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Basic properties of the Multivariate Fractional Brownian Motion

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Abstract

This paper reviews and extends some recent results on the multivariate fractional Brownian motion (mfBm) and its increment process. A characterization of the mfBm through its covariance function is obtained. Similarly, the correlation and spectral analyses of the increments are investigated. On the other hand we show that (almost) all mfBm's may be reached as the limit of partial sums of (super)linear processes. Finally, an algorithm to perfectly simulate the mfBm is presented and illustrated by some simulations.

keywords: Self similarity; Multivariate process; Long-range dependence; Superlinear process; Increment process; Limit theorem.

1 Introduction

The fractional Brownian motion is the unique Gaussian self-similar process with stationary increments. In the seminal paper of Mandelbrot and Van Ness[22], many properties of the fBm and its increments are developed (see also [30] for a review of the basic properties). Depending on the scaling factor (called Hurst parameter), the increment process may exhibit long-range dependence, and are commonly used in modeling physical phenomena. However in many fields of applications (e.g. neuroscience, economy, sociology, physics, etc), multivariate measurements are performed and they involve specific properties such as fractality, long-range dependence, self-similarity, etc. Examples can be found in economic time series (see [11], [14], [15]), genetic sequences [2], multipoint velocity measurements in turbulence, functional Magnetic Resonance Imaging of several regions of the brain [1].

It seems therefore natural to extend the fBm to a multivariate framework. Recently, this question has been investigated in [20, 19, 5]. The aim of this paper is to summarize and to complete some of these advances on the multivariate fractional Brownian motion and its increments. A multivariate extension of the fractional Brownian motion can be stated as follows:

Definition 1. A Multivariate fractional Brownian motion (p-mfBm or mfBm) with parameter $H \in (0,1)^p$ is a p-multivariate process starting from $0 \in \mathbb{R}^p$ and satisfying the three following properties

- Gaussianity,
- Self-similarity with parameter $H \in (0,1)^p$,
- Stationarity of the increments.

Here, self-similarity has to be understood as joint self-similarity. More formally, we use the following definition.

Definition 2. A multivariate process $(X(t) = (X_1(t), \dots, X_p(t)))_{t \in \mathbb{R}}$ is said self-similar if there exists a vector $H = (H_1, \dots, H_p) \in (0, 1)^p$ such that for any $\lambda > 0$,

$$(X_1(\lambda t), \cdots, X_p(\lambda t)))_{t \in \mathbb{R}} \stackrel{\text{fidi}}{=} (\lambda^{H_1} X_1(t), \cdots, \lambda^{H_p} X_p(t))_{t \in \mathbb{R}}, \tag{1}$$

where $\stackrel{\mathrm{fidi}}{=}$ denotes the equality of finite-dimensional distributions. The parameter H is called the self-similarity parameter.

This definition can be viewed as a particular case of operator self-similar processes by taking diagonal operators (see [12, 16, 17, 21]).

Note that, as in the univariate case [18], the Lamperti transformation induces an isometry between the self-similar and the stationary multivariate processes. Indeed, from Definition 2, it is not difficult to check that $(Y(t))_{t\in\mathbb{R}}$ is a p-multivariate stationary process if and only if there exists $H \in (0,1)^p$ such that its Lamperti transformation $(t^{H_1}Y_1(\log(t)), \ldots, t^{H_p}Y_p(\log(t)))_{t\in\mathbb{R}}$ is a p-multivariate self-similar process.

The paper is organized as follows. In Section 2, we study the covariance structure of the mfBm and its increments. The cross-covariance and the cross-spectral density of the increments lead to interesting long-memory type properties. Section 3 contains the time domain as well as the spectral domain stochastic integral representations of the mfBm. Thanks to these results we obtain a characterization of the mfBm through its covariance matrix function. Section 4 is devoted to limit theorems, the mfBm is obtained as the limit of partial sums of linear processes. Finally, we discuss in Section 5 the problem of simulating sample paths of the mfBm. We propose a Wood and Chan algorithm [32] well adapted to generate multivariate stationary Gaussian random fields with prescribed covariance matrix function.

2 Dependence structure of the mfBm and of its increments

2.1 Covariance function of the mfBm

In this part, we present the form of the covariance matrix of the mfBm.

Firstly, as each component is a fractional brownian motion, the covariance function of the i-th component is well-known and we have

$$\mathbb{E}X_i(s)X_i(t) = \frac{\sigma_i^2}{2} \left\{ |s|^{2H_i} + |t|^{2H_i} - |t - s|^{2H_i} \right\}. \tag{2}$$

with $\sigma_i^2 := \operatorname{var}(X_i(1))$. The cross covariances are given in the following proposition.

Proposition 3 (Lavancier et al. [20]). The cross covariances of the mfBm satisfy the following representation, for all $(i, j) \in \{1, ..., p\}^2$, $i \neq j$,

1. If $H_i + H_j \neq 1$, there exists $(\rho_{i,j}, \eta_{i,j}) \in [-1,1] \times \mathbb{R}$ with $\rho_{i,j} = \rho_{j,i} = \operatorname{corr}(X_i(1), X_j(1))$ and $\eta_{i,j} = -\eta_{j,i}$ such that

$$\mathbb{E}X_{i}(s)X_{j}(t) = \frac{\sigma_{i}\sigma_{j}}{2} \left\{ (\rho_{i,j} + \eta_{i,j}\operatorname{sign}(s))|s|^{H_{i}+H_{j}} + (\rho_{i,j} - \eta_{i,j}\operatorname{sign}(t))|t|^{H_{i}+H_{j}} - (\rho_{i,j} - \eta_{i,j}\operatorname{sign}(t-s))|t-s|^{H_{i}+H_{j}} \right\}.$$
(3)

2. If $H_i + H_j = 1$, there exists $(\tilde{\rho}_{i,j}, \tilde{\eta}_{i,j}) \in [-1,1] \times \mathbb{R}$ with $\tilde{\rho}_{i,j} = \tilde{\rho}_{j,i} = \operatorname{corr}(X_i(1), X_j(1))$ and $\tilde{\eta}_{i,j} = -\tilde{\eta}_{j,i}$ such that

$$\mathbb{E}X_{i}(s)X_{j}(t) = \frac{\sigma_{i}\sigma_{j}}{2} \left\{ \tilde{\rho}_{i,j}(|s| + |t| - |s - t|) + \tilde{\eta}_{i,j}(t\log|t| - s\log|s| - (t - s)\log|t - s|) \right\}. \tag{4}$$

Proof. Under some conditions of regularity, Lavancier et al. [20] actually prove that Proposition 3 is true for any L^2 self-similar multivariate process with stationary increments. The form of cross covariances is obtained as the unique solution of a functional equation. Formulae (3) and (4) correspond to expressions given in [20] after the following reparameterization: $\rho_{i,j} = (c_{i,j} + c_{j,i})/2$ and $\eta_{i,j} = (c_{i,j} - c_{j,i})/2$ where $c_{i,j}$ and $c_{j,i}$ arise in [20].

Remark 1. Extending the definition of parameters $\rho_{i,j}$, $\tilde{\rho}_{i,j}$, $\eta_{i,j}$, $\tilde{\eta}_{i,j}$ to the case i=j, we have $\rho_{i,i}=\tilde{\rho}_{i,i}=1$ and $\eta_{i,j}=\tilde{\eta}_{i,j}=0$, so that (2) coincides with (3) and (4).

Remark 2. The constraints on coefficients $\rho_{i,j}$, $\tilde{\rho}_{i,j}$, $\eta_{i,j}$, $\tilde{\eta}_{i,j}$ are necessary but not sufficient conditions to ensure that the functions defined by (4) and (3) are covariance functions. This problem will be discussed in Section 3.4.

Remark 3. Note that coefficients $\rho_{i,j}$, $\tilde{\rho}_{i,j}$, $\eta_{i,j}$, $\tilde{\eta}_{i,j}$ depend on the parameters (H_i, H_j) . Assuming the continuity of the cross covariances function with respect to the parameters (H_i, H_j) , the expression (4) can be deduced from (3) by taking the limit as $H_i + H_j$ tends to 1, noting that $((s+1)^H - s^H - 1)/(1-H) \to s\log|s| - (s+1)\log|s+1|$ as $H \to 1$. We obtain the following relations between the coefficients: as $H_i + H_j \to 1$

$$\rho_{i,j} \sim \tilde{\rho}_{i,j}$$
 and $(1 - H_i - H_j)\eta_{i,j} \sim \tilde{\eta}_{i,j}$.

This convergence result can suggest a reparametrisation of coefficients $\eta_{i,j}$ in $(1 - H_i - H_j)\eta_{i,j}$.

2.2 The increments process

This part aims at exploring the covariance structure of the increments of size δ of a multivariate fractional Brownian motion given by Definition 1. Let $\Delta_{\delta}X = (X(t+\delta) - X(t))_{t \in \mathbb{R}}$ denotes the increment process of the multivariate fractional Brownian motion of size δ and let $\Delta_{\delta}X_i$ be its i-th component.

Let $\gamma_{i,j}(h,\delta) = \mathbb{E}\Delta_{\delta}X_i(t)\Delta_{\delta}X_j(t+h)$ denotes the cross-covariance of the increments of size δ of the components i and j. Let us introduce the function $w_{i,j}(h)$ given by

$$w_{i,j}(h) = \begin{cases} (\rho_{i,j} - \eta_{i,j} \operatorname{sign}(h)) |h|^{H_i + H_j} & \text{if } H_i + H_j \neq 1, \\ \tilde{\rho}_{i,j} |h| + \tilde{\eta}_{i,j} h \log |h| & \text{if } H_i + H_j = 1. \end{cases}$$
 (5)

Then from Proposition 3, we deduce that $\gamma_{i,j}(h,\delta)$ is given by

$$\gamma_{i,j}(h,\delta) = \frac{\sigma_i \sigma_j}{2} \left(w_{i,j}(h-\delta) - 2w_{i,j}(h) + w_{i,j}(h+\delta) \right). \tag{6}$$

Now, let us present the asymptotic behaviour of the cross-covariance function.

Proposition 4. As $|h| \to +\infty$, we have for any $\delta > 0$

$$\gamma_{i,j}(h,\delta) \sim \sigma_i \sigma_j \delta^2 |h|^{H_i + H_j - 2} \kappa_{i,j}(\operatorname{sign}(h)),$$
 (7)

with

$$\kappa_{i,j}(\operatorname{sign}(h)) = \begin{cases} (\rho_{i,j} - \eta_{i,j}\operatorname{sign}(h))(H_i + H_j)(H_i + H_j - 1) & \text{if } H_i + H_j \neq 1, \\ \tilde{\eta}_{i,j}\operatorname{sign}(h) & \text{if } H_i + H_j = 1. \end{cases}$$
(8)

Proof. Let $\alpha = H_i + H_j$. Let us choose h, such that $|h| \geq \delta$, which ensures that $sign(h - \delta) = sign(h) = sign(h + \delta)$. When $\alpha \neq 1$, this allows us to write

$$\gamma_{i,j}(h,\delta) = \frac{\sigma_i \sigma_j}{2} |h|^{\alpha} \left(\rho_{i,j} - \eta_{i,j} \operatorname{sign}(h)\right) B(h),$$

with $B(h) = \left(1 - \frac{\delta}{h}\right)^{\alpha} - 2 + \left(1 + \frac{\delta}{h}\right)^{\alpha} \sim \alpha(\alpha - 1)\delta^2 h^{-2}$, as $|h| \to +\infty$. When $\alpha = 1$ and $|h| \ge \delta$, $\gamma_{i,j}(h,\delta)$ reduces to

$$\gamma_{i,j}(h,\delta) = \frac{\sigma_i \sigma_j}{2} \tilde{\eta}_{i,j} B(h) \text{ with } B(h) = \left((h-\delta) \log \left(1 - \frac{\delta}{h} \right) + (h+\delta) \log \left(1 + \frac{\delta}{h} \right) \right).$$

Using the expansion of $\log(1 \pm x)$ as $x \to 0$ leads to $B(h) \sim \delta^2 |h|^{-1}$ as $|h| \to +\infty$, which implies the result.

Proposition 4 and (6) lead to the following important remarks on the dependence structure. For $i \neq j$ and $H_i + H_j \neq 1$:

- If the two fractional Gaussian noises are short-range dependent (i.e. $H_i < 1/2$ and $H_j < 1/2$) then they are either short-range interdependent if $\rho_{i,j} \neq 0$ or $\eta_{i,j} \neq 0$, or independent if $\rho_{i,j} = \eta_{i,j} = 0$.
- If the two fractional Gaussian noises are long-range dependent (i.e. $H_i > 1/2$ and $H_j > 1/2$) then they are either long-range interdependent if $\rho_{i,j} \neq 0$ or $\eta_{i,j} \neq 0$, or independent if $\rho_{i,j} = \eta_{i,j} = 0$. This confirms the dichotomy principle observed in [12].
- In the other cases, the two fractional Gaussian noises can be short-range interdependent if $\rho_{i,j} \neq 0$ or $\eta_{i,j} \neq 0$ and $H_i + H_j < 1$, long-range interdependent if $\rho_{i,j} \neq 0$ or $\eta_{i,j} \neq 0$ and $H_i + H_j > 1$ or independent if $\rho_{i,j} = \eta_{i,j} = 0$.

Moreover, note that when $H_i + H_j = 1$, whatever the nature of the two fractional Gaussian noises (i.e. short-range or long-range dependent, or even independent), they are either long-range interdependent if $\tilde{\eta}_{i,j} \neq 0$ or independent if $\tilde{\eta}_{i,j} = 0$.

The following result characterizes the spectral nature of the increments of a mfBm.

Proposition 5 (Coeurjolly et al. [5]). Let $S_{i,j}(\cdot,\delta)$ be the (cross)-spectral density of the increments of size δ of the components i and j, i.e. the Fourier transform of $\gamma_{i,j}(\cdot,\delta)$

$$S_{i,j}(\omega,\delta) = \frac{1}{2\pi} \int_{\mathbb{R}} e^{-ih\omega} \gamma_{i,j}(h,\delta) dh =: FT(\gamma_{i,j}(\cdot,\delta)).$$

(i) For all i, j and for all H_i, H_j , we have

$$S_{i,j}(\omega,\delta) = \frac{\sigma_i \sigma_j}{\pi} \Gamma(H_i + H_j + 1) \frac{1 - \cos(\omega \delta)}{|\omega|^{H_i + H_j + 1}} \times \tau_{i,j}(\operatorname{sign}(\omega)), \tag{9}$$

where

$$\tau_{i,j}(\operatorname{sign}(\omega)) = \begin{cases} \rho_{i,j} \sin\left(\frac{\pi}{2}(H_i + H_j)\right) - \mathbf{i}\eta_{i,j}\operatorname{sign}(\omega)\cos\left(\frac{\pi}{2}(H_i + H_j)\right) & \text{if } H_i + H_j \neq 1, \\ \tilde{\rho}_{i,j} - \mathbf{i}\frac{\pi}{2}\tilde{\eta}_{i,j}\operatorname{sign}(\omega) & \text{if } H_i + H_j = 1. \end{cases}$$
(10)

(ii) For any fixed δ , when $H_i + H_j \neq 1$ then we have, as $\omega \to 0$,

$$\left| S_{i,j}(\omega,\delta) \right| \sim \frac{\sigma_i \sigma_j}{2\pi} \Gamma(H_i + H_j + 1) \delta^2 \frac{\left(\rho_{i,j}^2 \sin\left(\frac{\pi}{2}(H_i + H_j)\right)^2 + \eta_{i,j}^2 \cos\left(\frac{\pi}{2}(H_i + H_j)\right)^2 \right)^{1/2}}{|\omega|^{H_i + H_j - 1}}. \tag{11}$$

(iii) Moreover, when $H_i + H_j \neq 1$, the coherence function between the two components i and j satisfies, for all ω

$$C_{i,j}(\omega,\delta) := \frac{|S_{i,j}(\omega,\delta)|^2}{S_{i,i}(\omega,\delta)S_{j,j}(\omega,\delta)}$$

$$= \frac{\Gamma(H_i + H_j + 1)^2}{\Gamma(2H_i + 1)\Gamma(2H_j + 1)} \frac{\rho_{i,j}^2 \sin\left(\frac{\pi}{2}(H_i + H_j)\right)^2 + \eta_{i,j}^2 \cos\left(\frac{\pi}{2}(H_i + H_j)\right)^2}{\sin(\pi H_i)\sin(\pi H_j)}. (12)$$

(iv) When $H_i + H_j = 1$, (11) and (12) hold, replacing $\rho_{i,j}^2 \sin\left(\frac{\pi}{2}(H_i + H_j)\right)^2 + \eta_{i,j}^2 \cos\left(\frac{\pi}{2}(H_i + H_j)\right)^2$ by $\tilde{\rho}_{i,j}^2 + \frac{\pi^2}{4}\tilde{\eta}_{i,j}^2$.

Proof. The proof is essentially based on the fact that in the generalized function sense, for $\alpha > -1$,

$$FT(|h|^{\alpha}) = -\frac{1}{\pi}\Gamma(\alpha+1)\sin\left(\frac{\pi}{2}\alpha\right)|\omega|^{-\alpha-1},$$

$$FT(h_{+}^{\alpha}) = \frac{1}{2\pi}\Gamma(\alpha+1)e^{-\mathrm{i}\mathrm{sign}(\omega)\frac{\pi}{2}(\alpha+1)}|\omega|^{-\alpha-1},$$

$$FT(h_{-}^{\alpha}) = \frac{1}{2\pi}\Gamma(\alpha+1)e^{\mathrm{i}\mathrm{sign}(\omega)\frac{\pi}{2}(\alpha+1)}|\omega|^{-\alpha-1},$$

$$FT(h\log|h|) = \mathrm{i}\frac{\mathrm{sign}(\omega)}{2\omega^{2}}.$$

See [5] for more details.

Remark 4. From this proposition, we retrieve the same properties of dependence and interdependence of X_i and X_j as stated after Proposition 4.

2.3 Time reversibility

A stochastic process is said to be time reversible if X(t) = X(-t) for all t. As shows in [12], this is equivalent for zero-mean multivariate Gaussian stationary processes to $\mathbb{E}X_i(t)X_j(s) = \mathbb{E}X_i(s)X_j(t)$ for $s,t \in \mathbb{R}$ or that the cross covariance of the increments satisfies $\gamma_{i,j}(h,\delta) = \gamma_{i,j}(-h,\delta)$ for $h \in \mathbb{R}$. The following proposition characterizes this property.

Proposition 6. A mfBm is time reversible if and only if $\eta_{i,j} = 0$ (or $\tilde{\eta}_{i,j} = 0$) for all i, j = 1, ..., p.

Proof. If $\eta_{i,j} = 0$ (or $\tilde{\eta}_{i,j} = 0$), $\gamma_{i,j}(h,\delta)$ is proportional to the covariance of a fractional Gaussian noise with Hurst parameter $(H_i + H_j)/2$ and is therefore symmetric. Let us prove the converse. Let $\alpha = H_i + H_j$, then

$$\gamma_{i,j}(h,\delta) - \gamma_{i,j}(-h,\delta) = \sigma_i \sigma_j \times \\ \begin{cases} -\eta_{i,j} \left(\operatorname{sign}(h-\delta) |h-\delta|^{\alpha} + 2 \operatorname{sign}(h) |h|^{\alpha} - \operatorname{sign}(h+\delta) |h+\delta|^{\alpha} \right) & \text{if } \alpha \neq 1, \\ \tilde{\eta}_{i,j} \left((h-\delta) \log |h-\delta| - 2h \log |h| + (h+\delta) \log |h+\delta| \right) & \text{if } \alpha = 1. \end{cases}$$

Assuming $\gamma_{i,j}(h,\delta) - \gamma_{i,j}(-h,\delta)$ equals zero for all h leads to $\eta_{i,j} = 0$ (or $\tilde{\eta}_{i,j} = 0$).

Remark 5. This result can also be viewed from a spectral point view. The time reversibility of a mfBm is equivalent to the fact that the spectral density matrix is real. Using (9), this implies $\eta_{i,j} = 0$ (or $\tilde{\eta}_{i,j} = 0$).

3 Integral representation

3.1 Spectral representation

The following proposition contains the spectral representation of mfBm. This representation will be especially useful to obtain a condition easy to verify which ensures that the functions defined by (4) and (3) are covariance functions.

Theorem 7 (Didier and Pipiras, [12]). Let $(X(t))_{t\in\mathbb{R}}$ be a mfBm with parameter $(H_1, \dots, H_p) \in (0,1)^p$. Then there exists a $p \times p$ complex matrix A such that each component admits the following representation

$$X_i(t) = \sum_{j=1}^p \int \frac{e^{\mathbf{i}tx} - 1}{\mathbf{i}x} (A_{ik}x_+^{-H_i + 1/2} + \bar{A}_{ik}x_-^{-H_i + 1/2}) \tilde{B}_j(dx), \tag{13}$$

where for all j = 1, ..., p, \tilde{B}_j is a Gaussian complex measure such that $\tilde{B}_j = \tilde{B}_{j,1} + \mathbf{i}\tilde{B}_{j,2}$ with $\tilde{B}_{j,1}(x) = \tilde{B}_{j,1}(-x)$, $\tilde{B}_{j,2}(x) = -\tilde{B}_{j,2}(x)$, $\tilde{B}_{j,1}$ and $\tilde{B}_{j,2}$ are independent and $E(\tilde{B}_{j,i}(dx)\tilde{B}_{j,i}(dx)') = dx$, i = 1, 2.

Conversely, any p-multivariate process satisfying (13) is a mfBm process.

Proof. This representation is deduced from the general spectral representation of operator fractional Brownian motions obtained in [12]. By denoting $-\mathbb{H} + 1/2 := \operatorname{diag}(-H_1 + 1/2, \dots, -H_p + 1/2)$ we have indeed

$$X(t) = \int \frac{e^{\mathbf{i}tx} - 1}{\mathbf{i}x} (Ax_{+}^{-\mathbb{H}+1/2} + \bar{A}x_{-}^{-\mathbb{H}+1/2}) \tilde{B}(dx), \tag{14}$$

Any mfBm having representation (13) has a covariance function as in Proposition 3. The coefficients $\rho_{i,j}$, $\eta_{i,j}$, $\tilde{\rho}_{i,j}$ and $\tilde{\eta}_{i,j}$ involved in (3) and (4) satisfy

$$(AA^*)_{i,j} = \frac{\sigma_i \sigma_j}{2\pi} \Gamma(H_i + H_j + 1) \tau_{i,j}(1), \tag{15}$$

where $\tau_{i,j}$ is given in (10) and where A^* is the transpose matrix of \bar{A} . This relation is obtained by identification of the spectral matrix of the increments deduced on one hand from (13) and provided on the other hand in Proposition 5.

Given (13), relation (15) provides easily the coefficients $\rho_{i,j}$, $\eta_{i,j}$, $\tilde{\rho}_{i,j}$ and $\tilde{\eta}_{i,j}$ which define the covariance function. The converse is more difficult to obtain. Given a covariance function as in Proposition 3, obtaining the explicit representation (13) requires to find a matrix A such that (15) holds. This choice is possible if and only if the matrix on the right hand side of (15) is positive semidefinite. Then a matrix A (which is not unique) may be deduced by the Cholesky decomposition. When p = 2, an explicit solution is the matrix with entries, for i, j = 1, 2,

$$\begin{split} A_{i,j} &= \lambda_{i,j} \left[\left(\rho_{i,j} \sin \left(\frac{\pi}{2} (H_i + H_j) \right) + \eta_{i,j} \sqrt{\frac{1 - C_{i,j}}{C_{i,j}}} \cos \left(\frac{\pi}{2} (H_i + H_j) \right) \right) \right. \\ &\left. + i \left(\rho_{i,j} \sqrt{\frac{1 - C_{i,j}}{C_{i,j}}} \sin \left(\frac{\pi}{2} (H_i + H_j) \right) - \eta_{i,j} \cos \left(\frac{\pi}{2} (H_i + H_j) \right) \right) \right], \end{split}$$

where $\lambda_{i,j} = \frac{\sigma_i}{2\sqrt{\pi}} \frac{\Gamma(H_i + H_j + 1)}{\sqrt{\Gamma(2H_j + 1)\sin(H_j\pi)}}$ and $C_{i,j}$ is given in (12), provided $H_1 + H_2 \neq 1$. When $H_1 + H_2 = 1$, the same solution holds, replacing $\rho_{i,j}$ by $\tilde{\rho}_{i,j}$ and $\eta_{i,j}\cos\left(\frac{\pi}{2}(H_1 + H_2)\right)$ by $-\frac{\pi}{2}\tilde{\eta}_{i,j}$.

3.2 Moving average representation

In the next proposition, we give an alternative characterization of the mfBm from an integral representation in the time domain (or moving average representation).

Theorem 8 (Didier and Pipiras, [12]). Let $(X(t))_{t\in\mathbb{R}}$ be a mfBm with parameter $(H_1, \dots, H_p) \in (0,1)^p$. Assume that for all $i \in \{1,\dots,p\}$, $H_i \neq 1/2$. Then there exist M^+, M^- two $p \times p$ real matrices such that each component admits the following representation

$$X_{i}(t) = \sum_{j=1}^{p} \int_{\mathbb{R}} M_{i,j}^{+} \left((t-x)_{+}^{H_{i}-.5} - (-x)_{+}^{H_{i}-.5} \right) + M_{i,j}^{-} \left((t-x)_{-}^{H_{i}-.5} - (-x)_{-}^{H_{i}-.5} \right) W_{j}(\mathrm{d}x), \tag{16}$$

with $W(dx) = (W_1(dx), \dots, W_p(dx))$ is a Gaussian white noise with zero mean, independent components and covariance $\mathbb{E}W_i(dx)W_j(dx) = \delta_{i,j}dx$.

Conversely, any p-multivariate process satisfying (16) is a mfBm process.

Proof. This representation is deduced from the general representation obtained in [12]. \Box

Remark 6. When $H_i = 1/2$ for each $i \in \{1, ..., p\}$, it is shown in [12] that each component of the mfBm admits the following representation:

$$X_{i}(t) = \sum_{j=1}^{p} \int_{\mathbb{R}} M_{i,j}^{+}(\operatorname{sign}(t-x) - \operatorname{sign}(x)) + M_{i,j}^{-}(\log|t-x| - \log|x|) W_{j}(dx).$$

Our conjecture is that this representation remains valid when $H_i = 1/2$ whatever the values of other parameters H_j , $j \neq i$.

Starting from the moving average representation (16), using results in [27], we can specify the coefficients $\rho_{i,j}$, $\eta_{i,j}$, $\tilde{\rho}_{i,j}$ and $\tilde{\eta}_{i,j}$ involved in the covariances (3) and (4) (see [20]). More precisely, let us denote

$$M^{+}(M^{+})' = (\alpha_{i,j}^{++}), \quad M^{-}(M^{-})' = (\alpha_{i,j}^{--}), \quad M^{+}(M^{-})' = (\alpha_{i,j}^{+-})$$

where M' is the transpose matrix of M. The variance of each component is equal to

$$\sigma_i^2 = \frac{B(H_i + .5, H_i + .5)}{\sin(H_i \pi)} \left\{ \alpha_{i,i}^{++} + \alpha_{i,i}^{--} - 2\sin(H_i \pi) \alpha_{i,i}^{+-} \right\}.$$

Moreover, if $H_i + H_j \neq 1$ then

$$\sigma_i \sigma_j \rho_{i,j} = \frac{B(H_i + .5, H_j + .5)}{\sin((H_i + H_j)\pi)} \left\{ (\alpha_{i,j}^{++} + \alpha_{i,j}^{--})(\cos(H_i\pi) + \cos(H_j\pi)) - (\alpha_{i,j}^{+-} + \alpha_{i,j}^{-+})\sin((H_i + H_j)\pi) \right\},$$

$$\sigma_i \sigma_j \eta_{i,j} = \frac{B(H_i + .5, H_j + .5)}{\sin((H_i + H_j)\pi)} \left\{ (\alpha_{i,j}^{++} - \alpha_{i,j}^{--})(\cos(H_i\pi) - \cos(H_j\pi)) - (\alpha_{i,j}^{+-} - \alpha_{i,j}^{-+})\sin((H_i + H_j)\pi) \right\}.$$

If
$$H_i + H_j = 1$$
 then

$$\sigma_{i}\sigma_{j}\tilde{\rho}_{i,j} = B(H_{i} + .5, H_{j} + .5) \left\{ \frac{\sin(H_{i}\pi) + \sin(H_{j}\pi)}{2} (\alpha_{i,j}^{++} + \alpha_{i,j}^{--}) - \alpha_{i,j}^{+-} - \alpha_{i,j}^{-+} \right\},$$

$$\sigma_{i}\sigma_{j}\tilde{\eta}_{i,j} = (H_{j} - H_{i})(\alpha_{i,j}^{++} - \alpha_{i,j}^{--}).$$

Conversely, given a covariance function as in Proposition 3, if $H_i \neq 1/2$ for all i, one may find matrices M^+ and M^- such that (16) holds, provided the matrix on the right hand side of (15) is positive semidefinite. Indeed, in this case, a matrix A which solves (15) may be found by the Cholesky decomposition, then M^+ and M^- are deduced from relation (3.20) in [12]:

$$M^{\pm} = \sqrt{\frac{\pi}{2}} \left(D_1^{-1} A_1 \pm D_2^{-1} A_2 \right),\,$$

where $A = A_1 + \mathbf{i}A_2$ and

$$D_1 = \operatorname{diag}\left(\sin(\pi H_1)\Gamma(H_1 + \frac{1}{2}), \dots, \sin(\pi H_p)\Gamma(H_p + \frac{1}{2})\right),\,$$

$$D_2 = \operatorname{diag}\left(\cos(\pi H_1)\Gamma(H_1 + \frac{1}{2}), \dots, \cos(\pi H_p)\Gamma(H_p + \frac{1}{2})\right).$$

3.3 Two particular examples

Let us focus on two particular examples which are quite natural: the causal mfBm $(M^-=0)$ and the well-balanced mfBm $(M^-=M^+)$. In the causal case, the integral representation is a direct generalization of the integral representation of Mandelbrot and Van Ness [22] to the multivariate case. The well-balanced case is studied by Stoev and Taqqu in one dimension [27]. With the notation of the two previous sections, we note that the causal case (resp. well-balanced case) leads to $A_1 = \tan(\pi H)A_2$ (resp. $A_2 = 0$), where $\tan(\pi H) := \operatorname{diag}(\tan(\pi H_1), \ldots, \tan(\pi H_p))$. In these two cases, the covariance only depends on one parameter, for instance $\rho_{i,j}$ (or $\tilde{\rho}_{i,j}$). Indeed we easily deduce $\eta_{i,j}$ (or $\tilde{\eta}_{i,j}$) as follows:

• in the causal case : $M^- = 0$ or equivalently $A_1 = \tan(\pi H)A_2$.

$$\eta_{i,j} = -\rho_{i,j} \tan(\frac{\pi}{2}(H_i + H_j)) \tan(\frac{\pi}{2}(H_i - H_j)) \quad \text{if } H_i + H_j \neq 1,$$

$$\tilde{\eta}_{i,j} = \tilde{\rho}_{i,j} \frac{2}{\pi \tan(\pi H_i)} \quad \text{if } H_i + H_j = 1.$$

• in the well-balanced case : $M^- = M^+$ or equivalently $A_2 = 0$.

$$\begin{array}{rcl} \eta_{i,j} & = & 0 & \text{ if } H_i + H_j \neq 1, \\[1mm] \tilde{\eta}_{i,j} & = & 0 & \text{ if } H_i + H_j = 1. \end{array}$$

Remark 7. From Proposition 6, the well-balanced mfBm is therefore time reversible.

3.4 Existence of the covariance of the mfBm

In this paragraph, we highlight some of the previous results in order to exhibit the sets of the possible parameters $(\rho_{i,j}, \eta_{i,j})$ or $(\tilde{\rho}_{i,j}, \tilde{\eta}_{i,j})$ ensuring the existence of the covariance of the mfBm.

For $i, j = 1, \ldots, p$, let us give $(H_i, H_j) \in (0, 1)^2$, $(\sigma_i, \sigma_j) \in \mathbb{R}^+ \times \mathbb{R}^+$ and $(\rho_{i,j}, \eta_{i,j}) \in [-1, 1] \times \mathbb{R}$ with $\rho_{j,i} = \rho_{i,j}$ and $\eta_{j,i} = -\eta_{i,j}$ if $H_i + H_j \neq 1$, or $(\tilde{\rho}_{i,j}, \tilde{\eta}_{i,j}) \in [-1, 1] \times \mathbb{R}$ with $\tilde{\rho}_{j,i} = \tilde{\rho}_{i,j}$ and $\tilde{\eta}_{j,i} = -\tilde{\eta}_{i,j}$ if $H_i + H_j = 1$.

For this set of parameters, let us define the matrix $\Sigma(s,t) = (\Sigma_{i,j}(s,t))$ as follows: $\Sigma_{i,i}(s,t)$ is given by (2) and $\Sigma_{i,j}(s,t)$ is given by (3) when $H_i + H_j \neq 1$ and (4) when $H_i + H_j = 1$.

Proposition 9. The matrix $\Sigma(s,t)$ is a covariance matrix function if and only if the Hermitian matrix $Q = (\Gamma(H_i + H_j + 1)\tau_{i,j}(1))$ with $\tau_{i,j}$ defined in (10), is positive semidefinite. When p = 2, this condition reduces to $C_{1,2} \leq 1$ where $C_{1,2}$ is the coherence defined by (12).

Proof. First, note that since $\rho_{j,i} = \rho_{i,j}$ and $\eta_{j,i} = -\eta_{i,j}$, Q is a Hermitian matrix. Now, if Q is positive semidefinite, then so is the matrix $(2\pi)^{-1}(\sigma_i\sigma_jQ_{i,j})$. Therefore there exists a matrix A satisfying (15). From Theorem 7, there exists a mfBm having $\Sigma(s,t)$ as covariance matrix function. Conversely, if $\Sigma(s,t)$ is a covariance matrix function of a mfBm then the representation (13) holds and by (15), the matrix Q is positive semidefinite.

When p=2, the result comes from the fact that Q is positive semidefinite if and only if $det(Q) \geq 0$ or equivalently $C_{1,2} \leq 1$.

When p=2, for fixed values of (H_1,H_2) the condition $C_{1,2} \leq 1$ means that the set of possible parameters $(\rho_{1,2},\eta_{1,2})$ is the interior of an ellipse. These sets are represented in Figure 1 according to different values of H_1 and H_2 . Note that, in order to compare the cases $H_1+H_2\neq 1$ and $H_1+H_2=1$, we have reparameterized $\eta_{1,2}$ by $\eta'_{1,2}:=\eta_{1,2}/(1-H_1-H_2)$. In such a way, the second ellipse becomes the limit of the first one as $H_1+H_2\to 1$ (see also Remark 3).

Let us underline that the maximum possible correlation between two fBm's is obtained when $\eta_{1,2} = 0$, i.e. when the 2-mfBm is time reversible according to Proposition 6.

Remark 8. When $H_1 = \ldots = H_p = H \neq 1/2$, the matrix Q rewrites $Q_{i,j} = \Gamma(2H+1)(\sin(\pi H)\rho_{i,j} - i\eta_{i,j}\cos(\pi H))$ and

- if the mfBm is time reversible, i.e. $\eta_{i,j} = 0$ (for i, j = 1, ..., p), then Q is a correlation matrix and is therefore positive-semidefinite for any $|\rho_{i,j}| \leq 1$,
- when p=2, the set of possible values for $(\rho_{1,2}, \eta_{1,2})$ associated to H and 1-H are the same.

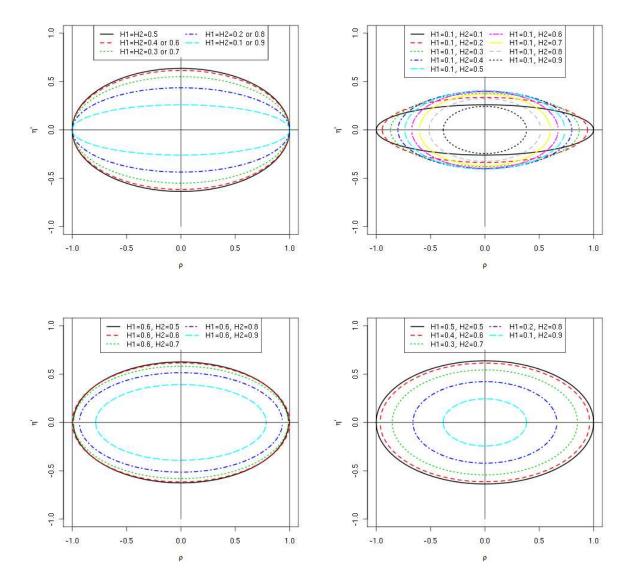


Figure 1: Various examples of possible values for $(\rho_{1,2}, \eta'_{1,2})$ with $\eta'_{1,2} := \eta_{1,2}/(1 - H_1 - H_2)$ when $H_1 + H_2 \neq 1$ and $(\tilde{\rho}_{1,2}, \tilde{\eta}_{1,2})$ when $H_1 + H_2 \neq 1$, ensuring that $\Sigma(s,t)$ is a covariance matrix function in the particular case p = 2.

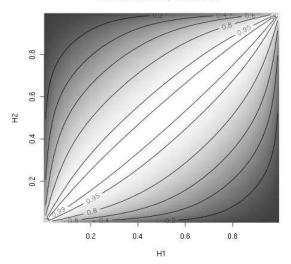
In the particular case of the causal or the well-balanced mfBm, the matrix $\Sigma(s,t)$ can be expressed through the sole parameter $\rho_{i,j}$. The maximal possible correlation when p=2 is given by

$$\rho_{1,2}^2 = \frac{\Gamma(2H_1+1)\Gamma(2H_2+1)}{\Gamma(H_1+H_2+1)^2} \frac{\sin(\pi H_1)\sin(\pi H_2)}{\sin(\frac{\pi}{2}(H_1+H_2))^2} \times \begin{cases} \cos(\frac{\pi}{2}(H_1-H_2))^2 & \text{in the causal case,} \\ 1 & \text{in the well-balanced case.} \end{cases}$$

Figure 2 represents $|\rho_{1,2}|$ with respect to (H_1, H_2) .



Maximal values of ρ - Well-balanced case



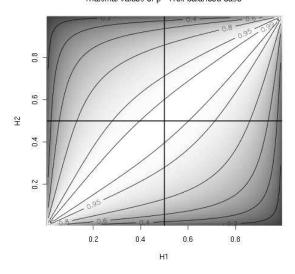


Figure 2: Maximal values of the absolute possible correlation parameter $|\rho_{1,2}|$ ensuring that $\Sigma(s,t)$ is a covariance matrix function in the case p=2, in terms of H_1 and H_2 for the causal and well-balanced mfBm.

Figures 1 and 2 illustrate the main limitation of the mfBm model. Under self-similarity condition (1), it is not possible to construct arbitrary correlated fractional Brownian motions. For example, when $H_1 = 0.1$ and $H_2 = 0.8$, the correlation cannot exceed 0.514.

4 The mfBm as a limiting process.

A natural way to construct self-similar processes is through limits of stochastic processes. In dimension one, the result is due to Lamperti [18]. In [16], an extension to operator self-similar processes is given. A similar result for the mfBm is deduced and stated below. In the following, a p-multivariate process $(X(t))_{t\in\mathbb{R}}$ is said proper if, for each t, the law of X(t) is not contained in a proper subspace of \mathbb{R}^p .

Theorem 10. Let $(X(t))_{t\in\mathbb{R}}$ be a p-multivariate proper process, continuous in probability. If there exist a p-multivariate process $(Y(t))_{t\in\mathbb{R}}$ and p real functions $a_1, ..., a_p$ such that

$$(a_1(n)Y_1(nt), \dots, a_p(n)Y_p(nt)) \xrightarrow{n \to \infty} X(t),$$
(17)

then the multivariate process (X(t)) is self-similar. Conversely, any multivariate self-similar process can be obtained as a such limit.

Proof. The proof is similar to Theorem 5 in [16]. Fix $k \in \mathbb{N}$ and r > 0. For each $T \in \mathbb{R}^k$ we denote $X(T) := (X(T_1), \dots, X(T_k))$. Let $\mathcal{D}_{r,k}$ be the set of all invertible diagonal matrices α such that, for all $T \in \mathbb{R}^k$, $X(rT) = \alpha X(T)$.

Let us first show that $\mathcal{D}_{r,k}$ is not empty. According to (17), we have

$$\operatorname{diag}(a_1(n),\ldots,a_p(n))Y(nrT) \xrightarrow[d]{n\to\infty} X(rT),$$

and

$$\operatorname{diag}(a_1(rn),\ldots,a_p(rn))Y(nrT) \xrightarrow{n\to\infty} X(T).$$

Since (X(t)) is proper, $\operatorname{diag}(a_1(n), \ldots, a_p(n))$ and $\operatorname{diag}(a_1(rn), \ldots, a_p(rn))$ are invertible for n large enough. Then, Theorem 2.3 in [31] ensures that α_n defined by

$$\alpha_n = \operatorname{diag}(a_1(n), \dots, a_p(n))\operatorname{diag}(a_1(nr), \dots, a_p(nr))^{-1}$$

has a limit in $\mathcal{D}_{r,k}$. Moreover if α is a limit of α_n then $X(rT) = \alpha X(T)$ and thus $\mathcal{D}_{r,k} \neq \emptyset$.

It is then straightforward to adapt Lemma 7.2-7.5 in [16] for the subgroup $\mathcal{D}_{r,k}$, which yields that for each r, $\cap_k \mathcal{D}_{r,k}$ is not empty. Therefore, for any fixed r > 0, there exists $\alpha \in \cap_k \mathcal{D}_{r,k}$ such that (X(rt)) and $(\alpha X(T))$ have the same finite dimensional distributions. Theorem 1 in [16] ensures that there exists $(H_1, \ldots, H_p) \in (0, 1)^p$ such that $\alpha = \operatorname{diag}(r^{H_1}, \ldots, r^{H_p})$. The converse is trivial.

As an illustration of Theorem 10, the mfBm can be obtained as the weak limit of partial sums of sum of linear processes (also called superlinear processes, see [33]). Some examples may be found in [8] and [19]. In Proposition 11 below, we give a general convergence result which allows to reach almost any mfBm from such partial sums. The unique restriction concerns the particular case when at least one of the Hurst parameters is equal to 1/2.

Let $(\epsilon_j(k))_{k\in\mathbb{Z}}$, $j=1,\ldots,p$ be p independent i.i.d. sequences with zero mean and unit variance. Let us consider the superlinear processes

$$Z_i(t) = \sum_{j=1}^p \sum_{k \in \mathbb{Z}} \psi_{i,j}(t-k)\epsilon_j(k), \quad i = 1, \dots, p,$$
(18)

where $\psi_{i,j}(k)$ are real coefficients with $\sum_{k\in\mathbb{Z}} \psi_{i,j}^2(k) < \infty$.

Moreover, we assume that $\psi_{i,j}(k) = \psi_{i,j}^+(k) + \psi_{i,j}^-(k)$ where $\psi_{i,j}^+(k)$ satisfies one of the following conditions:

(i)
$$\psi_{i,j}^+(k) = (\alpha_{i,j}^+ + o(1)) k_+^{d_{i,j}^+ - 1}$$
 as $|k| \to \infty$, with $0 < d_{i,j}^+ < \frac{1}{2}$ and $\alpha_{i,j}^+ \neq 0$,

(ii)
$$\psi_{i,j}^+(k) = (\alpha_{i,j}^+ + o(1)) k_+^{d_{i,j}^+ - 1}$$
 as $|k| \to \infty$, with $-\frac{1}{2} < d_{i,j}^+ < 0$, $\sum_{k \in \mathbb{Z}} \psi_{i,j}^+(k) = 0$ and $\alpha_{i,j}^+ \neq 0$,

(iii)
$$\sum_{k\in\mathbb{Z}} \left|\psi_{i,j}^+(k)\right| < \infty$$
 and let $\alpha_{i,j}^+ := \sum_{k\in\mathbb{Z}} \psi_{i,j}^+(k) \neq 0, \ d_{i,j}^+ := 0.$

Similarly, $\psi_{i,j}^-(k)$ is assumed to satisfy (i), (ii) or (iii) where k_+ , $d_{i,j}^+$ and $\alpha_{i,j}^+$ are replaced by k_- , $d_{i,j}^-$ and $\alpha_{i,j}^-$.

Proposition 11. Let $d_i = max(d_{i1}^+, d_{i1}^-, \dots, d_{ip}^+, d_{ip}^-)$, for $i = 1, \dots, p$. Consider the vector of partial sums, for $\tau \in \mathbb{R}$,

$$S_n(\tau) = \left(n^{-d_1 - (1/2)} \sum_{t=1}^{[n\tau]} Z_1(t), \cdots, n^{-d_p - (1/2)} \sum_{t=1}^{[n\tau]} Z_p(t)\right).$$

Then the finite dimensional distributions of $(S_n(\tau))_{\tau \in \mathbb{R}}$ converge in law towards a p-mfBm $(X(\tau))_{\tau \in \mathbb{R}}$.

- When $d_i \neq 0$, $(X_i(\tau))_{\tau \in \mathbb{R}}$ is defined through the integral representation (16) where $M_{i,j}^+ = \alpha_{i,j}^+ d_i^{-1} \mathbf{1}_{d_{i,j}^+ = d_i}$ and $M_{i,j}^- = \alpha_{i,j}^- d_i^{-1} \mathbf{1}_{d_{i,j}^- = d_i}$.
- When $d_i = 0$, $X_i(\tau) = \sum_{j=1}^d (\alpha_{i,j}^+ \mathbf{1}_{d_{i,j}^+ = 0} + \alpha_{i,j}^- \mathbf{1}_{d_{i,j}^- = 0}) W_j(\tau)$, where W_j is a standard Brownian motion.

Moreover, if for all j = 1, ..., p, $E(\epsilon_j(0)^{2\alpha}) < \infty$ with $\alpha > 1 \vee (1 + 2d_{max})^{-1}$ where $d_{max} = \max_i \{d_i\}$, then $S_n(.)$ converges towards the p-mfBm X(.) in the Skorohod space $\mathcal{D}([0,1])$.

Sketch of proof. We focus on the convergence in law of $S_n(\tau)$ to $X(\tau)$, for a fixed τ in \mathbb{R} , the finite dimensional convergence is deduced in the same way. We set for simplicity $\tau = 1$.

According to the Cramér-Wold device, for any vector $(\lambda_1, \ldots, \lambda_p) \in \mathbb{R}^p$, we must show that $\lambda' S_n(1)$ converges in law to $\lambda' X(1)$. We may rewrite $\lambda' S_n(1)$ as a sum of discrete stochastic integrals (see [29] and [4]):

$$\lambda' S_n(1) = \sum_{i=1}^p \lambda_i n^{-d_i - (1/2)} \sum_{t=1}^n Z_i(t)$$

$$= \sum_{i=1}^p \lambda_i \sum_{j=1}^p \sum_{k \in \mathbb{Z}} n^{-d_i - (1/2)} \sum_{t=1}^n (\psi_{i,j}^+(t-k) + \psi_{i,j}^-(t-k)) \epsilon_j(k)$$

$$= \sum_{i=1}^p \lambda_i \sum_{j=1}^p \int_{\mathbb{R}} (f_{i,j,n}^+(x) + f_{i,j,n}^-(x)) W_{j,n}(dx), \tag{19}$$

where the stochastic measures $W_{j,n}$, $j=1,\ldots,p$ are defined on finite intervals C by

$$W_{j,n}(C) = n^{-1/2} \sum_{k/n \in C} \epsilon_j(k),$$

and $f_{i,j,n}^+$, $f_{i,j,n}^-$ are piecewise constant functions defined for all $k \in \mathbb{Z}$ and for $nx \in (k-1,k]$ by $f_{i,j,n}^+(x) = n^{-d_i} \sum_{t=1}^n \psi_{i,j}^+(t-k)$, respectively $f_{i,j,n}^-(x) = n^{-d_i} \sum_{t=1}^n \psi_{i,j}^-(t-k)$.

The following lemma states the convergence of a linear combination of discrete stochastic

The following lemma states the convergence of a linear combination of discrete stochastic integrals as in (19). A function is said n-simple if it takes a finite number a nonzero constant values on intervals $(k/n, (k+1)/n], k \in \mathbb{Z}$.

Lemma 12. Let $(f_{1,n}, \dots, f_{p,n})_{n \in \mathbb{N}}$ be a sequence of p n-simple functions in $L^2(\mathbb{R})$. If for any $j = 1, \dots, p$, there exists $f_j \in L^2(\mathbb{R})$ such that $\int_{\mathbb{R}} |f_{j,n}(x) - f_j(x)|^2 dx \to 0$, then $\sum_{j=1}^p \int_{\mathbb{R}} f_{j,n}(x) W_{j,n}(dx)$ converges in law to $\sum_{j=1}^p \int_{\mathbb{R}} f_j(x) W_j(dx)$, where the W_j 's are independent standard Gaussian random measures.

When p=1, this lemma is proved in [28]. The case p=2 is considered in [4] and the extension to $p \geq 3$ is straightforward.

From Lemma 12 and (19), it remains to show that

$$\lim_{n \to \infty} \int_{\mathbb{R}} \left| f_{i,j,n}^{\pm}(x) - \frac{\alpha_{i,j}^{\pm}}{d_i} \left((1-x)_{\pm}^{d_i} - (-x)_{\pm}^{d_i} \right) \mathbf{1}_{d_{i,j}^{\pm} = d_i} \right|^2 dx = 0,$$

where we agree that $d_i^{-1}((1-x)_{\pm}^{d_i}-(-x)_{\pm}^{d_i})=\mathbf{1}_{[0,1]}(x)$ when $d_i=0$. Below, we only consider the pointwise convergence of $f_{i,j,n}^{\pm}(x)$, for $x\in\mathbb{R}$, when $d_{i,j}^{\pm}=d_i$. The convergence in L^2 is then deduced from the dominated convergence theorem (see [28], [29], [4] for details). It also follows easily that, when $d_{i,j}^{\pm}< d_i$, $\int_{\mathbb{R}} |f_{i,j,n}^{\pm}(x)|^2 dx \to 0$.

Under assumption (i), note that since $d_i > 0$, $(1-x)^{d_i}_{\pm} - (-x)^{d_i}_{\pm} = d_i \int_0^1 (t-x)^{d_i-1}_{\pm} dt$. Let us denote by $\lceil x \rceil$ the smallest integer not less than x. We have, for any $x \in \mathbb{R}$,

$$\begin{split} f_{i,j,n}^{\pm}(x) &= n^{-d_i} \sum_{t=1}^n \psi_{i,j}^{\pm}(t - \lceil nx \rceil) \\ &= n^{-d_i} \int_0^n \psi_{i,j}^{\pm}(\lceil t \rceil - \lceil nx \rceil) dt \\ &= n^{-d_i} \int_0^n \left(\alpha_{i,j}^{\pm} + o(1)\right) \left(\lceil t \rceil - \lceil nx \rceil\right)_{\pm}^{d_i - 1} dt \\ &= \int_0^1 \left(\alpha_{i,j}^{\pm} + o(1)\right) \left(\frac{\lceil nt \rceil - \lceil nx \rceil}{n}\right)_{\pm}^{d_i - 1} dt \longrightarrow \alpha_{i,j}^{\pm} \int_0^1 (t - x)_{\pm}^{d_i - 1} dt. \end{split}$$

Under assumption (ii), $d_i < 0$. When $x \le 0$, $(1-x)_+^{d_i} - (-x)_+^{d_i} = d_i \int_0^1 (t-x)^{d_i-1} dt$ and the convergence of $f_{i,j,n}^+(x)$ can be proved as above. When $x \ge 1$, $(1-x)_+^{d_i} - (-x)_+^{d_i} = 0 = f_{i,j,n}^+(x)$. When $0 \le x \le 1$, $(1-x)_+^{d_i} - (-x)_+^{d_i} = -d_i \int_1^{+\infty} (t-x)^{d_i-1} dt$ and, since $\sum_{k \in \mathbb{Z}} \psi_{i,j}^+(k) = 0$, we have

$$f_{i,j,n}^{+}(x) = n^{-d_i} \sum_{t=\lceil nx \rceil}^{n} \psi_{i,j}^{+}(t-\lceil nx \rceil) = n^{-d_i} \sum_{t=\lceil nx \rceil}^{n-\lceil nx \rceil} \psi_{i,j}^{+}(t) = -n^{-d_i} \sum_{t>n-\lceil nx \rceil} \psi_{i,j}^{+}(t).$$

Therefore,

$$\begin{split} f_{i,j,n}^+(x) &= -n^{-d_i} \int_{n-\lceil nx \rceil}^{+\infty} \left(\alpha_{i,j}^+ + o(1) \right) (\lceil t \rceil)^{d_i - 1} dt \\ &= - \int_{1-\frac{\lceil nx \rceil}{n}}^{+\infty} \left(\alpha_{i,j}^+ + o(1) \right) \left(\frac{\lceil nt \rceil}{n} \right)^{d_i - 1} dt \longrightarrow -\alpha_{i,j}^+ \int_{1-x}^{+\infty} t^{d_i - 1} dt = -\alpha_{i,j}^+ \int_{1}^{+\infty} (t-x)^{d_i - 1} dt. \end{split}$$

This proves $f_{i,j,n}^+(x) \to d_i^{-1}\alpha_{i,j}^+((1-x)_+^{d_i}-(-x)_+^{d_i})$, for any $x \in \mathbb{R}$, under assumption (ii). The same scheme may be used to prove that $f_{i,j,n}^-(x) \to d_i^{-1}\alpha_{i,j}^-((1-x)_-^{d_i}-(-x)_-^{d_i})$ under assumption (ii), noting that

$$(1-x)_{-}^{d_i} - (-x)_{-}^{d_i} = \begin{cases} 0 & \text{when } x \le 0, \\ -d_i \int_{-\infty}^{0} (t-x)^{d_i-1} dt & \text{when } 0 \le x \le 1, \\ d_i \int_{0}^{1} (t-x)_{-}^{d_i-1} dt & \text{when } x > 1. \end{cases}$$

Under assumption (iii),

$$f_{i,j,n}^{\pm}(x) = \sum_{t=1}^{n} \psi_{i,j}^{\pm}(t - \lceil nx \rceil) = \sum_{t=1-\lceil nx \rceil}^{n-\lceil nx \rceil} \psi_{i,j}^{\pm}(t).$$

Since $\sum_{t\in\mathbb{Z}} \psi_{i,j}^{\pm}(t) < \infty$, $f_{i,j,n}^{\pm}(x) \to 0$ for all $x \notin [0,1]$. When $x \in [0,1]$, we have $f_{i,j,n}^{\pm}(x) \to \alpha_{i,j}^{\pm}$. Therefore, the first claim of the theorem is proved, i.e. the convergence in law of the finite dimensional distribution of $(S_n(\tau))_{\tau \in \mathbb{R}}$ to $(X(\tau))_{\tau \in \mathbb{R}}$. To extend this convergence to a functional convergence in $\mathcal{D}([0,1])$, it remains to show tightness of the sequence $(S_n(\tau))_{\tau \in [0,1]}$. This follows exactly from the same arguments as in the proof of Theorem 1.2 in [4].

5 Synthesis of the mfBm

5.1 Introduction

The exact simulation of the fractional Brownian motion has been a question of great interest in the nineties. This may be done by generating a sample path of a fractional Gaussian noise. An important step towards efficient simulation was obtained after the work of Wood and Chan [32] about the simulation of arbitrary stationary Gaussian sequences with prescribed covariance function. The technique relies upon the embedding of the covariance matrix into a circulant matrix, a square root of which is easily calculated using the discrete Fourier transform. This leads to a very efficient algorithm, both in terms of computation time and storage needs. Wood and Chan methods is an exact simulation method provided that the circulant matrix is definite positive, a property that is not always satisfied. However, for the fractional Gaussian noise, it can be proved that the circulant matrix is definite positive for all $H \in (0,1)$, see [9, 13].

In [7], Wood and Chan extended their method and provided a more general algorithm adapted to multivariate stationary Gaussian processes. The main characteristic of this method is that if a certain condition for a familiy of Hermitian matrices holds then the algorithm is exact in principal, i.e. the simulated data has the true covariance. We present hereafter the main ideas, briefly describe the algorithm and propose some examples.

Remark 9. Other approaches could have been undertaken (see [3] for a review in the case p=1). Approximate simulations can be done by discretizing the moving-average or spectral stochastic integrals (13) or (16). [6] also proposed an approximate method based on the spectral density matrix of the increments for synthesizing multivariate Gaussian time series. Thanks to Proposition 5, this could also be envisaged for the mfBm.

5.2 Method and algorithm

For two arbitrary matrices $A = (A_{j,k})$ and B, we use $A \otimes B$ to denote the Kronecker product of A and B that is the block matrix $(A_{j,k}B)$.

Let $\Delta X := \Delta_1 X$ denotes the increments of size 1 $(\delta = 1)$ of a mfBm. We have $\Delta X = (\Delta X(t))_{t \in \mathbb{R}} = ((\Delta X_1(t), \dots, \Delta X_p(t))')_{t \in \mathbb{R}}$. The aim is to simulate a realization of a multivariate fractional Gaussian noise discretized at times $j = 1, \dots, n$, that is a realization of $(\Delta X(1), \dots, \Delta X(n))$. Then a realization of the discretized mfBm will be easily obtained.

We denote by $\Delta X^{(n)}$ the merged vector $\Delta X^{(n)} = (\Delta X(1)', \ldots, \Delta X(n)')'$ and by \mathbb{G} its covariance matrix. \mathbb{G} is the $np \times np$ Toeplitz block matrix $\mathbb{G} = (G(|i-j|))_{i,j=1,\ldots,n}$ where for $h = 0, \ldots, n-1, G(h)$ is the $p \times p$ matrix given by $G(h) := (\gamma_{j,k}(h))_{j,k=1,\ldots,p}$. The simulation problem can be viewed as the generation of a random vector following a $\mathcal{N}_{np}(0,\mathbb{G})$. This may be done by computing $\mathbb{G}^{1/2}$ but the complexity of such a procedure is $\mathcal{O}(pn^3)$. To overcome this numerical cost, the idea is to embed \mathbb{G} into the block circulant matrix $C = circ\{C(j), j = 0, \ldots, m-1\}$, where m is a power of 2 greater than 2(n-1) and where each C(j) is the $p \times p$ matrix defined by

$$C(j) = \begin{cases} G(j) & \text{if } 0 \le j < m/2\\ \frac{1}{2} (G(j) + G(j)') & \text{if } j = m/2\\ G(j - m) & \text{if } m/2 < j \le m - 1. \end{cases}$$
 (20)

Such a definition ensures that C is a symmetric matrix with nested block circulant structure and that $\mathbb{G} = \{C(j), j = 0, \dots, n-1\}$ is a submatrix of C. Therefore, the simulation of a $\mathcal{N}_{np}(0, \mathbb{G})$ may be achieved by taking the n "first" components of a vector $\mathcal{N}_{mp}(0, C)$, which is done by computing $C^{1/2}$. The last problem is more simple since one may exploit the circulant characteristic of C: there exist m Hermitian matrices B(j) of size $p \times p$ such that the following decomposition holds

$$C = (J \otimes I_p) \operatorname{diag}(B(j), j = 0, \dots, m - 1) (J^* \otimes I_p), \tag{21}$$

where Q is the $m \times m$ unitary matrix defined for j, k = 0, m - 1 by $J_{j,k} = e^{-2i\pi jk/m}$. The computation of $C^{1/2}$ is much less expensive than the computation of $\mathbb{G}^{1/2}$ since, as in the one-dimensional case (p = 1), (21) will allow us to make use of the Fast Fourier Transform (FFT) which considerable reduces the complexity.

Now, the algorithm proposed by Wood and Chan may be described through the following steps. Let m be a power of 2 greater than 2(n-1). Step 1. For $1 \le u \le v \le p$ calculate for $k = 0, \ldots, m-1$

$$B_{u,v}(k) = \sum_{j=0}^{m-1} C_{u,v}(j)e^{-2i\pi jk/m}$$

where $C_{u,v}(j)$ if the element (u,v) of the matrix C(j) defined by (20) and set $B_{vu}(k) = B_{u,v}(k)^*$.

Step 2. For each $j=0,\ldots,m-1$ determine a unitary matrix R(j) and real numbers $\xi_u(j)$ $(u=1,\ldots,p)$ such that B(j)=R(j) diag $(\xi_1(j),\ldots,\xi_p(j))$ $R(j)^*$.

Step 3. Assume that the eigenvalues $\xi_1(j), \ldots, \xi_p(j)$ are non-negative (see Remark 11) and define $\widetilde{B}(j) = R(j) \operatorname{diag}(\sqrt{\xi_1(j)}, \ldots, \sqrt{\xi_p(j)}) R(j)^*$.

Step 4. For j = 0, ..., m/2 generate independent vectors $U(j), V(j) \sim \mathcal{N}_p(0, I)$ and define

$$Z(j) = \frac{1}{\sqrt{2m}} \times \begin{cases} \sqrt{2}U(j) & \text{for } j = 0, \frac{m}{2} \\ U(j) + \mathbf{i}V(j) & \text{for } j = 1, \dots, \frac{m}{2} - 1, \end{cases}$$

let $Z(m-j) = \overline{Z}(j)$ for $j = \frac{m}{2} + 1, \dots, m-1$ and set $W(j) := \widetilde{B}(j)Z(j)$.

Step 5. For u = 1, ..., p calculate for k = 0, ..., m - 1

$$\Delta X_u(k) = \sum_{j=0}^{m-1} W_u(j)e^{-2\mathbf{i}\pi jk/m}$$

and return $\{\Delta X_u(k), 1 \leq u \leq p, k = 0, \dots, n-1\}.$

Step 6. For u = 1, ..., p take the cumulative sums ΔX_u to get the u - th component X_u of a sample path of a mfBm.

Figure 3 gives some examples of sample paths of mfBm's simulated with this algorithm.

Remark 10. Let us discuss the computation cost of the most expensive steps, that is steps 1, 2 and 5. Step 1 requires $\frac{p(p+1)}{2}$ applications of the FFT of signals of length m, Step 2 needs m diagonalisations of $p \times p$ Hermitian matrices and Step 5 requires p applications of the FFT of signals of length m. Therefore, the total cost, $\kappa(m, p)$ equals

$$\kappa(m,p) = \mathcal{O}\left(\frac{p(p+1)}{2}m\log m\right) + \mathcal{O}(mp^3) + \mathcal{O}(pm\log m).$$

Remark 11. The crucial point of the previous algorithm lies in the non-negativity of the eigenvalues $\xi_1(j), \ldots, \xi_p(j)$ for any $j=0,\ldots, m-1$. In the one-dimensional case (when p=1) Steps 2 and 3 disappear, and in Step 1, $B_{11}(k)$ corresponds to the k-th eigenvalue of the circulant matrix C_{11} with first line defined by $C_{11}(j)=\gamma_{11}(j)$ for $0 \le j \le m/2$ and $\gamma(m-j)$ for $j=m/2+1,\ldots, m-1$. For the fractional Gaussian noise, it has been proved by Craigmile [9] for H < 1/2, and by Dietrich and Newsam [13] for H > 1/2 that such a matrix is semidefinite-positive for any m (and so for the first power of 2 greater than 2(n-1)). In the more general case p > 1, the problem is much more complex: the quantities $B_{u,v}(k)$ are not necessarily real, and the establishment of a condition of positivity for the matrix $B_{u,v}(k)$ does not seem obvious. When the condition in Step 3 does not hold, Wood and Chan suggest to either increase the value of m and restart Steps 1,2 or to truncate the negative eigenvalues to zero which leads to an approximate procedure. These problems will be deserved in a separate paper. Let us assert that for the simulation examples presented in the next section, we have observed that this condition is satisfied for m equal to the first power of 2.

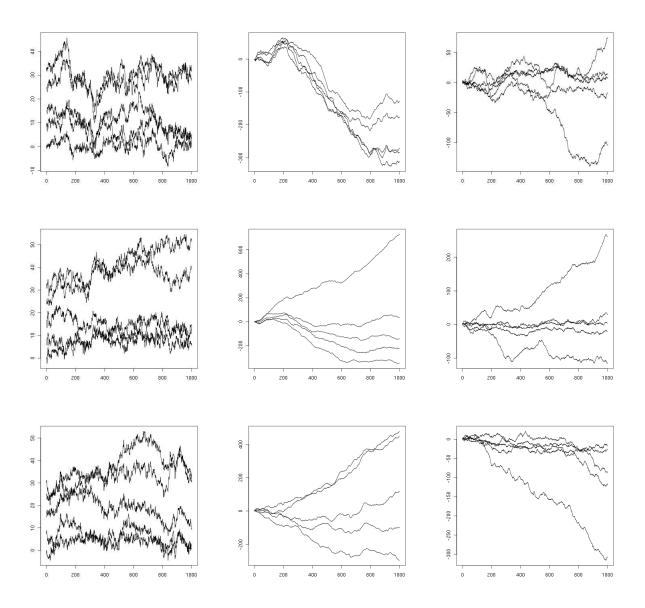


Figure 3: Examples of sample paths of length n=1000 normalized causal (top), well-balanced (middle) and general (bottom) multivariate fractional Brownian motion with p=5 components. The Hurst parameters are equally spaced in [0.3, 0.4] (left), [0.8, 0.9] (middle) and [0.4, 0.8] (right). The correlation parameters $\rho_{i,j}$ are all set to 0.6 (left, middle) and 0.3 (right). For the general mfBm (bottom), the parameters $\eta_{i,j}$ are set to $0.15 \times (1-H_i-H_j)$. Note that the existence condition discussed in Proposition 9 and the condition in Step 3 of the algorithm are satisfied for these different choices of parameters. For convenience, the sample paths of the left column have been decentered.

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