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NUMBER OF HIDDEN STATES AND MEMORY: A JOINT ORDER ESTIMATION PROBLEM FOR MARKOV CHAINS WITH MARKOV REGIME

ANTOINE CHAMBAZ¹ AND CATHERINE MATIAS²

Abstract. This paper deals with order identification for Markov chains with Markov regime (MCMR) in the context of finite alphabets. We define the joint order of a MCMR process in terms of the number \(k\) of states of the hidden Markov chain and the memory \(m\) of the conditional Markov chain. We study the properties of penalized maximum likelihood estimators for the unknown order \((k, m)\) of an observed MCMR process, relying on information theoretic arguments. The novelty of our work relies in the joint estimation of two structural parameters. Furthermore, the different models in competition are not nested. In an asymptotic framework, we prove that a penalized maximum likelihood estimator is strongly consistent without prior bounds on \(k\) and \(m\). We complement our theoretical work with a simulation study of its behaviour. We also study numerically the behaviour of the BIC criterion. A theoretical proof of its consistency seems to us presently out of reach for MCMR, as such a result does not yet exist in the simpler case where \(m = 0\) (that is for hidden Markov models).

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1. INTRODUCTION

Markov chains with Markov regime

Let \(X = \{1, \ldots, k\}\) and \(Y = \{1, \ldots, r\}\) be two finite sets and \(m\) be some integer. Here, \(\mathbb{N}^*\) denotes the set of positive integers and for any \(i \leq j\), we use \(x_i^j\) to denote the sequence \(x_i, x_{i+1}, \ldots, x_j\). We consider a process \(\{X_j, Y_j\}_{j \geq 1}\) on \((X \times Y)^{\mathbb{N}}\) with distribution as follows. Process \(\{X_j\}_{j \geq 1}\) is a Markov chain with memory one on \(X\) with transition matrix \(A = (a(i,j))_{1 \leq i, j \leq k}\). Besides, conditionally on \(\{X_j\}_{j \geq 1}\), process \(\{Y_j\}_{j \geq 1}\) is a Markov chain with memory \(m\) [abbreviated to MC(\(m\))], and the conditional distribution of \(Y_s\) conditional on \((\{X_j\}_{j \geq 1}, \{Y_j\}_{j < s})\) is given by \(b(Y_s|Y_{s-m}, X_s)\), for any \(s > m\). The process has some initial distribution \(\mu\) on \(X \times Y^m\).

Keywords and phrases. Markov regime, order estimation, hidden states, conditional memory, hidden Markov model.

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The set $\Pi_{k,m}$ denotes the set of all such probability measures $\mathbb{P}$ on $(\mathcal{X} \times \mathcal{Y})^n$ formally described by, for all $n \in \mathbb{N}$ and $(x^n_1, y^n_1) \in (\mathcal{X} \times \mathcal{Y})^n$,

$$\mathbb{P}(x^n_1, y^n_1) = \mu(x_1, y_1^n) \left( \prod_{i=1}^{n-1} a(x_i, x_{i+1}) \right) \left\{ \prod_{i=m+1}^{n} b(y_i | y_{i-m}^{i-1}; x_i) \right\}.$$  

(1)

Let us denote by $\mathcal{M}_1(\mathcal{X} \times \mathcal{Y}^m)$ the set of probability measures on $\mathcal{X} \times \mathcal{Y}^m$. The set $\Pi_{k,m}$ is naturally parametrized by $\mathcal{M}_1(\mathcal{X} \times \mathcal{Y}^m) \times \Theta_{k,m}$, where

$$\Theta_{k,m} = \left\{ \theta = (A, B) : A = (a(i, j))_{1 \leq i, j \leq k}, a(i, j) \geq 0, \sum_{j=1}^{k} a(i, j) = 1 \text{ and } \right.$$  

$$B = (b(y | y_{j-1}; x))_{y \in \mathcal{Y}, y_{j-1} \in \mathcal{Y}^n \times x}; b(y | y_{j-1}; x) \geq 0, \sum_{y=1}^{r} b(y | y_{j-1}; x) = 1 \right\}. $$

(2)

Thus, $\Pi_{k,m} = \{ \mathbb{P} = \mathbb{P}_{\mu, \theta} : (\mu, \theta) \in \mathcal{M}_1(\mathcal{X} \times \mathcal{Y}^m) \times \Theta_{k,m} \}$. Moreover, for stationary processes with stationary measure $\pi_\theta$ on $\mathcal{X} \times \mathcal{Y}^m$, we use the notation $\mathbb{P}_\theta = \mathbb{P}_{\pi_\theta}$ to remind that the initial probability is fixed.

The observations consist in $\{Y_j\}_{1 \leq j \leq n}$ which is called a Markov chain with Markov regime (abbreviated to MCMR). Note that $\{Y_j\}_{j \geq 1}$ is not a Markov process. We assume that its distribution is the marginal onto $\mathcal{Y}^m$ of some $\mathbb{P}_{\theta_0}$ ($\theta_0$ is the true and unknown parameter value), which is stationary, ergodic and belongs to $\Pi_{k_0,m_0}$ for some unknown $(k_0, m_0) \in \mathbb{N}^* \times \mathbb{N}$. In other words, it is assumed that there exists a hidden stationary process $\{X_j\}_{j \geq 1}$ such that the complete process $\{(X_j, Y_j)\}_{j \geq 1}$ has distribution $\mathbb{P}_{\theta_0} \in \Pi_{k_0,m_0}$. When there is no ambiguity, $\mathbb{P}_{\theta_0}$ will abbreviate to $\mathbb{P}_0$. In this setup, the cardinality $r$ of the observed alphabet is known.

While HMMs can model the heterogeneity of a sequence by distinguishing different segments with different i.i.d. distributions (i.e., $m = 0$), MCMRs enable furthermore a Markovian modelling of each segment ($m \geq 1$). HMMs and MCMRs are widely used in practical applications among which genomics, econometrics and speech recognition. We refer to [4,10] for recent and comprehensive overviews on this topic. Note that more flexibility could be added to these models by authorising different memory lengths for the different regimes but the choice of these lengths is a problem which is as delicate as the one we address here.

When the couple $(k_0, m_0)$ associated with the distribution $\mathbb{P}_0$ of a MCMR is a priori known, inference on the parameters has been investigated to a great extent (most recent results can be found in [12]). However, in many applications where MCMR are used as a modeling device, there is no clear indication about a good choice for $(k_0, m_0)$. So, inference about $(k_0, m_0)$ is a crucial issue, for even consistency may fail to hold in a wrong model.

In this paper, we propose a sound definition of the order of a MCMR which we substitute to $(k_0, m_0)$ as main quantity of interest. We explain why below.

**Defining the order of a MCMR**

Model selection for MCMRs already appears in [3]. The authors propose a reversible jump MCMC procedure to select the memory $m$ as well as the number of regimes $k$. However, no simulations were given to establish the correctness of the procedure (the method was rather directly applied to real biological data) and it is still an open question to know whether such a procedure is consistent or not.

Model selection for HMMs is a more widely studied subject (see for instance [11,13,18,19,23,24]). The order of a HMM simply is the minimal number of hidden states (here $m = 0$). Our approach to model selection for MCMRs draws its inspiration from [13].
ORDER ESTIMATION FOR MARKOV CHAINS WITH MARKOV REGIME

One of the interesting problems raised by HMM modeling is the question of identifiability: when do two different Markov chains generate the same stochastic process? This question first raised by [1] can be solved for HMM using linear algebra (see [11, 15]). To our knowledge, such a complete solution does not exist in the context of MCMR models. As an immediate consequence, the definition of the order of a MCMR has to be clarified.

In the convenient case where each model $M_x$ is characterized by $\alpha \in \mathbb{N}$, the order of the distribution of the observations is the smallest $\alpha$ such that this distribution belongs to $M_x$. This definition is motivated by the will to guarantee that the statistician is looking for the most economical representation of the process (the number of parameters required for its description is minimized). In contrast, the definition of the order may be more involved when the above notion of minimality does not have a natural meaning anymore. Two examples follow.

First, order identification for autoregressive moving average ARMA($p, q$) models is a well-known example where the structural parameter is bivariate (see for example [14, 22]). Nevertheless, this problem is very different from the one studied here because there exists a minimal representation ($p_0, q_0$) thus defined as the true one. Indeed, the spectral density of an ARMA process admits a unique representation of the form $\lambda \mapsto |Q/P(e^{-i\lambda})|^2/2\pi$ where $P$ and $Q$ are polynomial functions with no common factors, $P(z) \neq 0$, for all $|z| \leq 1$ and $Q(z) \neq 0$, for all $|z| < 1$. Then the true order of the ARMA process is defined as the couple $(p_0, q_0)$ of degrees of the polynomials $P$ and $Q$ respectively.

Second, when dealing with model selection for context trees, the order to be selected is a tree. However, there exists a natural ordering (given by the inclusion) which is not a total ordering. Csiszar and Talata [6] establish the consistency of both penalized (with Bayesian Information Criterion, alias BIC, penalization) maximum likelihood and minimum description length procedures.

A particularity of MCMR modeling is that the sets $\Pi^{k,m}$ are not globally nested, even though $\{\Pi^{k,m}\}_{k \geq 1}$ and $\{\Pi^{k,m}\}_{m \geq 0}$ are nested. In general, for a given probability $\mathbb{P} \in \bigcup_{(k,m) \in \mathbb{N}^* \times \mathbb{N}} \Pi^{k,m}$, there is no unique $(k_0, m_0) \in \mathbb{N}^* \times \mathbb{N}$ such that $\mathbb{P} \in \Pi^{k_0, m_0}$ and $\mathbb{P}$ does not belong to any of its subsets (that is, for any $(k, m) \in \mathbb{N}^* \times \mathbb{N}$ such that $(k < k_0, m = m_0)$, or $(k = k_0, m < m_0)$, or $(k < k_0, m < m_0)$, one has $\mathbb{P} \notin \Pi^{k,m}$).

So, we decide to rely on the point of view of minimizing the number of parameters in order to determine which of the possibly multiple representations is to be selected. Let us denote by $N(k, m)$ the number of parameters required to describe an element of $\Theta^{k,m}$

$$N(k, m) = \dim(\Theta^{k,m}) = k(k-1) + kr^m(r-1). \quad (3)$$

This induces an ordering of the set $\mathbb{N}^* \times \mathbb{N}$. For all $(k_1, m_1), (k_2, m_2) \in \mathbb{N}^* \times \mathbb{N}$,

$$(k_1, m_1) \prec (k_2, m_2) \quad \text{if and only if} \quad \{N(k_1, m_1) < N(k_2, m_2)\} \text{ or } \{N(k_1, m_1) = N(k_2, m_2) \text{ and } k_1 < k_2\}.$$  

Note that we made an arbitrary choice between $k$ and $m$ to get a total order. Obviously, all the results remain valid when using $m$ instead of $k$. In the following, $a \sim b$ means $b \sim a$ and $a \preceq b$ means $(a \sim b \text{ or } a = b)$.

We are now able to define the true order $(k_0, m_0)$ of a probability $\mathbb{P}$ belonging to $\bigcup_{k \geq 1, m \geq 0} \Pi^{k,m}$ as

$$(k_0, m_0) = \min \left\{ (k, m) \in (\mathbb{N}^* \times \mathbb{N}, \prec) : \mathbb{P} \in \Pi^{k,m} \right\}.$$  

Content of the paper

Next, we tackle the issue of estimating the true order of a MCMR by penalized maximum likelihood procedure. In Section 2, we introduce our penalized maximum likelihood estimator and two others code-based estimators. The two latter are not computable in practice, but their behaviour is strongly connected to that of our estimator. Its strong consistency (as well as that of the two other estimators) is established in two steps in Section 3: Section 3.1 is dedicated to overestimation and Section 3.2 to underestimation. We present in Section 4 the results of a simulation study.
2. Estimation procedure

The general form of our estimators writes as

\[
(\hat{k}, \hat{m})_n = \arg\min_{(k,m) \in \mathbb{N}^* \times \mathbb{N}} \left( -\log Q_{k,m}(Y^n_1) + \text{pen}(n, k, m) \right),
\]

where \(Q_{k,m}\) is a (coding) measure on \(\mathcal{Y}^n\) and \(\text{pen}(n, k, m)\) is a penalty term. Three different coding measures are considered: KT\(_{k,m}\), NML\(_{k,m}\) and ML\(_{k,m}\) defined below.

Let us consider the distribution density \(\nu_{k,m}\) on \(\Theta_{k,m}\), given for all \(\theta \in \Theta_{k,m}\) by

\[
\nu_{k,m}(\theta) = \prod_{i=1}^{k} \frac{1}{\Gamma(k/2) \Gamma(r/2)} \left( \prod_{j=1}^{r} a(i,j)^{1/2} \right) \left( \prod_{t \in \mathcal{Y}^m} \prod_{i=1}^{r} \frac{1}{b(t|t^m; i)^{1/2}} \right),
\]

where \(\Gamma(z) = \int_0^\infty x^{z-1} e^{-x} dx\).

The Krichevsky-Trofimov mixture is the probability measure KT\(_{k,m}\) on \((X \times Y)^\mathbb{N}^*\) whose marginals have density

\[
(x^n_1, y^n_1) \mapsto \int_{\theta \in \Theta_{k,m}} \mathbb{P}_{\tilde{\mu}^X \otimes \tilde{\mu}^Y, \theta}(x^n_1, y^n_1) \nu_{k,m}(\theta) d\theta,
\]

where \(\tilde{\mu}^X\) and \(\tilde{\mu}^Y\) are the uniform distributions on \(X\) and \(Y^m\), respectively. Note that we use for simplicity of notation the same symbol for the probability measure and its marginals on \(\mathcal{Y}^n\).

The maximum likelihood (ML\(_{k,m}\)) and the normalized maximum likelihood (NML\(_{k,m}\)) coding measures are defined in a natural way:

\[
\text{ML}_{k,m}(y^n_1) = \sup_{\theta \in \Theta_{k,m}} \mathbb{P}_\theta(y^n_1),
\]

and if we set \(C(n, k, m) = \sum_{y^n_1 \in \mathcal{Y}^n} \sup_{\theta \in \Theta_{k,m}} \mathbb{P}_\theta(y^n_1)\), then

\[
\text{NML}_{k,m}(y^n_1) = \sup_{\theta \in \Theta_{k,m}} \frac{\mathbb{P}_\theta(y^n_1)}{C(n, k, m)} = \frac{\text{ML}_{k,m}(y^n_1)}{C(n, k, m)}.
\]

We will use later that KT\(_{k,m}\) and NML\(_{k,m}\) (but not ML\(_{k,m}\)) are probability measures.

The so-called penalized maximum likelihood estimator of the order that we focus on corresponds to the coding measure ML\(_{k,m}\) and to a particular choice of penalty. It is computable, contrarily to the estimators based on KT\(_{k,m}\) and NML\(_{k,m}\) (which are not computable for large sample sizes even in the HMM framework).

Nevertheless, studying the two latter is important here because coding measures KT\(_{k,m}\) and NML\(_{k,m}\) are strongly related to ML\(_{k,m}\) (see Lem. 3.4). Note finally that Liu and Narayan dedicated an article [18] to the asymptotic study of the order estimator based on KT\(_{k,m}\) in the HMM framework.

3. Consistency issue

This section is dedicated to the statement and proof of the main consistency result.

**Theorem 3.1.** Let \(P_0\) be stationary, ergodic and belong to \(\bigcup_{k>1,m>0} \Pi_{k,m}^\mathbb{N}^*\) with unknown true order \((k_0, m_0)\).

Let \(\{Y_j\}_{1 \leq j \leq n}\) be a stationary process drawn from the marginal of \(P_0\) on \(\mathcal{Y}^n\).
Let us denote by $\varphi$ an increasing function which maps $(\mathbb{N}^* \times \mathbb{N}, \prec)$ to $\mathbb{N}$. Let us choose $\alpha > 1$ and introduce, for all $n \in \mathbb{N}^*$, $k \geq 1$ and $m \geq 0$,

$$
\tau(n, k, m) = \max\left(0, \log k + m \log r - k \log \frac{\Gamma(k/2)}{\Gamma(1/2)} - kr^m \log \frac{\Gamma(r/2)}{\Gamma(1/2)}
+ \frac{k^2(k-1)}{4n} + \frac{kr^{m+1}(r-1)}{4n} + \frac{5k}{24n}(1+r^m)\right).
$$

(6)

Let $(\widetilde{k, m})_n$ be defined by (4), with $Q_{k,m} = \text{ML}_{k,m}$ and

$$
\text{pen}(n, k, m) = \sum_{(k', m') \preceq (k, m)} \left(\frac{1}{2}N(k', m') \log n + \tau(n, k', m') + \alpha \varphi(k, m) \log n\right).
$$

(7)

Then, $\mathbb{P}_0$-almost surely, $(\widetilde{k, m})_n = (k_0, m_0)$ eventually.

Put in other words, $(\widetilde{k, m})_n$ does not overestimate, nor underestimate the true order $(k_0, m_0)$ eventually, $\mathbb{P}_0$-almost surely. The proof is naturally divided accordingly: overestimation is considered in Section 3.1 and underestimation in Section 3.2. Note that a simple way to choose $\varphi$ is to set $\varphi(k, m) = \text{card}\{\{(k', m') \in \mathbb{N}^* \times \mathbb{N} : (k', m') \preceq (k, m)\} \}$. 

Remark 3.2. The theorem is valid more generally for $Q_{k,m} = \text{KT}_{k,m}$ or $\text{NML}_{k,m}$ with the penalty

$$
\text{pen}(n, k, m) = \sum_{(k', m') \preceq (k, m)} \left(\frac{1}{2}N(k', m') \log n + \alpha \varphi(k, m) \log n\right).
$$

(7)

Note also that the precise form of the penalty is used in the non-overestimation step (see the proof of Prop. 3.3).

Any reader familiar with the BIC criterion will immediately interpret our penalty in terms of cumulated sum of BIC penalty terms (of the form $\frac{1}{2}N(k, m) \log n$). We do not prove here the consistency of the BIC procedure. We think this would be a very difficult task in our setup, and such a result does not even exist in the simpler HMM case. One explanation of this lack is that no explicit expression exists for the maximum likelihood estimate, turning explicit computations unfeasible. Thus our penalty is heavier than the BIC one but it is inspired by the penalty studied in [13] for order estimation in the HMM framework. However, if we cannot propose a theoretical study of the BIC estimator, we provide an original numerical study of the consistency of both our estimator and the BIC one in Section 4.

3.1. No overestimation

In this section, we prove that, $\mathbb{P}_0$-almost surely, $(\widetilde{k, m})_n$ does not overestimate the true order $(k_0, m_0)$ eventually. Besides, a rate of decrease to zero of the overestimation probability is also obtained.

Proposition 3.3. Under the assumptions and notations of Theorem 3.1, $\mathbb{P}_0$-almost surely, $(\widetilde{k, m})_n \preceq (k_0, m_0)$ eventually. Moreover,

$$
\mathbb{P}_0\left\{(\widetilde{k, m})_n > (k_0, m_0)\right\} = O(n^{-\alpha}),
$$

where $\alpha > 1$ is chosen in Theorem 3.1.

The proof of Proposition 3.3 heavily relies on the following

Lemma 3.4. Let us fix $(k, m) \in \mathbb{N}^* \times \mathbb{N}$ and denote by $Q_{k,m}$ the coding probability $\text{KT}_{k,m}$ or $\text{NML}_{k,m}$. Let us recall that $\tau$ is defined by (6). Then the following bounds hold:

$$
0 \leq \max_{y_1 \in Y^\ast} \left\{\log \frac{\text{ML}_{k,m}(y_1^n)}{Q_{k,m}(y_1^n)}\right\} \leq \frac{1}{2}N(k, m) \log n + \tau(n, k, m).
$$
Lemma 3.4 is a combination of results which essentially go back to [25] and [7]. The proof is similar to the proof of [18], Lemma 3.4 and thus omitted.

Applying Lemma 3.4 allows to control the distribution of \((\hat{k}, \hat{m})_n\) under \(P_0\) with respect to the dimensions of the involved models. More precisely, we have

**Proposition 3.5.** Under the assumptions of Theorem 3.1, for fixed \((k, m)\in\mathbb{N}^*\times\mathbb{N},\)

\[
P_0\left\{ (\hat{k}, \hat{m})_n = (k, m) \right\} \leq \exp\left\{ -\text{pen}(n, k, m) + \text{pen}(n, k_0, m_0) \right\}
\times \left( \exp\left\{ \frac{1}{2} N(k_0, m_0) \log n + \tau(n, k_0, m_0) \right\} \right)
\times \exp\left\{ \frac{1}{2} N(m_0) \log n \right\}
\times \exp\left\{ \frac{1}{2} N(k_0, m_0) \log n - \tau(n, k_0, m_0) \right\}.
\]

Proof of Proposition 3.5. Let \(Q_{k, m}\) be the probability measure \(\text{NML}_{k, m}\) or \(\text{KT}_{k, m}\). Using Definition (4) of \((\hat{k}, \hat{m})_n\) and Lemma 3.4 implies that

\[
P_0\left\{ (\hat{k}, \hat{m})_n = (k, m) \right\} \leq \exp\left\{ \log \frac{Q_{k, m}}{Q_{k_0, m_0}}(Y^n_1) \geq \text{pen}(n, k, m) - \text{pen}(n, k_0, m_0) \right\}
\leq \exp\left\{ \log \frac{Q_{k, m}}{M_{k_0, m_0}}(Y^n_1) \geq \text{pen}(n, k, m) - \text{pen}(n, k_0, m_0) - \frac{1}{2} N(k_0, m_0) \log n - \tau(n, k_0, m_0) \right\}.
\]

Because \(P_0\in\Pi^{k_0 \cdot m_0}\), we may use that \(-\log M_{k_0, m_0}(Y^n_1) \leq -\log P_0(Y^n_1), P_0\)-almost surely, hence we have,

\[
P_0\left\{ (\hat{k}, \hat{m})_n = (k, m) \right\} \leq \exp\left\{ \frac{1}{2} N(k_0, m_0) \log n - \tau(n, k_0, m_0) \right\}
\times \exp\left\{ \log \frac{Q_{k, m}}{P_0}(y^n_1) \geq \text{pen}(n, k, m) - \text{pen}(n, k_0, m_0) + \frac{1}{2} N(k_0, m_0) \log n - \tau(n, k_0, m_0) \right\}
\leq \exp\left\{ \frac{1}{2} N(k_0, m_0) \log n + \tau(n, k_0, m_0) - \text{pen}(n, k, m) + \text{pen}(n, k_0, m_0) \right\}.
\]

This is the expected result, since \(Q_{k, m}\) is a probability measure. Let us assume now that \(Q_{k, m} = \text{ML}_{k, m}\).

Similarly,

\[
P_0\left\{ (\hat{k}, \hat{m})_n = (k, m) \right\} \leq P_0\left\{ \log \frac{\text{ML}_{k, m}(Y^n_1)}{\text{ML}_{k_0, m_0}(Y^n_1)} \geq \text{pen}(n, k, m) - \text{pen}(n, k_0, m_0) \right\}
\leq \exp\left\{ \frac{1}{2} N(k_0, m_0) \log n + \tau(n, k_0, m_0) \right\}
\times \exp\left\{ -\text{pen}(n, k, m) + \text{pen}(n, k_0, m_0) \right\}.
\]

Using the bound \(\text{ML}_{k, m}(y^n_1) \leq \text{KT}_{k, m}(y^n_1) \exp\{N(k, m)/2 \cdot \log n + \tau(n, k, m)\}\) given by Lemma 3.4 yields the expected result. Thus, the proof is complete.

The proof of Proposition 3.3 is now at hand.
Proof of Proposition 3.3. Let us denote by \( A_n \) the event \( \{(k, m)_n > (k_0, m_0)\} \). By virtue of the Borel-Cantelli lemma, it is sufficient to prove that \( \sum_{n \geq 1} \mathbb{P}_0(A_n) \) is finite in order to conclude that overestimation eventually does not occur, \( \mathbb{P}_0 \)-almost surely.

Let us assume that \( \mathbb{Q}_{k, m} = \text{NML}_{k, m} \) or \( \text{KT}_{k, m} \) (the very similar proof in the case \( \mathbb{Q}_{k, m} = \text{ML}_{k, m} \) is omitted). If \( C_0 \) bounds sequence \( \{\tau(n, k_0, m_0)\}_n \), then

\[
\mathbb{P}_0\{A_n\} = \sum_{(k, m) > (k_0, m_0)} \mathbb{P}_0\{(k, m)_n = (k, m)\} \\
\leq (a) \sum_{(k, m) > (k_0, m_0)} \exp\left\{ \frac{1}{2}N(k, m) \log n + \tau(n, k_0, m_0) - \text{pen}(n, k, m) + \text{pen}(n, k_0, m_0) \right\} \\
\leq (b) \sum_{(k, m) > (k_0, m_0)} \exp\left\{ - \frac{1}{2}N(k', m') \log n \right\} + \tau(n, k_0, m_0) - \alpha[\varphi(k, m) - \varphi(k, m_0)] \log n \leq C_0 \sum_{(k, m) > (k_0, m_0)} \exp\{-\alpha[\varphi(k, m) - \varphi(k, m_0)] \log n\}.
\]

Here, Proposition 3.5 and \( N(k, m) \geq N(k_0, m_0) \) (for all \( (k, m) > (k_0, m_0) \)) yield (a) and (b) follows from the definition of the penalty term (note that the second sum may be empty). Now \( \varphi : \mathbb{N}^* \times \mathbb{N} \to \mathbb{N} \) increases, hence

\[
\mathbb{P}_0\{A_n\} \leq C_0 \sum_{j \geq 1} \exp\{-\alpha j \log n\} \leq C_0 n^{-\alpha}(1 - n^{-\alpha})^{-1} = O(n^{-\alpha}).
\]

Since \( \alpha > 1 \), the sum \( \sum_n \mathbb{P}_0\{A_n\} \) is finite, and the proof is complete. \( \square \)

3.2. No underestimation

In this section, we prove that, \( \mathbb{P}_0 \)-almost surely, \( (\widehat{k, m})_n \) does not underestimates the true order \( (k_0, m_0) \) eventually.

Proposition 3.6. Under the assumptions of Theorem 3.1, \( \mathbb{P}_0 \)-almost surely, \( (\widehat{k, m})_n \geq (k_0, m_0) \) eventually.

The first step while proving Proposition 3.6 is to relate the distribution of \( (\widehat{k, m})_n \) with the behaviour of the logarithm of the maximum likelihood ratio \( \log \text{ML}_{k, m}(Y^n_l) - \log \mathbb{P}_0(Y^n_l) \). This is the purpose of Lemma 3.7, whose proof is given in the appendix. From now on, “infinitely often” abbreviates to “i.o.”.

Lemma 3.7. Under the assumptions of Theorem 3.1, for every \( k \geq 1 \) and \( m \geq 0 \), there exists a sequence \( \{\varepsilon_n\} \) of random variables that converges to zero \( \mathbb{P}_0 \)-almost surely such that, for all \( n \geq 1 \),

\[
\mathbb{P}_0\{(\widehat{k, m})_n = (k, m) \text{ i.o.}\} \leq \mathbb{P}_0\left\{ \frac{1}{n} \log \text{ML}_{k, m}(Y^n_l) - \log \mathbb{P}_0(Y^n_l) \geq \varepsilon_n \text{ i.o.} \right\}.
\]

Now, Proposition 3.6 essentially relies on two properties: a) the existence of a convenient Strong Law of Large Numbers for logarithms of likelihood ratios, in the spirit of the Shannon-Breiman-McMillan theorem – see Lemma 3.8; b) the existence of a finite sieve for the set of all ergodic distributions in \( \Pi^{k, m} \) – see Lemma 3.9.

Let us recall that for any probability measures \( \mathbb{P}_1 \) and \( \mathbb{P}_2 \) on the same measurable space \( (\Omega, \mathcal{A}) \) the relative entropy \( D(\mathbb{P}_1 \| \mathbb{P}_2) \) is defined by

\[
D(\mathbb{P}_1 \| \mathbb{P}_2) = \int \log \frac{d\mathbb{P}_1}{d\mathbb{P}_2} d\mathbb{P}_1,
\]

if \( \mathbb{P}_1 \) is absolutely continuous with respect to \( \mathbb{P}_2 \), and \( +\infty \) otherwise.
Now, consider any probability measures \( P_1 \) and \( P_2 \) on the same sequence space \( (\Omega^N, \mathcal{A}^N) \), with marginals onto \( (\Omega^k, \mathcal{A}^k) \) denoted by \( P_1^0 \) and \( P_2^0 \), respectively. The asymptotic relative entropy \( D_\infty(P_1 | P_2) \) (or divergence rate) is defined, when it exists, by

\[
D_\infty(P_1 | P_2) = \lim_{n \to \infty} \frac{1}{n} D(P_1^n | P_2^n).
\]

Lemma 3.8 (Shannon-Breiman-McMillan). Let \( \{Y_j\}_{j \geq 1} \) be an ergodic stationary process whose distribution \( P_0 \) belongs to \( \bigcup_{k \geq 1, m \geq 0} \Pi_{k,m} \). For all \( k \geq 1, m \geq 0 \) and any stationary ergodic \( P_\theta \in \Pi_{k,m} \), the divergence rate \( D_\infty(P_0 | P_\theta) \) exists and is finite. Moreover, \( P_0 \)–almost surely,

\[
\lim_{n \to \infty} \frac{1}{n} \sum_{i \in I_{k,m}} \log P_\theta(Y_{1}^n_i) - \log P_0(Y_{1}^n_i) = -D_\infty(P_0 | P_\theta).
\]  

We omit the proof of Lemma 3.8, which is a generalization of a similar classical theorem that holds for hidden Markov models [2, 11, 13, 17]. Lemma 3.8 notably ensures the existence of \( D_\infty(P_1 | P_2) \) for stationary ergodic distributions \( P_1 \) and \( P_2 \) belonging to \( \bigcup_{k \geq 1, m \geq 0} \Pi_{k,m} \).

Stating the existence of a finite sieve involves two new subsets. For any \( \delta > 0 \), let us denote by \( \Pi_{k,m}^{\delta} \) the subset of stationary probabilities \( P_\theta \in \Pi_{k,m} \) such that \( \theta \) has all its coordinates lower bounded by \( \delta \). Moreover, let \( \Pi_{k,m} \) stand for the subset of stationary ergodic probabilities in \( \Pi_{k,m}^{\delta} \).

Lemma 3.9. Let us set \( k \geq 1 \) and \( m \geq 0 \). For every \( \varepsilon > 0 \), there exist \( \delta > 0 \), a finite set of indexes \( I_{k,m}^{\varepsilon} \) and a finite set of stationary probabilities \( \{P_i\}_{i \in I_{k,m}^{\varepsilon}} \) included in \( \Pi_{k,m}^{\delta} \) such that, for all stationary ergodic \( P_\theta \in \Pi_{k,m} \), there exists some \( P_i \) (\( i \in I_{k,m}^{\varepsilon} \)) which guarantees that:

\[
\sup_{n \in \mathbb{N}} \max_{y^n_i \in \mathcal{Y}^n} \frac{1}{n} \sum_{i \in I_{k,m}^{\varepsilon}} \log P_\theta(y^n_i) - \log P_i(y^n_i) \leq \varepsilon.
\]

Lemma 3.9 is a key for replacing the term \( \log P_\theta \) in the left-hand side of (8) by \( \log \text{ML}_{k,m} \) and the right-hand side term of the same equation by \( -\inf_{\mathcal{P}} D_\infty(P_0 | \mathcal{P}) \) (for \( \mathcal{P} \) ranging over \( \Pi_{k,m} \)). Its proof is given in the appendix.

Proof of Proposition 3.6. Let us set \( \varepsilon > 0 \) such that

\[
\min_{(k,m) < (k_0,m_0)} \inf_{\mathcal{P} \in \Pi_{k,m}} D_\infty(P_0 | \mathcal{P}) > \varepsilon.
\]

Such an \( \varepsilon \) exists according to a result (whose generalization is easy and omitted in our framework) first obtained by [16], Propositions 1 and 2.

Let us choose arbitrarily \( (k,m) = (k_0,m_0) \) and prove that \( \mathbb{P}_0 \{ (\widetilde{k}, \widetilde{m})_n = (k,m) \text{ i.o.} \} = 0 \).

According to Lemma 3.7, there exists a sequence \( \{\varepsilon_n\} \) of random variables that converges to zero \( \mathbb{P}_0 \)-almost surely such that

\[
\mathbb{P}_0 \left\{ (\widetilde{k}, \widetilde{m})_n = (k,m) \text{ i.o.} \right\} \leq \mathbb{P}_0 \left\{ \frac{1}{n} \sum_{i \in I_{k,m}^{\varepsilon_n}} \log \text{ML}_{k,m}(Y_{1}^n_i) - \log P_0(Y_{1}^n_i) \geq \varepsilon_n \text{ i.o.} \right\}.
\]

Now, Lemma 3.9 guarantees the existence of a finite set \( \{P_i\}_{i \in I_{k,m}^{\varepsilon_n}} \) of stationary probability measures which belong to \( \Pi_{k,m}^{\delta} \subset \Pi_{k,m} \) such that

\[
\mathbb{P}_0 \left\{ (\widetilde{k}, \widetilde{m})_n = (k,m) \text{ i.o.} \right\} \leq \mathbb{P}_0 \left\{ \frac{1}{n} \sum_{i \in I_{k,m}^{\varepsilon_n}} \max_{y^n \in \mathcal{Y}^n} \log P_i(Y_{1}^n_i) - \log P_0(Y_{1}^n_i) \geq (\varepsilon + \varepsilon_n) \text{ i.o.} \right\}.
\]
Table 1. The four smallest dimensions \(N(k,m)\) of MCMR of order \((k,m)\) when \(r = 4\).

<table>
<thead>
<tr>
<th>((m))</th>
<th>(1)</th>
<th>(26)</th>
<th>(0)</th>
<th>(8)</th>
<th>(15)</th>
<th>(24)</th>
<th>(2)</th>
<th>(3)</th>
<th>(4)</th>
<th>((k))</th>
</tr>
</thead>
</table>

Finally, Lemma 3.8 yields the convergence of \(n^{-1}[\log P(Y^n) - \log P_0(Y^n)]\) to \(-D_\infty(P_0||P_1)\), \(P_0\)-almost surely, for all \(i \in I_{k,m}^r\). The choice of \(\varepsilon\) then ensures that

\[
P_0 \left\{ (k,m)_n = (k,m) \text{ i.o.} \right\} = 0.
\]

Since \((k,m) \prec (k_0,m_0)\) was chosen arbitrarily, the previous equation implies that

\[
P_0 \left\{ (k,m)_n \preceq (k_0,m_0) \text{ i.o.} \right\} = 0
\]

or, put in other words, that \(P_0\)-almost surely, \((\hat{k,m})_n \succeq (k_0,m_0)\) eventually. Thus, the proof is complete. \(\square\)

4. Simulation study

In this section, we choose to discard the case \(k = 1\). Indeed, this case corresponds to Markov models and thus, to a data dependency structure which is very different from that of the case where there are at least two regimes. This distinction does not appear in the theoretical part of this article. However, all results (and their proofs) can be easily adapted to that slightly different framework. Finally note that in practice, MCMR modelling with at least two different regimes \((k \geq 2)\) is used for data with no finite memory. MCMR with one regime (Markov models) poorly fit such data.

Our theoretical study is motivated by application to biology and more precisely, to genome analysis. Choosing a good model within a prescribed family is a very sensitive task. In [20], MCMR order selection (not identification) is performed for mining Bacillus subtilis chromosome heterogeneity. After fitting all models with \(k \in \{2, \ldots, 8\}\) and \(m \in \{0, 1, 2, 3\}\), the authors select (by eyeball and using biological considerations) a MCMR of order \((k,m) = (3,2)\) for detecting atypical segments of length approximately 25 kb (1 kb equals 1,000 nucleotides) upon the 4,200 kb long chromosome. In this framework, \(Y\) stands for the nucleotides set \(\{A, C, G, T\}\) (\(r = 4\)). In particular, the four smallest dimensions of MCMR are given in Table 1.

In order to illustrate our work, we undertake a simple simulation study in the framework described above. Evaluation of ML\(k,m(y^n)\) is processed by Expectation-Maximization (EM) algorithm [4, 8]. We run EM with multiple random initializations, and select the final result presenting the highest value. We use the package SHOW [21], where SHOW stands for Structured HOMogeneities Watcher. It is a set of executable programs that implements different uses of MCMR models for DNA sequences. The source code of SHOW is freely available.

The software is protected by the GNU Public Licence.

We arbitrarily decide to consider only MCMR of dimension at most 26. The corresponding orders \((k,m)\) appear in Table 1. Set \(\mathcal{M} = \{\Pi^{k,m} : (k, m) \in \mathbb{N}^* \times \mathbb{N}, N(k,m) \leq 26\}\). For each model \(M_0 \in \mathcal{M}\) (line 1 in Fig. 1), we repeat 10 times (line 2) the following: we choose \(P_0 \in M_0\) (line 3), then simulate a chain \(y^n_0\) \((n = 100,000)\) with distribution \(P_0\) (line 4), next for each model \(M \in \mathcal{M}\) (line 5), for each \(n \in \{25,000; 50,000; 100,000\}\) (line 6), we evaluate sup\(_{P \in M} \sup P(y^n_i)\) (line 7). Afterwards, identifying the order boils down to applying (4) for a particular choice of penalty term. Before discussing this final step, let us go into details about the way we choose \(P_0 \in M_0\) (line 3). Because this simulation study is motivated by [20], we choose the final distribution obtained by fitting the same segment \([3,450,001; 3,475,000]\) of length 25 kb of the Bacillus subtilis chromosome than used in [20], Figure 1. For each repetition, a possibly slightly different distribution \(P_0\) is thus selected (EM is run with multiple random initializations).
A. CHAMBAZ AND C. MATIAS

\[ \text{foreach (} M_0 \in \mathcal{M} \text{) } \{
\begin{align*}
\text{1.} & \quad \text{repeat (10 times) } \{
\begin{align*}
\text{2.} & \quad \text{choice of a distribution } P_0 \text{ in model } M_0 \\
\text{3.} & \quad \text{simulation of a chain } y^n_1 \\n\text{4.} & \quad \text{foreach (} M \in \mathcal{M} \text{) } \{
\begin{align*}
\text{5.} & \quad \text{ordination of a chain } y^n_1 \\
\text{6.} & \quad \text{foreach (} \tilde{n} \in \{25000; 50000; 100000\} \text{) } \{
\begin{align*}
\text{7.} & \quad \text{EM-evaluation of } \sup_P P(y^n_1) \text{ for } P \text{ ranging over } M \\
\text{8.} & \quad \}
\text{9.} & \quad \}
\text{10.} & \quad \}
\end{align*}
\end{align*}
\end{align*}
\}
\end{align*}
\end{align*}
\]
Table 2. EM-evaluated maximum likelihood of the original sequence (length \( n = 25000 \)) for models MCMR of order \((k, m)\) and BIC penalty \( \frac{1}{2}N(k, m)\log n \). The resulting BIC order estimator equals \((2, 1)\).

<table>
<thead>
<tr>
<th>((k, m))</th>
<th>((2, 0))</th>
<th>((3, 0))</th>
<th>((4, 0))</th>
<th>((2, 1))</th>
</tr>
</thead>
<tbody>
<tr>
<td>(\log ML_{k,m}(y^n))</td>
<td>(-34372.5)</td>
<td>(-34197.2)</td>
<td>(-34075.9)</td>
<td>(-33984.3)</td>
</tr>
<tr>
<td>BIC penalty</td>
<td>(40.5)</td>
<td>(75.9)</td>
<td>(121.5)</td>
<td>(131.6)</td>
</tr>
<tr>
<td>pen((n, k, m))</td>
<td>(43.5)</td>
<td>(124.3)</td>
<td>(251.8)</td>
<td>(391.3)</td>
</tr>
</tbody>
</table>

and \(\text{pen}(n, k_0, m_0) = o(n)\).

Let us assume that \(Q_{k,m} = NML_{k,m}\) or \(KT_{k,m}\). Since \(\text{pen}(n, k, m)\) is non-negative, the definition of \((\hat{k}, \hat{m})_n\) readily yields that

\[
\mathbb{P}_0 \left\{ (\hat{k}, \hat{m})_n = (k, m) \text{ i.o.} \right\} \leq \mathbb{P}_0 \left\{ \log ML_{k,m}(Y^n_1) - \log ML_{0}(Y^n_1) \right\} \
\leq \log \frac{ML_{k,m}(Y^n_1)}{Q_{k,m}(Y^n_1)} - \log \frac{ML_{0}(Y^n_1)}{Q_{k_0,m_0}(Y^n_1)} - \text{pen}(n, k_0, m_0) \text{ i.o.} \right\}.
\]

Then, by virtue of Lemma 3.4, it holds that

\[
\frac{1}{n} \max_{y^n_1 \in \mathcal{Y}^n} \left\{ \log \frac{ML_{k,m}(y^n_1)}{Q_{k,m}(y^n_1)} \right\} \to 0, \quad n \to \infty \tag{9}
\]

\[
\frac{1}{n} \max_{y^n_1 \in \mathcal{Y}^n} \left\{ \log \frac{ML_{k_0,m_0}(y^n_1)}{Q_{k_0,m_0}(y^n_1)} \right\} \to 0. \quad n \to \infty \to \infty \tag{10}
\]

The final step is a variant of the so-called Barron’s lemma [11], Theorem 4.4.1: a smart application of the Borel-Cantelli lemma yields that, \(\mathbb{P}_0\)-almost surely,

\[
\liminf_{n \to \infty} \frac{1}{n} \log \mathbb{P}_0(Y^n_1) \geq \liminf_{n \to \infty} \frac{-2 \log n}{n} = 0. \tag{11}
\]

Now, combining (9,10,11) with \(\text{pen}(n, k, m) = o(n)\) ensures the existence of a sequence \(\{\varepsilon_n\}\) of random variables that converge to zero \(\mathbb{P}_0\)-almost surely such that

\[
\mathbb{P}_0 \left\{ (\hat{k}, \hat{m})_n = (k, m) \text{ i.o.} \right\} \leq \mathbb{P}_0 \left\{ \frac{1}{n} \log ML_{k,m}(Y^n_1) - \log \mathbb{P}_0(Y^n_1) \geq \varepsilon_n \text{ i.o.} \right\}. \tag{11}
\]

This concludes the proof of Lemma 3.7.

**B. Appendix B. Proof of Lemma 3.9 for the existence of finite sieves**

Let us set \(k \geq 1\) and \(m \geq 0\) and recall that the cardinality of \(\mathcal{Y}\) is denoted by \(r\). The proof of Lemma 3.9 is a straightforward consequence of the two lemmas below.

**Lemma B.1.** For all \(\delta > 0\), the set of functions \(\theta \mapsto P_\theta(y^n_1)\) indexed by \(n \in \mathbb{N}^*\) and \(y^n_1 \in \mathcal{Y}^n\) is equicontinuous over \(\Theta_{\delta}^{k,m}\).

**Lemma B.2.** For every \(\theta \in \Theta_{\delta}^{k,m}\) and \(\delta > 0\) small enough, there exists \(\theta_{\delta} \in \Theta_{\delta}^{k,m}\) such that, for all \(n \in \mathbb{N}^*\) and \(y^n_1 \in \mathcal{Y}^n\), the following bound holds:

\[
\frac{1}{n} \left[ \log \mathbb{P}_\theta(y^n_1) - \log \mathbb{P}_{\theta_{\delta}}(y^n_1) \right] \leq 2(k^2 + r^2)\delta.
\]


Lemma B.1 is a simple generalization of a result of Liu and Narayan [18] (Lem. 2.6), so we omit its proof. The proof of Lemma B.2 is also adapted from [18] (see their Ex. 2). The details are postponed after the proof of Lemma 3.9.

4 Proof of Lemma 3.9. Let us set $\varepsilon > 0$. According to Lemma B.1, for every $\theta \in \Theta_3^{k,m}$, there exists an open ball $B(\theta_0) \subset \Theta_3^{k,m}$ such that, for every $\theta \in B(\theta_0)$,

$$\sup_{n \in \mathbb{N}^*} \max_{y_1^n \in Y^n} \frac{1}{n} \left| \log P_\theta(y_1^n) - \log P_{\theta_0}(y_1^n) \right| \leq \varepsilon/2.$$  

Since $\Theta_3^{k,m}$ is a compact set, the Borel-Lebesgue property ensures the existence of a finite subset $\{\theta_i : i \in I_\varepsilon\}$ of $\Theta_3^{k,m}$ such that $\cup_{i \in I_\varepsilon} B(\theta_i) = \Theta_3^{k,m}$. Let us denote by $\mathbb{P}_i$ the probability measure $\mathbb{P}_{\theta_i}$ (for each $i \in I_\varepsilon$). In summary, for all $\theta \in \Theta_3^{k,m}$, there exists $i \in I_\varepsilon$ such that

$$\sup_{n \in \mathbb{N}^*} \max_{y_1^n \in Y^n} \frac{1}{n} \left| \log \mathbb{P}_\theta(y_1^n) - \log \mathbb{P}_i(y_1^n) \right| \leq \varepsilon/2. \quad (12)$$

Let us set $\delta = \varepsilon/[4(k^2 + r^2)]$. By virtue of Lemma B.2, for every $\theta \in \Theta_3^{k,m}$, there exists $\theta_\delta \in \Theta_3^{k,m}$ such that

$$\sup_{n \in \mathbb{N}^*} \max_{y_1^n \in Y^n} \frac{1}{n} \left| \log \mathbb{P}_\theta(y_1^n) - \log \mathbb{P}_{\theta_\delta}(y_1^n) \right| \leq 2(k^2 + r^2)\delta \leq \varepsilon/2. \quad (13)$$

Combining (12,13) concludes the proof. \hfill \Box

5 Proof of Lemma B.2. Set $\theta = (A, B) \in \Theta_3^{k,m}$ (see Definition 2 for the decomposition of parameter $\theta$) and $\delta > 0$.

The parameter $\theta_\delta$ is constructed in the following way.

For each row $i \in \{1, \ldots, k\}$ of matrix $A$, replace the maximal coefficient $a(i, j_{\text{max}})$ by $a(i, j_{\text{max}}) - (k-1)\delta$, then add $\delta$ to the other coefficients of this row. This yields the new parameter $A_\delta$. Moreover, for each fixed “row” $(t^m; x) \in Y^m \times X$, replace the maximal coefficient of matrix $B$, namely $b(j_{\text{max}}|t^m; x)$, by $b(j_{\text{max}}|t^m; x) - (r-1)\delta$, then add $\delta$ to the other coefficients.

It is easily checked that the constructed parameter $\theta_\delta = (A_\delta, B_\delta)$ belongs to $\Theta_3^{k,m}$ for $\delta \leq 1/\max(k^2, r^2)$. Besides, it is also readily seen that, for all $i, j \in \{1, \ldots, k\}$ and $(t^m; x) \in Y^m \times X$,

$$a(i; j) \leq \frac{a(i; j)}{1 - k^2\delta} \quad \text{and} \quad b(j|t^m; x) \leq \frac{b(j|t^m; x)}{1 - r^2\delta}.$$  

Therefore, for all $n \in \mathbb{N}^*$ and $y_1^n \in Y^n$,

$$P_\theta(y_1^n) \leq P_{\theta_\delta}(y_1^n)(1 - k^2\delta)^{-n}(1 - r^2\delta)^{-n},$$

hence

$$\frac{1}{n} \left| \log P_\theta(y_1^n) - \log P_{\theta_\delta}(y_1^n) \right| \leq - \log(1 - k^2\delta) - \log(1 - r^2\delta).$$

This concludes the proof, because $- \log(1 - u) \leq 2u$ for any $u$ small enough. \hfill \Box

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References


