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# ANISOTROPIC ADAPTIVE KERNEL DECONVOLUTION 

F. COMTE $^{(*)}$ AND C. LACOUR $^{(* *)}$


#### Abstract

In this paper, we consider a multidimensional convolution model for which we provide adaptive anisotropic kernel estimators of a signal density $f$ measured with additive error. For this, we generalize Fan's (1991) estimators to multidimensional setting and use a bandwidth selection device in the spirit of Goldenschluger and Lepski's (2011) proposal fr density estimation without noise. We consider first the pointwise setting and then, we study the integrated risk. Our estimators depend on an automatically selected random bandwidth. We assume both ordinary and super smooth components for measurement errors, which have known density. We also consider both anisotropic Hölder and Sobolev classes for $f$. We provide non asymptotic risk bounds and asymptotic rates for the resulting data driven estimator, which is proved to be adaptive. We provide an illustrative simulation study, involving the use of Fast Fourier Transform algorithms. We conclude by a proposal of extension of the method to the case of unknown noise density, when a preliminary pure noise sample is available.


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## 1. Introduction

There have been a lot of studies dedicated to the problem of recovering the distribution $f$ of a signal when it is measured with an additive noise with known density. Several strategies have been proposed since Fan (1991) in order to provide adaptive strategies for kernel (Delaigle and Gijbels (2004)) or projection (Pensky and Vidakovic (1999), Comte et al. (2006)) estimators. The question of the optimality of the rates revealed real difficulties, after the somehow classical cases studied by Fan (1991): the case of super smooth noise (i.e. with exponential decay of its characteristic function) in presence of possibly also super smooth density implies non standard bias variance compromises that requires new methods for proving lower bounds. These problems have been studied by Butucea (2004), Butucea and Tsybakov $(2007,2008)$ and by Butucea and Comte (2009).

Then new directions lead researchers to release the assumption that the characteristic function of the noise never vanishes, see Hall and Meister (2007); Meister (2008). Others released the assumption that the density of the noise is known. In physical contexts, where it is possible to obtain samples of noise alone, a solution has been proposed by Neumann (1997), extended to the adaptive setting by Comte and Lacour (2011), another idea is developed in Johannes (2009). Other authors assumed repeated measurements of the same signal, and proposed estimation strategy without noise sample, see Delaigle et al. (2008).

All these works are in one dimensional setting. Our aim here is to study the multidimensional setting, and to propose adaptive strategies that would take into account possible anisotropy for both the function to estimate and the noise structure. As already explained in Kerkyacharian et al. (2001), adaptive procedures are delicate in a multidimensional setting because of the lack
of natural ordering. For instance, the model selection method is difficult to apply here since it requires to bound terms on sums of anisotropic models. In this paper, we use a unified setting where all estimators can be seen as kernel estimators, and we use the so-called "Lepski methods" recently developed in Goldenschluger and Lepski (2010, 2011) to face anisotropy problems. The originality of our work is to use Talagrand inequality as the key of the deviation in the mean squared error case. This idea is also exploited in a different context by Doumic et al. (2011). And indeed, we succeed in building adaptive kernel estimators in many contexts. The bandwidth is automatically selected. We provide risk bounds for these estimators, for both pointwise risk when local bandwidth selection in proposed and for the integrated mean square risk (MISE) when the global selection is studied. We also consider both anisotropic Hölder and Sobolev classes for $f$, the Fourier-domain-definition of the last ones allowing to also deal with the case of super smooth functions to recover. Few papers study the multidimensional deconvolution problem; we can only mention Youndjé and Wells (2008) who consider a cross-validation method for bandwidth selection in an isotropic and ordinary smooth setting. Our paper considerably generalizes their results with a different method, and provides new results and new rates in both pointwise and global setting.

We want here to emphasize that our setting is indeed very general. We consider all possible cases: the noise can have both ordinary smooth (O.S.) components (i.e. a characteristic function with polynomial rate of decay in the corresponding directions) and super smooth (S.S.) components (exponential rate of decay), and the signal density also. In particular, we obtain surprising results in the mixed cases: if one component only of the noise is S.S. (all the others being O.S.), in presence of an O.S. signal, then the rate of convergence of the estimator is logarithmic. On the contrary, if the signal has $k$ out of $d$ components S.S. in presence of an O.S. noise, then the rate of the estimator is almost as good as if the dimension of the problem was $d-k$ instead of $d$. We obtain also natural extensions of the univariate rates, and in particular the important fact that the rates can be logarithmic if the noise is S.S. (for instance in the Gaussian case) but are much improved if the signal is also S.S.: for instance, if the signal is also Gaussian, then polynomial rates are recovered.

In spite of the difficulty of the problem, in particular because of the large number of parameters required to formalize the regularity indexes of the functions, we exhibit very synthetic penalties than can be used in all cases. We also provide more precise but more technical results. It is certainly worth mentioning that the adaptive strategy we propose in the pointwise setting is not only a generalization of the one-dimensional results obtained in Butucea and Comte (2009), but is also a different procedure.

The plan of the paper is the following. In Section 2, we describe the model and the assumptions: the functional classes and the kernels used in the following. We both give the conditions required in the following for the kernels and provide concrete examples of kernels fulfilling them. We define the general estimator by generalization of the one-dimensional kernel to multidimensional setting. In Section 3, we study the pointwise risk and we discuss the rates. Then we propose a pointwise bandwidth selection strategy and prove risk bounds for the estimator in the case of Hölder classes and for Sobolev classes. As in the univariate case, adaptation costs a logarithmic loss in the rates. In Section 4, we provide global MISE bounds and describe an adaptive estimator, which is studied both on Nilkols'kii (see Nikol'skiĭ (1975) and Kerkyacharian et al. (2001)) classes and for Sobolev densities. Here, it is possible that adaptation has no price and that the rate corresponds exactly to the optimal one found without adaptation. We provide in Section 5 illustrations and examples in dimension 2 , for models having possibly very different behavior in the two directions. We give results of a small Monte-Carlo study, obtained by clever use of IFFT to speed the programs. Up to our knowledge, these effective experiments are the first ones in such a general setting. In a
concluding Section 6, we pave the way for a generalization of the method to the case where the known noise density is replaced by an estimation based on a preliminary sample. To finish, all proofs are gathered in Section 7.

## 2. Model, estimator and ASSumptions.

2.1. Model and notation. We consider the following $d$-dimensional convolution model

$$
Y_{i}=\left(\begin{array}{l}
Y_{i, 1}  \tag{1}\\
\vdots \\
Y_{i, d}
\end{array}\right)=X_{i}+\varepsilon_{i}=\left(\begin{array}{l}
X_{i, 1} \\
\vdots \\
X_{i, d}
\end{array}\right)+\left(\begin{array}{l}
\varepsilon_{i, 1} \\
\vdots \\
\varepsilon_{i, d}
\end{array}\right), i=1, \ldots, n
$$

We assume that the $\varepsilon_{i}$ and the $X_{i}$ are i.i.d. and the two sequences are independent. Only the $Y_{i}$ 's are observed and our aim is to estimate the density $f$ of $X_{1}$ when the density $f_{\varepsilon}$ of $\varepsilon$ is known.

As far as possible, we shall denote by $x$ variables in the time domain and by $t$ or $u$ variables in the frequency domain. We denote by $g^{*}$ the Fourier transform of an integrable function $g$, $g^{*}(t)=\int e^{i\langle t, x\rangle} g(x) d x$ where $\langle t, x\rangle=\sum_{j=1}^{d} t_{j} x_{j}$ is the standard scalar product in $\mathbb{R}^{d}$. Moreover the convolution product of two functions $g_{1}$ and $g_{2}$ is denoted by $g_{1} \star g_{2}(x)=\int g_{1}(x-u) g_{2}(u) d u$. We recall that $\left(g_{1} \star g_{2}\right)^{*}=g_{1}^{*} g_{2}^{*}$. As usual, we define

$$
\left.\|g\|_{1}=\int|g(x)| d x \quad \text { and } \quad\|g\|=\|g\|_{2}=\left(\int|g(x)|^{2} d x\right)\right)^{1 / 2}
$$

The notation $x_{+}$means $\max (x, 0)$, and $a \leq b$ for $a, b \in \mathbb{R}^{d}$ means $a_{1} \leq b_{1}, \ldots, a_{d} \leq b_{d}$. For two functions $u, v$, we denote $u(x) \lesssim v(x)$ if there exists a positive constant $C$ not depending on $x$ such that $u(x) \leq C v(x)$ and $u(x) \approx v(x)$ if $u(x) \lesssim v(x)$ and $v(x) \lesssim u(x)$.
2.2. The estimator. Let us now define our collection of estimator. Let $K$ be a kernel in $\mathbb{L}^{2}\left(\mathbb{R}^{d}\right)$ such that $K^{*}$ exists. Then we define, for $h \in\left(\mathbb{R}_{+}^{*}\right)^{d}$,

$$
K_{h}(x)=\frac{1}{h_{1} \ldots h_{d}} K\left(\frac{x_{1}}{h_{1}}, \ldots, \frac{x_{d}}{h_{d}}\right) \text { and } L_{(h)}^{*}(t)=\frac{K_{h}^{*}(t)}{f_{\varepsilon}^{*}(t)}
$$

The kernel $K$ is such that Fourier inversion can be applied:

$$
L_{(h)}(x)=(2 \pi)^{-d} \int e^{-i\langle t, x\rangle} K_{h}^{*}(t) / f_{\varepsilon}^{*}(t) d t
$$

Considering that $f^{*}=f_{Y}^{*} / f_{\varepsilon}^{*}$, a natural estimator of $f$ is such that

$$
\hat{f}_{h}^{*}(t)=\widehat{f_{Y}^{*}}(t) L_{(h)}^{*}(t)=K_{h}^{*}(t) \frac{\widehat{f_{Y}^{*}}(t)}{f_{\varepsilon}^{*}(t)}, \quad \text { where } \quad \widehat{f_{Y}^{*}}(t)=\frac{1}{n} \sum_{k=1}^{n} e^{i\left\langle t, Y_{k}\right\rangle}
$$

and thus

$$
\hat{f}_{h}(x)=\frac{1}{n} \sum_{k=1}^{n} L_{(h)}\left(x-Y_{k}\right)
$$

Note that our estimator here is the same, in multivariate context, as the one proposed in one-dimensional setting by Fan (1991). It verifies

$$
\mathbb{E}\left(\hat{f}_{h}^{*}(t)\right)=K_{h}^{*}(t) \frac{f_{Y}^{*}(t)}{f_{\varepsilon}^{*}(t)}=K_{h}^{*}(t) f^{*}(t) \quad \text { so that } \quad \mathbb{E}\left(\hat{f}_{h}\right)=K_{h} \star f=: f_{h}
$$

To construct an adaptive estimator, we also introduce auxiliary estimators involving two kernels. This idea, already used in Devroye (1989), allows us in the following to automatically select
the bandwidth $h$ (see section 3.3), following a method described in Goldenschluger and Lepski (2011). We consider

$$
\hat{f}_{h, h^{\prime}}(x)=K_{h^{\prime}} \star \hat{f}_{h}(x)
$$

which implies that

$$
\hat{f}_{h, h^{\prime}}^{*}(t)=K_{h^{\prime}}^{*}(t) K_{h}^{*}(t) \frac{\widehat{f_{Y}^{*}}(t)}{f_{\varepsilon}^{*}(t)}
$$

Note that, for all $x \in \mathbb{R}^{d}$, we have $\hat{f}_{h, h^{\prime}}(x)=\hat{f}_{h^{\prime}, h}(x)$. The estimator which is finally studied is $\hat{f}_{\hat{h}}$ where $\hat{h}$ is defined by using the collection $\left(\hat{f}_{h, h^{\prime}}\right)$.
2.3. Noise assumptions. We assume that the characteristic function of the noise has a polynomial or exponential decrease:
$\left(\mathbf{H}_{\varepsilon}\right)$

$$
\begin{aligned}
& \exists \alpha \in\left(\mathbb{R}_{+}\right)^{d}, \rho \in\left(\mathbb{R}_{+}\right)^{d}, \beta \in \mathbb{R}^{d}\left(\beta_{j}>0 \text { if } \rho_{j}=0\right) \text { s. t. } \forall t \in \mathbb{R}^{d} \\
& \left|f_{\varepsilon}^{*}(t)\right| \approx \prod_{j=1}^{d}\left(t_{j}^{2}+1\right)^{-\beta_{j} / 2} \exp \left(-\alpha_{j}\left|t_{j}\right|^{\rho_{j}}\right)
\end{aligned}
$$

Note that this assumption implies $f_{\varepsilon}^{*}(t) \neq 0$. A component $j$ of the noise is said to be ordinary smooth (OS) if $\alpha_{j}=0$ or $\rho_{j}=0$ and super smooth otherwise. We take the convention that $\alpha_{j}=0$ if $\rho_{j}=0$ and $\rho_{j}=0$ if $\alpha_{j}=0$.

Let us recall that exponential or gamma type densities are ordinary smooth, and that Cauchy or Gaussian densities are super smooth. The Gaussian case is considered in many problems and enhances the interest of super smooth contexts, but exponential-type densities keep a great interest in physical contexts, see for instance the fluorescence model studied in Comte and Rebafka (2010) where the measurement error density is fitted as an exponential type distribution, belonging to the ordinary smooth class.

To be more precise, we introduce the following notation. We denote by $O S$ the set of directions $j$ with ordinary smooth regularity $\left(\alpha_{j}=\rho_{j}=0\right)$, and by $S S$ the set of directions $j$ with super smooth regularity $\left(\rho_{j}>0\right)$ so that under $\left(\mathbf{H}_{\varepsilon}\right)$,

$$
\left|f_{\varepsilon}^{*}(t)\right| \approx \prod_{j \in O S}\left(t_{j}^{2}+1\right)^{-\beta_{j} / 2} \prod_{k \in S S}\left(t_{k}^{2}+1\right)^{-\beta_{k} / 2} \exp \left(-\alpha_{k}\left|t_{k}\right|^{\rho_{k}}\right)
$$

2.4. Regularity assumptions. We consider in the sequel several types of regularity for the target function $f$, associated with slightly different definition of the estimator: the choice of the kernel depends on the type of regularity space. We used Greek letters for the noise regularity, and now, we use Latin letters for the function $f$ indexes.

First, for pointwise estimation purpose, we consider functions $f$ belonging to Hölder classes denoted by $\mathcal{H}(b, L), b=\left(b_{1}, \ldots, b_{d}\right)$ such that:
the function $f$ admits derivatives with respect to $x_{j}$ up to order $\left\lfloor b_{j}\right\rfloor$ (where $\left\lfloor b_{j}\right\rfloor$ denotes the largest integer less than $b_{j}$ ) and

$$
\left|\frac{\partial^{\left\lfloor b_{j}\right\rfloor} f}{\left(\partial x_{j}\right)^{\left\lfloor b_{j}\right\rfloor}}\left(x_{1}, \ldots, x_{j-1}, x_{j}^{\prime}, x_{j+1}, \ldots, x_{d}\right)-\frac{\partial^{\left\lfloor b_{j}\right\rfloor} f}{\left(\partial x_{j}\right)^{\left\lfloor b_{j}\right\rfloor}}(x)\right| \leq L\left|x_{j}^{\prime}-x_{j}\right|^{b_{j}-\left\lfloor b_{j}\right\rfloor} .
$$

Next for global estimation purpose, the functional spaces associated with standard kernel estimators are the anisotropic Nikol'skii class of functions, as in Goldenschluger and Lepski (2010), see also Nikol'skǐ̆ (1975), Kerkyacharian et al. (2001). We consider the class $\mathcal{N}(b, L)$ which is the set of functions $f: \mathbb{R}^{d} \rightarrow \mathbb{R}$ such that $f$ admits derivatives with respect to $x_{j}$ up to order $\left\lfloor b_{j}\right\rfloor$, and
(i) $\left\|\frac{\partial^{\left\lfloor b_{j}\right\rfloor} f}{\left(\partial x_{j}\right)^{\left.b_{j}\right\rfloor}}\right\| \leq L$, for all $j=1, \ldots, d$, where $\|\cdot\|$ denotes the $\mathbb{L}^{2}\left(\mathbb{R}^{d}\right)$-norm.
(ii) For all $j=1, \ldots, d$, for all $t \in \mathbb{R}$,

Lastly, and for both pointwise and global estimation, we shall consider general anisotropic Sobolev spaces $\mathcal{S}(b, a, r, L)$ defined as the class of integrable functions $f: \mathbb{R}^{d} \rightarrow \mathbb{R}$ satisfying

$$
\int\left|f^{*}\left(t_{1}, \ldots, t_{d}\right)\right|^{2} \prod_{j=1}^{d}\left(1+t_{j}^{2}\right)^{b_{j}} \exp \left(2 a_{j}\left|t_{j}\right|^{r_{j}}\right) d t_{1} \ldots d t_{d} \leq L^{2}
$$

We set $a_{j}=0$ if $r_{j}=0$, and reciprocally. If some $a_{j}$ are nonzero, the corresponding direction are associated with so-called "super smooth" regularities. To standardize notations, we set $a_{j}=r_{j}=0$ when Hölder or Nikol'skii regularity is considered.

We can note that Sobolev spaces allow one to take into account a global regularity rather than a pointwise one. Nevertheless, they have a convenient Fourier-domain representation, in particular when one wants to consider super smooth or analytical functions, even in pointwise setting. If the noise density can have such property in the case of Gaussian measurement error, it is natural to think that the signal density may have the same behavior.
2.5. Assumptions on the kernel. For the estimators to be correctly defined, the kernel must be chosen sufficiently regular to balance the noise.

We assume that $K(x)=K\left(x_{1}, \ldots, x_{d}\right)=\prod_{j=1}^{d} K_{j}\left(x_{j}\right)$. This assumption is not necessary, but simplifies the proofs. Besides, the kernels used in practice verify this condition. Moreover, we recall that $K$ belongs to $\mathbb{L}^{2}\left(\mathbb{R}^{d}\right)$ and admits a Fourier transform.

To ensure the finiteness of the estimators, we shall use the following assumption:
$\operatorname{Kvar}(\boldsymbol{\beta})$ For $j \in O S: \int\left|K_{j}^{*}(u)\right|^{2}\left(1+u^{2}\right)^{\beta_{j}} d u<\infty$ and $\int\left|K_{j}^{*}(u)\right|\left(1+u^{2}\right)^{\beta_{j} / 2} d u<\infty$ For $j \in S S: K_{j}^{*}(t)=0$ if $|t|>1$ and $\sup _{|t| \leq 1}\left|K_{j}^{*}(t)\right|<\infty$

Moreover, we may require a classical assumption to control the bias Hölder or Nikol'skii spaces described above.
$\operatorname{Korder}(\ell)$ The kernel $K$ is of order $\ell=\left(\ell_{1}, \ldots, \ell_{d}\right) \in \mathbb{R}_{+}^{d}$, i.e.

* $\int K(x) d x=1$
$* \forall 1 \leq j \leq d, \forall 1 \leq k \leq \ell_{j}, \int x_{j}^{k} K(x) d x=0$
$* \forall 1 \leq j \leq d, \int\left(1+\left|x_{j}\right|\right)^{\ell_{j}}|K(x)| d x<\infty$
Note that this implies the condition used in Fan (1991) which is stated in the Fourier domain.
This condition is verified by the following kernels defined in Goldenschluger and Lepski (2010).
We start by defining univariate functions $u_{j}(x)$ such that $\int u_{j}(x) d x=1, \int|x|^{\ell_{j}}\left|u_{j}(x)\right| d x<+\infty$ and then

$$
\begin{equation*}
K_{j}\left(x_{j}\right)=\sum_{k=1}^{\ell_{j}}\binom{\ell_{j}}{k}(-1)^{k+1} \frac{1}{k} u_{j}\left(\frac{x_{j}}{k}\right) . \tag{2}
\end{equation*}
$$

Then $K_{j}$ is a univariate kernel of order $\ell_{j}$. The multivariate kernel is defined by

$$
\begin{equation*}
K(x)=K\left(x_{1}, \ldots, x_{d}\right)=\prod_{j=1}^{d} K_{j}\left(x_{j}\right) \tag{3}
\end{equation*}
$$

The resulting kernel is such that $\int \prod_{j=1}^{d} x_{j}^{k_{j}} K(x) d x_{1} \ldots d x_{d}=0$ if $1 \leq k_{j} \leq \ell_{j}$ for one $j \in$ $\{1, \ldots, d\}$, and thus satisfies $\operatorname{Korder}(\ell)$.

We can give an example of kernel satisfying Assumptions $\operatorname{Kvar}(\boldsymbol{\beta})$ and $\operatorname{Korder}(\ell)$. We can use the construction above with $u_{j}\left(x_{j}\right)=v_{\ell_{j}+2}\left(x_{j}\right)$ where

$$
v_{p}(x)=c_{p}\left(\frac{\sin (x / p)}{x / p}\right)^{p}, v_{p}(0)=c_{p}, \quad v_{p}^{*}(t)=\frac{2 \pi p c_{p}}{2^{p}} \underbrace{\mathbb{1}_{[-1,1]} \star \cdots \star \mathbb{1}_{[-1,1]}}_{p \text { times }}(p t)
$$

where $c_{p}$ is such that $\int v_{p}(x) d x=1$. This is what can be done when the function under estimation is assumed to be in a Hölder or in a Nikol'skii space.

When considering Sobolev space and Assumption $\operatorname{Kvar} \boldsymbol{\operatorname { s i n }} \boldsymbol{\beta}$ is required, we can simply use the sinus cardinal kernel denoted by $K=\operatorname{sinc}$ and defined by

$$
K_{j}^{*}(t)=\mathbb{1}_{[-1,1]}(t)=v_{1}^{*}(t), \quad K_{j}\left(x_{j}\right)=\frac{\sin \left(x_{j}\right)}{\pi x_{j}}, K_{j}(0)=\frac{1}{\pi}
$$

Remark. When only ordinary smooth noises are considered on Hölder or Nikol'skii spaces, we may also use other type of kernels. For instance, use the construction of kernel of order $\ell$ based on

$$
u_{j}\left(x_{j}\right)=c_{j}\left(x_{j}-\frac{1}{2}\right)^{\left\lfloor\beta_{j}\right\rfloor+1}\left(x_{j}+\frac{1}{2}\right)^{\left\lfloor\beta_{j}\right\rfloor+1} \mathbb{1}_{\left[-\frac{1}{2}, \frac{1}{2}\right]}\left(x_{j}\right)
$$

Indeed, it can be proved that $K_{j}^{*}\left(t_{j}\right)=O\left(\left|t_{j}\right|^{-\left(\left\lfloor\beta_{j}\right\rfloor+2\right)}\right)$ when $\left|t_{j}\right| \rightarrow+\infty$.

## 3. Pointwise estimation

3.1. Bias and variance. Let $x_{0}$ be a point in $\mathbb{R}^{d}$. The aim is to study the estimator $\hat{f}_{h}$ of $f$, and more precisely its risk at point $x_{0}:\left|f\left(x_{0}\right)-\hat{f}_{h}\left(x_{0}\right)\right|$. It is well known that

$$
\mathbb{E}\left|f\left(x_{0}\right)-\hat{f}_{h}\left(x_{0}\right)\right|^{2}=\underbrace{\left|f\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right|^{2}}_{\text {bias }}+\underbrace{\mathbb{E}\left|f_{h}\left(x_{0}\right)-\hat{f}_{h}\left(x_{0}\right)\right|^{2}}_{\text {variance }}
$$

(recall that $\left.f_{h}=\mathbb{E}\left(\hat{f}_{h}\right)=K_{h} \star f\right)$. We first control the bias. We define

$$
B_{0}(h)= \begin{cases}\left\|f-f_{h}\right\|_{\infty} & \text { if }\|K\|_{1}<\infty \\ \left\|f^{*}-f_{h}^{*}\right\|_{1} /(2 \pi)^{d} & \text { otherwise }\end{cases}
$$

The following proposition holds.
Proposition 1. The bias verifies $\left|f\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right| \leq B_{0}(h)$ and, under assumptions

- $f$ belongs to Hölder class $\mathcal{H}(b, L)$ and the kernel verifies $\operatorname{Korder}(\ell)$ with $\ell \geq\lfloor b\rfloor$, or
- $f^{*} \in L^{1}, f$ belongs to Sobolev class $\mathcal{S}(b+1 / 2, a, r, L)$ and $K=\operatorname{sinc}$

Then $B_{0}(h) \lesssim L \sum_{j=1}^{d} h_{j}^{b_{j}+r_{j} / 2} \exp \left(-a_{j} h_{j}^{-r_{j}}\right)$.
Note that we recover the classical order $h_{j}^{b_{j}}$ when $a_{j}=0$. Let us now study the variance of estimators $\hat{f}_{h}$.

Proposition 2. The variance verifies $\mathbb{E}\left|f_{h}\left(x_{0}\right)-\hat{f}_{h}\left(x_{0}\right)\right|^{2} \leq V_{0}(h)$ where

$$
\begin{equation*}
V_{0}(h)=\frac{1}{(2 \pi)^{2 d}} \frac{1}{n} \min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|_{2}^{2},\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|_{1}^{2}\right) \tag{4}
\end{equation*}
$$

Moreover, under $\left(\mathbf{H}_{\varepsilon}\right)$ and $\operatorname{Kvar}(\boldsymbol{\beta})$, if $h_{j} \leq 1$ for all $j$,

$$
V_{0}(h) \lesssim \frac{1}{n} \prod_{j=1}^{d} h_{j}^{\left(\rho_{j}-1\right)_{+}+\rho_{j}-1-2 \beta_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right)
$$

When $f_{\varepsilon}^{*}=1$ (no noise), we obtain the classical order $\prod_{j} 1 /\left(n h_{j}\right)$.
Eventually, the bound on the MSE is obtained by adding the squared bias bound and the variance bound.

### 3.2. Rates of convergence.

3.2.1. Homogeneous cases. We first give the bandwidth choices and rates of convergence which are obtained when all components of both $f$ and $f_{\varepsilon}$ have the same smoothness. Recall that in dimension 1, the minimax rates are logarithmic when the noise is super smooth, unless the function $f$ is super smooth too : see Fan (1991), Pensky and Vidakovic (1999), Comte et al. (2006).

First, consider that both the function $f$ and the noise are ordinary smooth. We can compute the anisotropic rate that can be deduced from a "good" choice of $h=\left(h_{1}, \ldots, h_{d}\right)$. Indeed, let us look at

$$
\begin{aligned}
& \frac{\partial}{\partial h_{j}}\left(h_{1}^{2 b_{1}}+\cdots+h_{d}^{2 b_{d}}+n^{-1} \prod_{i=1}^{d} h_{i}^{-\left(2 \beta_{i}+1\right)}\right) \\
= & 2 b_{j} h_{j}^{2 b_{j}-1}-\left(2 \beta_{j}+1\right) n^{-1} h_{j}^{-\left(2 \beta_{j}+2\right)} \prod_{i=1, i \neq j}^{d} h_{i}^{-\left(2 \beta_{i}+1\right)} .
\end{aligned}
$$

Setting this to 0 for all $j$ yields

$$
\begin{equation*}
\prod_{i=1, i \neq j}^{d} h_{i, o p t}^{2 \beta_{i}+1} h_{j, o p t}^{2 b_{j}+2 \beta_{j}+1} \propto n^{-1}, j=1, \ldots, d \tag{5}
\end{equation*}
$$

and thus $h_{j, o p t}^{2 b_{j}}=h_{k, o p t}^{2 b_{k}}$. Therefore the optimal bandwidth choices are

$$
h_{j, o p t} \propto\left(n^{-1 /\left(2 b_{j}+b_{j} \sum_{i=1}^{d}\left[\left(2 \beta_{i}+1\right) / b_{i}\right]\right.}\right)
$$

and the resulting rate is

$$
\begin{equation*}
n^{-1 /\left(1+\frac{1}{2} \sum_{i=1}^{d} \frac{2 \beta_{i}+1}{b_{i}}\right)} \tag{6}
\end{equation*}
$$

Secondly, consider the case where the noise is super smooth (all $\left(\beta_{j}, \rho_{j}\right)$ nonzero) but the function is ordinary smooth. Then $h_{j, o p t}=\left(\left(2 \alpha_{j}+1\right) / \log (n)\right)^{1 / \rho_{j}}$ and the rate is

$$
\begin{equation*}
[\log (n)]^{-2 \min _{1 \leq j \leq d}\left(b_{j} / \rho_{j}\right)} \tag{7}
\end{equation*}
$$

We can remark two things in this case: the rates are logarithmic, and the bandwidth choice is known because it only depends on the parameters of the noise density, which is assumed to be known. This explains why no bandwidth selection procedure is required here, as long as only classical Hölder regularities are considered.

Now consider the case where the noise is ordinary smooth (all $\rho_{j}$ 's are zeros) but the function is super smooth (with all $\left(a_{j}, r_{j}\right)$ nonzero). Then we take $h_{j, o p t}=\left(a_{j} / \log (n)\right)^{1 / r_{j}}$ and the rate is

$$
\begin{equation*}
[\log (n)]^{\sum_{j=1}^{d}\left(2 \beta_{j}+1\right) / r_{j}} / n \tag{8}
\end{equation*}
$$

We can see that here, the rates are very good. It is worth mentioning that the first paper considering super smooth function $f$ is Pensky and Vidakovic (1999).

We do not give a general bandwidth choice in the case where both functions can be super smooth, because it is very intricate. General formula in dimension 1 are given in Lacour (2006), see also Butucea and Tsybakov (2007, 2008). We can just emphasize that in such case the rates can be considerably improved, compared to the logarithmic issue above. For instance, it is easy to see that the compromise between a bias of order $\exp \left(-1 / h^{2}\right)$ and a variance of order $\exp \left(1 / h^{2}\right) / n$ is obtained for $h=\sqrt{2 / \log (n)}$ and gives a rate of order $1 / \sqrt{n}$. To be even more precise, the optimal rate in dimension 1 , if the signal is $\mathcal{N}\left(0, \sigma^{2}\right)$ and the noise $\mathcal{N}\left(0, \sigma_{\varepsilon}^{2}\right)$, is $n^{-1 /\left(1+\theta^{2}\right)}[\log (n)]^{-\left(1+1 /\left(1+\theta^{2}\right)\right) / 2}, \theta^{2}=\sigma_{\varepsilon}^{2} / \sigma^{2}$, for $1 / h_{o p t}=\sqrt{[\log (n)+(1 / 2) \log (\log (n))] /\left(\sigma^{2}+\sigma_{\varepsilon}^{2}\right)}$. As the bandwidth choice is very difficult to describe in the general case, this enhances the interest of automatic adaptation which is proposed below, when Sobolev spaces are considered. Note that optimal choices of the bandwidth are of logarithmic orders in all those cases.
3.2.2. Discussion about mixed cases. Let us consider now the case where the function is still ordinary smooth, but components 1 to $j_{0}$ of the noise are ordinary smooth while components $j_{0}+1$ to $d$ are super smooth, $1 \leq j_{0}<d$. Then it is clear that exponential components must first be "killed" by choosing logarithmic bandwidths and as the bandwidths are involved additively in the bias term, the rate becomes logarithmic. More precisely, taking for $j=1, \ldots, j_{0}$, $h_{j, o p t} \propto n^{-1 /\left(2 d\left(2 \beta_{j}+1\right)\right)}$ and for $j=j_{0}+1, \ldots, d, h_{j, o p t}=\left[\log (n) /\left(4 d \alpha_{j}\right)\right]^{-1 / \rho_{j}}$ gives a variance term of order

$$
\begin{aligned}
& n^{-1} \prod_{j=1}^{j_{0}} h_{j, o p t}^{-2 \beta_{j}-1} \prod_{j=j_{0}+1}^{d} h_{j, o p t}^{\left(\rho_{j}-1\right)_{+}+\left(\rho_{j}-1\right)-2 \beta_{j}} \exp \left(2 \alpha_{j} h_{j, o p t}^{-\rho_{j}}\right) \\
\propto & n^{-1+j_{0} /(2 d)+\left(d-j_{0}\right) /(2 d)} \log ^{\omega}(n)=n^{-1 / 2} \log ^{\omega}(n)
\end{aligned}
$$

where $\omega=\sum_{j=j_{0}+1}^{d}\left(2 \beta_{j}+1-\rho_{j}-\left(\rho_{j}-1\right)_{+}\right) / \rho_{j}$. Therefore, the variance is negligible and the rate is determined by the bias terms and is proportional to

$$
\begin{equation*}
[\log (n)]^{-\min _{j_{0}+1 \leq j \leq d}\left(b_{j} / \rho_{j}\right)} \tag{9}
\end{equation*}
$$

The conclusion is that the presence of one super smooth component of the noise implies a logarithmic rate, when the function to estimate is ordinary smooth (and bandwidth selection is not required).

The other case we can handle is when the noise has all its components ordinary smooth, but the function has its $j_{0}$ first components ordinary smooth and the $d-j_{0}$ last ones super smooth. Let us take $d=2$ and $j_{0}=1$ for simplicity. Clearly, we can choose $h_{2, o p t}=\left(\log (n) / a_{2}\right)^{-1 / r_{2}}$, so that the MSE for $\left(h_{1, o p t}, h_{2, o p t}\right)$ is proportional to

$$
\begin{aligned}
& h_{1, o p t}^{2 b_{1}}+h_{2, o p t}^{2 b_{2}+r_{2}} \exp \left(-2 a_{2} h_{2, o p t}^{-r_{2}}\right)+n^{-1} h_{1, o p t}^{-2 \beta_{1}-1} h_{2, o p t}^{-2 \beta_{2}-1} \\
\propto \quad & h_{1, o p t}^{2 b_{1}}+n^{-2}[\log (n)]^{-\left(2 b_{2}+r_{2}\right) / r_{2}}+n^{-1} h_{1, o p t}^{-2 \beta_{1}-1}[\log (n)]^{\left(2 \beta_{2}+1\right) / r_{2}} .
\end{aligned}
$$

Therefore, the optimal choice of $h_{1}$ is obtained as in dimension 1 with respect to a sample size $n /[\log (n)]^{\left(2 \beta_{2}+1\right) / r_{2}}$ and we find $h_{1, o p t} \propto\left(n /[\log (n)]^{\left(2 \beta_{2}+1\right) / r_{2}}\right)^{-1 /\left(2 \beta_{1}+2 b_{1}+1\right)}$. The final rate is
proportional to $\left(n /[\log (n)]^{\left(2 \beta_{2}+1\right) / r_{2}}\right)^{-2 b_{1} /\left(2 \beta_{1}+2 b_{1}+1\right)}$. This is the rate corresponding to the onedimensional problem, up to a logarithmic factor.
More generally, we obtain in dimension $d$, the rate corresponding to dimension $j_{0}$ of the OS-OS problem, up to logarithmic factors.

### 3.3. Adaptive estimator.

3.3.1. General result. Now, our aim is to automatically select a bandwidth in a discrete set $\mathcal{H}_{0}$ (described below) such that the corresponding estimator reaches the minimax rate, without knowing the regularity of $f$. We have at our disposal estimators $\hat{f}_{h}\left(x_{0}\right)$ and $\hat{f}_{h, h^{\prime}}\left(x_{0}\right)=K_{h^{\prime}}$ 夫 $\hat{f}_{h}\left(x_{0}\right)$, for $x_{0}=\left(x_{0,1}, \ldots, x_{0, d}\right) \in \mathbb{R}^{d}$ such that $\hat{f}_{h, h^{\prime}}\left(x_{0}\right)=\hat{f}_{h^{\prime}, h}\left(x_{0}\right)$. We define

$$
\begin{equation*}
A_{0}\left(h, x_{0}\right)=\sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h^{\prime}}\left(x_{0}\right)-\hat{f}_{h, h^{\prime}}\left(x_{0}\right)\right|-\sqrt{\tilde{V}_{0}\left(h^{\prime}\right)}\right]_{+}, \tag{10}
\end{equation*}
$$

and

$$
\hat{h}\left(x_{0}\right)=\arg \min _{h \in \mathcal{H}_{0}}\left\{A_{0}\left(h, x_{0}\right)+\sqrt{\tilde{V}_{0}(h)}\right\}
$$

with

$$
\begin{equation*}
\tilde{V}_{0}(h)=c_{0} \log (n) V_{0}(h) \tag{11}
\end{equation*}
$$

and $c_{0}$ is a numerical constant to be specified later. The final estimator is $\tilde{f}\left(x_{0}\right)=\hat{f}_{\hat{h}\left(x_{0}\right)}\left(x_{0}\right)$. The term $\tilde{V}_{0}(h)$ corresponds to the variance of the estimate $\hat{f}_{h}\left(x_{0}\right)$ multiplied by $\log (n)$. Now, we can state the result concerning the adaptive estimator. Define

$$
N(K)= \begin{cases}\|K\|_{1} & \text { if }\|K\|_{1}<\infty \\ \left\|K^{*}\right\|_{\infty} & \text { otherwise }\end{cases}
$$

Theorem 1. Assume that $N(K)<\infty$ and let

$$
\begin{align*}
& \mathcal{H}_{0}=\left\{h^{(k)} \quad h_{j}^{(k)} \leq 1, \text { for } j=1, \ldots, d, V_{0}\left(h^{(k)}\right) \leq 1\right. \\
&\left.\left\|\frac{K_{h^{(k)}}^{*}}{f_{\varepsilon}^{*}}\right\|_{2}^{2}\left\|\frac{K_{h^{(k)}}^{*}}{f_{\varepsilon}^{*}}\right\|_{1}^{-2} \geq \frac{\log (n)}{n} \quad \text { for } k=1, \ldots,\left\lfloor n^{\epsilon}\right\rfloor\right\} \tag{12}
\end{align*}
$$

Let $q$ be a real larger than 1. Assume that $c_{0} \geq\left(4\left(1+\left\|K^{*}\right\|_{\infty}\right)(2 \epsilon+q)\right)^{2} / \min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}, 1\right)$. Then, with probability larger than $1-4 n^{-q}$,

$$
\begin{equation*}
\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq \inf _{h \in \mathcal{H}_{0}}\left\{(1+2 N(K)) B_{0}(h)+3 \sqrt{\tilde{V}_{0}(h)}\right\} \tag{13}
\end{equation*}
$$

We can make two comments about this result.
(1) Inequality (13) is a trajectorial oracle inequality, up to the $\log (n)$ factor in the term $\tilde{V}_{0}(h)$ which appears in place of $V_{0}(h)$.
(2) Condition (12) is typically verified if $\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2} \geq \log (n)$ and $\max \left(\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2},\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2}\right) \leq$ $n$. It is just slightly stronger than assuming the variance $V_{0}(h)$ bounded.
It is also important to see that we can deduce from Theorem 1 a mean oracle inequality. More precisely, we have $\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq\left(\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}+\left|f\left(x_{0}\right)\right|\right)$. Then, for $h \in \mathcal{H}_{0},\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2} \leq$ $(n / \log (n))\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}$ and $V_{0}(h) \leq 1$ imply $\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2} \leq n$. Thus $\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right|^{2} \lesssim n$. Therefore, Theorem 1 implies that, $\forall h \in \mathcal{H}_{0}$,

$$
\begin{equation*}
\mathbb{E}\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right|^{2} \leq\left\{(1+2 N(K)) B_{0}(h)+3 \sqrt{\tilde{V}_{0}(h)}\right\}^{2}+\frac{C}{n} \tag{14}
\end{equation*}
$$

We just have to choose $q \geq 2$ in Theorem 1 .
3.3.2. Study of Condition (12). Let us define $\bar{h}_{o p t}=\left(\bar{h}_{1, o p t}, \ldots, \bar{h}_{d, o p t}\right)$ the minimizer of the right hand side of equation (14):

$$
\bar{h}_{\text {opt }}=\arg \min _{h \in \mathbb{R}_{+}^{d}}\left\{B_{0}^{2}(h)+\tilde{V}_{0}(h)\right\} .
$$

Note that $\bar{h}_{\text {opt }}$ here corresponds to the value of $h_{\text {opt }}$ computed in Section 3.2 where $n$ is replaced by $n / \log (n)$. We need to check that $\bar{h}_{\text {opt }}$ belongs to $\mathcal{H}_{0}$ to ensure that the infimum in (13) is reached.

This is what is stated in the following Corollary.
Corollary 1. Assume that $\left(\mathbf{H}_{\varepsilon}\right)$ holds and either

1. $f$ belongs to Hölder class $\mathcal{H}(b, L)$, the noise has all its components $O S$ and the kernel verifies $\operatorname{Korder}(\ell)$ with $\ell \geq\lfloor b\rfloor, \operatorname{Kvar}(\boldsymbol{\beta})$, and is such that $K_{j}^{*}$ is lower bounded on $\left[-q_{j}, q_{j}\right]$ for $q_{j}>0$, and $j=1 \ldots, d$, or
2. $f^{*} \in L^{1}, f$ belongs to Sobolev class $\mathcal{S}(b+1 / 2, a, r, L)$ and $K=$ sinc.

Then $\bar{h}_{\text {opt }} \in \mathcal{H}_{0}$ and thus the infimum in Inequality (13) is reached.
In particular in case 1., we have

$$
\begin{equation*}
\mathbb{E}\left(\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right|^{2}\right)=O\left((n / \log (n))^{-1 /\left(1+\frac{1}{2} \sum_{i=1}^{d} \frac{2 \beta_{i}+1}{b_{i}}\right)}\right) \tag{15}
\end{equation*}
$$

We can notice that the proof of Corollary 1 relies on the intermediate result stating that Condition (12) is equivalent to the following one:

$$
\begin{equation*}
\prod_{j=1}^{d} h_{j}^{\left(\rho_{j}-1\right)} \lesssim n / \log (n) \tag{16}
\end{equation*}
$$

The consequence of Corollary 1 is that the right hand side of (13) always leads to the best compromise between the squared bias $B_{0}^{2}(h)$ and $\tilde{V}_{0}(h)$, that is the optimal rates of section 3.2 with respect to a sample size $n / \log (n)$.

Remark 1. As we already mentioned, we have an extra $\log (n)$ factor in Inequality (13). In case 1. above, we can concretely see the loss in the rate by comparing the right-hand-side of (15) to the optimal rate (6). This logarithmic loss, due to adaptation, is known to be nevertheless adaptive optimal for $d=1$, see Butucea and Tsybakov (2007, 2008) and Butucea and Comte (2009), and we can conjecture that it is also the case for larger dimension.

Remark 2. In the case of a super smooth noise on Hölder spaces, we already mentioned that no bandwidth selection is required. Indeed, we just have to take $h_{j}=\left(\log (n) / 2 \alpha_{j}\right)^{-1 / \rho_{j}}$ for the super smooth components and $h_{j}=n^{-1 /\left(2 d\left(2 \beta_{j}+1\right)\right)}$ for ordinary smooth components, and the rate has a logarithmic order determined by the bias term, see (9). This is the reason why general adaptation is studied only on Sobolev spaces. The rates can be then considerably improved compared to the rate (9).

## 4. Global estimation

Let us now study the procedure for global estimation. In this section we assume that $f$ belongs to $\mathbb{L}^{2}\left(\mathbb{R}^{d}\right)$.
4.1. Bias and variance. We study now the MISE $\mathbb{E}\left\|f-\hat{f}_{h}\right\|^{2}$, made up of a bias term plus a variance term. We can prove the following bound for the bias.

Proposition 3. Under assumptions

- $f$ belongs to Nikol'skii class $\mathcal{N}(b, L)$ and the kernel verifies $\operatorname{Korder}(\ell)$ with $\ell \geq\lfloor b\rfloor$, or
- $f$ belongs to Sobolev class $\mathcal{S}(b, a, r, L)$ and $K=\operatorname{sinc}$

Then $\left\|f-f_{h}\right\| \lesssim L \sum_{j=1}^{d} h_{j}^{b_{j}} \exp \left(-a_{j} h_{j}^{-r_{j}}\right)$
Let us now bound the variance of the estimator.
Proposition 4. We have $\mathbb{E}\left\|f_{h}-\hat{f}_{h}\right\|^{2} \leq V(h)$ where

$$
V(h)=\frac{1}{(2 \pi)^{d} n}\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|^{2}
$$

Moreover, under $\left(\mathbf{H}_{\varepsilon}\right)$ and $\operatorname{Kvar}(\boldsymbol{\beta})$

$$
V(h) \lesssim \frac{1}{n} \prod_{j=1}^{d} h_{j}^{-1-2 \beta_{j}+\rho_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right)
$$

We emphasize that the rates of convergence (6), (7) and (8) are formally preserved here, for the same optimal bandwidths choices, but with a definition of the parameters $b_{j}$ which is different (in case 2 . here, $f$ belongs to $\mathcal{S}(b, a, r, L)$ while in the pointwise setting it was chosen in $\mathcal{S}(b+1 / 2, a, r, L))$. Therefore, we refer to section 3.2 for all remarks concerning the quality of the rates and to the cases where part of the components of $f$ or $f_{\varepsilon}$ are ordinary smooth and others are super smooth.
4.2. The global adaptive estimator. Now, we describe the adaptive estimation. As previously, we define

$$
A(h)=\sup _{h^{\prime} \in \mathcal{H}}\left[\left\|\hat{f}_{h^{\prime}}-\hat{f}_{h, h^{\prime}}\right\|-\sqrt{\tilde{V}\left(h^{\prime}\right)}\right]_{+}
$$

and

$$
\hat{h}=\arg \min _{h \in \mathcal{H}}\{A(h)+\sqrt{\tilde{V}(h)}\}
$$

with $\tilde{V}(h)$ defined by

$$
\begin{equation*}
\tilde{V}(h)=\left(1+\left\|K^{*}\right\|_{\infty}\right)^{2}(1+2 \eta)^{2} V(h) C(h) \tag{17}
\end{equation*}
$$

where $\eta$ is a numerical constant and $C(h) \geq 1$ is a correcting term discussed below. Ideally, this term would be a constant but in super smooth cases, this may not be possible. The final estimator is $\check{f}=\hat{f}_{\hat{h}}$.

We give first an adaptive trajectorial result in term of a general constraint on $C(h)$.
Theorem 2. Assume that $\left\|K^{*}\right\|_{\infty}<\infty$ and let

$$
\begin{align*}
\mathcal{H}=\left\{h^{(k)}\right. & h_{j}^{(k)} \leq 1, \text { for } j=1, \ldots, d, V\left(h^{(k)}\right) \leq 1 \\
& \left.C(h) \max \left(1,\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2} /\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{\infty}^{2}\right) \geq(\log n)^{2} \quad \text { for } k=1, \ldots,\left\lfloor n^{\epsilon}\right\rfloor\right\} \tag{18}
\end{align*}
$$

Then, with probability larger than $1-n^{\epsilon} e^{-[\min (\eta, 1) \eta / 46](\log n)^{2}}$

$$
\begin{equation*}
\|\check{f}-f\| \leq \inf _{h \in \mathcal{H}}\left\{\left(1+2\left\|K^{*}\right\|_{\infty}\right)\left\|f-f_{h}\right\|+3 \sqrt{\tilde{V}(h)}\right\} \tag{19}
\end{equation*}
$$

Remark 3. Clearly, asymptotically when $n$ gets large, $\forall \epsilon>0, n^{\epsilon} e^{-[\min (\eta, 1) \eta / 46](\log n)^{2}}=O\left(1 / n^{-q}\right)$ for any integer $q$. But in practice, the cardinality $\left\lfloor n^{\epsilon}\right\rfloor$ of $\mathcal{H}$ should not be too large.

Note that, as in the pointwise setting, we can write

$$
\|f-\check{f}\| \leq\|f\|+\|\check{f}\| \leq\|f\|+\sqrt{n V(\hat{h})} \leq\|f\|+\sqrt{n}
$$

as $\hat{h}$ is chosen in $\mathcal{H}$. Therefore, Inequality (19) implies that

$$
\begin{equation*}
\mathbb{E}(\|\check{f}-f\|) \leq \inf _{h \in \mathcal{H}}\left\{\left(1+2\left\|K^{*}\right\|_{\infty}\right)\left\|f-f_{h}\right\|+3 \sqrt{\tilde{V}(h)}\right\}+\frac{C_{2}(\eta)}{\sqrt{n}} \tag{20}
\end{equation*}
$$

Now we can study condition (18) in our usual specific settings. Let us define $\breve{h}_{\text {opt }}$ as the optimal bandwidth choice:

$$
\check{h}_{\text {opt }}=\arg \min _{h \in \mathbb{R}_{+}^{d}}\left\{\left\|f-f_{h}\right\|+\tilde{V}(h)\right\} .
$$

As in the pointwise setting, the optimal compromise is automatically reached by the estimator if $\breve{h}_{\text {opt }}$ belongs to $\mathcal{H}$; but contrary to the pointwise setting, we may preserve a rate without loss if $C(h)$ can be taken equal to a constant. We can prove the following result.
Corollary 2. Assume that $\left(\mathbf{H}_{\varepsilon}\right)$ holds, that the noise has all its components OS and either 1. $f$ belongs to Nikol'skii class $\mathcal{N}(b, L)$, and $K$ verifies $\operatorname{Kvar}(\boldsymbol{\beta}), 0<\sup _{u_{j} \in \mathbb{R}}\left|K_{j}^{*}(u)\right| u^{2 \beta_{j}}<\infty$ for $j=1, \ldots, d$, $\operatorname{Korder}(\ell)$ with $\ell \geq\lfloor b\rfloor$,
or
2. $f^{*} \in L^{1}$, $f$ belongs to a Sobolev class $\mathcal{S}(b, 0,0, L)$ and $K=$ sinc.

Then, we can take $C(h)=1$ and have $\breve{h}_{\text {opt }} \in \mathcal{H}$ (where $\mathcal{H}$ as defined in Theorem 2). Thus, the infimum in Inequalities (19) and (20) are reached. That is, we have

$$
\begin{equation*}
\mathbb{E}\left(\|\check{f}-f\|^{2}\right)=O\left(n^{-1 /\left(1+\frac{1}{2} \sum_{i=1}^{d} \frac{2 \beta_{i}+1}{b_{i}}\right)}\right) \tag{21}
\end{equation*}
$$

Clearly in the case of ordinary smooth noise and function $f$, the estimator automatically reaches the optimal rate, without requiring the knowledge of the regularity of $f$, which is nevertheless involved in the resulting rate.

If we want to use constraint (18) in the general setting, we have to choose $C(h)=\log ^{2}(n)$ and then, a systematic loss occurs:
Corollary 3. Assume that $\left(\mathbf{H}_{\varepsilon}\right)$ holds, that $f^{*} \in L^{1}$, $f$ belongs to Sobolev class $\mathcal{S}(b, a, r, L)$ and $K=$ sinc. Take $C(h)=\log ^{2}(n)$. Then $\check{h}_{\text {opt }} \in \mathcal{H}$ and the infimum in Inequalities (19) and (20) are reached.

Nevertheless, if $\mathcal{H}$ is more precisely specified, we can prove a better result in expectation:
Theorem 3. Assume that $\left(\mathbf{H}_{\varepsilon}\right)$ holds, that $f^{*} \in L^{1}$, $f$ belongs to Sobolev class $\mathcal{S}(b, a, r, L)$ and $K=$ sinc. Define now for $M$ given, $M \leq n$,

$$
\mathcal{H}_{M}=\left\{h^{(k)}, h_{j}^{(k)}=\frac{1}{k}, j=1, \ldots, d, k=1, \ldots, M, \text { with } V\left(h^{(k)}\right) \leq 1\right\} .
$$

Choose

$$
\begin{equation*}
C(h)=\sum_{j=1}^{d} h_{j}^{-2 \rho_{j} \mathbb{1}_{\rho_{j} \geq 1 / 2}} \tag{22}
\end{equation*}
$$

Then choose $M$ such that $\check{h}_{\text {opt }} \in \mathcal{H}_{M}$ ( $M=n$ always suits). Then we have

$$
\begin{equation*}
\mathbb{E}(\|\check{f}-f\|) \leq 3 \inf _{h \in \mathcal{H}_{M}}\left\{\left\|f-f_{h}\right\|+\sqrt{\tilde{V}(h)}\right\}+\frac{C_{2}}{\sqrt{n}} \tag{23}
\end{equation*}
$$

Remark 4. By $\check{h}_{\text {opt }} \in \mathcal{H}_{M}$, we mean that $1 /\left[1 / \check{h}_{\text {opt }}\right] \in \mathcal{H}$ where $[x]$ denotes the integer part of $x$. In the formulation above, the infimum in (23) is necessarily reached.

The exact choice instead of (22) is the following

$$
\begin{equation*}
C(h)=\sum_{j=1}^{d} \omega_{j} h_{j}^{-\left(2 \rho_{j}-1\right)_{+}+\left(\rho_{j}-1\right)_{+}} \tag{24}
\end{equation*}
$$

for constants $\omega_{j}$ depending on $\alpha_{j}, \beta_{j}, \rho_{j}$ that can be specified (see Section 7.9 in Appendix).
Let us discuss the possible loss in the rate of convergence of the estimator resulting from the choice (22) of $C(h)$ and Inequality (23).
(1) If $f_{\varepsilon}$ is ordinary smooth, equation (22) says that $C(h)=1$ and therefore, as $\check{h}_{\text {opt }}$ belongs to $\mathcal{H}$, the optimal rate $\left(n^{-1 /\left(1+\frac{1}{2} \sum_{i=1}^{d} \frac{2 \beta_{i}+1}{b_{i}}\right)}\right.$ or $\left.[\log (n)]^{\sum_{j=1}^{d}\left(2 \beta_{j}+1\right) / r_{j}} / n\right)$ is automatically reached by the estimator.
(2) If $f_{\varepsilon}$ is super smooth, equation (22) says that the variance term has to be slightly increased.
(a) Nevertheless, if the function $f$ is ordinary smooth, the minimization in (20) still yields the optimal rate. Indeed, in that case the variance is made negligible with respect to the bias by the optimal bandwidth choice (see the computations in Section 3.2).
(b) When $f$ is also super smooth, if all $\rho_{j}$ 's are less than $1 / 2$, then there is no loss. Otherwise, the optimal bandwidth choice is such that, in part of the cases, the bias is dominating, and then there is still no loss. When some of the $\rho_{j}$ 's are larger than $1 / 2$ and the variance is dominating, there is a loss. But as the selected bandwidths have logarithmic orders in the concerned cases, the rates are deteriorated in a negligible way and less than if they were computed with respect to a sample size $n / \log ^{2 \max _{j} \rho_{j}}(n)$ instead of $n$. In other words, the loss is always negligible with respect to the rate.

## 5. Numerical illustration

5.1. Implementation. The theoretical study shows the advantages of the kernel sinc. It has also good properties for practical purposes, since it allows to use Fast Fourier Transform. Thus we consider in this section, in the case $d=2$, the kernel $K(x, y)=\operatorname{sinc}(x) \operatorname{sinc}(y) / \pi^{2}$. Let us denote $\varphi_{h, j}(x)=\pi / \sqrt{h_{1} h_{2}} K\left(x_{1} / h_{1}-\pi j_{1}, x_{2} / h_{2}-\pi j_{2}\right)$. The main trick used here follows from model selection works on deconvolution (see Comte et al. (2006) and Comte and Lacour (2011)). It is shown therein that $\left(\varphi_{h, j}\right)_{j \in \mathbb{Z}^{2}}$ is an orthonormal basis of the space of integrable functions having a Fourier transform with compact support included into $\left[-1 / h_{1}, 1 / h_{1}\right] \times\left[-1 / h_{2}, 1 / h_{2}\right]$. Then $\hat{f}_{h}$ can be written in this basis: $\hat{f}_{h}=\sum_{j} \hat{a}_{j}^{h} \varphi_{h, j}$ with

$$
\hat{a}_{j}^{h}=\frac{1}{4 \pi^{2}} \int \hat{f}_{h}^{*} \varphi_{h, j}^{*}=\frac{\sqrt{h_{1} h_{2}}}{4 \pi} \int_{-1 / h_{1}}^{1 / h_{1}} \int_{-1 / h_{2}}^{1 / h_{2}} \frac{\widehat{f_{Y}^{*}}}{f_{\varepsilon}^{*}}\left(u_{1}, u_{2}\right) e^{i \pi\left(u_{1} h_{1} j_{1}+u_{2} h_{2} j_{2}\right)} d u_{1} d u_{2}
$$

The interesting point is here that such coefficients can be computed via Fast Fourier Transform. So we implement our estimator in the following way

$$
\hat{f}_{h}=\sum_{\left|j_{1}\right| \leq M} \sum_{\left|j_{2}\right| \leq M} \hat{a}_{j}^{h} \varphi_{h, j}
$$

with $M=64$. Moreover, we use that with cardinal sine kernel, we have $f_{h, h^{\prime}}=f_{h \vee h^{\prime}}$, by denoting $h \vee h^{\prime}=\left(\max \left(h_{1}, h_{1}^{\prime}\right), \max \left(h_{2}, h_{2}^{\prime}\right)\right)$.

Then in the poinwise setting, we compute $A_{0}\left(h, x_{0}\right)$ as given by (10) with $\tilde{V}_{0}(h)$ given by (11) and $c_{0}=0.01$. Thus, the plots of the selected estimators $\hat{f}_{\hat{h}\left(x_{0}\right)}\left(x_{0}\right)$ are given on a grid of points $x_{0}$ in a domain which is specified in each example.

In the global setting, we can exploit additional useful properties of the representation. Indeed, for all $h^{\prime}, h^{\prime \prime}$,

$$
\left\|\hat{f}_{h^{\prime}}-\hat{f}_{h^{\prime \prime}}\right\|^{2}=\frac{1}{4 \pi^{2}}\left\|\hat{f}_{h^{\prime}}^{*}-\hat{f}_{h^{\prime \prime}}^{*}\right\|^{2}=\frac{1}{4 \pi^{2}}\left\|\frac{\widehat{f}_{Y}^{*}}{f_{\varepsilon}^{*}} \mathbb{1}_{D_{h^{\prime}}}-\frac{\widehat{f_{Y}^{*}}}{f_{\varepsilon}^{*}} \mathbb{1}_{D_{h^{\prime \prime}}}\right\|^{2}
$$

with $D_{h}=\left[-1 / h_{1}, 1 / h_{1}\right] \times\left[-1 / h_{2}, 1 / h_{2}\right]$. Then, if $D_{h^{\prime \prime}} \subset D_{h^{\prime}}$,

$$
\left\|\hat{f}_{h^{\prime}}-\hat{f}_{h^{\prime \prime}}\right\|^{2}=\frac{1}{4 \pi^{2}} \int_{D_{h^{\prime}} \backslash D_{h^{\prime \prime}}}\left|\frac{\widehat{f_{Y}^{*}}}{f_{\varepsilon}^{*}}\right|^{2}=\frac{1}{4 \pi^{2}} \int_{D_{h^{\prime}}}\left|\frac{\widehat{f_{Y}^{*}}}{f_{\varepsilon}^{*}}\right|^{2}-\frac{1}{4 \pi^{2}} \int_{D_{h^{\prime \prime}}}\left|\frac{\widehat{f_{Y}^{*}}}{f_{\varepsilon}^{*}}\right|^{2}=\left\|\hat{f}_{h^{\prime}}\right\|^{2}-\left\|\hat{f}_{h^{\prime \prime}}\right\|^{2}
$$

where we have $\left\|\hat{f}_{h}\right\|^{2}=\sum_{j}\left|\hat{a}_{j}^{h}\right|^{2}$. Then the computation of

$$
A(h)=\sup _{h^{\prime} \in \mathcal{H}}\left[\sqrt{\left\|\hat{f}_{h^{\prime}}\right\|^{2}-\left\|\hat{f}_{h \vee h^{\prime}}\right\|^{2}}-\sqrt{\tilde{V}\left(h^{\prime}\right)}\right]_{+}
$$

is considerably accelerated. We choose $\tilde{V}(h)=0.05 \log ^{2}(n) V(h)$, that is $C(h)$ in formula (17) is taken equal to $\log ^{2}(n)$ as recommended by Corollary 3 . Once the bandwidth is selected in the global setting, we have the coefficients $\hat{a}_{j}^{h}$ and thus, we can plot $\hat{f}_{\hat{h}}(x, y)$ at any point $(x, y)$.

We take $\mathcal{H}$ and $\mathcal{H}_{0}$ included in $\left\{4 / m, 1 \leq m \leq 3 n^{1 / 4}\right\}$.
5.2. Examples. Now we compute estimators for different signal densities and different noises. Let $\lambda=6, \mu=1 / 4$.
Example 1 Cauchy distribution: $f(x, y)=\left(\pi^{2}\left(1+x^{2}\right)\left(1+y^{2}\right)\right)^{-1}$ on $[-4,4]^{2}$ with a Laplace/Laplace noise, i.e.

$$
f_{\varepsilon}(x, y)=\frac{\lambda^{2}}{4} e^{-\lambda|x|} e^{-\lambda|y|} ; \quad f_{\varepsilon}^{*}(x, y)=\frac{\lambda^{2}}{\lambda^{2}+x^{2}} \frac{\lambda^{2}}{\lambda^{2}+y^{2}}
$$

The smoothness parameters are $b_{1}=b_{2}=0, r_{1}=r_{2}=1, \beta_{1}=\beta_{2}=2$ and $\rho_{1}=\rho_{2}=0$. For this example, we can compute that the rate is of order $(\log (n))^{10} / n$.
Example 2 Mixed Gaussian distribution: $X_{i, 1}=W / \sqrt{7}$ with $W \sim 0.4 \mathcal{N}(0,1)+0.6 \mathcal{N}(5,1)$, and $X_{i, 2}$ independent with distribution $\mathcal{N}(0,1)$. We estimate the density on $[-2,4]^{2}$. We consider that the noise follows a Laplace/Gaussian distribution, i.e.

$$
f_{\varepsilon}(x, y)=\frac{\lambda}{2} e^{-\lambda|x|} \frac{1}{\mu \sqrt{2 \pi}} e^{-y^{2} /\left(2 \mu^{2}\right)} ; \quad f_{\varepsilon}^{*}(x, y)=\frac{\lambda^{2}}{\lambda^{2}+x^{2}} e^{-\mu^{2} y^{2} / 2}
$$

The smoothness parameters are $b_{1}=b_{2}=0, r_{1}=r_{2}=2, \beta_{1}=2, \beta_{2}=0$ and $\rho_{1}=0, \alpha_{2}=\mu^{2} / 2, \rho_{2}=2$. Here the rate of convergence is $n^{-16 / 17}[\log (n)]^{63 / 34}$ in the global setting and $n^{-16 / 17}[\log (n)]^{23 / 17}$ for the bandwidths $h_{1}^{-1}=\sqrt{7 \log (n)}$ and


Figure 1. Example 2, global bandwidth selection, with $n=500$. Top right: true density $f$, top left: estimator $\check{f}$, bottom: sections, dark line for $f$ and light line for the estimator
$h_{2}^{-1}=\sqrt{a \log (n)-b \log (\log (n))}$ for $a=16 / 17$ and $b=40 / 17$ in both cases. We use that $\mu^{2}=1 / 16$.

|  | $n=100$ | $n=300$ | $n=500$ | $n=750$ | $n=1000$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Ex 1 Global | 0.419 | 0.289 | 0.215 | 0.161 | 0.137 |
| Ex 1 Pointwise | 0.269 | 0.140 | 0.101 | 0.083 | 0.068 |
| Ex 2 Global | 3.615 | 1.699 | 0.761 | 0.473 | 0.367 |
| Ex 2 Pointwise | 3.477 | 1.714 | 0.799 | 0.526 | 0.363 |
| Ex 3 Global | 0.800 | 0.402 | 0.303 | 0.248 | 0.212 |
| Ex 3 Pointwise | 0.622 | 0.293 | 0.212 | 0.167 | 0.138 |

TABLE 1. MISE $\times 100$ averaged over 100 samples

Example 3 Gamma distribution: $X_{i, 1} \sim \Gamma(5,1 / \sqrt{5})$ and $X_{i, 2} \sim \Gamma(5,1 / \sqrt{5})$. We estimate the density on $[0,8]^{2}$. The noise follow a Gaussian/Gaussian distribution, i.e.

$$
f_{\varepsilon}(x, y)=\frac{1}{2 \pi \mu^{2}} e^{-\left(x^{2}+y^{2}\right) /\left(2 \mu^{2}\right)} ; \quad f_{\varepsilon}^{*}(x, y)=e^{-\mu^{2}\left(x^{2}+y^{2}\right) / 2}
$$

So $b_{1}=b_{2}=5, r_{1}=r_{2}=0, \beta_{1}=\beta_{2}=0, \alpha_{1}=\alpha_{2}=\mu^{2} / 2$ and $\rho_{1}=\rho_{2}=2$. This is an example with pointwise rate $[\log (n)]^{-4}$ and global rate $(\log (n))^{-9 / 2}$ (which is not so slow, for instance, for $n=1000$, this term is smaller than $1 / n!$ ).
For these examples, we apply both global and pointwise estimation procedure, and we compute the Mean Integrated Squared Error on a grid of $50 \times 50$ points. The MISE (multiplied by 100,


Figure 2. Example 3, pointwise bandwidth selection, with $n=500$. Top right: true density $f$, top left: estimator $\tilde{f}$, bottom: sections, dark line for $f$ and light line for the estimator

|  | $n=100$ | $n=300$ | $n=500$ | $n=750$ | $n=1000$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Ex 1 | 1.48 | 2.04 | 2.01 | 1.96 | 1.97 |
| Ex 2 | 1.08 | 1.03 | 1.05 | 1.07 | 1.25 |
| Ex 3 | 1.36 | 1.53 | 1.57 | 1.57 | 1.62 |

TABLE 2. $C_{\text {oracle }}$ averaged over 100 samples
averaged over 100 samples) is given in Table 1. For each path, we also compare the MISE for the global procedure with the minimum risk for all bandwidths of the collection. Table 2 gives the empirical version of the oracle constant defined by

$$
C_{\text {oracle }}=\mathbb{E}\left(\frac{\|\check{f}-f\|^{2}}{\inf _{h \in \mathcal{H}}\left\|\hat{f}_{h}-f\right\|^{2}}\right) .
$$

It shows that the adaptation is performing, since the risk for the chosen $\hat{h}$ is very close to the best possible in the collection (the nearest of one $C_{\text {oracle }}$, the better the algorithm is).

We also illustrate the results with some figures. Figure 1 shows the surface $z=f(x, y)$ for Example 2 and the estimated surface $z=\check{f}(x, y)$ obtained by global bandwidth selection. For more visibility, sections of the previous surface are drawn. We can see the curves $z=f(x,-0.3)$ versus $z=\check{f}(x,-0.3)$ and the curves $z=f(-0.3, y)$ versus $z=\check{f}(-0.3, y)$. For this figure, the selected bandwidth is $\hat{h}=(0.29,0.57)$. Thus, the bandwidth in the first direction is twice smaller, to recover the two modes, that shows that our procedure takes really anisotropy into account.


Figure 3. Dependent case, global bandwidth selection, with $n=500$. Top right: true density $f$, top left: estimator $\tilde{f}$, bottom: sections, dark line for $f$ and light line for the estimator

Figure 2 is an analogous illustration of Example 3, but with a pointwise bandwidth selection, as described in Section 3. We obtain a slightly more angular figure. Nevertheless, we can notice by observing Table 1 that the MISE is almost always smaller for this kind of estimation.

To conclude this section, we would like to mention that we can keep good results even in case of dependent components of both the noise and the signal. More precisely, we can take $X \sim \mathcal{N}(0, \Sigma)$ and $\varepsilon \sim \mathcal{N}\left(0, \Sigma_{\varepsilon}\right)$ with $\Sigma=\left(\begin{array}{cc}1 & -0.7 \\ -0.7 & 2\end{array}\right)$ and $\Sigma_{\varepsilon}=10^{-2}\left(\begin{array}{cc}1 & 0.25 \\ 0.25 & 1.0625\end{array}\right)$, with $X$ and $\varepsilon$ independent. We present in Figure 3 an illustration of the results for the global method.

## 6. Concluding remarks: the case of unknown noise density

The assumption of the knowledge of the error distribution is often disputed. Relaxing this assumption requires conditions for obvious reasons of identifiability. Here is a quick description of what can be done in case of additional observations of the noise $\varepsilon_{-1}, \ldots, \varepsilon_{-N}$ (think of a measure device calibrated without signal). We use this preliminary noise sample to estimate $f_{\varepsilon}^{*}$ in the following way
where $\hat{f}_{\varepsilon}^{*}(x)=N^{-1} \sum_{j=1}^{N} e^{-i\left\langle x, \varepsilon_{-j}\right\rangle}$ is the natural estimator of $f_{\varepsilon}^{*}$. Then it is sufficient to write

$$
\bar{f}_{h}^{*}(t)=K_{h}^{*}(t) \frac{\widehat{f_{Y}^{*}}(t)}{\tilde{f}_{\varepsilon}^{*}(t)}
$$

to define new estimators of $f$ in this context. Adapting all the previous results in this framework is beyond the scope of this paper, but we can observe the effect of this modification on the integrated squared error, for instance. The bias is unchanged, but an additional term appears in the variance:

Proposition 5. We have $\mathbb{E}\left\|f_{h}-\bar{f}_{h}\right\|^{2} \lesssim V(h)+W(h)$ where

$$
W(h)=\frac{1}{(2 \pi)^{d} N}\left\|\frac{K_{h}^{*} f^{*}}{f_{\varepsilon}^{*}}\right\|^{2}
$$

It is possible to give a bound of $W(h)$ in term of the smoothness indices of $f_{\varepsilon}$ and $f$ but we skip this tedious formula, which is just a generalization of Lemma 2 in Comte and Lacour (2011). In the case of an ordinary smooth function and a fully ordinary smooth noise, we obtain $W(h) \lesssim N^{-1} \prod_{j=1}^{d} h_{j}^{-2\left(\beta_{j}-b_{j}\right)_{+}}$.

Thus, we get new rates of convergence in terms of $n$ and $N$. If $N>n, W(h)$ is always smaller than $V(h)$. In this case, an adaptive procedure is conceivable, replacing $\tilde{V}(h)$ by $\bar{V}(h)=$ $\bar{C}(h)\left\|K_{h}^{*} / \tilde{f}_{\varepsilon}^{*}\right\|^{2} / n$ and modifying $\mathcal{H}$ in the same way. The efficiency of this strategy can be proved by controlling terms of the form $\left[\left\|\bar{f}_{h}-\hat{f}_{h}\right\|^{2}-\bar{V}(h)\right]_{+}$. This was successfully established in Comte and Lacour (2011) in dimension 1, but such a study in dimension $d$ would be much too long here.

## 7. Proofs

We start with three useful lemmas.
Lemma 1. For all $m>0$,

- $\int_{-m}^{m}\left(x^{2}+1\right)^{\gamma} \exp \left(c|x|^{s}\right) d x \approx m^{2 \gamma+1-s} e^{c m^{s}}$,
- $\int_{m}^{\infty}\left(x^{2}+1\right)^{-\gamma} \exp \left(-c|x|^{s}\right) d x \approx m^{-2 \gamma+1-s} e^{-c m^{s}}$.

Proof of this lemma is based on integration by parts and is omitted. See also Butucea and Tsybakov (2007, 2008).
Lemma 2. [Bernstein inequality] Let $T_{1}, \ldots, T_{n}$ be independent random variables and $S_{n}(T)=$ $\sum_{i=1}^{n}\left[T_{i}-\mathbb{E}\left(T_{i}\right)\right]$. Then, for $\eta>0$,

$$
\mathbb{P}\left(\left|S_{n}(T)-\mathbb{E}\left(S_{n}(T)\right)\right| \geq n \eta\right) \leq 2 \max \left(\exp \left(-\frac{n \eta^{2}}{4 v}\right), \exp \left(-\frac{n \eta}{4 b}\right)\right)
$$

where $\operatorname{Var}\left(T_{1}\right) \leq v$ and $\left|T_{1}\right| \leq b$.
It is proved in Birgé and Massart (1998), p. 366 that $\mathbb{P}\left(\left|S_{n}(T)-\mathbb{E}\left(S_{n}(T)\right)\right| \geq n \eta\right) \leq$ $2 \exp \left(-n \eta^{2} /\left(2 v^{2}+2 b \eta\right)\right.$. Lemma 2 follows.
Lemma 3. [Talagrand Inequality] Let $Y_{1}, \ldots, Y_{n}$ be i.i.d. random variables and $\left.\nu_{n}(t)=\frac{1}{n} \sum_{i=1}^{n} \right\rvert\, \psi_{t}\left(Y_{i}\right)-$ $\mathbb{E}\left(\psi_{t}\left(Y_{i}\right)\right)$ ] for $t$ belonging to $\bar{B}$ a countable subset of functions. For any $\eta>0$,

$$
\begin{equation*}
P\left(\sup _{t \in \bar{B}}\left|\nu_{n}(t)\right| \geq(1+2 \eta) H\right) \leq \max \left(\exp \left(-\frac{\eta^{2}}{6} \frac{n H^{2}}{v}\right), \exp \left(-\frac{\min (\eta, 1) \eta}{21} \frac{n H}{M}\right)\right) \tag{25}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbb{E}\left[\sup _{t \in \bar{B}(0,1)}\left|\nu_{n}(t)\right|-(1+2 \eta) H\right]_{+} \leq\left(\sqrt{\frac{3 \pi}{2}} \sqrt{\frac{v}{n}} e^{-\frac{\eta^{2}}{6} \frac{n H^{2}}{v}}+\frac{21}{\eta \wedge 1} \frac{M}{n} e^{-\frac{(\eta \wedge 1) \eta}{21} \frac{n H}{M}}\right) \tag{26}
\end{equation*}
$$

with

$$
\sup _{t \in \bar{B}}\left\|\psi_{t}\right\|_{\infty} \leq M, \quad \mathbb{E}\left[\sup _{t \in \bar{B}}\left|\nu_{n}(t)\right|\right] \leq H, \quad \sup _{t \in \bar{B}} \frac{1}{n} \sum_{k=1}^{n} \operatorname{Var}\left(\psi_{t}\left(Y_{k}\right)\right) \leq v .
$$

Proof of Lemma 3: We apply the Talagrand concentration inequality given in Klein and Rio (2005) to the functions $s^{i}(x)=t(x)-\mathbb{E}\left(t\left(Y_{i}\right)\right)$ and we obtain

$$
P\left(\sup _{t \in \bar{B}}\left|\nu_{n}(t)\right| \geq H+\lambda\right) \leq \exp \left(-\frac{n \lambda^{2}}{2(v+4 H M)+6 M \lambda}\right) .
$$

Then we modify this inequality following Birgé and Massart (1998) Corollary 2 p.354. It gives

$$
\begin{equation*}
P\left(\sup _{t \in \bar{B}}\left|\nu_{n}(t)\right| \geq(1+\eta) H+\lambda\right) \leq \exp \left(-\frac{n}{3} \min \left(\frac{\lambda^{2}}{2 v}, \frac{\min (\eta, 1) \lambda}{7 M}\right)\right) . \tag{27}
\end{equation*}
$$

To conclude for (25), we set $\lambda=\eta H$.
For (26), we take $\lambda=\eta H+u$ and write

$$
\begin{aligned}
\mathbb{E}\left[\sup _{t \in \bar{B}(0,1)}\left|\nu_{n}(t)\right|-(1+2 \eta) H\right]_{+} & \leq \int_{0}^{+\infty} P\left(\sup _{t \in \bar{B}(0,1)}\left|\nu_{n}(t)\right| \geq(1+\eta) H+\eta H+u\right) d u \\
& \leq \int_{0}^{+\infty} e^{-\frac{n \eta^{2} H^{2}}{6 v}} e^{-\frac{n u^{2}}{6 v}} d u+\int_{0}^{+\infty} e^{-\frac{n \eta(\eta \wedge 1) H}{21 M}} e^{-\frac{n(\eta \wedge 1) u}{21 M}} d u \\
& =\sqrt{\frac{3 \pi}{2}} \sqrt{\frac{v}{n}} e^{-\frac{n \eta^{2} H^{2}}{6 v}}+\frac{21 M}{n(\eta \wedge 1)} e^{-\frac{n \eta(\eta \wedge 1) H}{21 M}}
\end{aligned}
$$

which is the result of (26).
7.1. Proof of Proposition 1. In the first case, the bias term is the same as in density estimation (see Tsybakov (2009)) and the use of Taylor formula to partial functions $t \mapsto f\left(x_{1}-\right.$ $\left.v_{1} h_{1}, \ldots, x_{i-1}-v_{i-1} h_{i-1}, t, x_{i+1}, \ldots, x_{d}\right)$ yield

$$
\left|f_{h}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq L \sum_{j=1}^{d} \frac{\int\left|x_{j}\right|^{b_{j}}|K(x)| d x}{\left\lfloor b_{j}\right\rfloor!} h_{j}^{b_{j}} .
$$

In the second case, since $f^{*}, f_{h}^{*} \in L^{1}$, we can write

$$
f\left(x_{0}\right)-f_{h}\left(x_{0}\right)=\frac{1}{(2 \pi)^{d}} \int e^{-i\left\langle x_{0}, u\right\rangle} \mathbb{1}_{\left(\prod_{j=1}^{d}\left[-1 / h_{j}, 1 / h_{j}\right]\right)^{c}}\left(u_{j}\right) f^{*}\left(u_{1}, \ldots, u_{d}\right) d u_{1} \ldots d u_{d}
$$

Then, for $f \in \mathcal{S}(b, a, r, L)$, the bias term is

$$
\begin{aligned}
\left|f\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right| \leq & \frac{1}{(2 \pi)^{d}} \sum_{j=1}^{d} \int \mathbb{1}_{\left|u_{j}\right| \geq 1 / h_{j}}\left|f^{*}\left(u_{1}, \ldots, u_{d}\right)\right| d u_{1} \ldots d u_{d} \\
\leq & \frac{1}{(2 \pi)^{d}} \sum_{j=1}^{d} \int\left[\mathbb{1}_{\left|u_{j}\right| \geq 1 / h_{j} \mid} \prod_{k=1}^{d}\left(1+u_{k}^{2}\right)^{-b_{k} / 2} \exp \left(-a_{k}\left|u_{k}\right|^{r_{k}}\right)\right] \\
& \times\left[\left|f^{*}\left(u_{1}, \ldots, u_{d}\right)\right| \prod_{k=1}^{d}\left(1+u_{k}^{2}\right)^{b_{k} / 2} \exp \left(a_{k}\left|u_{k}\right|^{r_{k}}\right)\right] d u_{1} \ldots d u_{d} \\
& \leq \frac{L}{(2 \pi)^{d}} \sum_{j=1}^{d}\left(\int_{|u| \geq 1 / h_{j}}\left(1+u^{2}\right)^{-b_{j}} \exp \left(-2 a_{j}|u|^{r_{j}}\right) d u\right)^{1 / 2}
\end{aligned}
$$

since

$$
\prod_{k \neq j}\left(1+u_{k}^{2}\right)^{-b_{k} / 2} \exp \left(-a_{k}\left|u_{k}\right|^{r_{k}}\right) \leq 1
$$

Then, using Lemma 1, $\left|f\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right| \lesssim L \sum_{j=1}^{d} h_{j}^{b_{j}+r_{j} / 2-1 / 2} \exp \left(-a_{j} h_{j}^{-r}\right)$.
7.2. Proof of Proposition 2. The independence of the observations gives

$$
\operatorname{Var}\left(\hat{f}_{h}\left(x_{0}\right)\right)=\frac{1}{n} \operatorname{Var}\left(\frac{1}{(2 \pi)^{d}} \int e^{-i\left\langle u, x_{0}\right\rangle} K_{h}^{*}(u) \frac{e^{i\left\langle u, Y_{1}\right\rangle}}{f_{\varepsilon}^{*}(u)} d u\right)
$$

A simple bound of the variance by the expectation of the square yields $\operatorname{Var}\left(\hat{f}_{h}\left(x_{0}\right)\right) \leq\left(n(2 \pi)^{2 d}\right)^{-1}\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2}$. But we can also write

$$
\begin{aligned}
\operatorname{Var}\left(\hat{f}_{h}\left(x_{0}\right)\right) n(2 \pi)^{2 d} & =\iint e^{-i\left\langle u-v, x_{0}\right\rangle} \frac{K_{h}^{*}(u) K_{h}^{*}(-v)}{f_{\varepsilon}^{*}(u) f_{\varepsilon}^{*}(-v)}\left(f_{Y}^{*}(u-v)-f_{Y}^{*}(u) f_{Y}^{*}(-v)\right) d u d v \\
& \leq \iint\left|\frac{K_{h}^{*}(u) K_{h}^{*}(-v)}{f_{\varepsilon}^{*}(u) f_{\varepsilon}^{*}(-v)}\right|\left|f_{Y}^{*}(u-v)\right| d u d v \\
& \leq \int\left|\frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)}\right|^{2} \int\left|f_{Y}^{*}(t)\right| d t \leq\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|_{2}^{2}\left\|f_{\varepsilon}^{*}\right\|_{1}
\end{aligned}
$$

using Schwarz inequality.
Now, under $\left(\mathbf{H}_{\varepsilon}\right),(2 \pi)^{2 d} n V_{0}(h)$ is bounded by the minimum of

$$
\left\|f_{\varepsilon}^{*}\right\|_{1} \prod_{j=1}^{d} \int\left|\frac{K_{j}^{*}\left(u_{j} h_{j}\right)}{\left(u_{j}^{2}+1\right)^{-\beta_{j} / 2} \exp \left(-\alpha_{j}\left|u_{j}\right|^{\rho_{j}}\right)}\right|^{2} d u_{j}
$$

and

$$
\left(\prod_{j=1}^{d} \int\left|\frac{K_{j}^{*}\left(u_{j} h_{j}\right)}{\left(u_{j}^{2}+1\right)^{-\beta_{j} / 2} \exp \left(-\alpha_{j}\left|u_{j}\right|^{\rho_{j}}\right)}\right| d u_{j}\right)^{2}
$$

If $j \in S S$, i.e. $\rho_{j}>0$ then $K_{j}^{*}(t)=0$ if $|t| \geq 1$. Consequently, using Lemma 1 ,

$$
\begin{aligned}
\int\left|\frac{K_{j}^{*}\left(u h_{j}\right)}{\left(u^{2}+1\right)^{-\beta_{j} / 2} \exp \left(-\alpha_{j}|u|^{\rho_{j}}\right)}\right|^{2} d u & =\int_{-1 / h_{j}}^{1 / h_{j}}\left|K_{j}^{*}(u h)\right|^{2}\left(u^{2}+1\right)^{\beta_{j}} \exp \left(2 \alpha_{j}|u|^{\rho_{j}}\right) d u \\
& \leq\left\|K_{j}^{*}\right\|_{\infty}^{2} \int_{-1 / h_{j}}^{1 / h_{j}}\left(u^{2}+1\right)^{\beta_{j}} \exp \left(2 \alpha_{j}|u|^{\rho_{j}}\right) d u \\
& \lesssim h_{j}^{-2 \beta_{j}-1+\rho_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right)
\end{aligned}
$$

In the same way

$$
\begin{aligned}
\int\left|\frac{K_{j}^{*}\left(u h_{j}\right)}{\left(u^{2}+1\right)^{-\beta_{j} / 2} \exp \left(-\alpha_{j}|u|^{\rho_{j}}\right)}\right| d u & =\int_{-1 / h_{j}}^{1 / h_{j}}\left|K_{j}^{*}(u h)\right|\left(u^{2}+1\right)^{\beta_{j} / 2} \exp \left(\alpha_{j}|u|^{\rho_{j}}\right) d u \\
& \leq\left\|K_{j}^{*}\right\|_{\infty} \int_{-1 / h_{j}}^{1 / h_{j}}\left(u^{2}+1\right)^{\beta_{j} / 2} \exp \left(\alpha_{j}|u|^{\rho_{j}}\right) d u \\
& \lesssim h_{j}^{-\beta_{j}-1+\rho_{j}} \exp \left(\alpha_{j} h_{j}^{-\rho_{j}}\right)
\end{aligned}
$$

Now, if $j \in O S$, i.e. $\alpha_{j}=\rho_{j}=0$, then

$$
\int\left|\frac{K_{j}^{*}\left(u h_{j}\right)}{\left(u^{2}+1\right)^{-\beta_{j} / 2}}\right|^{2} d u=h_{j}^{-1} \int\left|K_{j}^{*}(u)\right|^{2}\left(\left(u h_{j}^{-1}\right)^{2}+1\right)^{\beta_{j}} d u \lesssim h_{j}^{-1-2 \beta_{j}} \int\left|K_{j}^{*}(u)\right|^{2}\left(u^{2}+1\right)^{\beta_{j}} d u
$$

and $\int\left|\frac{K_{j}^{*}\left(u h_{j}\right)}{\left(u^{2}+1\right)^{-\beta_{j} / 2}}\right| d u \lesssim h_{j}^{-1-\beta_{j}} \int\left|K_{j}^{*}(u)\right|\left(u^{2}+1\right)^{\beta_{j} / 2} d u$. Finally, using that $h_{j} \leq 1$, we obtain the following bound for $n V_{0}(h)$

$$
\prod_{j \in S S} \min \left(1, h_{j}^{-1+\rho_{j}}\right) h_{j}^{-2 \beta_{j}-1+\rho_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right) \prod_{j \in 0 S} h_{j}^{-1-2 \beta_{j}}=\prod_{j=1}^{d} h_{j}^{\left(\rho_{j}-1\right)_{+}} h_{j}^{-2 \beta_{j}-1+\rho_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right)
$$

### 7.3. Proof of Theorem 1.

7.3.1. Proof of Theorem 1. We want to bound $\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right|$. Let $h \in \mathcal{H}_{0}$ be fixed. The following decomposition holds:

$$
\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq \underbrace{\left|\hat{f}_{\hat{h}\left(x_{0}\right)}\left(x_{0}\right)-\hat{f}_{h, \hat{h}\left(x_{0}\right)}\left(x_{0}\right)\right|}_{D_{1}}+\underbrace{\left|\hat{f}_{h, \hat{h}\left(x_{0}\right)}\left(x_{0}\right)-\hat{f}_{h}\left(x_{0}\right)\right|}_{D_{2}}+\left|\hat{f}_{h}\left(x_{0}\right)-f\left(x_{0}\right)\right| .
$$

By definition of $A\left(h, x_{0}\right)$,

$$
D_{1} \leq A_{0}\left(h, x_{0}\right)+\sqrt{\tilde{V}_{0}\left(\hat{h}\left(x_{0}\right)\right)}
$$

And by definition of $A_{0}\left(\hat{h}\left(x_{0}\right), x_{0}\right)$,

$$
D_{2} \leq A_{0}\left(\hat{h}\left(x_{0}\right), x_{0}\right)+\sqrt{\tilde{V}_{0}(h)}
$$

Therefore

$$
D_{1}+D_{2} \leq A_{0}\left(h, x_{0}\right)+\sqrt{\tilde{V}_{0}\left(\hat{h}\left(x_{0}\right)\right)}+A_{0}\left(\hat{h}\left(x_{0}\right), x_{0}\right)+\sqrt{\tilde{V}_{0}(h)} \leq 2\left[A_{0}\left(h, x_{0}\right)+\sqrt{\tilde{V}_{0}(h)}\right]
$$

by using the definition of $\hat{h}\left(x_{0}\right)$. Thus

$$
\begin{equation*}
\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq 2 A_{0}\left(h, x_{0}\right)+2 \sqrt{\tilde{V}_{0}(h)}+\left|\hat{f}_{h}\left(x_{0}\right)-f\left(x_{0}\right)\right| \tag{28}
\end{equation*}
$$

To study $A_{0}\left(h, x_{0}\right)$, we can write

$$
\hat{f}_{h^{\prime}}\left(x_{0}\right)-\hat{f}_{h, h^{\prime}}\left(x_{0}\right)=\hat{f}_{h^{\prime}}\left(x_{0}\right)-f_{h^{\prime}}\left(x_{0}\right)-\left(\hat{f}_{h, h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)\right)+f_{h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)
$$

where

$$
\begin{aligned}
f_{h}\left(x_{0}\right) & =\mathbb{E}\left(\hat{f}_{h}\left(x_{0}\right)\right)=K_{h} \star f\left(x_{0}\right) \\
f_{h, h^{\prime}}\left(x_{0}\right) & =\mathbb{E}\left(\hat{f}_{h, h^{\prime}}\left(x_{0}\right)\right)=K_{h^{\prime}} \star K_{h} \star f\left(x_{0}\right)
\end{aligned}
$$

For any $h^{\prime}$,

$$
\left|f_{h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)\right|=\left|K_{h^{\prime}} \star\left(f-K_{h} \star f\right)\left(x_{0}\right)\right| \leq N(K) B_{0}(h)
$$

We get back to the definition of $A_{0}\left(h, x_{0}\right)$

$$
\begin{align*}
A_{0}\left(h, x_{0}\right)= & \sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h^{\prime}}\left(x_{0}\right)-\hat{f}_{h, h^{\prime}}\left(x_{0}\right)\right|-\sqrt{\tilde{V}_{0}\left(h^{\prime}\right)}\right]_{+} \\
(29) \quad & \sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h^{\prime}}\left(x_{0}\right)-f_{h^{\prime}}\left(x_{0}\right)\right|-\sqrt{\tilde{V}_{0}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right]_{+}  \tag{29}\\
& +\sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h, h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)\right|-\left\|K^{*}\right\|_{\infty} \sqrt{\tilde{V}_{0}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right]_{+}+N(K) B_{0}(h)
\end{align*}
$$

We can prove the following concentration result:
Proposition 6. Under the Assumptions of Theorem 1, for all $h, h^{\prime} \in \mathcal{H}_{0}^{2}$, for all $p \geq 1$,

$$
\begin{align*}
& \mathbb{P}\left(\left|\hat{f}_{h}\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right|>c_{1}(p) \sqrt{\tilde{V}_{0}(h)}\right) \leq 2 / n^{p}  \tag{30}\\
& \mathbb{P}\left(\left|\hat{f}_{h, h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)\right|>c_{1}(p)\left\|K^{*}\right\|_{\infty} \sqrt{\tilde{V}_{0}\left(h^{\prime}\right)}\right) \leq 2 / n^{p} \tag{31}
\end{align*}
$$

as soon as $c_{1}(p)^{2} c_{0} \geq 16 p^{2} / \min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}, 1\right)$.
The proposition is proved below. It implies that if $c_{1}(p)=1 /\left(1+\left\|K^{*}\right\|_{\infty}\right)$ and $c_{0} \geq 16 p^{2}(1+$ $\left.\left\|K^{*}\right\|_{\infty}\right)^{2} / \min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}, 1\right)$,

$$
\mathbb{P}\left\{\sup _{h \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h}\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right|-\sqrt{\tilde{V}_{0}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}^{2}\right)\right]_{+}>0\right\} \leq 2 \sum_{h \in \mathcal{H}_{0}} n^{-p} \leq 2 n^{\epsilon-p}
$$

as $\operatorname{Card}\left(\mathcal{H}_{0}\right) \leq n^{\epsilon}$. In the same way, for all $h \in \mathcal{H}_{0}$,

$$
\mathbb{P}\left\{\sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h, h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)\right|-\left\|K^{*}\right\|_{\infty} \sqrt{\tilde{V}_{0}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right]_{+}>0\right\} \leq 2 n^{\epsilon-p}
$$

Thus, the following set

$$
\begin{aligned}
\Omega= & \left\{\sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h^{\prime}}\left(x_{0}\right)-f_{h^{\prime}}\left(x_{0}\right)\right|-\sqrt{\tilde{V}_{0}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right]_{+}=0\right\} \cap \\
& \left\{\forall h \in \mathcal{H}_{0}, \sup _{h^{\prime} \in \mathcal{H}_{0}}\left[\left|\hat{f}_{h, h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)\right|-\left\|K^{*}\right\|_{\infty} \sqrt{\tilde{V}_{0}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right]_{+}=0\right\}
\end{aligned}
$$

has probability larger than $1-4 n^{2 \epsilon-p}$. Now we choose $p=2 \epsilon+q$ and then $c_{0} \geq 16(1+$ $\left.\left\|K^{*}\right\|_{\infty}\right)^{2}(2 \epsilon+q)^{2} / \min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}, 1\right)$. Thus $P(\Omega)>1-4 n^{-q}$.

By gathering inequalities (28) and (29), we have on $\Omega$

$$
\begin{aligned}
\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right| & \leq 2 A_{0}\left(h, x_{0}\right)+2 \sqrt{\tilde{V}_{0}(h)}+\left|\hat{f}_{h}\left(x_{0}\right)-f\left(x_{0}\right)\right| \\
& \leq 2 N(K) B_{0}(h)+2 \sqrt{\tilde{V}_{0}(h)}+\left|\hat{f}_{h}\left(x_{0}\right)-f\left(x_{0}\right)\right|
\end{aligned}
$$

But, still on $\Omega$

$$
\begin{aligned}
\left|\hat{f}_{h}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq & B_{0}(h)+\left|\hat{f}_{h}\left(x_{0}\right)-f_{h}\left(x_{0}\right)\right|-\sqrt{\tilde{V}_{0}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right) \\
& +\sqrt{\tilde{V}_{0}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right) \\
\leq & B_{0}(h)+\sqrt{\tilde{V}_{0}(h)}
\end{aligned}
$$

Then, on $\Omega$,

$$
\left|\tilde{f}\left(x_{0}\right)-f\left(x_{0}\right)\right| \leq(1+2 N(K)) B_{0}(h)+3 \sqrt{\tilde{V}_{0}(h)}
$$

which ends the proof of Theorem 1.
7.3.2. Proof of Proposition 6. Let us define the independent random variables

$$
Z_{k}\left(x_{0}\right)=\frac{1}{(2 \pi)^{d}} \int e^{-i\left\langle u, x_{0}\right\rangle} K_{h}^{*}(u) \frac{e^{i\left\langle u, Y_{k}\right\rangle}}{f_{\varepsilon}^{*}(u)} d u
$$

Clearly,

$$
\hat{f}_{h}\left(x_{0}\right)-f_{h}\left(x_{0}\right)=\frac{1}{n} \sum_{k=1}^{n}\left[Z_{k}\left(x_{0}\right)-\mathbb{E}\left(Z_{k}\left(x_{0}\right)\right)\right]
$$

We apply Bernstein Inequality recalled in Lemma 2 to the $Z_{k}\left(x_{0}\right)^{\prime}$ s, with $\eta=c_{1}(p) \sqrt{\tilde{V}_{0}(h)}$. We find

$$
\left|Z_{1}\left(x_{0}\right)\right| \leq(2 \pi)^{-d} \int\left|\frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)}\right| d u=: b
$$

and $\operatorname{Var}\left(Z_{1}\left(x_{0}\right)\right) \leq n V_{0}(h)$. We obtain

$$
\mathbb{P}\left(\mid\left(\hat{f}_{h}\left(x_{0}\right)-f_{h}\left(x_{0}\right) \mid>c_{1}(p) \sqrt{\tilde{V}_{0}(h)}\right) \leq \mathbb{P}\left(\left|S_{n}\left(Z\left(x_{0}\right)\right)-\mathbb{E}\left(S_{n}\left(Z\left(x_{0}\right)\right)\right)\right| \geq c_{1}(p) \sqrt{\tilde{V}_{0}(h)}\right)\right.
$$

$$
\begin{equation*}
\leq 2 \max \left(\exp \left(-\frac{n\left(c_{1}(p) \sqrt{\tilde{V}_{0}(h)}\right)^{2}}{4 n V_{0}(h)}\right), \exp \left(-\frac{n\left(c_{1}(p) \sqrt{\tilde{V}_{0}(h)}\right)}{4 b}\right)\right) \tag{32}
\end{equation*}
$$

where $c_{1}(p)$ is chosen such that

$$
\begin{equation*}
\frac{n c_{1}(p)^{2} \tilde{V}_{0}(h)}{4 n V_{0}(h)} \geq p \log (n) \tag{33}
\end{equation*}
$$

that is $c_{1}(p)^{2} c_{0} \geq 4 p$ ( $c_{0}$ is the constant in the definition of $\left.\tilde{V}_{0}(h)\right)$. Moreover,

$$
\frac{n \sqrt{c_{1}(p)^{2} \tilde{V}_{0}(h)}}{4 b}=\frac{\sqrt{c_{1}(p)^{2} c_{0}}}{4} \sqrt{n \log (n)} \sqrt{\frac{n V_{0}(h)}{b^{2}}}
$$

But for $h \in \mathcal{H}_{0}$,

$$
n V_{0}(h) / b^{2}=\min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|_{2}^{2}\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|_{1}^{-2}, 1\right) \geq c_{3} \frac{\log (n)}{n}
$$

with $c_{3}=\min \left(\left\|f_{\varepsilon}^{*}\right\|_{1}, 1\right)$. Thus

$$
\begin{equation*}
\frac{n \sqrt{c_{1}(p)^{2} \tilde{V}_{0}(h)}}{4 b} \geq p \log (n) \tag{34}
\end{equation*}
$$

provided that $\sqrt{c_{3} c_{1}^{2}(p) c_{0}} \geq 4 p$. Note now that this last condition also ensures the first constraint $c_{1}(p)^{2} c_{0} \geq 4 p$. Therefore, inserting (33) and (34) in (32) implies the first inequality (30) of Proposition 6.

To prove (31), we follow the same line. For the study of

$$
\hat{f}_{h, h^{\prime}}\left(x_{0}\right)-f_{h, h^{\prime}}\left(x_{0}\right)=K_{h} \star\left(\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right)\left(x_{0}\right)
$$

we can simply replace $K_{h}^{*}(u)$ by $K_{h}^{*}(u) K_{h^{\prime}}^{*}(u)$, with $\left|K_{h}^{*}(u)\right| \leq\left\|K^{*}\right\|_{\infty}$ so that it adds a term $\left\|K^{*}\right\|_{\infty}$ in the previous computations. Thus we get (31) and this end the proof of Proposition 6.
7.4. Proof of Corollary 1. Let us denote $\left|f_{\varepsilon, j}^{*}(t)\right|$ the j-th component of the order of the noise characteristic function, i.e. $\left|f_{\varepsilon, j}^{*}(t)\right|=\left(1+t^{2}\right)^{-\beta_{j} / 2} \exp \left(-\alpha_{j}|t|^{\rho_{j}}\right)$. First, we write

$$
\begin{aligned}
\frac{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2}}{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}} & \lesssim \prod_{j=1}^{d} \frac{\left(\int\left|K_{j}^{*}\left(t_{j} h_{j}\right) \| f_{\varepsilon, j}^{*}\left(t_{j}\right)\right|^{-1} d t_{j}\right)^{2}}{\int\left|K_{j}^{*}\left(t_{j} h_{j}\right)\right|^{2}\left|f_{\varepsilon, j}^{*}\left(t_{j}\right)\right|^{-2} d t_{j}} \\
& \lesssim\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\left(\int\left|K_{j}^{*}\left(u_{j}\right) \| f_{\varepsilon, j}^{*}\left(u_{j} / h_{j}\right)\right|^{-1} d u_{j}\right)^{2}}{\int\left|K_{j}^{*}\left(u_{j}\right)\right|^{2}\left|f_{\varepsilon, j}^{*}\left(u_{j} / h_{j}\right)\right|^{-2} d u_{j}}
\end{aligned}
$$

Consider now case 1. Under $\left(\mathbf{H}_{\varepsilon}\right)$, in the OS case, we get

$$
\begin{aligned}
\frac{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2}}{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}} & \lesssim\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\left(\int\left|K_{j}^{*}\left(u_{j}\right)\right|\left(1+\left(u_{j} / h_{j}\right)^{2}\right)^{\beta_{j} / 2} d u_{j}\right)^{2}}{\int\left|K_{j}^{*}\left(u_{j}\right)\right|^{2}\left(1+\left(u_{j} / h_{j}\right)^{2}\right)^{\beta_{j}} d u_{j}} \\
& \lesssim\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\left(\int\left|K_{j}^{*}\left(u_{j}\right)\right|\left(h_{j}^{2}+u_{j}^{2}\right)^{\beta_{j} / 2} d u_{j}\right)^{2}}{\int\left|K_{j}^{*}\left(u_{j}\right)\right|^{2}\left(h_{j}^{2}+u_{j}^{2}\right)^{\beta_{j}} d u_{j}} \\
& \lesssim\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\left(\int\left|K_{j}^{*}\left(u_{j}\right)\right|\left(1+u_{j}^{2}\right)^{\beta_{j} / 2} d u_{j}\right)^{2}}{\int\left|K_{j}^{*}\left(u_{j}\right)\right|^{2} u_{j}^{2 \beta_{j}} d u_{j}}:=C(\varepsilon, K) \prod_{j=1}^{d} \frac{1}{h_{j}} .
\end{aligned}
$$

because $0<h_{j} \leq 1$ and the assumptions make all integrals finite.
Consider case 2., where $K_{j}=$ sinc, and use the equivalence Lemma 1 . Then we get straightforwardly

$$
\frac{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{1}^{2}}{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}} \lesssim \prod_{j=1}^{d} h_{j}^{\rho_{j}-1}
$$

Therefore $\bar{h}_{\text {opt }}$ belongs to $\mathcal{H}_{0}$ if condition (16) is satisfied. Let us explain why constraint (16) is fulfilled in the two cases of Corollary 1.

First, in case 1., it follows from (5) that $\bar{h}_{j, \text { opt }}$ are such that

$$
\left(\prod_{i=1}^{d} 1 / \bar{h}_{i, o p t}\right) \leq\left(\prod_{i=1}^{d}\left(\bar{h}_{i, o p t}^{P}\right)^{-2 \beta_{i}-1}\right)\left(\prod_{i=1, i \neq j}^{d} \bar{h}_{j, o p t}^{-2 b_{i}}\right) \propto n / \log (n)
$$

for $j=1, \ldots, d$ which implies clearly that they satisfy the constraint $\prod_{j=1}^{d}\left(1 / h_{j}\right) \leq n / \log (n)$. This is the reason why (16) and thus (15) hold.

Second, in case 2., the general constraint is also satisfied by the optimal bandwidths because the negative powers on the $h_{j}$ 's get smaller when $\rho_{j}$ increases, and each time a $\rho_{j}$ is nonzero, it is associated to a logarithmic order for the $h_{j}$ 's. Condition (16) can also easily be checked for mixed cases. Therefore, $\bar{h}_{\text {opt }}$ also belongs to $\mathcal{H}_{0}$ and Corollary 1 is proved.
7.5. Proof of Proposition 3. In the first case, standard methods (see Tsybakov (2009) or Kerkyacharian et al. (2001)) yield

$$
\left\|f_{h}-f\right\| \leq C(K, d, b) L \sum_{j=1}^{d} h_{j}^{b_{j}}
$$

In the Sobolev case, Parseval formula gives $\left\|f_{h}-f\right\|^{2}=(2 \pi)^{-d}\left\|f_{h}^{*}-f^{*}\right\|^{2}$ and

$$
\begin{aligned}
\left\|f_{h}^{*}-f^{*}\right\|^{2}= & \int_{\left(\prod_{j=1}^{d}\left[-1 / h_{j}, 1 / h_{j}\right]\right)^{c}}\left|f^{*}(u)\right|^{2} d u \\
\leq & \sum_{j=1}^{d} \int\left(1+u_{j}^{2}\right)^{-b_{j}} \exp \left(-2 a_{j}\left|u_{j}\right|^{r_{j}}\right) \mathbb{1}_{\left|u_{j}\right| \geq 1 / h_{j}} \\
& \left|f^{*}\left(u_{1}, \ldots, u_{d}\right)\right|^{2}\left(1+u_{j}^{2}\right)^{b_{j}} \exp \left(2 a_{j}\left|u_{j}\right|^{r_{j}}\right) d u_{1} \ldots d u_{j} \\
\lesssim & L \sum_{j=1}^{d} h_{j}^{2 b_{j}} \exp \left(-2 a_{j} h_{j}^{-r_{j}}\right)
\end{aligned}
$$

7.6. Proof of Proposition 4. The first bound is obtained by writing

$$
\mathbb{E}\left\|\hat{f}_{h}-f_{h}\right\|^{2}=\frac{1}{(2 \pi)^{d}} \int \operatorname{Var}\left(\frac{K_{h}^{*} \widehat{f_{\varepsilon}^{*}}}{f_{\varepsilon}^{*}}\right) \leq \frac{1}{(2 \pi)^{d} n} \int\left|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}} e^{i\left\langle u, Y_{1}\right\rangle}\right|^{2}
$$

Now we use the bound on $\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|^{2}$ proved for Proposition 2:

$$
n V(h) \lesssim \prod_{j \in S S} h_{j}^{-2 \beta_{j}-1+\rho_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right) \prod_{j \in 0 S} h_{j}^{-1-2 \beta_{j}}=\prod_{j=1}^{d} h_{j}^{-2 \beta_{j}-1+\rho_{j}} \exp \left(2 \alpha_{j} h_{j}^{-\rho_{j}}\right)
$$

### 7.7. Proof of Theorem 2.

7.7.1. Proof of Theorem 2. The beginning of the proof is the same as the one of Theorem 1. Let $h \in \mathcal{H}$ be fixed. The following decomposition holds:

$$
\begin{equation*}
\|\check{f}-f\| \leq \underbrace{\left\|\hat{f}_{\hat{h}}-\hat{f}_{h, \hat{h}}\right\|}_{D_{3}}+\underbrace{\left\|\hat{f}_{h, \hat{h}}-\hat{f}_{h}\right\|}_{D_{4}}+\left\|\hat{f}_{h}-f\right\| . \tag{35}
\end{equation*}
$$

By definition of $A(h)$,

$$
D_{3} \leq A(h)+\sqrt{\tilde{V}(\hat{h})} .
$$

And by definition of $A(\hat{h})$,

$$
D_{4} \leq A(\hat{h})+\sqrt{\tilde{V}(h)} .
$$

Therefore

$$
\begin{equation*}
D_{3}+D_{4} \leq A(h)+\sqrt{\tilde{V}(\hat{h})}+A(\hat{h})+\sqrt{\tilde{V}(h)} \leq 2[A(h)+\sqrt{\tilde{V}(h)}] \tag{36}
\end{equation*}
$$

by using the definition of $\hat{h}$. To study $A(h)$, we can write

$$
\hat{f}_{h^{\prime}}-\hat{f}_{h, h^{\prime}}=\hat{f}_{h^{\prime}}-f_{h^{\prime}}-\left(\hat{f}_{h, h^{\prime}}-f_{h, h^{\prime}}\right)+f_{h^{\prime}}-f_{h, h^{\prime}}
$$

But

$$
\left\|f_{h^{\prime}}-f_{h, h^{\prime}}\right\|=\left\|K_{h^{\prime}} \star\left(f-K_{h} \star f\right)\right\| \leq\left\|K_{h^{\prime}}^{*}\right\|_{\infty}\left\|f-f \star K_{h}\right\|
$$

as $\|u \star v\| \leq\left\|u^{*}\right\|_{\infty}\|v\|$, for functions $u$ with Fourier transform and $v \in \mathbb{L}_{2}\left(\mathbb{R}^{d}\right)$. As $\left\|K_{h^{\prime}}^{*}\right\|_{\infty}=$ $\left\|K^{*}\right\|_{\infty}$, we get

$$
\left\|f_{h^{\prime}}-f_{h, h^{\prime}}\right\| \leq\left\|K^{*}\right\|_{\infty}\left\|f-f_{h}\right\|
$$

In the same way,

$$
\left\|\hat{f}_{h, h^{\prime}}-f_{h, h^{\prime}}\right\| \leq\left\|K^{*}\right\|_{\infty}\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\|
$$

Then

$$
\left\|\hat{f}_{h^{\prime}}-\hat{f}_{h, h^{\prime}}\right\| \leq\left(1+\left\|K^{*}\right\|_{\infty}\right)\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\|+\left\|K^{*}\right\|_{\infty}\left\|f-f_{h}\right\| .
$$

We get back to the definition of $A(h)$

$$
\begin{align*}
A(h) & =\sup _{h^{\prime} \in \mathcal{H}}\left[\left\|\hat{f}_{h^{\prime}}-\hat{f}_{h, h^{\prime}}\right\|-\sqrt{\tilde{V}\left(h^{\prime}\right)}\right]_{+} \\
& \leq\left(1+\left\|K^{*}\right\|_{\infty}\right) \sup _{h^{\prime} \in \mathcal{H}}\left[\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\|-\sqrt{\tilde{V}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right]_{+}+\left\|K^{*}\right\|_{\infty}\left\|f-f_{h}\right\| . \tag{37}
\end{align*}
$$

We can prove the following concentration result:
Proposition 7. [Variance concentration] Under the assumptions of Theorem 2, for all $h^{\prime}$ in $\mathcal{H}$,

$$
\mathbb{P}\left\{\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\| \geq \sqrt{\tilde{V}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right\} \leq \exp \left(-\frac{\min (\eta, 1) \eta}{46}(\log n)^{2}\right)
$$

This proposition is proved below.
Then, if we define

$$
\Omega=\left\{\forall h^{\prime} \in \mathcal{H} \quad\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\| \leq \sqrt{\tilde{V}\left(h^{\prime}\right)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right\}
$$

then $P\left(\Omega^{c}\right) \leq \sum_{h^{\prime} \in \mathcal{H}} e^{-\kappa(\log n)^{2}} \leq \operatorname{card}(\mathcal{H}) e^{-\kappa(\log n)^{2}}$ with $\kappa=\min (\eta, 1) \eta / 46$. Now, gathering the terms yields, on $\Omega, \forall h \in \mathcal{H}$,

$$
\begin{aligned}
\|\check{f}-f\| & \leq 2\left\|K^{*}\right\|_{\infty}\left\|f-f_{h}\right\|+2 \sqrt{\tilde{V}(h)}+\left\|\hat{f}_{h}-f\right\| \\
& \leq\left(1+2\left\|K^{*}\right\|_{\infty}\right)\left\|f-f_{h}\right\|+2 \sqrt{\tilde{V}(h)}+\left\|\hat{f}_{h}-f_{h}\right\|
\end{aligned}
$$

But, on $\Omega,\left\|\hat{f}_{h}-f_{h}\right\| \leq \sqrt{\tilde{V}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right) \leq \sqrt{\tilde{V}(h)}$. Thus, on $\Omega$,

$$
\|\check{f}-f\| \leq\left(1+2\left\|K^{*}\right\|_{\infty}\right)\left\|f-f_{h}\right\|+3 \sqrt{\tilde{V}(h)}
$$

which ends the proof of Theorem 2.
7.7.2. Proof of Proposition 7. Let $B(0,1)=\left\{t \in \mathbb{L}_{2}\left(\mathbb{R}^{d}\right) \cap \mathbb{L}_{1}\left(\mathbb{R}^{d}\right),\|t\|=1\right\}$. We can note that $\hat{f}_{h}$ and $f_{h}$ belong to $\mathbb{L}_{2}\left(\mathbb{R}^{d}\right) \cap \mathbb{L}_{1}\left(\mathbb{R}^{d}\right)$, and

$$
\left\|\hat{f}_{h}-f_{h}\right\|=\sup _{t \in B(0,1)}\left\langle\hat{f}_{h}-f_{h}, t\right\rangle=\sup _{t \in \bar{B}(0,1)}\left\langle\hat{f}_{h}-f_{h}, t\right\rangle
$$

where $\bar{B}(0,1)$ is a dense countable subset of $B(0,1)$ (thanks to the separability of $\mathbb{L}_{2}(\mathbb{R})^{d}$, such a set exists).

Now

$$
\left.\left.\left\langle\hat{f}_{h}-f_{h}, t\right\rangle=\frac{1}{n} \sum_{i=1}^{n} \right\rvert\, \psi_{t}\left(Y_{i}\right)-\mathbb{E}\left(\psi_{t}\left(Y_{i}\right)\right)\right]=: \nu_{n}(t)
$$

where

$$
\psi_{t}(y)=\frac{1}{(2 \pi)^{d}} \int e^{i\langle u, y\rangle} t^{*}(-u) \frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)} d u
$$

then $\nu_{n}(t)$ is an empirical process, such that $t \mapsto \nu_{n}(t)$ is continuous.
We can apply Talagrand Inequality recalled in Lemma 3. To this aim, we compute $H^{2}, M$ and $v$.

First

$$
\begin{aligned}
\mathbb{E}\left(\sup _{t \in \bar{B}(0,1)} \nu_{n}^{2}(t)\right) & =\mathbb{E}\left(\sup _{t \in \bar{B}(0,1)}\left\langle\hat{f}_{h}-f_{h}, t\right\rangle^{2}\right) \leq \mathbb{E}\left(\sup _{t \in \bar{B}(0,1)}\left\|\hat{f}_{h}-f_{h}\right\|^{2}\|t\|^{2}\right) \\
& \leq \mathbb{E}\left(\left\|\hat{f}_{h}-f_{h}\right\|^{2}\right) \leq V(h) \leq V(h) C(h)=: H^{2}
\end{aligned}
$$

Next,

$$
\begin{aligned}
\sup _{t \in \bar{B}(0,1)}\left\|\psi_{t}\right\|_{\infty} & =\sup _{t \in \bar{B}(0,1)} \sup _{y \in \mathbb{R}^{d}}\left|\frac{1}{(2 \pi)^{d}} \int e^{i\langle u, y\rangle} t^{*}(-u) \frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)} d u\right| \\
& \leq \sup _{t \in \bar{B}(0,1)} \frac{1}{(2 \pi)^{d}}\left(\left\|t^{*}\right\|^{2} \int\left|\frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)}\right|^{2} d u\right)^{1 / 2} \leq \sqrt{n V(h)}=: M
\end{aligned}
$$

Last,

$$
\begin{aligned}
\sup _{t \in \bar{B}(0,1)} \operatorname{Var}\left(\psi_{t}\left(Y_{1}\right)\right) & \leq \sup _{t \in \bar{B}(0,1)} \mathbb{E}\left|\frac{1}{(2 \pi)^{d}} \int e^{i\left\langle u, Y_{1}\right\rangle} t^{*}(u) \frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)} d u\right|^{2} \\
& \leq \sup _{t \in \bar{B}(0,1)} \frac{1}{(2 \pi)^{2 d}} \iint t^{*}(u) t^{*}(-v) \frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)} \frac{K_{h}^{*}(-v)}{f_{\varepsilon}^{*}(-v)} f_{Y_{1}}^{*}(u-v) d u d v
\end{aligned}
$$

Clearly we can get first $\sup _{t \in \bar{B}(0,1)} \operatorname{Var}\left(\psi_{t}\left(Y_{1}\right)\right) \leq n V(h)$. But we can also apply Cauchy-Schwarz Inequality with respect to the measure $\left|f_{Y_{1}}^{*}(u-v)\right| d u d v$ and we obtain thus

$$
\begin{aligned}
\sup _{t \in \bar{B}(0,1)} \operatorname{Var}\left(\psi_{t}\left(Y_{1}\right)\right) & \leq \sup _{t \in \bar{B}(0,1)} \frac{1}{(2 \pi)^{2 d}} \iint\left|t^{*}(u)\right|^{2}\left|\frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)}\right|^{2}\left|f_{Y_{1}}^{*}(u-v)\right| d u d v \\
& \leq \frac{1}{(2 \pi)^{2 d}} \sup _{u \in \mathbb{R}^{d}}\left|\frac{K_{h}^{*}(u)}{f_{\varepsilon}^{*}(u)}\right|^{2} \sup _{t \in \bar{B}(0,1)}\left\|t^{*}\right\|^{2} \int\left|f_{Y_{1}}(z)\right| d z \\
& \leq \frac{1}{(2 \pi)^{d}}\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{\infty}^{2}
\end{aligned}
$$

Therefore,

$$
v:=\frac{1}{(2 \pi)^{d}} \min \left(\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{\infty}^{2},\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|^{2}\right)
$$

Inequality (25) gives

$$
P\left(\sup _{t \in \bar{B}}\left|\nu_{n}(t)\right| \geq(1+2 \eta) H\right) \leq \max \left(\exp \left(-\frac{\eta^{2}}{6} \frac{n H^{2}}{v}\right), \exp \left(-\frac{\min (\eta, 1) \eta}{21} \sqrt{n}\right)\right)
$$

Now, it is sufficient to use assumption (18) to obtain $n H^{2} / v \geq(\log n)^{2}$. Moreover $(1+2 \eta) H=$ $\sqrt{\tilde{V}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)$. Then

$$
\begin{aligned}
P\left(\sup _{t \in \bar{B}}\left|\nu_{n}(t)\right| \geq \sqrt{\tilde{V}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right) & \leq \max \left(\exp \left(-\frac{\eta^{2}}{6}(\log n)^{2}\right), \exp \left(-\frac{\min (\eta, 1) \eta}{21} \sqrt{n}\right)\right) \\
& \leq \exp \left(-\frac{\min (\eta, 1) \eta}{46}(\log n)^{2}\right)
\end{aligned}
$$

7.8. Proof of Corollary 2 and Corollary 3. We proceed as in the proof of Corollary 1 and we get

$$
\begin{aligned}
\frac{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}}{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{\infty}^{2}} & \approx \prod_{j=1}^{d} \frac{\int\left|K_{j}^{*}\left(t_{j} h_{j}\right)\right|^{2}\left|f_{\varepsilon, j}^{*}\left(t_{j}\right)\right|^{-2} d t_{j}}{\sup _{t_{j} \in \mathbb{R}}\left|K_{j}^{*}\left(t_{j} h_{j}\right)\right|^{2}\left|f_{\varepsilon, j}^{*}\left(t_{j}\right)\right|^{-2}} \\
& \approx\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\int\left|K_{j}^{*}\left(u_{j}\right)\right|^{2}\left|f_{\varepsilon, j}^{*}\left(u_{j} / h_{j}\right)\right|^{-2} d u_{j}}{\sup _{u_{j} \in \mathbb{R}}\left|K_{j}^{*}\left(u_{j}\right)\right|^{2}\left|f_{\varepsilon, j}^{*}\left(u_{j} / h_{j}\right)\right|^{-2}} .
\end{aligned}
$$

To prove Corollary 2, consider case 1. Under $\left(\mathbf{H}_{\varepsilon}\right)$, in the OS case, we get

$$
\begin{aligned}
\frac{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}}{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{\infty}^{2}} & \approx\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\int\left|K_{j}^{*}\left(u_{j}\right)\right|\left(h_{j}^{2}+u_{j}^{2}\right)^{\beta_{j}} d u_{j}}{\sup _{u_{j} \in \mathbb{R}}\left|K_{j}^{*}\left(u_{j}\right)\right|^{2}\left(h_{j}^{2}+u_{j}^{2}\right)^{\beta_{j}}} \\
& \approx\left(\prod_{j=1}^{d} \frac{1}{h_{j}}\right) \prod_{j=1}^{d} \frac{\int\left|K_{j}^{*}\left(u_{j}\right)\right|\left(1+u_{j}^{2}\right)^{\beta_{j}} d u_{j}}{\sup _{u_{j} \in \mathbb{R}}\left|K_{j}^{*}\left(u_{j}\right)\right|^{2} u_{j}^{2 \beta_{j}}}:=C(\varepsilon, K) \prod_{j=1}^{d} \frac{1}{h_{j}}
\end{aligned}
$$

because $0<h_{j}<1$ and the assumptions make all terms finite.
The result of Corollary 3 is obvious. Indeed, the choice $C(h)=\log ^{2}(n)$ ensures that condition (18) is fulfilled and thus $\check{h}_{\text {opt }} \in \mathcal{H}$.

To understand why it can not be improved, consider case 2. (in the general terminology of Corollary 1), where $K_{j}=\operatorname{sinc}$, and use the equivalence Lemma 1. Then we get straightforwardly

$$
\begin{equation*}
\max \left(1, \frac{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{2}^{2}}{\left\|K_{h}^{*} / f_{\varepsilon}^{*}\right\|_{\infty}^{2}}\right) \approx \prod_{j=1}^{d} h_{j}^{-\left(1-\rho_{j}\right)_{+}} \tag{38}
\end{equation*}
$$

Then we obtain the same order as in case 1. above if the $\rho_{j}$ 's are all zero, thus the same conclusion holds for $K$ taken as sinc and $f$ ordinary smooth.

It also follows from (38) that condition (18) in the definition of $\mathcal{H}$ is equivalent to

$$
\begin{equation*}
\prod_{j=1}^{d} h_{j}^{-\left(1-\rho_{j}\right)_{+}} C(h) \gtrsim \log ^{2}(n) \tag{39}
\end{equation*}
$$

In the case of ordinary smooth $f_{\varepsilon}^{*}$, consider the case where the function $f$ is super smooth. Then the condition (39) can be written $\prod_{j}\left(1 / h_{j}\right) C\left(h \gtrsim \log ^{2}(n)\right.$. This is not necessarily satisfied by the optimal bandwidths which have logarithmic orders, if we only set $C(h)=1$. But as the powers of $\log (n)$ involved in $\check{h}_{\text {opt }}$ depend on the regularity of $f$, which is unknown, the quantity missing to reach $\log ^{2}(n)$ is unknown. In the case of super smooth $f_{\varepsilon}^{*}$, it is clear that if all $\rho_{j}$ 's are larger than one, $C(h)=\log ^{2}(n)$ is the only possible choice for condition (39) to be fulfilled.
7.9. Proof of Theorem 3. The proof starts like the proof of Theorem 2 but we replace Proposition 7 by a bound in expectation obtained in an analogous way, but by using equation (26) instead of equation (25). As all bounds $M, v, H$ have been computed in the proof of Proposition 7 , we easily obtain that

$$
\mathbb{E}\left(\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\|-\sqrt{\tilde{V}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right)_{+} \leq C\left(\sqrt{\frac{v}{n}} e^{-\frac{\eta^{2}}{6} n \frac{\tilde{\frac{\tilde{C}}{}(h)}}{v}}+\sqrt{\frac{V(h)}{n}} e^{-\frac{(\eta \wedge 1) \eta}{21} \sqrt{n}}\right)
$$

To obtain the result, we need to prove that, in case 2. of the above terminology and with our new definition of $\mathcal{H}$, we have

$$
\sum_{h \in \mathcal{H}} \sqrt{v} e^{-\frac{\eta^{2}}{6} n \frac{\tilde{V}(h)}{v}}<+\infty
$$

Now we use the previous evaluations and in particular (38). We write $C(h)=\sum_{j=1}^{d} C_{j}\left(k_{j}\right)$. The following inequalities hold.

$$
\begin{aligned}
\sum_{h \in \mathcal{H}} \sqrt{v} e^{-\frac{\eta^{2}}{6} n \frac{\tilde{V}(h)}{v}} & \lesssim \sum_{1 \leq k_{1}, \ldots, k_{d} \leq M}\left(\prod_{j=1}^{d} k_{j}^{\beta_{j}-\left(\rho_{j}-1\right)_{+} / 2} e^{\alpha_{j} k_{j}^{\rho_{j}}}\right) e^{-\kappa \sum_{j=1}^{d} C_{j}\left(k_{j}\right) \prod_{j=1}^{d} k_{j}^{\left(1-\rho_{j}\right)+}} \\
& \lesssim \sum_{1 \leq k_{1}, \ldots, k_{d} \leq M}\left(\prod_{j=1}^{d} k_{j}^{\beta_{j}-\left(\rho_{j}-1\right)_{+} / 2} e^{\alpha_{j} k_{j}^{\rho_{j}}}\right) e^{-\kappa \sum_{j=1}^{d} C_{j}\left(k_{j}\right) k_{j}^{\left(1-\rho_{j}\right)+}} \\
& \lesssim \prod_{j=1}^{d}\left(\sum_{1 \leq k \leq M} k^{\beta_{j}-\left(\rho_{j}-1\right)_{+} / 2} e^{\left.\alpha_{j} k^{\rho_{j}-\kappa C_{j}(k) k^{\left(1-\rho_{j}\right)_{+}}}\right):=\Sigma,} .\right.
\end{aligned}
$$

where $\kappa$ can be specified in function of $\eta^{2} / 6$ and the constants involved in Lemma 1. This explains why we choose $C_{j}(k)=1$ if $0 \leq \rho_{j}<1 / 2$ which corresponds to the case where $k^{\rho_{j}}<k^{\left(1-\rho_{j}\right)+}=$ $k^{1-\rho_{j}}$. We choose $C_{j}(k)=\left(2 \alpha_{j} / \kappa\right) k^{2 \rho_{j}-1}$ if $1 / 2 \leq \rho_{j}<1$ because then $\alpha_{j} k^{\rho_{j}}-\kappa C_{j}(k) k^{\left(1-\rho_{j}\right)_{+}}=$ $-\alpha_{j} k^{\rho_{j}}$. In the same way, we take $C_{j}(k)=\left(2 \alpha_{j} / \kappa\right) k^{\rho_{j}}$ if $\rho_{j}>1$. Then the sums over $k$ are bounded and $\Sigma<+\infty$. These values give formula (24) which is overestimated by the proposal (22) in order to avoid the specification of tedious constants.

Thus, we have

$$
\sum_{h^{\prime} \in \mathcal{H}_{M}} \mathbb{E}\left(\left\|\hat{f}_{h^{\prime}}-f_{h^{\prime}}\right\|-\sqrt{\tilde{V}(h)} /\left(1+\left\|K^{*}\right\|_{\infty}\right)\right)_{+} \leq C\left(\frac{\Sigma}{\sqrt{n}}+\operatorname{card}\left(\mathcal{H}_{M}\right) e^{-\frac{(\eta \wedge 1) \eta}{21} \sqrt{n}}\right) \leq \frac{C^{\prime}}{\sqrt{n}}
$$

since $\operatorname{card}\left(\mathcal{H}_{M}\right) \leq n^{d}$.
Therefore, it follows from (37) that, as $\left\|K^{*}\right\|_{\infty}=1$ for $K=$ sinc, then

$$
\mathbb{E}(A(h)) \leq \frac{2 C^{\prime}}{\sqrt{n}}+2\left\|f-f_{h}\right\|
$$

and inserting this in (35) and (36) yields

$$
\mathbb{E}(\|\check{f}-f\|) \leq 3\left\|f-f_{h}\right\|+3 \sqrt{\tilde{V}(h)}+\frac{2 C^{\prime}}{\sqrt{n}},
$$

which is (23). This ends the proof of Theorem 3.
7.10. Proof of Proposition 5. First, note that Neumann's Lemma 2.1 (see Neumann (1997), and in particular the proof of the Lemma 2.1 page 323) can be straightforwardly extended to the multivariate setting. Define

$$
R(t)=\frac{1}{\tilde{f}_{\varepsilon}^{*}(t)}-\frac{1}{f_{\varepsilon}^{*}(t)} .
$$

The result can be written

$$
\mathbb{E}\left(|R(t)|^{2}\right) \leq C\left(\frac{1}{\left|f_{\varepsilon}^{*}(t)\right|^{2}} \wedge \frac{N^{-1}}{\left|f_{\varepsilon}^{*}(t)\right|^{4}}\right) .
$$

Then the following decomposition holds:

$$
\left\|f_{h}-\bar{f}_{h}\right\|=\frac{1}{(2 \pi)^{d / 2}}\left\|K_{h}^{*}\left[\frac{\widehat{f_{Y}^{*}}-f_{Y}^{*}}{f_{\varepsilon}^{*}}+\left(\widehat{f_{Y}^{*}}-f_{Y}^{*}\right) R+f_{Y}^{*} R\right]\right\|
$$

and thus

$$
\begin{aligned}
\mathbb{E}\left(\left\|f_{h}-\bar{f}_{h}\right\|^{2}\right) & \lesssim \int\left|K_{h}^{*}(t)\right|^{2} \frac{\mathbb{E}\left[\left|f_{Y}(t)-\widehat{f_{Y}^{*}}(t)\right|^{2}\right]}{\left|f_{\varepsilon}^{*}(t)\right|^{2}} d t \\
+ & \int\left|K_{h}^{*}(t)\right|^{2} \mathbb{E}\left[\left|f_{Y}(t)-\widehat{f_{Y}^{*}}(t)\right|^{2}\right] \mathbb{E}\left(|R(t)|^{2}\right) d t+\int\left|K_{h}^{*}(t)\right|^{2}\left|f_{Y}^{*}(t)\right|^{2} \mathbb{E}\left[|R(t)|^{2}\right] d t \\
& \lesssim \frac{1}{n}\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|^{2}+\frac{1}{n}\left\|\frac{K_{h}^{*}}{f_{\varepsilon}^{*}}\right\|^{2}+N^{-1}\left\|\frac{K_{h}^{*} f^{*}}{f_{\varepsilon}^{*}}\right\|^{2}
\end{aligned}
$$

where the second term is obtained by bounding $R(t)$ by $1 /\left|f_{\varepsilon}^{*}(t)\right|^{2}$ and the last one uses the second bound of $R(t)$ and the fact that $f_{Y}^{*}=f^{*} f_{\varepsilon}^{*}$. The first two terms are $V(h)$ and the last one is $W(h)$. Thus, we obtain $\mathbb{E}\left(\left\|f_{h}-\bar{f}_{h}\right\|^{2}\right) \lesssim V(h)+W(h)$.

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