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Preamble-Less Group Synchronization of Binary Linear Block Codes

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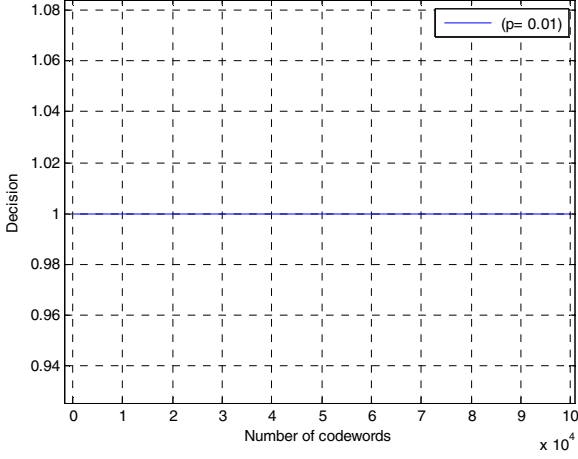


Fig. 2 H(7,4): Evolution of decision d for $p = 10^{-2}$

Fig. 3 presents the time evolution of the difference $Diff(P_s)$ computed with (13) and (24). This difference is sufficient large to take each time the good decision. However, the capacity of this algorithm to take good decisions is limited.

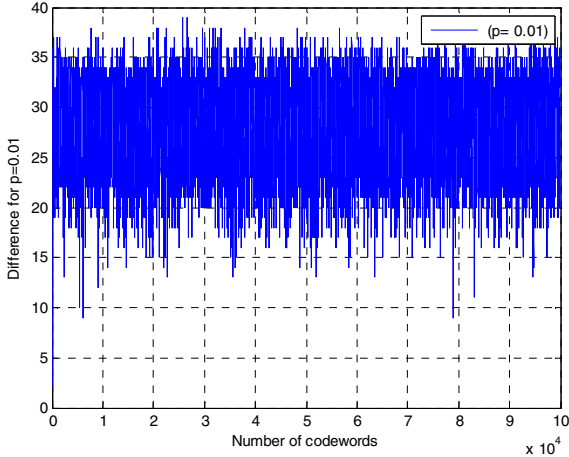


Fig. 3 Evolution of the difference $Diff(P_s)$

For example, for $p = 4 \cdot 10^{-2}$, as shown in Fig. 4, this algorithm has some wrong decisions.

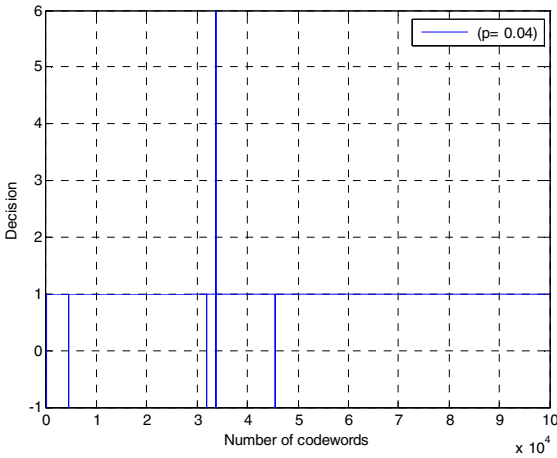


Fig. 4 Evolution of decision d for $p = 4 \cdot 10^{-2}$

The value $d = 6$ shows that for a bad enough channel, it is possible to obtain the maximum value of the cumulative sums $CS(d)$ for a wrong value of d (as shown before, because the received vector r starts with the first bit of a code word, the right decision for these simulations is $d = 1$).

It is also possible to observe in Fig. 4 several values $d = -1$. This indicates that the maximum value of the cumulative sums $CS(d)$, with $d = 1, 2, \dots, n$ is obtained for at least 2 different values of d . In this case, the decision cannot be correctly taken. However, it is possible to remark that the values $d = -1$ are isolated (before and after a value $d = -1$ one can observe good decisions $d = 1$). This remark suggests an improvement of the basic synchronisation algorithm.

IV. ALGORITHM SIMULATION FOR H(15,11)

In order to determine the performance of the proposed algorithm, a longer code is conserved for simulation: the Hamming code with a length $n = 15$ and $k = 11$ information symbols. As for the previous code, this code can correct just one error. Let consider:

$$v = [v_1 v_2 \dots, v_{15}] \quad (21)$$

the code word with the information symbols placed on the first $k = 11$ positions. The last $m = 4$ parity-check symbols can be computed as:

$$\begin{aligned} v_{12} &= v_1 \oplus v_2 \oplus v_4 \oplus v_5 \oplus v_7 \oplus v_9 \oplus v_{11} \\ v_{13} &= v_1 \oplus v_3 \oplus v_4 \oplus v_6 \oplus v_7 \oplus v_{10} \oplus v_{11} \\ v_{14} &= v_2 \oplus v_3 \oplus v_4 \oplus v_8 \oplus v_9 \oplus v_{10} \oplus v_{11} \\ v_{15} &= v_2 \oplus v_6 \oplus v_7 \oplus v_8 \oplus v_9 \oplus v_{10} \oplus v_{11} \end{aligned} \quad (22)$$

As explained in introduction, we prefer to inverse the coding relations (22):

$$\begin{aligned} v_{12} &= \overline{v_1 \oplus v_2 \oplus v_4 \oplus v_5 \oplus v_7 \oplus v_9 \oplus v_{11}} \\ v_{13} &= \overline{v_1 \oplus v_3 \oplus v_4 \oplus v_6 \oplus v_7 \oplus v_{10} \oplus v_{11}} \\ v_{14} &= \overline{v_2 \oplus v_3 \oplus v_4 \oplus v_8 \oplus v_9 \oplus v_{10} \oplus v_{11}} \\ v_{15} &= \overline{v_2 \oplus v_6 \oplus v_7 \oplus v_8 \oplus v_9 \oplus v_{10} \oplus v_{11}} \end{aligned} \quad (23)$$

For this code, $d = 1, 2, \dots, 15$. The symbols $s_j(d)$ are:

$$\begin{aligned} s_1(d) &= v_d \oplus v_{d+1} \oplus v_{d+3} \oplus v_{d+4} \oplus v_{d+6} \oplus v_{d+9} \oplus v_{d+10} \oplus v_{d+11} \\ s_2(d) &= v_d \oplus v_{d+2} \oplus v_{d+3} \oplus v_{d+5} \oplus v_{d+6} \oplus v_{d+9} \oplus v_{d+10} \oplus v_{d+12} \\ s_3(d) &= v_{d+1} \oplus v_{d+2} \oplus v_{d+3} \oplus v_{d+7} \oplus v_{d+8} \oplus v_{d+9} \oplus v_{d+10} \oplus v_{d+13} \\ s_4(d) &= v_{d+4} \oplus v_{d+5} \oplus v_{d+6} \oplus v_{d+7} \oplus v_{d+8} \oplus v_{d+9} \oplus v_{d+10} \oplus v_{d+14} \end{aligned} \quad (24)$$

For the simulation, we consider a noisy channel with the error probability $p = 10^{-2}$ and $P_s = 28$. The number of code words simulated is $N = 10^5$. The frame considered for simulation began with a code word. One can observe in Fig. 5 a good result obtained with $P_s = 28$. However, the first decisions are not correct. This is an expected result, because the cumulative sums given by (13) are computed with few terms $S(d)$. However, a small number of terms $S(d)$ (Fig. 6 indicates 2 terms) are sufficient to take a good decision.

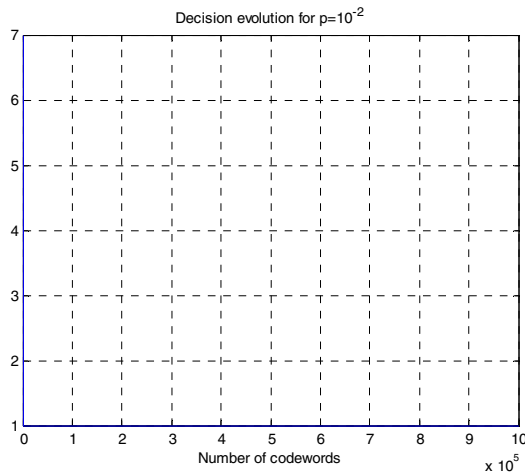


Fig. 5 H(15,11): Evolution of decision d for $p = 10^{-2}$

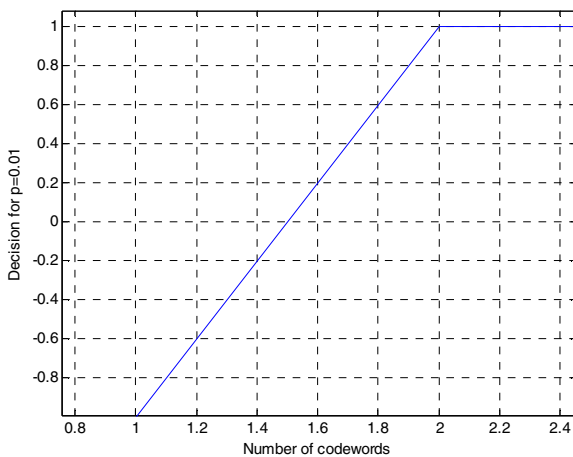


Fig. 6 H(15,11): Start of the evolution of decision d for $p = 10^{-2}$

Hence, after a transient regime, the group synchronization is realized without errors

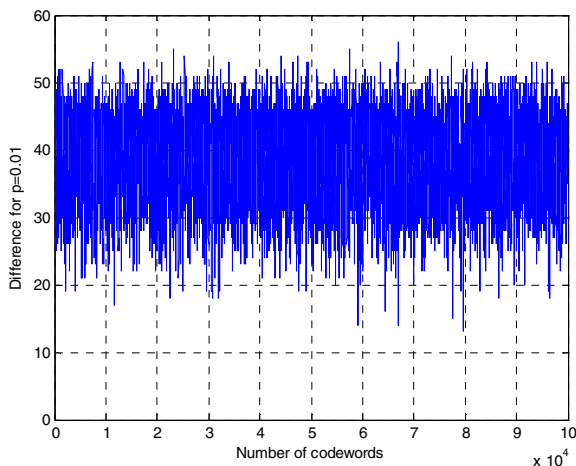


Fig. 7 H(15,11): Evolution of the difference $Diff(P_s)$

Fig. 7 presents the time evolution of the difference $Diff(P_s)$ computed with (25). One can observe that this difference is

sufficient large to take each time the good decision. This is possible after a short transient regime (some few code words).

With $p = 2 \cdot 10^{-2}$, these differences are smaller. Therefore, sometimes, some synchronization decisions are wrong. In this case, a larger value $P_r = 30$ is sufficient to obtain a good synchronization (as given in Fig. 5).

IV. CONCLUSION

A new and original non-preamble group synchronization based on coding relations has been proposed in this paper. With a convenient choice of length of the cumulative sums given by the parameter P_r , this algorithm gives good results even for quite bad transmission channels (error probability of 10^{-2}). The main advantage is the reliability of the decisions of the proposed algorithm without using a preamble and, therefore, without further reduction of the coding rate. However, for practical applications, this algorithm is convenient only for short code words. If the length of the code word increases, the number of electronic circuits needed for the implementation becomes quite large. However, for the actual FPGAs or ASICs, this can be easily realized.

The future work will focus on the convenient choice of the parameter P_r as a function of p and n for a given low value of the miss detection probability. It will be also interesting to confirm the simulation results by theoretical calculations. The theoretical values of the synchronization miss-detection and false-alarm probabilities must also be considered.

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