The convex hull of a regular set of integer vectors is polyhedral and effectively computable

Alain Finkel, Jérôme Leroux

The convex hull of a regular set of integer vectors is polyhedral and effectively computable

Alain Finkel

LSV, CNRS UMR 8643, ENS de Cachan, Cachan, France

Jérôme Leroux

DIRO, Université de Montréal, Montréal, QC, Canada

Abstract

Number Decision Diagrams (NDD) provide a natural finite symbolic representation for regular set of integer vectors encoded as strings of digit vectors (least or most significant digit first). The convex hull of the set of vectors represented by a NDD is proved to be an effectively computable convex polyhedron.

Key words: approximation algorithm, symbolic representation, polyhedral convex set, Presburger arithmetic

Presburger arithmetic [Pre29] is a decidable logic used in a large range of applications. Different techniques [GBD02] and tools have been developed for manipulating *the Presburger-definable sets* (the sets of integer vectors satisfying a Presburger formula): by working directly on the Presburger-formulas (implemented in Omega [Ome]), by using semi-linear sets [GS66] (implemented in Brain [RV02]), or by using NDD (automata that represent regular sets of integer vectors encoded as strings of digit vectors, least or most significant digit first) [Boi98, WB95, BC96] (implemented in Fast [BFLP03], Lash [Las] and CSL-ALV[BB03]). Presburger-formulas and semi-linear sets lack canonicity: there does not exist a natural way to canonically represent a set. As a direct consequence, a set that possesses a simple representation could unfortunately be represented in an unduly complicated way. Moreover,

Email addresses: finkel@lsv.ens-cachan.fr (Alain Finkel), leroujer@iro.umontreal.ca (Jérôme Leroux).

[1] Research funded by the Faculté des arts et des sciences of the Université de Montréal and by the Natural Sciences and Engineering Research Council of Canada through a discovery grant held by Pierre McKenzie.

deciding if a given vector of integers is in a given set, is at least *NP-hard* [Ber77, GS66]. On the other hand, a minimization procedure for automata provides a canonical representation for *NDD-definable sets* (a set represented by a NDD). That means, the NDD that represents a given set only depends on the set and not on the way we have computed it. For this reason, NDD are well adapted for applications that require a lot of Boolean manipulations like model-checking.

Verification of systems with unbounded integer variables is undecidable in general. That explains why we are interested in over-approximating the reachability set of such a system. By computing the convex hull of the set of initial states of such a system and by using a widening operator [CH78, HPR97], an over-approximation of the set of reachability set can be effectively computed.

In this presentation, the convex hull of a set of integer vectors represented by a NDD is proved to be a convex polyhedron. That shows that it can be finitely represented as a *finite intersection of half-spaces* or dually as a *finite set of rays*. Indeed, we provide an *exponential time algorithm* that effectively computes this convex hull (the exact complexity remains open).

This result is obtained by first proving that "the convex hull" of the language $\sigma_1^*.\sigma_2^*$ is equal to the convex hull of $\sigma_2^*.\sigma_1^*$ for any pair of words (σ_1, σ_2). From this commutativity result, we deduce that the convex hull of any regular language L, is equal to the convex hull of a finite union of regular languages of the form $w_0.\sigma_1^* \dots w_{n-1}.\sigma_n^*.w_n$.

1 Closed sets and convex sets

Recall that the *scalar product* of two real vectors $x, y \in \mathbb{R}^m$ where $m \geq 1$ is the real $\langle x, y\rangle = \sum_{i=1}^m x[i].y[i]$ where $x[i] \in \mathbb{R}$ corresponds to the ith component of x. We denote by $|x|_2$ the *norm* $|x|_2 = \sqrt{\langle x, x\rangle}$. The *open ball* centered in $x \in \mathbb{R}^m$ with a radius $\epsilon > 0$ is the subset $B_{x,\epsilon} = \{y \in \mathbb{R}^m;\ |x-y|_2 < \epsilon\}$. Recall that a subset $X \subseteq \mathbb{R}^m$ is said *open* if for any $x \in X$ there exists $\epsilon > 0$ such that $B_{x,\epsilon} \subseteq X$. A *closed set* X is a subset of $\mathbb{R}^m$ such that difference $\mathbb{R}^m \backslash X$ is open. Recall that any infinite or finite intersection of closed sets is closed and any subset X is included into a minimal (for the inclusion) closed set, called the *closure* of X. We denote by $\mathrm{cl} : \mathcal{P}(\mathbb{R}^m) \to \mathcal{P}(\mathbb{R}^m)$ the function such that $\mathrm{cl}(X)$ is the closure of X for any $X \subseteq \mathbb{R}^m$.

An *half-space* H is a subset of real vectors $\mathbb{R}^m$ such that there exists $\alpha \in \mathbb{R}^m$ and $c \in \mathbb{R}$ satisfying $H = \{x \in \mathbb{R}^m;\ \langle \alpha, x\rangle + c \# 0\}$ where $\# \in \{\geq, >\}$. Recall that such an half space H is closed if $\#$ is equal to $\geq$ and it is open if $\#$ is equal to $>$.

We denote by $\mathbb{R}_+$ and $\mathbb{R}_-$ respectively the set of non-negative reals $\mathbb{R}_+ = \{x \in \mathbb{R};\ x \geq 0\}$ and the set of non-positive reals $\mathbb{R}_-\{x \in \mathbb{R};\ x \leq 0\}$.

A *convex set* is a *finite or infinite* intersection of half-spaces. The *convex hull* of a subset $X \subseteq \mathbb{R}^m$ is the least (for the inclusion $\subseteq$) convex set that contains X. We denote by $\text{conv} : \mathcal{P}(\mathbb{R}^m) \to \mathcal{P}(\mathbb{R}^m)$ the function such that $\text{conv}(X)$ is the convex hull of X for any $X \subseteq \mathbb{R}^m$. Recall that a vector y is in $\text{conv}(X)$ if and only if there exists a finite sequence $(x_i)_{1 \leq i \leq n}$ of $n \geq 1$ vectors in X and a sequence $(t_i)_{1 \leq i \leq n}$ of n reals in $\mathbb{R}_+$ such that $\sum_{i=1}^n t_i = 1$ and such that $y = \sum_{i=1}^n t_i.x_i$. Recall that the closure of a convex set remains a convex set.

A convex set C is said *polyhedral* if C is equal to a finite intersection of *closed* half-spaces (in particular, a polyhedral convex set is closed). Recall that any polyhedral convex set P can be represented by a finite set of *rays* $R \subseteq \mathbb{R}^m \times \mathbb{R}_+$ such that $P = P(R) = \{x \in \mathbb{R}^m;\ (x, 1) \in C(R)\}$ where $C(R) \subseteq \mathbb{R}^m \times \mathbb{R}_+$ is the *polyhedral cone* defined by the following equality:

$$C(R) = \{\sum_{r \in R} t_r.r;\ t_r \in \mathbb{R}_+\}$$

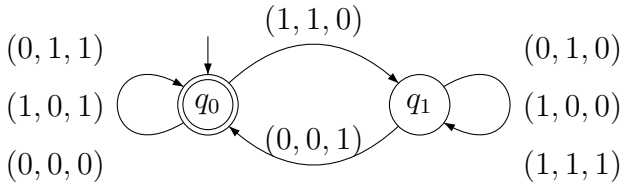
Recall that for any pair (P_1, P_2) of polyhedral convex sets respectively represented by a pair of finite set of rays (R_1, R_2), the convex set $\text{cl} \circ \text{conv}(P_1 \cup P_2)$ is polyhedral and represented by the set of rays $R_1 \cup R_2$.

2 Regular sets of integer vectors

Let us consider an integer $r \geq 2$ called the *basis of the decomposition* and an integer $m \geq 1$ called the *dimension of the represented vectors*. A *digit vector* b is an element of the finite alphabet $\Sigma_{r^m} = \{0 \dots r-1\}^m$. The vector $\rho(\sigma) \in \mathbb{N}^m$ associated with a word $\sigma = b_1 \dots b_n$ of $n \geq 1$ digit vectors $b_i \in \Sigma_{r^m}$ is defined by $\rho(\sigma) = \sum_{i=1}^n r^{i-1}.b_i$. We naturally define $\rho(\epsilon) = (0, \dots, 0)$, also written 0.

The set X represented by a *language* $L \subseteq \Sigma_{r^m}^*$ is defined by $X = \rho(L) = \{\rho(\sigma);\ \sigma \in L\}$. If L is *regular* (that means accepted by a *finite automaton*), the set X is naturally said *regular*. Let us recall that regular sets of vectors can be efficiently manipulated with finite automata (see [WB00, BC96]) and they correspond to the sets defined by a formula in the first order logic $\langle \mathbb{N}, +, \leq, V_r \rangle$ where V_r is the valuation function in base r defined by $y = V_r(x)$ if and only if y is the greatest power of r that divides x [BHMV94].

Example 1 *Consider the following automaton A_+ with basis $r = 2$ and dimension $m = 3$ depicted below. Intuitively, this automaton represents the set of vectors $(x, y, z) \in \mathbb{N}^3$ such that $x + y = z$ where the state q_i corresponds to the carry $i \in \{0, 1\}$ of the addition.*



3 The convex hull of a regular set of integer vectors

The main result of this paper is proved in this section. We show that the closure of the convex hull of a regular set of integer vectors is polyhedral and represented by a set of rays effectively computable in exponential time from any regular expression that defines this regular set.

As $\rho(\sigma w) = r^{|\sigma|}.\rho(w) + \rho(\sigma)$ for any pair of words (σ, w), we introduce the function $\Gamma_\sigma : \mathbb{R}^m \to \mathbb{R}^m$ defined by $\Gamma_\sigma(x) = r^{|\sigma|}.x + \rho(\sigma)$. Remark that any regular language L can be decomposed into a finite union of regular languages of the form $\sigma_{n+1}.L_n^*.\sigma_n \dots L_1^*.\sigma_1$ where $\sigma_i \in \Sigma_{r^m}^*$ and $L_i \subseteq \Sigma_{r^m}^*$. The following lemma is a first step toward the computation of $\mathrm{cl} \circ \mathrm{conv} \circ \rho(L)$.

Proposition 2 *Let us consider a language $L = \sigma_{n+1}.L_n^*.\sigma_n \dots L_1^*.\sigma_1$ where $n \geq 0$, $\sigma_i \in \Sigma_{r^m}^*$ and $L_i \subseteq \Sigma_{r^m}^*$. We have the following equality:*

$$\mathrm{cl}\circ\mathrm{conv}\circ\rho(L) = \Gamma_{\sigma_{n+1}\dots\sigma_1}\circ\mathrm{cl}\circ\left(\{(0,\dots,0)\} \cup \bigcup_{i=1}^{n} \mathbb{R}_-.\Gamma^{-1}_{\sigma_i\dots\sigma_1} \circ \mathrm{cl} \circ \mathrm{conv} \circ \xi(L_i^*)\right)$$

where $\sigma \to \xi(\sigma)$ is partially defined over $\Sigma_{r^m}^+$, by the following equality:

$$\xi(\sigma) = \frac{\rho(\sigma)}{1 - r^{|\sigma|}}$$

PROOF. We denote by $C(\sigma_{n+1}, L_n, \sigma_n, \dots, L_1, \sigma_1)$, the following set:

$$\Gamma_{\sigma_{n+1}\dots\sigma_1} \circ \mathrm{cl} \circ \left(\{(0,\dots,0)\} \cup \bigcup_{i=1}^{n} \mathbb{R}_-.\Gamma^{-1}_{\sigma_i\dots\sigma_1} \circ \mathrm{cl} \circ \mathrm{conv} \circ \xi(L_i^*)\right)$$

Let us first prove inclusion (1):

$$C(\sigma_{n+1}, L_n, \sigma_n, \dots, L_1, \sigma_1) \subseteq \mathrm{cl} \circ \mathrm{conv} \circ \rho(\sigma_{n+1}.L_n^*.\sigma_n \dots L_1^*.\sigma_1) \qquad (1)$$

If $n = 0$, inclusion is immediate. Assume that $n \geq 1$ and let $i \in \{1 \dots n\}$, we have just to show that $\mathbb{R}_-.\Gamma_{\sigma_i\dots\sigma_1} \circ \mathrm{cl} \circ \mathrm{conv} \circ \xi(L_i^*) \subseteq \mathrm{cl} \circ \mathrm{conv} \circ \rho(L)$. Naturally, if $L_i \backslash \{\epsilon\} = \emptyset$, this inclusion is immediate. Otherwise, let $w \in L_i^* \backslash \{\epsilon\}$. For any

$k \in \mathbb{N}$, we have $\sigma_{n+1} \dots \sigma_{i+1}.w^k.\sigma_i \dots \sigma_1 \subseteq L$. From the following equality, we get $\mathbb{R}_-.\Gamma_{\sigma_i \dots \sigma_1} \circ \mathrm{cl} \circ \mathrm{conv} \circ \xi(L_i^*) \subseteq \mathrm{cl} \circ \mathrm{conv} \circ \rho(L)$:

$$\rho(\sigma_{n+1} \dots \sigma_{i+1}.w^k.\sigma_i \dots \sigma_1) = \Gamma_{\sigma_{n+1} \dots \sigma_1}((1 - r^{k.|w|}).\Gamma^{-1}_{\sigma_i \dots \sigma_1}(\xi(w))$$

In particular, we have proved inclusion (1). Let us prove the converse inclusion. Consider a sequence $(w_i)_{1 \leq i \leq n+1}$ such that $w_i \in L_i^* \backslash \{\epsilon\}$. An immediate induction over $n \geq 0$, proves the following equality:

$$\rho(\sigma_{n+2}.w_{n+1}.\sigma_{n+1} \dots w_1.\sigma_1) = \Gamma_{\sigma_{n+1} \dots \sigma_1} \left(\sum_{i=1}^{n+1} r^{|w_{n+1} \dots w_{i+1}|}.(1 - r^{|w_i|}).\Gamma^{-1}_{\sigma_i \dots \sigma_1} \circ \xi(w_i) \right)$$

As $r^{|w_{n+1} \dots w_{i+1}|}.(1 - r^{|w_i|}) \in \mathbb{R}_-$, we deduce the following inclusion:

$$\mathrm{cl} \circ \mathrm{conv} \circ \rho(\sigma_{n+1}.(L_n^* \backslash \{\epsilon\}).\sigma_n \dots (L_1^* \backslash \{\epsilon\}).\sigma_1) \subseteq C(\sigma_{n+1}, L_n, \sigma_n, \dots, L_1, \sigma_1)$$

Naturally, from the previous inclusions taken over $n \geq 0$, we deduce the converse inclusion of (1). $\square$

The previous proposition explains why we are interested in computing $\mathrm{cl} \circ \mathrm{conv} \circ \xi(L^*)$ where L is a regular language. In fact, we have the following lemma.

Lemma 3 *For any $L \subseteq \Sigma^*_{r^m}$, we have* $\mathrm{conv} \circ \xi(L^*) = \mathrm{conv} \circ \xi(L)$.

PROOF. From $L \subseteq L^*$, we deduce the inclusion $\mathrm{conv} \circ \xi(L) \subseteq \mathrm{conv} \circ \xi(L^*)$. Let us prove the converse inclusion. Let $w \in L^* \backslash \{\epsilon\}$. There exists a sequence σ_1, ..., σ_k of $k \geq 1$ words in $L \backslash \{\epsilon\}$ such that $w = \sigma_1 \dots \sigma_k$. An immediate induction over $k \geq 1$ proves the following equality:

$$\xi(\sigma_1 \dots \sigma_k) = \sum_{i=1}^{k} r^{|\sigma_1 \dots \sigma_{i-1}|} \frac{r^{|\sigma_i|} - 1}{r^{|\sigma_1 \dots \sigma_k|} - 1}.\xi(\sigma_i)$$

As $\sum_{i=1}^{k} r^{|\sigma_1 \dots \sigma_{i-1}|} \frac{r^{|\sigma_i|}-1}{r^{|\sigma_1 \dots \sigma_k|}-1} = 1$ and $r^{|\sigma_1 \dots \sigma_{i-1}|} \frac{r^{|\sigma_i|}-1}{r^{|\sigma_1 \dots \sigma_k|}-1} \in \mathbb{R}_-$, we deduce that $\xi(w) \in \mathrm{conv} \circ \xi(L)$. We deduce $\xi(L^*) \subseteq \mathrm{conv} \circ \xi(L)$ and by minimality of the convex hull of $\xi(L^*)$, we get $\mathrm{conv} \circ \xi(L^*) \subseteq \mathrm{conv} \circ \xi(L)$. $\square$

Once again, we use the fact that a regular language L can be decomposed into a finite union of languages of the form $\sigma_{n+1}.L_n^*.\sigma_n.\cdots L_1^*.\sigma_1$.

Proposition 4 *Let us consider a language $L = \sigma_{n+1}.L_n^*.\sigma_n \dots L_1^*.\sigma_1$ where $n \geq 0$, $\sigma_i \in \Sigma^*_{r^m}$ and $L_i \subseteq \Sigma^*_{r^m}$. We have the following equality:*

$$\mathrm{cl} \circ \mathrm{conv} \circ \xi(L) = \mathrm{cl} \circ \mathrm{conv} \left(\xi(\{\sigma_{n+1} \dots \sigma_1\}) \bigcup_{i=1}^{n} \Gamma^{-1}_{\sigma_i \dots \sigma_1} \circ \mathrm{cl} \circ \mathrm{conv} \circ \xi(L_i) \right)$$

PROOF. Let us consider a language L of the form $L = \sigma_2.L_1^*.\sigma_1$ where $\sigma_1, \sigma_2 \in \Sigma_{r^m}^*$ and $L_1 \subseteq \Sigma_{r^m}^*$ and let us prove the proposition for L. Remark that if $L_1\backslash\{\epsilon\} = \emptyset$ or if $\sigma_2.\sigma_1 = \epsilon$, lemma 3 proves the proposition. So, we can assume that $L_1\backslash\{\epsilon\} \neq \emptyset$ and $\sigma_2.\sigma_1 \neq \epsilon$. Let $C = \text{cl} \circ \text{conv}(\xi(\{\sigma_2.\sigma_1\}) \cup \Gamma_{\sigma_1}^{-1} \circ \text{cl} \circ \text{conv} \circ \xi(L_1))$ and consider $\sigma \in L_1\backslash\{\epsilon\}$ and $k \in \mathbb{N}$. We have the following equality:

$$\xi(\sigma_2.\sigma^k.\sigma_1) = \frac{r^{|\sigma_2.\sigma_1|} - 1}{r^{|\sigma_2.\sigma_1|+k.|\sigma|} - 1}.\xi(\sigma_2.\sigma_1) + \frac{r^{|\sigma_2.\sigma_1|}.(r^{k.|\sigma|} - 1)}{r^{|\sigma_2.\sigma_1|+k.|\sigma|} - 1}.\Gamma_{\sigma_1}^{-1}(\xi(\sigma))$$

In particular we deduce that $\Gamma_{\sigma_1}^{-1} \circ \xi(\sigma) \in \text{cl} \circ \xi(\sigma_2.\sigma^*.\sigma_1)$. From $\sigma_2.\sigma^*.\sigma_1 \subseteq L$, we get $\Gamma_{\sigma_1}^{-1} \circ \xi(L_1) \subseteq \text{cl} \circ \xi(L)$. And by minimality of the closure and the convex hull, we get $\Gamma_{\sigma_1}^{-1} \circ \text{cl} \circ \text{conv} \circ \xi(L_1) \subseteq \text{cl} \circ \text{conv} \circ \xi(L)$. From $\sigma_2.\sigma_1 \in L$, we deduce that $\xi(\{\sigma_2.\sigma_1\}) \subseteq \xi(L)$. We obtain $C \subseteq \text{cl} \circ \text{conv} \circ \xi(L)$. Let us prove the converse inclusion. Consider $\sigma \in L$. There exists $w \in L_1^*$ such that $\sigma = \sigma_2.w.\sigma_1$. If $w = \epsilon$ then $\xi(\sigma) = \xi(\sigma_1.\sigma_2) \in C$. Otherwise, lemma 3 proves that $\xi(w) \in \text{conv} \circ \xi(L_1)$. As $\xi(\sigma) = \frac{r^{|\sigma_2.\sigma_1|}-1}{r^{|\sigma_2.\sigma_1|+|w|}-1}.\xi(\sigma_2.\sigma_1) + \frac{r^{|\sigma_2.\sigma_1|}.(r^{|w|}-1)}{r^{|\sigma_2.\sigma_1|+|w|}-1}.\Gamma_{\sigma_1}^{-1}(\xi(w))$, we deduce that $\xi(\sigma) \in C$. We deduce that the other inclusion $\text{cl} \circ \text{conv} \circ \xi(L) \subseteq C$. Therefore, the proposition is proved for L.

Now, assume the proposition proved for an integer $n \geq 1$ and let us consider a language $L = \sigma_{n+2}.L_{n+1}^*.\sigma_{n+1} \ldots L_1^*.\sigma_1$ where $\sigma_i \in \Sigma_{r^m}^*$ and $L_i \subseteq \Sigma_{r^m}^*$ and let us prove the proposition for L. Consider $w_{n+1} \in L_{n+1}^*$. As the proposition is proved for n, we deduce the following equality:

$$\begin{aligned}
&\text{cl} \circ \text{conv} \circ \xi(\sigma_{n+2}.w_{n+1}.\sigma_{n+1}.L_n^*.\sigma_n \ldots L_1^*.\sigma_1) \\
&= \text{cl} \circ \text{conv} \left(\xi(\{\sigma_{n+2}.w_{n+1}.\sigma_{n+1} \ldots \sigma_1\}) \bigcup_{i=1}^{n} \Gamma_{\sigma_i \ldots \sigma_1}^{-1} \circ \text{cl} \circ \text{conv} \circ \xi(L_i) \right)
\end{aligned}$$

We get in particular the following equality:

$$\begin{aligned}
&\text{cl} \circ \text{conv} \circ \xi(\sigma_{n+2}.L_{n+1}^*.\sigma_{n+1}.L_n^*.\sigma_n \ldots L_1^*.\sigma_1) \\
&= \text{cl} \circ \text{conv} \left(\xi(\sigma_{n+2}.L_{n+1}^*.\sigma_{n+1} \ldots \sigma_1\}) \bigcup_{i=1}^{n} \Gamma_{\sigma_i \ldots \sigma_1}^{-1} \circ \text{cl} \circ \text{conv} \circ \xi(L_i) \right) \\
&= \text{cl} \circ \text{conv} \left(\text{cl} \circ \text{conv} \circ \xi(\sigma_{n+2}.L_{n+1}^*.\sigma_{n+1} \ldots \sigma_1) \bigcup_{i=1}^{n} \Gamma_{\sigma_i \ldots \sigma_1}^{-1} \circ \text{cl} \circ \text{conv} \circ \xi(L_i) \right)
\end{aligned}$$

As the proposition is proved in the case $n = 1$, we also get the following equality:

$$\begin{aligned}
&\text{cl} \circ \text{conv} \circ \xi(\sigma_{n+2}.L_{n+1}^*.\sigma_{n+1} \ldots \sigma_1) \\
&= \text{cl} \circ \text{conv} \left(\xi(\{\sigma_{n+2} \ldots \sigma_1\}) \cup \Gamma_{\sigma_{n+1} \ldots \sigma_1}^{-1} \circ \text{cl} \circ \text{conv} \circ \xi(L_{n+1}) \right)
\end{aligned}$$

The two previous equality proved the proposition for L. By induction over $n \geq 1$, we have proved the proposition for any $n \geq 1$. $\square$

We can now prove our main result that extends [Lat04].

Theorem 5 *The convex hull of a regular set of integer vectors $X = \rho(L)$ is polyhedral and a finite set of rays R that represents* $\mathrm{conv}(X)$ *can be computed in exponential time from any regular expression that defines L.*

PROOF. Let C be a polyhedral convex set represented by a finite set of rays R. We know that for any $w \in \Sigma_{r^m}^*$, the convex sets $\Gamma_w(C)$ and $\Gamma_w^{-1}(C)$ are polyhedral and respectively represented by $\{(r^{|w|}.\alpha + c.\rho(w), c);\ (\alpha, c) \in R\}$ and $\{(\alpha - c.\rho(w), r^{|w|}.c);\ (\alpha, c) \in R\}$. Moreover, we also know that the convex set $\mathrm{cl}(\mathbb{R}_-.C)$ is polyhedral and represented by the finite set of rays $\{(0,1)\} \cup \{(-\alpha, 0);\ (\alpha, c) \in R\}$. By applying propositions 2 and 4 and lemma 3 over a regular expression that represents a regular language L, we deduce that $\mathrm{cl} \circ \mathrm{conv} \circ \rho(L)$ is polyhedral and represented by a finite set of rays R computable in exponential time from any regular expression that defines L. $\square$

References

[BB03] Constantinos Bartzis and Tevfik Bultan. Efficient symbolic representations for arithmetic constraints in verification. *International Journal of Foundations of Computer Science (IJFCS)*, 14(4):605–624, August 2003.

[BC96] Alexandre Boudet and Hubert Comon. Diophantine equations, Presburger arithmetic and finite automata. In *Proc. 21st Int. Coll. on Trees in Algebra and Programming (CAAP'96), Linköping, Sweden, Apr. 1996*, volume 1059 of *Lecture Notes in Computer Science*, pages 30–43. Springer, 1996.

[Ber77] Leonard Berman. Precise bounds for Presburger arithmetic and the reals with addition: Preliminary report. In *Proc. 18th IEEE Symp. Foundations of Computer Science (FOCS'77), Providence, RI, USA, Oct.-Nov. 1977*, pages 95–99, Providence, Rhode Island, 31 October–2 November 1977. IEEE.

[BFLP03] Sébastien Bardin, Alain Finkel, Jérôme Leroux, and Laure Petrucci. FAST: Fast Acceleration of Symbolic Transition systems. In *Proc. 15th Int. Conf. Computer Aided Verification (CAV'2003), Boulder, CO, USA, July 2003*, volume 2725 of *Lecture Notes in Computer Science*, pages 118–121. Springer, 2003.

[BHMV94] Véronique Bruyère, Georges Hansel, Christian Michaux, and Roger Villemaire. Logic and p-recognizable sets of integers. *Bull. Belg. Math. Soc.*, 1(2):191–238, March 1994.

[Boi98] Bernard Boigelot. *Symbolic Methods for Exploring Infinite State Spaces*. PhD thesis, Université de Liège, 1998.

[CH78] P. Cousot and N. Halbwachs. Automatic discovery of linear restraints among variables of a program. In *5th ACM Symposium on Principles of Programming Languages, POPL'78*, Tucson (Arizona), January 1978.

[GBD02] Vijay Ganesh, Sergey Berezin, and David L. Dill. Deciding presburger arithmetic by model checking and comparisons with other methods. In *Proc. 4th Int. Conf. Formal Methods in Computer Aided Design (FMCAD'02), Portland, OR, USA, nov. 2002*, volume 2517 of *Lecture Notes in Computer Science*, pages 171–186. Springer, 2002.

[GS66] Seymour Ginsburg and Edwin H. Spanier. Semigroups, Presburger formulas and languages. *Pacific J. Math.*, 16(2):285–296, 1966.

[HPR97] N. Halbwachs, Y.E. Proy, and P. Roumanoff. Verification of real-time systems using linear relation analysis. *Formal Methods in System Design*, 11(2), August 1997.

[Las] LASH homepage. `http://www.montefiore.ulg.ac.be/~boigelot/research/lash/`.

[Lat04] Louis Latour. From automata to formulas: Convex integer polyhedra. In *Proc. 19th Annual IEEE Symposium on Logic in Computer Science (LICS'04), Turku, Finland July 2004*, pages 120–129. IEEE Comp. Soc. Press, 2004.

[Ome] OMEGA homepage. `http://www.cs.umd.edu/projects/omega/`.

[Pre29] M. Presburger. Uber die volstandigkeit eines gewissen systems der arithmetik ganzer zahlen, in welchem die addition als einzige operation hervortritt. In *C. R. 1er congres des Mathematiciens des pays slaves, Varsovie*, pages 92–101, 1929.

[RV02] Tatiana Rybina and Andrei Voronkov. Brain: Backward reachability analysis with integers. In *Proc. 9th Int. Conf. Algebraic Methodology and Software Technology (AMAST'2002), Saint-Gilles-les-Bains, Reunion Island, France, Sep. 2002*, volume 2422 of *Lecture Notes in Computer Science*, pages 489–494. Springer, 2002.

[WB95] Pierre Wolper and Bernard Boigelot. An automata-theoretic approach to Presburger arithmetic constraints. In *Proc. 2nd Int. Symp. Static Analysis (SAS'95), Glasgow, UK, Sep. 1995*, volume 983 of *Lecture Notes in Computer Science*, pages 21–32. Springer, 1995.

[WB00] Pierre Wolper and Bernard Boigelot. On the construction of automata from linear arithmetic constraints. In *Proc. 6th Int. Conf. Tools and Algorithms for the Construction and Analysis of Systems (TACAS'2000), Berlin, Germany, Mar.-Apr. 2000*, volume 1785 of *Lecture Notes in Computer Science*, pages 1–19. Springer, 2000.