# Dynnikov coordinates on virtual braid groups 

Valerij G. Bardakov, Andrei Vesnin, Bert Wiest

## To cite this version:

Valerij G. Bardakov, Andrei Vesnin, Bert Wiest. Dynnikov coordinates on virtual braid groups. Journal of Knot Theory and Its Ramifications, 2012, 21 (5), 10.1142/S021821651101005X . hal00577935v2

## HAL Id: hal-00577935 <br> https://hal.science/hal-00577935v2

Submitted on 22 Jul 2011

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# DYNNIKOV COORDINATES ON VIRTUAL BRAID GROUPS 

VALERIY G. BARDAKOV and ANDREI YU. VESNIN<br>Sobolev Institute of Mathematics<br>pr. Koptyuga 4<br>630090, Novosibirsk, Russia<br>bardakov@math.nsc.ru, vesnin@math.nsc.ru

BERT WIEST
IRMAR, Université de Rennes 1,
Campus de Beaulieu
35042 Rennes Cedex, France
bertold.wiest@univ-rennes1.fr


#### Abstract

We define Dynnikov coordinates on virtual braid groups. We prove that they are faithful invariants of virtual 2-braids, and present evidence that they are also very powerful invariants for general virtual braids.

Keywords: braid; virtual braid; Dynnikov coordinates; faithful invariants Mathematics Subject Classification 2010: 20F36, 57M25


## 1. Virtual braid groups

The group of virtual braids $V B_{n}, n \geqslant 2$, on $n$ strings was introduced by Kauffman [4] as a generalization of the classical braid group $B_{n}$. The most useful system of generators and defining relations of $V B_{n}$ was introduced by Vershinin in [6]. The generators of $V B_{n}$ are

$$
\begin{equation*}
\sigma_{1}, \ldots, \sigma_{n-1}, \rho_{1}, \ldots, \rho_{n-1} \tag{1.1}
\end{equation*}
$$

and the defining relations are the following:

$$
\begin{gather*}
\sigma_{i} \sigma_{i+1} \sigma_{i}=\sigma_{i+1} \sigma_{i} \sigma_{i+1}, \quad \sigma_{i} \sigma_{j}=\sigma_{j} \sigma_{i} \quad \text { if }|i-j|>1,  \tag{1.2}\\
\rho_{i}^{2}=1, i=1, \ldots, n-1, \quad \rho_{i} \rho_{i+1} \rho_{i}=\rho_{i+1} \rho_{i} \rho_{i+1}, \quad \rho_{i} \rho_{j}=\rho_{j} \rho_{i} \text { if }|i-j|>1, \tag{1.3}
\end{gather*}
$$

$$
\begin{equation*}
\sigma_{i} \rho_{j}=\rho_{j} \sigma_{i} \quad \text { if } \quad|i-j|>1, \quad \rho_{i} \rho_{i+1} \sigma_{i}=\sigma_{i+1} \rho_{i} \rho_{i+1} \tag{1.4}
\end{equation*}
$$

Thus, the group generated by $\sigma_{1}, \ldots, \sigma_{n-1}$ with relations (1.2) is the braid group $B_{n}$; the group generated by $\rho_{1}, \ldots, \rho_{n-1}$ with relations (1.3) is the symmetric
group $S_{n}$; the relations (1.4) will be referred to as mixed relations. The last presented relation is equivalent to

$$
\begin{equation*}
\rho_{i+1} \rho_{i} \sigma_{i+1}=\sigma_{i} \rho_{i+1} \rho_{i} . \tag{1.5}
\end{equation*}
$$

We remark that the relations

$$
\begin{equation*}
\rho_{i} \sigma_{i+1} \sigma_{i}=\sigma_{i+1} \sigma_{i} \rho_{i+1}, \quad \rho_{i+1} \sigma_{i} \sigma_{i+1}=\sigma_{i+1} \sigma_{i} \rho_{i} \tag{1.6}
\end{equation*}
$$

do not hold in $V B_{n}$, and these relations will be referred to as forbidden relations. (Adding these forbidden relations yields the so-called braid permutation group [3]).

There is a natural epimorphism $\pi: V B_{n} \rightarrow S_{n}$ defined by

$$
\pi\left(\sigma_{i}\right)=\pi\left(\rho_{i}\right)=\rho_{i}, \quad i=1, \ldots, n-1
$$

The kernel $\operatorname{ker}(\pi)$ is called the virtual pure braid group and is denoted by $V P_{n}$. Generators and relations for $V P_{n}$ are described in [1]. It is easy to see that $V B_{n}$ is a semidirect product: $V B_{n}=V P_{n} \rtimes S_{n}$.

## 2. Coordinates on braid groups

In [2, Ch. 8] , an action of the braid group $B_{n}$ on the integer lattice $\mathbb{Z}^{2 n}$ by piecewiselinear bijections is defined. For the reader's convenience we recall the definition. For $x \in \mathbb{Z}$ denote $x^{+}=\max \{0, x\}$ and $x^{-}=\min \{x, 0\}$. Define actions

$$
\sigma, \sigma^{-1}: \mathbb{Z}^{4} \rightarrow \mathbb{Z}^{4}
$$

on $(a, b, c, d) \in \mathbb{Z}^{4}$ as follows:

$$
\begin{gather*}
(a, b, c, d) \cdot \sigma=\left(a+b^{+}+\left(d^{+}-e\right)^{+}, d-e^{+}, c+d^{-}+\left(b^{-}+e\right)^{-}, b+e^{+}\right)  \tag{2.1}\\
(a, b, c, d) \cdot \sigma^{-1}=\left(a-b^{+}-\left(d^{+}+f\right)^{+}, d+f^{-}, c-d^{-}-\left(b^{-}-f\right)^{-}, b-f^{-}\right) \tag{2.2}
\end{gather*}
$$

where

$$
\begin{equation*}
e=a-b^{-}-c+d^{+}, \quad f=a+b^{-}-c-d^{+} \tag{2.3}
\end{equation*}
$$

For a given vector $\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \in \mathbb{Z}^{2 n}$ we define the action by $\sigma_{i}^{\varepsilon} \in B_{n}$, where $i=1, \ldots, n-1$ :

$$
\begin{equation*}
\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot \sigma_{i}^{\varepsilon}=\left(a_{1}^{\prime}, b_{1}^{\prime}, \ldots, a_{n}^{\prime}, b_{n}^{\prime}\right) \tag{2.4}
\end{equation*}
$$

where $a_{k}^{\prime}=a_{k}, b_{k}^{\prime}=b_{k}$ if $k \neq i, i+1$, and

$$
\left(a_{i}^{\prime}, b_{i}^{\prime}, a_{i+1}^{\prime}, b_{i+1}^{\prime}\right)= \begin{cases}\left(a_{i}, b_{i}, a_{i+1}, b_{i+1}\right) \cdot \sigma, & \text { if } \varepsilon=1  \tag{2.5}\\ \left(a_{i}, b_{i}, a_{i+1}, b_{i+1}\right) \cdot \sigma^{-1}, & \text { if } \varepsilon=-1\end{cases}
$$

For a word $w$ in the alphabet $\left\{\sigma_{1}^{ \pm 1}, \ldots, \sigma_{n-1}^{ \pm 1}\right\}$ we define an action by $w$ :

$$
\left(a_{1}, b_{1}, \ldots a_{n}, b_{n}\right) \cdot w= \begin{cases}\left(a_{1}, b_{1}, \ldots a_{n}, b_{n}\right), & \text { if } w=1  \tag{2.6}\\ \left(\left(a_{1}, b_{1}, \ldots a_{n}, b_{n}\right) \cdot \sigma_{i}^{\varepsilon}\right) \cdot w^{\prime}, & \text { if } w=\sigma_{i}^{\varepsilon} w^{\prime}\end{cases}
$$

It can be shown that the above action by $B_{n}$ on $\mathbb{Z}^{2 n}$ is well defined, i.e. if two words $w_{1}$ and $w_{2}$ present the same element of the braid group $B_{n}$ then

$$
\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot w_{1}=\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot w_{2}
$$

for any vector $\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \in \mathbb{Z}^{2 n}$. By the Dynnikov coordinates of a braid we will mean the vector $(0,1, \ldots, 0,1) \cdot w$, where $w$ is a word representing that braid.

Example 2.1. Actions by some elements of $B_{2}$ on $(0,1,0,1) \in \mathbb{Z}^{2}$ are as follows:
$(0,1,0,1) \cdot \sigma_{1}=(1,0,0,2)$,
$(0,1,0,1) \cdot \sigma_{1}^{-1}=(-1,0,0,2)$,
$(0,1,0,1) \cdot \sigma_{1}^{2}=(1,-1,0,3)$,
$(0,1,0,1) \cdot \sigma_{1}^{-2}=(-1,-1,0,3)$,
$\vdots$ !
$(0,1,0,1) \cdot \sigma_{1}^{k}=(1,-k+1,0, k+1)$,
$(0,1,0,1) \cdot \sigma_{1}^{-k}=(-1,-k+1,0, k+1)$,
where $k \in \mathbb{N}$. Also, acting by some elements of $B_{3}$ on $(0,1,0,1,0,1) \in \mathbb{Z}^{6}$ we have

$$
\begin{aligned}
& (0,1,0,1,0,1) \cdot \sigma_{1} \sigma_{2}^{-1}=(1,0,-2,0,0,3) \\
& (0,1,0,1,0,1) \cdot \sigma_{1} \sigma_{2} \sigma_{1}=(2,0,1,0,0,3)
\end{aligned}
$$

Remark 2.2. It is also shown in [2] that Dynnikov coordinates are faithful invariants of braids, i.e. if $(0,1, \ldots, 0,1) \cdot w_{1}=(0,1, \ldots, 0,1) \cdot w_{2}$ then $w_{1}=w_{2}$ in $B_{n}$; thus, Dynnikov coordinates are very useful for solving the words problem in $B_{n}$.

Here is an outline of the proof: there is a bijection between vectors in $\mathbb{Z}^{2 n}$ and integer laminations of a sphere with $n+3$ punctures $P_{0}, P_{1}, \ldots, P_{n+1}, P_{\infty}$; under this bijection, our action of $B_{n}$ on $\mathbb{Z}^{2 n}$ corresponds to the $B_{n}$-action on a disk containing punctures $P_{1}, \ldots, P_{n}$. The key observation is that this disk is filled by the lamination encoded by the vector $(0,1, \ldots, 0,1)$ (i.e. cutting this disk along its intersection with the lamination yields only disks and once-punctured disks).

## 3. Coordinates on virtual braid groups

Let us define an action by elements of $V B_{n}$ on $\mathbb{Z}^{2 n}$. Consider the actions on $\mathbb{Z}^{4}$ by $\sigma$ and $\sigma^{-1}$ as defined in (2.1) and (2.2), and define the action by $\rho$ as the following permutation of coordinates:

$$
\begin{equation*}
(a, b, c, d) \cdot \rho=(c, d, a, b) \tag{3.1}
\end{equation*}
$$

For a given vector $\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \in \mathbb{Z}^{2 n}$ we define the action by $\rho_{i} \in V B_{n}$, $i=1, \ldots, n-1$ :

$$
\begin{equation*}
\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot \rho_{i}=\left(a_{1}^{\prime}, b_{1}^{\prime}, \ldots, a_{n}^{\prime}, b_{n}^{\prime}\right), \tag{3.2}
\end{equation*}
$$

where $a_{k}^{\prime}=a_{k}, b_{k}^{\prime}=b_{k}$ for $k \neq i, i+1$, and

$$
\begin{equation*}
\left(a_{i}^{\prime}, b_{i}^{\prime}, a_{i+1}^{\prime}, b_{i+1}^{\prime}\right)=\left(a_{i}, b_{i}, a_{i+1}, b_{i+1}\right) \cdot \rho \tag{3.3}
\end{equation*}
$$

The action by $\sigma_{i}^{\varepsilon} \in V B_{n}$ on $\mathbb{Z}^{2 n}$ is defined according to (2.4) and (2.5).

Suppose that $w$ is a word in the alphabet $\left\{\sigma_{1}^{ \pm 1}, \ldots, \sigma_{n-1}^{ \pm 1}, \rho_{1}, \ldots, \rho_{n-1}\right\}$ representing an element of the group $V B_{n}$. Then we define

$$
\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot w=\left\{\begin{array}{l}
\left(\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot \rho_{i}\right) \cdot w^{\prime}, \text { if } w=\rho_{i} w^{\prime}  \tag{3.4}\\
\left(\left(a_{1}, b_{1}, \ldots, a_{n}, b_{n}\right) \cdot \sigma_{i}^{\varepsilon}\right) \cdot w^{\prime}, \text { if } w=\sigma_{i}^{\varepsilon} w^{\prime}
\end{array}\right.
$$

To show that the action by $V B_{n}$ on $\mathbb{Z}^{2 n}$ is correctly defined we will verify that the defining relations of the group $V B_{n}$ are satisfied. Since $\rho_{i}$ acts by permuting pairs of coordinates, the relations of the group $S_{n}$ are obviously satisfied. The fact that relations of the group $B_{n}$ are satisfied follows from [2]. So, we need to check only the case of mixed relations, i.e. that for any $v \in \mathbb{Z}^{2 n}$ the relations

$$
\begin{gather*}
v \cdot\left(\sigma_{i} \rho_{j}\right)=v \cdot\left(\rho_{j} \sigma_{i}\right), \quad|i-j|>1  \tag{3.5}\\
v \cdot\left(\rho_{i} \rho_{i+1} \sigma_{i}\right)=v \cdot\left(\sigma_{i+1} \rho_{i} \rho_{i+1}\right) \tag{3.6}
\end{gather*}
$$

hold. Relations (3.5) hold obiously, because $\sigma_{i}$ acts non-trivial only on the subvector $\left(a_{i}, b_{i}, a_{i+1}, b_{i+1}\right)$ and $\rho_{j}$ acts non-trivially only on the subvector $\left(a_{j}, b_{j}, a_{j+1}, b_{j+1}\right)$. In order to verify (3.6) it is enough to consider the case $i=1$ in the group $V B_{3}$. Denote

$$
(x, y, z, t) \cdot \sigma=\left(a^{\prime}(x, y, z, t), b^{\prime}(x, y, z, t), c^{\prime}(x, y, z, t), d^{\prime}(x, y, z, t)\right)
$$

From

$$
\begin{aligned}
& \left(a_{1}, b_{1}, a_{2}, b_{2}, a_{3}, b_{3}\right) \cdot\left(\rho_{1} \rho_{2} \sigma_{1}\right)=\left(a_{2}, b_{2}, a_{1}, b_{1}, a_{3}, b_{3}\right) \cdot\left(\rho_{2} \sigma_{1}\right) \\
& \quad=\left(a_{2}, b_{2}, a_{3}, b_{3}, a_{1}, b_{1}\right) \cdot \sigma_{1}=\left(\left(a_{2}, b_{2}, a_{3}, b_{3}\right) \cdot \sigma, a_{1}, b_{1}\right)
\end{aligned}
$$

and

$$
\begin{gathered}
\left(a_{1}, b_{1}, a_{2}, b_{2}, a_{3}, b_{3}\right) \cdot\left(\sigma_{2} \rho_{1} \rho_{2}\right)=\left(a_{1}, b_{1},\left(a_{2}, b_{2}, a_{3}, b_{3}\right) \cdot \sigma\right) \cdot \rho_{1} \rho_{2} \\
=\left(a^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), b^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), a_{1}, b_{1}, c^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), d^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right)\right) \cdot \rho_{2} \\
=\left(a^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), b^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), c^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), d^{\prime}\left(a_{2}, b_{2}, a_{3}, b_{3}\right), a_{1}, b_{1}\right) \\
=\left(\left(a_{2}, b_{2}, a_{3}, b_{3}\right) \cdot \sigma, a_{1}, b_{1}\right)
\end{gathered}
$$

we see that (3.6) holds.
Example 3.1. Actions by some elements of $V B_{2}$ on $(0,1,0,1) \in \mathbb{Z}^{4}$ are as follows:

$$
\begin{aligned}
& (0,1,0,1) \cdot \sigma_{1} \rho_{1}=(0,2,1,0) \\
& (0,1,0,1) \cdot \sigma_{1} \rho_{1} \sigma_{1}=(3,0,0,2) \\
& (0,1,0,1) \cdot \sigma_{1} \rho_{1} \sigma_{1}^{-1}=(-2,-1,1,3) .
\end{aligned}
$$

Let us demonstrate that the forbidden relations are not satisfied. More exactly, we show that for $v=(0,1,0,1,0,1)$ we get

$$
\begin{align*}
& v \cdot\left(\rho_{1} \sigma_{2} \sigma_{1}\right) \neq v \cdot\left(\sigma_{2} \sigma_{1} \rho_{2}\right),  \tag{3.7}\\
& v \cdot\left(\rho_{2} \sigma_{1} \sigma_{2}\right) \neq v \cdot\left(\sigma_{1} \sigma_{2} \rho_{1}\right) . \tag{3.8}
\end{align*}
$$

Indeed, (3.7) holds because

$$
(0,1,0,1,0,1) \cdot\left(\rho_{1} \sigma_{2} \sigma_{1}\right)=(0,1,0,1,0,1) \cdot \sigma_{2} \sigma_{1}=(0,1,1,0,0,2) \cdot \sigma_{1}=(2,0,0,1,0,2)
$$

but

$$
(0,1,0,1,0,1) \cdot\left(\sigma_{2} \sigma_{1} \rho_{2}\right)=(2,0,0,1,0,2) \cdot \rho_{2}=(2,0,0,2,0,1)
$$

Analogously, (3.8) holds because
$(0,1,0,1,0,1) \cdot\left(\rho_{2} \sigma_{1} \sigma_{2}\right)=(0,1,0,1,0,1) \cdot \sigma_{1} \sigma_{2}=(1,0,0,2,0,1) \cdot \sigma_{2}=(1,0,2,0,0,3)$, but

$$
(0,1,0,1,0,1) \cdot\left(\sigma_{1} \sigma_{2} \rho_{1}\right)=(1,0,2,0,0,3) \cdot \rho_{1}=(2,0,1,0,0,3)
$$

Question 3.2. Is there any relation between our coordinates on $V B_{n}$ and the invariant of virtual braids defined by Manturov in [5]?

## 4. Faithfulness of the $V B_{n}$-action on $\mathbb{Z}^{2 n}$

In this section we will be concerned with the following
Question 4.1. Is the $V B_{n}$-action on $\mathbb{Z}^{2 n}$ faithful? In other words, is it true that only the trivial element of $V B_{n}$ acts as the identity on $\mathbb{Z}^{2 n}$ ?

In computer experiments, we have tested several billion $\left(10^{9}\right)$ random virtual braids with 3,4 and 5 strands, but failed to find one that would provide a negative answer. The programs used for these tests (written in Scilab) can be obtained from B. Wiest's web page [7].

It should be stressed that nontrivial elements of $V B_{n}$ may very well act trivially on individual vectors. Let us, for instance, look at the $V B_{3}$-action on $(0,1,0,1,0,1)$. The actions of $\rho_{1}$ and $\rho_{2}$ obviously fix this vector, but those of many other braids do, too. Here is one particularly striking example:

Example 4.2. The virtual 3 strand braid

$$
\beta=\sigma_{1} \rho_{2} \sigma_{1} \sigma_{2}^{-1} \sigma_{1} \sigma_{2} \sigma_{1}^{-1} \rho_{1} \sigma_{2} \rho_{1} \sigma_{1} \rho_{2} \sigma_{1}^{-1} \rho_{2} \sigma_{2}^{-1} \sigma_{1}^{-1} \sigma_{2} \sigma_{1}^{-1} \rho_{2} \sigma_{1}^{-1}
$$

acts trivially on the vector $(0,1,0,1,0,1)$, and indeed in computer experiments, we found that it acted nontrivially on only about $0.25 \%$ of randomly generated vectors of $\mathbb{Z}^{6}$ with integer coefficients between -100 and 100 . In this sense, $\beta$ is "nearly a negative answer" to Question 4.1. Another one is the virtual braid $\sigma_{2}^{-1} \sigma_{1} \rho_{2} \sigma_{2} \sigma_{1} \sigma_{2}^{-1} \rho_{2} \sigma_{1} \rho_{2} \sigma_{2} \rho_{1} \sigma_{2}^{-1} \rho_{1} \sigma_{1}^{-1} \sigma_{2}^{-1} \rho_{2} \sigma_{1}^{-1} \sigma_{2}$ which also moves only about $0.6 \%$ of random vectors.

We now turn our attention to the case $n=2$.
Example 4.3. It is known [5] that $\beta=\left(\sigma_{1}^{2} \rho_{1} \sigma_{1}^{-1} \rho_{1} \sigma_{1}^{-1} \rho_{1}\right)^{2} \in V B_{2}$ and the identity element $\mathbf{e} \in V B_{2}$ cannot be distinguished by the Burau representation. Considering
actions by these elements on $(0,1,0,1)$ we get $(0,1,0,1) \cdot \beta=(85,49,-90,-47)$, while $(0,1,0,1) \cdot \mathbf{e}=(0,1,0,1)$. Thus, these elements are distinguished by Dynnikov coordinates.

In fact, in the case $n=2$ we have a positive answer to Question 4.1.
Theorem 4.4. The $V B_{2}$-action on $\mathbb{Z}^{4}$ given by the above formulae is faithful.

Proof. We will, in fact show a stronger result than Theorem 4.4, namely that the only element of $V B_{2}$ which acts trivially on a vector $(0, x, 0, y)$, where $x$ and $y$ are different positive integers, is the trivial one. As a simplest vector of this type one can take $(0,2,0,1)$.

Consider the set of symbols $S=\{0,+,-,+0,-0\}$. With $s \in S$ we associate the following subset of $\mathbb{Z}$ :

$$
\begin{gathered}
s=0 \longleftrightarrow\{x \in \mathbb{Z}: x=0\}, \\
s=+\longleftrightarrow\{x \in \mathbb{Z}: x>0\}, \quad s=-\longleftrightarrow\{x \in \mathbb{Z}: x<0\}, \\
s=+0 \longleftrightarrow\{x \in \mathbb{Z}: x \geqslant 0\}, \quad s=-0 \longleftrightarrow\{x \in \mathbb{Z}: x \leqslant 0\} .
\end{gathered}
$$

A quadruple $\left(s_{1}, s_{2}, s_{3}, s_{4}\right)$, where $s_{i} \in S$, indicates the set all quadruples $(a, b, c, d) \in \mathbb{Z}^{4}$ such that $a, b, c, d$ belongs to subset of $\mathbb{Z}$ associated with symbols $s_{1}, s_{2}, s_{3}, s_{4}$, respectively. For example,

$$
(+,+0,0,-)=\left\{(a, b, c, d) \in \mathbb{Z}^{4}: a>0, b \geqslant 0, c=0, d<0\right\} .
$$

For instance, the vector $(-1,-1,0,4)$ belongs to sets associated with $(-,-, 0,+)$ and $(-,-0,+0,+)$, as well as with some other quadruples of symbols.

Let $\sigma, \sigma^{-1}, \rho: \mathbb{Z}^{4} \rightarrow \mathbb{Z}^{4}$ be the transformations defined by (2.1), (2.2), (3.1). Let us apply a sequence of such transformations (without fragments $\sigma \sigma^{-1}$, or $\sigma^{-1} \sigma$, or $\rho \rho)$ to the initial vector, say $(0,2,0,1)$. The statement of the theorem will follow from the fact that we trace out a path in the diagram shown in Figure 1, where an arrow with labels $\beta$ and $i . \beta$, where $i \in\{1,2, \ldots, 14\}$ and $\beta \in\left\{\sigma, \sigma^{-1}, \rho\right\}$ from box $\left(s_{1}, s_{2}, s_{3}, s_{4}\right)$ to box $\left(t_{1}, t_{2}, t_{3}, t_{4}\right)$ means that the image of any element of the subset of $\mathbb{Z}^{4}$ associated with $\left(s_{1}, s_{2}, s_{3}, s_{4}\right)$ under tranformation $\beta$ belongs to the subset of $\mathbb{Z}^{4}$ associated with $\left(t_{1}, t_{2}, t_{3}, t_{4}\right)$. The numbering of arrows by $1,2, \ldots, 14$ is done for the reader's convenience in the further discussion of cases.

It is easy to see from (2.1), (2.2) and (3.1) that for any $\beta \in V B_{2}$ there is the following invariant: if $\left(a^{*}, b^{*}, c^{*}, d^{*}\right)=(a, b, c, d) \cdot \beta$ then $b^{*}+d^{*}=b+d$. In particular, if the initial vector is taken to be $(0,2,0,1)$ then for any vector in the diagram the sum of its second and fourth coordinates is equal to 3 .

Below to simplify expressions we will use the following notations:

$$
\left(a^{\prime}, b^{\prime}, c^{\prime}, d^{\prime}\right)=(a, b, c, d) \cdot \sigma, \quad\left(a^{\prime \prime}, b^{\prime \prime}, c^{\prime \prime}, d^{\prime \prime}\right)=(a, b, c, d) \cdot \sigma^{-1}
$$



Fig. 1. The diagram of actions of $V B_{2}$.

By (2.1) and (2.2) we have

$$
\left\{\begin{array} { l } 
{ a ^ { \prime } = a + b ^ { + } + ( - a + b ^ { - } + c ) ^ { + } , }  \tag{4.1}\\
{ b ^ { \prime } = d - ( a - b ^ { - } - c + d ^ { + } ) ^ { + } , } \\
{ c ^ { \prime } = c + d ^ { - } + ( a - c + d ^ { + } ) ^ { - } , } \\
{ d ^ { \prime } = b + ( a - b ^ { - } - c + d ^ { + } ) ^ { + } , }
\end{array} \quad \left\{\begin{array}{l}
a^{\prime \prime}=a-b^{+}-\left(a+b^{-}-c\right)^{+}, \\
b^{\prime \prime}=d+\left(a+b^{-}-c-d^{+}\right)^{-}, \\
c^{\prime \prime}=c-d^{-}-\left(-a+c+d^{+}\right)^{-}, \\
d^{\prime \prime}=b-\left(a+b^{-}-c-d^{+}\right)^{-},
\end{array}\right.\right.
$$

First of all we remark that the arrows of the diagram related to the action by $\rho$ hold obviously. The other actions will be considered case by case according to the numbering of the arrows.

1. Consider the action by $\sigma^{-1}$ on $(0,+, 0,+)$. Each element of $(0,+, 0,+)$ has a form $(0, b, 0, d)$ for some $b, d>0$. Since its image $(0, b, 0, d) \cdot \sigma^{-1}=(-b, 0,0, b+d)$ belongs to $(-, 0,0,+)$, the corresponding arrow of the diagram is proven.
2. Consider the action by $\sigma$ on $(0,+, 0,+)$. Each element of $(0,+, 0,+)$ has a form $(0, b, 0, d)$ for some $b, d>0$. Since its image $(0, b, 0, d) \cdot \sigma=(b, 0,0, b+d)$ belongs to $(+, 0,0,+)$, the corresponding arrow of the diagram is proven.
3. Consider the action by $\sigma^{-1}$ on $(-, 0,0,+)$. Let $a<0, d>0$ then $(a, 0,0, d)$. $\sigma^{-1}=\left(a, d+(a-d)^{-}, 0,-(a-d)^{-}\right)=(a, a, 0,-a+d) \in(-,-, 0,+) \subset(-,-,+0,+)$.
4. Consider the action by $\sigma$ on $(+, 0,0,+)$. Let $a, d>0$ then $(a, 0,0, d) \cdot \sigma=$ $(a,-a, 0, a+d) \in(+,-, 0,+) \subset(+,-,-0,+)$.
5. Consider the action by $\sigma^{-1}$ on $(0,+,-, 0)$. Let $b>0, c<0$ then $(0, b, c, 0)$. $\sigma^{-1}=\left(-b-(-c)^{+}, 0, c-(c)^{-}, b-(-c)^{-}\right)=(-b+c, 0,0, b) \in(-, 0,0,+)$.
6. Consider the action by $\sigma$ on $(0,+,+, 0)$. Let $b, c>0$ then $(0, b, c, 0) \cdot \sigma=$ $(b+c, 0,0, b) \in(+, 0,0,+)$.
7. Consider the action by $\sigma$ on $(0,+,-, 0)$. Let $b>0, c<0$ then $(0, b, c, 0) \cdot \sigma=$ $(b, c, c, b-c) \in(+,-,-,+) \subset(+,-,-0,+)$.
8. Consider the action by $\sigma^{-1}$ on $(0,+,+, 0)$. Let $b, c>0$ then $(0, b, c, 0) \cdot \sigma^{-1}=$ $(-b,-c, c, b+c) \in(-,-,+,+) \subset(-,-,+0,+)$.
9. Let us demonstrate that $(-,-,+0,+) \cdot \sigma^{-1} \in(-,-,+0,+)$. Since $a<0$, $b<0, c \geqslant 0, d>0$, the action is given by formulae

$$
\left\{\begin{array}{l}
a^{\prime \prime}=a-(a+b-c)^{+} \\
b^{\prime \prime}=d+(a+b-c-d)^{-} \\
c^{\prime \prime}=c-(-a+c+d)^{-} \\
d^{\prime \prime}=b-(a+b-c-d)^{-}
\end{array}\right.
$$

Moreover, $a+b-c<0$ and $a+b-c-d<0$ imply that $(a, b, c, d) \cdot \sigma^{-1}=$ $(a, a+b-c, c,-a+c+d) \in(-,-,+0,+)$.
10. Let us demonstrate that $(+0,+,-,-) \cdot \sigma^{-1} \in(-,-,+0,+)$. Since $a \geqslant 0$, $b>0, c<0, d<0$, the action is given by formulae

$$
\left\{\begin{array}{l}
a^{\prime \prime}=a-b-(a-c)^{+} \\
b^{\prime \prime}=d+(a-c)^{-} \\
c^{\prime \prime}=c-d-(-a+c)^{-} \\
d^{\prime \prime}=b-(a-c)^{-}
\end{array}\right.
$$

Moreover, $a-c>0$ implies that $(a, b, c, d) \cdot \sigma^{-1}=(-b+c, d, a-d, b) \in(-,-,+,+) \subset$ $(-,-,+0,+)$.
11. Let us demonstrate that $(+0,+,-,-) \cdot \sigma \in(+,-,-0,+)$. Since $a \geqslant 0, b>0$, $c<0, d<0$, the action is given by formulae

$$
\left\{\begin{array}{l}
a^{\prime}=a+b+(-a+c)^{+} \\
b^{\prime}=d-(a-c)^{+} \\
c^{\prime}=c+d+(a-c)^{-} \\
d^{\prime}=b+(a-c)^{+}
\end{array}\right.
$$

Moreover, $a-c>0$ implies that $(a, b, c, d) \cdot \sigma=(a+b, d-a+c, c+d, b+a-c) \in$ $(+,-,-,+) \subset(+,-,-0,+)$.
12. Let us demonstrate that $(+,-,-0,+) \cdot \sigma=(+,-,-0,+)$. Since $a>0, b<0$, $c \leqslant 0, d>0$, the action is given by formulae

$$
\left\{\begin{array}{l}
a^{\prime}=a+(-a+b+c)^{+} \\
b^{\prime}=d-(a-b-c+d)^{+} \\
c^{\prime}=c+(a-c+d)^{-} \\
d^{\prime}=b+(a-b-c+d)^{+}
\end{array}\right.
$$

Moreover, $-a+b+c<0, a-b-c+d>0$, and $a-c+d>0$ imply that $(a, b, c, d) \cdot \sigma=(a,-a+b+c, c, a-c+d) \in(+,-,-0,+)$.
13. Let us demonstrate that $(-0,+,+,-) \cdot \sigma \in(+,-,-0,+)$. Since $a \leqslant 0, b>0$, $c>0, d<0$, the action is given by formulae

$$
\left\{\begin{array}{l}
a^{\prime}=a+b+(-a+c)^{+} \\
b^{\prime}=d-(a-c)^{+} \\
c^{\prime}=c+d+(a-c)^{-} \\
d^{\prime}=b+(a-c)^{+}
\end{array}\right.
$$

Moreover, $a-c<0$ implies that $(a, b, c, d) \cdot \sigma=(b+c, d, d+a, b) \in(+,-,-,+) \subset$ $(+,-,-0,+)$.
14. Let us demonstrate that $(-0,+,+,-) \cdot \sigma^{-1}=(-,-,+0,+)$. Since $a \leqslant 0$, $b>0, c>0, d<0$, the action is given by

$$
\left\{\begin{array}{l}
a^{\prime \prime}=a-b-(a-c)^{+}  \tag{4.2}\\
b^{\prime \prime}=d+(a-c)^{-} \\
c^{\prime \prime}=c-d-(-a+c)^{-} \\
d^{\prime \prime}=b-(a-c)^{-}
\end{array}\right.
$$

Moreover, $a-c<0$ implies that $(a, b, c, d) \cdot \sigma^{-1}=(a-b, d+a-c, c-d, b-a+c) \in$ $(-,-,+,+) \subset(-,-,+0,+)$. The proof is completed.

Remark 4.5. Theorem 4.4 allows us to introduce on $V B_{2}$ various "coordinate systems". For example, taking $(0,2,0,1)$ as the initial vector, for any $\beta \in V B_{2}$ one can define $(0,2,0,1) \cdot \beta$ as its coordinates. In this sense Theorem 4.4 gives an anolog of Dynnikov coordinates originally defined for braid groups.

Remark 4.6. It is shown in the proof of Theorem 4.4 that the $V B_{2}$-action is faithful on any vector of the form $(0, x, 0, y)$, where $x$ and $y$ are different positive integers. Note that the action on some other vectors of $\mathbb{Z}^{4}$ can fail to be faithful. For example, $(0,0,0,1) \cdot \sigma=(0,0,0,1)$ and $(0,1,0,1) \cdot \rho=(0,1,0,1)$.

Remark 4.7. Let us define the norm of a quadruple $\|(a, b, c, d)\|=|a|+|b|+|c|+|d|$. Obviously, the norm is invariant under the $\rho$-action. One can easily see from the proof of Theorem 4.4 that all the arrows labelled $\sigma$ or $\sigma^{-1}$ in Figure 1 increase the norm. For example, considering case 13 , one gets $\|(a, b, c, d) \cdot \sigma\|=\|(b+c, d, d+$
$a, b) \|=|b+c|+|d|+|d+a|+|b|>|a|+|b|+|c|+|d|$, because $a \leqslant 0, b>0, c>0$, $d<0$. However, this property doesn't hold if one takes an arbitrary vector from $\mathbb{Z}^{4}:\|(7,4,1,1)\|=13$, but $\|(7,4,1,1) \cdot \sigma\|=\|(3,1,6,1)\|=11$.

## Acknowledgements

Work performed under the auspices of the Russian Foundation for Basic Research by the grant 10-01-00642 and by the French - Russian grant 10-01-91056. The first and the second named authors thank IRMAR, Université de Rennes 1 and Abdus Salam School of Mathematical Sciences, GC University Lahore for their hospitality.

## References

[1] V. Bardakov, The virtual and universal braids, Fundamenta Mathematicae 184 (2004), 1-18.
[2] P. Dehornoy, with I. Dynnikov, D. Rolfsen, B. Wiest, Ordering braids, Math. Surveys and Monographs 148, AMS (2008)
[3] R. Fenn, R. Rimányi, C. Rourke, The braid-permutation group, Topology 36(1) (1997), 123-135.
[4] L. Kauffman, Virtual knot theory, Eur. J. Comb. 20(7) (1999), 669-690.
[5] V. O. Manturov, Recognition of virtual braids, J. of Math. Sciences 131(1) (2005), 267-286.
[6] V. Vershinin, Generalization of braids and homologies, J. Math. Sciences 134(2) (2006), 2002-2016.
[7] B. Wiest, http://perso.univ-rennes1.fr/bertold.wiest

