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AN EXAMPLE OF BRUNET-DERRIDA BEHAVIOR FOR A BRANCHING-SELECTION PARTICLE SYSTEM ON \mathbb{Z}

JEAN BÉRARD

ABSTRACT. We consider a branching-selection particle system on \mathbb{Z} with $N \geq 1$ particles. During a branching step, each particle is replaced by two new particles, whose positions are shifted from that of the original particle by independently performing two random walk steps according to the distribution $p\delta_1 + (1-p)\delta_0$, from the location of the original particle. During the selection step that follows, only the N rightmost particles are kept among the $2N$ particles obtained at the branching step, to form a new population of N particles. After a large number of iterated branching-selection steps, the displacement of the whole population of N particles is ballistic, with deterministic asymptotic speed $v_N(p)$. As N goes to infinity, $v_N(p)$ converges to a finite limit $v_\infty(p)$. Our main result is that, for every $0 < p < 1/2$, as N goes to infinity, the order of magnitude of the difference $v_\infty(p) - v_N(p)$ is $\log(N)^{-2}$. This is called Brunet-Derrida behavior in reference to the 1997 paper by E. Brunet and B. Derrida "Shift in the velocity of a front due to a cutoff" (see the reference within the paper), where such a behavior is established for a similar branching-selection particle system, using both numerical simulations and heuristic arguments.

1. INTRODUCTION

In [4, 5], E. Brunet and B. Derrida studied a branching-selection particle system on \mathbb{Z} enjoying the following property: as the number N of particles in the system goes to infinity, the asymptotic speed of the population of particles in the system converges to its limiting value at a surprisingly slow rate, of order $\log(N)^{-2}$. This behavior was established both by direct numerical simulation of the particle system, and by mathematically non-rigorous arguments of the following type: having a finite population of N particles instead of an infinite number of particles should be more or less equivalent, as far as the asymptotic speed is concerned, to introducing a cutoff value of $\epsilon = 1/N$, in the deterministic equations that govern the time-evolution of the distribution of particles in the infinite-population limit. In turn, these equations can be viewed as discrete versions of the well-known F-KPP equations, and the initial problem is thus related to that of assessing the effect of introducing a small cutoff in F-KPP equations, upon the speed of the travelling wave solutions. In turn, this problem was studied by heuristic arguments and computer simulations (see [4, 5]), and rigorous mathematical results for this last problem have recently been obtained, cite [2, 1, 8]. Another approach is based on adding a small white-noise term with scale $\epsilon = 1/N$ in the Fisher-KPP equation, see [6], and rigorous results have been

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derived for this model too, see [7, 10]. However, to our knowledge, no rigorous results dealing directly with a branching-selection particle system such as the one originally studied by Brunet and Derrida, are available. In this paper, we consider a branching-selection particle system that is similar (but not exactly identical) to the one considered by Brunet and Derrida in [4, 5]. To be specific, we consider a particle system with N particles on \mathbb{Z} defined through the repeated application of branching and selection steps defined as follows:

- Branching: each of the N particles is replaced by two new particles, whose positions are shifted from that of the original particle by independently performing two random walk steps according to the distribution $p\delta_1 + (1-p)\delta_0$, from the location of the original particle;
- Selection: only the N rightmost particles are kept among the $2N$ obtained at the branching step, to form the new population of N particles.

In Section 3, it is proved that, after a large number of iterated branching-selection steps, the displacement of the whole population of N particles is ballistic, with deterministic asymptotic speed $v_N(p)$, and that, as N goes to infinity, $v_N(p)$ increases to a finite limit $v_\infty(p)$ (which admits a more explicit characterization). Our main results are contained in the following two theorems:

Theorem 1. *For every $0 < p < 1/2$, there exists $0 < C_*(p) < +\infty$ such that, for all large N ,*

$$(1) \quad v_\infty(p) - v_N(p) \geq C_*(p) \log(N)^{-2}$$

Theorem 2. *For every $0 < p < 1/2$, there exists $0 < C^*(p) < +\infty$ such that, for all large N ,*

$$(2) \quad v_\infty(p) - v_N(p) \leq C^*(p) \log(N)^{-2}$$

The rest of the paper is organized as follows. In Section 2, we provide the precise notations and definitions that are needed in the sequel. Section 3 contains a discussion of various elementary properties of the model we consider. Section 4 contains the proof of Theorem 1, while Section 5 contains the proof of Theorem 2. Section 6 contains some concluding remarks.

2. NOTATIONS AND DEFINITIONS

Throughout the paper, p denotes a fixed parameter in $]0, 1/2[$. Since the particles we consider carry no other information than their position, it is convenient to represent finite populations of particles by finite counting measures on \mathbb{Z} . For all $N \geq 1$, let \mathcal{C}_N denote the set of finite counting measures on \mathbb{Z} with total mass equal to N , and \mathcal{C} the set of all finite counting measures on \mathbb{Z} .

For $\nu \in \mathcal{C}$, the total mass of ν (i.e. the number of particles in the population it describes) is denoted by $M(\nu)$. We denote by $\max \nu$ and $\min \nu$ respectively the maximum and minimum of the (finite) support of μ . We also define the diameter $d(\nu) := \max \nu - \min \nu$. Given two positive measures μ, ν on \mathbb{Z} , we use the notation $\mu \leq \nu$ to denote the fact that $\mu(x) \leq \nu(x)$ for every $x \in \mathbb{Z}$. On the other hand, we use the notation \prec to denote the stochastic order between positive measures: $\mu \prec \nu$

if and only if $\mu([x, +\infty[) \leq \nu([x, +\infty[)$ for all $x \in \mathbb{Z}$. In particular, $\mu \prec \nu$ implies that $M(\mu) \leq M(\nu)$, and it is easily seen that, if $\mu = \sum_{i=1}^{M(\mu)} \delta_{x_i}$ and $\nu = \sum_{i=1}^{M(\nu)} \delta_{y_i}$, with $x_1 \geq \dots \geq x_{M(\mu)}$ and $y_1 \geq \dots \geq y_{M(\nu)}$, $\mu \prec \nu$ is equivalent to $x_i \leq y_i$ for all $1 \leq i \leq M(\nu)$. From the order \prec on \mathcal{C} , we define the corresponding stochastic order on probability measures on \mathcal{C} and denote it by $\prec\prec$: given two probability measures Q and R on \mathcal{C} , $Q \prec\prec R$ means that for every bounded non-decreasing function $f : (\mathcal{C}, \prec) \rightarrow \mathbb{R}$, $Q(f) \leq R(f)$. An equivalent definition is that there exists a pair of random variables (X, Y) , X and Y taking values in \mathcal{C} , such that $X \rightsquigarrow Q$, $Y \rightsquigarrow R$, and $X \prec Y$ with probability one.

In this context, the dynamics of our particle systems can be defined through the following probability kernels. Let us first define the branching kernel $p_N^{Br.}$ on $\mathcal{C}_N \times \mathcal{C}_{2N}$ as follows. Given $\nu = \sum_{i=1}^N \delta_{x_i} \in \mathcal{C}_N$, $p_N^{Br.}(\nu, \cdot)$ is the probability distribution of $\sum_{i=1}^N \delta_{x_i+Y_{1,i}} + \delta_{x_i+Y_{2,i}} \in \mathcal{C}_{2N}$, where $(Y_{\ell,i})_{1 \leq i \leq N, \ell=1,2}$ is a family of i.i.d. Bernoulli random variables with common distribution $p\delta_1 + (1-p)\delta_0$. Then, we define the selection kernel $p_N^{Sel.}$ on $\mathcal{C}_{2N} \times \mathcal{C}_N$ as follows. Starting from $\nu = \sum_{i=1}^{2N} \delta_{x_i} \in \mathcal{C}_{2N}$, where $x_1 \geq \dots \geq x_{2N}$, $p_N^{Sel.}(\nu, \cdot)$ is the Dirac distribution concentrated on the counting measure $\sum_{i=1}^N \delta_{x_i}$.

The kernel p_N on $\mathcal{C}_N \times \mathcal{C}_N$ governing the evolution of particle systems with N particles is then defined as the product kernel $p_N := p_N^{Br.} p_N^{Sel.}$.

In the sequel, we use the notation $(X_n^N)_{n \geq 0}$ to denote a Markov chain on \mathcal{C}_N whose transition probabilities are given by p_N , and which starts at $X_0^N := N\delta_0$. We assume this Markov chain is defined on a reference probability space denoted by $(\Omega, \mathcal{F}, \mathbb{P})$.

Let \sim_N denote the equivalence relation on \mathcal{C}_N defined by $\nu \sim_N \mu$ if and only if there exists $m \in \mathbb{Z}$ such that ν is the image measure of μ by the translation of \mathbb{Z} $x \mapsto x + m$. Let π_N denote the canonical projection from \mathcal{C}_N to \mathcal{C}_N / \sim_N .

3. ELEMENTARY PROPERTIES OF THE MODEL

Proposition 1. *For all $1 \leq N_1 \leq N_2$, and $\mu \in \mathcal{C}_{N_1}$ and $\nu \in \mathcal{C}_{N_2}$ such that $\mu \prec \nu$, $p_{N_1}(\mu, \cdot) \prec\prec p_{N_2}(\nu, \cdot)$.*

Proof. The proof is by coupling. Let $\mu = \sum_{i=1}^{N_1} \delta_{x_i}$ and $\nu = \sum_{i=1}^{N_2} \delta_{y_i}$, with $x_1 \geq \dots \geq x_{N_1}$ and $y_1 \geq \dots \geq y_{N_2}$ such that $x_i \leq y_i$ for all $1 \leq i \leq N_1$. Let $(Y_{\ell,i})_{1 \leq i \leq N_2, \ell=1,2}$ denote a family of i.i.d. Bernoulli random variables with common distribution $p\delta_1 + (1-p)\delta_0$. By definition, the counting measure defined by $\mu_{Br.} := \sum_{i=1}^{2N_1} \delta_{x_i+Y_{1,i}} + \delta_{x_i+Y_{2,i}}$ has the distribution $\mu p_{N_1}^{Br.}$, and $\nu_{Br.} := \sum_{i=1}^{2N_2} \delta_{y_i+Y_{1,i}} + \delta_{y_i+Y_{2,i}}$ has the distribution $\nu p_{N_2}^{Br.}$. It is easily checked that $\mu_{Br.} \prec \nu_{Br.}$, owing to the fact that $x_i + Y_{\ell,i} \leq y_i + Y_{\ell,i}$ for all $1 \leq i \leq N_1$ and $\ell = 1, 2$. We deduce that $\mu p_{N_1}^{Br.} \prec\prec \nu p_{N_2}^{Br.}$. Then, it is obvious from the definition that $p_{N_1}^{Sel.}$ and $p_{N_2}^{Sel.}$ preserve $\prec\prec$. \square

Proposition 2. *For all $N \geq 1$, and all $n \geq 0$, $d(X_n^N) \leq \lceil \frac{\log(N)}{\log(2)} \rceil + 1$ with probability one.*

Proof. Let $m := \lceil \frac{\log(N)}{\log(2)} \rceil + 1$. The result is obvious for $n = 0, \dots, m$, since we perform 0 or 1 random walk steps starting from an initial condition where all particles are

at the origin. Now consider $n > m$, and let $y = \max X_{n-m}^N$. Assume first that $\min X_k^N < y$ for all $n+1-m \leq k \leq n$. Since all the random walk steps that are performed during branching steps are ≥ 0 , this implies that all the particles descended by branching from a particle located at y at time $n-m$, are preserved by the selection steps performed from X_{n-m}^N to X_n^N . Since there are $2^m > N$ such particles, this is a contradiction. As a consequence, we know that there must be an index $n+1-m \leq k \leq n$ such that $\min X_k^N \geq y$. Since by construction $t \mapsto \min X_t^N$ is non-decreasing, we deduce that $\min X_n^N \geq y$. Now, since all the random walk steps that are performed add 0 or 1 to the current position of a particle, we see from the definition of y that $\max X_n^N \leq y + m$. As a consequence, $d(X_n^N) = \max X_{n-m}^N - \min X_{n-m}^N \leq m$. \square

Proposition 3. *For all $N \geq 1$, the kernel p_N is compatible with the canonical projection π_N , that is: for all $\nu_1, \nu_2 \in \mathcal{C}_N$ such that $\nu_1 \sim_N \nu_2$, and all $\xi \in \mathcal{C}_N / \sim_N$, $p_N(\nu_1, \pi_N^{-1}(\xi)) = p_N(\nu_2, \pi_N^{-1}(\xi))$.*

Proof. Immediate: everything in the definition of the branching and selection steps is translation-invariant. \square

Proposition 4. *For all $N \geq 1$, the sequence $\pi_N(X_n^N)_{n \geq 0}$ is an ergodic Markov chain on a finite subset of \mathcal{C}_N / \sim_N .*

Proof. The fact that $\pi_N(X_n^N)_{n \geq 0}$ forms a Markov chain on \mathcal{C}_N / \sim_N is an immediate consequence of Proposition 3. Let $\mathcal{S}_N := \{\xi \in \mathcal{C}_N / \sim_N; \exists n \geq 0, \mathbb{P}(\pi_N(X_n^N) = \xi) > 0\}$. From Proposition 2, we see that \mathcal{S}_N is in fact a finite set. On the other hand, given any $\xi \in \mathcal{S}_N$, it is quite easy to find a finite path in \mathcal{S}_N starting at ξ and ending at $\pi_N(N\delta_0)$ that has positive probability. As a consequence, the restriction of $\pi_N(X_n^N)_{n \geq 0}$ to \mathcal{S}_N is an irreducible Markov chain. As for aperiodicity, the transition $\pi_N(N\delta_0) \mapsto \pi_N(N\delta_0)$ has e.g. a positive probability. \square

Corollary 1. *There exists $0 < v_N(p) < +\infty$ such that, with probability one, and in $L^1(\mathbb{P})$,*

$$\lim_{n \rightarrow +\infty} n^{-1} \min X_n^N = \lim_{n \rightarrow +\infty} n^{-1} \max X_n^N = v_N(p).$$

Proof. Note that, in view of Proposition 2, if the two limits in the above statement exist, they must be equal. Then observe that, for all $n \geq 0$, conditionally upon X_n^N , the distributions of the increments $\max X_{n+1}^N - \max X_n^N$ and $\min X_{n+1}^N - \min X_n^N$ depend only on $\pi_N(X_n^N)$. The result then follows by a classical argument using the law of large numbers for additive functionals of ergodic Markov chains. \square

Proposition 5. *The sequence $(v_N(p))_{N \geq 1}$ is non-decreasing.*

Proof. Consequence of the fact that, when $N_1 \leq N_2$, $N_1\delta_0 \prec N_2\delta_0$, and of the monotonicity property 1. \square

We can deduce from the above proposition that there exists $0 < v_\infty(p) < +\infty$ such that $\lim_{N \rightarrow +\infty} v_N(p) = v_\infty(p)$. A consequence of the proofs of Theorems 1 and 2 below is that $v_\infty(p)$ is in fact equal to the number $v(p)$ characterized as the unique root of the equation $\Lambda(x) = \log(2)$, where $x \in [0, 1]$ is the unknown, and where Λ is

the large deviations rate function associated with sums of i.i.d Bernoulli(p) random variables, i.e. $\Lambda(x) := x \log(x/p) + (1-x) \log(\frac{1-x}{1-p})$ for $x \in [0, 1]$. We note for future use that $p < v(p) < 1$ since $p \in]0, 1/2[$.

4. THE UPPER BOUND

The essential arguments used here in the proof of the upper bound, are largely borrowed from the paper [11] by R. Pemantle, which deals with the closely related question of obtaining complexity bounds for algorithms that seek near optimal paths in branching random walks. In fact, the proof of Theorem 1 given below is basically a rewriting of the proof of the lower complexity bound in [11] in the special case of algorithms that do not jump, with the slight difference that we are dealing with N independent branching random walks being explored in parallel, rather than a single branching random walk.

To explain the connexion between our model and the branching random walk, consider the following model. Let $\text{BRW}_1, \dots, \text{BRW}_N$ denote N independent branching random walks, each with value zero at the root, deterministic binary branching, and i.i.d. displacements with common distribution $p\delta_1 + (1-p)\delta_0$ along each edge. For $1 \leq i \leq N$, and $n \geq 0$, let $\text{BRW}_i(n)$ denote the set of vertices of BRW_i located at depth n in the tree, and let $T_n := \text{BRW}_1(n) \cup \dots \cup \text{BRW}_N(n)$. For every n , fix an a priori (i.e. depending only on the tree structure, not on the random walk values) total order on T_n . We now define by induction a sequence $(G_n)_{n \geq 0}$ of subsets such that, for each $n \geq 0$, G_n is a random subset of T_n with exactly N elements. First, let us set $G_0 := T_0$. Then, given $n \geq 0$ and G_n , let H_n denote the subset of $T(n+1)$ formed by the children of the vertices in G_n . Then, define G_{n+1} as the subset of H_n formed by the N vertices that are associated with the largest values of the underlying random walk (breaking ties by using the a priori order on T_n). It is now quite obvious that, for every $n \geq 0$, the (random) empirical distribution of the N random walk values associated with the vertices in G_n has the same distribution as X_n^N .

Given a branching random walk BRW of the type defined above, and one of its vertices u , we use the notation $Z(u)$ to denote the value of the random walk associated with u . The following definition is adapted from [11]. Given $0 < v < 1$ and $m \geq 1$, we say that a vertex $u \in \text{BRW}$ is (m, v) -good if there is a descending path $u =: u_0, u_1, \dots, u_m$ such that $Z(u_i) - Z(u_0) \geq vi$ for all $i \in \llbracket 0, m \rrbracket$. The importance of this definition comes from the two following lemmas, adapted from [11].

Lemma 1. (*Lemma 5.2 in [11]*) *Let $0 < v_1 < v_2 < 1$. If there exists a vertex $u \in \text{BRW}$ at depth n such that $Z(u) \geq v_2 n$, then the path from the root to u must contain at least $\frac{v_2 - v_1}{1 - v_1} \frac{n}{m} - 1 / (1 - v_1)$ vertices that are (m, v_1) -good.*

Lemma 2. (*Proposition 2.6 in [11]*) *There is a constant $\psi > 0$ such that, given a branching random walk BRW , the probability that the root is $(m, v(p) - m^{-2/3})$ -good is less than $\exp(-\psi m^{1/3})$.*

Since Lemma 1 admits so short a proof, we reproduce it below for the sake of completeness. On the other hand, to give a very rough idea where the $\exp(-\psi m^{1/3})$ in Lemma 2 comes from, let us just mention that it corresponds to the probability

that a random walk remains confined in a tube of size $m^{1/3}$ around its mean, for m time steps. Dividing the m steps into $m^{1/3}$ intervals of size $m^{2/3}$, we see that this amounts to asking for the realization of $m^{1/3}$ independent events, each of which has a probability of order a constant, by the usual Brownian scaling.

Proof of Lemma 1. (From [11].) Consider a vertex u as in the statement of the lemma. Consider the descending path $root =: x_0, \dots, x_n := u$ from the root to u . Let then $\tau_0 := 0$, and, given τ_i , define inductively $\tau_{i+1} := \inf\{j \geq \tau_i + 1; Z(x_j) < Z(x_{\tau_i}) + v_1(j - \tau_i) \text{ or } j = \tau_i + m\}$. Now color x_0, \dots, x_{n-1} according to the following rules: if $Z(x_{\tau_{i+1}}) \geq Z(x_{\tau_i}) + v_1(j - \tau_i)$ and $\tau_{i+1} \leq n + 1$, then $x_{\tau_i}, \dots, x_{\tau_{i+1}-1}$ are colored red. Note that this yields a segment of m red vertices, and that x_{τ_i} is then (m, v_1) -good. Otherwise, $x_{\tau_i}, \dots, x_{\tau_{i+1}-1}$ are colored blue. Let V_{red} (resp. V_{blue}) denote the number of red (resp. blue) vertices in x_0, \dots, x_{n-1} . Then decompose $Z(u)$ into the contributions of the red and blue vertices. On the one hand, the contribution of red vertices is $\leq V_{red}$. On the other, the contribution of blue vertices is $\leq V_{blue} \times v_1 + m$, where the m is added to take into account a possible last segment colored in blue only because it has reached depth n . Writing that $n = V_{red} + V_{blue}$, we deduce that $v_2 n \leq V_{red} + v_1(n - V_{red}) + m$, so that $V_{red} \geq \frac{v_2 - v_1}{1 - v_1} n - m/(1 - v_1)$. Then use the fact that at least V_{red}/m vertices are (m, v_1) -good. \square

In [11], Lemmas 1 and 2 are used in combination with an elaborate second moment argument. In the present context, the following quite simple first moment argument turns out to be sufficient.

Proof of Theorem 1. Consider an integer $r \geq 1$, and let $m := r[\log(N)^3]$. Let $n \geq m$, and let B_n denote the number of vertices in $BRW_1 \cup \dots \cup BRW_N$ that are $(m, v(p) - 2m^{-2/3})$ -good (each with respect to the BRW it belongs to) and belong to $G_0 \cup \dots \cup G_n$. From Lemma 1 and the definition of $(G_i)_{i \geq 0}$, we see that the fact that at least one vertex in G_n has a value larger than $(v(p) - m^{-2/3})n$ implies that, for large n (depending on m), $B_n \geq nm^{-5/3}$. On the other hand, B_n can be written as

$$(3) \quad B_n := \sum_{u \in BRW_1 \cup \dots \cup BRW_N} \mathbf{1}(u \text{ is } (m, v(p) - 2m^{-2/3})\text{-good}) \mathbf{1}(u \in G_0 \cup \dots \cup G_n).$$

Now observe that, by definition, for a vertex u of depth ℓ , by definition, the event $u \in G_0 \cup \dots \cup G_n$ is measurable with respect to the random walk steps performed up to depth ℓ , while the event that u is $(m, v(p) - 2m^{-2/3})$ -good is measurable with respect to the random walk steps performed starting from depth $\geq \ell$. As a consequence, these two events are independent. Since the total number of vertices in $G_0 \cup \dots \cup G_n$ is equal to $N(n + 1)$, we deduce from Lemma 2 and (3) that $E(B_n) \leq N(n + 1) \exp(-\psi m^{1/3})$. Using Markov's inequality, and letting n go to infinity, we deduce that

$$\limsup_{n \rightarrow +\infty} P(B_n \geq nm^{-5/3}) \leq Nm^{5/3} \exp(-\psi m^{1/3}).$$

Now, remembering that $P(B_n) = \mathbb{P}(\max X_n^N \geq (v(p) - m^{-2/3})n)$, and using the fact that $\max X_n^N \leq n$ with probability one, we finally deduce that

$$\limsup_{n \rightarrow +\infty} n^{-1} E(\max X_n^N) \leq v(p) - m^{-2/3} + Nm^{5/3} \exp(-\psi m^{1/3}).$$

Choosing r large enough in the definition of m makes the third term in the above r.h.s. negligible with respect to the second term, as N goes to infinity. The conclusion follows. \square

5. THE LOWER BOUND

The proof of the lower bound on the convergence rate of $v_N(p)$ to $v_\infty(p)$ is in some sense a rigorous version of the heuristic argument of Brunet and Derrida according to which we should compare the behavior of the particle system with N particles, with a version of the infinite population limit modified by a cutoff at $\epsilon = 1/N$.

Indeed, given a finite positive measure ν on \mathbb{Z} , let $F^{Br.}(\nu)$ be the measure defined by: $F^{Br.}(\nu) := 2\nu \star (p\delta_1 + (1-p)\delta_0)$. This $F^{Br.}$ describes the evolution of the distribution of particles in the infinite population limit above the threshold imposed by the selection step. The idea of the proof of the lower bound is to control the discrepancy between the finite and infinite population models above this threshold. One important observation is that, to prove a lower bound, one does not necessarily have to control the number of particles at every site, but may focus instead on sites where the probability of finding a particle is not too small.

We note the following two immediate properties of $F^{Br.}$: if $\mu \leq \nu$, then $F^{Br.}(\mu) \leq F^{Br.}(\nu)$, and, if $g \in \mathbb{R}_+$, $F^{Br.}(g\nu) = gF^{Br.}(\nu)$.

5.1. Admissible sequences of measures. Throughout this section, we consider $\epsilon > 0$, $0 < \alpha < v(p)$, $\beta > 1$, and $m \geq q := \lceil \frac{v(p)}{1-v(p)} \rceil$.

We say that a (deterministic) sequence $\delta_0 =: \nu_1, \dots, \nu_m$ of positive measures on \mathbb{Z} with finite support, is $(\epsilon, \alpha, \beta)$ -admissible, if the following properties hold:

- (i) $\nu_i = (2p)^i \delta_i$ for $0 \leq i \leq q$;
- (ii) for all $q+1 \leq i \leq m$, $\nu_i \leq F^{Br.}(\nu_{i-1})$;
- (iii) for all $0 \leq i \leq m-1$, and all $x \in \mathbb{Z}$ such that $\nu_i(x) > 0$, $\nu_i(x) \geq \epsilon$;
- (iv) for all $q \leq i \leq m-1$, the support of ν_i is contained in the interval $[(v(p) - \alpha)(i+1), +\infty[$;
- (v) $\nu_m(\mathbb{Z}) \geq \beta + 1$.

Note that the definition of q makes property (iv) automatic for $i = q$.

Let $B := \{\min(X_i^N) < (v(p) - \alpha)i \text{ for all } 1 \leq i \leq m\}$. The interest of admissible sequences of measures lies in the possibility of bounding $\mathbb{P}(B)$ from above, as explained in the following lemma.

Lemma 3. *Consider an $(\epsilon, \alpha, \beta)$ -admissible sequence ν_0, \dots, ν_m . Let $K := \sum_{i=0}^{m-1} \#\text{supp}(\nu_i)$, and $\delta := 1 - \exp\left(-\frac{\log(\beta)}{m}\right)$. Then the following inequality holds:*

$$\mathbb{P}(B) \leq 2K \exp(-N\beta^{-1}\epsilon p\delta^2).$$

Before proving the above lemma, we recall the following classical estimate for binomial random variables (see e.g. [9]):

Lemma 4. *Let $n \geq 1$ and $0 < r < 1$, and let Z be a binomial(n, r) random variable. Then, for all $0 < \delta < 1$, the probability that $Z \leq (1 - \delta)nr$ is less than $\exp(-\frac{1}{2}nr\delta^2)$.*

Proof of Lemma 3. For $k \in \llbracket 0, m \rrbracket$, let $A_k := \bigcap_{n \in \llbracket 1, k \rrbracket} \{X_n^N \geq N(1 - \delta)^n \nu_n\}$. Note that A_0 is the certain event. For $0 \leq k \leq m - 1$, and $x \in \mathbb{Z}$, define $N_k^1(x)$ (resp. $N_k^0(x)$) to be the number of particles that are created from a particle at position x in X_k^N during the branching step applied to X_k^N , and that have a position equal to $x + 1$ (resp. x). By definition, conditional upon X_0^N, \dots, X_k^N , $N_k^1(x)$ (resp. $N_k^0(x)$) follows a binomial distribution with parameters $(2X_k^N(x), p)$ (resp. $(2X_k^N(x), 1 - p)$). For $k \in \llbracket 0, m - 1 \rrbracket$, let $C_k := \{N_k^\ell(x) \geq (1 - \delta)2X_k^N(x)p; x \in \text{supp}(\nu_k), \ell = 0, 1\}$. Note that, by definition of δ , $(1 - \delta)^k \geq \beta^{-1}$ for all $0 \leq k \leq m$. In view of condition (iii), we deduce that, for $k \in \llbracket 1, m$, on A_{k-1} , $X_{k-1}^N(x) \geq N\beta^{-1}\epsilon$ for all $x \in \text{supp}(\nu_{k-1})$. As a consequence, Lemma 4 yields the fact that

$$(4) \quad \mathbb{P}(A_{k-1} \cap C_{k-1}^c) \leq 2\#\text{supp}(\nu_{k-1}) \exp(-N\beta^{-1}\epsilon p\delta^2),$$

where we have used the union bound and the fact that $p \leq 1 - p$ to combine the bounds given by Lemma 4 for all the $N_{k-1}^\ell(x)$, with $\ell \in \{0, 1\}$, and $x \in \text{supp}(\nu_{k-1})$. Now consider $k \in \llbracket 1, q \rrbracket$. On B , all the particles counted by $N_{k-1}^1(k - 1)$ must be kept after the selection step leading to X_k^N , since $k \geq (v(p) - \alpha)k$. As a consequence, $X_k^N(k) \geq N_{k-1}^1(k - 1)$, and we deduce that

$$(5) \quad A_{k-1} \cap C_{k-1} \cap B \subset A_k.$$

Assume now that $k \in \llbracket q + 1, m \rrbracket$. If B holds, we see that, according to (iv), for all x in the support of ν_{k-1} , the particles counted by $N_{k-1}^1(x)$ and $N_{k-1}^0(x)$ are all kept after the selection step leading to X_k^N . As a consequence, on C_{k-1} , $X_k^N \geq (1 - \delta)F^{Br} \cdot (X_{k-1}^N \mathbf{1}(\text{supp}(\nu_{k-1})))$, so that, on $B \cap A_{k-1} \cap C_{k-1}$, $X_k^N \geq (1 - \delta)^k \nu_k$, since $X_{k-1}^N \geq (1 - \delta)^{k-1} \nu_{k-1}$ and $\nu_k \leq F^{Br} \cdot (\nu_{k-1})$ by assumption (ii). We deduce that

$$(6) \quad A_{k-1} \cap C_{k-1} \cap B \subset A_k.$$

Now observe that, on A_m , one must have $X_m^N(\mathbb{Z}) \geq N(1 - \delta)^m \nu_m(\mathbb{Z}) \geq N\beta^{-1} \nu_m(\mathbb{Z}) > N$, a contradiction, so that $A_m = \emptyset$. From (5), (6), we deduce that $\mathbb{P}(B) \leq \sum_{k=0}^{m-1} \mathbb{P}(A_{k-1} \cap C_{k-1}^c)$, and, using (4), we deduce the result. \square

Let us now relate the above results with estimates on $v_N(p)$. Define the random variable $L := \inf\{1 \leq i \leq m; \min(X_i^N) \geq (v(p) - \alpha)i\}$, with the convention that $\inf \emptyset = m$.

Proposition 6. *For all $0 < p < 1/2$, for all $N \geq 1$,*

$$v_N(p) \geq (v(p) - \alpha)(1 - m\mathbb{P}(B)).$$

Proof. We define a modified branching-selection process $(Y_n^N)_{n \geq 0}$, composed of a succession of runs. Start with $L_0 := 0$ and $H_0 := 0$, and $i := 0$, and do the following.

- 1) Set $Z_0^N := N\delta_{H_i}$ and $k := 0$.
- 2) Do the following:
 $\{ \text{let } k := k + 1 \text{ and generate } Z_k^N \text{ from the distribution } p_N(Z_{k-1}^N, \cdot). \}$
- 3) Return to 2) until $k = m$ or $\min Z_k^N \geq (v(p) - \alpha)k + H_i$.
- 4) Set $L_{i+1} := L_i + k$ and $H_{i+1} := \min Z_k^N$.
- 5) Set $(Y_{L_i}^N, \dots, Y_{L_{i+1}-1}^N) := (Z_0^N, \dots, Z_{k-1}^N)$.
- 6) Let $i := i + 1$ and return to 1) for the next run.

One may describe the above process as follows: starting from a reference position H_i and a reference time index L_i , a run behaves like the original branching-selection process until either m steps have been performed or the minimum value in the population of particles exceeds the reference position by an amount of at least $(v(p) - \alpha)$ times the number of steps performed since the beginning of the run. Then the current population of N particles is collapsed onto its minimum position, the reference position is updated to this minimum position, and the time index to the current time, and a new run is started. Our modified process has a natural regeneration structure yielding the fact that the sequences $(L_{i+1} - L_i)_{i \geq 0}$ and $(H_{i+1} - H_i)$ are i.i.d. The common distribution of the $L_{i+1} - L_i$ is that of L , while the common distribution of the $H_{i+1} - H_i$ is that of $\min X_L^N$. From the fact that $\min Y_{L_i}^N \geq H_i$, it is easy to deduce that, with probability one, $\lim_{n \rightarrow +\infty} n^{-1} \min Y_n^N = \frac{\mathbb{E}(\min X_L^N)}{\mathbb{E}(L)}$, and, since $0 \leq n^{-1} Y_n^N \leq 1$, we also have that $\lim_{n \rightarrow +\infty} n^{-1} \mathbb{E}(\min Y_n^N) = \frac{\mathbb{E}(\min X_L^N)}{\mathbb{E}(L)}$. Now, by definition, $\min X_L^N \geq (v(p) - \alpha)L\mathbf{1}(B^c)$, so that $\mathbb{E}(\min X_L^N) \geq (v(p) - \alpha)(\mathbb{E}(L) - \mathbb{E}(L\mathbf{1}(B)))$. Using the fact that $1 \leq L \leq m$, we obtain that $\frac{\mathbb{E}(\min X_L^N)}{\mathbb{E}(L)} \geq (v(p) - \alpha)(1 - m\mathbb{P}(B))$.

Now, it should be intuitively obvious that the modified process $(Y_n^N)_{n \geq 0}$ is in some sense a lower bound for the original process $(X_n^N)_{n \geq 0}$, since we modify the original dynamics in a way that can only lower positions of particles. It is in fact an easy consequence of Proposition 1 that, for all n , the distribution of Y_n^N is stochastically dominated by that of X_n^N . A consequence is that $\mathbb{E}(\min Y_n^N) \leq \mathbb{E}(\min X_n^N)$. The result follows. \square

5.2. Construction of an admissible sequence of measures. Let A denote an integer ≥ 4 , and $m \geq q$. Then let $a_m := \lfloor m^{1/3} \rfloor$, $c_m := \lfloor m^{2/3} \rfloor$, $s_m := \lfloor \frac{a_m}{2(1-v(p))} \rfloor$. Define d_m by $d_m(k) := k$ for $k \in \llbracket 1, s_m \rrbracket$, and $d_m(k) := v(p)k + a_m$ for $k \in \llbracket s_m + 1, m \rrbracket$. Define g_m by $g_m(k) := k$ for $k \in \llbracket 1, s_m \rrbracket$, $g_m(k) := v(p)(k+1)$ for $k \in \llbracket s_m + 1, m - c_m \rrbracket$, and $g_m(k) := v(p)k - Aa_m$ for $k \in \llbracket m - c_m + 1, m \rrbracket$.

Then define a sequence of measures $(\nu_i)_{i \in \llbracket 0, m \rrbracket}$ on \mathbb{Z} as follows. Let $(S_i)_{i \in \llbracket 0, m \rrbracket}$ denote a simple random walk on \mathbb{Z} starting at zero, with step distribution $p\delta_1 + (1-p)\delta_0$, governed by a probability measure P , then let

$$\nu_i(x) := 2^i P [g_m(k) \leq S_k \leq d_m(k) \text{ for all } k \in \llbracket 0, i \rrbracket, S_i = x].$$

The main result in this section is the following:

Proposition 7. *For large enough A , there exists $\chi(A) > 0$ such that, for all large enough m , the above sequence is $(\exp(-\chi(A)m^{1/3}), 2Am^{-2/3}, 2008)$ -admissible.*

We need to establish several results before we can prove the above proposition.

First, consider the modified probability measure \hat{P} defined by

$$\frac{d\hat{P}}{dP} := \left(\frac{v(p)}{p}\right)^{S_m} \left(\frac{1-v(p)}{1-p}\right)^{m-S_m}.$$

With respect to \hat{P} , $(S_i)_{i \in \llbracket 0, m \rrbracket}$ is a simple random walk on \mathbb{Z} starting at zero, with step distribution $v(p)\delta_1 + (1-v(p))\delta_0$.

We now rewrite $\nu_i(x)$ in terms of this change of measure. To this end, introduce the compensated random walk defined by $\hat{S}_i := S_i - v(p)i$, let also $\hat{g}_m(k) := g_m(k) - v(p)k$ and $\hat{d}_m(k) := d_m(k) - v(p)k$. Finally, let $\gamma := \frac{p/(1-p)}{v(p)/(1-v(p))}$, and note that $\gamma < 1$ since $p < v(p)$. After a little algebra involving the definition of $v(p)$ in terms of Λ , we obtain the following expression:

$$(7) \quad \nu_i(x) = \hat{E} \left[\gamma^{\hat{S}_i} \mathbf{1} \left(\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k) \text{ for all } k \in \llbracket 0, i \rrbracket, S_i = x \right) \right],$$

where \hat{E} denotes expectation with respect to \hat{P} . From the definition of \hat{g}_m and \hat{d}_m , we see that, for large m , the only values of \hat{S}_i that contribute in the above expectation are $\leq m^{1/3}$. As a consequence,

$$(8) \quad \nu_i(x) \geq \gamma^{m^{1/3}} \hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k) \text{ for all } k \in \llbracket 0, i \rrbracket, S_i = x \right],$$

Lemma 5. *For some constant $\zeta_1 > 0$, as m goes to infinity,*

$$\hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k) \text{ for all } k \in \llbracket 0, m \rrbracket \right] \geq \exp(-\zeta_1 m^{1/3}).$$

We need an elementary lemma before the proof of Lemma 5.

Lemma 6. *Consider a random walk $(Z_i)_{i \geq 0}$ on \mathbb{R} , defined by $Z_i := Z_0 + \varepsilon_1 + \dots + \varepsilon_i$ for $i \geq 1$. Assume that the increments ε_i are i.i.d. with respect to some probability measure Q and satisfy $E(\varepsilon_1) = 0$ and $0 < \text{Var}(\varepsilon_1) < +\infty$. Then there exists $\lambda > 0$ such that, for all m large enough,*

$$(9) \quad Q [v \leq Z_i \leq a_m; i \in \llbracket 0, c_m \rrbracket, a_m/3 \leq Z_{c_m} \leq 2a_m/3 | a_m/3 \leq Z_0 \leq 2a_m/3] \geq \lambda.$$

$$(10) \quad Q [a_m/4 \leq Z_i \leq 3a_m/4; i \in \llbracket 0, c_m \rrbracket | a_m/3 \leq Z_0 \leq 2a_m/3] \geq \lambda.$$

Proof of Lemma 6. We use the convergence of the distribution of the random process $(M_t^m)_{t \in [0,1]}$ defined by $M_0^m := 0$, $M_{i/c_m}^m = a_m^{-1}(\varepsilon_1 + \dots + \varepsilon_i)$ for $i \in \llbracket 1, c_m \rrbracket$, and interpolated linearly on each $[i/c_m, (i+1)/c_m]$ towards the Brownian motion (on the space of real-valued continuous functions on $[0,1]$ equipped with the sup norm). An easy consequence is that there exists $\lambda_1 > 0$ such that, for all large m ,

$$Q [-a_m/7 \leq Z_i - Z_0 \leq a_m/7; i \in \llbracket 1, c_m \rrbracket, 0 \leq Z_{c_m} - Z_0 \leq a_m/7] \geq \lambda_1.$$

This estimate proves (9) when Z_0 belongs to $[a_m/3, a_m/2]$. A symmetric argument works when Z_0 belongs to $[a_m/2, 2a_m/3]$. The proof of (10) is quite similar. \square

Proof of Lemma 5. First note that, for all large enough m , $a_m/3 \leq s_m - v(p)s_m \leq 2a_m/3$. Then,

$$\hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k); k \in \llbracket 0, s_m \rrbracket \right] = v(p)^{s_m}.$$

Divide the interval $\llbracket s_m + 1, m \rrbracket$ into consecutive intervals I_j , $j \in \llbracket 1, h_m \rrbracket$, where each I_j for $j \in \llbracket 1, h_m - 1 \rrbracket$ is of the form $I_j := \llbracket s_m + 1 + (j - 1)c_m, s_m + 1 + jc_m \rrbracket$, while the last interval is $I_{h_m} := \llbracket s_m + 1 + (h_m - 1)c_m, m \rrbracket$, whose length is less than or equal to c_m . For $i \in \llbracket 1, h_m \rrbracket$, let $b_{m,j-1}$ and $b_{m,j}$ be defined by $I_j = \llbracket b_{m,j-1}, b_{m,j} \rrbracket$. Now, for $i \in \llbracket 1, h_m - 1 \rrbracket$, define the event $\Gamma_i := \left\{ v \leq \hat{S}_k \leq a_m; k \in I_i, a_m/3 \leq Z_{b_{m,i}} \leq 2a_m/3 \right\}$, and let $\Gamma_{h_m} := \left\{ a_m/4 \leq \hat{S}_k \leq 3a_m/4; k \in I_{h_m} \right\}$.

It is easily checked that, given that $S_{s_m} = s_m$,

$$\bigcap_{i \in \llbracket 1, h_m \rrbracket} \Gamma_i \subset \bigcap_{k \in \llbracket s_m + 1, m \rrbracket} \{ \hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k) \}.$$

Thanks to Lemma 6 and to the Markov property of \hat{Z} with respect to \hat{P} , we deduce that

$$\hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k); k \in \llbracket 0, m \rrbracket \right] \geq v(p)^{s_m} \lambda^{h_m}.$$

(We use exactly Lemma 6 for intervals I_i with $i \in \llbracket 1, h_m - 1 \rrbracket$, while, for $i = h_m$, we use that fact that the length of I_j is $\leq c_m$, whence the fact that the conditional probability of Γ_{h_m} given $\hat{S}_0, \dots, \hat{S}_{b_{m,h_m-1}}$ is larger than or equal to the probability appearing in (10) in Lemma 6.) Using the fact that $h_m \sim m^{1/3}$ for large m , the conclusion follows. \square

Lemma 7. *There exists $\zeta_2(A) > 0$ such that, as m goes to infinity,*

$$\inf \{ \nu_i(x); i \in \llbracket 0, m - 1 \rrbracket, \nu_i(x) > 0 \} \geq \exp(-\zeta_2(A)m^{1/3}).$$

We need the following lemma before giving the proof.

Lemma 8. *Let $\rho, \sigma \in \mathbb{R}$, with $\rho + 1 < \sigma$, $v \in]0, 1[$ and, let ℓ be an integer such that $\sigma + lv < \rho + \ell$ and $\rho + vl > \sigma$. Then, for all $x \in \mathbb{Z} \cap [\rho, \sigma]$, and all $y \in \mathbb{Z} \cap [\rho + vl, \sigma + vl]$, there exists a sequence $x =: x_0, x_1, \dots, x_\ell := y$ such that $x_{i+1} - x_i \in \{0, 1\}$ for all $i \in \llbracket 0, \ell - 1 \rrbracket$, and $\rho + vi \leq x_i \leq \sigma + vi$ for all $i \in \llbracket 0, \ell \rrbracket$.*

Proof of Lemma 8. Consider $x \in \mathbb{Z} \cap [\rho, \sigma]$, and $y \in \mathbb{Z} \cap [\rho + vl, \sigma + vl]$. Define inductively the sequence $(\tau_i, h_i)_{i \geq 0}$ as follows. Let $\tau_0 := x$, $h_0 := x$. Our assumption that $\rho + 1 < \sigma$ guarantees that x or $x + 1$ belongs to $[\rho + v, \sigma + v]$. If $x + 1$ belongs to $[\rho + v, \sigma + v]$, then let $d := 0$. Otherwise, let $d := 1$. Then, consider $i \geq 1$. If $i + d$ is even, let $\tau_i := \max\{j \in \llbracket \tau_{i-1} + 1, +\infty \rrbracket; h_{i-1} \geq \rho + vj\}$, and let $h_i := h_{i-1}$. If $i + d$ is odd, let $\tau_i := \max\{j \in \llbracket \tau_{i-1} + 1, +\infty \rrbracket; h_{i-1} + j - \tau_{i-1} \leq \sigma + vj\}$, and let $h_i := h_{i-1} + \tau_i - \tau_{i-1}$.

The fact that $\rho + 1 < \sigma$ and $v \in]0, 1[$ guarantees that every term in the sequence is finite. Define the sequence $(z_k)_{k \geq 0}$ by $z_k := h_{i-1}$ for $k \in \llbracket \tau_{i-1}, \tau_i \rrbracket$ when $i + d$ is even, and $z_k := h_{i-1} + k - \tau_{i-1}$ for $k \in \llbracket \tau_{i-1}, \tau_i \rrbracket$ when $i + d$ is odd. Our

assumptions yield the fact that $\rho + vk \leq z_k \leq \sigma + vk$ for all $k \geq 0$. Now note that, if $y = z_m$, the path z_0, \dots, z_m solves our problem. If $y > z_m$, the assumption that $\rho + \ell > \sigma + v\ell$ plus elementary geometric considerations show that there must be some $k \in \llbracket 0, m-1 \rrbracket$ such that $y - x_k = \ell - k$. From the path x_0, \dots, x_k , add +1 steps and stop at length ℓ . The corresponding path solves the problem. Now, if $y < z_m$, our assumption that $\sigma < \rho + v\ell$ plus elementary geometric considerations show that there must be a $k \in \llbracket \tau_{k-1}, m-1 \rrbracket$ such that $x_k = y$. From the path x_0, \dots, x_k , add +0 steps and stop at length ℓ . The corresponding path solves the problem. \square

Proof of Lemma 7. In the sequel, let $x_k := k$ for $k \in \llbracket 0, s_m \rrbracket$, and note that, for large enough m , $g_m(k) \leq x_k \leq d_m(k)$ for all $k \in \llbracket 0, s_m \rrbracket$.

Let $\alpha > \max(v(p)^{-1}, (1 - v(p))^{-1})$, and let $f_m := \lfloor \alpha a_m \rfloor$. For $i \in \llbracket s_m + 1, s_m + 2f_m \rrbracket$, and x in the support of ν_i , there must by definition be a sequence $s_m =: x_{s_m}, \dots, x_i := x$ such that $x_{j+1} - x_j \in \{0, 1\}$ and $g_m(j) \leq x_j \leq d_m(j)$ for all $j \in \llbracket s_m, i \rrbracket$. As a consequence, for every $i \in \llbracket 0, s_m + 2f_m \rrbracket$ and $x \in \text{supp}(\nu_i)$,

$$(11) \quad \hat{P}[S_k = x_k; k \in \llbracket 0, i \rrbracket, S_i = x] \geq (\min(v(p), 1 - v(p)))^{s_m + 2f_m}.$$

Now assume that $i \in \llbracket s_m + 2f_m + 1, m - c_m \rrbracket$, and consider the distribution of S_{i-f_m} with respect to \hat{P} , conditional upon $g_m(k) \leq S_k \leq d_m(k)$ for all $k \in \llbracket 0, i - f_m \rrbracket$. This probability distribution is concentrated on the set $\mathbb{Z} \cap [g_m(i - f_m), d_m(i - f_m)]$, which contains at most a_m elements. Consequently, there exists $u \in \mathbb{Z} \cap [g_m(i - f_m), d_m(i - f_m)]$ such that

$$\hat{P}[S_{i-f_m} = u | g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, i - f_m \rrbracket] \geq 1/a_m.$$

Now let x belong to the support of ν_i . By definition, $x \in \mathbb{Z} \cap [g_m(i), d_m(i)]$. In view of the definition of α , we see that, for all m large enough, we can apply Lemma 8 to obtain the existence of a sequence $u =: x_{i-f_m}, \dots, x_i := x$ such that $x_{j+1} - x_j \in \{0, 1\}$ and $g_m(j) \leq x_j \leq d_m(j)$ for all $j \in \llbracket i - f_m, i \rrbracket$. Thanks to the Markov property of $(S_k)_{k \geq 0}$ with respect to \hat{P} , we deduce that

$$\hat{P}[g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, i \rrbracket, S_i = x]$$

is larger than or equal to

$$\hat{P}[g_m(k) \leq S_k \leq d_m(k), k \in \llbracket 0, i - f_m \rrbracket] (1/a_m) (\min(v(p), 1 - v(p)))^{f_m}.$$

From Lemma 5, we have that, for m large enough,

$$\hat{P}[g_m(k) \leq S_k \leq d_m(k), k \in \llbracket 0, m \rrbracket] \geq \exp(-\zeta_1 m^{1/3}),$$

so that, for every $i \in \llbracket s_m + 2f_m + 1, m - c_m \rrbracket$,

$$(12) \quad \hat{P}[g_m(k) \leq S_k \leq d_m(k), k \in \llbracket 0, i \rrbracket, S_i = x] \geq \exp(-\zeta_1 m^{1/3}) \times (1/a_m) (\min(v(p), 1 - v(p)))^{f_m}.$$

For $i \in \llbracket m - c_m + 1, m - c_m + 2(A + 1)f_m \rrbracket$, any x in the support of $\nu_i(x)$ is such that there exists u in the support of ν_{m-c_m} and a sequence $u =: x_{m-c_m}, \dots, x_i := x$ such that $x_{j+1} - x_j \in \{0, 1\}$ and $g_m(j) \leq x_j \leq d_m(j)$ for all $j \in \llbracket m - c_m, i \rrbracket$. As a consequence,

$$\hat{P}[g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, i \rrbracket, S_i = x]$$

is larger than or equal to

$$\hat{P} [g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, m - c_m \rrbracket, S_{m-c_m} = u] \\ \times (\min(v(p), 1 - v(p))^{2(A+1)f_m}.$$

Using (12), we deduce that, for every $i \in \llbracket m - c_m + 1, m - c_m + 2(A+1)f_m \rrbracket$,

$$(13) \quad \hat{P} [g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, i \rrbracket, S_i = x] \geq \exp(-\zeta_1 m^{1/3}) \\ \times (1/a_m)(\min(v(p), 1 - v(p))^{2(A+1)+1}f_m).$$

Then an argument quite similar to that leading to (12) yields that, for any $i \in \llbracket m - c_m + 2(A+1)f_m + 1, m \rrbracket$,

$$(14) \quad \hat{P} [g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, i \rrbracket, S_i = x] \geq \exp(-\zeta_1 m^{1/3}) \\ \times (1/((A+1)a_m + 1))(\min(v(p), 1 - v(p))^{(A+1)f_m}.$$

The conclusion follows by using (8) and (11), (12), (13), (14). \square

Lemma 9. *There exists $\phi(A) > 0$ such that, as m goes to infinity,*

$$\hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k); k \in \llbracket 0, m \rrbracket, \hat{S}_m \leq -(A/2)a_m \right] \geq \phi(A) \exp(-\zeta_1 m^{1/3}).$$

We shall need the following elementary lemma.

Lemma 10. *Consider a random walk $(Z_i)_{i \geq 0}$ on \mathbb{R} , defined by $Z_i := Z_0 + \varepsilon_1 + \dots + \varepsilon_i$ for $i \geq 1$. Assume that the increments ε_i are i.i.d. with respect to some probability measure Q and satisfy $E(\varepsilon_1) = 0$ and $0 < \text{Var}(\varepsilon_1) < +\infty$. Then there exists $\phi(A) > 0$ such that, for all m large enough,*

$$Q [-Aa_m \leq Z_i \leq a_m; i \in \llbracket 1, c_m \rrbracket, Z_{c_m} \leq -(A/2)a_m | a_m/4 \leq Z_0 \leq 3a_m/4] \geq \phi(A).$$

Proof of Lemma 10. We re-use the notations of the proof of Lemma 6. The only point is to note that, by convergence to the Brownian motion, there exists $\phi(A) > 0$ such that for all large m ,

$$Q [-3Aa_m/4 \leq Z_i - Z_0 \leq a_m/4; i \in \llbracket 1, c_m \rrbracket, Z_{c_m} - Z_0 \leq -(A/2 + 3/4)a_m] \geq \phi(A).$$

The result follows easily (using the fact that A is assumed to be ≥ 4). \square

Proof of Lemma 9. From the proof of Lemma 5, we see that

$$\hat{P} \left[g_m(k) \leq S_k \leq d_m(k); k \in \llbracket 0, m - c_m \rrbracket, a_m/4 \leq \hat{S}_{m-c_m} \leq 3a_m/4 \right] \geq \exp(-\zeta_1 m^{1/3}).$$

Then, by Lemma 10, as m goes to infinity,

$$\hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k); k \in \llbracket m - c_m + 1, m \rrbracket, \hat{S}_m \leq -Aa_m/2 \mid a_m/4 \leq \hat{S}_{m-c_m} \leq 3a_m/4 \right]$$

is larger than or equal to $\phi(A)$. The conclusion follows. \square

Proof of Proposition 7. Properties (i) and (ii) are immediate consequences of the definition. Property (iii) is a direct consequence of Lemma 7, letting $\chi(A) := \zeta_2(A)$. From the definition, $g_m(k) \geq v(p)(k+1)$ for all $k \in \llbracket q, m - c_m \rrbracket$. Then, given A , for all large enough m , it is easily checked that $g_m(k) \geq (v(p) - 2Am^{-2/3})(k+1)$ for all

$k \in \llbracket m - c_m + 1, m \rrbracket$. This yields Property (iv). As for Property (v), consider (7). Clearly, since $\gamma < 1$,

$$\nu_m(\mathbb{Z}) \geq \gamma^{-(A/2)a_m} \hat{P} \left[\hat{g}_m(k) \leq \hat{S}_k \leq \hat{d}_m(k); k \in \llbracket 0, m \rrbracket, \hat{S}_m \leq -(A/2)a_m \right].$$

From Lemma 9, the probability in the r.h.s. of the above expression is $\geq \phi(A) \exp(-\zeta_1 m^{1/3})$, so that, choosing A large enough, the term $\gamma^{-(A/2)a_m}$ dominates for large m . As a consequence, for such an A , $\nu_m(\mathbb{Z}) \geq 2008 + 1$ as soon as m is large enough. \square

Proof of Theorem 2. Consider a parameter $\theta > 0$, and let m depend on N in the following way: $m := \lfloor \theta \log(N) \rfloor^3$. For N large enough, we can apply Proposition 7, and use Lemma 3, which states that

$$\mathbb{P}(B) \leq 2K \exp(-N\beta^{-1}\epsilon p \delta^2).$$

It is easily checked from the definition that $K \leq ((A+1)a_m + 1)m$. Note also that $\delta \sim \log(\beta)/m$ for large N . Finally, $\epsilon = \exp(-\chi(A)m^{1/3})$. Choosing θ small enough, we check that $m\mathbb{P}(B) \ll m^{-2/3}$ as N goes to infinity. Proposition 6 then implies that $v_N(p) \geq v(p) - 2Am^{-2/3}(1 + o(1))$. The result follows. \square

6. CONCLUDING REMARKS

Remark 1. *Can we derive a reasonably simple explanation of how the $\log(N)^{-2}$ arises, based on the mathematical proofs presented above? Broadly speaking, the key point in both the upper and the lower bound seems to be the following (we re-use some notations from Section 5): consider a large integer m and look for a scale Δ such that*

$$(15) \quad 2^m P(|\hat{S}_1|, \dots, |\hat{S}_m| \propto \Delta) \asymp 1/N.$$

In view of the change of measure, and of the fact that, by Brownian scaling, $\hat{P}(|\hat{S}_1|, \dots, |\hat{S}_m| \propto \Delta) \asymp \exp(-m/\Delta^2)$, we see that there are two factors involved in the above probability: $\gamma^{\pm\Delta}$, and $\exp(-m/\Delta^2)$. Equating the exponential scales of these two factors yields $\Delta \propto m^{1/3}$, and (15) then implies that $m \propto \log(N)^3$, whence an average velocity shift over the m steps of order $\Delta/m \propto \log(N)^{-2}$.

Remark 2. *We have focused in this paper on the case $0 < p < 1/2$. The situation is quite different when $p \geq 1/2$. Indeed, $v(p)$ is then equal to 1, and the convergence speed can be proved to be of order $1/N$ when $p = 1/2$, and exponential with respect to N when $p > 1/2$.*

Remark 3. *What we have proved is that the order of magnitude of $v_N(p) - v_\infty(p)$ is indeed $\log(N)^{-2}$. It would of course be quite interesting to get more precise asymptotic results for this quantity, since there is at least compelling numerical evidence that $v_N(p) - v_\infty(p) \sim c(p) \log(N)^{-2}$ for some constant c .*

Remark 4. *Both the upper and lower bound presented here rely upon controlling the behavior of the particle system for time intervals of length $m \propto \log(N)^3$. This is the same order of magnitude as the one observed for the coalescence times of the genealogical process underlying the branching-selection algorithm, from empirical*

studies and heuristic arguments (see e.g. [3]). Although we do not know how to establish a rigorous relationship between these facts, this at least provides another indication that the $\log(N)^3$ time scale is particularly relevant for the study of these systems.

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