligne–Mumford compactification $\overline{\mathcal{M}}_{g,n}$ of $\mathcal{M}_{g,n}$ also contains stable nodal curves of genus g with n distinct smooth marked points (a nodal curve is a set of smooth curves glued at nodal points, and thus nodal points are equivalent to pairs of marked points, and stability means that each punctured

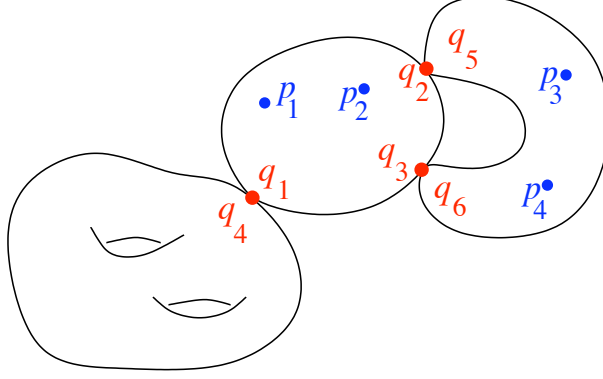


Figure 15: A stable curve in $\overline{\mathcal{M}}_{g,n}$ can be smooth or nodal. Here we have an example in $\overline{\mathcal{M}}_{3,4}$ of a stable curve of genus $g = 3$, with $n = 4$ marked points p_1, \dots, p_4 , and made of 3 components, glued by 3 nodal points. Each nodal point is a pair of marked points (q_i, q_j) . Each component is a smooth Riemann surface of some genus g_i , and with n_i marked or nodal points. Stability means that for each component $\chi_i = 2 - 2g_i - n_i < 0$. Here, one component has genus 2 and 1 nodal point q_4 so $\chi = -3$, another component is a sphere with 2 marked points p_1, p_2 and 3 nodal points q_1, q_2, q_3 i.e. $\chi = -3$, and the last component is a sphere with 2 marked points p_3, p_4 and 2 nodal points q_5, q_6 so $\chi = -2$. The total Euler characteristics is $\chi = -3 - 3 - 2 = -8$ which indeed corresponds to $2 - 2g - n$ for a Riemann surface of genus $g = 3$ with $n = 4$ marked points.

component curve has an Euler characteristics < 0), see fig 15. $\overline{\mathcal{M}}_{g,n}$ is then a compact space.

Let \mathcal{L}_i be the cotangent bundle at the marked point p_i , i.e. the bundle over $\overline{\mathcal{M}}_{g,n}$ whose fiber is the cotangent space $T^*(p_i)$ of Σ at p_i . It is customary to denote its first Chern class:

$$\psi_i = \psi(p_i) = c_1(\mathcal{L}_i). \quad (\text{B.2})$$

ψ_i is (the cohomology equivalence class modulo exact forms, of) a 2-form on $\overline{\mathcal{M}}_{g,n}$. Since $\dim_{\mathbb{R}} \overline{\mathcal{M}}_{g,n} = 2 \dim_{\mathbb{C}} \overline{\mathcal{M}}_{g,n} = 6g - 6 + 2n$, it makes sense to compute the integral of the exterior product of $3g - 3 + n$ 2-forms, i.e. to compute the "intersection number"

Definition B.1

$$\begin{aligned} \langle \tau_{d_1} \dots \tau_{d_n} \rangle_{g,n} &:= \langle \psi_1^{d_1} \dots \psi_n^{d_n} \rangle_{g,n} \\ &:= \begin{cases} \int_{\overline{\mathcal{M}}_{g,n}} \psi_1^{d_1} \dots \psi_n^{d_n} & \text{if } \sum_i d_i = d_{g,n} = 3g - 3 + n \\ 0 & \text{otherwise} \end{cases} \end{aligned} \quad (\text{B.3})$$

More interesting characteristic classes and intersection numbers are defined as follows. Let (we follow the notations of [31], and refer the reader to it for details)

$$\pi : \overline{\mathcal{M}}_{g,n+1} \rightarrow \overline{\mathcal{M}}_{g,n}$$

be the forgetful morphism (which forgets the last marked point), and let $\sigma_1, \dots, \sigma_n$ be the canonical sections of π , and D_1, \dots, D_n be the corresponding divisors in $\overline{\mathcal{M}}_{g,n+1}$. Let ω_π be the relative dualizing sheaf. We consider the following tautological classes on $\overline{\mathcal{M}}_{g,n}$:

- The ψ_i classes (which are 2-forms), already introduced above:

$$\psi_i = c_1(\sigma_i^*(\omega_\pi))$$

It is customary to use Witten's notation:

$$\psi_i^{d_i} = \tau_{d_i}. \quad (\text{B.4})$$

- The Mumford κ_k classes [47, 4]:

$$\kappa_k = \pi_*(c_1(\omega_\pi(\sum_i D_i))^{k+1}).$$

κ_k is a $2k$ -form. κ_0 is the Euler class, and in $\overline{\mathcal{M}}_{g,n}$, we have

$$\kappa_0 = -\chi_{g,n} = 2g - 2 + n.$$

κ_1 is known as the Weil-Petersson form since it is given by $2\pi^2\kappa_1 = \sum_i dl_i \wedge d\theta_i$ in the Fenchel-Nielsen coordinates (l_i, θ_i) in Teichmüller space [52].

In some sense, κ classes are the remnants of the ψ classes of (clusters of) forgotten points. There is the formula [4]:

$$\pi_* \psi_1^{d_1} \dots \psi_n^{d_n} \psi_{n+1}^{k+1} = \psi_1^{d_1} \dots \psi_n^{d_n} \kappa_k \quad (\text{B.5})$$

$$\pi_* \pi_* \psi_1^{d_1} \dots \psi_n^{d_n} \psi_{n+1}^{k+1} \psi_{n+2}^{k'+1} = \psi_1^{d_1} \dots \psi_n^{d_n} (\kappa_k \kappa_{k'} + \kappa_{k+k'}) \quad (\text{B.6})$$

and so on...

- The Hodge class $\Lambda(\alpha) = 1 + \sum_{k=1}^g (-1)^k \alpha^{-k} c_k(\mathbb{E})$ where $c_k(\mathbb{E})$ is the k^{th} Chern class of the Hodge bundle $\mathbb{E} = \pi_*(\omega_\pi)$. Mumford's formula [47, 21] says that

$$\Lambda_{\text{Hodge}}(\alpha) = e^{-\sum_{k \geq 1} \frac{B_{2k} \alpha^{1-2k}}{2k(2k-1)}} \left(\kappa_{2k-1} - \sum_i \psi_i^{2k-1} + \frac{1}{2} \sum_\delta \sum_j (-1)^j l_{\delta*} \psi_j \psi'^{2k-2-j} \right) \quad (\text{B.7})$$

where B_k is the k^{th} Bernoulli number, δ a boundary divisor (i.e. a cycle which can be pinched so that the pinched curve is a stable nodal curve, i.e. replacing the pinched

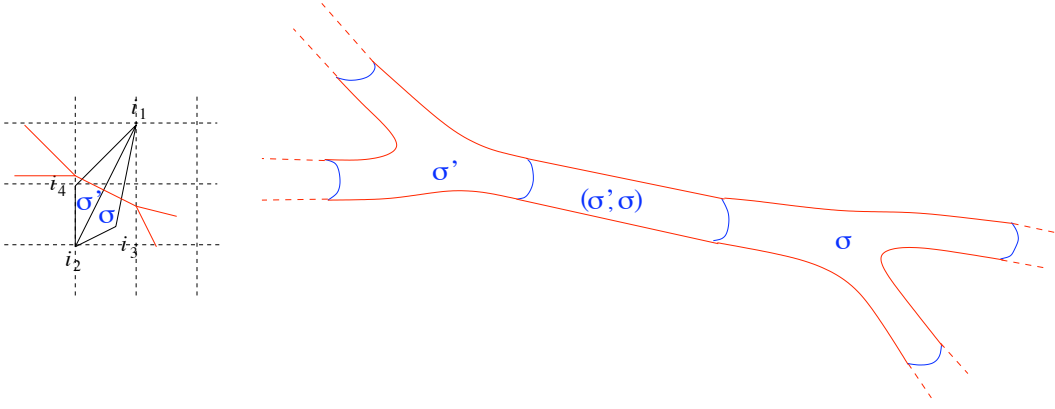


Figure 16: The curve \mathcal{C} is a union of cylinders $\mathcal{C}_{\sigma, \sigma'}$ corresponding to edges of the toric graph $\Upsilon_{\mathbf{x}}$ and of pairs of pants \mathcal{C}_{σ} corresponding to vertices of $\Upsilon_{\mathbf{x}}$. Its Bergman kernel can be obtained as a combination of the Bergman kernels of each pieces. Notice that the framing of the edge σ, σ' is $\mathfrak{f}_{\sigma, \sigma'} = -\mathfrak{f}_{\sigma', \sigma} = \mathfrak{f}_{b, \sigma'} = -\mathfrak{f}_{b, \sigma} = \beta_{i_2} - \beta_{i_1}$.

cycle by a pair of marked points, all components have a strictly negative Euler characteristics), and $l_{\delta*}$ is the natural inclusion into the moduli spaces of each connected component. In other words $\sum_{\delta} l_{\delta*}$ adds a nodal point in all possible stable ways, i.e. it adds two marked points, and ψ and ψ' are their ψ classes.

In fact, all tautological classes in $\overline{\mathcal{M}}_{g,n}$ can be expressed in terms of ψ -classes or their pull back or push forward from some $\overline{\mathcal{M}}_{h,m}$ [6]. Faber's conjecture [21] (partly proved in [46] and [31]) proposes an efficient method to compute intersection numbers of ψ, κ and Hodge classes.

C Bergman kernel of a spectral curve

Lemma 4.2 *Let σ, σ' be two vertices. Let $x \in \mathcal{C}_{\sigma}$ and $x' \in \mathcal{C}_{\sigma'}$, then we have*

$$\begin{aligned}
 & (2i\pi)^2 \left[\ln E(\mathcal{S}; \mathring{a}_{\sigma} + x, \mathring{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} \ln E(\mathcal{S}_{\sigma}; x, x') \right] \\
 = & \oint_{x_2 \in \partial_{\sigma} \mathcal{C}_{\sigma'}} \oint_{x_1 \in \partial_{\sigma'} \mathcal{C}_{\sigma}} \ln E(\mathcal{S}_{\sigma}; x, x_1) B(\mathcal{S}_{\sigma, \sigma'}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_{\sigma}) \ln E(\mathcal{S}_{\sigma'}; x_2, x') \\
 & + \sum_{\sigma_1} \oint_{x_2 \in \partial_{\sigma} \mathcal{C}_{\sigma_1}} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_{\sigma}} \ln E(\mathcal{S}_{\sigma}; x, x_1) B(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_{\sigma}) \\
 & \quad \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma'} + x') - \delta_{\sigma_1, \sigma'} \ln E(\mathcal{S}_{\sigma'}; x_2, x') \right)
 \end{aligned}
 \tag{C.1}$$

where

$$B(\mathcal{S}_{\sigma,\sigma'}; x_1, x_2) = A_{\sigma,\sigma'} \frac{1}{(\mathfrak{f}_{\sigma,\sigma'})^2} \frac{e^{-\frac{x_1}{\mathfrak{f}_{\sigma,\sigma'}}} e^{-\frac{x_2}{\mathfrak{f}_{\sigma,\sigma'}}}}{\left(e^{-\frac{x_1}{\mathfrak{f}_{\sigma,\sigma'}}} - e^{-\frac{x_2}{\mathfrak{f}_{\sigma,\sigma'}}}\right)^2} dx_1 \otimes dx_2 \quad (\text{C.2})$$

is the Bergman kernel on the cylinder $\mathcal{C}_{\sigma,\sigma'}$, $A_{\sigma,\sigma'}$ is the adjacency matrix of the toric graph, i.e. $A_{\sigma,\sigma'} = 1$ if σ and σ' are neighbors and 0 otherwise, and $\mathfrak{f}_{\sigma,\sigma'}$ is the framing of the edge (σ, σ') as defined in def 2.5.

proof:

For some choice of a basepoint o , we define the Cauchy kernel

$$dS(\mathcal{S}; x, x') = \int_{x''=o}^{x'} B(\mathcal{S}; x, x'') \quad (\text{C.3})$$

Notice that \mathcal{C} is not simply connected, neither is any pair of pants \mathcal{C}_σ nor any cylinder $\mathcal{C}_{\sigma,\sigma'}$, so the integral from o to x' might depend on the integration contour. However, since we have normalized our Bergman kernels on \mathcal{A} cycles (cf section 2.4), and \mathcal{A} -cycles surround cylinders, we see that $dS(\mathcal{S}; x, x')$ is globally well defined on any pair of pants \mathcal{C}_σ or on any cylinder $\mathcal{C}_{\sigma,\sigma'}$ (it would be ill defined on a subdomain of \mathcal{C} containing a \mathcal{B} -cycle because the \mathcal{B} -cycle integral of B does'nt vanish).

Locally near $x' = x$ it behaves like

$$dS(\mathcal{S}; x, x') \sim \frac{dx}{x - x'} + \text{analytical}. \quad (\text{C.4})$$

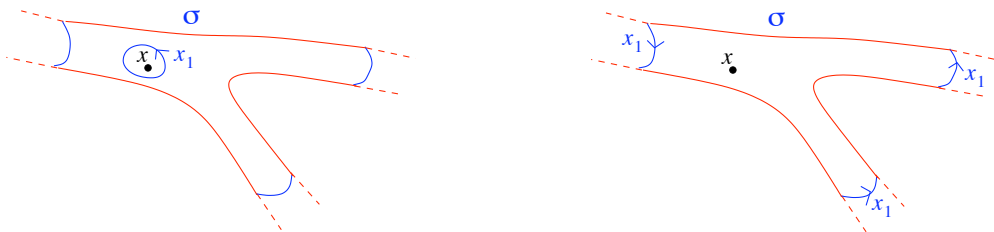
This can thus be used to write Cauchy formula, and we write:

$$B(\mathcal{S}; \overset{\circ}{a}_\sigma + x, \overset{\circ}{a}_{\sigma'} + x') = - \operatorname{Res}_{x_1 \rightarrow x} dS(\mathcal{S}_\sigma; x, x_1) B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_1, \overset{\circ}{a}_{\sigma'} + x') \quad (\text{C.5})$$

and by moving the integration contour (a small circle around x) to the boundaries of \mathcal{C}_σ (we pick a pole at $x_1 = x'$ in the case $x' \in \mathcal{C}_\sigma$, i.e. in the case $\sigma' = \sigma$), we get:

$$\begin{aligned} & B(\mathcal{S}; \overset{\circ}{a}_\sigma + x, \overset{\circ}{a}_{\sigma'} + x') - \delta_{\sigma,\sigma'} B(\mathcal{S}_\sigma, x, x') \\ &= - \sum_{\sigma_1} \frac{1}{2\pi i} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_1, \overset{\circ}{a}_{\sigma'} + x') \end{aligned} \quad (\text{C.6})$$

(we choose to orient the boundaries of \mathcal{C}_σ such that the surface lies on the left of its boundaries).

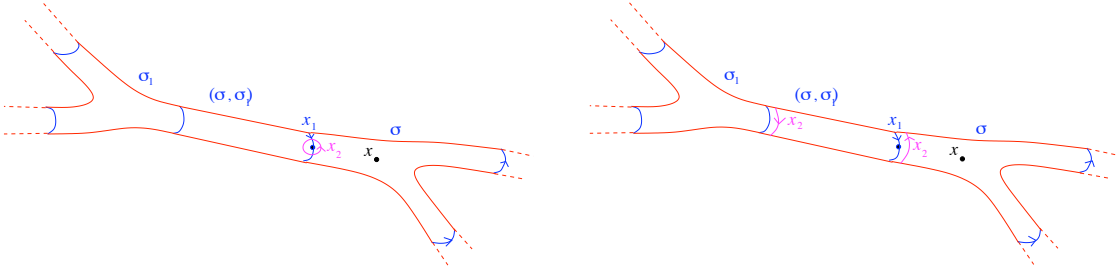


Then since $x_1 \in \mathcal{C}_{\sigma, \sigma_1}$, we write Cauchy formula again with the Cauchy kernel $dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2)$ of $\mathcal{C}_{\sigma, \sigma_1}$, i.e.

$$\begin{aligned}
& B(\mathcal{S}; \overset{\circ}{a}_\sigma + x, \overset{\circ}{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} B(\mathcal{S}_\sigma, x, x') \\
&= - \sum_{\sigma_1} \frac{1}{2\pi i} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_1, \overset{\circ}{a}_{\sigma'} + x') \\
&= \sum_{\sigma_1} \frac{1}{2\pi i} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} \text{Res}_{x_2 \rightarrow x_1} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2) B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_2, \overset{\circ}{a}_{\sigma'} + x') \\
& \quad (C.7)
\end{aligned}$$

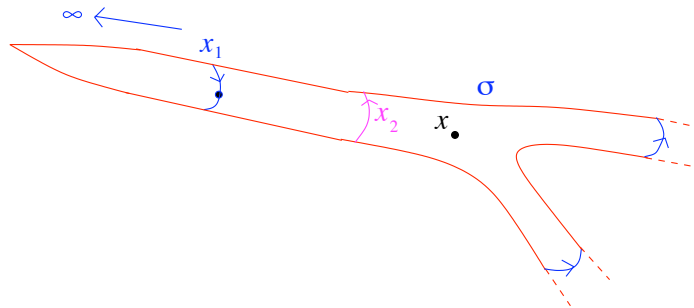
and again, moving the integration contour (a small circle around x_1) to a pair of circles around the cylinder $\mathcal{C}_{\sigma, \sigma_1}$, we get:

$$\begin{aligned}
& B(\mathcal{S}; \overset{\circ}{a}_\sigma + x, \overset{\circ}{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} B(\mathcal{S}_\sigma, x, x') \\
&= - \sum_{\sigma_1} \frac{1}{(2\pi i)^2} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} \oint_{x_2 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2) \\
& \quad B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_2, \overset{\circ}{a}_{\sigma'} + x') \\
&= - \sum_{\sigma_1} \frac{1}{(2\pi i)^2} \oint_{x_2 \in \partial_{\sigma} \mathcal{C}_{\sigma_1}} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2) \\
& \quad B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_2, \overset{\circ}{a}_{\sigma'} + x') \\
& \quad (C.8)
\end{aligned}$$



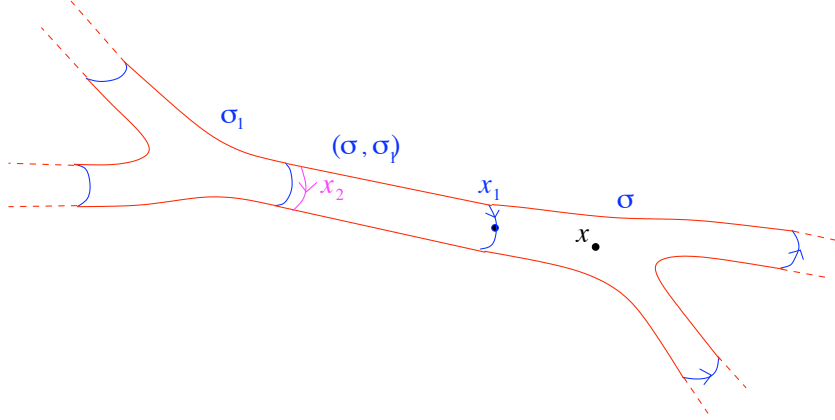
For the first line, notice that both \mathcal{C}_σ and $\mathcal{C}_{\sigma, \sigma_1}$ can be realized as the complex projective plane \mathbb{CP}^1 , and $\mathcal{C}_{\sigma, \sigma_1}$ can be realized as a subset of \mathcal{C}_σ (a disc around one of the punctures of $\mathcal{C}_\sigma = \mathbb{CP}^1 \setminus \{0, 1, \infty\}$) and we can send $x_1 \rightarrow \infty$ (i.e. to the puncture) without picking any singularity (because both $B(\mathcal{S}_\sigma; x, x_1)$ and $B(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2)$ are analytical at the punctures, they have poles only at coinciding points), i.e.

$$\oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} \oint_{x_2 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2) B(\mathcal{S}; \overset{\circ}{a}_\sigma + x_2, \overset{\circ}{a}_{\sigma'} + x') = 0 \quad (C.9)$$



Therefore, after changing the variable x_2 :

$$\begin{aligned}
& B(\mathcal{S}; \mathring{a}_\sigma + x, \mathring{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} B(\mathcal{S}_\sigma, x, x') \\
= & - \sum_{\sigma_1} \frac{1}{(2\pi i)^2} \oint_{x_2 \in \partial_\sigma \mathcal{C}_{\sigma_1}} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_\sigma) \\
& B(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma'} + x')
\end{aligned} \tag{C.10}$$



we may rewrite it as:

$$\begin{aligned}
& B(\mathcal{S}; \mathring{a}_\sigma + x, \mathring{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} B(\mathcal{S}_\sigma, x, x') \\
= & - \frac{1}{(2\pi i)^2} \oint_{x_2 \in \partial_\sigma \mathcal{C}_{\sigma'}} \oint_{x_1 \in \partial_{\sigma'} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma'}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma) B(\mathcal{S}_{\sigma'}; x_2, x') \\
& - \sum_{\sigma_1} \frac{1}{(2\pi i)^2} \oint_{x_2 \in \partial_\sigma \mathcal{C}_{\sigma_1}} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} dS(\mathcal{S}_\sigma; x, x_1) dS(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_\sigma) \\
& \left(B(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma'} + x') - \delta_{\sigma_1, \sigma'} B(\mathcal{S}_{\sigma'}; x_2, x') \right)
\end{aligned} \tag{C.11}$$

and integrating:

$$\begin{aligned}
& (2i\pi)^2 \left[\ln E(\mathcal{S}; \mathring{a}_\sigma + x, \mathring{a}_{\sigma'} + x') - \delta_{\sigma, \sigma'} \ln E(\mathcal{S}_\sigma, x, x') \right] \\
= & \oint_{x_2 \in \partial_\sigma \mathcal{C}_{\sigma'}} \oint_{x_1 \in \partial_{\sigma'} \mathcal{C}_\sigma} \ln E(\mathcal{S}_\sigma; x, x_1) B(\mathcal{S}_{\sigma, \sigma'}; x_1, x_2 + \mathring{a}_{\sigma'} - \mathring{a}_\sigma) \ln E(\mathcal{S}_{\sigma'}; x_2, x') \\
& + \sum_{\sigma_1} \oint_{x_2 \in \partial_\sigma \mathcal{C}_{\sigma_1}} \oint_{x_1 \in \partial_{\sigma_1} \mathcal{C}_\sigma} \ln E(\mathcal{S}_\sigma; x, x_1) B(\mathcal{S}_{\sigma, \sigma_1}; x_1, x_2 + \mathring{a}_{\sigma_1} - \mathring{a}_\sigma) \\
& \left(\ln E(\mathcal{S}; \mathring{a}_{\sigma_1} + x_2, \mathring{a}_{\sigma'} + x') - \delta_{\sigma_1, \sigma'} \ln E(\mathcal{S}_{\sigma'}; x_2, x') \right)
\end{aligned} \tag{C.12}$$

which proves the lemma. \square

D Local description of the spectral curve near branchpoints

Let $\mathcal{S} = (\mathcal{C}, x, y, B)$ be a regular spectral curve, let $\{\alpha_1, \alpha_2, \dots, \alpha_b\}$ be the set of its branchpoints, i.e. the zeroes of dx , and $a_i = x(\alpha_i)$. We first need to set up notations.

For each branchpoint a_σ we define the steepest descent path γ_σ , as a connected arc on \mathcal{C} passing through α_σ such that

$$x(\gamma_\sigma) - a_\sigma = \mathbb{R}_+, \quad (\text{D.1})$$

i.e. the vertical trajectory of x going through α_σ . In a vicinity of α_σ the following quantity is a good local coordinate

$$\sqrt{x(z) - a_\sigma}. \quad (\text{D.2})$$

D.1 Coefficients $\hat{B}_{\sigma,k;\sigma',l}$

We expand the Bergman kernel in the vicinity of branchpoints in powers of the local coordinates $\sqrt{x(z) - a}$ as follows:

$$\begin{aligned} B(z, z') \underset{\substack{z' \rightarrow \alpha_{\sigma'} \\ z \rightarrow \alpha_\sigma}}{\sim} & \left(\frac{\delta_{\sigma,\sigma'}}{(\sqrt{x(z) - a_\sigma} - \sqrt{x(z') - a_{\sigma'}})^2} \right. \\ & + \sum_{d,d' \geq 0} B_{\sigma,d;\sigma',d'} (x(z) - a_\sigma)^{d/2} (x(z') - a_{\sigma'})^{d'/2} \Big) \\ & \frac{dx(z) \otimes dx(z')}{4 \sqrt{x(z) - a_\sigma} \sqrt{x(z') - a_{\sigma'}}} \end{aligned} \quad (\text{D.3})$$

and then we define

$$\hat{B}_{\sigma,k;\sigma',k'} = (2k-1)!! (2l-1)!! 2^{-k-l-1} B_{\sigma,2k;\sigma',2k'}. \quad (\text{D.4})$$

It is useful to notice that the generating function of these last quantities can also be defined through Laplace transform, we define:

$$\check{B}_{\sigma,\sigma'}(u, v) = \sum_{k,k' \geq 0} \hat{B}_{\sigma,k;\sigma',k'} u^{-k} v^{-l}, \quad (\text{D.5})$$

which is given by the Laplace transform of the Bergman kernel

$$\check{B}_{\sigma,\sigma'}(u, v) = \delta_{\sigma,\sigma'} \frac{uv}{u+v} + \frac{\sqrt{uv} e^{ua_\sigma} e^{va_{\sigma'}}}{2\pi} \int_{z \in \gamma_\sigma} \int_{z' \in \gamma_{\sigma'}} B(z, z') e^{-ux(z)} e^{-vx(z')} \quad (\text{D.6})$$

where the double integral is conveniently regularized when $\sigma = \sigma'$, so that $\check{B}_{\sigma,\sigma'}(u, v)$ is a power series of u and v .

D.2 Basis of differential forms $d\xi_{\sigma,d}(z)$

We define the set of functions $\xi_{\sigma,d}(z)$ as follows:

$$d\xi_{\sigma,d}(z) = -(2d-1)!! 2^{-d} \operatorname{Res}_{z' \rightarrow \alpha_\sigma} B(z, z') (x(z') - a_\sigma)^{-1/2-d} \quad (\text{D.7})$$

It is a meromorphic 1-form defined on \mathcal{C} , with a pole only at $z = \alpha_\sigma$, of degree $2d + 2$.

Namely, near $z \rightarrow \alpha_{\sigma'}$ it behaves like

$$\xi_{\sigma,d}(z) \underset{z \rightarrow \alpha_{\sigma'}}{\sim} \delta_{\sigma,\sigma'} \frac{(2d-1)!!}{2^d (x(z) - a_{\sigma'})^{1/2+d}} - \frac{(2d-1)!!}{2^d} \sum_k \frac{1}{k+1} B_{\sigma,2d;\sigma',k} (x(z) - a_{\sigma'})^{\frac{k+1}{2}}. \quad (\text{D.8})$$

These differential forms will play an important role because they give the behavior of the Bergman kernel B near a branchpoint:

$$B(z, z') - B(\bar{z}, z') \underset{z \rightarrow a_\sigma}{\sim} -2 \sum_{d \geq 0} \frac{2^d}{(2d-1)!!} \zeta_{a_\sigma}(z)^{2d} d\zeta_{a_\sigma}(z) \otimes d\xi_{a_\sigma,d}(z') \quad (\text{D.9})$$

where $\zeta_{a_\sigma}(z) = \sqrt{x(z) - a_\sigma}$.

D.3 $f_{\sigma,\sigma'}(u)$

Knowing $\xi_{\sigma',0}(z)$, it is useful to define its Laplace transform along γ_σ as

$$\begin{aligned} f_{\sigma,\sigma'}(u) &= \frac{\sqrt{u}}{2\sqrt{\pi}} e^{ua_\sigma} \int_{\gamma_\sigma} e^{-ux} \xi_{\sigma',0} dx \\ &= \frac{1}{2\sqrt{\pi}u} e^{ua_\sigma} \int_{\gamma_\sigma} e^{-ux} d\xi_{\sigma',0} \\ &= \delta_{\sigma,\sigma'} - \sum_{k \geq 0} \frac{\hat{B}_{\sigma',0;\sigma,k}}{u^{k+1}}. \end{aligned} \quad (\text{D.10})$$

In [15], it was proved that

Lemma D.1 *If \mathcal{C} is a compact Riemann surface and dx is a meromorphic form on \mathcal{C} and B is the fundamental form of the second kind normalized on \mathcal{A} -cycles, we have*

$$\check{B}_{\sigma,\sigma'}(u, v) = \frac{uv}{u+v} \left(\delta_{\sigma,\sigma'} - \sum_{\sigma''=1}^b f_{\sigma,\sigma''}(u) f_{\sigma',\sigma''}(v) \right) \quad (\text{D.11})$$

so that all we need to compute is in fact $f_{\sigma,\sigma'}(u)$.

D.4 The times $\hat{t}_{\sigma,k}$

Finally we define the times $\hat{t}_{\sigma,k}$ at branchpoint a_σ in terms of the local behavior of $y(z)$ by the Laplace transform of ydx along γ_σ

$$e^{-\hat{t}_{\sigma,0}} e^{-g_\sigma(u)} = \frac{2u^{3/2} e^{ua_\sigma}}{\sqrt{\pi}} \int_{z \in \gamma_\sigma} e^{-ux(z)} y(z) dx(z) = \frac{2\sqrt{u} e^{ua_\sigma}}{\sqrt{\pi}} \int_{z \in \gamma_\sigma} e^{-ux(z)} dy(z) \quad (\text{D.12})$$

The times $\hat{t}_{\sigma,k}$ are the coefficients of the expansion of $g(u)$ at large u :

$$g_\sigma(u) = \sum_{k \geq 1} \hat{t}_{\sigma,k} u^{-k}. \quad (\text{D.13})$$

Notice that the time $\hat{t}_{\sigma,0}$ is given by

$$e^{-\hat{t}_{\sigma,0}} = \lim_{z \rightarrow \alpha_\sigma} \frac{y(z) - y(\bar{z})}{\sqrt{x(z) - a_\sigma}} \stackrel{\text{def}}{=} 2 y'(a_\sigma). \quad (\text{D.14})$$

Here we add another lemma:

Lemma D.2 *If \mathcal{C} is a compact Riemann algebraic surface of equation*

$$H(e^{-x}, e^{-y}) = 0 \quad (\text{D.15})$$

where H is a polynomial, and we assume that all poles of dy are also poles of dx , and the Bergman kernel B is the fundamental 2-form of the second kind normalized on \mathcal{A} -cycles (i.e. $\oint_{\mathcal{A}_i} B(\cdot, z) = 0$), then we have

$$e^{-g_\sigma(u)} = \sum_{\sigma'} e^{\hat{t}_{\sigma,0} - \hat{t}_{\sigma',0}} f_{\sigma,\sigma'}(u). \quad (\text{D.16})$$

proof:

Since e^{-x} and e^{-y} are meromorphic functions, their logarithmic derivatives are meromorphic forms, i.e. dx and dy are meromorphic forms, and thus

$$\frac{dy}{dx}$$

is a meromorphic function.

It has poles at all the zeroes of dx , namely

$$\frac{dy(z)}{dx(z)} \underset{z \rightarrow \alpha_\sigma}{\sim} \frac{y'(\alpha_\sigma)}{2 \sqrt{x(z) - x(\alpha_\sigma)}} \underset{z \rightarrow \alpha_\sigma}{\sim} \frac{y'(\alpha_\sigma)}{2} \xi_{\sigma,0}(z). \quad (\text{D.17})$$

Since dx and dy are logarithmic derivatives of meromorphic functions, they can only have simple poles, and we assumed that all poles of dy must also be poles of dx , therefore dy/dx has no pole at the poles of dy . The only poles of dy/dx are thus the α_σ , and therefore $dy/dx - \sum_\sigma y'(\alpha_\sigma) \xi_{\sigma,0}/2$ has no pole. Taking the differential once again says that

$$d \frac{dy}{dx} - \frac{1}{2} \sum_\sigma y'(\alpha_\sigma) d\xi_{\sigma,0} \quad (\text{D.18})$$

is a holomorphic differential without poles, therefore it can be written

$$d \frac{dy}{dx} = \frac{1}{2} \sum_\sigma y'(\alpha_\sigma) d\xi_{\sigma,0} + \sum_{i=1}^g c_i du_i \quad (\text{D.19})$$

where c_i are some coefficients determined by

$$c_i = -\frac{1}{2} \sum_{\sigma} y'(\alpha_{\sigma}) \oint_{\mathcal{A}_i} d\xi_{\sigma,0} = 0 \quad (\text{D.20})$$

(they vanish because $d\xi_{\sigma,0}$ is normalized on \mathcal{A}_i like B). This implies that

$$\frac{dy}{dx} = \frac{1}{2} \sum_{\sigma} y'(\alpha_{\sigma}) \xi_{\sigma,0} + C \quad (\text{D.21})$$

where C is some integration constant.

The Laplace transforms are:

$$e^{-\hat{t}_{\sigma,0}} e^{-g_{\sigma}(u)} = \frac{2\sqrt{u} e^{ua_{\sigma}}}{\sqrt{\pi}} \int_{\gamma_{\sigma}} e^{-ux} \frac{dy}{dx} dx \quad (\text{D.22})$$

and

$$f_{\sigma,\sigma'}(u) = \frac{\sqrt{u} e^{ua_{\sigma}}}{2\sqrt{\pi}} \int_{\gamma_{\sigma}} e^{-ux} \xi_{\sigma',0} dx \quad (\text{D.23})$$

We thus obtain (notice that the constant term doesn't contribute because it is the integral of a total derivative):

$$e^{-\hat{t}_{\sigma,0}} e^{-g_{\sigma}(u)} = 2 \sum_{\sigma'} y'(\alpha_{\sigma'}) f_{\sigma,\sigma'}(u) \quad (\text{D.24})$$

Notice that at large u we have $e^{-g_{\sigma}(u)} \rightarrow 1$ and $f_{\sigma,\sigma'}(u) \rightarrow \delta_{\sigma,\sigma'}$, therefore we recover the relationship eq. (D.14)

$$e^{-\hat{t}_{\sigma,0}} = 2y'(\alpha_{\sigma}) \quad (\text{D.25})$$

and finally as announced

$$e^{-g_{\sigma}(u)} = \sum_{\sigma'} e^{\hat{t}_{\sigma,0} - \hat{t}_{\sigma',0}} f_{\sigma,\sigma'}(u). \quad (\text{D.26})$$

□

D.5 More Lemmas

All the following formulae are easy to prove and we write them for bookkeeping purpose:

$$\frac{d\xi_{a,d}(z)}{dx(z)} = -\xi_{a,d+1}(z) - \sum_{a'} \hat{B}_{a,d;a',0} \xi_{a',0}(z) \quad (\text{D.27})$$

$$\left. \frac{\partial \xi_{a,d}(z)}{\partial Q} \right|_{x(z)} = \frac{\partial x(a)}{\partial Q} \xi_{a,d+1}(z) + \sum_{a'} \hat{B}_{a,d;a',0} \frac{\partial x(a')}{\partial Q} \xi_{a',0}(z) \quad (\text{D.28})$$

i.e.

$$\left. \frac{\partial \xi_{a,d}(z)}{\partial Q} \right|_{x(z)} + \frac{\partial x(a)}{\partial Q} \frac{d\xi_{a,d}(z)}{dx(z)} = \sum_{a' \neq a} \hat{B}_{a,d;a',0} \left(\frac{\partial x(a')}{\partial Q} - \frac{\partial x(a)}{\partial Q} \right) \xi_{a',0}(z) \quad (\text{D.29})$$

$$\frac{\partial f_{a'',a}(u)}{\partial Q} = u \left(\frac{\partial x(a'')}{\partial Q} - \frac{\partial x(a)}{\partial Q} \right) f_{a'',a}(u) + \sum_{a' \neq a} \hat{B}_{a,0;a',0} \left(\frac{\partial x(a')}{\partial Q} - \frac{\partial x(a)}{\partial Q} \right) f_{a'',a'}(u) \quad (\text{D.30})$$

$$\frac{\partial \hat{B}_{a,0;a'',k}}{\partial Q} = \left(\frac{\partial x(a'')}{\partial Q} - \frac{\partial x(a)}{\partial Q} \right) \hat{B}_{a,0;a'',k+1} + \sum_{a' \neq a} \hat{B}_{a,0;a',0} \left(\frac{\partial x(a')}{\partial Q} - \frac{\partial x(a)}{\partial Q} \right) \hat{B}_{a',0;a'',k} \quad (\text{D.31})$$

E Invariants of the topological vertex

Theorem E.1 [*"Mariño–Vafa formula"*] we have:

$$\begin{aligned} & W_{g,n}(\overset{\circ}{\mathcal{S}}_{\mathfrak{f}}; x_1, \dots, x_n) \\ &= \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f},0}(2-2g-n)}} \sum_{\{d_i\}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_a) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_b) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_a - \mathfrak{f}_b) \prod_{i=1}^n \tau_{d_i} \right\rangle_{g,n} \prod_{i=1}^n d\tilde{\xi}_{\mathfrak{f},d_i}^{\circ}(x_i) \end{aligned} \quad (\text{E.1})$$

where, if x lies near the puncture of $\mathbb{P}^1 \setminus \{0, 1, \infty\}$ (i.e. $z = 0, 1$ or ∞) corresponding to the half-edge ϵ , (whose framing is $\mathfrak{f}_{\epsilon} = \mathfrak{f}_b, \mathfrak{f}_a$ or $-\mathfrak{f}_a - \mathfrak{f}_b$ respectively):

$$\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = (-1)^d \left(\frac{d}{dx} \right)^d \overset{\circ}{\xi}_{\mathfrak{f},0}(x) = \sum_k \frac{k^{d+1}}{\mathfrak{f}_{\epsilon}^{d+2}} \gamma_{\mathfrak{f}}(k/\mathfrak{f}_{\epsilon}) e^{-\frac{k}{\mathfrak{f}_{\epsilon}} x} dx. \quad (\text{E.2})$$

Thus, if x_i lies near the puncture corresponding to the half-edge ϵ_i , (whose framing is \mathfrak{f}_{ϵ}):

$$\begin{aligned} & W_{g,n}(\overset{\circ}{\mathcal{S}}_{\mathfrak{f}}; x_1, \dots, x_n) \\ &= \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f},0}(2-2g-n)}} \sum_{\{k_i\}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_a) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_b) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_a - \mathfrak{f}_b) \prod_{i=1}^n \frac{1}{1 - \frac{k_i}{\mathfrak{f}_{\epsilon_i}}} \psi_i \right\rangle_{g,n} \\ & \quad \prod_{i=1}^n \frac{k_i}{\mathfrak{f}_{\epsilon_i}^2} \gamma_{\mathfrak{f}}(k_i/\mathfrak{f}_{\epsilon_i}) e^{-\frac{k_i}{\mathfrak{f}_{\epsilon_i}} x_i} dx_i \end{aligned} \quad (\text{E.3})$$

where the sum carries over positive integers $(k_1, \dots, k_n) \in \mathbb{Z}_+^n$.

proof:

This is a mere application of theorem 4.1, and is fully proved in [14], or alternatively, it can be seen as a consequence of the proof of BKMP for the framed vertex [11, 53].

According to theorem 4.1 the invariants of $\mathring{\mathcal{S}}_{\mathfrak{f}}$ are

$$W^{g,n}(\mathring{\mathcal{S}}_{\mathfrak{f}}; x_1, \dots, x_n) = \frac{2^{3g-3+n}}{e^{-\hat{t}_{\mathfrak{f},0}(2g-2+n)}} \sum_{d_1, \dots, d_n} \left\langle \hat{\Lambda}_{\mathring{\mathcal{S}}(\mathfrak{f})} \prod_{i=1}^n \psi_i^{d_i} \right\rangle_{\mathcal{M}_{g,n}} \prod_{i=1}^n d\mathring{\xi}_{\mathfrak{f},d}(x_i) \quad (\text{E.4})$$

where the classes $\hat{\Lambda}_{\mathring{\mathcal{S}}(\mathfrak{f})}$ and $d\mathring{\xi}_{\mathfrak{f},d}(x)$ are computed from the recipe given in theorem 4.1:

- the times $\hat{t}_{\mathfrak{f},k}$: their generating function $\mathring{g}_{\mathfrak{f}}(u) = \sum_k \hat{t}_{\mathfrak{f},k} u^{-k}$ is obtained by computing the Laplace transform of ydx :

$$\begin{aligned} e^{-\hat{t}_{\mathfrak{f},0}} e^{-\mathring{g}_{\mathfrak{f}}(u)} &= \frac{2u^{3/2}}{\sqrt{\pi}} \int_{\gamma} e^{-u\mathring{x}} \mathring{y} d\mathring{x} \\ &= \frac{2u^{1/2}}{\sqrt{\pi}} \int_{\gamma} e^{-u\mathring{x}} d\mathring{y} \\ &= \frac{2u^{1/2}}{\sqrt{\pi}} \frac{(\mathfrak{f}_a + \mathfrak{f}_b)^{(\mathfrak{f}_a + \mathfrak{f}_b)u}}{\mathfrak{f}_a^{\mathfrak{f}_a u} \mathfrak{f}_b^{\mathfrak{f}_b u}} \int_0^1 z^{\mathfrak{f}_b u} (1-z)^{\mathfrak{f}_a u} \left(\frac{\mathfrak{f}_c}{1-z} - \frac{\mathfrak{f}_d}{z} \right) dz \\ &= \frac{2u^{1/2}}{\sqrt{\pi}} \frac{(\mathfrak{f}_a + \mathfrak{f}_b)^{(\mathfrak{f}_a + \mathfrak{f}_b)u}}{\mathfrak{f}_a^{\mathfrak{f}_a u} \mathfrak{f}_b^{\mathfrak{f}_b u}} \left(\mathfrak{f}_c \frac{\Gamma(\mathfrak{f}_b u + 1) \Gamma(\mathfrak{f}_a u)}{\Gamma((\mathfrak{f}_a + \mathfrak{f}_b)u + 1)} - \mathfrak{f}_d \frac{\Gamma(\mathfrak{f}_b u) \Gamma(\mathfrak{f}_a u + 1)}{\Gamma((\mathfrak{f}_a + \mathfrak{f}_b)u + 1)} \right) \\ &= \frac{\mathfrak{f}_c \mathfrak{f}_b - \mathfrak{f}_d \mathfrak{f}_a}{\mathfrak{f}_a + \mathfrak{f}_b} \frac{2\sqrt{u} (\mathfrak{f}_a + \mathfrak{f}_b)^{(\mathfrak{f}_a + \mathfrak{f}_b)u}}{\sqrt{\pi} \mathfrak{f}_a^{\mathfrak{f}_a u} \mathfrak{f}_b^{\mathfrak{f}_b u}} \frac{\Gamma(\mathfrak{f}_a u) \Gamma(\mathfrak{f}_b u)}{\Gamma((\mathfrak{f}_a + \mathfrak{f}_b)u)} \\ &= - \frac{2\sqrt{2}}{\sqrt{\mathfrak{f}_a \mathfrak{f}_b (\mathfrak{f}_a + \mathfrak{f}_b)}} \frac{\hat{\Gamma}(\mathfrak{f}_a u) \hat{\Gamma}(\mathfrak{f}_b u)}{\hat{\Gamma}((\mathfrak{f}_a + \mathfrak{f}_b)u)} \\ &= - \frac{2\sqrt{2}}{\sqrt{\mathfrak{f}_a \mathfrak{f}_b (\mathfrak{f}_a + \mathfrak{f}_b)}} \frac{1}{\sqrt{\pi u} \gamma_{\mathfrak{f}}(u)} \end{aligned} \quad (\text{E.5})$$

where $\gamma_{\mathfrak{f}}(u)$ was introduced in eq. (3.21) for the localization formula in theorem 3.7:

$$\gamma_{\mathfrak{f}}(u) = \frac{1}{\sqrt{\pi u}} \frac{\hat{\Gamma}(u(\mathfrak{f}_a + \mathfrak{f}_b))}{\hat{\Gamma}(u \mathfrak{f}_a) \hat{\Gamma}(u \mathfrak{f}_b)}. \quad (\text{E.6})$$

That gives

$$e^{-\hat{t}_{\mathfrak{f},0}} = \frac{-2\sqrt{2}}{\sqrt{\mathfrak{f}_a \mathfrak{f}_b (\mathfrak{f}_a + \mathfrak{f}_b)}} \quad (\text{E.7})$$

and, using the Stirling expansion of the Log of the Gamma-function:

$$\mathring{g}_{\mathfrak{f}}(u) = \sum_{k \geq 1} u^{-k} \hat{t}_{\mathfrak{f},k} = \sum_{k \geq 1} u^{1-2k} \frac{\mathcal{B}_{2k}}{2k(2k-1)} ((\mathfrak{f}_a + \mathfrak{f}_b)^{1-2k} - \mathfrak{f}_a^{1-2k} - \mathfrak{f}_b^{1-2k}) \quad (\text{E.8})$$

where \mathcal{B}_k is the k^{th} Bernoulli number.

• the functions $\overset{\circ}{\xi}_{f,d}$ are found from eq. (4.23). For $d = 0$, eq. (4.23) implies that $\overset{\circ}{\xi}_{f,0}(x)$ is a meromorphic function on \mathcal{C}_σ , i.e. a rational function of the variable $z \in \mathbb{P}^1$, and with a simple pole at the branchpoint, and which behaves like:

$$\overset{\circ}{\xi}_{f,0}(x) \underset{x \rightarrow 0}{\sim} \frac{1}{\sqrt{x}} + \text{analytical.} \quad (\text{E.9})$$

We thus easily find the unique rational fraction of z having that property:

$$\overset{\circ}{\xi}_{f,0}(x) = \sqrt{\frac{2f_a f_b}{f_a + f_b}} \frac{1}{(f_a + f_b)z - f_b} \quad \text{where } x = \overset{\circ}{x}_f(z). \quad (\text{E.10})$$

Its Laplace transform is

$$\begin{aligned} f(u) &= \frac{\sqrt{u}}{2\sqrt{\pi}} \int_{z=0}^1 e^{-u\overset{\circ}{x}(z)} \overset{\circ}{\xi}_{f,0}(\overset{\circ}{x}(z)) d\overset{\circ}{x}(z) \\ &= \sqrt{\frac{2f_a f_b}{f_a + f_b}} \frac{\sqrt{u}}{2\sqrt{\pi}} \frac{(f_a + f_b)^{(f_a + f_b)u}}{f_a^{f_a u} f_b^{f_b u}} \int_{z=0}^1 z^{f_b u} (1-z)^{f_a u} \frac{dz}{z(1-z)} \\ &= \sqrt{\frac{f_a f_b}{f_a + f_b}} \frac{\sqrt{u}}{\sqrt{2\pi}} \frac{(f_a + f_b)^{(f_a + f_b)u}}{f_a^{f_a u} f_b^{f_b u}} \frac{\Gamma(f_a u) \Gamma(f_b u)}{\Gamma((f_a + f_b)u)} \\ &= e^{-g_f(u)} \end{aligned} \quad (\text{E.11})$$

(we could also have obtained this result directly from lemma D.2 in the appendix D).

Lemma E.1 *In general, if ϵ is one of the punctures $0, 1, \infty$, we write $f_\epsilon = f_a, f_b, -f_a - f_b$ respectively, and we have when x approaches the puncture ϵ :*

$$\overset{\circ}{\xi}_{f,0}(x) = \frac{-1}{f_\epsilon} \sum_{k=0}^{\infty} \gamma_f(k/f_\epsilon) e^{-\frac{k}{f_\epsilon} x} \quad (\text{E.12})$$

proof:

Let us prove it near the puncture $z = 0$ in $\mathbb{P}^1 \setminus \{0, 1, \infty\}$ (the other cases are obtained in the same way), we have $z \sim e^{-\overset{\circ}{x}(z)/f_b}$, and thus the Taylor expansion of $\overset{\circ}{\xi}_{f,0}$ into powers of z near $z \rightarrow 0$ gives a Fourier expansion in powers of $e^{-k\overset{\circ}{x}(z)/f_b}$:

$$\overset{\circ}{\xi}_{f,0}(x) \sim \sum_{k=0}^{\infty} c_k e^{-k \frac{x}{f_b}}, \quad (\text{E.13})$$

where the coefficients c_k can be computed by a residue formula:

$$\begin{aligned} c_k &= - \operatorname{Res}_{z \rightarrow 0} e^{k \frac{x}{f_b}} \overset{\circ}{\xi}_{f,0}(x) \frac{dx}{f_b} \\ &= \sqrt{\frac{2f_a f_b}{f_a + f_b}} \frac{f_a^k \frac{f_a}{f_b} f_b^k}{(f_a + f_b)^k \frac{f_a + f_b}{f_b}} \operatorname{Res}_{z \rightarrow 0} z^{-k} (1-z)^{-k \frac{f_a}{f_b}} \end{aligned}$$

$$\begin{aligned}
& \frac{1}{(\mathfrak{f}_a + \mathfrak{f}_b)z - \mathfrak{f}_b} \left(\frac{1}{z} + \frac{\mathfrak{f}_a}{\mathfrak{f}_b} \frac{1}{z-1} \right) dz \\
&= \frac{-1}{\mathfrak{f}_b} \sqrt{\frac{2\mathfrak{f}_a\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b}} \frac{\mathfrak{f}_a^k \frac{\mathfrak{f}_a}{\mathfrak{f}_b} \mathfrak{f}_b^k}{(\mathfrak{f}_a + \mathfrak{f}_b)^{k \frac{\mathfrak{f}_a + \mathfrak{f}_b}{\mathfrak{f}_b}}} \operatorname{Res}_{z \rightarrow 0} z^{-k-1} (1-z)^{-k \frac{\mathfrak{f}_a}{\mathfrak{f}_b} - 1} dz \\
&= \frac{-(\mathfrak{f}_a + \mathfrak{f}_b)}{\mathfrak{f}_a \mathfrak{f}_b} \sqrt{\frac{2\mathfrak{f}_a\mathfrak{f}_b}{\mathfrak{f}_a + \mathfrak{f}_b}} \frac{\mathfrak{f}_a^k \frac{\mathfrak{f}_a}{\mathfrak{f}_b} \mathfrak{f}_b^k}{(\mathfrak{f}_a + \mathfrak{f}_b)^{k \frac{\mathfrak{f}_a + \mathfrak{f}_b}{\mathfrak{f}_b}}} \frac{\Gamma(k \frac{\mathfrak{f}_a + \mathfrak{f}_b}{\mathfrak{f}_b})}{k! \Gamma(k \frac{\mathfrak{f}_a}{\mathfrak{f}_b})}
\end{aligned} \tag{E.14}$$

In other words we have

$$\begin{aligned}
\overset{\circ}{\xi}_{\mathfrak{f},0}(x) &= -\sqrt{\frac{2(\mathfrak{f}_a + \mathfrak{f}_b)}{\mathfrak{f}_a \mathfrak{f}_b}} \sum_{k=0}^{\infty} \frac{\mathfrak{f}_a^k \frac{\mathfrak{f}_a}{\mathfrak{f}_b} \mathfrak{f}_b^k}{(\mathfrak{f}_a + \mathfrak{f}_b)^{k \frac{\mathfrak{f}_a + \mathfrak{f}_b}{\mathfrak{f}_b}}} \frac{\Gamma(k \frac{\mathfrak{f}_a + \mathfrak{f}_b}{\mathfrak{f}_b})}{k! \Gamma(k \frac{\mathfrak{f}_a}{\mathfrak{f}_b})} e^{-\frac{k}{\mathfrak{f}_b} x} \\
&= -\frac{1}{\mathfrak{f}_b} \sum_k \gamma_{\mathfrak{f}}(k/\mathfrak{f}_b) e^{-\frac{k}{\mathfrak{f}_b} x}
\end{aligned} \tag{E.15}$$

This could also have been deduced by doing the inverse Laplace transform of eq. (E.11) and see that

$$\overset{\circ}{\xi}_{\mathfrak{f},0}(z) = -\frac{1}{2\pi i} \oint du \frac{2\sqrt{\pi}}{\sqrt{u}} f(u) e^{ux} \tag{E.16}$$

where the integration contour surrounds in the trigonometric direction all the points $-k/\mathfrak{f}_b$, $k \in \mathbb{N}$ (i.e. the poles of $\Gamma(\mathfrak{f}_b u)$), but not the points $-k/\mathfrak{f}_a$ (poles of $\Gamma(\mathfrak{f}_a u)$). Writing that this integral is the sum of residues at all poles of $\Gamma(\mathfrak{f}_b u)$ i.e. at $u = -k/\mathfrak{f}_b$ gives the expansion eq. (E.15).

□

• The coefficients $\hat{B}_{k,l}$. Their generating function $\hat{B}(u, v) = \sum_{k,l} \hat{B}_{k,l} u^{-k} v^{-l}$ is obtained from lemma D.1 in the appendix, i.e.

$$\hat{B}_{\mathfrak{f}}(u, v) = uv \frac{1 - f(u) f(v)}{u + v} = uv \frac{1 - e^{-\overset{\circ}{g}_{\mathfrak{f}}(u)} e^{-\overset{\circ}{g}_{\mathfrak{f}}(v)}}{u + v}. \tag{E.17}$$

Then, using Mumford formula [47] for the Hodge class:

$$\hat{\Lambda}_{\text{Hodge}}(\alpha) = e^{-\sum_{k=1}^{\infty} \frac{\mathcal{B}_{2k} \alpha^{1-2k}}{2k(2k-1)}} (\kappa_{2k-1} - \sum_{i=1}^n \psi_i^{2k-1} + \frac{1}{2} \sum_{\delta \in \partial \mathcal{M}_{g,n}} \sum_{l=0}^{2k-2} (-1)^l l_{\delta^*} \tau_l \tau_{2k-2-l}) \tag{E.18}$$

one can show (done in [14]) that the class $\hat{\Lambda}_{\mathcal{S}_{\mathfrak{f}}}$ defined in eq. (4.24), is a product of 3 Hodge classes:

Theorem E.2 (*proved in [14]*)

$$\hat{\Lambda}_{\mathcal{S}(\mathfrak{f})} \prod_{i=1}^n e^{-\overset{\circ}{g}_{\mathfrak{f}}(1/\psi_i)} = \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_a) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_b) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_a - \mathfrak{f}_b) \tag{E.19}$$

- The forms $d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x)$.

In order to absorb the term $e^{-\mathring{g}_{\mathfrak{f}}(1/\psi)}$ in theorem E.2 above, we shall define $d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x)$ such that:

$$\sum_d \psi^d d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = e^{-\mathring{g}_{\mathfrak{f}}(1/\psi)} \sum_d \psi^d d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x). \quad (\text{E.20})$$

For that purpose, let us start from eq. (D.9), and Laplace transform:

$$\sum_d u^{-d} d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = -\frac{\sqrt{u}}{\sqrt{\pi}} \oint_{\gamma} e^{-ux'} B(x', x) \quad (\text{E.21})$$

Doing another Laplace transform in x implies

$$\begin{aligned} \frac{\sqrt{v}}{2\sqrt{\pi}} \sum_d u^{-d} \oint_{\gamma} e^{-vx} d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) &= \frac{uv}{u+v} - \hat{B}(u, v) \\ &= \frac{uv e^{-\mathring{g}_{\mathfrak{f}}(u)} e^{-\mathring{g}_{\mathfrak{f}}(v)}}{u+v} \\ &= -\sum_d u^{-d} (-v)^{d+1} e^{-\mathring{g}_{\mathfrak{f}}(u)} e^{-\mathring{g}_{\mathfrak{f}}(v)} \\ &= -e^{-\mathring{g}_{\mathfrak{f}}(u)} \sum_d u^{-d} (-v)^{d+1} \frac{\sqrt{v}}{2\sqrt{\pi}} \oint_{\gamma} \tilde{\xi}_{\mathfrak{f},0}^{\circ}(x) e^{-vx} dx \\ &= -e^{-\mathring{g}_{\mathfrak{f}}(u)} \sum_d u^{-d} \frac{\sqrt{v}}{2\sqrt{\pi}} \oint_{\gamma} \tilde{\xi}_{\mathfrak{f},0}^{\circ}(x) (d/dx)^{d+1} e^{-vx} dx \\ &= -e^{-\mathring{g}_{\mathfrak{f}}(u)} \sum_d u^{-d} \frac{\sqrt{v}}{2\sqrt{\pi}} \oint_{\gamma} e^{-vx} (-d/dx)^{d+1} \tilde{\xi}_{\mathfrak{f},0}^{\circ}(x) dx \end{aligned} \quad (\text{E.22})$$

In other words

$$\sum_d u^{-d} \tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = e^{-\mathring{g}_{\mathfrak{f}}(u)} \sum_d u^{-d} (-d/dx)^d \tilde{\xi}_{\mathfrak{f},0}^{\circ}(x) \quad (\text{E.23})$$

We are thus led to define:

$$\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = (-1)^d (d/dx)^d \tilde{\xi}_{\mathfrak{f},0}^{\circ}(x). \quad (\text{E.24})$$

Using lemma E.1, we can expand $\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x)$ as:

$$\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = \sum_{k=0}^{\infty} \gamma_{\mathfrak{f}}(k/\mathfrak{f}_{\epsilon}) e^{-\frac{k}{\mathfrak{f}_{\epsilon}} x} \frac{-k^d}{\mathfrak{f}_{\epsilon}^{d+1}} \quad (\text{E.25})$$

and thus

$$\sum_d \psi^d d\tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = e^{-\mathring{g}_{\mathfrak{f}}(1/\psi)} \sum_d \psi^d \tilde{\xi}_{\mathfrak{f},d}^{\circ}(x) = e^{-\mathring{g}_{\mathfrak{f}}(1/\psi)} \frac{-1}{\mathfrak{f}_{\epsilon}} \sum_{k=0}^{\infty} \gamma_{\mathfrak{f}}(k/\mathfrak{f}_{\epsilon}) e^{-\frac{k}{\mathfrak{f}_{\epsilon}} x} \frac{1}{1 - \frac{k}{\mathfrak{f}_{\epsilon}} \psi} \quad (\text{E.26})$$

□

E.1 Summary of some formulae for the topological vertex

$$e^{-g(u)} = \frac{(f+1)^{(f+1)u} \sqrt{u}}{f^{fu} \sqrt{2\pi}} \frac{\Gamma(u) \Gamma(fu)}{\Gamma((f+1)u)} \quad (\text{E.27})$$

$$\mathring{B}(u, v) = uv \frac{1 - e^{-g(u)} e^{-g(v)}}{u - v} \quad (\text{E.28})$$

Notice that $g(u) = -g(-u)$ and we can write in the large u expansion:

$$e^{-g(-u)} = \frac{(f+1)^{(f+1)u} \sqrt{2\pi}}{f^{fu} \sqrt{u}} \frac{\Gamma((f+1)u)}{\Gamma(u) \Gamma(fu)} \quad (\text{E.29})$$

We also have:

$$\tilde{\xi}_{\mathfrak{f},d}(x) = \frac{-1}{\mathfrak{f}_\epsilon} \sum_{k=0}^{\infty} \gamma_{\mathfrak{f}}(k/\mathfrak{f}_\epsilon) e^{-\frac{k}{\mathfrak{f}_\epsilon} x} (k/\mathfrak{f}_\epsilon)^d \quad (\text{E.30})$$

$$dy_{\mathfrak{f}}(x) = \frac{-1}{\mathfrak{f}_\epsilon} \frac{e^{-\hat{t}_{\mathfrak{f},0}}}{4} \sum_{k=0}^{\infty} \gamma_{\mathfrak{f}}(k/\mathfrak{f}_\epsilon) e^{-\frac{k}{\mathfrak{f}_\epsilon} x} dx \quad (\text{E.31})$$

$$\mathring{B}_{\mathfrak{f}}(x, x') = \frac{1}{\mathfrak{f}_\epsilon \mathfrak{f}_{\epsilon'}} \sum_{k,l} \frac{\gamma_{\mathfrak{f}}(k/\mathfrak{f}_\epsilon) \gamma_{\mathfrak{f}}(l/\mathfrak{f}_{\epsilon'})}{\frac{k}{\mathfrak{f}_\epsilon} + \frac{l}{\mathfrak{f}_{\epsilon'}}} e^{-\frac{k}{\mathfrak{f}_\epsilon} x} e^{-\frac{l}{\mathfrak{f}_{\epsilon'}} x'} \frac{k}{\mathfrak{f}_\epsilon} dx \frac{l}{\mathfrak{f}_{\epsilon'}} dx' \quad (\text{E.32})$$

F Proof of Lemma 4.1

Lemma 4.1 *If $2 - 2g - n < 0$*

$$\begin{aligned} & W_{g,n}(\mathcal{S}_\sigma; x_1, \dots, x_n) \\ &= \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f}_\sigma,0}(2-2g-n)}} \sum_{k=0}^{\infty} \frac{1}{k!} \sum_{d_1, \dots, d_{n+k}} \prod_{i=1}^k R_{\sigma, d_{n+i}} \\ & \quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \prod_{j=1}^{n+k} \tau_{d_j} \right\rangle_{g, n+k} \prod_{j=1}^n d\tilde{\xi}_{\mathfrak{f}_\sigma, d_j}(x_j) \\ &= \frac{2^{3g-3+n}}{e^{\hat{t}_{\mathfrak{f}_\sigma,0}(2-2g-n)}} \sum_{d_1, \dots, d_n} \prod_{j=1}^n d\tilde{\xi}_{\mathfrak{f}_\sigma, d_j}(x_j) \\ & \quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) e^{l_{1*} \sum_d R_{\sigma, d} \tau_d} \prod_{j=1}^n \tau_{d_j} \right\rangle_{g, n} \end{aligned} \quad (\text{F.1})$$

where

$$R_{\sigma, d} = \frac{-2e^{\hat{t}_{\mathfrak{f}_\sigma,0}}}{2\pi i} \oint_{\partial \mathcal{C}_\sigma} \tilde{\xi}_{\mathfrak{f}_\sigma, d}(x) (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x)) dx, \quad (\text{F.2})$$

where $\partial\mathcal{C}_\sigma$ is the boundary of \mathcal{C}_σ , i.e. the union of three circles, oriented so that \mathcal{C}_σ lies on the left of $\partial\mathcal{C}_\sigma$. In the second equality, l_{1*} denotes the natural inclusion of $\mathcal{M}_{g,n} \subset \mathcal{M}_{g,n+1}$, so that $e^{l_{1*}\sum_d C_{\sigma,d}\psi^d}$ is just a short hand notation for the formula above.

And similarly for $(g, n) = (0, 2)$:

$$\begin{aligned}
W_{0,2}(\mathcal{S}_\sigma; x_1, x_2) &= B_\sigma(x_1, x_2) = \mathring{B}_{\mathfrak{f}_\sigma}(x_1 - a_\sigma + \mathring{a}_\sigma, x_2 - a_\sigma + \mathring{a}_\sigma) \\
&= \mathring{B}_{\mathfrak{f}_\sigma}(x_1, x_2) + \frac{1}{2} \sum_{k=1}^{\infty} \frac{1}{k!} \sum_{d_1, \dots, d_{k+2}} d\tilde{\xi}_{\mathfrak{f}_\sigma, d_1}(x_1) d\tilde{\xi}_{\mathfrak{f}_\sigma, d_2}(x_2) \prod_{i=3}^{k+2} R_{\sigma, d_i} \\
&\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \prod_{j=1}^{k+2} \tau_{d_j} \right\rangle_{0, k+2}
\end{aligned} \tag{F.3}$$

and for $(g, n) = (0, 1)$:

$$\begin{aligned}
W_{0,1}(\mathcal{S}_\sigma; x_1) &= (y(x_1 + \mathring{a}_\sigma) - \mathring{b}_\sigma) dx_1 \\
&= \mathring{y}_{\mathfrak{f}_\sigma}(x_1) dx_1 + \frac{1}{2\pi i} \oint_{\partial\mathcal{C}_\sigma} \mathring{B}_{\mathfrak{f}_\sigma}(x_1, x') \Phi(x') \\
&\quad + \frac{e^{-\hat{t}_{\mathfrak{f}_\sigma, 0}}}{4} \sum_{k=2}^{\infty} \frac{1}{k!} \sum_{d_1, \dots, d_{k+1}} d\tilde{\xi}_{\mathfrak{f}_\sigma, d_1}(x_1) \prod_{i=2}^{k+1} R_{\sigma, d_i} \\
&\quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathfrak{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathfrak{f}_{a,\sigma} - \mathfrak{f}_{b,\sigma}) \tau_{d_1} \prod_{j=2}^{k+1} \tau_{d_j} \right\rangle_{0, k+1}
\end{aligned} \tag{F.4}$$

proof:

The proof is based on the fact that almost by definition this lemma holds at the tropicla limit $t_j = +\infty$, and then, in order to show that it holds for all t_j 's (in an open vicinity of $t_j = +\infty$), we prove using special geometry, that both sides obey the same differential equation.

First, notice that $W_{g,n}(\mathring{\mathcal{S}}(\mathfrak{f}_\sigma); x_1, \dots, x_n)$ is a meromorphic form on $\mathcal{C}_\sigma = \mathbb{C} \setminus \{0, 1, \infty\}$, i.e. on \mathbb{CP}^1 , which has poles only at the branchpoint $x_i = 0$ without residue (when $2g - 2 + n > 0$), and thus its primitive is a meromorphic function. In other words

$$W_{g,n}(\mathring{\mathcal{S}}(\mathfrak{f}_\sigma); x_1, \dots, x_n) = d_1 \otimes \dots \otimes d_n \mathring{\Phi}_{g,n}(\mathring{\mathcal{S}}(\mathfrak{f}_\sigma); x_1, \dots, x_n) \tag{F.5}$$

and $\mathring{\Phi}_{g,n}$ is an algebraic function of each $X_i = e^{-x_i}$ for all $i = 1, \dots, n$, having a square-root branchcut $[0, \infty[$. In particular, it is analytical in a vicinity of $\partial\mathcal{C}_\sigma$ (see figure 6).

Notice that, by definition of $\mathring{y}_{\mathfrak{f}}$, $y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x)$ vanishes in the tropical limit $t_i \rightarrow +\infty$, i.e. at $Q_i = e^{-t_i} = 0$, and can be Taylor expanded in powers of $\mathbf{Q} = \{Q_i\}$ near $\mathbf{Q} = 0$.

Indeed, first observe that the coefficients $H_{i,j}$ of the algebraic equation $H_f(X, Y) = 0$, have a Laurent expansion in powers of \mathbf{Q} . Since \mathring{a}_σ and \mathring{b}_σ are linear combinations of the t_i 's, i.e. $e^{-\mathring{a}_\sigma}$ and $e^{-\mathring{b}_\sigma}$ are product or ratios of the Q_i 's, we see that $Y(x + \mathring{a}_\sigma)e^{\mathring{b}_\sigma}$ is an algebraic function of e^{-x} , which has a Laurent expansion into powers of Q_i 's. This implies that

$$\frac{\partial}{\partial Q_i} (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x)) = -\frac{1}{Y(x + \mathring{a}_\sigma)} \left(\frac{\partial Y(x + \mathring{a}_\sigma)}{\partial Q_i} + \frac{\partial \mathring{a}_\sigma}{\partial Q_i} \frac{\partial Y(x + \mathring{a}_\sigma)}{\partial x} \right) - \frac{\partial \mathring{b}_\sigma}{\partial Q_i} \quad (\text{F.6})$$

has a Laurent expansion in powers of Q_i 's, whose coefficients are algebraic functions of e^{-x} . And since we know that $(y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x))$ vanishes at $\mathbf{Q} = 0$, we see that the Laurent expansion is in fact a Taylor expansion. This implies that:

$$y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x) = \sum_{\mathbf{k}} \mathbf{Q}^k Y_{\mathbf{k}}(e^{-x}) \quad (\text{F.7})$$

where each $Y_{\mathbf{k}}(X)$ is an algebraic function of X on \mathcal{C}_σ . $Y_{\mathbf{k}}$ maybe singular at $x = 0$ (where \mathring{y} has a squareroot branchcut), or also at the punctures $0, 1, \infty$ in the pair of pants \mathcal{C}_σ .

Notice that due to the log, $y = -\ln Y$ was well defined only on \mathcal{C} cut along a tree, and similarly $\mathring{y}_{\mathfrak{f}_\sigma}$ is also well defined only on \mathcal{C}_σ with some cuts, but the difference $y(x + \mathring{a}_\sigma) - \mathring{y}_{\mathfrak{f}_\sigma}(x)$ has, order by order in \mathbf{Q} , no logarithmic cut.

In particular, order by order in powers of \mathbf{Q} , $(y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x))$ is analytical in a vicinity of $\partial\mathcal{C}_\sigma$. Therefore, the following integral makes sense (as a formal power series in \mathbf{Q}):

$$\oint_{\partial\mathcal{C}_\sigma} \mathring{\Phi}_{g,n}(\mathring{\mathcal{S}}(\mathfrak{f}_\sigma); x_1, \dots, x_n) (y(x_n + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x_n)) dx_n \quad (\text{F.8})$$

and it depends only on the homotopy class of the integration contour, i.e. it is invariant under small continuous deformations of the integration contour. We can also integrate by parts and write it as:

$$\oint_{\partial\mathcal{C}_\sigma} W_{g,n}(\mathring{\mathcal{S}}(\mathfrak{f}_\sigma); x_1, \dots, x_n) \Phi(x_n) \quad (\text{F.9})$$

where

$$\frac{d\Phi(x)}{dx} = y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x). \quad (\text{F.10})$$

Notice that a priori, $\Phi(x)$ seems to be defined only on a universal covering of \mathcal{C}_σ , i.e. it is not necessarily an algebraic function of e^{-x} . However, the monodromies of Φ are the integrals

$$\oint (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{\mathfrak{f}_\sigma}(x)) dx \quad (\text{F.11})$$

which are linear combinations of the t_i 's (due to the mirror map eq. (2.67)). This shows that

$$\frac{\partial}{\partial Q_i} \oint (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{f_\sigma}(x)) dx \propto \frac{1}{Q_i} \quad (\text{F.12})$$

and since $y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{f_\sigma}(x)$ is a power series of \mathbf{Q} with only positive powers of the Q_i 's, this shows that in fact the monodromies of Φ must be independent of \mathbf{Q} , and since they vanish at $\mathbf{Q} = 0$, they must vanish identically (the fact that the monodromies of Φ vanish could also have been deduced directly from the tropical limit of the mirror map relationship). This proves that $\Phi(x)$ is in fact, to each order in powers of \mathbf{Q} , an algebraic function of e^{-x} .

Therefore, we may define the following as a formal power series in \mathbf{Q} :

$$\begin{aligned} U_{g,n}(x_1, \dots, x_n) &= W_{g,n}(\mathring{\mathcal{S}}(f_\sigma); x_1, \dots, x_n) + \sum_{k=1}^{\infty} \frac{1}{(2\pi i)^k k!} \oint_{\partial \mathcal{C}_\sigma} \dots \oint_{\partial \mathcal{C}_\sigma} \\ &\quad W_{g,n+k}(\mathring{\mathcal{S}}(f_\sigma); x_1, \dots, x_n, x_{n+1}, \dots, x_{n+k}) \prod_{i=1}^k \Phi(x_{n+i}). \end{aligned} \quad (\text{F.13})$$

Taking a derivative with respect to any Q_i , we have

$$\begin{aligned} \frac{\partial}{\partial Q_i} U_{g,n}(x_1, \dots, x_n) &= \sum_{k=1}^{\infty} \frac{1}{(2\pi i)^k k!} k \oint_{\partial \mathcal{C}_\sigma} \dots \oint_{\partial \mathcal{C}_\sigma} \\ &\quad W_{g,n+k}(\mathring{\mathcal{S}}(f_\sigma); x_1, \dots, x_{n+k}) \prod_{i=1}^{k-1} \Phi(x_{n+i}) \frac{\partial}{\partial Q_i} \Phi(x_{n+k}) \\ &= \sum_{k=0}^{\infty} \frac{1}{(2\pi i)^{k+1} k!} \oint_{\partial \mathcal{C}_\sigma} \dots \oint_{\partial \mathcal{C}_\sigma} \\ &\quad W_{g,n+k+1}(\mathring{\mathcal{S}}(f_\sigma); x_1, \dots, x_{n+k}, x') \prod_{i=1}^k \Phi(x_{n+i}) \frac{\partial}{\partial Q_i} \Phi(x') \\ &= \frac{1}{2\pi i} \oint_{\partial \mathcal{C}_\sigma} U_{g,n+1}(x_1, \dots, x_n, x') \frac{\partial}{\partial Q_i} \Phi(x') \end{aligned} \quad (\text{F.14})$$

i.e.

$$\frac{\partial}{\partial Q_i} U_{g,n}(x_1, \dots, x_n) = \frac{1}{2\pi i} \oint_{\partial \mathcal{C}_\sigma} U_{g,n+1}(x_1, \dots, x_n, x') \frac{\partial}{\partial Q_i} \Phi(x'). \quad (\text{F.15})$$

Then, notice that we have

$$\begin{aligned} \frac{\partial}{\partial Q_i} (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma) dx &= \text{Res}_{x' \rightarrow x} B_\sigma(x, x') \frac{\partial \Phi(x')}{\partial Q_i} \\ &= \frac{1}{2i\pi} \oint_{\partial \mathcal{C}_\sigma} B_\sigma(x, x') \frac{\partial \Phi(x')}{\partial Q_i} \end{aligned} \quad (\text{F.16})$$

indeed, the first equality comes from the fact that B_σ has a double pole on the diagonal, and the second equality, holds order by order in powers of \mathbf{Q} , because to each order $\partial\Phi/\partial Q_i$ is an analytical function on \mathcal{C}_σ and thus one can move the integration contour.

From this, the "special geometry" property of spectral invariants (see [18] or appendix A) implies that

$$\frac{\partial}{\partial Q_i} W_{g,n}(\mathcal{S}_\sigma; x_1, \dots, x_n) = \frac{1}{2\pi i} \oint_{\partial\mathcal{C}_\sigma} W_{g,n+1}(\mathcal{S}_\sigma; x_1, \dots, x_n, x') \frac{\partial\Phi(x')}{\partial Q_i} \quad (\text{F.17})$$

We can now prove by recursion on the power of \mathbf{Q} , that:

$$\begin{cases} U_{g,n}(x_1, \dots, x_n) = W_{g,n}(\mathcal{S}_\sigma; x_1, \dots, x_n) \\ U_{0,1}(x) = (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma) dx \\ U_{0,2}(x, x') = B_\sigma(x, x') \end{cases} \quad (\text{F.18})$$

This is clearly true when $\mathbf{Q} = 0$, and if it is true to order \mathbf{Q}^k , then the right hand side of eq. (F.15) and eq. (F.17) coincide to order k , and thus $\partial W_{g,n}/\partial Q_i$ and $\partial U_{g,n}/\partial Q_i$ coincide to order k , which implies that $W_{g,n}$ and $U_{g,n}$ coincide to order $k+1$. We have thus proved the recursion hypothesis to order $k+1$, and thus it holds to all orders.

Then, when $2g - 2 + n + k > 0$, use theorem 4.3:

$$\begin{aligned} & W_{g,n}(\mathcal{S}_\sigma; x_1, \dots, x_n) \\ &= \sum_{d_1, \dots, d_n} \sum_k \frac{1}{k!} \sum_{d_{n+1}, \dots, d_{n+k}} \\ & \quad \frac{2^{3g-3+n+k}}{e^{\hat{t}_{f_\sigma, 0}(2-2g-n-k)}} \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathbf{f}_{a,\sigma} - \mathbf{f}_{b,\sigma}) \prod_{i=1}^{n+k} \tau_{d_i} \right\rangle_{g,n+k} \\ & \quad \prod_{i=1}^k \frac{1}{2\pi i} \oint_{x_{n+i} \in \partial\mathcal{C}_\sigma} \Phi(x_{n+i}) d\tilde{\xi}_{\sigma, d_{n+i}}(x_{n+i}) \prod_{i=1}^n d\tilde{\xi}_{\sigma, d_i}(x_i) \\ &= \frac{2^{3g-3+n}}{e^{\hat{t}_{f_\sigma, 0}(2-2g-n)}} \sum_{d_1, \dots, d_n} \sum_k \frac{1}{k!} \sum_{d_{n+1}, \dots, d_{n+k}} \\ & \quad \left\langle \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{a,\sigma}) \hat{\Lambda}_{\text{Hodge}}(\mathbf{f}_{b,\sigma}) \hat{\Lambda}_{\text{Hodge}}(-\mathbf{f}_{a,\sigma} - \mathbf{f}_{b,\sigma}) \prod_{i=1}^{n+k} \tau_{d_i} \right\rangle_{g,n+k} \\ & \quad \prod_{i=1}^k R_{\sigma, d_{n+i}} \prod_{i=1}^n d\tilde{\xi}_{\sigma, d_i}(x_i) \end{aligned} \quad (\text{F.19})$$

where

$$R_{\sigma, d} = \frac{2e^{\hat{t}_{f_\sigma, 0}}}{2\pi i} \oint_{x \in \partial\mathcal{C}_\sigma} \Phi(x) d\tilde{\xi}_{\sigma, d}(x)$$

$$= \frac{-2e^{\hat{t}_{f\sigma,0}}}{2\pi i} \oint_{x \in \partial C_\sigma} \tilde{\xi}_{\sigma,d}(x) (y(x + \mathring{a}_\sigma) - \mathring{b}_\sigma - \mathring{y}_{f\sigma}(x)) dx \quad (\text{F.20})$$

The cases $(g, n) = (0, 1)$ and $(0, 2)$ are obtained in the same way, except that we can't use theorem 4.3 for the first few values of k .

This proves the lemma. \square

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