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# About the modelling of Flocculation in the Chemostat \*

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#### Abstract

In this work, we study a model of the chemostat where the species are present in two forms, isolated bacteria, and flocks of bacteria. We show that our model contains a lot of models which was considered in the litterature. We assume that the dynamics of flocculation and deflocculation are fast with respect to the growth of the species and we consctruct a reduced model for which the growth functions depend on the density of the species.

**Keywords**. Chemostat, density dependent growth functions, flocculation.

## 1 Introduction

In culture of micro-organisms, the attachement of microbial individuals occurs frequently. The attachement can be either a "wall attachement" such as in the growth of biofilms [5, 7], or simply an agregation such as in the formation of flocks [44]. Flock formation is often observed in microbial engineering systems such as biological wastewater processing [29, 25, 6] and yeast fermentation [12]. It has a direct impact on growth dynamics, as access to the substrate is limited for micro-organisms inside the flocks. The mechanisms of attachement and detachment result from the coupling of hydrodynamics conditions and biological properties, but are not yet completly understood at the level of microbial individuals. Several attempts of computer models, using individual based representations, have been proposed and are under investigation for the simulation of these phenomenons [21, 4, 37, 35, 16, 33, 32, 22, 36, 17, 34, 38]. At a macroscopic level, substrate limitation can be measured experimentally in biofilms or flocks [45, 25, 6]. A rough representation, suited to the macroscopic level, consists in spliting the overall biomass into two parts: a" planctonic biomass",

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composed of free individuals and a "attached biomass" composed of indivuals that are stick together [23]. This consideration leads to a significant change on the performances of bioprocesses, compared to purely planctonic cultures. In a chemostat-like device, planctonic cells are expected to consume easily the substrates necessary for their growth, but are more keen to be carried off by the flow. On the contrary, cells among agregates or biofilms have a more difficult access to the ressources of the bulk fluid, but are more resistant to detachement induced by flow. Therefore, mathematical models are expected to understand and predict the issues of these trade-off. Several extensions of the well-known chemostat model [41], considering two compartments of free and attached biomass for each species have been proposed and studied in the literature. In models with wall attachement [3, 30, 2, 43, 42, 1, 19], attached biomass is assumed to be fixed, and detached individuals return directly to the planctonic compartment. In models with agregation, agregates are carried away by the flow but bacteria inside flocks are assumed to have no or reduced access to bulk ressources [13, 14]. Considering that attachment and detachment processes are usually fast compared to biological time, it is shown in [14] that the reduced dynamics of such systems amounts to have a single biomass compartment for each strain but with a density dependant growth rate. This justifies the consideration of density dependant growth functions of the chemostat model, as already introduced in the literature. In [27, 28, 26, 24], it has been shown that this could lead to the coexistence of several species in competition on a same limiting resource, invalidating the Competitive Exclusion Principle [15].

In [14], the agregates are assumed to have no biological growth (i.e. the attchement process is the only source of increase of the attached biomass). Agregates are also assumed to be washed-out with the same dilution rate than planctonic cells. On the opposite, in wall attachment models, the attached biomass is not washed out at all. We believe that these two opposite cases (same dilution rate than planctonic biomass or no dilution rate) are too extreme to be fully realistic. We propose in this paper to revist the chemostat model with two compartments, planctonic and aggregated biomass, but assuming that each biomass has its own growth rate and apparent dilution rate. This generalizes the two kind of models that we mention previously.

#### 2 Flocks of bacteria

Consider the following model of the chemostat in which a population of microorganisms compete for a single growth-limiting substrate [31, 41]:

$$\begin{cases} S' = D[S_{in} - S] - k\mu(S)X \\ X' = [\mu(S) - D_1]X \end{cases}$$

In these equations, S(t) denotes the concentration of the substrate at time t; X(t) denotes the concentration of the population of microorganisms at time t;  $\mu(S)$  represents the per-capita growth rate of the population and so Y = 1/k is the growth yield;  $S_{in}0$  and D denote, respectively, the concentration of substrate

in the feed bottle and the flow rate of the chemostat; each  $D_1$  represents the removal rate of the population.

Assume that the species is present in two forms: isolated bacteria, of density  $X_L$ , and flocks of bacteria, of density  $X_A$ . Isolated bacteria and flocks can stick together to form new flocks, with rate  $\alpha(\cdot)X_L$ , and flocks can split and liberate isolated bacteria, with rate  $\beta(\cdot)X_A$ :

$$X_L \xrightarrow{\alpha(\cdot)X_L} X_A, \qquad X_L \xleftarrow{\beta(\cdot)X_A} X_A.$$

One obtains the following equations [39]:

$$\begin{cases}
\dot{S} = D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\
\dot{X}_L = (\mu_L(S) - D_L)X_L - \alpha(\cdot)X_L + \beta(\cdot)X_A \\
\dot{X}_A = (\mu_A(S) - D_A)X_A + \alpha(\cdot)X_L - \beta(\cdot)X_A
\end{cases} \tag{1}$$

# 3 Examples

Some of the models considered in the existing litterature are examples of (1)

## 3.1 Adaptative nutrient uptake

Here  $X_L$  denotes the low growing cells and  $X_A$  denotes the fast growing cells. Let  $\alpha(\cdot) = \alpha(S)$ , and  $\beta(\cdot) = \beta(S)$  then (1) becomes the model considered in [40]:

$$\begin{cases} \dot{S} &= D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\ \dot{X}_L &= (\mu_L(S) - D_L)X_L - \alpha(S)X_L + \beta(S)X_A \\ \dot{X}_A &= (\mu_A(S) - D_A)X_A + \alpha(S)X_L - \beta(S)X_A \end{cases}$$

#### 3.2 Wall growth

Here  $X_L$  denotes the density of isolated bacteria, and  $X_A$  denotes the density of attached bacteria. Let  $\alpha(\cdot) = a$ , and  $\beta(\cdot) = b$ , then (1) becomes the model considered By Pilyugin and Waltman [30]:

$$\begin{cases} \dot{S} &= D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\ \dot{X}_L &= (\mu_L(S) - D_L)X_L - aX_L + bX_A \\ \dot{X}_A &= (\mu_A(S) - D_A)X_A + aX_L - bX_A \end{cases}$$

#### 3.3 Freter model

The previous model is a particular case of the model of Freter [10, 11, 19] for which

$$\alpha(\cdot) = a[1 - W], \quad \beta(\cdot) = b + \mu_A(S)[1 - G(W)]$$

where  $W = X_A/X_{A\max}$  eand G(W) is decreasing

$$\begin{cases} \dot{S} &= D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\ \dot{X}_L &= (\mu_L(S) - D_L)X_L - a(1 - W)X_L \\ &+ bX_A + \mu_A(S)[1 - G(W)]X_A \\ \dot{X}_A &= (\mu_A(S)G(W) - D_A - b)X_A + a[1 - W]X_L \end{cases}$$

In the case where  $X_{A\max} = \infty$  one obtains W = 0 and if G(0) = 1 then  $\alpha(\cdot) = a$  and  $\beta(\cdot) = b$ .

#### 3.4 Flocs of two bacteria

If one takes  $\alpha(\cdot) = aX_L$  and  $\beta(\cdot) = b$ , then (1) becomes

$$\begin{cases}
\dot{S} = D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\
\dot{X}_L = (\mu_L(S) - D_L)X_L - aX_L^2 + bX_A \\
\dot{X}_A = (\mu_A(S) - D_A)X_A + aX_L^2 - bX_A
\end{cases} (2)$$

This model considered by Hagueman and Rapaport [14, 9] in the case  $\mu_A(S) = 0$  where the bacteria in flocks does not consume the substrate and by Fekih-Salem and ali [9] in the more general case  $0 \le \mu_A(S) \le \mu_L(S)$  where the bacteria in flocs consume less of the substrate than the isolated bacteria. This model was extended also to case of flocs with an arbitrary numbers of bacterias [13]

#### 3.5 Biomass in flocs

If one takes  $\alpha(\cdot) = a(X_L + X_A)$  and  $\beta(\cdot) = b$  one obtains the following model

$$\begin{cases}
\dot{S} = D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\
\dot{X}_L = (\mu_L(S) - D_L)X_L - a(X_L + X_A)X_L + bX_A \\
\dot{X}_A = (\mu_A(S) - D_A)X_A + a(X_L + X_A)X_L - bX_A
\end{cases}$$
(3)

In this model [39] we do not take in consideration the sizes of the flocks. The biomass of isolated bacteria is denoted by  $X_L$  and the biomass in flocks is denoted by  $X_A$ . Hence isolated bacteria and isolated bacteria or flocks can stick together to form new flocks, with rate  $a(X_L + X_A)X_L$  proportional to both the density of isolated bacteria, that is  $X_L$ , and the total biomass density, that is  $X_L + X_A$ , and flocks can split and liberate isolated bacteria, with rate  $bX_A$  proportional the their density  $X_A$ .

# 4 Two time scales

The general model for the flocculation is

$$\begin{cases} \dot{S} &= D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\ \dot{X}_L &= (\mu_L(S) - D_L)X_L \\ &- \alpha(S, X_A, X_L)X_L + \beta(S, X_A, X_L)X_A \\ \dot{X}_A &= (\mu_A(S) - D_A)X_A \\ &+ \alpha(S, X_A, X_L)X_L - \beta(S, X_A, X_L)X_A \end{cases}$$

We assume that the dynamics of flocculation and deflocculation is faster than the growth of the species.

$$\begin{cases}
\dot{S} = D(S_{in} - S) - \mu_L(S)X_L - \mu_A(S)X_A \\
\dot{X}_L = (\mu_L(S) - D_L)X_L - \frac{\alpha(\cdot)}{\varepsilon}X_L + \frac{\beta(\cdot)}{\varepsilon}X_A \\
\dot{X}_A = (\mu_A(S) - D_A)X_A + \frac{\alpha(\cdot)}{\varepsilon}X_L - \frac{\beta(\cdot)}{\varepsilon}X_A
\end{cases} \tag{4}$$

Notice that

$$\dot{X} = (\mu_L(S) - D_L)X_L + (\mu_A(S) - D_A)X_A$$

where  $X = X_L + X_A$  is the total biomass. Thus

- $X_L$  and  $X_A$ : are fast variables,
- S and  $X = X_L + X_A$ : are slow variables.

On the slow manifold  $\dot{X}_L = 0$  (or  $\dot{X}_A = 0$ ) one has  $\alpha(\cdot)X_L = \beta(\cdot)X_A$ . Thus, the slow manifold is obtained by solving the system

$$\alpha(S, X_L, X_A)X_L = \beta(S, X_L, X_A)X_A,$$
$$X_L + X_A = X$$

Hence one has

$$X_L = p(S, X)X,$$
  $X_A = (1 - p(S, X))X.$ 

The reduced model is obtained by replacing the fast variables  $X_L$  and  $X_A$  in the equation of S and X:

$$\begin{cases}
\dot{S} = D(S_{in} - S) - \mu(S, X)X \\
\dot{X} = \left[\mu(S, X) - D(S, X)\right]X
\end{cases}$$
(5)

where

$$\mu(S, X) = p(S, X)\mu_L(S) + (1 - p(S, X))\mu_A(S),$$
  
$$D(S, X) = p(S, X)D_L + (1 - p(S, X))D_A.$$

Notice that p(S, X) depends on functions  $\alpha(.)$  and  $\beta(.)$ . This is a density dependent growth function model [27, 28, 26].

**Examples** For system (2) one has

$$\frac{\alpha(\cdot)}{\varepsilon} = \frac{a}{\varepsilon} X_L, \quad \frac{\beta(\cdot)}{\varepsilon} = \frac{b}{\varepsilon}, \qquad p(X) = \frac{2}{1 + \sqrt{1 + 4a/bX}}.$$

For system (3) one has

$$\frac{\alpha(\cdot)}{\varepsilon} = \frac{a}{\varepsilon}X, \quad \frac{\beta(\cdot)}{\varepsilon} = \frac{b}{\varepsilon}, \qquad p(X) = \frac{b}{b+aX}.$$

**Theorem 4.1** Let  $(S(t), X_L(t), X_A(t))$  be the solution of (4) with initial condition

$$S(0) \ge 0,$$
  $X_L(0) > 0, X_A(0) \ge 0$ 

Let  $(\overline{S}(t), \overline{X}(t))$  be the solution of the reduced problem (5) with initial conditions

$$\overline{S}(0) = S(0), \qquad \overline{X}(t) = X_L(0) + X_A(0)$$

Then we have

$$S(t) \approx \overline{S}(t), \qquad X(t) \approx \overline{X}(t)$$

uniformly for  $t \in [0, +\infty[$ , and

$$X_L(t) \approx p(\overline{S}(t), \overline{x}(t)) \overline{X}(t), \qquad X_A(t) \approx (1 - p(\overline{S}(t), \overline{x}(t))) \overline{x}(t)$$

uniformly for  $t \in [t_0, +\infty[$ , where  $t_0 > 0$  is arbitrarily small,

# 5 Density dependent growth function

These examples have motivated the study of the reduced model

$$\begin{cases} \dot{S} = D(S_{in} - S) - \mu(S, X)X \\ \dot{X} = \left[\mu(S, X) - D(X)\right]X \end{cases}$$

where

$$\mu(S, X) = p(X)\mu_L(S) + (1 - p(X))\mu_A(S), \quad D(X) = p(X)D_L + (1 - p(X))D_A.$$

We assume that  $\mu_L(S)$  and  $\mu_A(S)$  are increasing and  $\mu_L(S) \ge \mu_A(S)$ ,  $D_L \ge D_A$ . and  $0 \le p(X) \le 1$ , p(0) = 1,  $p(\infty) = 0$ , p'(X) < 0. The equilibria of the system are given by

$$\begin{cases} D(S_{in} - S) - \mu(S, X)X = 0 \\ [\mu(S, X) - D(X)]X = 0 \end{cases}$$

If X = 0 then  $S = S_{in}$  so that one has the washout equilibrium:  $E_0 = (S_{in}, 0)$ . If  $\mu(S, X) = D(X)$ , then  $D(S_{in} - S) = XD(X)$ . Hence

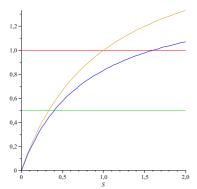
$$S = G(X) := S_{in} - \frac{XD(X)}{D}.$$

The mapping  $S \mapsto G(X)$  is decreasing. Notice

$$\lambda_L = \mu_L^{-1}(D_L), \qquad \lambda_A = \mu_A^{-1}(D_A).$$

Then equation  $\mu(S,X) = D(X)$  defines a function S = F(X) such that  $F(0) = \lambda_L$  and  $F(\infty) = \lambda_A$ . The positive equilibria of the system are given by the intersections of the graphs of S = F(X) and S = G(X), see Figure 1. If  $\lambda_L < \lambda_A$  the function  $S \mapsto F(S)$  is increasing and we have the following result

**Proposition 5.1** If  $\lambda_L < S_{in}$ , there is a unique positive equilibrium. It is stable. If  $\lambda_L > S_{in}$ , there is no positive equilibrium.



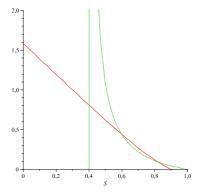


Figure 1: On the right the growth functions  $\mu_L$  and  $\mu_A$ . On the right, the mappings  $S \mapsto F(S)$  and  $S \mapsto G(S)$  showing the existence of two positive equilibria in the case when  $\lambda_L > S_{in}$ .

If  $\lambda_L > \lambda_A$  the function  $S \mapsto F(S)$  is decreasing, see Figure 1, and we have the following result

**Proposition 5.2** If  $\lambda_L < S_{in}$ , then there exists at least onr positive equilibrium. One can have an odd number of equilibria which are alternatively stable and unstable. If  $\lambda_L > S_{in}$ , then one can have 0 of and even number of equilibria which are alternatively stable and unstable.

Hence in the case when  $\lambda_L > \lambda_A$ , the system can exhibits bistability, see Figure 2: The whashout equilibrium is stable together with the positive equilibrium corresponding the the lowest value of S. The domains of attraction of the stable equilibria are separated by the stable sepratrix of the positive saddle node. The simulations shown in Figures 1 and 2 where obtained for the following Monod functions

$$\mu_L(S) = \frac{2S}{1+S}, \qquad \mu_L(S) = \frac{1.5S}{0.8+S}$$

and the following values of the parameters

$$D_L = D = 1$$
,  $D_A = 0.5$ ,  $a = 4$ ,  $b = 1$ ,  $S_{in} = 0.9$ .

# 6 N-species

We consider here the case of N-species competing for a substrate. We assume that each species is present in two forms: isolated bacteria of density  $u_i$ , and bacteria in flocks, of density  $v_i$ ,  $1 \le i \le n$ . We assume that isolated bacteria can

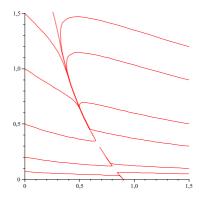


Figure 2: The system exhibits bistability.

stick with isolated bacteria or floks to form new flocks with rate  $\alpha_i(\cdot)u_i$  and we assume that flocks can liberate isolated bacteria with rate  $\beta_i(\cdot)v_i$ . The model equation are:

$$\begin{cases}
\dot{S} = D(S_{in} - S) - \sum_{i=1}^{n} \left[ \mu_{i1}(S)u_i + \mu_{i2}(S)v_i \right] \\
\dot{u}_i = (\mu_{i1}(S) - D)u_i - \alpha_i(\cdot)u_i + \beta_i(\cdot)v_i, & \text{for } 1 \le i \le n \\
\dot{v}_i = (\mu_{i2}(S) - D_i)v_i + \alpha_i(\cdot)u_i - \beta_i(\cdot)v_i, & \text{for } 1 \le i \le n
\end{cases}$$
(6)

We consider here the case [39] where

$$\alpha_i(\cdot) = \sum_{j=1}^n A_{ij} x_j, \qquad \beta_i(\cdot) = B_i$$

where  $A_{ij}$  and  $B_i$  are nonnegative constants. Moreover, we assume that the dynamics of flocculation and deflocculation are fast compared with the dynamics of the growth of bacteria, that is que l'on a

$$A_{ij} = \frac{a_{ij}}{\varepsilon}, \quad B_i = \frac{b_i}{\varepsilon},$$

The quasi steady state reduction of this model is the following reduced model

$$\begin{cases} \dot{S} = D(S_{in} - S) - \sum_{i=1}^{n} \mu_i(S, x_1, \dots, x_n) x_i \\ \dot{x}_i = \left[\nu_i(S, x_1, \dots, x_n) - D_i(x_1, \dots, x_n)\right] x_i, & \text{où } 1 \le i \le n \end{cases}$$
 (7)

where

$$\mu_i(S, x_1, \dots, x_n) = \frac{b_i \mu_{i1}(S) + \sum_{j=1}^n a_{ij} x_j \mu_{i2}(S)}{b_i + \sum_{j=1}^n a_{ij} x_j},$$

$$D_i(x_1, \dots, x_n) = \frac{Db_i + D_i \sum_{j=1}^n a_{ij} x_j}{b_i + \sum_{j=1}^n a_{ij} x_j}.$$

This approach give a motivation to density dependent growth function models [27, 28, 26].

### 7 Conclusion

In this work, we have analysed a general model of the chemostat with planctonic and attached biomass, under the assumption that attachment and detachment processes are fast compared to the biological scale. Each compartment of the biomass is characterized by its specific growth rate and apparent dilution rate, generalizing previous models of biofilms (with no dilution rate for the attached bacteria) or models of perfect flocks (with no growth rate for inside individuals). Our study reveals that the reduced dynamics may exhibit a bi-stable behavior even though each growth function is monotonic. This phenomenon is new and is usually met in chemostat but when the growth function is non-monotonic (such as the Haldane law). Here, it can be explained by the conjunction of different growth rate and dilution rate that leads to a density dependency of both apparent growth rate and dilution rate in the reduced dynamics.

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