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# LINEAR PREDICTION OF LONG-RANGE DEPENDENT TIME SERIES 

Fanny Godet ${ }^{1}$


#### Abstract

We present two approaches for linear prediction of long-memory time series. The first approach consists in truncating the Wiener-Kolmogorov predictor by restricting the observations to the last $k$ terms, which are the only available data in practice. We derive the asymptotic behaviour of the mean-squared error as $k$ tends to $+\infty$. The second predictor is the finite linear least-squares predictor i.e. the projection of the forecast value on the last $k$ observations. It is shown that these two predictors converges to the Wiener Kolmogorov predictor at the same rate $k^{-1}$.


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## 1. Introduction

ARMA (autoregressive moving-average) processes are often called short-memory processes because their covariances decay geometrically. On the other hand, a long-memory process is characterised by the following feature: the autocovariance function $\sigma$ decays more slowly in so far as it is not absolutely summable. These processes are so-named because of the strong association between observations widely separated in time. The long-memory time series models have attracted much attention lately and there is now a growing realisation that time series possessing long-memory characteristics arise in areas as diverse as Economics, Geophysics, Hydrology or telecom traffic (see, e.g., [14] and [8]). Although there exists substantial literature on the prediction of shortmemory processes (see [5] and [2] for the univariate case or [13] for the multivariate case), there are fewer results for long-memory time series. Most prediction methods are successfully applied on long memory data either simulated like in [7] or on real data like electricity demand (see [17]). In this paper, we consider the question of prediction in long memory models from a theoretical point of view.

More precisely, we compare two prediction methods for long-memory processes. We search linear predictors of $X_{k+h}$ knowing $\left(X_{1}, \ldots, X_{k}\right)$ which are optimal in the sense that they minimise the mean-squared error. We study the behaviour of the mean-squared errors as $k$ tends to infinity as [15] does for short memory processes. The paper is organised as follows. First we introduce our model and our main assumptions. Then, in Section 2, we study the best linear predictor knowing all the past i.e. the Wiener-Kolmogorov predictor proposed by [19] and by [3] for long-memory time series. In practice, only the last $k$ values of the process are available. Therefore we need to truncate the infinite series in the definition of the predictor and to derive the asymptotic behaviour of the mean-squared error as $k$ tends to $+\infty$. This method is for example used by [1] to forecast US monetary indices.

[^0]In Section 3 we discuss the asymptotic properties of the forecast error if we project onto the closed span of the last $k$ observations. This approach has been proposed by [16] for fractional noise series and by [7] for other simulated data. These authors view this approach as fitting a misspecified autoregressive model of order $k$. The simulations in [16] show that high-order AR-models predict fractional integrated noise very well.

Finally in Section 4 we compare the two previous methods for $h$-step prediction. We give some asymptotic properties of the mean-squared error of the linear least-squares predictor as $h$ tends to $+\infty$ in the particular case of long-memory processes. Then we study our $k$ th order predictors as $k$ tends to $+\infty$.

Let $\left(X_{n}\right)_{n \in \mathbb{Z}}$ be a discrete-time (weakly) stationary process in $\mathrm{L}^{2}$ with mean 0 and $\sigma$ its autocovariance function. We assume that the process $\left(X_{n}\right)_{n \in \mathbb{Z}}$ admits an infinite moving average representation as follows:

$$
\begin{equation*}
X_{n}=\sum_{j=0}^{\infty} b_{j} \varepsilon_{n-j} \tag{1}
\end{equation*}
$$

where $\left(\varepsilon_{n}\right)_{n \in \mathbb{Z}}$ is a white-noise series consisting of uncorrelated random variables, each with mean zero and variance $\sigma_{\varepsilon}^{2}$, and where $\left(b_{j}\right)_{j \in \mathbb{N}}$ is square-summable and $b_{0}=1$. We shall further assume that $\left(X_{n}\right)_{n \in \mathbb{Z}}$ admits an infinite autoregressive representation:

$$
\begin{equation*}
\varepsilon_{n}=\sum_{j=0}^{\infty} a_{j} X_{n-j} \tag{2}
\end{equation*}
$$

where the sequence $\left(a_{j}\right)_{j \in \mathbb{N}}$ is absolutely summable and $a_{0}=1$. We assume also that $\left(a_{j}\right)_{j \in \mathbb{N}}$ and $\left(b_{j}\right)_{j \in \mathbb{N}}$, occurring respectively in (2) and (1), satisfy the following conditions for all $\delta>0$ :

$$
\begin{align*}
\left|a_{j}\right| & \leq C_{1} j^{-d-1+\delta}  \tag{3}\\
\left|b_{j}\right| & \leq C_{2} j^{d-1+\delta} \tag{4}
\end{align*}
$$

where $C_{1}$ and $C_{2}$ are constants and $d$ is a parameter verifying $\left.d \in\right] 0,1 / 2[$. The class of processes satisfying (3) and (4) includes long memory processes i.e. processes with covariances not absolutely summable:

$$
\sum_{k=-\infty}^{\infty}|\sigma(k)|=\infty
$$

For example, the FARIMA process $\left(X_{n}\right)_{n \in \mathbb{Z}}$, the most studied long memory process, is the stationary solution to the difference equations:

$$
\begin{equation*}
\phi(B)(1-B)^{d} X_{n}=\theta(B) \varepsilon_{n} \tag{5}
\end{equation*}
$$

where $\left(\varepsilon_{n}\right)_{n \in \mathbb{Z}}$ is a white noise series in $\mathrm{L}^{2}$ with mean zero, $B$ is the backward shift operator and $\phi$ and $\theta$ are polynomials with no zero in the closed unit disk. The coefficients verify as $j$ goes to infinity

$$
\begin{aligned}
& \left|a_{j}\right| \underset{+\infty}{\sim} \\
& \left|b_{j}\right| \underset{+\infty}{\sim} \\
& \underset{+\infty}{\sim} C_{2} j^{-d-1} \\
& C_{2}^{d-1}
\end{aligned}
$$

and thus (3) and (4) hold.
More generally, conditions (3) and (4) hold when the coefficients are of the form:

$$
\begin{array}{lc}
\left|a_{j}\right| & \underset{+\infty}{\sim} \\
\left|b_{j}\right| & L(j) j^{-d-1}  \tag{7}\\
\underset{+\infty}{\sim} & L^{\prime}(j) j^{d-1}
\end{array}
$$

where $L$ and $L^{\prime}$ are slowly varying functions. A positive function $L$ is a slowly varying function in the sense of [20] if, for any $\delta>0, x \mapsto x^{-\delta} L(x)$ is ultimately decreasing and $x \mapsto x^{\delta} L(x)$ is ultimately increasing.

Under conditions (6) and (7), $\left(X_{n}\right)_{n \in \mathbb{Z}}$ is a long memory process. Indeed [11] proved that (7) implies that [11] proved that if:

$$
\sigma(j) \sim j^{2 d-1}\left[L^{\prime}(j) \beta(d, 1-2 d)\right]^{2}
$$

where $\beta$ is the beta function. Note that the converse is not true. More assumptions about the series $\left(b_{j}\right)_{j \in \mathbb{N}}$ are needed in order to get an asymptotic equivalent for $\left(b_{j}\right)_{j \in \mathbb{N}}$ using an asymptotic equivalent of $(\sigma(j))_{j \in \mathbb{N}}($ see $[12])$.

## 2. Wiener-Kolmogorov next step prediction theory

### 2.1. The Wiener-Kolmogorov predictor

The aim of this part is to compute the best linear one-step predictor (with minimum mean-squared distance from the true random variable) knowing all the past $\left\{X_{k+1-j}, j \leqslant 1\right\}$. Our predictor is therefore an infinite linear combination of the infinite past:

$$
\widetilde{X_{k}}(1)=\sum_{j=0}^{\infty} \lambda(j) X_{k-j}
$$

where $(\lambda(j))_{j \in \mathbb{N}}$ are chosen to minimise the mean squared prediction error:

$$
\mathbb{E}\left[\left(\widetilde{X_{k}}(1)-X_{k+1}\right)^{2}\right]
$$

Since $\varepsilon_{k+1}$ is orthogonal to the past $[\varepsilon]_{-\infty}^{k}=[X]_{-\infty}^{k}$, the Wiener-Kolmogorov predictor is equal to

$$
\begin{equation*}
\widetilde{X_{k}}(1)=-\sum_{j=1}^{\infty} a_{j} X_{k+1-j} . \tag{8}
\end{equation*}
$$

### 2.2. Mean-squared prediction error when the predictor is truncated

In practice, we only know a finite subset of the past, the one which we have observed. So the predictor should only depend on the observations. Assume that we only know the set $\left\{X_{1}, \ldots, X_{k}\right\}$ and that we replace the unknown values by 0 , then we have the following new predictor:

$$
\begin{equation*}
\widetilde{X_{k}^{\prime}}(1)=-\sum_{j=1}^{k} a_{j} X_{k+1-j} \tag{9}
\end{equation*}
$$

It is equivalent to say that we have truncated the infinite series (8) to $k$ terms. The following proposition provides the asymptotic properties of the mean-squared prediction error as a function of $k$.
Theorem 2.1. Let $\left(X_{n}\right)_{n \in \mathbb{Z}}$ be a linear stationary process defined by (1), (2) and verifying conditions (3) and (4). We can approximate the mean-squared prediction error of $\widetilde{X_{k}^{\prime}}(1)$ by:

$$
\forall \delta>0, \quad \mathbb{E}\left(\left[X_{k+1}-\widetilde{X_{k}^{\prime}}(1)\right]^{2}\right)=\sigma_{\varepsilon}^{2}+\mathrm{O}\left(k^{-1+\delta}\right) \text { as } k \rightarrow+\infty .
$$

Note that the prediction error is the sum of $\sigma_{\varepsilon}^{2}$, the error in the Wiener-Kolmogorov model, and the error due to the truncation to $k$ terms which is bounded by $\mathrm{O}\left(k^{-1+\delta}\right)$ for all $\delta>0$. We denote $\widetilde{\sigma}_{k}^{2}:=\mathbb{E}\left(\left[X_{k+1}-\widetilde{X_{k}^{\prime}}(1)\right]^{2}\right)$ hereafter the sum of these two errors.

The proof of Theorem (2.1) hinges on the following lemma:
Lemma 2.2. Under assumption (4), the autocovariance function $\sigma$ of the process $\left(X_{n}\right)_{n \in \mathbb{Z}}$ verifies:

$$
\begin{equation*}
\forall \delta>0, \exists C_{3} \in \mathbb{R}, \quad|\sigma(j)| \leq C_{3} j^{2 d-1+\delta} \tag{10}
\end{equation*}
$$

1 Proof. Notice that it suffices to prove (10) for $\delta$ near 0 in order to prove (10) for all $\delta>0$. Let $\delta<1-2 d$ :

2

3

We now prove Theorem 2.1.
Proof.

$$
\begin{equation*}
X_{k+1}-\widetilde{X_{k}^{\prime}}(1)=\varepsilon_{k+1}-\sum_{j=k+1}^{+\infty} a_{j} X_{k+1-j} \tag{11}
\end{equation*}
$$

The two parts of the sum (11) are orthogonal with respect to the inner product associated with the mean-squared norm. Consequently:

$$
\mathbb{E}\left(\left[X_{k+1}-\widetilde{X_{k}^{\prime}}(1)\right]^{2}\right)=\sigma_{\varepsilon}^{2}+\sum_{j=k+1}^{\infty} \sum_{l=k+1}^{\infty} a_{j} a_{l} \sigma(l-j) .
$$

The error due to the truncation, which we have to study, is then equal to:

$$
\begin{equation*}
\tilde{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2}=\sum_{j=k+1}^{\infty} \sum_{l=k+1}^{\infty} a_{j} a_{l} \sigma(l-j) \tag{12}
\end{equation*}
$$

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we have:

$$
\begin{aligned}
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j)= & 2 \sum_{j=k+1}^{+\infty} a_{j} \sum_{l=j+1}^{+\infty} a_{l} \sigma(l-j)+\sum_{j=k+1}^{+\infty} a_{j}^{2} \sigma(0) \\
\leq & 2 \sum_{j=k+1}^{+\infty}\left|a_{j}\right|\left|a_{j+1}\right||\sigma(1)|+\sum_{j=k+1}^{+\infty} a_{j}^{2} \sigma(0) \\
& +2 \sum_{j=k+1}^{+\infty}\left|a_{j}\right| \sum_{l=j+2}^{+\infty}\left|a_{l}\right||\sigma(l-j)|
\end{aligned}
$$

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From (3) and (10) and the triangular inequality, it follows that:

$$
\begin{align*}
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j) \leq & C_{1}^{2} C_{3}\left(2 \sum_{j=k+1}^{+\infty} j^{-d-1+\delta}(j+1)^{-d-1+\delta}+\sum_{j=k+1}^{+\infty}\left(j^{-d-1+\delta}\right)^{2}\right) \\
& +2 C_{1}^{2} C_{3} \sum_{j=k+1}^{+\infty} j^{-d-1+\delta} \sum_{l=j+2}^{+\infty} l^{-d-1+\delta}|l-j|^{2 d-1+\delta} \tag{13}
\end{align*}
$$

for all $\delta>0$. Assume now that $\delta<1 / 2-d$. For the terms (13), since $j \mapsto j^{-d-1+\delta}(j+1)^{-d-1+\delta}$ is a positive and decreasing function on $\mathbb{R}^{+}$, we have the following approximations:

$$
\begin{aligned}
2 C_{1}^{2} C_{3} \sum_{j=k+1}^{+\infty} j^{-d-1+\delta}(j+1)^{-d-1+\delta} & \sim 2 C_{1}^{2} C_{3} \int_{k}^{+\infty} j^{-d-1+\delta}(j+1)^{-d-1+\delta} \mathrm{d} j \\
& \sim \frac{2 C_{1}^{2} C_{3}}{1+2 d-2 \delta} k^{-2 d-1+2 \delta}
\end{aligned}
$$

Since the function $j \mapsto\left(j^{-d-1+\delta}\right)^{2}$ is also positive and decreasing, we can establish in a similar way that:

$$
\begin{aligned}
C_{1}^{2} C_{3} \sum_{j=k+1}^{+\infty}\left(j^{-d-1+\delta}\right)^{2} & \sim C_{1}^{2} C_{3} \int_{k}^{+\infty}\left(j^{-d-1+\delta}\right)^{2} \mathrm{~d} j \\
& \sim \frac{C_{1}^{2} C_{3}}{1+2 d-2 \delta} k^{-2 d-1+2 \delta}
\end{aligned}
$$

For the infinite double series (13), we will similarly compare the series with an integral. In the next lemma, we establish a necessary result for this comparison:
Lemma 2.3. Let $g$ the function $(l, j) \mapsto j^{-d-1+\delta} l^{-d-1+\delta}|l-j|^{2 d-1+\delta}$. Let $m$ and $n$ be two positive integers.
We assume that $\delta<1-2 d$ and $m \geq \frac{\delta-d-1}{\delta+2 d-1}$ for all $\left.\delta \in\right] 0, \frac{\delta-d-1}{\delta+2 d-1}[$. If $n \geq m+1$ then

$$
\int_{A_{n, m}} g(l, j) \mathrm{d} j \mathrm{~d} l \geq g(n+1, m)
$$

where $A_{n, m}$ is the square domain $[n, n+1] \times[m, m+1]$.
Assume now that $\delta<1-2 d$ without loss of generality. Thanks to the previous Lemma and the asymptotic equivalents of (13), there exists $K \in \mathbb{N}$ such that if $k>K$ :

$$
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j) \leq C \int_{k+1}^{+\infty} j^{-d-1+\delta}\left[\int_{j}^{+\infty} l^{-d-1+\delta}(l-j)^{2 d-1+\delta} \mathrm{d} l\right] \mathrm{d} j+\mathrm{O}\left(k^{-2 d-1+2 \delta}\right)
$$

By using the substitution $j l^{\prime}=l$ in the integral over $l$ we obtain:

$$
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j) \leq C^{\prime} \int_{k+1}^{+\infty} j^{-2+3 \delta} \int_{1}^{+\infty} l^{-d-1+\delta}(l-1)^{2 d-1+\delta} \mathrm{d} l \mathrm{~d} j+\mathrm{O}\left(k^{-2 d-1}\right)
$$

Since if $\delta<(1-d) / 2$

$$
\int_{1}^{+\infty} l^{-d-1+\delta}(l-1)^{2 d-1+\delta} \mathrm{d} l<+\infty
$$

it follows:

$$
\begin{align*}
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j) & \leq \mathrm{O}\left(k^{-1+3 \delta}\right)+\mathrm{O}\left(k^{-2 d-1}\right) \\
& \leq \mathrm{O}\left(k^{-1+3 \delta}\right) \tag{14}
\end{align*}
$$

If $\delta>0, \delta<1-2 d$ and $\delta<(1-d) / 2$, we have:

$$
\widetilde{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2}=\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j)=\mathrm{O}\left(k^{-1+3 \delta}\right) .
$$

Notice that if the equality is true under the assumptions $\delta>0, \delta<1-2 d$ and $\delta<(1-d) / 2$, it is also true for any $\delta>0$. This concludes the proof.

The result of Theorem 2.1 is not interesting for short memory processes. It is proved in [15] that the error due to the truncation $\left(\widetilde{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2}\right)$ converges to 0 at an exponential rate for short memory processes. We now prove that there exist long-memory processes whose prediction error attains the rate of convergence $k^{-1}$.

When we specify the form of the autoregressive coefficients and the autocovariance function, we obtain an equivalent of the mean-squared prediction error.

Proposition 2.4. Let $\left(X_{n}\right)_{n \in \mathbb{Z}}$ be a linear stationary process defined by (1), (2) and verifying (6). Assume that the coefficients $\left(a_{j}\right)_{j \in \mathbb{N}^{*}}$ are ultimately of constant sign. We assume also that the autocovariance function $\sigma$ of the process $\left(X_{n}\right)_{n \in \mathbb{Z}}$ verifies:

$$
|\sigma(j)| \underset{+\infty}{\sim} L^{\prime}(j) j^{2 d-1}
$$

with $L^{\prime}$ a slowly varying function and that the function $\sigma$ is of a constant sign. Then the rate of convergence $\mathrm{O}\left(k^{-1}\right)$ is optimal i.e. we have the following asymptotic equivalent:

$$
\begin{equation*}
\mathbb{E}\left(\left[X_{k+1}-\widetilde{X_{k}^{\prime}}(1)\right]^{2}\right)=\sigma_{\varepsilon}^{2}+L^{\prime \prime}(k) k^{-1}+\mathrm{o}\left(k^{-1}\right) \text { as } k \rightarrow+\infty \tag{15}
\end{equation*}
$$

where $L^{\prime \prime}$ is a slowly varying function.
Proof. In this particular case, we can estimate the prediction error more precisely:

$$
\begin{align*}
\left|\sum_{k+1}^{+\infty} \sum_{k+1}^{+\infty} a_{j} a_{l} \sigma(l-j)\right|= & \sum_{k+1}^{+\infty}\left|a_{j}\right| \sum_{j+1}^{+\infty}\left|a_{l}\right||\sigma(l-j)|+\sum_{k+1}^{+\infty} a_{j}^{2} \sigma(0) \\
= & \int_{k+1}^{+\infty} j^{-d-1} L(j) \int_{j+1}^{+\infty} l^{-d-1} L(l)(l-j)^{2 d-1} L^{\prime}(l-j) \mathrm{d} l \mathrm{~d} j \\
& +\frac{k^{-2 d-1} L^{2}(k)}{1+2 d}+\mathrm{O}\left(k^{-2 d-1}\right) \\
\sim & \int_{k+1}^{+\infty} j^{-2} L^{2}(j) L^{\prime}(j) \int_{1 / j+1}^{+\infty} l^{-d-1} \frac{L(l j)}{L(j)}(l-1)^{2 d-1} \frac{L^{\prime}(j(l-1))}{L^{\prime}(j)} \mathrm{d} l \mathrm{~d} j \\
\sim & k^{-1} \frac{L^{2}(k) L^{\prime}(k) \Gamma(1-d) \Gamma(2 d)}{\Gamma(1+d)} . \tag{16}
\end{align*}
$$

Example 2.5. Assume now that $\left(X_{n}\right)_{n \in \mathbb{Z}}$ is fractionally integrated noise, which is the stationary solution of the difference equation:

$$
\begin{equation*}
X_{n}=(1-B)^{-d} \varepsilon_{n} \tag{17}
\end{equation*}
$$

with $B$ the usual backward shift operator, $\left(\varepsilon_{n}\right)_{n \in \mathbb{Z}}$ is a white-noise series and $\left.d \in\right] 0,1 / 2[$ (see for example [6]). This is a particular case of FARIMA models defined in (5) with $\phi=\theta=1$. We can compute the coefficients and obtain that:

$$
\forall j>0, \quad a_{j}=\frac{\Gamma(j-d)}{\Gamma(j+1) \Gamma(-d)}<0
$$

and

$$
a_{j} \sim \frac{j^{-d-1}}{\Gamma(-d)} \quad \text { as } j \rightarrow \infty
$$

We can also compute the autocovariance function and we obtain:

$$
\forall j \geq 0, \quad \sigma(j)=\frac{(-1)^{j} \Gamma(1-2 d)}{\Gamma(j-d+1) \Gamma(1-j-d)} \sigma_{\varepsilon}^{2}>0
$$

and

$$
\sigma(j) \sim \frac{j^{2 d-1} \Gamma(1-2 d)}{\Gamma(d) \Gamma(1-d)} \sigma_{\varepsilon}^{2} \quad \text { as } j \rightarrow \infty
$$

In this particular case, we can estimate the prediction error more precisely and give the explicit expression of $L^{\prime \prime}$ defined in (15):

$$
\begin{equation*}
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j) \sim \frac{\Gamma(1-2 d) \Gamma(2 d) \sigma_{\varepsilon}^{2}}{\Gamma(-d)^{2} \Gamma(d) \Gamma(1+d)} k^{-1} \tag{18}
\end{equation*}
$$

since in this case the functions $L$ and $L^{\prime}$ are constant and equal respectively to $\frac{1}{\Gamma(-d)}$ and to $\frac{\Gamma(1-2 d) \sigma_{\varepsilon}^{2}}{\Gamma(d) \Gamma(1-d)}$.
In the specific case of fractionally integrated noise, we may write the prediction error as:

$$
\mathbb{E}\left(\left[X_{k+1}-\widetilde{X_{k}^{\prime}}(1)\right]^{2}\right)=\sigma_{\varepsilon}^{2}+C(d) k^{-1}+\mathrm{o}\left(k^{-1}\right)
$$

and we can express $C(d)$ as a function of $d$ :

$$
\begin{equation*}
C(d)=\frac{\Gamma(1-2 d) \Gamma(2 d) \sigma_{\varepsilon}^{2}}{\Gamma(-d)^{2} \Gamma(d) \Gamma(1+d)} \tag{19}
\end{equation*}
$$

It is easy to prove that $C(d) \rightarrow+\infty$ as $d \rightarrow 1 / 2$ and we may write the following asymptotic equivalent as $d \rightarrow 1 / 2$ :

$$
\begin{equation*}
C(d) \sim \frac{\sigma_{\varepsilon}^{2}}{(1-2 d) \Gamma(-1 / 2)^{2} \Gamma(1 / 2) \Gamma(3 / 2)} \tag{20}
\end{equation*}
$$

As $d \rightarrow 0, C(d) \rightarrow 0$ and we have the following equivalent as $d \rightarrow 0$ :

$$
C(d) \sim \sigma_{\varepsilon}^{2} d^{2}
$$

As Figure 1 suggests and the asymptotic equivalent given in (20) proves, the mean-squared error tends to $+\infty$ as $d \rightarrow 1 / 2$. By contrast, the constant $C(d)$ takes small values for $d$ in a large interval of $[0,1 / 2[$. Although the rate of convergence has a constant order $k^{-1}$, the forecast error is bigger when $d \rightarrow 1 / 2$. This result is not surprising since the correlation between the predicted variable and the unobserved variables increases when $d \rightarrow 1 / 2$.

Example 2.6. Long-memory processes with seasonal effects (see for example [18]) provide another class of long memory processes verifying assumptions of Theorem 2.1 but not those of Proposition 2.4. We can also prove that the rate of convergence $k^{-1}$ is attained for some seasonal processes. We consider the particular case of GARMA processes introduced by [10] and studied for example by [9]. We first recall their definition. $\left(X_{n}\right)_{n \in \mathbb{Z}}$ is a GARMA process if it is the stationary solution of the equation:

$$
\forall n \in \mathbb{Z}, X_{n}=\left(1-2 \cos \nu B+B^{2}\right)^{-d} \varepsilon_{n}
$$



Figure 1. Behaviour of constant $C(d), d \in[0,1 / 2[$, defined in (19).
1 with $\cos \nu \neq 0, d \in] 0,1 / 2\left[,\left(\varepsilon_{n}\right)_{n \in \mathbb{Z}}\right.$ a white noise and $B$ the backward shift operator. $\left(X_{n}\right)_{n \in \mathbb{Z}}$ admits an infinite 2 autoregressive representation like in (2). The coefficients verify:

$$
\begin{equation*}
a_{j}=\frac{\cos [(j-d) \nu+(d \pi / 2)]}{\Gamma(-d) \sin ^{-d}(\nu)}\left(\frac{2}{j}\right)^{1+d}+\mathrm{O}\left(j^{-5 / 2}\right) \tag{21}
\end{equation*}
$$

3 Its autocovariance function $\sigma$ is such that:

$$
\begin{equation*}
\sigma(j)=K \cos (j \nu) j^{2 d-1}\left(1+\mathrm{O}\left(j^{-1}\right)\right) \tag{22}
\end{equation*}
$$

where $K$ is a constant independent of $j$.
We now give the asymptotic behaviour of the mean-squared error of prediction for these processes.
Proposition 2.7. If $\left(X_{n}\right)_{n \in \mathbb{Z}}$ is a GARMA process, then

$$
\mathbb{E}\left(\left[X_{k+1}-\widetilde{X_{k}^{\prime}}(1)\right]^{2}\right)=\sigma_{\varepsilon}^{2}+C k^{-1}+\mathrm{o}\left(k^{-1}\right) \quad \text { as } k \rightarrow+\infty .
$$

Proof. The proof is given in Appendix.
After these results on the truncating Wiener-Kolmogorov predictor, we will propose another predictor. Instead of truncating to $k$ terms the series which defines the Wiener-Kolmogorov predictor it is more efficient to project directly onto the observations in order to minimise the forecast error. We study this method in the following section.

## 3. PREDICtion METHOD

In this section, we study the asymptotic properties of the forecast mean-squared error when we project the forecast random variable $X_{k+1}$ onto the closed span of the subset $\left\{X_{k}, \ldots, X_{1}\right\}$. This is a generalisation of the "autoregressive model fitting" approach developed by [16] in the case of fractionally integrated noise (defined in (17)). Fitting a $k$-th order autoregressive process is equivalent to projecting onto the span of the subset $\left\{X_{k}, \ldots, X_{1}\right\}$.

### 3.1. Definition of the predictor

Here $\left(X_{n}\right)_{n \in \mathbb{Z}}$ is a long-memory process which verifies the assumptions (1)-(4) of Section 1 . We choose to define the predictor as the projection mapping onto the closed span of the subset $\left\{X_{k}, \ldots, X_{1}\right\}$ of the Hilbert space $\mathrm{L}^{2}(\Omega, \mathcal{F}, \mathbb{P})$ with inner product $\langle X, Y\rangle=\mathbb{E}(X Y)$. Then the predictor can be written as:

$$
\widehat{X_{k}}(1)=-a_{1, k} X_{k}-\ldots-a_{k, k} X_{1}
$$

Consequently the coefficients $\left(-a_{i, k}\right)_{1 \leq i \leq k}$ of the projection verify the $k$ th order Yule-Walker equations:

$$
\begin{equation*}
\forall j \in \llbracket 1, k \rrbracket, \quad \sum_{i=1}^{k} a_{i, k} \sigma(i-j)=-\sigma(j) . \tag{23}
\end{equation*}
$$

The mean-squared prediction error is:

$$
\begin{equation*}
\mathbb{E}\left[\left(\widehat{X_{k}}(1)-X_{k+1}\right)^{2}\right]=\sigma_{\varepsilon}^{2}+\mathbb{E}\left[\left(-\sum_{j=1}^{\infty} a_{j} X_{k+1-j}+\sum_{j=1}^{k} a_{j, k} X_{k+1-j}\right)^{2}\right] \tag{24}
\end{equation*}
$$

### 3.2. Rate of convergence of the error by projection

In the next theorem we derive an asymptotic expression for the prediction error when projecting onto the finite past:

Theorem 3.1. Let $\left(X_{n}\right)_{n \in \mathbb{Z}}$ be a linear stationary process defined by (1), (2) and verifying conditions (3) and (4) of Section 1. We can approximate the mean-squared prediction error of $\widehat{X_{k}}(1)$ by:

$$
\begin{equation*}
\mathbb{E}\left[\left(\widehat{X_{k}}(1)-X_{k+1}\right)^{2}\right]-\sigma_{\varepsilon}^{2}=\mathrm{O}\left(k^{-1}\right) \text { as } k \rightarrow+\infty \tag{25}
\end{equation*}
$$

There exist long-memory processes such that:

$$
\mathbb{E}\left[\left(\widehat{X_{k}}(1)-X_{k+1}\right)^{2}\right]-\sigma_{\varepsilon}^{2} \sim C k^{-1} \text { as } k \rightarrow+\infty
$$

where $C$ is a constant.
Proof. Hereafter we will denote $\widehat{\sigma}_{k}^{2}:=\mathbb{E}\left[\left(\widehat{X_{k}}(1)-X_{k+1}\right)^{2}\right]$. Since the projection minimises the forecast error using $k$ observations, the error by using truncation is bigger and since the truncation method involves an error bounded by $\mathrm{O}\left(k^{-1}\right)$, we obtain (25).

Consequently we only need prove that this rate of convergence is attained. This is the case for the fractionally integrated processes defined in (17). We want to express the error made by projection in terms of the WienerKolmogorov truncation error. Therefore in the case of a fractionally integrated process we need only show that:

$$
\widehat{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2} \sim C k^{-1}
$$

Now, setting $a_{j, k}=0$ if $j>k$ and developping (24)

$$
\begin{align*}
\widehat{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2} & =\sum_{j=0}^{+\infty} \sum_{l=0}^{+\infty}\left(a_{j}-a_{j, k}\right)\left(a_{l}-a_{l, k}\right) \sigma(l-j) \\
& =\sum_{j=0}^{+\infty}\left(a_{j}-a_{j, k}\right) \sum_{l=0}^{+\infty} a_{l} \sigma(l-j)-\sum_{l=0}^{k} a_{l, k} \sum_{j=0}^{+\infty}\left(a_{j}-a_{j, k}\right) \sigma(l-j) \tag{26}
\end{align*}
$$

1 We first study the first term of the sum (26). For any $j>0$, we have $\sum_{l=0}^{+\infty} a_{l} \sigma(l-j)=0$ :

$$
\begin{aligned}
\varepsilon_{n} & =\sum_{j=0}^{\infty} a_{l} X_{n-l} \\
\mathbb{E}\left(X_{n-j} \varepsilon_{n}\right) & =\sum_{l=0}^{\infty} a_{l} \sigma(l-j)=0
\end{aligned}
$$

4 as $\varepsilon_{n}$ is orthogonal to $X_{n-j}$ for $j>0$. We can thus rewrite the first term of (26):

$$
\begin{aligned}
\sum_{j=0}^{+\infty}\left(a_{j}-a_{j, k}\right) \sum_{l=0}^{+\infty} a_{l} \sigma(l-j) & =\left(a_{0}-a_{0, k}\right) \sum_{l=0}^{+\infty} a_{l} \sigma(l) \\
& =0
\end{aligned}
$$

5 since $a_{0}=a_{0, k}=1$ according to definition. Next we study the second term of the sum in (26). And we obtain:

$$
\begin{align*}
\sum_{l=0}^{k} a_{l, k} \sum_{j=0}^{+\infty}\left(a_{j}-a_{j, k}\right) \sigma(l-j)= & \sum_{l=1}^{k}\left(a_{l, k}-a_{l}\right) \sum_{j=1}^{k}\left(a_{j}-a_{j, k}\right) \sigma(l-j) \\
& +\sum_{l=1}^{k}\left(a_{l, k}-a_{l}\right) \sum_{j=k+1}^{+\infty} a_{j} \sigma(l-j) \\
& +\sum_{l=0}^{k} a_{l} \sum_{j=1}^{k}\left(a_{j}-a_{j, k}\right) \sigma(l-j) \\
& +\sum_{l=0}^{k} a_{l} \sum_{j=k+1}^{+\infty} a_{j} \sigma(l-j) . \tag{27}
\end{align*}
$$

6 Similarly we rewrite the term (27) using the Yule-Walker equations:

7

$$
\sum_{l=1}^{k}\left(a_{l, k}-a_{l}\right) \sum_{j=k+1}^{+\infty} a_{j} \sigma(l-j)=-\sum_{l=1}^{k}\left(a_{l, k}-a_{l}\right) \sum_{j=0}^{k} a_{j} \sigma(l-j)
$$

8 We then remark that (27) is equal to the opposite of (27). Hence it follows that:

$$
\begin{align*}
\sum_{l=0}^{k} a_{l, k} \sum_{j=0}^{+\infty}\left(a_{j}-a_{j, k}\right) \sigma(l-j)= & \sum_{l=1}^{k}\left(a_{l, k}-a_{l}\right) \sum_{j=1}^{k}\left(a_{j}-a_{j, k}\right) \sigma(l-j) \\
& +2 \sum_{l=1}^{k}\left(a_{l, k}-a_{l}\right) \sum_{j=k+1}^{+\infty} a_{j} \sigma(l-j) \\
& +\sum_{l=0}^{k} a_{l} \sum_{j=k+1}^{+\infty} a_{j} \sigma(l-j) \tag{28}
\end{align*}
$$

In a similar way we can rewrite the third term of the sum in (28) using Fubini's Theorem and then the YuleWalker equations:

$$
\sum_{l=0}^{k} a_{l} \sum_{j=k+1}^{+\infty} a_{j} \sigma(l-j)=-\sum_{l=k+1}^{+\infty} \sum_{j=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j)
$$

This third term is therefore equal to the forecast error due to the truncation (12).
In order to compare the prediction error when truncating the Wiener-Kolmogorov predictor and when projecting onto the finite past for a fractionally integrated process, we need the sign of all the components of the sum in (28). For a fractionally integrated noise, we know the explicit formula for $a_{j}$ and $\sigma(j)$ :

$$
\forall j>0, \quad a_{j}=\frac{\Gamma(j-d)}{\Gamma(j+1) \Gamma(-d)}<0 \text { and } \forall j \geq 0, \quad \sigma(j)=\frac{(-1)^{j} \Gamma(1-2 d)}{\Gamma(j-d+1) \Gamma(1-j-d)} \sigma_{\varepsilon}^{2}>0
$$

In order to get the sign of $a_{l, k}-a_{l}$ we use the explicit formula given in [5] and we easily obtain that $a_{l, k}-a_{l}$ is negative for all $l \in \llbracket 1, k \rrbracket$.

$$
\begin{align*}
a_{l}-a_{l, k} & =\frac{\Gamma(l-d)}{\Gamma(l+1) \Gamma(-d)}-\frac{\Gamma(k+1) \Gamma(l-d) \Gamma(k-d-l+1)}{\Gamma(k-l+1) \Gamma(l+1) \Gamma(-d) \Gamma(k-d+1)} \\
& =-a_{l}\left(-1+\frac{\Gamma(k+1) \Gamma(k-d-l+1)}{\Gamma(k-l+1) \Gamma(k-d+1)}\right) \\
& =-a_{l}\left(\frac{k \ldots(k-j+1)}{(k-d) \ldots(k-d-j+1)}-1\right)>0 \tag{29}
\end{align*}
$$

since $\forall j \in \mathbb{N}^{*}, a_{j}<0$. To give an asymptotic equivalent for the prediction error, we use the sum given in (28). We have the sign of the three terms: the first is negative, the second is positive and the last is negative. Moreover the third is equal to the forecast error by truncation and we have proved that this asymptotic equivalent has order $\mathrm{O}\left(k^{-1}\right)$. The prediction error when projecting converges faster to 0 than the error by truncation only if the second term is equivalent to $C k^{-1}$, with $C$ constant. Consequently, we search for a bound for $a_{l}-a_{l, k}$ using (29):

$$
\begin{aligned}
a_{l}-a_{l, k} & =-a_{l}\left(\prod_{m=0}^{l-1}\left(\frac{1-\frac{m}{k}}{1-\frac{m+d}{k}}\right)-1\right) \\
& =-a_{l}\left(\prod_{m=0}^{l-1}\left(1+\frac{\frac{d}{k}}{1-\frac{d+m}{k}}\right)-1\right) .
\end{aligned}
$$

Then we use the following inequality:

$$
\forall x \in \mathbb{R}, \quad 1+x \leq \exp (x)
$$

which gives:

$$
\begin{aligned}
a_{l}-a_{l, k} & \leq-a_{l}\left(\exp \left(\sum_{m=0}^{l-1} \frac{\frac{d}{k}}{1-\frac{d+m}{k}}\right)-1\right) \\
& \leq-a_{l}\left(\exp \left(d \sum_{m=0}^{l-1} \frac{1}{k-d-m}\right)-1\right) \\
& \leq-a_{l} \exp \left(d \sum_{m=0}^{l-1} \frac{1}{k-d-m}\right)
\end{aligned}
$$

1 According to the previous inequality, we have:

$$
\begin{aligned}
\sum_{l=1}^{k}\left(a_{l}-a_{l, k}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j) \leq & \sum_{l=1}^{k-1}-a_{l} \exp \left(d \int_{0}^{l} \frac{1}{k-d-m} \mathrm{~d} m\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j) \\
& +\left(-a_{k}\right) \exp \left(d \int_{m=0}^{k-1} \frac{1}{k-d-m} \mathrm{~d} m\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(k-j)
\end{aligned}
$$

$$
\begin{aligned}
\sum_{l=1}^{k}\left(a_{l}-a_{l, k}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j)= & \sum_{l=1}^{k-1}\left(a_{l}-a_{l, k}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j) \\
& +\left(a_{k}-a_{k, k}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(k-j) \\
\leq & \sum_{l=1}^{k-1}-a_{l} \exp \left(d \sum_{m=0}^{j-1} \frac{1}{k-d-m}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j) \\
& +\left(-a_{k}\right) \exp \left(d \sum_{m=0}^{k-1} \frac{1}{k-d-m}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(k-j)
\end{aligned}
$$

As the function $x \mapsto \frac{1}{k-d-x}$ is increasing, we can bound the series by the integrals.

We now search a bound for $\exp \left(d \int_{m=0}^{k-1} \frac{1}{k-d-m} \mathrm{~d} m\right)$. We have:

$$
\begin{aligned}
\int_{m=0}^{k-1} \frac{1}{k-d-m} \mathrm{~d} m & \sim \ln (k) \\
& \leq \frac{3}{2} \ln (k)
\end{aligned}
$$

for $k$ large enough. Therefore there exists $K$ such that for all $k \geq K$ :

$$
\begin{aligned}
\sum_{l=1}^{k}\left(a_{l}-a_{l, k}\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j) \leq & \sum_{l=1}^{k-1}-a_{l} \exp \left(d \ln \left(\frac{k-d}{k-d-l}\right)\right) \sum_{j=k+1}^{+\infty}-a_{j} \sigma(l-j) \\
& -a_{k} k^{\frac{3}{2} d} \sum_{j=k+1}^{+\infty}-a_{j} \sigma(0) \\
\leq & C(k-d)^{d} \sum_{l=1}^{k-1} l^{-d-1}(k-d-l)^{-d} \sum_{j=k+1}^{+\infty} j^{-d-1}(j-l)^{2 d-1} \\
& +C k^{-d-1} k^{\frac{3}{2} d} k^{-d} \\
\leq & \frac{C}{(k-d)^{2}} \int_{1 /(k-d)}^{1} l^{-d-1}(1-l)^{-d}\left(\int_{1}^{+\infty} j^{-d-1}(j-1)^{2 d-1} \mathrm{~d} l\right) \mathrm{d} j \\
& +C k^{-\frac{1}{2} d-1} \\
\leq & C^{\prime}(k-d)^{-2+d}+C k^{-\frac{1}{2} d-1}
\end{aligned}
$$



Figure 2. Ratio $r(k), d \in] 0,1 / 2[$ defined in (30).
and so the positive term has a smaller asymptotic order than the forecast error made by truncating. Therefore we have proved that in the particular case of fractionally integrated processes, the two prediction errors are equivalent to $C k^{-1}$ with $C$ constant.

The two approaches to next-step prediction, by truncation to $k$ terms or by projection on the last $k$ observations have consequently a prediction error with the same rate of convergence $k^{-1}$. So it is interesting to study how the second approach improves the prediction and if the improvement is negligible with respect to the prediction error due to the truncation. In this aim, we define the following quotient:

$$
\begin{equation*}
r(k):=\frac{\left(\widetilde{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2}\right)-\left(\widehat{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2}\right)}{\widetilde{\sigma}_{k}^{2}-\sigma_{\varepsilon}^{2}} \tag{30}
\end{equation*}
$$

which is the ratio of the difference between the two prediction errors (prediction error due to the truncation (12) and prediction error due to the projection (26)) and the prediction error due to the truncation. By (28), we obtain:

$$
r(k)=\frac{\sum_{j=1}^{k}\left(a_{j, k}-a_{j}\right) \sum_{l=1}^{k}\left(a_{l}-a_{l, k}\right) \sigma(j-l)+2 \sum_{j=1}^{k}\left(a_{j, k}-a_{j}\right) \sum_{l=k+1}^{+\infty} a_{l} \sigma(j-l)}{\sum_{j=k+1}^{+\infty} a_{j} \sum_{l=k+1}^{+\infty} a_{l} \sigma(j-l)} .
$$

We evaluate this ratio in the particular case of a fractionally integrated noise defined in (17). Figure 2 shows that the prediction by truncation incurs a larger performance loss when $d \rightarrow 1 / 2$. The improvement reaches 50 percent when $d>0.3$ and $k>20$.

## 4. The multistep predictors

After obtaining an asymptotic equivalent for the next step predictor, we will generalise the two methods to $h$-step prediction and aim to obtain their asymptotic behaviour as $k \rightarrow+\infty$ but also as $h \rightarrow+\infty$.

### 4.1. The Wiener-Kolmogorov predictor

Since we assume that the process $\left(X_{n}\right)_{n \in \mathbb{Z}}$ has an autoregressive representation (2) and moving average representation (1), the linear least-squares predictor, $\widetilde{X}_{k}(h)$, of $X_{k+h}$ based on the infinite past $\left(X_{j}, j \leq k\right)$ is
given by:

$$
\widetilde{X}_{k}(h)=\sum_{j=h}^{+\infty} b_{j} \varepsilon_{k+h-j}
$$

(see for example Th. 5.5 . 1 of [6]). The corresponding mean squared error of prediction is:

$$
\mathbb{E}\left[\left(\widetilde{X_{k}}(h)-X_{k+h}\right)^{2}\right]=\sigma_{\varepsilon}^{2} \sum_{j=0}^{h-1} b_{j}^{2}
$$

As the prediction step $h$ tends to infinity, the mean-squared prediction error converges to $\sigma_{\varepsilon}^{2} \sum_{j=0}^{+\infty} b_{j}^{2}=\sigma(0)$, which is the the variance of the process $\left(X_{n}\right)_{n \in \mathbb{Z}}$. But if the mean-squared prediction error is equal to $\sigma(0)$, we have no more interest in the prediction method since its error is equal to the error of predicting the future by 0 . The convergence of the mean-squared error to $\sigma(0)$ is slower in the long-memory case than in the short-memory case since the sequence $b_{j}$ decays more slowly to 0 . More precisely in the case of a long-memory process under the assumption (7) we can explicit the asymptotic behaviour of the mean-squared error. We have as $h$ tends to infinity:

$$
\begin{align*}
& \sigma(0)-\mathbb{E}\left[\left(\widetilde{X_{k}}(h)-X_{k+h}\right)^{2}\right]=\sigma_{e}^{2} \sum_{j=h}^{+\infty} b_{j}^{2} \\
& \sim \sum_{j=h}^{+\infty} j^{2 d-2} L^{\prime 2}(j) \\
& \sim \int_{h}^{+\infty} j^{2 d-2} L^{\prime 2}(j) \mathrm{d} j \\
& \underset{h \rightarrow+\infty}{\sim} \frac{1}{1-2 d} h^{2 d-1} L^{\prime 2}(h) \tag{31}
\end{align*}
$$

according to Proposition 1.5 .10 of [4].
On the contrary, for short memory processes we can obtain an exponential rate of convergence of $\mathbb{E}\left[\left(\widetilde{X_{k}}(h)-X_{k+h}\right)^{2}\right]$ to the variance of the process $\sigma(0)$. Consider the classical ARMA processes (see for example [6]). The moving average coefficients $b_{j}$ are bounded by:

$$
\left|b_{j}\right| \leq C j^{m-1} \rho^{-j}
$$

where $\rho$ verifies $|\rho|<1$ and $m$ is a non negative integer (see for example [6] p. 92). Thus the mean-squared prediction error is equivalent to:

$$
\begin{aligned}
\sigma(0)-\mathbb{E}\left[\left(\widetilde{X_{k}}(h)-X_{k+h}\right)^{2}\right] \underset{h \rightarrow+\infty}{\sim} \sigma_{\varepsilon}^{2} C \sum_{j=h}^{+\infty} j^{2 m-2} \rho^{-2 j} \\
\underset{h \rightarrow+\infty}{\sim} \sigma_{\varepsilon}^{2} C(2 \log (\rho))^{1-2 m}(2 \log (\rho) h)^{2 m-2} \exp (2 \log (\rho) h) .
\end{aligned}
$$

We obtain that the rate of convergence is exponential. The mean-squared prediction error goes faster to $\sigma(0)$ when the predicting process is ARMA than when the process is a long-memory process.

The $h$-step prediction is then more interesting for the long-memory process than for the short-memory process, having observed the infinite past. We now consider the truncating effect and the projection effect.

### 4.2. Truncated Wiener-Kolmogorov predictor and the linear least-squares predictor

In practice, we only observe a finite number $k$ of data $\left(X_{1}, \ldots, X_{k}\right)$ so we cannot evaluate the Wiener-Kolmogorov predictor. We first study what happens when we truncate the series which defines this predictor.

We define the $h$-step truncated Wiener-Kolmogorov of order $k$ by induction as:

$$
\begin{equation*}
\widetilde{X_{k}^{\prime}}(h)=-\sum_{j=1}^{h-1} a_{j} \widetilde{X_{k}^{\prime}}(h-j)-\sum_{j=1}^{k} a_{h-1+j} X_{k+1-j} \tag{32}
\end{equation*}
$$

The following proposition describes the asymptotic behaviour of the mean-squared error of the predictor (32).
Proposition 4.1. Let $\left(X_{n}\right)_{n \in \mathbb{Z}}$ be a linear stationary process defined by (1), (2) and verifying (3) and (4). We can approximate the mean-squared prediction error of $\widetilde{X_{k}^{\prime}}(h)$ by:

$$
\begin{equation*}
\forall \delta>0, \mathbb{E}\left[\widetilde{X_{k}^{\prime}}(h)-X_{k+h}\right]^{2}=\sigma_{\varepsilon}^{2} \sum_{l=0}^{h-1} b_{l}^{2}+R(h, k) \tag{33}
\end{equation*}
$$

where $R(h, k) \geq 0$ and where for all $h$ and $k$,

$$
R(h, k) \leq C h^{2 d+\delta} k^{-1+\delta}
$$

with $C$ a constant independent of $(h, k)$.
Proof. First we write the difference between the predicted random variable and its predictor:

$$
\begin{aligned}
\widetilde{X_{k}^{\prime}}(h)-X_{k+h}= & -\sum_{j=1}^{h-1} a_{j} \widetilde{X_{k}^{\prime}}(h-j)-\sum_{l=1}^{k} a_{h-1+j} X_{k+1-j}-\varepsilon_{k+h}+\sum_{j=1}^{+\infty} a_{j} X_{k+h-j} \\
= & -\varepsilon_{k+h}+\sum_{j=1}^{h-1} a_{j}\left(X_{k+h-j}-\widetilde{X_{k}^{\prime}}(h-j)\right)+\sum_{j=1}^{k} a_{h-1+j}\left(X_{k+1-j}-X_{k+1-j}\right) \\
& +\sum_{j=k+1}^{+\infty} a_{h-1+j} X_{k+1-j} \\
= & -\varepsilon_{k+h}+\sum_{j=1}^{h-1} a_{j}\left(X_{k+h-j}-\widetilde{X_{k}^{\prime}}(h-j)\right)+\sum_{j=k+1}^{+\infty} a_{h-1+j} X_{k+1-j} .
\end{aligned}
$$

We proceed by induction on $h$ to show that

$$
\begin{aligned}
\widetilde{X_{k}^{\prime}}(h)-X_{k+h}= & -\sum_{l=0}^{h-1}\left(\sum_{j_{1}+j_{2}+\ldots+j_{h}=l}(-1)^{\operatorname{card}\left(\left\{i, j_{i} \neq 0\right\}\right)} a_{j_{1}} a_{j_{2}} \ldots a_{j_{h}}\right) \varepsilon_{k+h-l} \\
& +\sum_{j=k+1}^{+\infty}\left(\sum_{i_{1}+i_{2}+\ldots+i_{h}=h-1}(-1)^{\operatorname{card}\left(\left\{l>1, i_{l} \neq 0\right\}\right)} a_{j+i_{1}} a_{i_{2}} \ldots a_{i_{h}}\right) X_{k+1-j} .
\end{aligned}
$$

For $h=2$, we have for example

$$
\begin{equation*}
\widetilde{X_{k}^{\prime}}(2)-X_{k+2}=-\left(a_{0} \varepsilon_{k+2}-a_{1} \varepsilon_{k+1}\right)+\sum_{j=k+1}^{+\infty}\left(-a_{1} a_{j}+a_{j+1}\right) X_{k+1-j} \tag{17}
\end{equation*}
$$

Denote $A(z)=1+\sum_{j=1}^{+\infty} a_{j} z^{j}$ and $B(z)=1+\sum_{j=1}^{+\infty} b_{j} z^{j}$. Since we have $A(z)=B(z)^{-1}$, we obtain the following conditions on the coefficients:

$$
\begin{aligned}
b_{1} & =-a_{1} \\
b_{2} & =-a_{2}+a_{1}^{2} \\
b_{3} & =-a_{3}+2 a_{1} a_{2}-a_{1}^{3}
\end{aligned}
$$

So we obtain:

$$
\begin{equation*}
\widetilde{X_{k}^{\prime}}(h)-X_{k+h}=-\sum_{l=0}^{h-1} b_{l} \varepsilon_{k+h-l}+\sum_{j=k+1}^{+\infty} \sum_{m=0}^{h-1} a_{j+m} b_{h-1-m} X_{k+1-j} . \tag{34}
\end{equation*}
$$

Since the process $\left(\varepsilon_{n}\right)_{n \in \mathbb{Z}}$ is uncorrelated, the two terms of the sum (34) are orthogonal. We can rewrite the mean-squared error:

$$
\begin{equation*}
\mathbb{E}\left[\widetilde{X_{k}^{\prime}}(h)-X_{k+h}\right]^{2}=\sum_{l=0}^{h-1} b_{l}^{2} \sigma_{\varepsilon}^{2}+\mathbb{E}\left[\sum_{j=k+1}^{+\infty}\left(\sum_{m=0}^{h-1} a_{j+h-1-m} b_{m}\right) X_{k+1-j}\right]^{2} \tag{35}
\end{equation*}
$$

10 The first part of the error (35) is due to the prediction method and the second (35) due to truncating the predictor. We now approximate the error term (35) by using (3) and (4). We obtain the following upper bound:

$$
\begin{align*}
\forall \delta>0,\left|\sum_{m=0}^{h-1} a_{j+h-1-m} b_{m}\right| & \leq \sum_{m=1}^{h-1}\left|a_{j+h-1-m} b_{m}\right|+\left|b_{0} a_{j+h-1}\right| \\
& \leq C_{1} C_{2} \int_{0}^{h}(j+h-1-l)^{-d-1+\delta} l^{d-1+\delta} \mathrm{d} l+C_{1}(j+h)^{-d-1} \\
& \leq C_{1} C_{2} h^{-1+2 \delta} \int_{0}^{1}\left(\frac{j}{h}+1-l\right)^{-d-1+\delta} l^{d-1+\delta} \mathrm{d} l+C_{1}(j+h)^{-d-1} \\
& \leq C_{1} C_{2} h^{-1+2 \delta} j^{-d-1+\delta} \int_{0}^{1}\left(\frac{1}{h}+\frac{1-l}{j}\right)^{-d-1+\delta} l^{d-1+\delta} \mathrm{d} l+C_{1}(j+h)^{-d-1} \\
& \leq C_{1} C_{2} h^{d+2 \delta} j^{-d-1+\delta} \int_{0}^{1} l^{d-1+\delta} \mathrm{d} l+C_{1}(j+h)^{-d-1} \\
\left|\sum_{m=0}^{h} a_{j+h-m} b_{m}\right| & \leq C_{1} C_{2} \frac{h^{d+2 \delta}}{d} j^{-d-1+\delta} \tag{36}
\end{align*}
$$

where the constants $C_{1}$ and $C_{2}$ are independent of $(h, j)$. We then obtain by (36):

$$
\begin{align*}
\mathbb{E}\left[\sum_{j=k+1}^{+\infty}\left(\sum_{m=0}^{h-1} a_{j+h-1-m} b_{m}\right) X_{k+1-j}\right]^{2} & \leq \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty}\left(\sum_{m=0}^{h-1} a_{j+h-1-m} b_{m}\right)\left(\sum_{m=0}^{h-1} a_{l+h-1-m} b_{m}\right) \sigma(j-l) \\
& \leq\left(C_{1} C_{2} \frac{h^{d+2 \delta}}{d}\right)^{2} \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} j^{-d-1+\delta} l^{-d-1+\delta} \sigma(j-l) \tag{37}
\end{align*}
$$

The series in (37) is independent of $h$ and using Theorem 2.1 we have that it is bounded by $C k^{-1+\delta}$ with $C$ independent of $k$. This concludes the proof.

Remark 4.2. Gathering all the above results about the truncated $h$-step predictor $\widetilde{X_{k}^{\prime}}(h)$, the variance of prediction error is

$$
\mathbb{E}\left(X_{k+h}-\widetilde{X_{k}^{\prime}}(h)\right)^{2}=\sigma(0)-\sigma_{\varepsilon}^{2} \sum_{l=h}^{+\infty} b_{l}^{2}+R(h, k)
$$

where $\sigma(0)-\sigma_{\varepsilon}^{2} \sum_{l=h}^{+\infty} b_{l}^{2}$ is the optimal mean-squared error of linear prediction while $R(h, k)$ quantifies the truncating effect. Truncation always increases the variance of forecasting error but it is possible to keep it's effect as small as possible. Indeed, taking (31) into account, the condition

$$
\begin{equation*}
h^{2 d} k^{-1}=\mathrm{o}\left(h^{2 d-1}\right), \tag{38}
\end{equation*}
$$

which is satisfied if $h=\mathrm{o}(k)$, insures that the truncating effect is negligible with respect to the quality of the optimal linear predictor $\widetilde{X}_{k}(h)$.

In other words, long-step prediction in a long-memory context is interesting when the prediction is based on a sufficiently large sample $\left(X_{1}, \ldots, X_{k}\right)$.

We can compare the prediction error of the truncated Wiener-Kolmogorov predictor with the least-squares predictor defined as the projection on the finite past $\left(X_{1}, \ldots, X_{k}\right)$. Let $\widehat{X_{k}}(h)$ the predictor of $X_{k+h}$. It then can be written as:

$$
\widehat{X_{k}}(h)=-\sum_{j=1}^{k} c_{j, k} X_{k+1-j}
$$

where the vector $\left(c_{j, k}\right)_{1 \leq j \leq k}$ minimises the mean-squared error:

$$
\mathbb{E}\left[\widehat{X_{k}}(h)-X_{k+h}\right]^{2}
$$

Thus the coefficients $\left(c_{j, k}\right)_{1 \leq j \leq k}$ satisfy the following relation:

$$
\begin{equation*}
\left(c_{j, k}\right)_{1 \leq j \leq k}=-\Sigma_{k}^{-1}\left(\sigma_{h-1+j}\right)_{1 \leq j \leq k} \tag{39}
\end{equation*}
$$

where $\Sigma_{k}$ is the autocovariance matrix of the vector $\left(X_{1}, \ldots, X_{k}\right)$ i.e.

$$
\Sigma_{k}=\left(\begin{array}{cccc}
\sigma(0) & \sigma(1) & \ldots & \sigma(k-1) \\
\vdots & \vdots & \ddots & \vdots \\
\sigma(k-1) & \sigma(k-2) & \ldots & \sigma(0)
\end{array}\right)
$$

By construction of $\widehat{X_{k}}(h)$, the mean-squared error of prediction is lower than $\sigma(0)$ for any $k$ and $h$. Howewer it can be interesting to search a condition on $k$ and $h$ to have the prediction error due to the projection negligible with respect to the information (31) given by the Wiener-Kolmogorov predictor.

As $\widehat{X_{k}}(h)$ is the projection of $X_{k+h}$ onto $\left(X_{1}, \ldots, X_{k}\right)$, the mean-squared prediction error is also lower than the prediction error of the truncated Wiener-Kolmogorov predictor (see Fig. 3). The mean-squared error of prediction due to the projection onto the span of $\left(X_{1}, \ldots, X_{k}\right)$ tends at least as fast to zero as the mean-squared error due to truncation of the least-squares predictor. We obtain that under the assumptions of Proposition 4.1 and condition (38), the prediction error due to the projection is negligible with respect to the information (31) given by the Wiener-Kolmogorov predictor. In Figure 3, we show that the comportments of the truncated predictor and of the least-squares predictor are similar. In the both cases, the prediction error due to the prediction method is sufficiently small with respect to the available information (31) to obtain a good predictor in the case the fractionally integrated noise defined in (17) with $k=80$ and $h \in[1,150]$.


Figure 3. Mean-squared error of $\widetilde{X_{k}}(h)$ (MMSE), $\widetilde{X_{k}^{\prime}}(h)$ (TPMSE) and $\widehat{X_{k}}(h)$ (LLSPE) for $d=0.4$ and $k=80$ for fractionally integrated noise defined in (17).

## 5. Appendix: Proof of Proposition 2.7

2 We have to find an asymptotic equivalent of $\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j)$. First we replace the coefficients and 3 the autocovariances by their asymptotic expressions given in (21) and (22). We obtain:

$$
\begin{align*}
& \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{+\infty} a_{j} a_{l} \sigma(l-j)=\sum_{j=k+1}^{+\infty} a_{j}^{2} \sigma(0)+2 \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} a_{j} a_{l} \sigma(l-j) \\
& =\sum_{j=k+1}^{+\infty}\left[\left(\frac{\cos [(j-d) \nu+(d \pi / 2)]}{\Gamma(-d) \sin ^{-d}(\nu)}\right)^{2}\left(\frac{2}{j}\right)^{2+2 d}+\mathrm{O}\left(j^{-7 / 2-d}\right)\right] \sigma(0) \\
& \quad+\frac{2^{4} \sigma(0) \sigma_{\varepsilon}^{2} \sin (d \pi) \Gamma(1-2 d)}{\pi(\Gamma(-d))^{2}} \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} B_{j, l} \tag{40}
\end{align*}
$$

4 where $B_{j, l}$ is:

$$
\begin{aligned}
B_{j, l}= & \cos \left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \\
& \times\left(1+\mathrm{O}\left(j^{d-1 / 2}\right)\right)\left(1+\mathrm{O}\left(l^{d-1 / 2}\right)\right)\left(1+\mathrm{O}\left((j-l)^{-1}\right)\right)
\end{aligned}
$$

The first term (40) is bounded by $\mathrm{O}\left(k^{-2 d-1}\right)$ and thus negligible with respect to $k^{-1}$. For the second term (40):

$$
\begin{align*}
& \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} B_{j, l} \\
= & \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos \left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \\
+ & \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos \left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \mathrm{O}\left(j^{d-1 / 2}\right) \\
+ & \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos \left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \mathrm{O}\left(l^{d-1 / 2}\right) \\
+ & \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos \left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \mathrm{O}\left((j-l)^{-1}\right) . \tag{41}
\end{align*}
$$

We first prove that the terms (41), (41) and (41) are bounded by $\mathrm{O}\left(k^{d-3 / 2}\right)$ and thus negligible with respect to $k^{-1}$. For example, we study (41):

$$
\begin{aligned}
& \left|\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos \left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \mathrm{O}\left(j^{d-1 / 2}\right)\right| \leq \\
& C \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} j^{-3 / 2} l^{-1-d}(j-l)^{2 d-1}=\mathrm{O}\left(k^{d-3 / 2}\right) .
\end{aligned}
$$

The calculations for (41) and (41) have the same form. The dominant term of (40) is then (41). (41) can be broken into three parts:

$$
\begin{align*}
\sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos & {\left[(j-d) \nu+\frac{d \pi}{2}\right] \cos \left[(l-d) \nu+\frac{d \pi}{2}\right] \cos ((j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)}=} \\
& \frac{1}{2} \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1}(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \\
& +\frac{1}{2} \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1} \cos (2(j-l) \nu)(j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} \\
& +\frac{1}{4} \sum_{j=k+1}^{+\infty} \sum_{l=k+1}^{j-1}[\cos [(2 j-2 d) \nu+d \pi]+\cos [(2 l-2 d) \nu+d \pi]](j l)^{-1-d} \frac{\Gamma(j-l+2 d)}{\Gamma(j-l+1)} . \tag{42}
\end{align*}
$$

We have proved in Proposition 2.4 that (42) is equivalent to $C k^{-1}$. And it is easy to show (by Abel transformations), that (42) and (42) are negligible with respect to (42). This concludes the proof.

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