Stochastic algorithms for computing means of probability measures

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STOCHASTIC ALGORITHMS FOR COMPUTING MEANS OF PROBABILITY MEASURES

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Abstract. Consider a probability measure μ supported by a regular geodesic ball in a manifold. For any $p \geq 1$ we define a stochastic algorithm which converges almost surely to the p-mean e_p of μ. Assuming furthermore that the functional to minimize is regular around e_p, we prove that a natural renormalization of the inhomogeneous Markov chain converges in law into an inhomogeneous diffusion process. We give an explicit expression of this process, as well as its local characteristic.

Contents

1. Introduction

The geometric barycenter of a set of points is the point which minimizes the sum of the distances at the power 2 to these points. It is the most common estimator is statistics, however it is sensitive to outliers, and it is natural to replace power 2 by p for some $p \in [1, 2)$, which leads to the definition of p-mean. When $p = 1$, the minimizer is the median of the set of points, very often used in robust statistics. In many applications, p-means with some $p \in (1, 2)$ give the best compromise.

The Fermat-Weber problem concerns finding the median e_1 of a set of points in an Euclidean space. Numerous authors worked out algorithms for computing e_1. The first algorithm was proposed by Weiszfeld in [21]. It has been extended to

sufficiently small domains in Riemannian manifolds with nonnegative curvature by Fletcher and al in [7]. A complete generalization to manifolds with positive or negative curvature, including existence and uniqueness results (under some convexity conditions in positive curvature), has been given by one of the authors in [22].

The Riemannian barycenter or Karcher mean of a set of points in a manifold or more generally of a probability measure has been extensively studied, see e.g. [8], [10], [11], [5], [18], [2], where questions of existence, uniqueness, stability, relation with martingales in manifolds, behaviour when measures are pushed by stochastic flows have been considered. The Riemannian barycenter corresponds to $p = 2$ in the above description. Computation of Riemannian barycenters by gradient descent has been performed by Le in [13].

In [1] Afsari proved existence and uniqueness of p-means, $p \geq 1$ on geodesic balls with radius $r < \frac{1}{2}\min\left\{\mathrm{inj}(M), \frac{\pi}{2\alpha}\right\}$ if $p \in [1,2)$, and $r < \frac{1}{2}\min\left\{\mathrm{inj}(M), \frac{\pi}{\alpha}\right\}$ if $p \geq 2$. Here $\mathrm{inj}(M)$ is the injectivity radius of M and $\alpha > 0$ is such that the sectional curvatures in M are bounded above by α^2. The point is that in the case $p \geq 2$, the functional to minimize is not convex any more, which makes the situation much more difficult to handle.

In this paper, under the assumptions of [1] we provide in Theorem 2.3 stochastic algorithms which converge almost surely to p-means in manifolds, which are easier to implement than gradient descent algorithm since computing the gradient of the function to minimize is not needed. The idea is at each step to go in the direction of a point of the support of μ. The point is chosen at random according to μ and the size of the step is a well chosen function of the distance to the point, p and the number of the step. For general convergence results on recursive stochastic algorithms, see [14] Theorem 1. However they do not cover the manifold case and nonlinearity of geodesics. Here we give a proof using martingale convergence theorem, and the main point consists in determining and estimating all the geometric quantities, checking that under our curvature conditions all the convergence assumptions are fulfilled, since our processes live in manifolds. See also [3] for convergence in probability of recursive algorithms.

The speed of convergence is studied, and in theorem 2.6 we prove that the renormalized inhomogeneous Markov chain of Theorem 2.3 converges in law to an inhomogeneous diffusion process. This is an invariance principle type result, see e.g. [9], [15], [4], [6] for related works. Here again the main point is to obtain the characteristics of the limiting process from the curvature conditions, the conditions on the support of the mesure and estimates on Jacobi fields. Moreover we consider convergence in law for the Skorohod topology, and the limit depends in a crucial way on the decreasing steps of the algorithms.

Finally Section 4 is devoted to simulations.

2. Results

2.1. **p-means in regular geodesic balls.** Let M be a Riemannian manifold with pinched sectional curvatures. Let $\alpha, \beta > 0$ such that α^2 is a positive upper bound for sectional curvatures on M, and $-\beta^2$ is a negative lower bound for sectional curvatures on M. Denote by ρ the Riemannian distance on M.

In M consider a geodesic ball $B(a,r)$ with $a \in M$. Let μ be a probability measure with support included in a compact convex subset K_μ of $B(a,r)$. Fix $p \in [1,\infty)$. We will always make the following assumptions on (r,p,μ):

Assumption 2.1. The support of μ is not reduced to one point. Either $p > 1$ or the support of μ is not contained in a line, and the radius r satisfies

$$r < r_{\alpha,p} \quad \text{with} \begin{cases} r_{\alpha,p} = \frac{1}{2}\min\left\{\mathrm{inj}(M), \frac{\pi}{2\alpha}\right\} & \text{if } p \in [1,2) \\ r_{\alpha,p} = \frac{1}{2}\min\left\{\mathrm{inj}(M), \frac{\pi}{\alpha}\right\} & \text{if } p \in [2,\infty) \end{cases} \tag{2.1}$$

Note that $B(a,r)$ is convex if $r < \frac{1}{2}\min\left\{\mathrm{inj}(M), \frac{\pi}{\alpha}\right\}$.

Under assumption 2.1, it has been proved in [1] (Theorem 2.1) that the function

$$\begin{aligned} H_p : B(a,r) &\to \mathbb{R}_+ \\ x &\mapsto \int_M \rho^p(x,y)\mu(dy) \end{aligned} \tag{2.2}$$

has a unique minimizer e_p in M, the p-mean of μ, and moreover $e_p \in B(a,r)$. If $p = 1$, e_1 is the median of μ.

It is easily checked that if $p \in [1,2)$, then H_p is strictly convex on $B(a,r)$. On the other hand, if $p \geq 2$ then H_p is of class C^2 on $B(a,r)$.

Proposition 2.2. *Let K be a convex subset of $B(a,r)$ containing the support of μ. Then there exists $C_{p,\mu,K} > 0$ such that for all $x \in K$,*

$$H_p(x) - H_p(e_p) \geq \frac{C_{p,\mu,K}}{2}\rho(x,e_p)^2. \tag{2.3}$$

Moreover if $p \geq 2$ then we can choose $C_{p,\mu,K}$ so that for all $x \in K$,

$$\|\operatorname{grad}_x H_p\|^2 \geq C_{p,\mu,K}\left(H_p(x) - H_p(e_p)\right). \tag{2.4}$$

In the sequel, we fix

$$K = \bar{B}(a, r-\varepsilon) \quad \text{with} \quad \varepsilon = \frac{\rho(K_\mu, B(a,r)^c)}{2}. \tag{2.5}$$

We now state our main result: we define a stochastic gradient algorithm $(X_k)_{k\geq 0}$ to approximate the median e_p and prove its convergence.

Theorem 2.3. *Let $(P_k)_{k\geq 1}$ be a sequence of independent $B(a,r)$-valued random variables, with law μ. Let $(t_k)_{k\geq 1}$ be a sequence of positive numbers satisfying*

$$\forall k \geq 1, \quad t_k \leq \min\left(\frac{1}{C_{p,\mu,K}}, \frac{\rho(K_\mu, B(a,r)^c)}{2p(2r)^{p-1}}\right), \tag{2.6}$$

$$\sum_{k=1}^{\infty} t_k = +\infty \quad \textit{and} \quad \sum_{k=1}^{\infty} t_k^2 < \infty. \tag{2.7}$$

Letting $x_0 \in K$, define inductively the random walk $(X_k)_{k\geq 0}$ by

$$X_0 = x_0 \quad \textit{and for } k \geq 0 \quad X_{k+1} = \exp_{X_k}\left(-t_{k+1}\operatorname{grad}_{X_k} F_p(\cdot, P_{k+1})\right) \tag{2.8}$$

where $F_p(x,y) = \rho^p(x,y)$, with the convention $\operatorname{grad}_x F_p(\cdot,x) = 0$.

The random walk $(X_k)_{k\geq 1}$ converges in L^2 and almost surely to e.

In the following example, we focus on the case $M = \mathbb{R}^d$ and $p = 2$ where drastic simplifications occur.

Example 2.4. In the case when $M = \mathbb{R}^d$ and μ is a compactly supported probability measure on $\mathbb{R}^d$, the stochastic gradient algorithm (2.8) simplifies into

$$X_0 = x_0 \quad \text{and for } k \geq 0 \quad X_{k+1} = X_k - t_{k+1} \operatorname{grad}_{X_k} F_p(\cdot, P_{k+1}).$$

If furthermore $p = 2$, clearly $e_2 = \mathbb{E}[P_1]$ and $\operatorname{grad}_x F_p(\cdot, y) = 2(x - y)$, so that the linear relation

$$X_{k+1} = (1 - 2t_{k+1}X_k) + 2t_{k+1}P_{k+1}, \quad k \geq 0$$

holds true and an easy induction proves that

$$X_k = x_0 \prod_{j=0}^{k-1}(1 - 2t_{k-j}) + 2\sum_{j=0}^{k-1} P_{k-j} t_{k-j} \prod_{\ell=0}^{j-1}(1 - 2t_{k-\ell}), \quad k \geq 1. \tag{2.9}$$

Now, taking $t_k = \dfrac{1}{2k}$, we have

$$\prod_{j=0}^{k-1}(1 - 2t_{k-j}) = 0 \quad \text{and} \quad \prod_{\ell=0}^{j-1}(1 - 2t_{k-\ell}) = \frac{k-j}{k}$$

so that

$$X_k = \sum_{j=0}^{k-1} P_{k-j} \frac{1}{k} = \frac{1}{k}\sum_{j=1}^{k} P_j.$$

The stochastic gradient algorithm estimating the mean e_2 of μ is given by the empirical mean of a growing sample of independent random variables with distribution μ. In this simple case, the result of Theorem 2.3 is nothing but the strong law of large numbers. Moreover, fluctuations around the mean are given by the central limit theorem and Donsker's theorem.

2.2. **Fluctuations of the stochastic gradient algorithm.** The notations are the same as in the beginning of section 2.1. We still make assumption 2.1. Let us define K and ε as in (2.5) and let

$$\delta_1 = \min\left(\frac{1}{C_{p,\mu,K}}, \frac{\rho(K_\mu, B(a,r)^c)}{2p(2r)^{p-1}}\right). \tag{2.10}$$

We consider the time inhomogeneous M-valued Markov chain (2.8) in the particular case when

$$t_k = \min\left(\frac{\delta}{k}, \delta_1\right), \quad k \geq 1 \tag{2.11}$$

for some $\delta > 0$. The particular sequence $(t_k)_{k\geq 1}$ defined by (2.11) satisfies (2.6) and (2.7), so Theorem 2.3 holds true and the stochastic gradient algorithm $(X_k)_{k\geq 0}$ converges a.s. and in L^2 to the p-mean e_p.

In order to study the fluctuations around the p-mean e_p, we define for $n \geq 1$ the rescaled $T_{e_p}M$-valued Markov chain $(Y_k^n)_{k\geq 0}$ by

$$Y_k^n = \frac{k}{\sqrt{n}} \exp_{e_p}^{-1} X_k. \tag{2.12}$$

We will prove convergence of the sequence of process $(Y^n_{[nt]})_{0\leq t\leq 1}$ to a non-homogeneous diffusion process. The limit process is defined in the following proposition:

Proposition 2.5. *Assume that H_p is C^2 in a neighborhood of e_p, and that $\delta > C_{p,\mu,K}^{-1}$. Define*

$$\Gamma = \mathbb{E}\left[\mathrm{grad}_{e_p} F_p(\cdot, P_1) \otimes \mathrm{grad}_{e_p} F_p(\cdot, P_1)\right]$$

and $G_\delta(t)$ the generator

$$G_\delta(t)f(y) := \langle d_y f, t^{-1}(y - \delta \nabla dH_p(y,\cdot)^\sharp)\rangle + \frac{1}{2}\mathrm{Hess}_y f\,(\Gamma) \tag{2.13}$$

where $\nabla dH_p(y,\cdot)^\sharp$ denotes the dual vector of the linear form $\nabla dH_p(y,\cdot)$.

There exists a unique inhomogeneous diffusion process $(y_\delta(t))_{t>0}$ on $T_{e_p}M$ with generator $G_\delta(t)$ and converging in probability to 0 as $t \to 0^+$.

The process y_δ is continuous, converges a.s. to 0 as $t \to 0^+$ and has the following integral representation:

$$y_\delta(t) = \sum_{i=1}^{d} t^{1-\delta\lambda_i} \int_0^t s^{\delta\lambda_i - 1}\langle \delta\sigma\, dB_s, e_i\rangle e_i, \quad t \geq 0, \tag{2.14}$$

where B_t is a standard Brownian motion on $T_{e_p}M$, $\sigma \in \mathrm{End}(T_{e_p}M)$ satisfies $\sigma\sigma^* = \Gamma$, $(e_i)_{1\leq i\leq d}$ is an orthonormal basis diagonalizing the symmetric bilinear form $\nabla dH_p(e_p)$ and $(\lambda_i)_{1\leq i\leq d}$ are the associated eigenvalues.

Note that the integral representation (2.14) implies that y_δ is the centered Gaussian process with covariance

$$\mathbb{E}\left[y_\delta^i(t_1) y_\delta^j(t_2)\right] = \frac{\delta^2 \Gamma(e_i^* \otimes e_j^*)}{\delta(\lambda_i + \lambda_j) - 1} t_1^{1-\delta\lambda_i} t_2^{1-\delta\lambda_j} (t_1 \wedge t_2)^{\delta(\lambda_i+\lambda_j)-1}, \tag{2.15}$$

where $y_\delta^i(t) = \langle y_\delta(t), e_i\rangle$, $1 \leq i, j \leq d$ and $t_1, t_2 \geq 0$.

Our main result on the fluctuations of the stochastic gradient algorithm is the following:

Theorem 2.6. *Assume that H_p is C^2 in a neighborhood of e_p, and that $\delta > C_{p,\mu,K}^{-1}$. The sequence of processes $\left(Y_{[nt]}^n\right)_{t\geq 0}$ weakly converges in $\mathbb{D}((0,\infty), T_{e_p}M)$ to y_δ.*

Remark 2.7. From section 2.1 we know that, when $p \in (1, 2]$, the constant

$$C_{p,\mu,K} = p(2r)^{p-2}\left(\min\left(p - 1, 2\alpha r \cot\left(2\alpha r\right)\right)\right)$$

is explicit. The constraint $\delta > C_{p,\mu,K}^{-1}$ can easily be checked in this case.

Remark 2.8. In the case $M = \mathbb{R}^d$, $Y_k^n = \frac{k}{\sqrt{n}}(X_k - e_p)$ and the tangent space $T_{e_p}M$ is identified to $\mathbb{R}^d$. Theorem 2.6 holds and, in particular, when $t = 1$, we obtain a central limit Theorem: $\sqrt{n}(X_n - e)$ converges as $n \to \infty$ to a centered Gaussian d-variate distribution (with covariance structure given by (2.15) with $t_1 = t_2 = 1$). This is a central limit theorem: the fluctuations of the stochastic gradient algorithm are of scale $n^{-1/2}$ and asymptotically Gaussian.

3. Proofs

For simplicity, let us write shortly $e = e_p$ in the proofs.

3.1. **Proof of Proposition 2.2.**
For $p = 1$ this is a direct consequence of [22] Theorem 3.7.

Next we consider the case $p \in [1, 2)$.

Let $K \subset B(a, r)$ be a compact convex set containing the support of μ. Let $x \in K \backslash \{e\}$, $t = \rho(e, x)$, $u \in T_eM$ the unit vector such that $\exp_e(\rho(e, x)u) = x$, and γ_u the geodesic with initial speed u : $\dot{\gamma}_u(0) = u$. For $y \in K$, letting $h_y(s) = \rho(\gamma_u(s), y)^p$, $s \in [0, t]$, we have since $p > 1$

$$h_y(t) = h_y(0) + th'_y(0) + \int_0^t (t - s)h''_y(s)\, ds$$

with the convention $h''_y(s) = 0$ when $\gamma_u(s) = y$. Indeed, if $y \notin \gamma([0, t])$ then h_y is smooth, and if $y \in \gamma([0, t])$, say $y = \gamma(s_0)$ then $h_y(s) = |s - s_0|^p$ and the formula can easily be checked.

By standard calculation,

$$\begin{aligned} &h''_y(s) \\ &\geq p\rho(\gamma_u(s), y)^{p-2} \\ &\quad \times \Big((p-1)\|\dot{\gamma}_u(s)^{T(y)}\|^2 + \|\dot{\gamma}_u(s)^{N(y)}\|^2 \alpha\rho(\gamma_u(s), y) \cot(\alpha\rho(\gamma_u(s), y))\Big) \end{aligned} \tag{3.1}$$

with $\dot{\gamma}_u(s)^{T(y)}$ (resp. $\dot{\gamma}_u(s)^{N(y)}$) the tangential (resp. the normal) part of $\dot{\gamma}_u(s)$ with respect to $n(\gamma_u(s), y) = \dfrac{1}{\rho(\gamma_u(s), y)} \exp^{-1}_{\gamma_u(s)}(y)$:

$$\dot{\gamma}_u(s)^{T(y)} = \langle \dot{\gamma}_u(s), n(\gamma_u(s), y)\rangle n(\gamma_u(s), y), \quad \dot{\gamma}_u(s)^{N(y)} = \dot{\gamma}_u(s) - \dot{\gamma}_u(s)^{T(y)}.$$

From this we get

$$h''_y(s) \geq p\rho(\gamma_u(s), y)^{p-2} (\min(p - 1, 2\alpha r \cot(2\alpha r))). \tag{3.2}$$

Now

$$\begin{aligned} &H_p(\gamma_u(t')) \\ &= \int_{B(a,r)} h_y(\gamma_u(t'))\, \mu(dy) \\ &= \int_{B(a,r)} h_y(0)\, \mu(dy) + t' \int_{B(a,r)} h'_y(0)\, \mu(dy) + \int_0^{t'} (t' - s) \int_{B(a,r)} h_y(s)''\, \mu(dy) \end{aligned}$$

and $H_p(\gamma_u(t'))$ attains its minimum at $t' = 0$, so $\displaystyle\int_{B(a,r)} h'_y(0)\, \mu(dy) = 0$ and we have

$$H_p(x) = H_p(\gamma_u(t)) = H_p(e) + \int_0^t (t - s) \int_{B(a,r)} h_y(s)''\, \mu(dy).$$

Using Equation (3.2) we get

$$\begin{aligned} &H_p(x) \geq H_p(e) \\ &+ \int_0^t \left((t - s) \int_{B(a,r)} p\rho(\gamma_u(s), y)^{p-2} (\min(p - 1, 2\alpha r \cot(2\alpha K r)))\ \mu(dy) \right) ds. \end{aligned} \tag{3.3}$$

Since $p \leq 2$ we have $\rho(\gamma_u(s), y)^{p-2} \geq (2r)^{p-2}$ and

$$H_p(x) \geq H_p(e) + \frac{t^2}{2} p(2r)^{p-2} \left(\min\left(p-1, 2\alpha r \cot\left(2\alpha r\right)\right)\right). \tag{3.4}$$

So letting

$$C_{p,\mu,K} = p(2r)^{p-2} \left(\min\left(p-1, 2\alpha r \cot\left(2\alpha r\right)\right)\right)$$

we obtain

$$H_p(x) \geq H_p(e) + \frac{C_{p,\mu,K}\rho(e,x)^2}{2}. \tag{3.5}$$

To finish let us consider the case $p \geq 2$.

In the proof of [1] Theorem 2.1, it is shown that e is the only zero of the maps $x \mapsto \operatorname{grad}_x H_p$ and $x \mapsto H_p(x) - H_p(e)$, and that $\nabla dH_p(e)$ is strictly positive. This implies that (2.3) and (2.4) hold on some neighbourhood $B(e,\varepsilon)$ of e. By compactness and the fact that $H_p - H_p(e)$ and $\operatorname{grad} H_p$ do not vanish on $K\backslash B(e,\varepsilon)$ and $H_p - H_p(e)$ is bounded, possibly modifying the constant $C_{p,\mu,K}$, (2.3) and (2.4) also holds on $K\backslash B(e,\varepsilon)$.

□

3.2. **Proof of Theorem 2.3.**
Note that, for $x \neq y$,

$$\operatorname{grad}_x F(\cdot, y) = p\rho^{p-1}(x,y)\frac{-\exp_x^{-1}(y)}{\rho(x,y)} = -p\rho^{p-1}(x,y)n(x,y),$$

whith $n(x,y) := \dfrac{\exp_x^{-1}(y)}{\rho(x,y)}$ a unit vector. So, with the condition (2.6) on t_k, the random walk $(X_k)_{k\geq 0}$ cannot exit K: if $X_k \in K$ then there are two possibilities for X_{k+1}:

- either X_{k+1} is in the geodesic between X_k and P_{k+1} and belongs to K by convexity of K;
- or X_{k+1} is after P_{k+1}, but since

$$\begin{aligned}\left\|t_{k+1}\operatorname{grad}_{X_k} F_p(\cdot, P_{k+1})\right\| &= t_{k+1}p\rho^{p-1}(X_k, P_{k+1}) \\ &\leq \frac{\rho(K_\mu, B(a,r)^c)}{2p(2r)^{p-1}} p\rho^{p-1}(X_k, P_{k+1}) \\ &\leq \frac{\rho(K_\mu, B(a,r)^c)}{2},\end{aligned}$$

  we have in this case

$$\rho(P_{k+1}, X_{k+1}) \leq \frac{\rho(K_\mu, B(a,r)^c)}{2}$$

  which implies that $X_{k+1} \in K$.

First consider the case $p \in [1,2)$.

For $k \geq 0$ let

$$t \mapsto E(t) := \frac{1}{2}\rho^2\left(e, \gamma(t)\right),$$

$\gamma(t)_{t\in[0,t_{k+1}]}$ the geodesic satisfying $\dot\gamma(0) = -\operatorname{grad}_{X_k} F_p(\cdot, P_{k+1})$. We have for all $t \in [0, t_{k+1}]$

$$E''(t) \leq C(\beta, r, p) := p^2(2r)^{2p-1}\beta \operatorname{cotanh}(2\beta r) \tag{3.6}$$

(see e.g. [22]). By Taylor formula,

$$\begin{aligned}
&\rho(X_{k+1},e)^2\\
&= 2E(t_{k+1})\\
&= 2E(0) + 2t_{k+1}E'(0) + t_{k+1}^2 E''(t) \quad \text{for some } t\in[0,t_{k+1}]\\
&\leq \rho(X_k,e)^2 + 2t_{k+1}\langle \mathrm{grad}_{X_k} F_p(\cdot,P_{k+1}), \exp_{X_k}^{-1}(e)\rangle + t_{k+1}^2 C(\beta,r,p).
\end{aligned}$$

Now from the convexity of $x\mapsto F_p(x,y)$ we have for all $x,y\in B(a,r)$

$$F_p(e,y) - F_p(x,y) \geq \left\langle \mathrm{grad}_x F_p(\cdot,y), \exp_x^{-1}(e)\right\rangle. \tag{3.7}$$

This applied with $x=X_k$, $y=P_{k+1}$ yields

$$\rho(X_{k+1},e)^2 \leq \rho(X_k,e)^2 - 2t_{k+1}\left(F_p(X_k,P_{k+1}) - F_p(e,P_{k+1})\right) + C(\beta,r,p)t_{k+1}^2. \tag{3.8}$$

Letting for $k\geq 0$ $\mathscr{F}_k = \sigma(X_\ell, 0\leq \ell\leq k)$, we get

$$\begin{aligned}
&\mathbb{E}\left[\rho(X_{k+1},e)^2|\mathscr{F}_k\right]\\
&\leq \rho(X_k,e)^2 - 2t_{k+1}\int_{B(a,r)}\left(F_p(X_k,y) - F_p(e,y)\right)\mu(dy) + C(\beta,r,p)t_{k+1}^2\\
&= \rho(X_k,e)^2 - 2t_{k+1}\left(H_p(X_k) - H_p(e)\right) + C(\beta,r,p)t_{k+1}^2\\
&\leq \rho(X_k,e)^2 + C(\beta,r,p)t_{k+1}^2
\end{aligned}$$

so that the process $(Y_k)_{k\geq 0}$ defined by

$$Y_0 = \rho(X_0,e)^2 \quad \text{and for } k\geq 1 \quad Y_k = \rho(X_k,e)^2 - C(\beta,r,p)\sum_{j=1}^k t_j^2 \tag{3.9}$$

is a bounded supermartingale. So it converges in L^1 and almost surely. Consequently $\rho(X_k,e)^2$ also converges in L^1 and almost surely.

Let

$$a = \lim_{k\to\infty}\mathbb{E}\left[\rho(X_k,e)^2\right]. \tag{3.10}$$

We want to prove that $a=0$. We already proved that

$$\mathbb{E}\left[\rho(X_{k+1},e)^2|\mathscr{F}_k\right] \leq \rho(X_k,e)^2 - 2t_{k+1}\left(H_p(X_k) - H_p(e)\right) + C(\beta,r,p)t_{k+1}^2. \tag{3.11}$$

Taking the expectation and using Proposition 2.2, we obtain

$$\mathbb{E}\left[\rho(X_{k+1},e)^2\right] \leq \mathbb{E}\left[\rho(X_k,e)^2\right] - t_{k+1}C_{p,\mu,K}\mathbb{E}\left[\rho(X_k,e)^2\right] + C(\beta,r,p)t_{k+1}^2. \tag{3.12}$$

An easy induction proves that for $\ell\geq 1$,

$$\mathbb{E}\left[\rho(X_{k+\ell},e)^2\right] \leq \prod_{j=1}^{\ell}(1 - C_{p,\mu,K}t_{k+j})\mathbb{E}\left[\rho(X_k,e)^2\right] + C(\beta,r,p)\sum_{j=1}^{\ell} t_{k+j}^2. \tag{3.13}$$

Letting $\ell\to\infty$ and using the fact that $\sum_{j=1}^\infty t_{k+j} = \infty$ which implies

$$\prod_{j=1}^{\infty}(1 - C_{p,\mu,K}t_{k+j}) = 0,$$

we get

$$a \leq C(\beta, r, p) \sum_{j=1}^{\infty} t_{k+j}^2. \tag{3.14}$$

Finally using $\sum_{j=1}^{\infty} t_j^2 < \infty$ we obtain that $\lim_{k\to\infty} \sum_{j=1}^{\infty} t_{k+j}^2 = 0$, so $a = 0$. This proves L^2 and almost sure convergence.

Next assume that $p \geq 2$.

For $k \geq 0$ let

$$t \mapsto E_p(t) := H_p(\gamma(t)),$$

$\gamma(t)_{t\in[0,t_{k+1}]}$ the geodesic satisfying $\dot\gamma(0) = -\operatorname{grad}_{X_k} F_p(\cdot, P_{k+1})$. With a calculation similar to (3.6) we get for all $t \in [0, t_{k+1}]$

$$E_p''(t) \leq 2C(\beta, r, p) := \frac{p^3}{2}(2r)^{3p-4}\left(2r\beta \operatorname{cotanh}(2\beta r) + 2p - 4\right). \tag{3.15}$$

(see e.g. [22]). By Taylor formula,

$$\begin{aligned} H_p(X_{k+1}) &= E_p(t_{k+1}) \\ &= E_p(0) + t_{k+1}E_p'(0) + \frac{t_{k+1}^2}{2}E_p''(t) \quad \text{for some } t \in [0, t_{k+1}] \\ &\leq H_p(X_k) + t_{k+1}\langle d_{X_k}H_p, \operatorname{grad}_{X_k} F_p(\cdot, P_{k+1})\rangle + t_{k+1}^2 C(\beta, r, p). \end{aligned}$$

We get

$$\begin{aligned} &\mathbb{E}\left[H_p(X_{k+1})|\mathscr{F}_k\right] \\ &\leq H_p(X_k) - t_{k+1}\left\langle d_{X_k}H_p, \int_{B(a,r)} \operatorname{grad}_{X_k} F_p(\cdot, y)\mu(dy)\right\rangle + C(\beta, r, p)t_{k+1}^2 \\ &= H_p(X_k) - t_{k+1}\left\langle d_{X_k}H_p, \operatorname{grad}_{X_k} H_p(\cdot)\right\rangle + C(\beta, r, p)t_{k+1}^2 \\ &= H_p(X_k) - t_{k+1}\left\|\operatorname{grad}_{X_k} H_p(\cdot)\right\|^2 + C(\beta, r, p)t_{k+1}^2 \\ &\leq H_p(X_k) - C_{p,\mu,K}t_{k+1}\left(H_p(X_k) - H_p(e)\right) + C(\beta, r, p)t_{k+1}^2 \end{aligned}$$

(by Proposition 2.2) so that the process $(Y_k)_{k\geq 0}$ defined by

$$Y_0 = H_p(X_0) - H_p(e) \quad \text{and for } k \geq 1 \quad Y_k = H_p(X_k) - H_p(e) - C(\beta, r, p)\sum_{j=1}^{k} t_j^2 \tag{3.16}$$

is a bounded supermartingale. So it converges in L^1 and almost surely. Consequently $H_p(X_k) - H_p(e)$ also converges in L^1 and almost surely.

Let

$$a = \lim_{k\to\infty} \mathbb{E}\left[H_p(X_k) - H_p(e)\right]. \tag{3.17}$$

We want to prove that $a = 0$. We already proved that

$$\begin{aligned} &\mathbb{E}\left[H_p(X_{k+1}) - H_p(e)|\mathscr{F}_k\right] \\ &\leq H_p(X_k) - H_p(e) - C_{p,\mu,K}t_{k+1}\left(H_p(X_k) - H_p(e)\right) + C(\beta, r, p)t_{k+1}^2. \end{aligned} \tag{3.18}$$

Taking the expectation we obtain

$$\mathbb{E}\left[H_p(X_{k+1}) - H_p(e)\right] \leq (1 - t_{k+1}C_{p,\mu,K})\mathbb{E}\left[H_p(X_k) - H_p(e)\right] + C(\beta, r, p)t_{k+1}^2 \tag{3.19}$$

so that proving that $a = 0$ is similar to the previous case.

Finally (2.3) proves that $\rho(X_k, e)^2$ converges in L^1 and almost surely to 0. □

3.3. **Proof of Proposition 2.5.** Fix $\varepsilon > 0$. Any diffusion process on $[\varepsilon, \infty)$ with generator $G_\delta(t)$ is solution of a sde of the type

$$dy_t = \frac{1}{t}L_\delta(y_t)\,dt + \delta\sigma\,dB_t \tag{3.20}$$

where $L_\delta(y) = y - \delta\nabla dH_p(y, \cdot)^\sharp$ and B_t and σ are as in Proposition 2.5. This sde can be solved explicitely on $[\varepsilon, \infty)$. The symmetric endomorphism $y \mapsto \nabla dH_p(y, \cdot)^\sharp$ is diagonalisable in the orthonormal basis $(e_i)_{1\leq i\leq d}$ with eigenvalues $(\lambda_i)_{1\leq i\leq d}$. The endomorphism $L_\delta = \mathrm{id} - \delta\nabla dH_p(e)(\mathrm{id}, \cdot)^\sharp$ is also diagonalisable in this basis with eigenvalues $(1 - \delta\lambda_i)_{1\leq i\leq d}$. The solution $y_t = \sum_{i=1}^d y_t^i e_i$ of (3.20) started at $y_\varepsilon = \sum_{i=1}^d y_\varepsilon^i e_i$ is given by

$$y_t = \sum_{i=1}^d \left(y_\varepsilon^i \varepsilon^{\delta\lambda_i - 1} + \int_\varepsilon^t s^{\delta\lambda_i - 1}\langle \delta\sigma\,dB_s, e_i\rangle \right) t^{1-\delta\lambda_i} e_i, \quad t \geq \varepsilon. \tag{3.21}$$

Now by definition of $C_{p,\mu,K}$ we clearly have

$$C_{p,\mu,K} \leq \min_{1\leq i\leq d} \lambda_i. \tag{3.22}$$

So the condition $\delta C_{p,\mu,K} > 1$ implies that for all i, $\delta\lambda_i - 1 > 0$, and as $\varepsilon \to 0$,

$$\int_\varepsilon^t s^{\delta\lambda_i - 1}\langle \delta\sigma\,dB_s, e_i\rangle \to \int_0^t s^{\delta\lambda_i - 1}\langle \delta\sigma\,dB_s, e_i\rangle \quad \text{in probability.} \tag{3.23}$$

Assume that a continuous solution y_t converging in probability to 0 as $t \to 0^+$ exists. Since $y_\varepsilon^i \varepsilon^{\delta\lambda_i - 1} \to 0$ in probability as $\varepsilon \to 0$, we necessarily have using (3.23)

$$y_t = \sum_{i=1}^d t^{1-\delta\lambda_i} \int_0^t s^{\delta\lambda_i - 1}\langle \delta\sigma\,dB_s, e_i\rangle e_i, \quad t \geq 0. \tag{3.24}$$

Note y_δ^i is Gaussian with variance $\dfrac{t\delta^2\Gamma(e_i^* \otimes e_i^*)}{2\delta\lambda_i - 1}$, so it converges in L^2 to 0 as $t \to 0$. Conversely, it is easy to check that equation (3.24) defines a solution to (3.20).

To prove the a.s. convergence to 0 we use the representation

$$\int_0^t s^{\delta\lambda_i - 1}\langle \delta\sigma\,dB_s, e_i\rangle = B^i_{\varphi_i(t)}$$

where B_s^i is a Brownian motion and $\varphi_i(t) = \dfrac{\delta^2\Gamma(e_i^* \otimes e_i^*)}{2\delta\lambda_i - 1} t^{2\delta\lambda_i - 1}$. Then by the law of iterated logarithm

$$\limsup_{t\downarrow 0} t^{1-\delta\lambda_i} B^i_{\varphi_i(t)} \leq \limsup_{t\downarrow 0} t^{1-\delta\lambda_i} \sqrt{2\varphi_i(t)\ln\ln\left(\varphi_i^{-1}(t)\right)}$$

But for t small we have

$$\sqrt{2\varphi_i(t)\ln\ln\left(\varphi_i^{-1}(t)\right)} \leq t^{\delta\lambda_i - 3/4}$$

so

$$\limsup_{t\downarrow 0} t^{1-\delta\lambda_i} B^i_{\varphi_i(t)} \leq \lim_{t\downarrow 0} t^{1/4} = 0.$$

This proves a.s. convergence to 0. Continuity is easily checked using the integral representation (3.24). □

3.4. **Proof of Theorem 2.6.** Consider the time homogeneous Markov chain $(Z_k^n)_{k\geq 0}$ with state space $[0,\infty)\times T_eM$ defined by

$$Z_k^n = \left(\frac{k}{n}, Y_k^n\right). \tag{3.25}$$

The first component has a deterministic evolution and will be denoted by t_k^n; it satisfies

$$t_{k+1}^n = t_k^n + \frac{1}{n}, \quad k \geq 0. \tag{3.26}$$

Let k_0 be such that

$$\frac{\delta}{k_0} < \delta_1. \tag{3.27}$$

Using equations (2.8), (2.12) and (2.11), we have for $k \geq k_0$,

(3.28)
$$Y_{k+1}^n = \frac{nt_k^n+1}{\sqrt{n}} \exp_e^{-1}\left(\exp_{\exp_e \frac{1}{\sqrt{n}t_k^n} Y_k^n}\left(-\frac{\delta}{nt_k^n+1}\operatorname{grad}_{\frac{1}{\sqrt{n}t_k^n}Y_k^n} F_p(\cdot, P_{k+1})\right)\right).$$

Consider the transition kernel $P^n(z,dz')$ on $(0,\infty)\times T_eM$ defined for $z=(t,y)$ by

(3.29)
$$P^n(z,A) = \mathbb{P}\left[\left(t+\frac{1}{n}, \frac{nt+1}{\sqrt{n}}\exp_e^{-1}\left(\exp_{\exp_e\frac{1}{\sqrt{n}t}y}\left(-\frac{\delta}{nt+1}\operatorname{grad}_{\exp_e\frac{1}{\sqrt{n}t}y} F_p(\cdot,P_1)\right)\right)\right)\in A\right]$$

where $A \in \mathscr{B}((0,\infty)\times T_eM)$. Clearly this transition kernel drives the evolution of the Markov chain $(Z_k^n)_{k\geq k_0}$.

For the sake of clarity, we divide the proof of Theorem 2.6 into four lemmas.

Lemma 3.1. *Assume that for all $x \in B(a,r)$ the application $F_p(\cdot,x)$ is of class C^2 in a neighbourhood of e. Fix $\delta > 0$. Let B be a bounded set in T_eM and let $0<\varepsilon<T$. We have for all C^2 function f on T_eM*

(3.30)
$$\begin{aligned} &n\left(f\left(\frac{nt+1}{\sqrt{n}}\exp_e^{-1}\left(\exp_{\exp_e\frac{1}{\sqrt{n}t}y}\left(-\frac{\delta}{nt+1}\operatorname{grad}_{\exp_e\frac{1}{\sqrt{n}t}y}F_p(\cdot,x)\right)\right)\right)-f(y)\right)\\ &= \left\langle d_yf, \frac{y}{t}\right\rangle - \sqrt{n}\langle d_yf, \delta\operatorname{grad}_e F_p(\cdot,x)\rangle - \delta\nabla dF_p(\cdot,x)\left(\operatorname{grad}_y f, \frac{y}{t}\right)\\ &+\frac{\delta^2}{2}\mathrm{Hess}_y f\left(\operatorname{grad}_e F_p(\cdot,x)\otimes\operatorname{grad}_e F_p(\cdot,x)\right)+O\left(\frac{1}{\sqrt{n}}\right)\end{aligned}$$

uniformly in $y\in B$, $x\in K_\mu$, $t\in[\varepsilon,T]$.

Proof. Let $x \in K_\mu$, $y \in T_eM$, $u, v \in \mathbb{R}$ sufficiently close to 0, and $q = \exp_e\left(\frac{uy}{t}\right)$. For $s \in [0,1]$ denote by $a \mapsto c(a,s,u,v)$ the geodesic with endpoints $c(0,s,u,v) = e$ and

$$c(1,s,u,v) = \exp_{\exp_e\left(\frac{uy}{t}\right)}\left(-vs\,\mathrm{grad}_{\exp_e\left(\frac{uy}{t}\right)} F_p(\cdot,x)\right):$$

$$c(a,s,u,v) = \exp_e\left\{a\exp_e^{-1}\left[\exp_{\exp_e\left(\frac{uy}{t}\right)}\left(-sv\,\mathrm{grad}_{\exp_e\left(\frac{uy}{t}\right)} F_p(\cdot,x)\right)\right]\right\}.$$

This is a C^2 function of $(a,s,u,v) \in [0,1]^2 \times (-\eta,\eta)^2$, η sufficiently small. It also depends in a C^2 way of x and y. Letting $c(a,s) = c\left(a,s,\frac{1}{\sqrt{n}},\frac{\delta}{nt+1}\right)$, we have

$$\exp_e^{-1}\left(\exp_{\exp_e \frac{1}{\sqrt{n}t}y}\left(-\frac{\delta}{nt+1}\,\mathrm{grad}_{\exp_e \frac{1}{\sqrt{n}t}y} F_p(\cdot,x)\right)\right) = \partial_a c(0,1).$$

So we need a Taylor expansion up to order n^{-1} of $\frac{nt+1}{\sqrt{n}}\partial_a c(0,1)$.

We have $c(a,s,0,1) = \exp_e(-as\,\mathrm{grad}_e F_p(\cdot,x))$ and this implies

$$\partial_s^2\partial_a c(0,s,0,1) = 0, \quad \text{so} \quad \partial_s^2\partial_a c(0,s,u,1) = O(u).$$

On the other hand the identities $c(a,s,u,v) = c(a,sv,u,1)$ yields $\partial_s^2\partial_a c(a,s,u,v) = v^2\partial_s^2\partial_a c(a,s,u,1)$, so we obtain

$$\partial_s^2\partial_a c(0,s,u,v) = O(uv^2)$$

and this yields

$$\partial_s^2\partial_a c(0,s) = O(n^{-5/2}),$$

uniformly in s,x,y,t. But since

$$\|\partial_a c(0,1) - \partial_a c(0,0) - \partial_s\partial_a c(0,0)\| \le \frac{1}{2}\sup_{s\in[0,1]}\|\partial_s^2\partial_a c(0,s)\|$$

we only need to estimate $\partial_a c(0,0)$ and $\partial_s\partial_a c(0,0)$.

Denoting by $J(a)$ the Jacobi field $\partial_s c(a,0)$ we have

$$\frac{nt+1}{\sqrt{n}}\partial_a c(0,1) = \frac{nt+1}{\sqrt{n}}\partial_a c(0,0) + \frac{nt+1}{\sqrt{n}}\dot{J}(0) + O\left(\frac{1}{n^2}\right).$$

On the other hand

$$\frac{nt+1}{\sqrt{n}}\partial_a c(0,0) = \frac{nt+1}{\sqrt{n}}\frac{y}{\sqrt{n}t} = y + \frac{y}{nt}$$

so it remains to estimate $\dot{J}(0)$.

The Jacobi field $a \mapsto J(a,u,v)$ with endpoints $J(0,u,v) = 0_e$ and

$$J(1,u,v) = -v\,\mathrm{grad}_{\exp_e\left(\frac{uy}{t}\right)} F_p(\cdot,x)$$

satisfies

$$\nabla_a^2 J(a,u,v) = -R(J(a,u,v),\partial_a c(a,0,u,v))\partial_a c(a,0,u,v) = O(u^2 v).$$

This implies that

$$\nabla_a^2 J(a) = O(n^{-2}).$$

Consequently, denoting by $P_{x_1,x_2} : T_{x_1}M \to T_{x_2}M$ the parallel transport along the minimal geodesic from x_1 to x_2 (whenever it is unique) we have

$$P_{c(1,0),e}J(1) = J(0) + \dot{J}(0) + O(n^{-2}) = \dot{J}(0) + O(n^{-2}). \tag{3.31}$$

But we also have

$$\begin{aligned} P_{c(1,0,u,v),e}J(1,u,v) &= P_{c(1,0,u,v),e}\left(-v\,\mathrm{grad}_{c(1,0,u,v)}\,F_p(\cdot,x)\right) \\ &= -v\,\mathrm{grad}_e\,F_p(\cdot,x) - v\nabla_{\partial_a c(0,0,u,v)}\,\mathrm{grad}_{\cdot}\,F_p(\cdot,x) + O(vu^2) \\ &= -v\,\mathrm{grad}_e\,F_p(\cdot,x) - v\nabla dF_p(\cdot,x)\left(\frac{uy}{t},\cdot\right)^\sharp + O(vu^2) \end{aligned}$$

where we used $\partial_a c(0,0,u,v) = \frac{uy}{t}$ and for vector fields A, B on TM and a C^2 function f_1 on M

$$\begin{aligned} \langle \nabla_{A_e}\,\mathrm{grad}\,f_1, B_e\rangle &= A_e\langle \mathrm{grad}\,f_1, B_e\rangle - \langle \mathrm{grad}\,f_1, \nabla_{A_e}B\rangle \\ &= A_e\langle df_1, B_e\rangle - \langle df_1, \nabla_{A_e}B\rangle \\ &= \nabla df_1(A_e, B_e) \end{aligned}$$

which implies

$$\nabla_{A_e}\,\mathrm{grad}\,f_1 = \nabla df_1(A_e,\cdot)^\sharp.$$

We obtain

$$P_{c(1,0),e}J(1) = -\frac{\delta}{nt+1}\,\mathrm{grad}_e\,F_p(\cdot,x) - \frac{\delta}{\sqrt{n}(nt+1)}\nabla dF_p(\cdot,x)\left(\frac{y}{t},\cdot\right)^\sharp + O(n^{-2}).$$

Combining with (3.31) this gives

$$\dot{J}(0) = -\frac{\delta}{nt+1}\,\mathrm{grad}_e\,F_p(\cdot,x) - \frac{\delta}{nt+1}\nabla dF_p(\cdot,x)\left(\frac{y}{\sqrt{n}t},\cdot\right)^\sharp + O\left(\frac{1}{n^2}\right).$$

So finally

(3.32)

$$\frac{nt+1}{\sqrt{n}}\partial_a c(0,1) = y + \frac{y}{nt} - \frac{\delta}{\sqrt{n}}\,\mathrm{grad}_e\,F_p(\cdot,x) - \delta\nabla dF_p(\cdot,x)\left(\frac{y}{nt},\cdot\right)^\sharp + O\left(n^{-3/2}\right).$$

To get the final result we are left to make a Taylor expansion of f up to order 2. □

Define the following quantities:

$$b_n(z) = n\int_{\{|z'-z|\le 1\}}(z'-z)P^n(z,dz') \tag{3.33}$$

and

$$a_n(z) = n\int_{\{|z'-z|\le 1\}}(z'-z)\otimes(z'-z)P^n(z,dz'). \tag{3.34}$$

The following property holds:

Lemma 3.2. *Assume that there exists a neighbourhood V_e of e such that for all $x \in B(a,r)$ the application $F_p(\cdot,x)$ is of class C^2 in V_e.*

1. *For all $R > 0$ and $\varepsilon > 0$, there exists n_0 such that for all $n \ge n_0$ and $z \in [\varepsilon, T]\times B(0_e,R)$, where $B(0_e,R)$ is the open ball in T_eM centered at the origin with radius R,*

$$\int 1_{\{|z'-z|>1\}}\,P^n(z,dz') = 0. \tag{3.35}$$

(2) *For all* $R > 0$ *and* $\varepsilon > 0$,

$$\lim_{n\to\infty} \sup_{z\in[\varepsilon,T]\times B(0_e,R)} |b_n(z) - b(z)| = 0 \tag{3.36}$$

with

$$b(z) = \left(1, \frac{1}{t} L_\delta(y)\right) \quad \textit{and} \quad L_\delta(y) = y - \delta \nabla dH(y,\cdot)^\sharp. \tag{3.37}$$

(3) *For all* $R > 0$ *and* $\varepsilon > 0$,

$$\lim_{n\to\infty} \sup_{z\in[\varepsilon,T]\times B(0_e,R)} |a_n(z) - a(z)| = 0 \tag{3.38}$$

with

$$a(z) = \delta^2 \mathrm{diag}(0,\Gamma) \quad \textit{and} \quad \Gamma = \mathbb{E}\left[\mathrm{grad}_e F_p(\cdot,P_1) \otimes \mathrm{grad}_e F_p(\cdot,P_1)\right]. \tag{3.39}$$

Proof. (1) We use the notation $z = (t,y)$ and $z' = (t',y')$. We have

$$\begin{aligned}
&\int 1_{\{|z'-z|>1\}} P^n(z,dz') \\
&= \int 1_{\{\max(|t'-t|,|y'-y|)>1\}} P^n(z,dz') \\
&= \int 1_{\{\max(\frac{1}{n},|y'-y|)>1\}} P^n(z,dz') \\
&= \mathbb{P}\left[\left|\frac{nt+1}{\sqrt{n}} \exp_e^{-1}\left(\exp_{\exp_e \frac{1}{\sqrt{nt}} y}\left(-\frac{\delta}{nt+1}\mathrm{grad}_{\exp_e \frac{1}{\sqrt{nt}} y} F_p(\cdot,P_1)\right)\right) - y\right| > 1\right].
\end{aligned}$$

On the other hand, since $F_p(\cdot,x)$ is of class C^2 in a neighbourhood of e, we have by (3.32)

$$\left|\frac{nt+1}{\sqrt{n}} \exp_e^{-1}\left(\exp_{\exp_e \frac{1}{\sqrt{nt}} y}\left(-\frac{\delta}{nt+1}\mathrm{grad}_{\exp_e \frac{1}{\sqrt{nt}} y} F_p(\cdot,P_1)\right)\right) - y\right| \le \frac{C\delta}{\sqrt{n}\varepsilon} \tag{3.40}$$

for some constant $C > 0$.

(2) Equation (3.35) implies that for $n \ge n_0$

$$\begin{aligned}
&b_n(z) \\
&= n\int (z'-z)\, P^n(z,dz') \\
&= n\left(\frac{1}{n}, \mathbb{E}\left[\frac{nt+1}{\sqrt{n}} \exp_e^{-1}\left(\exp_{\exp_e \frac{y}{\sqrt{nt}}}\left(-\frac{\delta}{nt+1}\mathrm{grad}_{\exp_e \frac{y}{\sqrt{nt}}} F_p(\cdot,P_1)\right)\right)\right] - y\right).
\end{aligned}$$

We have by lemma 3.1

$$\begin{aligned}
&n\left(\frac{nt+1}{\sqrt{n}} \exp_e^{-1}\left(\exp_{\exp_e \frac{1}{\sqrt{nt}} y}\left(-\frac{\delta}{nt+1}\mathrm{grad}_{\exp_e \frac{1}{\sqrt{nt}} y} F_p(\cdot,P_1)\right)\right) - y\right) \\
&= \frac{1}{t} y - \delta\sqrt{n}\,\mathrm{grad}_e F_p(\cdot,P_1) - \delta \nabla dF_p(\cdot,P_1)\left(\frac{1}{t}y,\cdot\right)^\sharp + O\left(\frac{1}{n^{1/2}}\right)
\end{aligned}$$

a.s. uniformly in n, and since

$$\mathbb{E}\left[\delta\sqrt{n}\,\mathrm{grad}_e F_p(\cdot,P_1)\right] = 0,$$

this implies that

$$n\left(\mathbb{E}\left[\frac{nt+1}{\sqrt{n}} \exp_e^{-1}\left(\exp_{\exp_e \frac{1}{\sqrt{nt}} y}\left(-\frac{\delta}{nt+1}\mathrm{grad}_{\exp_e \frac{1}{\sqrt{nt}} y} F_p(\cdot,P_1)\right)\right)\right] - y\right)$$

converges to

$$\frac{1}{t}y - \mathbb{E}\left[\delta\nabla dF_p(\cdot, P_1)\left(\frac{1}{t}y, \cdot\right)^\sharp\right] = \frac{1}{t}y - \delta\nabla dH_p\left(\frac{1}{t}y, \cdot\right)^\sharp. \tag{3.41}$$

Moreover the convergence is uniform in $z \in [\varepsilon, T] \times B(0_e, R)$, so this yields (3.36).

(3) In the same way, using lemma 3.1,

$$\begin{aligned} & n\int (y'-y)\otimes(y'-y)\, P^n(z, dz') \\ &= \frac{1}{n}\mathbb{E}\left[\left(-\sqrt{n}\delta \operatorname{grad}_e F_p(\cdot, P_1)\right)\otimes\left(-\sqrt{n}\delta \operatorname{grad}_e F_p(\cdot, P_1)\right)\right] + o(1) \\ &= \delta^2\mathbb{E}\left[\operatorname{grad}_e F_p(\cdot, P_1)\otimes \operatorname{grad}_e F_p(\cdot, P_1)\right] + o(1) \end{aligned}$$

uniformly in $z \in [\varepsilon, T] \times B(0_e, R)$, so this yields (3.38).

□

Lemma 3.3. *Suppose that $t_n = \dfrac{\delta}{n}$ for some $\delta > 0$. For all $\delta > C_{p,\mu,K}^{-1}$,*

$$\sup_{n\geq 1} n\mathbb{E}\left[\rho^2(e, X_n)\right] < \infty. \tag{3.42}$$

Proof. First consider the case $p \in [1, 2)$.

We know by (3.12) that there exists some constant $C(\beta, r, p)$ such that

$$\mathbb{E}\left[\rho^2(e, X_{k+1})\right] \leq \mathbb{E}\left[\rho^2(e, X_k)\right]\exp\left(-C_{p,\mu,K}t_{k+1}\right) + C(\beta, r, p)t_{k+1}^2. \tag{3.43}$$

From this (3.42) is a consequence of Lemma 0.0.1 (case $\alpha > 1$) in [16]. We give the proof for completeness. We deduce easily by induction that for all $k \geq k_0$,

(3.44)

$$\begin{aligned} &\mathbb{E}\left[\rho^2(e, X_k)\right] \\ &\leq \mathbb{E}\left[\rho^2(e, X_{k_0})\right]\exp\left(-C_{p,\mu,K}\sum_{j=k_0+1}^{k} t_j\right) + C(\beta, r, p)\sum_{i=k_0+1}^{k} t_i^2 \exp\left(-C_{p,\mu,K}\sum_{j=i+1}^{k} t_j\right), \end{aligned}$$

where the convention $\sum_{j=k+1}^{k} t_j = 0$ is used. With $t_n = \frac{\delta}{n}$, the following inequality holds for all $i \geq k_0$ and $k \geq i$:

$$\sum_{j=i+1}^{k} t_j = \delta\sum_{j=i+1}^{k}\frac{1}{j} \geq \delta\int_{i+1}^{k+1}\frac{dt}{t} \geq \delta\ln\frac{k+1}{i+1}. \tag{3.45}$$

Hence,

$$\begin{aligned} &\mathbb{E}\left[\rho^2(e, X_k)\right] \\ &\leq \mathbb{E}\left[\rho^2(e, X_{k_0})\right]\left(\frac{k_0+1}{k+1}\right)^{\delta C_{p,\mu,K}} + \frac{\delta^2 C(\beta, r, p)}{(k+1)^{\delta C_{p,\mu,K}}}\sum_{i=k_0+1}^{k}\frac{(i+1)^{\delta C_{p,\mu,K}}}{i^2}. \end{aligned} \tag{3.46}$$

For $\delta C_{p,\mu,K} > 1$ we have as $k \to \infty$

(3.47)

$$\frac{\delta^2 C(\beta, r, p)}{(k+1)^{\delta C_{p,\mu,K}}}\sum_{i=k_0+1}^{k}\frac{(i+1)^{\delta C_{p,\mu,K}}}{i^2} \sim \frac{\delta^2 C(\beta, r, p)}{(k+1)^{\delta C_{p,\mu,K}}}\frac{k^{\delta C_{p,\mu,K}-1}}{\delta C_{p,\mu,K}-1} \sim \frac{\delta^2 C(\beta, r, p)}{\delta C_{p,\mu,K}-1}k^{-1}$$

and

$$\mathbb{E}\left[\rho^2(e, X_{k_0})\right]\left(\frac{k_0+1}{k+1}\right)^{\delta C_{p,\mu,K}} = o(k^{-1}).$$

This implies that the sequence $k\mathbb{E}\left[\rho^2(e, X_k)\right]$ is bounded.

Next consider the case $p \geq 2$.

Now we have by (3.19) that

(3.48)

$$\mathbb{E}\left[H_p(X_{k+1}) - H_p(e)\right] \leq \mathbb{E}\left[H_p(X_k) - H_p(e)\right]\exp\left(-C_{p,\mu,K}t_{k+1}\right) + C(\beta, r, p)t_{k+1}^2.$$

From this, arguing similarly, we obtain that the sequence $k\mathbb{E}\left[H_p(X_k) - H_p(e)\right]$ is bounded. We conclude with (2.3). □

Lemma 3.4. *Assume $\delta > C_{p,\mu,K}^{-1}$ and that H_p is C^2 in a neighbourhood of e. For all $0 < \varepsilon < T$, the sequence of processes $\left(Y^n_{[nt]}\right)_{\varepsilon \leq t \leq T}$ is tight in $\mathbb{D}([\varepsilon, T], \mathbb{R}^d)$.*

Proof. Denote by $\left(\tilde{Y}^n_\varepsilon = \left(Y^n_{[nt]}\right)_{\varepsilon \leq t \leq T}\right)_{n\geq 1}$, the sequence of processes. We prove that from any subsequence $\left(\tilde{Y}^{\phi(n)}_\varepsilon\right)_{n\geq 1}$, we can extract a further subsequence $\left(\tilde{Y}^{\psi(n)}_\varepsilon\right)_{n\geq 1}$ that weakly converges in $\mathbb{D}([\varepsilon, 1], \mathbb{R}^d)$.

Let us first prove that $\left(\tilde{Y}^{\phi(n)}_\varepsilon(\varepsilon)\right)_{n\geq 1}$ is bounded in L^2.

$$\left\|\tilde{Y}^{\phi(n)}_\varepsilon(\varepsilon)\right\|_2^2 = \frac{[\phi(n)\varepsilon]^2}{\phi(n)}\mathbb{E}\left[\rho^2(e, X_{[\phi(n)\varepsilon]})\right] \leq \varepsilon \sup_{n\geq 1}\left(n\mathbb{E}\left[\rho^2(e, X_n)\right]\right)$$

and the last term is bounded by lemma 3.3.

Consequently $\left(\tilde{Y}^{\phi(n)}_\varepsilon(\varepsilon)\right)_{n\geq 1}$ is tight. So there is a subsequence $\left(\tilde{Y}^{\psi(n)}_\varepsilon(\varepsilon)\right)_{n\geq 1}$ that weakly converges in T_eM to the distribution ν_ε. Thanks to Skorohod theorem which allows to realize it as an a.s. convergence and to lemma 3.2 we can apply Theorem 11.2.3 of [20], and we obtain that the sequence of processes $\left(\tilde{Y}^{\psi(n)}_\varepsilon\right)_{n\geq 1}$ weakly converges to a diffusion $(y_t)_{\varepsilon\leq t\leq T}$ with generator $G_\delta(t)$ given by (2.13) and such that y_ε has law ν_ε. This achieves the proof of lemma 3.4. □

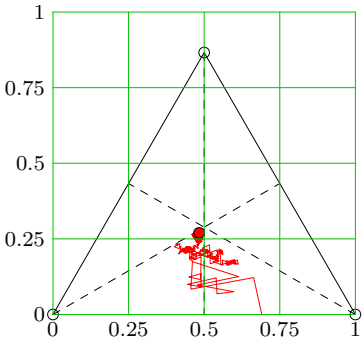
Proof of Theorem 2.6. Let $\tilde{Y}^n = \left(Y^n_{[nt]}\right)_{0\leq t\leq T}$. It is sufficient to prove that any subsequence of $\left(\tilde{Y}^n\right)_{n\geq 1}$ has a further subsequence which converges in law to $(y_\delta(t))_{0\leq t\leq T}$. So let $\left(\tilde{Y}^{\phi(n)}\right)_{n\geq 1}$ a subsequence. By lemma 3.4 with $\varepsilon = 1/m$ there exists a subsequence which converges in law on $[1/m, T]$. Then we extract a sequence indexed by m of subsequence and take the diagonal subsequence $\tilde{Y}^{\eta(n)}$. This subsequence converges in $\mathbb{D}((0, T], \mathbb{R}^d)$ to $(y'(t))_{t\in(0,T]}$. On the other hand, as in the proof of lemma 3.4, we have

$$\|\tilde{Y}^{\eta(n)}(t)\|_2^2 \leq Ct$$

for some $C > 0$. So $\|\tilde{Y}^{\eta(n)}(t)\|_2^2 \to 0$ as $t \to 0$, which in turn implies $\|y'(t)\|_2^2 \to 0$ as $t \to 0$. The unicity statement in Proposition 2.5 implies that $(y'(t))_{t\in(0,T]}$ and $(y_\delta(t))_{t\in(0,T]}$ are equal in law. This achieves the proof. □

4. Examples, simulations and pictures

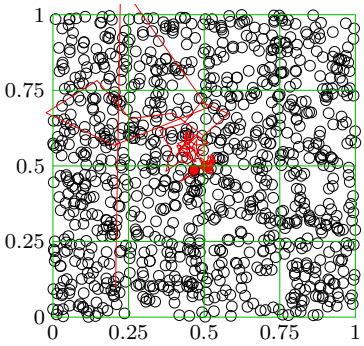
4.1. **Median of the uniform measure on an equilateral triangle in the plane.**



(4.1)

Here M is the Euclidean plane $\mathbb{R}^2$, μ is the uniform measure on an equilateral triangle. The red path represents one trajectory of the inhomogeneous Markov chain $(X_k)_{k\geq 0}$ corresponding to $p = 1$, with linear interpolation between the different steps. The red point in the middle is e_1.

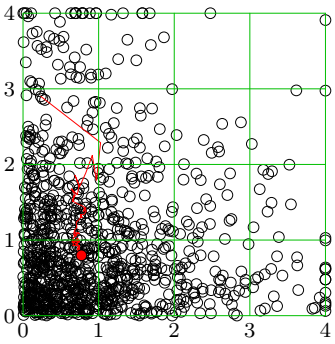
4.2. **Uniform measure on the unit square in the plane.**



(4.2)

Again M is the Euclidean plane $\mathbb{R}^2$, but here μ is the uniform measure on the square $[0, 1] \times [0, 1]$. The red path represents one trajectory of the inhomogeneous Markov chain $(X_k)_{k\geq 0}$ corresponding to $p = 1$, with linear interpolation between the different steps. The red point in the middle is e_1.

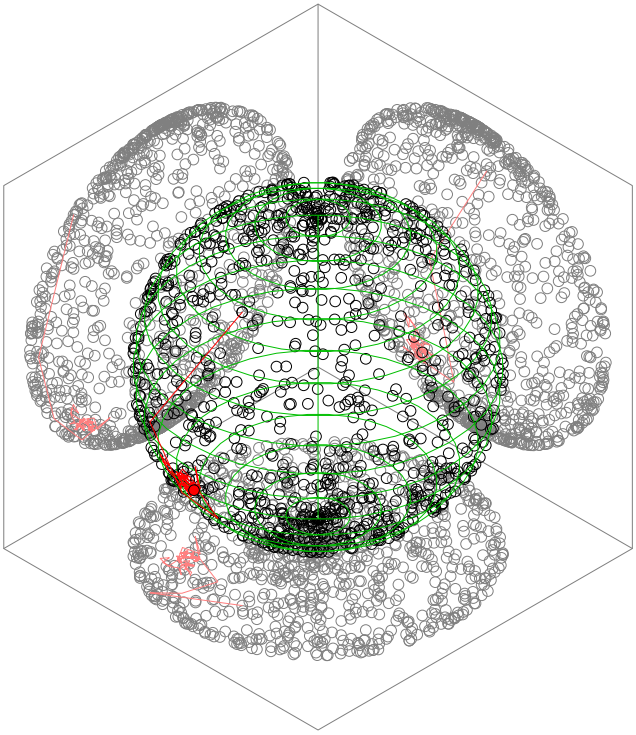
4.3. **A non uniform measure on a square in the plane.**



(4.3)

M is still the Euclidean plane $\mathbb{R}^2$, now here μ is the renormalized restriction to the square $[0,4]\times[0,4]$ of an exponential law on $[0,\infty)\times[0,\infty)$. The red path represents one trajectory of the inhomogeneous Markov chain $(X_k)_{k\geq 0}$ corresponding to $p=1$, with linear interpolation between the different steps. The red point is e_1. Black circles represent the values of $(P_k)_{k\geq 1}$

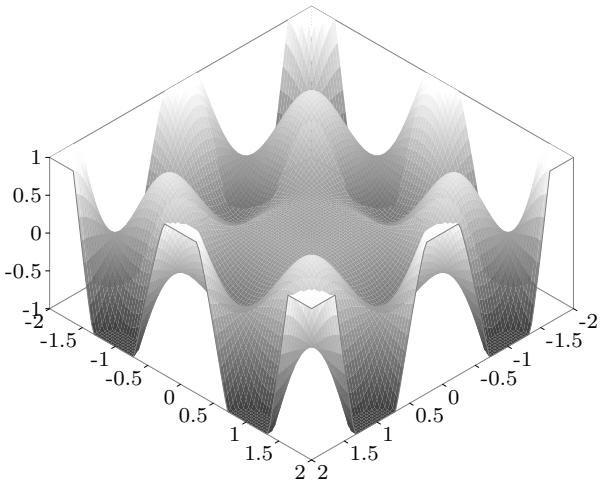
4.4. **A non uniform measure on the sphere S^2.**



(4.4)

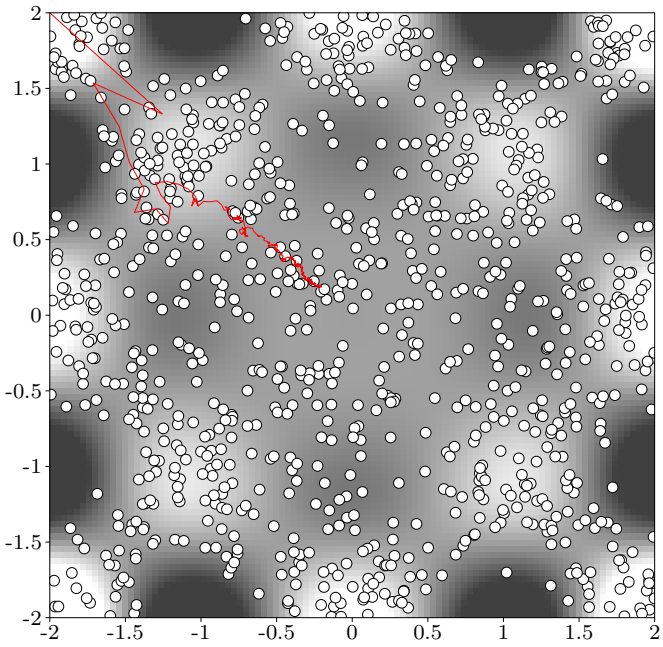
Here M is the embedded sphere S^2 and μ is a non uniform law. Again the red path represents one trajectory of the inhomogeneous Markov chain $(X_k)_{k\geq 0}$ corresponding to $p=1$, with linear interpolation between the different steps. The red point is e_1. Black circles represent the values of $(P_k)_{k\geq 1}$. One can observe that even if the convexity assumptions are not fulfilled, convergence still holds.

4.5. **Another non uniform measure on the unit square in the plane.**



(4.5)

This is an example of density on the square $[0,1] \times [0,1]$.



(4.6)

Here μ is given by the density of figure (4.5). The red path represents one trajectory of the inhomogeneous Markov chain $(X_k)_{k\geq 0}$ corresponding to $p = 1$, with linear interpolation between the different steps. The red point is e_1. Black circles represent the values of $(P_k)_{k\geq 1}$.

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