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Climbing on Pyramids

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Abstract

A new approach is proposed for finding the "best cut" in a hierarchy of partitions by energy minimization. Said energy must be "climbing" i.e. it must be hierarchically and scale increasing. It encompasses separable energies and those composed under supremum.

1 Introduction

The present note extends the results of [13], which themselves generalize some results of L. Guigues' Phd thesis [5] (see also [4]). In [5], any partition, or partial partition, of the space is associated with a "separable energy", i.e. with an energy whose value for the whole partition is the sum of the values over its various classes. Under this assumption, two problems are treated:

- 1. given a hierarchy of partitions and a separable energy ω , how to combine some classes of the hierarchy in order to obtain a new partition that minimizes ω ?
- 2. when ω depends on integer j, i.e. $\omega = \omega^j$, how to generate a sequence of minimum partitions that increase with j, which therefore should form a minimum hierarchy?

Though L. Guigues exploited linearity and affinity assumptions to lean original models on, it is not sure that they are the very cause of the properties he found. Indeed, for solving problem 1 above, an alternative and simpler condition of increasingness is proposed in [13]. After additional developments, it leads to the theorem 4 of this paper. The second question, of a minimum hierarchy, which was not treated in [13], is the concern of sections 3 to 5 of the text. The main results are the theorem 11, and the new algorithm developed in Section 5, more general but simpler than that of [5]. It is followed by the two sections 6 and 7 about the additive and the \lor -composed energies respectively. They show that Theorem 11 applies to linear energies (e.g. Mumford and Shah, Salembier and Garrido), as well to several useful non linear energies (Soille, Zanoguera).

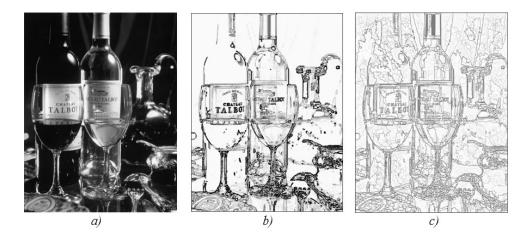


Figure 1: a) Basic input, b) and c) saliency maps from connected openings by dynamics [b] and by volume [c].

2 Hierarchy of partitions (reminder)

The space under study (Euclidean, digital, or else) is denoted by E, and the set of all partitions of E by $\mathcal{D}_0(E)$. Here a convenient notion is that *partial partition*, of C. Ronse [9]. When we associate a partition $\pi(A)$ of a set $A \in \mathcal{P}(E)$ and nothing outside A, then $\pi(A)$ is called a *partial partition* of E of support A. The family of all partial partitions of set E is denoted by $\mathcal{D}(E)$, or simply by \mathcal{D} when there is no ambiguity.

Finite hierarchies of partitions appeared initially in taxonomy, for classifying objects. One can quote in particular the works of J.P. Benzécri [2] and of E. Diday [3]. We owe to the first author the theorem linking ultrametrics with hierarchies, namely the equivalence between statements 1 and 3 in theorem 2 below. Hierarchies H of partitions usually derive from a chain of segmentations of some given function f on set E, i.e. from a stack of scalar or vector images, a chain which then serves as the framework for further operators. We consider, here, function f and hierarchy H as two starting points, possibly independent. This results in the following definition:

Definition 1 Let $\mathcal{D}_0(E)$ be the set of all partitions of E, equipped with the refinement ordering. A hierarchy H, of partitions π_i of E is a finite chain in $\mathcal{D}_0(E)$, i.e.

$$H = \{\pi_i, 0 \le i \le n, \pi_i \in \mathcal{D}_0(E) \mid i \le k \le n \Rightarrow \pi_i \le \pi_k\},\tag{1}$$

of extremities the universal extrema of $\mathcal{D}_0(E)$, namely $\pi_0 = \{\{x\}, x \in E\}$ and $\pi_n = E$.

Let $S_i(x)$ be the class of partition π_i of H at point $x \in E$. Denote by S the set of all classes $S_i(x)$, i.e. $S = \{S_i(x), x \in E, 0 \le i \le n\}$. Expression (1) means that at each point $x \in E$ the family of those classes $S_i(x)$ of S that contain x forms a finite chain S_x in $\mathcal{P}(E)$,



Figure 2: The initial image has been transformed by increasing alternated connected filters. They result in partitions into flat zones that increase from left to right.

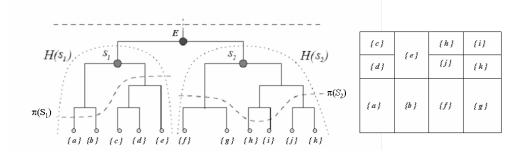


Figure 3: Left, hierarchical tree; right, the corresponding space structure. S_1 and S_2 are the nodes sons of E, and $H(S_1)$ and $H(S_1)$ are the associated sub-hierarchies. π_1 and π_2 are cuts of $H(S_1)$ and $H(S_1)$ respectively, and $\pi_1 \sqcup \pi_2$ is a cut of E.

of nested elements from $\{x\}$ to E:

$$\mathcal{S}_x = \{S_i(x), 0 \le i \le n\}.$$

According to a classical result, a family $\{S_i(x), x \in E, 0 \le i \le n\}$ of indexed sets generates the classes of a hierarchy iff

$$i \leq j \text{ and } x, y \in E \implies S_i(x) \subseteq S_j(y) \text{ or } S_i(x) \supseteq S_j(y) \text{ or } S_i(x) \cap S_j(y) = \emptyset.$$
 (2)

A hierarchy may be represented in space E by the saliencies of its frontiers, as depicted in Figure 1. Another representation, more adapted to the present study, emphasizes the classes rather than their edges, as depicted in Figure 2. Finally, one can also describe it, in a more abstract manner, by a family tree where each node of bifurcation is a class S, as depicted in Figure 3. The classes of π_{i-1} at level i-1 which are included in $S_i(x)$ are said to be the sons of $S_i(x)$. Clearly, the sets of the descenders of each S forms in turn a hierarchy H(S)of summit S, which is included in the complete hierarchy H = H(E).

The two zones $H(S_1)$ and $H(S_2)$, drawn in Figure 3 in small dotted lines, are examples of such sub hierarchies. The following theorem [13] makes more precise the hierarchical structure

Theorem 2 The three following statements are equivalent:

- 1. H is an indexed hierarchy,
- 2. the set S of all classes of the partition π_i of H forms an ultrametric space, of distance the indexing parameter,
- 3. every binary criterion $\sigma : (\mathcal{F}, \mathcal{S} \cup \emptyset) \to \{0, 1\}$ is connective.

This result shows that the connective segmentation approach is inefficient for hierarchies, and orients us towards the alternative method, which consists in optimizing an energy.

3 Optimum partitioning of a hierarchy

3.1 Cuts in a hierarchy

Following L. Guigues [5] [4], we say that any partition π of E whose classes are taken in S defines a *cut* in hierarchy H. The set of all cuts of E is denoted by $\Pi(E) = \Pi$. Every "horizontal" section $\pi_i(H)$ at level i is obviously a cut, but several levels can cooperate in a same cut, such as $\pi(S_1)$ and $\pi(S_2)$, drawn with thick dotted lines in Figure 3. Similarly, the partition $\pi(S_1) \sqcup \pi(S_2)$ generates a cut of H(E). The symbol \sqcup is used here for expressing that groups of classes are concatenated. Each class S may also be the matter of cuts in the sub-hierarchy H(S) whose it is the summit. Let $\Pi(S)$ be the family of all cuts of H(S). The unions of all these cuts, when node S spans hierarchy H is denoted by

$$\widetilde{\Pi}(H) = \bigcup \{ \Pi(S), S \in \mathcal{S}(H) \}.$$
(3)

Although the set $\Pi(H)$ does not regroup all possible partial partitions with classes in S, it contains the family $\Pi(E)$ of all cuts of H(E). The hierarchical structure of the data induces a relation between the family $\Pi(S)$ of the cuts of node S and the families $\Pi(T_1), ..., \Pi(T_q)$ of the sons $T_1, ..., T_q$ of S. Since all expressions of the form $\sqcup \{\pi(T_k); 1 \leq k \leq q\}$ define cuts of $S, \Pi(S)$ contains the whole family

$$\Pi'(S) = \{ \pi(T_1) \sqcup ... \pi(T_k) ... \sqcup \pi(T_q); \qquad \pi(T_1) \in \Pi(T_1) ... \pi(T_q) \in \Pi(T_q) \}.$$

plus the cut of S into a unique class, i.e. S itself, which is not a member of $\Pi'(S)$. And as the other unions of several T_k are not classes listed in S, there is no other possible cut, hence

$$\Pi(S) = \Pi'(S) \cup S. \tag{4}$$

3.2 Cuts of minimum energy and *h*-increasingness

In the present context, an energy $\omega : \mathcal{D}(E) \to \mathbb{R}^+$ is a non negative numerical function over the family $\mathcal{D}(E)$ of all partial partitions of set E. The cuts of $\Pi(E) \subseteq \widetilde{\Pi}$ of minimum energy are characterized under the assumption of *hierarchical increasingness*, or more shortly of *h-increasingness* [13].

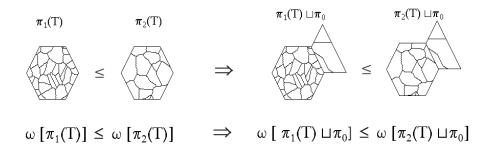


Figure 4: Hierachical increasingness.

Definition 3 Let π_1 and π_2 be two partial partitions of same support, and π_0 be a partial partition disjoint from π_1 and π_2 . An energy ω on $\mathcal{D}(E)$ is said to be hierarchically increasing, or h-increasing, in $\mathcal{D}(E)$ when, $\pi_0, \pi_1, \pi_2 \in \mathcal{D}(E), \pi_0$ disjoint of π_1 and π_2 , we have

$$\omega(\pi_1) \le \omega(\pi_2) \quad \Rightarrow \quad \omega(\pi_1 \sqcup \pi_0) \le \quad \omega(\pi_2 \sqcup \pi_0). \tag{5}$$

An illustration of the meaning of implication (5) is given in Figure 4. When the partial partitions are embedded in a hierarchy H, then Rel.(5) allows us an easy characterization of the cuts of minimum energy of H, according to the following property, valid for the class \mathcal{H} of all finite hierarchies on E

Theorem 4 Let $H \in \mathcal{H}$ be a finite hierarchy, and ω be an energy on $\mathcal{D}(E)$. Consider a node S of H with p sons $T_1...T_p$ of minimum cuts $\pi_1^*,...\pi_p^*$. The cut of minimum energy of node S is either the cut

$$\pi_1^* \sqcup \pi_2^* \sqcup \Pi_p^*, \tag{6}$$

or the partition of S into a unique class, if and only if S is h-increasing.

Proof. We firstly prove that the condition is sufficient. The *h*-increasingness implies of the energy implies that cut (6) has the lowest energy among all the cuts of type $\Pi'(S) = \bigcup \{\pi(T_k); 1 \le k \le p\}$ (it does not follow that it is unique). Now, from the decomposition (4), every cut of S is either an element of $\Pi'(S)$, or S itself. Therefore, the set formed by the cut (6) and S contains one minimum cut of S at least.

We will prove that the *h*-increasingness is necessary by means of a counter-example. Consider the hierarchies of *n* levels in $E = \mathbb{R}^2$, and associate an energy with the lengths of the frontiers as follows

$$\omega(\pi(S)) = \omega(T_1 \sqcup ... T_u ... \sqcup T_q) = \sum_{1 \le u \le q} (\partial T_u), \quad \text{when} \quad \sum_{1 \le u \le q} (\partial T_u) \le 5 \quad (7)$$
$$\omega(\pi(S)) = \sum_{1 \le u \le q} (\partial T_u) - 5 \quad \text{when not.}$$

where $\{T_u, 1 \le u \le q\}$ are the sons of node S. Calculate the minimum cut of the three levels partition depicted in Fig.5 a) b) and c). The size of the square is 1 and one must take half the

<i>T</i> ₁ <i>T</i> ₂	S		<i>T</i> ₁ <i>T</i> ₂	S
<i>T'</i> ₁ <i>T'</i> ₂	<i>S'</i>	L	S'	<i>T'</i> ₁ <i>T'</i> ₂
<i>a</i>)	<i>b)</i>	c)	<i>d</i>)	e)

Figure 5: a), b),c): three levels of a hierarchy H. Partition a) is the minimum cut for energy (7), which contradicts hierarchical increasingness. Partitions d) and e) are two minimum cuts of H for the sequence (16) of energies. They contradict scale increasingness.

length for the external edges. We find $\omega(T_1 \sqcup T_2) = 3$ and $\omega(S) = 2$. Hence S is the minimum cut of its own sub-hierarchy. So does S'. At the next level we have $\omega(S \sqcup S') = 4$, and $\omega(E) = 3$. Nevertheless, E is not the minimum cut, because $\omega(T_1 \sqcup T_2 \sqcup T'_1 \sqcup T'_2) = 6 - 5 = 1!$

The condition of h-increasingness (5) opens into a broad range of energies, and is easy to check. It encompasses the case of the separable energies [5] [11], as well as energies composed by suprema [1] [14] [16]. Computationally, it yields to the following Guigues' algorithm:

- scan in one pass all nodes of H according to an ascendant lexicographic order;
- determine at each node S a temporary minimum cut of H by comparing the energy of S to that of the concatenation of the temporary minimum cuts of the (already scanned) sons T_k of S.

3.3 Single minimum cuts

It may happen that in the family $\Pi(S)$ of Relation (4) a minimum cut of $\Pi'(S)$ has the same energy as that of S. This event introduces two solutions which are then carried over the whole induction. And since such a doublet can occur regarding any node S of H, the family M = M(H) of all minimum cuts may be very comprehensive. However, M turns out to be structured as a complete lattice for the ordering of the refinement, where the sup (resp. the inf) are obtained by taking the union (resp. the intersection) of the classes.

The risk of several minimum cuts w.r.t. ω may becomes sometimes cumbersome. Then one can always ensure unicity by slightly modifying a *h*-increasing energy ω :

Proposition 5 Let ω be a h-increasing energy over $\widetilde{\Pi}$. Introduce the additional energy ω' over $\widetilde{\Pi}$

$$\begin{aligned} \omega'[\pi(S)] &= 1, \qquad \pi(S) \neq S \\ \omega'[S] &= 0, \end{aligned}$$

for all $\{\pi(S) \in \Pi(S), S \in S\}$, then the sum $\omega + \omega'$ is h-increasing and associates a unique minimum cut with each sub-hierarchy H(S), and we have

either
$$\omega[\pi^*(S)] < \omega(\pi), \ \pi \in \Pi(S), \qquad or \quad \pi^*(S) = S.$$
 (8)

Proof. : Let $\pi_1, \pi_2 \in \Pi(S)$. If $\omega(\pi_1) \leq \omega(\pi_2)$ and $\pi_2 \neq S$, then energy $\omega + \omega'$ satisfies implication (5). If $\omega(\pi_1) \leq \omega(\pi_2)$ and $\pi_2 = S$, then two situations may occur. If $(\omega + \omega')(\pi_1) \not\leq (\omega + \omega')(\pi_2)$, then there is no longer need for implication (5). If not, then as neither $\pi_1 \sqcup \pi_0$ nor $S \sqcup \pi_0$ are summits, we obtain again $(\omega + \omega')(\pi_1 \sqcup \pi_0) \leq (\omega + \omega')(S \sqcup \pi_0)$.

Note that if we invert the two values 1 and 0 of ω' in Proposition 5, it remains valid. When this constraint is fulfilled, then $\pi^*(S)$ is said to be a *single minimum cut* and when it is fulfilled by all $S \in S$, and ω is said to have a *single minimum cutting*. Moreover, Condition (8) is a top-down property:

Proposition 6 Let $\pi^*(E)$ be the single minimum cut of a hierarchy H w.r. to a h-increasing energy ω , and let S be a node of H. If $\pi^*(E)$ meets the sub-hierarchy H(S) of summit S, then the restriction $\pi^*(S)$ of $\pi^*(E)$ to H(S) is the single minimum cut of the sub-hierarchy H(S).

Proof. We have to prove Relation (8). If $\pi^*(S) = S$, then the relation is obviously satisfied. Suppose now that the restriction $\pi^*(S)$ is different from S, and that there exists a cut π_0 of S with $\omega(\pi_0) \leq \omega(\pi^*(S))$. Denote by π^- the partial partition obtained when $\pi^*(S)$ is removed from $\pi^*(E)$. The *h*-increasingness then implies that $\omega(\pi_0 \sqcup \pi^-) \leq \omega(S \sqcup \pi^-) = \omega(\pi^*(E))$. But by definition of $\pi^*(E)$ we also have the reverse inequality, hence $\omega(\pi_0 \sqcup \pi^-) = \omega(\pi^*(E))$. Now, this equality contradicts the condition (8) applied to the whole space E, so that the inequality $\omega(\pi_0) \leq \omega(\pi^*(S))$ is impossible, and $\omega(\pi_0) > \omega(\pi^*(S))$ for all $\pi_0 \in \Pi(S)$.

3.4 Generation of *h*-increasing energies

As we saw, the energy $\omega : \mathcal{D}(E) \to \mathbb{R}^+$ is defined on the family $\mathcal{D}(E)$ of all partial partitions of E. An easy way to obtain a *h*-increasing energy consists in defining it, firstly, over all sets $S \in \mathcal{P}(E)$, considered as one class partial partitions $\{S\}$, and then in extending it to partial partitions by some law of composition. Then, the *h*-increasingness is introduced by the law of composition, and not by $\omega[\mathcal{P}(E)]$. The first two modes of composition which come to mind are, of course, addition and supremum, and indeed we can state

Proposition 7 Let E be a set and $\omega : \mathcal{P}(E) \to \mathbb{R}^+$ an arbitrary energy defined on $\mathcal{P}(E)$, and let $\pi \in \mathcal{D}(E)$ be a partial partition of classes $\{S_i, 1 \leq i \leq n\}$. Then the two extensions of ω to the partial partitions $\mathcal{D}(E)$

$$\omega(\pi) = \vee \{\omega(S_i), 1 \le i \le n\} \quad and \quad \omega(\pi) = \sum \{\omega(S_i), 1 \le i \le n\}$$
(9)

are *h*-increasing energies.

We shall study these two models in sections 6 and 7, when they depend on a parameter leading to multiscale structures. A number of other laws are compatible with *h*-increasingness. Instead of the supremum and the sum one could use the infimum, the product, the difference sup-inf, the quadratic sum, and their combinations. Moreover, one can make depend ω on more than one class, on the proximity of the edges, on another hierarchy, etc..

3.5 Stucture of the *h*-increasing energies

We now analyze how different *h*-increasing energies interact on a same hierarchy. The family Ω of all mappings $\omega : \mathcal{D} \to \mathbb{R}^+$ forms a complete lattice where

$$\omega \leq \omega' \quad \Leftrightarrow \quad \omega(\pi) \leq \omega'(\pi) \quad \text{for all } \pi \in \mathcal{D}$$

and whose extrema are $\omega(\pi) = 0$ and $\omega(\pi) = +\infty$. What can be said about the sub class of $\Omega' \subseteq \Omega$ of the *h*-increasing energies? The class Ω' is obviously closed under addition and multiplication by positive scalars, i.e.

$$\{\omega^j\} \subseteq \Omega', \lambda_j \ge 0 \quad \Rightarrow \quad \sum \lambda_j \omega^j \in \Omega' \tag{10}$$

Consider now a finite family $\{\omega_i, i \in I\}$ in Ω' such that, for $\pi_0, \pi_1, \pi_2 \in \mathcal{D}(E), \pi_0$ disjoint of π_1 and π_2 , we have

$$\omega_i(\pi_1) \le \omega_j(\pi_2) \qquad \Rightarrow \quad \omega_i(\pi_1 \sqcup \pi_0) \le \ \omega_j(\pi_2 \sqcup \pi_0), \quad \pi_0, \pi_1, \pi_2 \in \mathcal{D}$$
(11)

a relation that generalizes the h-increasingness (5).

Proposition 8 The family of those energies that satisfy implication (11) is a finite sub-lattice Ω' of Ω , and for any family $\{\omega_i, i \in I\}$ in Ω' we have

$$(\wedge \omega_i)(\pi) \leq (\wedge \omega_i)(\pi') \quad \Rightarrow \quad (\wedge \omega_i)(\pi \sqcup \pi_0) \leq (\wedge \omega_i)(\pi' \sqcup \pi_0) \tag{12}$$

$$(\forall \omega_i)(\pi) \leq (\forall \omega_i)(\pi') \quad \Rightarrow \quad (\forall \omega_i)(\pi \sqcup \pi_0) \leq (\forall \omega_i)(\pi' \sqcup \pi_0) \tag{13}$$

Proof. Consider a family $\{\omega_i, i \in I\}$ which satisfy the *h*-increasingness (11). Suppose that $(\wedge \omega_i)(\pi) \leq (\wedge \omega_i)(\pi')$, and let i_0 be the parameter of the smallest of the $\omega_i(\pi)$. Then we have $\omega_{i_0}(\pi) \leq \omega_i(\pi'), i \in I$, hence, from Rel.(11), $\omega_{i_0}(\pi \sqcup \pi_0) \leq \omega_i(\pi' \sqcup \pi_0)$, so that $\omega_{i_0}(\pi \sqcup \pi_0) \leq (\wedge \omega_i)(\pi' \sqcup \pi_0)$, and finally $(\wedge \omega_i)(\pi \sqcup \pi_0) \leq (\wedge \omega_i)(\pi' \sqcup \pi_0)$. Energy $(\wedge \omega_i)$ is thus *h*-increasing. Same proof for the supremum.

Note that the infimum cut $\pi_{\wedge\omega_i}$ related to energy $\wedge\omega_i$ is not the infimum $\wedge\pi^*_{\omega_i}$ of the minimum cuts generated by the ω_i . It has to be computed directly (dual statement for the supremum).

4 climbing energies

The usual energies are often given by finite sequences $\{\omega^j, 1 \leq j \leq p\}$ that depend on a positive index, or parameter, j. Therefore, the processing of hierarchy H results in a sequence of p optimum cuts π^{j*} , of labels $1 \leq j \leq p$. A priori, the π^{j*} are not ordered, but is they were, i.e. if

$$j \le k \quad \Rightarrow \quad \pi^{j*} \le \pi^{k*}, \qquad j, k \in J,$$

then we should obtain a nice progressive simplification of the optima. We now seek the conditions that permit such an increasingness.

Consider a finite family of energies $\{\omega^j, 1 \leq j \leq p\}$ on all partial partitions $\mathcal{D}(E)$ of set E, and apply these energies to the partial partitions $\widetilde{\Pi}(H)$ of hierarchy H (Relation (3)). The family $\{\omega^j\}$, not totally arbitrary, is supposed to satisfy the following condition of *scale increasingness*:¹

Definition 9 A family of energies $\{\omega^j, 1 \leq j \leq p\}$ on $\mathcal{D}(E)$ is said to be scale increasing when for $j \leq k$, each support $S \in \mathcal{S}$ and each partition $\pi \in \Pi(S)$, we have that

$$j \le k \quad and \quad \omega^j(S) \le \omega^j(\pi) \Rightarrow \omega^k(S) \le \omega^k(\pi), \qquad S \in \mathcal{P}(E).$$
 (14)

In case of a hierarchy H, relation (14) means that, if S is a minimum cut w.r. to energy ω^j for a partial hierarchy $\Pi(S)$, then S remains a minimum cut of $\Pi(S)$ for all energies ω^k , $k \geq j$. As j increases, the ω^j 's preserve the sense of energetic differences between the nodes of hierarchy H and their partial partitions. In particular, all energies of the type $\omega^j = j\omega$ are scale increasing.

Axiom (14) compares two energies at the same level of H, whereas axiom (5) allows us to compare a same energy at two different levels. Therefore, the most powerful energies should to be those which combine scale and h-increasingness, i.e.

Definition 10 We call climbing energy any family $\{\omega^j, 1 \leq j \leq p\}$ of energies over Π which satisfies the three following axioms, valid for $\omega^j, 1 \leq j \leq p$ and for all $\pi \in \Pi(S), S \in S$

• *i*) *h*-increasingness, *i.e.* relation(5):

$$\omega^{j}(\pi_{1}) \leq \omega^{j}(\pi_{2}) \quad \Rightarrow \quad \omega^{j}[(\pi_{1} \sqcup \pi_{0}] \leq \omega^{j}[(\pi_{2} \sqcup \pi_{0}], \qquad \pi_{1}, \pi_{2} \in H(S)$$

• *ii*) single minimum cutting, *i.e.* relation(8):

either
$$\omega^{j}[\pi^{*}(S)] < \omega^{j}(\pi), \text{ or } \pi^{*}(S) = S,$$

• *iii*) scale increasingness, *i.e.* relation(14) :

$$j \le k \text{ and } \omega^j(S) \le \omega^j(\pi) \Rightarrow \omega^k(S) \le \omega^k(\pi), \qquad \pi \in H(S).$$

¹Scale increasingness is called by L.Guigues "partial causality" in [5], p.161, where it appears as a consequence and not as a starting point.

Under these three assumptions, the climbing energies satisfy the very nice property to order the minimum cuts with respect to the parameter j, namely:

Theorem 11 Let $\{\omega^j, 1 \leq j \leq p\}$ be a family of energies, and let π^{j*} (resp. π^{k*}) be the minimum cut of hierarchy H according to the energy ω^j (resp. ω^k). The family $\{\pi^{j*}, 1 \leq j \leq p\}$ of the minimum cuts generates a unique hierarchy H^* of partitions, i.e.

$$j \le k \quad \Rightarrow \quad \pi^{j*} \le \pi^{k*}, \qquad 1 \le j \le k \le p$$

$$\tag{15}$$

if and only if the family $\{\omega^j\}$ is a climbing energy.

Proof. Assume that axiom *iii*) of a climbing energy is satisfied, and denote by S^j and S^k the two classes of π^{j*} and π^{k*} at a given point x. According to Rel.(2), we must have either $S^j \subseteq S^k$ or $S^k \subset S^j$. We will prove that the second inclusion is impossible. Suppose that class $S^k \subset S^j$. Then the restriction of the minimum cut π^{k*} to S^j generates a cut, π_0 say, of S^j . According to proposition 6, which involves axioms i) and ii) of a climbing energy, the restriction π_0 is in turn minimum for the energy ω^k over $\Pi(S^j)$, i.e. $\omega^k(\pi_0) < \omega^k(S^j)$. This implies, by scale increasingness, that $\omega^j(\pi_0) < \omega^j(S_j)$ (here Relation (14) has been red from right to left). But this inequality contradicts the fact that S^j is a minimum cut for its own hierarchy $H(S^j)$. Therefore the inclusion $S^k \subset S^j$ is rejected, and the alternative inclusion $S^j \subseteq S^k$ is satisfied whatever $x \in E$, which results in $\pi^{j*} \leq \pi^{k*}$. Moreover, because of the single minimum cutting axiom, each π^{j*} being unique, so does the whole hierarchy H^* .

The "only if" statement will be proved by means of a counter-example. The notation is the same as in system (7) but we add a term for the areas and we replace the length ∂T_u of the frontier of each T_u by the length $\partial_{hor}T_u$ (resp. $\partial_{vert}T_u$) of the horizontal (resp. vertical) projection of the said frontiers if $j \leq j_0$, (resp. if $j > j_0$).

$$\omega^{j}(\pi(S)) = \omega(T_{1} \sqcup ... T_{u} ... \sqcup T_{q}) = 4 \sum_{1 \le u \le q} (areaT_{u})^{2} + 2 \sum_{1 \le u \le q} (\partial_{hor}T_{u}), \text{ when } j \le j_{0}16) \\
\omega^{j}(\pi(S)) = \omega(T_{1} \sqcup ... T_{u} ... \sqcup T_{q}) = 4 \sum_{1 \le u \le q} (areaT_{u})^{2} + 2 \sum_{1 \le u \le q} (\partial_{vert}T_{u}), \text{ when } j > j_{0},$$

(border lengths being divided by 2). For each value of j, the energy ω_1^j is *h*-increasing, and one can apply proposition 5 for ensuring unicity. However, if $j \leq j_0$ then $\omega(T_1 \sqcup T_2) =$ $6, \omega(T'_1 \sqcup T'_2) = 4, \omega(S) = \omega(S') = 6, \omega(E) = 19$. Therefore the minimum cut is the partition $T'_1 \sqcup T'_2 \sqcup S$, depicted in Figure 5 d). By symmetry, if $j > j_0$ then the minimum cut becomes $T_1 \sqcup T_2 \sqcup S'$, of Figure 5 c). Now these two cuts are not comparable, which contradicts implication (15).

Relation (15) has been established by L. Guigues in his Phd thesis [5] for affine and separable energies, called by him climbing energies. However, the core of the assumption (14) concerns the propagation of energy through the scales (1...p), rather than affinity or linearity, and allows non additive laws (see Section 7). In addition, the new climbing axioms 10 lead to the algorithms of the next section, much simpler than that of [5].

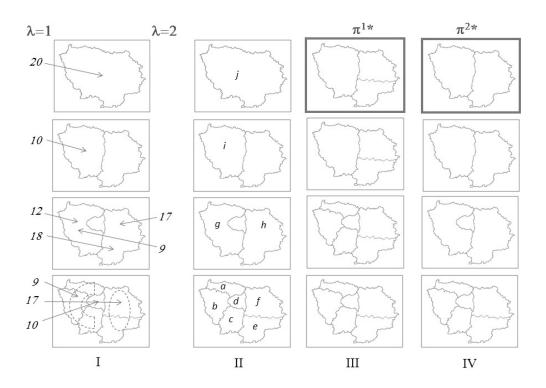


Figure 6: Column I: initial hierarchy and associated energies (left, for $\lambda = 1$; right, the changes for $\lambda = 2$); column II: reading order; columns III and IV: progressive extraction of the minimum cuts for $\lambda = 1$ and $\lambda = 2$, the two final minuma have bold frames.

The scale sequence has been supposed finite, i.e. with $1 \leq j \leq p$. We could replace j by a positive parameter $\lambda \in \mathbb{R}_+$. But the induction method for finding the optimal cut requires a finite hierarchy H. Therefore the number of the scale parameters actually involved in the processing of H will always be finite.

5 Implementation via a pedagogical example

We now describe step by step two algorithms for generating a hierarchy of minimum cuts. The input hierarchy H comprises the four levels and two energies $\{\omega_1, \omega_2\}$ depicted in Figure 6. The energies of the classes are given along column I, left for $\lambda = 1$, and right for the energies that are different for $\lambda = 2$. They are composed by supremum (the energies of the three partial partitions $\{a, b, c\}$, and $\{e, f\}$ are not decomposed). If class S is temporary minimum for ω_{λ} then is remains temporary minimum for all $\omega_{\mu}, \mu \geq \lambda$. The scale of apparition $\lambda^+(S) = \inf\{\lambda \mid S \text{ temporary minimum for } \omega_{\lambda}\}$ is the smallest λ for which S is a temporary minimum. A class S which is covered by a temporary minimum class Y at scale μ remains covered by temporary minima at all scales $\nu \geq \mu$. The scale of removal $\lambda^-(S) = \min\{\lambda^+(Y), Y \in H, S \subseteq Y\}$ is the smallest μ for which S is covered. Therefore, if $\lambda^+(S) < \lambda^-(S)$, then class $S \in H$ belongs to the minimum cuts $\pi^{\lambda*}$ for all λ of the interval of persistence $[\lambda^+(S), \lambda^-(S)]$. If $\lambda^-(S) \leq \lambda^+(S)$, then S, non-persistent, never appears as a class of a minimum cut. This happens to class g, for which $\lambda^-(g) = 1$ and $\lambda^+(g) = 2$.

When the two bounds $\lambda^+(S)$ and $\lambda^-(S)$ are known for all classes $S \in H$ then the hierarchy of the minimum cuts $\pi^{\lambda*}$ is completely determined. They are calculated in two passes as follows

1-take the nodes following their labels (ascending pass). For node S, calculate the two energies ω_{λ} of S and of its sons $\pi(S)$, for $\lambda = 1, 2$. Stop at the first λ such that $\omega_{\lambda}(S) \leq \omega_{\lambda}(\pi(S))$. This value is nothing but $\lambda^{+}(S)$. Continue for all nodes until he top of the hierarchy. This pass provides the $\lambda^{+}(S)$ values for all $S \in H$. In Figure 6 the sequence of the two energies is climbing: when a class is temporary minimum for $\lambda = 1$, it also does for $\lambda = 2$. Two changes occur from $\lambda = 1$ to $\lambda = 2 : g$ and h have now the same energies as $\{a, b, c\}$ and $\{e, f\}$ respectively.

2-The second pass progresses top down. Each class Y is compared to its sons Z_1, Z_i , and one allocates to each son Z_i the new value $\min\{\lambda^-(Y), \lambda^-(Z_i)\}$. At the end of the scan, all values $\lambda^-(S)$ are known.

6 Additive energies

The additive mode was introduced and studied by L.Guigues under the name of separable energies [5]. All classes S of S are supposed to be connected. Denote by $\{T_u, 1 \leq u \leq q\}$ the q sons which partition the node S, i.e. $\pi(S) = T_1 \sqcup ... T_u ... \sqcup T_q$. Provide the simply connected sets of $\mathcal{P}(E)$ with energy ω , and extend it from $\mathcal{P}(E)$ to the set $\mathcal{D}(E)$ of all partial partitions by using the sums

$$\omega(S) = \omega(T_1 \sqcup ... T_u ... \sqcup T_q) = \sum_1^q \omega(T_u).$$
(17)

All separable energies ω are clearly *h*-increasing on any hierarchy, since one can decompose the second member of implication (5) into $\omega(\pi_1 \sqcup \pi_0) = \omega(\pi_1) + \omega(\pi_0)$, and $\omega(\pi_2 \sqcup \pi_0) = \omega(\pi_2) + \omega(\pi_0)$. However, they do not always lend themselves to multiscale structures, and a supplementary assumption of affinity has to be added [5], by putting

$$\omega^{j}(S) = \omega_{\mu}(S) + \lambda^{j}\omega_{\partial}(S) \qquad S \in \mathcal{S}$$
(18)

where ω_{μ} is a goodness-of-fit term, and ω_{∂} a regularization one, and $\lambda^{j} \geq 0$ an increasing function of j. The term ω_{μ} is associated with the interior of A and ω_{∂} with its boundary. In such an affine energy, the function ω_{∂} must be c-additive on the boundary arcs F, in the sense of integral geometry, i.e. one must have

$$\omega_{\partial}(F_1 \cup F_2) + \omega_{\partial}(F_1 \cap F_2) = \omega_{\partial}(F_1) + \omega_{\partial}(F_2) \tag{19}$$

since most of the arcs $F_1, F_2, ..., F_i$ of the boundaries are shared between two adjacent classes. The passage "set \rightarrow partial partition" can then be obtain by the summation (17). One classically take for ω_∂ the arc length function (e.g. in Rel.(21)), but it is not the only choice. Below, one of the examples by Salemenbier and Garrido about thumbnails uses $\omega_\partial(S) = 1$. One can also think about another $\omega_\partial(S)$, which reflects the convexity of A.

6.1 Lagrangian interpretation

The axiom (14) of scale increasingness involves only increments of the energy ω , which suggests the following obvious consequence:

Proposition 12 If a family $\{\omega^j, 1 \leq j \leq p\}$ of energies is scale increasing, then any family $\{\omega^j + \omega_0, 1 \leq j \leq p\}$, where ω_0 is an arbitrary energy over Π which does not depends on j, is in turn scale increasing.

On the other hand, a classical Lagrange's theorem states that the (relative) minimum of an energy ω_0 under some constraint $\omega = k$ turns out to be the same as the (absolute) minimum of $\omega_0 + \lambda^j \omega$. For finding this value, and the coordinates of this minimum, one usually solves the system of partial derivatives of the sum $\omega_0 + \lambda^j \omega$. But the theorem 11 offers another way, since according to proposition 12 the energy $\omega^j = \omega_0 + \lambda^j \omega$ is scale increasing for all pairs (ω_0, ω) . In this equation, the λ^j of the minimum ω^j is unknown. But if we take a *h*-increasing ω^j with single minima, hence a climbing ω^j , then 11 applies and it suffices to calculate the series of the minimum cuts $\{\pi^{j*}, 1 \leq j \leq k \leq p\}$, w.r.t. the ω^j . The solution is given by the π^{j*} whose term $\omega(\pi^{j*})$ is the closest smaller than *k*. This technique has been proposed by L.Guigues for linear and affine energies [5], who remarks that it provides, at once, the solutions for all values *k* of the constraint ω .

6.2 Additive energy and convexity

Consider, indeed, in \mathbb{R}^2 a compact connected set X without holes, and let $d\alpha$ be the elementary rotation of its outward normal along the element du of the frontier ∂X . As the radius of curvature R equals $du/d\alpha$, and as the total rotation of the normal around ∂X equals π , we have

$$2\pi = \int_{R \ge 0} \frac{du}{R(u)} + \int_{R > 0} \frac{du}{|R(u)|}.$$
 (20)

When dealing with partitions, the distinction between outward and inward vanishes, but the parameter

$$n(X) = \frac{1}{2\pi} \int_{\partial X} \frac{du}{|R(u)|}$$

still makes sense. It reaches its minimum 1 when set X is convex, and increases with the degree of concavity. For a starfish with 5 pesudo-podes, it values around 5. Now n(X) is *c*-additive for the open parts of contours, therefore it can participate as a supplementary term in an additive energy. In digital implementation, the angles between contour arcs must be treated separately (since *c*-additivity applies on the open parts).

6.3 Mumford and Shah energy

Let $\pi(S)$ be the partition of summit S into its q sons $\{T_u, 1 \leq u \leq q\}$ i.e. $\pi(S) = T_1 \sqcup ... T_u ... \sqcup T_q$. The classical Mumford and Shah energy ω^j on $\pi(S)$ w.r.t. function f comprises two terms. The first one sums up the quadratic differences between f and its average $m(T_u)$ in the various T_u , and a second term weights by λ^j the lengths ∂T^i of the frontiers of all T_u , i.e.

$$\omega^{j}(\pi(S)) = \sum_{1 \le u \le q} \int_{x \in T^{u}} \| f(x) - m(T_{u}) \|^{2} + \lambda^{j} \sum_{1 \le u \le q} (\partial T_{u}),$$
(21)

where the weight λ^{j} is a numerical increasing function of j. Both increasingness relations (5) and (14) are satisfied. Therefore, if we add the single minimum cutting condition (8), then both two theorems 4 and 11 apply for this climbing energy.

6.4 Constraint and additive energy

The creation of thumbnails by Ph. Salembier and L. Garrido [11] [12] is a matter of affine separable model, but approached by applying Lagrange's theorem, as presented above. The aim is to generate "the best" reduced version of image f, from a hierarchy H of previous segmentations. In each node S of H, the thumbnail reduction consists in replacing the function f by its mean value m(S). This approximation is estimated in the L_2 norm, i.e.

$$\omega_{\mu}(S) = \sum_{x \in R} \parallel f(x) - m(T) \parallel^2$$

If the coding cost for a frontier element is c, that of the whole class S becomes

$$\omega_{\partial}(S) = 24 + \frac{c}{2} \mid \partial S \mid \tag{22}$$

with 24 bits for m(S). We want to minimize the coding cost, while preserving some quality, by setting $\omega_{\mu}(S) \leq 31 dB$. According to Lagrange formalism, the total energy of a cut π is thus written $\omega(\pi) = \lambda^{j} \omega_{\mu}(\pi) + \omega_{\partial}(\pi)$. An example of this optimum is depicted in Fig.7 a) and b). The cut b) has 219 classes and a perimeter length of 3684

Alternatively, one can decide to keep the same quality, but by minimizing the number of classes in the best cut. Then one takes $\omega_{\partial}(S) = 1$ for the regularization energy of every node $S \in \mathcal{S}$. The result is given in Fig.7 c) and d). The cut d) has 87 classes and a perimeter length of 4491

7 Energies composed by supremum

We now us go back to Rel.(17), and replace the sum by a supremum. It gives:

$$\omega(S) = (T_1 \sqcup ... T_u ... \sqcup T_q) = \bigvee_1^q \omega(T_u).$$

This time the second member of implication (5) is written $\omega[(\pi_1 \sqcup \pi_0] = \omega(\pi_1) \lor \omega(\pi_0)$, and $\omega[(\pi_2 \sqcup \pi_0] = \omega(\pi_2) \lor \omega(\pi_0)$, so that ω is *h*-increasing. The property remain true when \lor is replaced by \land .

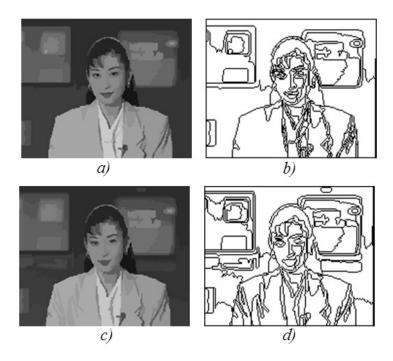


Figure 7: a) minimization by lenght of perimeter, b) associated optimum cut, c) minimization by number of flat zones, d) associated optimum cut.

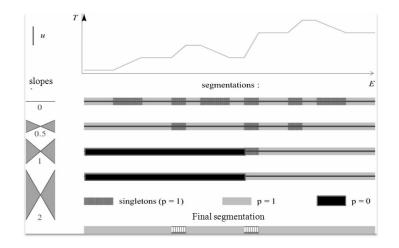


Figure 8: One-dimensionnal pedagogical exemple of connective segmentation under constraint.

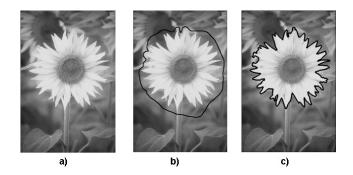


Figure 9: a) Initial image; b) manual lasso; c) contour of the union of the classes inside the lasso.

7.1 Connective segmentation under constraint

This method was proposed by P. Soille and J. Grazzini in [14] and [15] with several variants; it is re-formulated by C. Ronse in a more general framework in [10]. Start from a hierarchy H and a numerical function f. Define the energy ω^j for class S by

 $\omega^{j}(S) = 0 \quad \text{when} \quad \sup\{f(x), x \in S\} - \inf\{f(x), x \in S\} \le c^{j} \\ \omega^{j}(S) = 1 \quad \text{when not},$

where c^j is a given bound, and extend to partitions by \vee -composition. The class at point x of the largest partition of minimum energy is given by the largest $S \in S$, that contains x, and such that the amplitude of variation of f inside S be $\leq c^j$. As bound c^j increases, the $\{\omega^j\}$ form a climbing energy, as depicted by the pedagogical example of Figure 8.

7.2 Lasso

This algorithm, due to F. Zanoguera et Al. [16], appears also in [6]. An initial image has been segmented into α -flat zones, which generates a hierarchy as the slope α increases. The optimization consists then in drawing manually a closed curve around the object to segment. If A designates the inside of this lasso, then we take the following function

$$\begin{aligned}
\omega(S) &= 0 \quad \text{when } S \subseteq A \; ; \; S \in \mathcal{S} \\
\omega(S) &= 1 \quad \text{when not,}
\end{aligned} \tag{23}$$

for energy, and we go from classes to partitions by \lor -composition of the energies. The largest cut that minimizes ω is depicted in Figure 9c. We see that the resulting contour follows the edges of the petals. Indeed, a segmented class can jump over this high gradient only for α large enough, and then this class is rejected because it spreads out beyond the limit of the lasso.

By taking a series $\{A^j, 1 \leq j \leq p\}$ of increasing lassos A^j we make climbing the energy ω of Relation (23), and Theorem 11 applies. Unlike the previous case, where the λ^j are scalars numbers, the multiscale parametrization is now given by a family of increasing sets.

8 Conclusion

Other examples can be given, concerning colour imagery in particular [1]. At this stage, the main goal is to extend the above approach to vector data, and more generally to GIS type data.

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