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# Lévy processes and stochastic von Bertalanffy models of growth, with application to fish population analysis

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#### Abstract

The study of animal growth is a longstanding crucial topic of theoretical biology. In this paper we introduce a new class of stochastic growth models that enjoy two crucial properties: the growth path of an individual is monotonically increasing and the mean length at time t follows the classic von Bertalanffy model. Besides the theoretical development, the models are also tested against a large set of length-at-age data collected on Atlantic Herring (Clupea harengus): the mean lengths and variances of the cohorts were directly estimated by least squares. The results show that the use of subordinators can lead to models enjoying interesting properties, in particular able to catch some specific features often observed in fish growth data. The use of subordinators seems to allow for an increased fidelity in the description

of fish growth, whilst still conforming to the general parameters of the traditional von Bertalanffy equation.

Key words: Individual-based models, Subordinators, Fish growth, Clupea harengus, Fisheries

#### 1 1 Introduction

- <sup>2</sup> The modeling of growth and the analysis of intra-population pattern of size
- variability through time are central topics in animal population biology,
- 4 since the internal size structure of populations can have a decisive influence
- on the population dynamics (DeAngelis et al., 1993; Imsland et al., 1998;
- 6 Uchmanski, 2000; Kendall & Fox, 2002; Fujiwara et al., 2004). In general,
- <sup>7</sup> the von Bertalanffy growth function (VBGF von Bertalanffy, 1957) is the
- 8 best acknowledged and used relationship to describe the growth of fish and
- 9 other animals. This equation states that the size of an individual increases in
- 10 time according to the equation

$$x_t = L_{\infty}(1 - e^{-k(t+t_0)})$$
 (1.1)

- Where  $L_{\infty}$  is the extremal length that is attained as time goes to infinity,
- $t_0$  is the time of conception, at which the size should be 0 and k is a
- parameter that gives the speed of the process: the larger the value of k, the
- quickest the growth. The VBGF is most commonly used as a descriptive
- model of size-at-age data (Essington et al., 2001). Nevertheless, equation
- 16 (1.1) describes the relationship between age and mean length of a

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- population, whereas the variability among individuals of the same age (e.g.
- the variance or even the distribution of each cohort) is not included.
- 19 The popular assumption of gaussianity (Imsland et al., 1998) is clearly a first
- (rough) approximation in this direction. A natural approach to the problem
- of determining the appropriate form of the probability distribution for a
- population at a given time t is to model first the growth process of the
- 23 individuals (individual based models, IBM). Nowadays, both in ecological
- (Arino et al., 2004), evolutionary (Conover & Munch, 2002; Ernande et al.,
- 25 2004) and management (Caswell, 2001) contexts, one of the challenges of the
- <sup>26</sup> researcher is to model how the size of an individual changes in time and
- <sup>27</sup> deduce from the growth model which kind of probability distribution models
- the size of fish at a given age (Lv & Pitchford, 2007; Fujiwara et al., 2004).
- 29 A suitable model of growth should account for both individual and
- environmental variability. In fish, as in other animals, the first source of
- variability is rooted in the physiological processes and is the net result of two
- opposing processes, catabolism and anabolism (von Bertalanffy, 1938). The
- inter-individual variability in growth is the result of several internal (genetic)
- 34 and external (environmental) factors which affect these physiological
- processes. In fact, while each individual is born with a personal genetic
- architecture which primarily determines his growth profile, a number of
- physical and biological factors, such as water temperature (Sumpter, 1992),
- dissolved oxygen (Brett, 1979), photoperiod (Imsland et al., 2002), and the
- <sub>39</sub> availability of appropriate food sources (Rilling & Houde, 1999), have been
- shown to affect growth rates. In order to take into account these aspects as
- 41 well as individual variability, a class of individually based model (IBM) was
- developed (Lv & Pitchford, 2007; Sainsbury, 1980; Mulligan & Leaman,

- 43 1992; Wang & Thomas, 2003; Imsland et al., 2002; Wang, 1999;
- 44 Gudmundsson, 2005).
- 45 These models can be classified into two main categories. The first comprises
- 46 those which consider the inter-individual variability as a stochastic factor to
- be added to the general growth curve of the population. The distribution of
- 48 this factor is the same for all the individuals. In the most recent approaches
- of this kind (Gudmundsson, 2005; Lv & Pitchford, 2007; Wang, 1999) some
- 50 individual-based stochastic models of growth are proposed using a stochastic
- of differential equations. These models take the general form:

$$dL_t = f(L_t, t) + \alpha(L_t, t) dB(t)$$
(1.2)

- Here  $L_t$  is the size at time t,  $f(L_t,t)$  characterizes the deterministic intrinsic
- 53 growth (drift coefficient) of the individual (the same for all individuals);
- $\alpha(L_t, t)$  gives the magnitude of the random fluctuations (diffusion coefficient)
- and B(t) is a standard Brownian motion, or Wiener process, which is
- 56 commonly used to model a variety of background and environmental
- 57 fluctuations in physical, financial and biological contexts, see
- 58 Karlin & Taylor (1981) e.g.
- 59 The stochastic component of these models is intended to account both for
- the environment and the inter-individual variability. It should be stressed,
- 61 however, that (as already remarked in Gudmundsson, 2005) the solution of
- an equation as (1.2) cannot be monotonically increasing and therefore
- appears to be unsuitable to model the evolution of the size of an individual.
- Stochastic models like the one of (1.2) are conversely well suited in order to
- 65 model quantities, as prices in financial markets, that are characterized by an

- 66 oscillating and therefore non monotonic behaviour. This aspect seems to be
- 67 a drawback for a growth model of several animals like fish. In fact, for fish
- and other vertebrates, the physiological mechanism of growth in length (i.e.
- 69 addition of bone material to the axil unit of the skeleton that is the
- vertebra) leads to a pattern in which the size of an individual is necessarily
- increasing in time (Weatherley & Gill, 1987). Let us point out that there
- exist no Gaussian process which is increasing. Therefore, modeling size
- variability through an individual growth process, can not give rise to a
- 74 Gaussian distribution.
- Closely related to the models (1.2) are those introduced in Gudmundsson
- <sub>76</sub> (2005) where it is the derivative of the growth process that is the solution of
- a stochastic equation. It is possible in this way to obtain a stochastic process
- that is increasing. These models are interesting and deserve to be tried by
- testing against real data. Remark however that the mean size at time t of a
- <sup>80</sup> population following such a model does not follow a VBGF.
- The second category of stochastic models suggested so far comprises
- 82 non-deterministic models in which the individuals of a fish population have
- different parameters of the VBGF. In this way, each individual has its own
- triplet  $(L_{\infty}, t_0, k)$ , that is retained throughout its life (Sainsbury, 1980).
- Considering the length to age relationship, the length  $X_t$  at age t of the i-th
- individual with the parameters triple  $(L_i, t_{0,i}, k_i)$  is given by:

$$X_{t,i} = L_i (1 - e^{-k_i(t + t_{0,i})})$$
(1.3)

- 87 This model displays a monotonic behaviour and considers the
- 88 inter-individual variability of growth parameters, but does not account for

- the randomness coming from the environment, which can be seen as a
- 90 limitation of the model.
- $_{91}$  Finally, it should be considered that individual growth is a complex energetic
- process. Individual length increases only when enough energy from food is
- <sub>93</sub> available for growth. On the other hand lack of food does not usually lead to
- <sup>94</sup> a reduction in length, because organisms can lose body mass without
- 95 shrinking in length (Kooijman, 2000) also because of the presence of a
- skeleton. Energy may also be allocated to storage for future use, producing
- "memory" in growth dynamics. Individual organisms encounter and ingest
- 98 food, which is then assimilated. Assimilated food is transformed into reserve
- material such as protein and fat. A fixed fraction of the energy from the
- 100 reserve is used for both metabolic maintenance and growth, and the rest is
- used for reproduction. Looking at the length of an individual, we suggest that
- this process determines a pattern in which periods of no growth (determined
- by scant energy inlet) are separated by periods of growth. If the periods of
- growth are short, the growth process could be well described by a model
- allowing for discontinuities, i.e. for instantaneous increases of the length
- 106 (jumps). This idea is consistent with several observations reported for fish in
- general and for the species we are going to study (Hinrichsen et al., 2007).

108 In this paper we introduce two classes of stochastic models of growth that

- attempt to overcome the drawbacks pointed out above. The main idea
- developed in this paper is to model the growth process as the solution of a
- stochastic equation of the form

$$dX_t = (L_{\infty} - X_{t-}) dZ_t$$

- where  $(Z_t)_t$  is a subordinator. These are a class of stochastic processes that
- are strictly increasing and the solution  $(X_t)_t$  turns out to be increasing also.
- These models enjoy a certain number of desirable features, namely
- they take into account both the individual and environmental sources of
- 116 randomness;
- they are increasing.
- the mean size at time t follows a VBGF.
- In §2 we make a quick review on the topics of subordinators upon which our
- models are built. In §3 and §4 some models are developed, attempting to
- answer to the points exposed above. Finally in §6 we apply the proposed
- models to a large set of length-at-age data of Atlantic herring Clupea
- 123 harengus, presented in §5.

#### 2 Subordinators

- A subordinator is a stochastic process  $(Z_t)_t$  such that
- $Z_0 = 0$ ;
- its paths are right continuous and increasing almost surely;
- has independent and stationary increments.
- This means in particular that the distribution of  $Z_{t+h} Z_t$  is independent of
- t for every  $h \geq 0$  and that  $Z_t Z_s$  and  $Z_v Z_u$  are independent r.v.'s for
- $u < v \le s < t$ . Also the increments  $Z_{t+h} Z_t$  must be stationary, in the
- sense that their distribution depends on h only and not on t. The
- characterization of such processes (that are particular instances of Lévy
- processes) has received much attention in time and it is characterized in

terms of the Laplace transform of  $Z_t$ . It is immediate that if

$$M_t(\theta) = \mathcal{E}(e^{-\theta Z_t}), \qquad \theta \ge 0$$
 (2.4)

then M is of the form

$$M_t(\theta) = e^{t\phi(\theta)} \tag{2.5}$$

where the exponent  $\phi$  is characterized by the Lévy-Khintchin formula (see,

for the subjects developed in this section and in the next ones

139 Cont & Tankov 2004 and Sato 1999 e.g.). More precisely, the

Lévy-Khintchin formula for subordinators states that

$$\phi(\theta) = -\theta\gamma + \int_0^{+\infty} (e^{-\theta x} - 1) \nu(dx)$$

where  $\gamma \geq 0$  and  $\nu$ , the *Lévy measure*, is a positive measure on  $\mathbb{R}^+$  such that

$$\int_0^{+\infty} \frac{x}{1+x} \,\nu(dx) < +\infty \tag{2.6}$$

Intuitively a subordinator increases as the superposition of a deterministic evolution  $t \to \gamma t$  and of a stochastic process which only makes jumps. These are made at times governed by a Poisson process. More precisely, if 0 < a < b, then  $\nu([a,b])$  is the intensity of the Poisson process of the jumps whose size is larger than a and smaller than b. This means that if t is the (random) time at which the jump occurs, then the path has, at t, a left limit  $X_{t-}$  and a right limit  $X_{t+}$  that are different, with  $X_{t-} < X_{t+}$ . For our purposes we shall therefore be much interested in subordinators whose Lévy measure is large to near 0 and gives a small mass only away from 0. The resulting process would hence be characterized by many very small jumps.

As every Lévy process, the independence and stationarity properties of the

increments implies that if  $Z_t$  has a finite mean, then

$$E(Z_t) = \mu t$$

for some real number  $\mu$  and if it has a finite variance then

$$Var(Z_t) = \sigma^2 t$$

for some  $\sigma^2 \geq 0$ .

156 It is not possible for a general Lévy measure to compute explicitly the

Laplace transform and/or the density at time t of the associated

subordinator. The next examples introduce some families of subordinators of

interest for which these feature can be determined.

• the Gamma process, where the distribution of  $Z_t$  follows a  $\Gamma(\alpha t, \lambda)$ 

distribution. Recall that such a distribution has a density

$$f(x) = \frac{\lambda^{\alpha t}}{\Gamma(\alpha t)} x^{\alpha t - 1} e^{-\lambda x}, \qquad x > 0$$

and f(x) = 0 for  $x \leq 0$ . Of course the increment  $Z_t - Z_s$ , having the same

distribution as  $Z_{t-s}$ , has a  $\Gamma(\alpha(t-s), \lambda)$  distribution. Its Laplace transform is

$$M_t(\theta) = \left(\frac{\lambda}{\lambda + \theta}\right)^{\alpha t} \tag{2.7}$$

so that  $\phi(\theta) = -\alpha \log \frac{\lambda}{\lambda + \theta}$ . From well-known properties of the  $\Gamma(\alpha t, \lambda)$ 

distribution the statistical indices of interest of a Gamma process are:

mean =  $\alpha t/\lambda$ , variance =  $\alpha t/\lambda^2$ , skewness =  $2/\sqrt{\alpha t}$  and kurtosis =

$$3 + 6/(\alpha t)$$
.

168 Here the Lévy measure is

$$\nu(dy) = \frac{\alpha}{y} e^{-\lambda y} dy.$$

- This process therefore gives a high intensity to small jumps (see Fig 1).
- The inverse Gaussian processes, where  $Z_t$  is defined as the first time at
  which a process of the form  $\sqrt{\rho}B_s + bs$  crosses level t. Here  $(B_t)_t$  denotes a
  standard Brownian motion and  $\rho, b > 0$ . Its density at time t is, for x > 0,

$$f_t(x) = \frac{te^{bt/\rho}}{(2\pi\rho)^{1/2}x^{3/2}} \exp\left(-\frac{b^2}{2\rho}x - \frac{t^2}{2\rho x}\right).$$

173 It depends on the positive parameters  $b, \rho$ . Its Laplace transform at time t is

$$M_t(\theta) = \exp\left(-t\left(\sqrt{\frac{b^2}{\rho^2} + \frac{2\theta}{\rho}} - \frac{b}{\rho}\right)\right)$$
,

174 from which one can derive the expression of the statistical indices of interest:

mean = 
$$t/b$$
, variance =  $\rho t/b^3$ , skewness =  $3\sqrt{\rho/(tb)}$  and kurtosis =  $3+15\rho/(tb)$ .

177 The Lévy measure is

$$\nu(dy) = \frac{1}{\sqrt{2\pi\rho y^3}} e^{-\frac{1}{2\rho}b^2y} dy.$$
 (2.8)

We stress that both the Gamma and the inverse Gaussian process have a
Lévy measure that gives much weight to small jumps and that decreases fast
at infinity.

• The  $\alpha$ -stable process,  $0 < \alpha < 1$  whose Laplace transform is

$$M_t(\theta) = e^{-c\theta^{\alpha}t}$$
.

For these processes an explicit expression for the density does not exist,

unless  $\alpha = \frac{1}{2}$ . In this case, for  $c = \sqrt{2}$ , the density is, for x > 0,

$$f(x) = \frac{t}{(2\pi)^{1/2} x^{3/2}} e^{-\frac{t^2}{2x}}$$
.

Notice that, as  $x \to +\infty$  the density decreases very slowly and, in particular,

both expectation and variance are infinite. Also the Lévy measure decreases

very slowly at infinity, therefore allowing very large jumps. We shall see that

this model is not well suited for the growth phenomena of interest and we

mention it only for reasons of completeness.

189 To the previous examples one should add the deterministic increasing

process:  $Z_t = \gamma t$ . Recall also that the sum of independent subordinators is a

191 subordinator itself.

### 3 Modeling by time change

A first growth model using subordinators can be obtained by time change.

We simply consider that the size of the fish  $X_t$  at time t is given by

$$X_t = Z_{A_t}$$

where Z is the subordinator and A is the von Bertalanffy type function

$$A_t = (1 - e^{-k(t+t_0)}).$$

196 If the subordinator  $Z_t$  has finite mean, then for some real number  $\mu$ 

$$E(X_t) = \mu (1 - e^{-k(t+t_0)})$$

and the means follow therefore a VBGF, where  $\mu$  plays the role of  $L_{\infty}$  (recall that  $\mu=\mathrm{E}(Z_1)$ ).

If in particular Z is a Gamma process, then  $\mu = \frac{\alpha}{\lambda}$ . It is also immediate that, if  $Z_t$  has finite variance,

$$Var(X_t) = \sigma^2 (1 - e^{-k(t+t_0)})$$
 (3.9)

for some  $\sigma^2 > 0$  ( $\sigma^2 = \frac{\alpha}{\lambda^2}$  if Z is a Gamma process). Recall that the variance is always increasing in t. This fact makes that the models obtained by time change of a subordinator are rather rigid and are in particular unable to account for a non monotonic behaviour of the variance, as is often observed in data.

#### 206 4 Modeling by Doléans exponential

A more interesting model of growth is given by the process  $(X_t)_t$  which is obtained as the solution of the stochastic equation

$$dX_{t} = (L_{\infty} - X_{t-}) dZ_{t}$$

$$X_{-t_{0}} = 0$$
(4.10)

where  $(Z_t)_t$  is a subordinator. Here  $-t_0$  denotes the time of conception, at which the size must be considered equal to 0. If the subordinator Z has a drift  $\gamma$  equal to 0, the solution of (4.10) is a process that remains constant between the jumps of Z, whereas it has an increment of size

$$(L_{\infty} - X_{t-}) \, \Delta Z_t$$

whenever Z has a jump of size  $\Delta Z_t$ . The quantity  $X_{t-}$  denotes the value of X just before the jump that occurs at time t. If we define  $Y_t = L_{\infty} - X_t$ , then Y is the solution of

$$dY_t = -Y_{t-} dZ_t$$

$$Y_{-t_0} = L_{\infty} .$$

$$(4.11)$$

Therefore Y is equal to the Doléans exponential of the Lévy process -Z multiplied by  $L_{\infty}$ . The Doléans exponential of the Lévy process is a subject that has received much attention and it is possible to derive an explicit solution of (4.11), at least if one makes the assumption that the process Z cannot make jumps larger than 1 (which is a quite reasonable assumption, in

our case). Under this assumption the solution of (4.11) is

$$Y_t = L_{\infty} e^{-\widetilde{Z}_{t+t_0}} \tag{4.12}$$

where  $\widetilde{Z}$  is another subordinator whose Lévy measure  $\widetilde{
u}$  and drift  $\widetilde{\gamma}$  are

obtained from  $\nu$  and  $\gamma$  in an explicit way. More precisely  $\widetilde{\nu}$  is the image of  $\nu$ 

through the application  $x \to \log(1+x)$  and  $\tilde{\gamma} = \gamma$ . The solution of (4.10) is

225 therefore

$$X_t = L_{\infty} (1 - e^{-\widetilde{Z}_{t+t_0}}). \tag{4.13}$$

226 It is easy to compute the mean  $E(X_t)$ , as the quantity  $E(e^{-\widetilde{Z}_{t+t_0}})$  is the

Laplace transform at  $\theta = 1$  of the r.v.  $Z_{t+t_0}$ , which is easy to compute thanks

 $_{228}$  to (2.4) and (2.5):

$$E(X_t) = L_{\infty}(1 - e^{-(t+t_0)\widetilde{\phi}(1)}).$$
 (4.14)

229 Hence also for this model whatever the subordinator that is chosen (provided

230 its Lévy measure vanishes outside [0, 1]), the mean of the solution of (4.10)

231 follows a von Bertalanffy-type equation.

Note 4.1 Recall that the VBGF (1.1) is the solution of equation (4.10)

when Z is the deterministic subordinator  $Z_t = kt$ . Therefore (4.10) appears

234 as a natural stochastic extension of the VBGF.

235 Remark also that some models already present in the literature are

particular instances of (4.10). It is the case of the model (3.4) of

Lv & Pitchford (2007) where the authors actually consider  $Z_t = rt + \sigma B_t$ .

We point out again that the solution to (4.10) in this case does not have

239 paths which are monotonically increasing.

The solution (4.13) however has a drawback as a growth model because  $X_t \to L_\infty$  as  $t \to +\infty$  (unless  $Z_t \equiv 0$ ). This implies that  $\operatorname{Var}(X_t) \to 0$  as  $t \to +\infty$ , which is not realistic, as it would imply that all individuals should reach the same limiting size as t increases. In order to overcome this problem it seems natural to assume that the extremal size  $L_{\infty}$  is itself a random 244 variable, thus accounting for the individual variability. In this way the two sources of randomness,  $L_{\infty}$  and  $(Z_t)_t$ , appearing in equation (4.10) have the meaning of modeling the random individual variability and the 247 environmental randomness respectively. It is therefore natural to assume 248 that  $L_{\infty}$  and  $(Z_t)_t$  are independent. In this case formula (4.14) remains valid if one replaces  $L_{\infty}$  by  $E(L_{\infty})$ . Therefore the expectation  $E(X_t)$  still follows a von Bertalanffy-type pattern as in (4.14), but with  $L_{\infty}$  replaced by  $\mathrm{E}(L_{\infty})$ . 251 Similarly it is easy to compute the variance which is given by

$$Var(X_t) = Var(1 - e^{-\widetilde{Z}_{t+t_0}}) E[L_{\infty}^2] + Var(L_{\infty}^2) E[1 - e^{-\widetilde{Z}_{t+t_0}}]^2 =$$

$$= \left(e^{-(t+t_0)\widetilde{\phi}(2)} - e^{-2(t+t_0)\widetilde{\phi}(1)}\right) E[L_{\infty}^2] + Var(L_{\infty}^2) \left(1 - e^{-(t+t_0)\widetilde{\phi}(1)}\right)^2.$$
(4.15)

Notice that  $\operatorname{Var}(X_t)$  appears as the sum of two terms. As both  $\widetilde{\phi}(1)$  and  $\widetilde{\phi}(2)$  are positive, the first term vanishes at  $-t_0$  and at  $+\infty$  and it easy to see that (unless  $Z_t \equiv 0$ ) it increases at first and then decreases. The second one conversely is increasing in t. Therefore the variance of  $X_t$ , according to different values of the parameters, can exhibit two possible behaviours:

- increasing or
- first increasing and then decreasing.
- 260 See Figure 2 for an illustration of this typical behaviour.

- The non monotonic behaviour of the variance is an interesting feature that is enjoyed also by some of the models proposed by Gudmundsson, 2005 and Lv & Pitchford, 2007. This is not surprising as the computation above only makes use of the fact that  $(X_t)_t$  is the solution of equation (4.10) with a driving process  $(Z_t)_t$  which is a Lévy process, possibly a Brownian motion as it happens to be the case for the models of the authors above.
- Note 4.2 In §6 we adapt the models of this section and of §3 to a population of herrings. It is fair however to point out a limitation that arises when trying to model real populations with processes driven by subordinators. Recall that the driving subordinator is meant to model the 270 randomness of the growth process arising from the environment. The 271 assumption of independence and stationarity of the increments of the subordinator implies the assumption that the environment remains stable 273 and stationary in time, which is a feature that can be expected to hold in real world only for a short span of time, as the effect of season and of other sources of modification of the natural habitat should introduce a time-dependent effect. It is clear however that more realistic models would be far more complicated and, possibly, intractable in practice. The same observation, by the way, applies to the VBGF, which is an equation that is derived under the assumption of stationarity of the environment.
- In the rest of this section we give more details in two particular cases,
  making assumptions on Z that imply that  $\tilde{Z}$  is either a Gamma or an inverse
  Gaussian process.

- Assume that the Lévy measure  $\nu$  of Z has a density h with respect to the
- Lebesgue measure. h must be  $\geq 0$ , must vanish on  $[1, +\infty[$  and be such that

$$\int_0^1 yh(y)dy < +\infty$$

Then -Z has a drift  $=-\gamma$  and a Lévy measure  $\overline{\nu}$  given by the density

$$\overline{h}(y) = h(-y)$$

The image of the measure  $\overline{h}(y) dy$  by  $y \to \log(1+y)$  is

$$\widetilde{h}(y) = e^{-y}h(1 - e^{-y})$$

288 Example 4.3 (The Gamma process) Let us assume that

$$h(y) = \frac{\alpha}{-\log(1-y)} (1-y)^{\lambda-1}$$
 (4.16)

for  $0 < y \le 1$  and h(y) = 0 for y > 1, where  $\alpha > 0$ ,  $\lambda > 0$ . With this choice

290 we obtain

$$\widetilde{h}(y) = \frac{\alpha}{y} e^{-\lambda y}$$

which is the Lévy measure of a Gamma process. Hence if we choose a driving

subordinator Z with a Lévy measure as in (4.16) and drift  $\gamma$ , the solution of

293 (4.10) is

$$X_t = L_{\infty} (1 - e^{-\gamma t - \widetilde{Z}_{t+t_0}})$$
 (4.17)

where  $\tilde{Z}$  is a Gamma process with parameters  $\alpha$  and  $\lambda$  and drift  $\gamma$ . Thanks

to (4.10) and (2.7), for this model the mean is equal to

$$E(X_t) = E(L_{\infty}) \left( 1 - e^{-\gamma(t+t_0)} \left( \frac{\lambda}{\lambda+1} \right)^{\alpha(t+t_0)} \right)$$
(4.18)

which, as already noted, is a von Bertalanffy equation with

 $k = \gamma + \alpha \log \frac{\lambda+1}{\lambda}$ . The variance of  $X_t$  is also easily computed using (4.15):

$$\operatorname{Var}(X_{t}) = \operatorname{E}[L_{\infty}^{2}] e^{-2\gamma(t+t_{0})} \left[ \left( \frac{\lambda}{\lambda+2} \right)^{\alpha(t+t_{0})} - \left( \frac{\lambda}{\lambda+1} \right)^{2\alpha(t+t_{0})} \right] +$$

$$+ \operatorname{Var}(L_{\infty}) \left[ 1 - e^{\gamma(t+t_{0})} \left( \frac{\lambda}{\lambda+1} \right)^{\alpha(t+t_{0})} \right]^{2}.$$

$$(4.19)$$

It is also possible to compute the density of  $X_t$ , conditioned to the value of

 $L_{\infty} = l$ , which is given by

$$f(x) = \frac{\lambda^{\alpha(t+t_0)}(l-x)^{\lambda-1}}{\Gamma(\alpha(t+t_0))l^{\lambda}} \left(-\log(1-\frac{x}{l}) - \gamma(t+t_0)\right)^{\alpha(t+t_0)-1} e^{\lambda\gamma(t+t_0)}$$
(4.20)

for  $l(1 - e^{-\gamma(t+t_0)}) \le x \le l$  and f(x) = 0 otherwise. The graph of this density

for different values of t is produced in Figure 3. See in Figure 4 the graph of

some simulated paths of  $(X_t)_t$  with  $\gamma = 0$ .

Example 4.4 (The inverse Gaussian process) Let us assume that Z is a

Levy process such that  $\tilde{Z}$  is an inverse Gaussian process with drift  $\gamma$ . If the

Lévy measure of Z has a density

$$h(x) = \frac{1}{\sqrt{2\pi\rho}(-\log(1-x))^{3/2}} (1-x)^{\frac{b^2}{2\rho}-1}$$

for 0 < x < 1 and h(x) = 0 elsewhere, then it turns out that  $\widetilde{Z}$  is an inverse

Gaussian process with parameters b and  $\rho$ . The density of

 $X_t = L_{\infty}(1 - e^{-\widetilde{Z}_t - \gamma t})$  given  $L_{\infty} = l$  is straightforward to compute and is

$$f_t(x) = \frac{te^{bt/\rho}}{\sqrt{2\pi\rho}} \left(-\log(1-\frac{x}{l})\right)^{-3/2} \left(1-\frac{x}{l}\right)^{\frac{b^2}{2\rho}-1} \exp\left(\frac{t^2\rho}{2\log(1-\frac{x}{l})}\right)$$

for 0 < x < l and  $f_t(x) = 0$  otherwise.

One could also think of  $\widetilde{Z}$  as a stable process with exponent  $\alpha = \frac{1}{2}$ . This choice however does not seem really suitable. Indeed in this case it is also possible to compute the density, as the same type of computation produces in this case the density, conditional on  $L_{\infty} = l$ ,

$$g_t(x) = \frac{t + t_0}{\sqrt{2\pi}(l - x)(\log\frac{l}{l - x})^{3/2}} \exp\left(-\frac{(t + t_0)^2}{2\log\frac{l}{l - x}}\right), \quad 0 < x < l.$$

(with  $\gamma=0$ ). The expression of this density suggests that the use of stable subordinators is inappropriate in order to model fish growth, as  $g(x) \to +\infty$  as  $x \to l-$ , for every value of t.

The model based on the Doléans exponential (4.10) appears to enjoy many interesting features. It is fair however to point out that in order to take advantage of it there remains the question of determining an appropriate distribution for the maximal length  $L_{\infty}$ . It also appears difficult to find a distribution such that the density distribution of the length of the individuals of a given time t,  $L_{\infty}(1 - e^{-Z_{t+t_0}})$  has an explicit analytic expression. This density can be computed numerically, but it may be impossible to use of statistical methods based on maximum likelihood.

The question of determining a good candidate of distribution has been already tackled in (Sainsbury, 1980), where the author suggested a Gamma distribution.

#### 328 5 The Dataset

The data used in this study were collected as part of the EU FP5 project "HERGEN" (Mariani *et al.*, 2005; Ruzzante *et al.*, 2006), and include a

- homogeneous collection of genetically and phenotypically characterized
- North Sea Autumn Spawning herring (Clupea harengus L., 1758), from ICES
- areas zones IVa, IVb and IVc. Herring is the dominant converter of
- 234 zooplankton production, using the biomass of copepods, mysids, euphausids
- in the pelagic environment of the northern hemisphere (Winters & Wheeler,
- 336 1987). Additionally, herring is a central prey item for higher trophic levels.
- The spawning period of this species in the western North Sea is
- 338 September/October.
- The samples were collected east of the Shetland Islands in July 2005. At that
- moment, fish were located in that area to feed (summer feeding aggregation).
- Aging was performed by counting the otolith (sagitta) winter rings, following
- standard procedures (Ruzzante et al., 2006; AA.VV, 2007). This method was
- validated and tested for reliability following the procedure reported in
- Beverton et al. (2004). The dataset is composed by 1255 specimens
- belonging to 7 cohorts. The abundances and the ages of these cohorts are
- showed in Table 1. The values of the empirical means and variances of the
- cohorts can be found in Fig 5.

#### 348 6 Analysis of the herring dataset

- In order to apply the models developed in §3 and §4 to the analysis of a
- dataset as the herring one described in the previous section, one is
- 351 confronted with two kind of problems.
- The first one is the determination of the appropriate driving subordinator.
- Actually subordinators form a large family, every Lévy measure on  $\mathbb{R}^+$
- satisfying (2.6) being associated to a corresponding subordinator. This is

- therefore a non parametric problem and it appears very difficult to
- determine this Lévy measure starting from data in the form of cohorts, as is
- 357 the case for the herring dataset.
- The second order of problems comes from the fact that these models are to
- be considered only approximatively correct, as they do not take into account
- the time variability of the environment (see Note 4.2).
- 361 In this section we produce the results obtained fitting the models of §3 and 4
- to the herring dataset. In both cases we decided to work with the Gamma
- model, as it seemed to give better results than the inverse Gaussian.
- 364 In order to have a benchmark for the analysis of the dataset, we shall first
- adapt a normal Gaussian model inside each cohort. This is the default choice
- in literature (Imsland et al., 1998). Given the age  $t_i$ , the length  $X_{t_i}$  is
- assumed to be normally distributed with mean  $L_{\infty}(1-e^{-k(t_i+t_0)})$  and
- variance  $\sigma_i^2$  (different cohorts are allowed to have different variances). This
- model requires therefore a number of parameters that is equal to 3+the
- number of cohorts.
- 371 It is worth noting that this is not a mixture model, as we are able to assign
- every individual to its class. Recall also that, as stated in the introduction,
- 373 this is not a Individual Based Model.
- The normal and time change models have been estimated by means of
- maximum likelihood, which appears to be the most natural method for
- them. As already pointed out in §4, for the Doléans exponential model,
- which is the most promising, the maximum likelihood method is
- inapplicable, as the distribution of the maximal size  $L_{\infty}$  is not known. We
- therefore resorted to the least squares method in order to fit the moments.

- The estimates obtained with different models are shown in Table 2.
- 381 It is apparent that the normal model has a good agreement with the data,
- which is not surprising, given also the availability of many parameters.

#### 383 6.1 Time change model

- As already hinted in §3 this kind of models shows a certain rigidity. We give
- the estimates obtained using it for completeness sake only. Assuming that
- the lengths at time  $t_i$  follow a  $\Gamma(\alpha(1-e^{-k(t_i+t_0)}),\lambda)$  distribution, we have a
- model with 4 parameters (whatever the number of cohorts). The estimated
- values are  $\alpha = 388.2$ ,  $\lambda = 1.33$ , k = 0.64 and  $t_0 = 0.047$ . From this we deduce
- $\hat{L}_{\infty}$  as the ratio  $\hat{\alpha}/\hat{\lambda}$  (see Table 2). Estimates of the means and variances are
- obtained using (3.9).
- Notice that the estimated means are very close to the empirical means (with
- the exception of cohort 1). However it is clear that this model cannot
- accommodate the variances. Recall that for this model the variances are
- necessarily increasing with time, at a difference with the behaviour of the
- <sup>395</sup> empirical variances.
- As already mentioned above, the model based on time change is a
- particularly parsimonious explanation of the data in terms of number of
- parameters, but has limited capacities of catching some relevant features.

#### 399 6.2 Doléans exponential

- We tried a model based on the solution of (4.10) with respect to a Gamma
- 401 process, as in Example 4.3.
- 402 According to this model, the density of the observations follows a
- distribution, given  $L_{\infty} = l$ , that is given in (4.20). Noting that the mean
- values of the lengths of the different cohorts must lie on the VBGF, we
- decided to perform a two-stage method of moments, in which, at first, the
- empirical means are interpolated by a VBGF function (1.1), therefore
- estimating the parameters  $E(L_{\infty})$ , k and  $t_0$ . In the second stage, we
- interpolated the empirical variances with the function (4.19). In this way we
- obtained estimates of  $\alpha$ ,  $\lambda$ ,  $\gamma$  together with an estimate of  $\sigma_{L_{\infty}}^{2} = \text{Var}(L_{\infty})$ .
- Recall that the quantities k and  $\alpha$ ,  $\lambda$ ,  $\gamma$  are related by the constraint
- $k = \gamma + \alpha \log \frac{\lambda+1}{\lambda}$ . For both stages we used a least squares method in order
- to fit the moments.
- See Fig 5 for the graph of the fitted von Bertalanffy function and the
- empirical means with error bars.
- This method produces an estimate of the mean and variance of  $L_{\infty}$  without
- assuming any distribution for  $L_{\infty}$ . The estimates are  $\alpha = 1.3$ ,  $\lambda = 15$ ,
- <sub>417</sub>  $\gamma = 0.55, k = 0.63, t_0 = 0.072, E(L_{\infty}) = 297.3$  and  $\sigma_{L_{\infty}}^2 = 160$ . Finally, in
- order to obtain a concrete and visually appreciable estimate of the density of
- each cohort, we computed it numerically assuming for  $L_{\infty}$  a Gamma
- distribution having parameters matching the estimated mean and variance,
- that is with parameters  $\alpha_0 = 552.34$  and  $\lambda_0 = 1.86$ . Figure 6 produces a
- comparison between the density obtained as described above from the model

- and an empirical density, produced from the data with a usual kernel
- estimator. Taking into account the limited number of parameters employed
- by this model one can appreciate the nice fit for some of the cohorts.
- Discrepancies can be found for the first two cohorts and for the sixth one.
- For the fifth one there is a evident discrepancy: notice however that, as
- pointed out in Fig 5, also the estimated VBFG curve that fits the mean of
- this fifth cohort. At this point one should keep in mind Note 4.2.

#### <sup>430</sup> 7 Discussion

- 431 Although several stochastic model are available in the literature in order to
- compute the time evolution of the distribution of the size of a population, a
- certain number of drawbacks still remain, leading to the need of a more
- 434 appropriate formulation that is able to take into account some key aspects of
- 435 animal growth.
- These aspects basically concern the inclusion of the different sources of
- variability in growth rate among individuals, which directly determine the
- size density observed at different ages, and the property of the growth
- 439 process of being increasing. In this work we developed two models based on
- the use of subordinators as driving processes. Our aim was to provide a new
- stochastic model, mainly of theoretical interest for the description of the
- growth process for a large class of organisms. It turns out that one of them,
- the model based on the Doléans exponential giving rise to a Gamma process,
- 444 is also able to produce an appreciable fit with the data. In particular it is
- able to reproduce the non monotonic trend of the variance, that is the
- measure of intra-cohort variability of size. This is an important feature: a

- reduction of the demographic variance starting at some time is often
- observed in data (Gudmundsson, 2005 e.g.).
- In general, the variability in individual size increases within the same cohort
- through time when the individual growth rate is positively correlated with
- itself in time (Gudmundsson, 2005). This phenomenon is called "growth
- depensation".
- 453 Conversely, a reduction of the cohort variance (the so called "growth
- compensation") has been up to now explained with the fact that survival of
- individuals are not independent and identically distributed (Kendall & Fox,
- <sup>456</sup> 2002). In other words, there needs to be some systematic structure in the
- population. Common biological mechanisms that can produce a reduction of
- demographic variance are contest competition (including territoriality),
- 459 long-lived individuals with lifetime demographic traits ("individual
- heterogeneity"), maternally imposed variation, and directional or balancing
- selection.
- 462 Observe however that our model explains this typical behaviour of the
- variance without introducing an explicit selection mechanism related to some
- size-dependent mortality. By this we do not claim that such a mechanism
- does not exist (and we think that it might be natural to devise a more
- 466 sofisticated model including this feature), but simply that it is not necessary
- in order to explain the observed behavior of the empirical variances.
- The possibility to model and predict this aspect of fish growth seems to be of
- great importance in both theoretical studies and fishery management
- applications. This is particularly true if referred to the increasing use of
- measurement of the growth pattern of organisms (like fish) as an ecological

- indicator (Bennett et al., 1995). Further, assessment of growth pattern,
- 473 combined with other measurement of physiological condition, have the
- 474 potential to yield information on the history of environmental stress (e.g.
- from contaminants) or selective pressures (e.g. fisheries) and adaptation to
- environmental change (Jorgensen et al., 2007). In fact, statistical analyses of
- 477 long-term data from some exploited fish stocks have revealed evolutionary
- changes in reaction norms (Ernande et al., 2004). Accuracy of the growth
- 479 model at the basis of these analyses obviously affect the results, so that the
- development of sound approach to model and predict size distribution is a
- 481 main target.
- 482 A future direction will concern the assessment of the effect of the aging error
- on the estimates obtained using our model. Even if the aging method is
- reliable, it seems that errors in aging young cohorts can significantly affect
- the estimates. This is due to the fact that both VBGF and the variance
- 486 function converge with age.
- The present work represent a first attempt to apply the Lévy processes to
- the subject. We think that these and the ideas developed in this paper can
- be adapted to introduce stochasticity into more complex models of growth
- 490 (see Edwards *et al.*, 2007).

#### 491 8 Conclusion

- The aim of the present work was the development of a stochastic model of
- 493 growth, and therefore an Individual Based Model for the distribution of
- data, that is compatible with the von Bertalanffy function and might be able
- to catch more of the features empirically observed.

- The model developed in relation with the Doléans exponential shows
- interesting features. As other models already in the literature (Wang, 1999;
- Gudmundsson, 2005; Lv & Pitchford, 2007) it is able to explain the observed
- non monotonic behaviour of the variances. However, it is the first stochastic
- model producing paths that are increasing, thus, giving a realistic random
- model of individual growth.
- our main objective was mainly theoretical, but we think that the models
- $_{503}$  developed in  $\S 4$  can be of interest for practical applications such as stock
- assessment and forecasting. In this direction however some questions require
- 505 a deeper investigation.
- 506 These are
- The determination (elicitation) of a suitable distribution for the maximal
- size  $L_{\infty}$ .
- The determination of the appropriate subordinator.

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Fig. 1

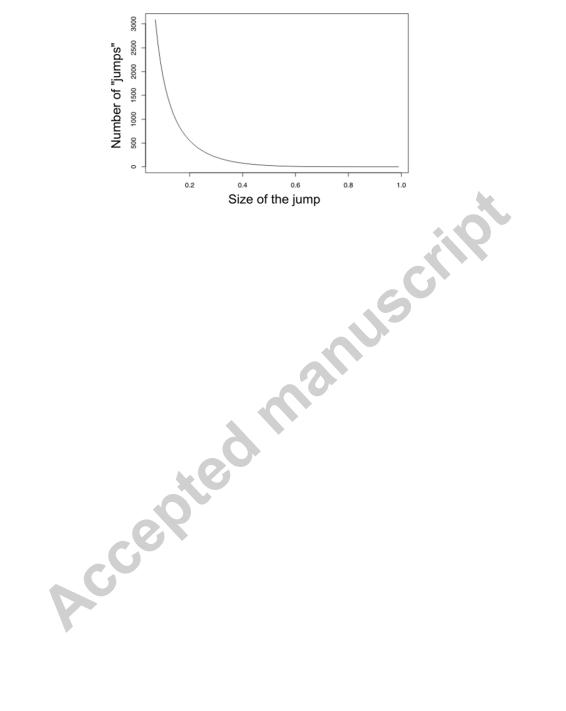


Fig. 2

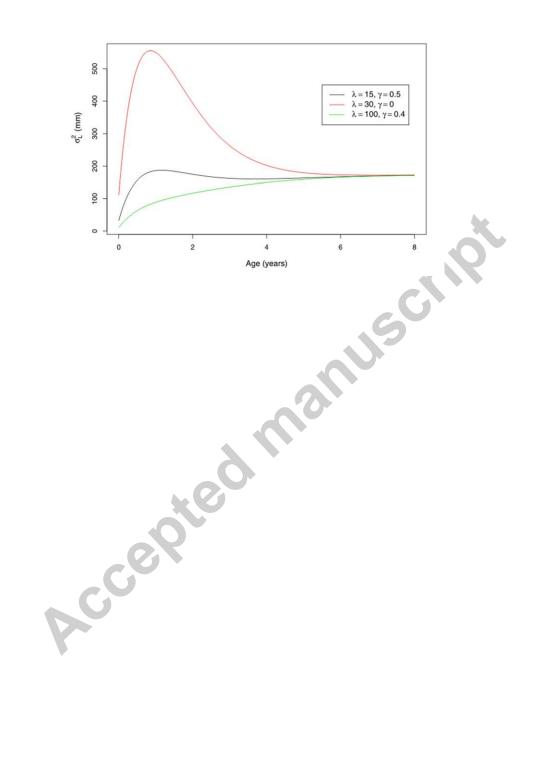


Fig. 3

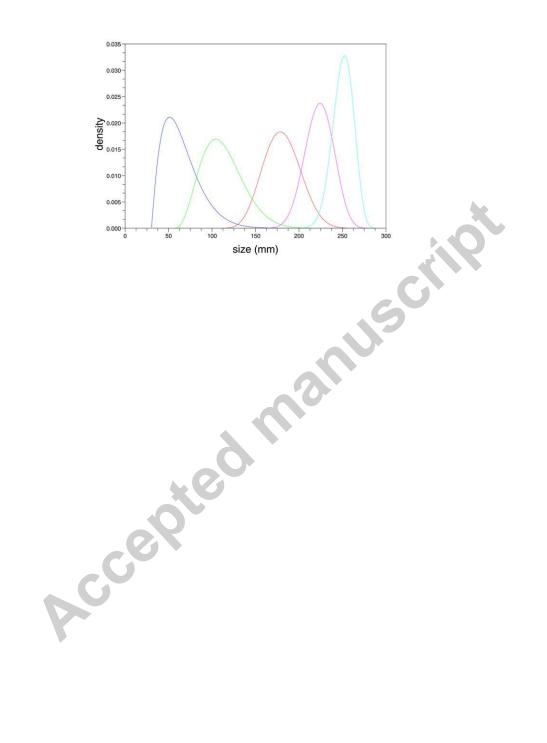


Fig. 4

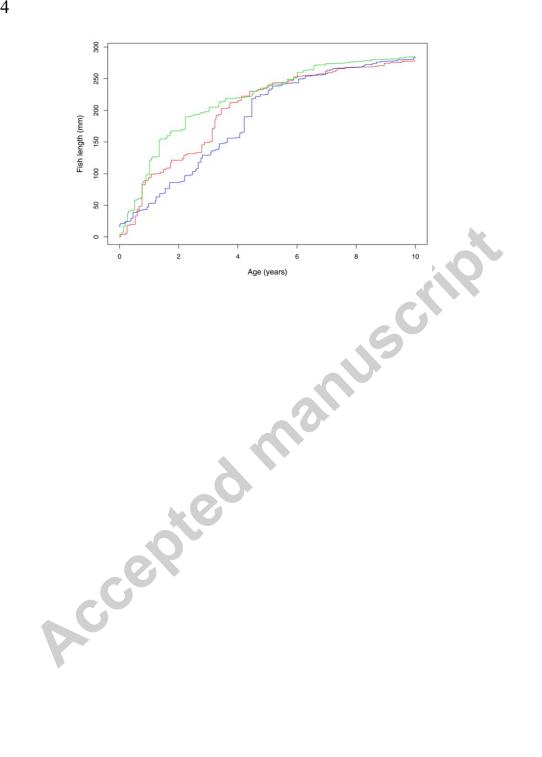


Fig. 5

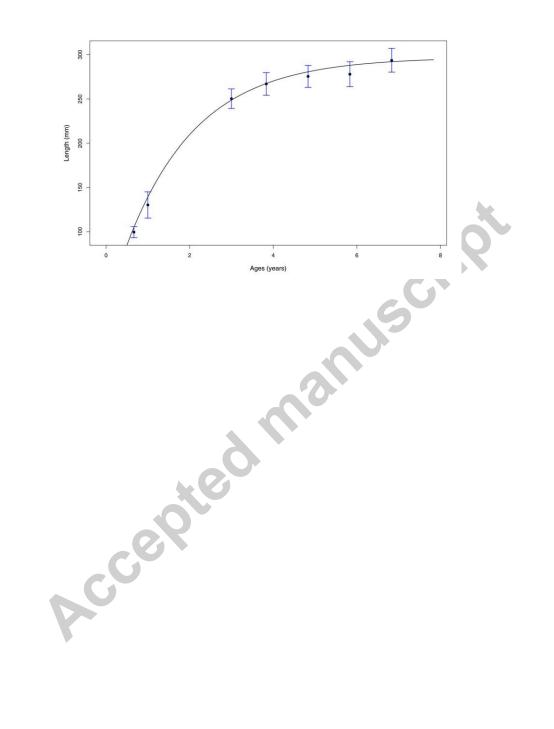


Fig. 6

