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# Mathematical modelling and analysis of replicated viruses for glioma cell control 

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#### Abstract

In this paper, we discuss biological background and mathematical analysis of glioma gene therapy for contributing to cancer treatment. By a reaction- diffusion system, we model interactions between gliom cells and viruses. We establish some sufficient conditions on model parameters which guarantee the permanence of the system and the existence of periodic solutions. Our study has experimental and theoretical implication in the perspective management strategy of therapy.


## 1 Introduction

Diffuse infiltrative gliomas are the most frequent primary central nervous system (CNS) tumors in adults. Their deserved reputation as devastating diseases is due in large part to their widespread invasiveness in the neuropil, i.e., the dense network of interwoven neuronal and glial cell processes.

Gene therapy consists of the delivery of a gene of interest to tumor cell populations to control and, when possible, kill the growing tumor. Viruses are prominent vehicles for gene therapy, and some adenoviral vectors exhibit oncolytic properties. To this end, a variety of viral vectors have been developed, with oncolytic viruses emerging as an innovative therapeutic tool

[^0]for these tumors. To be effective, a virus used for oncolytic therapy must have several features. The desired properties of these vectors include selectivity for the tumor target, minimal brain and systemic toxicities, and the capacity to penetrate and diffuse throughout the brain to reach all neoplastic foci residing beyond the resection border of the tumor. In addition, the viral vector needs to remain active despite evoking an immune response. The goal of developing an ideal vehicle for treatment of malignant brain tumors remains to be achieved. A wide variety of viral vectors have been developed and tested in the setting of gene therapy for malignant gliomas. These are based on different kinds of viruses, such as herpes simplex virus, retrovirus, measles virus, reovirus, and adenovirus. Some have shown promising results when tested in animal models of intra-cranial gliomas, but to date, clinical trials performed in humans have not shown a significant increase in survival.

Various vectors have been targeted toward cancer cells by deleting the genes responsible for bypassing those cells antiviral proteins. Without these genes, the designed vectors will only be able to replicate within cancer cells with disrupted antiviral mechanisms. The deletion of viral genes to enhance specificity for the killing of neoplastic cells is a principle well exemplified by the actions of two oncolytic adenoviruses, ONYX 015 and Ad5-Delta24. ONYX 015, has a deletion in the viral genomic region coding E1B 55kd. This deletion effectively limits the replication of the virus to neoplastic cells that have a defective p53 pathway (2; 12). A Phase I clinical trial to examine the effects of injection of ONYX 015 into peritumoral regions of recurrent malignant gliomas was recently completed and published (6). In that study, ONYX 015 was injected into the walls of tumor resection cavities. This trial proved that the injection of up to 1010 plaque-forming units of ONYX 015 into brain tissue surrounding a resected malignant glioma is safe in humans. Extensive efforts have been dedicated over many years to mathematical modelling of cancer development ( $14 ; 17 ; 18$ ). These mathematical models serve as valuable tools to predict possible outcomes of virus infection, and propose the optimal strategy of anti-virus therapy. Wodarz $(29 ; 30)$ presented a mathematical model that describes interaction between two types of tumor cells, the cells that are infected by the virus and the cells that are not infected but are susceptible to the virus so far as they have cancer phenotype and the immune system. Our system is more general than the one considered in $(29 ; 30)$ even when there is no diffusion. Because the free virus particles are very small, they disperse in the fluid tissue like Brownian particles. Therefore, we have incorporated into our model a diffusion term for the free viruses. We also assume that the tumor has a logistic growth, which can be slowed down by the inhibitor, captured in the expression $1-u$. Thus, the tumor admits a maximum size and density defined by the carrying capacity
$K$. When the virus is administered, the dynamic interactions between the virus and tumor cell populations is described by the following diffusive ratiodependent predator-prey model of reaction-diffusion equations in the tumor region $\Omega$,

$$
\begin{align*}
\frac{\partial V_{1}}{\partial t} & =\mu_{1} \Delta V_{1}+V_{1}\left[\rho(t, x)(1-u)\left(1-\frac{V_{1}}{K}\right)-d(x, t)\right] \\
& -\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}}, \quad x \in \Omega, \quad t>0  \tag{1}\\
\frac{\partial V_{2}}{\partial t} & =\mu_{2} \Delta V_{2}-V_{2}[a(t, x)(1-u)+d(t, x)] \\
& +\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}}, \quad x \in \Omega, \quad t>0  \tag{2}\\
\frac{\partial V_{3}}{\partial t} & =\mu_{3} \Delta V_{3}+k(t, x)(1-u) V_{2}-b(t, x) V_{3} \\
x & \in \Omega, \quad t>0,  \tag{3}\\
\left.\frac{\partial V_{1}}{\partial n}\right|_{\partial \Omega} & =0,\left.\quad \frac{\partial V_{2}}{\partial n}\right|_{\partial \Omega}=0,\left.\quad \frac{\partial V_{2}}{\partial n}\right|_{\partial \Omega}=0, t>0 \tag{4}
\end{align*}
$$

where $V_{1}$ is the number density of susceptible and uninfected tumor cells; $V_{2}$ is the number density of infected tumor cells and $V_{3}$ is the number density of free virus, i.e., virus in the extracellular tissue. When parameters of system (1-4) are constant, we determined in (5) the conditions for optimal therapy and estimated by numerical simulations, the patient survival time when tumor can not be cured. This paper is organized as follows: Section 2 is devoted to some preliminaries, which are needed in next sections, including some lemmas, due to Walter and Smith. In Section 3, some conditions for the ultimate boundedness of solutions and permanence of this system are established and in section 4, we study the existence of the unique periodic solutions of the system (1-4).

## 2 Preliminaries

We need the following lemmas due to Walter (27) and Smith (24), respectively.

Lemma 1. Suppose that vector-functions $v(t, x)=\left(v_{1}(t, x), \ldots, v_{m}(t, x)\right)$ and $w(t, x)=\left(w_{1}(t, x), \ldots, w_{m}(t, x)\right), m \geq 1$; satisfy the following conditions:
(i) they are of class $C^{2}$ in $x ; x \in X$ and of class $C^{1}$ in $(t, x) \in[a, b] \times \bar{\Omega}$, where $\Omega \subset \mathbb{R}^{n}$ is a bounded domain with smooth boundary;
(ii) $v_{t}-\mu \Delta v-g(t, x, v) \leq w_{t}-\mu \Delta w-g(t, x, w)$, where $(t, x) \in[a, b] \times \Omega, \mu=$ $\left(\mu_{1}, \ldots, \mu_{m}\right)>0$, vector-function $g(t, x, v)=\left(g_{1}(t, x, v), \ldots, g_{m}(t, x, v)\right)$ is continuously differential and quasi-monotonically increasing with respect to $u=\left(u_{1}, \ldots, u_{m}\right)$ and $\frac{\partial g_{i}\left(t, x, u_{1}, \ldots, u_{m}\right)}{\partial u_{j}} \geq 0, i, j=1, \ldots, m$, $i \neq j$;
(iii) $\frac{\partial v}{\partial n}=\frac{\partial w}{\partial n}=0,(t, x) \in[a, b] \times \partial \Omega$.

Then, $v(t, x) \leq w(t, x)$ for all $(t, x) \in[a, b] \times \bar{\Omega}$.
Lemma 2. Assume that $T$ and $\mu$ are positive real numbers, a function $u(t, x)$ is continuous on $[0, T] \times \bar{T}$, continuously differential in $x \in \bar{\Omega}$, with continuous derivatives $\frac{\partial^{2} u}{\partial x_{i} \partial x_{j}}$ and $\frac{\partial u}{\partial t}$ on $(0, T] \times \Omega$, and $u(t, x)$ satisfies the following inequalities:

$$
\begin{aligned}
u_{t}-\mu \Delta u-c(t, x, u) & \geq 0, \quad(t, x) \in(0, T] \times \Omega, \\
\frac{\partial u}{\partial n} & \geq 0, \quad(t, x) \in(0, T] \times \partial \Omega, \\
u(t, x) & \geq 0, \quad x \in \Omega,
\end{aligned}
$$

where $c(t, x, u)$ is bounded on $(0, T] \times \Omega$. Then $u(t, x) \geq 0$ on $x \in(0, T] \times$ $\bar{\Omega}$. Moreover, $u(t, x)$ is strictly positive on $x \in(0, T] \times \bar{\Omega}$ if $u(t, x)$ is not identically zero.

Consider the following logistic differential equation:

$$
\begin{equation*}
\frac{d z}{d t}=z(a-b z), \tag{5}
\end{equation*}
$$

where $z \in \mathbb{R}^{+} ; a$ and $b$ are positive constants.
Lemma 3. Every solution $z\left(t, 0, z_{0}\right), z_{0}>0$ of (5) satisfies

$$
\lim _{t \rightarrow+\infty} z(t)=\frac{a}{b} .
$$

## 3 Permanence

Throughout the paper we always assume that $(H): a(t, x), b(t, x), d(t, x)$, $k(t, x), r(t, x)$ and $\rho(t, x)$ are bounded positive-valued functions on $\mathbb{R} \times \bar{\Omega}$ continuously differential in $t$ and $x$, and are periodic in $t$ with a period $\omega>0$.

Definition 4. Solutions of system (1-4) are said to be ultimately bounded if there exist positive constants $N_{1}, N_{2}, N_{3}$ such that for every solution $\left(V_{1}\left(t, x, V_{01}, V_{03}, V_{03}\right) ; V_{2}\left(t, x, V_{01}, V_{03}, V_{03}\right) ; V_{3}\left(t, x, V_{01}, V_{03}, V_{03}\right)\right)$ there exists a moment of time $\bar{t}=\bar{t}\left(V_{01}, V_{03}, V_{03}\right)>0$ such that $V_{1}\left(t, x, V_{01}, V_{03}, V_{03}\right) \leq N_{1}$, $V_{2}\left(t, x, V_{01}, V_{03}, V_{03}\right) \leq N_{2}, V_{3}\left(t, x, V_{01}, V_{03}, V_{03}\right) \leq N_{3}$, for all $x \in \bar{\Omega}$ and $t>\bar{t}$.

Definition 5. System (1-4) is said to be permanent if there exist positive constants $\zeta$ and $\eta$ such that for every solution with non-negative initial functions $V_{01}(x), V_{02}(x)$ and $V_{03}(x), V_{01}(x) \neq 0, V_{02}(x) \neq 0, V_{03}(x) \neq 0$, there exists a moment of time $\hat{t}=\hat{t}\left(V_{01}, V_{03}, V_{03}\right)$ such that $\zeta \leq V_{1}\left(t, x, V_{01}, V_{03}, V_{03}\right) \leq \eta$, $\zeta \leq V_{2}\left(t, x, V_{01}, V_{03}, V_{03}\right) \leq \eta, \zeta \leq V_{3}\left(t, x, V_{01}, V_{03}, V_{03}\right) \leq \eta$, for all $x \in \bar{\Omega}$ and $t>\hat{t}$.

For simplicity, for a bounded function $\varphi(t, x)$, we denote $\varphi_{m}=\inf _{(t, x)} \varphi(t, x)$ and $\varphi_{M}=\sup _{(t, x)} \varphi(t, x)$. Now we have the following positively invariant principle for system (1-4)

Theorem 6. Assume that conditions $(H)$ hold, then non-negative and positive quadrants of $\mathbb{R}^{3}$ are positively invariant for system (1-4).

Proof. Suppose $\left(V_{1}\left(t, x, V_{01}, V_{03}, V_{03}\right) ; V_{2}\left(t, x, V_{01}, V_{03}, V_{03}\right) ; V_{3}\left(t, x, V_{01}, V_{03}, V_{03}\right)\right)$ is a solution of system $(1-4)$ with initial condition $V_{01}(x) \geq 0\left(V_{01}(x) \neq 0\right)$, $V_{02}(x) \geq 0\left(V_{02}(x) \neq 0\right), V_{03}(x) \geq 0\left(V_{03}(x) \neq 0\right)$. Let $\hat{V}_{1}(t, x)$ a solution of

$$
\begin{align*}
& \frac{\partial \hat{V}_{1}}{\partial t}-\mu_{1} \Delta \hat{V}_{1}+\hat{V}_{1}\left[d_{M}-\rho_{m}(1-u)\left(1-\frac{\hat{V}_{1}}{K}\right)+\varepsilon^{-1} \beta_{M} r_{M}\right]=0 \\
& \hat{V}_{1}(0, x)=V_{01}(x),\left.\quad \frac{\partial \hat{V}_{1}}{\partial n}\right|_{\partial \Omega} \geq 0, t>0 \tag{6}
\end{align*}
$$

It holds that

$$
\begin{aligned}
& \frac{\partial \hat{V}_{1}}{\partial t}-\mu_{1} \Delta \hat{V}_{1}+\hat{V}_{1}\left[d(x, t)-\rho(t, x)(1-u)\left(1-\frac{\hat{V}_{1}}{K}\right)\right]+\frac{\beta r(t, x) \hat{V}_{1} V_{3}}{1+\varepsilon V_{3}} \\
& \leq \frac{\partial \hat{V}_{1}}{\partial t}-\mu_{1} \Delta \hat{V}_{1}+\hat{V}_{1}\left[d_{M}-\rho_{m}(1-u)\left(1-\frac{\hat{V}_{1}}{K}\right)+\varepsilon^{-1} \beta_{M} r_{M}\right]
\end{aligned}
$$

which implies that $\hat{V}_{1}(t, x)$ is a lower solution of equation (1). By Lemme 2, we have $\hat{V}_{1}(t, x) \geq 0$ for all $t>0$ and $x \in \bar{\Omega}$. In addition, since $V_{01}(x) \geq 0$ $\left(V_{01}(x) \neq 0\right)$, then $\hat{V}_{1}(t, x)>0$ for all $t>0$ and $x \in \bar{\Omega}$. Thus by Lemme 1 , $V_{1}(t, x)$ is bounded from below by positive function $\hat{V}_{1}(t, x)$, and so $V_{1}(t, x)>$
0.

Let $\hat{V}_{2}(t, x)$ a solution of

$$
\begin{align*}
& \frac{\partial \hat{V}_{2}}{\partial t}-\mu_{2} \Delta \hat{V}_{2}+\hat{V}_{2}\left[a_{M}(1-u)+d_{M}\right]=0, \\
& \hat{V}_{2}(0, x)=V_{02}(x),\left.\frac{\partial \hat{V}_{2}}{\partial n}\right|_{\partial \Omega} \geq 0, t>0 \tag{7}
\end{align*}
$$

It holds that

$$
\begin{aligned}
& \frac{\partial \hat{V}_{2}}{\partial t}-\mu_{2} \Delta \hat{V}_{2}+\hat{V}_{2}[a(t, x)(1-u)+d(t, x)]-\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}} \\
& \leq \frac{\partial \hat{V}_{2}}{\partial t}-\mu_{2} \Delta \hat{V}_{2}+\hat{V}_{2}\left[a_{M}(1-u)+d_{M}\right]=0,
\end{aligned}
$$

which implies that $\hat{V}_{2}(t, x)$ is a lower solution of equation (2). Let $\hat{V}_{3}(t, x)$ a solution of

$$
\begin{align*}
& \frac{\partial \hat{V}_{3}}{\partial t}-\mu_{3} \Delta \hat{V}_{3}+b_{M} \hat{V}_{3}=0 \\
& \hat{V}_{3}(0, x)=V_{03}(x),\left.\frac{\partial \hat{V}_{3}}{\partial n}\right|_{\partial \Omega} \geq 0, t>0 \tag{8}
\end{align*}
$$

It holds that

$$
\begin{aligned}
& \frac{\partial \hat{V}_{3}}{\partial t}-\mu_{3} \Delta \hat{V}_{3}+b(t, x) \hat{V}_{3}-k(t, x)(1-u) V_{2} \\
& \leq \frac{\partial \hat{V}_{3}}{\partial t}-\mu_{3} \Delta \hat{V}_{3}+b_{M} \hat{V}_{3}=0
\end{aligned}
$$

which implies that $\hat{V}_{3}(t, x)$ is a lower solution of (3).
A similar argument to $V_{1}(t, x)$ leads that $V_{2}(t, x)$ and $V_{3}(t, x)$ are bounded from below respectively by positive functions $\hat{V}_{2}(t, x)$ and $\hat{V}_{3}(t, x)$.

Theorem 7. Assume that conditions ( $H$ ) hold, then all solutions of system (1-4) with non-negative initial functions are ultimately bounded.
Proof. Let $\bar{V}_{1}(t, x)$ a solution of

$$
\begin{align*}
& \frac{\partial \bar{V}_{1}}{\partial t}-\mu_{1} \Delta \bar{V}_{1}-\rho_{M}(1-u)\left(1-\frac{\bar{V}_{1}}{K}\right) \bar{V}_{1}=0, \\
& \bar{V}_{1}\left(0, M_{V_{1}}\right)=M_{V_{1}}, \tag{9}
\end{align*}
$$

where $M_{V_{1}}$ is such that $\max _{x \in \bar{\Omega}}\left|V_{01}(x)\right| \leq M_{V_{1}}$.

It holds that

$$
\begin{aligned}
0 & =\frac{\partial V_{1}}{\partial t}-\mu_{1} \Delta V_{1}+V_{1}\left[d(x, t)-\rho(t, x)(1-u)\left(1-\frac{V_{1}}{K}\right)\right]+\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}} \\
& \geq \frac{\partial V_{1}}{\partial t}-\mu_{1} \Delta V_{1}-\rho_{M}(1-u)\left(1-\frac{V_{1}}{K}\right) V_{1}
\end{aligned}
$$

So, we get

$$
\begin{aligned}
& 0=\frac{\partial \bar{V}_{1}}{\partial t}-\mu_{1} \Delta \bar{V}_{1}-\rho_{M}(1-u)\left(1-\frac{\bar{V}_{1}}{K}\right) \bar{V}_{1} \\
& \geq \frac{\partial V_{1}}{\partial t}-\mu_{1} \Delta V_{1}-\rho_{M}(1-u)\left(1-\frac{V_{1}}{K}\right) V_{1} .
\end{aligned}
$$

Therefore, Lemme 1 gives $V_{1}\left(t, x, V_{01}, V_{02}, V_{03}\right) \leq \bar{V}_{1}\left(t, M_{V_{1}}\right)$.
Note that, according to the uniqueness theorem, the solution $\bar{V}_{1}\left(t, M_{V_{1}}\right)$ of (9), does not depend on $x$ for $t>0$, and so $\bar{V}_{1}\left(t, M_{V_{1}}\right)$ satisfies the ordinary differential equation

$$
\frac{\partial \bar{V}_{1}}{\partial t}-\rho_{M}(1-u)\left(1-\frac{\bar{V}_{1}}{K}\right) \bar{V}_{1}=0 .
$$

By Lemme 3, we have

$$
\bar{V}_{1}\left(t, M_{V_{1}}\right) \longrightarrow K, \text { as } t \rightarrow+\infty .
$$

So, there exists $N_{1}$ and $t_{1}>0$ such that $V_{1}(t, x) \leq N_{1}$.
For the infected tumor cells, we have the following inequality

$$
\begin{aligned}
& 0=\frac{\partial V_{2}}{\partial t}-\mu_{2} \Delta V_{2}+V_{2}\left[a(t, x)(1-u) V_{2}+d(t, x)\right]-\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}} \\
& \geq \frac{\partial V_{2}}{\partial t}-\mu_{2} \Delta V_{2}+V_{2}\left[a_{m}(1-u)+d_{m}\right]-\varepsilon^{-1} \beta_{M} r_{M} N_{1} .
\end{aligned}
$$

So, we get

$$
\begin{aligned}
& 0=\frac{\partial \bar{V}_{2}}{\partial t}-\mu_{2} \Delta \bar{V}_{2}+\bar{V}_{2}\left[a_{m}(1-u)+d_{m}\right]-\varepsilon^{-1} \beta_{M} r_{M} N_{1} \\
& \geq \frac{\partial V_{2}}{\partial t}-\mu_{2} \Delta V_{2}+V_{2}\left[a_{m}(1-u)+d_{m}\right]-\varepsilon^{-1} \beta_{M} r_{M} N_{1} .
\end{aligned}
$$

Therefore, Lemme 1 gives $V_{2}\left(t, x, V_{01}, V_{02}, V_{03}\right) \leq \bar{V}_{2}\left(t, M_{V_{2}}\right)$, where $\bar{V}_{2}\left(t, M_{V_{2}}\right)$ satisfies the ordinary differential equation

$$
\frac{\partial \bar{V}_{2}}{\partial t}=-\bar{V}_{2}\left[a_{m}(1-u)+d_{m}\right]+\varepsilon^{-1} \beta_{M} r_{M} N_{1}, \bar{V}_{2}\left(0, M_{V_{2}}\right)=M_{V_{2}} .
$$

Since

$$
\bar{V}_{2}\left(t, M_{V_{2}}\right) \longrightarrow \frac{\varepsilon^{-1} \beta r_{M} N_{1}}{a_{m}(1-u)+d_{m}} \text { as } t \rightarrow+\infty
$$

thus, there exists $N_{2}$ and $t_{2}>0$ such that $V_{2}(t, x) \leq N_{2}$.
For the virus in the extracellular tissue, we have the following inequality

$$
\begin{aligned}
0 & =\frac{\partial V_{3}}{\partial t}-\mu_{3} \Delta V_{3}+b(t, x) V_{3}-k(t, x)(1-u) V_{2} \\
& \geq \frac{\partial V_{3}}{\partial t}-\mu_{3} \Delta V_{3}+b_{m} V_{3}-k_{M}(1-u) N_{2} .
\end{aligned}
$$

So, we get

$$
\begin{aligned}
& 0=\frac{\partial \bar{V}_{3}}{\partial t}-\mu_{3} \Delta \bar{V}_{3}+b_{m} \bar{V}_{3}-k_{M}(1-u) N_{2} \\
& \geq \frac{\partial V_{3}}{\partial t}-\mu_{3} \Delta V_{3}+b_{m} V_{3}-k_{M}(1-u) N_{2} .
\end{aligned}
$$

Therefore, Lemme 1 gives $V_{3}\left(t, x, V_{01}, V_{02}, V_{03}\right) \leq \bar{V}_{3}\left(t, M_{V_{3}}\right)$, where $\bar{V}_{3}\left(t, M_{V_{3}}\right)$ satisfies the ordinary differential equation

$$
\frac{\partial \bar{V}_{3}}{\partial t}=-b_{m} \bar{V}_{3}+k_{M}(1-u) N_{2}, \bar{V}_{3}\left(0, M_{V_{3}}\right)=M_{V_{3}} .
$$

Since

$$
\bar{V}_{3}\left(t, M_{V_{3}}\right) \longrightarrow \frac{k_{M}(1-u) N_{2}}{b_{m}} \text { as } t \rightarrow+\infty
$$

thus, there exists $N_{3}$ and $t_{3}>0$ such that $V_{3}(t, x) \leq N_{3}$.
Theorem 8. Assume that conditions ( $H$ ) hold, in addition, if $d_{M}+\beta \varepsilon^{-1} r_{M}<$ $\rho_{m}(1-u)$, then the system (1-4) is permanent.
Proof. Theorem 7 implies that there exists $\eta>0$ such that $V_{1}(t, x) \leq \eta$, $V_{2}(t, x) \leq \eta$ and $V_{3}(t, x) \leq \eta$ starting with a certain moment of time. Note that, by comparison principle, if $V_{01}(x) \geq 0\left(V_{01}(x) \neq 0\right), V_{02}(x) \geq 0$ $\left(V_{02}(x) \neq 0\right)$ and $V_{03}(x) \geq 0\left(V_{03}(x) \neq 0\right)$, then $V_{1}\left(t, x, V_{01}, V_{03}, V_{03}\right)>0$, $V_{2}\left(t, x, V_{01}, V_{03}, V_{03}\right)>0$ and $V_{3}\left(t, x, V_{01}, V_{03}, V_{03}\right)>0$ for all $x \in \bar{\Omega}$ and $t>0$. Considering the solution on the interval $t \geq \epsilon$ with some $\epsilon>0$, we get $\left(V_{1}\left(\epsilon, x, V_{01}, V_{03}, V_{03}\right) ; V_{2}\left(\epsilon, x, V_{01}, V_{03}, V_{03}\right) ; V_{3}\left(\epsilon, x, V_{01}, V_{03}, V_{03}\right)\right)$ separated from zero. Therefore, we can assume that $\min _{x \in \bar{\Omega}} V_{01}(x)=m_{V_{1}}>0$, $\min _{x \in \bar{\Omega}} V_{02}(x)=m_{V_{2}}>0$ and $\min _{x \in \bar{\Omega}} V_{03}(x)=m_{V_{3}}>0$. Let $\hat{V}_{1}(t, x) \mathrm{a}$ solution of

$$
\begin{align*}
& \frac{\partial \hat{V}_{1}}{\partial t}+\hat{V}_{1}\left[d_{M}-\rho_{m}(1-u)\left(1-\frac{\hat{V}_{1}}{K}\right)+\varepsilon^{-1} \beta_{M} r_{M}\right]=0, \\
& \hat{V}_{1}\left(0, M_{V_{1}}\right)=m_{V_{1}} \tag{10}
\end{align*}
$$

So using the inequality

$$
\begin{aligned}
0 & =\frac{\partial V_{1}}{\partial t}-\mu_{1} \Delta V_{1}+V_{1}\left[d(x, t)-\rho(t, x)(1-u)\left(1-\frac{V_{1}}{K}\right)\right]+\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}} \\
& \leq \frac{\partial V_{1}}{\partial t}-\mu_{1} \Delta V_{1}+V_{1}\left[d_{M}-\rho_{m}(1-u)\left(1-\frac{V_{1}}{K}\right)+\varepsilon^{-1} \beta_{M} r_{M}\right]
\end{aligned}
$$

one has by (10),

$$
\begin{aligned}
0 & =\frac{\partial \hat{V}_{1}}{\partial t}-\mu_{1} \Delta \hat{V}_{1}+\hat{V}_{1}\left[d_{M}-\rho_{m}(1-u)\left(1-\frac{\hat{V}_{1}}{K}\right)+\varepsilon^{-1} \beta_{M} r_{M}\right] \\
& \leq \frac{\partial V_{1}}{\partial t}-\mu_{1} \Delta V_{1}+V_{1}\left[d_{M}-\rho_{m}(1-u)\left(1-\frac{V_{1}}{K}\right)+\varepsilon^{-1} \beta_{M} r_{M}\right] .
\end{aligned}
$$

Therefore, Lemme 1 gives $V_{1}\left(t, x, V_{01}, V_{02}, V_{03}\right) \geq \hat{V}_{1}\left(t, m_{V_{1}}\right)$. By the condition $d_{M}+\varepsilon^{-1} \beta_{M} r_{M}<\rho_{m}(1-u)$, we have

$$
\hat{V}_{1}\left(t, m_{V_{1}}\right) \longrightarrow \frac{K\left[\rho_{m}(1-u)-d_{M}-\varepsilon^{-1} \beta_{M} r_{M}\right]}{\rho_{m}(1-u)}, t \rightarrow+\infty .
$$

Therefore, there exist $\zeta_{1}>0$ such that $V_{1}\left(t, x, V_{01}, V_{02}, V_{03}\right) \geq \zeta_{1}$ for $t$ large enough.
Let $\hat{V}_{2}(t, x)$ a solution of

$$
\begin{equation*}
\frac{\partial \hat{V}_{2}}{\partial t}+\hat{V}_{2}\left[a_{M}(1-u)+d_{M}\right]-\varepsilon^{-1} \beta_{M} r_{M} \zeta_{1}=0, \quad \hat{V}_{2}(0, x)=m_{V_{2}} . \tag{11}
\end{equation*}
$$

Using the inequality

$$
\begin{aligned}
0 & =\frac{\partial V_{2}}{\partial t}-\mu_{2} \Delta V_{2}+V_{2}[a(t, x)(1-u)+d(t, x)]-\frac{\beta r(t, x) V_{1} V_{3}}{1+\varepsilon V_{3}} \\
& \leq \frac{\partial V_{2}}{\partial t}-\mu_{2} \Delta V_{2}+V_{2}\left[a_{M}(1-u)+d_{M}\right]-\varepsilon^{-1} \beta_{M} r_{M} \zeta_{1},
\end{aligned}
$$

we have by (11),

$$
\begin{aligned}
& 0=\frac{\partial \hat{V}_{2}}{\partial t}-\mu_{2} \Delta \hat{V}_{2}+\hat{V}_{2}\left[a_{M}(1-u)+d_{M}\right]-\varepsilon^{-1} \beta_{M} r_{M} \zeta_{1} \\
& \leq \frac{\partial V_{2}}{\partial t}-\mu_{2} \Delta V_{2}+V_{2}\left[a_{M}(1-u)+d_{M}\right]-\varepsilon^{-1} \beta_{M} r_{M} \zeta_{1} .
\end{aligned}
$$

Therefore, $V_{2}\left(t, x, V_{01}, V_{02}, V_{03}\right) \geq \hat{V}_{2}\left(t, m_{V_{2}}\right) \longrightarrow \frac{\varepsilon^{-1} \beta_{M} r_{M} \zeta_{1}}{a_{M}(1-u)+d_{M}}$,
as $t \rightarrow+\infty$. Therefore, there exist $\zeta_{2}>0$ such that $V_{2}\left(t, x, V_{01}, V_{02}, V_{03}\right) \geq \zeta_{2}$
for $t$ large enough.
Now, let $\hat{V}_{3}(t, x)$ a solution of

$$
\begin{equation*}
\frac{\partial \hat{V}_{3}}{\partial t}+b_{M} \hat{V}_{3}-k_{M}(1-u) \zeta_{2}=0, \quad \hat{V}_{3}(0, x)=m_{V_{3}} \tag{12}
\end{equation*}
$$

By the following inequality,

$$
\begin{aligned}
0 & =\frac{\partial V_{3}}{\partial t}-\mu_{3} \Delta V_{3}+b(t, x) V_{3}-k(t, x)(1-u) V_{2} \\
& \leq \frac{\partial V_{3}}{\partial t}-\mu_{3} \Delta V_{3}+b_{M} V_{3}-k_{M}(1-u) \zeta_{2}
\end{aligned}
$$

we have
$\frac{\partial \hat{V}_{3}}{\partial t}-\mu_{3} \Delta \hat{V}_{3}+b_{M} \hat{V}_{3}-k_{M}(1-u) \zeta_{2} \leq \frac{\partial V_{3}}{\partial t}-\mu_{3} \Delta V_{3}+b_{M} V_{3}-k_{M}(1-u) \zeta_{2}$.
Therefore, $V_{3}\left(t, x, V_{01}, V_{02}, V_{03}\right) \geq \hat{V}_{3}\left(t, m_{V_{3}}\right) \longrightarrow \frac{k_{M}(1-u) \zeta_{2}}{b_{M}}$, as $t \rightarrow+\infty$. Therefore, there exist $\zeta_{3}>0$ such that $V_{3}\left(t, x, V_{01}, V_{02}, V_{03}\right) \geq \zeta_{3}$ for $t$ large enough.

## 4 Periodic solutions

Theorem 9. Assume that conditions (H) hold and system (1-4) is permanent. Moreover, if we assume the following conditions:

$$
\begin{align*}
& 2\left(\rho_{M}(1-u)(1-2 \zeta / K)-d_{m}\right)-\varepsilon^{-1} \beta_{M} r_{M}<0  \tag{13}\\
& \frac{\beta_{M}}{\varepsilon} r_{M}+k_{M}-4 \zeta a_{M}(1-u)+2 d_{M}<0,  \tag{14}\\
& k_{M}-2 b_{m}<0 \tag{15}
\end{align*}
$$

then, the system has a unique globally asymptotic stable strictly positive $\omega$ periodic solution.

Proof. For convenience, we denote $a=a(t, x)$, and similar meaning to $b, d, k$, $r$ and $\rho$. Let $\left(V_{1}^{1}(t, x), V_{2}^{1}(t, x), V_{3}^{1}(t, x)\right)$ and $\left(V_{2}^{1}(t, x), V_{2}^{2}(t, x), V_{3}^{2}(t, x)\right)$ be two solutions of system bounded by constants $\zeta$ and $\eta$ for below and above. Consider the function
$L(t)=\int_{\Omega}\left[\left(V_{1}^{1}(t, x)-V_{1}^{2}(t, x)\right)^{2}+\left(V_{2}^{1}(t, x)-V_{2}^{2}(t, x)\right)^{2}+\left(V_{3}^{1}(t, x)-V_{3}^{2}(t, x)\right)^{2}\right] d x$.

So,

$$
\begin{aligned}
\frac{L(t)}{d t} & =2 \int_{\Omega}\left(V_{1}^{1}-V_{1}^{2}\right)\left(\frac{\partial V_{1}^{1}}{\partial t}-\frac{\partial V_{1}^{2}}{\partial t}\right) d x+2 \int_{\Omega}\left(V_{2}^{1}-V_{2}^{2}\right)\left(\frac{\partial V_{2}^{1}}{\partial t}-\frac{\partial V_{2}^{2}}{\partial t}\right) d x \\
& +2 \int_{\Omega}\left(V_{3}^{1}-V_{3}^{2}\right)\left(\frac{\partial V_{3}^{1}}{\partial t}-\frac{\partial V_{3}^{2}}{\partial t}\right) d x \\
& =2 \mu_{1} \int_{\Omega}\left(V_{1}^{1}-V_{1}^{2}\right) \Delta\left(V_{1}^{1}-V_{1}^{2}\right) d x+2 \mu_{2} \int_{\Omega}\left(V_{2}^{1}-V_{2}^{2}\right) \Delta\left(V_{2}^{1}-V_{2}^{2}\right) d x \\
& +2 \mu_{3} \int_{\Omega}\left(V_{3}^{1}-V_{3}^{2}\right) \Delta\left(V_{3}^{1}-V_{3}^{2}\right) d x \\
& +2 \int_{\Omega}\left(V_{1}^{1}-V_{1}^{2}\right)^{2}\left[\rho(1-u)\left(1-\left(V_{1}^{1}+V_{1}^{2}\right) / K\right)-d\right] d x \\
& -2 \int_{\Omega}\left(V_{1}^{1}-V_{1}^{2}\right) \frac{\beta r V_{1}^{1} V_{3}^{1}}{1+\varepsilon V_{3}^{1}} d x+2 \int_{\Omega}\left(V_{1}^{1}-V_{1}^{2}\right) \frac{\beta r V_{1}^{2} V_{3}^{2}}{1+\varepsilon V_{3}^{2}} d x \\
& -2 \int_{\Omega}\left(V_{2}^{1}-V_{2}^{2}\right)^{2}\left[a(1-u)\left(V_{1}^{1}+V_{1}^{2}\right)+d\right] d x \\
& +2 \int_{\Omega}\left(V_{2}^{1}-V_{2}^{2}\right) \frac{\beta r V_{1}^{1} V_{3}^{1}}{1+\varepsilon V_{3}^{1}} d x-2 \int_{\Omega}\left(V_{2}^{1}-V_{2}^{2}\right) \frac{\beta r V_{1}^{2} V_{3}^{2}}{1+\varepsilon V_{3}^{2}} d x \\
& +2 \int_{\Omega} k(1-u)\left(V_{2}^{1}-V_{2}^{2}\right)\left(V_{3}^{1}-V_{3}^{2}\right) d x-2 \int_{\Omega} b\left(V_{3}^{1}-V_{3}^{2}\right)^{2} d x \\
& :=I_{1}+\ldots+I_{11} .
\end{aligned}
$$

It follows from the boundary condition (4) that
$I_{1}+I_{2}+I_{3}=-2 \int_{\Omega}\left[\mu_{1}\left|\nabla\left(V_{1}^{1}-V_{1}^{2}\right)\right|^{2}+\mu_{2}\left|\nabla\left(V_{2}^{1}-V_{2}^{2}\right)\right|^{2}+2 \mu_{3}\left|\nabla\left(V_{3}^{1}-V_{3}^{2}\right)\right|^{2}\right] d x \leq 0$.
The terms

$$
\begin{aligned}
I_{4}+I_{7}+I_{10}+I_{11} & \leq 2 \int_{\Omega}\left(\rho_{M}(1-u)(1-2 \zeta / K)-d_{m}\right)\left(V_{1}^{1}-V_{1}^{2}\right)^{2} d x \\
& -\int_{\Omega}\left(4 \zeta a_{M}(1-u)+2 d_{M}\right)\left(V_{2}^{1}-V_{2}^{2}\right)^{2} d x \\
& -2 \int_{\Omega} b_{m}\left(V_{3}^{1}-V_{3}^{2}\right)^{2} d x+\int_{\Omega} k_{M}\left[\left(V_{2}^{1}-V_{2}^{2}\right)^{2}+\left(V_{3}^{1}-V_{3}^{2}\right)^{2}\right] d x
\end{aligned}
$$

and

$$
\begin{aligned}
I_{5}+I_{6}+I_{8}+I_{9} & =2 \int_{\Omega} \frac{\beta r V_{1}^{1} V_{3}^{1}}{1+\varepsilon V_{3}^{1}}\left[\left(V_{2}^{1}-V_{2}^{2}\right)-\left(V_{1}^{1}-V_{1}^{2}\right)\right] d x \\
& +2 \int_{\Omega} \frac{\beta r V_{1}^{2} V_{3}^{2}}{1+\varepsilon V_{3}^{2}}\left[\left(V_{1}^{1}-V_{1}^{2}\right)-\left(V_{2}^{1}-V_{2}^{2}\right)\right] d x \\
& \leq 2 \int_{\Omega} \varepsilon^{-1} \beta_{M} r_{M} V_{1}^{1}\left[\left(V_{2}^{1}-V_{2}^{2}\right)-\left(V_{1}^{1}-V_{1}^{2}\right)\right] d x \\
& +2 \int_{\Omega} \varepsilon^{-1} \beta_{M} r_{M} V_{1}^{2}\left[\left(V_{1}^{1}-V_{1}^{2}\right)-\left(V_{2}^{1}-V_{2}^{2}\right)\right] d x \\
& \leq-2 \int_{\Omega} \varepsilon^{-1} \beta_{M} r_{M}\left(V_{1}^{1}-V_{1}^{2}\right)^{2} d x \\
& +2 \int_{\Omega} \varepsilon^{-1} \beta_{M} r_{M}\left(V_{1}^{1}-V_{1}^{2}\right)\left(V_{2}^{1}-V_{2}^{2}\right) d x \\
& \leq-\int_{\Omega} \varepsilon^{-1} \beta_{M} r_{M}\left[\left(V_{1}^{1}-V_{1}^{2}\right)^{2}-\left(V_{2}^{1}-V_{2}^{2}\right)^{2}\right] d x .
\end{aligned}
$$

Thus, we have

$$
\begin{aligned}
\frac{L(t)}{d t} & \leq \int_{\Omega}\left[2\left(\rho_{M}(1-u)(1-2 \zeta / K)-d_{m}\right)-\varepsilon^{-1} \beta_{M} r_{M}\right]\left(V_{1}^{1}-V_{1}^{2}\right)^{2} d x \\
& +\int_{\Omega}\left[\varepsilon^{-1} \beta_{M} r_{M}+k_{M}-4 \zeta a_{M}(1-u)+2 d_{M}\right]\left(V_{2}^{1}-V_{2}^{2}\right)^{2} d x \\
& +\int_{\Omega}\left[k_{M}-2 b_{m}\right]\left(V_{3}^{1}-V_{3}^{2}\right)^{2} d x \\
& \leq\left(V_{1}^{1}-V_{1}^{2}, V_{2}^{1}-V_{2}^{2}, V_{3}^{1}-V_{3}^{2}\right) P\left(V_{1}^{1}-V_{1}^{2}, V_{2}^{1}-V_{2}^{2}, V_{3}^{1}-V_{3}^{2}\right)^{T} \\
& \leq \lambda_{M}(P)\left[\left\|V_{1}^{1}-V_{1}^{2}\right\|_{L^{2}(\Omega)}^{2}+\left\|V_{2}^{1}-V_{2}^{2}\right\|_{L^{2}(\Omega)}^{2}+\left\|V_{3}^{1}-V_{3}^{2}\right\|_{L^{2}(\Omega)}^{2}\right]
\end{aligned}
$$

where $\lambda_{M}(P)$ is the maximal eigenvalue of the diagonal matrix $P=\operatorname{diag}\left(P_{1}, P_{2}, P_{3}\right)$ with

$$
\begin{aligned}
& P_{1}=2\left(\rho_{M}(1-u)(1-2 \zeta / K)-d_{m}\right)-\varepsilon^{-1} \beta_{M} r_{M} \\
& P_{2}=\varepsilon^{-1} \beta_{M} r_{M}+k_{M}-4 \zeta a_{M}(1-u)+2 d_{M} \\
& P_{3}=k_{M}-2 b_{m} .
\end{aligned}
$$

So, we deduce that

$$
L(t) \leq L(0) e^{\lambda_{M}(P) t} \longrightarrow 0, \text { as } t \rightarrow+\infty .
$$

Thus, $\left\|V_{1}^{1}-V_{1}^{2}\right\|_{L^{2}(\Omega)} \longrightarrow 0,\left\|V_{2}^{1}-V_{2}^{2}\right\|_{L^{2}(\Omega)} \longrightarrow 0$ and $\left\|V_{3}^{1}-V_{3}^{2}\right\|_{L^{2}(\Omega)} \longrightarrow 0$; as $t \rightarrow+\infty$. By Theorem 6, solutions of system (1-4) are bounded in the space $C^{1+\nu}\left(\bar{\Omega}, \mathbb{R}^{3}\right.$, where $0<\nu<2 l-1-n / p$ and $1 / 2+n /(2 p)<l<1$. Therefore,

$$
\begin{align*}
& \lim _{t \rightarrow+\infty} \sup _{x \in \Omega}\left|V_{1}^{1}(t, x)-V_{1}^{2}(t, x)\right|=0, \lim _{t \rightarrow+\infty} \sup _{x \in \Omega}\left|V_{2}^{1}(t, x)-V_{2}^{2}(t, x)\right|=0, \\
& \lim _{t \rightarrow+\infty} \sup _{x \in \Omega}\left|V_{3}^{1}(t, x)-V_{3}^{2}(t, x)\right|=0 . \tag{17}
\end{align*}
$$

Consider the sequence
$\left(V_{1}\left(q \omega, x, V_{01}, V_{02}, V_{03} ; V_{2}\left(q \omega, x, V_{01}, V_{02}, V_{03}\right) ; V_{3}\left(q \omega, x, V_{01}, V_{02}, V_{03}\right)=W\left(q \omega, W_{0}\right)\right.\right.$.
Then $\left\{W\left(q \omega, W_{0}\right), q \in \mathbb{N}\right\}$ is compact in the space $C(\bar{\Omega})^{3}$. Let $\bar{W}$ be a limit point of this sequence. It follows, from

$$
\begin{aligned}
\|W(\omega, \bar{W})-\bar{W}\|_{C} & \leq\left\|W(\omega, \bar{W})-W\left(\omega, W\left(q_{n} \omega, W_{0}\right)\right)\right\|_{C} \\
& +\left\|W\left(\omega, W\left(q_{n} \omega, W_{0}\right)\right)-W\left(q_{n} \omega, W_{0}\right)\right\|_{C} \\
& +\left\|W\left(q_{n} \omega, W_{0}\right)-\bar{W}\right\|_{C} \longrightarrow 0 \text { as } n \rightarrow+\infty,
\end{aligned}
$$

that $W(\omega, \bar{W})=\bar{W}$.
Next, let $\bar{W}$ and $\hat{W}$ two limit points of the sequence $\left\{W\left(q \omega, W_{0}\right), q \in \mathbb{N}\right\}$. Using (17) and $\hat{W}=W\left(q_{n} \omega, \hat{W}\right)$, we have
$\|\bar{W}-\hat{W}\|_{C} \leq\left\|\bar{W}-W\left(q_{n} \omega, W_{0}\right)\right\|_{C}+\left\|W\left(q_{n} \omega, W_{0}\right)-\hat{W}\right\|_{C} \longrightarrow 0$ as $n \rightarrow+\infty$.
Thus, $\bar{W}=\hat{W}$ and so $\left(V_{1}\left(t, x, \bar{V}_{1}, \bar{V}_{2}, \bar{V}_{3}\right) ; V_{2}\left(t, x, \bar{V}_{1}, \bar{V}_{2}, \bar{V}_{3}\right) ; V_{3}\left(t, x, \bar{V}_{1}, \bar{V}_{2}, \bar{V}_{3}\right)\right)$ is the unique periodic solutions of system (1-4). By (17), it is asymptotically stable.

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