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## To cite this version:

Amel Bentata, Rama Cont. Mimicking the marginal distributions of a semimartingale. 2009. hal00425345 v 1

HAL Id: hal-00425345
https://hal.science/hal-00425345v1
Preprint submitted on 21 Oct 2009 (v1), last revised 23 May 2011 (v3)

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# Mimicking the marginal distributions of a semimartingale 

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#### Abstract

We show that the flow of marginal distributions of a discontinuous semimartingale $X$ can be matched by a Markov process whose infinitesimal generator is expressed in terms of the local characteristics of $X$. Our results extend a "mimicking theorem" of Gyöngy (1986) to discontinuous semimartingales. We use this result to derive a partial integro-differential equation for the one-dimensional distributions of a semimartingale, extending the Kolmogorov forward equation to a non-Markovian setting.


MSC Classificiation Numbers: 60J75, 60H10

## Contents

1 Introduction ..... 2
2 A mimicking theorem for discontinuous semimartingales ..... 3
2.1 Markovian projection of a semimartingale ..... 3
2.2 Martingale-preserving property
3 Mimicking an Ito semimartingale ..... 8
4 Forward equations for semimartingales ..... 13
5 Examples ..... 15
5.1 Marked point processes ..... 15
5.2 Time changed Lévy processes ..... 17

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## 1 Introduction

Stochastic processes with path-dependent / non-Markovian dynamics used in various fields such as physics and mathematical finance present challenges for computation, simulation and estimation. In some applications where one is interested in the marginal distributions of such processes, such as option pricing or Monte Carlo simulation of densities, the complexity of the model can be greatly reduced by considering a low-dimensional Markovian model with the same marginal distributions. Given a process $X$, a Markov process $Y$ is said to mimick $X$ if $X$ and $Y$ have the same marginal distributions:

$$
\begin{equation*}
\forall t \geq 0, \quad X_{t} \stackrel{d}{=} Y_{t} \tag{1}
\end{equation*}
$$

$Y$ is called a Markovian projection of $X$. The existence, uniqueness and computation of such Markovian projections has been explored for queues [4], Ito processes [12] and marked point processes [6] and has various applications such as the derivation of forward equations for option pricing [9].

We give here such a Markovian projection result for a (possibly discontinuous) semimartingale [3]. Given a semimartingale $X$, we give conditions under which there exists a Markov process $Y$ whose flow of marginal distributions is identical to those of $X$, and give an explicit construction of the Markov process $Y$ as the solution of a martingale problem for an integro-differential operator [2. 18, 21, 22]. Our result can be seen as a generalization to the discontinuous case of a previous result by Gyöngy 12 for continuous semimartingales.

In the martingale case, the Markovian projection problem is related to the problem of constructing martingales with a given flow of marginals, which dates back to Kellerer 17 and has been recently explored by Yor and coauthors [1]. 13, 19] using a variety of techniques. In this work we shall focus on the Markov property -rather than the martingale property- of the mimicking process. We shall see nevertheless that the Markovian projection preserves the martingale property. Also, whereas the approaches described in [1, 13, 19] use as a starting point the marginal distributions of $X$, our construction describes the mimicking Markov process $Y$ in terms of the characteristic triplet [15] of the semimartingale $X$. Our construction thus applies more readily to solutions of stochastic differential equations where the local characteristics are known but not the marginal distributions.

Section 2 presents a Markovian projection result for a $\mathbb{R}^{d}$-valued semimartingale given by its local characteristics. Section 3 shows how this result can be applied to processes whose jumps are represented as the integral of a predictable jump amplitude with respect to a Poisson random measure, a representation often used in stochastic differential equations with jumps. We use these results in section to derive a partial integro-differential equation for the one-dimensional distributions of a discontinuous semimartingale, thus extending Kolmogorov's forward equation to a non-Markovian setting. Section 4 applies these results to particular classes of processes: multivariate marked point processes (Section 5.1) and time-changed Lévy processes (Section 5.2).

## 2 A mimicking theorem for discontinuous semimartingales

Consider, on a filtered probability space $\left(\Omega, \mathcal{F},\left(\mathcal{F}_{t}\right)_{t \geq 0}, \mathbb{P}\right)$, an Ito semimartingale given by the decomposition
$X_{t}=X_{0}+\int_{0}^{t} \beta_{s}^{X} d s+\int_{0}^{t} \delta_{s}^{X} d W_{s}+\int_{0}^{t} \int_{\|y\| \leq 1} y \tilde{M}_{X}(d s d y)+\int_{0}^{t} \int_{\|y\|>1} y M_{X}(d s d y)$,
where $W$ is a standard $\mathbb{R}^{n}$-valued Wiener process, $M_{X}$ is an integer-valued random measure on $[0, \infty] \times \mathbb{R}^{d}$ with compensator measure $\mu_{X}$ and $\tilde{M}_{X}=$ $M_{X}-\mu_{X}$ is the compensated measure [15, Ch.II,Sec.1], $\beta^{X}\left(\right.$ resp. $\left.\delta^{X}\right)$ is an adapted process with values in $\mathbb{R}^{d}\left(\right.$ resp. $\left.M_{d \times n}(\mathbb{R})\right)$. We will assume that
Assumption 1. For any $T>0,\left(\beta^{X}, \delta^{X}\right)$ are bounded on $[0, T]$ :

$$
\begin{equation*}
\forall T>0 \exists K_{T}>0, \forall t \in[0, T]\left\|\beta_{t}^{X}\right\| \leq K_{T}, \quad\left\|\delta_{t}^{X}\right\| \leq K_{T} \quad \text { a.s } \tag{H1}
\end{equation*}
$$

where $\|$.$\| denotes the Euclidean norm.$
Assumption 2. $\mu_{X}$ has a density $m_{X}(\omega, t, d y)$ with respect to the Lebesgue measure on $[0, \infty[$ and for any $T>0$,

$$
\begin{equation*}
\exists K_{T}^{\prime}>0, \int_{\mathbb{R}^{d}}\left(1 \wedge\|y\|^{2}\right) m_{X}(., t, d y) \leq K_{T}^{\prime}<\infty \quad \text { a.s. } \tag{H2}
\end{equation*}
$$

Note that (H2) is only slightly stronger than stating that $m_{X}$ is a Lévy kernel since in that case we already have $\int\left(1 \wedge\|y\|^{2}\right) m_{X}(., t, d y)<\infty$.

Let $\Omega_{0}=D\left(\left[0, \infty\left[, \mathbb{R}^{d}\right)\right.\right.$ be the Skorokhod space of right-continuous functions with left limits. Denote by $Y_{t}(\omega)=\omega(t)$ the canonical process on $\Omega_{0}$ and $\mathcal{F}_{t}^{0}$ its filtration. Our goal in this section is to construct a law $\mathbb{Q}$ on $\Omega_{0}$ such that $Y$ is a Markov process under $\mathbb{Q}$ and $X$ and $Y$ have the same one-dimensional distributions: $\forall t \geq 0, X_{t} \stackrel{\text { d }}{=} Y_{t}$. In order to this, we shall characterize $\mathbb{Q}$ as the solution of a martingale problem for an appropriately chosen integro-differential operator $L$. Recall that a probability measure $\mathbb{Q}$ on $\Omega_{0}$ is a solution to the martingale problem [23, 14, 11] for $(L, \mathcal{D}(L))$ if for any $f \in \mathcal{D}(L)$, the process

$$
f\left(Y_{t}\right)-f\left(Y_{0}\right)-\int_{0}^{t} L f\left(Y_{s}\right) d s
$$

is a $\mathbb{Q}$-martingale. $Y$ then has the Markov property under $\mathbb{Q}$ (14, 11].

### 2.1 Markovian projection of a semimartingale

Theorem 1 (Markovian projection). Define, for $t \geq 0, z \in \mathbb{R}^{d}, A \in \mathcal{B}\left(\mathbb{R}^{d}-\{0\}\right)$

$$
\begin{align*}
\beta^{Y}(t, z) & =\mathbb{E}\left[\beta_{t}^{X} \mid X_{t^{-}}=z\right] ; \\
a^{Y}(t, z) & =\mathbb{E}\left[{ }^{t} \delta_{t}^{X} \delta_{t}^{X} \mid X_{t^{-}}=z\right] ;  \tag{3}\\
m_{Y}(t, A, z) & =\mathbb{E}\left[m_{X}(., t, A) \mid X_{t^{-}}=z\right] .
\end{align*}
$$

If $\beta^{Y}, a^{Y}$ and $A \rightarrow m_{Y}(t, A, z)$ are continuous in $(t, z)$ on $\left[0, \infty\left[\times \mathbb{R}^{d}\right.\right.$, there exists a weak solution $\left(\left(Y_{t}\right)_{t \geq 0}, \mathbb{Q}_{X_{0}}\right)$ for the stochastic differential equation

$$
\begin{align*}
Y_{t} & =X_{0}+\int_{0}^{t} \beta^{Y}\left(u, Y_{u}\right) d u+\int_{0}^{t} \delta^{Y}\left(u, Y_{u}\right) d B_{u} \\
& +\int_{0}^{t} \int_{\|y\| \leq 1} y \tilde{M}_{Y}(d u d y)+\int_{0}^{t} \int_{\|y\|>1} y M_{Y}(d u d y) \tag{4}
\end{align*}
$$

where $\left(B_{t}\right)$ is an n-dimensional Brownian motion, $M_{Y}$ is an integer-valued random measure on $\left[0, \infty\left[\times \mathbb{R}^{d}\right.\right.$ with compensator $m_{Y}\left(t, d y, Y_{t-}\right) d t, \tilde{M}_{Y}$ the associated compensated random measure and $\delta^{Y}:\left[0, \infty\left[\times \mathbb{R}^{d} \mapsto M_{d \times n}(\mathbb{R})\right.\right.$ is a continuous function such that

$$
{ }^{t} \delta^{Y}(t, z) \delta^{Y}(t, z)=a^{Y}(t, z)
$$

Under $\mathbb{Q}_{X_{0}}, Y$ is a Markov process with infinitesimal generator $L$ given, for $f \in C_{0}^{\infty}\left(\left[0, \infty\left[\times \mathbb{R}^{d}\right)\right.\right.$, by

$$
\begin{align*}
L f(t, x) & =\beta^{Y} \cdot \nabla f(t, x)+\sum_{i, j=1}^{d} \frac{a_{i, j}^{Y}(t, x)}{2} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(t, x)  \tag{5}\\
& +\int_{\mathbb{R}^{d}}[f(t, x+y)-f(t, x)-y \cdot \nabla f(t, x)] m_{Y}(t, d y, x)
\end{align*}
$$

and the marginal distributions of $Y$ mimick those of $X$ :

$$
\forall t \geq 0, Y_{t} \stackrel{\mathrm{~d}}{=} X_{t} .
$$

We will call $\left(Y, \mathbb{Q}_{X_{0}}\right)$ the Markovian projection of $X$.
Proof. First, we observe that $m_{Y}$ is a Lévy kernel : for any $(z, t)$

$$
\int_{\mathbb{R}^{d}}\left(1 \wedge\|y\|^{2}\right) m_{Y}(t, d y, z)=\mathbb{E}\left[\int_{\mathbb{R}^{d}} 1 \wedge\|y\|^{2} m_{X}(t, d y) \mid X_{t^{-}}=z\right]<\infty \text { a.s. }
$$

where we applied Fubini's theorem using $\left(H_{2}\right)$. Assumptions $\left(H_{1}\right),\left(H_{2}\right)$ imply that $\beta^{Y}, a^{Y}$ are bounded with respect to $z$, uniformly in $t \in[0, T]$. Together with the assumption of continuity of the functions $\beta^{Y}, a^{Y}$ and $m_{Y}$ with respect to $(t, z)$ on $[0, T] \times \mathbb{R}^{d}$, these conditions imply the existence of a solution the martingale problem for the operator $L$ defined by (5) on $C_{0}^{\infty}\left([0, T] \times \mathbb{R}^{d}\right)$ 21, Theorem 2.2]. Let $\left(\left(Y_{t}\right)_{t \geq 0}, \mathbb{Q}_{X_{0}}\right)$ be such a solution. $\left(Y, \mathbb{Q}_{X_{0}}\right)$ is then a weak solution to (4) on the canonical space. To show that $Y_{T}$ and $X_{T}$ have the same marginal distributions for all $T \geq 0$, we will prove that for all bounded continuous functions $f$, and for all $T \geq 0$ :

$$
\mathbb{E}^{\mathbb{P}}\left[f\left(X_{T}\right)\right]=\mathbb{E}^{\mathbb{Q} x_{0}}\left[f\left(Y_{T}\right)\right]
$$

First, let $f$ be a $\mathcal{C}^{2}$ function with compact support on $\mathbb{R}^{d}$. Itô's formula yields

$$
\begin{aligned}
f\left(X_{T}\right) & =f\left(X_{0}\right)+\sum_{i=1}^{d} \int_{0}^{T} \sum_{i=1}^{d} \frac{\partial f}{\partial x_{i}}\left(X_{t^{-}}\right) d X_{t}^{i}+\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right] d t \\
& +\sum_{t \leq T}\left[f\left(X_{t^{-}}+\Delta X_{t}\right)-f\left(X_{t^{-}}\right)-\sum_{i=1}^{d} \frac{\partial f}{\partial x_{i}}\left(X_{t^{-}}\right) \Delta X_{t}^{i}\right] \\
& =f\left(X_{0}\right)+\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \beta_{t}^{X} d t+\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \delta_{t}^{X} d W_{t} \\
& +\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right] d t \\
& +\int_{0}^{T} \int_{\|y\| \leq 1}\left(\nabla f\left(X_{t^{-}}\right) \cdot y\right) \tilde{M}_{X}(d t d y)+\int_{0}^{T} \int_{\|y\|>1}\left(\nabla f\left(X_{t^{-}}\right) \cdot y\right) M_{X}(d t d y) \\
& +\int_{0}^{T} \int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-y \cdot \nabla f\left(X_{t^{-}}\right)\right) M_{X}(d t d y)
\end{aligned}
$$

where $a_{t}^{X}={ }^{t} \delta_{t}^{X} \cdot \delta_{t}^{X}$. We note that

- $\int_{0}^{T} \int_{\|y\| \leq 1}\left(\nabla f\left(X_{t^{-}}\right) . y\right) \quad \tilde{M}_{X}(d t d y)$ is well defined since $|\nabla f|$ is bounded and $y \rightarrow y^{2}$ is integrable with respect to $\mu_{X}$; thanks to $\left(H_{2}\right)$ this integral is a a martingale;
- $\int_{0}^{T} \int_{\|y\|>1}\left(\nabla f\left(X_{t^{-}}\right) . y\right) \quad M_{X}(d t d y)<\infty$ a.s. since $|\nabla f|$ is bounded;
- $\int_{0}^{T} \int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-y . \nabla f\left(X_{t^{-}}\right)\right) M_{X}(d t d y)$ is well defined since:

$$
\left|f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-y \cdot \nabla f\left(X_{t^{-}}\right)\right| \leq\|\nabla f\| \frac{\|y\|^{2}}{2}
$$

and $y \rightarrow y^{2}$ is integrable with respect to $\mu_{X}$;

- Since $\nabla f\left(X_{t^{-}}\right)$and $\delta_{t}^{X}$ are uniformly bounded on $[0, T], \int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \delta_{t}^{X} d W_{t}$ is a martingale.

$$
\begin{aligned}
f\left(X_{T}\right) & =f\left(X_{0}\right)+\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \beta_{t}^{X} d t+\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \delta_{t}^{X} d W_{t} \\
& +\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right] d t \\
& +\int_{0}^{T} \int_{\|y\| \leq 1}\left(\nabla f\left(X_{t^{-}}\right) \cdot y\right) \tilde{M}_{X}(d t d y) \\
& +\int_{0}^{T} \int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right) M_{X}(d t d y)
\end{aligned}
$$

Taking expectations and given the above remarks, we obtain

$$
\begin{aligned}
\mathbb{E}\left[f\left(X_{T}\right)\right] & =f\left(X_{0}\right)+\mathbb{E}\left[\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \beta_{t}^{X} d t\right]+\mathbb{E}\left[\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right] d t\right] \\
& +\mathbb{E}\left[\int_{0}^{T} \int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right) M_{X}(d t d y)\right] \\
& =f\left(X_{0}\right)+\mathbb{E}\left[\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \beta_{t}^{X} d t\right]+\mathbb{E}\left[\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right] d t\right] \\
& +\mathbb{E}\left[\int_{0}^{T} \int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right) m_{X}(t, d y) d t x\right]
\end{aligned}
$$

Observing that:

$$
\begin{aligned}
& \mathbb{E}\left[\int_{0}^{T} \nabla f\left(X_{t^{-}}\right) \cdot \beta_{t}^{X} d t\right] \leq\|\nabla f\|_{\infty} \mathbb{E}\left[\int_{0}^{T}\left\|\beta_{t}^{X}\right\| d t\right]<\infty \\
& \mathbb{E}\left[\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right] \leq\left\|\nabla^{2} f\right\|_{\infty} \mathbb{E}\left[\int_{0}^{T}\left\|a_{t}^{X}\right\| d t\right]<\infty\right. \\
& \mathbb{E}\left[\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right| m_{X}(t, d y) d t\right] \\
& \quad \leq \frac{\left\|\nabla^{2} f\right\|_{\infty}}{2} \mathbb{E}\left[\int_{0}^{T} \int_{\|y\| \leq 1}\|y\|^{2} m_{X}(t, d y) d t\right]+2\|f\|_{\infty} \mathbb{E}\left[\int_{0}^{T} \int_{\|y\|>1} m_{X}(t, d y) d t\right]<+\infty
\end{aligned}
$$

we may apply Fubini's theorem.

$$
\begin{aligned}
\mathbb{E}\left[f\left(X_{T}\right)\right] & =f\left(X_{0}\right)+\int_{0}^{T} \mathbb{E}\left[\nabla f\left(X_{t^{-}}\right) \cdot \beta_{t}^{X}\right] d t+\frac{1}{2} \int_{0}^{T} \mathbb{E}\left[\operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a_{t}^{X}\right]\right] d t \\
& +\int_{0}^{T} \mathbb{E}\left[\int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right) m_{X}(t, d y)\right] d t
\end{aligned}
$$

Conditioning on $X_{t-}$ and using the iterated expectation property we obtain

$$
\begin{aligned}
\mathbb{E}\left[f\left(X_{T}\right)\right] & =f\left(X_{0}\right)+\int_{0}^{T} \mathbb{E}\left[\nabla f\left(X_{t^{-}}\right) \cdot \mathbb{E}\left[\beta_{t}^{X} \mid X_{t-}\right]\right] d t+\frac{1}{2} \int_{0}^{T} \mathbb{E}\left[\operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) \mathbb{E}\left[a_{t}^{X} \mid X_{t-}\right]\right]\right] d t \\
& +\int_{0}^{T} \mathbb{E}\left[\mathbb{E}\left[\int_{\mathbb{R}^{d}}\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right) m_{X}(t, d y) \mid X_{t-}\right]\right] d t \\
& =f\left(X_{0}\right)+\int_{0}^{T} \mathbb{E}\left[\nabla f\left(X_{t^{-}}\right) \cdot \beta^{Y}\left(t, X_{t-}\right)\right] d t+\frac{1}{2} \int_{0}^{T} \mathbb{E}\left[\operatorname{tr}\left[\nabla^{2} f\left(X_{t^{-}}\right) a^{Y}\left(t, X_{t-}\right)\right]\right] d t \\
& +\int_{0}^{T} \int_{\mathbb{R}^{d}} \mathbb{E}\left[\left(f\left(X_{t^{-}}+y\right)-f\left(X_{t^{-}}\right)-1_{\{\|y\| \leq 1\}} y \cdot \nabla f\left(X_{t^{-}}\right)\right) m_{Y}\left(t, d y, X_{t-}\right)\right] d t \\
& =\mathbb{E}\left[f\left(Y_{T}\right)\right]
\end{aligned}
$$

if one applies also Itô formula to $f\left(Y_{t}\right)$. We leave this part for the reader. Now consider a continuous bounded function $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$. There exists a sequence $\left(f_{n}\right)_{n \leq 1}$ such that $f_{n}: \mathbb{R}^{d} \rightarrow \mathbb{R}$ is a $\mathcal{C}^{2}$ function with compact support and $\left\|f_{n}-f\right\|_{\infty} \rightarrow 0$. A dominated convergence argument shows that $E\left[f_{n}\left(Y_{T}\right)\right]=E\left[f_{n}\left(X_{T}\right)\right] \rightarrow E\left[f\left(X_{T}\right)\right]$ and $E\left[f_{n}\left(Y_{T}\right)\right] \rightarrow E\left[f\left(Y_{T}\right)\right]$, which shows our result.

Let us now discuss on the uniqueness of the Markovian projection of $X$. First, note that $L$ maps $C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$ into the set $B\left(\mathbb{R}^{d}\right)$ of bounded functions: $\forall f \in \mathcal{C}_{0}^{\infty}\left(\mathbb{R}^{d}\right), \quad \forall(t, x) \in[0, T] \times \mathbb{R}^{d}$,

$$
\begin{aligned}
|L f(t, x)| & \leq\left\|\beta^{Y}\right\|\|\nabla f\|_{\infty}+\sum_{i, j=1}^{d} \frac{\left\|a_{i, j}^{Y}\right\|}{2}\left\|\frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}\right\| \\
& +\int_{\mathbb{R}^{d}}\|f(t, x+y)-f(t, x)-y \cdot \nabla f(t, x)\| m_{Y}(t, d y, x) \\
& \leq K_{T}\|\nabla f\|_{\infty}+\sum_{i, j=1}^{d} \frac{K_{T}^{2}}{2}\left\|\nabla^{2} f\right\|_{\infty}+\int_{\mathbb{R}^{d}}\|\nabla f\|_{\infty} \frac{\|y\|^{2}}{2} m_{Y}(t, d y, x) \\
& \leq K_{T}\|\nabla f\|_{\infty}+\sum_{i, j=1}^{d} \frac{K_{T}^{2}}{2}\left\|\nabla^{2} f\right\|_{\infty}+K_{T}^{\prime}\|\nabla f\|_{\infty}
\end{aligned}
$$

We have shown above that any two solutions $Y^{1}$ and $Y^{2}$ of the martingale problem have the same marginal distributions. Applying [11, Theorem 4.2], we conclude that $Y^{1}$ and $Y^{2}$ have the same finite-dimensional distributions. This shows the uniqueness in law of the Markovian projection $Y$.

Remark 2.1. In the case where there are no jumps ( $\mu_{X} \equiv 0$ ) we recover a result similar to Gyöngy [12, Theorem 4.6] but under slightly different assumptions. Namely, in $\left[1 \mathrm{~J} / \delta^{X}\right.$ is assumed to verify the ellipticity condition

$$
{ }^{t} \delta_{t}^{X} \cdot \delta_{t}^{X} \geq \alpha I
$$

for some $\alpha>0$, in which case the continuity conditions on $\delta^{Y}, \beta^{Y}$ are not necessary. In our case we require continuity of the coefficients but not ellipticity: the diffusion term may be degenerate.

Remark 2.2 (Uniqueness in law). Generally mimicking theorems [1], [9, 19, 19] aim at constructing a process $Y$ in a certain class (Markov, martingale, ..) whose marginals mimick $X$, but Theorem 1 also shows that if one restricts $Y$ in the class of Markov processes then $Y$ is also unique in law. Under these conditions we can speak unambiguously of the Markovian projection of X. In particular, this guarantees that if $X$ is already a Markov process, then $Y={ }^{d} X$.

Remark 2.3. The boundedness assumptions (H1) and (H2) may be relaxed to local boundedness, using localization techniques developed in [21, 23]. In the unbounded case additional conditions are needed to ensure that $X$ does not explode, see [23, Chapter 10].

### 2.2 Martingale-preserving property

An important property of the construction of $Y$ in Theoremil is that it preserves the (local) martingale property.

Proposition 1 (Martingale preserving property). Consider a semimartingale $X$ which verifies the assumptions of Theorem 1 and whose large jumps are integrable:

$$
E\left[\int_{|y|>1}|y| \mu_{X}(d t d y)\right]<\infty
$$

If $X$ is a martingale then its Markovian projection $Y$ is also a (local) martingale.
Proof. If $X$ is a martingale then $E\left[\int_{|y|>1}|y| \mu_{X}(d t d y)\right]<\infty$ and the uniqueness of its semimartingale decomposition entails that $\mathbb{P}\left(\beta_{t}^{X}+\int_{\|y\| \geq 1} y m_{X}(t, d y) d t=\right.$ 0 a.e.) $=1$ so for any $T>0$,

$$
\mathbb{P}\left(\int_{0}^{T} d t\left[\beta^{Y}(t, z)+\int_{\|y\| \geq 1} y m_{Y}(t, z, d y)\right]=0\right)=1 .
$$

The assumptions on $m_{X}, \delta^{X}$ then entail that $Y$, as a sum of an Ito integral and a compensated Poisson integral, is a local martingale.

Baker and Yor [1] call a process $X$ a 1-martingale if its one-dimensional (i.e. marginal) distributions can be matched by those of a martingale. Our explicit construction yields a sufficient condition for a semimartingale $X$ to be a 1-martingale:

Corollary 1. If

$$
\begin{equation*}
\forall t \geq 0, \forall z \in \mathbb{R}^{d}, \quad \mathbb{E}\left[\beta_{t}^{X}+\int_{|y|>1} y \mu_{X}(d t d y) \mid X_{t^{-}}=z\right]=0 \tag{6}
\end{equation*}
$$

then $X$ is a 1-martingale.

## 3 Mimicking an Ito semimartingale

The representation (2) is not the most commonly used in applications, where a process is constructed as the solution to a stochastic differential equation driven by a Brownian motion and a Poisson random measure:

$$
\begin{equation*}
Z_{t}=Z_{0}+\int_{0}^{t} \beta_{s}^{Z} d s+\int_{0}^{t} \delta_{s}^{Z} d W_{s}+\int_{0}^{t} \int \psi_{s}(y) \tilde{N}_{Z}(d s d y) \tag{7}
\end{equation*}
$$

where $\beta^{Z}$ and $\delta^{Z}$ are non-anticipative cadlag processes, $N_{Z}$ is a Poisson random measure on $\left[0, \infty\left[\times \mathbb{R}^{d}\right.\right.$ with intensity $\nu_{Z}(d y) d t$ where

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}\left(1 \wedge\|y\|^{2}\right) \nu_{Z}(d y)<\infty, \quad \tilde{N}_{Z}=N_{Z}-\nu_{Z}(d y) d t \tag{8}
\end{equation*}
$$

and the random jump amplitude $\psi:\left[0, T_{*}\right] \times \Omega \times \mathbb{R}^{d} \mapsto \mathbb{R}^{d}$ is $\mathcal{P} \otimes \mathcal{B}\left(\mathbb{R}^{d}\right)$ measurable, where $\mathcal{P}$ is the predictable $\sigma$-algebra on $\left[0, T_{*}\right] \times \Omega$. We assume

$$
\begin{equation*}
\psi_{t}(\omega, 0)=0 \quad \forall T>0, \quad \mathbb{E}\left[\int_{0}^{T} \int_{\mathbb{R}^{d}}\left(1 \wedge\left\|\psi_{t}(., y)\right\|^{2}\right) \nu_{Z}(d y) d t\right]<\infty \tag{H3}
\end{equation*}
$$

The difference between this representation and (2) is the presence of a random jump amplitude $\psi_{t}(\omega,$.$) in (7). The relation between these two representations$ for semimartingales has been discussed in great generality in 10, 16. Here we give a less general result which suffices for our purpose. The following result expresses $Z$ in the form (2) suitable for applying Theorem 11:

Lemma 1 (Absorbing the jump amplitude in the compensator). Under (H1) and (H3)

$$
Z_{t}=Z_{0}+\int_{0}^{t} \beta_{s}^{Z} d s+\int_{0}^{t} \delta_{s}^{Z} d W_{s}+\int_{0}^{t} \int \psi_{s}(z) \tilde{N}_{Z}(d s d z)
$$

where $N_{Z}$ is a Poisson random measure with intensity $\nu_{Z}(d z) d t$, can be also represented as

$$
\begin{equation*}
Z_{t}=Z_{0}+\int_{0}^{t} \beta_{s}^{Z} d s+\int_{0}^{t} \delta_{s}^{Z} d W_{s}+\int_{0}^{t} \int y \tilde{M}_{Z}(d s d y) \tag{9}
\end{equation*}
$$

where $M_{Z}$ is an integer-valued random measure on $\mathbb{R}^{+} \times \mathbb{R}^{d}$ with compensator $\mu_{Z}(\omega, d t, d y)$ given by

$$
\forall A \in \mathcal{B}\left(\mathbb{R}^{d}-\{0\}\right), \quad \mu_{Z}(\omega, d t, A)=\nu_{Z}\left(\psi_{t}^{-1}(\omega, A)\right) d t
$$

where $\psi_{t}^{-1}(\omega, A)=\left\{z \in \mathbb{R}^{d}, \psi_{t}(\omega, z) \in A\right\}$ denotes the inverse image of $A$ under the partial map.

Proof. The result can be deduced from [10, Théorème 12] but we sketch here the proof for completeness. A Poisson random measure $N_{Z}$ on $[0, T] \times \mathbb{R}^{d}$ can be represented as a counting measure for some random sequence $\left(T_{n}, U_{n}\right)$ with values in $[0, T] \times \mathbb{R}^{d}$.

$$
\begin{equation*}
N_{Z}=\sum_{n \geq 1} 1_{\left\{T_{n}, U_{n}\right\}}, \tag{10}
\end{equation*}
$$

Let $M_{Z}$ be the integer-valued random measure defined by:

$$
\begin{equation*}
M_{Z}=\sum_{n \geq 1} 1_{\left\{T_{n}, \psi_{T_{n}}\left(., U_{n}\right)\right\}} . \tag{11}
\end{equation*}
$$

$\mu_{Z}$, the predictable compensator of $M_{Z}$ is characterized by the following property [15. Thm 1.8.]: for any positive $\mathcal{P} \otimes \mathcal{B}\left(\mathbb{R}^{d}\right)$-measurable map $\chi:[0, T] \times \Omega \times \mathbb{R}^{d} \rightarrow$ $\mathbb{R}^{+}$and any $A \in \mathcal{B}\left(\mathbb{R}^{d}-\{0\}\right.$,

$$
\begin{equation*}
\mathbb{E}\left[\int_{0}^{T} \int_{A} \chi(t, y) M_{Z}(d t d y)\right]=\mathbb{E}\left[\int_{0}^{T} \int_{A} \chi(t, y) \mu_{Z}(d t d y)\right] \tag{12}
\end{equation*}
$$

Similarly, for $B \in \mathcal{B}\left(\mathbb{R}^{d}-\{0\}\right)$

$$
\mathbb{E}\left[\int_{0}^{T} \int_{B} \chi(t, y) N_{Z}(d t d y)\right]=\mathbb{E}\left[\int_{0}^{T} \int_{B} \chi(t, y) \nu_{Z}(d y) d t\right]
$$

Using formulae (10) and (11):

$$
\begin{aligned}
\mathbb{E}\left[\int_{0}^{T} \int_{A} \chi(t, y) M_{Z}(d t d y)\right] & =\mathbb{E}\left[\sum_{n \geq 1} \chi\left(t, \psi_{T_{n}}\left(., U_{n}\right)\right)\right] \\
& =\mathbb{E}\left[\int_{0}^{T} \int_{\psi_{t}^{-1}(., A)} \chi\left(t, \psi_{t}(., z)\right) N_{Z}(d t d z)\right] \\
& =\mathbb{E}\left[\int_{0}^{T} \int_{\psi_{t}^{-1}(., A)} \chi\left(t, \psi_{t}(., z)\right) \nu_{Z}(d z) d t\right]
\end{aligned}
$$

Formula (12) and the equalities above lead to:

$$
\mathbb{E}\left[\int_{0}^{T} \int_{A} \chi(t, y) \mu_{Z}(d t d y)\right]=\mathbb{E}\left[\int_{0}^{T} \int_{\psi_{t}^{-1}(., A)} \chi\left(t, \psi_{t}(., z)\right) \nu_{Z}(d z) d t\right]
$$

Given $\psi$ is a predictable random function, the uniqueness of the predictable compensator $\mu_{Z}$ (take $\phi \equiv I d$ in 15. Thm 1.8.] entails

$$
\begin{equation*}
\mu_{Z}(\omega, d t, A)=\nu_{Z}\left(\psi_{t}^{-1}(\omega, A)\right) d t \tag{13}
\end{equation*}
$$

Formula (13) defines a new measure $\mu_{Z}$ which is a Lévy kernel (see (H3))

$$
\int_{0}^{T} \int 1 \wedge\|y\|^{2} \mu_{Z}(d y d t)=\int_{0}^{T} \int 1 \wedge\left\|\psi_{t}(., y)\right\|^{2} \nu_{Z}(d y) d t<\infty
$$

To end the proof, we observe that, due to (H3):

$$
\begin{aligned}
\int_{0}^{t} \int y \tilde{M}_{Z}(d s d y) & =\int_{0}^{t} \int y\left(M_{Z}-\mu_{Z}\right)(d s d y) \\
& =\int_{0}^{t} \int \psi_{s}(z)\left(N_{Z}(d s d z)-\nu_{Z}(d z) d s\right. \\
& =\int_{0}^{t} \int \psi_{s}(z) \tilde{N}_{Z}(d s d z)
\end{aligned}
$$

In the case where $\psi_{t}(\omega,):. \mathbb{R}^{d} \mapsto \mathbb{R}^{d}$ is invertible and differentiable, we can characterize the density of the compensator $\mu$ as follows:

Lemma 2 (Differentiable case). If the Lévy measure $\nu_{Z}$ has a density $n_{Z}(z)$ and if $\psi_{t}(\omega,):. \mathbb{R}^{d} \mapsto \mathbb{R}^{d}$ has a differentiable inverse i.e. there exists

$$
\phi:\left[0, T_{*}\right] \times \Omega \times \mathbb{R}^{d} \mapsto \mathbb{R}^{d}
$$

such that

- $\phi$ is predictable i.e. $\mathcal{P} \otimes \mathcal{B}\left(\mathbb{R}^{d}\right)$-measurable.
- $\phi_{t}(\omega,.) \in C^{1}\left(\mathbb{R}^{d}, \mathbb{R}^{d}\right)$
- $\forall t \in\left[0, T^{*}\right], \forall z \in \mathbb{R}^{d}, \quad \phi_{t}\left(\omega, \psi_{t}(\omega, z)\right)=z$.
then $Z$, given in (7), has the representation

$$
Z_{t}=Z_{0}+\int_{0}^{t} \beta_{s}^{Z} d s+\int_{0}^{t} \delta_{s}^{Z} d W_{s}+\int_{0}^{t} \int y \tilde{M}_{Z}(d s d y)
$$

where $M_{Z}$ is an integer-valued random measure with compensator

$$
\mu_{Z}(\omega ; d t d y)=\left|\operatorname{det} \nabla \phi_{t}(\omega, y)\right| n_{Z}\left(\phi_{t}(\omega, y)\right) d t d y
$$

where $\nabla_{y} \phi_{t}$ denotes the Jacobian matrix of $\phi_{t}(\omega,$.$) .$
Proof. We recall from the proof of Lemma 1:

$$
\mathbb{E}\left[\int_{0}^{T} \int_{A} \chi(t, y) \mu_{Z}(d t d y)\right]=\mathbb{E}\left[\int_{0}^{T} \int_{\psi_{t}^{-1}(., A)} \chi\left(t, \psi_{t}(., z)\right) n_{Z}(z) d t d z\right]
$$

We then proceed to the change of variable $z=\phi_{t}(., y)$ :
$\mathbb{E}\left[\int_{0}^{T} \int_{\psi_{t}^{-1}(., A)} \chi\left(t, \psi_{t}(., z)\right) n_{Z}(z) d t d z\right]=\mathbb{E}\left[\int_{0}^{T} \int_{A} \chi(t, y)\left|\operatorname{det} \nabla \phi_{t}(., y)\right| n_{Z}\left(\phi_{t}(., y)\right) d t d y\right]$
The density appearing in the right hand side is predictable since $\phi$ does. By uniqueness of the predictable compensator $\mu_{Z}$, we get:

$$
\mu_{Z}(\omega ; d t d y)=\left|\operatorname{det} \nabla \phi_{t}(\omega, y)\right| n_{Z}\left(\phi_{t}(\omega, y)\right) d t d y
$$

To combine Lemma 2 and Theorem 11 we make a further assumption:
Assumption 3. The Lévy measure $\nu_{Z}$ admits a density $n_{Z}(y)$ with respect to the Lebesgue measure on $\mathbb{R}^{d}$ and:

$$
\begin{equation*}
\forall T>0, \exists K_{T}^{\prime}>0 \quad \int_{0}^{T} \int_{\|y\|>1} 1 \wedge\left\|\psi_{t}(., y)\right\|^{2} n_{Z}(y) d y d t<K_{T}^{\prime} \text { a.s } \tag{H3b}
\end{equation*}
$$

Theorem 2. Let $\left(Z_{t}\right)$

$$
Z_{t}=Z_{0}+\int_{0}^{t} \beta_{s}^{Z} d s+\int_{0}^{t} \delta_{s}^{Z} d W_{s}+\int_{0}^{t} \int \psi_{s}(y) \tilde{N}_{Z}(d s d y)
$$

where $\psi_{t}(\omega,):. \mathbb{R}^{d} \mapsto \mathbb{R}^{d}$ is invertible and differentiable with inverse $\phi_{t}(\omega,$.$) ,$ $\beta^{Z}$ and $\delta^{Z}$ and satisfies Assumption (H1) and $\nu_{Z}$ Assumption (H3b). Define

$$
\begin{align*}
\beta^{Y}(t, z) & =\mathbb{E}\left[\beta_{t}^{Z} \mid Z_{t^{-}}=z\right] ; \\
a^{Y}(t, z) & =\mathbb{E}\left[{ }^{t} \delta_{t}^{X} \delta_{t}^{X} \mid X_{t^{-}}=z\right] ;  \tag{14}\\
m_{Y}(t, y, z) & =\mathbb{E}\left[n_{Z}\left(\phi_{t}(y)\right) \mid \operatorname{det} \nabla \phi_{t}(y) \| Z_{t^{-}}=z\right]
\end{align*}
$$

Consider the stochastic differential equation

$$
\begin{equation*}
Y_{t}=Z_{0}+\int_{0}^{t} \beta^{Y}\left(u, Y_{u}\right) d u+\int_{0}^{t} \delta^{Y}\left(u, Y_{u}\right) d B_{u}+\int_{0}^{t} \int y \tilde{M}_{Y}(d u d y) \tag{15}
\end{equation*}
$$

where $\left(B_{t}\right)$ is a Brownian motion, $M_{Y}$ is an integer-valued random measure on $[0, T] \times \mathbb{R}$ with compensator $\mu_{Y}(\omega ; d t d y)=n_{Y}\left(t, y, Y_{t-}\right) d t d y$ and $\tilde{M}_{Y}$ the associated compensated random measure and $\delta^{Y}:\left[0, \infty\left[\times \mathbb{R}^{d} \mapsto M_{d \times n}(\mathbb{R})\right.\right.$ is a measurable function such that

$$
{ }^{t} \delta^{Y}(t, z) \delta^{Y}(t, z)=a^{Y}(t, z)
$$

If the functions $\beta^{Y}, a^{Y}$ and $m_{Y}$ are continuous in $(t, z)$ on $[0, T] \times \mathbb{R}^{d}$, then (15) defines uniquely the law, $\mathbb{Q}_{Z_{0}}$ of a Markov process $\left(\left(Y_{t}\right)_{t \in[0, T]},, \mathbb{Q}_{Z_{0}}\right)$, defined as the solution to the martingale problem on $C_{0}^{\infty}\left([0, T] \times \mathbb{R}^{d}\right)$ for the operator

$$
\begin{align*}
L f(t, x) & =\beta^{Y} \cdot \nabla f(t, x)+\sum_{i, j=1}^{d} \frac{a_{i, j}^{Y}(t, x)^{2}}{2} \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(t, x)  \tag{16}\\
& +\int_{\mathbb{R}^{d}}[f(t, x+y)-f(t, x)-y \cdot \nabla f(t, x)] n_{Y}(t, y, x) d y
\end{align*}
$$

and $\left(Y_{t}\right)_{t \geq 0}$ has the same marginal distributions as $\left(Z_{t}\right)_{t \geq 0}$ :

$$
\forall t \geq 0 Y_{t} \stackrel{\mathrm{~d}}{=} Z_{t} .
$$

Proof. We first use Lemma 2 to obtain the new representation of $Z$ :

$$
Z_{t}=Z_{0}+\int_{0}^{t} \beta_{s}^{Z} d s+\int_{0}^{t} \delta_{s}^{Z} d W_{s}+\int_{0}^{t} \int y \tilde{M}_{Z}(d s d y)
$$

Then, we observe that :

$$
\begin{aligned}
\int_{0}^{t} \int y \tilde{M}_{Z}(d s d y) & =\int_{0}^{t} \int_{\|y\| \leq 1} y \tilde{M}_{Z}(d s d y)+\int_{0}^{t} \int_{\|y\|>1} y\left[M_{Z}(d s d y)-\mu_{Z}(d s d y)\right] \\
& =\int_{0}^{t} \int_{\|y\| \leq 1} y \tilde{M}_{Z}(d s d y)+\int_{0}^{t} \int_{\|y\|>1} y M_{Z}(d s d y)-\int_{0}^{t} \int_{\|y\|>1} y \mu_{Z}(d s d y)
\end{aligned}
$$

where the terms above are well-defined thanks to (H3B). Lemma 2 leads to:

$$
\int_{0}^{t} \int_{\|y\|>1} y \mu_{Z}(d s d y)=\int_{0}^{t} \int_{\|y\|>1}\left\|\psi_{s}(., y)\right\|^{2} n_{Z}(y) d y d s
$$

Hence:

$$
\begin{aligned}
Z_{t} & =Z_{0}+\left[\int_{0}^{t} \beta_{s}^{Z} d s-\int_{0}^{t} \int_{\|y\|>1}\left\|\psi_{s}(., y)\right\|^{2} n_{Z}(y) d y d s\right]+\int_{0}^{t} \delta_{s}^{Z} d W_{s} \\
& +\int_{0}^{t} \int_{\|y\| \leq 1} y \tilde{M}_{Z}(d s d y)+\int_{0}^{t} \int_{\|y\|>1} y M_{Z}(d s d y)
\end{aligned}
$$

This representation has the form (2) and ( $\mathrm{H1}$ ) and ( H 3 b ) guarantee that the characteristics of $Z$ also verify the boundedness assumptions (H1) and (H2). The result is then obtained by applying Theorem 1 to the semimartingale $Z$.

## 4 Forward equations for semimartingales

An important property of continuous-time Markov processes is their link with partial (integro-)differential equation (PIDE) which allows to use analytical tools for studying their probabilistic properties. In particular the transition density of a Markov process solves the forward Kolmogorov equation (or FokkerPlanck equation) 22. The above results allow us to derive a forward PIDE for semimartingales: we show that under the assumptions of Theorem 1, the flow $t \mapsto p_{t}^{X}($.) of marginal distributions of a semi-martingale $X$ can be represented as the solution to a partial (integro-differential) equation:

Theorem 3 (Kolmogorov Forward equation). Let $X$ be a semimartingale given by (2) and denote $p_{t}^{X}(d x)$ the law of $X_{t}$. Under the assumptions of Theorem 1, $t \mapsto p_{t}^{X}$ is a weak solution, in the sense of distributions, of the forward equation:

$$
\begin{equation*}
\frac{\partial p_{t}^{X}}{\partial t}=L_{t}^{\star} \cdot p_{t}^{X} \tag{17}
\end{equation*}
$$

where $L^{\star}$ is the Fokker-Planck operator, defined as the adjoint of (5):

$$
\begin{align*}
\forall g & \in C_{0}^{\infty}\left(\mathbb{R}^{d}, \mathbb{R}\right), \\
L_{t}^{\star} g(x) & =-\nabla\left[\beta^{Y}(t, x) g(x)\right]+\nabla^{2}\left[\frac{a^{Y}(t, x)}{2} g(x)\right]  \tag{18}\\
& +\int_{\mathbb{R}^{d}}\left[g(x-z) m_{Y}(t, z, x-z)-g(x) m_{Y}(t, z, x)-1_{\|z\| \leq 1} z . \nabla_{x}\left[g(x) m_{Y}(t, d z, x)\right]\right]
\end{align*}
$$

where the coefficients $\beta^{Y}, a^{Y}, m_{Y}$ are defined as in (3).
Proof. Under the assumptions of Theorem 1, $X$ has the same marginals as $Y$ where $\left(\left(Y_{t}\right)_{t \geq 0}, \mathbb{Q}^{\left(t_{0}, x_{0}\right)}\right)$ is a solution of the martingale problem on $C_{0}^{\infty}\left(\left[0, \infty\left[\times \mathbb{R}^{d}\right)\right.\right.$
with initial condition $Y_{t_{0}}=y_{0}$ for the operator

$$
\begin{align*}
L_{t} f(x) & =\beta^{Y}(t, x) \nabla f(x)+\operatorname{tr}\left[\frac{a^{Y}(t, x)}{2} \nabla^{2} f(x)\right] \\
& +\int_{\mathbb{R}}\left[f(t, x+y)-f(t, x)-1_{\{|y| \leq 1\}} y \frac{\partial f}{\partial x}(t, x)\right] m_{Y}(t, d y, x), \tag{19}
\end{align*}
$$

Let $p_{t_{0}, T}\left(x_{0}, d y\right)$ be the law of $Y_{T}$ under $\mathbb{Q}^{t_{0}, y_{0}}$. The mimicking property of $Y$ implies that

$$
p_{t_{0}, T}\left(x_{0}, d y\right)=p_{T}^{X}(d y)
$$

so it suffices to show that $p_{t_{0}, T}\left(x_{0},.\right)$ verifies (16). Recall the Chapman-Kolmogorov equation for $p$ :

$$
p_{t_{0}, T}\left(x_{0}, d y\right)=\int_{\mathbb{R}^{d}} p_{t, T}(z, d y) p_{t_{0}, t}\left(x_{0}, d z\right)
$$

So for $f \in C_{0}^{\infty}\left(\left[0, \infty\left[\times \mathbb{R}^{d}\right)\right.\right.$
$\frac{1}{T-t} \mathbb{E}^{\mathbb{Q}^{t_{0}, y_{0}}}\left[f\left(Y_{T}\right)-f\left(Y_{t}\right) \mid Y_{t_{0}}=y_{0}\right]=\int_{\mathbb{R}^{d}} p_{t_{0}, t}\left(x_{0}, d z\right) \int_{\mathbb{R}^{d}} f(y) \frac{p_{t, T}(z, d y)-\epsilon_{z}(d y)}{T-t}$
where $\epsilon_{z}(d y)$ denotes a point mass at $y$. Since $f \in C_{0}^{\infty}\left(\left[0, \infty\left[\times \mathbb{R}^{d}\right) \subset \operatorname{dom}\left(L_{t}\right)\right.\right.$,

$$
\int_{\mathbb{R}^{d}} f(y) \frac{p_{t, T}(z, d y)-\epsilon_{z}(d y)}{T-t} \xrightarrow{T \downarrow t} L_{t} f(z)
$$

so
$\frac{1}{T-t} \mathbb{E}^{\mathbb{Q}^{t_{0}, y_{0}}}\left[f\left(Y_{T}\right)-f\left(Y_{t}\right) \mid Y_{t_{0}}=y_{0}\right] \xrightarrow{T \downarrow t} \int_{\mathbb{R}^{d}} p_{t_{0}, t}\left(x_{0}, d z\right) L_{t} f(z)=\int_{\mathbb{R}^{d}} p_{t}^{X}(d z) L_{t} f(z)$
Viewing $p_{t}^{X}$ as an element of the dual of $C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$ i.e. a Schwartz distribution, we have

$$
\forall f \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right), \quad<\frac{p_{T}^{X}-p_{t}^{X}}{T-t}, f>\stackrel{T \rightarrow t}{\rightarrow}<p_{t}^{X}, L_{t} f>=<L_{t}^{*} p_{t}^{X}, f>
$$

where $L_{t}^{*}$ is the adjoint of $L_{t}$ and $<, .,>$ is the duality product. $p^{X}$ is thus a weak solution, in the sense of distributions, of

$$
\frac{\partial p_{T}^{X}}{\partial T}=L_{t}^{*} p_{T}^{X}
$$

We now compute $L_{t}^{*} f$ for $f \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$.

$$
\forall f \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right) \forall t \geq t_{0} \quad f\left(Y_{t}\right)-\int_{t_{0}}^{t} L_{s} f\left(Y_{s-}\right) d s
$$

is a $\mathbb{Q}^{t_{0}, y_{0}}$-martingale, hence :

$$
\mathbb{E}^{\mathbb{Q}^{t_{0}, y_{0}}}\left[f\left(Y_{T}\right)-f\left(Y_{t}\right) \mid Y_{t_{0}}=y_{0}\right]=\mathbb{E}^{\mathbb{Q}^{t_{0}, y_{0}}}\left[\int_{t}^{T} L f\left(Y_{s-}\right) d s\right]
$$

Using Fubini

$$
\mathbb{E}^{\mathbb{Q}^{t_{0}, y_{0}}}\left[f\left(Y_{T}\right)-f\left(Y_{t}\right) \mid Y_{t_{0}}=y_{0}\right]=\int_{t}^{T} d s \int p_{t_{0}, s}\left(y_{0}, d x\right) L f(x)
$$

For $z \in \mathbb{R}^{d}$, define the translation operator $\tau^{z}$ by $\tau_{z} f(x)=f(x+z)$. Then

$$
\begin{aligned}
& \int p_{t_{0}, s}\left(y_{0}, d x\right) L_{s} f(x) \\
= & \int p_{t_{0}, s}\left(y_{0}, d x\right)\left[\beta^{Y}(s, x) \nabla f(x)+\frac{1}{2} \operatorname{tr}\left[a^{Y} \nabla^{2} f(x)\right.\right. \\
+ & \int_{|z|>1}\left(\tau_{z} f(x)-f(x)\right) m_{Y}(s, d z, x) \\
+ & \left.\int_{|z| \leq 1}\left(\tau_{z} f(x)-f(x)-z \frac{\partial f}{\partial x}(t, x)\right) m_{Y}(s, d z, x)\right] \\
= & \int\left[-f(x) \frac{\partial}{\partial x}\left[\beta^{Y}(s, x) p_{t_{0}, s}\left(y_{0}, d x\right)\right]+f(x) \frac{\partial^{2} f}{\partial x^{2}}\left[\frac{a^{Y}(s, x)}{2} p_{t_{0}, s}\left(y_{0}, d x\right)\right]\right. \\
+ & \int_{|z|>1} f(x)\left(\tau_{-z}\left(p_{t_{0}, s}\left(y_{0}, d x\right) m_{Y}(s, d z, x)\right)-p_{t_{0}, s}\left(y_{0}, d x\right) m_{Y}(s, d z, x)\right) \\
+ & \int_{|z| \leq 1} f(x)\left(\tau_{-z}\left(p_{t_{0}, s}\left(y_{0}, d x\right) m_{Y}(s, d z, x)\right)-p_{t_{0}, s}\left(y_{0}, d x\right) m_{Y}(s, d z, x)\right) \\
- & \left.z \frac{\partial}{\partial x}\left(p_{t_{0}, s}\left(y_{0}, d x\right) m_{Y}(s, d z, x)\right)\right]
\end{aligned}
$$

Dividing by $T-t$ and taking $T-t \rightarrow 0$, we obtain

$$
\frac{1}{T-t} \mathbb{E}^{\mathbb{Q}^{t_{0}, y_{0}}}\left[f\left(T, Y_{T}\right)-f\left(t, Y_{t}\right) \mid Y_{t_{0}}=y_{0}\right] \rightarrow \int f(T, x) L^{\star} \cdot p_{t_{0}, T}\left(y_{0}, d x\right)
$$

where $L^{*}$ is given by (18).

## 5 Examples

We now give two examples of stochastic models used in finance, where Markovian projections can be characterized in a more explicit manner than in the general results above.

### 5.1 Marked point processes

We first consider the case of a multivariate marked point process [7] with mark space $\mathbb{R}^{d}$. Using the notations of Section 2, let $M_{X}(d t d x)$ be an integer-valued random measure whose compensator $\mu_{X}(d t d x ; \omega)=m_{X}(t, d x ; \omega) d t$ is assumed to be a finite measure whose mass

$$
\lambda_{t}(\omega)=\int_{\mathbb{R}^{d}-\{0\}} m_{X}(t, d x ; \omega)
$$

represents the (random) jump intensity of the point process $N_{t}=M_{X}([0, t] \times$ $\mathbb{R}^{d}$ ). Denote by $T_{1} \leq T_{2} \leq$.. the jump times of $N$. The process

$$
X_{t}=\int_{0}^{t} \int_{\mathbb{R}^{d}-\{0\}} x M_{X}(d t d x)
$$

is then a marked point process and may be represented as

$$
X_{t}=\sum_{k=1}^{N_{t}} Z_{k}
$$

where the "mark" $Z_{k}$ is distributed according to

$$
F_{t}(d x ; \omega)=\frac{m_{X}(t, d x ; \omega)}{\lambda_{t}(\omega)}
$$

Marked point processes form an important subclass of the processes considered in section 2 and the corresponding Markovian projection results are of interest in queuing theory and credit risk modeling. Markovian projection of point processes was first discussed in the case of queues by Brémaud [ 1 , p. 30] under the name of "first order equivalence" of queues. A mimicking theorem for marked point processes with IID marks (i.e. $F_{t}(d x ; \omega)=F(d x)$ ) is given in [6]. We recover here these results as a special case of Theorem 1], which covers the case of arbitrary (i.e. not necessarily independent) marks:

Proposition 2 (Markovian projection of a marked point process). There exists a weak solution to the stochastic differential equation

$$
Y_{t}=\int_{0}^{t} \int_{\mathbb{R}^{d}} x M_{Y}(d t d x)
$$

where $M_{Y}(d t d x)$ is an integer-valued random measure with compensator $m_{Y}\left(t, d x ; Y_{t-}\right) d t$ where

$$
\forall A \in \mathcal{B}\left(\mathbb{R}^{d}\right) \quad m_{Y}(t, A ; z)=E\left[m_{X}(t, A, .) \mid X_{t-}=z\right]
$$

The solution is a Markovian marked point process with intensity

$$
\begin{equation*}
\lambda^{Y}(t, z)=E\left[\lambda_{t} \mid X_{t-}=z\right] \tag{20}
\end{equation*}
$$

and mark distribution $F^{Y}\left(t, Y_{t-},.\right)$ where

$$
\begin{equation*}
F^{Y}(t, z ; d x)=\frac{m_{Y}(t, d x, z)}{\lambda^{Y}(t, z)} \tag{21}
\end{equation*}
$$

which mimicks the marginal distributions of $X: \forall t \geq 0, X_{t} \stackrel{\mathrm{~d}}{=} Y_{t}$.

Proof. $\left(Y_{t}\right)$ is built as the Markovian projection of $\left(X_{t}\right)$ defined in Theorem 1 . Since $m_{X}$ is a finite measure, this entails that $m^{Y}$ is also a finite measure. The intensity $\lambda^{Y}=m^{Y}\left(\mathbb{R}^{d}-\{0\}\right)$ then satisfies :

$$
\begin{aligned}
\lambda^{Y}(t, z) & =\int_{\mathbb{R}^{d}-\{0\}} m_{Y}(t, d x ; z) \\
& =\mathbb{E}\left[\int_{\mathbb{R}^{d}-\{0\}} m_{X}(t, d x, .) \mid X_{t-}=z\right] \\
& =\mathbb{E}\left[\lambda_{t} \mid X_{t-}=z\right]
\end{aligned}
$$

where the Fubini theorem is used using the fact that $m_{X}$ is a finite measure. This ends the proof.

### 5.2 Time changed Lévy processes

Models based on time-changed Lévy processes have been the focus of much recent work especially in mathematical finance [5]. Let $L_{t}$ be a Lévy process, $\left(b, \sigma^{2}, \nu_{L}\right)$ be its characteristic triplet, $N_{L}$ its jump measure. Define

$$
X_{t}=L_{T_{t}} \quad T_{t}=\int_{0}^{t} \theta_{s} d s
$$

where $\left(\theta_{t}\right)$ is a locally bounded $\mathcal{F}_{t}$-adapted positive cadlag process, interpreted as the rate of time change.

Theorem 4 (Markovian projection of time-changed Lévy processes). Let $L$ be a scalar Lévy process with triplet $\left(b, \sigma^{2}, \nu_{L}\right)$ and let $X_{t}=L\left(\int_{0}^{t} \theta_{s} d s\right)$ where $\theta_{t}>0$ is a positive semimartingale. Define

$$
\alpha(t, x)=E\left[\theta_{t} \mid X_{t-}=x\right]
$$

and suppose that $\alpha(t, z)$ is continuous in $(t, z)$ on $[0, \infty \times \mathbb{R}$. Then

- $\left(X_{t}\right)$ has the same marginals as $\left(Y_{t}\right)$, defined as the weak solution of

$$
\begin{aligned}
Y_{t}= & X_{0}+\int_{0}^{t} \sigma \sqrt{\alpha\left(s, Y_{s-}\right)} d B_{s}+\int_{0}^{t} b \alpha\left(s, Y_{s-}\right) d s \\
& +\int_{0}^{t} \int_{|z| \leq 1} z \tilde{N}(d s d z)+\int_{0}^{t} \int_{|z|>1} z N(d s d z)
\end{aligned}
$$

where $N$ is an integer-valued random measure with compensator $\nu(d t d z ; \omega)=$ $\alpha\left(t, Y_{t-}(\omega)\right) \nu_{L}(d z) d t$.

- The marginal distribution $p_{t}^{X}$ of $X_{t}$ is a weak solution of the forward equation:

$$
\frac{\partial p_{t}^{X}}{\partial t}=L_{t}^{\star} \cdot p_{t}^{X}
$$

where, $L_{t}^{*}$ is given by

$$
\begin{aligned}
L_{t}^{\star} g(x) & =-b \frac{\partial}{\partial x}[\alpha(t, x) g(x)]+\frac{\sigma^{2}}{2} \frac{\partial^{2}}{\partial x^{2}}\left[\alpha^{2}(t, x) g(x)\right] \\
& +\int_{\mathbb{R}^{d}} \nu_{L}(d z)\left[g(x-z) \alpha(t, x-z)-g(x) \alpha(t, x)-1_{\|z\| \leq 1} z \cdot \frac{\partial}{\partial x}[g(x) \alpha(t, x)]\right]
\end{aligned}
$$

Proof. Consider the Lévy-Ito decomposition of $L$ :

$$
L_{t}=b t+\sigma W_{t}+\int_{0}^{t} \int_{|z| \leq 1} z \tilde{N}_{L}(d s d z)+\int_{0}^{t} \int_{|z|>1} z N_{L}(d s d z)
$$

$X$ is then expressed as

$$
\begin{aligned}
X_{t} & =X_{0}+\sigma W\left(T_{t}\right)+b T_{t} \\
& +\int_{0}^{T_{t}} \int_{|z| \leq 1} z \tilde{N}_{L}(d s d z)+\int_{0}^{T_{t}} \int_{|z|>1} z N_{L}(d s d z)
\end{aligned}
$$

$W\left(T_{t}\right)$ is a continuous martingale with quadratic variation $T_{t}=\int_{0}^{t} \theta_{s} d s$ so, if $B$ is a Brownian motion independent of $Z$, we have

$$
W\left(T_{t}\right) \stackrel{d}{=} \int_{0}^{t} \sqrt{\theta_{s}} d B_{s}
$$

Hence $X_{t}$ can be written as :

$$
\begin{aligned}
X_{t} & =X_{0}+\int_{0}^{t} \sigma \sqrt{\theta_{s}} d B_{s}+\int_{0}^{t} b \theta_{s} d s \\
& +\int_{0}^{t} \int_{|z| \leq 1} z \theta_{s} \tilde{N}_{L}(d s d z)+\int_{0}^{t} \int_{|z|>1} z \theta_{s} N_{L}(d s d z)
\end{aligned}
$$

Using the notations of Theorem 1,

$$
\beta_{t}^{X}=b \theta_{t} \quad \delta_{t}^{X}=\sigma \sqrt{\theta_{t}} \quad m_{X}(t, y)=\theta_{t} \nu_{L}(d y) .
$$

Assumption $\left(H_{1}\right)$ and $\left(H_{2}\right)$ are satisfied, and :

$$
\begin{aligned}
\beta^{Y}(t, z) & =\mathbb{E}\left[\beta_{t}^{X} \mid X_{t^{-}}=z\right]=b \alpha(t, z) ; \\
\delta^{Y}(t, z) & =\mathbb{E}\left[\delta_{t}^{X} \mid X_{t^{-}}=z\right]=\sigma \sqrt{\alpha(t, z)} \\
m_{Y}(t, y, z) & =\mathbb{E}\left[m_{X}(t, y) \mid X_{t^{-}}=z\right]=\alpha(t, z) \nu_{L}(d y) .
\end{aligned}
$$

are all continuous in $(\mathrm{t}, \mathrm{z})$ on $[0, \infty[\times \mathbb{R}$, an application of Theorem 1$]$ and Theorem 3 yields the result.

The impact of the random time change on the marginals can be captured by making the characteristics state dependent

$$
\left(b \alpha\left(t, X_{t-}\right), \sigma^{2} \alpha\left(t, X_{t-}\right), \alpha\left(t, X_{t-}\right) \nu_{Z}\right)
$$

by introducing the same adjustment factor $\alpha\left(t, X_{t-}\right)$ to the drift, diffusion coefficient and Lévy measure. In particular if $\alpha(t, x)$ is affine in $x$ we get an affine process [8] where the affine dependence of the characteristics with respect to the state are restricted to be colinear, which is rather restrictive. This remark shows that time-changed Lévy processes, which in principle allow for a wide variety of choices for $\theta$ and $L$, may not be as flexible as apparently simpler affine models when it comes to reproducing marginal distributions.

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