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Poisson Point Processes Applied to Sensor Networks

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Motivation

The development of wireless ad hoc networking capability together with the decreasing costs and sizes of the electronical circuits allow an increasing using of sensor networks in building, utilities, industrial, home, agriculture, defense and many other contexts. The topology of such networks, particularly the connectiveness and coverage area, are important and, sometimes, critical factors. Recently, many works dealing with topology give interpretations and techniques capable to be applied on sensor networks. Besides, it is not possible to control the positions and number of sensors in many of those networks, which lead us to study the topology of random sensor networks by using the Poisson point processes.

> dimensions of the sensor are considered too reduced compared to the system, so the position of the sensor S_i is given by $x_i \in \mathbb{T}_a^d = (u_{i,1},...,u_{d,i})$, $u_{d,k} \in [0,a]$;

- A sensor receives the ID's from all other sensors closer then a deterministic distance ϵ , so if $||x_i - x_j|| \leq \epsilon$, sensors S_i and S_i are directly connected;
- We use the maximum norm, i.e.,

 $\|x_i - x_j\| = \max_i$ \boldsymbol{k} $(u_{i,k}-u_{j,k})$

Random Features of the System

Problem Formulation

The principal idea of the problem is that sensors $\{S_1, S_2, ..., S_n\}$ have a power suply allowing them to transmit theirs ID's and maybe some environmental information (such as temperature, pression, presence/absence of an element etc). At the same time, the sensors have receivers which can identify the transmitted ID's of other sensors above a threshold power. The sensors, knowing theirs ID's and the ID's of the close neighbors, create an information network.

 β_d denotes the number of d-dimensional holes. Particularly, β_0 , β_1 and β_2 measure, respectively, the connectiveness, the number of holes and the number of voids of a complex.

Physical Features of the System

• The sensors lie over a *d*-torus \mathbb{T}_a^d and the

 $0.25 \, \sqsubset$ Comparison between the calculations and the simulations

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Simplicial Homology

Simplicial complexes are structures composed by elements named simplices, which can be seen by d-dimensional filled spaces. Exemples of simplexes are given below:

Since a compensated Poisson point process can be seen as a martingale, we can use a concentration inequality to find a superior limit for $P(\beta_0 \ge c)$ in two dimensions

Results: Mean of k-simplexes, $\overline{s_k}$, and Euler's Characteristic, $\overline{\chi}$

It is possible to calculate the mean of k-simplices given the size of individual coverage ϵ , the density of sensors λ , the dimension d and the sizes of the d-torus, a :

 $\overline{s_{k-1}} =$ $\lambda^k a^d$ $k!$ k^d (ϵ $\left(k-1\right) ^{d},\quad\epsilon< a/3$

Below, we present the variation of $\overline{s_k}$ in function of ϵ for $a = 100$ and $\lambda = 0.10$ in two dimensions.

We can represent the topology of a sensor network by its Rips complex, which is obtained when we consider that whenever $k + 1$ points are 2 by 2 closer than ϵ between them, they create a k-simplex.

• The number of sensors lying over on \mathbb{T}_a^d $\frac{d}{a}$ / $\Phi(t)$, is distributed as poisson with mean λa^d , where λ is a constant in the model. Indeed, λ represent the density of sensors;

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Let B_d be the Bell's polynomial. Using the mean of k-simplexes, we can calculate the mean of the Euler's Characteristic χ :

The variation of $\overline{\chi}$ in function of λ is presented following, for $d = 1$, $d = 2$ and $d = 3$:

Based on simulations and analytical expressions, we can conjecture that, given a density of points, there are at most two dominating types of holes.

Results: Concentration Inequality

Interpreting a Sensor Network

References

- [1] R. Ghrist, A. Muhammad. Coverage and Hole-Detection in Sensor Networks Via Homology In *Fourth International Conference on Information Processing in Sensor Networks (IPSN'05), UCLA*, 2005.
- [2] C. Houdré, N. Privault. Concentration and deviation inaqualities in infinite dimensions via covariance representations *Bernoulli*, 2002.

Conjecture: β_i dominance region

• The distribution of the position of each sensor is independent of the other sensors and given by

