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Dynamic Adaptation through Event Reconfiguration

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Abstract. We introduce a new programming language called INI, which eases the development of self-adaptive software. INI combines both rule-based and event-based programming paradigms, by allowing the definitions of rules that can be triggered by events. Besides a convenient language-level support for synchronization, the key point with INI events is that they come with a configuration layer, which is set up through input parameters passed to the events when created. Additionally, events can be stopped, reconfigured, and restarted at runtime by the program itself. Ultimately, this re-configuration can be triggered by other events, thus allowing the program to adapt to new operational environments.

Keywords: Adaptive systems, rule-based programming, event-based programming, reconfiguration.

1 Introduction

The role of software in our society has become more and more important and to satisfy higher demands from customers, software systems must become more “versatile, flexible, resilient, dependable, robust, energy-efficient, recoverable, customizable, configurable, and self-optimizing” [1]. However, developing and maintaining software systems is hard and resource-consuming because they are operating in an environment that is not well defined or predictable. Consequently, software systems need a new and innovative approach for evolving and running. Currently, one of the most promising approaches to achieve such properties is building self-adaptation and self-management mechanisms [8].

In recent years, with the development of autonomic computing, software engineering researchers have been motivated to pay more attention to design and develop self-adaptive software systems. Basically, adaptive software comes with the assumption of dynamic environment while non-adaptive software does not [14]. By using rules explicitly or implicitly, most self-adaptive software can choose reactions to monitored events happening during execution [13]. Therefore, one of the current research trends is to develop a programming language to easily

express and capture those changes so that the systems can modify their behavior at runtime. In this paper, we introduce a new programming language calledINI, which we designed to assess rule-based and event-based oriented programming. InINI, we allow programmers to define events, which need to be captured and monitored. Events are usually executed asynchronously but can synchronize on other events with intuitive language constructs. Moreover, events can be reconfigured at runtime through a well-defined reconfiguration mechanism. As a result, when something happens during execution,INI program can capture and adapt to these changes automatically by reconfiguring its events.

The rest of this paper is organized as follows. In Section 2, we give an overview of related work. In Section 3, we discuss events inINI, including its syntax, built-in events and user-defined events. Events synchronization and reconfiguration are shown in Section 4. In that section, we also demonstrate the capabilities ofINI in handling variabilities in the operational environment with a small example. Finally, some conclusions and future work are presented in Section 5.

2 Related Work

A general overview of research and problems on self-adaptive software can be found in [7,12]. The key aspect of self-adaptive software is that code behavior is evaluated or tested at runtime, which may lead to a run-time change in behavior [7]. As a result, the run-time code should contain the following mechanisms:

- A mechanism to detect changes during execution
- A mechanism to switch algorithms and operations due to these above changes

Laddaga [7] discussed two useful paradigms for utilizing self-adaptive software. One of these is the planning paradigm, and the other is the control paradigm. In [13], Wang proposed a Rule Model for self-adaptive software, which includes three key concepts (event, parameter, and rule). In Wang’s paper, rules were used to adjust software’s behavior at runtime. Psaier *et al.* [11] presented a middleware for programming and adapting complex service-oriented systems. Their approach was based on monitoring and real-time intervention to regulate interactions based on behavior policies.

Cheng *et al.* [2] introduced a new language of adaptation, which ultimate aim is to automate human tasks in system management to achieve high-level stakeholder objectives. They claimed that such a language is “expressive enough to describe human expertise and comes with the flexibility and robustness to capture complex and potentially dynamic preferences”.

In our work, we developINI by combining both rule-based and event-based programming styles. INI takes inspirations from existing rule-based languages [3], and event-based programming similarly to the work above. With rule-based programming, an action is executed only if its guard is evaluated to true in the context of the function. With event-based programming, we allow programmers to write their own events to capture and monitor changes happening during execution. Moreover, we fully support events synchronization and reconfiguration. Although several event-based programming languages have been proposed

so far [4,6], their support for writing self-adaptive software are limited. To our knowledge, no languages support event reconfiguration at runtime. The key feature of INI compared to all the languages we have studied is that events are dynamically reconfigurable. This feature allows INI programs to automatically reconfigure themselves to adapt to changes in the environment.

3 Programming with INI

The interpreter of INI is currently implemented in Java and runs on a JVM, but INI's syntax and semantics are not Java's ones. Each INI program contains functions, in which the starting point is the function `main`. All functions are written with rules in combination with event expressions. Each rule is defined explicitly with a guard and an action. The guard triggers the evaluation of the action when evaluated to true in the context of the function. Along with rules, programmers can use events in INI to capture changes when their programs are running. In this paper, we focus on event-triggered rules since we use them as the main mechanism for self-adaptation.

3.1 Events in INI

Table 1. Some built-in events in INI

Built-in event kind	Meaning
<code>@init()</code>	The <code>@init</code> event is invoked when the function starts evaluating.
<code>@end()</code>	On the contrary to the <code>@init</code> event, the <code>@end</code> event is triggered when no more event can be applied and when the function is about to return.
<code>@every[time:Integer]()</code>	The <code>@every</code> event occurs periodically as specified by its input parameter (in milliseconds).
<code>@update[variable:T](oldValue:T,newValue:T)</code>	The <code>@update</code> event is invoked when a specific variable is changed during execution.

An event is defined as something happening during the execution of the program, which should be monitored and handled. Events in INI can be understood at three different levels: the *event kind* corresponds to the class/type of the event; the *event instance* (*event* for short) corresponds to the definition of an event-triggered rule in the INI program; the *event thread* corresponds to the execution of an event instance. By convention, event kinds start with `@` and can take input and output parameters. Input parameters can be understood as configuration parameters to tune the event execution. Output parameters are passed to the action. These parameters may be optional. Syntactically, each event (instance) is written as below. Optionally, an event can also be bound to an id, so that other parts of the program can refer to it.

```
id:@eventKind [inputParam1=value1, inputParam2=value2, ...]
               (outputParam1, outputParam2, ...) { <action> }
```

To allow programmers to write code more easily and conveniently,INI comes with some common built-in event kinds such as `@init`, `@end`, `@every`, `@update`. The meanings of these events are given in Table 1. For example, the following code creates an `@every` instance called `e`, which increments `v` every second. The `@update` instance `u` triggers the action (event handler) that prints out the `v` variable value when it changes, i.e. every second.

```
e: @every[time=1000]() { v = v + 1 }
u: @update[variable=v](oldv, newv) { println("v=" + newv) }
```

Beyond built-in events, we also allow programmers to write their own event kinds in Java or in C and integrate them into an INI program as explained in the next section.

3.2 Example

In this section, we discuss a sample INI program, written in an event-driven style. In our example, we use a video camera to detect the movement of a ball, get its positions in space periodically, and save them into a CSV file.

To do so, we first need to define a new event kind to detect the ball and send its position to the program when detected. Our event has one input parameter called `frequency`. This parameter is applied to set how long the event should sleep between two image detections (time unit is in milliseconds). Besides, we have three output parameters (`r,x,y`), which are the radius and coordinates of the detected ball in the captured image. In Java, we need to subclass the `ini.event.Event` class to define the behavior of our new event kind as shown in the code below.

```
1 public class BallDetection extends ini.event.Event {
2     Thread ballDetectionThread;
3     @Override public void eval(final IniEval eval) {
4         (ballDetectionThread = new Thread() {
5             @Override public void run() {
6                 ...
7                 do {
8                     try {
9                         // Sleep as long as the configuration indicates
10                         sleep(getContext().get("frequency")
11                             .getNumber().longValue());
12                         // Use OpenCV to detect the ball
13                         ...
14                         // Write data to output parameters
15                         variables.put(outParameters.get(0), r);
16                         variables.put(outParameters.get(1), x);
17                         variables.put(outParameters.get(2), y);
18                         // Execute the event action
19                         execute(eval, variables);
20                     } catch (Exception e) {...}
21                 } while (!checkTerminated());
22         }).start();
23     }
24 }
```

```

22     }
23     }).start();
24   }
25   @Override public void terminate() {...}
26 }
```

In the `BallDetection` class, the method `eval` will be upcalled by the INI evaluator when the program uses our event. It creates a thread that sleeps accordingly to the event configuration (line 10), detects the ball using the OpenCV library (line 13) [5] and write the results in output parameters to be passed to the INI program (lines 15-17). The event-triggered action, also called *event thread*, is executed at line 19 using the `execute` method provided by the API, which by default runs asynchronously. Finally, the method `terminate` is overridden to stop the event: INI upcalls this method when the program exits or forces the event to shutdown. To understand more about built-in events in INI and how to write user-defined events, interested readers may refer to INI Language Reference Documentation [10].

```

1 import "lib_io.ini"
2 @ballDetection[frequency:Integer](Float, Integer, Integer)
3   => "ini.ext.events.BallDetection"
4 function main() {
5   @init() { f = file("ballData.csv") }
6   // Use our event get notified for ball detection
7   @ballDetection[frequency = 1](r,x,y){
8     case {
9       !file_exists(f) {
10         // Create a new CSV file to store data
11         create_file(f)
12         fprintf(f, "Time,rx,ux,uy")
13       }
14     }
15     fprintf(f,to_string(time())+","+r+","+x+","+y)
16   }
17 }
```

Fig. 1. A sample INI program with event-driven style

In Figure 1, we write the actual INI program, which binds our Java user-defined to the `@ballDetection` event kind (lines 2-3). In the `@init` event, we define a variable `f`, which indicates the CSV file we want to store data in after collecting the ball positions over time. In INI, all variables are global within the function where they are defined. This means that `f` can be accessed anywhere in the function `main`. In our program, the `@ballDetection` event is triggered periodically, i.e. each millisecond. If a ball is detected, we check whether the CSV file exists or not (line 9). If the file does not exist, we create a new one and

write the header. Finally, we write the data to the file (line 15), including the time when the ball was detected and its position.

4 Events Synchronization and Reconfiguration

The event reconfiguration mechanism is developed in INI so that we can modify the input parameters (configuration) of the event-triggered rules at runtime. For example, an event can be notified for a change in the environment and decide to reconfigure another event to adapt the program to the new environment. However, to achieve safe reconfiguration, synchronization among events is also essential. In this section, we first explain event synchronization, and then discuss event reconfiguration, which we illustrate using our ball-detection example.

4.1 Events Synchronization

Except for the `@init` and `@end` events, most INI events are executed asynchronously by default. From an implementation perspective, it means that each event handler runs in its own thread, potentially simultaneously to other events. In many cases, a given event e_0 may want to synchronize to other events e_1, \dots, e_N , which means that the synchronizing event e_0 must wait for all the target event threads to be terminated before running. For instance, it can be used to ensure that a shared variable accessed both for reading and writing has a consistent state, or also to ensure that all event threads have terminated before reconfiguring the associated event-triggered rule. Thus, INI provides a specific language construct: the symbol `$` along with the list of identifiers of target events with which we want to synchronize. For example, the following code ensures that the above discussed event e_0 synchronizes N target events.

```
$(e1, e2, ..., eN) e0:@eventKind [...] (...) { <action> }
```

Note that one of the target events can also be synchronized with e_0 . Cross-synchronization of events means that their executions are mutually exclusive. We now precisely define the semantics of synchronization in INI.

To implement synchronization in INI, we use one lock and one *count* variable associated with each event. The lock is an instance of `java.util.concurrent.locks.ReentrantLock` and is used to avoid concurrent execution when required. We use the functions `lock` (blocking), `tryLock` (non-blocking and returns true or false depending on whether the locking was successful or not), and `unlock`. For more details, refer to the Java document of the methods of the same names in the `ReentrantLock` class [9]. The *count* variable holds the number of threads currently executing for the associated event. We use the following notation: for an event e_i , we call l_i its associated lock and $count_i$ its associated thread counting variable.

Let (e_1, e_2, \dots, e_N) be the list of target events with which e_0 synchronizes. To execute the event e_0 in INI, we apply Algorithm 1, which also applies to any event execution in the INI system. We can see that the execution of events

Algorithm 1 Our algorithm to execute e_0 synchronized with (e_1, e_2, \dots, e_n)

```

1: repeat
2:    $allLocked := true$ 
3:    $lock(l_0)$ 
4:   for  $i := 1$  to  $N$  step 1 do
5:     if  $\neg tryLock(l_i)$  then
6:        $allLocked := false$ 
7:       for  $i := 1$  to  $i - 1$  step 1 do
8:          $unlock(l_j)$ 
9:       end for
10:       $unlock(l_0)$ 
11:       $sleep(randomTime())$ 
12:      break
13:    end if
14:   end for
15: until  $\neg allLocked$ 
16: for  $i := 1$  to  $N$  step 1 do
17:   wait-until  $count_i = 0$ 
18: end for
19:  $count_0 := count_0 + 1$ 
20: for  $i := 1$  to  $N$  step 1 do
21:    $unlock(l_i)$ 
22: end for
23:  $unlock(l_0)$ 
24:  $eval(e_0)$ 
25:  $count_0 := count_0 - 1$ 

```

includes four steps. First, e_0 locks its own lock and tries to lock all target events (lines 1-15). When all events are locked, the event e_0 needs to wait until all other events are terminated (lines 16-18). The **wait-until** mechanism in our algorithm is currently implemented with Java monitors and thread notification. Next, the number of threads executing for event e_0 is incremented and locks for all events are released (lines 19-23). Finally, the event can be actually evaluated and when it is terminated, the number of running threads for it is decremented (lines 24-25).

4.2 Example Using Synchronization

Let us take again our example shown in Figure 1. Assuming that after we collect data about positions of a ball in space, we need to upload the CSV file to an FTP server. To do this, we create a new **@every** event as shown in Figure 2. Inside this event, first, we compress data and then upload the compressed file. Since we collect data periodically, we use a timestamp (line 4) to distinguish data at different time.

```

1 ...
2 // Compress and upload the collected data to an FTP server
3 @every[time = 5000](){
4     t = time()
5     zip(file_name(f), to_string(t)+"ballData.zip")
6     upload_ftp("ftp_address", "user_name", "password",
7         to_string(t)+"ballData.zip",
8         to_string(t)+"uploadedBallData.zip")
9 }

```

Fig. 2. An event used to upload collected data

By default, the two events `@ballDetection` and `@every` will be executed asynchronously. However, it is essential that when we collect data (`@ballDetection`), the uploading process (`@every`) should not happen and vice versa. In other words, these two events need to be mutually exclusive. To ensure this, the programmer needs to modify the program at lines 7 of Figure 1 and 3 of Figure 2 by naming the two events and use their identifiers to cross-synchronize them, as it is shown in the following code:

```

$(e) b:@ballDetection[frequency = 1](r,x,y) { ...
$(b) e:@every[time = 5000](){ ...

```

4.3 Event Reconfiguration

In this section, we will demonstrate the capabilities of INI in handling changes happening in the environment though the event-reconfiguration mechanism. Event reconfiguration consists of changing the values of the event-triggered rule input parameters. Programmers can call the built-in function `reconfigure(eventId, [inputParam1=value1, inputParam2=value2,...])` to reconfigure their events. Moreover, we also allow programmers to stop and restart events with the built-in functions `stop_event(eventId)` and `restart_event(eventId)`. Typically, it is required to stop an event before reconfiguring it.

Let us now consider that our ball-detection example of Section 3 runs in an embedded environment where the power is supplied by a battery. One way to take into account this new constraint is to adapt the data-collection frequency to the power level. First, we add a new user-defined event kind called `@powerAlarm`, which notifies the program each time the power level passes a given threshold both ways, when charging or discharging. This event has one input parameter named `threshold`, and one output parameter named `currentLevel`, which tells us if the level is currently lower or greater than the threshold. When the program below is running, if it detects that the power-level is lower than 50% (configured line 1), it stops the event `b:@ballDetection` (line 4), then changes the value of its input parameter (i.e., `frequency`) to 1000 (line 5), and finally restarts it (line 6). Conversely, if the power goes over the threshold the value for the parameter

frequency is set again to 1 (lines 8 - 10). The event @powerAlarm is synchronized with events b:@ballDetection and e:@every as specified by \$(b,e) at line 1 in order to avoid unfinished detection or upload jobs to be stopped.

```

1   ...
2   // Adapt the ball detection frequency at the 50% threshold
3   $(b,e) p:@powerAlarm [threshold = 0.5](currentLevel) {
4     case {
5       currentLevel < threshold {
6         stop_event(b)
7         reconfigure(b, [frequency = 1000])
8         restart_event(b)
9     } default {
10       stop_event(b)
11       reconfigure(b, [frequency = 1])
12       restart_event(b)
13     }
14   }
15 }
```

Finally in the following code, we show how to add a second @powerAlarm instance that stops all other events when the threshold goes below 10%.

```

1   $(b,e) @powerAlarm [threshold = 0.1](currentLevel) {
2     case {
3       currentLevel < threshold { stop_events([b, e, p]) }
4       default { restart_events([b, e, p]) }
5     }
6   }
```

5 Conclusion and Future Work

In this paper, we introduce a new language called INI, which can be used to write self-adaptive software through events synchronization and reconfiguration mechanisms. Programs written in INI may dynamically change their behavior or improve their operation depending on dynamic operational conditions of the environment. With the example that we used along the paper to demonstrate the capabilities of INI, we can see that using INI to write new event-driven rules does not require too much effort. The programmers can capture the changes during execution by writing their own user-defined events and then define suitable actions for them. The changes necessary to take into account new constraints can thus be localized and encapsulated within some rules, which implies code maintainability and robustness with regard to changes.

For future work, we will improve INI so that it can handle changes in environment more efficiently. For example, as stated in [2], we need a mechanism to handle failure during adaptation execution. If a failure happens when our systems try to adapt to the environment, it is essential to recover from that failure. Besides, we will define formal semantics for validating and verifying useful

properties ofINI programs and prove the soundness of its type system. Finally, we also have a plan to perform more case studies to evaluate the capabilities ofINI.

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