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DISTANCE TO THE DISCRIMINANT

C. RAFFALLI

ABSTRACT. We will study algebraic hyper-surfaces on the real unit sphere S^{n-1} given by an homogeneous polynomial of degree d in n variables with the view point, rarely exploited, of Euclidian geometry using Bombieri's scalar product and norm. This view point is mostly present in work about the topology of random hyper-surfaces [4, 3].

Our first result (lemma 2.2 page 4) is a formula for the distance $\text{dist}(P, \Delta)$ of a polynomial to the *real discriminant* Δ , i.e. the set of polynomials with a real singularity on the sphere. This formula is given for any distance coming from a scalar product on the vector space of polynomials.

Then, we concentrate on Bombieri scalar product and its remarkable properties. For instance we establish a combinatoric formula for the scalar product of two products of linear-forms (lemma 3.2 page 5) which allows to give a (new ?) proof of the invariance of Bombieri's norm by composition with the orthogonal group. These properties yield a simple formula for the distance in theorem 4.3 page 9 from which we deduce the following inequality:

$$\text{dist}(P, \Delta) \leq \min_{x \text{ critical point of } P \text{ on } S^{n-1}} |P(x)|$$

The definition 4.2 page 8 classifies in two categories the ways to make a polynomial singular to realise the distance to the discriminant. Then, we show, in theorem 5.3 page 15, that one of the category is forbidden in the case of an *extremal* hyper-surfaces (i.e. with maximal Betti numbers). This implies as a corollary 5.4 (page 19) that the above inequality becomes an equality in that case.

The main result in this paper concerns extremal hyper-surfaces $P = 0$ that maximise the distance to the discriminant (with $\|P\| = 1$). They are very remarkable objects which enjoy properties similar to those of quadratic forms: they are linear combination of power of linear forms $x \mapsto \langle x | u_i \rangle^d$ where the vector u_i are the critical points of P on S^{n-1} corresponding to the least positive critical value of $|P|$. This is corollary 6.2 page 21 of a similar theorem 6.1 page 20 for all algebraic hyper-surfaces.

We also obtain metric information about algebraic hyper-surfaces. First, in the case of extremal hyper-surface, we give an upper bound (theorem 7.3 page 22) on the length of an integral curve of the gradient of P in the band where $|P|$ is less than the least positive critical value of $|P|$. Then, a general lower bound on the size and distance between the connected components (corollary 8.1 and theorem 8.2).

The last section will present experimental results among which are five extremal sextic curves far from the discriminant. These are obtained by very long running numerical optimisation (many months).

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1. NOTATION

Let \mathcal{S}^{n-1} be the unit sphere of \mathbb{R}^n . We write $\|x\|$ the usual Euclidean norm on \mathbb{R}^n .

We consider $\mathbb{E} = \mathbb{R}[X_1, \dots, X_n]_d$ the vector space of homogeneous polynomials in $n > 1$ variables of degree $d > 1$. Let N be the dimension of this vector space, we have $N = \binom{d+n-1}{n-1} \geq n$

Let $\langle \cdot, \cdot \rangle$ be a scalar product on \mathbb{E} and $\| \cdot \|$ the associated norm. We use the same notation for the scalar product and norm of \mathbb{E} as for \mathbb{R}^n , the context should make it clear what norm we are using.

Let $\mathcal{B} = (E_1, \dots, E_N)$ be an orthonormal basis of \mathbb{E} .

For $x \in \mathbb{R}^n$, $C(x)$ denotes the line vector $(E_1(x), \dots, E_N(x))$ and $B_i(x)$ for $i \in \{1, \dots, n\}$ denotes the line vector $(\frac{\partial E_1(x)}{\partial x_i}, \dots, \frac{\partial E_N(x)}{\partial x_i})$. Let $B(x)$ be the $n \times N$ matrix whose lines are $B_i(x)$ for $i \in \{1, \dots, n\}$.

For $P \in \mathbb{E}$, let $P_{\mathcal{B}}$ be the column vector coordinates of P in the basis \mathcal{B} . We may write:

$$P(x) = C(x)P_{\mathcal{B}}, \frac{\partial P(x)}{\partial x_i} = B_i(x)P_{\mathcal{B}} \text{ and } \nabla P(x) = B(x)P_{\mathcal{B}}$$

We will also use the following notation for the normal and tangent component of a vector field $V(x)$ defined for $x \in \mathcal{S}^{n-1}$:

$$\begin{aligned} V^N(x) &= \langle x | V(x) \rangle x \\ V^T(x) &= V(x) - V(x)^N \end{aligned}$$

In the particular case of $\nabla P(x)$, we write $\nabla^T P(x)$ and we have Euler's relation $\nabla^N P(x) = dP(x)x$, which gives:

$$\nabla P(x) = \nabla^T P(x) + dP(x)x \text{ with } \langle \nabla^T P(x) | x \rangle = 0$$

Similarly, we write $\mathcal{H}P(x)$ for the hessian matrix of P at x . We have that

$$\begin{aligned} {}^tV\mathcal{H}P(x)x &= {}^tV\mathcal{H}P(x)V = (d-1)\langle \nabla P(x)|V \rangle \\ &= (d-1)\langle \nabla^T P(x)|V \rangle + d(d-1)P(x)\langle x|V \rangle \\ \text{and } {}^tV\mathcal{H}P(x)x &= d(d-1)P(x)\|x\|^2 \end{aligned}$$

Hence, we can find a symmetric matrix $\mathcal{H}^T P(x)$ whose kernel contains x and such that :

$${}^tV\mathcal{H}P(x)V = d(d-1)P(x)\langle x|V \rangle^2 + 2(d-1)\langle \nabla^T P(x)|V \rangle \langle x|V \rangle + {}^tV\mathcal{H}^T P(x)V$$

Geometrically, $\mathcal{H}^T P(x)$ is the matrix of the linear application defined as $\pi(x) \circ \nabla^2 P(x) \circ \pi(x)$ where $\pi(x)$ is the projection on the plane tangent to the unit sphere at x and $\nabla^2 P(x)$ is the second derivative of P seen as a linear application.

Fact 1.1. *The matrix $B(x)$ is always of maximal rank (i.e. of rank n) for all $x \neq 0$.*

Proof. Let us prove first that $B(x)$ is of maximal rank when the elements of \mathcal{B} are monomials with arbitrary coefficients. By symmetry, we may assume that $x_1 \neq 0$. Thus, $B(x)$ contains the following columns coming from the partial derivatives of $a_i x_1^{n-1} x_i$ for $1 \leq i \leq n$:

$$\begin{pmatrix} a_1 n x_1^{n-1} & a_2 (n-1) x_1^{n-2} x_2 & a_3 (n-1) x_1^{n-2} x_3 & \dots & a_n (n-1) x_1^{n-2} x_n \\ 0 & a_2 x_1^{n-1} & 0 & \dots & 0 \\ 0 & 0 & a_3 x_1^{n-1} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & a_n x_1^{n-1} \end{pmatrix}$$

This proves that the n lines of $B(x)$ are linearly independent when the basis contains only monomials. Second, If for some basis $B(x)$ where of rank less than n , this would yield a linear combination with some non zero coefficients such that $\sum_{1 \leq i \leq n} \lambda_i B_i(x) = 0$, implying that for any polynomial P we would have $(\lambda_1, \dots, \lambda_n)B(x)P_{\mathcal{B}} = \sum_{1 \leq i \leq n} \lambda_i \frac{\partial P}{\partial x_i}(x) = 0$, and this being independent of the basis would mean that $B(x)$ is never of maximal rank for that x . \square

2. DISTANCE TO THE REAL DISCRIMINANT

Definition 2.1. *The real discriminant Δ of the space \mathbb{E} of polynomials of degree d in n variables is the set of polynomials $P \in \mathbb{E}$ such that there exists $x \in \mathcal{S}^{n-1}$ where $P(x) = 0$ and $\nabla P(x) = 0$.*

This can be written

$$\Delta = \bigcup_{x \in \mathcal{S}^{n-1}} \Delta_x \text{ where } \Delta_x = \{P \in \mathbb{E}; B(x)P_{\mathcal{B}} = 0 \text{ and } C(x)P_{\mathcal{B}} = 0\}$$

As usual, the equation $C(x)P_{\mathcal{B}} = 0$ is redundant because of the Euler's relation which can be written here $C(x) = \frac{1}{d}(x_1, \dots, x_n)B(x)$.

Therefore, the discriminant Δ is a union of sub-vector spaces of \mathbb{E} of codimension n (given that $B(x)$ is of maximal rank).

Let P be a given polynomial in \mathbb{E} . We give a way to compute the distance between P and Δ .

We first choose $x_0 \neq 0$ and we compute the distance from P to Δ_{x_0} . Therefore, we look for $Q \in \mathbb{E}$, such that:

- $P + Q \in \Delta_{x_0}$.
- $\|Q\|$ minimal.

The first condition may be written

$$B(x_0)(P_{\mathcal{B}} + Q_{\mathcal{B}}) = 0$$

The second condition is equivalent to Q orthogonal to Δ_{x_0} , which means that $Q_{\mathcal{B}}$ is a linear combination of the vectors ${}^t B_i(x_0)$, the columns of ${}^t B(x_0)$.

This means that there exists a column vector H of size n such that

$$Q_{\mathcal{B}} = {}^t B(x_0)H.$$

This gives:

$$B(x_0)P_{\mathcal{B}} + B(x_0){}^t B(x_0)H = 0$$

Let us define

$$A(x) = B(x){}^t B(x) \text{ and } M(x) = A(x)^{-1}$$

$B(x)$ is a $n \times N$ matrix of maximal rank with $n \leq N$. This implies that $A(x)$ is an $n \times n$ symmetrical and definite matrix for all $x \neq 0$. Hence, $M(x)$ is well defined and symmetrical.

We have

$$B(x_0)P_{\mathcal{B}} + A(x_0)H = 0 \text{ which implies } H = -M(x_0)B(x_0)P_{\mathcal{B}}$$

and

$$Q_{\mathcal{B}} = -{}^t B(x_0)M(x_0)B(x_0)P_{\mathcal{B}}$$

We can now write the distance to Δ_{x_0} by

$$\begin{aligned} \text{dist}^2(P, \Delta_{x_0}) &= \|Q\|^2 \\ &= {}^t Q_{\mathcal{B}} Q_{\mathcal{B}} \\ &= {}^t P_{\mathcal{B}} {}^t B(x_0)M(x_0)B(x_0){}^t B(x_0)M(x_0)B(x_0)P_{\mathcal{B}} \\ &= {}^t P_{\mathcal{B}} {}^t B(x_0)M(x_0)A(x_0)M(x_0)B(x_0)P_{\mathcal{B}} \\ &= {}^t P_{\mathcal{B}} {}^t B(x_0)M(x_0)B(x_0)P_{\mathcal{B}} \\ &= {}^t \nabla P(x_0)M(x_0)\nabla P(x_0) \end{aligned}$$

The above formula established for any $x_0 \neq 0$ is homogeneous in x_0 . We can therefore state our first lemma:

Lemma 2.2. *Let (E_1, \dots, E_N) be an orthonormal basis of $\mathbb{E} = \mathbb{R}[X_1, \dots, X_n]_d$ for a given scalar product. Let $B(x)$ be the $n \times N$ matrix defined by:*

$$B(x) = \begin{pmatrix} \frac{\partial E_j(x)}{\partial x_i} \end{pmatrix}_{\substack{1 \leq i \leq n \\ 1 \leq j \leq N}}$$

For any homogeneous polynomial $P \in \mathbb{E}$, the distance to the discriminant Δ associated to the given scalar product is given by

$$\text{dist}(P, \Delta) = \min_{x \in \mathbb{S}^{n-1}} \sqrt{{}^t \nabla P(x) M(x) \nabla P(x)} \text{ with } M(x) = (B(x)^t B(x))^{-1}$$

3. THE BOMBIERI NORM

The above lemma can be simplified in the particular case of Bombieri norm[1]. To do so, we recall the definition and properties of Bombieri norm and scalar product.

Notation: let $\alpha = (\alpha_1, \dots, \alpha_n)$ be a vector in \mathbb{N}^n and $x = (x_1, \dots, x_n) \in \mathbb{R}^n$, we write:

- $|\alpha| = \sum_{i=1}^n \alpha_i = d$,
- $\alpha! = \prod_{i=1}^n \alpha_i!$,
- $x^\alpha = \prod_{i=1}^n x_i^{\alpha_i}$ for $x \in \mathbb{R}^n$,
- $\chi_i = (0, \dots, 0, 1, 0, \dots, 0)$ where the index of 1 is i .

Definition 3.1 (Bombieri norm and scalar product). *The Bombieri scalar product [1] for homogeneous polynomial of degree d is defined by*

$$\|x^\alpha\|^2 = \frac{\alpha!}{|\alpha|!} \text{ and } \langle x^\alpha | x^\beta \rangle = 0 \text{ if } \alpha \neq \beta$$

The Bombieri scalar product and the associated norm have the remarkable property to be invariant by the action of the orthogonal group of \mathbb{R}^n . It was originally introduced because it verifies the Bombieri inequalities for product of polynomials. However, we do not use this property here.

We now give a lemma establishing the invariance and a result we need later in this article:

Lemma 3.2. *Let $\{u_i\}_{1 \leq i \leq d}$ and $\{v_i\}_{1 \leq i \leq d}$ be two families of vectors of \mathbb{R}^n . Let us consider the two following homogeneous polynomials in \mathbb{E} :*

$$U(x) = \prod_{1 \leq i \leq d} \langle x | u_i \rangle \qquad V(x) = \prod_{1 \leq i \leq d} \langle x | v_i \rangle$$

The Bombieri scalar product of these polynomials is given by the following formula which directly relates the Bombieri scalar product of polynomials to the Euclidian one in \mathbb{R}^n :

$$\langle U | V \rangle = \frac{1}{d!} \sum_{\sigma \in S_n} \prod_{1 \leq i \leq d} \langle u_i | v_{\sigma(i)} \rangle$$

When the two families are constant i.e. $U(x) = \langle x | u \rangle^d$ and $V(x) = \langle x | v \rangle^d$, this simplifies to:

$$\langle U | V \rangle = \langle u | v \rangle^d$$

Proof. We start by developing the polynomials U and V . For this, we use ρ, ρ' to denote applications from $\{1, \dots, d\}$ to $\{1, \dots, n\}$ and we write $M(\rho) \in \mathbb{N}^n$ the vector such that $M_i(\rho) = \text{Card}(\rho^{-1}(\{i\}))$.

$$\begin{aligned}
\langle U|V \rangle &= \left\langle \sum_{|\alpha|=d} x^\alpha \sum_{M(\rho)=\alpha} \prod_{1 \leq i \leq d} u_{i,\rho(i)} \middle| \sum_{|\alpha|=d} x^\alpha \sum_{M(\rho')=\alpha} \prod_{1 \leq j \leq d} v_{j,\rho'(j)} \right\rangle \\
&= \sum_{|\alpha|=d} \frac{\alpha!}{|\alpha|!} \sum_{M(\rho)=M(\rho')=\alpha} \prod_{1 \leq i,j \leq d} u_{i,\rho(i)} v_{j,\rho'(j)} \\
&= \sum_{|\alpha|=d} \frac{1}{|\alpha|!} \sum_{\sigma \in S_d} \sum_{M(\rho)=\alpha} \prod_{1 \leq i \leq d} u_{i,\rho(i)} v_{\sigma i,\rho(i)} \\
&\quad \text{Using the } \alpha! \text{ permutations in } S_d \text{ such that } \rho' = \rho \circ \sigma \\
&= \frac{1}{d!} \sum_{\sigma \in S_d} \sum_{|\alpha|=d} \sum_{M(\rho)=\alpha} \prod_{1 \leq i \leq d} u_{i,\rho(i)} v_{\sigma i,\rho(i)} \\
&= \frac{1}{d!} \sum_{\sigma \in S_d} \prod_{1 \leq i \leq d} \langle u_i | v_{\sigma(i)} \rangle
\end{aligned}$$

□

Corollary 3.3. *The Bombieri norm is invariant by composition with the orthogonal group.*

Proof. Proving this corollary is just proving that the Bombieri norm does not depend upon the choice of coordinates in \mathbb{R}^n . The last theorem establishes this for product of linear forms that generate all polynomials. □

We will use the following inequality which are proved in appendix A:

Lemma 3.4. *For all $P \in \mathbb{E}$ and all $x \in \mathbb{R}^n$, we have:*

$$\begin{aligned}
|P(x)| &\leq \|P\| \|x\|^d \\
\|\nabla P(x)\| &\leq d \|P\| \|x\|^{d-1} \\
\|\mathcal{H}P(x)\|_2 &\leq \|\mathcal{H}P(x)\|_F \leq d(d-1) \|P\| \|x\|^{d-2}
\end{aligned}$$

Using the following norms:

- The Euclidian norm on \mathbb{R}^n (for x and $\nabla P(x)$),
- The Bombieri norm for polynomials (for P)
- The Frobenius norm written $\|-\|_F$ which is the square root of the sum of the squares of the matrix coefficients (for the Hessian $\mathcal{H}P(x)$).
- The spectral norm written $\|-\|_2$ which is the largest absolute value of the eigenvalues of the matrix (also for the Hessian $\mathcal{H}P(x)$).

All this inequalities are equalities for the monomial x_i^d for $1 \leq i \leq n$ and by invariance for d power of linear form. In this case, the Hessian matrix will have only one non null eigenvalue which implies that $\|\mathcal{H}P(x)\|_2 = \|\mathcal{H}P(x)\|_F$.

4. DISTANCE WITH BOMBIERI NORM

Here is the formulation of the lemma 2.2 in the particular case of Bombieri's norm. It can be established from lemma 2.2, but we propose a more direct proof using the invariance by composition with the orthogonal group.

Theorem 4.1. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. The distance to the real discriminant Δ for the Bombieri norm is given by:*

$$\text{dist}(P, \Delta) = \min_{x \in \mathcal{S}^{n-1}} \sqrt{P(x)^2 + \frac{\|\nabla^T P(x)\|^2}{d}}$$

Proof. Consider $c \in \mathcal{S}^{n-1}$. We want to compute $\text{dist}(P, \Delta_c)$. One can always find h an element of the orthogonal group such that

$$h(0, \dots, 0, 1) = c \text{ and } h(1, 0, \dots, 0) = \frac{\nabla^T P(c)}{\|\nabla^T P(c)\|} \text{ which implies}$$

$$(4.1) \quad P \circ h(x) = P(c)x_n^d + \|\nabla^T P(c)\|x_1x_n^{d-1} + Q(x)$$

where the monomials x_n^d and $x_i x_n^{d-1}$ for $i \in \{1, \dots, n\}$ do not appear in $Q(x)$.

Then, using the fact that the Bombieri norm is invariant by isometry, the fact that distinct monomials are orthogonal and the fact that $Q \in \Delta_{(0, \dots, 0, 1)}$ which implies that $Q \circ h^{-1} \in \Delta_c$, we have:

$$\begin{aligned} \text{dist}^2(P, \Delta_c) &= \text{dist}^2(P \circ h, Q) \\ &= \|P(c)x_n^d + \nabla^T P(c)x_1x_n^{d-1}\|^2 \\ &= P(c)^2 + \frac{1}{d}\|\nabla^T P(c)\|^2 \\ &= \frac{1}{d^2}\|\nabla^N P(c)\|^2 + \frac{1}{d}\|\nabla^T P(c)\|^2 \\ &= \frac{d^2 P(c)^2}{d^2} + \frac{\|\nabla^T P(c)\|^2}{d} \\ (4.2) \quad &= P(c)^2 + \frac{\|\nabla^T P(c)\|^2}{d} \end{aligned}$$

We can also give an alternate formulation avoiding the decomposition of the gradient in normal and tangent components:

$$\begin{aligned} \text{dist}^2(P, \Delta_c) &= \frac{\|\nabla^N P(c)\|^2}{d^2} + \frac{\|\nabla^T P(c)\|^2}{d} \\ &= \frac{\|\nabla^N P(c)\|^2}{d^2} - \frac{\|\nabla^N P(c)\|^2}{d} + \frac{\|\nabla P(c)\|^2}{d} \\ (4.3) \quad &= (1-d)P(c)^2 + \frac{\|\nabla P(c)\|^2}{d} \end{aligned}$$

□

Let us define from equation (4.3) $\delta_P(x) = \frac{\|\nabla P(x)\|^2}{d} - (d-1)P(x)^2$. In the theorem 4.1, it is enough to consider the critical points of δ_P on the unit sphere, that is points where $\nabla^T \delta_P(x) = 0$. This means we have:

$$\text{dist}(P, \Delta) = \min_{x \in \mathcal{S}^{n-1}, \nabla^T \delta_P(x) = 0} \sqrt{\delta_P(x)}$$

Using $\mathcal{H}P(x)x = (d-1)\nabla P(x)$ and $\langle \nabla P(x)|x \rangle = dP(x)$, we compute:

$$\begin{aligned} \frac{d}{2} \nabla \delta_P(x) &= \mathcal{H}P(x)\nabla P(x) - d(d-1)P(x)\nabla P(x) \\ &= \mathcal{H}P(x)\nabla P(x) - \langle \nabla P(x)|x \rangle \mathcal{H}P(x)x \\ &= \mathcal{H}P(x)(\nabla P(x) - \langle \nabla P(x)|x \rangle x) \\ &= \mathcal{H}P(x)\nabla^T P(x) \\ (4.4) \quad &= \mathcal{H}^T P(x)\nabla^T P(x) + (d-1)\|\nabla^T P(x)\|^2 x \end{aligned}$$

The first term in (4.4) is $\frac{d}{2} \nabla^T \delta_P(x)$. Hence, we have:

$$(4.5) \quad \text{dist}(P, \Delta) = \min_{x \in \mathcal{S}^{n-1}, \mathcal{H}^T P(x)\nabla^T P(x) = 0} \sqrt{P(x)^2 + \frac{\|\nabla^T P(x)\|^2}{d}}$$

This motivates the following definition:

Definition 4.2 (quasi-singular points, contact polynomial, contact radius). *We will call quasi-singular points for $P \in \mathbb{E}$ the critical points of δ_d with norm 1 where the distance to the discriminant is reached. This means that*

$$c \in \mathcal{S}^{n-1} \text{ is a quasi-singular points iff } \text{dist}(P, \Delta) = \delta_P(c).$$

A necessary condition for c to be a quasi singular point of P is

$$\mathcal{H}^T P(c)\nabla^T P(c) = 0$$

We will say that Q is a contact polynomial for P at c if c is a quasi-singular point for P , $Q \in \Delta_c$ (this means that $\{x \in \mathcal{S}^{n-1}; Q(x) = 0\}$ has a singularity at c) and $\text{dist}(P, \Delta) = \|Q - P\|$.

When Q is contact polynomial for P at c , we will say that $R = Q - P$ is a contact radius for P at c . A contact radius R is therefore the smallest polynomial for Bombieri norm that must be added to P to create a singularity.

Then, we distinguish two kinds of quasi-singular points for P (their names will be explained later):

quasi-double points: c is quasi-double point if it is a quasi-singular point of P and a critical point of P on the unit sphere (i.e. satisfying $\nabla^T P(c) = 0$).

quasi-cusp points: c is quasi-cups point for P if it is a quasi-singular point of P which is not a critical point of P . In this case, $\nabla^T P(c)$ is a non zero member of the kernel of $\mathcal{H}^T P(c)$.

First, using the quasi-double points, we can find a very simple inequality for the distance to the discriminant:

Theorem 4.3. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. The distance to the real discriminant Δ for the Bombieri norm satisfies:*

$$\text{dist}(P, \Delta) \leq \min_{x \in \mathcal{S}^{n-1}, \nabla^T P(x)=0} |P(x)|$$

The condition $\nabla^T P(x) = 0$ means that x is a critical point of P and our theorem means that the distance to the discriminant is less or equal to the minimal critical value of P in absolute value.

Proof. We use the theorem 4.1:

$$(4.6) \quad \begin{aligned} \text{dist}^2(P, \Delta) &= \min_{x \in \mathcal{S}^{n-1}} \left(P(x)^2 + \frac{\|\nabla^T P(x)\|^2}{d} \right) \\ &\leq \min_{x \in \mathcal{S}^{n-1}, \nabla^T P(x)=0} P(x)^2 \end{aligned}$$

□

Theorem 4.4. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree $d \geq 2$ with n variables. Let c be a quasi-singular point for P . Then, the contact radius at c is the polynomial*

$$R(x) = -P(c)\langle x | c \rangle^d - \langle x | \nabla^T P(c) \rangle \langle x | c \rangle^{d-1}.$$

and $Q(x) = P(x) + R(x)$, the contact polynomial for P at c , has no other singularity than c and $-c$.

Moreover, when $d = 2$, c is always a quasi double point (i.e. $\nabla^T P(c) = 0$).

Proof. The formula for $R(x)$ is a consequence of the equation 4.1 established in the proof of theorem 4.1 (given just after the theorem).

Let us assume that Q has another singularity $c' \neq c$ and $c' \neq -c$ on the unit sphere (recall that we imposed quasi-singular point to lie on the unit sphere). This means that $\text{dist}(P, \Delta_c) = \text{dist}(P, \Delta_{c'})$, Q lying at the intersection of Δ_c and $\Delta_{c'}$.

We can therefore write $Q(x) = P(x) + S(x)$, where S is the contact radius at c' :

$$S(x) = -P(c')\langle x | c' \rangle^d - \langle x | \nabla^T P(c') \rangle \langle x | c' \rangle^{d-1}.$$

We necessarily have $S = R$. It remains to show that this is impossible. We have:

$$\begin{aligned} R(x) &= -\langle x | c \rangle^{d-1} \langle x | P(c)c + \nabla^T P(c) \rangle \\ S(x) &= -\langle x | c' \rangle^{d-1} \langle x | P(c')c' + \nabla^T P(c') \rangle \end{aligned}$$

When $d \geq 3$, the hyper-surface $R(x) = 0$ contains the plane $\langle x | c \rangle = 0$ with multiplicity $d - 1$ union the plane $\langle x | P(c)c + \nabla^T P(c) \rangle = 0$ with multiplicity one. $S(x) = 0$ uses that same plane with c replaced by c' , which imposes $c = c'$ or $c = -c'$.

When $d = 2$, we will show in the study of quasi-cusp point that they exist only from degree 3, hence we know that we only have quasi-double points, which means that $\nabla^T P(c) = \nabla^T P(c') = 0$. Therefore, R and S become:

$$\begin{aligned} R(x) &= -P(c)\langle x | c \rangle^d \\ S(x) &= -P(c')\langle x | c' \rangle^d \end{aligned}$$

And again, $R = S$ implies $c = c'$ or $c = -c'$. \square

4.1. Study of quasi-double points. Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Let c be a quasi-double point for P , meaning that we have $\nabla^T P(c) = 0$ and $\text{dist}^2(P, \Delta) = P(c)^2 > 0$.

The Bombieri norm being invariant by the orthogonal group, using a rotation we can assume that $c = (0, \dots, 0, 1)$ and that the matrix $\mathcal{H}^T P(c)$ is diagonal.

Knowing that $\nabla^T P(c) = 0$, we can write:

$$P(x) = \alpha x_n^d + \frac{1}{2} \sum_{1 \leq i < n} \lambda_i x_i^2 x_n^{d-2} + T(x) \text{ with } \alpha = P(c) \text{ and } \lambda_i = \frac{\partial^2 P}{\partial x_i^2}(c)$$

with no monomial of degree ≤ 2 in x_1, \dots, x_{n-1} in $T(x)$, i.e. T has valuation at least 3 in x_1, \dots, x_{n-1} .

Then, by theorem 4.4, the contact radius is

$$R(x) = -\alpha \langle x | c \rangle^d$$

and the contact polynomial is

$$Q(x) = P(x) + R(x) = \frac{1}{2} \sum_{1 \leq i < n} \lambda_i x_i^2 x_n^{d-2} + T(x)$$

The singularity at c of the variety $\{x \in \mathcal{S}^{n-1} | Q(x) = 0\}$ is at least a double point (justifying the name quasi-double point) and it has no other singularities by theorem 4.4.

Next, we will reveal some constraints on the eigenvalues $\lambda_i = \frac{\partial^2 P}{\partial x_i^2}(c)$ of the hessian matrix. For this, we consider the point

$$c_h = \frac{1}{\sqrt{1+h^2}}(h, 0, \dots, 0, 1)$$

and compute $(\text{dist}^2(P, \Delta_{c_h}) - \text{dist}^2(P, Q))(1+h^2)^d$ which is non negative because $\text{dist}(P, \Delta_{c_h}) \geq \text{dist}(P, Q)$.

$$\begin{aligned}
& (\text{dist}^2(P, \Delta_{c_h}) - \text{dist}^2(P, Q)) (1 + h^2)^d \\
&= \left((1-d)P^2(c_h) + \frac{\|\nabla P(c_h)\|^2}{d} - P(c)^2 \right) (1 + h^2)^d \\
&= (1-d)P^2(h, 0, \dots, 0, 1) \\
&\quad + \frac{\|\nabla P(h, 0, \dots, 0, 1)\|^2}{d} (1 + h^2) - P(c)^2 (1 + h^2)^d \\
&= (1-d) \left(\alpha + \frac{1}{2} \lambda_1 h^2 + o(\|h\|^2) \right)^2 \\
&\quad + \frac{\left(d\alpha + (d-2)\frac{1}{2} \lambda_1 h^2 + o(\|h\|^2) \right)^2 + (\lambda_1 h + o(\|h\|))^2}{d} (1 + h^2) \\
&\quad - \alpha^2 (1 + dh^2 + o(\|h\|^2)) \\
&= ((1-d) + d-1)\alpha^2 + ((1-d) + (d-2))\alpha \lambda_1 h^2 + \frac{1}{d} \lambda_1^2 h^2 \\
&\quad + d\alpha^2 h^2 - d\alpha^2 h^2 + o(\|h\|^2) \\
&= \left(-\alpha \lambda_1 + \frac{1}{d} \lambda_1^2 \right) h^2 + o(\|h\|^2)
\end{aligned}$$

Therefore, $\text{dist}(P, \Delta_{c_h}) > \text{dist}(P, \Delta)$ implies:

$$\lambda_1 (\lambda_1 - d\alpha) \geq 0$$

The same is true for all the eigenvalues and this means that when λ_i and $P(c)$ have the same sign then $|\lambda_i| \geq d|P(c)|$ (recall that by definition $\alpha = P(c)$).

This study establishes the following theorem:

Theorem 4.5. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables, let c be a quasi-double point for P and Q a corresponding contact polynomial at c . Then, the contact radius is*

$$R(x) = -P(c)\langle x|c \rangle^d$$

The contact polynomial $Q(x) = P(x) + R(x)$ has only one singularity in c on \mathcal{S}^{n-1} which is at least a double-point.

Moreover, if λ is an eigenvalue of $\mathcal{H}^T P(x)$ with the same sign than $P(c)$, then $|\lambda| \geq d|P(c)| > 0$.

4.2. Study of quasi-cusp point. Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Let c be a quasi-cusp point for P , meaning that we have $\nabla^T P(c) \neq 0$ and $\mathcal{H}^T P(c) \nabla^T P(c) = 0$.

The Bombieri norm being invariant by the orthogonal group, using a rotation we can assume that $c = (0, \dots, 0, 1)$ and that the matrix $\mathcal{H}^T P(c)$ is diagonal and that $(0, 1, 0, \dots, 0)$ is the direction of $\nabla^T P(c)$ which is an eigenvector of $\mathcal{H}^T P(c)$.

We can write:

$$P(x) = \alpha x_n^d + \beta x_1 x_n^{d-1} + \frac{1}{2} \sum_{2 \leq i < n} \lambda_i x_i^2 x_n^{d-2} + \frac{1}{6} \mu_1 x_1^3 x_n^{d-3} + T(x)$$

with $\alpha = P(c)$, $\beta = \frac{\partial P}{\partial x_1}(c)$, $\lambda_i = \frac{\partial^2 P}{\partial x_i^2}(c)$, $\mu_1 = \frac{\partial^3 P}{\partial x_1^3}(c)$ and no monomial of degree ≤ 2 in x_1, \dots, x_{n-1} , nor $x_1^3 x_n^{d-3}$ in $T(x)$.

The fact that the coefficient of $x_1^2 x_n^{d-1}$ is null is the condition $\mathcal{H}^T P(c) \nabla^T P(c) = 0$. Then, by theorem 4.4, the contact radius is

$$R(x) = -\alpha x_n^d - \beta x_1 x_n^{d-1}$$

and the contact polynomial is

$$Q(x) = P(x) + R(x) = \sum_{2 \leq i < n} \frac{1}{2} \lambda_i x_i^2 x_n^{d-2} + \frac{1}{6} \mu_1 x_1^3 x_n^{d-3} + T(x)$$

The singularity at c of $Q(x) = 0$ on the unit sphere is at least a cusp (justifying the name quasi-cusp point) and it has no other singularities by theorem 4.4.

We now use a computation similar to the previous case to reveal a constraint on μ_1 . For this, we consider the point $c_h = \frac{1}{\sqrt{1+h^2}}(h, 0, \dots, 0, 1)$ and compute $(\text{dist}^2(P, \Delta_{c_h}) - \text{dist}^2(P, Q))(1+h^2)^d$ which is non negative because $\text{dist}(P, \Delta_{c_h}) \geq \text{dist}(P, Q)$.

$$\begin{aligned} & (\text{dist}^2(P, \Delta_{c_h}) - \text{dist}^2(P, Q))(1+h^2)^d \\ &= \left((1-d)P^2(c_h) + \frac{\|\nabla P(c_h)\|^2}{d} - P(c)^2 - \frac{\|\nabla^T P(c)\|^2}{d} \right) (1+h^2)^d \\ &= (1-d)P^2(h, 0, \dots, 0, 1) + \frac{\|\nabla P(h, 0, \dots, 0, 1)\|^2}{d} (1+h^2) \\ &\quad - \left(\alpha^2 + \frac{\beta^2}{d} \right) (1+h^2)^d \\ &= (1-d)(\alpha + \beta h + o(\|h\|^2))^2 \\ &\quad + \frac{(d\alpha + (d-1)\beta h + o(\|h\|^2))^2 + (\beta + \frac{1}{2}\mu_1 h^2 + o(\|h\|^2))^2}{d} (1+h^2) \\ &\quad - \left(\alpha^2 + \frac{\beta^2}{d} \right) (1+dh^2 + o(\|h\|^2)) \\ &= ((1-d) + d-1)\alpha^2 + \left(\frac{1}{d} - \frac{1}{d} \right) \beta^2 + (2(1-d) + 2(d-1))\alpha\beta h \\ &\quad + \left((1-d) + \frac{(d-1)^2}{d} + \frac{1}{d} - 1 \right) \beta^2 h^2 + \frac{1}{d} \beta \mu_1 h^2 + o(\|h\|^2) \\ &= \left(\frac{2-2d}{d} \beta^2 + \frac{1}{d} \beta \mu_1 \right) h^2 + o(\|h\|^2) \end{aligned}$$

Therefore, $\text{dist}(P, \Delta_{c_h}) > \text{dist}(P, \Delta)$ implies:

$$\beta(2(1-d)\beta + \mu_1) \geq 0$$

This forces $\beta \mu_1 > 0$ hence $\mu_1 \neq 0$ (because $d = 2$).

We remark that if $d = 2$, then $\mu_1 = 0$ and together with $\beta \neq 0$, this implies $\text{dist}(P, \Delta_{c_h}) < \text{dist}(P, \Delta)$ for h small enough. This proves that quasi-cusp points exist only when $d > 2$. This computation does not require theorem 4.4 (we just use the fact that c is a local minima of δ_P). This fills the gap in the proof of theorem 4.4 for the degree 2.

It remains to explicit the constraints on the eigenvalues $\lambda_i = \frac{\partial^2 P}{\partial x_i^2}(c)$ for $2 \leq i < n$. They change compared to the case of quasi-double points. In this case, we have to take into account the coefficient of $x_1 x_i^2$ for $2 \leq i < n$ which is $\frac{1}{2}\mu_i$ with $\mu_i = \frac{\partial^3 P}{\partial x_1 \partial x_i^2}(c)$.

For this, we consider the point $c_h = \frac{1}{\sqrt{1+h^2}}(0, h, 0, \dots, 0, 1)$ and compute $(\text{dist}^2(P, \Delta_{c_h}) - \text{dist}^2(P, Q))(1+h^2)^d$ which is non negative because $\text{dist}(P, \Delta_{c_h}) \geq \text{dist}(P, Q)$.

$$\begin{aligned}
& (\text{dist}(P, \Delta_{c_h}) - \text{dist}(P, Q))(1+h^2)^d \\
&= \left((1-d)P^2(c_h) + \frac{\|\nabla P(c_h)\|^2}{d} - P(c)^2 - \frac{\|\nabla^T P(c)\|^2}{d} \right) (1+h^2)^d \\
&= (1-d)P^2(0, h, 0, \dots, 0, 1) + \frac{\|\nabla P(0, h, 0, \dots, 0, 1)\|^2}{d} (1+h^2) \\
&\quad - \left(\alpha^2 + \frac{\beta^2}{d} \right) (1+h^2)^d \\
&= (1-d)\left(\alpha + \frac{1}{2}\lambda_2 h^2 + o(\|h\|^2) \right)^2 \\
&\quad + \frac{(d\alpha + (d-2)\frac{1}{2}\lambda_2 h^2 + o(\|h\|^2))^2}{d} (1+h^2) \\
&\quad + \frac{(\beta + \frac{1}{2}\mu_2 h^2 + o(\|h\|^2))^2 + (\lambda_2 h + o(\|h\|^2))^2}{d} (1+h^2) \\
&\quad - \left(\alpha^2 + \frac{\beta^2}{d} \right) (1+dh^2 + o(\|h\|^2)) \\
&= ((1-d) + d-1)\alpha^2 + \left(\frac{1}{d} - \frac{1}{d} \right) \beta^2 + ((1-d) + (d-2))\alpha\lambda_2 h^2 \\
&\quad + \left(\frac{1}{d} - 1 \right) \beta^2 h^2 + \frac{1}{d}\lambda_2^2 h^2 + \frac{1}{d}\beta\mu_2 h^2 + o(\|h\|^2) \\
&= \frac{1}{d}((1-d)\beta^2 - d\alpha\lambda_2 + \lambda_2^2 + \beta\mu_2)h^2 + o(\|h\|^2)
\end{aligned}$$

Therefore, $\text{dist}(P, \Delta_{c_h}) > \text{dist}(P, \Delta)$ implies:

$$(1-d)\beta^2 - d\alpha\lambda_2 + \lambda_2^2 + \beta\mu_2 \geq 0$$

Hence, if $\lambda_2 = 0$ we have $\mu_2 \neq 0$ with the same sign as β .

By symmetry, the same holds for λ_i with $i \geq 2$. Moreover, up to reordering, we may assume that $\lambda_2 = \dots = \lambda_k = 0$ and that $\lambda_i \neq 0$ for $k < i < n$. In fact, $k+1$ is the dimension of the kernel of the matrix $\mathcal{H}^T P$, this is at least 2, because it contains at least $(1, 0, \dots, 0)$ and $(0, \dots, 0, 1)$.

Then, we consider the hessian matrix of $\frac{\partial P}{\partial x_1}$, restricted to the variables x_1, \dots, x_k and consider a change of coordinates such that this matrix is diagonal. In such a coordinates system, we can write:

$$P(x) = \alpha x_n^d + \beta x_1 x_n^{d-1} + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 x_n^{d-2} + \frac{1}{6} \mu_1 x_1^3 x_n^{d-3} + \frac{1}{2} \sum_{2 \leq i \leq k} \mu_i x_1 x_i^2 x_n^{d-3} + T(x)$$

where T has no monomial of degree less than 3 in x_1, \dots, x_{n-1} and no monomial of degree 3 in x_1, \dots, x_{n-1} , using only the variables x_1, \dots, x_k .

This study allows us to state the following theorem:

Theorem 4.6. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Let c be a quasi-cusp point for P . Then, the contact radius at c is the polynomial*

$$R(x) = -P(c)\langle x | c \rangle^d - \langle x | \nabla^T P(c) \rangle \langle x | c \rangle^{d-1}.$$

The contact polynomial $Q(x) = P(x) + R(x)$ has only one singularity in c which is at least a cusp.

We also have

$$\mathcal{H}^T P(c) \cdot \nabla^T P(c) = 0 \text{ and } \nabla^T P(c) \neq 0$$

Moreover, we can choose coordinates where $c = (0, \dots, 0, 1)$, $\nabla^T P(c) = (\beta, 0, \dots, 0)$ and $k+1 \geq 2$ is the dimension of the kernel of the matrix $\mathcal{H}^T P(c)$ (c and $\nabla^T P(c)$ are in the kernel of $\mathcal{H}^T P(c)$) and

$$P(x) = \alpha x_n^d + \beta x_1 x_n^{d-1} + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 x_n^{d-2} + \frac{1}{6} \mu_1 x_1^3 x_n^{d-3} + \frac{1}{2} \sum_{2 \leq i \leq k} \mu_i x_1 x_i^2 x_n^{d-3} + T(x)$$

where T has no monomial of degree less than 3 in x_1, \dots, x_{n-1} and no monomial of degree 3 in x_1, \dots, x_{n-1} , using only the variables x_1, \dots, x_k . We also have the following constraints:

- $\beta, \mu_1, \dots, \mu_k$ are non zero and have the same sign and
- $(1-d)\beta^2 - d\alpha\lambda_i + \lambda_i^2 + \beta\mu_i \geq 0$ for $2 \leq i < n$ where $\mu_i = \frac{\partial^3 P}{\partial x_1 \partial^2 x_i}(c)$.
- $\lambda_i \neq 0$ for $k < i < n$.

5. APPLICATION TO EXTREMAL HYPER-SURFACES

Definition 5.1 (Extremal hyper-surface). *An hyper-surface on the projective space or the unit sphere of dimension $n-1$ defined by an equation $P(x) = 0$ where P is an homogeneous polynomial of degree d in n variables is extremal if the tuple of its Betti numbers (b_0, \dots, b_{n-2}) is maximal for pointwise ordering for such polynomials.*

Remark: considering the same polynomial on the projective space or the sphere just doubles the Betti numbers.

The next theorem also applied to locally extremal surface:

Definition 5.2 (Locally extremal hyper-surface). *An algebraic hyper-surface \mathcal{H} in the projective plane or the unit sphere of dimension $n-1$ is locally extremal if there exists no algebraic hyper-surface of the same degree isotopic to \mathcal{H} with a disc*

replaced by a disc with a m -handle for $0 \leq m \leq n-2$ ($m=0$ or $m=n-2$ means adding a connected components).

It is clear that an extremal hyper-surface is locally extremal, but the converse is not true in general.

Theorem 5.3. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d in n variables. Assume that the zero level of P on the unit sphere is smooth and locally extremal. Then, we have:*

- P admit no quasi-cusp point.
- If c is a quasi-double point of P , then at least one of the eigenvalue λ of $\mathcal{H}^T P(c)$ for an eigen vector distinct from c itself satisfies $\lambda P(c) \leq 0$ (we always have $(\mathcal{H}^T P(c))c = 0$ by definition of \mathcal{H}^T).

Proof. Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d in n variables with a smooth and extremal zero level on the unit sphere.

For the first item, assume that c is a quasi-cusp of P , and that R and Q are respectively the contact radius and polynomial of P at c .

By theorem 4.6, we can find coordinates where $c = (0, \dots, 0, 1)$ and

$$P(x) = \alpha x_n^d + \beta x_1 x_n^{d-1} + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 x_n^{d-2} + \frac{1}{6} \mu_1 x_1^3 x_n^{d-3} + \frac{1}{2} \sum_{2 \leq i \leq k} \mu_i x_1 x_i^2 x_n^{d-3} + T(x)$$

with the properties given above by theorem 4.6 and especially $\mu_i > 0$ for $1 \leq i \leq k$.

First, without loss of generality, we can assume $\alpha \geq 0$ (by considering $-P$ instead of P) and $\beta > 0$ (using the transformation $x_1 \mapsto -x_1$). We furthermore reorder variables and define $m \in \mathbb{N}$ to have

- $\lambda_{k+1}, \dots, \lambda_m > 0$
- $\lambda_{m+1}, \dots, \lambda_{n-1} < 0$.

We will study and change the topology of the zero level of P in a neighbourhood of the point $c : (0, \dots, 0, 1)$. Hence we will work till the end of the proof with affine coordinates and set $x_n = 1$.

We will study the following families of polynomials (only the coefficient of x_1 is changing):

$$\begin{aligned}
P_t(x) &= \alpha t^5 + \beta t x_1 + \sum_{2 \leq i \leq k} t x_i^2 + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 \\
&\quad + \frac{1}{6} \mu_1 x_1^3 + \frac{1}{2} \sum_{2 \leq i \leq k} \mu_i x_1 x_i^2 + T(x) \\
P_t^+(x) &= \alpha t^5 + \beta t^3 x_1 + \sum_{2 \leq i \leq k} t x_i^2 + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 \\
&\quad + \frac{1}{6} \mu_1 x_1^3 + \frac{1}{2} \sum_{2 \leq i \leq k} \mu_i x_1 x_i^2 + T(x) \\
P_t^-(x) &= \alpha t^5 - \beta t^3 x_1 + \sum_{2 \leq i \leq k} t x_i^2 + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 \\
&\quad + \frac{1}{6} \mu_1 x_1^3 + \frac{1}{2} \sum_{2 \leq i \leq k} \mu_i x_1 x_i^2 + T(x)
\end{aligned}$$

We have $\text{dist}^2(P, P_t) = \alpha^2(1-t^5)^2 + \frac{\beta^2}{d}(1-t)^2 + \frac{2(k-1)}{d(d-1)}t^2 = \alpha^2 + \frac{\beta^2}{d}(1-2t) + o(t)$ and this is smaller than $\text{dist}^2(P, \Delta) = \alpha^2 + \frac{\beta^2}{d}$ for t small enough. This implies that $P_t(x) = 0$ has the same topology than $P(x) = 0$ for $t \in]0, \epsilon[$ for some $\epsilon > 0$ (1).

For t small enough, the topologies of $P_t(x) = 0$, $P_t^+(x) = 0$ and $P_t^-(x) = 0$ can be computed using Viro's theorem [5, 6]. To do so, we attribute a height to each vertex of Newton's polyhedra: if $x_1^{\alpha_1}, \dots, x_{n-1}^{\alpha_{n-1}}$ is a monomial of P_t , we consider the point $(\alpha_1, \dots, \alpha_{n-1}, h_\alpha) \in \mathbb{N}^n$. To simplify the discussion, we will identify the point $(\alpha_1, \dots, \alpha_{n-1}, h_\alpha) \in \mathbb{N}^n$ with the corresponding monomial.

All monomials are given 0 height except 1 which we place at height 5, x_i^2 for $2 \leq i \leq k$ which we place at height 1, x_1^2 which height changes among the three families.

The triangulation needed by Viro's theorem is computed as the projection of the convex hull of the points of Newton's polytopes with their given height. It is easy to see that all vertices with non zero coefficient are on the convex hull, just looking at the axes.

In what follows, we consider that t is small enough to have (1) and for the topologies of $P_t(x) = 0$, $P_t^+(x) = 0$ and $P_t^-(x) = 0$ to be given by Viro's theorem, gluing the topologies of the polynomial in each polyhedron.

Hence, we only need to consider polyhedra changing among the three polynomials. The only vertices that belong to a polyhedra which is not the same for the Viro's decomposition of P_t , P_t^+ and P_t^- are among

- $1, x_1, x_1^2, x_1^3,$
- $x_1 x_i^2$ for $2 \leq i \leq k,$
- x_i^2 for $k < i < n$ and
- monomials without $x_1.$

This is true because the only monomial that changes height is x_1 . Therefore, if a polyhedron that contains a monomial x^α changes, then, it must contain a segment from x^α to x_1 . Because the vertices of x_1^3 , $x_1x_i^2$ for $2 \leq i \leq k$ and x_i^2 for $k < i < n$ are at height 0, if x^α is not among those, it must satisfy $\alpha_1 = 0$ because otherwise the segment joining x^α to x_1 can not have 0 height when it crosses the simplex corresponding to x_1^3 , $x_1x_i^2$ for $2 \leq i \leq k$ and x_i^2 for $k < i < n$.

This means that to study the change of topology of $P_t(x) = 0$, $P_t^+(x) = 0$ and $P_t^-(x) = 0$, we can consider that T is constant in x_1 .

The rest of the proof is in two steps: we already know that $P(x) = 0$ and $P_t(x) = 0$ have the same topology. It remains to show that $P_t(x) = 0$, $P_t^+(x) = 0$ also have the same topology and that $P_t^-(x) = 0$, compared to $P_t^-(x) = 0$, has at least two Betti numbers that increase while the others are non decreasing.

For the first two polynomials: $P(x) = 0$ and $P_t(x) = 0$, they have the same topology because, considering that T is constant in x_1 , they can be written :

$$P_t(x) = \frac{1}{6}\mu x_1^3 + \left(\beta t + \frac{1}{2} \sum_{1 < i \leq k} \mu_i x_i^2 \right) x_1 + \left(\alpha t^5 + \frac{1}{2} \sum_{2 \leq i \leq k} t x_i^2 + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 + T(x) \right)$$

and

$$P_t^+(x) = \frac{1}{6}\mu x_1^3 + \left(\beta t^3 + \frac{1}{2} \sum_{1 < i \leq k} \mu_i x_i^2 \right) x_1 + \left(\alpha t^5 + \frac{1}{2} \sum_{2 \leq i \leq k} t x_i^2 + \frac{1}{2} \sum_{k < i < n} \lambda_i x_i^2 + T(x) \right)$$

In both case, all non constant coefficients in x_1 are positive, implying that the polynomial has exactly one root because its discriminant in x_1 is negative. This means that $P_t(x) = 0$ and $P_t^+(x) = 0$ defines a graph of x_1 as a function of the other variables and hence have the same topology. Moreover, the infinite branch are the same in both case, not changing the gluing with the polyhedra corresponding to neglected monomials in T (those using x_1).

Finally, for the change of topology between $P_t^+(x) = 0$ and $P_t^-(x) = 0$, we only need to consider the following polyhedra which are simplices:

- A:** with vertices 1 , x_1 and x_i^2 for $1 < i < n$.
- B:** with vertices x_1 , x_1^3 and x_i^2 for $1 < i < n$.

It is easy to check that the chosen height for the monomials forces these simplices to appear.

In the case of $P_t^+(x) = 0$, all coefficients are positive (see figure 1), which leads to a disc of dimension $n - 2$ inside the polyhedra A and B , regardless of the sign of the coefficient λ_i .

In the case of $P_t^-(x) = 0$, only the sign of x_1^2 changes. The change is illustrated by figure 2 and 3.

We show that the topology of the hyper-surface $P_t^-(x) = 0$ in the polyhedra A and B and their counterparts in all orthants is a disc with a pair of handles. The

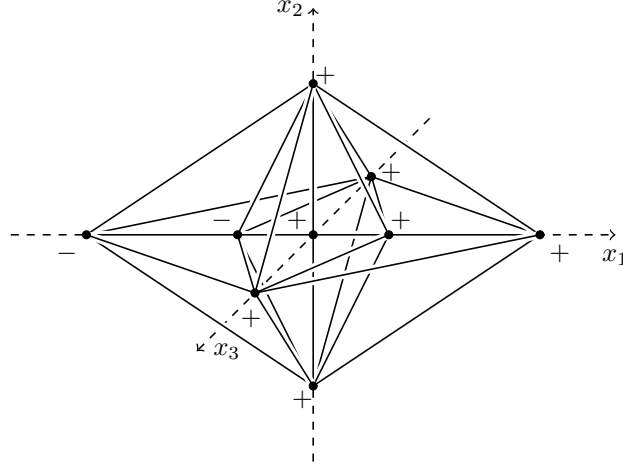


FIGURE 1. Topology of $P_t^+(x) = 0$ near c , with $k = n$.

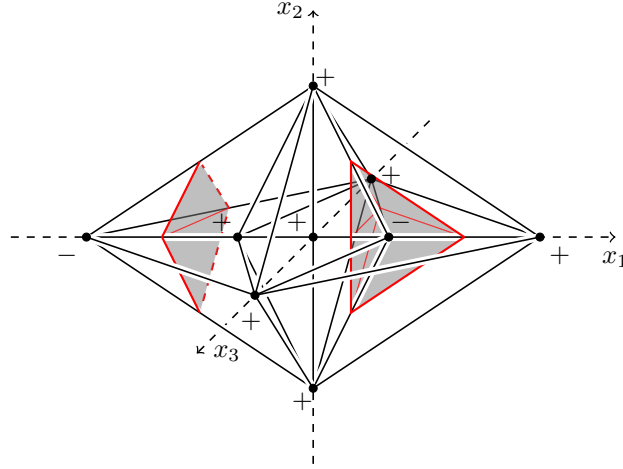


FIGURE 2. Topology of $P_t^-(x) = 0$ near c with $\lambda_3 > 0$. Only the rear faces are shown, rear border dashed.

two polyhedra A and B being simplices, the topology is given by the sign at the vertices.

First, we see that the polynomial admits three roots on the x_1 axes, one negative and two positive. Let us name those roots ϕ^- , ϕ^0 and ϕ^+ (ϕ^0 being the positive root nearest to 0).

In the dimension x_1, \dots, x_m , the monomial x_1 is negative surrounded by positive monomials in polyhedra A and B . This gives us a component S_A homeomorphic to a sphere of dimension $m - 1$, inside the hypersurface $P_t^-(x) = 0$. Moreover, we can also find a topological sphere S'_A (by inflating S_A a little) that does not meet the hyper-surface $P_t^-(x) = 0$ and that contains a point on the x_1 axes between ϕ^- and ϕ^0 .

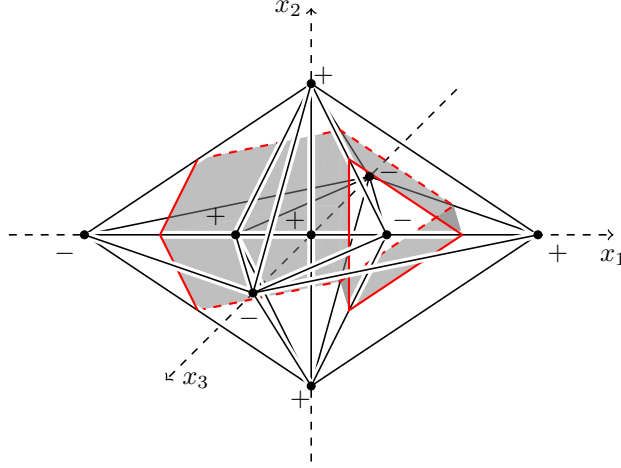


FIGURE 3. Topology of $P_t^-(x) = 0$ near c with $k = 2$ or $\lambda_2 > 0$ and $\lambda_3 < 0$. Only the rear faces are shown, rear border dashed.

Similarly, In the dimension $x_1, x_{m+1}, \dots, x_{n-1}$, the monomials $-x_1$ and 1 ($-x_1$ alone if $\alpha = 0$) are positive and surrounded by negative vertices.

This gives us a component S_B homeomorphic to a sphere of dimension $n - m - 1$, inside the hypersurface $P_t^-(x) = 0$. Moreover, we can also find a topological sphere S'_B (by inflating S_B a little) that does not meet the same hyper-surface and that contains a point on the x_1 axes between ϕ^0 and ϕ^+ .

Now, the sum of the dimensions of the spheres S_A and S_B is $m - 1 + n - m - 1 = n - 2$ which is one less than the dimension of the ambient space \mathbb{R}^{n-1} . The spheres S_A (resp. S_B) are non contractile because of the existence of the spheres S'_B (resp. S'_A) that do not meet the hypersurface. Therefore, the presence of S_A and S_B ensures that we have at least a $m-1$ -handle on a disc of dimension $n - 2$ inside the polyhedra A and B .

This means that $P_t^+(x) = 0$ is a desingularisation of $Q(x) = 0$ that creates a disc while $P_t^-(x) = 0$ creates a dist with at least one handle (in fact no more, but we don't need to prove this). But, $P_t^+(x) = 0$ gives us the topology of $P(x) = 0$. This establishes the equation $P(x) = 0$ does not define a locally extremal hyper-surface.

The last part of the theorem is easier: a quasi-double point c for P such that all eigen values of $\mathcal{H}^T P(c)$ (except c itself) satisfies $\lambda P(c) > 0$ would mean that c is a local minimum of $|P(c)|$ and therefore, c is an isolated point of the hyper-surface $Q(x) = 0$ where $Q \in \Delta$ is the contact polynomial $Q(x) = P(x) - P(c)\langle x|c \rangle^d$ for P . This allows to add a new connected component to the variety of equation $P(x) = 0$. This is also impossible in the case of a locally extremal algebraic hyper-surface. \square

Corollary 5.4. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Assume that the zero level of P is extremal. Then, the distance to the discriminant is the minimal absolute critical value of P i.e.*

$$\text{dist}(P, \Delta) = \min_{\nabla^T P(x)=0} |P(x)|$$

Remark: this implies that the right member of the above equality is continuous in the coefficient of P which is not true in general.

Proof. Immediate from the first item of the previous theorem, the definition 4.2 and the equation 4.5 that precedes it. \square

6. FURTHER FROM THE DISCRIMINANT

We now establish a property verified by polynomials that maximise the distance to the discriminant:

Theorem 6.1. *Let P be an homogenous polynomial in n variables, of degree d , Bombieri norm 1 and such that $\text{dist}(P, \Delta)$ is locally maximal among polynomials of Bombieri norm 1.*

Let $\{c_1, -c_1, \dots, c_k, -c_k\}$ be the set of the quasi-singular points of P . Let R_1, \dots, R_k be the corresponding contact radius (we choose one for each pair $(c, -c)$ because the contact radius corresponding to c and $-c$ are equal or opposite, depending upon the degree).

Then, P is a linear combination of the R_i .

Proof. We consider an homogeneous polynomial P satisfying the condition of the theorem, its quasi-critical points $\{c_1, -c_1, \dots, c_k, -c_k\}$ and R_1, \dots, R_k the corresponding contact radius (which means that the contact polynomial $Q_i = P_i + R_i$ has a singularity in c_i and $-c_i$ for $1 \leq i \leq k$).

By absurd, let us assume that P is not a linear combination of R_1, \dots, R_k . Let P_1 be the orthogonal projection of P on the vector space generated by R_1, \dots, R_k and let $D = P_1 - P \neq 0$. We also consider the sphere \mathcal{S}_P , centered at P of radius $\text{dist}(P, \Delta)$. This is schematically represented in figure 4.

Next, we define $P_t = P + tD$. Let us choose a contact polynomial Q_t for P_t which means that $\text{dist}(P_t, \Delta) = \text{dist}(P_t, Q_t)$. We consider Q_t^s , the intersection of the segment $[P_t, Q_t]$ with the sphere \mathcal{S}_P . Let h_t be the distance from Q_t^s to the affine sub-space containing P and directed by R_1, \dots, R_k . We know that $\lim_{t \rightarrow 0} h_t = 0$ because Q_t converges to the set $\{P + R_1, \dots, P + R_k\}$.

We have :

$$\begin{aligned} \text{dist}^2(P_t, \Delta) &= \text{dist}^2(P_t, Q_t) \\ &\leq \text{dist}^2(P_t, Q_t^s) \\ &\leq (h_t - t\|D\|)^2 + \text{dist}^2(P, \Delta) - h_t^2 \\ &\leq \text{dist}^2(P, \Delta) - 2th_t\|D\| + t^2\|D\|^2 \end{aligned}$$

But, P_t is not of norm 1: $\|P_t\|^2 = \|P_1\|^2 + (1-t)^2\|D\|^2 = 1 - 2t\|D\|^2 + t^2\|D\|^2$ because $\|P_1\|^2 + \|D\|^2 = \|P\|^2 = 1$. Thus, we consider the polynomial $\hat{P}_t = \frac{P_t}{\|P_t\|}$ and we have:

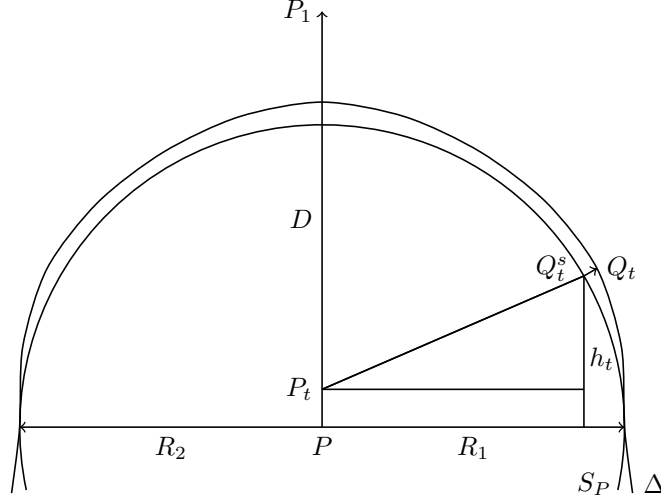


FIGURE 4. Figure for the proof of theorem 6.1

$$\begin{aligned}
 \text{dist}^2(\hat{P}_t, \Delta) &= \frac{\text{dist}^2(P_t, \Delta)}{1 - 2t\|D\|^2 + t^2\|D\|^2} \\
 &\leq \frac{\text{dist}^2(P, \Delta) - 2th_t\|D\| + t^2\|D\|^2}{1 - 2t\|D\|^2 + t^2\|D\|^2} \\
 &\leq (\text{dist}^2(P, \Delta) - 2th_t\|D\| + t^2\|D\|^2)(1 + 2t\|D\|^2 + o(t)) \\
 &\leq \text{dist}^2(P, \Delta)(1 + 2t\|D\|^2) + o(t) \text{ because } th_t \in o(t)
 \end{aligned}$$

This proves that $\text{dist}^2(\hat{P}_t, \Delta) > \text{dist}^2(P, \Delta)$ when t is positive and small enough contradicting the fact that P is a local maxima for the distance to Δ . \square

Remarque: This gives a descent direction for an algorithm to compute local maxima for the distance to Δ . However, our experiments show that this is not a very good direction. We got much better results using the direction T given by $\langle P|T \rangle = 0$ and for $1 \leq i \leq k$, $\langle R_i|T \rangle < 0$. This descent direction is orthogonal to $\|D\|$ and is much better in practice, despite the fact that it produces a vector of norm greater than one that needs normalisation. However, from the fact that P is a local maxima, we only get, using T , that P, R_1, \dots, R_k are linearly dependant which is weaker than the previous theorem.

This means that the better descent direction to do proofs is not the best one to do local optimisation.

Corollary 6.2. *Let P be an homogeneous polynomial in n variables, of degree d , Bombieri norm 1 and such that $\text{dist}(P, \Delta)$ is locally maximal among polynomials of Bombieri norm 1. Assume also that $P = 0$ defines an extremal hyper-surface.*

Let $\{c_1, -c_1, \dots, c_k, -c_k\}$ be the set of quasi-double points of P (which are the critical points of P on \mathcal{S}^{n-1} corresponding to the smallest critical value in absolute value).

Then, we can find $\lambda_1, \dots, \lambda_k$ such that:

$$P(x) = \sum_{i=1}^k \lambda_i \langle x | c_i \rangle^d$$

Proof. We established that P is a linear combination of $\{R_1, \dots, R_k\}$. By theorem 5.3, P admits no quasi-cusp point and therefore $R_i(x) = -P(c_i) \langle c_i | x \rangle^d$ with $|P(c_i)| = \text{dist}(P, \Delta)$. \square

7. CRITICAL BAND OF EXTREMAL HYPER-SURFACES

Corollary 7.1. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Assume that the zero level of P on the unit sphere is locally extremal. Let $m = \text{dist}(P, \Delta)$,*

$$\text{if } \|x\| = 1 \text{ and } |P(x)| \leq m \text{ then } \|\nabla^T P(x)\|^2 > d(m^2 - P(x)^2)$$

Proof. By theorem 4.1, we have for all x in the unit sphere:

$$\text{dist}(P, \Delta_x) = P(x)^2 + \frac{1}{d} \|\nabla^T P(x)\|^2 \geq \text{dist}(P, \Delta) = m$$

If it existed $x \in \mathcal{S}^{n-1}$ such that $P(x)^2 + \frac{1}{d} \|\nabla^T P(x)\|^2 = \text{dist}(P, \Delta)$, x would be a quasi-cusp, by definition, contradicting the first item of the previous theorem.

Thus, for all $x \in \mathcal{S}^{n-1}$ we have $P(x)^2 + \frac{1}{d} \|\nabla^T P(x)\|^2 > m$ which yields the wanted inequality. \square

Definition 7.2. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Let $m = \text{dist}(P, \Delta)$, the critical band of P is the following set:*

$$\mathcal{B}_c(P) = \{x \in \mathcal{S}^{n-1} \text{ s.t. } |P(x)| < m\}$$

Theorem 7.3. *Let $P \in \mathbb{E}$ be an homogeneous polynomial of degree d with n variables. Assume that the zero level of P on the unit sphere is locally extremal.*

Let $\gamma : [a, b] \rightarrow \mathcal{B}_c(P)$ be an integral curve of $\nabla^T P$. Then, we have the following inequality:

$$\text{length}(\gamma) < \frac{1}{\sqrt{d}} \left| \arcsin\left(\frac{b}{m}\right) - \arcsin\left(\frac{a}{m}\right) \right|$$

This is bounded by $\frac{\pi}{\sqrt{d}}$ and, if a and b have the same sign, by half of it.

Proof. We can consider that γ is parametrised by the value of P because $\nabla^T P$ does not vanish in $\mathcal{B}_c(P)$ and therefore, the value of P will be monotonous along the arc. We may also assume without loss of generality that $a < b$.

This means that we have $P(\gamma(y)) = y$ which by derivation gives

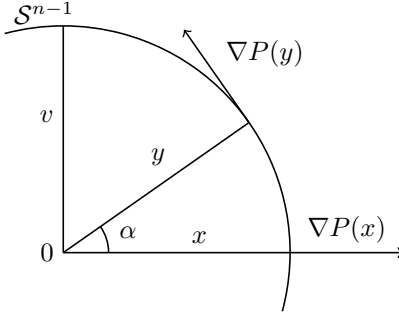


FIGURE 5.

$$\langle \nabla P(\gamma(y)) | \gamma'(y) \rangle = \langle \nabla^T P(\gamma(y)) | \gamma'(y) \rangle = 1$$

The previous corollary and the fact that $\gamma'(y)$ and $\nabla^T P(\gamma(y))$ are colinear yields:

$$\|\gamma'(y)\| = \frac{1}{\|\nabla^T P(\gamma(y))\|} < \frac{1}{\sqrt{d(m^2 - P(\gamma(y))^2)}} = \frac{1}{\sqrt{d(m^2 - y^2)}}$$

Finally, for the length, we have:

$$\begin{aligned} \text{length}(\gamma) &= \int_a^b \|\gamma'(y)\| dy \\ &< \frac{1}{\sqrt{d}} \int_a^b \frac{dy}{\sqrt{m^2 - y^2}} \\ &< \frac{1}{\sqrt{d}} \left(\arcsin\left(\frac{b}{m}\right) - \arcsin\left(\frac{a}{m}\right) \right) \end{aligned}$$

If $b < a$, reversing the arc gives the wanted result. \square

8. LARGE COMPONENTS FAR FROM THE DISCRIMINANT

The following proposition will have as consequence a lower bound for the size of connected components of an algebraic hyper-surfaces:

Proposition 1. *Let $P \in \mathbb{E}$ (i.e. P is an homogeneous polynomial of degree d with n variables). Let $\text{dist}(P, \Delta) \neq 0$ be the distance between P and the real discriminant of \mathbb{E} , then for any $x \in \mathcal{S}^{n-1}$ a critical point of P , the open spherical cap of \mathcal{S}^{n-1} with center x and radius angle $\alpha = \frac{1}{d} \sqrt{\frac{2 \text{dist}(P, \Delta)}{\|P\|}}$ does not meet the zero level of P .*

Proof. Let us consider $x \in \mathcal{S}^{n-1}$ a critical point of P and $y \in \mathcal{S}^{n-1}$ such that $P(y) = 0$. Consider α the measure of the angle $x0y$, and consider $v \in \mathcal{S}^{n-1}$ such that v orthogonal to x and $y = \cos(\alpha)x + \sin(\alpha)v$. See figure 5.

Then, we define:

$$f(\theta) = P(\cos(\theta)x + \sin(\theta)v)$$

We have:

$$\begin{aligned}
f(0) &= P(x) \\
f(\alpha) &= P(y) = 0 \\
f'(\theta) &= {}^t(-\sin(\theta)x + \cos(\theta)v)\nabla P(\cos(\theta)x + \sin(\theta)v) \\
f'(0) &= {}^t v \nabla P(x) = 0 \text{ because } v \text{ orthogonal to } x \text{ and } \nabla P(x) \\
f''(\theta) &= {}^t(-\sin(\theta)x + \cos(\theta)v)\mathcal{H}P(\cos(\theta)x + \sin(\theta)v)(-\sin(\theta)x + \cos(\theta)v) \\
&\quad + {}^t(-\cos(\theta)x - \sin(\theta)v)\nabla P(\cos(\theta)x + \sin(\theta)v)
\end{aligned}$$

Using the inequality of lemma 3.4 and the fact that $\cos(\theta)x + \sin(\theta)v \in \mathcal{S}^{n-1}$, we have:

$$\begin{aligned}
|f''(\theta)| &\leq \|\mathcal{H}P(\cos(\theta)x + \sin(\theta)v)\|_2 \|\sin(\theta)x + \cos(\theta)v\|^2 \\
&\quad + \|\nabla P(\cos(\theta)x + \sin(\theta)v)\| \|\cos(\theta)x - \sin(\theta)v\| \\
&= \|\mathcal{H}P(\cos(\theta)x + \sin(\theta)v)\|_2 + \|\nabla P(\cos(\theta)x + \sin(\theta)v)\| \\
&\leq d(d-1)\|P\| \|\cos(\theta)x + \sin(\theta)v\|^{d-2} + d\|P\| \|\cos(\theta)x + \sin(\theta)v\|^{d-1} \\
&= d^2\|P\|
\end{aligned}$$

Then, using Taylor-Lagrange equality, we find $\theta \in [0, \alpha]$ such that

$$0 = f(\alpha) = f(0) + \alpha f'(0) + \frac{\alpha^2}{2} f''(\theta) = P(x) + \frac{\alpha^2}{2} f''(\theta)$$

This implies:

$$|P(x)| \leq \frac{d^2 \alpha^2}{2} \|P\|$$

and therefore with theorem 4.3, we have

$$\alpha \geq \frac{1}{d} \sqrt{\frac{2 \operatorname{dist}(P, \Delta)}{\|P\|}}$$

□

Corollary 8.1. *Let $P \in \mathbb{E}$ and $\operatorname{dist}(P, \Delta) \neq 0$ be the distance between P and the discriminant for \mathbb{E} . Each connected component of the complement of the zero level of P in \mathcal{S}^{n-1} contains an open spherical cap of \mathcal{S}^{n-1} with center x and radius angle*

$$\alpha = \frac{1}{d} \sqrt{\frac{2 \operatorname{dist}(P, \Delta)}{\|P\|}}$$

Proof. Immediate because every connected component of the complement of the zero level of P contains at least one extrema of P which is a critical point of P . □

These two last results can also be used in the projective space $\mathcal{P}^{n-1}(\mathbb{R})$ with the metric induced by the metric on the sphere \mathcal{S}^{n-1} because the radius angle of the spherical cap in \mathcal{S}^{n-1} is the radius of a disk in $\mathcal{P}^{n-1}(\mathbb{R})$.

Theorem 8.2. *Let $P \in \mathbb{S}$ and $\operatorname{dist}(P, \Delta) \neq 0$ be the distance between P and the discriminant for \mathbb{E} . The distance (measured as an arc length) between two distinct connected components of the zero level of P in \mathcal{S}^{n-1} is greater or equal to*

$$\alpha = \frac{2}{d} \sqrt{\frac{2 \operatorname{dist}(P, \Delta)}{\|P\|}}$$

Proof. Consider an arc $[A, B]$ on \mathcal{S}^{n-1} joining two distinct connected components of the zero level of P . By the Ehresmann theorem [2], There is a point C on $[A, B]$

where P reaches a value greater, in absolute value, than a critical value of P . We can take C a point where $|P(x)|$ is maximum on $[A, B]$.

Then, by exactly the same computation than for the previous theorem, using the fact that $\nabla P(C)$ is zero in the direction of the segment, we find that the arc length of $[A, C]$ and $[C, B]$ are greater or equal to $\frac{1}{d} \sqrt{\frac{2\text{dist}(P, \Delta)}{\|P\|}}$ which ends the proof. \square

9. EXPERIMENTS WITH EXTREMAL CURVES

Section 6 suggests an algorithm to numerically optimise the distance to the discriminant of an hyper-surface: this algorithm requires to compute the quasi-singular points and solve a linear system to get a direction in which the distance increase. At each step, we do not need to recompute the quasi-singular points because we can use Newton's method to move the previous ones.

We have implemented such an algorithm as part of our GISurf software. It is not a robust algorithm and it sometimes encounter numerical problems. Nevertheless, we managed to use it on all maximal curves up to degree 6 (inclusive) and some curves of higher degree. We relate those experiments in the table 1 in the hope that they could help to build new conjectures.

Remark: because we deal with curves, we reinforced our theorem taking into account the nesting of connected components which give more locally extremal hyper-surfaces that just considering the number of connected components: there are two sextic curves with nine ovals that do not have the maximum $b_0 = 11$ but that are locally extremal.

It is important to note that these experiments only produce polynomials of Bombieri norm 1 that are likely to be near a local maxima of the distance to the discriminant. We currently have no way to find accurately (numerically or theoretically) the global maxima in each connected component of the complement of the real discriminant.

Degree 2, 3 and maximally nested ovals. Curves which have the maximum number of nested ovals are a particular case (i.e. $d/2$ nested ovals if the degree d is even and $(d - 1)/2$ nested ovals plus a projective line otherwise).

It seems from experiments that the polynomial maximising the distance to the discriminant in these cases is obtained as the revolution of a polynomial in two variables that has the maximum number of roots equally spaced on the unit circle. This may be defined as:

$$T_n(x, t) = \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} (-1)^k \binom{n}{2k} t^k x^{n-2k}$$

$$P_n(x, y, z) = T_n(x, y^2 + z^2)$$

The polynomials P_n are not of norm 1, and have infinitely many critical points with the critical value ± 1 . In fact the curve $P_n(1, x, y) = 0$ is a union of concentric circles centred in 0 plus one line at infinity, when n is odd. Therefore, they are

Degree	Topology	$\text{dist}(P, \Delta)$	$\ D\ $	$k = k^+ + k^-$
2	O	$\frac{1}{\sqrt{3}} \simeq 0.577$	0	$\infty = 1 + \infty$
3	$ O$	$\frac{1}{\sqrt{7}} \simeq 0.378$	0	$\infty = 1 + \infty$
4	$O \times 4$	7.1210^{-2}	1.4910^{-28}	$10 = 4 + 6$
4	(O)	$\frac{\sqrt{3}}{\sqrt{47}} \simeq 0.253$	0	$\infty = \infty + \infty$
5	$ O \times 6$	2.4910^{-3}	1.7210^{-20}	$15 = 6 + 9$
5	$ (O)$	$\frac{\sqrt{3}}{\sqrt{103}} \simeq 0.171$	0	$\infty = \infty + \infty$
6	$(O)O \times 9$	9.6110^{-5}	1.0110^{-13}	$22 = 9 + 13$
6	$(O \times 5)O \times 5$	6.5310^{-11}	2.1710^{-1}	$21 = 10 + 11$
6	$(O \times 9)O$	5.8110^{-9}	6.9110^{-3}	$21 = 11 + 10$
6	$(O \times 2)O \times 6$	2.4810^{-4}	6.5610^{-12}	$21 = 10 + 11$
6	$(O \times 6)O \times 2$	6.5610^{-7}	2.9310^{-6}	$20 = 10 + 10$
6	$((O))$	$\frac{\sqrt{5}}{\sqrt{371}}$	0	$\infty = \infty + \infty$
7	$ O \times 15$	2.3810^{-6}	1.5810^{-7}	$30 = 15 + 15$
8	$(O \times 3)O \times 18$	1.7810^{-8}	9.2910^{-1}	$39 = 18 + 21$

Degree: the degree of the polynomial (which has Bombieri norm 1)

Topology: O represents an oval, $|$ a projective lines (...) an oval containing other curves and we use \times to shorten the representation.

dist(P, Δ): the distance to the discriminant at the stage we stopped the optimisation.

||D||: following the notation of the proof of theorem 6.1. It converges toward 0 and gives a good indication to know it we are near the local minima. We highlighted in bold values which are not small enough to draw definitive conclusion.

k = k⁺ + k⁻: The number of pairs of quasi-double points together with the sign of the polynomials. For odd degree, this make only sense if we assume that the sign is taken on same half of S^{n-1} , split by the projective line that is always present in $P = 0$. We count in k^+ the critical values which are inside ovals not contained in other ovals.

TABLE 1. Experimental results

not irreducible. The point $(1, 0, 0)$ is the only isolated critical point. This is how we filled the corresponding lines of the table 1 with $\frac{1}{\|P_n\|}$. Experiments seems to indicate that these are global maxima of the corresponding connected components of Δ^c .

Extremal sextic curves and beyond. The table 1 includes five locally extremal sextic curves including the three curves with eleven components.

The most *difficult* one is Gudkov's sextic followed by Hilbert's. We have run our optimisation algorithm on these curves for several months! Yet, more computation are needed, as shown in the table. Computing accurately the direction of descent requires to use more than the 64 bits of precision available in *modern* processor. It is a pity that 128 bits have been abandoned in hardware, but luckily we used GNU MP.

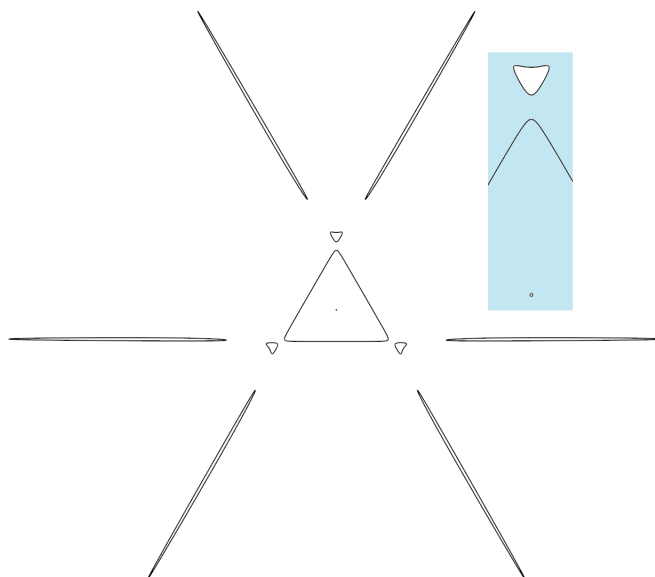


FIGURE 6. Harnack's sextic

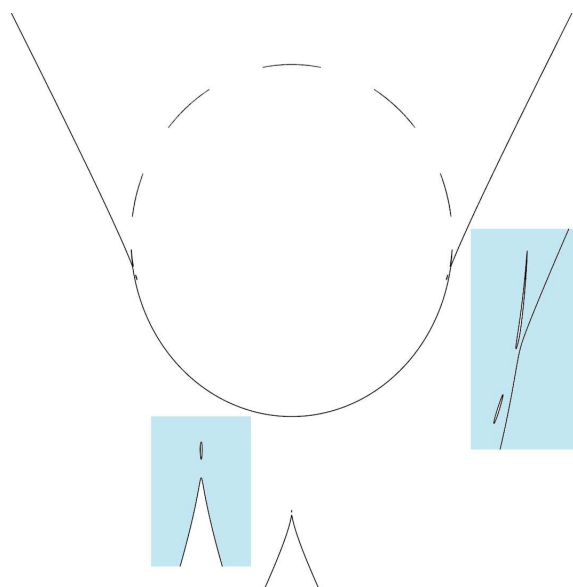


FIGURE 7. Hilberts' sextic

Remark: those curves are most of the time (always as far as the author knows) shown in literature as schemata. We give here in figure 6 to 10 drawing of the *real* curves. If you are interested to get the corresponding polynomials, you are welcome to visit the following web page:

<http://lama.univ-savoie.fr/~raffalli/glsurf-optimisation.php>

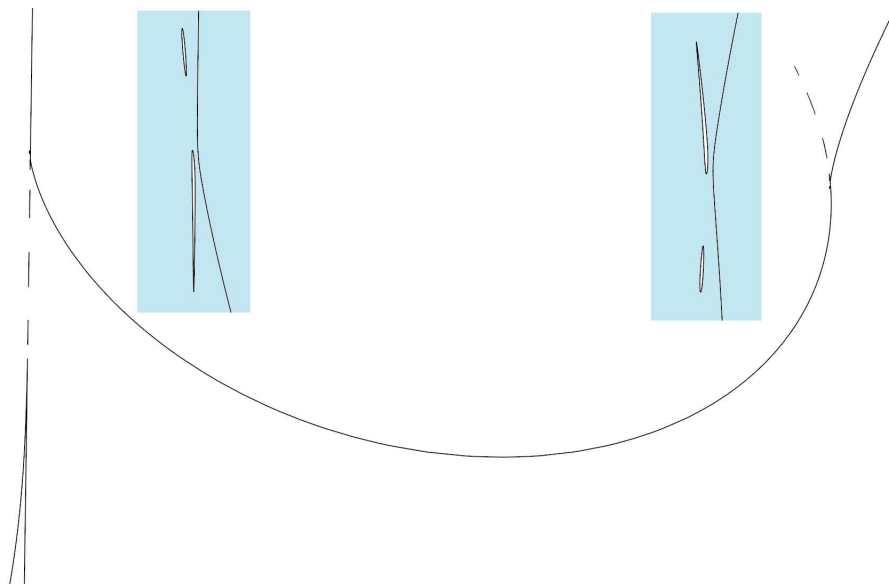


FIGURE 8. Gudkov's sextic

FIGURE 9. Sextic with topology $(O \times 6) OO$

The extremal curves which have only nine components are interesting. They show some *useless* pikes which are quite surprising. Probably, these pikes are necessary to have enough critical points.

We have also included results for Harnack's curves of degree seven and height. The later is also not yet optimised enough.

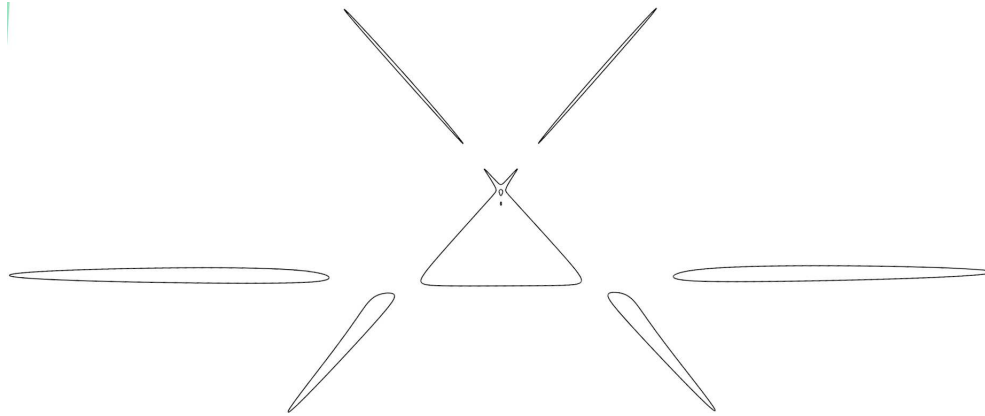


FIGURE 10. Sextic with topology $(OO) O \times 6$

APPENDIX A. PROOF OF THE INEQUALITIES FOR THE BOMBIERI NORM

We now prove the inequalities of lemma 3.4:

$$\begin{aligned} |P(x)| &\leq \|P\| \|x\|^d \\ \|\nabla P(x)\| &\leq d \|P\| \|x\|^{d-1} \\ \|\mathcal{H}P(x)\|_2 &\leq \|\mathcal{H}P(x)\|_F \leq d(d-1) \|P\| \|x\|^{d-2} \end{aligned}$$

We consider that $P_{\mathcal{B}} = (a_{\alpha})_{|\alpha|=d}$ and therefore, $P(x) = \sum_{|\alpha|=d} a_{\alpha} \sqrt{\frac{d!}{\alpha!}} x^{\alpha}$:

(1) For the first inequality, the proof is easy:

$$\begin{aligned} P(x)^2 &= \left(\sum_{|\alpha|=d} a_{\alpha} \sqrt{\frac{d!}{\alpha!}} x^{\alpha} \right)^2 \\ &\leq \sum_{|\alpha|=d} a_{\alpha}^2 \sum_{|\alpha|=d} \frac{d!}{\alpha!} x^{2\alpha} \text{ by Cauchy-Schwartz inequality} \\ &= \|P\|^2 \|x\|^{2d} \end{aligned}$$

(2) For the second inequality, we first consider the partial derivative $\frac{\partial P(x)}{\partial x_i}$:

$$\begin{aligned} \left(\frac{\partial P(x)}{\partial x_i} \right)^2 &= \left(\sum_{|\alpha|=d} a_{\alpha} \sqrt{\frac{d!}{\alpha!}} \alpha_i x^{\alpha - \chi_i} \right)^2 \\ &\leq \sum_{|\alpha|=d} \alpha_i a_{\alpha}^2 \sum_{|\alpha|=d} \frac{d!}{\alpha!} \alpha_i x^{2(\alpha - \chi_i)} \text{ by Cauchy-Schwartz} \\ &= d \sum_{|\alpha|=d} \alpha_i a_{\alpha}^2 \sum_{|\alpha|=d, \alpha_i \neq 0} \frac{(d-1)!}{(\alpha - \chi_i)!} x^{2(\alpha - \chi_i)} \\ &= d \sum_{|\alpha|=d} \alpha_i a_{\alpha}^2 \sum_{|\beta|=d-1} \frac{(d-1)!}{\beta!} x^{2\beta} \\ &= d \|x\|^{2(d-1)} \sum_{|\alpha|=d} \alpha_i a_{\alpha}^2 \end{aligned}$$

This means that:

$$\begin{aligned}
\|\nabla P(x)\|^2 &= \sum_{1 \leq i \leq n} \left(\frac{\partial P(x)}{\partial x_i} \right)^2 \\
&\leq \sum_{1 \leq i \leq n} \left(d \|x\|^{2(d-1)} \sum_{|\alpha|=d} \alpha_i a_\alpha^2 \right) \\
&= d \|x\|^{2(d-1)} \sum_{1 \leq i \leq n} \sum_{|\alpha|=d} \alpha_i a_\alpha^2 \\
&= d \|x\|^{2(d-1)} \sum_{|\alpha|=d} \left(\sum_{1 \leq i \leq n} \alpha_i \right) a_\alpha^2 \\
&= d^2 \|x\|^{2(d-1)} \sum_{|\alpha|=d} a_\alpha^2 \\
&= d^2 \|P\|^2 \|x\|^{2(d-1)}
\end{aligned}$$

(3) For the last inequality, we consider the partial derivative $\frac{\partial^2 P(x)}{\partial x_i \partial x_j}$ when $i \neq j$:

$$\begin{aligned}
\left(\frac{\partial^2 P(x)}{\partial x_i \partial x_j} \right)^2 &= \left(\sum_{|\alpha|=d} a_\alpha \sqrt{\frac{d!}{\alpha!}} \alpha_i \alpha_j x^{\alpha - \chi_i - \chi_j} \right)^2 \\
&\leq \sum_{|\alpha|=d} \alpha_i \alpha_j a_\alpha^2 \sum_{|\alpha|=d} \frac{d!}{\alpha!} \alpha_i \alpha_j x^{2(\alpha - \chi_i - \chi_j)} \text{ by Cauchy-Schwartz} \\
&= d(d-1) \sum_{|\alpha|=d} \alpha_i \alpha_j a_\alpha^2 \sum_{|\alpha|=d, \alpha_i \neq 0, \alpha_j \neq 0} \frac{(d-2)!}{\alpha - \chi_i - \chi_j!} x^{2(\alpha - \chi_i - \chi_j)} \\
&= d(d-1) \sum_{|\alpha|=d} \alpha_i \alpha_j a_\alpha^2 \sum_{|\beta|=d-2} \frac{(d-2)!}{\beta!} x^{2\beta} \\
&= d(d-1) \|x\|^{2(d-2)} \sum_{|\alpha|=d} \alpha_i \alpha_j a_\alpha^2
\end{aligned}$$

Now, we consider the partial derivative $\frac{\partial^2 P(x)}{\partial x_i^2}$:

$$\begin{aligned}
\left(\frac{\partial^2 P(x)}{\partial x_i^2} \right)^2 &= \left(\sum_{|\alpha|=d} a_\alpha \sqrt{\frac{d!}{\alpha!}} \alpha_i (\alpha_i - 1) x^{\alpha - 2\chi_i} \right)^2 \\
&\leq \sum_{|\alpha|=d} \alpha_i (\alpha_i - 1) a_\alpha^2 \sum_{|\alpha|=d} \frac{d!}{\alpha!} \alpha_i (\alpha_i - 1) x^{2(\alpha - 2\chi_i)} \text{ by Cauchy-Schwartz} \\
&= d(d-1) \sum_{|\alpha|=d} \alpha_i (\alpha_i - 1) a_\alpha^2 \sum_{|\alpha|=d, \alpha_i \geq 2} \frac{(d-2)!}{(\alpha - 2\chi_i)!} x^{2(\alpha - 2\chi_i)} \\
&= d(d-1) \sum_{|\alpha|=d} \alpha_i (\alpha_i - 1) a_\alpha^2 \sum_{|\beta|=d-2} \frac{(d-2)!}{\beta!} x^{2\beta} \\
&= d(d-1) \|x\|^{2(d-2)} \sum_{|\alpha|=d} \alpha_i (\alpha_i - 1) a_\alpha^2
\end{aligned}$$

Let us define $\iota_{i,j} = 0$ when $i \neq j$ and $\iota_{i,i} = 1$. Then, we have:

$$\begin{aligned}
\|\mathcal{H}P(x)\|_F^2 &= \sum_{1 \leq i, j \leq n} \left(\frac{\partial^2 P(x)}{x_i x_j} \right)^2 \\
&\leq \sum_{1 \leq i, j \leq n} \left(d(d-1) \|x\|^{2(d-2)} \sum_{|\alpha|=d} \alpha_i (\alpha_j - \iota_{i,j}) a_\alpha^2 \right) \\
&= d(d-1) \|x\|^{2(d-2)} \sum_{1 \leq i, j \leq n} \sum_{|\alpha|=d} \alpha_i (\alpha_j - \iota_{i,j}) a_\alpha^2 \\
&= d(d-1) \|x\|^{2(d-2)} \sum_{1 \leq i \leq n} \sum_{|\alpha|=d} \alpha_i (d-1) a_\alpha^2 \\
&= d(d-1) \|x\|^{2(d-2)} \sum_{|\alpha|=d} d(d-1) a_\alpha^2 \\
&= d^2 (d-1)^2 \|P\|^2 \|x\|^{2(d-2)}
\end{aligned}$$

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