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# AN EXAMPLE OF BRUNET-DERRIDA BEHAVIOR FOR A BRANCHING-SELECTION PARTICLE SYSTEM ON $\mathbb Z$

#### JEAN BÉRARD

ABSTRACT. We consider a branching-selection particle system on  $\mathbb{Z}$  with  $N \geq 1$ particles. During a branching step, each particle is replaced by two new particles, whose positions are shifted from that of the original particle by independently performing two random walk steps according to the distribution  $p\delta_1 + (1-p)\delta_0$ , from the location of the original particle. During the selection step that follows, only the N rightmost particles are kept among the 2N particles obtained at the branching step, to form a new population of N particles. After a large number of iterated branching-selection steps, the displacement of the whole population of N particles is ballistic, with deterministic asymptotic speed  $v_N(p)$ . As N goes to infinity,  $v_N(p)$  converges to a finite limit  $v_{\infty}(p)$ . The main result is that, for every 0 , as N goes to infinity, the order of magnitude of the difference $v_{\infty}(p) - v_N(p)$  is  $\log(N)^{-2}$ . This is called Brunet-Derrida behavior in reference to the 1997 paper by E. Brunet and B. Derrida "Shift in the velocity of a front due to a cutoff' (see the reference within the paper), where such a behavior is established for a similar branching-selection particle system, using both numerical simulations and heuristic arguments. The case where  $1/2 \le p < 1$  is briefly discussed.

#### 1. INTRODUCTION

In [4, 5], E. Brunet and B. Derrida studied a branching-selection particle system on  $\mathbb{Z}$  enjoying the following property: as the number N of particles in the system goes to infinity, the asymptotic speed of the population of particles in the system converges to its limiting value at a surprisingly slow rate, of order  $\log(N)^{-2}$ . This behavior was established both by direct numerical simulation of the particle system, and by mathematically non-rigorous arguments of the following type: having a finite population of N particles instead of an infinite number of particles should be more or less equivalent, as far as the asymptotic speed is concerned, to introducing a cutoff value of  $\epsilon = 1/N$ , in the deterministic equations that govern the time-evolution of the distribution of particles in the infinite-population limit. In turn, these equations can be viewed as discrete versions of the well-known F-KPP equations, and the initial problem is thus related to that of assessing the effect of introducing a small cutoff in F-KPP equations, upon the speed of the travelling wave solutions. In turn, this problem was studied by heuristic arguments and computer simulations (see [4, 5]), and rigorous mathematical results for this last problem have recently been obtained, cite [2, 1, 8]. Another approach is based on adding a small whitenoise term with scale parameter  $\sigma^2 = 1/N$  in the Fisher-KPP equation, see [6], and

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rigorous results have been derived for this model too, see [7, 10]. However, to our knowledge, no rigorous results dealing directly with a branching-selection particle system such as the one originally studied by Brunet and Derrida, are available. In this paper, we consider a branching-selection particle system that is similar (but not exactly identical) to the one considered by Brunet and Derrida in [4, 5]. To be specific, we consider a particle system with N particles on  $\mathbb{Z}$  defined through the repeated application of branching and selection steps defined as follows:

- Branching: each of the N particles is replaced by two new particles, whose positions are shifted from that of the original particle by independently performing two random walk steps according to the distribution  $p\delta_1 + (1-p)\delta_0$ , from the location of the original particle;
- Selection: only the N rightmost particles are kept among the 2N obtained at the branching step, to form the new population of N particles.

In Section 3, it is proved that, after a large number of iterated branching-selection steps, the displacement of the whole population of N particles is ballistic, with deterministic asymptotic speed  $v_N(p)$ , and that, as N goes to infinity,  $v_N(p)$  increases to a finite limit  $v_{\infty}(p)$  (which admits a more explicit characterization). The main results concerning the branching-selection particle system are contained in the following two theorems:

**Theorem 1.** For every  $0 , there exists <math>0 < C_*(p) < +\infty$  such that, for all large N,

(1) 
$$v_{\infty}(p) - v_N(p) \ge C_*(p) \log(N)^{-2}$$

**Theorem 2.** For every  $0 , there exists <math>0 < C^*(p) < +\infty$  such that, for all large N,

(2) 
$$v_{\infty}(p) - v_N(p) \le C^*(p) \log(N)^{-2}$$

In the case p = 1/2 or 1/2 , the behavior turns out to be quite different, as stated in the following theorems.

**Theorem 3.** For p = 1/2, there exists  $0 < C_*(1/2) \le C^*(1/2) < +\infty$  such that, for all large N,

(3) 
$$C_*(1/2)N^{-1} \le v_\infty(p) - v_N(p) \le C^*(1/2)N^{-1}$$

**Theorem 4.** For p > 1/2, there exists  $0 < C_*(p) \le C^*(p) < +\infty$  such that, for all large N,

(4) 
$$C_*(p)N \le -\log(v_{\infty}(p) - v_N(p)) \le C^*(p)N.$$

The rest of the paper is organized as follows. In Section 2, we provide the precise notations and definitions that are needed in the sequel. Section 3 contains a discussion of various elementary properties of the model we consider. Section 4 contains the proof of Theorem 1, while Section 5 contains the proof of Theorem 2. The proofs of Theorems 3 and 4 are sketched in Section 6. Section 7 contains some concluding remarks.

#### 2. NOTATIONS AND DEFINITIONS

Throughout the paper, p denotes a fixed parameter in ]0, 1/2[. Since the particles we consider carry no other information than their position, it is convenient to represent finite populations of particles by finite counting measures on  $\mathbb{Z}$ . For all  $N \ge 1$ , let  $\mathcal{C}_N$  denote the set of finite counting measures on  $\mathbb{Z}$  with total mass equal to N, and  $\mathcal{C}$  the set of all finite counting measures on  $\mathbb{Z}$ .

For  $\nu \in \mathcal{C}$ , the total mass of  $\nu$  (i.e. the number of particles in the population it describes) is denoted by  $M(\nu)$ . We denote by max  $\nu$  and min  $\nu$  respectively the maximum and minimum of the (finite) support of  $\mu$ . We also define the diameter  $d(\nu) := \max \nu - \min \nu$ . Given two positive measures  $\mu, \nu$  on  $\mathbb{Z}$ , we use the notation  $\mu \leq \nu$  to denote the fact that  $\mu(x) \leq \nu(x)$  for every  $x \in \mathbb{Z}$ . On the other hand, we use the notation  $\prec$  to denote the stochastic order between positive measures:  $\mu \prec \nu$ if and only if  $\mu([x, +\infty[) \leq \nu([x, +\infty[) \text{ for all } x \in \mathbb{Z}$ . In particular,  $\mu \prec \nu$  implies that  $M(\mu) \leq M(\nu)$ , and it is easily seen that, if  $\mu = \sum_{i=1}^{M(\mu)} \delta_{x_i}$  and  $\nu = \sum_{i=1}^{M(\nu)} \delta_{y_i}$ , with  $x_1 \geq \cdots \geq x_{M(\mu)}$  and  $y_1 \geq \cdots \geq y_{M(\nu)}, \ \mu \prec \nu$  is equivalent to  $x_i \leq y_i$  for all  $1 \leq i \leq M(\nu)$ . From the order  $\prec$  on  $\mathcal{C}$ , we define the corresponding stochastic order on probability measures on  $\mathcal{C}$  and denote it by  $\prec \prec$ : given two probability measures Q and R on  $\mathcal{C}, \ Q \prec \prec R$  means that for every bounded non-decreasing function  $f : (\mathcal{C}, \prec) \to \mathbb{R}, \ Q(f) \leq R(f)$ . An equivalent definition is that there exists a pair of random variables  $(X, Y), \ X$  and Y taking values in  $\mathcal{C}$ , such that  $X \rightsquigarrow Q, \ Y \rightsquigarrow R$ , and  $X \prec Y$  with probability one.

In this context, the dynamics of our particle systems can be defined through the following probability kernels. Let us first define the branching kernel  $p_N^{Br}$  on  $\mathcal{C}_N \times \mathcal{C}_{2N}$  as follows. Given  $\nu = \sum_{i=1}^N \delta_{x_i} \in \mathcal{C}_N$ ,  $p_N^{Br}(\nu, \cdot)$  is the probability distribution of  $\sum_{i=1}^N \delta_{x_i+Y_{1,i}} + \delta_{x_i+Y_{2,i}} \in \mathcal{C}_{2N}$ , where  $(Y_{\ell,i})_{1 \leq i \leq N, \ell=1,2}$  is a family of i.i.d. Bernoulli random variables with common distribution  $p\delta_1 + (1-p)\delta_0$ . Then, we define the selection kernel  $p_N^{Sel.}$  on  $\mathcal{C}_{2N} \times \mathcal{C}_N$  as follows. Starting from  $\nu = \sum_{i=1}^{2N} \delta_{x_i} \in \mathcal{C}_{2N}$ , where  $x_1 \geq \cdots \geq x_{2N}$ ,  $p_N^{Sel.}(\nu, \cdot)$  is the Dirac distribution concentrated on the counting measure  $\sum_{i=1}^N \delta_{x_i}$ .

The kernel  $p_N$  on  $\mathcal{C}_N \times \mathcal{C}_N$  governing the evolution of particle systems with N particles is then defined as the product kernel  $p_N := p_N^{Br} p_N^{Sel}$ .

In the sequel, we use the notation  $(X_n^N)_{n\geq 0}$  to denote a Markov chain on  $\mathcal{C}_N$ whose transition probabilities are given by  $p_N$ , and which starts at  $X_0^N := N\delta_0$ . We assume this Markov chain is defined on a reference probability space denoted by  $(\Omega, \mathcal{F}, \mathbb{P})$ .

Let  $\sim_N$  denote the equivalence relation on  $\mathcal{C}_N$  defined by  $\nu \sim_N \mu$  if and only if there exists  $m \in \mathbb{Z}$  such that  $\nu$  is the image measure of  $\mu$  by the translation of  $\mathbb{Z}$  $x \mapsto x + m$ . Let  $\pi_N$  denote the canonical projection from  $\mathcal{C}_N$  to  $\mathcal{C}_N / \sim_N$ .

#### 3. Elementary properties of the model

**Proposition 1.** For all  $1 \leq N_1 \leq N_2$ , and  $\mu \in C_{N_1}$  and  $\nu \in C_{N_2}$  such that  $\mu \prec \nu$ ,  $p_{N_1}(\mu, \cdot) \prec \neq p_{N_2}(\nu, \cdot)$ .

Proof. The proof is by coupling. Let  $\mu = \sum_{i=1}^{N_1} \delta_{x_i}$  and  $\nu = \sum_{i=1}^{N_2} \delta_{y_i}$ , with  $x_1 \geq \cdots \geq x_{N_1}$  and  $y_1 \geq \cdots \geq y_{N_2}$  such that  $x_i \leq y_i$  for all  $1 \leq i \leq N_1$ . Let  $(Y_{\ell,i})_{1 \leq i \leq N_2}$ ,  $\ell=1,2$  denote a family of i.i.d. Bernoulli random variables with common distribution  $p\delta_1 + (1-p)\delta_0$ . By definition, the couting measure defined by  $\mu_{Br.} := \sum_{i=1}^{2N_1} \delta_{x_i+Y_{1,i}} + \delta_{x_i+Y_{2,i}}$  has the distribution  $\mu p_{N_1}^{Br.}$ , and  $\nu_{Br.} := \sum_{i=1}^{2N_2} \delta_{y_i+Y_{1,i}} + \delta_{y_i+Y_{2,i}}$  has the distribution  $\mu p_{N_2}^{Br.}$ . It is easily checked that  $\mu_{Br.} \prec \nu_{Br.}$ , owing to the fact that  $x_i + Y_{\ell,i} \leq y_i + Y_{\ell,i}$  for all  $1 \leq i \leq N_1$  and  $\ell = 1, 2$ . We deduce that  $\mu p_{N_1}^{Br.} \prec \mu p_{N_2}^{Br.}$ . Then, it is obvious from the definition that  $p_{N_1}^{Sel.}$  and  $p_{N_2}^{Sel.}$  preserve  $\prec \prec$ .  $\Box$ 

**Proposition 2.** For all  $N \ge 1$ , and all  $n \ge 0$ ,  $d(X_n^N) \le \lceil \frac{\log(N)}{\log(2)} \rceil + 1$  with probability one.

*Proof.* Let  $m := \lceil \frac{\log(N)}{\log(2)} \rceil + 1$ . The result is obvious for  $n = 0, \ldots, m$ , since we perform 0 or 1 random walk steps starting from an initial condition where all particles are at the origin. Now consider n > m, and let  $y = \max X_{n-m}^N$ . Assume first that  $\min X_k^N < y$  for all  $n + 1 - m \le k \le n$ . Since all the random walk steps that are performed during branching steps are  $\ge 0$ , this implies that all the particles descended by branching from a particle located at y at time n - m, are preserved by the selection steps performed from  $X_{n-m}^N$  to  $X_n^N$ . Since there are  $2^m > N$  such particles, this is a contradiction. As a consequence, we know that there must be an index  $n + 1 - m \le k \le n$  such that  $\min X_k^N \ge y$ . Since by construction  $t \mapsto \min X_t^N$  is non-decreasing, we deduce that  $\min X_n^N \ge y$ . Now, since all the random walk steps that are performed add 0 or 1 to the current position of a particle, we see from the definition of y that  $\max X_n^N \le y + m$ . As a consequence,  $d(X_n^N) = \max X_{n-m}^N - \min X_{n-m}^N \le m$ . □

**Proposition 3.** For all  $N \geq 1$ , the kernel  $p_N$  is compatible with the canonical projection  $\pi_N$ , that is: for all  $\nu_1, \nu_2 \in C_N$  such that  $\nu_1 \sim_N \nu_2$ , and all  $\xi \in C_N / \sim_N$ ,  $p_N(\nu_1, \pi_N^{-1}(\xi)) = p_N(\nu_2, \pi_N^{-1}(\xi))$ .

*Proof.* Immediate: everything in the definition of the branching and selection steps is translation-invariant.  $\Box$ 

**Proposition 4.** For all  $N \ge 1$ , the sequence  $\pi_N(X_n^N)_{n\ge 0}$  is an ergodic Markov chain on a finite subset of  $C_N/\sim_N$ .

Proof. The fact that  $\pi_N(X_n^N)_{n\geq 0}$  forms a Markov chain on  $\mathcal{C}_N/\sim_N$  is an immediate consequence of Proposition 3. Let  $\mathcal{S}_N := \{\xi \in \mathcal{C}_N/\sim_N; \exists n \geq 0, \mathbb{P}(\pi_N(X_n^N) = \xi) > 0\}$ . From Proposition 2, we see that  $\mathcal{S}_N$  is in fact a finite set. On the other hand, given any  $\xi \in \mathcal{S}_N$ , it is quite easy to find a finite path in  $\mathcal{S}_N$  starting at  $\xi$  and ending at  $\pi_N(N\delta_0)$  that has positive probability. As a consequence, the restriction of  $\pi_N(X_n^N)_{n\geq 0}$  to  $\mathcal{S}_N$  is an irreducible Markov chain. As for aperiodicity, the transition  $\pi_N(N\delta_0) \mapsto \pi_N(N\delta_0)$  has e.g. a positive probability.  $\Box$ 

**Corollary 1.** There exists  $0 < v_N(p) < +\infty$  such that, with probability one, and in  $L^1(\mathbb{P})$ ,

$$\lim_{n \to +\infty} n^{-1} \min X_n^N = \lim_{n \to +\infty} n^{-1} \max X_n^N = v_N(p).$$

*Proof.* Note that, in view of Proposition 2, if the two limits in the above statement exist, they must be equal. Then observe that, for all  $n \ge 0$ , conditionally upon  $X_n^N$ , the distributions of the increments  $\max X_{n+1}^N - \max X_n^N$  and  $\min X_{n+1}^N - \min X_n^N$  depend only on  $\pi_N(X_n^N)$ . The result then follows by a classical argument using the law of large numbers for additive functionals of ergodic Markov chains.

**Proposition 5.** The sequence  $(v_N(p))_{N\geq 1}$  is non-decreasing.

*Proof.* Consequence of the fact that, when  $N_1 \leq N_2$ ,  $N_1\delta_0 \prec N_2\delta_0$ , and of the monotonicity property 1.

We can deduce from the above proposition that there exists  $0 < v_{\infty}(p) < +\infty$  such that  $\lim_{N \to +\infty} v_N(p) = v_{\infty}(p)$ . A consequence of the proofs of Theorems 1 and 2 below is that  $v_{\infty}(p)$  is in fact equal to the number v(p) characterized as the unique root of the equation  $\Lambda(x) = \log(2)$ , where  $x \in [0, 1]$  is the unknown, and where  $\Lambda$  is the large deviations rate function associated with sums of i.i.d Bernoulli(p) random variables, i.e.  $\Lambda(x) := x \log(x/p) + (1-x) \log(\frac{1-x}{1-p})$  for  $x \in [0, 1]$ . We note for future use that p < v(p) < 1 since  $p \in ]0, 1/2[$ .

#### 4. The upper bound

The essential arguments used here in the proof of the upper bound, are largely borrowed from the paper [11] by R. Pemantle, which deals with the closely related question of obtaining complexity bounds for algorithms that seek near optimal paths in branching random walks. In fact, the proof of Theorem 1 given below is basically a rewriting of the proof of the lower complexity bound in [11] in the special case of algorithms that do not jump, with the slight difference that we are dealing with N independent branching random walks being explored in parallel, rather than a single branching random walk.

To explain the connexion between our model and the branching random walk, consider the following model. Let  $BRW_1, \ldots, BRW_N$  denote N independent branching random walks, each with value zero at the root, deterministic binary branching, and i.i.d. displacements with common distribution  $p\delta_1 + (1-p)\delta_0$  along each edge. For  $1 \leq i \leq N$ , and  $n \geq 0$ , let  $BRW_i(n)$  denote the set of vertices of  $BRW_i$  located at depth n in the tree, and let  $T_n := BRW_1(n) \cup \cdots \cup BRW_N(n)$ . For every n, fix an a priori (i.e. depending only on the tree structure, not on the random walk values) total order on  $T_n$ . We now define by induction a sequence  $(G_n)_{n\geq 0}$  of subsets such that, for each  $n \geq 0$ ,  $G_n$  is a random subset of  $T_n$  with exactly N elements. First, let us set  $G_0 := T_0$ . Then, given  $n \geq 0$  and  $G_n$ , let  $H_n$  denote the subset of T(n+1) formed by the children of the vertices in  $G_n$ . Then, define  $G_{n+1}$  as the subset of  $H_n$  formed by the N vertices that are associated with the largest values of the underlying random walk (breaking ties by using the a priori order on  $T_n$ ). It is now quite obvious that, for every  $n \geq 0$ , the (random) empirical distribution of the N random walk values associated with the vertices in  $G_n$  has the same distribution as  $X_n^N$ .

Given a branching random walk BRW of the type defined above, and one of its vertices u, we use the notation Z(u) to denote the value of the random walk associated with u. The following definition is adapted from [11]. Given 0 < v < 1 and

 $m \geq 1$ , we say that a vertex  $u \in BRW$  is (m, v)-good if there is a descending path  $u =: u_0, u_1, \ldots, u_m$  such that  $Z(u_i) - Z(u_0) \geq vi$  for all  $i \in [0, m]$ . The importance of this definition comes from the two following lemmas, adapted from [11].

**Lemma 1.** (Lemma 5.2 in [11]) Let  $0 < v_1 < v_2 < 1$ . If there exists a vertex  $u \in BRW$  at depth n such that  $Z(u) \ge v_2n$ , then the path from the root to u must contain at least  $\frac{v_2-v_1}{n}\frac{n}{m}-1/(1-v_1)$  vertices that are  $(m,v_1)$ -good.

**Lemma 2.** (Proposition 2.6 in [11]) There is a constant  $\psi > 0$  such that, given a branching random walk BRW, the probability that the root is  $(m, v(p) - m^{-2/3})$ -good is less than  $\exp(-\psi m^{1/3})$ .

Since Lemma 1 admits so short a proof, we reproduce it below for the sake of completeness. On the other hand, to give a very rough idea where the  $\exp(-\psi m^{1/3})$  in Lemma 2 comes from, let us just mention that it corresponds to the probability that a random walk remains confined in a tube of size  $m^{1/3}$  around its mean, for m time steps. Dividing the m steps into  $m^{1/3}$  intervals of size  $m^{2/3}$ , we see that this amounts to asking for the realization of  $m^{1/3}$  independent events, each of which has a probability of order a constant, by the usual Brownian scaling.

Proof of Lemma 1. (From [11].) Consider a vertex u as in the statement of the lemma. Consider the descending path  $root =: x_0, \ldots, x_n := u$  from the root to u. Let then  $\tau_0 := 0$ , and, given  $\tau_i$ , define inductively  $\tau_{i+1} := \inf\{j \ge \tau_i + 1; Z(x_j) < Z(x_{\tau_i}) + v_1(j - \tau_i) \text{ or } j = \tau_i + m\}$ . Now color  $x_0, \ldots, x_{n-1}$  according to the following rules: if  $Z(x_{\tau_{i+1}}) \ge Z(x_{\tau_i}) + v_1(j - \tau_i)$  and  $\tau_{i+1} \le n+1$ , then  $x_{\tau_i}, \ldots, x_{\tau_{i+1}-1}$  are colored red. Note that this yields a segment of m red vertices, and that  $x_{\tau_i}$  is then  $(m, v_1)$ -good. Otherwise,  $x_{\tau_i}, \ldots, x_{\tau_{i+1}-1}$  are colored blue. Let  $V_{red}$  (resp.  $V_{blue}$ ) denote the number of red (resp. blue) vertices in  $x_0, \ldots, x_{n-1}$ . Then decompose Z(u) into the contributions of the red and blue vertices. On the one hand, the contribution of red vertices is  $\le V_{red}$ . On the other, the contribution of blue vertices is  $\le V_{blue} \times v_1 + m$ , where the m is added to take into account a possible last segment colored in blue only because it has reached depth n. Writing that  $n = V_{red} + V_{blue}$ , we deduce that  $v_2n \le V_{red} + v_1(n - V_{red}) + m$ , so that  $V_{red} \ge \frac{v_2 - v_1}{1 - v_1}n - m/(1 - v_1)$ . Then use the fact that at least  $V_{red}/m$  vertices are  $(m, v_1)$ -good.

In [11], Lemmas 1 and 2 are used in combination with an elaborate second moment argument. In the present context, the following quite simple first moment argument turns out to be sufficient.

Proof of Theorem 1. Consider an integer  $r \geq 1$ , and let  $m := r \lfloor \log(N)^3 \rfloor$ . Let  $n \geq m$ , and let  $B_n$  denote the number of vertices in BRW<sub>1</sub>  $\cup \cdots$  BRW<sub>N</sub> that are  $(m, v(p) - 2m^{-2/3})$ -good (each with respect to the BRW it belongs to) and belong to  $G_0 \cup \cdots \cup G_n$ . From Lemma 1 and the definition of  $(G_i)_{i\geq 0}$ , we see that the fact that at least one vertex in  $G_n$  has a value larger than  $(v(p) - m^{-2/3})n$  implies that, for large n (depending on m),  $B_n \geq nm^{-5/3}$ . On the other hand,  $B_n$  can be written

as(5)

$$B_n := \sum_{u \in \text{BRW}_1 \cup \dots \text{BRW}_N} \mathbf{1}(\ u \text{ is } (m, v(p) - 2m^{-2/3}) - \text{good}) \mathbf{1}(u \in G_0 \cup \dots \cup G_n).$$

Now observe that, by definition, for a vertex u of depth  $\ell$ , by definition, the event  $u \in G_0 \cup \cdots \cup G_n$  is measurable with respect to the random walk steps performed up to depth  $\ell$ , while the event that u is  $(m, v(p) - 2m^{-2/3})$ -good is measurable with respect to the random walk steps performed starting from depth  $\geq \ell$ . As a consequence, these two events are independent. Since the total number of vertices in  $G_0 \cup \cdots \cup G_n$  is equal to N(n + 1), we deduce from Lemma 2 and (5) that  $E(B_n) \leq N(n + 1) \exp(-\psi m^{1/3})$ . Using Markov's inequality, and letting n go to infinity, we deduce that

$$\limsup_{n \to +\infty} P(B_n \ge nm^{-5/3}) \le Nm^{5/3} \exp(-\psi m^{1/3}).$$

Now, remembering that  $P(B_n) = \mathbb{P}(\max X_n^N \ge (v(p) - m^{-2/3})n)$ , and using the fact that  $\max X_n^N \le n$  with probability one, we finally deduce that

$$\limsup_{n \to +\infty} n^{-1} E(\max X_n^N) \le v(p) - m^{-2/3} + Nm^{5/3} \exp(-\psi m^{1/3}).$$

Choosing r large enough in the definition of m makes the third term in the above r.h.s. negligible with respect to the second term, as N goes to infinity. The conclusion follows.

#### 5. The lower bound

The proof of the lower bound on the convergence rate of  $v_N(p)$  to  $v_{\infty}(p)$  is in some sense a rigorous version of the heuristic argument of Brunet and Derrida according to which we should compare the behavior of the particle system with N particles, with a version of the infinite population limit modified by a cutoff at  $\epsilon = 1/N$ .

Indeed, given a finite positive measure  $\nu$  on  $\mathbb{Z}$ , let  $F^{Br.}(\nu)$  be the measure defined by:  $F^{Br.}(\nu) := 2\nu \star (p\delta_1 + (1-p)\delta_0)$ . This  $F^{Br.}$  describes the evolution of the distribution of particles in the infinite population limit above the threshold imposed by the selection step. The idea of the proof of the lower bound is to control the discrepancy between the finite and infinite population models above this threshold. One important observation is that, to prove a lower bound, one does not necessarily have to control the number of particles at every site, but may focus instead on sites where the probability of finding a particle is not too small.

We note the following two immediate properties of  $F^{Br.}$ : if  $\mu \leq \nu$ , then  $F^{Br.}(\mu) \leq F^{Br.}(\nu)$ , and, if  $g \in \mathbb{R}_+$ ,  $F^{Br.}(g\nu) = gF^{Br.}(\nu)$ .

5.1. Admissible sequences of measures. Throughout this section, we consider  $\epsilon > 0, \ 0 < \alpha < v(p), \ \beta > 1$ , and  $m \ge q := \lceil \frac{v(p)}{1 - v(p)} \rceil$ .

We say that a (deterministic) sequence  $\delta_0 =: \nu_1, \ldots, \nu_m$  of positive measures on  $\mathbb{Z}$  with finite support, is  $(\epsilon, \alpha, \beta)$ -admissible, if the following properties hold:

(i)  $\nu_i = (2p)^i \delta_i$  for  $0 \le i \le q$ ;

- (ii) for all  $q + 1 \le i \le m, \nu_i \le F^{Br}(\nu_{i-1});$
- (iii) for all  $0 \le i \le m-1$ , and all  $x \in \mathbb{Z}$  such that  $\nu_i(x) > 0$ ,  $\nu_i(x) \ge \epsilon$ ;
- (iv) for all  $q \leq i \leq m-1$ , the support of  $\nu_i$  is contained in the interval  $[(v(p) \alpha)(i+1), +\infty];$
- (v)  $\nu_m(\mathbb{Z}) \ge \beta + 1$ .

Note that the definition of q makes property (iv) automatic for i = q.

Let  $B := {\min(X_i^N) < (v(p) - \alpha)i \text{ for all } 1 \le i \le m}$ . The interest of admissible sequences of measures lies in the possibility of bounding  $\mathbb{P}(B)$  from above, as explained in the following lemma.

**Lemma 3.** Consider an  $(\epsilon, \alpha, \beta)$ -admissible sequence  $\nu_0, \ldots, \nu_m$ . Let  $K := \sum_{i=0}^{m-1} \# supp(\nu_i)$ , and  $\delta := 1 - \exp\left(-\frac{\log(\beta)}{m}\right)$ . Then the following inequality holds:

$$\mathbb{P}(B) \le 2K \exp\left(-N\beta^{-1}\epsilon p\delta^2\right).$$

Before proving the above lemma, we recall the following classical estimate for binomial random variables (see e.g. [9]):

**Lemma 4.** Let  $n \ge 1$  and 0 < r < 1, and let Z be a binomial(n, r) random variable. Then, for all  $0 < \delta < 1$ , the probability that  $Z \le (1-\delta)nr$  is less than  $\exp(-\frac{1}{2}nr\delta^2)$ .

Proof of Lemma 3. For  $k \in [0, m]$ , let  $A_k := \bigcap_{n \in [1,k]} \{X_n^N \ge N(1-\delta)^n \nu_n\}$ . Note that  $A_0$  is the certain event. For  $0 \le k \le m-1$ , and  $x \in \mathbb{Z}$ , define  $N_k^1(x)$  (resp.  $N_k^0(x)$ ) to be the number of particles that are created from a particle at position x in  $X_k^N$  during the branching step applied to  $X_k^N$ , and that have a position equal to x+1 (resp. x). By definition, conditional upon  $X_0^N, \ldots, X_k^N, N_k^1(x)$  (resp.  $N_k^0(x)$ ) follows a binomial distribution with parameters  $(2X_k^N(x), p)$  (resp.  $(2X_k^N(x), 1-p))$ ). For  $k \in [0, m-1]$ , let  $C_k := \{N_k^\ell(x) \ge (1-\delta)2X_k^N(x)p; \ x \in \operatorname{supp}(\nu_k), \ \ell = 0, 1\}$ . Note that, by definition of  $\delta$ ,  $(1-\delta)^k \ge \beta^{-1}$  for all  $0 \le k \le m$ . In view of condition (iii), we deduce that, for  $k \in [1, m, \text{ on } A_{k-1}, X_{k-1}^N(x) \ge N\beta^{-1}\epsilon$  for all  $x \in \operatorname{supp}(\nu_{k-1})$ . As a consequence, Lemma 4 yields the fact that

(6) 
$$\mathbb{P}(A_{k-1} \cap C_{k-1}^c) \le 2\# \operatorname{supp}(\nu_{k-1}) \exp\left(-N\beta^{-1}\epsilon p\delta^2\right),$$

where we have used the union bound and the fact that  $p \leq 1 - p$  to combine the bounds given by Lemma 4 for all the  $N_{k-1}^{\ell}(x)$ , with  $\ell \in \{0,1\}$ , and  $x \in \operatorname{supp}(\nu_{k-1})$ . Now consider  $k \in [\![1,q]\!]$ . On B, all the particles counted by  $N_{k-1}^1(k-1)$  must be kept after the selection step leading to  $X_k^N$ , since  $k \geq (v(p) - \alpha)k$ . As a consequence,  $X_k^N(k) \geq N_{k-1}^1(k-1)$ , and we deduce that

(7) 
$$A_{k-1} \cap C_{k-1} \cap B \subset A_k.$$

Assume now that  $k \in [[q+1,m]]$ . If *B* holds, we see that, according to (iv), for all *x* in the support of  $\nu_{k-1}$ , the particles counted by  $N_{k-1}^1(x)$  and  $N_{k-1}^0(x)$  are all kept after the selection step leading to  $X_k^N$ . As a consequence, on  $C_{k-1}$ ,  $X_k^N \ge$  $(1-\delta)F^{Br}(X_{k-1}^N\mathbf{1}(\operatorname{supp}(\nu_{k-1})))$ , so that, on  $B \cap A_{k-1} \cap C_{k-1}$ ,  $X_k^N \ge (1-\delta)^k \nu_k$ , since  $X_{k-1}^N \ge (1-\delta)^{k-1}\nu_{k-1}$  and  $\nu_k \le F^{Br}(\nu_{k-1})$  by assumption (ii). We deduce

that (8)

$$) A_{k-1} \cap C_{k-1} \cap B \subset A_k.$$

Now observe that, on  $A_m$ , one must have  $X_m^N(\mathbb{Z}) \geq N(1-\delta)^m \nu_m(\mathbb{Z}) \geq N\beta^{-1}\nu_m(\mathbb{Z}) > N$ , a contradiction, so that  $A_m = \emptyset$ . From (7), (8), we deduce that  $\mathbb{P}(B) \leq \sum_{k=0}^{m-1} \mathbb{P}(A_{k-1} \cap C_{k-1}^c)$ , and, using (6), we deduce the result.  $\Box$ 

Let us now relate the above results with estimates on  $v_N(p)$ . Define the random variable  $L := \inf\{1 \le i \le m; \min(X_i^N) \ge (v(p) - \alpha)i\}$ , with the convention that  $\inf \emptyset := m.$ 

#### **Proposition 6.** For all $0 , for all <math>N \ge 1$ ,

$$v_N(p) \ge (v(p) - \alpha)(1 - m\mathbb{P}(B)).$$

*Proof.* We define a modified branching-selection process  $(Y_n^N)_{n\geq 0}$ , composed of a succession of runs. Start with  $L_0 := 0$  and  $H_0 := 0$ , and i := 0, and do the following.

- 1) Set  $Z_0^N := N \delta_{H_i}$  and k := 0.
- 2) Do the following:
- $\{ \text{ let } k := k + 1 \text{ and generate } Z_k^N \text{ from the distribution } p_N(Z_{k-1}^N, \cdot). \}$   $3) \text{ Return to 2) until } k = m \text{ or } \min Z_k^N \ge (v(p) \alpha)k + H_i.$   $4) \text{ Set } L_{i+1} := L_i + k \text{ and } H_{i+1} := \min Z_k^N$   $5) \text{ Set } (Y_{L_i}^N, \dots, Y_{L_{i+1}-1}^N) := (Z_0^N, \dots, Z_{k-1}^N)$  6) Let i := i + 1 or d actume to 1) for the set i = 1

- 6) Let i := i + 1 and return to 1) for the next run.

One may describe the above process as follows: starting from a reference position  $H_i$  and a reference time index  $L_i$ , a run behaves like the original branchingselection process until either m steps have been performed or the minimum value in the population of particles exceeds the reference position by an amount of at least  $(v(p) - \alpha)$  times the number of steps performed since the beginning of the run. Then the current population of N particles is collapsed onto its minimum position, the reference position is updated to this minimum position, and the time index to the current time, and a new run is started. Our modified process has a natural regeneration structure yielding the fact that the sequences  $(L_{i+1}-L_i)_{i\geq 0}$  and  $(H_{i+1}-H_i)$  are i.i.d. The common distribution of the  $L_{i+1}-L_i$ is that of L, while the common distribution of the  $H_{i+1} - H_i$  is that of min  $X_L^N$ . From the fact that  $\min Y_{L_i}^N \geq H_i$ , it is easy to deduce that, with probability From the fact that  $\min Y_{L_i}^N \geq \pi_i$ , it is easy to deduce that, i.e., if  $Y_{L_i}^N \geq \pi_i$  one,  $\lim_{n \to +\infty} n^{-1} \min Y_n^N = \frac{\mathbb{E}(\min X_L^N)}{\mathbb{E}(L)}$ , and, since  $0 \leq n^{-1}Y_n^N \leq 1$ , we also have that  $\lim_{n \to +\infty} n^{-1}\mathbb{E}(\min Y_n^N) = \frac{\mathbb{E}(\min X_L^N)}{\mathbb{E}(L)}$ . Now, by definition,  $\min X_L^N \geq (v(p) - \alpha)L\mathbf{1}(B^c)$ , so that  $\mathbb{E}(\min X_L^N) \geq (v(p) - \alpha)(\mathbb{E}(L) - \mathbb{E}(L\mathbf{1}(B)))$ . Using the fact that  $1 \leq L \leq m$ , we obtain that  $\frac{\mathbb{E}(\min X_L^N)}{\mathbb{E}(L)} \geq (v(p) - \alpha)(1 - m\mathbb{P}(B))$ .

Now, it should be intuitively obvious that the modified process  $(Y_n^N)_{n\geq 0}$  is in some sense a lower bound for the original process  $(X_n^N)_{n\geq 0}$ , since we modify the original dynamics in a way that can only lower positions of particles. It is in fact an easy consequence of Proposition 1 that, for all n, the distribution of  $Y_n^N$  is stochastically

dominated by that of  $X_n^N$ . A consequence is that  $\mathbb{E}(\min Y_n^N) \leq \mathbb{E}(\min X_n^N)$ . The result follows.

5.2. Construction of an admissible sequence of measures. Let A denote an integer  $\geq 4$ , and  $m \geq q$ . Then let  $a_m := \lfloor m^{1/3} \rfloor$ ,  $c_m := \lfloor m^{2/3} \rfloor$ ,  $s_m := \lfloor \frac{a_m}{2(1-v(p))} \rfloor$ . Define  $d_m$  by  $d_m(k) := k$  for  $k \in \llbracket 1, s_m \rrbracket$ , and  $d_m(k) := v(p)k + a_m$  for  $k \in \llbracket s_m + 1, m \rrbracket$ . Define  $g_m$  by  $g_m(k) := k$  for  $k \in \llbracket 1, s_m \rrbracket$ ,  $g_m(k) := v(p)(k+1)$  for  $k \in \llbracket s_m + 1, m - c_m \rrbracket$ . and  $g_m(k) := v(p)k - Aa_m$  for  $k \in \llbracket m - c_m + 1, m \rrbracket$ .

Then define a sequence of measures  $(\nu_i)_{i \in [0,m]}$  on  $\mathbb{Z}$  as follows. Let  $(S_i)_{i \in [0,m]}$ denote a simple random walk on  $\mathbb{Z}$  starting at zero, with step distribution  $p\delta_1 + (1-p)\delta_0$ , governed by a probability measure P, then let

$$\nu_i(x) := 2^i P[g_m(k) \le S_k \le d_m(k) \text{ for all } k \in [0, i]], S_i = x].$$

The main result in this section is the following:

**Proposition 7.** For large enough A, there exists  $\chi(A) > 0$  such that, for all large enough m, the above sequence is  $(\exp(-\chi(A)m^{1/3}, 2Am^{-2/3}, 2008)$ -admissible.

We need to establish several results before we can prove the above proposition. First, consider the modified probability measure  $\hat{P}$  defined by

$$\frac{d\hat{P}}{dP} := \left(\frac{v(p)}{p}\right)^{S_m} \left(\frac{1-v(p)}{1-p}\right)^{m-S_m}$$

With respect to  $\hat{P}$ ,  $(S_i)_{i \in [0,m]}$  is a simple random walk on  $\mathbb{Z}$  starting at zero, with step distribution  $v(p)\delta_1 + (1 - v(p))\delta_0$ .

We now rewrite  $\nu_i(x)$  in terms of this change of measure. To this end, introduce the compensated random walk defined by  $\hat{S}_i := S_i - v(p)i$ , let also  $\hat{g}_m(k) := g_m(k) - v(p)k$  and  $\hat{d}_m(k) := d_m(k) - v(p)k$ . Finally, let  $\gamma := \frac{p/(1-p)}{v(p)/(1-v(p))}$ , and note that  $\gamma < 1$  since p < v(p). After a little algebra involving the definition of v(p) in terms of  $\Lambda$ , we obtain the following expression:

(9) 
$$\nu_i(x) = \hat{E}\left[\gamma^{\hat{S}_i} \mathbf{1}\left(\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k) \text{ for all } k \in [[0, i]], S_i = x\right)\right],$$

where  $\hat{E}$  denotes expectation with respect to  $\hat{P}$ . From the definition of  $\hat{g}_m$  and  $\hat{d}_m$ , we see that, for large m, the only values of  $\hat{S}_i$  that contribute in the above expectation are  $\leq m^{1/3}$ . As a consequence,

(10) 
$$\nu_i(x) \ge \gamma^{m^{1/3}} \hat{P}\left[\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k) \text{ for all } k \in [[0, i]], S_i = x\right],$$

**Lemma 5.** For some constant  $\zeta_1 > 0$ , as m goes to infinity,

$$\hat{P}\left[\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k) \text{ for all } k \in [[0,m]]\right] \ge \exp(-\zeta_1 m^{1/3}).$$

We need an elementary lemma before the proof of Lemma 5.

**Lemma 6.** Consider a random walk  $(Z_i)_{i\geq 0}$  on  $\mathbb{R}$ , defined by  $Z_i := Z_0 + \varepsilon_1 + \cdots + \varepsilon_i$ for  $i \geq 1$ . Assume that the increments  $\varepsilon_i$  are *i.i.d.* with respect to some probability measure Q and satisfy  $E(\varepsilon_1) = 0$  and  $0 < Var(\varepsilon_1) < +\infty$ . Then there exists  $\lambda > 0$  such that, for all m large enough, on the event that  $a_m/3 \leq Z_0 \leq 2a_m/3$ ,

(11)  $Q[v \le Z_i \le a_m; i \in [[0, c_m]], a_m/3 \le Z_{c_m} \le 2a_m/3 | Z_0] \ge \lambda,$ 

(12) 
$$Q[a_m/4 \le Z_i \le 3a_m/4; \ i \in [[0, c_m]] | Z_0] \ge \lambda.$$

Proof of Lemma 6. We use the convergence of the distribution of the random process  $(M_t^m)_{t\in[0,1]}$  defined by  $M_0^m := 0$ ,  $M_{i/c_m}^m = a_m^{-1}(\varepsilon_1 + \cdots + \varepsilon_i)$  for  $i \in [\![1, c_m]\!]$ , and interpolated linearly on each  $[i/c_m, (i+1)/c_m]$  towards the Brownian motion (on the space of real-valued continuous functions on [0, 1] equipped with the sup norm). An easy consequence is that there exists  $\lambda_1 > 0$  such that, for all large m,

 $Q[-a_m/7 \le Z_i - Z_0 \le a_m/7; i \in [[1, c_m]], 0 \le Z_{c_m} - Z_0 \le a_m/7] \ge \lambda_1.$ 

This estimate proves (11) when  $Z_0$  belongs to  $[a_m/3, a_m/2]$ . A symmetric argument works when  $Z_0$  belongs to  $[a_m/2, 2a_m/3]$ . The proof of (12) is quite similar.

Proof of Lemma 5. First note that, for all large enough m,  $a_m/3 \leq s_m - v(p)s_m \leq 2a_m/3$ . Then,

$$\hat{P}\left[\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k); \ k \in [[0, s_m]]\right] = v(p)^{s_m}$$

Divide the interval  $[\![s_m + 1, m]\!]$  into consecutive intervals  $I_j$ ,  $j \in [\![1, h_m]\!]$ , where each  $I_j$  for  $j \in [\![1, h_m - 1]\!]$  is of the form  $I_j := [\![s_m + 1 + (j - 1)c_m, s_m + 1 + jc_m]\!]$ , while the last interval is  $I_{h_m} := [\![s_m + 1 + (h_m - 1)c_m, m]\!]$ , whose length is less than or equal to  $c_m$ . For  $i \in [\![1, h_m]\!]$ , let  $b_{m,j-1}$  and  $b_{m,j}$  be defined by  $I_j = [\![b_{m,j-1}, b_{m,j}]\!]$ . Now, for  $i \in [\![1, h_m - 1]\!]$ , define the event  $\Gamma_i := \left\{ v \leq \hat{S}_k \leq a_m; \ k \in I_i, \ a_m/3 \leq Z_{b_{m,i}} \leq 2a_m/3 \right\}$ , and let  $\Gamma_{h_m} := \left\{ a_m/4 \leq \hat{S}_k \leq 3a_m/4; \ k \in I_{h_m} \right\}$ .

It is easily checked that, given that  $S_{s_m} = s_m$ ,

$$\bigcap_{i \in [\![1,h_m]\!]} \Gamma_i \subset \bigcap_{k \in [\![s_m+1,m]\!]} \{\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k)\}.$$

Thanks to Lemma 6 and to the Markov property of  $\hat{Z}$  with respect to  $\hat{P}$ , we deduce that

$$\hat{P}\left[\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k); \ k \in \llbracket 0, m \rrbracket\right] \ge v(p)^{s_m} \lambda^{h_m}$$

(We use exactly Lemma 6 for intervals  $I_i$  with  $i \in [\![1, h_m - 1]\!]$ , while, for  $i = h_m$ , we use that fact that the length of  $I_j$  is  $\leq c_m$ , whence the fact that the conditional probability of  $\Gamma_{h_m}$  given  $\hat{S}_0, \ldots, \hat{S}_{b_{m,h_m-1}}$  is larger than or equal to the probability appearing in (12) in Lemma 6.) Using the fact that  $h_m \sim m^{1/3}$  for large m, the conclusion follows.

**Lemma 7.** There exists  $\zeta_2(A) > 0$  such that, as m goes to infinity,

$$\inf\{\nu_i(x); i \in [0, m-1]], \nu_i(x) > 0\} \ge \exp(-\zeta_2(A)m^{1/3}).$$

We need the following lemma before giving the proof.

**Lemma 8.** Let  $\rho, \sigma \in \mathbb{R}$ , with  $\rho + 1 < \sigma$ ,  $v \in ]0, 1[$  and, let  $\ell$  be an integer such that  $\sigma + \ell v < \rho + \ell$  and  $\rho + v\ell > \sigma$ . Then, for all  $x \in \mathbb{Z} \cap [\rho, \sigma]$ , and all  $y \in \mathbb{Z} \cap [\rho + v\ell, \sigma + v\ell]$ , there exists a sequence  $x =: x_0, x_1, \ldots, x_\ell := y$  such that  $x_{i+1} - x_i \in \{0, 1\}$  for all  $i \in [0, \ell - 1]$ , and  $\rho + vi \leq x_i \leq \sigma + vi$  for all  $i \in [0, \ell]$ .

Proof of Lemma 8. Consider  $x \in \mathbb{Z} \cap [\rho, \sigma]$ , and  $y \in \mathbb{Z} \cap [\rho + v\ell, \sigma + v\ell]$ . Define inductively the sequence  $(\tau_i, h_i)_{i \geq 0}$  as follows. Let  $\tau_0 := x, h_0 := x$ . Our assumption that  $\rho + 1 < \sigma$  guarantees that x or x + 1 belongs to  $[\rho + v, \sigma + v]$ . If x + 1 belongs to  $[\rho + v, \sigma + v]$ , then let d := 0. Otherwise, let d := 1. Then, consider  $i \geq 1$ . If i + d is even, let  $\tau_i := \max\{j \in [\tau_{i-1} + 1, +\infty[; h_{i-1} \geq \rho + vj]\}$ , and let  $h_i := h_{i-1}$ . If i + d is odd, let  $\tau_i := \max\{j \in [[\tau_{i-1} + 1, +\infty[; h_{i-1} + j - \tau_{i-1} \leq \sigma + vj]\}$ , and let  $h_i := h_{i-1} + \tau_i - \tau_{i-1}$ .

The fact that and  $\rho + 1 < \sigma$  and  $v \in ]0, 1[$  guarantees that every term in the sequence is finite. Define the sequence  $(z_k)_{k\geq 0}$  by  $z_k := h_{i-1}$  for  $k \in [[\tau_{i-1}, \tau_i]]$  when i + d is even, and  $z_k := h_{i-1} + k - \tau_{i-1}$  for  $k \in [[\tau_{i-1}, \tau_i]]$  when i + d is odd. Our assumptions yield the fact that  $\rho + vk \leq z_k \leq \sigma + vk$  for all  $k \geq 0$ . Now note that, if  $y = z_m$ , the path  $z_0, \ldots, z_m$  solves our problem. If  $y > z_m$ , the assumption that  $\rho + \ell > \sigma + v\ell$  plus elementary geometric considerations show that there must be some  $k \in [[0, m-1]]$  such that  $y - x_k = \ell - k$ . From the path  $x_0, \ldots, x_k$ , add +1 steps and stop at length  $\ell$ . The corresponding path solves the problem. Now, if  $y < z_m$ , our assumption that  $\sigma < \rho + v\ell$  plus elementary geometric considerations show that  $\tau_k = y$ . From the path  $x_0, \ldots, x_k$ , add +0 steps and stop at length  $\ell$ . The corresponding path solves the problem.

Proof of Lemma 7. In the sequel, let  $x_k := k$  for  $k \in [[0, s_m]]$ , and note that, for large enough  $m, g_m(k) \le x_k \le d_m(k)$  for all  $k \in [[0, s_m]]$ .

Let  $\alpha > \max(v(p)^{-1}, (1 - v(p))^{-1})$ , and let  $f_m := \lfloor \alpha a_m \rfloor$ . For  $i \in [\![s_m + 1, s_m + 2f_m]\!]$ , and x in the support of  $\nu_i$ , there must by definition be a sequence  $s_m := x_{s_m}, \ldots, x_i := x$  such that  $x_{j+1} - x_j \in \{0, 1\}$  and  $g_m(j) \le x_j \le d_m(j)$  for all  $j \in [\![s_m, i]\!]$ . As a consequence, for every  $i \in [\![0, s_m + 2f_m]\!]$  and  $x \in \operatorname{supp}(\nu_i)$ ,

(13) 
$$\hat{P}[S_k = x_k; k \in [[0, i]], S_i = x] \ge (\min(v(p), 1 - v(p))^{s_m + 2f_m}.$$

Now assume that  $i \in [\![s_m+2f_m+1, m-c_m]\!]$ , and consider the distribution of  $S_{i-f_m}$ with respect to  $\hat{P}$ , conditional upon  $g_m(k) \leq S_k \leq d_m(k)$  for all  $k \in [\![0, i-f_m]\!]$ . This probability distribution is concentrated on the set  $\mathbb{Z} \cap [g_m(i-f_m), d_m(i-f_m)]$ , which contains at most  $a_m$  elements. Consequently, there exists  $u \in \mathbb{Z} \cap [g_m(i-f_m), d_m(i-f_m)]$  $f_m), d_m(i-f_m)$ ] such that

$$\hat{P}\left[S_{i-f_m} = u | g_m(k) \le S_k \le d_m(k); \ k \in [[0, i - f_m]] \ge 1/a_m.$$

Now let x belong to the support of  $\nu_i$ . By definition,  $x \in \mathbb{Z} \cap [g_m(i), d_m(i)]$ . In view of the definition of  $\alpha$ , we see that, for all m large enough, we can apply Lemma 8 to obtain the existence of a sequence  $u =: x_{i-f_m}, \ldots, x_i := x$  such that  $x_{j+1} - x_j \in \{0, 1\}$  and  $g_m(j) \leq x_j \leq d_m(j)$  for all  $j \in [[i - f_m, i]]$ . Thanks to the Markov property of

 $(S_k)_{k>0}$  with respect to  $\hat{P}$ , we deduce that

$$\hat{P}[g_m(k) \le S_k \le d_m(k); \ k \in [[0, i]], \ S_i = x]$$

is larger than or equal to

$$\hat{P}[g_m(k) \le S_k \le d_m(k), \ k \in [[0, i - f_m]]] (1/a_m)(\min(v(p), 1 - v(p))^{f_m})$$

From Lemma 5, we have that, for m large enough,

$$P[g_m(k) \le S_k \le d_m(k), \ k \in [[0,m]]] \ge \exp(-\zeta_1 m^{1/3}),$$

so that, for every  $i \in [\![s_m + 2f_m + 1, m - c_m]\!]$ ,

(14) 
$$\hat{P}[g_m(k) \le S_k \le d_m(k), \ k \in [0, i]], \ S_i = x] \ge \exp(-\zeta_1 m^{1/3}) \times (1/a_m)(\min(v(p), 1 - v(p))^{f_m}.$$

For  $i \in [m - c_m + 1, m - c_m + 2(A + 1)f_m]$ , any x in the support of  $\nu_i(x)$  is such that there exists u in the support of  $\nu_{m-c_m}$  and a sequence  $u =: x_{m-c_m}, \ldots, x_i := x$  such that  $x_{j+1} - x_j \in \{0, 1\}$  and  $g_m(j) \leq x_j \leq d_m(j)$  for all  $j \in [m - c_m, i]$ . As a consequence,

$$\hat{P}[g_m(k) \le S_k \le d_m(k); \ k \in [[0, i]], \ S_i = x]$$

is larger than or equal to

$$\dot{P}[g_m(k) \le S_k \le d_m(k); \ k \in [[0, m - c_m]], \ S_{m-c_m} = u] \times (\min(v(p), 1 - v(p))^{2(A+1)f_m}.$$

Using (14), we deduce that, for every  $i \in [m - c_m + 1, m - c_m + 2(A + 1)f_m],$ 

(15) 
$$\hat{P}[g_m(k) \le S_k \le d_m(k); k \in [[0, i]], S_i = x] \ge \exp(-\zeta_1 m^{1/3}) \times (1/a_m)(\min(v(p), 1 - v(p))^{(2(A+1)+1)f_m}.$$

Then an argument quite similar to that leading to (14) yields that, for any  $i \in [m - c_m + 2(A+1)f_m + 1, m]$ ,

(16) 
$$\hat{P}[g_m(k) \le S_k \le d_m(k); \ k \in [[0, i]], \ S_i = x] \ge \exp(-\zeta_1 m^{1/3}) \times (1/((A+1)a_m+1))(\min(v(p), 1-v(p))^{(A+1)f_m}.$$

The conclusion follows by using (10) and (13), (14), (15), (16).

**Lemma 9.** There exists  $\phi(A) > 0$  such that, as m goes to infinity,

$$\hat{P}\left[\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k); \ k \in [[0,m]], \ \hat{S}_m \le -(A/2)a_m\right] \ge \phi(A)\exp(-\zeta_1 m^{1/3}).$$

We shall need the following elementary lemma.

**Lemma 10.** Consider a random walk  $(Z_i)_{i\geq 0}$  on  $\mathbb{R}$ , defined by  $Z_i := Z_0 + \varepsilon_1 + \cdots + \varepsilon_i$ for  $i \geq 1$ . Assume that the increments  $\varepsilon_i$  are i.i.d. with respect to some probability measure Q and satisfy  $E(\varepsilon_1) = 0$  and  $0 < Var(\varepsilon_1) < +\infty$ . Then there exists  $\phi(A) > 0$  such that, for all m large enough, on the event  $a_m/4 \leq Z_0 \leq 3a_m/4$ ,

$$Q[-Aa_m \le Z_i \le a_m; i \in [[1, c_m]], Z_{c_m} \le -(A/2)a_m | Z_0] \ge \phi(A).$$

Proof of Lemma 10. We re-use the notations of the proof of Lemma 6. The only point is to note that, by convergence to the Brownian motion, there exists  $\phi(A) > 0$  such that for all large m,

$$Q\left[-3Aa_m/4 \le Z_i - Z_0 \le a_m/4; \ i \in [[1, c_m]], \ Z_{c_m} - Z_0 \le -(A/2 + 3/4)a_m\right] \ge \phi(A).$$

The result follows easily (using the fact that A is assumed to be  $\geq 4$ ).

Proof of Lemma 9. From the proof of Lemma 5, we see that

$$\hat{P}\left[g_m(k) \le S_k \le d_m(k); k \in [[0, m - c_m]], a_m/4 \le \hat{S}_{m - c_m} \le 3a_m/4\right] \ge \exp(-\zeta_1 m^{1/3}).$$

Then, by Lemma 10, as m goes to infinity,

$$\hat{P}\left[\hat{g}_{m}(k) \leq \hat{S}_{k} \leq \hat{d}_{m}(k); k \in [\![m-c_{m}+1,m]\!], \hat{S}_{m} \leq -Aa_{m}/2 \middle| a_{m}/4 \leq \hat{S}_{m-c_{m}} \leq 3a_{m}/4 \right]$$

is larger than or equal to  $\phi(A)$ . The conclusion follows.

Proof of Proposition 7. Properties (i) and (ii) are immediate consequences of the definition. Property (iii) is a direct consequence of Lemma 7, letting  $\chi(A) := \zeta_2(A)$ . From the definition,  $g_m(k) \ge v(p)(k+1)$  for all  $k \in [\![q, m-c_m]\!]$ . Then, given A, for all large enough m, it is easily checked that  $g_m(k) \ge (v(p) - 2Am^{-2/3})(k+1)$  for all  $k \in [\![m-c_m+1,m]\!]$ . This yields Property (iv). As for Property (v), consider (9). Clearly, since  $\gamma < 1$ ,

$$\nu_m(\mathbb{Z}) \ge \gamma^{-(A/2)a_m} \hat{P}\left[\hat{g}_m(k) \le \hat{S}_k \le \hat{d}_m(k); \ k \in [\![0,m]\!], \ \hat{S}_m \le -(A/2)a_m\right].$$

From Lemma 9, the probability in the r.h.s. of the above expression is  $\geq \phi(A) \exp(-\zeta_1 m^{1/3})$ , so that, choosing A large enough, the term  $\gamma^{-(A/2)a_m}$  dominates for large m. As a consequence, for such an A,  $\nu_m(\mathbb{Z}) \geq 2008 + 1$  as soon as m is large enough.

Proof of Theorem 2. Consider a parameter  $\theta > 0$ , and let *m* depend on *N* in the following way:  $m := \lfloor \theta \log(N) \rfloor^3$ . For *N* large enough, we can apply Proposition 7, and use Lemma 3, which states that

$$\mathbb{P}(B) \le 2K \exp\left(-N\beta^{-1}\epsilon p\delta^2\right).$$

It is easily checked from the definition that  $K \leq ((A+1)a_m+1)m$ . Note also that  $\delta \sim \log(\beta)/m$  for large N. Finally,  $\epsilon = \exp(-\chi(A)m^{1/3})$ . Choosing  $\theta$  small enough, we check that  $m\mathbb{P}(B) \ll m^{-2/3}$  as N goes to infinity. Proposition 6 then implies that  $v_N(p) \geq v(p) - 2Am^{-2/3}(1+o(1))$ . The result follows.

#### 6. The case $1/2 \le p < 1$

In the case  $1/2 \le p < 1$ , it turns out that  $v_{\infty}(p) = v(p) = 1$ , which makes it much easier to obtain estimates.

6.1. Upper bound when p = 1/2. It is easily checked that, for all  $m \ge 0$ , the number of particles at position exactly m after m steps, that is,  $X_m^N(m)$ , is stochastically dominated by the total population at the m-th generation of a family of N independent Galton-Watson trees, with offspring distribution binomial(2, 1/2). This corresponds to the critical case of Galton-Watson trees, and the probability that such a tree survives up to the m-th generation is  $\le cm^{-1}$  for some constant c > 0 and all large m. As a consequence, for large enough m,  $\mathbb{P}(X_m^N(m) \ge 1) \le \mathbb{E}(X_m^N(m)) \le cNm^{-1}$ .

On the other hand, we have by definition that  $m^{-1}\mathbb{E}\max(X_m^N) \leq 1 - \frac{1}{m}\mathbb{P}(X_m^N(m) = 0)$ . Choosing m := AN, where  $A \geq 1$  is an integer, we see that, for large  $N, m^{-1}\mathbb{E}\max(X_m^N) \leq 1 - 1/AN(1 - c/A)$ . The upper bound in (3) follows by choosing A > c.

6.2. Lower bound when p = 1/2. Given  $m \ge 1$ , define  $U := \inf\{n \in [\![1,m]\!]; X_n^N(n) \le 2N/3\}$ , with the convention that  $\inf \emptyset := m$ . Let D denote the event that  $\min X_U^N < U - 1$ .

Using an argument similar to the proof of Proposition 6, with U and D in place of L and B respectively, we deduce that

(17) 
$$v_N(p) \ge 1 - \frac{1}{\mathbb{E}(D)} - m\mathbb{P}(D).$$

The lower bound in (3) is then a consequence of the two following claims.

Our first claim is that there exists c > 0 such that  $\mathbb{P}(D) \leq \exp(-cN)$  for all large N. Recall the definition of  $N_k^{\ell}(x)$  from the proof of Lemma 3, and choose  $\delta$ small enough so that  $(1 - \delta)4N/3 > N$ . It is easily seen that  $D \subset \{N_{U-1}^1(U-1) \leq (1 - \delta)2N/3\} \cup \{N_{U-1}^0(U-1) \leq (1 - \delta)2N/3\}$ . Now, by definition, one has that  $X_{U-1}^N(U-1) \geq 2N/3$ , so that, by the bound of Lemma 4, conditional on  $X_{U-1}^N$ , the probabilities of  $N_{U-1}^1(U-1) \leq (1 - \delta)2N/3$  and  $N_{U-1}^0(U-1) \leq (1 - \delta)2N/3$  are both  $\leq \exp(-c(\delta)N)$ . The bound on  $\mathbb{P}(D)$  follows.

Our second claim is that, for small enough  $\epsilon > 0$ , with  $m := \lfloor \epsilon N \rfloor$ , there exists  $c(\epsilon) > 0$  such that  $\mathbb{E}(D) \ge c(\epsilon)N$  for all large N. To prove it, introduce the Markov chains  $(V_k)_{k\ge 0}$  and  $(Z_k)_{k\ge 0}$  on  $\mathbb{N}$ , defined as follows. First,  $V_0 \in \mathbb{N}$ , and, given  $V_0, \ldots, V_k$ , the next term  $V_{k+1}$  is the minimum of N and of a random variable with a binomial  $(2V_k, 1/2)$  distribution. On the other hand,  $Z_0 \in \mathbb{N}$ , and, given  $Z_0, \ldots, Z_k$ , the distribution of  $Z_{k+1}$  is binomial  $(2Z_k, 1/2)$ . Observe that the sequence  $(X_n^N(n))_{n\ge 0}$  is a version of V started at  $V_0 := N$ . Now, it is easily seen that, given two starting points  $x, y \in \mathbb{N}$  such that  $x \le y$ , one can couple two versions of V starting from x and y respectively, in such a way that the version starting from y is always above the version starting from x. As a consequence, U stochastically dominates the random variable  $T := \inf\{n \in [\![1,m]\!]; V_n \le 2N/3\}$  (again with  $\inf \emptyset := m$ ), where V is started at  $V_0 := \lfloor 3N/4 \rfloor$ . Then observe that the distributions of V and Z started with  $V_0 := Z_0 := \lfloor 3N/4 \rfloor$ , considered up to the hitting time of  $[\![N, +\infty[\!], \text{coincide}]$ . As a consequence, the probabilities of the events  $\{\sup_{k\in [\![0,m]\!]} |V_k - \lfloor 3N/4 \rfloor| \ge N/16\}$  and  $\{\sup_{k\in [\![0,m]\!]} |Z_k - \lfloor 3N/4 \rfloor| \ge N/16\}$  coincide, and the first of these two events implies

that T = m. Now,  $(Z_k)_{k\geq 0}$  is a martingale, so that, by Doob's maximal inequality,  $P\left(\sup_{k\in[0,m]} |Z_k - \lfloor 3N/4 \rfloor| \geq N/16\right) \leq E(Z_m - \lfloor 3N/4 \rfloor)^2 (N/16)^{-2}$ . Then, it is easily checked from the definition that  $E(Z_{k+1}^2|Z_k) = Z_k^2 + Z_k/2$ , and, using again the fact that  $(Z_k)_{k\geq 0}$  is a martingale, we deduce that  $E(Z_m - \lfloor 3N/4 \rfloor)^2 \leq mN/2$ . As a consequence, we see that, choosing  $\epsilon > 0$  small enough, we can ensure that  $P\left(\sum_{k\in[0,\lfloor\epsilon N\rfloor]} |Z_k - \lfloor 3N/4 \rfloor| \geq N/16\right) \leq 1/2008$  for all large N. For such an  $\epsilon$ , and all N large enough, we thus have that  $\mathbb{P}(U = m) \geq P(T = m) \geq 1/2008$ . The conclusion follows.

6.3. Upper and lower bound when  $1/2 . As for the upper bound, observe that asking all the 2N particles generated during the branching step to remain at the position from which they are originated has a probability equal to at most <math>(1-p)^{2N}$ , so that  $\mathbb{E}(\max X_n) \leq n(1-(1-p)^{2N})$ . As for the lower bound, observe that, starting from N particles at a site, the number of particles generated from these during a branching step and that perform +1 random walk steps has a binomial(2N, p) distribution, whose expectation is 2pN, with 2p > 1. Using the bound stated in Lemma 4, we see that the probability for this number to be less than N is  $\leq \exp(-cN)$  for some c > 0. As a consequence,  $\mathbb{E}(\min X_n) \geq n(1-\exp(-cN))$ .

#### 7. Concluding Remarks

**Remark 1.** Can we derive a reasonably simple explanation of how the  $\log(N)^{-2}$  arises, based on the mathematical proofs presented above ? Broadly speaking, the key point in both the upper and the lower bound seems to be the following (we re-use some notations from Section 5): consider a large integer m and look for a scale  $\Delta$  such that

(18) 
$$2^m P(|\hat{S}_1|, \dots, |\hat{S}_m| \propto \Delta) \asymp 1/N.$$

In view of the change of measure, and of the fact that, by Brownian scaling,  $\hat{P}(|\hat{S}_1|,\ldots,|\hat{S}_m| \propto \Delta) \simeq \exp(-m/\Delta^2)$ , we see that there are two factors involved in the above probability:  $\gamma^{\pm \Delta}$ , and  $\exp(-m/\Delta^2)$ . Equating the exponential scales of these two factors yields  $\Delta \propto m^{1/3}$ , and (18) then implies that  $m \propto \log(N)^3$ , whence an average velocity shift over the m steps of order  $\Delta/m \propto \log(N)^{-2}$ .

**Remark 2.** What we have proved is that the order of magnitude of  $v_N(p) - v_{\infty}(p)$  is indeed  $\log(N)^{-2}$ . It would of course be quite interesting to get more precise asymptotic results for this quantity, since there is at least compelling numerical evidence that  $v_N(p) - v_{\infty}(p) \sim c(p) \log(N)^{-2}$  for some constant c.

**Remark 3.** Both the upper and lower bound presented here relie upon controlling the behavior of the particle system for time intervals of length  $m \propto \log(N)^3$ . This is the same order of magnitude as the one observed for the coalescence times of the genealogical process underlying the branching-selection algorithm, from empirical studies and heuristic arguments (see e.g. [3]). Although we do not know how to establish a rigorous relationship between these facts, this at least provides another indication that the  $\log(N)^3$  time scale is particularly relevant for the study of these systems.

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