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# A New Interior Point Method for Linear Complementarity Problem 

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#### Abstract

For a given n-vector $q$ and a real square matrix $M \in \mathrm{IR}^{n \times n}$, the linear complementarity problem, denoted $\operatorname{LCP}(M, q)$, is that of finding nonnegative vector $z \in \mathrm{IR}^{n}$ such that $z^{T}(M z+q)=0$ and $M z+q \geqslant 0$. In this paper we suppose that the matrix $M$ must be a symmetric and positive definite and the set $$
S=\left\{z \in \operatorname{IR}^{n} / z>0 \text { and } M z+q>0\right\} ;
$$ named interior points set of the $\operatorname{LCP}(M, q)$ must be nonempty. The aim of this paper is to show that the $\operatorname{LCP}(M, q)$ is completely equivalent to a convex quadratic programming problem ( $C Q P P$ ) under linear constraints. To solve the second problem, we propose an iterative method of interior points which converge in polynomial time to the exact solution; this convergence requires at most $o\left(n^{0,5} L\right)$ iterations, where $n$ is the number of the variables and $L$ is the length of a binary coding of the input; furthermore, the algorithm does not exceed $o\left(n^{3,5} L\right)$ arithmetic operations until its convergence and in the end, we close our paper with some numerical examples which illustrate our theoretical results.


Key words and phrases: Linear Complementarity Problem, Convex Quadratic Programming with Equilibrium Constraints, Matrix symmetric and positive definite, Interior Point Algorithm.

## 1. Introduction

We consider the linear complementarity problem $\operatorname{LCP}(M, q)$ that is, given a real square matrix $M \in \mathrm{IR}^{n \times n}$ and $q$ an element of $\mathrm{IR}^{n}$, find vectors $z \in \mathrm{IR}^{n}$ such that

$$
\left\{\begin{aligned}
<z, M z+q> & =0 \\
M z+q & \geqslant 0 \\
z & \geqslant 0
\end{aligned}\right.
$$

This problem has important applications in game theory, operational research, and some other areas of engineering (see [3], [4], [5], [6], [7], [9], [10], [13], [14], [15], [16] and [17]). For solving this problem, many results exist, for instance Lemke[11] have developed an algorithm for solving a linear complementarity problem which is based on pivot steps. Mukherjee[12] gave an iterative method for finding a solution to a linear and quasi-linear complementarity problem. Kojima[8] and Achache[1] have showed that the linear complementarity problem is completely equivalent to solving quadratic convex problem $(Q C P)$; each of them gave a different iterative method to solve the second problem.
Our notation in this paper is the usual one. In particular, $\mathrm{IR}^{n}$ denotes the space of real $n$-dimensional vectors,
$\operatorname{IR}_{+}^{n}:=\left\{x \in \operatorname{IR}^{n}: x_{i} \geqslant 0, i=1 . . n\right\}$ is the nonnegative orthant and its interior is $\mathrm{IR}_{++}^{n}:=\left\{x \in \mathrm{IR}^{n}: x_{i}>0, i=1 . . n\right\}$.
With $x \in \operatorname{IR}^{n}$ we define $|x|=\left(\left|x_{1}\right|, . .,\left|x_{n}\right|\right)^{T} \in \operatorname{IR}^{n}$.
We denote by $I$ the identity matrix.
Let $x, y \in \mathrm{IR}^{n}, x^{T} y$ or $<x, y>$ is the inner product of the $x$ and $y ;\|x\|$ is the Euclidean norm.
For $x \in \mathrm{IR}^{n}$ and $k$ a nonnegative integer, $x^{(k)}$ refers to the vector obtained after $k$ iterations; for $1 \leqslant i \leqslant n, x_{i}$ refers to the $i^{t h}$ element of $x$, and $x_{i}^{(k)}$ refers to the $i^{t h}$ element of the vector obtained after $k$ iterations.
For $A \in \mathrm{IR}^{n \times n}$ and $k$ a nonnegative integer, $A^{(k)}$ refers to the matrix obtained after $k$ iterations; for $p$ a nonnegative integer, $A^{p,(k)}$ refers to the matrix at puissance $p$ obtained after $k$ iterations and $A^{-p,(k)}$ denotes the inverse of the matrix $A^{p,(k)}$.
Let $x, y \in \mathrm{IR}^{n}$, the expression $x \leqslant y$ (respectively $x<y$ ) meaning that $x_{i} \leqslant y_{i}$ (respectively $x_{i}<y_{i}$ ) for each $i=1 . . n$.
Given a vector $x$ in $\mathrm{IR}^{n}, X=\operatorname{diag}(x)$ is the $n \times n$ diagonal matrix with $X_{i i}=x_{i}$ for all $i$ and $X_{i j}=0$ for all $i \neq j$.
The transpose of a vector (respectively matrix) is denoted by super script $T$, such as the transpose of the vector $x$ (respectively the matrix $A$ ) is given by $x^{T}$ (respectively $A^{T}$ ).
Remember that the spectrum $\sigma(A)$ of the matrix $A$ is the set of its eigenvalues and its spectral radius $\rho$ is given by $\rho(A):=\sup \{|\lambda|$ such that $\lambda \in \sigma(A)\}$.
We recall that a matrix $M$ is called symmetric and positive definite matrix if and only if

$$
x^{t} M x>0, \forall x \neq 0
$$

and a matrix $M$ is called symmetric and positive matrix if and only if

$$
x^{t} M x \geqslant 0, \forall x .
$$

The paper is organized as follows. In the next section, we show that solving linear complementarity problem associated with a matrix $M$ and a vector $q$ is completely equivalent to finding the minimum of a convex quadratic programming problem ( $C Q P P$ ); for solving the second problem we propose to construct a sequence of vectors $\left\{z^{(k)}\right\}_{k=0,1, . .}$ which converges to a vector $z^{*}$ (the exact solution of linear complementarity problem $L C P$ ). In the third section, we show that the convergence of this method requires $o(\sqrt{n} L)$ number by iteration where $L$ is the length of a binary coding of the input data of the problem and in the end, we close our paper with some numerical examples which illustrate our theoretical results.

## 2. Equivalent reformulation of the problem

In this section, we show that solving a linear complementarity problem $(L C P)$ is equivalent to finding the minimum of a convex quadratic programming problem $(C Q P P)$ under linear constraints.
Consider the linear complementarity problem as follows
Find $z \in \operatorname{IR}^{n}$ such that:

$$
\left\{\begin{array}{r}
<z, M z+q>=0  \tag{1}\\
M z+q \geqslant 0 \\
z \geqslant 0
\end{array}\right.
$$

where $M \in \operatorname{IR}^{n \times n}$ and $q \in \mathrm{IR}^{n}$ are given data.
and let's consider

$$
S=\left\{z \in \operatorname{IR}^{n} / z>0 \text { and } M z+q>0\right\}
$$

named interior points set of the $\operatorname{LCP}(M, q)$.
Theorem 1 : If $M$ is symmetric positive matrix and the interior points set of the linear complementarity problem

$$
S:=\left\{z \in \operatorname{IR}^{n} / z>0 \text { and } M z+q>0\right\}
$$

is nonempty then the problem $\operatorname{LCP}(M, q)$ has one and only one solution.
Proof. : For a proof of the above theorem we refer to [1].
Consider the minimization problem under linear constraints $(C Q P P)$ as follows

$$
\left\{\begin{array}{r}
\min f(z):=<z, M z+q>  \tag{2}\\
\text { Subject to: } \\
M z+q \geqslant 0 \\
z \geqslant 0
\end{array}\right.
$$

We note that if $z^{*}$ is a solution of the linear complementarity problem $\operatorname{LCP}(M, q)$ then zero is the global minimum of the problem(2) (see [18]). Inversely, if $z^{*}$ is the minimum of the problem(2) then we have two situations:

- If $f\left(z^{*}\right)=0$, then $z^{*}$ is a solution of the $\operatorname{LCP}(M, q)$.
- Otherwise (ie $f\left(z^{*}\right)>0$ ), then the linear complementarity problem $\operatorname{LCP}(M, q)$ admits no solution.

That is to say the problem(1) and the problem(2) are equivalent.
The Lagrange function associated with the problem(2) is given by

$$
L\left(z, \lambda_{1}, \lambda_{2}\right):=f(z)-<\lambda_{1}, M z+q>-<\lambda_{2}, z>
$$

where $\lambda_{1}$ and $\lambda_{2}$ are the Lagrange multipliers associated with the problem(2). The KKT conditions applied to the problem(2) imply that if $z$ is a stationary point, then there exists $\lambda_{1} \in I R^{n}$ and $\lambda_{2} \in I R^{n}$ such that

$$
\left\{\begin{array}{l}
2 M z+q-M \lambda_{1}-\lambda_{2}=0  \tag{3}\\
\lambda_{1}^{t}(M z+q)=0 \\
\lambda_{2}^{t} z=0 \\
M z+q \geqslant 0 \\
z \geqslant 0 \\
\lambda_{1} \geqslant 0 \\
\lambda_{2} \geqslant 0
\end{array}\right.
$$

Let's consider

$$
T:=\left\{\left(z, \lambda_{1}, \lambda_{2}\right) / 2 M z+q-M \lambda_{1}-\lambda_{2}=0 ; z, M z+q, \lambda_{1}, \lambda_{2} \geqslant 0\right\}
$$

In this paper we propose to construct a sequence of vectors

$$
\left\{\left(z^{(k)}, \lambda_{1}^{(k)}, \lambda_{2}^{(k)}\right)\right\}_{k=0 \ldots} \in T
$$

such that

$$
\lim _{k \rightarrow+\infty}\left(<\lambda_{1}^{(k)}, M z^{(k)}+q>+<\lambda_{2}^{(k)}, z^{(k)}>\right)=0
$$

To achieve this objective we consider the iterative method which starts from an arbitrary point $\left(z^{(0)}, \lambda_{1}^{(0)}, \lambda_{2}^{(0)}\right) \in T$ and generates successively points

$$
z^{(k+1)}:=z^{(k)}+d^{(k)}
$$

where the vectors $d^{(k)}$ are the directions chosen to generate the vectors $z^{(k+1)}$, they are defined by the Newton directions associated with the following penalized problem (see [2])

$$
\left\{\begin{array}{l}
\min f_{\mu}(z) \\
\text { Subjects to: } \\
\quad M z+q>0 \\
z>0
\end{array}\right.
$$

where

$$
f_{\mu}(z):=<z, M z>+<q, z>-\mu \sum_{i=1}^{n} \log \left(z_{i}\right)-\mu \sum_{i=1}^{n} \log \left(w_{i}\right)
$$

and

$$
w=M z+q .
$$

The Newton direction at $z^{(k)}$ is the optimal solution of the following quadratic problem

$$
\begin{equation*}
\min g_{\mu, z^{(k)}}\left(d^{(k)}\right) \tag{4}
\end{equation*}
$$

where

$$
g_{\mu}\left(z^{(k)}\right):=\frac{1}{2}<d^{(k)}, \nabla^{2} f_{\mu_{k}}\left(z^{(k)}\right) d^{(k)}>+<\nabla f_{\mu_{k}}\left(z^{(k)}\right), d^{(k)}>
$$

Now we show that
Theorem 2 : The problem(4) admits one and only one solution; this solution is given by

$$
d^{(k)}=-H^{-1,(k)} \nabla f_{\mu_{k}}\left(z^{(k)}\right)
$$

where

$$
\left\{\begin{array}{c}
H^{(k)}:=2 M+\mu_{k}\left(M W^{-2,(k)} M+Z^{-2,(k)}\right) \\
Z:=\operatorname{diag}(z) \\
W:=\operatorname{diag}(w) \\
w=M z+q
\end{array}\right.
$$

Proof. : The Hessian of the penalty function $f_{\mu}$ at $z^{(k)}$ noted by $H^{(k)}$ is given by

$$
H^{(k)}:=2 M+\mu_{k}\left(M W^{-2,(k)} M+Z^{-2,(k)}\right) .
$$

Since the matrix $M$ is symmetric and positive definite, then the matrix $H^{(k)}$ is symmetric definite positive.
Therefore, the problem(4) admits one and only one solution.
This solution is given by

$$
H^{(k)} d^{(k)}+\nabla f_{\mu_{k}}\left(z^{(k)}\right)=0
$$

this implies

$$
d^{(k)}=-H^{-1,(k)} \nabla f_{\mu_{k}}\left(z^{(k)}\right) .
$$

After calculating the direction $d^{(k)}$, we can write

$$
\left\{\begin{array}{l}
z^{(k+1)}:=z^{(k)}+d^{(k)} \\
\lambda_{1}^{(k+1)}:=\mu_{k} W^{-1,(k)}\left(e-W^{-1,(k)} M d^{(k)}\right) \\
\lambda_{2}^{(k+1)}:=\mu_{k} Z^{-1,(k)}\left(e-Z^{-1,(k)} d^{(k)}\right)
\end{array}\right.
$$

Now we give the following algorithm for solving our problem

## Algorithm:

(Initialization):

$$
\begin{aligned}
& k=0 \\
& \mu_{0}>0: \text { Parameter penalty. } \\
& \epsilon>0: \text { Tolerance wanted. }
\end{aligned}
$$

(Calculation of the vector $z^{(k+1)}, \lambda_{1}^{(k+1)}, \lambda_{2}^{(k+1)}$ )

$$
\left\{\begin{array}{l}
d^{(k)}=-H^{-1,(k)} \nabla f_{\mu_{k}}\left(z^{(k)}\right) \\
z^{(k+1)}:=z^{(k)}+d^{(k)} \\
w^{(k+1)}:=M z^{(k+1)}+q \\
\lambda_{1}^{(k+1)}:=\mu_{k} W^{-1,(k)}\left(e-W^{-1,(k)} M d^{(k)}\right) \\
\lambda_{2}^{(k+1)}:=\mu_{k} Z^{-1,(k)}\left(e-Z^{-1,(k)} d^{(k)}\right) \\
\mu_{k+1}:=2 \mu_{k} \frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}}
\end{array}\right.
$$

## (Stopping criterion):

if $<\lambda_{1}^{(k+1)}, w^{(k+1)}>+<\lambda_{2}^{(k+1)}, z^{(k+1)}><\epsilon$ then STOP.
otherwise:

$$
\begin{aligned}
& k:=k+1 . \\
& \text { GO TO the previous step. }
\end{aligned}
$$

## 3. Convergence

In this section, in the one hand, we show that all points generated by this algorithm are in the set $T$ and $\left(<\lambda_{1}^{(k)}, w^{(k)}>+<\lambda_{2}^{(k)}, z^{(k)}>\right)$ converges to zero when $k \rightarrow+\infty$; on the other hand, we prove that our algorithm has $o(\sqrt{n} L)$ iteration complexity; more precisely we will show that the algorithm does not exeed $O\left(n^{3.5} L\right)$ arithmetic operations until its convergence. To so do, we suppose that there exist $z^{(0)}>0$ and $0<\delta<1 / 2$ such that: $\left\|Z^{-1,(0)} d^{(0)}\right\| \leqslant \delta$ and $\left\|W^{-1,(0)} M d^{(0)}\right\| \leqslant \delta$ and we prove that if $k$ is positive integer then we have

$$
\left\|Z^{-1,(k)} d^{(k)}\right\| \leqslant \delta
$$

and

$$
\left\|W^{-1,(k)} M d^{(k)}\right\| \leqslant \delta
$$

to achieve this goal, we will need the following four lemmas
Lemma 3 : Let $k$ be a positive integer, if

$$
\left\|Z^{-1,(k)} d^{(k)}\right\| \leqslant \delta
$$

then we have

$$
\left\|Z^{(k+1)} Z^{-1,(k)}-I\right\| \leqslant \delta
$$

where $I$ is the identity matrix.

Proof. : For each $i=1, . ., n$ we have

$$
\begin{aligned}
\left(\left(Z^{(k+1)} Z^{-1,(k)}-I\right) e\right)_{i} & =\frac{z_{i}^{(k+1)}}{z_{i}^{(k)}}-1 \\
& =\frac{d_{i}^{(k)}}{z_{i}^{(k)}} \\
& =\left(Z^{-1,(k)} d^{(k)}\right)_{i}
\end{aligned}
$$

Lemma 4 : Let $k$ be a positive integer, if

$$
\left\|W^{-1,(k)} M d^{(k)}\right\| \leqslant \delta
$$

then we have

$$
\left\|W^{(k+1)} W^{-1,(k)}-I\right\| \leqslant \delta
$$

Proof. : For each $i=1, . ., n$ we have

$$
\begin{align*}
\left(\left(W^{(k+1)} W^{-1,(k)}-I\right) e\right)_{i} & =\frac{w_{i}^{(k+1)}}{w_{i}^{(k)}}-1  \tag{5}\\
& =\frac{\sum_{j=1}^{n} m_{i j} d_{i}^{(k)}}{w_{i}^{(k)}} \\
& =\left(W^{-1,(k)} M d^{(k)}\right)_{i}
\end{align*}
$$

Lemma 5 : Let $k$ be a positive integer, if

$$
\left\|Z^{-1,(k)} d^{(k)}\right\| \leqslant \delta
$$

then we have

$$
\left\|Z^{(k+1)} Z^{-2,(k)} d^{(k)}+\frac{\mu_{k+1}}{\mu_{k}} e-Z^{(k+1)} Z^{-1,(k)} e\right\| \leqslant \delta \frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}}
$$

where

$$
\begin{equation*}
\mu_{k+1}:=2 \mu_{k} \frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}} \tag{6}
\end{equation*}
$$

Proof. To show that we use the definition

$$
\begin{equation*}
\frac{\mu_{k+1}}{\mu_{k}} e:=e-\frac{\delta-\delta^{2}}{\delta+2 \sqrt{n}} e \tag{1}
\end{equation*}
$$

and the relation

$$
Z^{(k+1)}=Z^{(k)}+D^{(k)}
$$

where $Z^{(k)}, D^{(k)}$ are respectively the diagonal matrix of the vector $z^{(k)}$ and $d^{(k)}$.
By multiplying the last relation by the matrix $Z^{-1,(k)}$ we get

$$
\begin{aligned}
Z^{(k+1)} Z^{-1,(k)} & =I+D^{(k)} Z^{-1,(k)} \\
& =I+Z^{-1,(k)} D^{(k)}
\end{aligned}
$$

this implies

$$
\begin{align*}
\left(Z^{(k+1)} Z^{-1,(k)}-I\right) e & =Z^{-1,(k)} D^{(k)} e  \tag{2}\\
& =Z^{-1,(k)} d^{(k)}
\end{align*}
$$

if we note that

$$
\Delta_{1}:=\left\|Z^{(k+1)} Z^{-2,(k)} d^{(k)}+\frac{\mu_{k+1}}{\mu_{k}} e-Z^{(k+1)} Z^{-1,(k)} e\right\|
$$

then we have

$$
\begin{aligned}
\Delta_{1} & =\left\|\left(Z^{(k+1)} Z^{-1,(k)}-I\right) Z^{-1,(k)} d^{(k)}-\frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} e\right\| \\
& \leqslant\left\|Z^{(k+1)} Z^{-1,(k)}-I\right\| \cdot\left\|Z^{-1,(k)} d^{(k)}\right\|+\sqrt{n} \frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} \\
& \leqslant \delta \cdot \delta+\sqrt{n} \frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} \\
& =\delta \frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}} .
\end{aligned}
$$

Lemma 6 : Let $k$ be a positive integer, if

$$
\left\|W^{-1,(k)} M d^{(k)}\right\| \leqslant \delta
$$

then we have

$$
\left\|W^{(k+1)} W^{-2,(k)} M d^{(k)}+\frac{\mu_{k+1}}{\mu_{k}} e-W^{(k+1)} W^{-1,(k)} e\right\| \leqslant \delta \frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}}
$$

Proof. : In the one hand, if we use (5) we can write

$$
\left(I-W^{(k+1)} W^{-1,(k)}\right) e=-W^{-1,(k)} M d^{(k)}
$$

and in the other hand, if we note that

$$
\Delta_{2}:=\left\|W^{(k+1)} W^{-2,(k)} M d^{(k)}+\frac{\mu_{k+1}}{\mu_{k}} e-W^{(k+1)} W^{-1,(k)} e\right\|
$$

then we get

$$
\begin{aligned}
\Delta_{2} & =\left\|W^{(k+1)} W^{-2,(k)} M d^{(k)}+e-W^{(k+1)} W^{-1,(k)} e-\frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} e\right\| \\
& =\left\|W^{(k+1)} W^{-2,(k)} M d^{(k)}+\left(I-W^{(k+1)} W^{-1,(k)}\right) e-\frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} e\right\| \\
& \leqslant\left\|W^{(k+1)} W^{-2,(k)} M d^{(k)}-W^{-1,(k)} M d^{(k)}-\frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} e\right\| \\
& \leqslant\left\|\left(W^{(k+1)} W^{-1,(k)}-I\right) W^{-1,(k)} M d^{(k)}-\frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} e\right\| \\
& \leqslant\left\|W^{(k+1)} W^{-1,(k)}-I\right\| \cdot\left\|W^{-1,(k)} M d^{(k)}\right\|+\sqrt{n} \frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} e \| \\
& \leqslant \delta . \delta+\sqrt{n} \frac{\delta-2 \delta^{2}}{\delta+2 \sqrt{n}} \\
& =\delta \frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}} .
\end{aligned}
$$

Now we show that
Theorem 7 : If we suppose that

$$
\left\{\begin{array}{l}
\left\|Z^{-1,(k)} d^{(k)}\right\| \leqslant \delta \\
\left\|W^{-1,(k)} M d^{(k)}\right\| \leqslant \delta
\end{array}\right.
$$

then we have

$$
\left\{\begin{array}{l}
\left\|Z^{-1,(k+1)} d^{(k+1)}\right\| \leqslant \delta \\
\left\|W^{-1,(k+1)} M d^{(k+1)}\right\| \leqslant \delta
\end{array}\right.
$$

Proof. : Since

$$
H^{(k)} d^{(k)}+\nabla f_{\mu_{k}}\left(z^{(k)}\right)=0
$$

we have

$$
\left\{\begin{array}{l}
H^{(k)} d^{(k)}+\nabla f_{\mu_{k}}\left(z^{(k)}\right)=0 \\
H^{(k+1)} d^{(k+1)}+\nabla f_{\mu_{k+1}}\left(z^{(k+1)}\right)=0
\end{array}\right.
$$

By multiplying the two equations by $d^{(k+1)}$ we get

$$
\left\{\begin{array}{c}
<d^{(k+1)},\left(2 M+\mu_{k}\left(M W^{-2,(k)} M+Z^{-2,(k)}\right)\right) d^{(k)}>+ \\
<d^{(k+1)}, 2 M z^{(k)}+q-\mu_{k}\left(M W^{-1,(k)}+Z^{-1,(k)}\right) e>=0 \\
<d^{(k+1)},\left(2 M+\mu_{k+1}\left(M W^{-2,(k+1)} M+Z^{-2,(k+1)}\right)\right) d^{(k+1)}>+ \\
<d^{(k+1)}, 2 M z^{(k+1)}+q-\mu_{k+1}\left(M W^{-1,(k+1)}+Z^{-1,(k+1)}\right) e>=0
\end{array}\right.
$$

if we note

$$
\Delta_{3}:=\mu_{k+1}\left(\left\|W^{-1,(k+1)} M d^{(k+1)}\right\|^{2}+\left\|Z^{-1,(k+1)} d^{(k+1)}\right\|^{2}\right)
$$

then we have

$$
\begin{aligned}
& \Delta_{3} \leqslant \mu_{k+1}<d^{(k+1)},\left(M W^{-1,(k+1)}+Z^{-1,(k+1)}\right) e>-<d^{(k+1)}, 2 M z^{(k+1)}+q> \\
& =\mu_{k+1}<W^{-1,(k+1)} M d^{(k+1)}, e>+\mu_{k+1}<Z^{-1,(k+1)} d^{(k+1)}, e> \\
& -\left(\mu_{k}<d^{(k+1)},\left(M W^{-1,(k)}+Z^{-1,(k)}\right) e>\right. \\
& \left.-\mu_{k}<d^{(k+1)},\left(M W^{-2,(k)} M+Z^{-2,(k)}\right) d^{(k)}>\right) \\
& =\mu_{k}<d^{(k+1)}, \frac{\mu_{k+1}}{\mu_{k}} M W^{-1,(k+1)} e-M W^{-1,(k)} e+M W^{-2,(k)} M d^{(k)}> \\
& +\mu_{k}<d^{(k+1)}, \frac{\mu_{k+1}}{\mu_{k}} Z^{-1,(k+1)} e-Z^{-1,(k)} e+Z^{-2,(k)} d^{(k)}> \\
& =\mu_{k}<d^{(k+1)}, M W^{-1,(k+1)}\left(W^{(k+1)} W^{-2,(k)} M d^{(k)}+\frac{\mu_{k+1}}{\mu_{k}} e-W^{(k+1)} W^{-1,(k)} e>\right. \\
& +\mu_{k}<d^{(k+1)}, Z^{-1,(k+1)}\left(Z^{(k+1)} Z^{-2,(k)} d^{(k)}+\frac{\mu_{k+1}}{\mu_{k}} e-Z^{(k+1)} Z^{-1,(k)} e>\right. \\
& \leqslant \mu_{k} \delta \frac{\delta^{2}+\sqrt{n}}{\delta^{2}+2 \sqrt{n}}\left(\left\|W^{-1,(k+1)} M d^{(k+1)}\right\|+\left\|Z^{-1,(k+1)} d^{(k+1)}\right\|\right) \\
& \text { so } \\
& \mu_{k+1}\left(\left\|W^{-1,(k+1)} M d^{(k+1)}\right\|+\left\|Z^{-1,(k+1)} d^{(k+1)}\right\|\right) \leqslant 2 \mu_{k} \delta \frac{\delta^{2}+\sqrt{n}}{\delta^{2}+2 \sqrt{n}}
\end{aligned}
$$

finally

$$
\left\|W^{-1,(k+1)} M d^{(k+1)}\right\|+\left\|Z^{-1,(k+1)} d^{(k+1)}\right\| \leqslant \delta
$$

hence the result.
Now we show that all points generated by the algorithm $\left(z^{(k)}, \lambda_{1}^{(k)}, \lambda_{2}^{(k)}\right)$ remain in the set $T$.

For that, let's assume that:

$$
\left(z^{(k)}, \lambda_{1}^{(k)}, \lambda_{2}^{(k)}\right) \in T
$$

then we have

$$
\begin{aligned}
z^{(k+1)} & =z^{(k)}+d^{(k)} \\
& =Z^{(k)}\left(e+Z^{-1,(k)} d^{(k)}\right) \\
& >0
\end{aligned}
$$

$$
\begin{aligned}
w^{(k+1)} & =M z^{(k+1)}+q \\
& =w^{(k)}+M d^{(k)} \\
& =W^{(k)}\left(e+W^{-1,(k)} M d^{(k)}\right) \\
& >0
\end{aligned}
$$

- 

$$
\begin{aligned}
\lambda_{1}^{(k+1)} & :=\mu_{k} W^{-1,(k)}\left(e-W^{-1,(k)} M d^{(k)}\right) \\
& >0 .
\end{aligned}
$$

$$
\begin{aligned}
\lambda_{2}^{(k+1)} & :=\mu_{k} Z^{-1,(k)}\left(e-Z^{-1,(k)} d^{(k)}\right) \\
& >0 .
\end{aligned}
$$

- 

$$
\begin{aligned}
\lambda_{2}^{(k+1)}= & \mu_{k} Z^{-1,(k)}\left(e-Z^{-1,(k)} d^{(k)}\right) \\
= & \mu_{k} Z^{-1,(k)} e-\mu_{k} Z^{-2,(k)} d^{(k)} \\
= & \mu_{k} Z^{-1,(k)} e-\left(H^{(k)}-2 M-\mu_{k} M W^{-2,(k)} M\right) d^{(k)} \\
= & \mu_{k} Z^{-1,(k)} e-H^{(k)} d^{(k)}+\left(2 M z^{(k+1)}+q\right)-\left(2 M z^{(k)}+q\right) \\
& \quad \quad+\mu_{k} M W^{-2,(k)} M d^{(k)} \\
= & \mu_{k} Z^{-1,(k)} e+\left(2 M z^{(k)}+q-\mu_{k} M W^{-1,(k)} e-\mu_{k} Z^{-1,(k)} e\right) \\
& \quad+\left(2 M z^{(k+1)}+q\right)-\left(2 M z^{(k)}+q\right)+\mu_{k} M W^{-2,(k)} M d^{(k)} \\
= & -\mu_{k} M W^{-1,(k)} e+\left(2 M z^{(k+1)}+q\right)+\mu_{k} M W^{-2,(k)} M d^{(k)} \\
= & \left(2 M z^{(k+1)}+q\right)-\mu_{k} M W^{-1,(k)}\left(e-W^{-1,(k)} M d^{(k)}\right) \\
= & \left(2 M z^{(k+1)}+q\right)-M \lambda_{1}^{(k+1)} .
\end{aligned}
$$

Now we give the following proposition
Proposition 8 : For any positive integer $k$, we have

$$
<w^{(k)}, \lambda_{1}^{(k)}>+<z^{(k)}, \lambda_{2}^{(k)}>\leqslant 2 \mu_{k-1}(\delta+\sqrt{n})^{2}
$$

Proof. : From the above we can write

$$
\begin{aligned}
& \quad<w^{(k+1)}, \lambda_{1}^{(k+1)}>+<z^{(k+1)}, \lambda_{2}^{(k+1)}> \\
& \quad=<W^{(k)}\left(e+W^{-1,(k)} M d^{(k)}\right), \mu_{k} W^{-1,(k)}\left(e-W^{-1,(k)} M d^{(k)}\right)>+ \\
& \quad<Z^{(k)}\left(e+Z^{-1,(k)} d^{(k)}\right), \mu_{k} Z^{-1,(k)}\left(e-Z^{-1,(k)} d^{(k)}\right)> \\
& =\mu_{k}\left(<e+W^{-1,(k)} M d^{(k)}, e-W^{-1,(k)} M d^{(k)}>+\right. \\
& \left.\quad<e+Z^{-1,(k)} d^{(k)}, e-Z^{-1,(k)} d^{(k)}>\right) \\
& \leqslant
\end{aligned}
$$

Hence the quantity $\left(<w^{(k)}, \lambda_{1}^{(k)}>+<z^{(k)}, \lambda_{2}^{(k)}>\right)$ converges to zero. Now we prove that our algorithm has $o(\sqrt{n} L)$ iteration complexity; more
precisely we will show that the algorithm does not exceed $o\left(n^{3.5} L\right)$ arithmetic operations until its convergence, and in the end we will establish the total number of iterations performed by the algorithm so that its convergence is reached.

Proposition 9 : The total number of iterations performed by the algorithm is less than or equal to

$$
k^{*}=\frac{\delta+2 \sqrt{n}}{\delta-\delta^{2}+\sqrt{n}} \ln \frac{2(\delta+\sqrt{n})^{2} \mu_{0}}{\epsilon}
$$

where $\epsilon$ denotes the tolerance of the problem and $\mu_{0}$ is the parameter of the initial penalty.

Proof. : The algorithm ends when

$$
2(\delta+\sqrt{n})^{2} \mu_{k} \leqslant \epsilon
$$

thus, it is enough to show that $k^{*}$ satisfies this inequality.
From the definition of $k^{*}$ we can write

$$
\begin{aligned}
\ln (\epsilon) & =-\frac{\delta-\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}} k^{*}+\ln \left[2(\delta+\sqrt{n})^{2} \mu_{0}\right] \\
& \geqslant k^{*} \ln \left(\frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}}\right)+\ln \left[2(\delta+\sqrt{n})^{2} \mu_{0}\right] \\
& =\ln \left(\frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}}\right)^{k^{*}}+\ln \left[2(\delta+\sqrt{n})^{2} \mu_{0}\right] \\
& =\ln \left[2(\delta+\sqrt{n})^{2} \mu_{0}\left(\frac{\delta^{2}+\sqrt{n}}{\delta+2 \sqrt{n}}\right)^{k^{*}}\right] \\
& =\ln \left[2(\delta+\sqrt{n})^{2} \mu_{k^{*}}\right]
\end{aligned}
$$

this implies

$$
2(\delta+\sqrt{n})^{2} \mu_{k^{*}} \leqslant \epsilon
$$

If we denote by $L$ the length of a binary coding of the input data of the problem $L C P(M, q)$, then we have

Corollary 10 : If $\log _{2}\left(\mu_{0}\right)=o(L)$ and $\log _{2}(\epsilon)=-o(L)$ then the algorithm stops in at most $o(\sqrt{n} L)$ iterations with o $\left(n^{3.5} L\right)$ arithmetic operations.

Proof. : From this assumption we have

$$
\left\{\begin{array}{l}
\log _{2}\left(\mu_{0}\right)=o(L) \\
\text { and } \\
\log _{2}(\epsilon)=-o(L)
\end{array}\right.
$$

then

$$
k^{*}=o(\sqrt{n} L)
$$

But to solve a linear system we need $o\left(n^{3}\right)$ arithmetic operations, then the algorithm converges in at most $o\left(n^{3.5} L\right)$ arithmetic operations.

## 1. Numerical example

In this part, we consider the following example to test our method. Consider the following linear complementarity problem

Example 11 Find vector $z$ in $\operatorname{IR}^{n}$ satisfying $z^{T}(M z+q)=0, M z+q \geqslant 0$, $z \geqslant 0$,
where $M=\left[\begin{array}{cccc}100 & -2 & -3 & -4 \\ -2 & 50 & -6 & -7 \\ -3 & -6 & 100 & -11 \\ -4 & -7 & -11 & 200\end{array}\right]$ and $q=\left[\begin{array}{c}1 \\ -2 \\ 3 \\ -4\end{array}\right]$.
The exact solution is $z^{*}=\left(0, \frac{4}{93}, 0, \frac{2}{93}\right)^{T}$.
The solution of this problem with six significant digits is presented in following Table.

| Iteration | $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ |
| :--- | :---: | :---: | :--- | :---: |
| $k=01$ | 1,217700 | 4,030283 | 10,748913 | 6,834140 |
| $k=05$ | 1,094700 | 3,627983 | 9,659913 | 6,147865 |
| $k=10$ | 0,971700 | 3,225683 | 8,570913 | 5,461590 |
| $k=15$ | 0,848700 | 2,823383 | 7,481913 | 4,775315 |
| $k=20$ | 0,725700 | 2,421083 | 6,392913 | 4,089040 |
| $k=25$ | 0,602700 | 2,018783 | 5,303913 | 3,402765 |
| $k=30$ | 0,479700 | 1,616483 | 4,214913 | 2,716490 |
| $k=35$ | 0,356700 | 1,214183 | 3,125913 | 2,030215 |
| $k=40$ | 0,233700 | 0,811883 | 2,036913 | 1,343940 |
| $k=45$ | 0,110700 | 0,409583 | 0,947913 | 0,657665 |
| $k=50$ | 0,073800 | 0,288893 | 0,621213 | 0,451783 |
| $k=52$ | 0,036900 | 0,168203 | 0,294513 | 0,245900 |
| $k=53$ | 0,012300 | 0,096750 | 0,012340 | 0,145670 |
| $k=54$ | 0,000000 | 0,043010 | 0,000000 | 0,021505 |

## Conclusion:

In this paper we have showed that, on the one hand, linear complementarity problem can be written as a quadratic convex programming problem; on the other, we have built a method to solve it; the convergence of this method requires $o(\sqrt{n} L)$ number of iterations where $L$ is the length of a binary coding of the input data of the problem $\operatorname{LCP}(M, q)$.

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