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# On some spectral problems arising in dynamic populations 

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This paper is dedicated to Michel Pierre who sparks off the mathematical career of the three authors.

## 1 Introduction

This work has its origin in the talk given by Michel Langlais during the Workshop "Partial Differential Equations and Applications" devoted to the sixtieth birthday of Michel Pierre in Vittel, October 22-24, 2009. In this work, we can find two among the favorites topics of Michel Pierre : reaction-diffusion systems and shape optimization. Indeed, in his talk entitled "Some mathematical reaction-diffusion problems arising in population dynamics and posed on non coincident spatial domains", Michel Langlais has presented several works (developed in [1], [4], [6]). In particular, was shown some global existence results together with internal stabilisation for a reaction-diffusion systems of predator-prey model posed on non coincident spatial domains.

Predator-prey model presented by M. Langlais in his talk describes the evolution of two species which, contrary to the classic models, live on two different domains and which interact only on the intersection of these two domains supposed not empty. This is motivated by the fact that the observations show that the domain of reproduction of the predators and their domain of predation are often different.

For the sake of completeness and for the reader's convenience let us recall how one can derive the mathematical problem describing or modeling predator-prey model posed on non coincident spatial domains. For more details, see [1], [4], [6] and its references.

Let $u=u(t, x)$ be the density of predators at time $t \geq 0$ and position $x \in \Omega_{1}$ and $v=v(t, y)$ the density of preys at time $t \geq 0$ and position $y \in \Omega_{2}$ where $\Omega_{1}$ and $\Omega_{2}$ are nonempty bounded open subsets of $\mathbb{R}^{N}$ with smooth boundaries and $\Omega_{1} \cap \Omega_{2} \neq \emptyset$.
We follow here [4] and the references therein. One assumes that in absence of prey the predator population will decay at some exponentiel rate $a(x)$, and diffuses with a constant diffusivity $d_{1}>0$. Then one assumes that in absence of predators the dynamic of the prey population is governed by a logistic growth, with a naturel growth rate $r(y) \geq 0$ and a density depend effect on mortality $k(y)>0$ while preys diffuse with a constant diffusivity $d_{2}>0$.
As announced previously, interactions only occur in the common zone $\Omega_{1} \cap \Omega_{2}$ through the
quantity $\pi(u(t, y), v(t, y), y)$ which represents the number of preys killed by predator at time $t \geq 0$ and position $y \in \Omega_{1} \cap \Omega_{2}$.
The biomass obtained with the killed preys is assumed to be transformed in birth rate through the parameter $\varepsilon>0$. Nevertheless, since the reproduction areas are generally distinct from predation areas, is introduced a function $\ell(x, y) \geq 0$ which represents the biomass transfer from a point $y \in \Omega_{1} \cap \Omega_{2}$ to a point $x \in \Omega_{1}$. To ensure conservation of biomass, we need to impose

$$
\int_{\Omega_{1}} \ell(x, y) d x=1, \text { for all } y \in \Omega_{1} \cap \Omega_{2}
$$

and that $\ell(x, y)=0$ for any $y \in \Omega_{2} \backslash \Omega_{1}$. Moreover, we assume that predators and preys are isolated in their respective areas and that at time $t=0$, we have $u(0, x)=u_{0}(x)$ and $v(0, y)=v_{0}(y)$ with given data $u_{0}$ and $v_{0}$.

These considerations yield to the following reaction-diffusion system :

$$
(\mathcal{S})\left\{\begin{array}{llll}
\partial_{t} u-d_{1} \Delta_{x} u & =-a(x) u+\varepsilon \int_{\Omega_{1} \cap \Omega_{2}} \ell(x, y) \pi(u(t, y), v(t, y), y) u(t, y) d y & t>0 x \in \Omega_{1} \\
\partial_{t} v-d_{2} \Delta_{y} v & =(r(y)-k(y) v) v-\chi \Omega_{1} \cap \Omega_{2}(y) \pi(u(t, y), v(t, y), y) u(y) & & t>0 \quad y \in \Omega_{2} \\
\frac{\partial u}{\partial \nu_{1}}(t, x) & =0 & & t>0 x \in \partial \Omega_{1} \\
\frac{\partial v}{\partial \nu_{2}}(t, y) & =0 & & t>0 \quad y \in \partial \Omega_{2} \\
u(0, x) & =u_{0}(x) & x \in \Omega_{1} \\
v(0, y) & =v_{0}(y) & y \in \Omega_{2},
\end{array}\right.
$$

where we denote by :
$\chi_{\Omega_{1} \cap \Omega_{2}}$ the characteristic function of the intersection $\Omega_{1} \cap \Omega_{2}, \nu_{1}(x)$ the exterior unit normal vector to $\partial \Omega_{1}$ at $x \in \partial \Omega_{1}$ and $\nu_{2}(y)$ the exterior unit normal vector to $\partial \Omega_{2}$ at $y \in \partial \Omega_{2}$.

It is proved in $[1$, Theorem 1] that the system $(\mathcal{S})$ admits a unique nonnegative global solution when the functions $a, r$ and are constants and $\pi(u(t, y), v(t, y), y)=\frac{e v(t, y)}{1+h e v(t, y)}$ where $h$ and $e$ are positive reals numbers.

In this work, we are interested in the large time stabilization of the population of the predators towards 0 while preserving a population of preys, i.e. $u(t,.) \rightarrow 0$ and $v(t,.) \rightarrow v^{*}()>$. when $t \rightarrow+\infty$. To this end, a control localized on a small subdomain $\omega$ of $\Omega_{1}$ can be introduced. Then equation describing the density of predators is modified into :

$$
\partial_{t} u-d_{1} \Delta u=-a(x) u-\gamma \chi_{\omega} u+\varepsilon \int_{\Omega_{1} \cap \Omega_{2}} \ell(x, y) \frac{e v(t, y)}{1+\operatorname{hev}(t, y)} u(t, y) d y, \quad(t, x) \in(0,+\infty) \times \Omega_{1}
$$

It is well known that asymptotic behaviour of solutions is closely connected to the sign and the magnitude of the first eigenvalue for the problem

$$
\left\{\begin{array}{rlrl}
-d_{1} \Delta u(x)+a(x) u(x)+\gamma u(x) \chi_{\omega}-\int_{\Omega_{1} \cap \Omega_{2}} \ell(x, y) \frac{e v^{*}(y)}{1+h e v^{*}(y)} u(y) d y & =\lambda_{1}(\omega) u(x) & x \in \Omega_{1} \\
\frac{\partial u}{\partial \nu_{1}}(x) & =0 & x \in \partial \Omega_{1}
\end{array}\right.
$$

Moreover, the greatest $\lambda_{1}(\omega)$ is, the quickest the extinction of predator's population will be. Therefore, the naturel question is to investigate the existence of an admissible subdomain $\omega^{*}$ which maximizes $\lambda_{1}(\omega)$. And if the answer is yes, it is possible to specify its localization?

Intuitively the optimal subdomain $\omega^{*}$ should be localized in the common zone $\Omega_{1} \cap \Omega_{2}$. Indeed, it was shown by some numerical experiments presented by M. Langlais in his talk and confirmed by some simple computations which appear at section 5 .

In this article, we are going to study these questions in a rather general framework. Since some of the basic ideas have an abstract character, we choose to write first some general properties and specialize to the one-dimensional case only when needed. The general model is of the form

$$
(\mathcal{P})\left\{\begin{array}{rr}
-\Delta u+a(x) u+\gamma u \chi_{\omega}-\int_{\Omega} K(x, y) u(y) d y=\lambda_{1}(\omega) u & x \in \Omega \\
\frac{\partial u}{\partial \nu}(x)=0 & x \in \partial \Omega,
\end{array}\right.
$$

where $K$ is a non symmetric kernel i.e $K(x, y) \neq K(y, x)$ as explained in the above modelization.
Since the operator is not self-adjoint, the problem is more difficult to tackle. In particular, variational techniques using a min formula cannot be used. Thus, a general study for the maximization problem of the first eigenvalue of $(\mathcal{P})$, following the lines of [5] (see also [7, chapter 8]) cannot be used here.

In section 2, we prove the existence of a subdomain $\omega^{*}$ such that

$$
\lambda_{1}\left(\omega^{*}\right)=\max _{\omega \in \mathcal{A}_{V_{0}, c}} \lambda_{1}(\omega)
$$

where $\mathcal{A}_{V_{0}, c}:=\left\{\omega\right.$ measurable ; $\left.\omega \subset \Omega,|\omega|=V_{0},|\partial \omega| \leq c\right\}$.
In section 3 , we prove differentiability of the first eigenvalue $\lambda_{1}(\omega)$ with respect to the domain $\omega$. In section 4 we give some elements of answer to the second question in dimension 1. More precisely, under some natural assumption on the kernel $K$, we prove that the optimal domain $\omega^{*}$ must intersect $\Omega_{1} \cap \Omega_{2}$ when its length $\ell$ is small enough. This result is probably true without any assumption on the length. In the last section, we give some perspectives.

## 2 Existence of an optimal domain

Let us consider the problem

$$
\left(\mathcal{P}_{1}\right)\left\{\begin{array}{rlrl}
-\Delta u(x)+a(x) u(x)+\gamma \chi_{\omega}(x) u-\int_{\Omega} K(x, y) u(y) d y+\zeta u(x) & =g(x) & x \in \Omega \\
\frac{\partial u}{\partial \nu}(x) & =0 & & x \in \partial \Omega,
\end{array}\right.
$$

where $\Omega$ is a bounded regular (Lipschitz) open subset of $\mathbb{R}^{N}, \omega$ is a nonempty measurable set such that $\bar{\omega} \subset \Omega,(\gamma, \zeta) \in] 0,+\infty{ }^{2}, a \in L^{\infty}(\Omega), K \in L^{\infty}(\Omega \times \Omega)$ such that $a, K \geq 0$ a.e. Let us recall that the kernel $K$ is not symmetric.
Assume that

$$
\begin{equation*}
1+\|a\|_{L^{\infty}(\Omega)}+\|K\|_{L^{2}(\Omega \times \Omega)}<\zeta . \tag{1}
\end{equation*}
$$

- For $(u, v) \in H^{1}(\Omega) \times H^{1}(\Omega)$, let us set

$$
\mathcal{A}_{\omega}(u, v)=\int_{\Omega} \nabla u \nabla v+\int_{\Omega} a u v+\int_{\Omega} \gamma u \chi_{\omega} v-\int_{\Omega}\left(\int_{\Omega} K(x, y) u(y) d y\right) v(x) d x+\int_{\Omega} \zeta u v .
$$

Thanks to (1), the bilinear form $\mathcal{A}_{\omega}$ is continuous and elliptic in $H^{1}(\Omega)$ (moreover the ellipticity constant can be chosen independently for $\omega$ ). Then, Lax-Milgram's theorem implies that for any $g \in L^{2}(\Omega)$, the problem ( $P_{1}$ ) admits a unique solution $\psi \in H^{1}(\Omega)$. Let us denote by $T_{\omega}$ the operator associating to every $g \in L^{2}(\Omega)$ the solution $\psi=T_{\omega}(g)$ of $\left(P_{1}\right)$.
One can easily verify that $T_{\omega}: L^{2}(\Omega) \rightarrow L^{2}(\Omega)$ is a linear compact operator, with positive spectral radius $r\left(T_{\omega}\right)$ and satisfies $T_{\omega}(\mathcal{E}) \subset \mathscr{\mathcal { E }}$, where $\mathcal{E}:=\left\{\psi \in L^{2}(\Omega) ; \psi \geq 0\right.$ a.e in $\left.\Omega\right\}$ and $\dot{\mathcal{E}}$ is its interior.
We remark that, except if $K$ is symmetric $(K(x, y)=K(y, x))$, the operator $T_{\omega}$ is not selfadjoint.
Since $\mathcal{E}$ is a solid cone, Krein-Rutman's theorem (see e.g [2, théorème VI.13]) yields that the spectral radius $r\left(T_{\omega}\right)$ is an eigenvalue of $T_{\omega}$ with an eigenfunction $u \in \mathcal{E} \backslash\{0\}$ such that $T_{\omega}(u)=r\left(T_{\omega}\right) u$. Moreover, $r\left(T_{\omega}^{*}\right)=r\left(T_{\omega}\right)$ is an eigenvalue of the adjoint operator $T_{\omega}^{*}$ with an eigenfunction $u^{*} \in \mathcal{E} \backslash\{0\}$.
It follows that $\lambda_{1}(\omega)=\frac{1}{r\left(T_{\omega}\right)}-\zeta$ is an eigenvalue for the following elliptic problem

$$
\left(\mathcal{P}_{2}\right)\left\{\begin{array}{rl}
-\Delta u+a(x) u+\gamma u \chi_{\omega}-\int_{\Omega} K(x, y) u(y) d y=\lambda_{1}(\omega) u & x \in \Omega \\
\frac{\partial u}{\partial \nu}(x)=0 & x \in \partial \Omega,
\end{array}\right.
$$

with $\widetilde{\psi}$ as a corresponding nonnegative eigenfunction, and $\lambda_{1}(\omega)$ is also eigenvalue for the adjoint problem

$$
\left(\mathcal{P}_{2}^{*}\right)\left\{\begin{array}{rl}
-\Delta u^{*}+a(x) u^{*}+\gamma u^{*} \chi_{\omega}-\int_{\Omega} K(y, x) u^{*}(y) d y=\lambda_{1}(\omega) u^{*} & x \in \Omega \\
\frac{\partial u^{*}}{\partial \nu}(x)=0 & x \in \partial \Omega .
\end{array}\right.
$$

Krein-Rutman's theorem also implies that $\lambda_{1}(\omega)$ is a simple eigenvalue for $\left(\mathcal{P}_{2}\right)$ and ( $\left.\mathcal{P}_{2}^{*}\right)$ and there is no other eigenvalue with positive eigenfunctions.

- Let $V_{0}$ and $c$ be two positive real numbers such that $V_{0}<|\Omega|$. We introduce the class of admissible domains

$$
\mathcal{A}_{V_{0}, c}=\left\{\omega \text { measurable } ; \omega \subset \Omega,|\omega|=V_{0},|\partial \omega| \leq c\right\} .
$$

Equip $\mathcal{A}_{V_{0}, c}$ with the following topology :
let $\left\{\omega_{n}\right\}_{n \geq 0}$ be a sequence of sets in $\mathcal{A}_{V_{0}, c}$ and let $\omega \in \mathcal{A}_{V_{0}, c}$; we say that $\left\{\omega_{n}\right\}_{n \geq 0}$ converges in the sense of characteristic functions towards $\omega$ when $\chi_{\omega_{n}} \rightarrow \chi_{\omega}$ in $L^{p}\left(\mathbb{R}^{N}\right), \forall p \in[1,+\infty[$.
According to Henrot and Pierre [8, théorème 2.3.10 and proposition 2.3.6], the set $\mathcal{A}_{V_{0}, c}$ equipped with the above topology is compact.

Theorem 1 There exists $\omega^{*} \in \mathcal{A}_{V_{0}, c}$ such that

$$
\lambda_{1}\left(\omega^{*}\right)=\max _{w \in \mathcal{A}_{V_{0}, c}} \lambda_{1}(\omega) .
$$

## Proof of Theorem 1 :

To prove theorem 1, it suffices to prove that the map $\omega \mapsto \lambda_{1}(\omega)$ from $\mathcal{A}_{V_{0}, c}$ to $\mathbb{R}$ is continuous. For this, we are going to prove the two following lemmas.

Lemma 1 The map $\omega \mapsto T_{\omega}$ from $\mathcal{A}_{V_{0}, c}$ to $\mathcal{K}\left(L^{2}(\Omega)\right)$ is continuous where $\mathcal{K}\left(L^{2}(\Omega)\right)$ denotes the subspace of compact linear operators from $L^{2}(\Omega)$ into $L^{2}(\Omega)$.

## Proof of Lemma 1 :

- Let $\left\{\omega_{n}\right\}$ be a sequence of elements of $\mathcal{A}_{V_{0}, c}$ which converges to $\omega$ in $\mathcal{A}_{V_{0}, c}$. We have to prove that $\left\{T_{\omega_{n}}\right\}$ converges to $T_{\omega}$ strongly i.e

$$
\lim _{n \rightarrow+\infty}\left\|T_{\omega_{n}}-T_{\omega}\right\|=0
$$

But according to Henrot [7, theorem 2.3.2], it suffices to prove that
(i) the operators $T_{\omega_{n}}$ (and $T_{\omega}$ ) are uniformly bounded;
(ii) for fixed $g \in L^{2}(\Omega), \lim _{n \rightarrow+\infty}\left\|T_{\omega_{n}}(g)-T_{\omega}(g)\right\|_{L^{2}(\Omega)}=0$.

In the following, we set $u_{n}=T_{\omega_{n}}(g)$ et $u=T_{\omega}(g)$.

- First, $(i)$ comes immediately from uniform ellipticity (i.e with a constant independant of $\omega_{n}$ ) of the bilinear forms $\mathcal{A}_{\omega_{n}}$, and we also have

$$
\begin{equation*}
\left\|u_{n}\right\|_{H^{1}(\Omega)} \leq C\|g\|_{L^{2}(\Omega)} \quad \text { with } C \text { independent of } n \tag{2}
\end{equation*}
$$

- Let us prove (ii)

By virtue of (2), the sequence $\left\{u_{n}\right\}$ is bounded in $H^{1}(\Omega)$. Therefore, we can extract a subsequence, still denoted $u_{n}$, such that $u_{n}$ converges weakly in $H^{1}(\Omega)$ and strongly in $L^{2}(\Omega)$ to some fonction $w$ which belongs to $H^{1}(\Omega)$. We have to prove that $w=u$ and the whole sequence converges to $u$.

- For any $n$ and for any $v \in H^{1}(\Omega)$, we have

$$
\begin{equation*}
\int_{\Omega} \nabla u_{n} \nabla v+\int_{\Omega} a u_{n} v+\gamma \int_{\Omega} \chi_{\omega_{n}} u_{n} v-\int_{\Omega} v(x)\left(\int_{\Omega} K(x, y) u_{n}(y) d y\right) d x+\zeta \int_{\Omega} u_{n} v=\int_{\Omega} g v \tag{3}
\end{equation*}
$$

We want to pass to the limit in the variationnal formulation (3).
By Rellich theorem, $H^{1}(\Omega)$ is compactly embedded in $L^{p}(\Omega)$ for any $p<\frac{2 N}{N-2}$ if $N>2$ (and for any $p<+\infty$ if $N=2$ ). Thus we can assume that $u_{n}$ converges strongly in $L^{2(N-1) /(N-2)}(\Omega)$ to $w$ which implies that $u_{n} v$ converges strongly to $w v$ in $L^{(N-1) /(N-2)}(\Omega)$. Since $\chi_{\omega_{n}} \rightarrow \chi_{\omega}$ in $L^{N-1}(\Omega)$ it follows that $\int_{\Omega} \chi_{\omega_{n}} u_{n} v \rightarrow \int_{\Omega} \chi_{\omega} w v$.
Passing to the limit in the other terms is easy and we get that $w$ satisfies

$$
\begin{equation*}
\int_{\Omega} \nabla w \nabla v+\int_{\Omega} a w v+\gamma \int_{\Omega} \chi_{\omega} w v-\int_{\Omega} v(x)\left(\int_{\Omega} K(x, y) w(y) d y\right) d x+\zeta \int_{\Omega} w v=\int_{\Omega} g v . \tag{4}
\end{equation*}
$$

But (4) is exactly the variationnel formulation defining $u$, then $u=w$.

- At last, since $u$ is the only accumulation point of the sequence $u_{n}$, the whole sequence converges to $u$. $\square$

Lemma 2 The map $T_{\omega} \mapsto r\left(T_{\omega}\right)$ from $\mathcal{K}\left(L^{2}(\Omega)\right)$ to $[0,+\infty[$ is continuous.

## Proof of Lemma 2 :

Lemma 2 is a particular case of the following general result :
Let $E$ be a $\mathbb{K}$-Banach space where $K=\mathbb{R}$ or $\mathbb{C}$. Denote by $\mathcal{L}(E)$ its space of bounded linear operators and by $\mathcal{K}(E)$ the subspace of compact linear operators. Then with respect to the normoperator the spectral radius mapping is upper semi-continuous on $\mathcal{L}(E)$ and continuous on $\mathcal{K}(E)$.

For a detailed proof see Degla [3, Theorem 2.1], but for the sake of completeness and for the reader's convenience, we sketch a proof going along the lines of Kato [9, paragraph 3.5.].

Let $\left\{T_{n}\right\}_{n}$ be a sequence in $\mathcal{K}(E)$ which converges to some $T \in \mathcal{L}(E)$. We are going to prove that

$$
\limsup _{n \rightarrow+\infty} r\left(T_{n}\right) \leq r(T) \leq \liminf _{n \rightarrow+\infty} r\left(T_{n}\right)
$$

- Let $\varepsilon, R \in(0,+\infty)$ such that $r(T)+\varepsilon<R$. Since $T_{n} \rightarrow T$ and thanks to Kato [9, theorem 3.1], the compact set $\{z \in \mathbb{C} ; r(T)+\varepsilon<|z|<R\}$ is contained in the resolvent set of $T_{n}$ (denoted $\left.\rho\left(T_{n}\right)\right)$ for $n$ enough large. Therefore, there exists $n_{0} \in \mathbb{N}$ such that for $n \geq n_{0}$, we have

$$
\{z \in \mathbb{C} ; r(T)+\varepsilon<|z|\} \subset \rho\left(T_{n}\right)
$$

and thus

$$
\sigma\left(T_{n}\right) \subset\{z \in \mathbb{C} ;|z| \leq r(T)+\varepsilon\}
$$

where $\sigma\left(T_{n}\right)$ denotes the spectrum of $T_{n}$. Hence $\limsup _{n \rightarrow+\infty} r\left(T_{n}\right) \leq r(T)$.

- Since $\mathcal{K}(E)$ is a closed subspace of $\mathcal{L}(E), T$ is necessarily compact.

If $r(T)=0$,the result is clearly true.
Assume that $r(T)>0$. Using Krein-Rutman's Theorem, there exists an isolated eigenvalue $\lambda$ of $T$ such that $|\lambda|=r(T)$. Therefore, there exists $\varepsilon_{0}>0$ such that the circle $\mathcal{C}_{0}$ with center $\lambda$ and radius $\varepsilon_{0}$ does not contain any other eigenvalue of $T$. According to Kato [9, paragraph 3.5] and since $T_{n} \rightarrow T$, for any $\varepsilon<\varepsilon_{0}, \exists n_{0}$ such that for $n \geq n_{0}$, the circle $\mathcal{C}_{0}$ contains an eigenvalue $\lambda_{k}\left(T_{n}\right)$ of $T_{n}$. But $\lambda_{k}\left(T_{n}\right) \leq r\left(T_{n}\right)$. Then $r(T) \leq \liminf _{n \rightarrow+\infty} r\left(T_{n}\right)$.

## Remark on the perimeter constraint

If we remove the perimeter constraint, meaning that we work with the class

$$
\mathcal{A}_{V_{0}}=\left\{\omega \text { measurable } \subset \Omega,|\omega|=V_{0}\right\},
$$

the problem becomes ill-posed. Indeed, we have the following result, in the particular case $a=K=0$ which should extend to the general case.

Proposition 1 Assume that $a=K=0$, then $\sup \left\{\lambda_{1}(\omega) ; \omega \in \mathcal{A}_{V_{0}}\right\}=\frac{\gamma V_{0}}{|\Omega|}$ and it is not achieved (meaning that the maximization problem has no solution).

## Proof of Proposition 1 :

- Since $K=0$, the operator is self-adjont here and we have $\lambda_{1}(\omega)=\min _{v \in H^{1}(\Omega)} \frac{\int_{\Omega}|\nabla v|+\gamma \int_{\Omega} \chi_{\omega} v^{2}}{\int_{\Omega} v^{2}}$
for every $\omega \in \mathcal{A}_{V_{0}}$. Thus taking $v=1$, we obtain $\lambda_{1}(\omega) \leq \frac{\gamma V_{0}}{|\Omega|}$. So that $\sup _{\omega \in \mathcal{A}_{V_{0}}} \lambda_{1}(\omega) \leq \frac{\gamma V_{0}}{|\Omega|}$.
- Let us show that in fact $\sup _{\omega \in \mathcal{A}_{V_{0}}} \lambda_{1}(\omega)=\frac{\gamma V_{0}}{|\Omega|}$.

According to Henrot and Pierre [8, Proposition 7.2.14], we can construct a sequence $\left\{\omega_{n}\right\}$ of elements of $\mathcal{A}_{V_{0}}$ such that $\chi_{\omega_{n}}$ converges towards a constant $\ell$ in the weak-* topology. In this way,

$$
\int_{\Omega} \chi_{\omega_{n}}=\left|\omega_{n}\right|=V_{0} \rightarrow \int_{\Omega} \ell=\ell|\Omega|
$$

and thus $\ell=\frac{V_{0}}{|\Omega|}$.
Now, according to Henrot [7, Theorem 8.1.2] (Continuity of $\lambda_{1}(V)$ for the weak-*convergence), we have

$$
\lambda_{1}\left(\chi_{\omega_{n}}\right)=\lambda_{1}\left(\omega_{n}\right) \rightarrow \lambda_{1}\left(\frac{V_{0}}{|\Omega|}\right)
$$

Moreover, $\lambda_{1}\left(\frac{V_{0}}{|\Omega|}\right)$ is the first eigenvalue of the following Neumann problem

$$
\left\{\begin{array}{lll}
-\Delta u+\frac{\gamma V_{0}}{|\Omega|} u & = & \lambda u
\end{array} \quad \text { on } \Omega,\right.
$$

whence $\lambda_{1}\left(\frac{V_{0}}{|\Omega|}\right)=\frac{\gamma V_{0}}{|\Omega|}$.
Hence we have found a sequence $\left\{\omega_{n}\right\}$ such that $\lambda_{1}\left(\omega_{n}\right) \rightarrow \frac{\gamma V_{0}}{|\Omega|}$, proving the equality.
But for every $\omega \in \mathcal{A}_{V_{0}}$, we have $\lambda_{1}(\omega)<\frac{\gamma V_{0}}{|\Omega|}$. For if we had equality, then the function $u=1$ would necessarily be an eigenfunction for

$$
\left\{\begin{array}{lll}
-\Delta u+\chi_{\omega} u & =\lambda u & \text { on } \Omega \\
\frac{\partial u}{\partial \nu} & =0 & \text { on } \partial \Omega
\end{array}\right.
$$

which is impossible

## 3 Proof of differentiability of the eigenvalue

In this section, we prove differentiability of the first eigenvalue with respect to the domain. We follow notations of [8]. Let us consider a set $\omega \subset \Omega$ and an application $\Phi$ such that $\Phi: t \in$ $\left[0, T\left[\rightarrow W^{1, \infty}\left(\mathbb{R}^{N}, \mathbb{R}^{N}\right)\right.\right.$ is differentiable at 0 with $\Phi(0)=I, \Phi^{\prime}(0)=V$, where $W^{1, \infty}\left(\mathbb{R}^{N}, \mathbb{R}^{N}\right)$ is the set of bounded Lipschitz maps from $\mathbb{R}^{N}$ into itself, $I$ is the identity and $V$ is a deformation field. Let us denote by $\omega_{t}=\Phi(t)(\omega)$ and $\lambda_{1}(t)$ the first eigenvalue $\lambda_{1}\left(\Omega, \omega_{t}, \gamma\right)$ of problem $\left(\mathcal{P}_{2}\right)$ with $\omega$ replaced by $\omega_{t}$. We will also denote by $u(t)$ a normalized eigenfunction associated to $\lambda_{1}(t)$ and by $u^{*}(t)$ a normalized eigenfunction associated to the adjoint problem $\left(\mathcal{P}_{2}^{*}\right)$. We are interested in the differentiability of the map $t \mapsto \lambda_{1}(t)$. The following Theorem states the differentiability and gives the formula of the first derivative when $\omega$ is Lipschitz.

Theorem 2 Let $\lambda_{1}$, $u$ and $u^{*}$ denote respectively, the first eigenvalue, a normalized associated eigenfunction of problem $\left(\mathcal{P}_{2}\right)$ and a normalized eigenfunction associated to the adjoint problem ( $\mathcal{P}_{2}^{*}$ ).
Then the map $t \mapsto \lambda_{1}(t)$ is differentiable at $t=0$. Moreover, if $\omega$ is Lipschitz regular, the derivative is given by

$$
\begin{equation*}
\lambda_{1}^{\prime}(0)=\gamma \frac{\int_{\partial \omega} u u^{*} V \cdot \nu d \sigma}{\int_{\Omega} u u^{*}(x) d x} \tag{5}
\end{equation*}
$$

where $\nu$ is the exterior unit normal vector to $\partial \omega$.

## Proof of Theorem 2 :

In the proof we denote by $H$ the Hilbert space $H^{1}(\Omega)$ and by $H^{\prime}$ its dual space. Let us introduce the operator $\mathcal{F}$ from $\mathbb{R} \times H \times \mathbb{R}$ with values in $H^{\prime} \times \mathbb{R}$ and defined by the formula

$$
\mathcal{F}(t, v, \lambda)=\left(-\Delta v+a(x) v+\gamma \chi_{\omega_{t}} v-\int_{\Omega} K(x, y) v(y) d y-\lambda v, \int_{\Omega} v^{2}-1\right)
$$

This operator is $\mathcal{C}^{1}$, the only difficulty being to prove differentiability of $t \mapsto \chi_{\omega_{t}} v$. But in $H^{\prime}$, $\chi_{\omega_{t}} v$ is the linear map $u \mapsto \int_{\Omega} \chi_{\omega_{t}} u v d x=\int_{\omega_{t}} u v d x$ which is $\mathcal{C}^{1}$ (and actually $\mathcal{C}^{\infty}$ ) according to [8, Theorem 5.2.2]. Moreover its derivative at $t=0$ is given by

$$
\begin{equation*}
\frac{d}{d t}\left(\chi_{\omega_{t}} v\right)=\int_{\omega} \operatorname{div}(u v V) d x \tag{6}
\end{equation*}
$$

which can be written, if $\omega$ is Lipschitz,

$$
\begin{equation*}
\frac{d}{d t}\left(\chi_{\omega_{t}} v\right)=\int_{\partial \omega} u v V \cdot \nu d \sigma \tag{7}
\end{equation*}
$$

Now differentiating $\mathcal{F}$ with respect to its second and third variables yields, for any $(\hat{v}, \hat{\lambda}) \in H \times \mathbb{R}$ :

$$
D_{v, \lambda} \mathcal{F}\left(0, u, \lambda_{1}\right)(\hat{v}, \hat{\lambda})=\left(-\Delta \hat{v}+a(x) \hat{v}+\gamma \chi_{\omega} \hat{v}-\int_{\Omega} K(x, y) \hat{v}(y) d y-\lambda_{1} \hat{v}-\hat{\lambda} u, 2 \int_{\Omega} u \hat{v}\right) .
$$

Let us now prove that $D_{v, \lambda} \mathcal{F}\left(0, u, \lambda_{1}\right)$ is an isomorphism from $H \times \mathbb{R}$ onto $H^{\prime} \times \mathbb{R}$. Since it is a continuous map, we have only to prove that it is one to one, thanks to the Banach open mapping Theorem. This is the purpose of the following Lemma.

Lemma 3 Let $(Z, \Lambda) \in H^{\prime} \times \mathbb{R}$ be given, then there exists a unique solution $(\hat{v}, \hat{\lambda}) \in H \times \mathbb{R}$ for the system

$$
\left\{\begin{array}{c}
-\Delta \hat{v}+a(x) \hat{v}+\gamma \chi_{\omega} \hat{v}-\int_{\Omega} K(x, y) \hat{v}(y) d y \lambda_{1} \hat{v}-\hat{\lambda} u=Z \quad x \in \Omega  \tag{8}\\
\frac{\partial \hat{v}}{\partial \nu}(x)=0 \quad x \in \partial \Omega \\
2 \int_{\Omega} u \hat{v}=\Lambda .
\end{array}\right.
$$

## Proof of Lemma 3 :

Of course, the system (8) has to be understood in the variational sense. By compactness of the operator $\left(-\Delta+a(x) I+\gamma \chi_{\omega} I \int_{\Omega} K(x, y) . d y\right)^{-1}: H^{\prime} \rightarrow H \subset H^{\prime}$, we can apply Fredholm alternative to the operator $-\Delta+a(x) I+\gamma \chi_{\omega} I-\int_{\Omega} K(x, y) \cdot d y-\lambda_{1} I$. Since $\lambda_{1}$ is a simple eigenvalue, by definition the kernel of this operator is of dimension 1 and its image is characterized
by one relation of orthogonality with the corresponding eigenfunction. Applying this alternative to $Z+\hat{\lambda} u$ writes

$$
0=\langle Z+\hat{\lambda} u, u\rangle_{H^{\prime} \times H}=\hat{\lambda}+\langle Z, u\rangle .
$$

This equality uniquely defines $\hat{\lambda}$. Now, any possible inverse image of $Z+\hat{\lambda} u$ by $-\Delta+a(x) I+$ $\gamma \chi_{\omega} I-\int_{\Omega} K(x, y) . d y-\lambda_{1} I$ can be written $v_{0}+s u$ where $v_{0}$ is a particular one. But the relation $2 \int_{\Omega} u \hat{v}=\Lambda$ implies

$$
\Lambda=2 \int_{\Omega} u\left(v_{0}+s u\right)=2 s+\int_{\Omega} u v_{0} .
$$

Thus, $s$ is also uniquely determined : this proves existence and uniqueness of a solution for system (8).

We come back to the proof of Theorem 2. We can now apply the Implicit Function Theorem : there exists a map $t \mapsto(v(t), \lambda(t)) \in H \times \mathbb{R}$ which is of class $\mathcal{C}^{\infty}$ on a neighborhood $\mathcal{V}$ of the origin and a neighborhood $\mathcal{O}$ of $\left(0, u, \lambda_{1}\right)$ in $\mathbb{R} \times H \times \mathbb{R}$ such that

$$
v(0)=u, \quad \lambda(0)=\lambda_{1}, \quad \mathcal{F}^{-1}(\{0\}) \cap \mathcal{O}=\{(t, v(t), \lambda(t)) ; t \in \mathcal{V}\} .
$$

Thus $t \rightarrow(v(t), \lambda(t))$ necessarily coincides with the continuous function $t \mapsto\left(u(t), \lambda_{1}(t)\right)$ and the differentiability of $t \mapsto \lambda_{1}(t)$ and $t \mapsto u(t)$ is proved. In the same way, we can prove differentiability of $t \mapsto u^{*}(t)$.

Now we want to prove formula (5). For that purpose, we differentiate the variational formulation of $\left(\mathcal{P}_{2}\right)$. We denote by $\lambda_{1}^{\prime}, u^{\prime}$ and $u^{* \prime}$ the derivatives (at $t=0$ ) of $\lambda_{1}(t), u(t)$ and $u^{*}(t)$ respectively. For any fixed $v \in H$, using formula (7) and the chain rule, we have

$$
\begin{array}{r}
\int_{\Omega} \nabla u^{\prime} . \nabla v d x+\int_{\Omega} a(x) u^{\prime} v d x+\gamma \int_{\omega} u^{\prime} v d x+\gamma \int_{\partial \omega} u v V \cdot \nu d \sigma- \\
\int_{\Omega} \int_{\Omega} K(x, y) u^{\prime}(y) v(x) d y d x=\lambda_{1} \int_{\Omega} u^{\prime} v d x+\lambda^{\prime} \int_{\Omega} u v d x . \tag{9}
\end{array}
$$

We will also use the variational formulation of the adjoint problem ( $\mathcal{P}_{2}^{*}$ ), for any $v \in H$ :

$$
\begin{align*}
& \int_{\Omega} \nabla u^{*} . \nabla v d x+\int_{\Omega} a(x) u^{*} v d x+\gamma \int_{\omega} u^{*} v d x- \\
& \int_{\Omega} \int_{\Omega} K(y, x) u^{*}(y) v(x) d y d x=\lambda_{1} \int_{\Omega} u^{*} v d x . \tag{10}
\end{align*}
$$

Now, we choose $v=u^{*}$ in (9) and $v=u^{\prime}$ in (10) and we substract the two equations to get

$$
\begin{equation*}
\int_{\Omega} u u^{*}(x) d x \lambda^{\prime}(0)=\gamma \int_{\partial \omega} u u^{*} V \cdot \nu d \sigma . \tag{11}
\end{equation*}
$$

which is the desired formula and finishes the proof. $\square$
In one dimension, when looking for a subset $\omega$ which is a single interval $\left(x_{1}, x_{1}+\ell\right)$, we will use in the next section the derivative of the first eigenvalue $\lambda_{1}$ with respect to $x_{1}$. The previous Theorem gives immediately the answer since derivative with respect to $x_{1}$ is equivalent to look at the derivative with respect to a translation of the domain. Thus, we need to apply formula (5) with $V . \nu=+1$ on the right side of the interval and $V . \nu=-1$ on the left side. Therefore, we have proved

Corollary 1 In one dimension, when we consider an interval $\omega=\left(x_{1}, x_{1}+\ell\right)$, the derivative of the first eigenvalue with respect to $x_{1}$ is given by

$$
\begin{equation*}
\lambda_{1}^{\prime}\left(x_{1}\right)=\gamma \frac{u u^{*}\left(x_{1}+\ell\right)-u u^{*}\left(x_{1}\right)}{\int_{\Omega} u u^{*}(x) d x} \tag{12}
\end{equation*}
$$

## 4 Position of the optimal domain

Intuitively the position of the optimal domain should be localized in the common zone. Nevertheless this result is not easy to prove in the general case. That is why we assume $a$ constant and we study only the case of the one dimension with a domain of control with a "small size". Furthermore, in one dimension bounding the perimeter corresponds to bound the number of connected components, we shall thus study the case of a single interval.
Let $\Omega=(0,1)$ and

$$
K(x, y)=\chi_{(0, \alpha)}(y) \hat{K}(x, y), \quad \alpha \in(0,1)
$$

(this means that the common domain is $(0, \alpha))$ and assume that the control domain is $\omega=$ $(z, z+\ell)$ with $z \in(0,1)$ and $\ell>0$ small enough.

With this notations the eigenvalue problem and its adjoint problem can be written

$$
\begin{gathered}
\left(\mathcal{P}_{\ell}\right)\left\{\begin{array}{c}
-u_{\ell}^{\prime \prime}+a u_{\ell}+\gamma \chi_{(z, z+\ell)} u_{\ell}-\int_{0}^{1} K(x, y) u_{\ell}(y) d y=\lambda_{1, \ell}(z) u_{\ell} \\
u_{\ell}^{\prime}(0)=u_{\ell}^{\prime}(1)=0 \\
\left\|u_{\ell}\right\|_{L^{2}(0,1)}=1,
\end{array}\right. \\
\left(\mathcal{P}_{\ell}^{*}\right)\left\{\begin{array}{c}
-\left(u_{\ell}^{*}\right)^{\prime \prime}+a u_{\ell}^{*}+\gamma \chi_{(z, z+\ell)} u_{\ell}^{*}-\int_{0}^{1} K(y, x) u_{\ell}^{*}(y) d y=\lambda_{1, \ell}(z) u_{\ell}^{*} \quad x \in(0,1) \\
\left(u_{\ell}^{*}\right)^{\prime}(0)=\left(u_{\ell}^{*}\right)^{\prime}(1)=0 \\
\left\|u_{\ell}^{*}\right\|_{L^{2}(0,1)}=1 .
\end{array}\right.
\end{gathered}
$$

where $\lambda_{1, \ell}(z), u_{\ell}$ and $u_{\ell}^{*}$ denote respectively the first eigenvalue, the normalized associated eigenfunction of problem $\left(\mathcal{P}_{\ell}\right)$ and the normalized associated eigenfunction of the adjoint problem $\left(\mathcal{P}_{\ell}^{*}\right)$.

For domains of control $\omega=(z, z+\ell)$ with a small size, we prove under a condition on $\hat{K}(x, y)$ that the optimal domain of control must have a non empty intersection with the common zone $(0, \alpha)$.

Theorem 3 If the map $x \mapsto \hat{K}(x, y)$ is decreasing for all $y \in(0, \alpha)$, then there exits $\ell_{0}>0$ such that for all $\ell \in\left(0, \ell_{0}\right)$ the optimal interval $\omega^{*}=\left(z^{*}, z^{*}+\ell\right)$ satisfies $z^{*} \leq \alpha$.

## Proof of Theorem 3 :

The proof of this result relies on the corollary 1 which ensures that for all $\ell>0$

$$
\begin{equation*}
\frac{\partial \lambda_{1, \ell}}{\partial z}(z)=\gamma \frac{u_{\ell} u_{\ell}^{*}(z+\ell)-u_{\ell} u_{\ell}^{*}(z)}{\int_{0}^{1} u_{\ell} u_{\ell}^{*}(x) d x} \tag{13}
\end{equation*}
$$

As it is not obvious to describe the variations of the map $x \mapsto u_{\ell} u_{\ell}^{*}(x)$, we first study the variations of the map $x \mapsto u_{0} u_{0}^{*}(x)$ where $u_{0}$ and $u_{0}^{*}$ are solutions of the limit problem with
$\ell=0:$

$$
\begin{gathered}
\left(\mathcal{P}_{0}\right)\left\{\begin{array}{c}
-u_{0}^{\prime \prime}+a u_{0}-\int_{0}^{\alpha} \hat{K}(x, y) u_{0}(y) d y=\lambda_{1,0} u_{0} \quad x \in(0,1) \\
u_{0}^{\prime}(0)=u_{0}^{\prime}(1)=0 \\
\left\|u_{0}\right\|_{L^{2}(0,1)}=1,
\end{array}\right. \\
\left(\mathcal{P}_{0}^{*}\right)\left\{\begin{array}{c}
-\left(u_{0}^{*}\right)^{\prime \prime}+a u_{0}^{*}-\chi_{(0, \alpha)} \int_{0}^{1} \hat{K}(y, x) u_{0}^{*}(y) d y=\lambda_{1,0} u_{0}^{*} \quad x \in(0,1) \\
\left(u_{0}^{*}\right)^{\prime}(0)=\left(u_{0}^{*}\right)^{\prime}(1)=0 \\
\left\|u_{0}^{*}\right\|_{L^{2}(0,1)}=1 .
\end{array}\right.
\end{gathered}
$$

First, we prove the uniform convergence on $(0,1)$ of $u_{\ell} u_{\ell}^{*}$ to $u_{0} u_{0}^{*}$ and of $\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}$ to $\left(u_{0} u_{0}^{*}\right)^{\prime}$.
Lemma 4 For all $z \in(0,1)$, we have

$$
\begin{equation*}
\lim _{\ell \rightarrow 0}\left\|u_{\ell} u_{\ell}^{*}-u_{0} u_{0}^{*}\right\|_{\infty}=0, \quad \lim _{\ell \rightarrow 0}\left\|\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}-\left(u_{0} u_{0}^{*}\right)^{\prime}\right\|_{\infty}=0 \tag{14}
\end{equation*}
$$

## Proof of Lemma 4 :

Let $z$ in $(0,1)$ and let $\left(\ell_{n}\right)$ be a sequence converging to 0 . In order to simplify notations, we put $u_{n}=u_{\ell_{n}}$ and $\lambda_{1, n}=\lambda_{1, \ell_{n}}(z)$.

- First, we multiply the first equation of $\left(\mathcal{P}_{n}\right)$ by $1 / \int_{0}^{1} u_{n}$ and we integrate on $(0,1)$. As we have $\int_{0}^{1} \hat{K}(x, y) d x=1$ for all $y \in(0, \alpha)$, we obtain

$$
\lambda_{1, n}=a+\gamma \frac{\int_{z}^{z+\ell_{n}} u_{n}(x) d x}{\int_{0}^{1} u_{n}}-\frac{\int_{0}^{\alpha} u_{n}(y) d y}{\int_{0}^{1} u_{n}} .
$$

Thus, the sequence $\left(\lambda_{1, n}\right)$ is uniformly bounded

$$
\begin{equation*}
\left|\lambda_{1, n}\right| \leq a+\gamma+1 \tag{15}
\end{equation*}
$$

and up to a subsequence we can consider that $\left(\lambda_{1, n}\right)$ converges to $\bar{\lambda}$.

- Multiplying the first equation of $\left(\mathcal{P}_{n}\right)$ by $u_{n}$ and integrating on $(0,1)$ we obtain

$$
\int_{0}^{1}\left(u_{n}^{\prime}\right)^{2} \leq\|K\|_{L^{2}((0,1) \times(0,1))}+\lambda_{1, n}
$$

Then, using (15), we obtain that there exists a constant $C>0$ independent of $\ell_{n}$ and $z$ such that $\left\|u_{n}\right\|_{H^{1}} \leq C$. Using the classical compact embedding $H^{1} \hookrightarrow L^{\infty}$, we immediately deduce that up to a subsequence $\left(u_{n}\right)$ converges uniformly to $\bar{u}$. Note that $\bar{u}$ is nonnegative since for all $n \in \mathbb{N}, u_{n}$ is nonnegative and $\|\bar{u}\|_{L^{2}(0,1)}=1$.

- We also have, for all $n$ and for all $v \in H^{1}(0,1)$

$$
\int_{0}^{1} u_{n}^{\prime} v^{\prime}+a \int_{0}^{1} u_{n} v+\gamma \int_{z}^{z+\ell} u_{n} v-\int_{0}^{1}\left(\int_{0}^{\alpha} \hat{K}(x, y) u_{n}(y) d y\right) v(x) d x=\lambda_{1, n} \int_{0}^{1} u_{n} v
$$

When we pass to the limit, we obtain

$$
\int_{0}^{1} \bar{u}^{\prime} v^{\prime}+a \int_{0}^{1} \bar{u} v-\int_{0}^{1}\left(\int_{0}^{\alpha} \hat{K}(x, y) \bar{u}(y) d y\right) v(x) d x=\bar{\lambda} \int_{0}^{1} \bar{u} v .
$$

As $\bar{u}$ is nonnegative and $\|\bar{u}\|_{L^{2}(0,1)}=1$, then necessarily $\bar{u}=u_{0}$ and $\bar{\lambda}=\lambda_{1,0}$. At last, since $u_{0}$ and $\lambda_{1,0}$ are respectively the only accumulation point of the sequences $\left(u_{n}\right)$ and $\left(\lambda_{1, n}\right)$, the whole sequences converge to $u_{0}$ and $\lambda_{1,0}$ respectively.

In conclusion, we have for all $z \in(0,1)$

$$
\lim _{\ell \rightarrow 0} \lambda_{1, n}(z)=\lambda_{1,0} \quad \text { and } \quad \lim _{\ell \rightarrow 0}\left\|u_{\ell}-u_{0}\right\|_{\infty}=0 .
$$

- Now, we have for all $x \in(0,1)$

$$
\begin{aligned}
\left(u_{\ell}^{\prime}-u_{0}^{\prime}\right)(x)= & \int_{0}^{x}\left(u_{\ell}^{\prime \prime}-u_{0}^{\prime \prime}\right)(y) d y \\
\leq & a \int_{0}^{x}\left(u_{\ell}-u_{0}\right)(y) d y+\gamma \ell\left\|u_{\ell}\right\|_{\infty} \\
& -\int_{0}^{\alpha}\left(\left(u_{\ell}-u_{0}\right)(t) \int_{0}^{x} \hat{K}(y, t) d y\right) d t-\lambda_{1, \ell}(z) \int_{0}^{x} u_{\ell}(y) d y \\
& +\lambda_{1,0} \int_{0}^{x} u_{\ell}(y) d y
\end{aligned}
$$

thus

$$
\left\|u_{\ell}^{\prime}-u_{0}^{\prime}\right\|_{\infty} \leq C\left(\ell+\left|\lambda_{1, n}-\lambda_{1,0}\right|+\left\|u_{\ell}-\bar{u}\right\|_{\infty}\right) .
$$

which gives the uniform convergence of $\left(u_{\ell}^{\prime}\right)$ to $\left(\bar{u}^{\prime}\right)$.
By a similar computation, we obtain the uniform convergence of $\left(u_{\ell}^{*}\right)$ and $\left(\left(u_{\ell}^{*}\right)^{\prime}\right)$ respectively to $u_{0}^{*}$ and $\left(u_{0}^{*}\right)^{\prime}$ and the result follows.

Now, we study the limit problem and we have the following result :
Lemma 5 If the map $x \mapsto \hat{K}(x, y)$ is decreasing for all $y \in(0, \alpha)$, then there exists two positive constants $C_{0}$ and $\theta$ such that

$$
\left(u_{0} u_{0}^{*}\right)^{\prime}(x)<C_{0} \operatorname{sh}(\theta(x-1)) \quad \forall x \in(\alpha, 1) .
$$

## Proof of Lemma 5 :

First, note that on ( $\alpha, 1$ ), $u_{0}^{*}$ is solution of the equation

$$
-\left(u_{0}^{*}\right)^{\prime \prime}(x)+\theta^{2} u_{0}^{*}(x)=0, \quad\left(u_{0}^{*}\right)^{\prime}(1)=0
$$

with $\theta^{2}=a-\lambda_{1,0}$. Thus, there exists $A>0$ such that for all $x \in(\alpha, 1)$

$$
u_{0}^{*}(x)=A \operatorname{ch}(\theta(1-x)) .
$$

Note also, that $u_{0}$ satisfies on $(0,1)$ the following equation

$$
-u_{0}^{\prime \prime}(x)+\theta^{2} u_{0}(x)=f(x), \quad u_{0}^{\prime}(0)=u_{0}^{\prime}(1)=0,
$$

where

$$
f(x)=\int_{0}^{\alpha} \hat{K}(x, y) u_{0}(y) d y
$$

So, we have for all $x \in(0,1)$

$$
u_{0}(x)=\frac{\operatorname{ch}(\theta x)}{\theta \operatorname{sh}(\theta)} \int_{0}^{1} \operatorname{ch}(\theta(1-t)) f(t) d t-\frac{1}{\theta} \int_{0}^{x} \operatorname{sh}(\theta(x-t)) f(t) d t
$$

Then, we deduce that for all $x \in(\alpha, 1)$

$$
\begin{gathered}
\left(u_{0} u_{0}^{*}\right)^{\prime}(x)=\frac{A}{\operatorname{sh}(\theta)}\left[\operatorname{sh}(\theta(2 x-1)) \int_{x}^{1} \operatorname{ch}(\theta(1-t)) f(t) d t\right. \\
\left.\quad-\operatorname{sh}(2 \theta(1-x)) \int_{0}^{x} \operatorname{ch}(\theta t) f(t) d t\right] .
\end{gathered}
$$

Now, since $x \mapsto \hat{K}(x, y)$ is assumed to be decreasing for all $y \in(0, \alpha)$, the map $x \mapsto f(x)$ is also decreasing and then we have for all $x \in(\alpha, 1)$

$$
\begin{aligned}
\left(u_{0} u_{0}^{*}\right)^{\prime}(x) & \leq \frac{A g(x)}{\theta \operatorname{sh}(\theta)}[\operatorname{sh}(\theta(2 x-1)) \operatorname{sh}(\theta(1-x))-\operatorname{sh}(2 \theta(1-x)) \operatorname{sh}(\theta x)] \\
& \leq \frac{A g(x)}{\theta} \operatorname{sh}(\theta(x-1))
\end{aligned}
$$

where

$$
g(x)=\left\{\begin{array}{lll}
f(x) & \text { if } & x \geq 1 / 2 \\
f(1) & \text { if } & x \leq 1 / 2
\end{array}\right.
$$

Finally, we obtain

$$
\left(u_{0} u_{0}^{*}\right)^{\prime}(x)<C_{0} \operatorname{sh}(\theta(x-1)) \quad \forall x \in(\alpha, 1)
$$

where $C_{0}$ is a positive constant.
We are now in position to prove the theorem 3 . By lemma 4 , $\left(u_{\ell} u_{\ell}^{*}\right)$ converges uniformly to $u_{0} u_{0}^{*}$, and lemma 5 gives the sign of $u_{0} u_{0}^{*}(z+\ell)-u_{0} u_{0}^{*}(z)$. However to obtain the sign of the application $u_{\ell} u_{\ell}^{*}(z+\ell)-u_{\ell} u_{\ell}^{*}(z)$ up to $x=1$, we have to cut the interval $[\alpha, 1-\ell]$ in two parts $[\alpha, 1-\beta]$ and $[1-\beta, 1-\ell]$.

Let $C_{1}=\left\|\left(u_{0} u_{0}^{*}\right)^{\prime}\right\|_{\infty}+1$ and let $\beta>0$ small enough such that

$$
\begin{equation*}
\frac{C_{0}}{\theta}[\operatorname{ch}(\theta(1-\alpha-\beta / 2))-\operatorname{ch}(\theta \beta)] \geq \beta C_{1}+C_{0}(1-\alpha) \operatorname{sh}(\theta \beta / 2) . \tag{16}
\end{equation*}
$$

The lemma 4 ensures the uniform convergence of $\left(\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}\right)$ to $\left(u_{0} u_{0}^{*}\right)^{\prime}$, so there exists $\ell_{1}>0$ such that for all $\ell \in\left(0, \ell_{1}\right)$,

$$
\begin{equation*}
\left\|\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}\right\|_{\infty} \leq C_{1} \tag{17}
\end{equation*}
$$

and there exits $\ell_{2}>0$ such that for all $\ell \in\left(0, \ell_{2}\right)$

$$
\left\|\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}-\left(u_{0} u_{0}^{*}\right)^{\prime}\right\|_{\infty} \leq C_{0} \operatorname{sh}(\theta \beta / 2)
$$

which gives combining with lemma 5

$$
\begin{equation*}
\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}(x) \leq C_{0} \operatorname{sh}(\theta(x-1))+C_{0} \operatorname{sh}(\theta \beta / 2) \tag{18}
\end{equation*}
$$

for all $\ell \in\left(0, \ell_{2}\right)$ and for all $x \in(\alpha, 1)$.

Now, we put $\ell_{0}=\min \left(\ell_{1}, \ell_{2}, \beta / 2\right)$ and let $\ell \in\left(0, \ell_{0}\right)$.

- From (13), we have for all $\left(z, z^{\prime}\right) \in[\alpha, 1-\ell]^{2}$

$$
\begin{align*}
\lambda_{1, \ell}\left(z^{\prime}\right)-\lambda_{1, \ell}(z) & =\frac{1}{\int_{0}^{1} u_{\ell} u_{\ell}^{*}(x) d x} \int_{z}^{z^{\prime}} u_{\ell} u_{\ell}^{*}(y+\ell)-u_{\ell} u_{\ell}^{*}(y) d y  \tag{19}\\
& =C(\ell) \int_{z}^{z^{\prime}} \int_{y}^{y+\ell}\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}(t) d t d y \tag{20}
\end{align*}
$$

Thus, for all $z \in(\alpha, 1-\beta)$ we have

$$
\lambda_{1, \ell}(z)-\lambda_{1, \ell}(\alpha)=C(\ell) \int_{\alpha}^{z} \int_{y}^{y+\ell}\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}(t) d t d y
$$

and as $z+\ell<z+\ell_{0}<z+\beta / 2$, we deduce immediately using (18)

$$
\lambda_{1, \ell}(z) \leq \lambda_{1, \ell}(\alpha), \quad \text { for all } z \in(\alpha, 1-\beta)
$$

- The estimate on $[1-\beta, 1-\ell]$ is more difficult to obtain. By $(20)$, we have for all $z \in[1-\beta, 1-\ell]$

$$
\lambda_{1, \ell}(z)-\lambda_{1, \ell}(1-\beta)=C(\ell) \int_{1-\beta}^{z} \int_{y}^{y+\ell}\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}(t) d t d y
$$

and then, using (17), we obtain for all $z \in[1-\beta, 1-\ell]$

$$
\begin{equation*}
\lambda_{1, \ell}(z) \leq \lambda_{1, \ell}(1-\beta)+C(\ell) \beta C_{1} \ell \tag{21}
\end{equation*}
$$

By (20), we also have

$$
\lambda_{1, \ell}(\alpha)-\lambda_{1, \ell}(1-\beta)=-C(\ell) \int_{\alpha}^{1-\beta} \int_{y}^{y+\ell}\left(u_{\ell} u_{\ell}^{*}\right)^{\prime}(t) d t d y
$$

and using (18), we deduce

$$
\begin{aligned}
\lambda_{1, \ell}(\alpha)-\lambda_{1, \ell}(1-\beta) \geq & -C(\ell) \int_{\alpha}^{1-\beta} \int_{y}^{y+\ell}\left(C_{0} \operatorname{sh}(\theta(t-1))+C_{0} \operatorname{sh}(\theta \beta / 2)\right) d t d y \\
\geq & -C(\ell) \ell(1-\beta-\alpha) C_{0} \operatorname{sh}(\theta \beta / 2) \\
& +\frac{C(\ell) C_{0} \ell}{\theta}[\operatorname{ch}(\theta(1-\alpha-\ell))-\operatorname{ch}(\theta(\ell-\beta))]
\end{aligned}
$$

As $\ell \leq \ell_{0} \leq \beta / 2$, we deduce that

$$
\lambda_{1, \ell}(\alpha)-\lambda_{1, \ell}(1-\beta) \geq \ell C(\ell)\left[-(1-\alpha) C_{0} \operatorname{sh}(\theta \beta / 2)+\frac{C_{0}}{\theta}[\operatorname{ch}(\theta(\alpha-1-\beta / 2))-\operatorname{ch}(\theta \beta)]\right]
$$

Finally, using (16) and (21) we get $\lambda_{1, \ell}(z) \leq \lambda_{1, \ell}(\alpha)$, for all $z \in[1-\beta, 1-\ell]$.

In conclusion, we have for all $z \in[\alpha, 1-\ell]$

$$
\lambda_{1, \ell}(z) \leq \lambda_{1, \ell}(\alpha)
$$

## 5 Conclusion

Some numerical simulations confirm Theorem 3. The Figure 1 presents the graph of $z \mapsto \lambda_{1}(z)$ for $\ell=0.2$ with the following choices of the kernel $K$ :
$-($ left $): K(x, y)=4 \chi_{(0,1 / 4)}(y)$,
$-($ right $): K(x, y)=\left(2(1-x) \cos ^{2}(y)+(e /(e-1)) \exp (-x) \sin ^{2}(y)\right) \chi_{(0,1 / 4)}$.
As we can see, the optimal interval is completely on the left in the first case, while it is shifted to the right in the second case but stays inside the common zone $\Omega_{1} \cap \Omega_{2}$.


Fig. 1 - Graph of $z \mapsto \lambda_{1}(z)$

We have been able to prove that the optimal domain is in the common zone $\Omega_{1} \cap \Omega_{2}$ only under the three following assumptions :

- dimension one
- interval of small size
- the kernel $K(x, y)$ is decreasing with respect to $x$.

It would be interesting to extend this result to intervals of arbitrary size and possibly for more general kernels. Nevertheless, we think that some assumptions on the kernel are needed to get such a property of the optimal domain. At last, it seems us challenging to study the same question in higher dimension.

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