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# Analytical Prediction of Magnetic Field in Parallel Double Excitation and Spoke-Type Permanent-Magnet Machines Accounting for ToothTips and Shape of Polar Pieces 

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#### Abstract

This paper presents an analytical method based on subdomain method for the computation of open circuit, armature reaction and on-load magnetic field distribution in integer slot winding parallel double excitation and Spoke-Type tangential permanent-magnet machines. The proposed model takes into account for stator and rotor slots tooth tips and shape of polar piece. A 2D exact analytical solution of magnetic field distribution is established. It involves solution of Laplace's and Poisson's equations in semi-closed stator and rotor slots, airgap, buried permanent magnets into rotor semi-closed slots, and non magnetic region under magnets. Obtained exact analytical results of open circuit, armature reaction and on-load magnetic field distribution are verified with those issued from finite element method (FEM).


Index Terms- Exact analytical calculation, finite element method, magnetic field distribution, parallel double excitation, SpokeType permanent magnet machines.

## I. Introduction

Double excitation machines are synchronous machines that have two coexisting excitation field sources: permanent magnets and wound field excitation. The goal behind the use of double excitation principle is to combine advantages of permanent-magnet excited machines and wound field synchronous machines. The combination of permanent magnets and wound field excitation constitutes an additional degree of freedom which can be used to optimize the energy consumption of the electric propulsion system. Among various double excitation machines, parallel double excitation machines have some advantages than series double excitation machines [1]-[5]. The flux created by excitation coils and permanent magnets have different trajectories and the flux created by excitation coils doesn't pass through permanent magnets, hence the demagnetization risk is avoided. Depending on DC excitation current direction, excitation coils can either be used to enhance or decrease excitation flux passing through armature windings.
There are no authors who applied analytical model for predicting magnetic field in this type of hybrid excitation machines with slotted rotor and stator and buried tangential permanent magnet taking into account rotor and stator tooth tips and real structure of polar piece. Analytical methods are useful tools for a first evaluation of electrical motors performances and for design optimization. However, finite element method is used at the final stage of the design. In reference [5], exact analytical calculation of magnetic field distribution is developed for a slotted stator series double excitation machine, where coils current excitation are situated in the slotted rotor with radial surface mounted permanent magnets. There are other structures of double excitation permanent magnet machines with complicated geometry [6][8], where the study is done by finite element method only.

Permanent magnet brushless dc (BLDC) motors have been widely used due to their many advantages such as high torque and high efficiency. In particular, the spoke-type BLDC motor, which can concentrate the flux from low cost ferrite permanent magnets, has a high torque density per unit volume resulting from the additional reluctance torque. The prediction of open circuit, armature reaction and on load magnetic field distribution of this type of motors is done generally by the finite element method (FEM) [9]-[11] and there are very few authors which use analytical methods [12]-[13]. This is due to the structure of those machines, where buried tangential PM region has high height and low width with presence of non magnetic region under magnet. In reference [12], Lin et all. used conformal transformation of rotor and stator slots to determine a relative permeance function to take into account the rotor and stator slotting effects. In reference [13], authors used also a Schwarz-Christoffel transformation to determine d-axial and q-axial airgap magnetic field. Conformal transformation leads to an approximation of magnetic field distribution in a simplified structure of slotted stator spoketype permanent magnet motors. Investigations in applying analytical and numerical conformal mapping have been done in [14] and show the inaccuracy of conformal mapping method in magnetic field modeling of this type of machines. This is not due to the stator slotting effect but to the presence of a deep and small thickness of permanent magnet region. To the author's knowledge, there is no study on the slotted or slotless Spoke-Type PM machines that solves analytically Poisson's and Laplace's equations. However, many authors have used exact analytical method based on subdomain model to take into account stator slotting effect and tooth tips in open circuit and armature reaction magnetic field with circular and tubular radial surface mounted and inset permanent magnet motors [15]-[24]. Inset PM subregion in PM machines is not deep and the width is high. So, it can be modeled accurately
with conformal mapping [25]. In references [15]-[17], authors have developed an exact analytical solution based on subdomain model for predicting open circuit and armature reaction in slotted stator radial surface mounted permanent magnet motor taking into account tooth tips. In [18] and [19], scalar potential magnetic field is used to predict open circuit magnetic field in slotted stator surface and inset radial permanent magnet motors. Authors in [20] and [21] have developed an exact analytical solution based on subdomain model for predicting open circuit and armature reaction in tubular surface mounted and inset radial permanent magnet machines. In [22]-[24], the authors have developed respectively an exact analytical solution also based on subdomain model for flux switching permanent magnet machines and a tubular slotless stator with axially magnetized permanent magnet in rotor.

In this paper, an exact analytical prediction based on subdomain model of open circuit, armature reaction and onload magnetic field distribution in integer slot winding parallel double excitation and spoke-type tangential permanent magnet machines is presented. It involves the solution of Poisson's and Laplace's equations in semi-closed stator slots, buried permanent magnets placed in semi-closed slots, rotor double excitation semi-closed slots, airgap and non magnetic region under permanent magnets. To handle permanent magnets, rotor and stator slots current at the same time, The magnetic vector potential formulation is used. All results from the developed analytical model are then compared to those found by the finite element method (FEM).

## II. Magnetic Field Solution in Parallel Double Excitation PM Machines

Figs. 1 and 2 show the machine model where region I represents the air gap, region II the magnets, regions III and V the stator semi-closed slots, region IV a non magnetic material under magnets, region VI the rotor slots at the top of permanent magnets, regions VII and VIII the rotor excitation semi-closed slots. The model is formulated in vector potential and two-dimensional polar coordinates with the following assumptions.

The stator and rotor cores are assumed to be infinitely permeable.

Eddy current effects are neglected.
The axial length of the machine is infinite i.e. end effects are neglected.

The current density has only one component along the z axis.

The stator and rotor slots have radial sides.
The partial differential equations for magnetic fields in a continuous and isotopic region in term of vector potential $A$ which has one component in $z$ direction and independent of $z$ can be expressed by

$$
\begin{align*}
& \nabla^{2} A=0, \text { in region I, IV, V, VI and VIII }  \tag{1}\\
& \nabla^{2} A=-\mu_{0} \nabla \times M, \text { in region II }  \tag{2}\\
& \nabla^{2} A=-\mu_{0} J, \text { in region III } \tag{3}
\end{align*}
$$

$$
\begin{equation*}
\nabla^{2} A=-\mu_{0} J_{f}, \text { in region VII } \tag{4}
\end{equation*}
$$

where $M$ is the magnetization of permanent magnets, $J$ the stator slots current density, $\mathrm{J}_{\mathrm{f}}$ the excitation rotor slots current density and $\mu_{0}$ the permeability of vacuum.


Fig. 1. Studied parallel double excitation PM machine.


Fig. 2. Simplified model.


Fig. 3. ith stator semi-closed slot subdomains


Fig. 4. jth permanent magnet subdomains


Fig. 5. irth rotor semi-closed slot subdomains
The field vectors $B$ and $H$, in the different regions, are coupled by

$$
\begin{equation*}
B=\mu_{0} H, \text { in regions I, III, IV, V, VI, VII and VIII } \tag{5}
\end{equation*}
$$

where $B_{r}=\mu_{0} H_{r}, B_{\theta}=\mu_{0} H_{\theta}$.

$$
\begin{equation*}
B=\mu_{0} \mu_{r} H+\mu_{0} M, \text { in region II } \tag{6}
\end{equation*}
$$

where $B_{r}=\mu_{0} \mu_{r} H_{r}+\mu_{0} M_{r}, B_{\theta}=\mu_{0} \mu_{r} H_{\theta}+\mu_{0} M_{\theta}$
and $\mu_{r}$ is the relative recoil permeability of permanent magnets. Radial and circumferential flux density components are deduced from $A$ by

$$
\begin{equation*}
B_{r}=\frac{1}{r} \frac{\partial A}{\partial \theta} ; B_{\theta}=-\frac{\partial A}{\partial r} \tag{7}
\end{equation*}
$$

## A. General Solution of Poisson's Equation in Stator Semiclosed Slot Subdomain (Region III)

In each slot subdomain (i) of region III (Fig. 3), we have to solve Poisson's equation

$$
\begin{equation*}
\frac{\partial^{2} A I I I_{i}}{\partial r^{2}}+\frac{1}{r} \frac{\partial A I I I_{i}}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A I I I_{i}}{\partial \theta^{2}}=-\mu_{0} J_{i} \tag{8}
\end{equation*}
$$

where $J_{i}$ is the current density in the slot $i$.
As shown in Fig. 3, the ith slot subdomain (region III) where $i$ vary from 1 to $Q_{s}$ ( $Q_{s}$ is the number of stator slots) is associated with boundary conditions at the bottom and at each sides of the slot as

$$
\begin{align*}
& \left.\frac{\partial A I I I_{i}}{\partial \theta}\right|_{\theta=\alpha_{i}-\frac{c}{2}}=0 \text { and }\left.\frac{\partial A I I I_{i}}{\partial \theta}\right|_{\theta=\alpha_{i}+\frac{c}{2}}=0  \tag{9}\\
& \left.\frac{\partial A I I I_{i}}{\partial r}\right|_{r=r_{4}}=0 \tag{10}
\end{align*}
$$

where $\alpha_{i}$ is the angular position of the $i t h$ slot and $c$ the slot opening in radian.

The boundary condition (9), leads to the eigenvalues and eigenfunctions of the partial differential equation (8) as shown in details in [26]. The eigenfunctions are called spatial frequencies of the considered region [23]. The boundary condition (10), leads to the general solution of equation (8) with only two integration constants $\mathrm{C}_{\mathrm{i}, 0}$ and $\mathrm{C}_{\mathrm{i}, \mathrm{m}}$ as shown in (11).

From above boundary conditions (9) and (10), the solution of (8) using the method of separation of variables is

$$
\begin{align*}
& \text { AIII }_{i}(r, \theta)=C_{i, 0}+\frac{1}{2} \mu_{0} J_{i} r_{4}^{2} \ln (r)-\frac{1}{4} \mu_{0} J_{i} r^{2}  \tag{11}\\
& +\sum_{m=1}^{\infty} C_{i, m}\left[\left(\frac{r}{r_{4}}\right)^{\frac{m \pi}{c}}-\left(\frac{r}{r_{4}}\right)^{-\frac{m \pi}{c}}\right] \cos \left(\frac{m \pi}{c}\left(\theta-\alpha_{i}+\frac{c}{2}\right)\right)
\end{align*}
$$

where m is a positive integer.
B. General Solution of Laplace's Equation in Stator SemiClosed Slot Subdomain (Region V)
In each stator semi-closed slot subdomain (i) of region V (Figs. 2, 3), we have to solve Laplace's equation

$$
\begin{equation*}
\frac{\partial^{2} A V_{i}}{\partial r^{2}}+\frac{1}{r} \frac{\partial A V_{i}}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A V_{i}}{\partial \theta^{2}}=0 \tag{12}
\end{equation*}
$$

As shown in Fig. 3, the ith slot subdomain (region V) where $i$ vary from 1 to $Q_{s}$ ( $Q_{s}$ number of stator slots) is associated with the following boundary conditions

$$
\begin{equation*}
\left.\frac{\partial A V_{i}}{\partial \theta}\right|_{\theta=\alpha_{i}-\frac{d}{2}}=0 \text { and }\left.\frac{\partial A V_{i}}{\partial \theta}\right|_{\theta=\alpha_{i}+\frac{d}{2}}=0 \tag{13}
\end{equation*}
$$

where $d$ is the semi-closed slot opening in radian.
From above boundary conditions (13), the solution of (12) using the method of separation of variables is

$$
\begin{align*}
& A V_{i}(r, \theta)=A 11_{i, 0}+A 12_{i, 0} \ln (r)  \tag{14}\\
& +\sum_{k=1}^{\infty}\left(A 11_{i, k} r^{-\frac{k \pi}{d}}+A 12_{i, k} r^{\frac{k \pi}{d}}\right) \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right)
\end{align*}
$$

where k is a positive integer.

## C. General Solution of Poisson's Equation in Permanent Magnet Subdomain (Region II)

In each permanent magnet subdomain (j) of region II (Figs. 2 and 4), we have to solve Poisson's equation (2). The magnetization of parallel double excitation motor is purely tangential. Equation (2) is then reduced to

$$
\begin{equation*}
\frac{\partial^{2} A I I_{j}}{\partial r^{2}}+\frac{1}{r} \frac{\partial A I I_{j}}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A I I_{j}}{\partial \theta^{2}}=-\mu_{0} \frac{M_{\theta}}{r} \tag{15}
\end{equation*}
$$

where $M_{\theta}=M_{j}=(-1)^{j} \frac{B_{r e m}}{\mu_{0}}$
For a $2 p$ poles machine, j vary from 1 to $2 p$ and $B_{\text {rem }}$ is the remanence of magnetization.

As shown in Fig. 4, the jth magnet subdomain (region II) is associated with the following boundary conditions

$$
\begin{equation*}
\left.\frac{\partial A I I_{j}}{\partial \theta}\right|_{\theta=g_{j}-\frac{a}{2}}=0 \text { and }\left.\frac{\partial A I I_{j}}{\partial \theta}\right|_{\theta=g_{j}+\frac{a}{2}}=0 \tag{16}
\end{equation*}
$$

where $g_{j}$ is the angular position of the $j t h$ magnet and $a$ the magnet opening in radian.

From above boundary conditions (16), the general solution of (15) using the method of separation of variables is given by

$$
\begin{aligned}
& A I I_{j}(r, \theta)=A 5_{j, 0}+A 6_{j, 0} \ln (r)-\mu_{0} M_{j} r \\
+ & \sum_{m=1}^{\infty}\left(A 5_{j, m} r^{-\frac{m \pi}{a}}+A 6_{j, m} r^{\frac{m \pi}{a}}\right) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right)
\end{aligned}
$$

## D. General Solution of Laplace's Equation in Rotor Semi-

 Closed Slot Subdomain (Region VI)In each rotor semi-closed slot subdomain ( j ) of region VI (Figs. 2, 4), we have to solve Laplace's equation

$$
\begin{equation*}
\frac{\partial^{2} A V I_{j}}{\partial r^{2}}+\frac{1}{r} \frac{\partial A V I_{j}}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A V I_{j}}{\partial \theta^{2}}=0 \tag{18}
\end{equation*}
$$

As shown in Fig. 4, the jth slot subdomain (region VI) where j vary from 1 to $2 p$ is associated with the following boundary conditions

$$
\begin{equation*}
\left.\frac{\partial A V I_{j}}{\partial \theta}\right|_{\theta=g_{j}-\frac{b}{2}}=0 \text { and }\left.\frac{\partial A V I_{j}}{\partial \theta}\right|_{\theta=g_{j}+\frac{b}{2}}=0 \tag{19}
\end{equation*}
$$

where $b$ is the semi-closed slot opening in radian.
From above boundary conditions (19), the solution of (18) using the method of separation of variables is

$$
\begin{aligned}
& A V I_{j}(r, \theta)=A 13_{j, 0}+A 14_{j, 0} \ln (r) \\
& +\sum_{k=1}^{\infty}\left(A 13_{j, k} r^{-\frac{k \pi}{b}}+A 14_{j, k} r^{\frac{k \pi}{b}}\right) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right)
\end{aligned}
$$

## E. General Solution of Laplace's Equation in Airgap Subdomain (Region I)

The Laplace equation (1) in the airgap subdomain (region I) which is an annular domain delimited by the radii $R_{m}$ and $R_{s}$ (Fig. 2) is given by

$$
\begin{equation*}
\frac{\partial^{2} A I}{\partial r^{2}}+\frac{1}{r} \frac{\partial A I}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A I}{\partial \theta^{2}}=0 \tag{21}
\end{equation*}
$$

Taking into account the periodicity boundary condition between $\theta=0$ and $\theta=2 \pi / p$ for the studied machine with integer slot winding, the solution of equation (21) is

$$
\begin{align*}
A I(r, \theta)= & \sum_{n=1}^{\infty}\left(A 1_{n} r^{n p}+A 2_{n} r^{-n p}\right) \sin (n p \theta)  \tag{22}\\
& +\left(A 3_{n} r^{n p}+A 4_{n} r^{-n p}\right) \cos (n p \theta)
\end{align*}
$$

where n is a positive integer.

## F. General Solution of Laplace's Equation in the Non Magnetic Subdomain (Region IV)

The Laplace's equation (1) in the non magnetic subdomain region IV which is an annular domain delimited by the radii $R_{i}$ and $R_{r}$ and where the relative recoil permeability is equal to 1 is given by

$$
\begin{equation*}
\frac{\partial^{2} A I V}{\partial r^{2}}+\frac{1}{r} \frac{\partial A I V}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A I V}{\partial \theta^{2}}=0 \tag{23}
\end{equation*}
$$

Taking into account the periodicity boundary condition between $\theta=0$ and $\theta=2 \pi / p$, the general solution of (23) is

$$
\begin{align*}
A I V(r, \theta)= & \sum_{n=1}^{\infty}\left(A 7_{n} r^{n p}+A 8_{n} r^{-n p}\right) \sin (n p \theta)  \tag{24}\\
& +\left(A 9_{n} r^{n p}+A 10_{n} r^{-n p}\right) \cos (n p \theta)
\end{align*}
$$

The magnetic vector potential must be finite in region IV. In this case, constants $A 8_{\mathrm{n}}$ and $\mathrm{A} 10_{\mathrm{n}}$ are equals to zero and equation (24) is reduced to

$$
\begin{align*}
A I V(r, \theta)= & \sum_{n=1}^{\infty} A 7_{n} r^{n p} \sin (n p \theta)  \tag{25}\\
& +A 9_{n} r^{n p} \cos (n p \theta)
\end{align*}
$$

## G. General Solution of Poisson's Equation in Rotor

 Excitation Coil Slot Subdomain (Region VII)In each rotor slot subdomain (ir) of region VII, we have to solve Poisson's equation (26)

$$
\begin{equation*}
\frac{\partial^{2} A V I I_{i r}}{\partial r^{2}}+\frac{1}{r} \frac{\partial A V I I_{i r}}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A V I I_{i r}}{\partial \theta^{2}}=-\mu_{0} J_{f_{i r}} \tag{26}
\end{equation*}
$$

where $J_{f i r}$ is the current density in rotor slot $i r$.
As shown in Fig. 5, the irth slot subdomain (region VII) where ir vary from 1 to $N_{r}$ ( $N_{r}$ is total number of rotor excitation slots) is associated with the following boundary conditions

$$
\begin{align*}
& \left.\frac{\partial A V I I_{i r}}{\partial \theta}\right|_{\theta=\beta_{i r}-\frac{c r}{2}}=0 \text { and }\left.\frac{\partial A V I I_{i r}}{\partial \theta}\right|_{\theta=\beta_{i r}+\frac{c r}{2}}=0  \tag{27}\\
& \left.\frac{\partial A V I I_{i r}}{\partial r}\right|_{r=r_{1}}=0 \tag{28}
\end{align*}
$$

where $\beta_{i r}$ is the angular position of the irth slot and $c_{r}$ the rotor slot opening in radian.

From the above boundary conditions (27) and (28), the solution of (26) using the method of separation of variables is

$$
\begin{align*}
A V I I_{i r}(r, \theta)= & C 1_{i r, 0}+\frac{1}{2} \mu_{0} J_{f_{i r}} r_{1}^{2} \ln (r)-\frac{1}{4} \mu_{0}  \tag{29}\\
& +\sum_{m=1}^{\infty} C 1_{i r, m}\left[\left(\frac{r}{r_{1}}\right)^{\frac{m \pi}{c_{r}}}-\left(\frac{r}{r_{1}}\right)^{-\frac{m \pi}{c_{r}}}\right] . \\
& \cos \left(\frac{m \pi}{c_{r}}\left(\theta-\beta_{i r}+\frac{c_{r}}{2}\right)\right)
\end{align*}
$$

H. General Solution of Laplace's Equation in Rotor Excitation Coil Slot Subdomain (Region VIII)
In each semi-closed slot subdomain (ir) of region VIII (Fig. 5), we have to solve Laplace's equation

$$
\begin{equation*}
\frac{\partial^{2} A V I I I_{i r}}{\partial r^{2}}+\frac{1}{r} \frac{\partial A V I I I_{i r}}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} A V I I I_{i r}}{\partial \theta^{2}}=0 \tag{30}
\end{equation*}
$$

As shown in Fig. 5, the irth slot subdomain (region VIII) where ir vary from 1 to $N_{r}$ is associated with the following boundary conditions

$$
\begin{equation*}
\left.\frac{\partial A V I I I_{i r}}{\partial \theta}\right|_{\theta=\beta_{i r}-\frac{d r}{2}}=0 \text { and }\left.\frac{\partial A V I I I_{i r}}{\partial \theta}\right|_{\theta=\beta_{i r}+\frac{d r}{2}}=0 \tag{31}
\end{equation*}
$$

where $d r$ is the semi-closed slot opening in radian.
From previous boundary conditions (31), the solution of partial differential equation (30) using the method of separation of variables is

$$
\begin{align*}
A_{V I I I}(r, \theta)= & A 15_{i r, 0}+A 16_{i r, 0} \ln (r)  \tag{32}\\
+ & \sum_{k=1}^{\infty}\left(A 15_{i r, k} r^{-\frac{k \pi}{d r}}+A 16_{i r, k} r^{\frac{k \pi}{d r}}\right) \\
& \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right)
\end{align*}
$$

## III. Boundary and Interface Conditions

To determine Fourier series unknown constants $A 1_{n}, A 2_{n}$, $A 3_{n}, A 4_{n}, A 5_{j, 0}, A 6_{j, 0}, A 5_{j, m}, A 6_{j, m}, A 7_{n}, A 9_{n}, A 11_{i, 0}, A 12_{i, 0}$, $\mathrm{A} 11_{\mathrm{i}, \mathrm{k}}, \mathrm{A} 12_{\mathrm{i}, \mathrm{k}}, \mathrm{A} 13_{\mathrm{j}, 0}, \mathrm{~A} 14_{\mathrm{j}, 0}, \mathrm{~A} 13_{\mathrm{j}, \mathrm{k}}, \mathrm{A} 14_{\mathrm{j}, \mathrm{k},}, \mathrm{C}_{\mathrm{i}, 0}, \mathrm{C}_{\mathrm{i}, \mathrm{m}}, \mathrm{C} 1_{\mathrm{ir}, 0}$, $\mathrm{C} 1_{\mathrm{ir}, \mathrm{m}}, \mathrm{A} 15_{\mathrm{ir}, 0}, \mathrm{~A} 16_{\mathrm{ir}, 0}, \mathrm{~A} 15_{\mathrm{ir}, \mathrm{k}}$ and $\mathrm{A} 16_{\mathrm{ir}, \mathrm{k}}$, boundary and interface conditions should be introduced.

The interface conditions between regions IV and II at $R_{r}$ are

$$
\begin{equation*}
A I I_{j}\left(R_{r}, \theta\right)=\operatorname{AIV}\left(R_{r}, \theta\right) \tag{33}
\end{equation*}
$$

where $g_{j}-\frac{a}{2} \leq \theta \leq g_{j}+\frac{a}{2}$.

$$
\begin{equation*}
H I I_{\theta_{j}}\left(R_{r}, \theta\right)=H I V_{\theta}\left(R_{r}, \theta\right) \tag{34}
\end{equation*}
$$

where $g_{j}-\frac{a}{2} \leq \theta \leq g_{j}+\frac{a}{2}$.
$\operatorname{HIV}_{\theta}\left(R_{r}, \theta\right)=0$ elsewhere.
The interface conditions between regions II and VI at $r_{2}$ are

$$
\begin{equation*}
A V I_{j}\left(r_{2}, \theta\right)=A I I_{j}\left(r_{2}, \theta\right) \tag{35}
\end{equation*}
$$

where $g_{j}-\frac{b}{2} \leq \theta \leq g_{j}+\frac{b}{2}$.

$$
\begin{equation*}
H V I_{\theta_{j}}\left(r_{2}, \theta\right)=H I I_{\theta_{j}}\left(r_{2}, \theta\right) \tag{36}
\end{equation*}
$$

where $g_{j}-\frac{b}{2} \leq \theta \leq g_{j}+\frac{b}{2}$.
$H I I_{\theta_{j}}\left(r_{2}, \theta\right)=0$ elsewhere.
The interface condition between regions I and VI at $\mathrm{R}_{\mathrm{m}}$ is

$$
\begin{equation*}
A V I_{j}\left(R_{m}, \theta\right)=A I\left(R_{m}, \theta\right) \tag{37}
\end{equation*}
$$

where $g_{j}-\frac{b}{2} \leq \theta \leq g_{j}+\frac{b}{2}$.
The interface condition between regions I and VIII at $\mathrm{R}_{\mathrm{m}}$ is
$A I\left(R_{m}, \theta\right)=A V I I I_{i r}\left(R_{m}, \theta\right)$
where $\beta_{i r}-\frac{d_{r}}{2} \leq \theta \leq \beta_{i r}+\frac{d_{r}}{2}$.
The interface conditions between regions I, VI and VIII at $\mathrm{R}_{\mathrm{m}}$ are
$H I_{\theta}\left(R_{m}, \theta\right)=H V I_{\theta_{j}}\left(R_{m}, \theta\right)$
for $g_{j}-\frac{b}{2} \leq \theta \leq g_{j}+\frac{b}{2}$ and
$H I_{\theta}\left(R_{m}, \theta\right)=\operatorname{HVIII}_{\theta i r}\left(R_{m}, \theta\right)$
for $\beta_{i r}-\frac{d_{r}}{2} \leq \theta \leq \beta_{i r}+\frac{d_{r}}{2}$ and
$H I_{\theta}\left(R_{m}, \theta\right)=0$ elsewhere.
The interface conditions between regions I and V at $R_{s}$ are

$$
\begin{equation*}
A I\left(R_{s}, \theta\right)=A V_{i}\left(R_{s}, \theta\right) \tag{40}
\end{equation*}
$$

where $\alpha_{i}-\frac{d}{2} \leq \theta \leq \alpha_{i}+\frac{d}{2}$.

$$
\begin{equation*}
H I_{\theta}\left(R_{s}, \theta\right)=H V_{\theta i}\left(R_{s}, \theta\right) \tag{41}
\end{equation*}
$$

where $\alpha_{i}-\frac{d}{2} \leq \theta \leq \alpha_{i}+\frac{d}{2}$.
$H I_{\theta}\left(R_{s}, \theta\right)=0$ elsewhere.
The interface conditions between regions III and V at $r_{3}$ are

$$
\begin{equation*}
A I I I_{i}\left(r_{3}, \theta\right)=A V_{i}\left(r_{3}, \theta\right) \tag{42}
\end{equation*}
$$

where $\alpha_{i}-\frac{d}{2} \leq \theta \leq \alpha_{i}+\frac{d}{2}$.

$$
\begin{equation*}
H I I I_{\theta_{i}}\left(r_{3}, \theta\right)=H V_{\theta i}\left(r_{3}, \theta\right) \tag{43}
\end{equation*}
$$

where $\alpha_{i}-\frac{d}{2} \leq \theta \leq \alpha_{i}+\frac{d}{2}$.
$H I I I_{\theta i}\left(r_{3}, \theta\right)=0$ elsewhere.
The interface conditions between regions VII and VIII at $r_{0}$ are

$$
\begin{equation*}
A V I I_{i r}\left(r_{0}, \theta\right)=A V I I I_{i r}\left(r_{0}, \theta\right) \tag{44}
\end{equation*}
$$

where $\beta_{i r}-\frac{d_{r}}{2} \leq \theta \leq \beta_{i r}+\frac{d_{r}}{2}$

$$
\begin{equation*}
H V I I_{\theta i r}\left(r_{0}, \theta\right)=H V I I I_{\theta i r}\left(r_{0}, \theta\right) \tag{45}
\end{equation*}
$$

where $\beta_{i r}-\frac{d_{r}}{2} \leq \theta \leq \beta_{i r}+\frac{d_{r}}{2}$
$H V I I_{\theta i r}\left(r_{0}, \theta\right)=0$ elsewhere
Interface conditions (33) to (45) concern regions with different subdomain frequencies which need Fourier series expansions to satisfy equalities of vector potential and magnetic field at each interface radius.

Interface condition (33) represents also the continuity of radial flux density at the permanent magnet opening at $R_{r}$. According to Fourier series expansion, we obtain two equations as

$$
\begin{equation*}
A 5_{j, 0}+A 6_{j, 0} \ln \left(R_{r}\right)-M_{j} \mu_{0} R_{r} \tag{46}
\end{equation*}
$$

$=\frac{1}{a} \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} A I V\left(R_{r}, \theta\right) d \theta$
$A 5_{j, m} R_{r}^{-\left(\frac{m \pi}{a}\right)}+A 6_{j, m} R_{r}^{\left(\frac{m \pi}{a}\right)}$
$=\frac{2}{a} \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \operatorname{AIV}\left(R_{r}, \theta\right) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta$
Interface condition (34) gives
$\left(\frac{n p}{\mu_{0}}\right)\left(-A 7_{n} R_{r}^{n p-1}\right)$
$=\frac{1}{\pi} \sum_{j=1}^{2 p} \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} H I I_{\theta_{j}}\left(R_{r}, \theta\right) \sin (n p \theta) d \theta$

$$
\begin{equation*}
\left(\frac{n p}{\mu_{0}}\right)\left(-A 9_{n} R_{r}^{n p-1}\right) \tag{49}
\end{equation*}
$$

$$
=\frac{1}{\pi} \sum_{j=1}^{2 p} \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} H I I_{\theta_{j}}\left(R_{r}, \theta\right) \cos (n p \theta) d \theta
$$

Fourier series expansion of interface condition (35) between region II and VI at radius $\mathrm{r}_{2}$ gives

$$
\begin{align*}
& A 13_{j, 0}+A 14_{j, 0} \ln \left(r_{2}\right)  \tag{50}\\
&= \frac{1}{b} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} A I I_{j}\left(r_{2}, \theta\right) d \theta \\
& A 13_{j, k} r_{2}^{-\frac{k \pi}{b}}+A 14_{j, k} r_{2}{ }^{\frac{k \pi}{b}}  \tag{51}\\
&= \frac{2}{b} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} A I I I_{j}\left(r_{2}, \theta\right) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta
\end{align*}
$$

From interface condition (36), we get

$$
\begin{align*}
& -\frac{A 6_{j, 0}}{r_{2}} \frac{1}{\mu_{0} \mu_{r}}=\frac{1}{a} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} H V I_{\theta j}\left(r_{2}, \theta\right) d \theta  \tag{52}\\
&  \tag{53}\\
& \frac{1}{\mu_{0} \mu_{r}} \frac{m \pi}{a}\left(A 5_{j, m} r_{2}^{-\frac{m \pi}{a}-1}-A 6_{j, m} r_{2}^{\frac{m \pi}{a}-1}\right) \\
& = \\
& \frac{2}{a} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} H V I_{\theta j}\left(r_{2}, \theta\right) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta
\end{align*}
$$

At radius $\mathrm{R}_{\mathrm{m}}$, Fourier series expansions of the three interface conditions (37) to (39) between regions I, VI and VIII result in 6 equations. Interface condition (37) gives

$$
\begin{align*}
& A 13_{j, 0}+A 14_{j, 0} \ln \left(R_{m}\right)=\frac{1}{b} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} A I\left(R_{m}, \theta\right) d \theta  \tag{54}\\
& A 13_{j, k} R_{m}^{-\frac{k \pi}{b}}+A 14_{j, k} R_{m}^{\frac{k \pi}{b}}  \tag{55}\\
& =\frac{2}{b} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} A I\left(R_{m}, \theta\right) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta
\end{align*}
$$

Fourier series expansion of interface condition (38) gives

$$
\begin{equation*}
A 15_{i r, 0}+A 16_{i r, 0} \ln \left(R_{m}\right)=\frac{1}{b} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} A I\left(R_{m}, \theta\right) d \theta \tag{56}
\end{equation*}
$$

$A 15_{i r, k} R_{m}^{-\frac{k \pi}{d r}}+A 16_{i r, k} R_{m}^{\frac{k \pi}{d r}}$
$=\frac{2}{d r} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} A I\left(R_{m}, \theta\right) \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right)$
Fourier series expansion of interface condition (39) gives
$\frac{n p}{\mu_{0}}\left(-A 1_{n} R_{m}^{n p-1}+A 2_{n} R_{m}^{-n p-1}\right)$
$=\frac{1}{\pi} \sum_{j=1}^{2 p} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} H V I_{\theta_{j}}\left(R_{m}, \theta\right) \sin (n p \theta) d \theta$
$+\frac{1}{\pi} \sum_{i r=1}^{N_{r}} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} H V I I I_{\theta i r}\left(R_{m}, \theta\right) \sin (n p \theta) d \theta$
$\frac{n p}{\mu_{0}}\left(-A 3_{n} R_{m}^{n p-1}+A 4_{n} R_{m}^{-n p-1}\right)$
$=\frac{1}{\pi} \sum_{j=1}^{2 p} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} H V I_{\theta j}\left(R_{m}, \theta\right) \cos (n p \theta) d \theta$
$+\frac{1}{\pi} \sum_{i r=1}^{N_{r}} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} H V I I I_{\theta i r}\left(R_{m}, \theta\right) \cos (n p \theta) d \theta$
At radius $\mathrm{R}_{\mathrm{s}}$, Fourier series expansions of interface condition (40) gives

$$
\begin{equation*}
A 11_{i, 0}+A 12_{i, 0} \ln \left(R_{s}\right)=\frac{1}{d} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} A I\left(R_{s}, \theta\right) d \theta \tag{60}
\end{equation*}
$$

$A 11_{i, k} R_{s}^{-\frac{k \pi}{d}}+A 12_{i, k} R_{s}^{\frac{k \pi}{d}}$
$=\frac{2}{d} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} A I\left(R_{s}, \theta\right) \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) d \theta$
Interface condition (41) gives
$\frac{n p}{\mu_{0}}\left(-A 1_{n} R_{s}^{n p-1}+A 2_{n} R_{s}^{-n p-1}\right)$
$=\frac{1}{\pi} \sum_{i=1}^{Q_{s}} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} H V_{\theta i}\left(R_{s}, \theta\right) \sin (n p \theta) d \theta$
$\frac{n p}{\mu_{0}}\left(-A 3_{n} R_{s}^{n p-1}+A 4_{n} R_{s}^{-n p-1}\right)$

$$
=\frac{1}{\pi} \sum_{i=1}^{Q_{s}} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} H V_{\theta i}\left(R_{s}, \theta\right) \cos (n p \theta) d \theta
$$

Fourier series expansion of interface condition (42) gives

$$
\begin{equation*}
A 11_{i, 0}+A 12_{i, 0} \ln \left(r_{3}\right)=\frac{1}{d} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} A I I I_{i}\left(r_{3}, \theta\right) d \theta \tag{64}
\end{equation*}
$$

$$
\begin{equation*}
A 11_{i, k} r_{3}^{-\frac{k \pi}{d}}+A 12_{i, k} r_{3}^{\frac{k \pi}{d}} \tag{65}
\end{equation*}
$$

$$
=\frac{2}{d} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} A I I I_{i}\left(r_{3}, \theta\right) \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) d \theta
$$

Fourier series expansion of interface condition (43) gives

$$
\begin{equation*}
\frac{1}{\mu_{0}}\left(-\frac{1}{2} \frac{\mu_{0} J_{i} r_{4}^{2}}{r_{3}}+\frac{1}{2} \mu_{0} J_{i} r_{3}\right) \tag{66}
\end{equation*}
$$

$$
=\frac{1}{c} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} H V_{\theta i}\left(r_{3}, \theta\right) d \theta
$$

$$
\begin{equation*}
-\frac{C_{i, m}}{\mu_{0}}\left(\frac{m \pi}{c r_{3}}\right)\left(\left(\frac{r_{3}}{r_{4}}\right)^{\frac{m \pi}{c}}+\left(\frac{r_{3}}{r_{4}}\right)^{-\frac{m \pi}{c}}\right) \tag{67}
\end{equation*}
$$

$$
=\frac{2}{c} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} H V_{\theta i}\left(r_{3}, \theta\right) \cos \left(\frac{m \pi}{c}\left(\theta-\alpha_{i}+\frac{c}{2}\right)\right) d \theta
$$

Fourier series expansion of interface condition (44) gives

$$
\begin{equation*}
A 15_{i r, 0}+A 16_{i r, 0} \ln \left(r_{0}\right) \tag{68}
\end{equation*}
$$

$$
\begin{align*}
& =\frac{1}{d r} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} A V I I_{i r}\left(r_{0}, \theta\right) d \theta \\
& A 15_{i r, k} r_{0}^{-\frac{k \pi}{d r}}+A 16_{i r, k} r_{0}^{\frac{k \pi}{d r}} \tag{69}
\end{align*}
$$

$$
=\frac{2}{d r} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} A V I I_{i r}\left(r_{0}, \theta\right) \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta
$$

Fourier series expansion of interface condition (45) gives

$$
\begin{equation*}
\frac{1}{\mu_{0}}\left(-\frac{1}{2} \frac{\mu_{0} J_{\text {fir }} r_{1}^{2}}{r_{0}}+\frac{1}{2} \mu_{0} J_{f i r} r_{0}\right) \tag{70}
\end{equation*}
$$

$$
\begin{aligned}
& =\frac{1}{c r} \int_{\beta_{i i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} H V I I I_{\theta i r}\left(r_{0}, \theta\right) d \theta \\
& -\frac{C 1_{i r, m}}{\mu_{0}} \frac{m \pi}{c r r_{0}}\left(\left(\frac{r_{0}}{r_{1}}\right)^{\frac{m \pi}{c r}}+\left(\frac{r_{0}}{r_{1}}\right)^{-\frac{m \pi}{c r}}\right)= \\
& \frac{2}{c r} \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} H V I I I_{\theta i r}\left(r_{0}, \theta\right) \cos \left(\frac{m \pi}{c r}\left(\theta-\beta_{i r}+\frac{c r}{2}\right)\right) d \theta
\end{aligned}
$$

Some developments of equations (46) to (71) are given in appendix.

From equations (46)-(71) we can calculate the 26 coefficients $A 1_{\mathrm{n}}, \mathrm{A} 2_{\mathrm{n}}, \mathrm{A} 3_{\mathrm{n}}, \mathrm{A} 4_{\mathrm{n}}, \mathrm{A} 5_{\mathrm{j}, 0}, \mathrm{~A} 6_{\mathrm{j}, 0}, \mathrm{~A} 5_{\mathrm{j}, \mathrm{m}}, \mathrm{A} 6_{\mathrm{j}, \mathrm{m}}, \mathrm{A} 7_{\mathrm{n}}$, $\mathrm{A} 9_{\mathrm{n}}, \mathrm{A} 11_{\mathrm{i}, 0}, \mathrm{~A} 12_{\mathrm{i}, 0}, \mathrm{~A} 11_{\mathrm{i}, \mathrm{k}}, \mathrm{A} 12_{\mathrm{i}, \mathrm{k}}, \mathrm{A} 13_{\mathrm{j}, 0}, \mathrm{~A} 14_{\mathrm{j}, 0}, \mathrm{~A} 13_{\mathrm{j}, \mathrm{k}}, \mathrm{A} 14_{\mathrm{j}, \mathrm{k},}$, $\mathrm{C}_{\mathrm{i}, 0}, \mathrm{C}_{\mathrm{i}, \mathrm{m}}, \mathrm{C} 1_{\mathrm{ir}, 0}, \mathrm{C} 1_{\mathrm{ir}, \mathrm{m}}, \mathrm{A} 15_{\mathrm{ir}, 0}, \mathrm{~A} 16_{\mathrm{ir}, 0}, \mathrm{~A} 15_{\mathrm{ir}, \mathrm{k}}, \mathrm{A} 16_{\mathrm{ir}, \mathrm{k}}$ with a given number of harmonics for $\mathrm{n}, \mathrm{m}$ and k .

Spoke-Type PM machine shown in Fig. 6 is a particular case of parallel double excitation PM machine. The analytical developments are the same where subregions VII and VIII are omitted.


Fig. 6. Studied Spoke-Type PM machine.

## IV. Results and Validation

The developed exact analytical method based on subdomain model for parallel double excitation and SpokeType permanent magnet machines taking into account rotor and stator slot tooth tips and real structure of polar piece is used to determine open circuit, armature reaction and on load magnetic field distribution in the middle of the airgap. The main dimensions and parameters of the studied machine are given in Table I. Then, analytical results are verified by finite element method (FEM) [27]. For the FE simulations, we have used 92882 nodes and 184906 elements.
In order to calculate armature reaction, on load and rotor double excitation magnetic field distribution, stator current
density in slots is defined by a matrix connection between phase current and stator slots as

$$
C=\left[\begin{array}{cccccccccccc}
1 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0  \tag{72}\\
0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & -1 \\
0 & -1 & 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 & 0
\end{array}\right]
$$

The studied machine is fed by $120^{\circ}$ rectangular currents and has an integer number of slot per pole and per phase (Table I). Stator current densities in slots are defined as

$$
J_{i}=\frac{N_{c}}{S} C^{T}\left[\begin{array}{lll}
I_{m} & 0 & -I_{m} \tag{73}
\end{array}\right]
$$

where $S$ is the area of slot, $N_{c}$ the number of conductors in slot and $I_{m}$ the stator phase peak current.
Rotor double excitation current density for one pole pair is defined as

$$
J_{f_{n r}}=\frac{N_{f} I_{f}}{S_{f}}\left[\begin{array}{llll}
-1 & -1 & 1 & 1 \tag{74}
\end{array}\right]
$$

where $N_{f}$ is the number of conductors in slot, $I_{f}$ the DC excitation current and $S_{f}$ the surface of rotor slot.
Analytical calculation of magnetic field can be done for one pole pair to minimize the number of harmonics for $n, k$ and $m$ and to reduce the computation time. It should be noted that the number of harmonics are defined carefully and including proper scaling of machine model dimensions to get good results and avoid solution to diverge [22]. Finite element method which uses a meshed geometry has a limited accuracy related to the density of the mesh. Analytical subdomain model based on Fourier theory exhibits a similar problem. The inaccuracies of the proposed method are related to the limited amount of harmonics included in the solution. When the number of harmonic terms increase, the system of equations written in matrix form can be ill-conditioned and the solution becomes inaccurate. This problem has been reduced in our calculations by including proper scaling of machine model dimensions in radial direction for all regions

$$
\begin{equation*}
r_{\text {scal }}=r_{\text {real }} 10^{x c} \tag{75}
\end{equation*}
$$

for a given real radii of the studied machine (Table I), new scaled radii are given by equation (75).
Limiting the number of harmonics for limiting computational time will lead to inaccurate field solutions, especially for PM machines where airgap length is small, PM subregion with high height and small thickness and high number of subregions with different spatial frequencies. For the studied parallel double excitation PM machine, the number of subregions is equal to 50 . To obtain an accurate magnetic field solution, $x c=1.45$ with the number of harmonics 250 for $n$ and 80 for $m$ and $k$. An optimum number of harmonics and scaling factor with limiting computational time can be found with using for example, different harmonics for all of the 8 regions. Of course, the number of harmonics in the airgap and PM should be high but the number of harmonics in the non magnetic region VI can be small.
Figs. 7 to 14 show a comparison between analytical and FEM open circuit, armature reaction and on load magnetic field distribution results in the middle of the airgap of parallel double excitation PM machine accounting for tooth tips and real structure of polar piece. The results are in excellent
agreement. This type of PM machines has a small magnet arc to pole pitch ratio ( 0.2 ) and a very high height ( 29.8 mm ) in comparison with radial surface mounted and inset PM machines which present a small PM height and high width. Analytical method based on subdomain model give a very good accuracy even when PM subregion is deep. In Figs. 7 to 12, radial and tangential flux density in the middle of the airgap is given for 3 conditions: Permanent magnets alone; stator currents alone and rotor excitation currents alone. The radial and tangential flux density distribution for on-load condition is shown in Figs. 13 and 14. The machine is fed by $120^{\circ}$ rectangular stator current and we consider the permanent magnets and rotor DC current acting together. Figs. 15 and 16 show the flux lines obtained by FEM due to rotor excitation current and stator currents. We can observe that all analytical results are in very good agreement with those obtained by FEM. In Figs. 17 to 20, we show radial and tangential flux densities for on load condition in the cases where the hybrid PM machine has stator and rotor slots fed by current and PM does not exist and only stator slots are fed and PM are considered. Those two cases represent the contribution of permanent magnet and rotor excitation current to magnetic field on load. In control process of magnetic field in the air gap, current excitation can be set to zero to decrease magnetic field. It is important to note here that the results are obtained for a recoil relative permeability of permanent magnet equal to unity, but the method take into account the effect of non unity permeability. Figs. 21 to 26 show open circuit, armature reaction and on load radial and tangential flux density in the middle of airgap in integer slot winding Spoke-Type PM machine accounting for tooth tips and real structure of polar piece. All analytical results are in very good agreement with those obtained by FEM, which confirm the accuracy of analytical subdomain model in predictions of this type of permanent magnet machines even when a PM subregion is very deep with small thickness and with taking into account tooth tips and real structure of polar piece. Fig. 27 shows magnetic field on load obtained by FEM in Spoke-Type PM machine.

TABLE I
Parameters Of Studied Parallel Double Excitation and Spoke-Type Permanent-Magnet Motor

| Parameter | Symbol | Value and <br> unit |
| :--- | :---: | :---: |
| Magnet remanence (Ferrite) | $B_{r}$ | 0.4 T |
| Relative recoil permeability of magnet | $\mu_{r}$ | 1 |
| Number of conductors per stator slot | $N_{c}$ | 12 |
| Peak phase current | $I_{m}$ | 12.5 A |
| DC excitation current | $I_{f}$ | 5 A |
| Number of conductors per rotor slot | $N_{f}$ | 10 |
| Number of stator slots | $Q_{s}$ | 12 |
| Stator slot opening width | $c$ | $14^{\circ}$ |
| Rotor slot opening width | $c_{r}$ | $14^{\circ}$ |
| Number of pole pairs | $p$ | 2 |
| Number of rotor excitation slots | $N_{r}$ | 8 |
| External radius of rotor slot | $r_{0}$ | 40.8 mm |
| Internal radius of rotor slot | $r_{1}$ | 27.8 mm |
| External radius of magnet | $r_{2}$ | 40 mm |
| Internal radius of stator slot | $r_{3}$ | 49 mm |
| External radius of stator slot | $r_{4}$ | 58 mm |
| Rotor slot opening width | $d r$ | $8^{\circ}$ |
| Magnet slot opening width | $b$ | $12^{\circ}$ |
| Stator slot opening width | $d$ | $8^{\circ}$ |
| Radius of the external stator surface | $R_{o}$ | 70 mm |


| Radius of the stator outer surface $R_{s}$ 45 mm <br> Radius of the rotor inner surface at the <br> magnet surface $R_{m}$ 44.8 mm <br> Radius of the rotor inner surface at the <br> magnet bottom $R_{r}$ 15 mm <br> Air-gap length $g$ 0.2 mm <br> Height of a magnet $h_{m}$ 29.8 mm <br> Height of stator slot $h_{s}$ 9 mm <br> Stack length $L_{u}$ 57 mm <br> Magnet arc to pole pitch ratio $a$ 0.2 <br> Rotor speed $w r m$ $157 \mathrm{rd} / \mathrm{s}$ |
| :--- | :---: | :---: |



Fig. 7. Radial flux density due to permanent magnet alone in parallel double excitation PM machine


Fig. 8. Tangential flux density due to permanent magnet alone in parallel double excitation PM machine


Fig. 9. Radial flux density due to stator current alone in parallel double excitation PM machine


Fig. 10. Tangential flux density due to stator current alone in parallel double excitation PM machine


Fig. 11. Radial flux density due to rotor excitation current alone in parallel double excitation PM machine


Fig. 12. Tangential flux density due to rotor excitation current alone in parallel double excitation PM machine


Fig. 13. Radial flux density on load in parallel double excitation PM machine


Fig. 14. Tangential flux density on load in parallel double excitation PM machine


Fig. 15. Magnetic field due to rotor double excitation current alone in parallel double excitation PM machine


Fig. 16. Magnetic field on load in parallel double excitation PM machine


Fig. 17. Radial flux density due to rotor excitation and stator currents (on load) in parallel double excitation PM machine


Fig. 18. Tangential flux density due to rotor excitation and stator currents (on load) in parallel double excitation PM machine


Fig. 19. Radial flux density due to permanent magnet and stator currents (on load) in parallel double excitation PM machine


Fig. 20. Tangential flux density due to permanent magnet and stator currents (on load) in parallel double excitation PM machine


Fig. 21. Radial flux density due to permanent magnet alone in Spoke-Type PM machine


Fig. 22. Tangential flux density due to permanent magnet alone in Spoke-Type PM machine


Fig. 23. Radial flux density due to stator current alone in Spoke-Type PM machine


Fig. 24. Tangential flux density due to stator current alone in Spoke-Type PM machine


Fig. 25. Radial flux density on load in Spoke-Type PM machine


Fig. 26. Tangential flux density on load in Spoke-Type PM machine


Fig. 27. Magnetic field on load in Spoke-Type PM machine

## V. CONCLUSION

In this paper, we have proposed an improved analytical subdomain model for predicting open circuit, armature reaction and on-load magnetic field distribution in integer stator slot distributed winding parallel double excitation and Spoke-Type permanent magnet machines. The proposed model takes into account the rotor and stator slots tooth tips and the shape of polar pieces. The whole domain is divided into eight subregions for parallel double excitation motor and six subregions for Spoke-Type permanent magnet motor, stator semi-closed slots, rotor semi-closed slots, airgap, buried tangential permanent magnet and non magnetic region under magnet. Poisson's and Laplace's equations are solved analytically using the method of separation of variables. Analytical results are in excellent agreement with the ones obtained by FEM. From these results, we have shown the accuracy of analytical subdomain model to predict magnetic field accounting for rotor and stator tooth tips and shape of polar piece, even when PM subregion is deep with small thickness.

## APPENDIX

Fourier series coefficients of general solution in different regions of parallel double excitation and Spoke-Type permanent magnet machines are determined by resolution of a system of equations as seen above. Some of those equations are detailed as follows.
From equation (46), we get

$$
\begin{align*}
& A 5_{j, 0}+A 6_{j, 0} \ln \left(R_{r}\right)-M_{j} \mu_{0} R_{r}  \tag{A-1}\\
= & \frac{1}{a} \sum_{n=1}^{\infty}\left(A 7_{n} R_{r}^{n p}\right) \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \sin (n p \theta) d \theta \\
+ & \frac{1}{a} \sum_{n=1}^{\infty}\left(A 9_{n} R_{r}^{n p}\right) \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \cos (n p \theta) d \theta
\end{align*}
$$

$$
\text { for } m^{2} \pi^{2}-p^{2} n^{2} a^{2} \neq 0, \text { and }
$$

$=\frac{\cos \left(-n p g_{j}+\frac{n p a}{2}\right)}{4 n p}-\frac{\cos \left(n p g_{j}+\frac{3 n p a}{2}\right)}{4 n p}$
$-\frac{a \sin \left(-n p g_{j}+\frac{n p a}{2}\right)}{2}$ for $m^{2} \pi^{2}-p^{2} n^{2} a^{2}=0$
and $\int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \cos (n p \theta) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta$
$=-\frac{n p a^{2}\left(1+(-1)^{m}\right) \sin \left(\frac{n p a}{2}\right) \cos \left(n p g_{j}\right)}{m^{2} \pi^{2}-p^{2} n^{2} a^{2}}$
$-\frac{n p a^{2}\left(-1+(-1)^{m}\right) \sin \left(n p g_{j}\right) \cos \left(\frac{n p a}{2}\right)}{m^{2} \pi^{2}-p^{2} n^{2} a^{2}}$
for $m^{2} \pi^{2}-p^{2} n^{2} a^{2} \neq 0$ and
$=\frac{a \cos \left(-n p g_{j}+\frac{n p a}{2}\right)}{2}+\frac{\sin \left(-n p g_{j}+\frac{n p a}{2}\right)}{4 n p}$
$+\frac{\sin \left(n p g_{j}+\frac{3 n p a}{2}\right)}{4 n p}$ for $m^{2} \pi^{2}-p^{2} n^{2} a^{2}=0$.
From equation (48), we have:
$\left(\frac{n p}{\mu_{0}}\right)\left(-A 7_{n} R_{r}^{n p-1}\right)$
$=\frac{1}{\pi \mu_{0} \mu_{r}} \sum_{j=1}^{2 p} \sum_{m=1}^{\infty}\left(\frac{m \pi}{a} A 5_{j, m} R_{r}^{-\frac{m \pi}{a}-1}-\frac{m \pi}{a} A 6_{j, m} R_{r}^{\frac{m \pi}{a}-1}\right)$.
$\int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \sin (n p \theta) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta$
$-\left(\frac{1}{\pi \mu_{0} \mu_{r}}\right) \sum_{j=1}^{2 p} \frac{A 6_{j, 0}}{R_{r}} \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \sin (n p \theta) d \theta$
Equation (49) gives
$\left(\frac{n p}{\mu_{0}}\right)\left(-A 9_{n} R_{r}^{n p-1}\right)$
$=\frac{1}{\pi \mu_{0} \mu_{r}} \sum_{j=1}^{2 p} \sum_{m=1}^{\infty}\left(\frac{m \pi}{a} A 5_{j, m} R_{r}^{-\frac{m \pi}{a}-1}-\frac{m \pi}{a} A 6_{j, m} R_{r}^{\frac{m \pi}{a}-1}\right)$.
$\int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \cos (n p \theta) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta$
$-\left(\frac{1}{\pi \mu_{0} \mu_{r}}\right) \sum_{j=1}^{2 p} \frac{A 6_{j, 0}}{R_{r}} \int_{g_{j}-\frac{a}{2}}^{g_{j}+\frac{a}{2}} \cos (n p \theta) d \theta$
Equation (50) gives
$A 13_{j, 0}+A 14_{j, 0} \ln \left(r_{2}\right)$
(A-5)
$=A 5_{j, 0}+A 6_{j, 0} \ln \left(r_{2}\right)-M_{j} \mu_{0} r_{2}$
$+\frac{1}{b} \sum_{m=1}^{\infty}\left(A 5_{j, m} r_{2}^{-\frac{m \pi}{a}}+A 6_{j, m} r_{2}^{\frac{m \pi}{a}}\right)$.
$\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta$
where $\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta$
$=\frac{2 a \sin \left(\frac{\pi m p}{2 a}\right) \cos \left(\frac{m \pi}{2}\right)}{\pi m}$
From equation (51), we have
$A 13_{j, k} r_{2}^{-\frac{k \pi}{b}}+A 14_{j, k} r_{2}^{\frac{k \pi}{b}}$
(A-6)
$=\frac{2}{b} \sum_{m=1}^{\infty}\left(A 5_{j, m} r_{2}^{-\frac{m \pi}{a}}+A 6_{j, m} r_{2}^{\frac{m \pi}{a}}\right)$.
$\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta$
$+\frac{2}{b}\left(A 5_{j, 0}+A 6_{j, 0} \ln \left(r_{2}\right)-M_{j} \mu_{0} r_{2}\right)$.
$\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta$
where $\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta=0$, and
$\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta$
$=-\frac{m b^{2} a\left(1+(-1)^{k}\right) \sin \left(\frac{\pi m b}{2 a}\right) \cos \left(\frac{m \pi}{2}\right)}{\pi\left(-m^{2} b^{2}+k^{2} a^{2}\right)}$
$-\frac{m b^{2} a\left(-1+(-1)^{k}\right) \sin \left(\frac{m \pi}{2}\right) \cos \left(\frac{\pi m b}{2 a}\right)}{\pi\left(-m^{2} b^{2}+k^{2} a^{2}\right)}$
for $-m^{2} b^{2}+k^{2} a^{2} \neq 0$ and
$=\frac{1}{4 \pi k}\left(2 b k \pi \cos \left(\frac{-b k \pi+k \pi a}{2 b}\right)\right)$
$+\frac{1}{4 k \pi}\left(-b \sin \left(\frac{-b k \pi+k a \pi}{2 b}\right)+b \sin \left(\frac{3 b k \pi+k a \pi}{2 b}\right)\right)$
for $-m^{2} b^{2}+k^{2} a^{2}=0$.
Development of equation (52) is reduced to

$$
\begin{equation*}
-\frac{A 6_{j, 0}}{r_{2}} \frac{1}{\mu_{0} \mu_{r}}=-\frac{A 14_{j, 0} b}{a \mu_{0} r_{2}} \tag{A-7}
\end{equation*}
$$

From equation (53), we have

$$
\begin{aligned}
& \frac{1}{\mu_{0} \mu_{r}} \frac{m \pi}{a}\left(A 5_{j, m} r_{2}^{-\frac{m \pi}{a}-1}-A 6_{j, m} r_{2}^{\frac{m \pi}{a}-1}\right) \\
& =\frac{2}{a \mu_{0}}\left(-\frac{A 14_{j, 0}}{r_{2}}\right)_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \int^{2} \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta \\
& -\frac{2}{a \mu_{0}} \sum_{k=1}^{\infty} \frac{k \pi}{b}\left(-A 13_{j, k} r_{2}^{-\frac{k \pi}{b}-1}+A 14_{j, k} r_{2}^{\frac{k \pi}{b}-1}\right)
\end{aligned}
$$

$$
\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) \cos \left(\frac{m \pi}{a}\left(\theta-g_{j}+\frac{a}{2}\right)\right) d \theta
$$

From equation (54), we have

$$
\begin{equation*}
A 13_{j, 0}+A 14_{j, 0} \ln \left(R_{m}\right) \tag{A-9}
\end{equation*}
$$

$=\frac{1}{b} \sum_{n=1}^{\infty}\left(A 1_{n} R_{m}^{n p}+A 2_{n} R_{m}^{-n p}\right) \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \sin (n p \theta) d \theta$
$+\frac{1}{b} \sum_{n=1}^{\infty}\left(A 3_{n} R_{m}^{n p}+A 4_{n} R_{m}^{-n p}\right) \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos (n p \theta) d \theta$
Equation (55) development gives

$$
\begin{align*}
& A 13_{j, k} R_{m}^{-\frac{k \pi}{b}}+A 14_{j, k} R_{m}^{\frac{k \pi}{b}}  \tag{A-10}\\
& =\frac{2}{b} \sum_{n=1}^{\infty}\left(A 1_{n} R_{m}^{n p}+A 2_{n} R_{m}^{-n p}\right) .
\end{align*}
$$

$$
\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \sin (n p \theta) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta
$$

$$
\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos (n p \theta) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta
$$

From equation (56), we have
$A 15_{i r, 0}+A 16_{i r, 0} \ln \left(R_{m}\right)$

$$
\begin{align*}
& =\frac{1}{b} \sum_{n=1}^{\infty}\left(A 1_{n} R_{m}^{n p}+A 2_{n} R_{m}^{-n p}\right) \cdot \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \sin (n p \theta) d \theta  \tag{A-11}\\
& +\frac{1}{b} \sum_{n=1}^{\infty}\left(A 3_{n} R_{m}^{n p}+A 4_{n} R_{m}^{-n p}\right) \cdot \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos (n p \theta) d \theta
\end{align*}
$$

$$
+\frac{2}{b} \sum_{n=1}^{\infty}\left(A 3_{n} R_{m}^{n p}+A 4_{n} R_{m}^{-n p}\right)
$$

From equation (57), we have
$A 15_{i r, k} R_{m}^{-\frac{k \pi}{d r}}+A 16_{i r, k} R_{m}^{\frac{k \pi}{d r}}$
$=\frac{2}{d r} \sum_{n=1}^{\infty}\left(A 1_{n} R_{m}^{n p}+A 2_{n} R_{m}^{-n p}\right)$.
$\int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \sin (n p \theta) \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta$
$+\frac{2}{d r} \sum_{n=1}^{\infty}\left(A 3_{n} R_{m}^{n p}+A 4_{n} R_{m}^{-n p}\right)$.
$\int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos (n p \theta) \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta$
Development of equation (58) gives
$\frac{n p}{\mu_{0}}\left(-A 1_{n} R_{m}^{n p-1}+A 2_{n} R_{m}^{-n p-1}\right)$
$=\frac{1}{\pi \mu_{0}} \sum_{j=1}^{2 p} \sum_{k=1}^{\infty} \frac{k \pi}{b}\left(A 13_{j, k} R_{m}^{-\frac{k \pi}{b}-1}-A 14_{j, k} R_{m}^{\frac{k \pi}{b}-1}\right)$.
$\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \sin (n p \theta) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta$
$-\sum_{j=1}^{2 p} \frac{A 14_{j, 0}}{\pi R_{m} \mu_{0}} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \sin (n p \theta) d \theta$
$+\sum_{i r=1}^{N_{r}} \sum_{k=1}^{\infty} \frac{k \pi}{d r}\left(A 15_{i r, k} R_{m}^{-\frac{k \pi}{d r}-1}-A 16_{i r, k} R_{m}^{\frac{k \pi}{d r}-1}\right)$.
$\int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \sin (n p \theta) \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta$
$-\sum_{i r=1}^{N_{r}}\left(\frac{A 16_{i r, 0}}{\pi \mu_{0} R_{m}}\right)_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \sin (n p \theta) d \theta$
From equation (59), we have
$\frac{n p}{\mu_{0}}\left(-A 3_{n} R_{m}^{n p-1}+A 4_{n} R_{m}^{-n p-1}\right)$
$=\frac{1}{\pi \mu_{0}} \sum_{j=1}^{2 p} \sum_{k=1}^{\infty} \frac{k \pi}{b}\left(A 13_{j, k} R_{m}^{-\frac{k \pi}{b}-1}-A 14_{j, k} R_{m}^{\frac{k \pi}{b}-1}\right)$.
$\int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos (n p \theta) \cos \left(\frac{k \pi}{b}\left(\theta-g_{j}+\frac{b}{2}\right)\right) d \theta$
$-\sum_{j=1}^{2 p} \frac{A 14_{j, 0}}{\pi R_{m} \mu_{0}} \int_{g_{j}-\frac{b}{2}}^{g_{j}+\frac{b}{2}} \cos (n p \theta) d \theta$
$+\sum_{i r=1}^{N_{r}} \sum_{k=1}^{\infty} \frac{k \pi}{d r}\left(A 15_{i r, k} R_{m}^{-\frac{k \pi}{d r}-1}-A 16_{i r, k} R_{m}^{\frac{k \pi}{d r}-1}\right)$.
$\int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos (n p \theta) \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta$
$-\sum_{i r=1}^{N_{r}}\left(\frac{A 16_{i r, 0}}{\pi \mu_{0} R_{m}}\right)_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos (n p \theta) d \theta$
Equation (60) development is

$$
\begin{aligned}
& A 11_{i, 0}+A 12_{i, 0} \ln \left(R_{s}\right) \\
& =\frac{1}{d} \sum_{n=1}^{\infty}\left(A 1_{n} R_{s}^{n p}+A 2_{n} R_{s}^{-n p}\right) \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \sin (n p \theta) d \theta \\
& +\frac{1}{d} \sum_{n=1}^{\infty}\left(A 3_{n} R_{s}^{n p}+A 4_{n} R_{s}^{-n p}\right) \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos (n p \theta) d \theta
\end{aligned}
$$

From equation (61), we have
$A 11_{i, k} R_{s}^{-\frac{k \pi}{d}}+A 12_{i, k} R_{s}^{\frac{k \pi}{d}}$
$=\frac{2}{d} \sum_{n=1}^{\infty}\left(A 1_{n} R_{s}^{n p}+A 2_{n} R_{s}^{-n p}\right)$.
$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) \sin (n p \theta) d \theta$
$+\frac{2}{d} \sum_{n=1}^{\infty}\left(A 3_{n} R_{s}^{n p}+A 4_{n} R_{s}^{-n p}\right)$.
$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) \cos (n p \theta) d \theta$
From equation (62), we have

$$
\begin{aligned}
& \frac{n p}{\mu_{0}}\left(-A 1_{n} R_{s}^{n p-1}+A 2_{n} R_{s}^{-n p-1}\right) \\
& =\frac{1}{\pi \mu_{0}} \sum_{i=1}^{Q_{s}} \sum_{k=1}^{\infty}-\frac{k \pi}{d}\left(-A 11_{i, k} R_{s}^{-\frac{k \pi}{d}-1}+A 12_{i, k} R_{s}^{\frac{k \pi}{d}-1}\right)
\end{aligned}
$$

$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) \sin (n p \theta) d \theta$
$-\sum_{i=1}^{Q_{s}} \frac{A 12_{i, 0}}{\pi R_{s} \mu_{0}} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \sin (n p \theta) d \theta$
From equation (63), we have
$\frac{n p}{\mu_{0}}\left(-A 3_{n} R_{s}^{n p-1}+A 4_{n} R_{s}^{-n p-1}\right)$
$=\frac{1}{\pi \mu_{0}} \sum_{i=1}^{Q_{s}} \sum_{k=1}^{\infty}-\frac{k \pi}{d}\left(-A 11_{i, k} R_{s}^{-\frac{k \pi}{d}-1}+A 12_{i, k} R_{s}^{\frac{k \pi}{d}-1}\right)$.
$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) \cos (n p \theta) d \theta$
$-\sum_{i=1}^{Q_{s}} \frac{A 12_{i, 0}}{\pi R_{s} \mu_{0}} \int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos (n p \theta) d \theta$
From equation (64), we have
$A 11_{i, 0}+A 12_{i, 0} \ln \left(r_{3}\right)$
$=C_{i, 0}+\frac{1}{2} \mu_{0} J_{i} r_{4}^{2} \ln \left(r_{3}\right)-\frac{1}{4} \mu_{0} J_{i} r_{3}^{2}$
$+\frac{1}{d} \sum_{m=1}^{\infty} C_{i, m}\left(\left(\frac{r_{3}}{r_{4}}\right)^{\frac{m \pi}{c}}-\left(\frac{r_{3}}{r_{4}}\right)^{-\frac{m \pi}{c}}\right)$.
$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{m \pi}{c}\left(\theta-\alpha_{i}+\frac{c}{2}\right)\right) d \theta$
From equation (65), we have
$A 11_{i, k} r_{3}^{-\frac{k \pi}{d}}+A 12_{i, k} r_{3}^{\frac{k \pi}{d}}$
$=\frac{2}{d}\left(C_{i, 0}+\frac{1}{2} \mu_{0} J_{i} r_{4}^{2} \ln \left(r_{3}\right)-\frac{1}{4} \mu_{0} J_{i} r_{3}^{2}\right)$.
$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) d \theta$
$+\frac{2}{d} \sum_{m=1}^{\infty} C_{i, m}\left(\left(\frac{r_{3}}{r_{4}}\right)^{\frac{m \pi}{c}}-\left(\frac{r_{3}}{r_{4}}\right)^{-\frac{m \pi}{c}}\right)$.
$\int_{\alpha_{i}-\frac{d}{2}}^{\alpha_{i}+\frac{d}{2}} \cos \left(\frac{m \pi}{c}\left(\theta-\alpha_{i}+\frac{c}{2}\right)\right) \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) d \theta$
Equation (66) is reduced to
$\frac{1}{\mu_{0}}\left(-\frac{1}{2} \frac{\mu_{0} J_{i} r_{4}^{2}}{r_{3}}+\frac{1}{2} \mu_{0} J_{i} r_{3}\right)=-\frac{A 12_{i, 0} d}{c \mu_{0} r_{3}}$
From equation (67), we have
$-\frac{C_{i, m}}{\mu_{0}}\left(\frac{m \pi}{c r_{3}}\right)\left(\left(\frac{r_{3}}{r_{4}}\right)^{\frac{m \pi}{c}}+\left(\frac{r_{3}}{r_{4}}\right)^{-\frac{m \pi}{c}}\right)_{\text {(A-22) }}^{c \mu_{0}}\left(-\frac{2}{r_{3}}\right)_{\alpha_{i}-\frac{d}{2}}^{\int_{i, 0}} \cos \left(\frac{m \pi}{c}\left(\theta-\alpha_{i}+\frac{c}{2}\right)\right) d \theta$
$+\frac{2}{c \mu_{0}} \sum_{k=1}^{\infty} \frac{k \pi}{d}\left(A 11_{i, k} r_{3}^{-\frac{k \pi}{d}-1}-A 12_{i, k} r_{3}^{\frac{k \pi}{d}-1}\right)$.
$\alpha_{i}+\frac{d}{2}$
$\int_{\alpha_{i}-\frac{d}{2}}^{c} \cos \left(\frac{k \pi}{d}\left(\theta-\alpha_{i}+\frac{d}{2}\right)\right) \cos \left(\frac{m \pi}{c}\left(\theta-\alpha_{i}+\frac{c}{2}\right)\right) d \theta$
From equation (68), we have

$$
\begin{align*}
& A 15_{i r, 0}+A 16_{i r, 0} \ln \left(r_{0}\right)  \tag{A-23}\\
& =C 1_{i r, 0}+\frac{1}{2} \mu_{0} J_{f i r} r_{1}^{2} \ln \left(r_{0}\right)-\frac{1}{4} \mu_{0} J_{f i r} r_{0}^{2} \\
& +\frac{1}{d r} \sum_{m=1}^{\infty} C 1_{i r, m}\left(\left(\frac{r_{0}}{r_{1}}\right)^{\frac{m \pi}{c_{r}}}-\left(\frac{r_{0}}{r_{1}}\right)^{-\frac{m \pi}{c_{r}}}\right) . \\
& \int_{\beta_{i r}+\frac{d r}{2}}^{\beta^{\frac{d r}{2}}} \cos \left(\frac{m \pi}{c r}\left(\theta-\beta_{i r}+\frac{c r}{2}\right)\right) d \theta
\end{align*}
$$

From equation (69), we have

$$
\begin{aligned}
& A 15_{i r, k} r_{0}^{-\frac{k \pi}{d r}}+A 16_{i r, k} r_{0}^{\frac{k \pi}{d r}} \\
& =\frac{2}{d r}\left(C 1_{i r, 0}+\frac{1}{2} \mu_{0} J_{f i r} r_{1}^{2} \ln \left(r_{0}\right)-\frac{1}{4} \mu_{0} J_{f i r} r_{0}^{2}\right) \\
& \int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}^{2}} \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta \\
& +\frac{2}{d r} \sum_{m=1}^{\infty} C 1_{i r, m}\left(\left(\frac{r_{0}}{r_{1}}\right)^{\frac{m \pi}{c r}}-\left(\frac{r_{0}}{r_{1}}\right)^{-\frac{m \pi}{c r}}\right)
\end{aligned}
$$

$\int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta$.
$\int_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos \left(\frac{m \pi}{c r}\left(\theta-\beta_{i r}+\frac{c r}{2}\right)\right) d \theta$
Equation (70) is reduced to

$$
\begin{equation*}
\frac{1}{\mu_{0}}\left(-\frac{1}{2} \frac{\mu_{0} J_{f i r} r_{1}^{2}}{r_{0}}+\frac{1}{2} \mu_{0} J_{f i r} r_{0}\right)=-\frac{A 16_{i r, 0} d r}{c r \mu_{0} r_{0}} \tag{A-25}
\end{equation*}
$$

From equation (71), we have

$$
\begin{align*}
& -\frac{C 1_{i r, m}}{\mu_{0}} \frac{m \pi}{c r r_{0}}\left(\left(\frac{r_{0}}{r_{1}}\right)^{\frac{m \pi}{c r}}+\left(\frac{r_{0}}{r_{1}}\right)^{-\frac{m \pi}{c r}}\right)  \tag{A-26}\\
& =\frac{2}{\mu_{0} c r} \sum_{k=1}^{\infty} \frac{k \pi}{d r}\left(A 15_{i r, k} r_{0}^{-\frac{k \pi}{d r}-1}-A 16_{i r, k} r_{0}^{\frac{k \pi}{d r}-1}\right) \\
& \int_{\beta_{i}+\frac{d r}{2}} \cos \left(\frac{k \pi}{d r}\left(\theta-\beta_{i r}+\frac{d r}{2}\right)\right) d \theta \\
& \beta_{i r}-\frac{d r}{2} \\
& \beta_{i r}+\frac{d r}{2} \\
& \int_{\beta_{i r}-\frac{d r}{2}}^{\cos }\left(\frac{m \pi}{c r}\left(\theta-\beta_{i r}+\frac{c r}{2}\right)\right) d \theta \\
& -\frac{2}{c r \mu_{0}}\left(\frac{A 16_{i r, 0}}{r_{0}}\right)_{\beta_{i r}-\frac{d r}{2}}^{\beta_{i r}+\frac{d r}{2}} \cos \left(\frac{m \pi}{c r}\left(\theta-\beta_{i r}+\frac{c r}{2}\right)\right) d \theta
\end{align*}
$$

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