

Backward stochastic differential equations in infinite dimensions with continuous driver and applications

Marco Fuhrman, Ying Hu

▶ To cite this version:

Marco Fuhrman, Ying Hu. Backward stochastic differential equations in infinite dimensions with continuous driver and applications. Applied Mathematics and Optimization, 2007, 56 (2), pp.265-302. 10.1007/s00245-007-0897-2. hal-00364758

HAL Id: hal-00364758 https://hal.science/hal-00364758

Submitted on 11 Dec 2017

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Backward Stochastic Differential Equations in Infinite Dimensions with Continuous Driver and Applications

Marco Fuhrman¹ and Ying Hu²

¹Dipartimento di Matematica, Politecnico di Milano, piazza Leonardo da Vinci 32, 20133 Milano, Italy marco.fuhrman@polimi.it

²IRMAR, Université Rennes 1, Campus de Beaulieu, 35042 Rennes Cedex, France ying.hu@univ-rennes1.fr

Abstract. In this paper we prove the existence of a solution to backward stochastic differential equations in infinite dimensions with continuous driver under various assumptions. We apply our results to a stochastic game problem with infinitely many players.

Key Words. Backward stochastic differential equations, Stochastic differential games.

AMS Classification. 60H10, 60H30.

1. Introduction

In this paper we consider the following backward stochastic differential equation (BSDE), in the sense of [19], on a finite time interval [0, T], in an infinite-dimensional setting:

$$dY_t = -BY_t \, dt - \psi(t, X_t, Y_t, Z_t) \, dt + Z_t \, dW_t, \qquad Y_T = \varphi(X_T). \tag{1.1}$$

In the above, *W* is a cylindrical Wiener process in a Hilbert space Ξ , *B* is the infinitesimal generator of a strongly continuous dissipative compact semigroup (e^{tB}) in a Hilbert space *K*, *X* is a Markov process with respect to the filtration generated by *W*, and ψ and φ are deterministic functions with values in *K*. The solution (*Y*, *Z*) takes values in $K \times L_2(\Xi, K)$, where $L_2(\Xi, K)$ denotes the space of Hilbert–Schmidt operators from Ξ to *K*. The solution is understood in an appropriate sense, see below.

BSDEs in infinite dimensions were first studied in [17]. In this paper the authors proved the existence and uniqueness of the solution to BSDE (1.1) assuming that the driver ψ is uniformly Lipschitz with respect to (y, z).

BSDEs in infinite dimensions were also studied in [1]–[3], [10], [14], [18] and [20], in the more general case when the driver ψ can be random. In [9]–[12], (1.1) was considered when the process X takes values in a Hilbert space H and is defined as the solution to a stochastic evolution equation of the form

$$dX_t = AX_t dt + F(t, X_t) dt + G(t, X_t) dW_t, \qquad X_0 = x \in H.$$
(1.2)

Here A is the infinitesimal generator of a strongly continuous semigroup (e^{tA}) in H, and F and G are appropriate functions with values in H and in the space of bounded linear operators from Ξ to H, respectively. Various problems were considered in these papers, including applications to nonlinear partial differential equations for functions defined on $[0, T] \times H$ and optimal stochastic control. In [13] the fully coupled case is addressed, i.e. when F and G may depend on the unknown processes Y and Z.

In this paper we prove the existence of a solution to BSDE (1.1) assuming that ψ is only continuous with respect to (y, z).

Our starting point is the result in [15], where all the processes W, X, Y, Z take values in finite-dimensional vector spaces. In that paper ψ is assumed to have linear growth with respect to (y, z); this allows one to prove the existence result for the BSDE and to prove the existence of a Nash equilibrium in an N-player stochastic differential game. A crucial assumption in that paper is a condition on the densities of transition probabilities of the process X with respect to the Lebesgue measure. This condition is fulfilled in the case when G is uniformly nondegenerate. The result of [15] was generalized in [16] to the case of discrete-functional-type drivers.

In our paper we also impose conditions on the transition probabilities of the process X. However, due to the infinite-dimensional nature of the state space H, we need completely different assumptions.

In Section 3 we consider the case when X is an Ornstein–Uhlenbeck process, i.e. it solves (1.2) with F = 0 and G constant. In this case explicit conditions are known to ensure equivalence of transition probabilities. We prove a formula for mutual densities, generalizing a result in [4], and use it to prove the existence of a solution to (1.1) assuming that ψ has linear growth with respect to (y, z). Generalizations of this result to more general processes X seem to be possible, for instance using the formulae for transition densities introduced in [22]–[24]. The present result is however sufficient for the applications to stochastic games that we present.

In Section 6 we apply the existence result for the BSDE to prove the existence of a Nash equilibrium in a stochastic game. The underlying controlled process has a nonlinear drift and constant diffusion coefficient: see (6.1). This time, using the infinite-dimensionality of the process Y, we are able to study a stochastic game with infinitely many players. Stochastic games with an infinite number of players are a mathematical model used to describe a variety of economical and financial markets, but so far a dynamical setting with continuous time was not considered to our knowledge, perhaps due to the complexity of the techniques involved.

In Sections 4 and 5 we only assume that X is a Markov process with values in a metric space, and we prove the existence of a solution to the BSDE assuming that

 ψ is bounded. We impose two kinds of conditions. First, in Section 4, we require the transition probabilities of X to be equivalent to each other (but no condition is imposed on the corresponding densities). An application is given in Section 4.1, again in the case of a process solution of an evolution equation of the form (1.2). Second, in Section 5, we address a case where transition probabilities can be even singular, and we require a continuity condition with respect to the variation norm: see (5.2). This kind of property is customary in the theory of stochastic evolution equations in infinite-dimensional spaces: it has been deeply investigated in connection with the so-called strong Feller property and several conditions are known which guarantee that it is verified: see [6]. One example is given below, see Section 5.1, to show applicability of the general result.

In Section 2 we introduce notation, we state a general approximation lemma and recall some facts about the Ornstein–Uhlenbeck process in a Hilbert space.

Some results of this paper have been announced at the Fourth International Conference on Backward Stochastic Differential Equations and Applications, Shanghai, May 30th to June 1st, 2005. The first author thanks the Université de Rennes 1 for his stay during which this article was begun.

2. Preliminaries

In this section we collect material that will be used in what follows. First we recall some notation, then we define the Ornstein–Uhlenbeck semigroup that is used in Sections 3 and 6, finally we state and prove an approximation lemma that is frequently used afterwards.

2.1. Notation

In this paper the letters H, K, Ξ denote Hilbert spaces. All Hilbert spaces are assumed to be real and separable. The norm is denoted $|\cdot|$ and the scalar product $\langle \cdot, \cdot \rangle$, with a subscript to indicate the space, if necessary. L(H, K) denotes the space of linear bounded operators from H to K, with its usual norm. We shorten L(H, H) to L(H). $L_2(H, K)$ denotes the space of Hilbert–Schmidt operators from H to K, with the Hilbert–Schmidt norm. Operator norms are also denoted by $|\cdot|$, with a subscript if necessary.

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space. A cylindrical Wiener process $\{W_t, t \ge 0\}$ in a Hilbert space Ξ is a family of linear mappings $\xi \to W_t^{\xi}$, defined for $\xi \in \Xi$ with values in $L^2(\Omega, \mathcal{F}, \mathbb{P})$, such that $\{W_t^{\xi}, t \ge 0\}$ is a real Wiener process and $\mathbb{E}[W_t^{\xi}W_s^{\eta}] = (t \land s)\langle \xi, \eta \rangle$ for $\xi, \eta \in \Xi$ and $t, s \ge 0$. By \mathcal{F}_t we denote the σ -algebra generated by the random variables $\{W_s^{\xi}, s \in [0, t], \xi \in \Xi\}$ and by the \mathbb{P} -null sets of \mathcal{F} . We call $(\mathcal{F}_t)_{t\ge 0}$ the Brownian filtration of W.

Stochastic integration theory can be defined with respect to W: we refer to [5] for details. If $\{\Psi_t, t \in [0, T]\}$ is an (\mathcal{F}_t) -predictable process with values in $L_2(\Xi, H)$, satisfying \mathbb{P} -a.s. $\int_0^T |\Psi_t|_{L_2(\Xi,H)}^2 < \infty$ then the stochastic integral $\{\int_0^t \Psi_s dW_s, t \in [0, T]\}$ is an (\mathcal{F}_t) -local martingale with values in H admitting a continuous version.

2.2. The Ornstein–Uhlenbeck Process

Let H, Ξ be Hilbert spaces. We are given two linear operators A: $D(A) \subset H \to H$ and $G \in L(\Xi, H)$ such that

Hypothesis 1.

- (i) The operator A: $D(A) \subset H \to H$ is the infinitesimal generator of a strongly continuous semigroup $\{e^{tA}, t \ge 0\}$ of bounded linear operators in H.
- (ii) $G: \Xi \to H$ is a bounded linear operator.
- (iii) The operators

$$Q_t x = \int_0^t e^{sA} G G^* e^{sA^*} x \, ds, \qquad x \in H,$$

(iv) are of trace class for all
$$t \ge 0$$
.
(iv) $e^{tA}(H) \subset Q_t^{1/2}(H)$, for all $t > 0$.

We define the Ornstein–Uhlenbeck process as the solution of the following stochastic equation:

$$dX_t = AX_t dt + G dW_t, \qquad X_0 = x, \tag{2.1}$$

where $x \in H$ is given and W is a cylindrical Wiener process in Ξ . Equation (2.1) is understood in the so-called mild sense: the solution is by definition the process

$$X_t = e^{tA}x + \int_0^t e^{(t-s)A}G \, dW_s, \qquad t \ge 0.$$
(2.2)

It is well known (see, e.g. [5]) that under assumptions (i)–(iii) in Hypothesis 1 the Ito integral is well defined and X_t is a random variable with values in H with law $\mathcal{N}(e^{tA}x, Q_t)$, i.e. the Gaussian measure with mean $e^{tA}x$ and covariance operator Q_t . Moreover, condition (iv) ensures that the measures { $\mathcal{N}(e^{tA}x, Q_t), t > 0, x \in H$ } are all equivalent. In the following we fix $0 < t \leq T, x \in H$ and we denote by $k_{tT}(x, \cdot)$ the density of $\mathcal{N}(e^{tA}x, Q_t)$ with respect to $\mathcal{N}(0, Q_T)$.

Lemma 2. Assume that Hypothesis 1 holds, and let $0 < t \le T$ and $x \in H$ be given. *Define*

$$\Theta_{tT} = Q_T^{-1/2} e^{tA} Q_{T-t} (Q_T^{-1/2} e^{tA})^*.$$
(2.3)

Then $1 - \Theta_{tT}$ is a positive operator with bounded inverse and we have, for $\mathcal{N}(0, Q_T)$ almost every $y \in H$,

$$k_{tT}(x, y) = \det(1 - \Theta_{tT})^{-1/2} \exp\{-\frac{1}{2}\langle (1 - \Theta_{tT})^{-1}Q_{T}^{-1/2}e^{tA}x, Q_{T}^{-1/2}e^{tA}x\rangle + \langle (1 - \Theta_{tT})^{-1}Q_{T}^{-1/2}e^{tA}x, Q_{T}^{-1/2}y\rangle - \frac{1}{2}\langle \Theta_{tT}(1 - \Theta_{tT})^{-1}Q_{T}^{-1/2}y, Q_{T}^{-1/2}y\rangle\}.$$
(2.4)

We also have the following estimates:

$$|(1 - \Theta_{tT})^{-1}| \le 1 + |Q_{T-t}||Q_t^{-1/2}e^{tA}|^2$$
(2.5)

and

$$\det(1 - \Theta_{tT})^{-1} \le \exp\{(1 + |Q_{T-t}||Q_t^{-1/2}e^{tA}|^2) |Q_t^{-1/2}e^{tA}|^2 \operatorname{Trace} Q_{T-t}\}.$$
 (2.6)

By 1 we also denote the identity operator. These formulae need some explanations. First we note that, as a consequence of Hypothesis 1, one can prove that the operators $Q_T^{-1/2}e^{tA}$ and $Q_t^{-1/2}e^{tA}$ are everywhere defined and bounded and that Θ_{tT} is a symmetric trace class operator satisfying $0 \le \Theta_{tT} < 1$. Next, the determinant occurring in (2.4) and (2.6) is understood as the infinite product of eigenvalues. It is well defined, since Θ_{tT} is trace class. Finally, for arbitrary $b \in H$ and trace class symmetric operator M the functions $\langle b, Q_T^{-1/2} y \rangle$ and $\langle M Q_T^{-1/2} y, Q_T^{-1/2} y \rangle$, $y \in H$, are defined by the formulae

$$\langle b, Q_T^{-1/2} y \rangle = \sum_{j=1}^{\infty} \lambda_j^{-1/2} \langle b, e_j \rangle \langle y, e_j \rangle$$
(2.7)

and

$$\langle MQ_T^{-1/2}y, Q_T^{-1/2}y \rangle = \sum_{j,k=1}^{\infty} \lambda_j^{-1/2} \lambda_k^{-1/2} \langle Me_k, e_j \rangle \langle y, e_j \rangle \langle y, e_k \rangle,$$

where (e_k) , (λ_k) are the eigenvectors and eigenvalues of Q_T , the eigenvalues are strictly positive. The series converge in $L^2(H, \mathcal{N}(0, Q_T))$ so that formula (2.4) defines a function $k_{tT}(x, \cdot)$ up to a set of $\mathcal{N}(0, Q_T)$ measure 0. In particular, the function $y \to \langle b, Q_T^{-1/2} y \rangle$ defined in (2.7) has centered gaussian law with covariance $|b|^2$ on the probability space $(H, \mathcal{N}(0, Q_T))$ and it follows that

$$\int_{H} \exp\{\langle b, Q_T^{-1/2} y \rangle\} \mathcal{N}(0, Q_T)(dy) = \exp\{\frac{1}{2}|b|^2\}.$$
(2.8)

Lemma 2 is similar to Proposition 4.2 in [4], where densities with respect to the invariant measure of the process X were considered instead of densities with respect to $\mathcal{N}(0, Q_T)$. Here we do not assume that X has an invariant measure. The proof of Lemma 2 is postponed to the Appendix.

2.3. An Approximation Procedure

Lemma 3. Let M be a metric space, let H and K be Hilbert spaces and let ψ : $M \times H \to K$ be a Borel measurable function satisfying

$$|\psi(m,h)| \le C(|h| + g(m)), \qquad m \in M, \quad h \in H,$$

for some constant C > 0 and some function $g: M \to [0, \infty)$. Let $\psi(m, \cdot): H \to K$ be a continuous function for every $m \in M$. Then there exists a sequence of Borel measurable

functions $\psi_n: M \times H \to K$ satisfying the following conditions:

(i) There exists a constant C' > 0 such that, for every n,

 $|\psi_n(m,h)| \le C'(|h| + g(m) + 1), \qquad m \in M, \quad h \in H.$

- (ii) For every $m \in M$, $\psi_n(m, \cdot)$: $H \to K$ is infinitely Fréchet differentiable.
- (iii) There exist constants $C_n > 0$ such that, for every n,

 $|\psi_n(m,h) - \psi_n(m,k)| \le C_n |h-k|, \qquad m \in M, \quad h, k \in H.$

(iv) If $h_n \to h$ in H then $\psi_n(m, h_n) \to \psi(m, h)$ in K, for every $m \in M$.

Proof. We use the construction in [21]. Let (e_i) denote a basis of H and define the projection P_n : $H \to \mathbb{R}^n$ setting $P_n h = (\langle e_i, h \rangle)_{i=1}^n$, $h \in H$. Then for $y = (y_i)_{i=1}^n \in \mathbb{R}^n$ we have $P_n^* y = \sum_{i=1}^n y_i e_i$. Let $\rho_n \colon \mathbb{R}^n \to [0, \infty)$ be infinitely differentiable functions such that $\int_{\mathbb{R}^n} \rho_n(y) dy = 1$ with support contained in $\{y \in \mathbb{R}^n \colon |y|_{\mathbb{R}^n} \le 1/n\}$. Define

$$\overline{\psi}_n(m,h) = \int_{\mathbb{R}^n} \psi(m, P_n^*(P_nh + y))\rho_n(y) \, dy, \qquad h \in H, \quad m \in M$$

It is easy to show that $\overline{\psi}_n(m, \cdot)$: $H \to K$ is infinitely Fréchet differentiable, that $\overline{\psi}_n(m, h_n) \to \psi(m, h)$ whenever $h_n \to h$ in H, and to prove the estimate $|\overline{\psi}_n(m, h)| \leq C'(|h|+g(m)+1)$, for some constant C'. Next we take $\eta_n \in C^{\infty}(\mathbb{R})$ such that $\eta_n(x) = 1$ for $x \leq n$, $\eta_n(x) = 0$ for $x \geq n+1$, and $|\eta_n(x)| + |\eta'_n(x)| \leq c$ for some constant c. Then setting

$$\psi_n(m,h) = \eta_n(\sqrt{1+|h|^2} - 1 + g(m))\overline{\psi}_n(m,h), \qquad h \in H, \quad m \in M$$

it is easy to show that the gradient of ψ_n is bounded by some constant (depending on *n*) and that all the conclusions of the lemma are satisfied.

3. BSDE with a Linear Growth Continuous Driver

In this section we consider a BSDE of the form

$$dY_t = -BY_t \, dt - \psi(t, X_t, Y_t, Z_t) \, dt + Z_t \, dW_t, \qquad Y_T = \varphi(X_T), \tag{3.1}$$

for *t* varying on a bounded time interval [0, *T*]. *W* is a cylindrical Wiener process in a Hilbert space Ξ and we denote by (\mathcal{F}_t) its Brownian filtration. The unknown processes *Y* and *Z* take values in a Hilbert space *K* and in the Hilbert space $L_2(\Xi, K)$, respectively. *X* is a given (\mathcal{F}_t) -predictable process in another Hilbert space *H*. On the drivers *B* and ψ and the final datum φ we assume the following.

Hypothesis 4.

(i) The operator B: $D(B) \subset K \to K$ is the infinitesimal generator of a strongly continuous dissipative semigroup $\{e^{tB}, t \ge 0\}$ of linear bounded operators on K.

- (ii) φ: H → K and ψ: [0, T] × H × K × L₂(Ξ, K) → K are Borel measurable functions, and there exist two constants C > 0 and p ≥ 1 such that |φ(x)| ≤ C(1 + |x|^p), x ∈ H, |ψ(t, x, y, z)| ≤ C(1 + |x|^p + |y| + |z|),
 - $t \in [0, T], x \in H, y \in K, z \in L_2(\Xi, K).$
- (iii) For every $t \in [0, T]$ and $x \in H$, the function $\psi(t, x, \cdot, \cdot)$: $K \times L_2(\Xi, K) \to K$ is continuous.

Let us suppose that $\sup_{t \in [0,T]} \mathbb{E} |X_t|^{2p} < \infty$. We say that an (\mathcal{F}_t) -predictable process (Y, Z) with values in $K \times L_2(\Xi, K)$ is a mild solution of (3.1) if

$$\sup_{t\in[0,T]} \mathbb{E} |Y_t|^2 + \mathbb{E} \int_0^T |Z_t|^2 dt < \infty$$
(3.2)

and for every $t \in [0, T]$ the following equality holds:

$$Y_{t} + \int_{t}^{T} e^{(s-t)B} Z_{s} dW_{s}$$

= $e^{(T-t)B} \varphi(X_{T}) + \int_{t}^{T} e^{(s-t)B} \psi(s, X_{s}, Y_{s}, Z_{s}) ds$, P-a.s. (3.3)

The result of [17] states that there exists a unique mild solution if, in addition to the previous assumptions, one supposes that the function $\psi(t, x, \cdot, \cdot)$ is Lipschitz continuous. In the following we drop the Lipschitz condition and prove some existence results. We first need some preliminary estimates.

Lemma 5. Assume that Hypothesis 4 holds and let X be an (\mathcal{F}_t) -predictable process satisfying $\sup_{t \in [0,T]} \mathbb{E}|X_t|^{2p} < \infty$. Let (Y, Z) be a mild solution to (3.1). Then

$$\sup_{t \in [0,T]} \mathbb{E} |Y_t|^2 + \mathbb{E} \int_0^T |Z_t|^2 dt \le C \sup_{t \in [0,T]} \mathbb{E} (1 + |X_t|^{2p}).$$
(3.4)

If ψ' , φ' are functions satisfying Hypothesis 4 and (Y', Z') is a corresponding mild solution then

$$\mathbb{E} \int_{0}^{T} |Z_{t} - Z_{t}'|^{2} dt \leq \mathbb{E} |\varphi(X_{T}) - \varphi'(X_{T})|^{2} + C \left(\sup_{t \in [0,T]} \mathbb{E} (1 + |X_{t}|^{2p}) \right)^{1/2} \left(\mathbb{E} \int_{0}^{T} |Y_{t} - Y_{t}'|^{2} dt \right)^{1/2}.$$
 (3.5)

In (3.4) and (3.5) the constant C depends only on T and on the constants C, p in Hypothesis 4.

Proof. We introduce the operators $J_k = k(k \cdot 1 - B)^{-1}$, k > 0. A direct computation shows that $BJ_k = k^2(k \cdot 1 - B)^{-1} - k \cdot 1$, so in particular the operators BJ_k are bounded (they are called the Yosida approximations of *B*). We set $Y_t^k = J_k Y_t$, $Z_t^k = J_k Z_t$. We now verify that Y^k admits the Itô differential

$$dY_t^k = -BY_t^k dt - J_k \psi(t, X_t, Y_t, Z_t) dt + Z_t^k dW_t.$$
(3.6)

In fact applying J_k to both sides of (3.3) we have

$$Y_{t}^{k} + \int_{t}^{T} e^{(s-t)B} Z_{s}^{k} dW_{s}$$

= $e^{(T-t)B} J_{k} \varphi(X_{T}) + \int_{t}^{T} e^{(s-t)B} J_{k} \psi(s, X_{s}, Y_{s}, Z_{s}) ds.$ (3.7)

Applying *B* to both sides and integrating we obtain, for every $r \in [0, T]$,

$$\int_{r}^{T} BY_{t}^{k} dt + \int_{r}^{T} \int_{t}^{T} e^{(s-t)B} BZ_{s}^{k} dW_{s} dt$$

$$= \int_{r}^{T} e^{(T-t)B} BJ_{k} \varphi(X_{T}) dt$$

$$+ \int_{r}^{T} \int_{t}^{T} e^{(s-t)B} BJ_{k} \psi(s, X_{s}, Y_{s}, Z_{s}) ds dt.$$
(3.8)

We have

$$\int_r^T e^{(T-t)B} B J_k \varphi(X_T) dt = e^{(T-r)B} J_k \varphi(X_T) - J_k \varphi(X_T)$$

and, applying the stochastic Fubini theorem (see, e.g. [5])

$$\int_{r}^{T} \int_{t}^{T} e^{(s-t)B} B Z_{s}^{k} dW_{s} dt = \int_{r}^{T} \int_{r}^{s} e^{(s-t)B} B Z_{s}^{k} dt dW_{s}$$
$$= \int_{r}^{T} (e^{(s-r)B} Z_{s}^{k} - Z_{s}^{k}) dW_{s}.$$

Substituting in (3.8) and comparing with (3.7) gives

$$\int_{r}^{T} BY_{t}^{k} dt = Y_{r}^{k} + \int_{r}^{T} Z_{s}^{k} dW_{s} - J_{k}\varphi(X_{T}) - \int_{r}^{T} J_{k}\psi(s, X_{s}, Y_{s}, Z_{s}) ds,$$

which proves (3.6).

Applying the Itô formula to $|Y_t^k|^2$ we obtain

$$\begin{aligned} |Y_t^k|^2 + \int_t^T |Z_s^k|^2 ds \\ &= |J_k \varphi(X_T)|^2 + 2 \int_t^T (\langle Y_s^k, BY_s^k \rangle + \langle Y_s^k, J_k \psi(s, X_s, Y_s, Z_s) \rangle) \, ds \\ &- 2 \int_t^T \langle Y_s^k, Z_s^k dW_s \rangle. \end{aligned}$$

We have

$$\mathbb{E}\left(\int_{0}^{T} |(Z_{s}^{k})^{*}Y_{s}^{k}|^{2} ds\right)^{1/2} \leq \mathbb{E}\left[\sup_{s \in [0,T]} |Y_{s}^{k}| \left(\int_{0}^{T} |Z_{s}^{k}|^{2} ds\right)^{1/2}\right] < \infty,$$
(3.9)

since it follows from (3.6) and Burkholder's inequality that $\mathbb{E} \sup_{t \in [0,T]} |Y_t^k|^2 < \infty$. Inequality (3.9) ensures that we can take expectation in the previous equality and obtain

$$\mathbb{E}|Y_t^k|^2 + \mathbb{E}\int_t^T |Z_s^k|^2 ds$$

= $\mathbb{E}|J_k\varphi(X_T)|^2 + 2\mathbb{E}\int_t^T (\langle Y_s^k, BY_s^k \rangle + \langle Y_s^k, J_k\psi(s, X_s, Y_s, Z_s) \rangle) ds.$

Now we use the dissipativity of *B* and we obtain

$$\mathbb{E}|Y_t^k|^2 + \mathbb{E}\int_t^T |Z_s^k|^2 ds \leq \mathbb{E}|J_k\varphi(X_T)|^2 + 2\mathbb{E}\int_t^T \langle Y_s^k, J_k\psi(s, X_s, Y_s, Z_s)\rangle ds.$$

It is well known that $|J_k|_{L(K)} \leq 1$ and $J_kh \rightarrow h$ for every $h \in K$. By the growth condition on ψ , the hypothesis $\sup_{t \in [0,T]} \mathbb{E}|X_t|^{2p} < \infty$ and by (3.2) we can apply the dominated convergence theorem and we arrive at

$$\mathbb{E}|Y_t|^2 + \mathbb{E}\int_t^T |Z_s|^2 ds \le \mathbb{E}|\varphi(X_T)|^2 + 2\mathbb{E}\int_t^T \langle Y_s, \psi(s, X_s, Y_s, Z_s)\rangle ds.$$
(3.10)

Next we have, for every $\varepsilon > 0$ and for some constant C_{ε} ,

$$\langle Y_s, \psi(s, X_s, Y_s, Z_s) \rangle \le C |Y_s| (1 + |X_s|^p + |Y_s| + |Z_s|)$$

 $\le \varepsilon |Z_s|^2 + C_{\varepsilon} (1 + |X_s|^{2p} + |Y_s|^2).$

Choosing ε sufficiently small we obtain, for some C, c > 0,

$$\mathbb{E}|Y_t|^2 + c\mathbb{E}\int_t^T |Z_s|^2 ds \leq \mathbb{E}|\varphi(X_T)|^2 + 2\mathbb{E}\int_t^T (1 + |X_s|^{2p} + |Y_s|^2) ds$$
$$\leq C \sup_{t \in [0,T]} (1 + \mathbb{E}|X_t|^{2p}) + C\mathbb{E}\int_t^T |Y_s|^2 ds,$$

and (3.4) follows from Gronwall's lemma.

In order to prove (3.5) we write the equation satisfied by (Y - Y', Z - Z') and, introducing the operators J_k and proceeding as before, instead of (3.10) we arrive at

$$\mathbb{E}|Y_t - Y'_t|^2 + \mathbb{E}\int_t^T |Z_s - Z'_s|^2 ds$$

$$\leq \mathbb{E}|\varphi(X_T) - \varphi'(X_T)|^2$$

$$+ 2\mathbb{E}\int_t^T \langle Y_s - Y'_s, \psi(s, X_s, Y_s, Z_s) - \psi'(s, X_s, Y'_s, Z'_s) \rangle ds$$

We set $f_s = \psi(s, X_s, Y_s, Z_s) - \psi'(s, X_s, Y'_s, Z'_s)$ and note that

$$|f_s| \le C(1 + |X_s|^p + |Y_s| + |Z_s| + |Y'_s| + |Z'_s|).$$

From estimate (3.4) we deduce

$$\mathbb{E} \int_0^T |f_s|^2 \, ds \le C \sup_{t \in [0,T]} \mathbb{E} \left(1 + |X_t|^{2p} \right)$$

and we obtain

$$\begin{split} \mathbb{E}|Y_{t} - Y_{t}'|^{2} + \mathbb{E} \int_{t}^{T} |Z_{s} - Z_{s}'|^{2} ds \\ &\leq \mathbb{E}|\varphi(X_{T}) - \varphi'(X_{T})|^{2} + 2\left(\mathbb{E} \int_{t}^{T} |Y_{s} - Y_{s}'|^{2} ds\right)^{1/2} \left(\mathbb{E} \int_{t}^{T} |f_{s}|^{2} ds\right)^{1/2} \\ &\leq \mathbb{E}|\varphi(X_{T}) - \varphi'(X_{T})|^{2} + C\left(\sup_{t \in [0,T]} \mathbb{E} \left(1 + |X_{t}|^{2p}\right)\right)^{1/2} \\ &\left(\mathbb{E} \int_{t}^{T} |Y_{s} - Y_{s}'|^{2} ds\right)^{1/2}. \end{split}$$

Inequality (3.5) follows immediately.

We are now able to state and prove the main result of this section, where for the process *X* we take the Ornstein–Uhlenbeck process introduced in Section 2.2: given $x_0 \in H$ we define

$$X_t = e^{tA} x_0 + \int_0^t e^{(t-s)A} G \, dW_s.$$
(3.11)

Theorem 6. Assume that Hypotheses 1 and 4 hold and suppose that the operators e^{tB} are compact for t > 0. Let X be the Ornstein–Uhlenbeck process defined by (3.11). Then there exists a mild solution (Y, Z) to (3.1). Moreover there exist Borel measurable functions u: $[0, T] \times H \to K$, v: $[0, T] \times H \to L_2(\Xi, K)$ such that, \mathbb{P} -a.s.,

$$Y_t = u(t, X_t), \quad for all \quad t \in [0, T];$$

$$Z_t = v(t, X_t),$$
 for almost all $t \in [0, T].$

Proof. First Step. Approximation. We apply Lemma 3 to the metric space $[0, T] \times H$ and the Hilbert space $K \times L_2(\Xi, K)$ and obtain a sequence of functions ψ^n : $[0, T] \times H \times K \times L_2(\Xi, K) \to K$ such that, for any $n \ge 1$,

$$|\psi^{n}(t, x, y, z)| \le C(1 + |x|^{p} + |y| + |z|), \qquad (3.12)$$

and for fixed n, ψ^n is Lipschitz with respect to (y, z) uniformly with respect to (t, x).

 \Box

Let $(Y^{n,t,x}, Z^{n,t,x})$ be the unique mild solution of

$$dY_{s}^{n,t,x} = -BY_{s}^{n,t,x} ds - \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds + Z_{s}^{n,t,x} dW_{s},$$

$$Y_{T}^{n,t,x} = \varphi(X_{T}^{t,x}),$$
(3.13)

where $X_s^{t,x}$ is the Ornstein–Uhlenbeck process starting from x at time t:

$$X_{s}^{t,x} = e^{(s-t)A}x + \int_{t}^{s} e^{(s-r)A}G \, dW_{r}, \qquad 0 \le t \le s \le T$$

(we define $X_s^{t,x} = x$ for s < t). It is easy to prove that $\sup_{s \in [0,T]} \mathbb{E} |X_s^{t,x}|^{2p} \le C(1+|x|^{2p})$ and (3.4) implies

$$\sup_{s \in [t,T]} \mathbb{E} |Y_s^{n,t,x}|^2 + \mathbb{E} \int_0^T |Z_s^{n,t,x}|^2 \, ds \le C(1+|x|^{2p}). \tag{3.14}$$

Moreover, there exist Borel measurable functions u^n : $[0, T] \times H \to K$ and v^n : $[0, T] \times H \to L_2(\Xi, K)$, such that

$$Y_s^{n,t,x} = u^n(s, X_s^{t,x}), \qquad Z_s^{n,t,x} = v^n(s, X_s^{t,x}).$$
(3.15)

The proof of (3.15) can be found in [8] (see also Proposition 3.2 of [9] for a direct proof in the infinite-dimensional case).

Second Step. In this step we prove that there exists a subsequence of $u^n(t, x)$ which is convergent in K for every t, x. This is obvious for t = T, since $u^n(T, x) = \varphi(x)$, so we can assume t < T.

We denote by $\mu_t(x, dy)$ the gaussian measure $\mathcal{N}(e^{tA}x, Q_t)(dy)$ and by $\mu_T(dy)$ the measure $\mathcal{N}(0, Q_T)(dy)$, and we note that the law of $X_s^{t,x}$ is $\mu_{s-t}(x, dy), 0 \le t \le s \le T$. Noting that $u^n(t, x) = Y_t^{n,t,x}$, taking expectation in the BSDE we have

$$u^{n}(t,x) = \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \mathbb{E} \int_{t}^{T} e^{(s-t)B} \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds$$
$$= \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \mathbb{E} \int_{t}^{T} e^{(s-t)B} \psi^{n}(s, X_{s}^{t,x}, u^{n}(s, X_{s}^{t,x}), v^{n}(s, X_{s}^{t,x})) ds$$

$$= \mathbb{E} e^{(T-t)B} \varphi(X_T^{t,x}) + \int_t^T e^{(s-t)B} \int_H \Psi^n(s, y) \ \mu_{s-t}(x, dy) \, ds, \qquad (3.16)$$

where $\Psi^n(s, y) = \psi^n(s, y, u^n(s, y), v^n(s, y))$. For t < T and $\delta > 0$ so small that $t + \delta \leq T$ we decompose $u^n(t, x)$ as follows:

$$u^{n}(t,x) = q(t,x) + a^{n}_{\delta}(t,x) + b^{n}_{\delta}(t,x), \qquad (3.17)$$

where $q(t, x) = \mathbb{E} e^{(T-t)B} \varphi(X_T^{t,x})$,

$$a_{\delta}^{n}(t,x) = \int_{t}^{t+\delta} e^{(s-t)B} \int_{H} \Psi^{n}(s,y) \ \mu_{s-t}(x,dy) \, ds,$$
$$b_{\delta}^{n}(t,x) = \int_{t+\delta}^{T} e^{(s-t)B} \int_{H} \Psi^{n}(s,y) \ \mu_{s-t}(x,dy) \, ds.$$

We note that the inequality

$$\left| \int_{H} \Psi^{n}(s, y) \, \mu_{s-t}(x, dy) \right| = \left| \mathbb{E} \, \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) \right| \\ \leq C \, \mathbb{E} \left(1 + |X_{s}^{t,x}|^{p} + |Y_{s}^{n,t,x}| + |Z_{s}^{n,t,x}| \right)$$
(3.18)

implies

$$\begin{aligned} |a_{\delta}^{n}(t,x)| &\leq C \mathbb{E} \int_{t}^{t+\delta} (1+|X_{s}^{t,x}|^{p}+|Y_{s}^{n,t,x}|+|Z_{s}^{n,t,x}|) \, ds \\ &\leq C \, \delta^{1/2} \left(\mathbb{E} \int_{t}^{t+\delta} (1+|X_{s}^{t,x}|^{2p}+|Y_{s}^{n,t,x}|^{2}+|Z_{s}^{n,t,x}|^{2}) \, ds \right)^{1/2} \\ &\leq C_{x} \, \delta^{1/2}, \end{aligned}$$

$$(3.19)$$

by (3.14). Next we consider $b_{\delta}^{n}(t, x)$ that we rewrite

$$b_{\delta}^{n}(t,x) = \int_{t+\delta}^{T} e^{(s-t)B} \int_{H} \Psi^{n}(s,y) d^{s,t}(x,y) \ \mu_{s}(0,dy) \, ds,$$

where we have denoted $d^{s,t}(x, y)$ the density of $\mu_{s-t}(x, \cdot)$ with respect to $\mu_s(0, \cdot)$. We consider the Hilbert space of Borel measurable functions $[0, T] \times H \to K$, square summable with respect to the measure $\mu_s(0, dy) ds$, equipped with the usual inner product. It will be denoted $L^2([0, T] \times H; \mu_s(0, dy) ds; K)$. Let us check that (Ψ^n) is a bounded set in this space: Indeed, we have

$$\int_0^T \int_H |\Psi^n(s, y)|^2 \,\mu_s(0, dy) \,ds$$

= $\mathbb{E} \int_0^T |\psi^n(s, X_s^{0,0}, Y_s^{n,0,0}, Z_s^{n,0,0})|^2 ds$
 $\leq C \mathbb{E} \int_0^T (1 + |X_s^{0,0}|^{2p} + |Y_s^{n,0,0}|^2 + |Z_s^{n,0,0}|^2) \,ds$
 $\leq C,$

by (3.14). The sequence (Ψ^n) is therefore weakly compact and there exists a subsequence (still denoted (Ψ^n)) which is weakly convergent in $L^2([0, T] \times H; \mu_s(0, dy) ds; K)$.

For fixed $k \in K$ define

$$\varphi(s, y) = 1_{[t+\delta,T]}(s)d^{s,t}(x, y) e^{(s-t)B^*}k$$

and assume for a moment that φ (which of course depends also on t, x, δ, k) belongs to $L^2([0, T] \times H; \mu_s(0, dy) ds; K)$. The function φ is chosen so that

$$\begin{aligned} \langle b^n_{\delta}(t,x),k \rangle &= \int_{t+\delta}^T \int_H \langle e^{(s-t)B} \Psi^n(s,y),k \rangle d^{s,t}(x,y) \ \mu_s(0,dy) \, ds \\ &= \langle \Psi^n,\varphi \rangle_{L^2([0,T] \times H;\mu_s(0,dy) \, ds;K)}. \end{aligned}$$

It follows that, for integers $n, m \ge 1$,

$$\begin{aligned} \langle u^n(t,x) - u^m(t,x),k \rangle \\ &= \langle a^n_{\delta}(t,x) - a^m_{\delta}(t,x),k \rangle + \langle b^n_{\delta}(t,x) - b^m_{\delta}(t,x),k \rangle \\ &= \langle a^n_{\delta}(t,x) - a^m_{\delta}(t,x),k \rangle + \langle \Psi^n - \Psi^m,\varphi \rangle_{L^2([0,T] \times H;\mu_s(0,dy)\,ds;K)}. \end{aligned}$$

From (3.19) it follows that

$$|\langle u^{n}(t,x) - u^{m}(t,x),k\rangle| \leq C \,\delta^{1/2}|k| + |\langle \Psi^{n} - \Psi^{m},\varphi\rangle_{L^{2}([0,T]\times H;\mu_{s}(0,dy)\,ds;K)}|,$$

and since (Ψ^n) is weakly convergent we conclude that $(\langle u^n(t, x), k \rangle)_n$ is a Cauchy sequence for every $k \in K$, so that, for all $t, x, (u^n(t, x))_n$ is a weakly convergent sequence in K.

It remains to check that $\varphi \in L^2([0, T] \times H; \mu_s(0, dy) ds; K)$. From Lemma 2, the density $d^{s,t}(x, y)$ has the form

$$d^{s,t}(x, y) = \det(1 - \Theta^{s,t})^{-1/2} \exp\{-\frac{1}{2} \langle (1 - \Theta^{s,t})^{-1} Q_s^{-1/2} e^{(s-t)A} x, Q_s^{-1/2} e^{(s-t)A} x \rangle + \langle (1 - \Theta^{s,t})^{-1} Q_s^{-1/2} e^{(s-t)A} x, Q_s^{-1/2} y \rangle - \frac{1}{2} \langle \Theta^{s,t} (1 - \Theta^{s,t})^{-1} Q_s^{-1/2} y, Q_s^{-1/2} y \rangle\},$$

where $\Theta^{s,t} = Q_s^{-1/2} e^{(s-t)A} Q_t (Q_s^{-1/2} e^{(s-t)A})^*$. So setting

$$h_{s,t,x} = (1 - \Theta^{s,t})^{-1} Q_s^{-1/2} e^{(s-t)A} x,$$

we obtain $0 \le d^{s,t}(x, y) \le \det(1 - \Theta^{s,t})^{-1/2} \exp(\langle h_{s,t,x}, Q_s^{-1/2} y \rangle)$ and recalling formula (2.8) we find

$$\int_{0}^{T} \int_{H} |\varphi(s, y)|^{2} \mu_{s}(0, dy) \, ds \leq C \int_{t+\delta}^{T} \int_{H} |d^{s,t}(x, y)|^{2} \mu_{s}(0, dy) \, ds$$
$$\leq C \int_{t+\delta}^{T} \det(1 - \Theta^{s,t})^{-1} \exp(2|h_{s,t,x}|^{2}) \, ds. \quad (3.20)$$

By (2.6) we have

$$\det(1 - \Theta^{s,t})^{-1} \le \exp[(1 + |Q_t| |Q_{s-t}^{-1/2} e^{(s-t)A}|^2) |Q_{s-t}^{-1/2} e^{(s-t)A}|^2 \operatorname{Trace} Q_t]$$

and, taking into account (2.5),

$$\begin{aligned} |h_{s,t,x}| &\leq |(1 - \Theta^{s,t})^{-1}||Q_s^{-1/2}Q_{s-t}^{1/2}||Q_{s-t}^{-1/2}e^{(s-t)A}||x|\\ &\leq (1 + |Q_t||Q_{s-t}^{-1/2}e^{(s-t)A}|^2)|Q_s^{-1/2}Q_{s-t}^{1/2}||Q_{s-t}^{-1/2}e^{(s-t)A}||x|.\end{aligned}$$

Since $Q_s \ge Q_{s-t}$ it follows that $|Q_s^{-1/2}Q_{s-t}^{1/2}| \le 1$. Using inequality (A.6) and noting that $s - t \ge \delta$ we obtain $|Q_{s-t}^{-1/2}e^{(s-t)A}| \le |Q_{\delta}^{-1/2}e^{\delta A}|$. It follows that

$$\det(1 - \Theta^{s,t})^{-1} \le \exp[(1 + |Q_t||Q_{\delta}^{-1/2}e^{\delta A}|^2) |Q_{\delta}^{-1/2}e^{\delta A}|^2 \operatorname{Trace} Q_t],$$

$$|h_{s,t,x}| \le (1 + |Q_t||Q_{\delta}^{-1/2}e^{\delta A}|^2) |Q_{\delta}^{-1/2}e^{\delta A}||x|.$$

This shows that the right-hand side of (3.20) is finite and therefore φ belongs to $L^2([0, T] \times H; \mu_s(0, dy) ds; K)$.

So far in Step 2 we have proved that, for all t, x, the sequence $(u^n(t, x))_n$ is weakly convergent in K. We will now prove that the convergence takes place in the norm of K. To this purpose it is enough to show that, for fixed t, x, the sequence $(u^n(t, x))_n$ is relatively compact in K or, equivalently, that it is totally bounded.

We fix (t, x) and let $\varepsilon > 0$ be arbitrary. We consider again the decomposition (3.17). By (3.19) we can choose δ such that $|a_{\delta}^{n}(t, x)| < \varepsilon/2$ for every *n*. Next note that

$$b_{\delta}^{n}(t,x) = e^{\delta B} \int_{t+\delta}^{T} e^{(s-t-\delta)B} \int_{H} \Psi^{n}(s,y) \ \mu_{s-t}(x,dy) \, ds,$$

and from (3.18) it follows that

$$\left| \int_{t+\delta}^{T} e^{(s-t-\delta)B} \int_{H} \Psi^{n}(s, y) \, \mu_{s-t}(x, dy) \, ds \right|$$

$$\leq C \mathbb{E} \int_{0}^{T} (1 + |X_{s}^{t,x}|^{p} + |Y_{s}^{n,t,x}| + |Z_{s}^{n,t,x}|) \, ds \leq C(t, x, \delta)$$

by (3.14). Since $e^{\delta B}$ is compact by our assumptions, the sequence $(b_{\delta}^{n}(t, x))_{n}$ is relatively compact, hence totally bounded. So there exists a finite set $A \subset K$ such that for any *n* there exists $a \in A$ satisfying $|b_{\delta}^{n}(t, x) - a| < \varepsilon/2$. So for every *n* there exists $a \in A$ such that $|u^{n}(t, x) - q(t, x) - a| < \varepsilon$. This proves that $(u^{n}(t, x))_{n}$ is totally bounded. We have now proved that $(u^{n}(t, x))_{n}$ is a convergent sequence in *K* for every (t, x).

Third Step. Convergence of Y^n and Z^n .

We consider again the Ornstein–Uhlenbeck process $X_s = X_s^{0,x_0}$ defined in (3.11) and we denote $Y_s^n = Y_s^{n,0,x_0}$, $Z_s^n = Z_s^{n,0,x_0}$. Denoting by u(t, x) the limit of $u^n(t, x)$ then obviously $Y_s^n = u^n(s, X_s)$ converges to $u(s, X_s)$, which we denote by Y_s . Setting s = tin (3.14) we have $|u^n(t, x)| = \mathbb{E}|Y_t^{n,t,x}| \le C(1 + |x|^p)$ and consequently

$$|Y_s^n|^2 = |u^n(s, X_s)|^2 \le C(1 + |X_s|^{2p});$$

since $\mathbb{E} \int_0^T |X_t|^{2p} dt < \infty$ we conclude that Y^n converges to Y in $L^2(\Omega \times [0, T]; K)$. From inequality (3.5) of Lemma 5 it follows that

$$\mathbb{E}\int_{0}^{T} |Z_{t}^{n} - Z_{t}^{m}|^{2} dt \leq C \left(\sup_{t \in [0,T]} \mathbb{E} \left(1 + |X_{t}|^{2p} \right) \right)^{1/2} \left(\mathbb{E}\int_{0}^{T} |Y_{t}^{n} - Y_{t}^{m}|^{2} dt \right)^{1/2}$$
$$\leq C_{x_{0}} \left(\mathbb{E}\int_{0}^{T} |Y_{t}^{n} - Y_{t}^{m}|^{2} dt \right)^{1/2}$$
(3.21)

from which we conclude that (Z^n) is a Cauchy sequence in $L^2(\Omega \times [0, T]; L_2(\Xi, K))$. We denote by Z its limit. Passing to a subsequence, we can assume that $|Z_t^n - Z_t| \to 0$, \mathbb{P} -a.s. for almost every t. We define a function v: $[0, T] \times H \to L_2(\Xi, K)$ by setting $v(t, x) = \lim_{n \to \infty} v^n(t, x)$ for all (t, x) for which the limit exists, v(t, x) = 0 elsewhere. Then v is Borel measurable and we have $Z_t = v(t, X_t)$, \mathbb{P} -a.s. for almost every t. *Fourth Step.* Existence of the solution. For every $t \in [0, T]$, (Y^n, Z^n) satisfies \mathbb{P} -a.s.:

$$Y_t^n + \int_t^T e^{(t-s)B} Z_s^n \, dW_s = e^{(T-t)B} \varphi(X_T) + \int_t^T e^{(t-s)B} \psi^n(s, X_s, Y_s^n, Z_s^n) \, ds.$$

To prove that (Y, Z) is a solution to (3.3) it remains to check that

$$\mathbb{E}\int_0^T |\psi^n(s, X_s, Y_s^n, Z_s^n) - \psi(s, X_s, Y_s, Z_s)| \, ds \to 0.$$

From (iv) of Lemma 3 we obtain $\psi^n(s, x, y_n, z_n) \rightarrow \psi(s, x, y, z)$ in *K*, whenever $y_n \rightarrow y$ in *K* and $z_n \rightarrow z$ in $L_2(\Xi, K)$, for every $s \in [0, T]$, $x \in H$. Taking into account (3.12) and (3.14) we have

$$\mathbb{E}\int_0^T |\psi^n(s, X_s, Y_s^n, Z_s^n)|^2 \, ds \le C \mathbb{E}\int_0^T (1 + |X_s|^{2p} + |Y_s^n|^2 + |Z_s^n|^2) \, ds \le C$$

which shows that $(\psi^n(s, X_s, Y_s^n, Z_s^n))$ is uniformly integrable on $\Omega \times [0, T]$ and the required convergence follows immediately.

4. BSDE with Bounded Continuous Generator

In this section and in the following one we adopt a more general approach and we consider a process X with values in a metric space. We assume that X is a Markov process with respect to a Brownian filtration. More precisely, in what follows we make the following assumptions:

- (1) $(\Omega, \mathcal{F}, \mathbb{P})$ is a complete probability space and $\{W_t, t \in [0, T]\}$ is a cylindrical Wiener process in a Hilbert space Ξ . For an arbitrary interval $[s, t] \subset [0, T]$ we denote by $\mathcal{F}_{[s,t]}$ the σ -algebra generated by the random variables $\{W_r^{\xi} W_s^{\xi}, r \in [s, t], \xi \in \Xi\}$ and by the \mathbb{P} -null sets of \mathcal{F} .
- (2) $X = \{X_s^{t,x}(\omega), \ \omega \in \Omega, \ 0 \le t \le s \le T, \ x \in M\}$ is a stochastic process with values in a complete separable metric space M, measurable with respect to $\mathcal{F} \times \mathcal{B}(\Delta) \times \mathcal{B}(M)$ and $\mathcal{B}(M)$, respectively (here by Δ we denote the set $\{(t, s), \ 0 \le t \le s \le T\}$ and by $\mathcal{B}(\Lambda)$ the Borel σ -algebra of any topological space Λ).
- (3) For every $t \in [0, T]$ and $x \in M$, the process $\{X_s^{t,x}, s \in [t, T]\}$ has continuous paths and is adapted to the filtration $\{\mathcal{F}_{[t,s]}, s \in [t, T]\}$.
- (4) For $0 \le t \le s \le T$ and $x \in M$ we have, \mathbb{P} -a.s.,

$$X_t^{t,x} = x, \qquad X_r^{s, X_s^{t,x}} = X_r^{t,x}, \qquad \tau \in [s, T].$$
 (4.1)

We denote by

$$\mu_s^{t,x}(A) = \mathbb{P}(X_s^{t,x} \in A), \qquad 0 \le t \le s \le T, \quad x \in M, \quad A \in \mathcal{B}(M),$$

the transition probabilities. Standard arguments show that *X* is a Markov process, in the sense that for every bounded Borel function φ on *M* and for $0 \le t \le s \le r \le T$ and $x \in M$, we have

$$\mathbb{E}^{\mathcal{F}_s}\varphi(X_r^{t,x}) = \int_M \varphi(y) \ \mu_r^{s,X_s^{t,x}}(dy), \qquad \mathbb{P}\text{-a.s.}$$

We need the following lemma, that has been proved in Proposition 3.2 of [9], in the special case when M is a Hilbert space. Exactly the same arguments carry over to the general case.

Lemma 7. Assume properties (1)–(4) above. Suppose that:

- (i) $z = \{z(\omega, s, t, x), \omega \in \Omega, 0 \le t \le s \le T, x \in M\}$ is a stochastic process with values in a Hilbert space V, measurable with respect to $\mathcal{F} \times \mathcal{B}(\Delta) \times \mathcal{B}(M)$ and $\mathcal{B}(V)$, respectively.
- (ii) For every $t \in [0, T]$ and $x \in M$, the process $\{z(s, t, x), s \in [t, T]\}$ is predictable with respect to the filtration $\{\mathcal{F}_{[t,s]}, s \in [t, T]\}$.
- (iii) For $0 \le t \le s \le T$ and $x \in M$ we have, \mathbb{P} -a.s.,

$$z(r, s, X_s^{t,x}) = z(r, t, x), \qquad \text{for almost all} \quad r \in [s, T].$$

$$(4.2)$$

Then there exists a Borel measurable function $v: [0, T] \times M \rightarrow V$ such that, for $t \in [0, T]$ and $x \in H$, we have \mathbb{P} -a.s.

$$z(s, t, x) = v(s, X_s^{t, x}), \qquad \text{for almost all} \quad s \in [t, T].$$

$$(4.3)$$

We fix arbitrary $x \in M$ and consider the following BSDE:

$$dY_t = -BY_t dt - \psi(t, X_t^{0,x}, Y_t, Z_t) dt + Z_t dW_t, \qquad Y_T = \varphi(X_T^{0,x}), \tag{4.4}$$

under the following assumptions.

Hypothesis 8.

- (i) *The process X satisfies properties* (1)–(4) *above.*
- (ii) The operator B: $D(B) \subset K \to K$ is the infinitesimal generator of a strongly continuous dissipative semigroup $\{e^{tB}, t \ge 0\}$ of bounded linear operators in K.
- (iii) $\varphi: M \to K \text{ and } \psi: [0, T] \times M \times K \times L_2(\Xi, K) \to K \text{ are Borel measurable functions,}$

 $\mathbb{E} |\varphi(X_T^{t,x})|^2 < \infty, \qquad t \in [0,T], \quad x \in M,$

and there exists a constant C > 0 such that

 $|\psi(t, x, y, z)| \le C$, $t \in [0, T]$, $x \in M$, $y \in K$, $z \in L_2(\Xi, K)$.

(iv) For every $t \in [0, T]$ and $x \in M$ the function $\psi(t, x, \cdot, \cdot)$: $K \times L_2(\Xi, K) \to K$ is continuous.

We say that an (\mathcal{F}_t) -predictable process (Y, Z) with values in $K \times L_2(\Xi, K)$ is a mild solution of (4.4) if

$$\sup_{t\in[0,T]} \mathbb{E} |Y_t|^2 + \mathbb{E} \int_0^T |Z_t|^2 dt < \infty$$
(4.5)

and for every $t \in [0, T]$ the following equality holds:

$$Y_{t} + \int_{t}^{T} e^{(t-s)B} Z_{s} dW_{s}$$

= $e^{(T-t)B} \varphi(X_{T}^{0,x}) + \int_{t}^{T} e^{(t-s)B} \psi(s, X_{s}^{0,x}, Y_{s}, Z_{s}) ds, \quad \mathbb{P}\text{-a.s.}$ (4.6)

Lemma 9. Assume that Hypothesis 8 holds and let (Y, Z) be a mild solution to (4.4). *Then*

$$\sup_{t \in [0,T]} \mathbb{E} |Y_t|^2 + \mathbb{E} \int_0^T |Z_t|^2 dt \le C \ (1 + \mathbb{E} |\varphi(X_T^{0,x})|^2).$$
(4.7)

If ψ' , φ' are functions satisfying Hypothesis 8 and (Y', Z') is a corresponding mild solution then

$$\mathbb{E}\int_{0}^{T}|Z_{t}-Z_{t}'|^{2}dt \leq \mathbb{E}|\varphi(X_{T}^{0,x})-\varphi'(X_{T}^{0,x})|^{2}+C \mathbb{E}\int_{0}^{T}|Y_{t}-Y_{t}'|dt.$$
(4.8)

In (4.7) and (4.8) the constant C depends only on T and on the constant C in Hypothesis 8.

Proof. Proceeding as in the proof of Lemma 5 we obtain (compare (3.10))

$$\mathbb{E}|Y_t|^2 + \mathbb{E}\int_t^T |Z_s|^2 \, ds \le \mathbb{E}|\varphi(X_T^{0,x})|^2 + 2\mathbb{E}\int_t^T \langle Y_s, \psi(s, X_s^{0,x}, Y_s, Z_s)\rangle \, ds.$$
(4.9)

Since ψ is bounded we have

$$\mathbb{E}|Y_t|^2 + \mathbb{E}\int_t^T |Z_s|^2 ds \leq \mathbb{E}|\varphi(X_T^{0,x})|^2 + C\mathbb{E}\int_t^T |Y_s| ds$$
$$\leq \mathbb{E}|\varphi(X_T^{0,x})|^2 + C\mathbb{E}\int_t^T (1+|Y_s|^2) ds,$$

and (4.7) follows from Gronwall's lemma.

In order to prove (4.8) we write the equation satisfied by (Y - Y', Z - Z') and proceeding as before we arrive at

$$\begin{split} \mathbb{E}|Y_t - Y'_t|^2 + \mathbb{E} \int_t^T |Z_s - Z'_s|^2 \, ds \\ &\leq \mathbb{E}|\varphi(X_T^{0,x}) - \varphi'(X_T^{0,x})|^2 \\ &+ 2\mathbb{E} \int_t^T \langle Y_s - Y'_s, \psi(s, X_s^{0,x}, Y_s, Z_s) - \psi'(s, X_s^{0,x}, Y'_s, Z'_s) \rangle \, ds. \end{split}$$

By the boundedness assumptions on ψ , ψ' we obtain

$$\mathbb{E}|Y_t - Y'_t|^2 + \mathbb{E}\int_t^T |Z_s - Z'_s|^2 ds$$

$$\leq \mathbb{E}|\varphi(X_T^{0,x}) - \varphi'(X_T^{0,x})|^2 + C\mathbb{E}\int_t^T |Y_s - Y'_s| ds.$$

Inequality (4.8) follows immediately.

Theorem 10. Assume that Hypothesis 8 holds, that the operators e^{tB} are compact for t > 0, and that the transition probabilities of the process X:

$$\mu_s^{t,x}, \qquad 0 \le t < s \le T, \quad x \in M,$$

are all equivalent measures on M. Then there exists a mild solution to (4.4). Moreover, there exist Borel measurable functions $u: [0, T] \times M \to K, v: [0, T] \times M \to L_2(\Xi, K)$ such that, \mathbb{P} -a.s.,

$$Y_t = u(t, X_t),$$
 for all $t \in [0, T];$
 $Z_t = v(t, X_t),$ for almost all $t \in [0, T].$

Proof. First Step. Approximation. We apply Lemma 3 to the metric space $[0, T] \times M$ and the Hilbert space $K \times L_2(\Xi, K)$ and obtain a sequence of functions ψ^n : $[0, T] \times M \times K \times L_2(\Xi, K) \to K$ such that, for any $n \ge 1$,

$$|\psi^n(t,x,y,z)| \le C,\tag{4.10}$$

and, for fixed n, ψ^n is Lipschitz with respect to (y, z) uniformly with respect to (t, x). Let $(Y^{n,t,x}, Z^{n,t,x})$ be the unique mild solution of

$$dY_{s}^{n,t,x} = -BY_{s}^{n,t,x} ds - \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds + Z_{s}^{n,t,x} dW_{s},$$

$$Y_{T}^{n,t,x} = \varphi(X_{T}^{t,x}),$$
(4.11)

where we use the convention $X_s^{t,x} = x$ for s < t. By (4.7)

$$\sup_{s \in [t,T]} \mathbb{E}|Y_s^{n,t,x}|^2 + \mathbb{E} \int_0^T |Z_s^{n,t,x}|^2 \, ds \le C(1 + \mathbb{E}|\varphi(X_T^{t,x})|^2) < \infty.$$
(4.12)

Moreover, from the uniqueness of the solution to (4.11) it is easy to deduce the following identities: for $0 \le t \le s \le T$ and $x \in M$, we have, \mathbb{P} -a.s.,

$$Y_r^{n,s,X_s^{t,x}} = Y_r^{n,t,x}, \quad \text{for all} \quad r \in [s, T],$$
$$Z_r^{n,s,X_s^{t,x}} = Z_r^{n,t,x}, \quad \text{for almost all} \quad r \in [s, T].$$

Setting $u^n(t, x) = Y_t^{n,t,x}$ it follows immediately that, for every t, x, \mathbb{P} -a.s.,

$$Y_s^{n,t,x} = u^n(s, X_s^{t,x}), \qquad s \in [t, T].$$

Applying Lemma 7 to the process $z(s, t, x) = Z_s^{n,t,x}$ we conclude that there exist Borel measurable functions v^n : $[0, T] \times M \to L_2(\Xi, K)$, such that, for every t, x, \mathbb{P} -a.s.,

$$Z_s^{n,t,x} = v^n(s, X_s^{t,x}),$$
 for almost all $s \in [t, T].$

Second Step. In this step we prove that there exists a subsequence of $u^n(t, x)$ which is convergent in K for every t, x. This is obvious for t = T, since $u^n(T, x) = \varphi(x)$, so we can assume t < T.

Noting that $u^n(t, x) = Y_t^{n,t,x}$, taking expectation in the BSDE we have

$$u^{n}(t,x) = \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \mathbb{E} \int_{t}^{T} e^{(s-t)B} \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds$$

$$= \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \mathbb{E} \int_{t}^{T} e^{(s-t)B} \psi^{n}(s, X_{s}^{t,x}, u^{n}(s, X_{s}^{t,x}), v^{n}(s, X_{s}^{t,x})) ds$$

$$= \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \int_{t}^{T} e^{(s-t)B} \int_{M} \Psi^{n}(s, y) \ \mu_{s}^{t,x}(dy) ds, \qquad (4.13)$$

where $\Psi^n(s, y) = \psi^n(s, y, u^n(s, y), v^n(s, y))$. We fix an arbitrary $x_0 \in M$ and note that, from our assumptions, $\mu_s^{t,x}$ is absolutely continuous with respect to μ_s^{0,x_0} for s > t and $x \in M$. We denote by $d^{s,t}(x, y)$ the corresponding density. Then

$$u^{n}(t,x) = \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \int_{t}^{T} \int_{M} e^{(s-t)B} \Psi^{n}(s,y) d^{s,t}(x,y) \ \mu_{s}^{0,x_{0}}(dy) \, ds.$$

Since (Ψ^n) is uniformly bounded, this family is a bounded set in $L^{\infty}([0, T] \times M; \mu_s^{0,x_0}(dy) ds; K)$, whence relatively compact in the weak* topology. Since, in addition, the space $L^1([0, T] \times M; \mu_s^{0,x_0}(dy) ds; K)$ is separable, there exists a sequence (still denoted Ψ^n) and a function $\Psi^0 \in L^{\infty}([0, T] \times M; \mu_s^{0,x_0}(dy) ds; K)$ such that for any $\varphi \in L^1([0, T] \times M; \mu_s^{0,x_0}(dy) ds; K)$ we have

$$\lim_{n\to\infty}\int_0^T\int_M \langle \Psi^n(s,y)-\Psi^0(s,y),\varphi(s,y)\rangle_K\ \mu_s^{0,x_0}(dy)\,ds=0.$$

For any fixed (t, x) and for every $k \in K$,

$$\int_{0}^{T} \int_{M} 1_{s \in [t,T]} d^{s,t}(x, y) |e^{(s-t)B^{*}}k| \, \mu_{s}^{0,x_{0}}(dy) \, ds$$
$$= \int_{t}^{T} \int_{M} |e^{(s-t)B^{*}}k| \, \mu_{s}^{t,x}(dy) \, ds$$
$$\leq C \int_{t}^{T} \int_{M} \mu_{s}^{t,x}(dy) \, ds = C \cdot (T-t),$$

which shows that $\varphi(s, y) = 1_{s \in [t,T]} d^{s,t}(x, y) e^{(s-t)B^*} k$ belongs to $L^1([0,T] \times M;$

 $\mu_s^{0,x_0}(dy) ds; K$). We conclude that

$$\begin{split} \lim_{n \to \infty} \langle u^n(t, x), k \rangle &= \mathbb{E} \ \langle e^{(s-t)B} \varphi(X_T^{t, x}), k \rangle \\ &+ \lim_{n \to \infty} \int_0^T \int_M \langle \Psi^n(s, y), \varphi(s, y) \rangle_K \ \mu_s^{0, x_0}(dy) \, ds \\ &= \mathbb{E} \ \langle e^{(s-t)B} \varphi(X_T^{t, x}), k \rangle \\ &+ \int_t^T \int_M \langle \Psi^0(s, y), e^{(s-t)B^*} k \rangle d^{s, t}(x, y) \ \mu_s^{0, x_0}(dy) \, ds. \end{split}$$

and so that $(u^n(t, x))_n$ is weakly convergent in K for every t, x.

To prove that $(u^n(t, x))_n$ is convergent in the norm of *K* we will show that, for every (t, x), the sequence $(u^n(t, x))_n$ is totally bounded.

For t < T and $\delta > 0$ so small that $t + \delta \leq T$ we decompose $u^n(t, x)$ as follows (compare (4.13)):

$$u^{n}(t,x) = q(t,x) + a^{n}_{\delta}(t,x) + b^{n}_{\delta}(t,x),$$
(4.14)
reaction of the second sec

where $q(t, x) = \mathbb{E} e^{(T-t)B} \varphi(X_T^{t,x})$,

$$a_{\delta}^{n}(t,x) = \int_{t}^{t+\delta} e^{(s-t)B} \int_{M} \Psi^{n}(s,y) \ \mu_{s}^{t,x}(dy) \, ds,$$
$$b_{\delta}^{n}(t,x) = \int_{t+\delta}^{T} e^{(s-t)B} \int_{M} \Psi^{n}(s,y) \ \mu_{s}^{t,x}(dy) \, ds.$$

Let us fix (t, x) and let $\varepsilon > 0$ be arbitrary. Since (Ψ^n) is uniformly bounded, we have $\left|\int_M \Psi^n(s, y) \, \mu_s^{t,x}(dy) \, ds\right| \le C$, so it follows that $|a_{\delta}^n(t, x)| \le C \,\delta$, and we can choose δ such that $|a_{\delta}^n(t, x)| < \varepsilon/2$ for every *n*. Next note that

$$b_{\delta}^{n}(t,x) = e^{\delta B} \int_{t+\delta}^{T} e^{(s-t-\delta)B} \int_{M} \Psi^{n}(s,y) \ \mu_{s}^{t,x}(dy) \ ds$$

and

$$\left|\int_{t+\delta}^{T} e^{(s-t-\delta)B} \int_{M} \Psi^{n}(s, y) \ \mu_{s}^{t,x}(dy) \, ds\right| \leq C.$$

Since $e^{\delta B}$ is compact by our assumptions, the sequence $(b_{\delta}^{n}(t, x))_{n}$ is relatively compact, hence totally bounded. So there exists a finite set $A \subset K$ such that for any *n* there exists $a \in A$ satisfying $|b_{\delta}^{n}(t, x) - a| < \varepsilon/2$. So for every *n* there exists $a \in A$ such that $|u^{n}(t, x) - q(t, x) - a| < \varepsilon$. This shows that $(u^{n}(t, x))_{n}$ is totally bounded and the claim is proved.

Third Step. Convergence of Y^n and Z^n .

We denote $Y_s^n = Y_s^{n,0,x_0}$, $Z_s^n = Z_s^{n,0,x_0}$. Denoting by $u^0(t, x)$ the limit of $u^n(t, x)$ then obviously $Y_s^n = u^n(s, X_s)$ converges to $u(s, X_s)$, which we denote by Y_s . From

(4.12) it follows that

$$\sup_{n} \mathbb{E} \int_{0}^{T} |Y_{s}^{n}|^{2} \, ds < \infty$$

and we deduce that Y^n converges to Y in $L^1(\Omega \times [0, T]; K)$. From inequality (4.8) of Lemma 9 it follows that

$$\mathbb{E}\int_0^T |Z_t^n - Z_t^m|^2 dt \le C \mathbb{E}\int_0^T |Y_t^n - Y_t^m| dt$$

from which we conclude that (Z^n) is a Cauchy sequence in $L^2(\Omega \times [0, T]; L_2(\Xi, K))$. We denote by Z its limit. Passing to a subsequence, we can assume that $|Z_t^n - Z_t| \to 0$, \mathbb{P} -a.s. for almost every t. We define a function v: $[0, T] \times H \to L_2(\Xi, K)$ setting $v(t, x) = \lim_{n \to \infty} v^n(t, x)$ for all (t, x) for which the limit exists, v(t, x) = 0 elsewhere. Then v is Borel measurable and we have $Z_t = v(t, X_t)$, \mathbb{P} -a.s. for almost every t.

Fourth Step. Existence of solution. For every $t \in [0, T]$, (Y^n, Z^n) satisfies \mathbb{P} -a.s.

$$Y_t^n + \int_t^T e^{(t-s)B} Z_s^n \, dW_s = e^{(T-t)B} \varphi(X_T^{0,x_0}) + \int_t^T e^{(t-s)B} \psi^n(s, X_s^{0,x_0}, Y_s^n, Z_s^n) \, ds.$$

To prove that (Y, Z) is a solution to (3.3) it remains to check that

$$\mathbb{E}\int_0^T |\psi^n(s, X_s^{0, x_0}, Y_s^n, Z_s^n) - \psi(s, X_s^{0, x_0}, Y_s, Z_s)| \, ds \to 0.$$

From (iv) of Lemma 3 we obtain $\psi^n(s, x, y_n, z_n) \rightarrow \psi(s, x, y, z)$ in *K*, whenever $y_n \rightarrow y$ in *K* and $z_n \rightarrow z$ in $L_2(\Xi, K)$, for every $s \in [0, T]$, $x \in H$. Taking into account (4.10) the required convergence follows from the dominated convergence theorem. \Box

4.1. *Example*

Let *W* be a cylindrical Wiener process in a Hilbert space Ξ with Brownian filtration (\mathcal{F}_t). Consider the following equation on the time interval [0, *T*] for an unknown process *X* with values in a Hilbert space *H*:

$$dX_t = AX_t dt + F(t, X_t) dt + G dW_t, \qquad X_0 = x,$$

where $x \in H$, the operators A and G satisfy Hypothesis 1, F: $[0, T] \times H \to H$ is a Borel measurable mapping such that, for some constant $C \ge 0$,

$$|F(t, x) - F(t, x')| \le C |x - x'|,$$

|F(t, x)| \le C (1 + |x|), t \in [0, T], x, x' \in H,

and there exists $\alpha > 0$ such that

Trace
$$\int_0^1 s^{-\alpha} e^{sA} G G^* e^{sA^*} ds < \infty$$

(this is a stronger assumption than Hypothesis 1(iii)).

It is well known (see, e.g. [5]) that under these conditions there exists a unique mild solution, i.e. an (\mathcal{F}_t) -adapted process X, with continuous paths in H, such that, \mathbb{P} -a.s.,

$$X_t = e^{tA}x + \int_0^t e^{(t-s)A}F(s, X_s) \, ds + \int_0^t e^{(t-s)A}G \, dW_s, \qquad t \ge 0.$$

X is unique up to indistinguishability. We denote by $\mu_t^{0,x}$ the law of X_t .

We assume further that the image of F is contained in the image of G and there exists $C \ge 0$ such that

$$|G^{-1}F(t,x)| \le C, \qquad t \in [0,T], \quad x \in H,$$

where G^{-1} denotes the pseudo-inverse of *G*. We consider the Ornstein–Uhlenbeck process *X'* solution of

$$dX'_t = AX'_t dt + G dW_t, \qquad X'_0 = x.$$

By the Girsanov theorem, setting

$$\rho = \exp\left(\int_0^T \langle G^{-1}F(s, X'_s), dW_s \rangle - \frac{1}{2} \int_0^T |G^{-1}F(s, X'_s)|^2 ds\right),$$

we have $\mathbb{E}\rho = 1$ and the process $W'_t = W_t - \int_0^t G^{-1}F(s, X'_s) ds$, $t \in [0, T]$, is a cylindrical Wiener process with respect to the probability \mathbb{P}' admitting density ρ with respect to \mathbb{P} . Then we have

$$dX'_t = AX'_t dt + F(t, X'_t) dt + G dW'_t, \qquad X_0 = x,$$

and it follows that the law of X' under \mathbb{P}' is the same as the law of X under \mathbb{P} . Since \mathbb{P} and \mathbb{P}' are equivalent measures, it follows in particular that the $\mu_t^{0,x}$ is equivalent to $\mathcal{N}(e^{tA}x, Q_t)$, and therefore that $\{\mu_t^{0,x}, t \in (0, T], x \in H\}$ is a family of equivalent measures. In the same way one proves that the process $X_s^{t,x}$, a solution in the mild sense to the equation

$$dX_{s}^{t,x} = AX_{s}^{t,x} ds + F(s, X_{s}^{t,x}) dt + G dW_{s}, \qquad X_{t} = x_{s}$$

on the interval $[t, T] \subset [0, T]$, satisfies all the requirements of Theorem 10. So if B, ψ , φ satisfy the assumptions in Hypothesis 8 and the operators e^{tB} are compact for t > 0, then there exists a mild solution to (4.4).

5. BSDE with Bounded Continuous Generator: Second Case

In this section we still consider a Markov process $X = \{X_s^{t,x}, 0 \le t \le s \le T, x \in M\}$, with values in a complete separable metric space M, satisfying properties (1)–(4) of Section 4. We denote by $\mu_s^{t,x}$ the transition probabilities of X. We suppose that Hypothesis 8 holds and, in addition, that the function φ is bounded. In particular, the conclusions of Lemma 9 still hold.

We fix arbitrary $x \in M$ and we consider the same BSDE as in formula (4.4):

$$dY_t = -BY_t dt - \psi(t, X_t^{0,x}, Y_t, Z_t) dt + Z_t dW_t, \qquad Y_T = \varphi(X_T^{0,x}).$$
(5.1)

As before an (\mathcal{F}_t) -predictable process (Y, Z) with values in $K \times L_2(\Xi, K)$ is called a mild solution of (5.1) if it satisfies (4.5) and (4.6).

In this section we replace the requirement of mutual absolute continuity of the transition probabilities of X with a continuity assumption of the map $x \to \mu_s^{t,x}$ with respect to the variation norm.

More precisely we assume that for every sequence x_n converging to x in M and for $0 \le t < s \le T$ we have

$$\operatorname{Var}(\mu_s^{t,x} - \mu_s^{t,x_n}) \to 0, \tag{5.2}$$

for $n \to \infty$, where Var denotes the total variation.

Theorem 11. Assume that Hypothesis 8 holds, that the operators e^{tB} are compact for t > 0, that the transition probabilities of the process X satisfy (5.2) and that $|\varphi(x)| \le C$ for some constant C > 0 and every $x \in M$. Then there exists a mild solution to (5.1). Moreover, there exist Borel measurable functions $u: [0, T] \times M \to K, v: [0, T] \times M \to L_2(\Xi, K)$ such that, \mathbb{P} -a.s.,

$$Y_t = u(t, X_t), \quad for all \quad t \in [0, T];$$

$$Z_t = v(t, X_t),$$
 for almost all $t \in [0, T].$

Proof. First Step. Approximation. Applying Lemma 3 we construct a sequence of functions ψ^n : $[0, T] \times M \times K \times L_2(\Xi, K) \to K$ such that, for any $n \ge 1$,

$$|\psi^n(t, x, y, z)| \le C \tag{5.3}$$

and, for fixed n, ψ^n is Lipschitz with respect to (y, z) uniformly with respect to (t, x). Let $(Y^{n,t,x}, Z^{n,t,x})$ be the unique mild solution of

$$dY_{s}^{n,t,x} = -BY_{s}^{n,t,x} ds - \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds + Z_{s}^{n,t,x} dW_{s},$$

$$Y_{T}^{n,t,x} = \varphi(X_{T}^{t,x}),$$
(5.4)

where we define $X_s^{t,x} = x$ for s < t. By (4.7) and the boundedness of φ ,

$$\sup_{s \in [t,T]} \mathbb{E} |Y_s^{n,t,x}|^2 + \mathbb{E} \int_0^T |Z_s^{n,t,x}|^2 \, ds \le C(1 + \mathbb{E} |\varphi(X_T^{t,x})|^2) \le C.$$
(5.5)

Arguing as in the proof of Theorem 10 we deduce that there exist Borel measurable functions u^n : $[0, T] \times M \to K, v^n$: $[0, T] \times M \to L_2(\Xi, K)$, such that, for every t, x, \mathbb{P} -a.s.,

$$Y_s^{n,t,x} = u^n(s, X_s^{t,x}), \qquad s \in [t, T],$$
$$Z_s^{n,t,x} = v^n(s, X_s^{t,x}), \qquad \text{for almost all} \quad s \in [t, T]$$

Second Step. In this step we prove that there exists a subsequence of $u^n(t, x)$ which is convergent in K for every t, x.

We first claim that for fixed (t, x) there exists a subsequence (n_k) (depending on (t, x) such that $(u^{n_k}(t, x))_k$ is convergent in K. This is obvious for t = T, since $u^n(T, x) = \varphi(x)$, we can assume t < T. It is enough to show that, for fixed t, x, the sequence $(u^n(t, x))_n$ is relatively compact in K or, equivalently, that it is totally bounded.

From the definition of the mild solution to (5.4) we obtain, taking expectation,

$$u^{n}(t,x) = Y_{t}^{n,t,x} = \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \mathbb{E} \int_{t}^{T} e^{(s-t)B} \psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds$$
$$= \mathbb{E} e^{(T-t)B} \varphi(X_{T}^{t,x}) + \int_{t}^{T} e^{(s-t)B} g^{n,t,x}(s) ds,$$

where $g^{n,t,x}(s) = \mathbb{E}\psi^n(s, X_s^{t,x}, Y_s^{n,t,x}, Z_s^{n,t,x})$ satisfies $|g^{n,t,x}(s)| \leq C$. It follows that $|u^n(t,x)| \leq C$, i.e. the sequence $(u^n(t,x))_n$ is uniformly bounded. For $\delta > 0$ so small that $t + \delta \leq T$ we decompose $u^n(t, x)$ as follows:

$$u^{n}(t,x) = q(t,x) + a^{n}_{\delta}(t,x) + b^{n}_{\delta}(t,x),$$
(5.6)

where $q(t, x) = \mathbb{E} e^{(T-t)B} \varphi(X_T^{t,x})$,

$$a_{\delta}^{n}(t,x) = \int_{t}^{t+\delta} e^{(s-t)B} g^{n,t,x}(s) \, ds, \qquad b_{\delta}^{n}(t,x) = \int_{t+\delta}^{T} e^{(s-t)B} g^{n,t,x}(s) \, ds.$$

We fix (t, x) and let $\varepsilon > 0$ be arbitrary. We have $|a_{\delta}^{n}(t, x)| \leq C \delta$, so that we can choose δ such that $|a_{\delta}^{n}(t, x)| < \varepsilon/2$ for every *n*. Next note that

$$b_{\delta}^{n}(t,x) = e^{\delta B} \int_{t+\delta}^{T} e^{(s-t-\delta)B} g^{n,t,x}(s) \, ds$$

and

$$\left|\int_{t+\delta}^{T} e^{(s-t-\delta)B} g^{n,t,x}(s) \, ds\right| \leq C.$$

Since $e^{\delta B}$ is compact by our assumptions, the sequence $(b^n_{\delta}(t, x))_n$ is relatively compact, hence totally bounded. So there exists a finite set $A \subset K$ such that for any *n* there exists $a \in A$ satisfying $|b_{\delta}^{n}(t, x) - a| < \varepsilon/2$. So for every *n* there exists $a \in A$ such that $|u^n(t, x) - q(t, x) - a| < \varepsilon$. This shows that $(u^n(t, x))_n$ is totally bounded and the claim is proved.

Next note that

$$u^{n}(t,x) = \mathbb{E}e^{(T-t)B}\varphi(X_{T}^{t,x}) + \mathbb{E}\int_{t}^{T}e^{(s-t)B}\psi^{n}(s,X_{s}^{t,x},Y_{s}^{n,t,x},Z_{s}^{n,t,x})\,ds$$

$$= \mathbb{E}e^{(T-t)B}\varphi(X_{T}^{t,x}) + \mathbb{E}\int_{t}^{T}e^{(s-t)B}\psi^{n}(s,X_{s}^{t,x},u^{n}(s,X_{s}^{t,x}),v^{n}(s,X_{s}^{t,x}))\,ds$$

$$= \int_{M}e^{(T-t)B}\varphi(y)\,\mu_{T}^{t,x}(dy) + \int_{t}^{T}e^{(s-t)B}\int_{M}\Psi^{n}(s,y)\,\mu_{s}^{t,x}(dy)\,ds,$$

ere $\Psi^{n}(s,y) = \psi^{n}(s,y,u^{n}(s,y),y^{n}(s,y)).$

whe $(s, y) = \psi (s, y, u (s, y),$ Let us fix a dense sequence (t_j) in [0, T] and a dense sequence (x_i) in M. By the previous claim and a diagonal procedure we can find a subsequence (n_k) such that $(u^{n_k}(t_j, x_i))_k$ converges for every i, j. By a change of notation we can assume that the original sequence $(u^n(t_i, x_i))_n$ is convergent for every i, j.

Next we fix *j* and we prove that $(u^n(t_j, x))_n$ is convergent for every $x \in M$. The assertion is trivial if $t_j = T$, so we assume $t_j < T$. We start from the inequality

$$|u^{n}(t_{j}, x) - u^{m}(t_{j}, x)| \leq |u^{n}(t_{j}, x) - u^{n}(t_{j}, x_{i})| + |u^{m}(t_{j}, x) - u^{m}(t_{j}, x_{i})| + |u^{n}(t_{j}, x_{i}) - u^{m}(t_{j}, x_{i})|.$$
(5.7)

We have

$$u^{n}(t_{j}, x) - u^{n}(t_{j}, x_{i}) = e^{(T-t)B} \int_{M} \varphi(y) \left[\mu_{T}^{t_{j}, x}(dy) - \mu_{T}^{t_{j}, x_{i}}(dy) \right] + \int_{t_{j}}^{T} e^{(s-t)B} \int_{M} \Psi^{n}(s, y) \left[\mu_{s}^{t_{j}, x}(dy) - \mu_{s}^{t_{j}, x_{i}}(dy) \right] ds,$$

and since φ is bounded and Ψ^n is uniformly bounded we obtain

$$\left| \int_{t_j}^T e^{(s-t)B} \int_M \Psi^n(s, y) \left[\mu_s^{t_j, x}(dy) - \mu_s^{t_j, x_i}(dy) \right] ds \right| \le C \int_{t_j}^T \operatorname{Var}(\mu_s^{t_j, x} - \mu_s^{t_j, x_i}) ds,$$

and

$$\left| e^{(T-t)B} \int_{M} \varphi(y) \left[\mu_{T}^{t_{j},x}(dy) - \mu_{T}^{t_{j},x_{i}}(dy) \right] ds \right| \leq C \operatorname{Var}(\mu_{T}^{t_{j},x} - \mu_{T}^{t_{j},x_{i}}).$$

We note that by (5.2) for every sequence $x_n \to x$ we have $\operatorname{Var}(\mu_s^{t_j,x} - \mu_s^{t_j,x_n}) \to 0$ for $s > t_j$. Since $\operatorname{Var}(\mu_s^{t_j,x} - \mu_s^{t_j,x_n}) \le 2$, by the dominated convergence theorem we obtain

$$\int_{t_j}^T \operatorname{Var}(\mu_s^{t_j,x} - \mu_s^{t_j,x_n}) \, ds \to 0.$$

Given $\varepsilon > 0$, from the previous inequalities it follows that we can choose x_i so close to x that

$$|u^n(t_j, x) - u^n(t_j, x_i)| \le \varepsilon,$$

for every *n*. In a similar way one proves that x_i can be chosen such that in addition $|u^m(t_j, x) - u^m(t_j, x_i)| \le \varepsilon$ for every *m*, and since $(u^n(t_j, x_i))_n$ is convergent we conclude from (5.7) that $(u^n(t_j, x))_n$ is a Cauchy sequence for every $x \in M$.

Next we prove that $(u^n(t, x))_n$ is convergent for every $t \in [0, T]$ and $x \in M$. We can assume t < T, otherwise the assertion is trivial. We first claim that for t < r we have

$$\left| u^{n}(t,x) - \int_{M} u^{n}(r,y) \ \mu^{t,x}_{r}(dy) \right| \leq C \cdot (r-t).$$
(5.8)

From (5.4) we obtain

$$Y_t^{n,t,x} - Y_r^{n,t,x} = \int_t^r e^{(s-t)B} \psi^n(s, X_s^{t,x}, Y_s^{n,t,x}, Z_s^{n,t,x}) \, ds - \int_t^r e^{(s-t)B} Z_s^{n,t,x} \, dW_s$$

Taking expectation we obtain

$$\mathbb{E}\int_{t}^{r} e^{(s-t)B}\psi^{n}(s, X_{s}^{t,x}, Y_{s}^{n,t,x}, Z_{s}^{n,t,x}) ds = \mathbb{E}\left[Y_{t}^{n,t,x} - Y_{r}^{n,t,x}\right]$$
$$= \mathbb{E}[u^{n}(t,x) - u^{n}(r, X_{r}^{t,x})]$$
$$= u^{n}(t,x) - \int_{M} u^{n}(r,y) \ \mu_{r}^{t,x}(dy),$$

and since ψ^n is uniformly bounded, (5.8) follows immediately.

Then we have, for $t_i > t$,

$$\begin{aligned} |u^{n}(t,x) - u^{m}(t,x)| &\leq \left| u^{n}(t,x) - \int_{M} u^{n}(t_{j},y) \ \mu^{t,x}_{t_{j}}(dy) \right| \\ &+ \left| u^{m}(t,x) - \int_{M} u^{m}(t_{j},y) \ \mu^{t,x}_{t_{j}}(dy) \right| \\ &+ \left| \int_{M} u^{n}(t_{j},y) \ \mu^{t,x}_{t_{j}}(dy) - \int_{M} u^{m}(t_{j},y) \ \mu^{t,x}_{t_{j}}(dy) \right|. \end{aligned}$$

Given $\varepsilon > 0$, we choose j such that $t_i - t < \varepsilon$. For $n, m \ge N$ we have

$$|u^{n}(t,x) - u^{m}(t,x)| \le C \cdot \varepsilon + \int_{M} \sup_{n,m \ge N} |u^{n}(t_{j},y) - u^{m}(t_{j},y)| \ \mu^{t,x}_{t_{j}}(dy)$$

Since the sequence $(u^n(t_j, y))_n$ is convergent for every y and it is uniformly bounded, the last integral tends to 0 for $N \to \infty$. The proof of step 2 is finished.

The third and fourth steps are the same as in Theorem 10 and this concludes the proof. $\hfill \Box$

5.1. *Example*

Let *W* be a cylindrical Wiener process in a Hilbert space Ξ with Brownian filtration (\mathcal{F}_t). We take $H = \Xi$ and consider the following equation on the time interval $[t, T] \subset [0, T]$ for an unknown process *X* with values in *H*:

$$dX_s = AX_s \, ds + F(X_s) \, ds + G(X_s) \, dW_s, \qquad X_t = x,$$

where $x \in H$, the operator A: $D(A) \subset H \to H$ is the infinitesimal generator of a strongly continuous semigroup $\{e^{tA}, t \ge 0\}$ of bounded linear operators in H, and $F: H \to H$ and $G: H \to L(H)$ are Borel measurable mappings such that, for some constant $C \ge 0$,

$$|F(x) - F(x')| \le C |x - x'|,$$

 $|G(x) - G(x')|_{L(H)} \le C |x - x'|, \qquad x, x' \in H.$

We also assume that $e^{tA} \in L_2(H, H)$ for t > 0 and that $\int_0^T e^{-\alpha t} |e^{tA}|^2_{L_2(H,H)} dt < \infty$ for some $\alpha > 0$. It is well known (see, e.g. [5]) that under these conditions there exists a mild solution i.e. an (\mathcal{F}_t) -adapted process, with continuous paths in H, such that, \mathbb{P} -a.s.,

$$X_{s} = e^{(s-t)A}x + \int_{t}^{s} e^{(s-r)A}F(X_{r}) dr + \int_{t}^{s} e^{(s-r)A}G(X_{r}) dW_{r}, \qquad s \in [t, T].$$

X is unique up to indistinguishability. The solution will be denoted $X_s^{t,x}$, to stress the dependence on x and t. The process X constructed in this way satisfies conditions (1)–(4) of Section 4. We denote by $\mu_s^{t,x}$ the law of $X_s^{t,x}$.

Assume now in addition that G(x) is invertible for every $x \in H$ and there exists $C \ge 0$ such that $|G(x)^{-1}|_{L(H)} \le C$ for all $x \in H$. Then the following inequality has been proved in [21] (see also Theorem 7.1.1 and Lemma 7.1.5 of [6]):

$$\operatorname{Var}(\mu_s^{t,x} - \mu_s^{t,x'}) \le \frac{C}{\sqrt{s-t}} |x - x'|, \qquad 0 \le t < s \le T, \quad x, x' \in H.$$

So under the previous assumptions, condition (5.2) clearly holds, and so if B, ψ , φ satisfy the other requirements in Theorem 11 then there exists a mild solution to (5.1).

6. A Stochastic Game with Infinitely Many Players

Let *W* be a cylindrical Wiener process in a Hilbert space Ξ , defined on a complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$, and let (\mathcal{F}_t) be its Brownian filtration.

We consider the Ornstein–Uhlenbeck process in a Hilbert space *H* defined by the equation $dX_t = AX_t dt + G dW_t$, more precisely

$$X_t = e^{tA}x + \int_0^t e^{(t-s)A}G \, dW_s, \qquad t \in [0, T],$$

with A and G satisfying Hypothesis 1, and $x \in H$.

Hypothesis 12.

- (i) Let I be a finite or countable set.
- (ii) For every $i \in I$, a metric space U_i is given. We denote $U = \times_{i \in I} U_i$ the product space.
- (iii) We assume that Borel measurable functions are given

 $R: [0, T] \times H \times U \to \Xi, \qquad l^{i}: [0, T] \times H \times U \to \mathbb{R}, \qquad \varphi^{i}: H \to \mathbb{R},$ for every $i \in I$. Moreover, there exist constants $c_{R} \geq 0, c_{i} \geq 0$ such that $|R(t, x, v)| \leq c_{R}, \qquad |l^{i}(t, x, v)| + |\varphi^{i}(x)| \leq c_{i}(1 + |x|^{p}),$ $t \in [0, T], \quad x \in H, \quad v \in U, \quad i \in I.$ Finally we assume that, for every $t \in [0, T], x \in H$ and $i \in I$, the functions $R(t, x, \cdot): U \to \Xi, \qquad l^{i}(t, x, \cdot): U \to \mathbb{R}$ are continuous.

(iv) For every $i \in I$, a number $\lambda_i \ge 0$ is given. If I is infinite, identifying I with the natural numbers, we assume that $\lambda_i \to +\infty$ as $i \to \infty$.

Each element $i \in I$ represents a player. U_i represents the set of actions that player i can take at any time. Coordinates of an element $v \in U$ are denoted v^i and we use the notation $v = (v^i)_i$.

 λ_i is a discount factor in the cost of player *i*, as defined below.

An (\mathcal{F}_t) -adapted process $u = \{u_t, t \in [0, T]\}$, with values in U, is called an admissible decision process. Each component $u^i = \{u_t^i, t \in [0, T]\}, i \in I$, is then a process with values in U_i ; u_t^i represents the action taken by player i at time t.

For every admissible decision process u, a cost $J^i(u)$ for the player $i \in I$ is defined as follows. By the Girsanov theorem the process

$$W_t^u = W_t - \int_0^t R(s, X_s, u_s) \, ds, \qquad t \in [0, T],$$

is a Wiener process under the probability measure \mathbb{P}^u admitting the density ρ^u with respect to \mathbb{P} given by

$$\rho^{u} = \exp\left(\int_{0}^{T} \langle R(s, X_{s}, u_{s}), dW_{s} \rangle - \frac{1}{2} \int_{0}^{T} |R(s, X_{s}, u_{s})|^{2} ds\right).$$

We define

$$J^{i}(u) = \mathbb{E}^{u}\left[\int_{0}^{T} e^{-\lambda_{i}t} l^{i}(t, X_{t}, u_{t}) dt + e^{-\lambda_{i}T} \varphi^{i}(X_{T})\right], \qquad i \in I.$$

Since *R* is bounded, the application of the Girsanov theorem is justified and we also have $\mathbb{E}|\rho^u|^p < \infty$ for every $p \in [1, \infty)$. We note that *X* satisfies

$$X_{t} = e^{tA}x + \int_{0}^{t} e^{(t-s)A}GR(s, X_{s}, u_{s}) ds + \int_{0}^{t} e^{(t-s)A}G dW_{s}^{u}, \qquad t \in [0, T].$$
(6.1)

Therefore, under \mathbb{P}^{u} , *X* is the solution of a controlled stochastic equation with nonlinear drift.

An admissible decision process \hat{u} is called a Nash equilibrium if, for each $i \in I$, the equality

$$J^i(\widehat{u}) \le J^i(u)$$

takes place for arbitrary decision process u satisfying, for all $j \neq i$,

$$u_t^j = \widehat{u}_t^j$$
, \mathbb{P} -a.s. for almost every $t \in [0, T]$.

The aim of this section is to show that a Nash equilibrium exists under appropriate conditions. Our main assumption is Hypothesis 13 below. Before its statement we introduce some notation. We fix numbers $\rho_i > 0$ such that $\sum_{i \in I} c_i^2 \rho_i < \infty$, where c_i are the constants introduced in Hypothesis 12. In what follows we consider backward equations for processes with values in the Hilbert space $\ell_{\rho}^2(I)$, the space of real sequences $(y^i)_i$ satisfying $\sum_{i \in I} |y^i|^2 \rho_i < \infty$, endowed with the inner product

$$\langle y, v \rangle_{\ell^2_{\rho}(I)} = \sum_{i \in I} y^i v^i \rho_i, \qquad y = (y^i)_i \in \ell^2_{\rho}(I), \quad v = (v^i)_i \in \ell^2_{\rho}(I).$$

For $i \in I$ we denote by g_i the element of $\ell_{\rho}^2(I)$ defined by $g_i^j = 0$ if $i \neq j$, $g_i^i = 1/\rho_i$. We note that $\langle y, g_i \rangle_{\ell_{\rho}^2(I)} = y^i$ for every $y = (y^i)_i \in \ell_{\rho}^2(I)$ and that the family $\{g_i \sqrt{\rho_i}, i \in I\}$ is a complete orthonormal basis of $\ell_{\rho}^2(I)$. For every $z \in L_2(\Xi, \ell_{\rho}^2(I))$ we can define elements $z^i \in \Xi^*$ by the formula

$$z^{\iota}\xi = \langle z\xi, g_i \rangle_{\ell^2_{\rho}(I)}, \qquad \xi \in \Xi, \quad i \in I.$$

Since z is a Hilbert–Schmidt operator we have

$$\sum_{i\in I} |z^i|^2_{\Xi^*} \rho_i < \infty, \tag{6.2}$$

so that the sequence $(z^i)_i$ belongs to the Hilbert space $\ell_{\rho}^2(I, \Xi^*)$ consisting of Ξ^* -valued sequences satisfying (6.2), endowed with the natural inner product. It is easy to check that the mapping $z \to (z^i)_i$ is a Hilbert space isomorphism between $L_2(\Xi, \ell_{\rho}^2(I))$ and $\ell_{\rho}^2(I, \Xi^*)$. In what follows we make the identification $z = (z^i)_i$.

Hypothesis 13. There exists a Borel measurable function \underline{u} : $[0, T] \times H \times L_2(\Xi, \ell_{\rho}^2(I))$ $\rightarrow U$ such that for every $t \in [0, T], x \in H, z = (z^i)_i \in L_2(\Xi, \ell_{\rho}^2(I)), i \in I$ the inequality

$$z^{i}R(t, x, \underline{u}(t, x, z)) + l^{i}(t, x, \underline{u}(t, x, z)) \le z^{i}R(t, x, v) + l^{i}(t, x, v)$$

holds for every $v \in U$ satisfying $v^j = \underline{u}^j(t, x, z)$ for all $j \neq i$. Moreover, for every $t \in [0, T], x \in H$ and $i \in I$ the function $\underline{u}^i(t, x, \cdot)$: $L_2(\Xi, \ell_\rho^2(I)) \to U$ is continuous.

Remark 14. Hypotheses 12 and 13 are easier to check in the special case

$$R(t, x, v) = \sum_{j \in I} R_j(t, x, v^j),$$

$$l^i(t, x, v) = \sum_{j \in I} l^i_j(t, x, v^j), \quad t \in [0, T], \quad x \in H, \quad v \in U,$$
(6.3)

i.e. when *R* and each l^i are sums of functions depending only on one coordinate $v^j \in U_j$ of $v \in U$. More precisely suppose that I, U_i, φ^i satisfy the assumptions of Hypothesis 12 (in particular, $|\varphi^i(x)| \le \hat{c}_i(1 + |x|^p)$ for every x, i and for some constants $\hat{c}_i \ge 0$) and that for every $i, j \in I$ there exist Borel measurable functions

$$R_j: [0,T] \times H \times U_j \to \Xi, \qquad l_j^i: [0,T] \times H \times U_j \to \mathbb{R},$$

and constants c_{Ri} , c_{ii} such that

$$\begin{aligned} |R_j(t, x, a)| &\leq c_{Rj}, \\ |l_j^i(t, x, a)| &\leq c_{ij}(1 + |x|^p), \qquad t \in [0, T], \quad x \in H, \quad a \in U_j \end{aligned}$$

and $\sum_{j} c_{Rj} < \infty$, $\sum_{j} c_{ij} < \infty$ for every $i \in I$. We also assume that, for every $t \in [0, T]$, $x \in H$ and $i, j \in I$, the functions

$$R_j(t, x, \cdot): U_j \to \Xi, \qquad l_j^i(t, x, \cdot): U_j \to \mathbb{R}$$

are continuous. If *R* and l^i are defined by (6.3) then Hypothesis 12 is satisfied with $c_i = \sum_j c_{ij} + \hat{c}_i$. Suppose now that there exist Borel measurable functions \underline{u}^i : $[0, T] \times H \times \Xi^* \to U_i, i \in I$, such that

$$\eta R_i(t, x, \underline{u}^i(t, x, \eta)) + l_i^i(t, x, \underline{u}^i(t, x, \eta)) \le \eta R_i(t, x, a) + l_i^i(t, x, a),$$
(6.4)

for every $i \in I$, $t \in [0, T]$, $x \in H$, $\eta \in \Xi^*$, $a \in U_i$. Moreover, assume that for every $t \in [0, T]$, $x \in H$ and $i \in I$ the function $\underline{u}^i(t, x, \cdot)$: $\Xi^* \to U_i$ is continuous. Then setting

$$\underline{u}(t, x, z) = (\underline{u}^{i}(t, x, z^{i}))_{i}$$

it is easy to verify that Hypothesis 13 is satisfied.

Note that (6.4) can be expressed as

$$\underline{u}^{i}(t, x, \eta) \in \operatorname*{argmin}_{a \in U_{i}} \left[\eta R_{i}(t, x, a) + l_{i}^{i}(t, x, a) \right].$$

The existence of a function \underline{u}^i satisfying (6.4) and such that $\underline{u}^i(t, x, \cdot)$ is continuous can be effectively checked in particular cases. For instance, in addition to the previous assumptions, suppose that all the metric spaces U_i coincide with the ball B(0, r) of radius r > 0 centered at the origin of another Hilbert space \mathcal{A} . Furthermore, assume that R_j are defined by

$$R_i(t, x, a) = R_i(t, x)a, \qquad t \in [0, T], \quad x \in H, \quad a \in \mathcal{A},$$

where each $\overline{R}_j(t, x)$ is a linear bounded operator from \mathcal{A} to $\Xi, \overline{R}_j(\cdot, \cdot)a$: $[0, T] \times H \to \Xi$ is Borel measurable for every $a \in \mathcal{A}$, and $|\overline{R}_j(t, x)| \leq \overline{c}_{Rj}, t \in [0, T], x \in H$, for some constants $\overline{c}_{Rj} \geq 0$ satisfying $\sum_j \overline{c}_{Rj} < \infty$. Suppose finally that l_i^i have the special form $l_i^i(t, x, a) = |a|^2, a \in B(0, r)$. Then a minimizer of $a \to \eta R_i(t, x, a) + l_i^i(t, x, a) =$ $\eta \overline{R}_i(t, x)a + |a|^2$ over B(0, r) can be easily computed, and the required function \underline{u}^i can be defined by

$$\underline{u}^{i}(t, x, \eta) = \begin{cases} -\frac{1}{2}(\eta \overline{R}_{i}(t, x))^{*} & \text{if } |\eta \overline{R}_{i}(t, x)| \leq 2r, \\ -r \frac{(\eta \overline{R}_{i}(t, x))^{*}}{|\eta \overline{R}_{i}(t, x)|} & \text{if } |\eta \overline{R}_{i}(t, x)| > 2r, \end{cases}$$

for $t \in [0, T]$, $x \in H$, $\eta \in \Xi^*$, where by $(\eta \overline{R}_i(t, x))^* \in \mathcal{A}$ we denote the image of $\eta \overline{R}_i(t, x) \in \mathcal{A}^*$ under the Riesz isometry $\mathcal{A}^* \to \mathcal{A}$.

Theorem 15. Under Hypotheses 1, 12 and 13 there exists a Nash equilibrium \hat{u} . Moreover, there exists a Borel measurable function $v: [0, T] \times H \to L_2(\Xi, \ell_o^2(I))$ such that

$$\widehat{u}_t = \underline{u}(t, X_t, v(t, X_t)), \qquad \mathbb{P}\text{-}a.s. \text{ for almost every} \quad t \in [0, T].$$
(6.5)

Remark 16. By equality (6.5), \hat{u} is called a closed-loop Nash equilibrium.

Proof. We define an operator B in $\ell_{\rho}^{2}(I)$ setting $(By)_{i} = -\lambda_{i}y^{i}$ for $y \in D(B) = \{(y^{i})_{i}: \sum_{i \in I} \lambda_{i}^{2} | y^{i} |^{2} \rho_{i} < \infty\}$. B is a self-adjoint operator with eigenvectors g_{i} and eigenvalues $-\lambda_{i}$. It is the infinitesimal generator of the dissipative semigroup given by the formula $(e^{tB}y)_{i} = e^{-\lambda_{i}t}y^{i}$. The condition $\lambda_{i} \to \infty$ ensures that e^{tB} is compact for every t > 0.

We define
$$\varphi(x) = (\varphi^{i}(x))_{i}$$
 and $f(t, x, z) = (f^{i}(t, x, z))_{i}$, where
 $f^{i}(t, x, z) = z^{i} R(t, x, \underline{u}(t, x, z)) + l^{i}(t, x, \underline{u}(t, x, z)),$
 $t \in [0, T], \quad x \in H, \quad z \in L_{2}(\Xi, \ell_{\rho}^{2}(I)),$
(6.6)

and we consider the backward equation

$$dY_t = -BY_t \, dt - f(t, X_t, Z_t) \, dt + Z_t \, dW_t, \qquad Y_T = \varphi(X_T), \tag{6.7}$$

where the unknown processes Y and Z take values in $\ell_{\rho}^{2}(I)$ and $L_{2}(\Xi, \ell_{\rho}^{2}(I))$, respectively.

Next we verify that the functions

$$f: [0,T] \times H \times L_2(\Xi, \ell_\rho^2(I)) \to \ell_\rho^2(I), \qquad \varphi: H \to \ell_\rho^2(I)$$

satisfy the assumptions of Theorem 6. By Hypothesis 12,

$$\begin{split} |f(t,x,z)|_{\ell_{\rho}^{2}(I)} &\leq \left(\sum_{i} |z^{i}R(t,x,\underline{u}(t,x,z))|^{2}\rho_{i}\right)^{1/2} \\ &+ \left(\sum_{i} |l^{i}(t,x,\underline{u}(t,x,z))|^{2}\rho_{i}\right)^{1/2} \\ &\leq c_{R} \left(\sum_{i} |z^{i}|_{\Xi^{*}}^{2}\rho_{i}\right)^{1/2} + \left(\sum_{i} c_{i}^{2}\rho_{i}\right)^{1/2} (1+|x|^{p}) \\ &= c_{R}|z|_{L_{2}(\Xi,\ell_{\rho}^{2}(I))} + \left(\sum_{i} c_{i}^{2}\rho_{i}\right)^{1/2} (1+|x|^{p}), \\ |\varphi(x)|_{\ell_{\rho}^{2}(I)} &= \left(\sum_{i} |\varphi^{i}(x)|^{2}\rho_{i}\right)^{1/2} \leq \left(\sum_{i} c_{i}^{2}\rho_{i}\right)^{1/2} (1+|x|^{p}). \end{split}$$

The functions $f^i(t, x, \cdot)$ are continuous since they are defined in terms of the continuous mappings $R(t, x, \cdot)$, $l^i(t, x, \cdot)$ and $\underline{u}(t, x, \cdot)$. To check continuity of $f(t, x, \cdot)$, we consider a sequence z_n converging to z in $L_2(\Xi, \ell_{\rho}^2(I))$ and note that

$$\begin{split} |f^{i}(t, x, z_{n}) - f^{i}(t, x, z)| \\ &\leq |z_{n}^{i}R(t, x, \underline{u}(t, x, z_{n})) - z^{i}R(t, x, \underline{u}(t, x, z))| \\ &+ |l^{i}(t, x, \underline{u}(t, x, z_{n})) - l^{i}(t, x, \underline{u}(t, x, z))| \\ &\leq c_{R}|z_{n}^{i} - z^{i}| + |z^{i}| |R(t, x, \underline{u}(t, x, z_{n})) - R(t, x, \underline{u}(t, x, z))| \\ &+ |l^{i}(t, x, \underline{u}(t, x, z_{n})) - l^{i}(t, x, \underline{u}(t, x, z))|. \end{split}$$

It follows that

$$\begin{split} |f(t, x, z_n) - f(t, x, z)|_{\ell_{\rho}^2(I)} \\ &= \left(\sum_i |f^i(t, x, z_n) - f^i(t, x, z)|^2 \rho_i\right)^{1/2} \\ &\leq c_R |z_n - z|_{L_2(\Xi, \ell_{\rho}^2(I))} \\ &+ \left(\sum_i |z^i|^2 |R(t, x, \underline{u}(t, x, z_n)) - R(t, x, \underline{u}(t, x, z))|^2 \rho_i\right)^{1/2} \\ &+ \left(\sum_i |l^i(t, x, \underline{u}(t, x, z_n)) - l^i(t, x, \underline{u}(t, x, z))|^2 \rho_i\right)^{1/2}. \end{split}$$

Since *R* is bounded, $\sum_i |z^i|^2 \rho_i < \infty$, $|l^i(t, x, \underline{u}(t, x, z_n))| \le c_i(1+|x|^p)$ and $\sum_i c_i^2 \rho_i < \infty$ we conclude that $|f(t, x, z_n) - f(t, x, z)|_{\ell_\rho^2(I)} \to 0$.

Theorem 6 shows that (6.7) has a solution satisfying, in particular, $\mathbb{E} \int_0^T |Z_s^i|^2 ds < \infty$. Moreover, there exists a Borel measurable function $v: [0, T] \times H \to L_2(\Xi, \ell_{\rho}^2(I))$ such that $Z_t = v(t, X_t)$, \mathbb{P} -a.s. for almost every $t \in [0, T]$.

We will show that the process $\hat{u}_t = \underline{u}(t, X_t, Z_t) = \underline{u}(t, X_t, v(t, X_t)), t \in [0, T]$, is a Nash equilibrium. Writing (6.7) in the form specified by definition (3.3) and taking the scalar product with g_i we obtain, for every $i \in I$,

$$Y_t^i + \int_t^T e^{-\lambda_i(s-t)} Z_s^i \, dW_s = e^{-\lambda_i(T-t)} \varphi^i(X_T) + \int_t^T e^{-\lambda_i(s-t)} f^i(s, X_s, Z_s) \, ds.$$

For every admissible decision process u, by the definition of W^u we obtain

$$Y_0^i - e^{-\lambda_i T} \varphi^i(X_T) = -\int_0^T e^{-\lambda_i s} Z_s^i \, dW_s^u -\int_0^T e^{-\lambda_i s} Z_s^i R_s(s, X_s, u_s) \, ds + \int_0^T e^{-\lambda_i s} f^i(s, X_s, Z_s) \, ds.$$

We recall that W^u is a Wiener process under \mathbb{P}^u and we note that

$$\mathbb{E}^{u} \left(\int_{0}^{T} |Z_{s}^{i}|^{2} ds \right)^{1/2} = \mathbb{E} \left[\rho^{u} \left(\int_{0}^{T} |Z_{s}^{i}|^{2} ds \right)^{1/2} \right]$$
$$\leq \left(\mathbb{E} |\rho^{u}|^{2} \right)^{1/2} \left(\mathbb{E} \int_{0}^{T} |Z_{s}^{i}|^{2} ds \right)^{1/2} < \infty.$$

It follows that $\int_0^t Z_s^i dW_s^u$, $t \in [0, T]$, is a \mathbb{P}^u -martingale. Taking expectation we obtain

$$Y_{0}^{i} = e^{-\lambda_{i}T} \mathbb{E}^{u} \varphi^{i}(X_{T}) + \mathbb{E}^{u} \int_{0}^{T} e^{-\lambda_{i}s} [f^{i}(s, X_{s}, Z_{s}) - Z_{s}^{i}R(s, X_{s}, u_{s})] ds$$

= $J^{i}(u) + \mathbb{E}^{u} \int_{0}^{T} e^{-\lambda_{i}s} [f^{i}(s, X_{s}, Z_{s}) - Z_{s}^{i}R(s, X_{s}, u_{s}) - l^{i}(s, X_{s}, u_{s})] ds.$ (6.8)

By the definition of f^i and Hypothesis 13, for every $i \in I$,

 $f^{i}(t, x, z) \leq z^{i} R(t, x, v) + l^{i}(t, x, v),$

 $t \in [0, T], \quad x \in H, \quad z \in L_2(\Xi, \ell_\rho^2(I)),$

for every $v \in U$ satisfying $v^j = \underline{u}^j(t, x, z)$ for all $j \neq i$. It follows that

$$f^{i}(t, X_{t}, Z_{t}) \leq Z_{t}^{i} R(t, X_{t}, u_{t}) + l^{i}(t, X_{t}, u_{t}),$$
(6.9)

for every decision process such that $u_t^j = \widehat{u}_t^j = \underline{u}^j(t, X_t, Z_t)$ for all $j \neq i$.

On the other hand from (6.6) we obtain

$$f^{i}(t, X_{t}, Z_{t}) = Z_{t}^{i} R(t, X_{t}, \widehat{u}_{t}) + l^{i}(t, X_{t}, \widehat{u}_{t}).$$
(6.10)

From (6.8) and (6.9) it follows that $Y_0^i \leq J^i(u)$; from (6.8) and (6.10) it follows that $Y_0^i = J^i(\widehat{u})$; we conclude that $J^i(\widehat{u}) \leq J^i(u)$, which shows that \widehat{u} is a Nash equilibrium.

Acknowledgments

The authors thank the two anonymous referees for their helpful comments.

Appendix

This appendix is devoted to the proof of Lemma 2. We follow closely the proof of Proposition 4.2 of [4]. We keep the notation of Section 2.2; by Im we denote the image of an operator. We first state a lemma on gaussian measures.

Lemma 17. Suppose that Q, R are nonnegative, injective, trace class linear operators on H satisfying

$$\operatorname{Im} Q^{1/2} = \operatorname{Im} R^{1/2}; \tag{A.1}$$

suppose, moreover, that the operator

$$G = (R^{-1/2}Q^{1/2})^* R^{-1/2}Q^{1/2} - 1$$
(A.2)

is trace class. Then $\mathcal{N}(0, R)$ is equivalent to $\mathcal{N}(0, Q)$ and, for $\mathcal{N}(0, Q)$ -a.e. $x \in H$,

$$\frac{d\mathcal{N}(0,R)}{d\mathcal{N}(0,Q)}(x) = \det(1+G)^{1/2} \exp(-\frac{1}{2} \langle GQ^{-1/2}x, Q^{-1/2}x \rangle).$$
(A.3)

The determinant is understood as the infinite product of eigenvalues. It is well defined, since G is trace class. Equivalence of measures follows from the Feldman–Hajek Theorem, while the formula for the density can be found in Section II.4.3, Remark 4.4 and formula (4.16) of [7]. A simple direct proof can be found in [4].

In the rest of this appendix we assume that Hypothesis 1 holds. We state two wellknown properties of the operators Q_t , whose short proofs are reported for the reader's convenience.

(i) The operators Q_t , t > 0, are injective.

Indeed, by a duality argument (see for instance Appendix B of [5]), Hypothesis 1(iv) implies that for every t > 0 there exists $C_t > 0$ such that

$$|e^{tA^*}y| \le C_t |Q_t^{1/2}y|, \qquad y \in H$$

So if $Q_t x = 0$ for some t > 0, then $Q_s x = 0$, $s \le t$, and consequently $e^{sA^*}x = 0$, $s \le t$; letting $s \to 0$, we obtain x = 0. (ii) For every t > 0, Im $Q_T^{1/2} = \text{Im } Q_t^{1/2}$. In particular, $Q_T^{-1/2}e^{tA}$ is a linear

bounded operator on H.

We notice the equality $Q_T = Q_t + e^{tA}Q_{T-t}e^{tA^*}$, which is a consequence of the definition of Q_t and Q_T . We obtain

$$Q_T = Q_t + e^{tA} Q_{T-t} e^{tA^*} = Q_t^{1/2} [1 + (Q_t^{-1/2} e^{tA}) Q_{T-t} (Q_t^{-1/2} e^{tA})^*] Q_t^{1/2},$$

which yields, for some constant $C_{tT} > 0$,

$$|Q_T^{1/2}x|^2 = |[1 + (Q_t^{-1/2}e^{tA})Q_{T-t}(Q_t^{-1/2}e^{tA})^*]^{1/2}Q_t^{1/2}x|^2$$

$$\leq C_{tT}|Q_t^{1/2}x|^2, \qquad x \in H.$$
(A.4)

On the other hand,

$$|Q_t^{1/2}x|^2 = \langle Q_t x, x \rangle \le \langle Q_T x, x \rangle = |Q_T^{1/2}x|^2, \qquad x \in H.$$
 (A.5)

By a duality argument (see, e.g. Appendix B of [5]) we conclude that Im $Q_T^{1/2} =$ Im $Q_t^{1/2}$.

(iii) For $0 < s \le t$ we have

$$|Q_t^{-1/2}e^{tA}| \le |Q_s^{-1/2}e^{sA}|. \tag{A.6}$$

We start from the easily verified identity $Q_t = Q_{t-s} + e^{(t-s)A} Q_s e^{(t-s)A^*}$, which implies $Q_t \ge e^{(t-s)A} Q_s e^{(t-s)A^*}$ and therefore $|Q_t^{1/2} x|^2 \ge |Q_s^{1/2} e^{(t-s)A^*} x|^2$, $x \in H$. By a duality argument it follows that $|Q_t^{-1/2} e^{(t-s)A} Q_s^{1/2}| \le 1$ and consequently $|Q_t^{-1/2} e^{tA} x| = |Q_t^{-1/2} e^{(t-s)A} Q_s^{1/2} Q_s^{-1/2} e^{sA} x| \le |Q_s^{-1/2} e^{sA} x|$, which proves the claim.

Proof of Lemma 2. The kernel *k* is the Radon–Nikodym density

$$k_t(x, \cdot) = \frac{d\mathcal{N}(e^{tA}x, Q_t)}{d\mathcal{N}(0, Q_T)}.$$

We first prove the special case corresponding to x = 0, namely that

$$k_t(0,\cdot) = \det(1-\Theta_{tT})^{-1/2} \exp\{-\frac{1}{2} \langle \Theta_{tT}(1-\Theta_{tT})^{-1} Q_T^{-1/2} y, Q_T^{-1/2} y \rangle\}.$$
 (A.7)

Since Q_{T-t} is a trace class operator and $Q_T^{-1/2}e^{tA}$ is linear bounded, the operator Θ_{tT} is trace class. Moreover, since

$$Q_{t} = Q_{T} - e^{tA}Q_{T-t}e^{tA^{*}} = Q_{T}^{1/2}[1 - (Q_{T}^{-1/2}e^{tA})Q_{T-t}(Q_{T}^{-1/2}e^{tA})^{*}]Q_{T}^{1/2}$$

= $Q_{T}^{1/2}(1 - \Theta_{tT})Q_{T}^{1/2}$

we have

$$(1 - \Theta_{tT})x = Q_T^{-1/2} Q_t Q_T^{-1/2} x, \qquad x \in \operatorname{Im} Q_T^{1/2}.$$
(A.8)

Therefore, $\langle (1 - \Theta_{tT})x, x \rangle \ge 0$ for $x \in \text{Im } Q_T^{1/2}$, a dense subset of H; it follows that $(1 - \Theta_{tT})$ is nonnegative. Equality (A.8) also implies, by standard arguments, that $(1 - \Theta_{tT})$ is invertible and

$$(1 - \Theta_{tT})^{-1} = (Q_t^{-1/2} Q_T^{1/2})^* Q_t^{-1/2} Q_T^{1/2}.$$
(A.9)

Define $G = (Q_t^{-1/2} Q_T^{1/2})^* Q_t^{-1/2} Q_T^{1/2} - 1$. Then

$$G = (1 - \Theta_{tT})^{-1} - 1 = \Theta_{tT} (1 - \Theta_{tT})^{-1},$$
(A.10)

so G is trace class and formula (A.7) follows from Lemma 17.

To prove the general case, we use the equality

$$k_t(x,\cdot) = \frac{d\mathcal{N}(e^{tA}x, Q_t)}{d\mathcal{N}(0, Q_t)} \frac{d\mathcal{N}(0, Q_t)}{d\mathcal{N}(0, Q_T)} = \frac{d\mathcal{N}(e^{tA}x, Q_t)}{d\mathcal{N}(0, Q_t)} k_t(0, \cdot),$$
(A.11)

and we notice that, by the Cameron–Martin Theorem (see, e.g. [5]),

$$\frac{d\mathcal{N}(e^{tA}x, Q_t)}{d\mathcal{N}(0, Q_t)}(y) = \exp(\langle Q_t^{-1/2}e^{tA}x, Q_t^{-1/2}y \rangle - \frac{1}{2}|Q_t^{-1/2}e^{tA}x|^2),$$

for $\mathcal{N}(0, Q_t)$ -a.e. $y \in H$. If $m \in \text{Im } Q_t$, then (A.9) implies $(1 - \Theta_{tT})^{-1}Q_T^{-1/2}m = Q_T^{1/2}Q_t^{-1}m$ and we have, for $y \in H$, a.e. with respect to $\mathcal{N}(0, Q_T)$ and $\mathcal{N}(0, Q_t)$,

$$\langle Q_t^{-1/2}m, Q_t^{-1/2}y \rangle = \langle Q_t^{-1}m, y \rangle = \langle Q_T^{1/2}Q_t^{-1}m, Q_T^{-1/2}y \rangle$$

= $\langle (1 - \Theta_{tT})^{-1}Q_T^{-1/2}m, Q_T^{-1/2}y \rangle.$ (A.12)

Equation (A.9) also implies

$$|Q_t^{-1/2}m|^2 = |(1 - \Theta_{tT})^{-1/2}Q_T^{-1/2}m|^2.$$
(A.13)

The equalities (A.12) and (A.13) extend by continuity to every $m \in \text{Im } Q_t^{1/2}$. So we can set $m = e^{tA}x$, and substituting into (A.11) and using (A.7), we prove the formula for k.

It remains to prove the inequalities (2.5) and (2.6).

The equality (A.9) shows that $|(1 - \Theta_{tT})^{-1}| = |Q_t^{-1/2} Q_T^{1/2}|^2$. The first equality in (A.4) implies that

$$|Q_t^{-1/2}Q_T^{1/2}|^2 \le |1 + (Q_t^{-1/2}e^{tA})Q_{T-t}(Q_t^{-1/2}e^{tA})^*|,$$

and since $(Q_t^{-1/2}e^{tA})Q_{T-t}(Q_t^{-1/2}e^{tA})^* \ge 0$, we conclude that

$$|(1 - \Theta_{tT})^{-1}| \le 1 + |(Q_t^{-1/2}e^{tA})Q_{T-t}(Q_t^{-1/2}e^{tA})^*| \le 1 + |Q_{T-t}||Q_t^{-1/2}e^{tA}|^2,$$
(A.14)

which proves (2.5).

In what follows we denote for simplicity

$$a = |Q_{T-t}||Q_t^{-1/2}e^{tA}|^2.$$

To prove (2.6) we first recall that Θ_{tT} is a trace class nonnegative operator and we denote by $\lambda_0, \lambda_1, \ldots$ its eigenvalues, arranged in decreasing order. Since $0 \le \Theta_{tT} < 1$ we have $0 \le \cdots \le \lambda_1 \le \lambda_0 = |\Theta_{tT}| < 1$. It follows that $(1 - \lambda_0)^{-1} = |(1 - \Theta_{tT})^{-1}|$ and by (A.14) we have $(1 - \lambda_0)^{-1} \le 1 + a$ and we first conclude that $\lambda_0 \le a/(1 + a)$.

Next we compute

$$\det(1-\Theta_{tT})^{-1} = \prod_{k=0}^{\infty} (1-\lambda_k)^{-1} = \exp\left[-\sum_{k=0}^{\infty} \log(1-\lambda_k)\right]$$

Since the function $x \to (-\log(1-x))/x$ is increasing in the interval (0, 1) we have, in particular,

$$\frac{-\log(1-\lambda_k)}{\lambda_k} \le \frac{-\log(1-\lambda_0)}{\lambda_0} \le \frac{-\log(1-a/(1+a))}{a/(1+a)}$$
$$= \frac{\log(1+a)}{a}(1+a) \le 1+a,$$

and we obtain

$$\det(1 - \Theta_{tT})^{-1} \le \exp\left[(1+a)\sum_{k=0}^{\infty}\lambda_k\right] = \exp\left[(1+a)\operatorname{Trace}\Theta_{tT}\right]$$

Then we have

Trace
$$\Theta_{tT} = \text{Trace}((Q_T^{-1/2}e^{tA})Q_{T-t}(Q_T^{-1/2}e^{tA})^*) \le (\text{Trace } Q_{T-t})|Q_T^{-1/2}e^{tA}|^2$$

and since inequality (A.5) implies that $|Q_T^{-1/2}Q_t^{1/2}| \le 1$, we deduce that

$$|Q_T^{-1/2}e^{tA}| \le |Q_T^{-1/2}Q_t^{-1/2}||Q_t^{-1/2}e^{tA}| \le |Q_t^{-1/2}e^{tA}|.$$

Substituting, we obtain det $(1 - \Theta_{tT})^{-1} \leq \exp[(1 + a)(\operatorname{Trace} Q_{T-t})|Q_t^{-1/2}e^{tA}|^2]$ and (2.6) is proved.

References

- 1. F. Confortola. Dissipative backward stochastic differential equations in infinite dimensions. Ph.D. Thesis, University of Milan, 2004.
- 2. F. Confortola. Dissipative backward stochastic differential equations in infinite dimensions. Infin. Dimens. Anal. Quantum Probab. Relat. Top. 9(1) (2006), 155–168.
- 3. F. Confortola. Dissipative backward stochastic differential equation with locally Lipschitz nonlinearity. Stochastic Process. Appl., to appear.
- G. Da Prato, M. Fuhrman and J. Zabczyk. A note on regularizing properties of Ornstein–Uhlenbeck semigroups in infinite dimensions. In: G. Da Prato and L. Tubaro (Eds.) Stochastic Partial Differential Equations and Applications, pp. 167–182. Marcel Dekker, New York, 2002.
- 5. G. Da Prato and J. Zabczyk. Stochastic Equations in Infinite Dimensions. Encyclopedia of Mathematics and its Applications. Cambridge University Press, Cambridge, 1992.
- 6. G. Da Prato and J. Zabczyk. Ergodicity for Infinite-Dimensional Systems. London Mathematical Society Lecture Note Series, 229. Cambridge University Press, Cambridge, 1996.
- 7. Yu. Dalecky and S.V. Fomin. Measures and Differential Equations in Infinite-Dimensional Space. Kluwer Academic, Dordrecht, 1991.
- 8. N. El Karoui, S. Peng and M.C. Quenez. Backward stochastic differential equations in finance. Math. Finance 7 (1997), 1–71.
- 9. M. Fuhrman. A class of stochastic optimal control problems in Hilbert spaces: BSDEs and optimal control laws, state constraints, conditioned processes. Stochastic Process. Appl. 108 (2003), 263–298.
- M. Fuhrman and G. Tessitore. Nonlinear Kolmogorov equations in infinite dimensional spaces: the backward stochastic differential equations approach and applications to optimal control. Ann. Probab. 30 (2002), 1397–1465.
- M. Fuhrman and G. Tessitore. The Bismut–Elworthy formula for backward SDEs and applications to nonlinear Kolmogorov equations and control in infinite dimensional spaces. Stoch. Stoch. Rep. 74 (2002), 429–464.
- 12. M. Fuhrman and G. Tessitore. Infinite horizon backward stochastic differential equations and elliptic equations in Hilbert spaces. Ann. Probab. 32 (2004), 607–660.
- G. Guatteri. On a class of forward-backward stochastic differential systems in infinite dimensions, J. Appl. Math. Stochastic Anal. (2007), Art. ID 42640, 33 pp.
- G. Guatteri and G. Tessitore. On the backward stochastic Riccati equation in infinite dimensions. SIAM J. Control Optim. 44 (2005), 159–194.

- S. Hamadene, J.P. Lepeltier and S. Peng. BSDEs with continuous coefficients and stochastic differential games. In: N. El Karoui and L. Mazliak (Eds.), Backward Stochastic Differential Equations (Paris, 1995–1996), pp. 115–128. Pitman Research Notes in Mathematics Series, Vol. 364. Longman, Harlow, 1997.
- 16. Y. Hu and J. Ma. Nonlinear Feynman–Kac formula and discrete-functional-type BSDEs with continuous coefficients. Stochastic Process. Appl. 112 (2004), 23–51.
- 17. Y. Hu and S. Peng. Adapted solution of a backward semilinear stochastic evolution equation. Stochastic Anal. Appl. 9 (1991), 445–459.
- 18. B. Øksendal and T. Zhang. On backward stochastic partial differential equations. Preprint, 2001.
- 19. E. Pardoux and S. Peng. Adapted solution of a backward stochastic differential equation. Systems Control Lett. 14 (1990), 61–74.
- 20. E. Pardoux and A. Rascanu. Backward stochastic variational inequalities. Stoch. Stoch. Rep. 67(3–4) (1999), 159–167.
- 21. S. Peszat and J. Zabczyk. Strong Feller property and irreducibility for diffusions on Hilbert spaces. Ann. Probab. 23 (1995), 157–172.
- 22. I. Simão. A conditioned Ornstein–Uhlenbeck process on a Hilbert space. Stochastic Anal. Appl. 9 (1991), 85–98.
- 23. I. Simão. Regular fundamental solution for a parabolic equation on an infinite-dimensional space. Stochastic Anal. Appl. 11 (1993), 235–247.
- 24. I. Simão. Regular transition densities for infinite-dimensional diffusions. Stochastic Anal. Appl. 11 (1993), 309–336.