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The large central charge limit of conformal blocks

Vladimir Fateev^{1,2} and Sylvain Ribault¹

¹*Laboratoire Charles Coulomb UMR 5221 CNRS-UM2
Université Montpellier 2, Place Eugène Bataillon - CC070
F-34095 Montpellier Cedex 5 - France*

²*Landau Institute for Theoretical Physics
142432 Chernogolovka, Russia*

`vladimir.fateev@univ-montp2.fr, sylvain.ribault@univ-montp2.fr`

ABSTRACT: We study conformal blocks of conformal field theories with a W_3 symmetry algebra in the limit where the central charge is large. In this limit, we compute the four-point block as a special case of an sl_3 -invariant function. In the case when two of the four fields are semi-degenerate, we check that our results agree with the block's combinatorial expansion as a sum over Young diagrams. We also show that such a block obeys a sixth-order differential equation, and that it has an unexpected singularity at $z = -1$, in addition to the expected singularities at $z = 0, 1, \infty$.

KEYWORDS: Conformal blocks, sl_N -invariant functions.

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1. Introduction

Since the work of Belavin, Polyakov and Zamolodchikov [1], the conformal bootstrap method has been an effective tool for studying two-dimensional conformal field theories. That method relies on a systematic exploitation of the symmetries of the theory. These symmetries determine functions called conformal blocks. The simplest conformal blocks are the characters of the representations of the symmetry algebra, which may be called zero-point blocks on the torus. The correlation functions of the theory are then combinations of the conformal blocks. For example, the partition function on the torus is a combination of characters.

Combinatorial expansions for the conformal blocks of the Virasoro algebra have recently been found [2], inspired by the conjecture of Alday, Gaiotto and Tachikawa on the relation between two-dimensional CFTs and four-dimensional gauge theories [3]. Until then, no explicit formulas for four-point blocks on the sphere were known. It would be very interesting to generalize such

combinatorial expansions to conformal blocks of other algebras, in particular the W_N algebras [4, 5, 6] which are natural generalizations of the Virasoro algebra.

This is however a challenging problem, in particular because the fusion products of $W_{N \geq 3}$ representations in general exhibit infinite fusion multiplicities. (See for instance Section 2.3 of [7].) This feature is at the origin of difficulties in computing the three-point correlation functions in conformal Toda theories. These CFTs have W_N symmetry algebras, and their three-point correlation functions are only known in special cases [8, 9]. Here we will show how to take infinite fusion multiplicities into account and how to compute conformal blocks in the limit where the central charge c of the W_N algebra is large. (The conformal dimensions of the fields are meanwhile kept fixed; this is sometimes called the light asymptotic limit.) It is this limit which was used by Al. Zamolodchikov as the starting point of the characterization of Virasoro ($N = 2$) conformal blocks by recurrence [10]. In this limit, sl_N conformal Toda theory reduces to the quantum mechanics of a point particle on $SL_N(\mathbb{C})$, the W_N algebra reduces to sl_N , and the W_N conformal blocks reduce to special cases of sl_N -invariant functions. We will study such functions in detail in the cases $N = 2$ and $N = 3$.

This will enable us to test a proposal for the combinatorial expansion of a class of W_N conformal blocks [11]. The proposed expansion, which we will summarize, is given for all values of c , assuming that all involved fields except two of them are almost fully degenerate. This assumption eliminates the problem of the infinite fusion multiplicities. We will compare our results for large c conformal blocks of that class, with the large c limit of the combinatorial expansion. The two expansions agree up to the order z^5 , which supports the validity of the proposed combinatorial expansion.

Plan of the article. In Section 2, after a reminder on the large c limit of Virasoro conformal blocks, we study sl_3 -invariant functions and their relations with the large c limit of W_3 conformal blocks. Then, in the concluding Section 3, we comment on some aspects of the results, and compare them with the combinatorial expansion. Appendix A is devoted to the study of a quantum particle on $SL_N(\mathbb{C})$ (with $N = 2, 3$), which is at the basis of the computation of the large c limit of correlation functions of sl_N conformal Toda theory, and provides some justification for a number of the equations of Section 2. Appendix B is devoted to deriving the series expansion (2.65) of certain conformal blocks. Appendix C is devoted to the study of detailed properties of such conformal blocks: the differential equation they obey, and their critical exponents.

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2. W_3 conformal blocks and sl_3 -invariant functions

2.1 Virasoro conformal blocks and sl_2 -invariant functions

We first review the case of Virasoro conformal blocks, before moving to the technically more complicated case of W_3 conformal blocks. Basic information on Virasoro conformal blocks can be found in [12]. A four-point s -channel Virasoro conformal block on the sphere $\mathcal{G}_{\Delta_s}(c|\Delta_i|z_i)$ is a function of the positions $(z_1, z_2, z_3, z_4) \in \mathbb{C}^4$ of four primary fields, which are characterized

by their conformal dimensions $(\Delta_1, \Delta_2, \Delta_3, \Delta_4)$. Such a conformal block also depends on an s -channel conformal dimension Δ_s , and on the central charge c of the Virasoro algebra. The conformal block is defined as a sum over the states of the highest-weight representation of the Virasoro algebra with conformal dimension Δ_s . We are interested in the "large c block"

$$\mathcal{F}_{\Delta_s}(\Delta_i|z_i) = \lim_{c \rightarrow \infty} \mathcal{G}_{\Delta_s}(c|\Delta_i|z_i). \quad (2.1)$$

This large c block, like the conformal block itself, is supposed to have an analytic expansion in the neighbourhood of $z_1 = z_2$,

$$\mathcal{F}_{\Delta_s}(\Delta_i|z_i) = z_{12}^{\Delta_s - \Delta_1 - \Delta_2} (1 + O(z_{12})), \quad (2.2)$$

where we use the notation $z_{12} = z_1 - z_2$. The conformal block and its large c limit also share the same behaviour under global conformal transformations, which we now review.

The Virasoro algebra has an sl_2 subalgebra of global conformal transformations, with generators (L_{-1}, L_0, L_1) and commutation relations

$$[L_0, L_{\pm 1}] = \pm L_{\pm 1}, \quad [L_1, L_{-1}] = 2L_0. \quad (2.3)$$

A representation of the Virasoro algebra with conformal dimension Δ corresponds to an sl_2 representation of spin $-\Delta$. Notice that two Virasoro representations whose dimensions are related by the reflection

$$\Delta^* = 1 - \Delta, \quad (2.4)$$

correspond to two isomorphic sl_2 representations. A primary field with position z and conformal dimension Δ behaves as a vector in an sl_2 representation of spin $-\Delta$ and isospin variable z . The action of the sl_2 subalgebra on the primary field is given by the differential operators

$$D_{(\Delta, z)}(L_1) = \frac{\partial}{\partial z}, \quad D_{(\Delta, z)}(L_0) = -z \frac{\partial}{\partial z} - \Delta, \quad D_{(\Delta, z)}(L_{-1}) = -z^2 \frac{\partial}{\partial z} - 2\Delta z, \quad (2.5)$$

which are such that $D_{(\Delta, z)}$ preserves the commutation relations (2.3). The blocks $\mathcal{G}_{\Delta_s}(c|\Delta_i|z_i)$, and therefore their large c limits $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$, are sl_2 -invariant four-points functions. What we call an sl_2 -invariant n -points function is a function $\mathcal{E}(\Delta_i|z_i)$ of $(\Delta_1, \Delta_2, \dots, \Delta_n)$ and (z_1, z_2, \dots, z_n) such that

$$\forall t^a \in \{L_{-1}, L_0, L_1\}, \quad \left(\sum_{i=1}^n D_{(\Delta_i, z_i)}(t^a) \right) \mathcal{E}(\Delta_i|z_i) = 0. \quad (2.6)$$

The invariant two- and three-points functions are well-known to be

$$\mathcal{E}(\Delta_1, \Delta_2|z_1, z_2) = z_{12}^{-2\Delta_1}, \quad (\text{assuming } \Delta_1 = \Delta_2), \quad (2.7)$$

$$\mathcal{E}(\Delta_1, \Delta_2, \Delta_3|z_1, z_2, z_3) = z_{12}^{\Delta_3 - \Delta_1 - \Delta_2} z_{23}^{\Delta_1 - \Delta_2 - \Delta_3} z_{31}^{\Delta_2 - \Delta_3 - \Delta_1}. \quad (2.8)$$

Any invariant four-points function $\mathcal{E}(\Delta_i|z_i)$ can be written in terms of its values when three of the z_i s are fixed, for example $(z_1, z_3, z_4) = (0, 1, \infty)$,

$$\mathcal{E}(\Delta_i|z_i) = P(\Delta_i|z_i) z^{\Delta_1 + \Delta_2} \mathcal{E}(\Delta_i|0, z, 1, \infty), \quad (2.9)$$

where we define the cross-ratio z and prefactor $P(\Delta_i|z_i)$ are

$$P(\Delta_i|z_i) = z_{12}^{-\Delta_1-\Delta_2} z_{13}^{-\Delta_3+\Delta_4} z_{43}^{-\Delta_3-\Delta_4} z_{42}^{\Delta_1-\Delta_2} z_{14}^{-\Delta_1+\Delta_2+\Delta_3-\Delta_4} , \quad z = \frac{z_{12}z_{34}}{z_{13}z_{24}} . \quad (2.10)$$

(Notice that we have $P(\Delta_i|z_i) = \mathcal{E}(\Delta_1, \Delta_2, 0|z_1, z_2, z_4)\mathcal{E}(0, \Delta_3, \Delta_4|z_1, z_3, z_4)$.) For brevity we will sometimes use the notation $\mathcal{E}(z) = \mathcal{E}(\Delta_i|0, z, 1, \infty)$.

After these reminders on the global conformal symmetry, we are ready to write an explicit integral formula for the large c four-point conformal block,

$$\mathcal{F}_{\Delta_s}(\Delta_i|z_i) = \mathcal{N} \int_C dz_s \mathcal{E}(\Delta_1, \Delta_2, \Delta_s|z_1, z_2, z_s) \mathcal{E}(\Delta_s^*, \Delta_3, \Delta_4|z_s, z_3, z_4) , \quad (2.11)$$

where the normalization factor \mathcal{N} (a function of Δ_i, Δ_s) and integration contour C are determined by the condition (2.2). This expression is justified in Appendix A.1. With a general integration contour, the integral in eq. (2.11) would yield a linear combination of the two "reflected" blocks \mathcal{F}_{Δ_s} and $\mathcal{F}_{\Delta_s^*}$. Explicitly, we find

$$\mathcal{F}_{\Delta_s}(\Delta_i|0, z, 1, \infty) = z^{-\Delta_{12}^s} \sum_{n=0}^{\infty} \frac{(\Delta_s - \Delta_1 + \Delta_2)_n (\Delta_s - \Delta_4 + \Delta_3)_n}{(2\Delta_s)_n} z^n , \quad (2.12)$$

$$= z^{-\Delta_{12}^s} F(\Delta_s - \Delta_1 + \Delta_2, \Delta_s - \Delta_4 + \Delta_3, 2\Delta_s, z) , \quad (2.13)$$

where F is the hypergeometric function, and we use the notations

$$(t)_n = \prod_{i=0}^{n-1} (t+i) = \frac{\Gamma(t+n)}{\Gamma(t)} , \quad (2.14)$$

and

$$\Delta_{12}^s = \Delta_1 + \Delta_2 - \Delta_s . \quad (2.15)$$

2.2 sl_3 -invariant functions

In preparation for writing the large c conformal blocks of the W_3 algebra, we need to study sl_3 -invariant functions. This is because the W_3 algebra reduces to sl_3 in the large c limit. (The eight generators $L_0, L_{\pm 1}, W_0, W_{\pm 1}, W_{\pm 2}$ of the W_3 algebra which survive in the large c limit can be identified with linear combinations of the generators h^i, e^i, f^i of sl_3 which we are about to introduce.)

The algebra sl_3 is generated by two Cartan elements (h^1, h^2) , three generators (f^1, f^2, f^3) which are eigenvectors of the adjoint actions of h^1 and h^2 for the respective eigenvalues $(-2, 1, -1)$ and $(1, -2, -1)$, and three generators (e^1, e^2, e^3) which are also eigenvectors but with opposite eigenvalues. The remaining nonzero commutators are

$$[f^1, f^2] = -f^3 , \quad [e^1, e^2] = e^3 , \quad (2.16)$$

$$[e^1, f^1] = h^1 , \quad [e^2, f^2] = h^2 , \quad [e^3, f^3] = h^1 + h^2 , \quad (2.17)$$

$$[e^1, f^3] = -f^2 , \quad [e^2, f^3] = f^1 , \quad [e^3, f^1] = -e^2 , \quad [e^3, f^2] = e^1 . \quad (2.18)$$

In order to parametrize the representations of sl_3 , let us introduce its simple roots (e_1, e_2) and fundamental weights (h_1, h_2, h_3) (not to be confused with the sl_3 generators e^i, h^j). The roots are supposed to be two independent vectors, with a scalar product given by the Cartan matrix, $(e_i, e_j) = K_{ij}$ with $K = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$. The fundamental weights are

$$h_1 = \frac{2}{3}e_1 + \frac{1}{3}e_2 \quad , \quad h_2 = -\frac{1}{3}e_1 + \frac{1}{3}e_2 \quad , \quad h_3 = -\frac{1}{3}e_1 - \frac{2}{3}e_2 \quad . \quad (2.19)$$

A representation is parametrized by a spin vector j in root space, whose coordinates we denote as

$$r = -(e_1, j) \quad , \quad s = -(e_2, j) \quad . \quad (2.20)$$

Two representations are isomorphic when they are related by one of the six Weyl transformations

$$(r, s) \rightarrow \begin{cases} (r, s), & (3 - r - s, r), & (s, 3 - r - s), \\ (2 - r, -1 + r + s), & (-1 + r + s, 2 - s), & (2 - s, 2 - r), \end{cases} \quad (2.21)$$

among which we single out the maximal Weyl reflection $j \rightarrow j^*$ where

$$j = (r, s) \Rightarrow j^* = (2 - s, 2 - r) \quad . \quad (2.22)$$

There is another useful reflection of the root space called the Dynkin diagram automorphism $j \rightarrow j^\omega$ where

$$j = (r, s) \Rightarrow j^\omega = (s, r) \quad . \quad (2.23)$$

In the previous Subsection, we represented sl_2 transformations in terms of differential operators (2.5), whose isospin variable z could be interpreted as the position of a CFT field on the complex plane. In order to faithfully represent sl_3 transformations, we need a triple of variables $Z = (w, x, y)$. (The number of needed variables is the number of creation operators e^i ; in the case of sl_n this would be $\frac{n(n-1)}{2}$.) The sl_3 generators (h^i, e^i, f^i) are represented as [12](Section 15.7.4)

$$D_{(j,Z)}(h^1) = 2x\partial_x + r - y\partial_y + w\partial_w \quad , \quad (2.24)$$

$$D_{(j,Z)}(h^2) = 2y\partial_y + s - x\partial_x + w\partial_w \quad , \quad (2.25)$$

$$D_{(j,Z)}(e^1) = x^2\partial_x + rx + (w - xy)\partial_y + xw\partial_w \quad , \quad (2.26)$$

$$D_{(j,Z)}(e^2) = y^2\partial_y + sy - w\partial_x \quad , \quad (2.27)$$

$$D_{(j,Z)}(e^3) = w^2\partial_w + s(w - xy) + rw + xw\partial_x + y(w - xy)\partial_y \quad , \quad (2.28)$$

$$D_{(j,Z)}(f^1) = -\partial_x \quad , \quad (2.29)$$

$$D_{(j,Z)}(f^2) = -\partial_y - x\partial_w \quad , \quad (2.30)$$

$$D_{(j,Z)}(f^3) = -\partial_w \quad . \quad (2.31)$$

An sl_3 -invariant n -point function associated to n spins j_1, j_2, \dots, j_n is a function $\mathcal{E}(j_i|Z_i)$ such that

$$\forall t^a \in \{h^i, e^i, f^i\}, \quad \left(\sum_{i=1}^n D_{(j_i, Z_i)}(t^a) \right) \mathcal{E}(j_i|Z_i) = 0 \quad . \quad (2.32)$$

Such an invariant will obey additional equations if some representations are degenerate. We will call the representation of spin j_1 semi-degenerate of the first ($k = 1$) or second ($k = 2$) kind if

$$(e_k, j_1) = 0 \quad \text{and} \quad d_{Z_1}^{(k)} \mathcal{E}(j_i | Z_i) = 0, \quad (2.33)$$

where the differential operators $d_Z^{(k)}$ are defined as

$$d_Z^{(1)} = \partial_x + y \partial_w, \quad d_Z^{(2)} = \partial_y. \quad (2.34)$$

These formulas for $d_Z^{(1)}$ and $d_Z^{(2)}$ will be justified in Appendix A.2.

Let us write the solutions of the sl_3 invariance equation (2.32) in the cases of two- and three-point invariants. We will write the solutions of these equations in terms of convenient combinations of isospin variables $Z_i = (w_i, x_i, y_i)$,

$$\rho_{ij} = y_i(x_i - x_j) - (w_i - w_j), \quad (2.35)$$

$$\sigma_{ijk} = x_i w_j - x_j w_i + x_j w_k - x_k w_j + x_k w_i - x_i w_k, \quad (2.36)$$

$$\begin{aligned} \chi_{ijk} = & y_i w_j - y_j w_i + y_j w_k - y_k w_j + y_k w_i - y_i w_k \\ & + y_i y_j (x_i - x_j) + y_j y_k (x_j - x_k) + y_k y_i (x_k - x_i). \end{aligned} \quad (2.37)$$

We also introduce the three-point invariant

$$\theta_{ijk} = \frac{\rho_{ij} \rho_{jk} \rho_{ki}}{\rho_{ji} \rho_{kj} \rho_{ik}} \Rightarrow \left(D_{(0, Z_i)}(t^a) + D_{(0, Z_j)}(t^a) + D_{(0, Z_k)}(t^a) \right) \theta_{ijk} = 0. \quad (2.38)$$

Our combinations are related by identities of the type

$$\sigma_{123} \chi_{123} = \rho_{21} \rho_{32} \rho_{13} (\theta_{123} + 1), \quad (2.39)$$

$$\chi_{123} \rho_{41} + \chi_{134} \rho_{21} + \chi_{142} \rho_{31} = 0. \quad (2.40)$$

We then find that a nonzero two-point invariant can exist only provided $j_1 = j_2^\omega$ (up to Weyl reflections), and the invariant is then

$$\mathcal{E}(j_1, j_2 | Z_1, Z_2) = \rho_{21}^{-r_1} \rho_{12}^{-s_1}, \quad (\text{assuming } j_1 = j_2^\omega). \quad (2.41)$$

Consider now three-point invariants. The function $\mathcal{E}(j_1, j_2, j_3 | Z_1, Z_2, Z_3)$ depends on nine variables which are the components of Z_1, Z_2, Z_3 , and is subject to the eight equations (2.32). Therefore, there exists an infinite-dimensional space of solutions. This corresponds to the existence of a nontrivial invariant θ_{123} (2.38). In the special case when one of the three representations is semi-degenerate, we have an extra equation of the type (2.33), and the space of solutions is one-dimensional. Let us start with the case when the first representation is semi-degenerate of the first kind. The three-point invariant should be built from combinations of isospin variables which are killed by the differential operator $d_{Z_1}^{(1)}$ (2.34), for instance

$$d_{Z_1}^{(1)} \rho_{12} = 0, \quad d_{Z_1}^{(1)} \chi_{123} = 0. \quad (2.42)$$

We then find the three-point invariant

$$\mathcal{E}(j_1, j_2, j_3 | Z_1, Z_2, Z_3) = \chi_{123}^{-J} \rho_{12}^{-J-r_2+s_3} \rho_{13}^{-J-r_3+s_2} \rho_{23}^{J-s_2} \rho_{32}^{J-s_3}, \quad (r_1 = 0), \quad (2.43)$$

where we introduced the combination of spins

$$J = (h_2, j_1 + j_2 + j_3) = \frac{1}{3}(s_1 + s_2 + s_3 - r_1 - r_2 - r_3). \quad (2.44)$$

Similarly, if the first representation is semi-degenerate of the second kind, we can use combinations which are killed by $d_{Z_1}^{(2)}$, in particular

$$d_{Z_1}^{(2)} \rho_{21} = 0 \quad , \quad d_{Z_1}^{(2)} \sigma_{123} = 0, \quad (2.45)$$

and we find the three-point invariant

$$\mathcal{E}(j_1, j_2, j_3 | Z_1, Z_2, Z_3) = \sigma_{123}^J \rho_{21}^{J+r_3-s_2} \rho_{31}^{J+r_2-s_3} \rho_{23}^{-J-r_3} \rho_{32}^{-J-r_2}, \quad (s_1 = 0). \quad (2.46)$$

In general, when no representation is semi-degenerate, the most general three-point invariant is

$$\mathcal{E}_{g_1}(j_i | Z_i) = \chi_{123}^{-J} \rho_{12}^{-J-r_1-r_2+s_3} \rho_{13}^{-J-r_3+s_2} \rho_{23}^{J-s_2} \rho_{32}^{J+r_1-s_3} \rho_{31}^{-r_1} g_1(\theta_{123}), \quad (2.47)$$

$$= \sigma_{123}^J \rho_{21}^{J+r_3-s_1-s_2} \rho_{31}^{J+r_2-s_3} \rho_{23}^{-J-r_3+s_1} \rho_{32}^{-J-r_2} \rho_{13}^{-s_1} g_2(\theta_{123}). \quad (2.48)$$

This depends on an arbitrary ‘‘multiplicity function’’ $g_1(\theta)$, or on the equivalent function $g_2(\theta) = \theta^{-J-r_1-r_2+s_3} (\theta + 1)^{-J} g_1(\theta)$. This function encodes the infinite multiplicity of say the third representation in the tensor product of the first two representations. The same feature manifests itself in the fusion products of W_3 representations, we have called this the problem of the infinite fusion multiplicities in the Introduction.

Bases of n -point invariants can be built from three-point invariants. For instance, s -channel four-point invariants can be built as

$$\mathcal{E}_{g,g'|j_s}(j_i | Z_i) = \mathcal{N} \int_C dZ_s \mathcal{E}_g(j_1, j_2, j_3 | Z_1, Z_2, Z_s) \mathcal{E}_{g'}(j_s^{*\omega}, j_3, j_4 | Z_s, Z_3, Z_4), \quad (2.49)$$

where j_s is the s -channel spin, g, g' are two multiplicity functions, \mathcal{N} is a normalization factor which may depend on j_s, j_i, g, g' , and C is an integration domain for $Z_s \in \mathbb{C}^3$. The integration measure is the sl_3 -invariant measure $dZ = dwdxdy$.

2.3 W_3 conformal blocks in the large c limit

A four-point s -channel W_3 conformal block on the sphere $\mathcal{G}_{g,g'|\alpha_s}(c|\alpha_i|z_i)$ is a function of the positions (z_1, z_2, z_3, z_4) of four primary fields characterized by their momenta $(\alpha_1, \alpha_2, \alpha_3, \alpha_4)$, and of the central charge c of the W_3 algebra. The block also depends on an s -channel momentum α_s , and on two multiplicity functions g, g' . The presence of such multiplicity functions is in general necessary due to the presence of infinite fusion multiplicities, and we have given a precise definition of such multiplicity functions in the case of sl_3 -invariant functions in the previous Subsection. We will however not try to define such functions in the case of W_3 conformal blocks, except in the large c limit.

Let us introduce standard notations on W_3 representations. Let b and $q = b + b^{-1}$ be such that the central charge is $c = 2 + 24q^2$. A highest-weight representation of the W_3 algebra is parametrized by its momentum α , a two-dimensional vector which belongs to the root space of

sl_3 . Such a representation can alternatively be parametrized by its conformal dimension Δ_α and a charge $q_\alpha^{(3)}$ which is (up to a normalization factor) the eigenvalue of the spin 3 current, such that

$$\Delta_\alpha = \frac{1}{2}(\alpha, 2Q - \alpha) \quad , \quad q_\alpha^{(3)} = -3b \prod_{i=1}^3 (h_i, \alpha - Q) \quad , \quad (2.50)$$

where we defined $Q = q\rho$, which involves the Weyl vector $\rho = e_1 + e_2$.

The large c limit is defined as $c \rightarrow \infty$ with $\Delta, q^{(3)}$ fixed, or alternatively

$$b \rightarrow 0 \quad , \quad \alpha = -bj \quad , \quad j \text{ fixed} \quad . \quad (2.51)$$

This is sometimes called the light asymptotic limit. In the large c limit, the W_3 algebra reduces to sl_3 , and the vector j is the spin of an sl_3 representation. This spin is related to the limits $\Delta = \lim_{b \rightarrow 0} \Delta_{-bj}$ and $q^{(3)} = \lim_{b \rightarrow 0} q_{-bj}^{(3)}$ by

$$\Delta = r + s \quad , \quad q^{(3)} = r - s \quad , \quad (2.52)$$

where r and s are the components of the spin j , see eq. (2.20). Let us define the large c four-point conformal blocks,

$$\mathcal{F}_{g,g'|j_s}(j_i|z_i) = \lim_{b \rightarrow 0} \mathcal{G}_{g,g'|-bj_s}(c| -bj_i|z_i) \quad . \quad (2.53)$$

In analogy with the case of Virasoro conformal blocks, the large c conformal blocks of the W_3 algebra can be computed as special cases of sl_3 -invariant functions. We claim that an isospin variable $Z = (w, x, y)$ of an sl_3 -invariant function must then be of the type $Z = \vec{z}$ where we define

$$\vec{z} = \left(\frac{1}{2}z^2, z, z \right) \quad . \quad (2.54)$$

This relation between the isospin Z and the worldsheet position z comes from the following identities, which hold for any function $\mathcal{E}(Z)$:

$$D_{(j,Z)}(h^1 + h^2)\mathcal{E}(Z)|_{Z=\vec{z}} = -D_{(\Delta,z)}(L_0)\mathcal{E}(\vec{z}) \quad , \quad (2.55)$$

$$D_{(j,Z)}(e^1 + e^2)\mathcal{E}(Z)|_{Z=\vec{z}} = -\frac{1}{2}D_{(\Delta,z)}(L_{-1})\mathcal{E}(\vec{z}) \quad , \quad (2.56)$$

$$D_{(j,Z)}(f^1 + f^2)\mathcal{E}(Z)|_{Z=\vec{z}} = -D_{(\Delta,z)}(L_1)\mathcal{E}(\vec{z}) \quad , \quad (2.57)$$

where the sl_2 differential operators $D_{(\Delta,z)}(t^a)$ were defined in eq. (2.5), and the sl_3 operators $D_{(j,Z)}(t^a)$ in eq. (2.24)-(2.31). These identities show that the principally embedded sl_2 subalgebra of sl_3 with generators $(h^1 + h^2, e^1 + e^2, f^1 + f^2)$ can be identified with the sl_2 algebra of global conformal transformations. Therefore, a large c four-point block is a special case of a four-point sl_3 -invariant function (2.49),

$$\mathcal{F}_{g,g'|j_s}(j_i|z_i) = \mathcal{N} \int_C dZ_s \mathcal{E}_g(j_1, j_2, j_s|\vec{z}_1, \vec{z}_2, Z_s) \mathcal{E}_{g'}(j_s^{*\omega}, j_3, j_4|Z_s, \vec{z}_3, \vec{z}_4) \quad , \quad (2.58)$$

where the maximal Weyl reflection $j \rightarrow j^*$ and the Dynkin diagram automorphism $j \rightarrow j^\omega$ were defined in eqs. (2.22) and (2.23), and the three-point invariant \mathcal{E}_g was given in eq. (2.47). The

normalization factor \mathcal{N} and the integration domain C for $Z_s \in \mathbb{C}^3$ are determined by the condition (2.2). Other choices of integration domains in eq. (2.58) would lead to linear combinations of six conformal blocks whose spins j_s are related by Weyl transformations (2.21). Notice that the condition (2.2) of analyticity and normalization of conformal blocks also constrains the multiplicity functions g, g' . Applying that condition to a three-point invariant function $\mathcal{E}_g(j_1, j_2, j_3 | \vec{z}_1, \vec{z}_2, Z_s)$ leads to the conditions

$$g(1) = 2^{\frac{1}{3}(r+2s-2r_1-s_1-2r_2-s_2)} \quad , \quad g(\theta) \text{ is analytic near } \theta = 1 \quad . \quad (2.59)$$

We will now focus on a large c four-point block $\mathcal{F}_{j_s}(j_i | z_i)$ such that the fields with numbers 2, 3 are semi-degenerate of the first kind, so that the multiplicity functions g, g' disappear and the components r_2, r_3 of the spins j_2, j_3 vanish. The assumptions $Z_1 = \vec{z}_1$ and $Z_2 = \vec{z}_2$ lead to simplifications in the combinations ρ_{12} (2.35) and χ_{123} (2.37),

$$\rho_{12}(\vec{z}_1, \vec{z}_2) = \frac{1}{2} z_{12}^2 \quad , \quad (2.60)$$

$$\chi_{123}(\vec{z}_1, \vec{z}_2, Z_3) = \frac{1}{2} z_{12} (z_1 z_2 - y_3 z_1 - y_3 z_2 + 2x_3 y_3 - 2w_3) \quad , \quad (2.61)$$

so that the relevant three-point invariants eq. (2.43) become

$$\begin{aligned} \mathcal{E}(j_1, j_2, j_3 | \vec{z}_1, \vec{z}_2, Z_3) &= 2^{-J-r_3+s_1+s_2} z_{12}^{\Delta_3-\Delta_1-\Delta_2} \\ &\times (z_1 z_2 - y_3 z_1 - y_3 z_2 + 2x_3 y_3 - 2w_3)^{-J} \left(y_3 x_3 - y_3 z_1 - w_3 + \frac{1}{2} z_1^2 \right)^{J-s_3} \\ &\times \left(w_3 - x_3 z_2 + \frac{1}{2} z_2^2 \right)^{-J-r_3+s_1} \left(w_3 - x_3 z_1 + \frac{1}{2} z_1^2 \right)^{J-s_1} \quad , \quad (r_2 = 0) \quad . \quad (2.62) \end{aligned}$$

where the conformal dimensions Δ_i are associated to the spins j_i as in eq. (2.52). Then the formula (2.58) implies that $z^{\Delta_1+\Delta_2} \mathcal{F}_{j_s}(j_i | 0, z, 1, \infty)$ depends on only four combinations of the six nonvanishing components of the spins j_1, j_2, j_3, j_4 , namely

$$r_1 - s_2 \quad , \quad s_1 \quad , \quad r_4 - s_3 \quad , \quad s_4 \quad . \quad (2.63)$$

It is actually convenient to use the following four combinations, where we call (r, s) the components of j_s ,

$$\begin{aligned} \alpha &= \frac{1}{3}(s_3 + s_4 + s - r_3 - r) \quad , \quad \beta = \frac{1}{3}(s_1 + s_2 - s - r_1 + r) \quad , \\ \gamma &= \alpha - s_4 + r \quad , \quad \delta = \beta - s_1 + s \quad . \end{aligned} \quad (2.64)$$

The integral in eq. (2.58) can be expanded near $z_1 = z_2$, see Appendix B. This leads to the expansion of the large c four-point block $\mathcal{F}_{j_s}(z) = \mathcal{F}_{j_s}(j_i | 0, z, 1, \infty)$ near $z = 0$,

$$\begin{aligned} \mathcal{F}_{j_s}(z) &= z^{-\Delta_{12}^s} \sum_{n,i,j=0}^{\infty} \frac{z^{2n+i+j}}{n!i!j!(r+s-1)_n} \frac{(\beta)_i(-\beta+r)_n(\gamma)_{n+i}}{(r)_{n+i}} \frac{(\alpha)_j(-\alpha+s)_n(\delta)_{n+j}}{(s)_{n+j}} \quad (2.65) \\ &= z^{-\Delta_{12}^s} \sum_{n=0}^{\infty} \frac{z^{2n}}{n!} \frac{(r-\beta)_n(\gamma)_n(s-\alpha)_n(\delta)_n}{(r)_n(s)_n(r+s-1)_n} \\ &\quad \times F(\beta, \gamma+n, r+n, z) F(\alpha, \delta+n, s+n, z) \quad , \quad (2.66) \end{aligned}$$

where the notation $(t)_n$ was defined in eq. (2.14). The second form of this expression is obtained by performing the sums over i and j , and can be helpful in numerical computations. A similar

expression can be obtained if the fields with numbers 2, 3 are semi-degenerate of the second kind (instead of the first kind), by exchanging the two components r and s of each spin.

There are five special cases where the block $\mathcal{F}_{j_s}(z)$ (2.65) reduces to a hypergeometric function:

1. Case $\alpha = \beta = 0$: In this case $(\beta)_i = \delta_{i0}$ and $(\alpha)_j = \delta_{j0}$, so that

$$\mathcal{F}_{j_s}(z) = z^{-\Delta_{12}^s} F(\gamma, \delta, r + s - 1, z^2). \quad (2.67)$$

This shows that blocks can have a singularity at $z = -1$, in addition to the physical singularities at $z = 0, 1, \infty$ which appear when two of the fields at z_1, z_2, z_3, z_4 come together.

2. Case $\gamma = 0$: In this case $(\gamma)_{n+i} = \delta_{n+i,0}$ and we have

$$\mathcal{F}_{j_s}(z) = z^{-\Delta_{12}^s} F(\alpha, \delta, s, z). \quad (2.68)$$

3. Case $\delta = 0$: In this case $(\delta)_{n+j} = \delta_{n+j,0}$ and we have

$$\mathcal{F}_{j_s}(z) = z^{-\Delta_{12}^s} F(\beta, \gamma, r, z). \quad (2.69)$$

4. Case $\alpha = s$: In this case $(s - \alpha)_n = \delta_{n,0}$ and we have

$$\mathcal{F}_{j_s}(z) = z^{-\Delta_{12}^s} (1 - z)^{-\delta} F(\beta, \gamma, r, z). \quad (2.70)$$

5. Case $\beta = r$: In this case $(r - \beta)_n = \delta_{n,0}$ and we have

$$\mathcal{F}_{j_s}(z) = z^{-\Delta_{12}^s} (1 - z)^{-\gamma} F(\alpha, \delta, s, z). \quad (2.71)$$

Further properties of the block $\mathcal{F}_{j_s}(z) = \mathcal{F}_{j_s}(j_i|0, z, 1, \infty)$ (2.65) are studied in Appendix C.

3. Conclusion

3.1 Comparison with the combinatorial expansion

A combinatorial expansion is proposed in [11] for four-point conformal blocks of the W_3 algebras, such that two fields are semi-degenerate and therefore no infinite fusion multiplicities are present. If the fields with numbers 2, 3 have momenta along the first fundamental weight h_1 , that is $\begin{cases} \alpha_2 = r_2 h_1 \\ \alpha_3 = r_3 h_1 \end{cases}$, then the four-point block $\mathcal{G}_{\alpha_s}(c|\alpha_i|0, z, 1, \infty)$ reads

$$\mathcal{G}_{\alpha_s}(c|\alpha_i|0, z, 1, \infty) = (1 - z)^{r_3(\frac{1}{3}r_2 - q)} z^{-\Delta_{12}^s} \sum_{\vec{\lambda}} z^{|\vec{\lambda}|} \frac{F_{\vec{0}, \vec{\lambda}}^-(\alpha_4^\omega, \alpha_s, r_3) F_{\vec{\lambda}, \vec{0}}^-(\alpha_s, \alpha_1, r_2)}{F_{\vec{\lambda}, \vec{\lambda}}^-(\alpha_s, \alpha_s, 0)}. \quad (3.1)$$

where the function $F_{\vec{\lambda}, \vec{\lambda}'}^-(\alpha, \alpha', r)$ is defined as

$$F_{\vec{\lambda}, \vec{\lambda}'}^-(\alpha, \alpha', r) = \prod_{i,j=1}^3 \left(\prod_{s \in \lambda'_i} \left[(h_j, \alpha - Q) - (h_i, \alpha' - Q) - \frac{1}{3}r - b l_{\lambda_j}(s) + b^{-1}(a_{\lambda'_i}(s) + 1) \right] \right. \\ \left. \times \prod_{s \in \lambda_j} \left[(h_j, \alpha - Q) - (h_i, \alpha' - Q) - \frac{1}{3}r + b(l_{\lambda'_i}(s) + 1) - b^{-1}a_{\lambda_j}(s) \right] \right) \quad (3.2)$$

Besides the " W_3 notations" Δ, α, Q, q, b introduced in Subsection 2.3 and the definition (2.23) of the Dynkin diagram automorphism $j \rightarrow j^\omega$, these formulas use notations for Young diagrams which we now review. (See [2] for more details.) The sum in eq. (3.1) is over triples $\vec{\lambda} = (\lambda_1, \lambda_2, \lambda_3)$ of Young diagrams. Each diagram is a collection of boxes, and each box s has an arm length $a_\lambda(s)$ and leg length $l_\lambda(s)$ relative to a diagram λ , which are positive if $s \in \lambda$. The triple $\vec{0} = (0, 0, 0)$ is the set of three empty diagrams.

We have checked that the large c limit (2.51) of the block (3.1) agrees with the independently derived prediction eq. (2.65) up to the order z^5 , modulo the exchange of the components r and s of the spins due to the use of different kinds of semi-degenerate fields. The agreement is rather non-trivial, because individual terms of the sum over Young diagrams can have spurious poles (as functions of the components of α_s), and these spurious poles cancel when the sum is performed.

3.2 Concluding remarks

In this article, we have given an integral formula (2.58) for the large c limits of arbitrary W_3 conformal blocks on the sphere. This formula is a special case of an sl_3 -invariant function, where the isospin variables take special values determined by the positions of the fields. This result implies that the large c conformal block depends nontrivially on only eight combinations of the ten components of the spins $(j_s, j_1, j_2, j_3, j_4)$, in the same way as the large c Virasoro conformal block (2.13) depends nontrivially on only three combinations of the five conformal dimensions.

We have thus shown how to take infinite fusion multiplicities into account in this limit. This might be helpful for solving the problem of the infinite fusion multiplicities in general, and allow us to deal with arbitrary conformal blocks in conformal field theories with W_N symmetries. So far, we know combinatorial expansions only for blocks with no fusion multiplicities. For fusion multiplicities to be absent, it is necessary to restrict the momenta of the fields, such that they are all almost fully degenerate except two of them. (See also [11].) While we can deal with large c blocks in general, imposing such restrictions brings important simplifications. Thus we could study the detailed properties a certain class of W_3 large c four-point conformal blocks with two semi-degenerate fields, and in particular derive their series expansion (2.65). We found that, for generic values of the parameters, such blocks have a singularity at $z = -1$, in addition to the expected singularities at $z = 0, 1, \infty$. We believe that the singularity at $z = -1$ is absent for non-infinite values of the central charge c . It would be interesting to confirm this expectation, and to understand how the singularity disappears for finite values of c .

We expect that our results can be generalized to sl_N -invariant functions and W_N conformal blocks in the large c limit. In particular, we expect the large c limit of a W_N four-point conformal block with two almost fully degenerate fields to obey a differential equation of order $N!$, as we observe in the cases $N = 2$ and $N = 3$ in Appendix C.

A. Quantum mechanics of a point particle on $SL_N(\mathbb{C})$

For any integer $N \geq 2$, the algebra W_N is the symmetry algebra of a CFT called sl_N conformal Toda theory. In the case $N = 2$ for example, the Virasoro (W_2) algebra is the symmetry algebra of Liouville (sl_2 conformal Toda) theory. The functional integral representation of the correlation functions of sl_N conformal Toda theory can be used for studying their large c limits, which turn

out to be correlation functions of the quantum mechanics of a point particle on $SL_N(\mathbb{C})$. (See for instance [8].) This will provide some justification for our identification of large c conformal blocks with sl_N -invariant functions. We will start with the case of the point particle on $SL_2(\mathbb{C})$, before dealing with the technically more complicated case of $SL_3(\mathbb{C})$.

A.1 Point particle on $SL_2(\mathbb{C})$

Let us call $V_\Delta(z, \bar{z})$ a primary vertex operator of Liouville theory. This depends on the complex coordinates (z, \bar{z}) of a point on the complex plane, and on the conformal dimension Δ of the corresponding Virasoro representation. The functional integral representation of a correlation function $\langle \prod_{i=1}^n V_{\Delta_i}(z_i, \bar{z}_i) \rangle$ of n such vertex operators leads to the large c limit

$$\lim_{c \rightarrow \infty} \left\langle \prod_{i=1}^n V_{\Delta_i}(z_i, \bar{z}_i) \right\rangle = \int_{SL_2(\mathbb{C})} dg \prod_{i=1}^n \Phi_{z_i, \bar{z}_i}^{\Delta_i}(g), \quad (\text{A.1})$$

where $\Phi_{z, \bar{z}}^\Delta(g)$ is the classical limit of the field $V_\Delta(z, \bar{z})$, evaluated on a solution of the Liouville equation labelled by $g \in SL_2(\mathbb{C})$,

$$\Phi_{z, \bar{z}}^\Delta(g) = [v_z g v_{\bar{z}}^T]^{-2\Delta}, \quad v_z = (1, z). \quad (\text{A.2})$$

The functions $\Phi_{z, \bar{z}}^\Delta(g)$ and v_z have a simple behaviour under sl_2 transformations of the matrix g :

$$v_z t^a = D_{(-\frac{1}{2}, z)}(t^a) v_z, \quad \Phi_{z, \bar{z}}^\Delta((1 + \epsilon t^a)g) = (1 + \epsilon D_{(\Delta, z)}(t^a)) \Phi_{z, \bar{z}}^\Delta(g) + O(\epsilon^2), \quad (\text{A.3})$$

where the differential operators $D_{(\Delta, z)}(t^a)$ were introduced in eq. (2.5), and the generators $(t^a) = (L_1, L_0, L_{-1})$ of sl_2 are realized as the matrices

$$L_1 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad L_0 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad L_{-1} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}. \quad (\text{A.4})$$

As a result, $\Phi_{z, \bar{z}}^\Delta(g)$ is an eigenvector of the sl_2 -invariant Laplacian on $SL_2(\mathbb{C})$,

$$g_{ab} D_{(\Delta, z)}(t^a) D_{(\Delta, z)}(t^b) \Phi_{z, \bar{z}}^\Delta(g) = C_2(\Delta) \Phi_{z, \bar{z}}^\Delta(g), \quad (\text{A.5})$$

where we defined

$$g^{ab} = \frac{1}{2} \text{Tr } t^a t^b, \quad C_2(\Delta) = \Delta(\Delta - 1). \quad (\text{A.6})$$

The functions $\Phi_{z, \bar{z}}^\Delta(g)$ provide a basis of functions of $SL_2(\mathbb{C})$, whose completeness can be expressed as the decomposition of the Dirac delta function $\delta(g, g')$,

$$\delta(g, g') = \int_{\frac{1}{2} + i\mathbb{R}} d\Delta \int_{\mathbb{C}} d^{(2)}z \Phi_{z, \bar{z}}^\Delta(g) \Phi_{z, \bar{z}}^{\Delta^*}(g'), \quad (\text{A.7})$$

where the reflected dimension $\Delta^* = 1 - \Delta$ was defined in eq. (2.4). The equivalence between representations with labels Δ and Δ^* manifests itself in the relation $C_2(\Delta^*) = C_2(\Delta)$, and in the reflection relation

$$\Phi_{z, \bar{z}}^\Delta(g) = R(\Delta) \int_{\mathbb{C}} d^{(2)}z' |\mathcal{E}(\Delta, \Delta | z, z')|^2 \Phi_{z', \bar{z}'}^{\Delta^*}(g), \quad (\text{A.8})$$

where $R(\Delta)$ is a reflection coefficient, and the two-point invariant $\mathcal{E}(\Delta, \Delta|z, z')$ was given in eq. (2.7).

Let us go back to Liouville theory, of which $SL_2(\mathbb{C})$ quantum mechanics is the large c limit. An important axiom of conformal field theory is the assumption that a four-point function can be decomposed into four-point conformal blocks,

$$\left\langle \prod_{i=1}^4 V_{\Delta_i}(z_i, \bar{z}_i) \right\rangle = \int d\Delta_s C(c|\Delta_1, \Delta_2, \Delta_s) C(c|\Delta_s, \Delta_3, \Delta_4) |\mathcal{G}_{\Delta_s}(c|\Delta_i|z_i)|^2, \quad (\text{A.9})$$

where the structure constant $C(c|\Delta_1, \Delta_2, \Delta_3)$ depends on the central charge c and on the conformal dimensions Δ_i , but not on the field positions z_i . (We will not study how the c -dependent contour of integration must be manipulated in the large c limit.) We now check that our formula (2.11) for the large c four-point block $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$ is compatible with the large c limit of this axiom. To do this, we insert the identity $1 = \int_{SL_2(\mathbb{C})} dg' \delta(g, g')$ together with the formula (A.7) for $\delta(g, g')$ in the large c limit (A.1) of the four-point function,

$$\lim_{c \rightarrow \infty} \left\langle \prod_{i=1}^4 V_{\Delta_i}(z_i, \bar{z}_i) \right\rangle = \int_{\frac{1}{2} + i\mathbb{R}} d\Delta_s \int_{\mathbb{C}} d^{(2)}z_s \int_{SL_2(\mathbb{C})} dg \left(\Phi_{z_1, \bar{z}_1}^{\Delta_1} \Phi_{z_2, \bar{z}_2}^{\Delta_2} \Phi_{z_s, \bar{z}_s}^{\Delta_s} \right) (g) \int_{SL_2(\mathbb{C})} dg' \left(\Phi_{z_s, \bar{z}_s}^{\Delta_s^*} \Phi_{z_3, \bar{z}_3}^{\Delta_3} \Phi_{z_4, \bar{z}_4}^{\Delta_4} \right) (g'). \quad (\text{A.10})$$

The integrals over g and g' produce z -dependent factors proportional to the three-point invariant $\mathcal{E}(\Delta_1, \Delta_2, \Delta_3|z_1, z_2, z_3)$ (2.8), and z -independent factors which we call $B(\Delta_1, \Delta_2, \Delta_3)$,

$$\lim_{c \rightarrow \infty} \left\langle \prod_{i=1}^4 V_{\Delta_i}(z_i, \bar{z}_i) \right\rangle = \int_{\frac{1}{2} + i\mathbb{R}} d\Delta_s B(\Delta_1, \Delta_2, \Delta_s) B(\Delta_s^*, \Delta_3, \Delta_4) \times \int_{\mathbb{C}} d^{(2)}z_s |\mathcal{E}(\Delta_1, \Delta_2, \Delta_s|z_1, z_2, z_s) \mathcal{E}(\Delta_s^*, \Delta_3, \Delta_4|z_s, z_3, z_4)|^2. \quad (\text{A.11})$$

Decomposing the integral $\int_{\mathbb{C}} d^{(2)}z_s$ into a combination of contour integrals over z_s and \bar{z}_s yields a linear combination of the two terms $|\mathcal{F}_{\Delta_s}(\Delta_i|z_i)|^2$ and $|\mathcal{F}_{\Delta_s^*}(\Delta_i|z_i)|^2$ where $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$ is given by eq. (2.11). But these two terms give the same contribution to $\lim_{c \rightarrow \infty} \left\langle \prod_{i=1}^4 V_{\Delta_i}(z_i, \bar{z}_i) \right\rangle$, because the integration contour in $\int_{\frac{1}{2} + i\mathbb{R}} d\Delta_s$ is invariant under the reflection $\Delta_s \rightarrow \Delta_s^*$. Absorbing any remaining prefactors into the B -factors, we obtain

$$\lim_{c \rightarrow \infty} \left\langle \prod_{i=1}^4 V_{\Delta_i}(z_i, \bar{z}_i) \right\rangle = \int_{\frac{1}{2} + i\mathbb{R}} d\Delta_s B(\Delta_1, \Delta_2, \Delta_s) B(\Delta_s^*, \Delta_3, \Delta_4) |\mathcal{F}_{\Delta_s}(\Delta_i|z_i)|^2. \quad (\text{A.12})$$

This formula can be interpreted as the large c limit of the decomposition (A.9) of a four-point function into four-point conformal blocks, provided we have $B(\Delta_1, \Delta_2, \Delta_3) = \lim_{c \rightarrow \infty} C(c|\Delta_1, \Delta_2, \Delta_3)$. This provides a justification for the formula (2.11) for $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$.

A.2 Point particle on $SL_3(\mathbb{C})$

A basis of functions on $SL_3(\mathbb{C})$ can be defined as

$$\Phi_{Z,\bar{Z}}^j(g) = [u_Z P g^{-1T} P u_{\bar{Z}}^T]^{-r} [v_Z g v_{\bar{Z}}^T]^{-s}, \quad \begin{cases} u_Z = (w, -x, 1) \\ v_Z = (xy - w, -y, 1) \end{cases}, \quad P = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad (\text{A.13})$$

where we recall that $Z = (w, x, y)$ is a three-component isospin vector, and that the components (r, s) of the spin j are defined in eq. (2.20). The vectors u_Z and v_Z are such that

$$u_Z \omega(t^a) = D_{(-h_1, Z)}(t^a) u_Z, \quad v_Z t^a = D_{(h_3, Z)}(t^a) v_Z, \quad (\text{A.14})$$

where the differential operators $D_{(j, Z)}(t^a)$ are defined in eqs. (2.24)-(2.31) and the fundamental weights h_i in eq. (2.19), the sl_3 generators t^a are represented as the matrices

$$h^1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad h^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad (\text{A.15})$$

$$e^1 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad e^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad e^3 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (\text{A.16})$$

$$f^1 = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad f^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad f^3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad (\text{A.17})$$

and the action of the Dynkin diagram automorphism ω on such matrices is

$$\omega(t^a) = -P(t^a)^T P. \quad (\text{A.18})$$

It follows that the function $\Phi_{Z,\bar{Z}}^j(g)$ behaves under sl_3 transformation as

$$\Phi_{Z,\bar{Z}}^j((1 + \epsilon t^a)g) = (1 + \epsilon D_{(j, Z)}(t^a)) \Phi_{Z,\bar{Z}}^j(g) + O(\epsilon^2). \quad (\text{A.19})$$

As a result, $\Phi_{Z,\bar{Z}}^j(g)$ is an eigenvector of the quadratic (Laplacian) and cubic invariant differential operators on $SL_3(\mathbb{C})$, with the respective eigenvalues

$$C_2(j) = (j, j + 2e_1 + 2e_2) = \frac{2}{3}(r^2 + s^2 + rs) - 2r - 2s, \quad (\text{A.20})$$

$$C_3(j) = -6 \prod_{i=1}^3 (h_i, j + e_1 + e_2) = \frac{2}{9}(r - s)(2r + s - 3)(2s + r - 3). \quad (\text{A.21})$$

These Casimir numbers can be derived by computing sl_3 -invariant combinations of the differential operators $D_{(j, Z)}(t^a)$, using the covariant tensors

$$g^{ab} = \text{Tr } t^a t^b, \quad d^{abc} = \text{Tr } (t^a t^b t^c + t^a t^c t^b). \quad (\text{A.22})$$

Then we have

$$g_{ab} D_{(j, Z)}(t^a) D_{(j, Z)}(t^b) \Phi_{Z,\bar{Z}}^j(g) = C_2(j) \Phi_{Z,\bar{Z}}^j(g) \quad (\text{A.23})$$

$$d_{abc} D_{(j, Z)}(t^a) D_{(j, Z)}(t^b) D_{(j, Z)}(t^c) \Phi_{Z,\bar{Z}}^j(g) = C_3(j) \Phi_{Z,\bar{Z}}^j(g). \quad (\text{A.24})$$

The Casimir numbers $C_2(j)$ and $C_3(j)$ are invariant under the six Weyl reflections (2.21), which is a manifestation of the equivalence of two representations whenever their spins are related by a

reflection. At the level of the function $\Phi_{Z,\bar{Z}}^j(g)$, this equivalence manifests itself as a relation which we now write in the case of the maximal reflection $j \rightarrow j^*$,

$$\Phi_{Z,\bar{Z}}^j(g) = R(j) \int dZ' d\bar{Z}' |\mathcal{E}(j, j^\omega | Z, Z')|^2 \Phi_{Z',\bar{Z}'}^{j^*}(g), \quad (\text{A.25})$$

where $R(j)$ is a reflection coefficient, and the two-point invariant $\mathcal{E}(j, j^\omega | Z, Z')$ was given in eq. (2.41). This generalizes the $SL_2(\mathbb{C})$ reflection relation eq. (A.8).

Now, the function $\Phi_{Z,\bar{Z}}^j(g)$ simplifies if either $r = 0$ or $s = 0$, and then it obeys the differential equations,

$$d_Z^{(1)} \Phi_{Z,\bar{Z}}^{(0,s)}(g) = d_{\bar{Z}}^{(1)} \Phi_{Z,\bar{Z}}^{(0,s)}(g) = 0 \quad , \quad d_Z^{(2)} \Phi_{Z,\bar{Z}}^{(r,0)}(g) = d_{\bar{Z}}^{(2)} \Phi_{Z,\bar{Z}}^{(r,0)}(g) = 0, \quad (\text{A.26})$$

where the operators $d_Z^{(1)}$ and $d_{\bar{Z}}^{(2)}$ were defined in eq. (2.34). This is a consequence of the vectors u_Z and v_Z obeying $d_Z^{(2)} u_Z = d_{\bar{Z}}^{(1)} v_Z = 0$, and this justifies our definitions of $d_Z^{(1)}$ and $d_{\bar{Z}}^{(2)}$. Notice that these operators obey the remarkable property

$$d_Z^{(k)} D_{(0,Z)}(t^a) = D_{(-e_k,Z)}(t^a) d_Z^{(k)}, \quad (k = 1, 2). \quad (\text{A.27})$$

(We recall that e_k are the simple roots of sl_3 ; for instance the coordinates of the spin $j = -e_1$ are $(r, s) = (2, -1)$.)

Finally, we can write the analog in sl_3 conformal Toda theory of the expression (A.1) for large c Liouville theory correlation functions, by using the functions $\Phi_{Z,\bar{Z}}^j(g)$ on $SL_3(\mathbb{C})$. The isospin variable Z must be specialized as $Z = \bar{z} = (\frac{1}{2}z^2, z, z)$ (as in eq. (2.54)), and we must remember the relation (2.51) between W_3 momenta α and sl_3 spins j . Calling $V_\alpha(z, \bar{z})$ the vertex operator of sl_3 conformal Toda theory with the momentum α , we have [8]

$$\lim_{c \rightarrow \infty} \left\langle \prod_{i=1}^n V_{\alpha_i}(z_i, \bar{z}_i) \right\rangle = \int_{SL_3(\mathbb{C})} dg \prod_{i=1}^n \Phi_{\bar{z}_i, \bar{z}_i}^{j_i}(g). \quad (\text{A.28})$$

B. Derivation of the expansion of a four-point block

Here we derive the expansion eq. (2.65) of the large c four-point block $\mathcal{F}_{j_s}(z) = \mathcal{F}_{j_s}(j_i | 0, z, 1, \infty)$, starting from the integral formula eq. (2.58). We propose two possible ways to perform the calculation. The first way is more straightforward, but it leads to a formula (B.4) which is less symmetric than eq. (2.65) and has spurious poles. The second way is less straightforward as it starts with a six-dimensional (instead of three-dimensional) integral, but the symmetry $(\alpha, \delta, s) \leftrightarrow (\beta, \gamma, r)$ of eq. (2.65) is manifest throughout the calculation. (We recall that r and s are the components of j_s , and that the combinations of spin components $\alpha, \beta, \gamma, \delta$ are defined in eq. (2.64).)

B.1 First way

After performing a few change of variables, the integral formula (2.58) (together with eq. (2.62)) leads to

$$\begin{aligned} \mathcal{F}_{j_s}(z) &= z^{-\Delta_{12}^s} e^{i\pi(\beta-\delta+s)} \frac{\Gamma(r)\Gamma(s)\Gamma(r+s-1)}{\Gamma(\beta+s-1)\Gamma(\delta)\Gamma(-\delta+r+s-1)\Gamma(r-\beta)} \int_{C_0} dw dx dy \\ & w^{\delta-s} (xy-w)^{\beta+s-2} (y+w-xy)^{-\beta} (w-x+1)^{-\delta+r+s-2} (1-yz)^{-\alpha} (1-xz+wz^2)^{-\gamma}, \end{aligned} \quad (\text{B.1})$$

where the condition (2.2) has been used for determining the prefactor and the integration contour

$$C_0 : \quad y \in \left(\frac{w}{x}, \frac{w}{x-1}\right) \quad \text{then} \quad w \in (x-1, 0) \quad \text{then} \quad x \in (0, 1). \quad (\text{B.2})$$

Let us denote the integral (B.1) as $\mathcal{F}_{j_s}(z) = \langle (1-yz)^{-\alpha}(1-xz+wz^2)^{-\gamma} \rangle$, and expand the integrand in powers of z . This reduces the problem to computing expectation values of monomials $w^n x^k y^m$, and we find

$$\langle w^n x^k y^m \rangle = z^{-\Delta_{12}^s} (-1)^n \frac{(\delta)_{m+n} (r-\beta)_n}{(r+s-1)_{m+n}} \sum_{\ell=0}^m C_m^\ell \frac{(\beta-\ell)_k}{(s)_\ell (r)_{k+n-\ell}}, \quad (\text{B.3})$$

where the notation $(t)_n$ was introduced in eq. (2.14), and we write $C_m^\ell = \frac{m!}{\ell!(m-\ell)!}$. This leads to

$$\mathcal{F}_{j_s}(z) = z^{-\Delta_{12}^s} \sum_{q,m=0}^{\infty} \frac{(\gamma)_q (\alpha)_m}{q! m!} \sum_{i=0}^q \sum_{\ell=0}^m z^{q+m+i} C_q^i C_m^\ell \frac{(r-\beta)_i (\beta-\ell)_{q-i} (\delta)_{m+i}}{(s)_\ell (r)_{q-\ell} (r+s-1)_{m+i}}. \quad (\text{B.4})$$

This can be seen to agree with eq. (2.65) by an automatic calculation of the first few orders in z . This agreement is non-trivial, as it involves the cancellation of the spurious poles which are present in eq. (B.4).

B.2 Second way

We start again with eq. (2.58). We first want to make this formula more symmetric, at the expense of replacing the three-dimensional integral over Z_s with a six-dimensional integral. This is done by using a reflection relation for conformal blocks, which is the holomorphic half of the reflection relation eq. (A.25) for functions on $SL_3(\mathbb{C})$. This leads to

$$\begin{aligned} \mathcal{F}_{j_s}(j_i|z_i) &= \mathcal{N}_1 \int_{C_1} dZ_s dZ'_s \mathcal{E}(j_1, j_2, j_s | \vec{z}_1, \vec{z}_2, Z_s) \mathcal{E}(j_s^{*\omega}, j_s^* | Z_s, Z'_s) \mathcal{E}(j_s^\omega, j_3, j_4 | Z'_s, \vec{z}_3, \vec{z}_4) \quad (\text{B.5}) \\ &= \mathcal{N}_1 \rho_{34}^{s-\alpha-r_4} \rho_{12}^{r-\beta-r_1} \int_{C_1} dZ_s dZ'_s \chi_{34s}^{-\alpha} \rho_{s4}^{\alpha-s} \rho_{4s}^{\gamma-r} \rho_{3s'}^{-\gamma} \rho_{ss'}^{s-2} \rho_{s's}^{r-2} \chi_{12s'}^{-\beta} \rho_{s'1}^{\beta-r} \rho_{1s'}^{\delta-s} \rho_{2s'}^{\delta} \quad (\text{B.6}) \end{aligned}$$

The notations come from Subsection 2.2, except the definitions of \vec{z} (2.54) and of $\alpha, \beta, \gamma, \delta$ (2.64). The contour C_1 and normalization factor \mathcal{N}_1 are supposed to be determined by the condition (2.2). We will not keep track of contours and normalizations explicitly; instead we will call C_i and \mathcal{N}_i the various contours and normalizations which appear in the calculation.

Out of the six integrals $\int dZ_s dZ'_s$ in eq. (B.6), the two integrals over y_s and y'_s can be performed immediately using the formula $\int_C dy \prod_{i=1}^3 (a_i y - b_i)^{\alpha_i} = \mathcal{N} \prod_{i < j} (a_i b_j - a_j b_i)^{\alpha_i + \alpha_j + 1}$ (assuming $\sum_{i=1}^3 \alpha_i = -2$), where the choice of the integration contour C only affects the normalization factor \mathcal{N} and is therefore not important for us. Then, we replace the four remaining variables (w_s, x_s, w'_s, x'_s) with four new variables (w, x, w', x') , using the change of variables

$$x_s = \frac{\frac{z_4 z_{12}}{z_{24}} x + \frac{z_1 z_{34}}{z_{31}} - \frac{1}{2}(z_1 + z_4)z(w+x+1)}{\frac{z_{12}}{z_{42}} x + \frac{z_{34}}{z_{31}} - z(w+x+1)}, \quad (\text{B.7})$$

$$w_s = \frac{1}{2} \frac{\frac{z_4^2 z_{12}}{z_{42}} x + \frac{z_1^2 z_{34}}{z_{31}} - z_1 z_4 z(w+x+1)}{\frac{z_{12}}{z_{42}} x + \frac{z_{34}}{z_{31}} - z(w+x+1)}, \quad (\text{B.8})$$

and similarly for x'_s and z'_s , with the exchanges of indices $(\begin{smallmatrix} 1 \leftrightarrow 4 \\ 2 \leftrightarrow 3 \end{smallmatrix})$. We can then check global conformal invariance, and restrict our attention to $\mathcal{F}_{j_s}(z) = \mathcal{F}_{j_s}(j_i|0, z, 1, \infty)$ as in eq. (2.9),

$$\begin{aligned} \mathcal{F}_{j_s}(z) &= z^{-\Delta_{12}^s} \mathcal{N}_2 \int_{C_2} dx dx' dw' (w' - wx' + 1 - xx')^{\alpha-1} (w - w'x + 1 - xx')^{\beta-1} \\ &\quad \times (w' - wx')^{-\alpha+s-1} (w - w'x)^{-\beta+r-1} (1 - z(w+1))^{-\gamma} (1 - z(w'+1))^{-\delta}. \end{aligned} \quad (\text{B.9})$$

We now perform another change of integration variables, introducing new variables σ, τ which this time mix the unprimed (x, w) and primed (x', w') variables:

$$\sigma = w' - wx' \quad , \quad \tau = w - w'x. \quad (\text{B.10})$$

We also introduce the notation $\omega = 1 - xx'$ for convenience, and we obtain

$$\begin{aligned} \mathcal{F}_{j_s}(z) &= z^{-\Delta_{12}^s} \mathcal{N}_3 \int_{C_3} dx dx' d\sigma d\tau \omega^{-1} (\sigma + \omega)^{\alpha-1} (\tau + \omega)^{\beta-1} \sigma^{-\alpha+s-1} \tau^{-\beta+r-1} \\ &\quad \times \left(1 - \frac{z}{\omega}(x\sigma + (\tau + \omega))\right)^{-\gamma} \left(1 - \frac{z}{\omega}(x'\tau + (\sigma + \omega))\right)^{-\delta}. \end{aligned} \quad (\text{B.11})$$

We expand the last two factors, for instance

$$\left(1 - \frac{z}{\omega}(x\sigma + (\tau + \omega))\right)^{-\gamma} = \sum_{n,i=0}^{\infty} \frac{(\gamma)_{n+i}}{n!i!} \left(\frac{z}{\omega}\right)^{n+i} (x\sigma)^n (\tau + \omega)^i, \quad (\text{B.12})$$

where the notation $(t)_n$ was introduced in eq. (2.14). Then we integrate over $\sigma, \tau \in (0, \infty)$, and then over $x, x' \in \mathbb{C}$ such that $\bar{x}' = -x$ using $\int_{\bar{x}' = -x} dx dx' (1 - xx')^{t-2} x^n x'^{n'} = \mathcal{N} \delta_{n,n'} \frac{n!}{(t)_n}$, where \mathcal{N} is an n -independent normalization factor. This directly leads to eq. (2.65).

C. Differential equation and critical exponents for large c conformal blocks

C.1 Case of Virasoro conformal blocks

The large c limit $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$ of a Virasoro four-point block obeys a second-order hypergeometric differential equation, as follows from the integral expression (2.11) for $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$. This large c block is indeed a function of four variables z_i , which obeys the three equations (2.6) of global conformal invariance. In addition, the three-point invariant $\mathcal{E}(\Delta_1, \Delta_2, \Delta_s|z_1, z_2, z_s)$ which appears in the integral expression (2.11) also obeys these equations, and together with the relation (A.5) for the quadratic Casimir $C_2(\Delta)$ this implies

$$g_{ab}(D_{(\Delta_1, z_1)} + D_{(\Delta_2, z_2)})(t^a)(D_{(\Delta_1, z_1)} + D_{(\Delta_2, z_2)})(t^b)\mathcal{F}_{\Delta_s}(\Delta_i|z_i) = C_2(\Delta_s)\mathcal{F}_{\Delta_s}(\Delta_i|z_i) \quad (\text{C.1})$$

where the differential operators $D_{(\Delta, z)}(t^a)$ are defined in eq. (2.5). Thus $\mathcal{F}_{\Delta_s}(\Delta_i|z_i)$ obeys four differential equations, and $\mathcal{F}_{\Delta_s}(\Delta_i|0, z, 1, \infty)$ obeys one differential equation, which turns out to be the hypergeometric equation, whose solution (subject to the condition (2.2)) we wrote in eq. (2.13).

The critical exponents of the hypergeometric equation are known, and we deduce the critical exponents λ_i of $z^{\Delta_1+\Delta_2}\mathcal{F}_{\Delta_s}(\Delta_i|0, z, 1, \infty)$ at the three singularities $z = 0, 1, \infty$:

<i>exponent</i>	0	1	∞	
λ_1	Δ_s	0	$\Delta_1 - \Delta_2$	(C.2)
λ_2	Δ_s^*	$\Delta_1 + \Delta_4 - \Delta_2 - \Delta_3$	$\Delta_4 - \Delta_3$	

The number $\lambda_2^{(0)} = \Delta_s^* = 1 - \Delta_s$ is not really a critical exponent of the block itself, rather it corresponds to another block with another s -channel dimension Δ_s^* . Notice that the exponents at 1 and ∞ are Δ_s -independent; conformal blocks can be expected to behave so simply at these singularities only in the large c limit. The transformations of the hypergeometric functions can be used to rewrite $\mathcal{F}_{\Delta_s}(\Delta_i|0, z, 1, \infty)$ as a combination of two functions with simple monodromy at say $z = 1$, but these two functions are not themselves conformal blocks in another channel.

C.2 Differential equation

That our large c four-point conformal block $\mathcal{F}_{j_s}(j_i|z_i)$ (2.65) with two semi-degenerate fields obeys a differential equation follows from a simple counting of variables and equations. We consider first the corresponding sl_3 four-point invariant function $\mathcal{E}_{j_s}(j_i|Z_i)$, which depends on 12 isospin variables, namely the components of Z_1, Z_2, Z_3, Z_4 , and is such that $\mathcal{F}_{j_s}(j_i|z_i) = \mathcal{E}_{j_s}(j_i|\vec{z}_i)$ where \vec{z} is defined in eq. (2.54). There are three types of equations for $\mathcal{E}_{j_s}(j_i|Z_i)$:

1. The sl_3 symmetry condition (2.32) yields 8 equations.
2. As two fields are semi-degenerate, we have two equations $d_{Z_1}^{(1)}\mathcal{E}_{j_s}(j_i|Z_i) = d_{Z_4}^{(1)}\mathcal{E}_{j_s}(j_i|Z_i) = 0$, where $d_Z^{(1)}$ was defined in eq. (2.34).
3. The sl_3 symmetry condition for the three-point invariant $\mathcal{E}_g(j_1, j_2, j_s|Z_1, Z_2, Z_s)$ which appears in the integral formula (2.49) will yield two more equations. The sl_3 symmetry condition (2.32) applied to $\mathcal{E}_g(j_1, j_2, j_s|Z_1, Z_2, Z_s)$ indeed implies

$$g_{ab}(D_{(j_1, Z_1)} + D_{(j_2, Z_2)})(t^a)(D_{(j_1, Z_1)} + D_{(j_2, Z_2)})(t^b)\mathcal{E}_{j_s}(j_i|Z_i) = C_2(j_s)\mathcal{E}_{j_s}(j_i|Z_i) \quad (\text{C.3})$$

$$\begin{aligned} d_{abc}(D_{(j_1, Z_1)} + D_{(j_2, Z_2)})(t^a)(D_{(j_1, Z_1)} + D_{(j_2, Z_2)})(t^b)(D_{(j_1, Z_1)} + D_{(j_2, Z_2)})(t^c)\mathcal{E}_{j_s}(j_i|Z_i) \\ = -C_3(j_s)\mathcal{E}_{j_s}(j_i|Z_i), \quad (\text{C.4}) \end{aligned}$$

where the Casimir numbers $C_2(j_s)$ and $C_3(j_s)$ were defined in eqs. (A.23)-(A.24).

The function $\mathcal{E}_{j_s}(j_i|Z_i)$ of 12 variables therefore obeys 12 partial differential equations. Now the function $\mathcal{F}_{j_s}(j_i|z_i)$ can be written in terms of a function of just one variable (the cross-ratio of z_1, z_2, z_3, z_4), and this function obeys one differential equation. The order of the differential equation can be guessed to be six, the order of the Weyl group of sl_3 . This is because our differential equations (C.3) and (C.4) depend on the spin j_s through the Weyl invariants $C_2(j_s)$ and $C_3(j_s)$. Given a solution, Weyl reflections of j_s therefore provide five other solutions.

Let us explain how the differential equation for $\mathcal{F}_{j_s}(j_i|z_i)$ can be derived in principle. We will not perform the derivation to the end, as the resulting equation would be too complicated to be

useful. We will stop at the partial differential equations for $\mathcal{E}_{j_s}(j_i|Z_i)$, which imply the equation for $\mathcal{F}_{j_s}(j_i|z_i)$ and are much simpler. It is from these partial differential equations that we will derive interesting information like the critical exponents of $\mathcal{F}_{j_s}(j_i|z_i)$. To begin with, the first ten equations allow us to rewrite $\mathcal{E}_{j_s}(j_i|Z_i)$ in terms of a function of two variables $\hat{\mathcal{E}}_{j_s}(j_i|U, V)$,

$$\mathcal{E}_{j_s}(j_i|Z_i) = Q(j_i|Z_i)\hat{\mathcal{E}}_{j_s}(j_i|U, V), \quad (\text{C.5})$$

where the cross-ratios U, V are solutions of our ten equations when all spins are taken to zero,

$$U = \frac{\rho_{34} \chi_{412}}{\rho_{24} \chi_{431}}, \quad V = \frac{\rho_{21} \chi_{341}}{\rho_{31} \chi_{421}}, \quad (\text{C.6})$$

and the prefactor $Q(j_i|Z_i)$ is the product of two three-point invariants of the type (2.43) with one spin set to zero in each invariant (thereby imitating the prefactor $P(\Delta_i|z_i)$ (2.10) of sl_2 -invariant functions),

$$Q(j_i|Z_i) = \mathcal{E}(j_1, j_2, 0|Z_1, Z_2, Z_4)\mathcal{E}(0, j_3, j_4|Z_1, Z_3, Z_4), \quad (\text{C.7})$$

$$= \chi_{124}^{-j_{12}} \chi_{134}^{-j_{34}} \rho_{41}^{j_{12}+j_{34}-s_4} \rho_{14}^{j_{12}+j_{34}-s_1} \rho_{21}^{-j_{12}-r_1} \rho_{31}^{-j_{34}+s_4} \rho_{34}^{-j_{34}-r_4} \rho_{24}^{-j_{12}+s_1}, \quad (\text{C.8})$$

where we defined

$$j_{12} = (h_2, j_1 + j_2) = \frac{1}{3}(s_1 + s_2 - r_1), \quad j_{34} = (h_2, j_3 + j_4) = \frac{1}{3}(s_3 + s_4 - r_4). \quad (\text{C.9})$$

We have $Q(j_i|z_i) = P(\Delta_i|z_i)$ where $P(\Delta_i|z_i)$ was defined in eq. (2.10) and Δ_i in eq. (2.52), and together with the expression (2.9) for $\mathcal{F}_{j_s}(j_i|z_i)$ in terms of $\mathcal{F}_{j_s}(z) = \mathcal{F}_{j_s}(j_i|0, z, 1, \infty)$ this leads to

$$z^{\Delta_1+\Delta_2}\mathcal{F}_{j_s}(z) = \hat{\mathcal{E}}_{j_s}(j_i|z, z). \quad (\text{C.10})$$

The two equations (C.3) and (C.4) amount to two partial differential equations for $\hat{\mathcal{E}}_{j_s}(j_i|U, V)$, which we computed with the help of the mathematical software Sage. The equations are of the type $E_2\hat{\mathcal{E}}_{j_s}(j_i|U, V) = E_3\hat{\mathcal{E}}_{j_s}(j_i|U, V) = 0$, where the differential operators E_2 and E_3 are

$$\begin{aligned} E_2 = & (1-U)D_U^2 + (1-V)D_V^2 - D_UD_V - (1+(j_{12}-s_1)U)D_U - (1+(j_{34}-s_4)V)D_V \\ & + U(j_{12}-s_1+D_U)(-j_{34}+D_V) + V(j_{34}-s_4+D_V)(-j_{12}+D_U) \\ & - U(j_{12}-s_1+D_U)V(j_{34}-s_4+D_V) - \frac{1}{2}C_2(j_s), \quad (\text{C.11}) \end{aligned}$$

$$\begin{aligned} E_3 = & [(1-U)D_U^2 - ((j_{12}+j_{34}-s_1)U+1)D_U - j_{34}(j_{12}-s_1)U] \\ & \times [1+(j_{34}-s_4)V - (1-V)D_V] \\ & - [(1-V)D_V^2 - ((j_{12}+j_{34}-s_4)V+1)D_V - j_{12}(j_{34}-s_4)V] \\ & \times [1+(j_{12}-s_1)U - (1-U)D_U] - \frac{1}{6}C_3(j_s), \quad (\text{C.12}) \end{aligned}$$

where we defined $D_U = U\frac{\partial}{\partial U}$ and $D_V = V\frac{\partial}{\partial V}$.

Let us sketch how a sixth-order differential equation for $\hat{\mathcal{E}}_{j_s}(j_i|z, z)$ is obtained from the two partial differential equations E_2 and E_3 for $\hat{\mathcal{E}}_{j_s}(j_i|U, V)$. We cannot directly set $U = V$ in E_2 and E_3 , because these differential operators do not keep the line $\{U = V\}$ invariant. To cure this

problem, we take linear combinations of E_2 and E_3 with differential operators as coefficients, so as to eliminate $D_U - D_V$ while keeping the derivative $D_U + D_V$ along $\{U = V\}$. This yields a differential operator of the type $E_6 = \sum_{i=0}^6 c_i(U, V)(D_U + D_V)^i$ such that $E_6 \hat{\mathcal{E}}_{j_s}(j_i|U, V) = 0$, and we thus have $\left[\sum_{i=0}^6 c_i(z, z)(2z \frac{\partial}{\partial z})^i \right] \mathcal{F}_{j_s}(j_i|z) = 0$.

The resulting differential equation is however too complicated to be useful. We were able to compute it explicitly (with the help of a computer) only in special cases when some parameters j_i, j_s vanish. Even so, the equation is rather complicated, and we do not display it. We will however discuss its singularities and the corresponding critical exponents. Knowing the critical exponents at a given singularity is equivalent to knowing the leading term of the differential equation E_6 near that singularity. To derive this, the algorithm for obtaining the differential equation E_6 from E_2 and E_3 can be applied to the first few leading terms of E_2, E_3 near the singularity. (Keeping one term of each equation is in general not enough, except at the singularity $z = 0$ as we shall see.)

The differential equation can also be used for computing the expansion of a block near a singularity. In the special case when $s_1 = s_4 = s_2 - r_1 = s_3 - r_4 = 0$, we have checked the expansion (2.65) of $\mathcal{F}_{j_s}(z)$ up to the order z^4 using the differential equation.

C.3 Critical exponents

A four-point correlation function $\langle \prod_{i=1}^4 V_{\alpha_i}(z_i) \rangle$ in sl_3 conformal Toda theory (or actually in any conformal field theory) is expected to have singularities at $z_i = z_j$, which in terms of the cross-ratio amounts to $z = 0, 1, \infty$. A conformal block like $\mathcal{G}_{g, g' | \alpha_s}(c | \alpha_i | z_i)$, and its large c limit $\mathcal{F}_{g, g' | j_s}(j_i | z_i)$, is therefore also expected to be singular at these points. However, nothing in principle excludes the existence of extra singularities in conformal blocks, and in the case when two fields are semi-degenerate, we will indeed find that $\mathcal{F}_{j_s}(j_i | z_i)$ has an unexpected singularity at $z = -1$, as we already noticed in a special case (2.67).

While it is not clear to us why this singularity appears, we can at least explain why the point $z = -1$ is special. The set $\{0, 1, \infty\}$ of the physical singularities is invariant under a set of six $PSL_2(\mathbb{Z})$ transformations $z \rightarrow (z, 1 - z, \frac{1}{z}, \frac{1}{1-z}, \frac{z}{z-1}, 1 - \frac{1}{z})$. But in our correlation functions the fields 1 and 4 are semi-degenerate, and the only nontrivial transformation which does not mix them with the other fields is $z \rightarrow \frac{1}{z}$. Then the point $z = -1$ is characterized as the nontrivial fixed point of that transformation. Notice that this argument is specific neither to s -channel conformal blocks (as opposed to blocks in other channels or to correlation functions), nor to the large c limit (as opposed to generic values of c).

But let us first comment on the singularity at $z = 0$. In the limit $U, V \rightarrow 0$, the partial differential equations E_2 (C.11) and E_3 (C.12) for $\hat{\mathcal{E}}_{j_s}(j_i|U, V)$ become

$$E_2 \underset{U, V \rightarrow 0}{\sim} D_U^2 - D_U + D_V^2 - D_V - D_U D_V - \frac{1}{2} C_2(j_s), \quad (\text{C.13})$$

$$E_3 \underset{U, V \rightarrow 0}{\sim} (D_U - 1)(D_V - 1)(D_V - D_U) - \frac{1}{6} C_3(j_s). \quad (\text{C.14})$$

Let look for solutions of the type $\hat{\mathcal{E}}_{j_s}(j_i|U, V) = U^\mu V^\nu (1 + O(U) + O(V))$ for some exponents (μ, ν) . Using the expressions (A.20) and (A.21) for $C_2(j_s)$ and $C_3(j_s)$ respectively, we find six solutions which correspond to the pairs (μ, ν) such that $j_s = -\nu e_1 - \mu e_2$ up to Weyl reflections. Using eq. (C.10), we find $z^{\Delta_1 + \Delta_2} \mathcal{F}_{j_s}(z) = z^\lambda (1 + O(z))$ with $\lambda = \mu + \nu = \Delta_s = r + s$ up to

Weyl reflections, where r, s are the components of j_s . Therefore, one of the critical exponents of $z^{\Delta_1+\Delta_2}\mathcal{F}_{j_s}(z)$ at $z = 0$ is the conformal dimension Δ_s . This agrees with the general behaviour of conformal blocks eq. (2.2). The other five exponents are the Weyl images of Δ_s , and they correspond to other solutions of the differential equation, which are conformal blocks with Weyl-reflected spins j_s .

It is less straightforward to compute the critical exponents of $z^{\Delta_1+\Delta_2}\mathcal{F}_{j_s}(z)$ at the other critical points $z = 0, \infty, -1$, and we present only the results, where the six exponents at a given singularity are numbered arbitrarily:

<i>exponent</i>	0	∞	1	-1
λ_1	$r + s$	$-1 - t + s_1 + s_4$	$-1 - t + s_1 + s_4$	$-1 + s_1 + s_4$
λ_2	$1 + r$	$-t + s_1 + s_4$	$-t + s_1 + s_4$	0
λ_3	$1 + s$	$r_4 + s_4 - s_3$	0	1
λ_4	$3 - r$	$r_1 + s_1 - s_2$	$-2t + s_1 + s_4$	2
λ_5	$3 - s$	$t + r_1 - s_2$	$-t + s_1$	3
λ_6	$4 - r - s$	$t + r_4 - s_3$	$-t + s_4$	4

(C.15)

where we used the notation $t = j_{12} + j_{34} = \frac{1}{3}(s_1 + s_2 + s_3 + s_4 - r_1 - r_4)$. We rewrite the table in terms of the combinations $\alpha, \beta, \gamma, \delta$ of spin components defined in eq. (2.64),

<i>exponent</i>	0	∞	1	-1
λ_1	$r + s$	$r + s - \gamma - \delta - 1$	$r + s - \gamma - \delta - 1$	λ
λ_2	$1 + r$	$r + s - \gamma - \delta$	$r + s - \gamma - \delta$	0
λ_3	$1 + s$	$r + s - \alpha - 2\gamma$	0	1
λ_4	$3 - r$	$r + s - \delta - 2\beta$	$r + s - \alpha - \beta - \gamma - \delta$	2
λ_5	$3 - s$	$r + \alpha - \beta - \delta$	$s - \alpha - \delta$	3
λ_6	$4 - r - s$	$s + \beta - \alpha - \gamma$	$r - \beta - \gamma$	4

(C.16)

where the nontrivial critical exponent at $z = -1$ is

$$\lambda = r + s + \alpha + \beta - \gamma - \delta - 1. \quad (\text{C.17})$$

These critical exponents of $z^{\Delta_1+\Delta_2}\mathcal{F}_{j_s}(z)$ can be compared with those of conformal blocks of the Virasoro algebra (C.2). Notice that the critical exponents at a regular point are $(0, 1, 2, 3, 4, 5)$, so the point -1 is almost regular in that only one exponent is not an integer. The sum of all exponents (with a minus sign for the exponents at ∞) is $\sum_{i=1}^6 (\lambda_i^{(0)} - \lambda_i^{(\infty)} + \lambda_i^{(1)} + \lambda_i^{(-1)}) = 21$.

These exponents were derived for generic values of the parameters r, s, r_i, s_i . There are however special cases where two or more of the exponents coincide. When such a resonance happen, say $\lambda_i^{(1)} = \lambda_j^{(1)}$ for some indices i, j , it can be that the true exponents are not $(\lambda_i^{(1)}, \lambda_i^{(1)})$ as predicted by the general result, but $(\lambda_i^{(1)}, \lambda_i^{(1)} + 1)$. In some other cases, the exponents remain $(\lambda_i^{(1)}, \lambda_i^{(1)})$, which in general indicates the appearance of logarithmic solutions of the differential equation.

In the five special cases at the end of Subsection 2.3, the blocks reduce to hypergeometric functions, and at each singularity we recover two exponents out of six. Most of the critical exponents (C.16) predicted by the differential equation can thus be confirmed in these special cases.

Finally, the existence of the surprising singularity at $z = -1$, and the value of the critical exponent λ , can be confirmed using the integral representation (B.1) of the conformal block. After some manipulations which are rather straightforward, we indeed find that the block has the asymptotic behaviour (if $\lambda < 0$)

$$\mathcal{F}_{j_s}(z) \underset{z \rightarrow -1}{\sim} \frac{\Gamma(r)\Gamma(s)\Gamma(r+s-1)\Gamma(-\lambda)}{\Gamma(\gamma)\Gamma(\delta)\Gamma(s-\alpha)\Gamma(r-\beta)} 2^\lambda (z+1)^\lambda, \quad (\text{C.18})$$

Moreover, the coefficient of $(z+1)^\lambda$ vanishes in the four special cases where the singularity at $z = -1$ disappears, see eq. (2.68)-(2.71).

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