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Probabilistic Automata on Finite Words: Decidable and Undecidable Problems

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Abstract. This paper tackles three algorithmic problems for probabilistic automata on finite words: the Emptiness Problem, the Isolation Problem and the Value 1 Problem. The *Emptiness Problem* asks, given some probability $0 \leq \lambda \leq 1$, whether there exists a word accepted with probability greater than λ , and the *Isolation Problem* asks whether there exist words whose acceptance probability is arbitrarily close to λ . Both these problems are known to be undecidable [8, 2, 3]. About the Emptiness problem, we provide a new simple undecidability proof and prove that it is decidable for automata with one probabilistic transition and undecidable for automata with as few as two probabilistic transitions. The *Value 1 Problem* is the special case of the Isolation Problem when $\lambda = 1$ or $\lambda = 0$. The decidability of the Value 1 Problem was an open question. We show that the Value 1 Problem is undecidable. Moreover, we introduce a new class of probabilistic automata, \sharp -acyclic automata, for which the Value 1 Problem is decidable.

Introduction

Probabilistic automata on finite words are a computation model introduced by Rabin [10]. Like deterministic automata on finite words, a probabilistic automaton reads finite words from a finite alphabet A . Each time a new letter $a \in A$ is read, a transition from the current state $s \in Q$ to a new state $t \in Q$ occurs. In a deterministic automaton, t is a function of s and a . In a probabilistic automaton, a lottery determines the new state, according to transition probabilities which depend on the current state s and letter a .

Since the seminal paper of Rabin, probabilistic automata on finite words have been extensively studied, see [4] for a survey of 416 papers and books about probabilistic automata published in the 60s and 70s.

Quite surprisingly, relatively few *algorithmic* results are known about probabilistic automata on finite words and almost all of them are undecidability results. There are two main algorithmic problems for probabilistic automata on finite words: the Emptiness Problem and the Isolation Problem. The *Emptiness Problem* asks, given some probability $0 \leq \lambda \leq 1$, whether there exists a word accepted with probability greater than λ , while the *Isolation Problem*

asks whether there exist words whose acceptance probability is arbitrarily close to λ . Both these problems were shown undecidable, respectively by Paz [8] and Bertoni [2, 3]. To our knowledge, the known decidability results known for probabilistic automata on finite words are rather straightforward: they either apply to one-letter probabilistic automata, in other words Markov chains, or to problems where the probabilistic nature of the automaton is not taken into account.

In contrast, several algorithmic results recently appeared for probabilistic automata on *infinite* words. In [1], Baier et al. proved that for probabilistic Büchi automata, the emptiness problem may be undecidable (when the acceptance condition is "positive Büchi") or decidable (for "almost-sure Büchi"). In [9] is presented a class of probabilistic Büchi automata which recognize exactly ω -regular languages. In this paper, we only consider automata on finite words but several of our results seem to be extendable to probabilistic automata on infinite words.

Our contributions are the following.

First, we provide in Section 2.1 a new proof for the undecidability of the Emptiness Problem.

Second, we strengthen Paz result: the Emptiness Problem is undecidable even for automata with as few as two probabilistic transitions (Proposition 4) and is decidable for automata with one probabilistic transition (Proposition 3).

Third, we solve an open problem: Bertoni's result shows that for any fixed cut-point $0 < \lambda < 1$, the Isolation Problem is undecidable. However, as stated by Bertoni himself, the proof seems hardly adaptable to the symmetric cases $\lambda = 0$ and $\lambda = 1$. We show that both these cases are undecidable as well, in other words the Value 1 Problem is undecidable (Theorem 4).

Fourth, we introduce a new class of probabilistic automata, \sharp -acyclic automata, for which the Value 1 Problem is decidable (Theorem 5). To our knowledge, this is the first non-immediate decidability result for probabilistic automata on finite words. Moreover, we believe this is a first interesting step towards the design of classes of stochastic games with partial observation for which the value 1 problem is decidable.

These undecidability results show once again that probabilistic automata are very different from deterministic and non-deterministic automata on finite or infinite words, for which many algorithmic problems are known to be decidable (e.g. emptiness, universality, equivalence). Surprisingly maybe, we remark that several natural decision problems about deterministic and non-deterministic automata are undecidable as well (Corollaries 1 and 2).

1 Probabilistic Automata

A probability distribution on Q is a mapping $\delta \in [0, 1]^Q$ such that $\sum_{s \in S} \delta(s) = 1$. The set $\{s \in Q \mid \delta(s) > 0\}$ is called the support of δ and denoted $\text{Supp}(\delta)$. For every non-empty subset $S \subseteq Q$, we denote δ_S the uniform distribution on S defined by $\delta(q) = 0$ if $q \notin S$ and $\delta(q) = \frac{1}{|S|}$ if $q \in S$. We denote $\mathcal{D}(Q)$ the set of probability distributions on Q .

Formally, a probabilistic automaton is a tuple $\mathcal{A} = (Q, A, (M_a)_{a \in A}, q_0, F)$, where Q is a finite set of states, A is the finite input alphabet, $(M_a)_{a \in A}$ are the transition matrices, q_0 is the initial state and F is the set of accepting states. For each letter $a \in A$, $M_a \in [0, 1]^{Q \times Q}$ defines transition probabilities: $0 \leq M_a(s, t) \leq 1$ is the probability to go from state s to state t when reading letter a . Of course, for every $s \in S$ and $a \in A$, $\sum_{t \in S} M_a(s, t) = 1$, in other word in the matrix M_a , the line with index s is a probability distribution on Q .

Transition matrices define a natural action of A^* on $\mathcal{D}(Q)$. For every word $a \in A$ we denote $\delta \cdot a$ the probability distribution in $\mathcal{D}(Q)$ defined by $(\delta \cdot a)(t) = \sum_{s \in Q} \delta(s) \cdot M_a(s, t)$. This action extends naturally to words of A^* : $\forall w \in A^*, \forall a \in A, \delta \cdot (wa) = (\delta \cdot w) \cdot a$.

The computation of \mathcal{A} on an input word $w = a_0 \dots a_n \in A^*$ is the sequence $(\delta_0, \delta_1, \dots, \delta_n) \in \mathcal{D}(Q)^{n+1}$ of probability distributions over Q such that $\delta_0 = \delta_{\{q_0\}}$ and for $0 \leq i < n, \delta_{i+1} = \delta_i \cdot a_i$.

For every state $q \in Q$ and for every set of states $R \subseteq Q$, we denote $\mathbb{P}_{\mathcal{A}}(q \xrightarrow{w} R) = \sum_{r \in R} (\delta_q \cdot w)(r)$ the probability to reach the set R from state q when reading the word w .

Definition 1 (Value and acceptance probability). *The acceptance probability of a word $w \in A^*$ by \mathcal{A} is $\mathbb{P}_{\mathcal{A}}(w) = \mathbb{P}_{\mathcal{A}}(q_0 \xrightarrow{w} F)$. The value of \mathcal{A} , denoted $val(\mathcal{A})$, is the supremum acceptance probability: $val(\mathcal{A}) = \sup_{w \in A^*} \mathbb{P}_{\mathcal{A}}(w)$.*

2 The Emptiness Problem

Rabin defined the language recognized by a probabilistic automaton as $\mathcal{L}_{\mathcal{A}}(\lambda) = \{w \in A^* \mid \mathbb{P}_{\mathcal{A}}(w) \geq \lambda\}$, where $0 \leq \lambda \leq 1$ is called the cut-point. Hence, a canonical decision problem for probabilistic automata is:

Problem 1 (Emptiness Problem) *Given a probabilistic automaton \mathcal{A} and $0 \leq \lambda \leq 1$, decide whether there exists a word w such that $\mathbb{P}_{\mathcal{A}}(w) \geq \lambda$.*

The *Strict Emptiness Problem* is defined the same way except the large inequality $\mathbb{P}_{\mathcal{A}}(w) \geq \frac{1}{2}$ is replaced by a strict inequality $\mathbb{P}_{\mathcal{A}}(w) > \frac{1}{2}$.

The special cases where $\lambda = 0$ and $\lambda = 1$ provide a link between probabilistic and non-deterministic automata on finite words. First, the Strict Emptiness Problem for $\lambda = 0$ reduces to the emptiness problem of non-deterministic automata, which is decidable in non-deterministic logarithmic space. Second, the Emptiness Problem for $\lambda = 1$ reduces to the universality problem for non-deterministic automata, which is PSPACE-complete [6]. The two other cases are trivial: the answer to the Emptiness Problem for $\lambda = 0$ is always yes and the answer to the Strict Emptiness Problem for $\lambda = 1$ is always no.

In the case where $0 < \lambda < 1$, both the Emptiness and the Strict Emptiness Problems are undecidable, this was proved by Paz [8]. The proof of Paz is a reduction of the Emptiness Problem to an undecidable problem about free context grammars. An alternative proof was given by Madani, Hanks and Condon [7], based on a reduction to the emptiness problem for two counter machines. Since

Paz was focusing on expressiveness aspects of probabilistic automata rather than on algorithmic questions, his undecidability proof is spread on the whole book [8], which makes it arguably hard to read. The proof of Madani et al. is easier to read but quite long and technical.

In the next section, we present a new simple undecidability proof of the Emptiness Problem.

2.1 New proof of undecidability

In this section we show the undecidability of the (Strict) Emptiness Problem for the cut-point $\frac{1}{2}$ and for a restricted class of probabilistic automata called *simple* probabilistic automata:

Definition 2 (Simple automata). *A probabilistic automaton is called simple if every transition probability is in $\{0, \frac{1}{2}, 1\}$.*

The proof is based on a result of Bertoni [2]: the undecidability of the Equality Problem.

Problem 2 (Equality problem) *Given a simple probabilistic automaton \mathcal{A} , decide whether there exists a word $w \in A^*$ such that $\mathbb{P}_{\mathcal{A}}(w) = \frac{1}{2}$.*

Proposition 1 (Bertoni). *The equality problem is undecidable.*

The short and elegant proof of Bertoni is a reduction of the Post Correspondence Problem (PCP) to the Equality Problem.

Problem 3 (PCP) *Let $\varphi_1 : A \rightarrow \{0, 1\}^*$ and $\varphi_2 : A \rightarrow \{0, 1\}^*$ two functions, naturally extended to A^* . Is there a word $w \in A^*$ such that $\varphi_1(w) = \varphi_2(w)$?*

Roughly speaking, the proof of Proposition 1 consists in encoding the equality of two words in the decimals of transition probabilities of a well-chosen probabilistic automaton. While the reduction of PCP to the Equality problem is relatively well-known, it may be less known that there exists a simple reduction of the Equality problem to the Emptiness and Strict Emptiness problems:

Proposition 2. *Given a simple probabilistic automaton \mathcal{A} , one can compute probabilistic automata \mathcal{B} and \mathcal{C} whose transition probabilities are multiple of $\frac{1}{4}$ and such that:*

$$\left(\exists w \in A^+, \mathbb{P}_{\mathcal{A}}(w) = \frac{1}{2} \right) \iff \left(\exists w \in A^+, \mathbb{P}_{\mathcal{B}}(w) \geq \frac{1}{4} \right) \quad (1)$$

$$\iff \left(\exists w \in A^+, \mathbb{P}_{\mathcal{C}}(w) > \frac{1}{8} \right) . \quad (2)$$

Proof. The construction of \mathcal{B} such that (1) holds is based on a very simple fact: a real number x is equal to $\frac{1}{2}$ if and only if $x(1-x) \geq \frac{1}{4}$. Consider the automaton \mathcal{B} which is the cartesian product of \mathcal{A} with a copy of \mathcal{A} whose accepting states

are the non accepting states of \mathcal{A} . Then for every word $w \in A^*$, $\mathbb{P}_{\mathcal{A}_1}(w) = \mathbb{P}_{\mathcal{A}}(w)(1 - \mathbb{P}_{\mathcal{A}}(w))$, thus (1) holds.

The construction of \mathcal{C} such that (2) holds is based on the following idea. Since \mathcal{A} is simple, transition probabilities of \mathcal{B} are multiples of $\frac{1}{4}$, thus for every word w of length $|w|$, $\mathbb{P}_{\mathcal{B}}(w)$ is a multiple of $\frac{1}{4^{|w|}}$. As a consequence, $\mathbb{P}_{\mathcal{B}}(w) \geq \frac{1}{4}$ if and only if $\mathbb{P}_{\mathcal{B}}(w) > \frac{1}{4} - \frac{1}{4^{|w|}}$. Adding three states to \mathcal{B} , one obtains easily a probabilistic automaton \mathcal{C} such that for every non-empty word $w \in A^*$ and letter $a \in A$, $\mathbb{P}_{\mathcal{C}}(aw) = \frac{1}{2} \cdot \mathbb{P}_{\mathcal{B}}(w) + \frac{1}{2} \cdot \frac{1}{4^{|w|}}$, thus (2) holds. To build \mathcal{C} , simply add a new initial state that goes with equal probability $\frac{1}{2}$ either to the initial state of \mathcal{B} or to a new accepting state q_f . From q_f , whatever letter is read, next state is q_f with probability $\frac{1}{4}$ and with probability $\frac{3}{4}$ it is a new non-accepting absorbing sink state q_* . \square

As a consequence:

Theorem 1 (Paz). *The emptiness and the strict emptiness problems are undecidable for probabilistic automata. These problems are undecidable even for simple probabilistic automata and cut-point $\lambda = \frac{1}{2}$.*

To conclude this section, we present another connection between probabilistic and non-probabilistic automata on finite words.

Corollary 1. *The following problem is undecidable. Given a non-deterministic automaton on finite words, does there exist a word such that at least half of the computations on this word are accepting?*

At first, there is no obvious connection between this automata-theoretic decision problem and probabilities. However we do not know a simple undecidability proof for this problem that does not make use of probabilistic automata.

2.2 Probabilistic automata with few probabilistic transitions

Hirvensalo showed that the emptiness problem is undecidable for probabilistic automata which have as few as 2 input letters and 25 states [5].

On the other hand, the emptiness problem is decidable for *deterministic* automata. This holds whatever be the number of states, as long as there are no probabilistic transition in the automaton. Formally, a probabilistic transition is a couple (s, a) of a state $s \in S$ and a letter $a \in A$ such that for at least one state $t \in S$, $0 < M_a(s, t) < 1$.

This motivates the following question: *what is the minimal number of probabilistic transitions for which the emptiness problem is undecidable?*

The answer to this question is somewhat surprising: the emptiness problem is decidable for automaton with *one* probabilistic transition (Proposition 3) but undecidable for automaton with as few as *two* probabilistic transitions (Proposition 5).

Proposition 3. *The emptiness problem for automata with one probabilistic transition is decidable and PSPACE-complete. It is decidable in PTIME for automata with bounded outdegree.*

A slight variant of the emptiness problem for probabilistic automata with one probabilistic transition is undecidable:

Proposition 4. *The following problem is undecidable: given a simple probabilistic automaton over an alphabet A with one probabilistic transition and given a rational language of finite words $L \subseteq A^*$, decide whether $\mathbb{P}_{\mathcal{A}}(w) \geq \frac{1}{2}$ for some word $w \in L$.*

A simple corollary of Proposition 4 is the following undecidability result:

Proposition 5. *The emptiness problem is undecidable for probabilistic automata with two probabilistic transitions.*

Thus, the undecidability border is easily crossed when working with probabilistic automata.

3 The Value 1 Problem

In this section like in the previous one we give yet another way to cross the undecidability border, this time we follow the road of the value 1-problem.

3.1 Undecidability of the Value 1 problem

In his seminal paper about probabilistic automata [10], Rabin introduced the notion of *isolated cut-points*.

Definition 3. *A real number $0 \leq \lambda \leq 1$ is an isolated cut-point with respect to a probabilistic automaton \mathcal{A} if:*

$$\exists \varepsilon > 0, \forall w \in A^*, |\mathbb{P}_{\mathcal{A}}(w) - \lambda| \geq \varepsilon .$$

Rabin motivates the introduction of this notion by the following theorem:

Theorem 2 (Rabin). *Let \mathcal{A} a probabilistic automaton and $0 \leq \lambda \leq 1$ a cut-point. If λ is isolated then the language $\mathcal{L}_{\mathcal{A}}(\lambda) = \{u \in A^* \mid \mathbb{P}_{\mathcal{A}}(u) \geq \lambda\}$ is rational.*

This result suggests the following decision problem.

Problem 4 (Isolation Problem) *Given a probabilistic automaton \mathcal{A} and a cut-point $0 \leq \lambda \leq 1$, decide whether λ is isolated with respect to \mathcal{A} .*

Bertoni [2] proved that the Isolation Problem is undecidable in general:

Theorem 3 (Bertoni). *The Isolation Problem is undecidable for probabilistic automata with five states.*

A closer look at the proof of Bertoni shows that the Isolation Problem is undecidable for a fixed λ , provided that $0 < \lambda < 1$.

However the same proof does not seem to be extendable to the cases $\lambda = 0$ and $\lambda = 1$. This was pointed out by Bertoni in the conclusion of [2]:

”Is the following problem solvable: $\exists \delta > 0, \forall x, (p(x) > \delta)$? For automata with 1-symbol alphabet, there is a decision algorithm bound with the concept of transient state [8]. We believe it might be extended but have no proof for it”.

The open question mentioned by Bertoni is the Isolation Problem for $\lambda = 0$. The case $\lambda = 1$ is essentially the same, since 0 is isolated in an automaton \mathcal{A} if and only if 1 is isolated in the automaton obtained from \mathcal{A} by turning final states to non-final states and vice-versa. When $\lambda = 1$, the Isolation Problem asks whether there exists some word accepted by the automaton with probability arbitrarily close to 1. We use the game-theoretic terminology and call this problem the Value 1 Problem.

The open question of Bertoni can be rephrased as the decidability of the following problem:

Problem 5 (Value 1 Problem) *Given a probabilistic automaton \mathcal{A} , decide whether \mathcal{A} has value 1.*

Unfortunately,

Theorem 4. *The Value 1 Problem is undecidable.*

The proof of Theorem 4 is a reduction of the Strict Emptiness Problem to the Value 1 Problem. It is similar to the proof of undecidability of the Emptiness Problem for probabilistic Büchi automata of Baier et al. [1]. The core of the proof is the following proposition.

Proposition 6. *Let $0 < x < 1$ and \mathcal{A}_x be the probabilistic automaton depicted on Fig. 1. Then \mathcal{A}_x has value 1 if and only if $x > \frac{1}{2}$.*

The proof of Theorem 4 relies on the fact that there is a natural way to combine \mathcal{A}_x with an arbitrary automaton \mathcal{B} so that the resulting automaton has value 1 if and only if some word is accepted by \mathcal{B} with probability strictly greater than $\frac{1}{2}$.

The value 1 problem for simple probabilistic automata can be straightforwardly rephrased as a ”quantitative” decision problem about non-deterministic automaton on finite words, which shows that:

Corollary 2. *This decision problem is undecidable: given a non-deterministic automaton on finite words, does there exist words such that the proportion of non-accepting computation paths among all computation paths is arbitrarily small?*

4 The class of \sharp -acyclic probabilistic automata

In this section, we introduce a new class of probabilistic automata, \sharp -acyclic probabilistic automata, for which the value 1 problem is decidable.

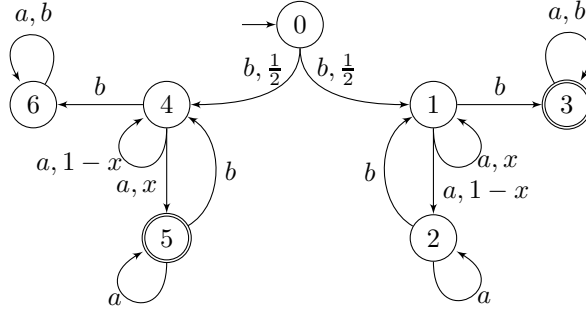


Fig. 1. This automaton has value 1 if and only if $x > \frac{1}{2}$.

To get a decision algorithm for the value 1 problem, our starting point is the usual subset construction for non-deterministic automata, defined by mean of the natural action of letters on subsets of Q . However the quantitative aspect of the Value 1 Problem stressed in Corollary 2 suggests that the subset construction needs to be customized. Precisely, we use not only the usual action $S \cdot a$ of a letter a on a subset $S \subseteq Q$ of states but consider also another action a^\sharp . Roughly speaking, a^\sharp deletes states that are transient when reading letter a forever.

Definition 4 (Actions of letters and \sharp -reachability). Let \mathcal{A} a probabilistic automaton with alphabet A and set of states Q . Given $S \subseteq Q$ and $a \in A$, we denote:

$$S \cdot a = \{t \in Q \mid \exists s \in S, M_a(s, t) > 0\} .$$

A state $t \in Q$ is a -reachable from $s \in Q$ if for some $n \in \mathbb{N}$, $\mathbb{P}_{\mathcal{A}}(s \xrightarrow{a^n} t) > 0$. A state $s \in Q$ is a -recurrent if for any state $t \in Q$,

$$(t \text{ is } a\text{-reachable from } s) \implies (s \text{ is } a\text{-reachable from } t) .$$

A set $S \subseteq Q$ is a -stable if $S = S \cdot a$. If S is a -stable, we denote:

$$S \cdot a^\sharp = \{s \in S \mid s \text{ is } a\text{-recurrent}\} .$$

The support graph $\mathcal{G}_{\mathcal{A}}$ of a probabilistic automaton \mathcal{A} with alphabet A and set of states Q is the directed graph whose vertices are the non-empty subsets of Q and whose edges are the pairs (S, T) such that for some letter $a \in A$, either $(S \cdot a = T)$ or $(S \cdot a = S \text{ and } S \cdot a^\sharp = T)$.

Reachability in the support graph of \mathcal{A} is called \sharp -reachability in \mathcal{A} .

The class of \sharp -acyclic probabilistic automata is defined as follows.

Definition 5 (\sharp -acyclic probabilistic automata). A probabilistic automaton is \sharp -acyclic if the only cycles in its support graph are self-loops.

Obviously, this acyclicity condition is quite strong. However, it does not forbid the existence of cycles in the transition table, see for example the automaton depicted on Fig. 2. Note also that the class of \sharp -acyclic automata enjoys good properties: it is closed under cartesian product and parallel composition.

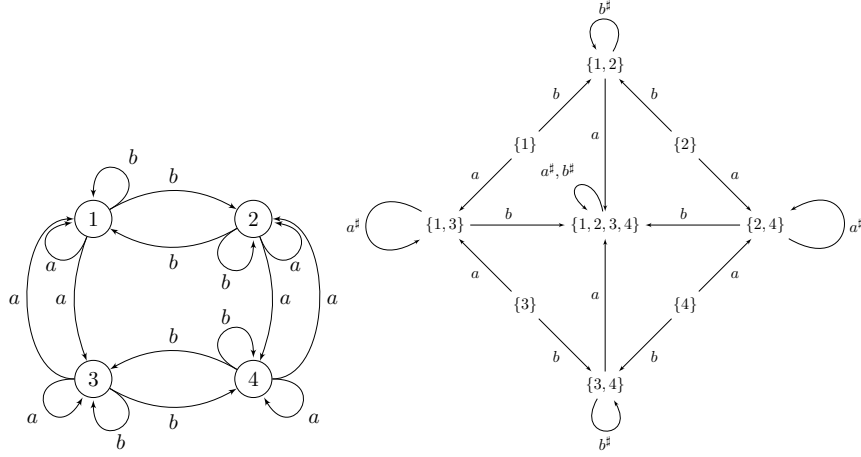


Fig. 2. A $\#$ -acyclic automaton (on the left) and its support graph (on the right). All transition probabilities are equal to $\frac{1}{2}$.

4.1 The value 1 problem is decidable for $\#$ -acyclic automata

For $\#$ -acyclic probabilistic automata, the value 1 problem is decidable:

Theorem 5. *Let \mathcal{A} be a probabilistic automaton with initial state q_0 and final states F . Suppose that \mathcal{A} is $\#$ -acyclic. Then \mathcal{A} has value 1 if and only if F is $\#$ -reachable from $\{q_0\}$ in \mathcal{A} .*

The support graph can be computed on the fly in polynomial space thus deciding whether a probabilistic automaton is $\#$ -acyclic and whether an $\#$ -acyclic automaton has value 1 are PSPACE decision problems.

The rest of this section is dedicated to the proof of Theorem 5. This proof relies on the notion of limit-paths.

Definition 6 (Limit paths and limit-reachability). *Let \mathcal{A} be a probabilistic automaton with states Q and alphabet A . Given two subsets S, T of Q , we say that T is limit-reachable from S in \mathcal{A} if there exists a sequence $w_0, w_1, w_2, \dots \in A^*$ of finite words such that for every state $s \in S$:*

$$\mathbb{P}_{\mathcal{A}}(s \xrightarrow{w_n} T) \xrightarrow[n \rightarrow \infty]{} 1 .$$

The sequence w_0, w_1, w_2, \dots is called a limit path from S to T , and T is said to be limit-reachable from S in \mathcal{A} .

In particular, an automaton has value 1 if and only if F is limit-reachable from $\{q_0\}$.

To prove Theorem 5, we show that in $\#$ -acyclic automata, $\#$ -reachability and limit-reachability coincide. The following proposition shows that $\#$ -reachability always imply limit-reachability, may the automaton be $\#$ -acyclic or not.

Proposition 7. Let \mathcal{A} be a probabilistic automaton with states Q and $S, T \subseteq Q$. If T is \sharp -reachable from S in \mathcal{A} then T is limit-reachable from S in \mathcal{A} .

The converse implication is not true in general. For example, consider the automaton depicted on Fig. 3. There is only one final state, state 3. The initial state is not represented, it leads with equal probability to states 1, 2 and 3. The transitions from states 1, 2 and 3 are either deterministic or have probability $\frac{1}{2}$.

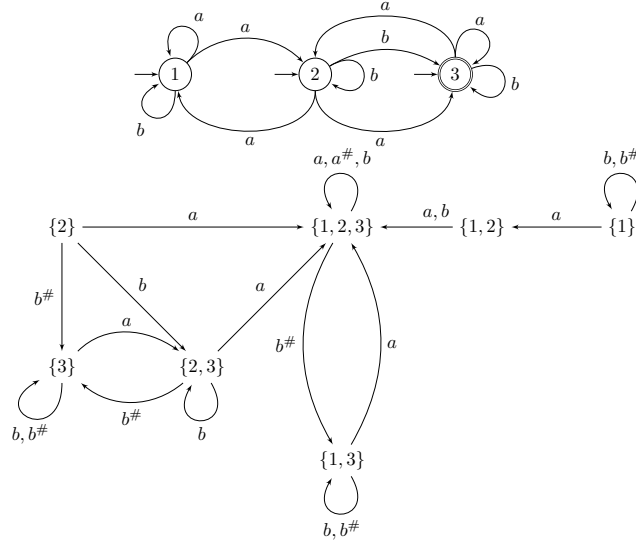


Fig. 3. This automaton has value 1 and is not \sharp -acyclic .

It turns out that the automaton on Fig. 3 has value 1, because $((b^n a)^n)_{n \in \mathbb{N}}$ is a limit-path from $\{1, 2, 3\}$ to $\{3\}$. However, $\{3\}$ is *not* reachable from $\{1, 2, 3\}$ in the support graph. Thus, limit-reachability does not imply \sharp -reachability in general. This automaton is *not* \sharp -acyclic, because his support graph contains a cycle of length 2 between $\{1, 2, 3\}$ and $\{1, 3\}$. It is quite tempting to add an edge labelled $(ab^\sharp)^\sharp$ between $\{1, 3\}$ and $\{3\}$.

Now we prove that for \sharp -acyclic automata, limit-reachability implies \sharp -reachability.

Definition 7 (Stability and \sharp -stability). Let \mathcal{A} be a probabilistic automaton with states Q . The automaton \mathcal{A} is stable if for every letter $a \in A$, Q is a -stable. A stable automaton \mathcal{A} is \sharp -stable if for every letter $a \in A$ $Q \cdot a^\sharp = Q$.

The proof relies on the blowing, the flooding and the leaf lemmas.

Lemma 1 (Blowing lemma). Let \mathcal{A} be a \sharp -acyclic probabilistic automaton with states Q and $S \subseteq Q$. Suppose that \mathcal{A} is \sharp -acyclic and \sharp -stable. If Q is limit-reachable from S in \mathcal{A} , then Q is \sharp -reachable from S as well.

Proof (of the blowing lemma). If $S = Q$ there is nothing to prove. If $S \neq Q$, we prove that there exists $S_1 \subseteq Q$ such that (i) S_1 is \sharp -reachable from S , (ii) $S \subsetneq S_1$, and (iii) Q is limit-reachable from S_1 . Since $S \subsetneq Q$ and since there exists a limit-path from S to Q there exists at least one letter a such that S is not a -stable, i.e. $S \cdot a \not\subseteq S$. Since \mathcal{A} is subset-acyclic, there exists $n \in \mathbb{N}$ such that $S \cdot a^{n+1} = S \cdot a^n$ i.e. $S \cdot a^n$ is a -stable. Let $S_1 = (S \cdot a^n) \cdot a^\sharp$. Then (i) is obvious.

To prove (ii), we prove that S_1 contains both S and $S \cdot a$. Let $s \in S$. By definition, every state t of $S \cdot a^n$ is a -accessible from s . Since \mathcal{A} is \sharp -stable, state s is a -recurrent and by definition of a -recurrence, s is a -accessible from t . Since $t \in S \cdot a^n$ and $S \cdot a^n$ is a -stable, $s \in S \cdot a^n$ and since s is a -recurrent $s \in (S \cdot a^n) \cdot a^\sharp = S_1$. The proof that $S \cdot a \subseteq S_1$ is similar.

If $S_1 = Q$ the proof is complete, because (i) holds. If $S_1 \subsetneq Q$, then (iii) holds because $S \subseteq S_1$ thus Q is limit-reachable not only from S but from S_1 as well, using the same limit-path. As long as $S_n \neq Q$, we use (iii) to build inductively an increasing sequence $S \subsetneq S_1 \subsetneq S_2 \subsetneq \dots \subsetneq S_n = Q$ such that for every $1 \leq k < n$, S_{k+1} is \sharp -reachable from S_k . Since \sharp -reachability is transitive this completes the proof of the blowing lemma. \square

Second, in a \sharp -stable and \sharp -acyclic automata, once a computation has flooded the whole state space, it cannot shrink back.

Lemma 2 (Flooding lemma). *Let \mathcal{A} be a probabilistic automaton with states Q . Suppose that \mathcal{A} is \sharp -acyclic and \sharp -stable. Then Q is the only set of states limit-reachable from Q in \mathcal{A} .*

Now, we turn our attention to leaves of the acyclic support graph.

Definition 8. *Let \mathcal{A} be a probabilistic automaton with states Q . A non-empty subset $R \subseteq Q$ is called a leaf if for every letter $a \in A$, $R \cdot a = R$ and $R \cdot a^\sharp = R$.*

In a stable \sharp -acyclic automaton, there is a unique leaf:

Lemma 3 (Leaf lemma). *Let \mathcal{A} be a probabilistic automaton with states Q . Suppose that \mathcal{A} is \sharp -acyclic and stable. Then there exists a unique leaf \sharp -accessible from Q . Every set limit-reachable from Q contains this leaf.*

Proof (of the leaf lemma). Since \mathcal{A} is \sharp -acyclic, there exists at least one leaf S which is \sharp -reachable from Q .

We prove that every set limit-reachable from Q contains the leaf S . Let R limit-reachable from Q and $(u_n)_{n \in \mathbb{N}}$ a limit-path from Q to R . Since for every $a \in A$, S is a -stable, then a fortiori $(u_n)_{n \in \mathbb{N}}$ is a limit-path from S to $R \cap S$. Since S is a leaf, the restriction $\mathcal{A}[S]$ of the automaton \mathcal{A} to S is \sharp -stable. According to the flooding lemma applied to $\mathcal{A}[S]$, $S = R \cap S$, thus $S \subseteq R$. Since \sharp -reachability imply limit-reachability, this implies unicity of the leaf reachable from Q . \square

To prove that limit-reachability implies \sharp -reachability, we proceed by induction on the depth in the support graph. The inductive step is:

Lemma 4 (Inductive step). *Let \mathcal{A} be a probabilistic automaton with states Q and $S_0, T \subseteq Q$. Suppose that \mathcal{A} is \sharp -acyclic and T is limit-reachable from S_0 . Then either $S_0 = T$ or there exists $S_1 \neq S_0$ such that S_1 is \sharp -reachable from S_0 in \mathcal{A} and T is limit-reachable from S_1 in \mathcal{A} .*

Repeated use of Lemma 4 gives:

Proposition 8. *Let \mathcal{A} be a probabilistic automaton with states Q and $S_0, T \subseteq Q$. Suppose that \mathcal{A} is \sharp -acyclic. If T is limit-reachable from S_0 in \mathcal{A} , then T is \sharp -reachable from S_0 as well.*

Thus, limit-reachability and \sharp -reachability coincide in \sharp -acyclic automata and Theorem 5 holds.

Is the maximal distance between two \sharp -reachable sets in the support graph bounded by a polynomial function of $|A|$ and $|Q|$? The answer to this question could lead to a simpler proof and/or algorithm.

Conclusion

The class of \sharp -acyclic automata can be probably extended to a larger class of automata for which the value 1 problem is still decidable. Another interesting research direction is to find classes of automata for which the emptiness problem is decidable, unfortunately this is not the case for \sharp -acyclic automata.

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Appendix

Proof (of Proposition 1). Given any instance $\varphi_1, \varphi_2 : A \rightarrow \{0, 1\}^*$ of the PCP problem, we build an automaton \mathcal{A} which accepts some word with probability $\frac{1}{2}$ if and only if PCP has a solution. Let $\psi : \{0, 1\}^* \rightarrow [0, 1]$ the injective mapping defined by:

$$\psi(a_0 \dots a_n) = \frac{a_n}{2} + \dots + \frac{a_0}{2^n} ,$$

and let $\theta_1 = \psi \circ \varphi_1$ and $\theta_2 = \psi \circ \varphi_2$. Let $\mathcal{A}_1 = (Q, A, M, q_0^1, q_F^1)$ the probabilistic automaton with two states $Q = \{q_0^1, q_F^1\}$ and transitions:

$$\forall a \in A, M(a) = \begin{bmatrix} 1 - \theta_1(a) & \theta_1(a) \\ 1 - \theta_1(a) - 2^{-|\varphi_1(a)|} & \theta_1(a) + 2^{-|\varphi_1(a)|} \end{bmatrix} .$$

A simple computation shows that:

$$\forall w \in A^*, \mathbb{P}_{\mathcal{A}_1}(w) = \theta_1(w) . \quad (3)$$

A very similar construction produces a two-states automaton \mathcal{A}_2 such that:

$$\forall w \in A^*, \mathbb{P}_{\mathcal{A}_2}(w) = 1 - \theta_2(w) . \quad (4)$$

Let \mathcal{A} be the disjoint union of these two automata \mathcal{A}_1 and \mathcal{A}_2 plus a new initial state that leads with equal probability $\frac{1}{2}$ to one of the initial states q_0^1 and q_0^2 of \mathcal{A}_1 and \mathcal{A}_2 . Then for every word $w \in A^*$ and every letter $a \in A$,

$$\begin{aligned} \left(\exists w \in A^*, \mathbb{P}_{\mathcal{A}}(aw) = \frac{1}{2} \right) &\iff \left(\exists w \in A^*, \frac{1}{2}\mathbb{P}_{\mathcal{A}_1}(w) + \frac{1}{2}\mathbb{P}_{\mathcal{A}_2}(w) = \frac{1}{2} \right) \\ &\iff (\exists w \in A^*, \theta_1(w) = \theta_2(w)) \\ &\iff (\exists w \in A^*, \varphi_1(w) = \varphi_2(w)) \\ &\iff \text{PCP has a solution,} \end{aligned}$$

where the first equivalence is by definition of \mathcal{A} , the second is by (3) and (4), the third holds because ψ is injective and the fourth is by definition of PCP. This completes the proof of Proposition 1. \square

Proof. According to Proposition 1 and Proposition 2 the emptiness and the strict emptiness problems are undecidable for cut-point $\frac{1}{2}$ and automata whose transition probabilities are multiples of $\frac{1}{8}$. The transformation of such automata into simple automata is easy.

5 Proof of Proposition 3

Proof. We first assume that the set of accepting states F is absorbant. Let $(q, a) \in S \times A$ be the unique couple of states and action such that $0 < M_a(s, t) < 1$ for some states s, t . Without loss of generality, we can suppose that q is the initial state. Let $n \geq 1$ and $\{s_0, \dots, s_n\}$ be the set of states s_i such that $0 <$

$M_a(q, s_i)$. Let \mathcal{A}_i be the deterministic automaton on finite words obtained from \mathcal{A} by choosing s_i as initial state, removing the transition (q, a) and keeping the same final states. Denote $\mathcal{L}_{s_i \rightarrow F} \subseteq A^*$ the language accepted by \mathcal{A}_i and $\mathcal{L}_{s_i \rightarrow q}$ the set of words labeling a path from s_i to q for every $0 \leq i \leq n$.

We prove that :

$$val_{\mathcal{A}} = \max_{I \times J \subseteq \{s_0, \dots, s_n\}^2} \left\{ \frac{\sum_{s_i \in I} M_a(q, s_i)}{1 - \sum_{s_j \in J} M_a(q, s_j)} \right\}, \quad (5)$$

under the constraint:

$$\begin{cases} \left(\bigcap_{s_i \in I} \mathcal{L}_{s_i \rightarrow F} \right) \cap \left(\bigcap_{s_j \in J} \mathcal{L}_{s_j \rightarrow q} \right) \neq \emptyset, \\ I \cap J = \emptyset. \end{cases}$$

We first prove the direct inequality. Let $I, J \subseteq \{s_0, \dots, s_n\}$ for which the maximum is reached in (5). Let $x_1 = \sum_{s_i \in I} M_a(q, s_i)$ and $x_2 = \sum_{s_j \in J} M_a(q, s_j)$. Let $w \in \left(\bigcap_{s_i \in I} \mathcal{L}_{s_i \rightarrow F} \right) \cap \left(\bigcap_{s_j \in J} \mathcal{L}_{s_j \rightarrow q} \right)$. We have $(\delta_0 \cdot aw)(q) = x_2$ and $(\delta_0 \cdot aw)(F) = x_1$. Since F is absorbant reading this word n times leads the following distribution $(\delta_0 \cdot (aw)^n)(F) = \sum_{i=0}^n x_1 \cdot x_2^i$. Hence $val_{\mathcal{A}}$ is greater than the right hand-side of (5).

We prove the converse inequality. Let $w \in A^*$ a word accepted by \mathcal{A} with probability p . If w is the empty string. Since w is accepted then q is accepting and $p = 1$. Assume now that w is different from the empty string. $w = au$ for some $u \in A^*$. Let $I = \{i \mid u \in \mathcal{L}_{s_i \rightarrow F}\}$ and $J = \{j \mid u \notin \mathcal{L}_{s_j \rightarrow F}\}$, for i and j in $\{0, \dots, n\}$. Let K_1 and K_2 a partition of J such that $K_1 = \{j \in J \mid u \in \mathcal{L}_{s_j \rightarrow q}\}$ and $K_2 = \{j \in J \mid u \notin \mathcal{L}_{s_j \rightarrow q}\}$. We have $\mathbb{P}_{\mathcal{A}}(w) = \sum_{i \in I} M_a(q, s_i) + \sum_{j \in K_2} M(q, s_j) \cdot \mathbb{P}_{\mathcal{A}}(w)$, thus:

$$\mathbb{P}_{\mathcal{A}}(w) = \frac{\sum_{i \in I} M_a(q, s_i)}{1 - \sum_{j \in K_2} M(q, s_j)}.$$

Since we are maximizing this quantity, it is clear that $\mathbb{P}_{\mathcal{A}}(w)$ is less than the right hand-side of (5).

If the set of accepting states is not absorbant. We construct a new automaton $\mathcal{A}_{\#}$ so that the value of $val_{\mathcal{A}} = val_{\mathcal{A}_{\#}}$. We add a new letter $\#$ and a new absorbant state $f_{\#}$ to \mathcal{A} such that $M_{\#}(s, s) = 1$ if s is not accepting in \mathcal{A} ($\#$ has no effect on the automaton) and $M_{\#}(s, f_{\#}) = 1$ if s is accepting in \mathcal{A} . The unique accepting state in $\mathcal{A}_{\#}$ is $f_{\#}$. It is easy to see that $val_{\mathcal{A}} = val_{\mathcal{A}_{\#}}$ once we notice that for every word $w \in A^*$ accepted by \mathcal{A} with probability p , the word $w\#$ is accepted by $\mathcal{A}_{\#}$ with same probability.

To prove the PSPACE completeness we reduce the problem of deciding the intersection of n Automata on finite words which is known to be PSPACE complete [6]. Given n deterministic automata denoted $\mathcal{A}_i = (Q_i, A, \delta_i, q_0^i, F_i)$ and $i \in \{1, \dots, n\}$, we construct the probabilistic automaton \mathcal{B} by adding a new state q_0 and a new letter $\#$ to the alphabet such that $M_{\#}(q_0, q_0^i) = \frac{1}{n}$. The letter

\sharp has no effect on the other states. If this probabilistic automaton has the value one, there exists then a word $w \in A^*$ such that for every $i \in \{1, \dots, n\}$ we have $w \in \mathcal{L}_{\mathcal{A}_i}$. Otherwise the intersection of all the \mathcal{A}_i is empty. This shows the PSPACE completeness. \square

6 Proof of Proposition 4

Proof. To prove Proposition 4, we provide an algorithm which takes as input a simple probabilistic automaton \mathcal{A} on an alphabet A (with an arbitrary number of probabilistic transitions) and outputs a simple automaton \mathcal{A}' over an alphabet A' with only one probabilistic transition and a rational language $L' \subseteq (A')^*$ such that:

$$\left(\exists w \in A^*, \mathbb{P}_{\mathcal{A}}(w) \geq \frac{1}{2} \right) \iff \left(\exists w \in L', \mathbb{P}_{\mathcal{A}'}(w') \geq \frac{1}{2} \right). \quad (6)$$

According to Theorem 1, the Emptiness Problem for simple probabilistic automata and cut-point $\frac{1}{2}$ is undecidable, hence (6) proves Proposition 4.

The intuition for the construction of A', L' and \mathcal{A}' is as follows. In the simple probabilistic automaton \mathcal{A} , after a word u has been read, the probability distribution on states is $\delta_{q_0} \cdot u$. Then, when a letter a is read, for every state p a coin toss is made to choose which of the successors q_0 and q_1 of p should be the next state (with $q_0 = q_1$ if the transition (p, a) is deterministic). Then, the probability $(\delta_{q_0} \cdot u)(p)$ is split in twice $\frac{1}{2}(\delta_{q_0} \cdot u)(p)$, moved to q_0 and q_1 and added to probabilities that result of other simultaneous coin tosses.

To simulate this phenomenon with only one probabilistic state, we realize the coin tosses one by one, rather than simultaneously. The introduction of new letters in the alphabet allows the automaton to toss coins state by state, while freezing the other states. Hence, while the original automaton would realize $|Q|$ simultaneous transitions, the new automaton realizes $3|Q| + 1$ sequential transitions.

When the coin toss on p is simulated, the probability in p is moved to a new state s_* , then split by a coin toss and then moved to two new states s_0 and s_1 . For the result of the coin toss not to interfere with subsequent coin tosses over q_0 and q_1 , the result is then stored in two new copy states $q_{0,\sharp}$ and $q_{1,\sharp}$, until all coin tosses have been realized and the simulation round is over. At the end of the simulation round, a “flushing letter” a_\sharp sends the results stored in new copy states $q_\sharp \in Q_\sharp$ back to the original states $q \in Q$, and a new simulation round begins.

To implement this new automaton, only one probabilistic transition is needed: the transition from s_* to s_0 and s_1 . Other transitions are deterministic.

The rational constraint L' checks that coin tosses are realized in the right order and that the flushing letter is played at the end of each simulation round.

Now we give the formal description of the automaton. The alphabet A' , the automaton \mathcal{A}' and the rational language L' are computed as follows. If $\mathcal{A} = (Q, A, \mathcal{M}, q_0, F)$ then $\mathcal{A}' = (Q', A', \mathcal{M}', q_0, F)$ is defined by:

1. The alphabet A' is made of two new letters a_* (the coin toss letter) and $a_\#$ (the flushing letter) plus, for each letter $a \in A$ and state $s \in Q$, two new letters $\alpha(a, s)$ and $\beta(a, s)$ so that:

$$A' = \{a_*, a_\#\} \cup \bigcup_{a \in A, s \in Q} \{\alpha(a, s), \beta(a, s)\} .$$

2. The set of states of \mathcal{A}' is obtained from Q by addition of three new states s_*, s_0, s_1 , plus a copy $q_\#$ of each state $q \in Q$ so that:

$$Q' = Q \cup Q_\# \cup \{s_*, s_0, s_1\} .$$

3. The initial state q_0 and the set of final states F are left unchanged.
4. The transitions of \mathcal{A}' are as follows. For every letter $a \in A$ and state $s \in Q$, the new letter $\alpha(a, s)$ has no effect on states $u \neq s$ (i.e. $M_{\alpha(a, s)}(u) = u$), while from state s the transition is deterministic to state s_* i.e. $M_{\alpha(a, s)}(s) = s_*$.
5. The new letter a_* has no effect on states $u \neq s_*$, while from state s_* this is the only probabilistic transition of \mathcal{A}' , defined by $M_{a_*}(s_*) = \frac{1}{2}s_0 + \frac{1}{2}s_1$.
6. For every letter $a \in A$ and state $s \in Q$, the new letter $\beta(a, s)$ has no effect on states $u \notin \{s_0, s_1\}$. Transitions on letter $\beta(a, q)$ from states s_0 and s_1 are deterministic and depend on $M_a(s)$. If the transition $M_a(s)$ is deterministic, i.e. if $M_a(s, r) = 1$ for some state r then $M_{\beta(a, s)}(s_0) = r_\#$ and $M_{\beta(a, s)}(s_1) = r_\#$. If the transition $M_a(s)$ is probabilistic i.e. if $M_a(s) = \frac{1}{2}r + \frac{1}{2}r'$ for some states r, r' then $M_{\beta(a, s)}(s_0) = r_\#$ and $M_{\beta(a, s)}(s_1) = r'_\#$.
7. The new letter $a_\#$ has no effect on states that are not in $Q_\#$. For every state $q_\# \in Q_\#$ which is a copy of a state $q \in Q$, the letter $a_\#$ sends deterministically state $q_\#$ to q .

Now we define the rational language L' . Choose some enumeration $\{s_0, s_1, \dots, s_n\} = Q$ of states of \mathcal{A} and for each letter a , define the word

$$u_a = \alpha(a, s_0)a_*\beta(a, s_0)\alpha(a, s_1)a_*\beta(a, s_1) \cdots \alpha(a, s_n)a_*\beta(a, s_n)a_\# \in A'^* ,$$

and let $L' = \{u_a, a \in A\}^*$.

Then (6) holds because for every word $a_0a_1a_2 \cdots \in A^*$,

$$\mathbb{P}_{\mathcal{A}}(a_0a_1a_2 \cdots) = \mathbb{P}_{\mathcal{A}'}(u_{a_0}u_{a_1}u_{a_2} \cdots) .$$

Since automaton \mathcal{A}' has only one probabilistic transition, this completes the proof of Proposition 4. \square

7 Proof of Proposition 5

Proof. The undecidable problem described in Proposition 4 reduces to the emptiness problem for simple probabilistic automata with two probabilistic transitions: given \mathcal{A} and L , add a new initial state to \mathcal{A} and from this new initial state, proceed with probability $\frac{1}{2}$ either to the original initial state of \mathcal{A} to the initial state of a deterministic automaton that checks whether the input word is in L . This new automaton accepts a word with probability more than $\frac{3}{4}$ if and only if the original automaton accepts a word with probability more than $\frac{1}{2}$. \square

8 Proof of Proposition 6

Proof (of Proposition 6). We shall prove:

$$\left(x > \frac{1}{2}\right) \iff (\forall \varepsilon > 0, \exists w \in A^*, \mathbb{P}_{\mathcal{A}_x}(w) \geq 1 - \varepsilon) . \quad (7)$$

In order to prove this equivalence we notice that: $\mathbb{P}_{\mathcal{A}_x}(1 \xrightarrow{a^n b} 3) = x^n$ and $\mathbb{P}_{\mathcal{A}_x}(4 \xrightarrow{a^n b} 6) = (1 - x)^n$. Let $(n_k)_{k \in \mathbb{N}}$ an increasing sequence of integers. By reading the word $w = a^{n_0} b a^{n_1} b \dots a^{n_i} b$, we get:

$$\begin{cases} \mathbb{P}_{\mathcal{A}_x}(1 \xrightarrow{w} 3) = 1 - \prod_{k \geq 0} (1 - x^{n_k}) \\ \mathbb{P}_{\mathcal{A}_x}(4 \xrightarrow{w} 6) = (1 - x)^{n_1} + (1 - (1 - x)^{n_1})(1 - x)^{n_2} + \dots \\ \qquad \qquad \qquad = 1 - \prod_{k \geq 0} (1 - (1 - x)^{n_k}) \leq \sum_{k \geq 0} (1 - x)^{n_k} \end{cases}$$

If $x \leq \frac{1}{2}$ then $\mathbb{P}_{\mathcal{A}_x}(1 \xrightarrow{w} 3) \leq \mathbb{P}_{\mathcal{A}_x}(4 \xrightarrow{w} 6)$ therefore no word w can be accepted with arbitrarily high probability if $x \leq \frac{1}{2}$ what proves the converse implication on (7). Assume that $x > \frac{1}{2}$, we exhibit an increasing sequence of integers $(n_k)_{k \in \mathbb{N}}$ such that for every $\varepsilon > 0$ we have:

$$\begin{cases} \sum_{k \geq 0} x^{n_k} = \infty \\ \sum_{k \geq 0} (1 - x)^{n_k} \leq \varepsilon \end{cases} \quad (8)$$

Let $C \in \mathbb{R}$ and $n_k = \ln_x(\frac{1}{k}) + C$, notice that $\sum_{k \geq 0} (x)^{n_k} = x^C \cdot \sum_{k \geq 0} \frac{1}{k} = \infty$. In the other hand we have:

$$\begin{aligned} 1 - x &= x^{\ln_x(1-x)} \\ &= x^{\frac{\ln(1-x)}{\ln x}} \end{aligned}$$

There exists $\beta > 1$ such that: $1 - x = x^\beta$, hence $\sum_{k \geq 0} (1 - x)^{n_k} = \sum_{k \geq 0} x^{\beta n_k}$. So: $\sum_{k \geq 0} x^{\beta n_k} = x^{\beta C} \sum_{k \geq 0} x^{\beta \ln_x(\frac{1}{k})} = x^{\beta C} \sum_{k \geq 0} \frac{1}{k^\beta}$. Since this series converge, we satisfy (8) by choosing a suitable constant. It is easy to see that a sequence of finite words $(a^{n_0} b a^{n_1} b \dots a^{n_i} b)_{i \in \mathbb{N}}$ is accepted with probability arbitrarily close to 1. \square

9 Proof of Theorem 4

Proof (of Theorem 4). Given a probabilistic automaton \mathcal{B} with alphabet A such that $a, b \notin \mathcal{B}$, we combine \mathcal{B} and the automaton \mathcal{A}_x on Fig.1 to obtain an automaton \mathcal{C} which has value 1 if and only if there exists a word w such that

$\mathbb{P}_{\mathcal{A}}(w) > \frac{1}{2}$. The input alphabet of \mathcal{C} is $A \cup \{b\}$ plus a new letter \sharp . \mathcal{C} is computed as follows. First, the transitions in \mathcal{A}_x on letter a are deleted. Second, we make two copies \mathcal{A}_4 and \mathcal{A}_1 of the automaton \mathcal{B} , such that the initial state of \mathcal{A}_4 is 4 and the initial state of \mathcal{A}_1 is 1. From states of \mathcal{A}_4 and \mathcal{A}_1 other than the initial states, reading letter b leads to the sink state 6. Third, from a state s of \mathcal{A}_4 the transition on the new letter \sharp is deterministic and leads to 5 if s is a final state and to 4 if s is not a final state. Fourth, from a state s of \mathcal{A}_1 the transition on the new letter \sharp is deterministic and leads to 1 if s is a final state and to 2 if s is not a final state. Fifth, the final states of \mathcal{C} are 5 and 3. Sixth, states 0, 3, 6, 5 and 2 are absorbing for letters in A .

Then suppose there exists w such that $\mathbb{P}_{\mathcal{A}}(w) > \frac{1}{2}$ and let us show that \mathcal{C} has value 1. Let $\epsilon > 0$ and let $u_\epsilon = ba^{i_0}ba^{i_1}ba^{i_2}b \cdots a^{i_k}$ be a word accepted by \mathcal{B} with probability $1 - \epsilon$. Then by construction of \mathcal{C} ,

$$\mathbb{P}_{\mathcal{C}}(b(w\sharp)^{i_0}b(w\sharp)^{i_1}b(w\sharp)^{i_2}b \cdots (w\sharp)^{i_k}) \geq \mathbb{P}_{\mathcal{A}}(u_\epsilon) \geq 1 - \epsilon,$$

thus \mathcal{C} has value 1.

Now suppose that for every $w \in A^*$, $\mathbb{P}_{\mathcal{A}}w \leq \frac{1}{2}$ and let us show that \mathcal{C} has not value 1. Let $w' \in (A \cup \{b, \sharp\})^*$. Factorize w' in $w' = u_0v_0\sharp u_1v_1\sharp u_kv_k \cdots$ such that $u_i \in b^*$ and $v_i \in A^*$. Then by construction of \mathcal{C} and by hypothesis, $\mathbb{P}_{\mathcal{C}}(w') \leq \mathbb{P}_{\mathcal{A}_{\frac{1}{2}}}(u_0au_1au_2a \cdots u_k a) \leq \text{val}(\mathcal{A}_{\frac{1}{2}})$. Thus $\text{val}(\mathcal{C}) \leq \text{val}(\mathcal{A}_{\frac{1}{2}})$ and according to Proposition 6, $\text{val}(\mathcal{C}) < 1$. \square

10 Proof of Theorem 5

Proof (of Proposition 7). Proposition 7 is a consequence of the two following facts.

First, if there is an edge from S to T in the support graph of \mathcal{A} , then T is limit reachable from S : let $S, T \subseteq Q$ and $a \in A$. If $S \cdot a = T$, then the sequence constant equal to a is a limit path from S to T . If $S \cdot a = S$ and $S \cdot a^\sharp = T$ then by definition of $S \cdot a^\sharp$, $(a^n)_{n \in \mathbb{N}}$ is a limit path from S to T .

Second, limit-reachability is a transitive relation: let $S_0, S_1, S_2 \subseteq Q$ such that S_1 is limit-reachable from S_0 and S_2 is limit-reachable from S_1 . Let $(u_n)_{n \in \mathbb{N}}$ a limit-path from S_0 to S_1 and $(v_n)_{n \in \mathbb{N}}$ a limit-path from S_1 to S_2 . Then $(u_nv_n)_{n \in \mathbb{N}}$ is a limit-path from S_0 to S_2 . \square

Proof (of the Flooding lemma). Let $(u_n)_{n \in \mathbb{N}}$ be a limit path from Q to some set of states $T \subsetneq Q$. We shall prove that $T = Q$. Let $A_T = \{a \in A \mid T \cdot a \subseteq T\}$.

First, we prove that for every letter $a \in A_T$, $Q \setminus T$ is a -stable. Otherwise there would be $a \in A_T$ and $t \in T$ such that t is a -reachable from some state $s \in Q \setminus T$. Since \mathcal{A} is \sharp -stable, s and t are both a -recurrent, and by definition of a -recurrence, since t is a -reachable from s , s would be a -reachable from t as well. But $s \in Q \setminus T$ and $t \in T$, which contradicts the a -stability of T .

Second, we prove that $u_n \in A_T^*$ for only finitely many $n \in \mathbb{N}$. Since for every $a \in A_T$, $Q \setminus T$ is a -stable, then during the computation $\delta_Q = \delta_0, \delta_1, \dots, \delta_{|u_n|}$ on

the word u_n , $\sum_{s \in Q \setminus T} \delta_k(s)$ is constant. Thus, for every $n \in \mathbb{N}$,

$$\mathbb{P}_{\mathcal{A}}(s \xrightarrow{u_n} T) = \sum_{s \in Q \setminus T} (\delta_Q \cdot u_n)(s) = \sum_{s \in Q \setminus T} \delta_Q(s) = \frac{|Q| - |T|}{|Q|} > 0.$$

Since $(u_n)_{n \in \mathbb{N}}$ is a limit-path from Q to T , $\mathbb{P}_{\mathcal{A}}(s \xrightarrow{u_n} T)$ converges to 0 hence the inequality can hold only for finitely many $n \in \mathbb{N}$.

Now we show that there exists $T_1 \subseteq Q$ such that:

- (i) $T_1 \neq T$,
- (ii) T is \sharp -reachable from T_1 in \mathcal{A} ,
- (iii) and T_1 is limit-reachable from Q in \mathcal{A} .

Since any infinite subsequence of a limit-path is a limit-path, and since we proved that $u_n \in A_T^*$ for only finitely many $n \in \mathbb{N}$, we can assume w.l.o.g. that for every $n \in \mathbb{N}$, $u_n \notin A_T^*$. Thus for every $n \in \mathbb{N}$, there exists $v_n \in A^*$, $a_n \in A \setminus A_T$ and $w_n \in A_T^*$ such that $u_n = v_n a_n w_n$. W.l.o.g. again, since A is finite and $\mathcal{D}(Q)$ is compact, we can assume that $(a_n)_{n \in \mathbb{N}}$ is constant equal to a letter $a \in A \setminus A_T$ and that $(\delta_Q \cdot v_n)_{n \in \mathbb{N}}$ converges to a probability distribution $\delta \in \mathcal{D}(Q)$.

The choice of T_1 such that (i),(ii) and (iii) hold depends on $\text{Supp}(\delta) \cdot a$.

If $\text{Supp}(\delta) \cdot a = T$ then we choose $T_1 = \text{Supp}(\delta)$. Then (i) holds because $a \notin A_T$, (ii) holds because $T = T_1 \cdot a$ and (iii) holds because $(v_n)_{n \in \mathbb{N}}$ is a limit-path from Q to T_1 .

If $\text{Supp}(\delta) \cdot a \neq T$ then we choose $T_1 = \text{Supp}(\delta) \cdot a$. Then (i) clearly holds and (iii) holds because $(v_n a)_{n \in \mathbb{N}}$ is a limit path from Q to T_1 in \mathcal{A} . To prove that (ii) holds, consider the restriction $\mathcal{A}[T, A_T]$ of automaton \mathcal{A} to states T and alphabet A_T . Then $(w_n)_{n \in \mathbb{N}}$ is a limit-path from T_1 to T in $\mathcal{A}[T, A_T]$. Moreover, since \mathcal{A} is \sharp -acyclic and \sharp -stable, $\mathcal{A}[T, A_T]$ also is. Thus, we can apply the blowing lemma to $\mathcal{A}[T, A_T]$ and T_1 , which proves that T is \sharp -reachable from T_1 in $\mathcal{A}[T, A_T]$, thus in \mathcal{A} as well.

If $T_1 = Q$, the proof is complete. Otherwise, as long as $T_n \neq Q$, we use condition (iii) to build inductively a sequence $T = T_0, T_1, T_2, \dots, T_n$ such that for every $0 \leq k < n$, $T_k \neq T_{k+1}$ (condition (i)) and T_k is \sharp -reachable from T_{k+1} in \mathcal{A} (condition (ii)). Since \mathcal{A} is \sharp -acyclic, $T_n = Q$ after at most 2^Q inductive steps.

Since \sharp -reachability is transitive, this proves that T is \sharp -reachable from Q . Since \mathcal{A} is \sharp -stable, the only set \sharp -reachable from Q is Q thus $T = Q$, which completes the proof of the flooding lemma. \square

Proof (of Lemma 4). Let $(u_n)_{n \in \mathbb{N}}$ be a limit-path from S_0 to T . Let $A_0 = \{a \in A \mid S_0 \cdot a = S_0\}$. For every $n \in \mathbb{N}$, let v_n be the longest prefix of u_n in A_0^* . Since every infinite subsequence of a limit-path is a limit-path, and since $\mathcal{D}(Q)$ is compact, we can suppose without loss of generality that $(\delta_{S_0} \cdot v_n)_{n \in \mathbb{N}}$ converges to some distribution $\delta \in \mathcal{D}(Q)$.

Suppose first that $\text{Supp}(\delta) = S_0$. If $u_n \in A_0^*$ for infinitely many $n \in \mathbb{N}$ then $T = S_0$. Otherwise, since A is finite we can suppose w.l.o.g. that there exists a letter $a \in A \setminus A_0$ such that for every $n \in \mathbb{N}$, $v_n a$ is a prefix of u_n . Let also w_n

such that $u_n = v_n a w_n$. Let $S_1 = S_0 \cdot a$. Then $S_1 \neq S_0$ because $a \notin A_0$ and S_1 is clearly \sharp -reachable from S_0 . Moreover $(w_n)_{n \in \mathbb{N}}$ is a limit-path from S_1 to T , this completes the proof.

Suppose now that $\text{Supp}(\delta) \neq S_0$. Let $\mathcal{A}[S_0, A_0]$ the probabilistic automaton obtained from \mathcal{A} by restriction to the alphabet A_0 and to the state space S_0 . By definition of A_0 , $\mathcal{A}[S_0, A_0]$ is stable and it is \sharp -acyclic because \mathcal{A} is. According to the leaf lemma, $\mathcal{A}[S_0, A_0]$ has a unique leaf. Let S_1 be this unique leaf. Since $\text{Supp}(\delta)$ is limit-reachable from S_0 in $\mathcal{A}[S_0, A_0]$, according to the leaf lemma again, $S_1 \subseteq \text{Supp}(\delta)$ hence $S_1 \neq S_0$. Moreover, since it is the unique leaf, S_1 is \sharp -reachable from S_0 in $\mathcal{A}[S_0, A_0]$ hence in \mathcal{A} as well. For every $n \in \mathbb{N}$, let w_n such that $u_n = v_n w_n$. Then $(w_n)_{n \in \mathbb{N}}$ is a limit-path from S_1 to T . This completes the proof. \square

Proof (of Proposition 8). Apply again and again Lemma 4 to build a sequence S_0, S_1, S_2, \dots such that for every k , $S_k \neq S_{k+1}$, S_{k+1} is \sharp -reachable from S_k and T is limit-reachable from S_{k+1} . As long as $S_k \neq T$, Lemma 4 is used to build S_{k+1} . Since \mathcal{A} is subset-acyclic, the sequence has length at most 2^Q thus for some k , $S_k = T$. Since \sharp -reachability is transitive, this proves that T is \sharp -reachable from S_0 . \square