Cooperation between Human and Machine for Shop Scheduling Under Uncertainties

Guillaume Pinot Nasser Mebarki Jean-Michel Hoc

IRCCyN — UMR CNRS 6597 Nantes, France firstname.lastname@irccyn.ec-nantes.fr

HOPS Conference 2008



Guillaume Pinot, Nasser Mebarki, Jean-Michel Hoc

Cooperation for Scheduling Under Uncertainties

< 同 > < 三 > < 三

1/22

- 1 Introduction
- **2** Group Sequencing
- **3** The human-machine system of ORABAID for the reactive phase
- 4 A new human-machine system for the reactive phase

5 Conclusion

< 同 > < 三 > < 三

1 Introduction

2 Group Sequencing

3 The human-machine system of ORABAID for the reactive phase

A new human-machine system for the reactive phase

5 Conclusion

- 4 同 ト 4 目 ト 4 目

Introduction

Group sequencing:

- is a scheduling method;
- describes a set of schedules;
- guarantees a minimal quality corresponding to the worst case.

A better human-machine system for the execution of the schedule can be done.



Introduction

Group sequencing:

- is a scheduling method;
- describes a set of schedules;
- guarantees a minimal quality corresponding to the worst case.

A better human-machine system for the execution of the schedule can be done.

1 Introduction

2 Group Sequencing

3 The human-machine system of ORABAID for the reactive phase

A new human-machine system for the reactive phase

5 Conclusion

< 同 > < 三 > < 三

Group Sequencing

Group sequencing:

- provides sequential flexibility during the execution of the schedule;
- guarantees a minimal quality corresponding to the worst case.

To manage sequential flexibility, usage of "groups of permutable operations."



- 4 同 ト 4 ヨ ト 4 ヨ ト

Group Sequencing

Group sequencing:

- provides sequential flexibility during the execution of the schedule;
- guarantees a minimal quality corresponding to the worst case.

To manage sequential flexibility, usage of "groups of permutable operations."

< 同 > < 三 > < 三

Example: a Job Shop Problem

i: the index of the operations, $\Gamma^{-}(i)$: the set of the predecessors of O_i , m_i : the resource needed by O_i , p_i : the processing time needed by O_i .

A Job Shop Problem											
	i	1	2	3	4	5	6	7	8	9	
	$\Gamma^{-}(i)$	Ø	{1}	{2}	Ø	{4}	{5}	Ø	{7}	{8}	
	mi	M_1	M_2	M_3	M_2	M_3	M_1	M_3	M_1	M_2	
	p _i	3	3	3	4	3	1	2	2	2	

A Solution to This Problem



Guillaume Pinot, Nasser Mebarki, Jean-Michel Hoc

Cooperation for Scheduling Under Uncertainties

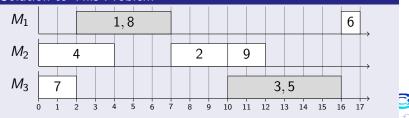
7/22

Example: a Job Shop Problem

i: the index of the operations, $\Gamma^{-}(i)$: the set of the predecessors of O_i , m_i : the resource needed by O_i , p_i : the processing time needed by O_i .

A Job Shop Problem											
	i	1	2	3	4	5	6	7	8	9	
	$\Gamma^{-}(i)$	Ø	{1}	{2}	Ø	{4}	{5}	Ø	{7}	{8}	
	m _i	M_1	M_2	M_3	M_2	M_3	M_1	M_3	M_1	M_2	
	p _i	3	3	3	4	3	1	2	2	2	

A Solution to This Problem

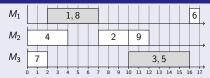


Guillaume Pinot, Nasser Mebarki, Jean-Michel Hoc

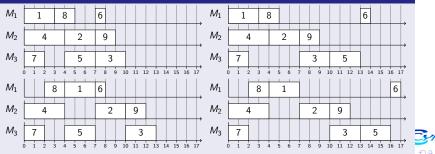
Cooperation for Scheduling Under Uncertainties

Execution of the Example

The Group Sequence



The Corresponding Semi-Active Schedules



Guillaume Pinot, Nasser Mebarki, Jean-Michel Hoc

Why is Group Sequencing Interesting?

Why is group sequencing interesting?

- proactive reactive method;
- flexibility on sequences;
- widely studied in the last twenty years: [Erschler and Roubellat, 1989, Wu et al., 1999, Artigues et al., 2005]
- no need to model the uncertainties;
- the method is able to absorb some uncertainties: [Wu et al., 1999, Esswein, 2003, Pinot et al., 2007];
- evaluation of the group sequence in the worst case in polynomial time for *minmax* regular objectives as C_{\max} and L_{\max} .
- evaluation of the group sequence in the best-case is feasible for any regular objective [Pinot and Mebarki, 2008].

9/22

Why is Group Sequencing Interesting?

Why is group sequencing interesting?

- proactive reactive method;
- flexibility on sequences;
- widely studied in the last twenty years: [Erschler and Roubellat, 1989, Wu et al., 1999, Artigues et al., 2005]
- no need to model the uncertainties;
- the method is able to absorb some uncertainties: [Wu et al., 1999, Esswein, 2003, Pinot et al., 2007];
- evaluation of the group sequence in the worst case in polynomial time for *minmax* regular objectives as C_{\max} and L_{\max} .
- evaluation of the group sequence in the best-case is feasible for any regular objective [Pinot and Mebarki, 2008].

A better human-machine system can be done for the reactive phase.

1 Introduction

2 Group Sequencing

3 The human-machine system of ORABAID for the reactive phase

A new human-machine system for the reactive phase

5 Conclusion

イロト イボト イヨト イヨト

ORABAID

ORABAID method is:

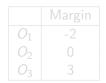
- the first system using group sequencing;
- used in the ORDO software [Roubellat et al., 1995];
- the only system used in real manufacturing systems.

・ 同 ト ・ ヨ ト ・ ヨ

Description of the human-machine system

The human-machine system for the reactive phase is based on the free sequential margin:

- free margin adapted for group sequencing;
- easily computable;
- allow to monitor the satisfaction of the deadlines;
- it is recommended to execute the operation with the greatest margin.



< 同 > < 三 > < 三

Description of the human-machine system

The human-machine system for the reactive phase is based on the free sequential margin:

- free margin adapted for group sequencing;
- easily computable;
- allow to monitor the satisfaction of the deadlines;
- it is recommended to execute the operation with the greatest margin.

	Margin		
O_1	-2		
<i>O</i> ₂	0		
<i>O</i> ₃	3		

・ 同 ト ・ ヨ ト ・ ヨ

Analysis of the human-machine-system

Advantages:

- The system alerts the human when deadlines must not be satisfied;
- The human makes the decision.

Drawbacks:

- The system recommends a decision;
- The workload to analyze the different decision is very high;
- The human can became inactive.

Analysis of the human-machine-system

Advantages:

- The system alerts the human when deadlines must not be satisfied;
- The human makes the decision.

Drawbacks:

- The system recommends a decision;
- The workload to analyze the different decision is very high;
- The human can became inactive.

- 1 Introduction
- **2** Group Sequencing
- **3** The human-machine system of ORABAID for the reactive phase
- 4 A new human-machine system for the reactive phase

5 Conclusion

< ロ > < 同 > < 回 > < 回 >

Description of the human-machine system

Different indicators:

- free sequential margin;
- worst-case quality;
- best-case quality;
- processing time;
- etc.

	Margin	$L_{\rm max}^{WC}$	L_{\max}^{BC}	pi
O_1	-2	2		5
02		1		3
<i>O</i> ₃	3	-1	-2	7

▲ 同 ▶ ▲ 国 ▶ ▲ 国

15/22

Description of the human-machine system

Different indicators:

- free sequential margin;
- worst-case quality;
- best-case quality;
- processing time;
- etc.

	Margin	$L_{\rm max}^{WC}$	L_{\max}^{BC}	pi
O_1	-2	2	0	5
<i>O</i> ₂	0	1	0	3
<i>O</i> ₃	3	-1	-2	7

Goals of this system

To correct ORABAID's drawbacks:

- The system does not recommend a decision;
- The machine exposes its knowledge to the human, which should help the human to make the decision;
- The human should became active.

・ 同 ト ・ ヨ ト ・ ヨ

1 Introduction

2 Group Sequencing

3 The human-machine system of ORABAID for the reactive phase

A new human-machine system for the reactive phase

5 Conclusion

イロト イボト イヨト イヨト

Conclusion

We have proposed a new human-machine system for the reactive phase of group sequencing:

- it corrects ORABAID's drawbacks;
- it uses the best-case and the worst-case quality;
- the human should became active.

To validate this proposition, experiments will study different aspects:

- the implication of the operator in the decision;
- the effectiveness of the new decision support system in comparison with the other;
- the usage of the indicators by the operator.

These experiments will be done in collaboration with Clément Guérin and Jean-Michel Hoc.

< ロ > < 同 > < 三 > < 三

Conclusion

We have proposed a new human-machine system for the reactive phase of group sequencing:

- it corrects ORABAID's drawbacks;
- it uses the best-case and the worst-case quality;
- the human should became active.

To validate this proposition, experiments will study different aspects:

- the implication of the operator in the decision;
- the effectiveness of the new decision support system in comparison with the other;
- the usage of the indicators by the operator.

These experiments will be done in collaboration with Clément Guérin and Jean-Michel Hoc.

Thank You

Thank you for your attention.



Bibliography I

 Artigues, C., Billaut, J.-C., and Esswein, C. (2005).
 Maximization of solution flexibility for robust shop scheduling. European Journal of Operational Research, 165(2):314–328.

Erschler, J. and Roubellat, F. (1989).

An approach for real time scheduling for activities with time and resource constraints.

In Slowinski, R. and Weglarz, J., editors, *Advances in project scheduling*. Elsevier.

Esswein, C. (2003).

Un apport de flexibilité séquentielle pour l'ordonnancement robuste.

Thèse de doctorat, Université François Rabelais Tours.

20/22

・ 同 ト ・ ヨ ト ・ ヨ

Bibliography II

Pinot, G., Cardin, O., and Mebarki, N. (2007).

A study on the group sequencing method in regards with transportation in an industrial FMS.

In Proceedings of the IEEE SMC 2007 International Conference.

- Pinot, G. and Mebarki, N. (2008).
 Le meilleur des cas dans un ordonnancement de groupes.
 In ROADEF 2008, Livre des résumés.
- Roubellat, F., Billaut, J.-C., and Villaumie, M. (1995). Ordonnancement d'atelier en temps réel : d'ORABAID à ORDO.

Revue d'automatique et de productique appliquées, 8(5):683–713.

< ロ > < 同 > < 三 > < 三

Bibliography III



Wu, S. D., Byeon, E.-S., and Storer, R. H. (1999).

A graph-theoretic decomposition of the job shop scheduling problem to achieve scheduling robustness.

Operations Research, 47(1):113–124.



- 4 同 ト 4 ヨ ト 4 ヨ ト