

The nonlinear membrane energy: variational derivation under the constraint $\det \nabla u > 0$

Omar Anza Hafsa, Jean-Philippe Mandallena

▶ To cite this version:

Omar Anza Hafsa, Jean-Philippe Mandallena. The nonlinear membrane energy: variational derivation under the constraint det $\nabla u > 0$. Bulletin des Sciences Mathématiques, 2008, 132, pp.272-291. 10.1016/j.bulsci.2007.05.004 . hal-00584064

HAL Id: hal-00584064 https://hal.science/hal-00584064v1

Submitted on 30 Sep 2024

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



Distributed under a Creative Commons Attribution - NonCommercial 4.0 International License

The nonlinear membrane energy: variational derivation under the constraint "det $\nabla u > 0$ "

Omar Anza Hafsa^a, Jean-Philippe Mandallena^{b,c,*}

 ^a LMGC UMR-CNRS 5508, Université Montpellier II, Place Eugène Bataillon, 34095 Montpellier France
 ^b Equipe AVA (Analyse Variationnelle et Applications), Université de Nîmes, Site des Carmes, Place Gabriel Péri, Cedex 01, 30021 Nîmes, France
 ^c I3M UMR-CNRS 5149, Université Montpellier II, Place Eugène Bataillon, 34095 Montpellier, France

In [Anza Hafsa, O., Mandallena, J.-P., The nonlinear membrane energy: variational derivation under the constraint "det $\nabla u \neq 0$ ", J. Math. Pures Appl. 86 (2006) 100–115] we gave a variational definition of the nonlinear membrane energy under the constraint "det $\nabla u \neq 0$ ". In this paper we obtain the nonlinear membrane energy under the more realistic constraint "det $\nabla u > 0$ ".

Keywords: Dimensional reduction; Nonlinear membrane energy; Determinant condition

1. Introduction

Consider an elastic material occupying in a reference configuration the bounded open set $\Sigma_{\varepsilon} \subset \mathbb{R}^3$ given by

$$\Sigma_{\varepsilon} := \Sigma \times \left] - \frac{\varepsilon}{2}, \frac{\varepsilon}{2} \right[,$$

^{*} Corresponding author.

E-mail addresses: Omar.Anza-Hafsa@univ-montp2.fr (O. Anza Hafsa), jean-philippe.mandallena@unimes.fr (J.-P. Mandallena).

where $\varepsilon > 0$ is very small and $\Sigma \subset \mathbb{R}^2$ is Lipschitz, open and bounded. A point of Σ_{ε} is denoted by (x, x_3) with $x \in \Sigma$ and $x_3 \in]-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}[$. Let $W : \mathbb{M}^{3 \times 3} \to [0, +\infty]$ be the stored-energy function supposed to be *continuous* and *coercive*, i.e., $W(F) \ge C|F|^p$ for all $F \in \mathbb{M}^{3 \times 3}$ and some C > 0. In order to take into account the important physical properties that the interpenetration of matter does not occur and that an infinite amount of energy is required to compress a finite volume into zero volume, i.e.,

$$W(F) \to +\infty$$
 as det $F \to 0$,

where det F denotes the determinant of the 3×3 matrix F, we assume that:

 $W(F) = +\infty \text{ if and only if det } F \leq 0; \tag{1}$

for every $\delta > 0$, there exists $c_{\delta} > 0$ such that for all $F \in \mathbb{M}^{3 \times 3}$, (2)

if det
$$F \ge \delta$$
 then $W(F) \le c_{\delta} (1 + |F|^p)$.

Our goal is to show that as $\varepsilon \to 0$ the three-dimensional free energy functional $E_{\varepsilon}: W^{1,p}(\Sigma_{\varepsilon}; \mathbb{R}^3) \to [0, +\infty]$ (with p > 1) defined by

$$E_{\varepsilon}(u) := \frac{1}{\varepsilon} \int_{\Sigma_{\varepsilon}} W(\nabla u(x, x_3)) \, \mathrm{d}x \, \mathrm{d}x_3 \tag{3}$$

converges in a variational sense (see Definition 2.1) to the two-dimensional free energy functional $E_{\text{mem}}: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ given by

$$E_{\text{mem}}(v) := \int_{\Sigma} W_{\text{mem}}(\nabla v(x)) \,\mathrm{d}x \tag{4}$$

with $W_{\text{mem}}: \mathbb{M}^{3\times 2} \to [0, +\infty]$. Usually, E_{mem} is called the nonlinear membrane energy associated with the two-dimensional elastic material with respect to the reference configuration Σ . Furthermore we wish to give a representation formula for W_{mem} .

To our knowledge, the problem of giving a variational definition of the nonlinear membrane energy was studied for the first time by Percivale in [15]. His paper deals with the constraint "det $\nabla u > 0$ " but seems to contain some mistakes (it never was published). Nevertheless, Percivale introduced the "good" formula for W_{mem} , i.e., $W_{\text{mem}} = QW_0$ where W_0 is given by (5) and $\mathcal{Q}W_0$ denotes the quasiconvex envelope of W_0 . Then, in [14] Le Dret and Raoult gave a complete proof of Percivale's conjecture in the simpler case where W is of p-polynomial growth, i.e., $W(F) \leq c(1+|F|^p)$ for all $F \in \mathbb{M}^{3\times 3}$ and some c > 0. Although the *p*-polynomial growth case is not compatible with (1) and (2) their paper established a suitable framework to deal with dimensional reduction problems (it is the point of departure of many works on the subject). After Percivale, Ben Belgacem also considered the constraint "det $\nabla u > 0$ ". In [7, Theorem 1] he announced to have succeed to handle (1) and (2). In [8], which is the paper corresponding to the note [7], the statement [7, Theorem 1] is partly proved (however, a more detailed proof, but not fully complete, can be found in his thesis [6]). Moreover, for Ben Belgacem $W_{\text{mem}} = \mathcal{QR}W_0$ where $\mathcal{R}W_0$ denotes the rank one convex envelope of W_0 (in fact, as we proved in [2,3], $QRW_0 = QW_0$). Nevertheless, Ben Belgacem's thesis highlighted the role of approximation theorems for Sobolev functions by smooth immersions in the studying of the passage 3D-2D in presence of (1) and (2). Recently, in [3] we gave a variational definition of the nonlinear membrane energy under the constraint "det $\nabla u \neq 0$ ". In the present paper, using the same method as in [3] and some results of Ben Belgacem's thesis (mainly, Theorem A.1 and Lemma 5.4), we obtain the nonlinear membrane energy under the more realistic constraint "det $\nabla u > 0$ ".

An outline of the paper is as follows. The variational convergence of E_{ε} to E_{mem} as $\varepsilon \to 0$ as well as a representation formula for W_{mem} are given by Corollary 2.9 in Section 2.4. Corollary 2.9 is a consequence of Theorems 2.5, 2.6 and 2.8. Roughly, Theorems 2.5 and 2.6 establish the existence of the variational limit of E_{ε} as $\varepsilon \to 0$ (see Section 2.2), and Theorem 2.8 gives an integral representation for the corresponding variational limit, and so a representation formula for W_{mem} (see Section 2.3). In fact, Theorem 2.8 is obtained from Theorem 2.6 which furnishes a "simplified" formula for the variational limit.

Theorem 2.5 is proved in Section 4. The principal ingredients are Theorems 2.6 and 3.4 whose proof (given in Section 3) uses an interchange theorem of infimum and integral that we obtained in [1]. (Note that the techniques used to prove Theorems 2.5 and 3.4 are the same as in [3, Sections 3 and 4].)

Theorem 2.6 is proved is Section 5. The main arguments are two approximation theorems developed by Ben Belgacem–Bennequin (see [6]) and Gromov–Eliashberg (see [11]). These theorems are stated in Appendix A.

Theorem 2.8 is proved in [3, Appendix A] (see also [2]).

2. Results

2.1. Variational convergence

To accomplish our asymptotic analysis, we use the notion of convergence introduced by Anzellotti, Baldo and Percivale in [4] in order to deal with dimension reduction problems in mechanics. Let $\pi = {\pi_{\varepsilon}}_{\varepsilon}$ be the family of maps $\pi_{\varepsilon} : W^{1,p}(\Sigma_{\varepsilon}; \mathbb{R}^3) \to W^{1,p}(\Sigma; \mathbb{R}^3)$ defined by

$$\pi_{\varepsilon}(u) := \frac{1}{\varepsilon} \int_{-\varepsilon/2}^{\varepsilon/2} u(\cdot, x_3) \, \mathrm{d}x_3.$$

Definition 2.1. We say that $E_{\varepsilon} \Gamma(\pi)$ -converges to E_{mem} as $\varepsilon \to 0$, and we write $E_{\text{mem}} = \Gamma(\pi)$ -lim_{$\varepsilon \to 0$} E_{ε} , if the following two assertions hold:

(i) for all $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$ and all $\{u_{\varepsilon}\}_{\varepsilon} \subset W^{1,p}(\Sigma_{\varepsilon}; \mathbb{R}^3)$,

if
$$\pi_{\varepsilon}(u_{\varepsilon}) \to v$$
 in $L^{p}(\Sigma; \mathbb{R}^{3})$ then $E_{\text{mem}}(v) \leq \liminf_{\varepsilon \to 0} E_{\varepsilon}(u_{\varepsilon})$

(ii) for all $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$, there exists $\{u_{\varepsilon}\}_{\varepsilon} \subset W^{1,p}(\Sigma_{\varepsilon}; \mathbb{R}^3)$ such that:

$$\pi_{\varepsilon}(u_{\varepsilon}) \to v \text{ in } L^{p}(\Sigma; \mathbb{R}^{3}) \text{ and } E_{\text{mem}}(v) \ge \limsup_{\varepsilon \to 0} E_{\varepsilon}(u_{\varepsilon}).$$

In fact, Definition 2.1 is a variant of De Giorgi's Γ -convergence. This is made clear by Lemma 2.3. Consider $\mathcal{E}_{\varepsilon}: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ defined by

$$\mathcal{E}_{\varepsilon}(v) := \inf \{ E_{\varepsilon}(u) \colon \pi_{\varepsilon}(u) = v \}.$$

Definition 2.2. We say that $\mathcal{E}_{\varepsilon}$ Γ -converges to E_{mem} as $\varepsilon \to 0$, and we write $E_{\text{mem}} = \Gamma$ -lim_{$\varepsilon \to 0$} $\mathcal{E}_{\varepsilon}$ if for every $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$,

$$\left(\Gamma - \liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}\right)(v) = \left(\Gamma - \limsup_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}\right)(v) = E_{\text{mem}}(v),$$

where

$$\left(\Gamma - \liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}\right)(v) := \inf \left\{ \liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}(v_{\varepsilon}) : v_{\varepsilon} \to v \text{ in } L^{p}(\Sigma; \mathbb{R}^{3}) \right\}$$

and

$$\Big(\Gamma - \limsup_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}\Big)(v) := \inf \Big\{ \limsup_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}(v_{\varepsilon}) : v_{\varepsilon} \to v \text{ in } L^{p}(\Sigma; \mathbb{R}^{3}) \Big\}.$$

For a deeper discussion of the Γ -convergence theory we refer to the book [9]. Clearly, Definition 2.2 is equivalent to assertions (i) and (ii) in Definition 2.1 with " $\pi(u_{\varepsilon}) \rightarrow v$ " replaced by " $v_{\varepsilon} \rightarrow v$ ". It is then obvious that

Lemma 2.3. $E_{\text{mem}} = \Gamma(\pi) - \lim_{\varepsilon \to 0} E_{\varepsilon}$ if and only if $E_{\text{mem}} = \Gamma - \lim_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}$.

The $\Gamma(\pi)$ -convergence of E_{ε} in (3) to E_{mem} in (4) as $\varepsilon \to 0$ as well as a representation formula for W_{mem} are given by Corollary 2.9. It is a consequence of Theorems 2.5, 2.6 and 2.8. Roughly, Theorems 2.5 and 2.6 establish the existence of the $\Gamma(\pi)$ -limit of E_{ε} as $\varepsilon \to 0$ (see Section 2.2), and Theorem 2.8 gives an integral representation for the corresponding $\Gamma(\pi)$ -limit, and so a representation formula for W_{mem} (see Section 2.3).

2.2. Γ -convergence of $\mathcal{E}_{\varepsilon}$ as $\varepsilon \to 0$

Denote by $C^1(\overline{\Sigma}; \mathbb{R}^3)$ the space of all restrictions to $\overline{\Sigma}$ of C^1 -differentiable functions from \mathbb{R}^2 to \mathbb{R}^3 , and set

$$C^{1}_{*}(\overline{\Sigma}; \mathbb{R}^{3}) := \{ v \in C^{1}(\overline{\Sigma}; \mathbb{R}^{3}) : \partial_{1}v(x) \wedge \partial_{2}v(x) \neq 0 \text{ for all } x \in \overline{\Sigma} \},\$$

where $\partial_1 v(x)$ (resp. $\partial_2 v(x)$) denotes the partial derivative of v at $x = (x_1, x_2)$ with respect to x_1 (resp. x_2). (In fact, $C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ is the set of all C^1 -immersions from $\overline{\Sigma}$ to \mathbb{R}^3 .) Let $\mathcal{E}: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ be defined by

$$\mathcal{E}(v) := \begin{cases} \int_{\Sigma} W_0(\nabla v(x)) \, \mathrm{d}x & \text{if } v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3), \\ +\infty & \text{otherwise,} \end{cases}$$

where $W_0: \mathbb{M}^{3 \times 2} \to [0, +\infty]$ is given by

$$W_0(\xi) := \inf_{\zeta \in \mathbb{R}^3} W(\xi \mid \zeta) \tag{5}$$

with $(\xi \mid \zeta)$ denoting the element of $\mathbb{M}^{3\times 3}$ corresponding to $(\xi, \zeta) \in \mathbb{M}^{3\times 2} \times \mathbb{R}^3$. (As *W* is coercive, it is easy to see that W_0 is coercive, i.e., $W_0(\xi) \ge C |\xi|^p$ for all $\xi \in \mathbb{M}^{3\times 2}$ and some C > 0.) The following lemma gives three elementary properties of W_0 (the proof is left to the reader). Note that conditions (1) and (2) imply W_0 is not of *p*-polynomial growth.

Lemma 2.4. Denote by $\xi_1 \wedge \xi_2$ the cross product of vectors $\xi_1, \xi_2 \in \mathbb{R}^3$.

- (i) W_0 is continuous.
- (ii) If (1) holds then $W_0(\xi_1 | \xi_2) = +\infty$ if and only if $\xi_1 \wedge \xi_2 = 0$.
- (iii) If (2) holds then:

for all
$$\delta > 0$$
, there exists $c_{\delta} > 0$ such that for all $\xi = (\xi_1 \mid \xi_2) \in \mathbb{M}^{3 \times 2}$, (6)
if $|\xi_1 \wedge \xi_2| \ge \delta$ then $W_0(\xi) \le c_{\delta} (1 + |\xi|^p)$.

Taking Lemma 2.3 into account, we see that the existence of the $\Gamma(\pi)$ -limit of E_{ε} as $\varepsilon \to 0$ follows from Theorem 2.5.

Theorem 2.5. Let assumptions (1) and (2) hold. Then Γ -lim $_{\varepsilon \to 0} \mathcal{E}_{\varepsilon} = \overline{\mathcal{E}}$ with $\overline{\mathcal{E}} : W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ given by

$$\overline{\mathcal{E}}(v) := \inf \left\{ \liminf_{n \to +\infty} \mathcal{E}(v_n) \colon W^{1,p}(\Sigma; \mathbb{R}^3) \ni v_n \to v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

The proof of Theorem 2.5 is established in Section 4. It uses Theorem 3.4 (see Section 3) and Theorem 2.6.

Theorem 2.6. If (6) holds then $\overline{\mathcal{E}}(v) = \mathcal{I}(v)$ for all $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$, where $\mathcal{I}: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ is given by

$$\mathcal{I}(v) := \inf \left\{ \liminf_{n \to +\infty} \int_{\Sigma} W_0(\nabla v_n(x)) \, \mathrm{d}x \colon W^{1,p}(\Sigma; \mathbb{R}^3) \ni v_n \to v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

Theorem 2.6 is proved in Section 6 by using two approximation theorems developed by Ben Belgacem–Bennequin (see [6]) and Gromov–Eliashberg (see [11]). These theorems are stated in Appendix A.

2.3. Integral representation of \mathcal{I}

From now on, given a bounded open set $D \subset \mathbb{R}^2$ with $|\partial D| = 0$, we denote by Aff $(D; \mathbb{R}^3)$ the space of all continuous piecewise affine functions from D to \mathbb{R}^3 , i.e., $v \in Aff(D; \mathbb{R}^3)$ if and only if v is continuous and there exists a finite family $(D_i)_{i \in I}$ of open disjoint subsets of D such that $|\partial D_i| = 0$ for all $i \in I$, $|D \setminus \bigcup_{i \in I} D_i| = 0$ and for every $i \in I$, $\nabla v(x) = \xi_i$ in D_i with $\xi_i \in \mathbb{M}^{3 \times 2}$ (where $|\cdot|$ denotes the Lebesgue measure in \mathbb{R}^2). Define $\mathcal{Z}W_0: \mathbb{M}^{3 \times 2} \to [0, +\infty]$ by

$$\mathcal{Z}W_{0}(\xi) := \inf\left\{\int_{Y} W_{0}\left(\xi + \nabla\phi(y)\right) dy: \phi \in \operatorname{Aff}_{0}\left(Y; \mathbb{R}^{3}\right)\right\}$$
(7)

where $Y :=]0, 1[^2$ and $Aff_0(Y; \mathbb{R}^3) := \{\phi \in Aff(Y; \mathbb{R}^3): \phi = 0 \text{ on } \partial Y\}$. (As W_0 is coercive, it is easy to see that $\mathcal{Z}W_0$ is coercive.) Recall the definitions of quasiconvexity and quasiconvex envelope:

Definition 2.7. Let $f: \mathbb{M}^{3 \times 2} \to [0, +\infty]$ be a Borel measurable function.

(i) We say that f is quasiconvex if for every $\xi \in \mathbb{M}^{3 \times 2}$, every bounded open set $D \subset \mathbb{R}^2$ with $|\partial D| = 0$ and every $\phi \in W_0^{1,\infty}(D; \mathbb{R}^3)$,

$$f(\xi) \leqslant \frac{1}{|D|} \int_{D} f(\xi + \nabla \phi(x)) \,\mathrm{d}x$$

- (ii) By the quasiconvex envelope of f, we mean the unique function (when it exists) $Qf : \mathbb{M}^{3 \times 2} \to [0, +\infty]$ such that:
 - Qf is Borel measurable, quasiconvex and $Qf \leq f$;
 - for all $g: \mathbb{M}^{3\times 2} \to [0, +\infty]$, if g is Borel measurable, quasiconvex and $g \leq f$, then $g \leq \mathcal{Q}f$.

(Usually, for simplicity, we say that Qf is the greatest quasiconvex function which less than or equal to f.)

Under (6), we proved that ZW_0 is of *p*-polynomial growth and so continuous (see [3, Propositions A.3 and A.1(iii)]) and that ZW_0 is the quasiconvex envelope of W_0 , i.e., $ZW_0 = QW_0$ (see [3, Proposition A.5]). Taking Theorems 2.5 and 2.6 together with Lemmas 2.3 and 2.4(iii) into account, we see that Theorem 2.8 gives an integral representation for the $\Gamma(\pi)$ -limit of E_{ε} as $\varepsilon \to 0$ as well as a representation formula for W_{mem} .

Theorem 2.8. If (6) holds then for every $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$,

$$\mathcal{I}(v) = \int_{\Sigma} \mathcal{Q}W_0\big(\nabla v(x)\big) \,\mathrm{d}x$$

Theorem 2.8 is proved in [3, Appendix A] (see also [2]).

2.4. $\Gamma(\pi)$ -convergence of E_{ε} to E_{mem} as $\varepsilon \to 0$

According to Lemmas 2.3 and 2.4(iii), a direct consequence of Theorems 2.5, 2.6 and 2.8 is the following.

Corollary 2.9. Let assumptions (1) and (2) hold. Then as $\varepsilon \to 0$, E_{ε} in (3) $\Gamma(\pi)$ -converge to E_{mem} in (4) with $W_{\text{mem}} = QW_0$.

Remark 2.10. Corollary 2.9 can be applied when $W: \mathbb{M}^{3\times 3} \to [0, +\infty]$ is given by

 $W(F) := h(\det F) + |F|^p,$

where $h : \mathbb{R} \to [0, +\infty]$ is a continuous function such that:

- $-h(t) = +\infty$ if and only if $t \leq 0$;
- for every $\delta > 0$, there exists $r_{\delta} > 0$ such that $h(t) \leq r_{\delta}$ for all $t \geq \delta$.

3. Representation of \mathcal{E}

The goal of this section is to show Theorem 3.4. To this end, we begin by proving two lemmas.

For every $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ and $j \ge 1$, we define the multifunction $\Lambda^j_v : \overline{\Sigma} \Longrightarrow \mathbb{R}^3$ by

$$\Lambda_{v}^{j}(x) := \left\{ \zeta \in \mathbb{R}^{3} \colon \det \left(\nabla v(x) \mid \zeta \right) \ge \frac{1}{j} \right\}.$$

Lemma 3.1. Let $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$. Then:

- (i) for every $j \ge 1$, Λ_v^j is a nonempty convex closed-valued lower semicontinuous¹ multifunction;
- (ii) for every $x \in \overline{\Sigma}$, $\Lambda_v^1(x) \subset \cdots \subset \Lambda_v^j(x) \subset \cdots \subset \bigcup_{j \ge 1} \Lambda_v^j(x) = \Lambda_v(x)$, where $\Lambda_v(x) := \{\zeta \in \mathbb{R}^3 : \det(\nabla v(x) \mid \zeta) > 0\}$.

Proof. (ii) is obvious. Prove then (i). Let $j \ge 1$. It is easy to see that for every $x \in \overline{\Sigma}$, $\Lambda_v^j(x)$ is nonempty, convex and closed. Let X be a closed subset of \mathbb{R}^3 , let $x \in \overline{\Sigma}$, and let $\{x_n\}_{n\ge 1} \subset \overline{\Sigma}$ such that $|x_n - x| \to 0$ as $n \to +\infty$ and $\Lambda_v^j(x_n) \subset X$ for all $n \ge 1$. Let $\zeta \in \Lambda_v^j(x)$ and let $\{\zeta_m\}_{m\ge 1} \subset \mathbb{R}^3$ be given by $\zeta_m := \zeta + \frac{1}{m}\zeta$. Then, for every $m \ge 1$,

$$\det(\nabla v(x) \mid \zeta_m) = \det(\nabla v(x) \mid \zeta) + \frac{1}{m}\det(\nabla v(x) \mid \zeta) \ge \frac{1}{j} + \frac{1}{mj}.$$
(8)

Fix any $m \ge 1$. Since det $(\nabla v(x_n) | \zeta_m) \to \det(\nabla v(x) | \zeta_m)$ as $n \to +\infty$, using (8) we see that det $(\nabla v(x_{n_0}) | \zeta_m) > \frac{1}{j}$ for some $n_0 \ge 1$, so that $\zeta_m \in \Lambda_v^j(x_{n_0})$. Thus $\zeta_m \in X$ for all $m \ge 1$. As X is closed we have $\zeta = \lim_{m \to +\infty} \zeta_m \in X$. \Box

In the sequel, given $\Lambda: \overline{\Sigma} \Longrightarrow \mathbb{R}^3$ we set

$$C(\overline{\Sigma}; \Lambda) := \left\{ \phi \in C\left(\overline{\Sigma}; \mathbb{R}^3\right) : \phi(x) \in \Lambda(x) \text{ for all } x \in \overline{\Sigma} \right\}.$$

where $C(\overline{\Sigma}; \mathbb{R}^3)$ denotes the space of all continuous functions from $\overline{\Sigma}$ to \mathbb{R}^3 .

Lemma 3.2. Given $v \in C^1_*(\Sigma; \mathbb{R}^3)$ and $j \ge 1$, if (2) holds, then

$$\inf_{\phi \in C(\overline{\Sigma}; \Lambda_v^j)} \int_{\Sigma} W(\nabla v(x) \mid \phi(x)) \, \mathrm{d}x = \int_{\Sigma} \inf_{\zeta \in \Lambda_v^j(x)} W(\nabla v(x) \mid \zeta) \, \mathrm{d}x.$$

To prove Lemma 3.2 we need the following interchange theorem of infimum and integral (that we proved in [1, Corollary 5.4]).

Theorem 3.3. Let $\Gamma : \overline{\Sigma} \Longrightarrow \mathbb{R}^3$ and let $f : \overline{\Sigma} \times \mathbb{R}^3 \to [0, +\infty]$. Assume that:

(H₁) *f* is a Carathéodory integrand;

(H₂) Γ is a nonempty convex closed-valued lower semicontinuous multifunction; (H₃) $C(\overline{\Sigma}; \Gamma) \neq \emptyset$ and for every $\phi, \hat{\phi} \in C(\overline{\Sigma}; \Gamma)$,

$$\int_{\Sigma} \max_{\alpha \in [0,1]} f\left(x, \alpha \phi(x) + (1-\alpha)\hat{\phi}(x)\right) \mathrm{d}x < +\infty.$$

¹ A multifunction $\Lambda: \overline{\Sigma} \to \mathbb{R}^3$ is said to be lower semicontinuous if for every closed subset X of \mathbb{R}^3 , every $x \in \overline{\Sigma}$ and every $\{x_n\}_{n \ge 1} \subset \overline{\Sigma}$ such that $|x_n - x| \to 0$ as $n \to +\infty$ and $\Lambda(x_n) \subset X$ for all $n \ge 1$, we have $\Lambda(x) \subset X$ (see [5] for more details).

Then,

$$\inf_{\phi \in C(\overline{\Sigma}; \Gamma)} \int_{\Sigma} f(x, \phi(x)) \, \mathrm{d}x = \int_{\Sigma} \inf_{\zeta \in \Gamma(x)} f(x, \zeta) \, \mathrm{d}x.$$

Proof of Lemma 3.2. Since *W* is continuous, (H₁) holds with $f(x, \zeta) = W(\nabla v(x) | \zeta)$. Lemma 3.1 shows that (H₂) is satisfied with $\Gamma = \Lambda_v^j$, and $C(\overline{\Sigma}; \Lambda_v^j) \neq \emptyset$ (for example $\Phi: \overline{\Sigma} \to \mathbb{R}^3$ defined by (12) belongs to $C(\overline{\Sigma}; \Lambda_v^j)$). Given $\phi, \hat{\phi} \in C(\overline{\Sigma}; \Lambda_v^j)$, it is clear that $\det(\nabla v(x) | \alpha \phi(x) + (1 - \alpha)\hat{\phi}(x)) \ge 1/j$ for all $\alpha \in [0, 1]$ and all $x \in \overline{\Sigma}$. By (2) there exists c > 0 depending only on *j*, *v*, ϕ and $\hat{\phi}$ such that $W(\nabla v(x) | \alpha \phi(x) + (1 - \alpha)\hat{\phi}(x)) \le c$ for all $x \in \overline{\Sigma}$. Thus (H₃) is verified with $f(x, \zeta) = W(\nabla v(x) | \zeta)$ and $\Gamma = \Lambda_v^j$, and Lemma 3.2 follows from Lemma 3.3.

Here is our (non-integral) representation theorem for \mathcal{E} .

Theorem 3.4. If (1) and (2) hold, then for every $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$,

$$\mathcal{E}(v) = \inf_{j \ge 1} \inf_{\phi \in C(\overline{\Sigma}; \Lambda_v^j)} \int_{\Sigma} W(\nabla v(x) \mid \phi(x)) \, \mathrm{d}x.$$
(9)

Proof. Fix $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ and denote by $\hat{\mathcal{E}}(v)$ the right-hand side of (9). It is easy to verify that $\mathcal{E}(v) \leq \hat{\mathcal{E}}(v)$. We are thus reduced to prove that

$$\hat{\mathcal{E}}(v) \leqslant \mathcal{E}(v). \tag{10}$$

Using Lemma 3.2, we obtain

$$\hat{\mathcal{E}}(v) \leqslant \inf_{j \ge 1} \int_{\Sigma} \inf_{\zeta \in A_v^j(x)} W(\nabla v(x) \mid \zeta) \,\mathrm{d}x.$$
⁽¹¹⁾

Consider the continuous function $\Phi: \overline{\Sigma} \to \mathbb{R}^3$ defined by

$$\Phi(x) := \frac{\partial_1 v(x) \wedge \partial_2 v(x)}{|\partial_1 v(x) \wedge \partial_2 v(x)|^2}.$$
(12)

Then, det $(\nabla v(x) | \Phi(x)) = 1$ for all $x \in \overline{\Sigma}$. Using (2) we deduce that there exists c > 0 depending only on p such that

$$\int_{\Sigma} \inf_{\zeta \in \Lambda_v^1(x)} W\big(\nabla v(x) \mid \zeta\big) \, \mathrm{d}x \leqslant c\big(|\Sigma| + \|\nabla v\|_{L^p(\Sigma;\mathbb{M}^{3\times 2})}^p + \|\varPhi\|_{L^p(\Sigma;\mathbb{R}^3)}^p\big).$$

It follows that $\inf_{\zeta \in \Lambda_v^1(\cdot)} W(\nabla v(\cdot) | \zeta) \in L^1(\Sigma)$. From Lemma 3.1(i) and (ii), we see that $\{\inf_{\zeta \in \Lambda_v^j(\cdot)} W(\nabla v(\cdot) | \zeta)\}_{j \ge 1}$ is non-increasing, and that for every $x \in \overline{\Sigma}$,

$$\inf_{j \ge 1} \inf_{\zeta \in \Lambda_v^j(x)} W(\nabla v(x) \mid \zeta) = W_0(\nabla v(x)), \tag{13}$$

and (23) follows from (11) and (13) by using Lebesgue's dominated convergence theorem. \Box

4. Existence of Γ -lim_{$\varepsilon \to 0$} $\mathcal{E}_{\varepsilon}$

In this section we prove Theorem 2.5. Since Γ -lim $\inf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon} \leq \Gamma$ -lim $\sup_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}$, we only need to show that:

- (a) $\overline{\mathcal{E}} \leqslant \Gamma \liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon};$
- (b) Γ -lim sup $_{\varepsilon \to 0} \mathcal{E}_{\varepsilon} \leqslant \overline{\mathcal{E}}$.

In the sequel, we follow the notation used in Section 3.

4.1. Proof of (a)

Let $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$ and let $\{v_{\varepsilon}\}_{\varepsilon} \subset W^{1,p}(\Sigma; \mathbb{R}^3)$ be such that $v_{\varepsilon} \to v$ in $L^p(\Sigma; \mathbb{R}^3)$. We have to prove that

$$\liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}(v_{\varepsilon}) \geqslant \overline{\mathcal{E}}(v). \tag{14}$$

Without loss of generality we can assume that $\sup_{\varepsilon>0} \mathcal{E}_{\varepsilon}(v_{\varepsilon}) < +\infty$. To every $\varepsilon > 0$ there corresponds $u_{\varepsilon} \in \pi_{\varepsilon}^{-1}(v_{\varepsilon})$ such that

$$\mathcal{E}_{\varepsilon}(v_{\varepsilon}) \geqslant E_{\varepsilon}(u_{\varepsilon}) - \varepsilon. \tag{15}$$

Defining $\hat{u}_{\varepsilon}: \Sigma_1 \to \mathbb{R}^3$ by $\hat{u}_{\varepsilon}(x, x_3) := u_{\varepsilon}(x, \varepsilon x_3)$ we have

$$E_{\varepsilon}(u_{\varepsilon}) = \int_{\Sigma_1} W\left(\partial_1 \hat{u}_{\varepsilon}(x, x_3) \mid \partial_2 \hat{u}_{\varepsilon}(x, x_3) \mid \frac{1}{\varepsilon} \partial_3 \hat{u}_{\varepsilon}(x, x_3)\right) dx dx_3.$$
(16)

Using the coercivity of W, we deduce that $\|\partial_3 \hat{u}_{\varepsilon}\|_{L^p(\Sigma_1;\mathbb{R}^3)} \leq c\varepsilon^p$ for all $\varepsilon > 0$ and some c > 0, and so $\|\hat{u}_{\varepsilon} - v_{\varepsilon}\|_{L^p(\Sigma_1;\mathbb{R}^3)} \leq c'\varepsilon^p$ by Poincaré–Wirtinger's inequality, where c' > 0 is a constant which does not depend on ε . It follows that $\hat{u}_{\varepsilon} \to v$ in $L^p(\Sigma_1;\mathbb{R}^3)$. For $x_3 \in]-\frac{1}{2}$, $\frac{1}{2}[$, let $w_{\varepsilon}^{x_3} \in$ $W^{1,p}(\Sigma;\mathbb{R}^3)$ given by $w_{\varepsilon}^{x_3}(x) := \hat{u}_{\varepsilon}(x, x_3)$. Then (up to a subsequence) $w_{\varepsilon}^{x_3} \to v$ in $L^p(\Sigma;\mathbb{R}^3)$ for a.e. $x_3 \in]-\frac{1}{2}, \frac{1}{2}[$. Taking (15) and (16) into account and using Fatou's lemma, we obtain

$$\liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}(v_{\varepsilon}) \geq \int_{-1/2}^{1/2} \left(\liminf_{\varepsilon \to 0} \int_{\Sigma} W_0(\nabla w_{\varepsilon}^{x_3}(x)) dx\right) dx_3,$$

and so $\liminf_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}(v_{\varepsilon}) \ge \mathcal{I}(v)$, and (14) follows by using Theorem 2.6. \Box

4.2. Proof of (b)

As Γ -lim sup $_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}$ is lower semicontinuous with respect to the strong topology of $L^p(\Sigma; \mathbb{R}^3)$ (see [9, Proposition 6.8 p. 57]), it is sufficient to prove that for every $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$,

$$\limsup_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}(v) \leqslant \mathcal{E}(v). \tag{17}$$

Given $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$, fix any $j \ge 1$, and any $n \ge 1$. Using Theorem 3.4 we obtain the existence of $\phi \in C(\overline{\Sigma}; \Lambda^j_v)$ such that

$$\int_{\Sigma} W(\nabla v(x) | \phi(x)) dx \leqslant \mathcal{E}(v) + \frac{1}{n}.$$
(18)

By Stone–Weierstrass's approximation theorem, there exists $\{\phi_k\}_{k \ge 1} \subset C^{\infty}(\overline{\Sigma}; \mathbb{R}^3)$ such that

$$\phi_k \to \phi$$
 uniformly as $k \to +\infty$. (19)

We claim that:

(c₁) det($\nabla v(x) | \phi_k(x)$) $\geq \frac{1}{2j}$ for all $x \in \overline{\Sigma}$, all $k \geq k_v$ and some $k_v \geq 1$; (c₂) lim_{k \to +\infty} $\int_{\Sigma} W(\nabla v(x) | \phi_k(x)) dx = \int_{\Sigma} W(\nabla v(x) | \phi(x)) dx$.

Indeed, setting $\mu_v := \sup_{x \in \overline{\Sigma}} |\partial_1 v(x) \wedge \partial_2 v(x)|$ ($\mu_v > 0$) and using (19), we deduce that there exists $k_v \ge 1$ such that for every $k \ge k_v$,

$$\sup_{x\in\overline{\Sigma}} \left|\phi_k(x) - \phi(x)\right| < \frac{1}{j\mu_v}.$$
(20)

Let $x \in \overline{\Sigma}$, and let $k \ge k_v$. As $\phi \in C(\overline{\Sigma}; \Lambda_v^j)$ we have

$$\det\left(\nabla v(x) \mid \phi_k(x)\right) \ge \frac{1}{j} - \det\left(\nabla v(x) \mid \phi_k(x) - \phi(x)\right).$$
(21)

Noticing that det($\nabla v(x) | \phi_k(x) - \phi(x)$) $\leq |\partial_1 v(x) \wedge \partial_2 v(x)| |\phi_k(x) - \phi(x)|$, from (20) and (21) we deduce that det($\nabla v(x) | \phi_k(x)$) $\geq \frac{1}{2j}$, and (c₁) is proved. Combining (c₁) with (2) we see that $\sup_{k \geq k_v} W(\nabla v(\cdot) | \phi_k(\cdot)) \in L^1(\Sigma)$. As *W* is continuous we have $\lim_{k \to +\infty} W(\nabla v(x) | \phi_k(x)) = W(\nabla v(x) | \phi(x))$ for all $x \in V$, and (c₂) follows by using Lebesgue's dominated convergence theorem, which completes the claim.

Fix any $k \ge k_v$ and define θ : $]-\frac{1}{2}, \frac{1}{2}[\rightarrow \mathbb{R} \text{ by } \theta(x_3) := \inf_{x \in \overline{\Sigma}} \det(\nabla v(x) + x_3 \nabla \phi_k(x) | \phi_k(x)).$ Clearly θ is continuous. By (c₁) we have $\theta(0) \ge \frac{1}{2j}$, and so there exists $\eta_v \in]0, \frac{1}{2}[$ such that $\theta(x_3) \ge \frac{1}{4j}$ for all $x_3 \in]-\eta_v, \eta_v[$. Let $u_k : \Sigma_1 \to \mathbb{R}$ be given by $u_k(x, x_3) := v(x) + x_3 \phi_k(x)$. From the above it follows that

(c₃) det
$$\nabla u_k(x, \varepsilon x_3) \ge \frac{1}{4j}$$
 for all $\varepsilon \in]0, \eta_v[$ and all $(x, x_3) \in \overline{\Sigma} \times]-\frac{1}{2}, \frac{1}{2}[$.

As in the proof of (c_1) , from (c_3) together with (2) and the continuity of W, we obtain

$$\lim_{\varepsilon \to 0} E_{\varepsilon}(u_k) = \lim_{\varepsilon \to 0} \int_{\Sigma_1} W(\nabla u_k(x, \varepsilon x_3)) \, \mathrm{d}x \, \mathrm{d}x_3 = \int_{\Sigma} W(\nabla v(x) \mid \phi_k(x)) \, \mathrm{d}x.$$
(22)

For every $\varepsilon > 0$ and every $k \ge k_v$, since $\pi_{\varepsilon}(u_k) = v$ we have $\mathcal{E}_{\varepsilon}(v) \le E_{\varepsilon}(u_k)$. Using (22), (c₂) and (18), we deduce that

 $\limsup_{\varepsilon\to 0} \mathcal{E}_{\varepsilon}(v) \leqslant \mathcal{E}(v) + \frac{1}{n},$

and (17) follows by letting $n \to +\infty$.

5. A simplified formula for $\overline{\mathcal{E}}$

In this section, we prove of Theorem 2.6. It is based upon two approximation theorems by Ben Belgacem–Bennequin (see Section A.1) and Gromov–Eliashberg (see Section A.2).

Recall the definition of rank one convexity and rank one convex envelope:

Definition 5.1. Let $f: \mathbb{M}^{3 \times 2} \to [0, +\infty]$ be a Borel measurable function.

(i) We say that f is rank one convex if for every $\alpha \in]0, 1[$ and every $\xi, \xi' \in \mathbb{M}^{3 \times 2}$ with $\operatorname{rank}(\xi - \xi') = 1$,

$$f(\alpha\xi + (1-\alpha)\xi') \leq \alpha f(\xi) + (1-\alpha)f(\xi').$$

(ii) By the rank one convex envelope of f, that we denote by $\mathcal{R}f$, we mean the greatest rank one convex function which less than or equal to f.

In [6, Proposition 7 p. 32 and Lemma 8 p. 34] (see also [8, Section 5.1], [16, Proposition 3.4.4 p. 112] and [17, Lemma 6.5]) Ben Belgacem proved the following lemma that we will use in the proof of Theorem 2.6. (As W_0 is coercive, it is easy to see that $\mathcal{R}W_0$ is coercive.)

Lemma 5.2. If (6) holds then:

(i) $\mathcal{R}W_0(\xi) \leq c(1+|\xi|^p)$ for all $\xi \in \mathbb{M}^{3\times 2}$ and some c > 0;

(ii) $\mathcal{R}W_0$ is continuous.

Define
$$I: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$$
 by

$$I(v) := \inf \left\{ \liminf_{n \to +\infty} \int_{\Sigma} W_0(\nabla v_n(x)) \, \mathrm{d}x: \, \mathrm{Aff}_{\mathrm{li}}(\Sigma; \mathbb{R}^3) \ni v_n \to v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}$$

with $\operatorname{Aff}_{\operatorname{li}}(\Sigma; \mathbb{R}^3) := \{v \in \operatorname{Aff}(\Sigma; \mathbb{R}^3): v \text{ is locally injective}\}$ (Aff $(\Sigma; \mathbb{R}^3)$ is defined in Section 2.3). To prove Theorem 2.6 we will use Proposition 5.3.

Proposition 5.3. I = J with $J: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ given by

$$J(v) := \inf \left\{ \liminf_{n \to +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) \, \mathrm{d}x \colon \operatorname{Aff}_{\mathrm{li}}(\Sigma; \mathbb{R}^3) \ni v_n \to v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

To prove Proposition 5.3 we need Lemma 5.4 whose proof is contained in the thesis of Ben Belgacem [6]. Since it is difficult to lay hands on this thesis (which is written in French), we give the proof of Lemma 5.4 in Appendix B.

Lemma 5.4. $I(v) \leq \int_{\Sigma} \mathcal{R}W_0(\nabla v(x)) \, dx$ for all $v \in \operatorname{Aff}_{\operatorname{li}}(\Sigma; \mathbb{R}^3)$.

Proof of Proposition 5.3. Clearly $J \leq I$. We are thus reduced to prove that

$$I \leqslant J. \tag{23}$$

Fix any $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$ and any sequence $v_n \to v$ in $L^p(\Sigma; \mathbb{R}^3)$ with $v_n \in Aff_{li}(\Sigma; \mathbb{R}^3)$. Using Lemma 5.4 we have $I(v_n) \leq \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) dx$ for all $n \geq 1$. Thus,

$$I(v) \leq \liminf_{n \to +\infty} I(v_n) \leq \liminf_{n \to +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) \, \mathrm{d}x,$$

and (23) follows. \Box

Proof of Theorem 2.6. We first prove that

$$\overline{\mathcal{E}} \leqslant I. \tag{24}$$

As in the proof of Proposition 5.3, it suffices to show that if $v \in \text{Aff}_{\text{li}}(\Sigma; \mathbb{R}^3)$ then

$$\overline{\mathcal{E}}(v) \leqslant \int_{\Sigma} W_0 \big(\nabla v(x) \big) \, \mathrm{d}x.$$
⁽²⁵⁾

Let $v \in \operatorname{Aff}_{\operatorname{li}}(\Sigma; \mathbb{R}^3)$. By Theorem A.1-bis (and Lemma A.2), there exists $\{v_n\}_{n \ge 1} \subset C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ such that (28) and (29) holds and $\nabla v_n(x) \to \nabla v(x)$ a.e. in Σ . As W_0 is continuous (see Lemma 2.4(i)), we have

$$\lim_{n \to +\infty} W_0(\nabla v_n(x)) = W_0(\nabla v(x)) \quad \text{a.e. in } \Sigma.$$

Using (6) together with (29), we deduce that there exists c > 0 such that for every $n \ge 1$ and every measurable set $A \subset \Sigma$,

$$\int_{A} W_0 \left(\nabla v_n(x) \right) \mathrm{d}x \leq c \left(|A| + \int_{A} \left| \nabla v_n(x) - \nabla v(x) \right|^p \mathrm{d}x + \int_{A} \left| \nabla v(x) \right|^p \mathrm{d}x \right)$$

But $\nabla v_n \to \nabla v$ in $L^p(\Sigma; \mathbb{M}^{3\times 2})$ by (28), hence $\{W_0(\nabla v_n(\cdot))\}_{n \ge 1}$ is absolutely uniformly integrable. Using Vitali's theorem, we obtain

$$\lim_{n \to +\infty} \int_{\Sigma} W_0(\nabla v_n(x)) \, \mathrm{d}x = \int_{\Sigma} W_0(\nabla v(x)) \, \mathrm{d}x.$$

and (25) follows.

We now prove that

$$J \leqslant \bar{J},\tag{26}$$

with $\overline{J}: W^{1,p}(\Sigma; \mathbb{R}^3) \to [0, +\infty]$ given by

$$\bar{J}(v) := \inf \left\{ \liminf_{n \to +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) \, \mathrm{d}x : W^{1,p}(\Sigma; \mathbb{R}^3) \ni v_n \to v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

It is sufficient to show that

$$J(v) \leqslant \int_{\Sigma} \mathcal{R}W_0(\nabla v(x)) \,\mathrm{d}x.$$
⁽²⁷⁾

Let $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$. By Corollary A.6, there exists $\{v_n\}_{n \ge 1} \subset \operatorname{Aff}_{\operatorname{li}}(\Sigma; \mathbb{R}^3)$ such that $\nabla v_n \to \nabla v$ in $L^p(\Sigma; \mathbb{R}^3)$ and $\nabla v_n(x) \to \nabla v(x)$ a.e. in Σ . Taking Lemma 5.2 into account, from Vitali's lemma, we see that

$$\lim_{n \to +\infty} \int_{\Sigma} \mathcal{R} W_0 \big(\nabla v_n(x) \big) \, \mathrm{d}x = \int_{\Sigma} \mathcal{R} W_0 \big(\nabla v(x) \big) \, \mathrm{d}x,$$

and (27) follows.

Noticing that $\mathcal{I} \leq \overline{\mathcal{E}}$ and $\overline{J} \leq \mathcal{I}$, and combining Proposition 5.3 with (24) and (26), we conclude that $\overline{\mathcal{E}} = \mathcal{I}$. \Box

Appendix A. Approximation theorems

A.1. Ben Belgacem-Bennequin's theorem

Denote by $\operatorname{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ the space of Ekeland–Temam continuous piecewise affine functions from Σ to \mathbb{R}^3 , i.e., $u \in \operatorname{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ if and only if v is continuous and there exists a finite family $(V_i)_{i \in I}$ of open disjoint subsets of Σ such that $|\Sigma \setminus \bigcup_{i \in I} V_i| = 0$ and for every $i \in I$, the restriction of v to V_i is affine. Note that from Ekeland–Temam [10], we know that $\operatorname{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ is strongly dense in $W^{1,p}(\Sigma; \mathbb{R}^3)$. Set

 $\operatorname{Aff}_{\operatorname{li}}^{ET}(\Sigma; \mathbb{R}^3) := \{ v \in \operatorname{Aff}^{ET}(\Sigma; \mathbb{R}^3) \colon v \text{ is locally injective} \}.$

In [6, Lemma 8 p. 114] (see also [16, Proposition C.0.4 p. 127] and [17, Lemma 1.3]) Ben Belgacem and Bennequin proved the following result.

Theorem A.1. For every $v \in \operatorname{Aff}_{\operatorname{li}}^{ET}(\Sigma; \mathbb{R}^3)$, there exists $\{v_n\}_{n \ge 1} \subset C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ such that:

$$v_n \to v \text{ in } W^{1,p}(\Sigma; \mathbb{R}^3);$$
(28)

$$\left|\partial_1 v_n(x) \wedge \partial_2 v_n(x)\right| \ge \delta \quad \text{for all } x \in \Sigma, \text{ all } n \ge 1 \text{ and some } \delta > 0.$$
(29)

Denote by Aff^V(Σ ; \mathbb{R}^3) the space of Vitali continuous piecewise affine functions from Σ to \mathbb{R}^3 (introduced by Ben Belgacem in [6,8]), i.e., $v \in Aff^V(\Sigma; \mathbb{R}^3)$ if and only if v is continuous and there exists a finite or countable family $(O_i)_{i \in I}$ of disjoint open subsets of Σ such that $|\partial O_i| = 0$ for all $i \in I$, $|\Sigma \setminus \bigcup_{i \in I} O_i| = 0$, and $v(x) = \xi_i \cdot x + a_i$ if $x \in O_i$, where $a_i \in \mathbb{R}^3$, $\xi_i \in \mathbb{M}^{3 \times 2}$ and Card $\{\xi_i : i \in I\}$ is finite. In [16, Lemma 3.1.5 p. 99] Trabelsi remarked that Theorem A.1 can be generalized replacing the space Aff_{li}^{ET}(\Sigma; \mathbb{R}^3) by

$$\operatorname{Aff}_{\operatorname{li}}^{V}(\Sigma; \mathbb{R}^{3}) := \{ v \in \operatorname{Aff}^{V}(\Sigma; \mathbb{R}^{3}) \colon v \text{ is locally injective} \}.$$

Theorem A.1-bis. For every $v \in \operatorname{Aff}_{\operatorname{li}}^{V}(\Sigma; \mathbb{R}^{3})$, there exists $\{v_{n}\}_{n \geq 1} \subset C_{*}^{1}(\overline{\Sigma}; \mathbb{R}^{3})$ satisfying (28) and (29).

Here we consider the space $\operatorname{Aff}(\Sigma; \mathbb{R}^3)$ defined in Section 2.3. It is clear that $\operatorname{Aff}^{ET}(\Sigma; \mathbb{R}^3) \subset \operatorname{Aff}(\Sigma; \mathbb{R}^3)$, and so $\operatorname{Aff}(\Sigma; \mathbb{R}^3)$ is strongly dense in $W^{1,p}(\Sigma; \mathbb{R}^3)$. Moreover, we have

Lemma A.2. Aff^V(Σ ; \mathbb{R}^3) = Aff(Σ ; \mathbb{R}^3).

Proof. Setting $D_i := \{x \in \bigcup_{i \in I} O_i : \nabla v(x) = \xi_i\}$ with $v \in \operatorname{Aff}^V(\Sigma; \mathbb{R}^3)$, we see that $\operatorname{Card}\{D_i : i \in I\}$ is finite. Thus $\operatorname{Aff}^V(\Sigma; \mathbb{R}^3) \subset \operatorname{Aff}(\Sigma; \mathbb{R}^3)$. Given $v \in \operatorname{Aff}(\Sigma; \mathbb{R}^3)$, let $(O_j)_{j \in J_i}$ be the connected components of D_i with $i \in I$ (where I is finite). Since D_i is open, O_j is open for all $j \in J_i$, hence J_i is finite or countable because \mathbb{Q}^2 is dense in \mathbb{R}^2 . Moreover, for each $j \in J_i$, the restriction of v to O_j is affine. Thus $\operatorname{Aff}(\Sigma; \mathbb{R}^3) \subset \operatorname{Aff}^V(\Sigma; \mathbb{R}^3)$. \Box

A.2. Gromov–Eliashberg's theorem

In [11, Theorem 1.3.4B] (see also [12, Theorem B'_1 p. 20]) Gromov and Eliashberg proved the following result.

Theorem A.3. Let $1 \leq N < m$ be two integers and let M be a compact N-dimensional manifold which can be immersed in \mathbb{R}^m . Then, for each C^1 -differentiable function v from M to \mathbb{R}^m there exists a sequence $\{v_n\}_n$ of C^1 -immersions from M to \mathbb{R}^m such that $v_n \to v$ in $W^{1,p}(M; \mathbb{R}^m)$.

In our context, we have

Theorem A.4. For every $v \in C^1(\overline{\Sigma}; \mathbb{R}^3)$ there exists $\{v_n\}_{n \ge 1} \subset C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ such that $v_n \to v$ in $W^{1,p}(\Sigma; \mathbb{R}^3)$.

Moreover, from [16, Proposition 3.1.7 p. 100], we have

Proposition A.5. For every $v \in C^1_*(\overline{\Sigma}; \mathbb{R}^3)$ there exists $\{v_n\}_{n \ge 1} \subset \operatorname{Aff}_{\operatorname{li}}^{ET}(\Sigma; \mathbb{R}^3)$ such that $v_n \to v$ in $W^{1,p}(\Sigma; \mathbb{R}^3)$.

Thus, as a consequence of Theorem A.4 and Proposition A.5, we obtain

Corollary A.6. Aff^{*ET*}_{li}(Σ ; \mathbb{R}^3) is strongly dense in $W^{1,p}(\Sigma; \mathbb{R}^3)$.

Appendix B. Ben Belgacem's lemma

In this appendix we prove Ben Belgacem's lemma, i.e., Lemma 5.4.

B.1. Preliminaries

Define the sequence $\{\mathcal{R}_i W_0\}_{i \ge 0}$ by $\mathcal{R}_0 W_0 = W_0$ and for every $i \ge 1$ and every $\xi \in \mathbb{M}^{3 \times 2}$,

$$\mathcal{R}_{i+1}W_0(\xi) := \inf_{\substack{a \in \mathbb{R}^2 \\ b \in \mathbb{R}^3 \\ t \in [0,1]}} \left\{ (1-t)\mathcal{R}_i W_0(\xi - ta \otimes b) + t\mathcal{R}_i W_0(\xi + (1-t)a \otimes b) \right\}$$

Recall that W_0 is coercive and continuous (see Lemma 2.4(i)). The following lemma is due to Kohn and Strang [13].

Lemma B.1. $\mathcal{R}_{i+1}W_0 \leq \mathcal{R}_i W_0$ for all $i \geq 0$ and $\mathcal{R}W_0 = \inf_{i \geq 0} \mathcal{R}_i W_0$.

Fix any $i \ge 0$ and any $v \in Aff_{li}(\Sigma; \mathbb{R}^3) := \{v \in Aff(\Sigma; \mathbb{R}^3): v \text{ is locally injective}\}$ (with $Aff(\Sigma; \mathbb{R}^3)$ defined in Section 2.3). By definition, there exists a finite family $(V_j)_{j \in J}$ of open disjoint subsets of Σ such that $|\partial V_j| = 0$ for all $j \in J$, $|\Sigma \setminus \bigcup_{j \in J} V_j| = 0$ and, for every $j \in J$, $\nabla v(x) = \xi_j$ in V_j with $\xi_j \in \mathbb{M}^{3 \times 2}$. (As v is locally injective we have rank $(\xi_j) = 2$ for all $j \in J$.) Fix any $j \in J$. For a proof of Lemmas B.2 and B.3 we refer to [16, Proposition 3.1.2 p. 96].

Lemma B.2. $\mathcal{R}_i W_0$ is continuous.

Lemma B.3. There exist $a \in \mathbb{R}^2$, $b \in \mathbb{R}^3$ and $t \in [0, 1]$ such that

 $\mathcal{R}_{i+1}W_0(\xi_j) = (1-t)\mathcal{R}_i W_0(\xi_j - ta \otimes b) + t\mathcal{R}_i W_0(\xi_j + (1-t)a \otimes b).$

Without loss of generality we can assume that a = (1, 0). For each $n \ge 3$ and each $k \in \{0, ..., n-1\}$, consider $A_{k,n}^-, A_{k,n}^+, B_{k,n}, B_{k,n}^-, B_{k,n}^+, C_{k,n}, C_{k,n}^-, C_{k,n}^+ \subset Y$ given by:

$$\begin{split} A_{k,n}^{-} &:= \left\{ (x_1, x_2) \in Y \colon \frac{k}{n} \leqslant x_1 \leqslant \frac{k}{n} + \frac{1-t}{n} \text{ and } \frac{1}{n} \leqslant x_2 \leqslant 1 - \frac{1}{n} \right\}; \\ A_{k,n}^{+} &:= \left\{ (x_1, x_2) \in Y \colon \frac{k}{n} + \frac{1-t}{n} \leqslant x_1 \leqslant \frac{k+1}{n} \text{ and } \frac{1}{n} \leqslant x_2 \leqslant 1 - \frac{1}{n} \right\}; \\ B_{k,n} &:= \left\{ (x_1, x_2) \in Y \colon \frac{k}{n} \leqslant x_1 \leqslant \frac{k+1}{n} \text{ and } 0 \leqslant x_2 \leqslant -x_1 + \frac{k+1}{n} \right\}; \\ B_{k,n}^{-} &:= \left\{ (x_1, x_2) \in Y \colon -x_2 + \frac{k+1}{n} \leqslant x_1 \leqslant -tx_2 + \frac{k+1}{n} \text{ and } 0 \leqslant x_2 \leqslant \frac{1}{n} \right\}; \\ B_{k,n}^{+} &:= \left\{ (x_1, x_2) \in Y \colon -tx_2 + \frac{k+1}{n} \leqslant x_1 \leqslant \frac{k+1}{n} \text{ and } 0 \leqslant x_2 \leqslant \frac{1}{n} \right\}; \\ C_{k,n}^{-} &:= \left\{ (x_1, x_2) \in Y \colon \frac{k}{n} \leqslant x_1 \leqslant \frac{k+1}{n} \text{ and } x_1 + 1 - \frac{k+1}{n} \leqslant x_2 \leqslant 1 \right\}; \\ C_{k,n}^{-} &:= \left\{ (x_1, x_2) \in Y \colon x_2 - 1 + \frac{k+1}{n} \leqslant x_1 \leqslant t(x_2 - 1) + \frac{k+1}{n} \text{ and } 0 \leqslant x_2 \leqslant \frac{1}{n} \right\}; \\ C_{k,n}^{+} &:= \left\{ (x_1, x_2) \in Y \colon t(x_2 - 1) + \frac{k+1}{n} \leqslant x_1 \leqslant \frac{k+1}{n} \text{ and } 0 \leqslant x_2 \leqslant \frac{1}{n} \right\}, \end{split}$$

and define $\{\sigma_n\}_{n \ge 1} \subset \operatorname{Aff}_0(Y; \mathbb{R})$ by

$$\sigma_n(x_1, x_2) := \begin{cases} -t(x_1 - \frac{k}{n}) & \text{if } (x_1, x_2) \in A_{k,n}^-, \\ (1 - t)(x_1 - \frac{k+1}{n}) & \text{if } (x_1, x_2) \in A_{k,n}^+ \cup B_{k,n}^+ \cup C_{k,n}^+, \\ -t(x_1 + x_2 - \frac{k+1}{n}) & \text{if } (x_1, x_2) \in B_{k,n}^-, \\ -t(x_1 - x_2 + 1 - \frac{k+1}{n}) & \text{if } (x_1, x_2) \in C_{k,n}^-, \\ 0 & \text{if } (x_1, x_2) \in B_{k,n} \cup C_{k,n} \end{cases}$$

(see Fig. B.1).

Set

$$b_{\ell} := \begin{cases} b & \text{if } b \notin \operatorname{Im} \xi_j, \\ b + \frac{1}{\ell} \nu & \text{if } b \in \operatorname{Im} \xi_j \end{cases}$$

(with Im $\xi_i := \{\xi_i \cdot x : x \in \mathbb{R}^2\}$) where $\ell \ge 1$ and $\nu \in \mathbb{R}^3$ is a normal vector to Im ξ_i .

Lemma B.4. *Define* $\{\theta_{n,\ell}\}_{n,\ell \ge 1} \subset \operatorname{Aff}_0(Y; \mathbb{R}^3)$ *by*

$$\theta_{n,\ell}(x) := \sigma_n(x) b_\ell$$

Then:

- (i) for every $\ell \ge 1$, $\theta_{n,\ell} \to 0$ in $L^p(Y; \mathbb{R}^3)$; (ii) $\lim_{\ell \to +\infty} \lim_{n \to +\infty} \int_Y \mathcal{R}_i W_0(\xi_j + \nabla \theta_{n,\ell}(x)) \, \mathrm{d}x = \mathcal{R}_{i+1} W_0(\xi_j)$.



Fig. B.1. The function σ_n and the sets $A_{k,n}^-, A_{k,n}^+, B_{k,n}, B_{k,n}^-, B_{k,n}^+, C_{k,n}, C_{k,n}^-, C_{k,n}^+$.

Proof. (i) It suffices to prove that $\sigma_n \to 0$ in $L^p(Y; \mathbb{R})$. For every $k \in \{0, ..., n-1\}$, it is clear that $|\sigma_n(x)|^p \leq \frac{t^p(1-t)^p}{p}$ for all $x \in]\frac{k}{n}, \frac{k+1}{n} [\times]0, 1[$, and so

$$\int_{\left|\frac{k}{n},\frac{k+1}{n}\right| \times]0,1[} \left|\sigma_n(x)\right|^p \mathrm{d}x \leqslant \frac{t^p (1-t)^p}{n^{p+1}}.$$

As

$$\int_{Y} |\sigma_n(x)|^p \, \mathrm{d}x = \sum_{k=0}^{n-1} \int_{]^{\frac{k}{n}, \frac{k+1}{n}} [\times]0,1[} |\sigma_n(x)|^p \, \mathrm{d}x$$

it follows that

$$\int_{Y} \left| \sigma_n(x) \right|^p \mathrm{d}x \leqslant \frac{t^p (1-t)^p}{n^p},$$

which gives the desired conclusion.

(ii) Recalling that a = (1, 0) we see that

$$\xi_{j} + \nabla \theta_{n,\ell}(x) := \begin{cases} \xi_{j} - ta \otimes b_{\ell} & \text{if } x \in \operatorname{int}(A_{k,n}^{-}), \\ \xi_{j} + (1 - t)a \otimes b_{\ell} & \text{if } x \in \operatorname{int}(A_{k,n}^{+} \cup B_{k,n}^{+} \cup C_{k,n}^{+}), \\ \xi_{j} - t(a + a^{\perp}) \otimes b_{\ell} & \text{if } x \in \operatorname{int}(B_{k,n}^{-}), \\ \xi_{j} - t(a - a^{\perp}) \otimes b_{\ell} & \text{if } x \in \operatorname{int}(C_{k,n}^{-}), \\ \xi_{j} & \text{if } x \in \operatorname{int}(B_{k,n}) \cup \operatorname{int}(C_{k,n}) \end{cases}$$

with $a^{\perp} = (0, 1)$ (and int(*E*) denotes the interior of the set *E*). Moreover, we have:

$$\begin{split} & \int_{\bigcup_{k=0}^{n-1} A_{k,n}^{-}} \mathcal{R}_{i} W_{0}(\xi_{j} - ta \otimes b_{\ell}) \, \mathrm{d}x = (1 - t) \left(1 - \frac{2}{n}\right) \mathcal{R}_{i} W_{0}(\xi_{j} - ta \otimes b_{\ell}); \\ & \int_{\bigcup_{k=0}^{n-1} A_{k,n}^{+}} \mathcal{R}_{i} W_{0}(\xi_{j} + (1 - t)a \otimes b_{\ell}) \, \mathrm{d}x = t \left(1 - \frac{2}{n}\right) \mathcal{R}_{i} W_{0}(\xi_{j} + (1 - t)a \otimes b_{\ell}); \\ & \int_{\bigcup_{k=0}^{n-1} (B_{k,n}^{+} \cup C_{k,n}^{+})} \mathcal{R}_{i} W_{0}(\xi_{j} + (1 - t)a \otimes b_{\ell}) \, \mathrm{d}x = \frac{t}{n} \mathcal{R}_{i} W_{0}(\xi_{j} + (1 - t)a \otimes b_{\ell}); \\ & \bigcup_{k=0}^{n-1} B_{k,n}^{-}} \mathcal{R}_{i} W_{0}(\xi_{j} - t(a + a^{\perp}) \otimes b_{\ell}) \, \mathrm{d}x = \frac{1 - t}{n} \mathcal{R}_{i} W_{0}(\xi_{j} - t(a + a^{\perp}) \otimes b_{\ell}); \\ & \int_{\bigcup_{k=0}^{n-1} C_{k,n}^{-}} \mathcal{R}_{i} W_{0}(\xi_{j} - t(a - a^{\perp}) \otimes b_{\ell}) \, \mathrm{d}x = \frac{1 - t}{2n} \mathcal{R}_{i} W_{0}(\xi_{j} - t(a - a^{\perp}) \otimes b_{\ell}); \\ & \int_{\bigcup_{k=0}^{n-1} (B_{k,n} \cup C_{k,n})} \mathcal{R}_{i} W_{0}(\xi_{j}) \, \mathrm{d}x = \frac{1}{n} \mathcal{R}_{i} W_{0}(\xi_{j}). \end{split}$$

Hence

$$\begin{split} &\int\limits_{Y} \mathcal{R}_{i} W_{0} \big(\xi_{j} + \nabla \theta_{n,\ell}(x) \big) \, \mathrm{d}x \\ &= \Big(1 - \frac{2}{n} \Big) \big[(1 - t) \mathcal{R}_{i} W_{0}(\xi_{j} - ta \otimes b_{\ell}) + t \mathcal{R}_{i} W_{0} \big(\xi_{j} + (1 - t)a \otimes b_{\ell} \big) \big] \\ &\quad + \frac{1}{n} \bigg[t \mathcal{R}_{i} W_{0} \big(\xi_{j} + (1 - t)a \otimes b_{\ell} \big) + \frac{1 - t}{2} \big(\mathcal{R}_{i} W_{0} \big(\xi_{j} - t \big(a + a^{\perp} \big) \otimes b_{\ell} \big) \big) \\ &\quad + \mathcal{R}_{i} W_{0} \big(\xi_{j} - t \big(a - a^{\perp} \big) \otimes b_{\ell} \big) \big) + \mathcal{R}_{i} W_{0} \big(\xi_{j} \big) \bigg] \end{split}$$

for all $n, \ell \ge 1$. It follows that for every $\ell \ge 1$,

$$\lim_{n \to +\infty} \int_{Y} \mathcal{R}_{i} W_{0}(\xi_{j} + \nabla \theta_{n,\ell}(x)) dx = (1-t)\mathcal{R}_{i} W_{0}(\xi_{j} - ta \otimes b_{\ell}) + t\mathcal{R}_{i} W_{0}(\xi_{j} + (1-t)a \otimes b_{\ell}).$$

Taking Lemma B.2 into account and noticing that $b_{\ell} \rightarrow b$, we deduce that

$$\lim_{\ell \to +\infty} \lim_{n \to +\infty} \int_{Y} \mathcal{R}_{i} W_{0}(\xi_{j} + \nabla \theta_{n,\ell}(x)) dx = (1-t)\mathcal{R}_{i} W_{0}(\xi_{j} - ta \otimes b) + t\mathcal{R}_{i} W_{0}(\xi_{j} + (1-t)a \otimes b),$$

and (ii) follows by using Lemma B.3. \Box

Consider $V_q^j \subset V_j$ given by $V_q^j := \{x \in V_j: \operatorname{dist}(x, \partial V_j) > \frac{1}{q}\}$ with $q \ge 1$ large enough. By Vitali's covering theorem, there exists a finite or countable family $(r_m + \rho_m Y)_{m \in M}$ of disjoint

subsets of V_q^j , with $r_m \in \mathbb{R}^2$ and $\rho_m \in]0, 1[$, such that $|V_q^j \setminus \bigcup_{m \in M} (r_m + \rho_m Y)| = 0$ (and so $\sum_{m \in M} \rho_m^2 = |V_q^j|$). Let $\{\phi_{n,\ell,q}\}_{n,\ell,q \ge 1} \subset \operatorname{Aff}_0(V_j; \mathbb{R}^3)$ be given by

$$\phi_{n,\ell,q}(x) := \begin{cases} \rho_m \theta_{n,\ell}((x-r_m)/\rho_m) & \text{if } x \in r_m + \rho_m Y \subset V_q^j, \\ 0 & \text{if } x \in V_j \setminus V_q^j. \end{cases}$$

Lemma B.5. Define $\{\Phi_{n,\ell,q}^j\}_{n,\ell,q \ge 1} \subset \operatorname{Aff}(V_j; \mathbb{R}^3)$ by

$$\Phi_{n,\ell,q}^{j}(x) := v(x) + \phi_{n,\ell,q}(x).$$
(30)

Then:

- (i) for every $n, \ell, q \ge 1$, $\Phi_{n,\ell,q}^{j}$ is locally injective;
- (ii) for every $\ell, q \ge 1$, $\Phi_{n,\ell,q}^j \to v$ in $L^p(V_j; \mathbb{R}^3)$;
- (iii) $\lim_{q \to +\infty} \lim_{\ell \to +\infty} \lim_{n \to +\infty} \int_{V_i} \mathcal{R}_i W_0(\nabla \Phi_{n,\ell,q}^j(x)) \, \mathrm{d}x = |V_j| \mathcal{R}_{i+1} W_0(\xi_j).$

Proof. (i) Let $x \in V_j$ and let $W \subset V_j$ be the connected component of V_j such that $x \in W$ (as V_j is open, so is W). Since $\nabla v = \xi_j$ in W, there exists $c \in \mathbb{R}^3$ such that $v(x') = \xi_j \cdot x' + c$ for all $x' \in W$. We claim that $\Phi_{n,\ell,q}^j \downarrow_W$ is injective. Indeed, let $x' \in W$ be such that $\Phi_{n,\ell,q}^j(x) = \Phi_{n,\ell,q}^j(x')$. One the three possibilities holds:

(a) $\Phi_{n,\ell,q}^{j}(x) = \xi_{j} \cdot x + c + \rho_{m}\sigma_{n}(\frac{x-r_{m}}{\rho_{m}})b_{\ell}$ and $\Phi_{n,\ell,q}^{j}(x') = \xi_{j} \cdot x' + c + \rho_{m'}\sigma_{n}(\frac{x'-r_{m'}}{\rho_{m'}})b_{\ell}$; (b) $\Phi_{n,\ell,q}^{j}(x) = \xi_{j} \cdot x + c + \rho_{m}\sigma_{n,\ell}(\frac{x-r_{m}}{\rho_{m}})b_{\ell}$ and $\Phi_{n,\ell,q}^{j}(x') = \xi_{j} \cdot x' + c$; (c) $\Phi_{n,\ell,q}^{j}(x) = \xi_{j} \cdot x + c$ and $\Phi_{n,\ell,q}^{j}(x') = \xi_{j} \cdot x' + c$.

Setting $\alpha := \rho_m \sigma_n(\frac{x-r_m}{\rho_m}) - \rho_{m'} \sigma_n(\frac{x'-r_{m'}}{\rho_{m'}})$ and $\beta := \rho_m \sigma_n(\frac{x-r_m}{\rho_m})$ we have:

$$\begin{cases} \xi_j(x'-x) = 0 & \text{if } \alpha = 0, \\ b_\ell = \frac{1}{\alpha} \xi_j(x'-x) & \text{if } \alpha \neq 0 \end{cases}$$
 when (a) is satisfied;
$$\begin{cases} \xi_j(x'-x) = 0 & \text{if } \beta = 0, \\ b_\ell = \frac{1}{\beta} \xi_j(x'-x) & \text{if } \beta \neq 0 \end{cases}$$
 when (b) is satisfied;

 $\xi_j(x'-x) = 0$ when (c) is satisfied.

It follows that if $x \neq x'$ then either rank $(\xi_j) < 2$ or $b_\ell \in \text{Im} \xi_j$ which is impossible. Hence x = x', and the claim is proved. Thus $\Phi_{n,\ell,q}^j$ is locally injective.

(ii) As $\rho_m \in [0, 1[$ for all $m \in M$ and $\sum_{m \in M} \rho_m^2 = |V_q^j|$ we have

$$\int_{V_q^j} \left| \phi_{n,\ell,q}(x) \right|^p \mathrm{d}x \leqslant \left| V_q^j \right| \int_Y \left| \theta_{n,\ell}(x) \right|^p \mathrm{d}x.$$

Using Lemma B.4(i) we deduce that for every $\ell, q \ge 1$,

$$\lim_{n \to +\infty} \int_{V_q^j} \left| \phi_{n,\ell,q}(x) \right|^p \mathrm{d}x = 0,$$

and (ii) follows.

(iii) Recalling that $\sum_{m \in M} \rho_m^2 = |V_q^j|$ we see that

$$\begin{split} \int_{V_j} \mathcal{R}_i W_0 \big(\nabla \Phi_{n,\ell,q}^j(x) \big) \, \mathrm{d}x &= \int_{V_j} \mathcal{R}_i W_0 \big(\xi_j + \nabla \phi_{n,\ell,q}(x) \big) \, \mathrm{d}x \\ &= \int_{V_q^j} \mathcal{R}_i W_0 \big(\xi_j + \nabla \phi_{n,\ell,q}(x) \big) \, \mathrm{d}x + \big| V_j \setminus V_q^j \big| \mathcal{R}_i W_0(\xi_j) \\ &= \big| V_q^j \big| \int_Y \mathcal{R}_i W_0 \big(\xi_j + \nabla \theta_{n,\ell}(x) \big) \, \mathrm{d}x + \big| V_j \setminus V_q^j \big| \mathcal{R}_i W_0(\xi_j). \end{split}$$

Using Lemma B.4(ii) we deduce that for every $q \ge 1$,

$$\lim_{\ell \to +\infty} \lim_{n \to +\infty} \int_{V_j} \mathcal{R}_i W_0 \left(\nabla \Phi_{n,\ell,q}^j(x) \right) \mathrm{d}x = \left| V_q^j \right| \mathcal{R}_{i+1} W_0(\xi_j) + \left| V_j \setminus V_q^j \right| \mathcal{R}_i W_0(\xi_j),$$

and (iii) follows by noticing that $|V_q^j| \to |V_j|$ and $|V_j \setminus V_q^j| \to 0$. \Box

B.2. Proof of Lemma 5.4

According to Lemma B.1, it is sufficient to show that for every $i \ge 0$,

$$I(v) \leqslant \int_{\Sigma} \mathcal{R}_{i} W_{0}(\nabla v(x)) \, \mathrm{d}x \text{ for all } v \in \mathrm{Aff}_{\mathrm{li}}(\Sigma; \mathbb{R}^{3}).$$

$$(P_{i})$$

The proof is by induction on *i*. As $R_0W_0 = W_0$ it is clear that (P_0) is true. Assume that (P_i) is true, and prove that (P_{i+1}) is true. Let $v \in Aff_{li}(\Sigma; \mathbb{R}^3)$. By definition, there exists a finite family $(V_j)_{j \in J}$ of open disjoint subsets of Σ such that $|\partial V_j| = 0$ for all $j \in J$, $|\Sigma \setminus \bigcup_{j \in J} V_j| = 0$ and, for every $j \in J$, $\nabla v(x) = \xi_j$ in V_j with $\xi_j \in \mathbb{M}^{3 \times 2}$. Define $\{\Psi_{n,\ell,q}\}_{n,\ell,q \ge 1} \subset Aff(\Sigma; \mathbb{R}^3)$ by

$$\Psi_{n,\ell,q}(x) := \Phi_{n,\ell,q}^j(x) \quad \text{if } x \in V_j$$

with $\Phi_{n,\ell,q}^{j}$ given by (30). Taking Lemma B.5(i) into account (and recalling that v is locally injective), it is easy to see that $\Psi_{n,\ell,q}$ is locally injective. Using (P_i) we can assert that

$$I(\Psi_{n,\ell,q}) \leqslant \int_{\Sigma} R_i W_0 \big(\nabla \Psi_{n,\ell,q}(x) \big) \, \mathrm{d}x \text{ for all } n, \ell, q \ge 1.$$

By Lemma B.5(ii) it is clear that for every $\ell, q \ge 1, \Psi_{n,l,q} \to v$ in $L^p(\Sigma; \mathbb{R}^3)$. It follows that

$$I(v) \leqslant \lim_{n \to +\infty} I(\Psi_{n,\ell,q}) \leqslant \lim_{n \to +\infty} \int_{\Sigma} R_i W_0(\nabla \Psi_{n,\ell,q}(x)) \, \mathrm{d}x \quad \text{for all } \ell, q \ge 1.$$

Moreover, from Lemma B.5(iii) we see that

$$\lim_{q \to +\infty} \lim_{\ell \to +\infty} \lim_{n \to +\infty} \int_{\Sigma} R_i W_0 \big(\nabla \Psi_{n,\ell,q}(x) \big) \, \mathrm{d}x = \int_{\Sigma} \mathcal{R}_{i+1} W_0 \big(\nabla v(x) \big) \, \mathrm{d}x.$$

Hence

$$I(v) \leqslant \int_{\Sigma} \mathcal{R}_{i+1} W_0 \big(\nabla v(x) \big) \, \mathrm{d} x.$$

and the proof is complete. \Box

References

- O. Anza Hafsa, J.-P. Mandallena, Interchange of infimum and integral, Calc. Var. Partial Differential Equations 18 (2003) 433–449.
- [2] O. Anza Hafsa, J.-P. Mandallena, Relaxation of variational problems in two-dimensional nonlinear elasticity, Ann. Mat. Pura Appl. 186 (2007) 187–198.
- [3] O. Anza Hafsa, J.-P. Mandallena, The nonlinear membrane energy: variational derivation under the constraint "det $\nabla u \neq 0$ ", J. Math. Pures Appl. 86 (2006) 100–115.
- [4] G. Anzellotti, S. Baldo, D. Percivale, Dimension reduction in variational problems, asymptotic development in Γ -convergence and thin elastic structures in elasticity, Asymptotic Anal. 9 (1994) 61–100.
- [5] J.-P. Aubin, H. Frankowska, Set-Valued Analysis, Birkäuser, Boston, 1990.
- [6] H. Ben Belgacem, Modélisation de structures minces en élasticité non linéaire, Thèse de Doctorat, Université Pierre et Marie Curie, 1996.
- [7] H. Ben Belgacem, Une méthode de Γ-convergence pour un modèle de membrane non linéaire, C. R. Acad. Sci. Paris, Sér. I 323 (1996) 845–849.
- [8] H. Ben Belgacem, Relaxation of singular functionals defined on Sobolev spaces, ESAIM: COCV 5 (2000) 71-85.
- [9] G. Dal Maso, An Introduction to Γ -Convergence, Birkäuser, Boston, 1993.
- [10] I. Ekeland, R. Temam, Analyse Convexe et Problèmes Variationnels, Dunod, Gauthier-Villars, Paris, 1974.
- [11] M.L. Gromov, J.A.M. Eliashberg, Construction of nonsingular isoperimetric films, Trudy Mat. Inst. Steklov 116 (1971) 18–33. Translated in Proc. Steklov Inst. Math. 116 (1971) 13–28.
- [12] M.L. Gromov, Partial Differential Relations, Springer-Verlag, Berlin, 1986.
- [13] R. Kohn, G. Strang, Optimal design and relaxation of variational problems, II, Comm. Pure Appl. Math. 39 (1986) 139–182.
- [14] H. Le Dret, A. Raoult, The nonlinear membrane model as variational limit of nonlinear three-dimensional elasticity, J. Math. Pures Appl. 74 (1995) 549–578.
- [15] D. Percivale, The variational method for tensile structures, preprint n^o 16, Dipartimento di Matematica Politecnico di Torino, 1991.
- [16] K. Trabelsi, Sur la modélisation des plaques minces en élasticité non linéaire, Thèse de Doctorat, Université Pierre et Marie Curie, 2004.
- [17] K. Trabelsi, Modeling of a membrane plate model for incompressible materials via Gamma-convergence, Anal. Appl. (Singapore) 4, 31–60 (2006), in press.