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Adsorption and onset of lubrication by a double-chained cationic surfactant on silica surfaces

Laurence Serreau, Muriel Beauvais, Caroline Heitz, and Etienne Barthel

*Laboratoire Surface du Verre et Interfaces, UMR 125, CNRS/Saint-Gobain, 39
quai Lucien Lefranc, B.P. 135, F-93303 Aubervilliers cedex, France*

Abstract

In the context of glass fiber manufacturing the onset of lubrication by a C₁₈ double-chained cationic surfactant has been investigated at high normal contact pressures. Comparison with adsorption kinetics demonstrates that lubrication is not directly connected to the surfactant surface excess but originates from the transition to a defect-free bilayer which generates limited dissipation. The impact of ionic strength and shear rate has also been studied.

Key words: Friction, lubrication, silica, glass, surfactant, surface modification

PACS:

Email address: `etienne.barthel@saint-gobain.com` (Laurence Serreau,
Muriel Beauvais, Caroline Heitz, and Etienne Barthel).

1 INTRODUCTION

2 During glass fiber manufacturing, the high friction characteristic of silicate
3 surfaces in water results in surface damage and eventually prejudices the ten-
4 sile strength of the fibers. The necessary lubrication can be imparted through
5 an aqueous dispersion (sizing) which is applied at the initial stage of the glass
6 fiber manufacturing process. The sizing serves many purposes but double-
7 chained cationic surfactants (softeners) are often added to this dispersion to
8 participate in lubrication. However, it is well known that adsorption of sur-
9 factants proceeds slowly [1,2], especially for long-chained amphiphiles [3]. The
10 question we address in this paper is the kinetics of lubrication: once surfactant
11 adsorption has started, when will lubrication be effective ?

12 It is expected that the answer depends upon the mechanical loading and the
13 friction velocity in a complex manner. In practice, the typical drawing speed
14 is several meters per second, but the contacts between the several hundred
15 glass filaments within one fiber will slide at much slower velocities, which can
16 be in the range of millimeters per second or lower. The filaments slide against
17 each other in the presence of the sizing which initiates both adsorption and
18 lubrication. Such are the operating conditions we emulate in the present study.

19 Numerous studies have been conducted on the contact and also the friction
20 properties of surfactant covered surfaces. For practical reasons, the bulk of
21 the literature is devoted to short, single chain surfactants, which exhibit
22 faster equilibration [4,5,6]. Simultaneously, because of their relevance in bi-
23 ological applications, numerous papers deal with the adsorption of lipids. In
24 particular the structure of the surface aggregates and the mechanical response

25 of these insoluble double-chained surfactants have been studied in great de-
26 tails [6,7,8,9,10].

27 In this paper, we investigate the early stages of lubrication just after immersion
28 of silica surfaces in an aqueous dispersion of a typical double-chained (2 C₁₈)
29 cationic surfactant. The surfactant dispersion was investigated by Small Angle
30 Xray Scattering (SAXS) and Static Light Scattering (SLS) and the adsorption
31 kinetics on silica surfaces by Attenuated Total Reflection (ATR) Fourier Trans-
32 form Infrared (FTIR) spectroscopy. Using atomic force microscopy (AFM) and
33 macroscopic friction tests, we have measured the contact properties (repulsive
34 barrier, adhesion and friction) of macroscopic silica surfaces in the initial stages
35 of adsorption as a function of time after immersion. The results highlight the
36 impact of the adsorption kinetics and the changes of the surfactant configura-
37 tion during the early stages of adsorption. The picture which emerges is that
38 of a gradual transition from a disordered adsorbed layer with high friction to
39 a lubricating defect-free bilayer. Shear is shown to play a role in the transition
40 to the lubricating state.

41 **2 EXPERIMENTAL SECTION**

42 *2.1 Materials*

43 The double-chained cationic surfactant 1-methyl-2-noroleyl-3-oleic acid-aminoethyl-
44 imidazolinium methosulfate (DOAIM, Figure 1) in isopropanol (25% wt) is
45 obtained from Goldschmidt Rewo GmbH & Co.,(Germany) and used as re-
46 ceived. The molecular weight is 740 g/mol and the density 0.97 g/cm³. The
47 CMC with isopropanol measured by surface tension is 1×10^{-5} M. The chain

melting temperature is 46°C as measured by DSC, in agreement with the values obtained for similar compounds [11]. All the experiments were performed at ambient temperature.

Solutions of DOAIM at 5×10^{-4} M or 1×10^{-3} M were prepared in milli Q water with 24 hours gentle stirring after evaporation of the isopropanol at 60°C. Most experiments were carried out at natural pH \simeq 4.6. In a set of experiments, the ionic strength was varied with acetic acid/sodium acetate while maintaining constant pH=4.5. Such concentration and pH conditions are typical for actual sizing formulations.

2.2 Methods

2.2.1 Equilibrium characterization

The SAXS experiments were performed in a Kratky set-up (Anton Paar) with a Cu K $_{\alpha}$ source (0.1542 nm) and a linear gas detector placed at 23 cm from the source. The SLS experiments were performed on a Malvern Zetasizer 3 equipped with an He-Ne laser (633 nm), a photomultiplier and a goniometer. The same piece of equipment was used to measure the zeta potential by electrophoretic mobility in a liquid cell. The laser interferometric comb method was used. The test system was 200 nm diameter silica particles (Stoeber synthesis). Adsorption at a given concentration was carried out by dilution from a 10^{-4} M surfactant solution followed by 5 hour equilibration time. Surface tension was measured by the Wilhelmy plate method.

70 Adsorption kinetics were measured by FTIR spectroscopy in the ATR mode
 71 using a Nicolet Nexus 670 spectrometer equipped with a MIR source, a KBr
 72 beamsplitter and a MCT-A detector. The experiments were carried out on
 73 a germanium internal reflection element (trapezoidal, $50 \times 10 \times 1 \text{ mm}^3$, 45° inci-
 74 dent angle) covered on the larger side by a silica layer $\simeq 7 \text{ nm}$ thick deposited by
 75 magnetron sputtering. Before use, the surfaces were cleaned with a sequence
 76 of detergent solution, deionized water, acetone and absolute ethanol for 15
 77 minutes in an ultrasonic bath, followed by a final UV/Ozone treatment for
 78 1 h. After cleaning, the wafer was introduced in the internal multi-reflection
 79 cell which was immediately assembled and aligned in the sample compartment
 80 of the spectrometer. A peristaltic pump and a three-way valve were used to
 81 circulate either the pure solvent or the surfactant solution through the flow
 82 cell. Spectra were taken at a resolution of 4 cm^{-1} for 8, 32 or 128 scans. A
 83 background spectrum was collected after the cell was filled with water, before
 84 the surfactant solution was pumped in. Following Harrick [12,13,14,15,16], the
 85 amount of adsorbed surfactant can be quantified from the absorbance of some
 86 vibration band of the molecule. In our case we have followed the evolution
 87 of the CH_2 bands between 2800 and 3000 cm^{-1} . Absorbance of the vibration
 88 band $\nu_s (\text{CH}_2)$ at 2854 cm^{-1} is used to determine the surface excess as a
 89 function of time. This band has been chosen because it is less affected by the
 90 baseline drift associated with the strong band of water in the range $3200\text{-}3300$
 91 cm^{-1} . The surface excess Γ is calculated from [12,14]

$$92 \quad A = k\epsilon \left[\frac{c_s d_p}{2} + \Gamma \right] \quad (1)$$

$$d_p = \frac{\lambda}{2\pi n_1 \sqrt{\sin^2 \theta - \left(\frac{n_2}{n_1}\right)^2}} \quad (2)$$

$$k = \frac{n_2 E_0^2}{n_1 \cos \theta} N \quad (3)$$

where d_p is the penetration length of the evanescent wave, λ the wavelength, N the number of internal reflections, E_0 the electric field amplitude, n_1 and n_2 the refractive index of the germanium and the solution respectively, θ the incident angle, A and ϵ respectively the absorbance and molecular extinction coefficient of the vibration band considered, and c_s the concentration of the absorbing species in solution. Assumption is made that c_s is not modified by adsorption. In practice N and E_0 cannot easily be determined so that k is determined from relation (1) by a calibration with a non adsorbing compound of known extinction coefficient (tert-butanol).

2.2.3 AFM Surface forces measurement

AFMs have been used for surface forces measurements in various environments [17,18,19]. Here the experiments were performed on a Nanoscope III (Digital Instrument) with a silicon nitride tip using a liquid cell. Prior to the experiment, the tip was cleaned by irradiation for 60 minutes in a UV-ozone flow. A typical AFM experiment starts with a control of the tip shape quality and the silica surface cleanliness by measuring interaction forces between the AFM tip and the silica surface in milli-Q water. The DOAIM solution is then introduced and the surface forces profiles between tip and silica substrate are recorded every 3 minutes.

114 2.2.4 Friction experiments

115 Friction experiments have been performed on two reciprocating ball-on-plate
116 tribometers: for low pressure friction measurements, a home built millitribome-
117 ter with a 50 mN load range and a 0.02 mms^{-1} maximum sliding velocity was
118 used; for a larger friction velocity range, a commercial (Plint T79) tribometer
119 with sliding velocity ranging from 0.01 to 10 mms^{-1} . However, for this lat-
120 ter equipment, the normal load ranges between 0.1 and 20 N which results
121 in larger mean pressures. The plate is a silica, 2 mm thick substrate optically
122 polished on both sides (GE quartz). The ball is a fused silica sphere made from
123 silica rods (GE quartz). The end of the rod was melted with a blowtorch until
124 a molten droplet of glass formed with a radius of 2 to 4 mm. Both surfaces
125 were cleaned before use with a detergent-water-absolute ethanol sequence for
126 15 minutes in an ultrasonic bath.

127 To emulate lubrication in the presence of the sizing, the friction experiments
128 were all conducted in the presence of the aqueous surfactant dispersion, in-
129 side a liquid cell. It is also important to note that to minimize and control
130 the impact of shear, the typical friction experiments were not conducted as
131 continuous runs as is usually done for such measurements: on the contrary, un-
132 less otherwise stated, the surfaces were brought into contact every 5 minutes
133 for a series of two cycles only, typically lasting a few seconds and were then
134 separated again (Fig. 2). The friction force was measured by averaging on the
135 second cycle. When separated, care was taken that the silica surfaces remained
136 immersed in the solution until the next measurement. For each experiment,
137 the friction coefficient was first measured between surfaces immersed in pure
138 water. The water was then removed and replaced by the solution under study.
139 The first point in each friction graph is therefore the friction coefficient in pure

140 water.

141 3 Results

142

143 3.1 Characterization of the solution and adsorption

144 The pure surfactant system (after extraction of the isopropanol) is optically
145 birefringent. The SAXS diffractogram exhibits one single, fine Bragg peak
146 (Fig. 3) typical for an L_β phase. The repeat distance is 3.31 nm. After di-
147 lution in water (1 M), the system exhibits shear induced birefringence which
148 persists over days. In the SAXS diffractogram, a series of equally spaced peaks
149 is recorded (Fig. 3). These features are also typical for a lamellar phase. The
150 first order diffraction peak has moved to smaller wave vector and the repeat
151 distance has increased to 7.85 nm, which is fully consistent with the 7.65 nm
152 value expected for dilution of the lamellar phase to 1 M. Upon further dilu-
153 tion the Xray signal and the optical birefringence is lost. Around 1×10^{-3} M,
154 well above the CMC, the bilayer conformation is also evidenced optically by
155 the presence of multilamellar vesicles. At lower concentrations, SLS exper-
156 iments were carried out. The scattered intensity recorded for 2.5×10^{-3} and
157 1.0×10^{-4} M are displayed on Fig. 4. Beyond the quadratic behaviour for small
158 diffusion wave vectors, the static correlation function exhibits a moderate de-
159 cay. The full shape of the correlation function is consistent with extended
160 disks [20] as expected for large dilutions where the correlation between lamel-
161 lae is lost. The measured correlation length are 310 and 550 nm for 2.5×10^{-3}

162 and 1.0×10^{-4} M, showing that the materials behaves as sheets at lengthscales
163 smaller than the correlation length. In conclusion, the surfactant solution ex-
164 hibits a lamellar phase resulting from the bilayer association of the individual
165 surfactant molecules and the bilayer structure is preserved upon dilution.

166 From the surface tension as a function of concentration, we determined a criti-
167 cal micelle concentration $\text{CMC} = 9 \times 10^{-6}$ M and an area per head $A_H = 0.71 \text{ nm}^2$.
168 The results of the zeta potential measurements at natural pH are displayed on
169 Fig. 5. The zeta potential of the bare silica spheres is found at the expected
170 -60 mV value. Upon adsorption, the surface charge decreases and is finally
171 reversed at the point of zero charge $\text{PZC} = 5 \times 10^{-6}$ M well below the CMC.
172 This charge reversal behavior is characteristic for the adsorption of a bilayer
173 at the surface.

174 3.2 Friction – Time effect

175 A first series of friction experiments were carried out at low contact pressures
176 (concentration $C = 10^{-3}$ M, natural pH, sliding velocity $v = 0.014 \text{ mms}^{-1}$, mean
177 contact pressure $P_m = 90 \text{ MPa}$, Figure 6). The typical friction coefficient of
178 silica surfaces immersed in pure water is 0.6 ± 0.1 with a variability due to
179 surface preparation. Typical friction coefficients after five minutes of immer-
180 sion in the DOAIM solution ($C = 10^{-3}$ M) are down to 0.50 which indicates
181 negligible (though measurable) lubrication. On the other hand, if the surfaces
182 are first immersed 15 hours in a solution of DOAIM (10^{-3} M) before the fric-
183 tion experiment starts (procedure C) then the measured friction coefficient
184 is lower than 0.1, and sometimes reaches 0.03, revealing fully lubricated sur-
185 faces. Similar results are recorded for $C = 5 \times 10^{-4}$ M. The long equilibration

time in procedure C is typical for surfactant lubrication experiments [21,22]. A friction coefficient of about 0.1 or lower is usual for surfactant lubrication, especially for double-chained surfactants with long chains [8,23,24]. However, when the same friction experiment starts immediately after immersion in the surfactant solution (procedure A), the friction coefficient decreases to reach the low friction value (about 0.05) after only *ca* 2 hours. The transition is not linear with time. With repeated friction tests carried out every 5 min we observe an initial plateau at the high friction value around 0.5-0.6, which typically lasts 1 hour before the friction coefficient starts to decrease by one order of magnitude down to values around 0.05. These results exemplify the fact that lubrication with double-chained surfactants is not instantaneous but starts after an induction period.

3.3 *AFM surface forces measurements*

In the AFM force measurements, the force vs distance curve (Figure 7, inset) first displays a repulsive long range interaction, followed by a steeper repulsive interaction starting around 10 nm. The former has not been quantified due to the low signal to noise ratio but the results are consistent with the electrostatic double layer interaction demonstrated by the zeta potential measurements (Fig. 5). The latter is due to the mechanical compression of the bilayer. Then, for distances close to 3-4 nm, the AFM tip jumps into contact. This jump-in distance of 3-4 nm is close to the thickness of a DOAIM bilayer. Such a behaviour is well-known in the literature [4,25,26,27]. The jump-in force, defined as the repulsive force at jump-in, is an estimate of the mechanical resistance of the bilayers. Pulling the tip back induces the rupture of the

tip-surface contact: a negative force is registered which signals adhesion (not shown on the inset). The amplitude of this pull-out force is a measure of the tip-surface adhesion energy [28,29]. The jump-in force in a solution of DOAIM (1×10^{-3} M) has been measured as a function of time, as well as the pull-out force (Figure 7). We note that the jump-in and the pull-out forces measured here are tightly correlated, as already reported in the literature [21]. The jump-in force (counted positive) increases as the magnitude of the pull-out force (counted negative) decreases. They obey a time evolution similar to the friction coefficient: in procedure A, it stays constant for about one hour before the decrease to low friction; similarly jump-in and pull-out forces exhibit an initial plateau before a transition around 60 min to equilibrium values with large jump-in force and negligible adhesion. More complete results on the adsorption isotherm measured by ellipsometry and the mechanical response of the surfactant bilayer at equilibrium obtained with a Surface Forces Apparatus will be published separately.

3.4 Adsorption kinetics of DOAIM

In this context, it is interesting to correlate the time evolution of the contact properties with the amount of surfactant adsorbed on the surface (surface excess). A measurement of the adsorption kinetics (5×10^{-4} M, FTIR-ATR) is shown on Figure 8. Two different regimes are observed and the data is reasonably well fitted by a double exponential function with a fast time constant $\tau_1=25$ min and a slow time constant $\tau_2=205$ min, leading to a pseudo-plateau. At pseudo-saturation, the adsorbed amount is $6.2 \mu\text{molm}^{-2}$. Rinsing with recirculating water leads to little desorption, down to $5.5 \mu\text{molm}^{-2}$. The area

234 per molecule determined from surface tension measurements is 0.79 nm^2 . From
 235 this value we conclude that at saturation, a full bilayer is formed at the sil-
 236 ica surface. A comparison of Figures 6 and 7 with Figure 8 demonstrates that
 237 during the induction period, when the friction coefficient is high and constant,
 238 the adsorption of the surfactant is fast. When the transition to the lubricated
 239 state occurs (procedure A), we can estimate that the surface excess is already
 240 roughly as large as half a bilayer. From this observation we conclude that there
 241 is no simple proportionality relation between the adsorbed amount and the
 242 friction coefficient in this regime but that a more complex mechanism is called
 243 for to explain the onset of lubrication. In order to gain a clearer view of this
 244 mechanism, we have performed a series of experiments to probe the impact of
 245 kinetic parameters on the lubrication of the surfaces.

246 3.5 *Impact of shear on the onset of lubrication*

247 We measured the friction when the experiment starts only three hours after
 248 immersion in the solution (procedure B, Figure 6). In such conditions, the
 249 adsorption is almost complete (the surface excess amounts to 85% of the max-
 250 imum, Figure 8) and a lubricated surface is obtained following procedure A.
 251 If lubrication were only controlled by the adsorption of the surfactant, then a
 252 low friction coefficient would be expected, as with procedure C. In contrast, a
 253 trend similar to procedure A is observed: after 3 hours of induction, we mea-
 254 sure an initial value of the friction coefficient of approximately 0.5. Transition
 255 towards a low friction coefficient is observed around 1.5 hours after the friction
 256 experiment has started, and a low value (0.07) is reached about 2 hours after
 257 the beginning of the friction experiment, that is a total of about 5 hours after

immersion. This result attests to the fact that shear accelerates the onset of lubrication: low friction is obtained after 2 hours in procedure A, in which friction is probed every 5 minutes, but only after 5 hours in procedure B, where the system is completely at rest for the first 3 hours.

3.6 Ionic strength effect

Ionic strength also impacts the adsorption process. In the presence of salt (pH 4.5), the adsorption kinetics is much faster (Figure 8, inset) and for an ionic strength of 2×10^{-2} M, half-coverage of the surface is reached within minutes. Figure 9 shows the evolution of the friction coefficient with time (DOAIM 5×10^{-4} M, $P_m = 320\text{--}340$ MPa, pH=4.5) for different salt concentrations. The experiments follow procedure A where friction starts immediately after immersion. We observe that the transition towards low friction is considerably faster, a trend similar to the adsorption kinetics. The initial friction plateau has now been suppressed and the time to reach the lubricating state decreases when the ionic strength increases. For the highest salt concentration, the initial value of the friction coefficient after 5 minutes of immersion is already 3 times lower than in pure water. Note that the friction spike to 0.2 which follows the first low friction data point (Figure 9) is a reproducible feature presumably connected to more dissipative intermediate configurations towards a fully lubricated surface. Similarly at high ionic strength the AFM force curves demonstrate an almost instantaneous build-up of the repulsive force wall (not shown).

281 We have demonstrated in section 3.5 that shear accelerates the transition to
282 the lubricated state. A final set of experiments aims at exploring the im-
283 pact of *shear rate*. Friction experiments at different sliding velocities were
284 performed ($P_m=320\text{-}340$ MPa) following procedure A. For the lower velocity
285 (0.01 mms^{-1}), the global evolution is similar to the evolution recorded at lower
286 mean pressure in contact (90 MPa): the high (0.53) initial friction coefficient
287 decreases with time to reach a stable value of 0.06. However, we can perform
288 experiments in a wider velocity range only at higher loads (section 2.2.4). This
289 is why the transition towards low friction coefficient is achieved after 5 hours
290 instead of 2. For high velocities, the equilibrium configuration is reached much
291 faster, within 5-10 minutes. Figure 10 summarizes the main effects of the slid-
292 ing velocity on the initial and final values of the friction coefficient. Note that
293 the magnitude of the lubrication effect also decreases, since the value of the
294 friction coefficient of silica surfaces in pure water decreases with the sliding
295 velocity [30].

296 4 Discussion

297 4.1 *The generic lubricating state*

298 In the lubricated state, the friction coefficient is as low as 0.05, as observed for
299 instance in procedure C, after a 15 hour adsorption period. For the types of
300 loading used here, the mean normal pressures in the contact are significantly
301 larger than typical hemifusion thresholds for double-chained C_{18} surfactants

(several 10 MPa) [31]. As a result, hemifusion of the bilayers present on both surfaces occurs and this low value for the friction coefficient results from the friction between two hydrocarbon monolayers (Figure 11 b'). In this lubricated state, the average interfacial shear stress τ is of the order of 20 MPa and is little affected by the sliding velocity. Such a value is typical for monolayer-monolayer contacts in air [24] and is consistent with an approximate model connecting friction and adhesion hysteresis $\Delta\gamma$ [23]. Indeed it has been proposed that

$$\tau \simeq \Delta\gamma/\delta \quad (4)$$

where δ is a molecular dimension. Reasonable values are $\Delta\gamma \simeq 10 \text{ mJm}^{-2}$ and $\delta \simeq 1 \text{ nm}$ [24], so that $\tau \simeq 10 \text{ MPa}$. Friction between the outermost surfaces of the two pristine bilayers would lead to much lower friction coefficients: values one order of magnitude lower, as low as 0.004, were reported for instance for gemini surfactants [22].

4.2 Organisation during adsorption

As amply demonstrated by our present results, this configuration is not readily obtained upon adsorption from the solution. Indeed, the equilibrium configuration in the bulk is usually different from the equilibrium configuration of the surfactant aggregates adsorbed on a surface and the same surface excess may lead to very different surfactant conformations, with either dissipation and friction or lubrication. Subtle effects control the surfactant conformation after adsorption [32,33,34,35,36].

This is especially true when the interaction is strong, which is the case when surface and surfactant are oppositely charged: for cationic surfactants, the

325 electrostatic interaction with the negatively charged silica surface results in
 326 fast initial adsorption (Fig. 8). After this first adsorption stage, reorganization
 327 is required. For example, Chattoraj and Biswas [2] observed two characteris-
 328 tics times for the adsorption kinetics of short-chained cationic surfactants on
 329 silica surfaces. The mechanism they propose is as follows: in the first step, sur-
 330 factant molecules from the bulk diffuse to the surface and adsorb quickly with
 331 random orientation onto the silica surface; in the second step, the crowded
 332 molecules tend to re-orient in a regular fashion leading to the formation of ad-
 333 sorbed patches of surface micellar aggregates. Such configuration changes will
 334 create more vacant spaces for further adsorption of surfactant from the bulk to
 335 the surface. Similarly, for adsorption of CTAB *above* the cmc on mica surfaces,
 336 Chen *et al.* [1] propose a slightly different model where micelles adsorb directly
 337 on the surfaces and subsequently reorganize. The idea is supported by the fact
 338 that the same density of molecules is measured in the adsorbed layer and in
 339 the micelles in solution. DOAIM, as many double-chained C_{18} surfactant, is
 340 dispersed as bilayers as further demonstrated by the present optical, SAXS
 341 and SLS results. An adsorption process similar to lipid vesicle deposition must
 342 therefore be considered: the charged vesicles present in the solution will adsorb
 343 quickly as patches of bilayers and in an uncorrelated way [38,39]. Rearrange-
 344 ment must proceed before a defect-free bilayer is obtained [15]. This scenario
 345 parallels the mechanism proposed by Chen [1] but here the rearrangement is
 346 expected to be slower: the characteristic times for adsorption are considerably
 347 larger than for short chain surfactants [2,4] since for long chain surfactants,
 348 below the chain melting temperature, reorganization is hampered by the slow
 349 dynamics [3].

350 4.3 Bilayers, depletion and contact properties

351 The defective nature of the surfactant layer in the initial stage of adsorp-
352 tion strongly impacts its mechanical response. SFA experiments have shown
353 that lipid bilayers exhibit a smaller jump-in force and a larger pull-out force
354 when depleted, *i.e.* depletion facilitates hemifusion and increases adhesion [21].
355 Along the same line of thought, hemifusion in the SFA has been shown to corre-
356 late with defect density (monolayer or bilayer holes) as identified by AFM [40].
357 The defect density was controlled by the deposition pressure in the Langmuir-
358 Blodgett trough. Similar studies have been reported for the mechanical re-
359 sponse of lipid bilayers measured by AFM as a function of surface excess.
360 AFM experiments have shown that depletion [8] and ionic strength [6] impact
361 friction. The results were somehow discussed in terms of packing density. For
362 lipid bilayers, an interesting suggestion is that the reduced stability results
363 from the increased hydrophobic interactions between depleted bilayers [21],
364 not from a simple decrease in the density. Similarly, for shorter single-chained
365 surfactant it has also been observed either by SFA or AFM force measure-
366 ments that near the CMC, when the surfaces are pushed to bilayer contact,
367 the jump-in force increases with surfactant concentration while the adhesion is
368 maximum for monolayer coverage [16,41]. A connexion between micellization
369 energy and mechanical resistance at equilibrium has also been established [27].

370 These observations all converge to demonstrate that an increase in the packing
371 density of molecules in the outer layer of the bilayer leads to enhanced stability
372 and reduction of adhesion. In the present experiments the results demonstrate
373 an increase of the jump-in force and a reduction of adhesion as a function of
374 time (Fig. 7). For DOAIM adsorbed at concentrations significantly larger than

the CMC, the initial conformation is characteristic of frustrated aggregates adsorbed at the surface (Fig. 11, a), which we loosely call defective bilayer. Our results are in complete agreement with the picture of a gradual healing of the initially defective bilayer.

4.4 *Friction and onset of lubrication*

Initially, before the defect-free bilayer is formed, a large friction coefficient is recorded, around 0.5. Compared to the bare silica-silica friction coefficient, this value demonstrate a very moderate impact of the adsorbed surfactant. We suggest that this sizeable interfacial shear results from the dissipation which accompanies the deformation of the aggregates present at the surface. These deformations may be transitions from bilayer to tilted bilayer, aggregate ruptures, etc (Fig. 11, a'). Defective bilayers give rise not only to easier hemifusion and enhanced adhesion, but also to friction because they allow for more deformation at the molecular scale. The results are similar to the large friction recorded for lipid bilayers in AFM experiments when a second mechanical transition threshold is reached, well above hemifusion, and for which "direct surface contact" is evoked [6,8,38].

The decrease towards low friction is typically observed after 1 hour (Fig 6). In parallel the surface forces exhibit a decrease in the adhesion force and the repulsive jump-in force becomes more pronounced (Fig. 7). This trend we connect with the organization at the surface which evolves to a structure closer to a more ordered, stable, bilayer exposing fewer hydrophobic moieties. The transition at the local scale from a defective towards a stable bilayer has been completed. Indeed the friction (Fig. 6) and adhesion (Fig. 7) drops recorded

399 here are consistent with Eq. 4.

400 There remains to be explained why the transition is abrupt and does not di-
401 rectly correlate with the surface excess. It is possible that a critical flaw size
402 exists below which the pressure-induced transition to a tilted or disorganized
403 layer is prevented. This concept parallels the theory for bilayer stability [42,43].
404 If the flaw density is large enough, as occurs initially, the full surface induces
405 dissipation through aggregate edges. It is only when sufficient healing has
406 occurred and some defect-free patches have formed that the overall friction
407 coefficient decreases. In this scheme, the lubricated state results from stabili-
408 sation of the surfactant layer through healing of the larger defects.

409 The transition towards the lubricated state occurs faster in the presence of
410 salt, because ionic strength screens long range electrostatic double layer in-
411 teractions and facilitates rearrangement. Similarly, we have observed that the
412 transition towards lubricating state occurs earlier in time when the system
413 is submitted to friction immediately after immersion. Higher sliding velocity
414 also accelerates the transition. We conclude that shear and/or contact due to
415 the friction experiment itself favors the bilayer organization of the surfactant
416 between the two surfaces [41]. Indeed shear provides the symmetry breaking
417 driving force which promotes layering [44,45] as well as the mechanical energy
418 which activates structural transitions [46]. It favours surfactant accumulation
419 and lamellar ordering turning the adsorbed material into a fully formed bi-
420 layer [9,41].

421 5 Conclusion

422 The friction coefficient between millimetric silica surfaces was measured dur-
423 ing adsorption of a C₁₈ double-chained surfactant. A transition from high to
424 low friction is observed which parallels the contact properties measured with
425 the AFM. The results are not directly correlated to the surface excess. They
426 point to the role of the organisation of the surfactant into a defect-free bi-
427 layer for lubrication to be effective. Lubrication is obtained faster at higher
428 ionic strength and under shear because both facilitate the bilayer organiza-
429 tion. We have also study the impact of addition of other surface active sizing
430 components such as silanes on surfactant lubrication. Strong effects have been
431 evidenced due to interaction and/or competitive adsorption, which have been
432 published separately [47].

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435 References

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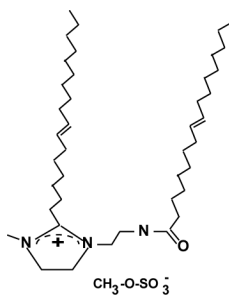


Fig. 1. Chemical structure of the DOAIM

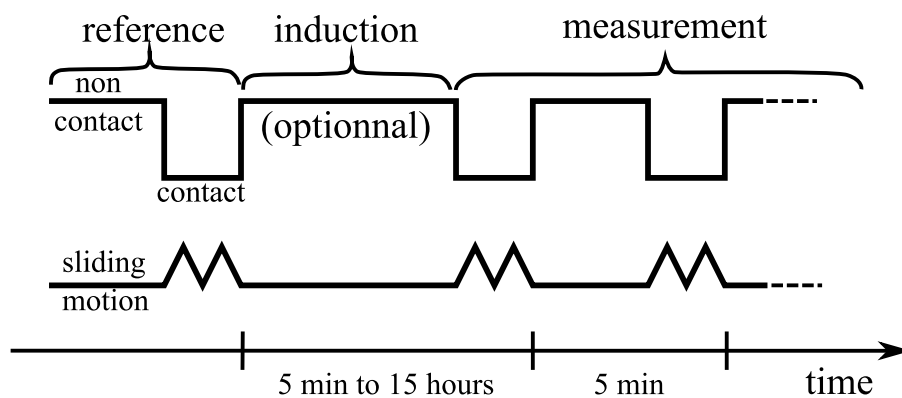


Fig. 2. Experimental protocol for the measurement of the kinetics of the onset of lubrication. The friction measurement proceeds by short friction runs separated by 5 min intervals during which the surfaces are kept far apart but submerged in the solution, in order to avoid drying problems. The measurement period is optionally preceded by an induction period during which the surfaces are kept far apart in the solution, without contact or friction measurement. The reference are individual runs performed initially in water and immediately after introducing the solution.

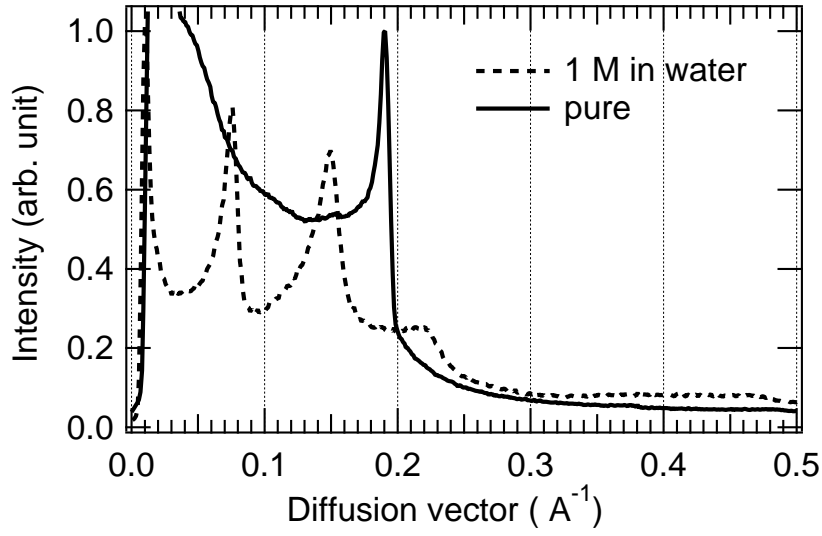


Fig. 3. X-ray diffraction spectra for pure and diluted DOAIM. The fine diffraction peaks shifting to smaller wave vector with dilution demonstrate the presence of a lamellar phase.

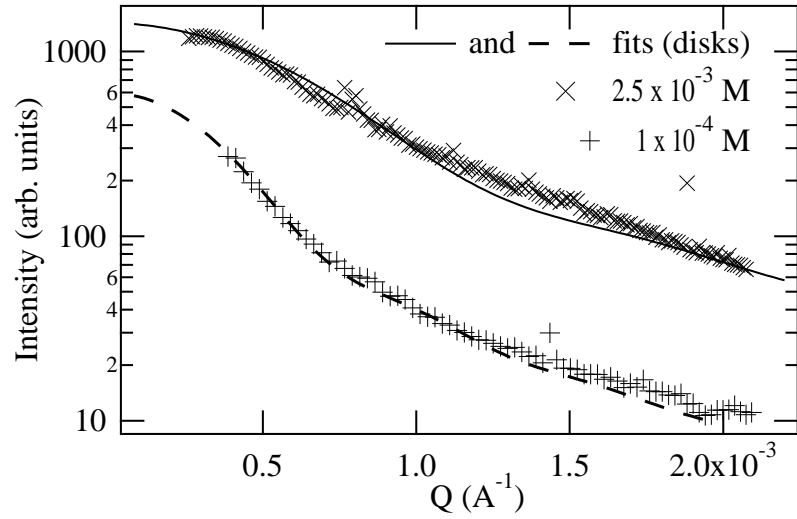


Fig. 4. Static light scattering of DOAIM at low concentrations with fits to disks shaped objects. The fits support the expected extremely diluted bilayer structure at these low concentrations.

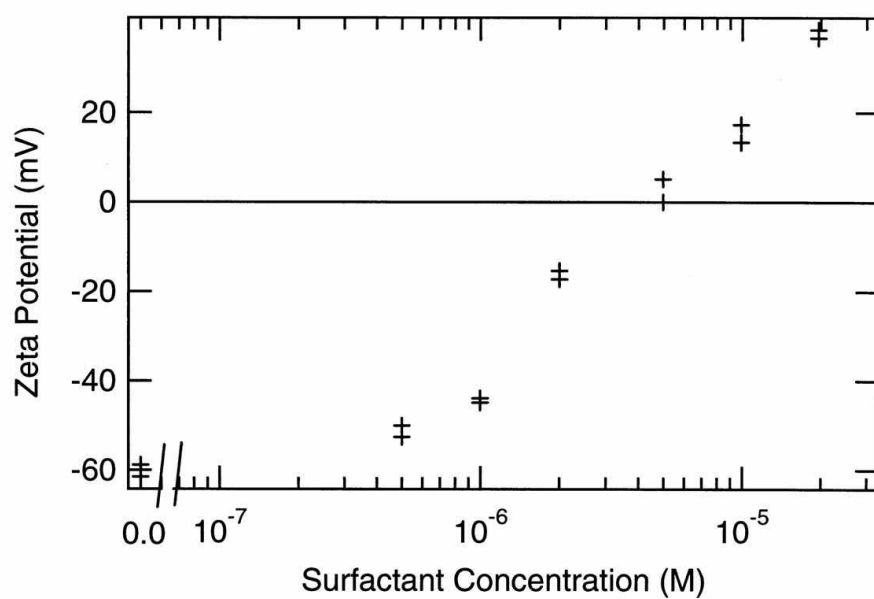


Fig. 5. Zeta potential as a function of surfactant concentration. The charge reversal is typical for the build-up of a surfactant bilayer at the surface.

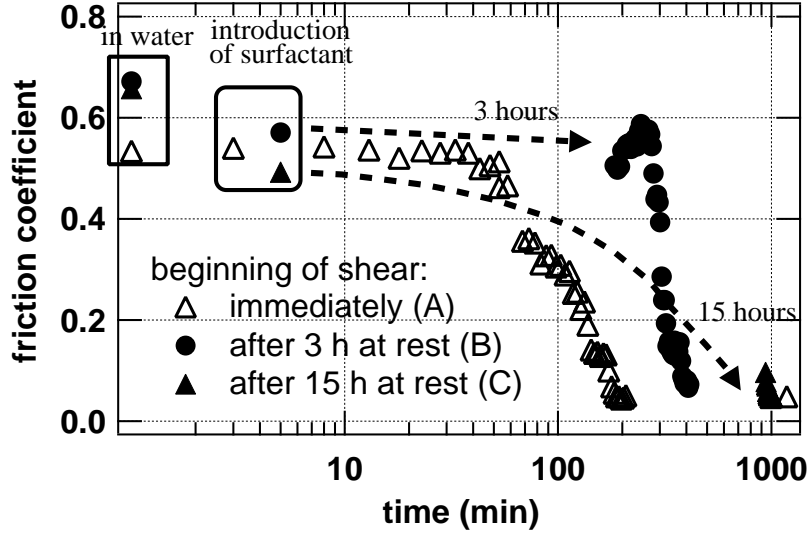


Fig. 6. Evolution of the friction coefficient vs immersion time ($C=10^{-3}$ M, $v=0.014$ mm s^{-1} , $P_m=90$ MPa). In all cases, the friction coefficient is first measured in pure water, then immediately after introduction of the surfactant. In procedure A, the friction coefficient is measured every 5 min. Procedures B and C are identical to procedure A, but the system is first left at rest for respectively 3 and 15 hours before the friction coefficient measurement starts. With procedures A and B, the friction is initially high and stays constant for some induction period. Low friction is observed immediately after the end of the 15 hour wait period in procedure C.

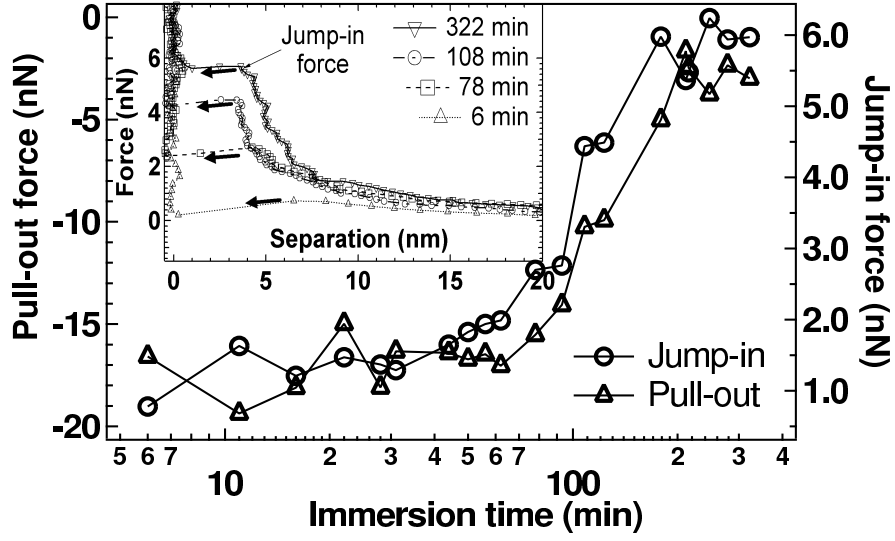


Fig. 7. Time evolution of the jump-in and of the pull-out forces between a silicon nitride tip and a silica surface ($C=1 \times 10^{-3}$ M). A few typical force vs distance curves are shown as inset.

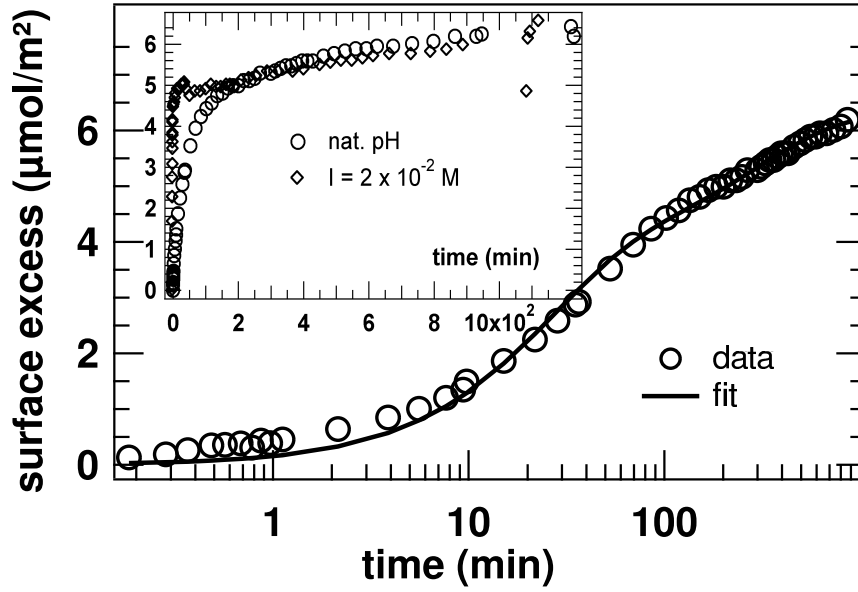


Fig. 8. Adsorption kinetics for DOAIM (5×10^{-4} M) in pure water and fit to a double exponential function ($\tau_1=25$ min, $\tau_2=205$ min). The inset compares the same data with the much faster kinetics at high ionic strength (2×10^{-2} M) on a linear time scale.

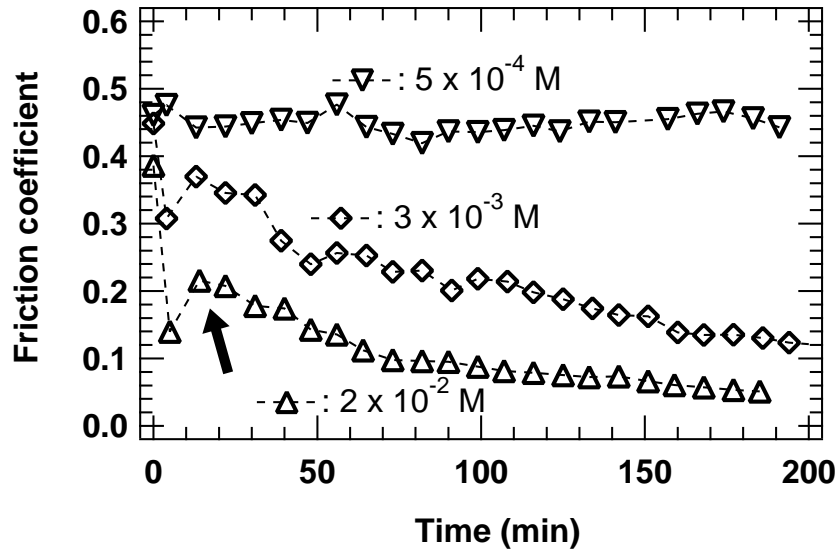


Fig. 9. Evolution of the friction coefficient versus immersion time ($C=5 \times 10^{-4}$ M, natural pH) at different ionic strengths. The arrow points to the friction spike observed after the initial lubrication effect of the surfactant.

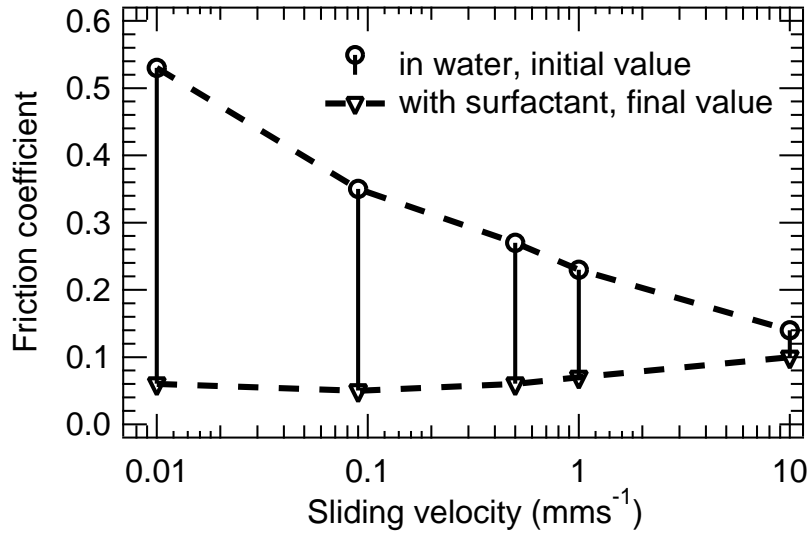


Fig. 10. Impact of shear velocity on the evolution of the friction coefficient between silica surfaces ($C=10^{-3}$ M, $P_m=320\text{-}340$ MPa, $v=10$ mms^{-1}).

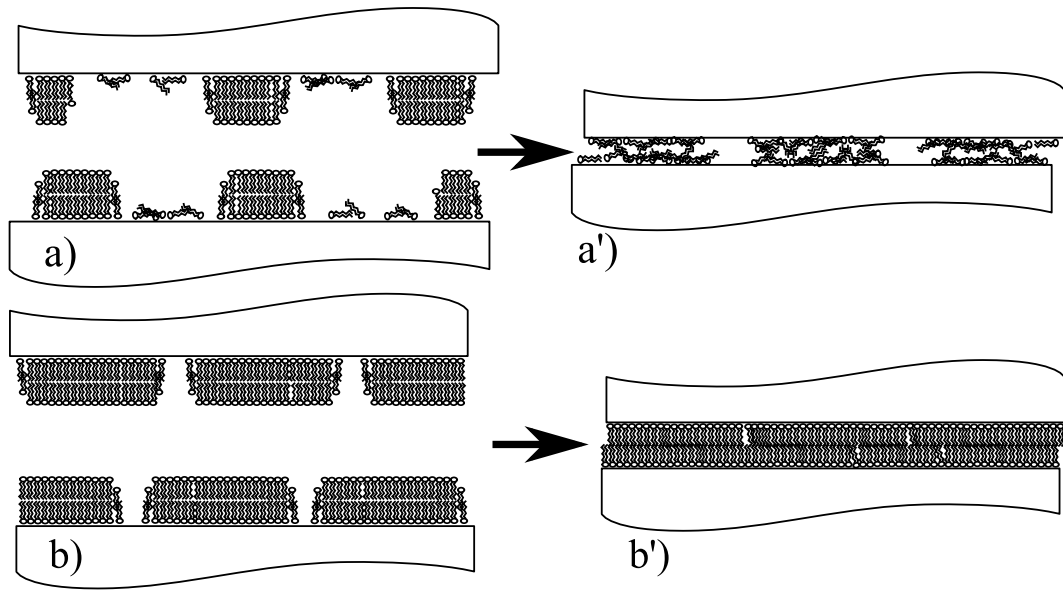


Fig. 11. Schematics of the surfactant instability for a highly defective (a, a') and an almost defect-free (b, b') bilayer.