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High-Order Optimal Edge Elements for Pyramids, Prisms and Hexahedra

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Abstract

Edge elements are a popular method to solve Maxwell's equations especially in time-harmonic domain. However, when non-affine elements are considered, elements of the Nedelec's first family are not providing an optimal rate of the convergence of the numerical solution toward the solution of the exact problem in $H(\text{curl})$ -norm. We propose new finite element spaces for pyramids, prisms, and hexahedra in order to recover the optimal convergence. In the particular case of pyramids, a comparison with other existing elements found in the literature is performed. Numerical results show the good behaviour of these new finite elements.

Keywords: Edge Elements, High-order finite element, Pyramids, Maxwell's equations

1. Introduction

We are interested in the resolution of 3-D time-harmonic Maxwell's equations

$$-\omega^2 \varepsilon E + \text{curl} \left(\frac{1}{\mu} \text{curl} E \right) = f \quad (1)$$

where ε, μ may be heterogeneous. Many numerical methods have been developed to solve this equation. Using nodal finite elements is possible by considering either a weighted regularization (Costabel and Dauge, 2002) or a Discontinuous Galerkin formulation (Perugia et al., 2002). A more natural choice consists of using edge elements, and considering the following variational formulation:

$$-\omega^2 \int_{\Omega} \varepsilon E \cdot \varphi \, dx + \int_{\Omega} \frac{1}{\mu} \text{curl} E \cdot \text{curl} \varphi \, dx = \int_{\Omega} f \cdot \varphi \, dx \quad (2)$$

We restrict ourselves to the study of Nédélec's first family elements since optimal convergence of the convergence of the numerical solution toward the solution of the exact problem is sought in $H(\text{curl})$ -norm. These elements are well-known in the case of tetrahedra, prisms, and hexahedra (see for example (Monk, 2002)).

However, these elements are not providing an optimal convergence $O(h^r)$ in $H(\text{curl})$ -norm when non-affine hexahedra and prisms are considered, that is to say when the transformation from the reference element to the real element of the mesh is in \mathbb{Q}_1 instead of being affine. An improved finite element space has been proposed in (Arnold et al., 2005) in 2-D for quadrilaterals, and in 3-D in (Falk et al., 2010) for first-order hexahedra. We propose here optimal finite element spaces in 3-D for hexahedra, prisms and pyramids at any order of approximation. Nodal basis functions are constructed by inverting a Vandermonde matrix, but this matrix appears to be bad-conditioned for pyramids. Hierarchical basis functions are given for all the types of elements, with a tensor structure, which can be exploited to obtain a fast matrix-vector product or a fast computation of finite element matrix.

In the special case of pyramidal elements, we propose a finite element space compatible with spaces of Nédélec's first family of other elements. Moreover, a comparison is performed with pyramidal edge elements proposed in the literature, e.g. (Coulomb et al., 1997), (Nigam and Phillips, 2007), (Graglia and Gheorma, 1999).

2. Optimal Finite element spaces

Let us introduce the following classical spaces:

Definition 1. • *In 2-D:*

$$\begin{aligned}\mathbb{Q}_{m,n}(x, y) &= \text{Span} \{x^i y^j, 0 \leq i \leq m, 0 \leq j \leq n\} \\ \mathbb{P}_r(x, y) &= \text{Span} \{x^i y^j, i, j \geq 0, i + j \leq r\} \\ \tilde{\mathbb{P}}_r(x, y) &= \text{Span} \{x^i y^j, i, j \geq 0, i + j = r\} \\ \mathcal{S}_r(x, y) &= \left\{ u = (u_1, u_2) \in \tilde{\mathbb{P}}_r^2, \text{ such that } u_1 x + u_2 y = 0 \right\} \\ \mathcal{R}_r(x, y) &= (\mathbb{P}_{r-1}(x, y))^2 \oplus \mathcal{S}_r(x, y)\end{aligned}$$

• *In 3-D:*

$$\begin{aligned}\mathbb{Q}_{m,n,p}(x, y, z) &= \text{Span} \{x^i y^j z^k, 0 \leq i \leq m, 0 \leq j \leq n, 0 \leq k \leq p\} \\ \mathbb{P}_r(x, y, z) &= \text{Span} \{x^i y^j z^k, i, j, k \geq 0, i + j + k \leq r\} \\ \tilde{\mathbb{P}}_r(x, y, z) &= \text{Span} \{x^i y^j z^k, i, j, k \geq 0, i + j + k = r\} \\ \mathcal{S}_r(x, y, z) &= \left\{ u \in \widetilde{\mathbb{P}}_r^3 \text{ so that } u_1 x + u_2 y + u_3 z = 0 \right\} \\ \mathcal{R}_r(x, y, z) &= \mathbb{P}_{r-1}^3 \oplus \mathcal{S}_r\end{aligned}$$

\mathcal{R}_r is the Nédélec's first family introduced by Nédélec (Nédélec, 1980). We also introduce the approximation space for continuous pyramidal element (see (Bergot et al., 2010))

$$\mathbb{B}_r = \mathbb{P}_r(x, y, z) \oplus \sum_{k=0}^{r-1} \mathbb{P}_k(x, y) \left(\frac{xy}{1-z} \right)^{r-k}$$

and this space written on the cube $[-1, 1] \times [0, 1]$:

$$\mathbb{C}_r = \text{Span} \{x^i y^j (1-z)^k, 0 \leq i, j \leq k \leq r\}$$

The finite element approximation is constructed by considering a transformation F from a reference element \hat{K} (unit tetrahedron, symmetric pyramid, unit prism, unit cube) to a real element K on the mesh. This transformation is written as

$$F = \sum_{1 \leq i \leq n_i} S_i \hat{\varphi}_i^1, \quad (3)$$

where n_i is the number of vertices of the element, $S_i = (x_i, y_i, z_i)$ are the vertices and $\hat{\varphi}_i^1$ are mapping functions depending on the considered type of the element.

For pyramidal elements, the mapping functions given in (Bedrosian, 1992) using rational fractions are the following:

$$\left\{ \begin{array}{l} \hat{\varphi}_1^1 = \frac{1}{4} \left(1 - \hat{x} - \hat{y} - \hat{z} + \frac{\hat{x}\hat{y}}{1-\hat{z}} \right) \\ \hat{\varphi}_2^1 = \frac{1}{4} \left(1 + \hat{x} - \hat{y} - \hat{z} - \frac{\hat{x}\hat{y}}{1-\hat{z}} \right) \\ \hat{\varphi}_3^1 = \frac{1}{4} \left(1 + \hat{x} + \hat{y} - \hat{z} + \frac{\hat{x}\hat{y}}{1-\hat{z}} \right) \\ \hat{\varphi}_4^1 = \frac{1}{4} \left(1 - \hat{x} + \hat{y} - \hat{z} - \frac{\hat{x}\hat{y}}{1-\hat{z}} \right) \\ \hat{\varphi}_5^1 = \hat{z} \end{array} \right.$$

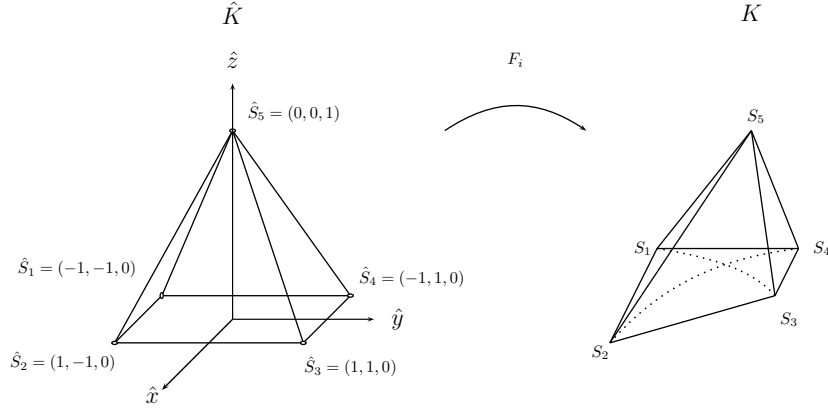


Figure 1: transformation F for a pyramid

The obtained transformation is shown in Fig. 1

For the other types of elements, the transformation is classical (see (Solin et al., 2003)).

Let us denote

$$H(\text{curl}, \Omega) = \{u \in (L^2(\Omega))^3 \text{ such that } \text{curl } u \in (L^2(\Omega))^3\}$$

The electric field E and test function φ of the variational formulation (2) are belonging to the following finite element space:

$$V_h = \{u \in H(\text{curl}, \Omega) \text{ so that } u|_K \in P_r^F\}$$

where $P_r^F(K)$ denotes the finite element space on the real element K . This space is induced by the choice of the space $\hat{P}_r(\hat{K})$ thanks to Piola $H(\text{curl})$ -conforming transform

$$P_r^F(K) = \{u \text{ so that } DF^* u \circ F \in \hat{P}_r(\hat{K})\}$$

The space $\hat{P}_r(\hat{K})$ is independent from the element K , since it depends only on the reference element \hat{K} and on the order of approximation r . We denote by DF the jacobian matrix of transformation F .

In order to obtain an optimal convergence in $O(h^r)$ for $H(\text{curl})$ -norm, where h denotes the mesh size, a sufficient condition (see (Monk, 2002)) is that the space P_r^F includes all polynomials of space \mathcal{R}_r .

Definition 2. $\hat{P}_r(\hat{K})$ is said to be optimal if for any element K , $P_r^F \supset \mathcal{R}_r$

After a careful examination of $DF^* \mathbf{p} \circ F$ for all the polynomials \mathbf{p} in \mathcal{R}_r , the following optimal finite element spaces can be obtained.

Theorem 1. The optimal space $\hat{P}_r(\hat{K})$ is equal to:

- **Tetrahedron:**

$$\hat{P}_r(\hat{K}) = \mathcal{R}_r$$

- **Hexahedron:**

$$\hat{P}_r(\hat{K}) = \mathcal{Q}_r = \mathcal{Q}_{r-1, r+1, r+1} \times \mathcal{Q}_{r+1, r-1, r+1} \times \mathcal{Q}_{r+1, r+1, r-1}$$

- **Prism:**

$$\hat{P}_r(\hat{K}) = \mathcal{W}_r = (\mathcal{R}_r(\hat{x}, \hat{y}) \otimes \mathbb{P}_{r+1}(\hat{z})) \times (\mathbb{P}_{r+1}(\hat{x}, \hat{y}) \otimes \mathbb{P}_{r-1}(\hat{z}))$$

• **Pyramid:**

$$\begin{aligned} \hat{P}_r(\hat{K}) = \mathcal{B}_r = \mathbb{B}_{r-1}^3 \oplus & \left\{ \frac{\hat{x}^p \hat{y}^p}{(1-\hat{z})^{p+2}} \begin{bmatrix} \hat{y}(1-\hat{z}) \\ \hat{x}(1-\hat{z}) \\ \hat{x}\hat{y} \end{bmatrix}, 0 \leq p \leq r-1 \right\} \\ & \oplus \left\{ \frac{\hat{x}^m \hat{y}^{n+2}}{(1-\hat{z})^{m+2}} \begin{bmatrix} (1-\hat{z}) \\ 0 \\ \hat{x} \end{bmatrix}, \frac{\hat{x}^{n+2} \hat{y}^m}{(1-\hat{z})^{m+2}} \begin{bmatrix} 0 \\ (1-\hat{z}) \\ \hat{y} \end{bmatrix}, 0 \leq m \leq n \leq r-2 \right\} \\ & \oplus \left\{ \frac{\hat{x}^p \hat{y}^q}{(1-\hat{z})^{p+q+1-r}} \begin{bmatrix} (1-\hat{z}) \\ 0 \\ \hat{x} \end{bmatrix}, \frac{\hat{x}^q \hat{y}^p}{(1-\hat{z})^{p+q+1-r}} \begin{bmatrix} 0 \\ (1-\hat{z}) \\ \hat{y} \end{bmatrix}, 0 \leq p \leq r-1, 0 \leq q \leq r+1 \right\} \end{aligned}$$

If we denote T the transformation from the cube $[-1, 1]^2 \times [0, 1]$ to the symmetric pyramid:

$$\begin{aligned} \hat{x} &= (1-\tilde{z})\tilde{x} \\ \hat{y} &= (1-\tilde{z})\tilde{y} \\ \hat{z} &= \tilde{z} \end{aligned}$$

The optimal space of the pyramid on the cube is equal to

$$\begin{aligned} \mathcal{C}_r &= \mathcal{B}_r(\hat{x}, \hat{y}, \hat{z}) \circ T \\ &= \left(\mathbb{B}_{r-1} \circ T(\tilde{x}, \tilde{y}, \tilde{z}) \right)^3 \oplus \left\{ \tilde{x}^p \tilde{y}^p (1-\tilde{z})^p \begin{bmatrix} \tilde{y} \\ \tilde{x} \\ \tilde{x}\tilde{y} \end{bmatrix}, 0 \leq p \leq r-1 \right\} \\ &\quad \oplus \left\{ \tilde{x}^m \tilde{y}^{n+2} (1-\tilde{z})^{n+1} \begin{bmatrix} 1 \\ 0 \\ \tilde{x} \end{bmatrix}, \tilde{x}^{n+2} \tilde{y}^m (1-\tilde{z})^{n+1} \begin{bmatrix} 0 \\ 1 \\ \tilde{y} \end{bmatrix}, 0 \leq m \leq n \leq r-2 \right\} \\ &\quad \oplus \left\{ \tilde{x}^p \tilde{y}^q (1-\tilde{z})^r \begin{bmatrix} 1 \\ 0 \\ \tilde{x} \end{bmatrix}, \tilde{x}^q \tilde{y}^p (1-\tilde{z})^r \begin{bmatrix} 0 \\ 1 \\ \tilde{y} \end{bmatrix}, 0 \leq p \leq r-1, 0 \leq q \leq r+1 \right\} \end{aligned}$$

One should remark that we have applied a simple change of variables on the cube, and not an $H(\text{curl})$ -conforming transformation since DT^* has not been applied.

Proof. The proof is done only for pyramids since this case is the most interesting and difficult to treat. Similar computations have been lead for hexahedra and triangular prisms but are not reported here. The proof is performed by considering a monomial $\mathbf{p}(x, y, z)$ in \mathcal{R}_r , we compute $\hat{\mathbf{p}} = \mathbf{p} \circ F$, and Piola transform DF^* is applied to $\hat{\mathbf{p}}$ and we search all the monomials in $(\hat{x}, \hat{y}, \hat{z})$ independent of F that are combined to obtain $DF^* \mathbf{p} \circ F$. The transformation F can be written under the form:

$$F(\hat{x}, \hat{y}, \hat{z}) = A_0 + A_1 \hat{x} + A_2 \hat{y} + A_3 \hat{z} + \frac{\hat{x}\hat{y}}{1-\hat{z}} C$$

where A_1, A_2, A_3 and C belong to \mathbb{R}^3 and depend on the geometry. The transformation F is polynomial in $(\tilde{x}, \tilde{y}, \tilde{z})$ (variables in the cube):

$$F(\tilde{x}, \tilde{y}, \tilde{z}) = A_0 + A_1 \tilde{x}(1-\tilde{z}) + A_2 \tilde{y}(1-\tilde{z}) + A_3 \tilde{z} + \tilde{x}\tilde{y}(1-\tilde{z})C$$

The derivatives of F are equal to:

$$\frac{\partial F}{\partial \hat{x}} = A_1 + \frac{\hat{y}}{1-\hat{z}} C = A_1 + C\tilde{y}$$

$$\begin{aligned}\frac{\partial F}{\partial \tilde{y}} &= A_2 + \frac{\hat{x}}{1 - \hat{z}} C = A_2 + C \tilde{x} \\ \frac{\partial F}{\partial \hat{z}} &= A_3 + \frac{\hat{x} \tilde{y}}{(1 - \hat{z})^2} C = A_3 + C \tilde{x} \tilde{y}\end{aligned}$$

For a polynomial p in \mathcal{R}_r , $\hat{p} = \mathbf{p} \circ F$ is the expression of p in the symmetric pyramid \hat{K} and \tilde{p} the expression on the cube $[-1, 1]^2 \times [0, 1]$. When Piola transform DF^* is applied to \hat{p} :

$$DF^* \hat{p} = \begin{bmatrix} (A_1 + C \tilde{y}) \cdot \tilde{p} \\ (A_2 + C \tilde{x}) \cdot \tilde{p} \\ (A_3 + C \tilde{x} \tilde{y}) \cdot \tilde{p} \end{bmatrix}$$

For $\mathbf{p} \in \mathbb{P}_{r-1}^3$, as it has been proven in (Bergot et al., 2010), one can equivalently consider $\tilde{p} \in \mathbb{C}_{r-1}^3$:

$$\tilde{p} = \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k E_0$$

where $i, j \leq k \leq r - 1$ and E_0 a constant vector of \mathbb{R}^3 . One gets:

$$DF^* \tilde{p} = \begin{bmatrix} A_1 \cdot E_0 \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k + C \cdot E_0 \tilde{x}^i \tilde{y}^{j+1} (1 - \tilde{z})^k \\ A_2 \cdot E_0 \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k + C \cdot E_0 \tilde{x}^{i+1} \tilde{y}^j (1 - \tilde{z})^k \\ A_3 \cdot E_0 \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k + C \cdot E_0 \tilde{x}^{i+1} \tilde{y}^{j+1} (1 - \tilde{z})^k \end{bmatrix}$$

The left side is equal to (when $C = 0$, i.e. affine pyramids)

$$\begin{bmatrix} A_1 \cdot E_0 \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k \\ A_2 \cdot E_0 \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k \\ A_3 \cdot E_0 \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^k \end{bmatrix}$$

belongs to \mathbb{C}_{r-1}^3 . It means that all functions of \mathbb{C}_{r-1}^3 are needed. For the right side, four cases appear

- $i = j = k = p - 1$, with $1 \leq p \leq r$, we then have:

$$\begin{bmatrix} \tilde{x}^{p-1} \tilde{y}^p (1 - \tilde{z})^{p-1} \\ \tilde{x}^p \tilde{y}^{p-1} (1 - \tilde{z})^{p-1} \\ \tilde{x}^p \tilde{y}^p (1 - \tilde{z})^{p-1} \end{bmatrix} \in \mathcal{B}_r$$

- $i = k = m + 1$ and $j < k$, then $j \leq m$ and $m \leq r - 2$. We have:

$$\begin{bmatrix} 0 \\ \tilde{x}^{m+2} \tilde{y}^j (1 - \tilde{z})^{m+1} \\ \tilde{x}^{m+2} \tilde{y}^{j+1} (1 - \tilde{z})^{m+1} \end{bmatrix} \in \mathcal{B}_r + \begin{bmatrix} \tilde{x}^{m+1} \tilde{y}^{j+1} (1 - \tilde{z})^{m+1} \\ 0 \\ 0 \end{bmatrix} \in \mathbb{C}_{r-1}^3$$

- $j = k = m + 1$ and $i = p < k$, then $p \leq m$ and $m \leq r - 2$. We have:

$$\begin{bmatrix} \tilde{x}^p \tilde{y}^{m+2} (1 - \tilde{z})^{m+1} \\ 0 \\ \tilde{x}^{p+1} \tilde{y}^{m+2} (1 - \tilde{z})^{m+1} \end{bmatrix} \in \mathcal{B}_r + \begin{bmatrix} 0 \\ \tilde{x}^{p+1} \tilde{y}^{m+1} (1 - \tilde{z})^{m+1} \\ 0 \end{bmatrix} \in \mathbb{C}_{r-1}^3$$

- $i, j < k$, in this case $DF^* \tilde{p} \in \mathbb{C}_{r-1}^3$

It can be noticed that in order to generate P_{r-1}^3 , a necessary and sufficient condition is that \hat{P}_r^K includes the polynomial space:

$$\mathbb{C}_{r-1}^3 \oplus \begin{bmatrix} \tilde{x}^j \tilde{y}^{k+2} (1 - \tilde{z})^{k+1} \\ 0 \\ \tilde{x}^{j+1} \tilde{y}^{k+2} (1 - \tilde{z})^{k+1} \end{bmatrix} \oplus \begin{bmatrix} 0 \\ \tilde{x}^{k+2} \tilde{y}^j (1 - \tilde{z})^{k+1} \\ \tilde{x}^{k+2} \tilde{y}^{j+1} (1 - \tilde{z})^{k+1} \end{bmatrix} \oplus \begin{bmatrix} \tilde{x}^{p-1} \tilde{y}^p (1 - \tilde{z})^{p-1} \\ \tilde{x}^p \tilde{y}^{p-1} (1 - \tilde{z})^{p-1} \\ \tilde{x}^p \tilde{y}^p (1 - \tilde{z})^{p-1} \end{bmatrix}$$

with $j \leq k \leq r-2$, $1 \leq p \leq r$. This space should be considered for the construction of edge elements of Nédélec's second family (\mathbb{P}_r^3 for tetrahedra).

We now consider a function of \mathcal{S}_r :

$$\begin{bmatrix} 0 \\ x^i y^j z^{k+1} \\ -x^i y^{j+1} z^k \end{bmatrix}, \quad i+j \leq r-1, k = r-1-i-j$$

The degree of $x^i y^j z^k$ is exactly $r-1$, therefore this monomial can be written as a linear combination of $\tilde{x}^i \tilde{y}^j (1 - \tilde{z})^{r-1}$ with $i, j \leq r-1$. In order to simplify the computations, it is equivalent to consider a function of \mathcal{S}_r under the form:

$$\tilde{x}^i \tilde{y}^j (1 - \tilde{z})^{r-1} \begin{bmatrix} 0 \\ z \\ -y \end{bmatrix}, \quad i, j \leq r-1$$

Let us denote

$$E = \begin{bmatrix} 0 \\ z \\ -y \end{bmatrix} = \begin{bmatrix} 0 \\ (A_0^z - A_3^z) + \tilde{x}(1 - \tilde{z})A_1^z + \tilde{y}(1 - \tilde{z})A_2^z - (1 - \tilde{z})A_3^z + \tilde{x}\tilde{y}(1 - \tilde{z})C^z \\ -[(A_0^y - A_3^y) + \tilde{x}(1 - \tilde{z})A_1^y + \tilde{y}(1 - \tilde{z})A_2^y - (1 - \tilde{z})A_3^y + \tilde{x}\tilde{y}(1 - \tilde{z})C^y] \end{bmatrix}$$

with

$$\begin{aligned} A_0 &= (A_0^x, A_0^y, A_0^z), \quad A_1 = (A_1^x, A_1^y, A_1^z), \quad A_2 = (A_2^x, A_2^y, A_2^z) \\ A_3 &= (A_3^x, A_3^y, A_3^z), \quad C = (C^x, C^y, C^z) \end{aligned}$$

The first component of DF^*E is:

$$\begin{aligned} (DF^*E)_x &= [A_1^y(A_0^z - A_3^z) - A_1^z(A_0^y - A_3^y)] + [C^y(A_0^z - A_3^z) - C^z(A_0^y - A_3^y)]\tilde{y} + \\ &\quad [A_1^y A_2^z - A_1^z A_2^y]\tilde{y}(1 - \tilde{z}) + [C^y A_2^z - C^z A_2^y]\tilde{y}^2(1 - \tilde{z}) \\ &\quad + [A_1^z A_3^y - A_1^y A_3^z](1 - \tilde{z}) + [A_3^y C^z - A_3^z C^y]\tilde{y}(1 - \tilde{z}) \\ &= b_0 + b_1 \tilde{y} + (b_2 + b_3)\tilde{y}(1 - \tilde{z}) + b_4(1 - \tilde{z}) + b_5 \tilde{y}^2(1 - \tilde{z}) \end{aligned}$$

where

$$\begin{aligned} b_0 &= A_1^y(A_0^z - A_3^z) - A_1^z(A_0^y - A_3^y) \\ b_1 &= C^y(A_0^z - A_3^z) - C^z(A_0^y - A_3^y) \\ b_2 &= A_1^y A_2^z - A_1^z A_2^y \\ b_3 &= A_3^y C^z - A_3^z C^y \\ b_4 &= A_1^z A_3^y - A_1^y A_3^z \\ b_5 &= C^y A_2^z - C^z A_2^y \end{aligned}$$

The second component DF^*E reads

$$\begin{aligned} (DF^*E)_y &= [A_2^y(A_0^z - A_3^z) - A_2^z(A_0^y - A_3^y)] + [C^y(A_0^z - A_3^z) - C^z(A_0^y - A_3^y)]\tilde{x} + \\ &\quad [A_2^y A_1^z - A_2^z A_1^y]\tilde{x}(1 - \tilde{z}) + [C^y A_1^z - C^z A_1^y]\tilde{x}^2(1 - \tilde{z}) \\ &\quad + [A_3^y A_2^z - A_3^z A_2^y](1 - \tilde{z}) + [A_3^y C^z - A_3^z C^y]\tilde{x}(1 - \tilde{z}) \\ &= b_6 + b_1 \tilde{x} + (b_3 - b_2)\tilde{x}(1 - \tilde{z}) + b_8(1 - \tilde{z}) + b_7 \tilde{x}^2(1 - \tilde{z}) \end{aligned}$$

where

$$\begin{aligned} b_6 &= A_2^y(A_0^z - A_3^z) - A_2^z(A_0^y - A_3^y) \\ b_7 &= C^y A_1^z - C^z A_1^y \\ b_8 &= A_3^y A_2^z - A_3^z A_2^y \end{aligned}$$

The last component is equal to

$$\begin{aligned} (DF^*E)_z &= [A_3^y A_0^z - A_3^z A_0^y] + [C^y(A_0^z - A_3^z) - C^z(A_0^y - A_3^y)]\tilde{x}\tilde{y} \\ &\quad + [A_1^z A_3^y - A_1^y A_3^z]\tilde{x}(1 - \tilde{z}) + [C^y A_1^z - C^z A_1^y]\tilde{x}^2\tilde{y}(1 - \tilde{z}) + [A_3^y A_2^z - A_3^z A_2^y]\tilde{y}(1 - \tilde{z}) \\ &\quad + [C^y A_2^z - C^z A_2^y]\tilde{x}\tilde{y}^2(1 - \tilde{z}) + 2[A_3^y C^z - A_3^z C^y]\tilde{x}\tilde{y}(1 - \tilde{z}) \\ &= b_9 + b_1\tilde{x}\tilde{y} + b_4\tilde{x}(1 - \tilde{z}) + b_7\tilde{x}^2(1 - \tilde{z}) + b_5\tilde{x}\tilde{y}^2(1 - \tilde{z}) \\ &\quad + (b_3 - b_2)\tilde{x}\tilde{y}(1 - \tilde{z}) + (b_3 + b_2)\tilde{x}\tilde{y}(1 - \tilde{z}) + b_8\tilde{y}(1 - \tilde{z}) \end{aligned}$$

where

$$b_9 = A_3^y A_0^z - A_3^z A_0^y$$

We have:

$$\begin{aligned} DF^*E &= \begin{bmatrix} b_0 \\ b_6 \\ b_9 \end{bmatrix} + b_1 \begin{bmatrix} \tilde{y} \\ \tilde{x} \\ \tilde{x}\tilde{y} \end{bmatrix} + (b_2 + b_3) \begin{bmatrix} \tilde{y}(1 - \tilde{z}) \\ 0 \\ \tilde{x}\tilde{y}(1 - \tilde{z}) \end{bmatrix} + (b_3 - b_2) \begin{bmatrix} 0 \\ \tilde{x}(1 - \tilde{z}) \\ \tilde{x}\tilde{y}(1 - \tilde{z}) \end{bmatrix} \\ &\quad + b_4 \begin{bmatrix} 1 - \tilde{z} \\ 0 \\ \tilde{x}(1 - \tilde{z}) \end{bmatrix} + b_5 \begin{bmatrix} \tilde{y}^2(1 - \tilde{z}) \\ 0 \\ \tilde{x}\tilde{y}^2(1 - \tilde{z}) \end{bmatrix} + b_7 \begin{bmatrix} 0 \\ \tilde{x}^2(1 - \tilde{z}) \\ \tilde{x}^2\tilde{y}(1 - \tilde{z}) \end{bmatrix} + b_8 \begin{bmatrix} 0 \\ (1 - \tilde{z}) \\ \tilde{y}(1 - \tilde{z}) \end{bmatrix} \end{aligned}$$

The function

$$\tilde{x}^i \tilde{y}^j (1 - \tilde{z})^{r-1} \begin{bmatrix} b_0 \\ b_6 \\ b_9 \end{bmatrix}$$

belongs to C_{r-1}^3 . The coefficients $b_1, (b_2 + b_3), (b_3 - b_2), b_4, b_5, b_7$ and b_8 , viewed as functions as A_0, A_1, A_2, A_3, C , are linearly independent, The following functions are necessary and sufficient:

$$\begin{aligned} &\tilde{x}^i \tilde{y}^j (1 - \tilde{z})^{r-1} \left\{ \begin{bmatrix} \tilde{y} \\ \tilde{x} \\ \tilde{x}\tilde{y} \end{bmatrix}, \begin{bmatrix} \tilde{y}(1 - \tilde{z}) \\ 0 \\ \tilde{x}\tilde{y}(1 - \tilde{z}) \end{bmatrix}, \begin{bmatrix} 1 - \tilde{z} \\ 0 \\ \tilde{x}(1 - \tilde{z}) \end{bmatrix}, \begin{bmatrix} \tilde{y}^2(1 - \tilde{z}) \\ 0 \\ \tilde{x}\tilde{y}^2(1 - \tilde{z}) \end{bmatrix} \right\} \\ &\tilde{x}^i \tilde{y}^j (1 - \tilde{z})^{r-1} \left\{ \begin{bmatrix} 0 \\ \tilde{x}(1 - \tilde{z}) \\ \tilde{x}\tilde{y}(1 - \tilde{z}) \end{bmatrix}, \begin{bmatrix} 0 \\ \tilde{x}^2(1 - \tilde{z}) \\ \tilde{x}^2\tilde{y}(1 - \tilde{z}) \end{bmatrix}, \begin{bmatrix} 0 \\ (1 - \tilde{z}) \\ \tilde{y}(1 - \tilde{z}) \end{bmatrix} \right\} \end{aligned}$$

We can regroup them in three families:

- A first group

$$\begin{bmatrix} \tilde{x}^i \tilde{y}^{j+1} (1 - \tilde{z})^{r-1} \\ \tilde{x}^{i+1} \tilde{y}^j (1 - \tilde{z})^{r-1} \\ \tilde{x}^{i+1} \tilde{y}^{j+1} (1 - \tilde{z})^{r-1} \end{bmatrix}, i, j \leq r - 1$$

is the same as in the treatment of \mathbb{P}_{r-1}^3 (with $k = r - 1$).

- Two other groups

$$\begin{bmatrix} \tilde{x}^i \tilde{y}^j (1 - \tilde{z})^r \\ 0 \\ \tilde{x}^{i+1} \tilde{y}^j (1 - \tilde{z})^r \end{bmatrix}, \quad \begin{bmatrix} 0 \\ \tilde{x}^j \tilde{y}^i (1 - \tilde{z})^r \\ \tilde{x}^j \tilde{y}^{i+1} (1 - \tilde{z})^r \end{bmatrix}, \quad i \leq r - 1, j \leq r + 1$$

are the two last families of \mathcal{B}_r .

When similar computations are conducted for the two other families of functions of \mathcal{S}_r :

$$\begin{bmatrix} x^i y^j z^{k+1} \\ 0 \\ -x^{i+1} y^j z^k \end{bmatrix}, \quad \begin{bmatrix} x^i y^{j+1} z^k \\ -x^{i+1} y^j z^k \\ 0 \end{bmatrix}, \quad k = r - 1 - i - j$$

We obtain exactly the same form for DF^*E , only the expression of coefficients b_0, b_1, \dots, b_9 being different. Therefore, we have shown that to generate \mathcal{R}_r , all the functions of \mathcal{B}_r are necessary and sufficient. \square

Proposition 1. *The dimensions of the optimal finite elements spaces are the following ones:*

- *Tetrahedron:* $\dim \mathcal{R}_r = \frac{r(r+2)(r+3)}{2}$
- *Hexahedron:* $\dim \mathcal{Q}_r = 3r(r+2)^2$
- *Prism:* $\dim \mathcal{W}_r = \frac{r(r+2)(3r+7)}{2}$
- *Pyramid:* $\dim \mathcal{B}_r = \frac{r(r+3)(2r+3)}{2}$

Remark 1. *The optimal finite element spaces \hat{P}_r we constructed will be called “Optimal first family”, since their construction relies on the inclusion of Nédélec’s first family in the real space. The usual Nédélec’s first family, denoted \hat{P}_r^1 consist of the following spaces:*

- **Tetrahedron:**

$$\hat{P}_r^1 = \mathcal{R}_r$$

- **Hexahedron:**

$$\hat{P}_r^1 = \mathcal{Q}_{r-1,r,r} \times \mathcal{Q}_{r,r-1,r} \times \mathcal{Q}_{r,r,r-1}$$

- **Prism:**

$$\hat{P}_r^1 = (\mathcal{R}_r(\hat{x}, \hat{y}) \otimes \mathbb{P}_r(\hat{z})) \times (\mathbb{P}_r(\hat{x}, \hat{y}) \otimes \mathbb{P}_{r-1}(\hat{z}))$$

- **Pyramid:**

$$\begin{aligned} \hat{P}_r^1 = & \mathbb{B}_{r-1}^3 \oplus \left\{ \frac{\hat{x}^p \hat{y}^p}{(1-\hat{z})^{p+2}} \begin{bmatrix} \hat{y}(1-\hat{z}) \\ \hat{x}(1-\hat{z}) \\ \hat{x}\hat{y} \end{bmatrix}, 0 \leq p \leq r-1 \right\} \\ & \oplus \left\{ \frac{\hat{x}^m \hat{y}^{n+2}}{(1-\hat{z})^{m+2}} \begin{bmatrix} (1-\hat{z}) \\ 0 \\ \hat{x} \end{bmatrix}, \frac{\hat{x}^{n+2} \hat{y}^m}{(1-\hat{z})^{m+2}} \begin{bmatrix} 0 \\ (1-\hat{z}) \\ \hat{y} \end{bmatrix}, 0 \leq m \leq n \leq r-2 \right\} \\ & \oplus \left\{ \frac{\hat{x}^p \hat{y}^q}{(1-\hat{z})^{p+q+1-r}} \begin{bmatrix} (1-\hat{z}) \\ 0 \\ \hat{x} \end{bmatrix}, \frac{\hat{x}^q \hat{y}^p}{(1-\hat{z})^{p+q+1-r}} \begin{bmatrix} 0 \\ (1-\hat{z}) \\ \hat{y} \end{bmatrix}, \begin{matrix} 0 \leq p \leq r-1 \\ 0 \leq q \leq r \end{matrix} \right\} \end{aligned}$$

Here, the finite element space we propose on the pyramid is issued from the optimal space by enforcing conformity with hexahedra of the first family. The dimension of this pyramidal space is equal to $\frac{r(2r^2 + 9r + 5)}{2}$. Hexahedral and pyramidal spaces of the first family \hat{P}_r^1 need $(r+1)^3$ Gauss-Legendre-like quadrature points to ensure a positive definite mass matrix and keep the optimal order of convergence in $O(h^{r-1})$ for deformed meshes, whereas optimal spaces \hat{P}_r need $(r+2)^3$ quadrature points for a convergence in $O(h^r)$. Cubature rules used for pyramidal basis functions are the same formulas as described in (Bergot et al., 2010).

3. $H(\text{curl})$ conformity and tangential traces

In the construction of these optimal finite element spaces, the $H(\text{curl})$ -conformity between elements has not been enforced but is nevertheless ensured, as the tangential restriction of the optimal finite element spaces is the following:

- **Triangular faces:** $\mathcal{R}_r(x, y)$
- **Quadrilateral faces:** $\mathbb{Q}_{r-1, r+1} \times \mathbb{Q}_{r+1, r-1}$

It should be noticed that the restriction on quadrilateral faces coincide with the optimal finite element space for edge elements in 2-D (see (Arnold et al., 2005)), and that optimal hexahedral finite element space is the same as the space found in (Falk et al., 2010) (for $r = 1$). However, the construction proposed by Falk, Gatto and Monk is different from our construction, since it relies on the construction of facet elements (for the discretization of $H(\text{div})$). For pyramidal elements, since the $H(\text{curl})$ conformity is not immediate, we provide a proof of that.

Lemma 1. • If $p \in \mathbb{B}_r(\hat{K})$, $p \in H^{5/2-\varepsilon}(\hat{K})$ for any $\varepsilon > 0$.

- If $p = \hat{x}^i \hat{y}^j (1 - \hat{z})^{k-(i+j)}$, p belongs to $H^{3/2+k-\varepsilon}(\hat{K})$ with $H^m(\hat{K})$ the classical Sobolev space.

Proof. Let us take

$$p = \hat{x}^i \hat{y}^j (1 - \hat{z})^{k-(i+j)}$$

For $m_1 < i, m_2 < j, i + j < k$, the m -th derivative of p is proportional to:

$$\frac{\partial p}{\partial \hat{x}^{m_1} \partial \hat{y}^{m_2} \partial \hat{z}^{m_3}} = \alpha \hat{x}^{i-m_1} \hat{y}^{j-m_2} (1 - \hat{z})^{k-i-j-m_3}$$

Then when writing the integral in the cube:

$$\begin{aligned} \int_{\hat{K}} \left(\frac{\partial p}{\partial \hat{x}^{m_1} \partial \hat{y}^{m_2} \partial \hat{z}^{m_3}} \right)^2 d\hat{x} d\hat{y} d\hat{z} &= \int_{[-1,1] \times [0,1]} (1 - \tilde{z})^2 \left(\frac{\partial p}{\partial \hat{x}^{m_1} \partial \hat{y}^{m_2} \partial \hat{z}^{m_3}} \right)^2 d\tilde{x} d\tilde{y} d\tilde{z} \\ &= \alpha^2 \int_{[-1,1] \times [0,1]} \tilde{x}^{2(i-m_1)} \tilde{y}^{2(j-m_2)} (1 - \tilde{z})^{2(k-m_1-m_2-m_3+1)} d\tilde{x} d\tilde{y} d\tilde{z} \end{aligned}$$

This integral is definite under the condition

$$k + 1 - (m_1 + m_2 + m_3) \geq -\frac{1}{2} + \varepsilon \Leftrightarrow (m_1 + m_2 + m_3) \leq k + \frac{3}{2} - \varepsilon$$

with $\varepsilon > 0$. For any monomial p of $\mathbb{B}_r(\hat{K})$, p is either constant or $p = \hat{x}^i \hat{y}^j (1 - \hat{z})^{k-(i+j)}$ with $k \geq 1$. As a result, $\mathbb{B}_r(\hat{K}) \subset H^{5/2-\varepsilon}(\hat{K})$. \square

Theorem 2. With the optimal finite element spaces P_r^F constructed in the previous section, we have

$$V_h(\Omega) \subset H(\text{curl}, \Omega).$$

Proof. • In a first place, we have to check that on each element K , $P_r^F \subset H(\text{curl}, K)$. Let us consider $\mathbf{p} \in P_r^F$, we have:

$$\begin{aligned} \hat{p} &= DF^* \mathbf{p} \circ F \\ \text{curl } \hat{p} &= |DF| DF^{-1} \text{curl } \mathbf{p} \circ F \end{aligned}$$

The transformation F belongs to $H^{5/2-\varepsilon}(\hat{K})$ (with $\varepsilon > 0$), and DF belongs to $H^{3/2-\varepsilon}(\hat{K})$, by application of lemma (1). Therefore, it is equivalent to prove that \hat{p} belongs to $H(\text{curl}, \hat{K})$.

If $\hat{p} \in \mathbb{B}_{r-1}^3$, \hat{p} belongs to $H^{5/2-\varepsilon}(\hat{K})$, then $\text{curl } \hat{p}$ belongs to $H^{3/2-\varepsilon}(\hat{K})$. For the other monomials of \mathcal{B}_r , two cases are distinguished:

$$-\hat{p} = \begin{bmatrix} \frac{\hat{y}}{1-\hat{z}} \\ \frac{\hat{x}}{1-\hat{z}} \\ \frac{\hat{x}\hat{y}}{(1-\hat{z})^2} \end{bmatrix} = \nabla \left(\frac{\hat{x}\hat{y}}{1-\hat{z}} \right),$$

Since the curl of a gradient is null, we have

$$\hat{\text{curl}} \hat{p} = 0$$

By applying lemma (1), $\hat{p} \in H^{3/2-\varepsilon}(\hat{K})$.

- Each component is of the form $\hat{p}_n = \hat{x}^i \hat{y}^j (1-\hat{z})^{k-i-j}$ with $i, j \leq k+1$ and $k \geq 1$. By application of lemma (1), $\hat{p} \in H^{5/2-\varepsilon}(\hat{K})$, and $\hat{\text{curl}} p \in H^{3/2-\varepsilon}(\hat{K})$.

As a result, $\mathcal{B}_r \subset H^{5/2-\varepsilon}(\hat{K})$ and $\text{curl } \mathcal{B}_r \subset H^{3/2-\varepsilon}(\hat{K})$. It should also be noticed that the curl of each function of \mathcal{B}_r is bounded in \hat{K} , even though the limit of $\text{curl } p$ when $(\hat{x}, \hat{y}, \hat{z})$ tends to the apex of the pyramid is multi-valued.

- In a second place, we have to check that the tangential restriction of \mathcal{B}_r is equal to $\mathcal{R}_r(x, z)$ for a triangular face, and to $\mathbb{Q}_{r-1, r+1} \times \mathbb{Q}_{r+1, r-1}$ for a quadrilateral face. The result is immediate for the quadrilateral face. Let us consider a triangular face $\hat{x} = (1-\hat{z})$, with $n = [1, 0, 1]$. A first step is to write $\mathcal{S}_r(\hat{y}, \hat{z})$ on this face.

We consider the transformation f from the unit triangle $\hat{T}(\eta, \xi)$ to the triangular face $\hat{x} = 1-\hat{z}$ of the pyramid $\hat{K}(\hat{x}, \hat{y}, \hat{z})$

$$f = \begin{cases} \hat{x} = 1 - \xi \\ \hat{y} = 2\eta + \xi - 1 \\ \hat{z} = \xi \end{cases}$$

This transformation f is a diffeomorphism from \hat{T} to the face $\hat{x} = 1-\hat{z}$. We have

$$Df = \begin{bmatrix} 0 & -1 \\ 2 & 1 \\ 0 & 1 \end{bmatrix}, \quad Df^{-*} = \frac{1}{4} \begin{bmatrix} 1 & -2 \\ 2 & 0 \\ -1 & 2 \end{bmatrix}$$

where Df is the jacobian of transformation f and Df^{-*} the transpose of the pseudo-inverse of Df . We consider a monomial $\varphi \in \mathcal{S}_r(\eta, \xi)$:

$$\varphi(\eta, \xi) = \begin{bmatrix} \eta^i \xi^{j+1} \\ -\eta^{i+1} \xi^j \end{bmatrix}$$

with $i+j = r-1$. On the face $\hat{x} = 1-\hat{z}$ of \hat{K} , φ reads

$$\varphi(\hat{x}, \hat{y}, \hat{z}) = Df^{-*} \varphi(\eta, \xi) \circ f^{-1} = \left(\frac{\hat{y}+1-\hat{z}}{2} \right)^i \hat{z}^j \begin{bmatrix} \hat{y}+1 \\ 2\hat{z} \\ -\hat{y}-1 \end{bmatrix}$$

One can add as many polynomials of \mathbb{P}_{r-1}^2 as we want, since the additional space \mathcal{S}_r is searched ($\mathcal{R}_r = \mathbb{P}_{r-1}^2 + \mathcal{S}_r$). We add $(t_1 - 2t_2) \left(\frac{\hat{y}+1-\hat{z}}{2} \right)^i \hat{z}^j$ with

$$t_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \quad t_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

Therefore, we obtain

$$\mathcal{S}_r(\hat{y}, \hat{z}) = \text{Span} \left\{ \begin{bmatrix} \hat{y}^{j+1} (1-\hat{z})^i \\ -2\hat{y}^j (1-\hat{z})^{i+1} \\ -\hat{y}^{j+1} (1-\hat{z})^i \end{bmatrix}, \quad i+j = r-1 \right\}$$

Let us now compute the tangential restrictions of \mathcal{B}_r , that is $p_n(\hat{y}, \hat{z}) = (p \times n) \times n|_{\hat{x}=(1-\hat{z})}$

- If $p \in \mathbb{B}_{r-1}^3$, we have immediatly $p_n \in \mathbb{P}_{r-1}^2(\hat{y}, \hat{z})$.
- Otherwise, for $0 \leq i \leq r-1$

$$p = \begin{bmatrix} \frac{\hat{x}^i \hat{y}^{i+1}}{(1-\hat{z})^{i+1}} \\ \frac{\hat{x}^{i+1} \hat{y}^i}{(1-\hat{z})^{i+1}} \\ \frac{\hat{x}^{i+1} \hat{y}^{i+1}}{(1-\hat{z})^{i+2}} \end{bmatrix} \implies p_n = \begin{bmatrix} 0 \\ \hat{y}^i \\ 0 \end{bmatrix} \in \mathbb{P}_{r-1}^2(\hat{y}, \hat{z})$$

For $0 \leq m \leq n \leq r-2$,

$$p = \begin{bmatrix} \frac{\hat{x}^m \hat{y}^{n+2}}{(1-\hat{z})^{m+1}} \\ 0 \\ \frac{\hat{x}^{m+1} \hat{y}^{n+2}}{(1-\hat{z})^{m+2}} \end{bmatrix} \implies p_n = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$p = \begin{bmatrix} 0 \\ \frac{\hat{x}^{n+2} \hat{y}^m}{(1-\hat{z})^{m+1}} \\ \frac{\hat{x}^{n+2} \hat{y}^{m+1}}{(1-\hat{z})^{m+2}} \end{bmatrix} \implies p_n = \begin{bmatrix} \hat{y}^{m+1} (1-\hat{z})^{n-m} \\ -2\hat{y}^m (1-\hat{z})^{n-m+1} \\ -\hat{y}^{m+1} (1-\hat{z})^{n-m} \end{bmatrix} \in \mathbb{P}_{r-1}^2(\hat{y}, \hat{z})$$

For $0 \leq p \leq r-1$, $0 \leq q \leq r+1$

$$p = \begin{bmatrix} \frac{\hat{x}^p \hat{y}^q}{(1-\hat{z})^{p+q-r}} \\ 0 \\ \frac{\hat{x}^{p+1} \hat{y}^q}{(1-\hat{z})^{p+q+1-r}} \end{bmatrix} \implies p_n = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$p = \begin{bmatrix} 0 \\ \frac{\hat{x}^q \hat{y}^p}{(1-\hat{z})^{p+q-r}} \\ \frac{\hat{x}^q \hat{y}^{p+1}}{(1-\hat{z})^{p+q+1-r}} \end{bmatrix} \implies p_n = \begin{bmatrix} \hat{y}^{p+1} (1-\hat{z})^{r-p-1} \\ -2\hat{y}^p (1-\hat{z})^{r-p} \\ -\hat{y}^{p+1} (1-\hat{z})^{r-p-1} \end{bmatrix} \in \mathcal{S}_r(\hat{y}, \hat{z})$$

The same result can be obtained with other triangular faces.

By considering dimension of the spaces, we obtain

$$\begin{aligned} \hat{P}_{r| \hat{x}=1-\hat{z} \text{ ou } \hat{x}=\hat{z}-1} &= \mathcal{R}_r(\hat{y}, \hat{z}) \\ \hat{P}_{r| \hat{y}=1-\hat{z} \text{ ou } \hat{y}=\hat{z}-1} &= \mathcal{R}_r(\hat{x}, \hat{z}) \\ \hat{P}_{r| \hat{z}=0} &= \mathbb{Q}_{r-1, r+1}(\hat{x}, \hat{y}) \times \mathbb{Q}_{r+1, r-1}(\hat{x}, \hat{y}), \end{aligned} \tag{4}$$

These restrictions are the same as the restrictions obtained with hexahedra, prisms and tetrahedra. \square

4. Nodal basis functions

Nodal basis functions are popular for continuous finite elements discretizing $H^1(\Omega)$, but are less known for edge elements. Let us mention the works of Graglia (Graglia et al., 1997) for tetrahedra and the works of Cohen & Monk (Cohen and Monk, 1998) for hexahedra. For edge elements, each degree of freedom is associated with a position and a direction. If $(\xi_i)_{1 \leq i \leq r+1}$ are Gauss-Lobatto points, the points $(\xi_1^I, \xi_2^I, \xi_3^I) = (\xi_2, \xi_3, \dots, \xi_r)$ will be called interior Gauss-Lobatto points. For nodal points of the triangle, we will choose electrostatic points as described in (Hesthaven and Teng, 1999). Let us detail the positions and directions of the degrees of freedom for the different elements:

Hexahedron : As shown in figure Fig. 2 a tensor product between Gauss-Lobatto points and interior Gauss-Lobatto points is considered, more precisely, three families of degrees of freedom:

$$\begin{aligned} &(\xi_i^I, \xi_j, \xi_k) \text{ with direction } e_x, \quad 1 \leq i \leq r, \quad 1 \leq j, k \leq r+2 \\ &(\xi_j, \xi_i^I, \xi_k) \text{ with direction } e_y, \quad 1 \leq i \leq r, \quad 1 \leq j, k \leq r+2 \\ &(\xi_j, \xi_k, \xi_i^I) \text{ with direction } e_z, \quad 1 \leq i \leq r, \quad 1 \leq j, k \leq r+2 \end{aligned}$$

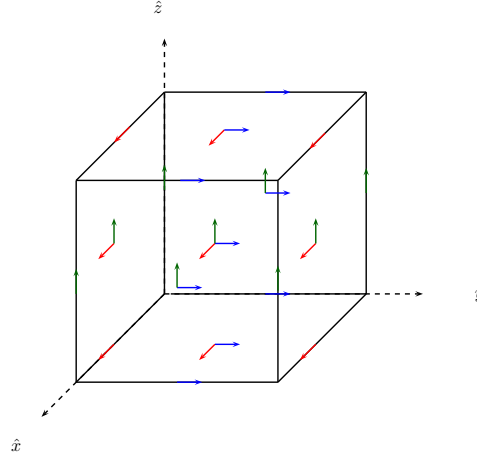


Figure 2: Location of degrees of freedom for first-order hexahedron

Tetrahedron : As displayed in figure Fig 3 for first-order tetrahedra, degrees of freedom are placed as follows

- For the edges, degrees of freedom are placed on interior Gauss-Lobatto points
- For the faces, two degrees of freedom are placed on each interior point of a nodal triangle of order $r+1$
- For the volume, three degrees of freedom are placed on each interior point of a nodal tetrahedron of order $r+1$ (nodal points are chosen as in (Hesthaven and Teng, 1999)).

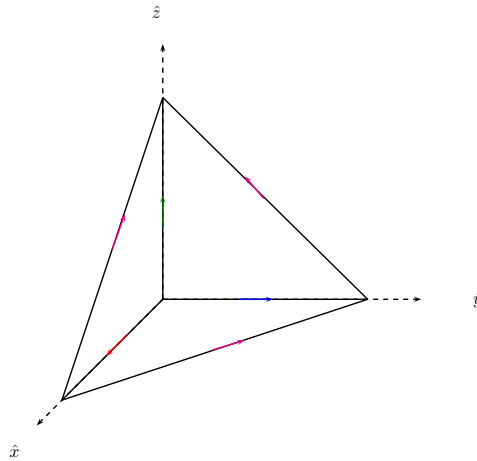


Figure 3: Location of degrees of freedom for first-order tetrahedron

Prisms : As shown in figure Fig. 4 for the first-order prism, degrees of freedom along (\hat{x}, \hat{y}) are chosen as the tensorial product between a triangle equal to the triangular face of a tetrahedron and Gauss-Lobatto points. For the degrees of freedom oriented along \hat{z} , they are equal to the tensorial product of a nodal triangle of order $r+1$ and interior Gauss-Lobatto points.

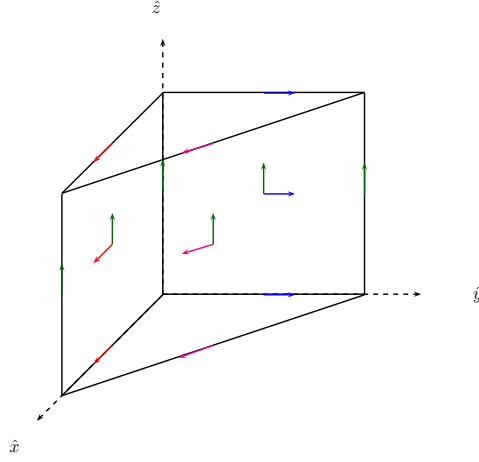


Figure 4: Location of degrees of freedom for first-order prism

Pyramids : As displayed in figure Fig. 5 for the first-order pyramid, degrees of freedom on the quadrilateral base are placed in the same way as a face of an hexahedron, degrees of freedom on the triangular faces are placed similarly to a face of a tetrahedron. Three degrees of freedom are associated with each interior point of a nodal pyramid of order $r+1$. The location of nodal points on the pyramid is detailed in (Bergot et al., 2010).

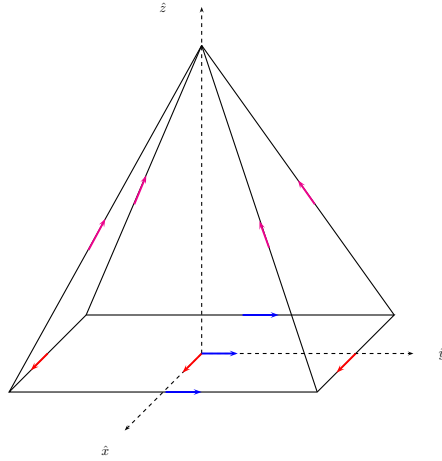


Figure 5: Location of degrees of freedom for first-order pyramid

The nodal basis functions $\hat{\varphi}$ are defined as follows:

Definition 3. Let (\hat{M}_i) be the position of degrees of freedom and \hat{t}_i the direction associated with each degree of freedom, and $(\psi_i)_{1 \leq i \leq n_r}$ a basis of the finite element space \hat{P}_r . The Vandermonde matrix is equal to:

$$VDM_{i,j} = \hat{\psi}_i(\hat{M}_j) \cdot \hat{t}_j, \quad 1 \leq i, j \leq n_r,$$

The basis function $\hat{\varphi}_i$ associated with the point \hat{M}_i is defined by the relation

$$\hat{\varphi}_i = \sum_{1 \leq j \leq n_r} (VDM^{-1})_{i,j} \hat{\psi}_j. \quad (5)$$

Remark 2. The points \hat{M}_i are specified with an orientation \hat{t}_i , but can correspond to a same geometric point (at most three degrees of freedom per geometric point).

Remark 3. The invertibility of Vandermonde matrix is an open issue, but with our choice of degrees of freedom, we have observed that this matrix is invertible, therefore the finite element is unisolvent.

The main drawback of nodal basis functions is the bad condition number of Vandermonde matrix, that can lead to important round-off errors in the computations. The figure Fig 6 shows the condition number of Vandermonde matrix for the optimal first family and first family in the case of tetrahedra, prisms and pyramids. We notice that the prism uses actually the Vandermonde matrix of a triangle, which contains much less degrees of freedom than tetrahedra. As a result the condition number of Vandermonde matrix for triangles is quite small.

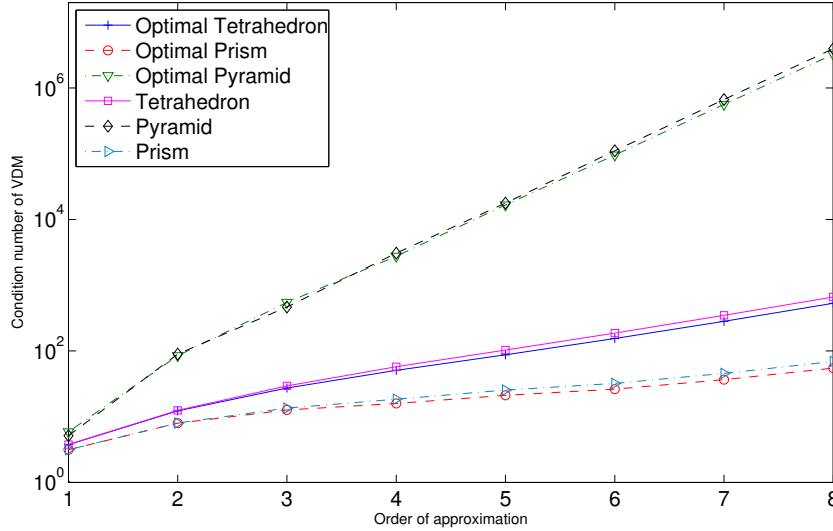


Figure 6: Condition number of Vandermonde matrix versus the order of approximation for first family and optimal first family for the tetrahedron, pyramid and prism.

It can be noticed that the condition number is not very different for the two families, the optimal finite element spaces providing a better condition number. For the first family \hat{P}_r^1 , Gauss points have been chosen instead of interior Gauss-Lobatto points. We remark that basis functions ψ_i chosen for the pyramid do not provide a good conditioning, which is problematic for $r \geq 5$. The basis functions ψ_i expressed on the cube chosen for the pyramid are the following

ones:

$$\begin{aligned}
& \left\{ \begin{bmatrix} P_{i,j,k} \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ P_{i,j,k} \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ P_{i,j,k} \end{bmatrix}, \begin{matrix} 0 \leq i, j \leq r-1 \\ 0 \leq k \leq r-1 - \max(i, j) \end{matrix} \right\} \\
& \left\{ P_p^{0,0}(\tilde{x}) P_p^{0,0}(\tilde{y}) (1-\tilde{z})^p \begin{bmatrix} \tilde{y} \\ \tilde{x} \\ \tilde{x}\tilde{y} \end{bmatrix}, 0 \leq p \leq r-1 \right\} \\
& \left\{ P_m^{0,0}(\tilde{x}) P_{n+2}^{0,0}(\tilde{y}) (1-\tilde{z})^{n+1} \begin{bmatrix} 1 \\ 0 \\ \tilde{x} \end{bmatrix}, P_{n+2}^{0,0}(\tilde{x}) P_m^{0,0}(\tilde{y}) (1-\tilde{z})^{n+1} \begin{bmatrix} 0 \\ 1 \\ \tilde{y} \end{bmatrix}, 0 \leq m \leq n \leq r-2 \right\} \\
& \left\{ P_p^{0,0}(\tilde{x}) P_q^{0,0}(\tilde{y}) (1-\tilde{z})^r \begin{bmatrix} 1 \\ 0 \\ \tilde{x} \end{bmatrix}, P_q^{0,0}(\tilde{x}) P_p^{0,0}(\tilde{y}) (1-\tilde{z})^r \begin{bmatrix} 0 \\ 1 \\ \tilde{y} \end{bmatrix}, \begin{matrix} 0 \leq p \leq r-1 \\ 0 \leq q \leq r+1 \end{matrix} \right\}
\end{aligned}$$

with

$$\begin{aligned}
\tilde{x} &= \frac{\hat{x}}{1-\hat{z}}, \quad \tilde{y} = \frac{\hat{y}}{1-\hat{z}}, \quad \tilde{z} = \hat{z} \\
P_{i,j,k} &= P_i^{0,0}(\tilde{x}) P_j^{0,0}(\tilde{y}) P_k^{2\max(i,j)+2,0}(2\tilde{z}-1)(1-\tilde{z})^{\max(i,j)}
\end{aligned}$$

This basis is written by using Jacobi polynomials $P_n^{\alpha,\beta}$ which are orthogonal with respect to weight $(1-x)^\alpha(1+x)^\beta$. In order to reduce the condition number, each basis function ψ_i is normalized so that $\|\psi_i\|_{L^2(\hat{K})} = 1$.

5. Hierarchical basis functions

Hierarchical basis functions are more popular in finite elements since they are often written with a tensorial structure in the cube, and they do not need the inversion of a Vandermonde matrix. Therefore, we present a hierarchical base for the optimal first family. Jacobi polynomials $P_{i,j}^{\alpha,\beta}$ are used, but other choices could be considered such as integrated Lobatto-shape functions (see (Solin et al., 2003)).

Proposition 2. *The following basis functions are an hierarchical basis $H(\text{curl})$ conforming of \hat{P}_r*

- **Hexahedron:** *We consider the following parameters (each parameter being associated with a face of the cube)*

$$\begin{aligned}
& \begin{cases} \lambda_1 = \hat{x} \\ \lambda_2 = \hat{y} \\ \lambda_3 = \hat{z} \end{cases} & \begin{cases} \lambda_4 = 1 - \hat{x} \\ \lambda_5 = 1 - \hat{y} \\ \lambda_6 = 1 - \hat{z} \end{cases}
\end{aligned}$$

HIERARCHICAL H(CURL) FUNCTIONS FOR THE CUBE

For an edge a : Let a_1 and a_2 the two faces that do not contain any vertex of a

If a is oriented along e_x

$$\begin{bmatrix} \lambda_{a_1} \lambda_{a_2} \\ 0 \\ 0 \end{bmatrix} P_i^{0,0}(2\hat{x} - 1), \quad 0 \leq i \leq r - 1$$

If a is oriented along e_y

$$\begin{bmatrix} 0 \\ \lambda_{a_1} \lambda_{a_2} \\ 0 \end{bmatrix} P_i^{0,0}(2\hat{y} - 1), \quad 0 \leq i \leq r - 1$$

If a is oriented along e_z

$$\begin{bmatrix} 0 \\ 0 \\ \lambda_{a_1} \lambda_{a_2} \end{bmatrix} P_i^{0,0}(2\hat{z} - 1), \quad 0 \leq i \leq r - 1$$

For a face f : Let f_1 be the face directly opposite to f

If f is in the plane (e_x, e_y)

$$\begin{bmatrix} \lambda_2 \lambda_5 \lambda_{f_1} \\ 0 \\ 0 \end{bmatrix} P_i^{0,0}(2\hat{x} - 1) P_j^{1,1}(2\hat{y} - 1) \\ \begin{bmatrix} 0 \\ \lambda_1 \lambda_4 \lambda_{f_1} \\ 0 \end{bmatrix} P_j^{1,1}(2\hat{x} - 1) P_i^{0,0}(2\hat{y} - 1) \quad 0 \leq i, j \leq r - 1$$

If f is in the plane (e_y, e_z)

$$\begin{bmatrix} 0 \\ \lambda_3 \lambda_6 \lambda_{f_1} \\ 0 \end{bmatrix} P_i^{0,0}(2\hat{y} - 1) P_j^{1,1}(2\hat{z} - 1) \\ \begin{bmatrix} 0 \\ 0 \\ \lambda_2 \lambda_5 \lambda_{f_1} \end{bmatrix} P_j^{1,1}(2\hat{y} - 1) P_i^{0,0}(2\hat{z} - 1) \quad 0 \leq i, j \leq r - 1$$

If f is in the plane (e_x, e_z)

$$\begin{bmatrix} \lambda_3 \lambda_6 \lambda_{f_1} \\ 0 \\ 0 \end{bmatrix} P_i^{0,0}(2\hat{x} - 1) P_j^{1,1}(2\hat{z} - 1) \\ \begin{bmatrix} 0 \\ 0 \\ \lambda_1 \lambda_4 \lambda_{f_1} \end{bmatrix} P_j^{1,1}(2\hat{x} - 1) P_i^{0,0}(2\hat{z} - 1) \quad 0 \leq i, j \leq r - 1$$

For the interior functions :

$$\begin{bmatrix} \lambda_2 \lambda_3 \lambda_5 \lambda_6 \\ 0 \\ 0 \end{bmatrix} P_k^{0,0}(2\hat{x} - 1) P_i^{1,1}(2\hat{y} - 1) P_j^{1,1}(2\hat{z} - 1) \\ \begin{bmatrix} 0 \\ \lambda_1 \lambda_3 \lambda_4 \lambda_6 \\ 0 \end{bmatrix} P_i^{1,1}(2\hat{x} - 1) P_k^{0,0}(2\hat{y} - 1) P_j^{1,1}(2\hat{z} - 1) \quad 0 \leq i, j, k \leq r - 1 \\ \begin{bmatrix} 0 \\ 0 \\ \lambda_1 \lambda_2 \lambda_4 \lambda_5 \end{bmatrix} P_i^{1,1}(2\hat{x} - 1) P_j^{1,1}(2\hat{y} - 1) P_k^{0,0}(2\hat{z} - 1)$$

- **Triangular prism:** We consider the following parameters (each parameter being associated with a face). The parameters λ are also associated with vertices of a triangular face.

$$\begin{cases} \lambda_1 = \lambda_4 = 1 - \hat{x} - \hat{y} \\ \lambda_2 = \lambda_5 = \hat{x} \\ \lambda_3 = \lambda_6 = \hat{y} \end{cases} \quad \begin{cases} \beta_1 = 1 - \hat{z} \\ \beta_2 = \hat{z} \end{cases}$$

HIERARCHICAL H(CURL) FUNCTIONS FOR THE PRISM

For an horizontal edge a : Let a_1 and a_2 the two extremities of the edge a , and f' the horizontal opposite face

$$(\lambda_{a_1} \nabla \lambda_{a_2} - \lambda_{a_2} \nabla \lambda_{a_1}) \beta_{f'} P_i^{0,0}(\lambda_{a_2} - \lambda_{a_1}), \quad 0 \leq i \leq r-1, \quad 1 \leq a \leq 6$$

For a vertical edge a : Let a_1 the face that does not contain any vertex of a

$$\begin{bmatrix} 0 \\ 0 \\ \lambda_{a_1} \end{bmatrix} P_i^{0,0}(\beta_2 - \beta_1), \quad 0 \leq i \leq r-1, \quad 1 \leq a \leq 3$$

For a quadrilateral face f : Let $[a_1, a_2]$ an edge in common with a triangular face f' , and f_1, f_2 the two other quadrilateral faces

$$\begin{aligned} & (\lambda_{a_1} \nabla \lambda_{a_2} - \lambda_{a_2} \nabla \lambda_{a_1}) \beta_1 \beta_2 P_i^{0,0}(\lambda_{a_2} - \lambda_{a_1}) P_j^{1,1}(2\hat{z} - 1) \\ & \begin{bmatrix} 0 \\ 0 \\ \lambda_{a_1} \lambda_{a_2} \end{bmatrix} P_j^{1,1}(\lambda_{a_2} - \lambda_{a_1}) P_i^{0,0}(2\hat{z} - 1) \quad \begin{matrix} 0 \leq i \leq r-1 \\ 0 \leq j \leq r-1 \end{matrix} \quad 1 \leq f \leq 3 \end{aligned}$$

For a triangular face f : Let $[a_1, a_2]$ and $[a_1, a_3]$ two edges of the triangular, f_1 and f_2 the associated quadrilateral faces, and f' the opposite triangular face

$$\begin{aligned} & (\lambda_{a_1} \nabla \lambda_{a_2} - \lambda_{a_2} \nabla \lambda_{a_1}) \lambda_{f_1} \beta_{f'} P_i^{0,0}(\lambda_{a_2} - \lambda_{a_1}) P_j^{0,0}(\lambda_{a_3} - \lambda_{a_1}) \\ & (\lambda_{a_1} \nabla \lambda_{a_3} - \lambda_{a_3} \nabla \lambda_{a_1}) \lambda_{f_2} \beta_{f'} P_i^{0,0}(\lambda_{a_2} - \lambda_{a_1}) P_j^{0,0}(\lambda_{a_3} - \lambda_{a_1}) \\ & i, j \geq 0, \quad 0 \leq i + j \leq r-2 \end{aligned}$$

For interior functions :

$$\begin{aligned} & (\lambda_2 \nabla \lambda_3 - \lambda_3 \nabla \lambda_2) \lambda_1 \beta_1 \beta_2 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \\ & (\lambda_1 \nabla \lambda_3 - \lambda_3 \nabla \lambda_1) \lambda_2 \beta_1 \beta_2 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \quad \begin{matrix} i, j \geq 0 \\ 0 \leq i + j \leq r-2 \end{matrix} \\ & \begin{bmatrix} 0 \\ 0 \\ \lambda_1 \lambda_2 \lambda_3 \end{bmatrix} P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \quad 0 \leq k \leq r-1 \end{aligned}$$

avec

$$P_{ijk}(\hat{x}, \hat{y}, \hat{z}) = P_i^{0,0}\left(\frac{2\hat{x}}{1-\hat{y}} - 1\right)(1-\hat{y})^i P_j^{2i+1,0}(2\hat{y}-1) P_k^{0,0}(2\hat{z}-1)$$

- **Pyramid:** We consider the following parameters:

$$\left\{ \begin{array}{l} \beta_1 = \frac{1 - \hat{x} - \hat{z}}{2} \\ \beta_2 = \frac{1 - \hat{y} - \hat{z}}{2} \\ \beta_3 = \frac{1 + \hat{x} - \hat{z}}{2} \\ \beta_4 = \frac{1 + \hat{y} - \hat{z}}{2} \end{array} \right. \quad \left\{ \begin{array}{l} \lambda_1 = \frac{\beta_1 \beta_2}{1 - \hat{z}} \\ \lambda_2 = \frac{\beta_2 \beta_3}{1 - \hat{z}} \\ \lambda_3 = \frac{\beta_3 \beta_4}{1 - \hat{z}} \\ \lambda_4 = \frac{\beta_4 \beta_1}{1 - \hat{z}} \\ \lambda_5 = \hat{z} \end{array} \right. \quad \left\{ \begin{array}{l} \gamma_1 = \frac{2\hat{z} + \hat{x} + \hat{y}}{2} \\ \gamma_2 = \frac{2\hat{z} - \hat{x} + \hat{y}}{2} \\ \gamma_3 = \frac{2\hat{z} - \hat{x} - \hat{y}}{2} \\ \gamma_4 = \frac{2\hat{z} + \hat{x} - \hat{y}}{2} \end{array} \right.$$

$$\left\{ \begin{array}{l} \delta_1 = \delta_3 = \hat{x} \\ \delta_2 = \delta_4 = \hat{y} \end{array} \right.$$

Parameters β_i are associated with triangular faces, since $\beta_i = 0$ is the equation of a triangular face i . Parameters λ_i are associated with vertices, since $\lambda_i(S_j) = \delta_{i,j}$, S_j being the vertices. Parameters γ_i are parametrizations of vertical edges, and δ_i parametrizations of horizontal edges.

H(CURL) FUNCTIONS FOR THE PYRAMID

For an horizontal edge a : *The edge is oriented from vertex a_1 to vertex a_2 , and the adjacent horizontal edges are $[a_1, a_4]$ et $[a_2, a_3]$*

$$(\lambda_{a_1} \nabla(\lambda_{a_2} + \lambda_{a_3}) - \lambda_{a_2} \nabla(\lambda_{a_1} + \lambda_{a_4})) P_i^{0,0}(\delta_a), \quad 0 \leq i \leq r-1$$

For a vertical edge a : *Let s the vertex of a belonging to the base*

$$(\lambda_s \nabla \lambda_5 - \lambda_5 \nabla \lambda_s) P_i^{0,0}(\gamma_s), \quad 0 \leq i \leq r-1, \quad 1 \leq a \leq 4$$

For the base :

$$\begin{aligned} & (\lambda_1 \nabla(\lambda_2 + \lambda_3) - \lambda_2 \nabla(\lambda_1 + \lambda_4)) \beta_4 P_i^{0,0} \left(\frac{\beta_3 - \beta_1}{1 - \hat{z}} \right) P_j^{1,1} \left(\frac{\beta_4 - \beta_2}{1 - \hat{z}} \right) (1 - \hat{z})^{\max(i,j)-1} \\ & (\lambda_1 \nabla(\lambda_3 + \lambda_4) - \lambda_4 \nabla(\lambda_2 + \lambda_1)) \beta_3 P_j^{1,1} \left(\frac{\beta_3 - \beta_1}{1 - \hat{z}} \right) P_i^{0,0} \left(\frac{\beta_4 - \beta_2}{1 - \hat{z}} \right) (1 - \hat{z})^{\max(i,j)-1} \\ & 0 \leq i, j \leq r-1 \end{aligned}$$

For a triangular face f : *Let $[a_1, a_2]$ the horizontal edge, and $[a_1, a_4]$ et $[a_2, a_3]$ the two adjacent edges, and f_1 the triangular face of base $[a_1, a_4]$*

$$\begin{aligned} & (\lambda_{a_2} \nabla(\lambda_{a_1} + \lambda_{a_4}) - \lambda_{a_1} \nabla(\lambda_{a_2} + \lambda_{a_3})) \lambda_5 P_i^{0,0}(\delta_f) P_j^{0,0}(\gamma_{a_1}) \\ & (\lambda_{a_1} \nabla \lambda_5 - \lambda_5 \nabla \lambda_{a_1}) \beta_{f_1} P_i^{0,0}(\delta_f) P_j^{0,0}(\gamma_{a_1}) \end{aligned} \quad 0 \leq i + j \leq r-2$$

For interior functions :

$$\begin{aligned} & (\lambda_1 \nabla(\lambda_2 + \lambda_3) - \lambda_2 \nabla(\lambda_1 + \lambda_4)) \beta_4 \lambda_5 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \\ & (\lambda_1 \nabla(\lambda_3 + \lambda_4) - \lambda_4 \nabla(\lambda_2 + \lambda_1)) \beta_3 \lambda_5 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \quad \begin{array}{l} 0 \leq i, j \leq r-2, \\ 0 \leq k \leq r-2 - \max(i, j) \end{array} \\ & (\lambda_1 \nabla \lambda_5 - \lambda_5 \nabla \lambda_1) \beta_3 \beta_4 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \end{aligned}$$

with

$$P_{ijk}(\hat{x}, \hat{y}, \hat{z}) = P_i^{0,0} \left(\frac{\beta_3 - \beta_1}{1 - \hat{z}} \right) P_j^{0,0} \left(\frac{\beta_4 - \beta_2}{1 - \hat{z}} \right) P_k^{2\max(i,j)+2,0} (2\hat{z} - 1) (1 - \hat{z})^{\max(i,j)-1}$$

- **Tetrahedron:** We consider the following parameters

$$\begin{cases} \lambda_1 = 1 - \hat{x} - \hat{y} - \hat{z} \\ \lambda_2 = \hat{x} \\ \lambda_3 = \hat{y} \\ \lambda_4 = \hat{z} \end{cases}$$

The parameters λ_i are associated with faces, since $\lambda_i = 0$ is the equation of face i . They are also associated with vertices since $\lambda_i(S_j) = \delta_{i,j}$, S_i being the vertices.

HIERARCHICAL H(CURL) FUNCTIONS FOR A TETRAHEDRON

For an edge a : The edge is oriented from vertex a_1 to vertex a_2

$$(\lambda_{a_1} \nabla \lambda_{a_2} - \lambda_{a_2} \nabla \lambda_{a_1}) P_i^{0,0}(\lambda_{a_2} - \lambda_{a_1}), \quad 0 \leq i \leq r-1, \quad 1 \leq a \leq 6$$

For a triangular face f : Let a_1, a_2 and a_3 the vertices f , f_1 the other face containing edge $[a_1, a_2]$ and f_2 the other face containing $[a_1, a_3]$

$$\begin{aligned} & (\lambda_{a_1} \nabla \lambda_{a_2} - \lambda_{a_2} \nabla \lambda_{a_1}) \lambda_{f_1} P_{ij}(\hat{x}, \hat{y}, \hat{z}) \\ & (\lambda_{a_1} \nabla \lambda_{a_3} - \lambda_{a_3} \nabla \lambda_{a_1}) \lambda_{f_2} P_{ij}(\hat{x}, \hat{y}, \hat{z}) \end{aligned} \quad 0 \leq i+j \leq r-2$$

with

$$P_{ij}(\hat{x}, \hat{y}, \hat{z}) = P_i^{0,0}(\lambda_{a_2} - \lambda_{a_1}) P_j^{0,0}(\lambda_{a_3} - \lambda_{a_1})$$

For interior functions :

$$\begin{aligned} & (\lambda_1 \nabla \lambda_4 - \lambda_4 \nabla \lambda_1) \lambda_2 \lambda_3 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \\ & (\lambda_1 \nabla \lambda_2 - \lambda_2 \nabla \lambda_1) \lambda_3 \lambda_4 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \\ & (\lambda_1 \nabla \lambda_3 - \lambda_3 \nabla \lambda_1) \lambda_2 \lambda_4 P_{ijk}(\hat{x}, \hat{y}, \hat{z}) \end{aligned} \quad 0 \leq i+j+k \leq r-3$$

with

$$\begin{aligned} P_{ijk}(\hat{x}, \hat{y}, \hat{z}) = & P_i^{0,0}\left(\frac{2\hat{x}}{1-\hat{y}-\hat{z}} - 1\right) P_j^{2i+1,0}\left(\frac{2\hat{y}}{1-\hat{z}} - 1\right) \\ & (1-\hat{y}-\hat{z})^i (1-\hat{z})^j P_k^{2(i+j+1),0}(2\hat{z}-1) \end{aligned}$$

By construction, these hierarchical functions are a base of the optimal spaces \hat{P}_r for each element, and the restriction on triangular faces and quadrilateral faces coincide if the orientation is the same. For quadrilateral faces, when the orientation is different, signs have to be considered. For triangular faces, a linear operator, involving degrees of freedom associated with the interior of the face, is considered.

6. Comparison With Other Pyramidal Elements

In this section, a comparison with previous elements proposed in the literature is performed.

- For $r = 1$, the first family space \hat{P}_r^1 (see remark 1) is exactly the same as proposed in (Coulomb et al., 1997), (Graglia and Gheorma, 1999), (Doucet et al., 2008), (Nigam and Phillips, 2007).

- The finite element space proposed in (Gradinaru and Hiptmair, 1999) is the same, if we change basis functions into the followings γ_6 and γ_7 :

$$\gamma_6 = \begin{bmatrix} -z + \frac{yz}{1-z} \\ \frac{xz}{1-z} \\ x - \frac{xy}{1-z} + \frac{xyz}{(1-z)^2} \end{bmatrix}, \quad \gamma_7 = \begin{bmatrix} \frac{yz}{1-z} \\ -z + \frac{xz}{1-z} \\ y - \frac{xy}{1-z} + \frac{xyz}{(1-z)^2} \end{bmatrix}$$

- In (Nigam and Phillips, 2007), the vertical basis functions must be corrected to ensure that tangential restrictions are polynomial on triangular faces:

$$\tilde{F}_{e_1} = \left\{ \frac{1}{(1+z)^{k+1-\gamma}} \begin{bmatrix} -z(y-1) \\ -z(x-1) \\ (x-1)(y-1) \end{bmatrix}, 0 \leq \gamma \leq k-1 \right\}$$

Once this correction is applied, it is easy to check the space generated by basis functions of the first family \hat{P}_r^1 associated with edges and faces (by adapting basis functions of proposition 2) is the same space generated by edge and face basis functions proposed in (Nigam and Phillips, 2007). Therefore the difference between our finite element space and Nigam & Phillips' one is due to interior basis functions. The proposed interior space in (Nigam and Phillips, 2007) contains $3r(r-1)^2$ degrees of freedom, therefore $r(r-1)(4r-5)/2$ more degrees of freedom compared to \hat{P}_r^1 , and the same convergence rate is observed.

- The second space proposed by (Nigam and Phillips, 2009) is much smaller, since its dimension is equal to $r(2r^2 + 7r + 7)/2$, that is $r(r-1)$ less degrees of freedom than \hat{P}_r^1 . However, this second space does not include the first-order optimal space \hat{P}_1 . Indeed the following basis functions are not included:

$$\begin{bmatrix} \frac{\hat{y}^2}{1-\hat{z}} \\ 0 \\ \frac{\hat{x}\hat{y}^2}{(1-\hat{z})^2} \end{bmatrix} \quad \begin{bmatrix} 0 \\ \frac{\hat{x}^2}{1-\hat{z}} \\ \frac{\hat{x}^2\hat{y}}{(1-\hat{z})^2} \end{bmatrix}$$

Since \mathcal{R}_r is included, the space proposed in (Nigam and Phillips, 2009) will provide an optimal convergence for affine pyramids, but will be not consistent for non-affine pyramids.

- Zaglmayr cited by (Demkowicz et al., 2007) propose a space presented as a Nédélec's second family space. However a practical expression of this space is difficult to obtain, and basis functions are not provided. Moreover, it seems that the dimension of space contains four degrees of freedom for $r = 1$ and 21 degrees of freedom for $r = 2$, which is problematic because 21 is less than the number of degrees of freedom needed to ensure the tangential continuity with the other types of faces. We hope that a future publication of Zaglmayr will clarify the situation.
- Second-order basis functions proposed by (Coulomb et al., 1997) do not seem to be appropriate, since basis functions related to faces vanish completely on other faces, whereas only the tangential trace should vanish. Furthermore, spurious modes are observed with these basis functions, this observation is also confirmed by (Marais and Davidson, 2008).
- (Graglia and Gheorma, 1999) propose nodal basis functions on the pyramid. These functions are constructed from the first-order basis functions of \hat{P}_1^1 by multiplying them by polynomials, whereas it should involve rational fractions. As a result, the optimal space \hat{P}_1 is never included by these functions, leading to non-consistent space with non-affine pyramids. Moreover, spurious modes are observed with affine pyramids, as stated by (Marais and Davidson, 2008).

- (Marais and Davidson, 2008) propose to split pyramids in two tetrahedra. A similar approach (Bluck and Walker, 2008) has been proposed for continuous elements, but the extension to higher order is non consistent for non-affine pyramids (see (Bergot et al., 2010)). Therefore we did not test this approach for edge elements.

The table Tab. 1 summarizes the properties of the different spaces.

Table 1: Inclusion of Nigam/Phillips, Graglia and Zgainski finite element spaces for $r \geq 2$

Space V_r	Inclusion in first family \hat{P}_r^1	Inclusion in optimal first family \hat{P}_r
Zgainski	$\hat{P}_1^1 \subset V_2$	$\hat{P}_1 \subset V_2 \subset \hat{P}_3$
Graglia	$\hat{P}_1^1 \subset V_2$	$\hat{P}_1 \subsetneq V_2$
(Nigam and Phillips, 2007)	$\hat{P}_r^1 \subset V_r$	$\hat{P}_{r-1} \supset V_r$
(Nigam and Phillips, 2009)	$\hat{P}_1^1 \subset V_1$	$\hat{P}_1 \subsetneq V_r$

A dispersion analysis (see (Bergot et al., 2010) for more details) has been performed for the different finite element spaces for a mesh made of a repeated cell composed of non-affine pyramids and affine pyramids, as shown in Fig. 7. The dispersion error obtained for these kinds of meshes is displayed in Fig. 8. For affines pyramids, Nigam & Phillips' spaces and optimal spaces give a dispersion error in $O(h^{2r})$ as expected, whereas Graglia and Zgainski basis functions give an error in $O(h^2)$ only. For non-affine pyramids, optimal spaces give again a dispersion error in $O(h^{2r})$, whereas the first space of Nigam & Phillips provide an error in $O(h^{2r-2})$, the second space being non-consistent.

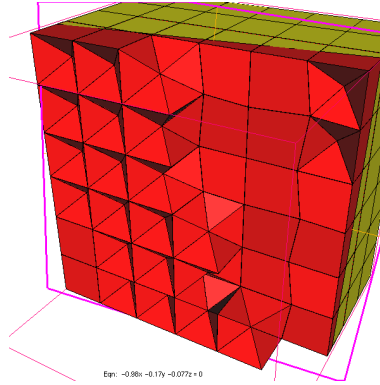


Figure 7: Pyramidal mesh used for the dispersion analysis.

We have also checked the accuracy of the source problem (1) for the same family of meshes, the error obtained between the numerical solution and a reference solution is displayed in Fig. 8. We can see that the optimal finite element space gives a better accuracy than the spaces described in (Coulomb et al., 1997), (Nigam and Phillips, 2007), (Graglia and Gheorma, 1999). Due to the presence of spurious modes, the spaces of (Coulomb et al., 1997) and (Graglia and Gheorma, 1999) may lead to non-convergent solutions. We have numerically computed eigenmodes in a cubic cavity, we observed spurious modes for these spaces, whereas no spurious mode was observed for the optimal finite element spaces or spaces proposed by (Nigam and Phillips, 2007). Numerical properties of different spaces are summarized in table Tab. 2. By compatibility, we mean the compatibility with other elements (hexahedra and tetrahedra).

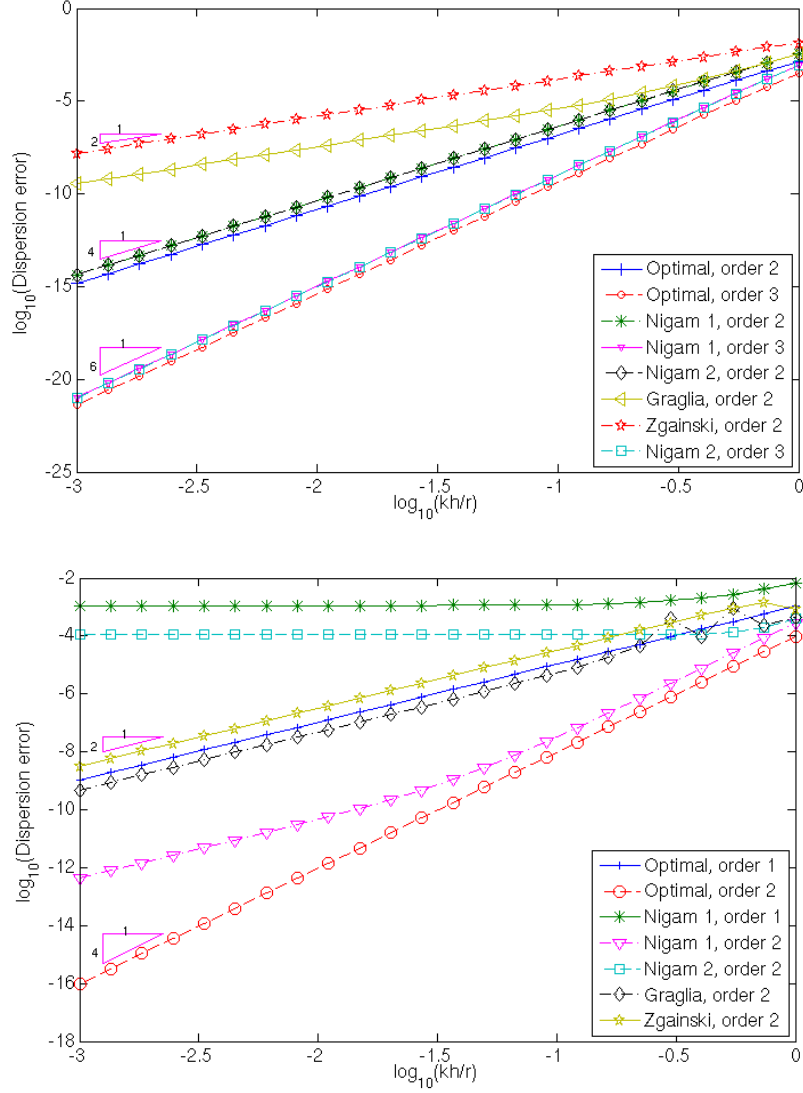


Figure 8: Dispersion error in log-log scale for a mesh comprising affine pyramids for the curve on top, and for a mesh comprising affines and non-affine pyramids for the bottom curve.

Table 2: Properties of different finite element spaces

Property	Zgainski, $r = 2$	Graglia, $r = 2$	Nigam/Phillips 1	Nigam/Phillips 2	Optimal
Convergence with affine pyramids	$O(h)$	$O(h)$	$O(h^r)$	$O(h^r)$	$O(h^r)$
Convergence with non-affine pyramids	$O(h)$	$O(1)$	$O(h^{r-1})$	$O(1)$	$O(h^r)$
Spurious modes	yes	yes	no	no	no
Compatibility	no	yes	yes	yes	yes

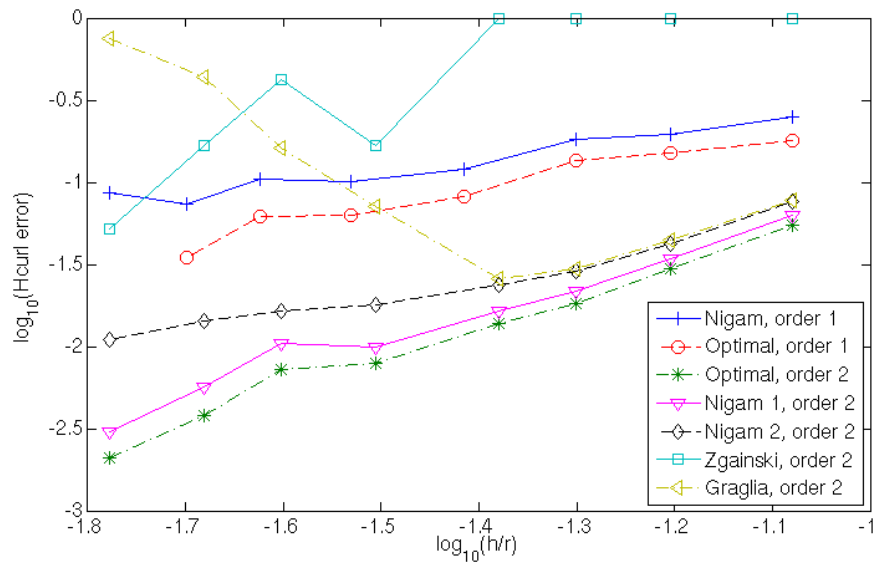


Figure 9: $H(\text{curl})$ -error in log-log scale for a mesh comprising affines and non-affine pyramids (Gaussian source inside a cubic cavity).

7. Numerical Results

In this section, the following scattering problem will be solved

$$\begin{cases} -\omega^2 \varepsilon E + \text{curl}(\frac{1}{\mu} \text{curl} E) = f \text{ in } \Omega \\ E \times n = -E^{\text{inc}} \times n \text{ on } \Gamma \\ \text{curl} E \times n = i k (n \times E) \times n \text{ on } \Sigma \end{cases}$$

where n is the normal to the boundary, Ω the computational domain, Γ the scattered object and Σ the external boundary.

The wave number k is equal to

$$k = \omega \sqrt{\varepsilon \mu}$$

And the incident field is chosen as a plane wave

$$E^{\text{inc}} = E^0 \exp(i \vec{k} \cdot x)$$

where \vec{k} is the wave vector and E_0 the polarization (we will chose $E^0 = e_x$). Here, an homogeneous media will be treated, i.e :

$$\varepsilon = \mu = 1$$

The boundary condition set on Σ is the Silver-Muller condition.

As a first validation, we consider the scattering of the sphere of radius 2 and $\omega = 2\pi$. A family of hybrid meshes (generated with Harpoon mesh generator) of the cube $[-3, 3]$ containing a sphere of radius 2 (see Fig. 10). The

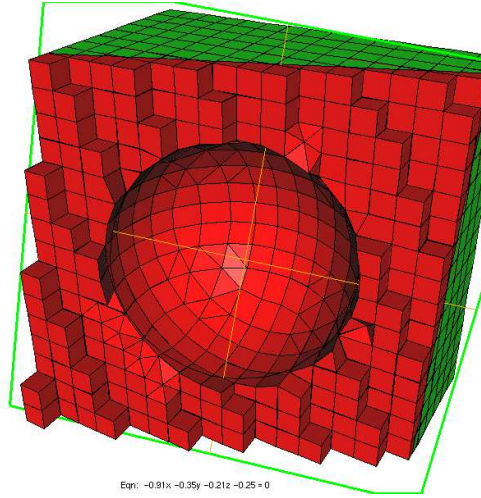


Figure 10: Example of hybrid mesh used for the scattering by a sphere

solution obtained is displayed in figure Fig. 11. On this simple shape, curved elements are used to approximate accurately the geometry. A reference solution is computed on a purely hexahedral mesh with $r = 8$ and containing about 4 million degrees of freedom. The convergence of the numerical solution obtained with Nédélec first family space \hat{P}_r^1 and optimal finite element spaces is plotted in figure Fig. 12. It can be noticed that optimal finite element spaces provide a better accuracy for a same mesh size. However, it is important to remind that the number of degrees of freedom will be more important with the optimal spaces.

In order to validate hierarchical basis functions, we have used a variable order for the scattering of a satellite, the hybrid surface mesh of the object is displayed in figure Fig. 13. Because of thin solar panels and the presence of thin slots, some geometric details need very fine cells in order to be correctly approximated. In that regions, the geometric

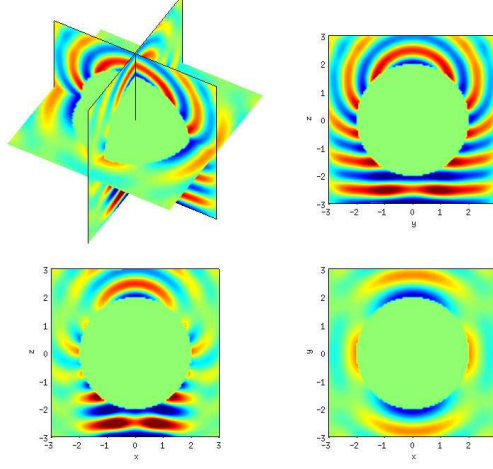


Figure 11: Real part of the diffracted field E_x for a sphere of radius 2.

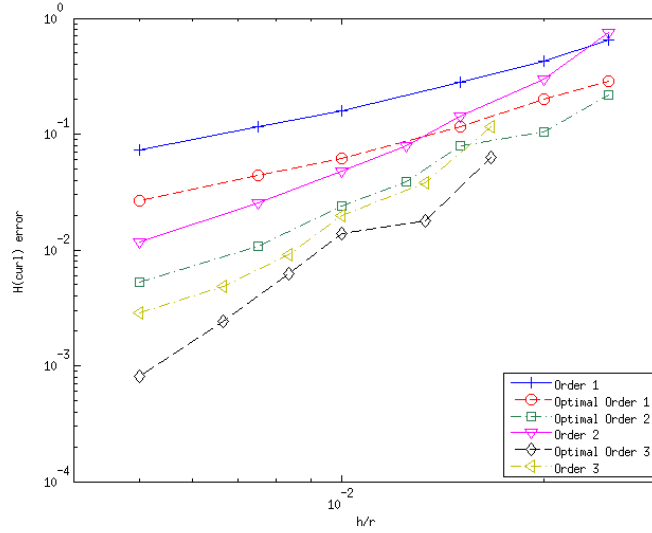


Figure 12: Convergence obtained for the perfectly conducting sphere with first family \hat{P}_r^1 and optimal first family \hat{P}_r .

step is much smaller than the wavelength, and first or second-order approximation is sufficient, whereas an high order of approximation is used for large cells in order to fit the thumb rule “10 points per wavelength”. This rule is corrected since 10-th order element provide good results with 5 points per wavelength whereas first-order elements often need twenty or more points per wavelength. Thanks to that rule, an order of approximation is computed for each edge of the mesh, then the order associated with each face is set to the maximum among edges of the face. The order associated with the interior of the element is set to the maximum among edges of the element. In the hierarchical functions given in section 5, the order r is actually different for each edge, face and interior of the element. The order associated with elements of the mesh is displayed in figure 14. The diffracted and total field are computed with Nédélec’s first family \hat{P}_r^1 (see Fig 15). The mesh contains 35006 tetrahedra, 50390 hexahedra (40 659 affine hexahedra), 48865 pyramids (40 508 affine pyramids), 4582 wedges. With our strategy of adaptive order, the number of degrees of freedom is equal to 2 570 034. Because of the large amount of affine elements and the reduced number of degrees of freedom, the use of Nédélec’s first family \hat{P}_r^1 seems relevant.

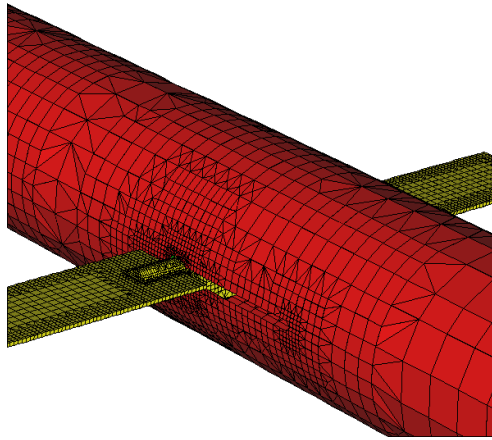


Figure 13: Surface of the hybrid mesh used for the scattering by a satellite

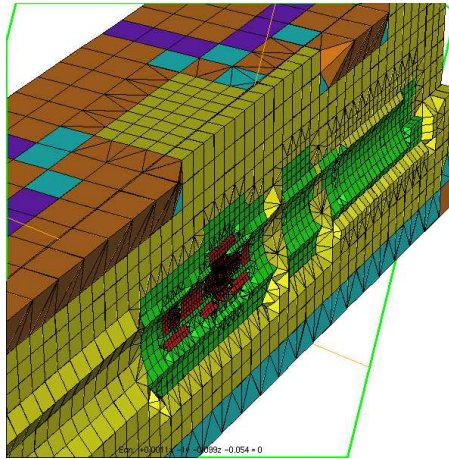


Figure 14: Hybrid mesh used for the scattering by a satellite. Each color is associated with a different order of approximation (red : 1, green : 2, yellow : 3, cyan : 4, orange : 5, purple : 6)

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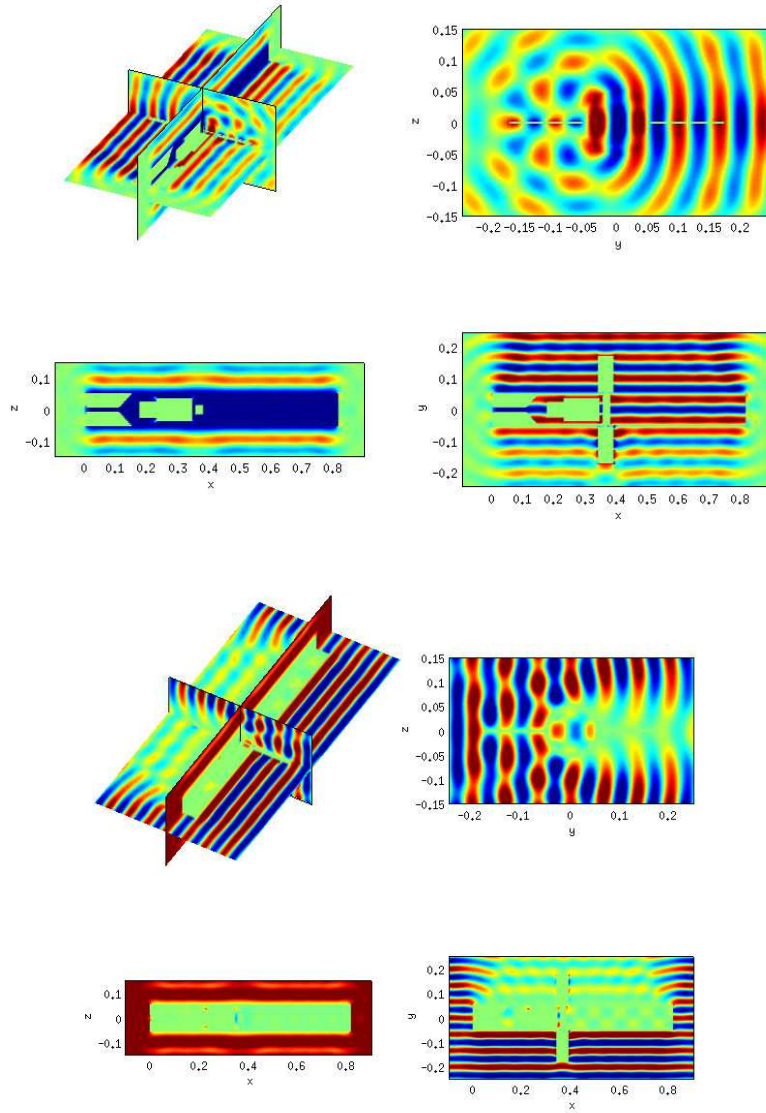


Figure 15: On top, real part of diffracted field E_x , and on bottom the total field. Scattering by a satellite

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