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## Substorm onset identification using neural networks and Pi2 pulsations

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**Abstract.** The pattern recognition capabilities of artificial neural networks (ANNs) have for the first time been used to identify Pi2 pulsations in magnetometer data, which in turn serve as indicators of substorm onsets and intensifications. The pulsation spectrum was used as input to the ANN and the network was trained to give an output of +1 for Pi2 signatures and -1 for non-Pi2 signatures. In order to evaluate the degree of success of the neural-network procedure for identifying Pi2 pulsations, the ANN was used to scan a number of data sets and the results compared with visual identification of Pi2 signatures. The ANN performed extremely well with a success rate of approximately 90% for Pi2 identification and a timing accuracy generally within 1 min compared to visual identification. A number of potential applications of the neural-network Pi2 scanning procedure are discussed.

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### 1 Introduction

Over the past number of years artificial intelligence (AI) methods have been increasingly recognised as powerful analysis tools in solar-terrestrial physics. They have enabled or facilitated the identification of relationships and patterns in a variety of data sets (McPherron, 1993; Joselyn *et al.*, 1993). Artificial neural networks (ANNs) are a branch of AI methods which are proving particularly successful in solar-terrestrial time-series prediction (Koons and Gorney, 1991; Lundstedt, 1992; Gorney *et al.*, 1993; Lundstedt and Wintoft, 1994; Wu and Lundstedt, 1996). In this paper the pattern recognition capabilities of ANNs have for the first time been used to identify Pi2 pulsations, and consequently substorm onsets, in magnetometer data.

Pi2 pulsations are impulsive damped ULF, i.e. frequency band 6–25 mHz, oscillations of the geomagnetic field which occur at the time of magnetospheric

substorm onsets and intensifications. Two decades ago, Saito *et al.* (1976) pointed out that Pi2 pulsations recorded at low latitudes, where amplitudes typically lie in the range 0.25–2.5 nT, are one of the clearest indicators of substorm onsets. They also pointed out the shortcomings of some of the other methods of identifying substorms. For example, auroral electrojet (AE) indices suffer due to the inadequate spatial coverage of observing stations. DMSP satellite observations suffer from inadequate temporal coverage due to the satellite orbital period around the earth. The mid-latitude positive bay signature of substorms has a gradual onset, i.e. does not provide accurate timing, and is not observed in association with weak substorms. In their definition of a magnetospheric substorm, Rostoker *et al.* (1980) required that at least one Pi2 pulsation burst occur and stated that, if well defined, it accurately ( $\pm 1$  min) identifies the substorm onset. Furthermore, Pi2s occur with each substorm intensification. More recently Yeoman *et al.* (1994) made a comparison of mid-latitude Pi2 pulsations and geostationary orbit particle injections and confirmed that Pi2s serve as effective indicators of the onset of the substorm expansive phase. As a result of the utility of Pi2s for the identification of substorm onsets, many researchers visually scan low-latitude magnetometer data for the occurrence of Pi2 pulsations in the course of their substorm research. The first preliminary attempts to automate this scanning process using digital data were only recently made. Nosé *et al.* (1995) used wavelet analysis for the detection of Pi2 pulsations for monitoring substorm onsets. Sutcliffe (1995) attempted three methods for the automated detection of Pi2 pulsations; these were data adaptive filtering, maximum entropy prediction error filtering, and neural networks. These initial attempts indicated that neural networks had the greatest potential for success.

This paper builds on those initial successes. In particular, it has been found that specific pre-processing of the data makes the results more robust and significantly improves the detection success rate. We are not

aware of any other automated means of detecting substorm onsets with a comparable degree of success.

## 2 Neural-network training and verification

The ANN which we used for Pi2 pattern recognition was of the type known as a multilayer perceptron (Haykin, 1994). Our feed-forward fully connected ANN with one hidden layer was trained using the back-propagation algorithm, which remains the most widely used supervised training method. During this iterative process the ANN was trained to map a set of input values to a single target value. The network architecture and this process are illustrated schematically in Fig. 1. The central goal in ANN training is not to memorize the training data, but rather to model the underlying generator of the data (Bishop, 1996). An important factor in achieving this goal is that the amount of training be sufficient, but that the network not be over-trained. A recommended method to ensure that an ANN is not over-trained is to stop training when the error measured using an independent validation set starts to increase. Consequently, an independent set of input values was used to determine when the ANN was sufficiently trained; training was ceased when the rms

error between the computed and target output values reached a stable minimum. We found limited pre-processing of the data (Bishop, 1996) to be important and to have a significant effect on the quality of the results.

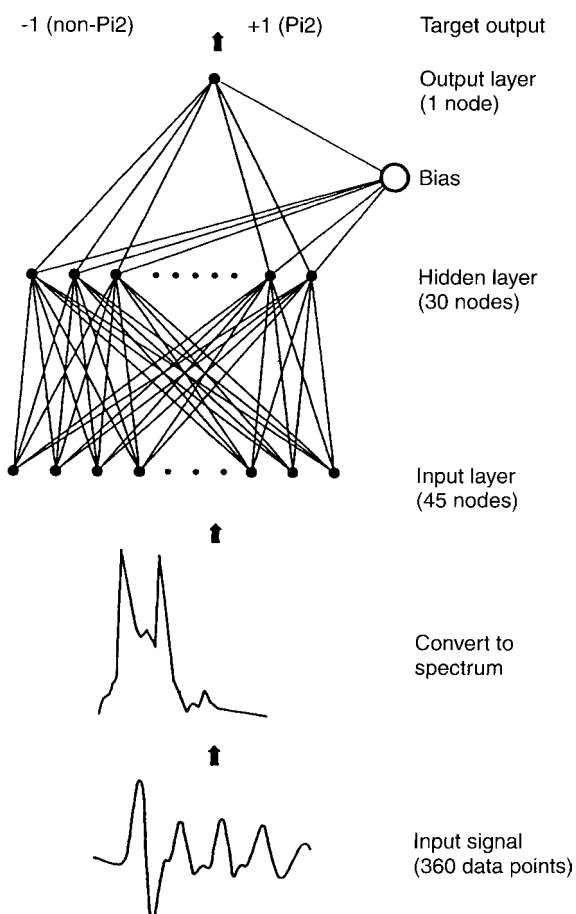
The input data for the ANN were obtained by selecting ULF pulsation events from the induction magnetometer data digitally recorded at the Hermanus Magnetic Observatory (HMO) with 1-s sampling. Event lengths ranging from 5 to 10 min were tried; however, experimentation indicated that a 6-min event length appeared to give the best overall results. The selected events were classified into two groups, namely Pi2 signatures and non-Pi2 signatures. The event start times of Pi2 signatures were selected to be approximately 0.5 min prior to the onset of the Pi2 pulsations. Some of the selected Pi2 pulsations decayed within the 6-min event window, while others extended beyond it. Non-Pi2 events were intervals of either Pc3 pulsation activity, which typically have higher frequencies and smaller amplitudes than Pi2s, or insignificant pulsation activity. Examples of these various types of events are shown in Fig. 2.

Initially we used these event time-series as the input values for training the ANN. The number of nodes in the input layer in this case was thus 360. Increasing the sampling interval by up to eight times, in order to reduce the number of input nodes, had little effect on the results. After much experimentation we found that more robust results were obtained by first computing the Fourier spectrum for each event. The first 45 points of the amplitude spectrum (i.e. low-frequency end) were then used as the input values to the ANN with 45 input nodes. The amplitude spectra of the time-series in Fig. 2 are shown in Fig. 3. The ANN was trained to give target output values of +1 for Pi2 events and -1 for non-Pi2 events. The set of input values contained equal numbers of Pi2 and non-Pi2 events.

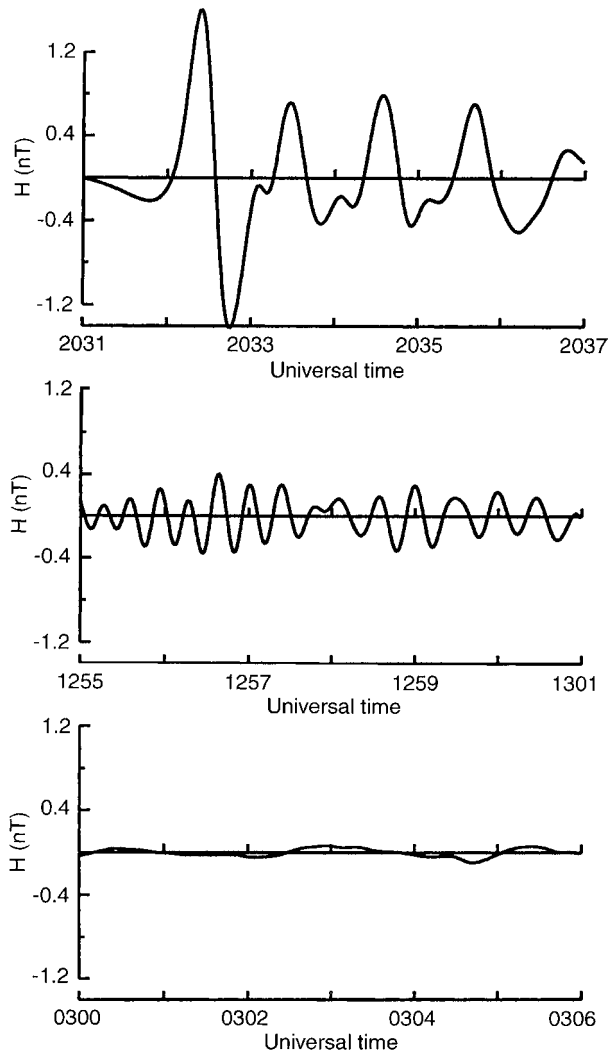
An important condition for good generalisation of an ANN is that the training examples form a sufficiently large and representative sample of the population of all cases. In initial tests we found relatively small differences in the results for ANNs trained using 50 and 100 examples, indicating these to be sufficiently large samples. In forming the samples of training examples we tried to ensure that Pi2s with a variety of shapes, frequencies and amplitudes were selected. For purposes of demonstration, we trained ANNs for each of three independent sets of input values; the first set consisted of only four events (ANN-S4), which is obviously not a representative sample, set two of ten events (ANN-S10), and set three of 100 events (ANN-S100), which we believe to be a representative sample.

## 3 Neural-network scanning

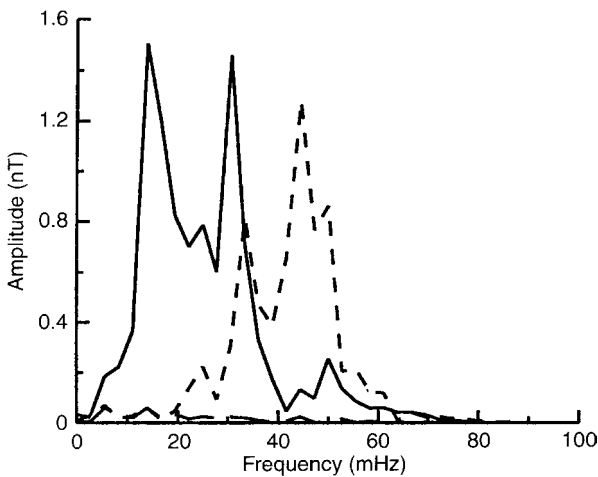
Each of the three trained ANNs were utilised to scan digital induction magnetometer data for the occurrence of Pi2 pulsations. In order to do this, data windows commencing 1 min apart and equal in length to that of



**Fig. 1.** Schematic representation of the data pre-processing and neural-network architecture used to identify Pi2 pulsations



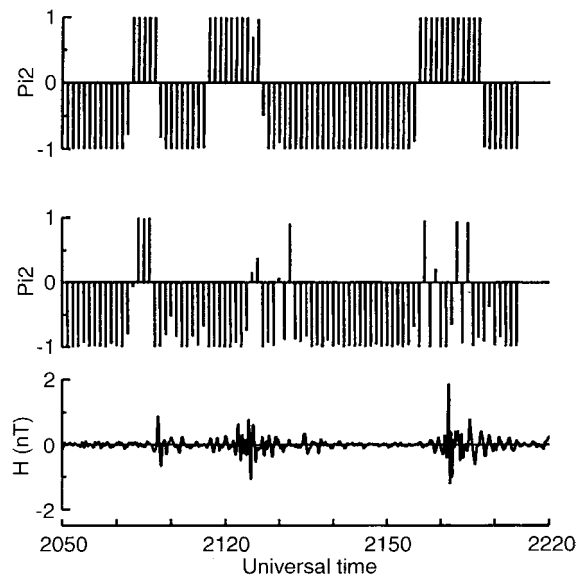
**Fig. 2.** Examples of the types of events used to train the ANN; Pi2 signature (*upper*) and non-Pi2 signatures, i.e. Pc3 pulsation (*centre*) and insignificant activity (*lower*)



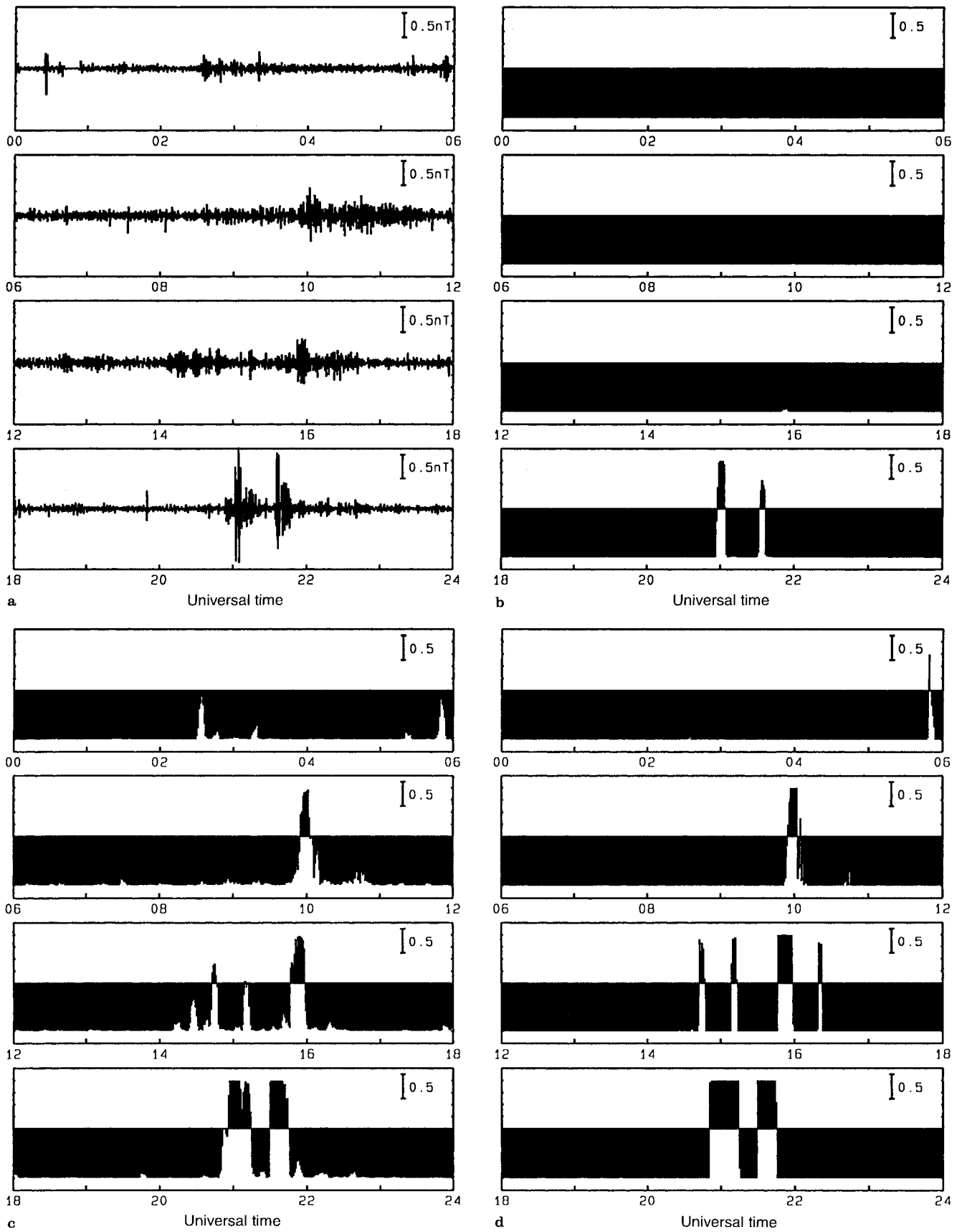
**Fig. 3.** Amplitude spectra of the time-series in Fig. 2; Pi2 signature (*solid line*), Pc3 pulsation (*short dashed line*), and insignificant activity (*long dashed line*)

the events used for training, that is 6 min, were sequentially taken from the interval of data to be scanned. The data for each window were pre-processed in a manner similar to that of the training data, that is, computation of Fourier amplitude spectrum, and then presented to the ANN. For each data window thus presented to the ANN a single output value in the range  $-1$  to  $+1$  was obtained. The expected result of this process is that if the data window contains no evidence of a Pi2 pulsation, the output value will lie close to  $-1$ . However, if the data window contains evidence of a Pi2 pulsation, the expected output is a value close to  $+1$ . In the lower part of Fig. 4 the induction magnetometer data for an interval spanning a number of Pi2 pulsations are plotted. Also plotted are the output values of the ANN for each data window; each output value is plotted at the time equal to the start time of the corresponding data window. The output values in the centre part of Fig. 4 are those where the input values to the ANN were the actual time-series data, while the output values in the upper part are those where the amplitude spectrum was used as input. The results in Fig. 4, and many others like it, showed that converting the input data to a Fourier spectrum prior to presentation to the ANN gave more decisive and consistent results than those using the time-series directly.

In Fig. 5a the H-component data for a 24-h interval, i.e. 29 January 1988, are plotted. Also plotted are the output values for the ANNs trained using the three independent sets of training data. The output values in Fig. 5b are those for the ANN trained using the set of four events, those in Fig. 5c using the set of ten events, and those in Fig. 5d using the set of 100 events. In all cases conversion to Fourier spectrum was made at the pre-processing stage. The two large, clear Pi2 signatures with onsets at 2054 and 2133 UT were identified by all



**Fig. 4.** Examples of the output from the ANN when a section of data containing Pi2 signatures (*lower*) is scanned. The outputs at *centre* and *upper* are those obtained when the time-series itself and the amplitude spectrum of the time-series, respectively, are used



**Fig. 5.** **a** Example of a 24-h interval of induction magnetometer data. The sequences of output values for the ANNs trained using **b** 4 events, **c** 10 events, and **d** 100 events are also shown for comparison

three ANNs; these were the only Pi2s identified by ANN-S4. Since ANN-S4 was trained using an extremely limited set of patterns, we might expect that it would only be able to recognise clearly defined and isolated Pi2s. These two Pi2s occurred within an hour of the time at which Pi2s occur with maximum frequency at Hermanus (Sutcliffe, 1975), that is, the time when Pi2s are also most clearly and easily observed. ANN-S10 and ANN-S100 also clearly identified Pi2s with onsets at 0958 and 1550 UT; these are dayside Pi2 pulsations. Generally, Pi2s are regarded as nightside phenomena; however, Sutcliffe and Yumoto (1989, 1991) demonstrated that at low latitudes they are regularly observed during the daytime, although often hidden by other pulsation types. Inspection of the AE indices revealed that, on the basis of AE magnitude, these were the onsets of the two largest substorms observed on 29 January 1988. ANN-S100 identified a number of other Pi2s, but with less certainty, that is, with a lesser number of positive values and with these values less than +1. Inspection of the Hermanus pulsation data revealed what appeared to be small Pi2s at 1445 and 1512 UT. We also inspected the magnetometer data from Kakioka, which was in the nightside hemisphere at these times, and found clear Pi2 signatures. Inspection of the Hermanus and Kakioka pulsation data at 0550 and 1620 UT revealed slight enhancements in pulsation activity, but it was not possible to say with certainty whether or not these were Pi2s. On the basis of these and other similar examples, we implemented a cut-off criterion in the computer program which scans for Pi2s. If a sequence of four or more positive spikes exceeding 0.4 in value occur then the occurrence of a Pi2 is signalled. In all subsequent scans for Pi2s we used this criterion with the ANN-S100 network. Thus on 29 January 1988 the occurrence of Pi2s are reported at 0958, 1446, 1512, 1550, 2054 and 2133 UT when the Hermanus data are used.

#### 4 Results

In order to evaluate the degree of success of the neural-network procedure for identifying Pi2 pulsations the ANN-S100 was used to scan three data sets. The first two of these sets each consisted of intervals of ten consecutive days of magnetometer data selected so as to exclude the occurrence of any major magnetic storm activity. Storm periods were excluded in order to guarantee intervals of isolated substorms rather than the complex superposition of substorm activity which occurs during large storms. The first data set consisted of the Hermanus induction magnetometer data for the period 1988 day numbers 24 to 33. This interval fell within the 6-month period from which the events used for training the ANN were selected. The second data set consisted of Hermanus induction magnetometer data for the period 1987 day numbers 185 to 194, which fell outside the period from which the training events were selected. The third data set consisted of isolated days of

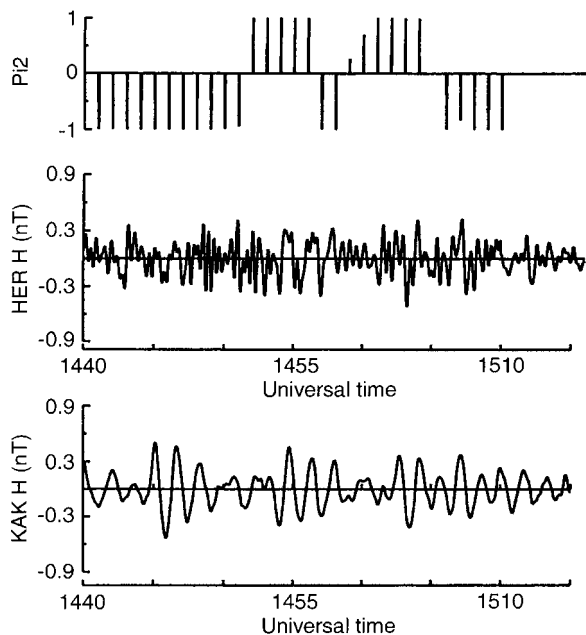
magnetometer data when conditions were such that the ANN might be expected to fail.

Each data set was first inspected visually and the onset times of all Pi2 pulsation events noted to the nearest minute. Since Pi2 pulsations at low latitudes are generally more clearly defined in the H component than in D, the H component was primarily used for this purpose. However, in those cases where the D component was more clearly defined, the D-component onset times were used. The H- and D-component data for each set were then scanned separately using the ANN-S100. The number of events identified by these various means for the first two data sets are compared in Table 1, where the non-parenthesised values are those which satisfy the cut-off criterion mentioned previously. The results in the table show that the ANN performed well in the identification of Pi2 events, with a combined success rate for the two data sets of 90% if both H and D are scanned. If only the H component is scanned, then the combined success rate is reduced to 81%.

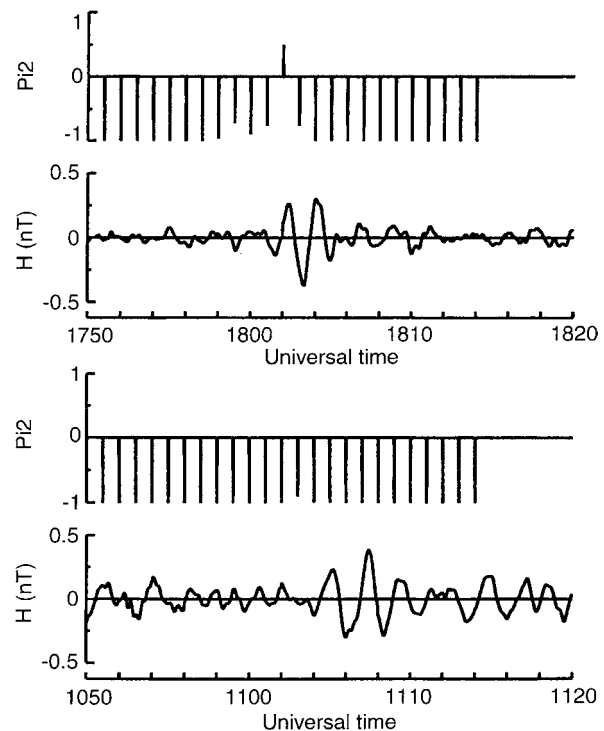
We now briefly consider the reasons for some of the apparent failures. In the first data set a total of 75 Pi2 events were identified. Four of the events identified by the ANN were not identified visually, thus it was necessary to investigate whether or not the ANN was selecting some non-Pi2 events. Each of these reported events occurred during mid-afternoon at Hermanus, which closely corresponds to local midnight at Kakioka in Japan. Consequently, the Kakioka magnetometer data were inspected and in each case a Pi2 pulsation was clearly visible at the times corresponding to the ANN events at Hermanus. Inspection of the AE indices at the reported times revealed significant electrojet intensifications confirming that they were associated with substorm onsets or enhancements. Thus it is concluded that the ANN was able to identify Pi2s which were missed by visual scanning. The reason for these Pi2s not being visible to the eye is that they were masked by superposed continuous pulsation activity. Sutcliffe and Yumoto (1989) found this to be the reason why many daytime Pi2s are not easily visible. An example is shown in Fig. 6 where the lower trace clearly shows a train of three successive Pi2s at Kakioka. The centre trace shows the corresponding data for Hermanus, where the Pi2s are masked by superposed Pc3 pulsation activity, which is typical of the dayside hemisphere. The upper trace shows the output of ANN-S100 scanning in which two of the Pi2s at 1453 and 1502 UT are clearly identified. In the second data set eight of the Pi2 events identified by

**Table 1.** Comparisons of the total numbers of Pi2 events with the numbers identified visually and by the ANN for each of the data sets

Data set	Number of events			
	Total	Visual H and/or D	ANN H and/or D	ANN H only
1	75	71	71 (72)	60
2	83	75	71 (80)	68



**Fig. 6.** Example where the ANN was able to identify Pi2 signatures which were not visually discernible due to the presence of Pc3 pulsations. The *upper* diagram shows the sequence of ANN output values obtained for the input data in the *centre* diagram. The Kakioka magnetometer data (*lower*) confirms the occurrence of Pi2 signatures



**Fig. 7.** Examples where the ANN failed to identify Pi2 signatures which were visually discernible. In the *lower* example there is no evidence of the Pi2 in the ANN output. In the *upper* example there is evidence of the Pi2 in the ANN output, but it failed the selection criteria for reporting

the ANN were not identified visually; all occurred during local daytime. Five of these events were confirmed to be Pi2s by inspection of Kakioka data. However, three appeared to be non-Pi2 events; the reason for their selection by the ANN was due to enhancements in the amplitude of pre-existing Pc4 pulsation activity being interpreted as Pi2 signatures.

Table 1 indicates that a number of Pi2 signatures were identified by visual observation but not by the ANN; there were four such cases in the first data set. Inspection of the data revealed that in all cases the pulsations were of small amplitude. Two examples are illustrated in Fig. 7. In the lower example the Pi2 at 1104 UT was not detected at all by the ANN. In the upper example the Pi2 at 1801 UT was detected by the ANN, but not reported because it did not pass the selection criteria discussed previously. Inspection of the AE indices at the times of these Pi2s revealed that they were associated with extremely weak substorms, probably with a significantly contracted auroral oval. In the second data set there were twelve events which were identified visually but not by the ANN. Plots of the ANN output revealed that nine of these were in fact detected by the ANN, but rejected due to the selection criteria. If all events detected by the ANN are taken into account, as indicated by the numbers in parentheses in Table 1, then the combined success rate of the ANN is increased to 96%. An advantage of the ANN method of Pi2 identification is that if desired, the network can be trained to be more sensitive by including more small-amplitude examples in the training data set.

The ANN utilises the amplitude spectrum of pulsation events as input. Therefore, we might expect the

presence of non-Pi2 oscillations with frequencies lying in the Pi2 band to result in apparently positive identification of non-Pi2 events. In order to test this inference, the third data set was constituted of isolated days on which pulsation activity in the Pi2 frequency band occurred. Two types of activity were investigated, namely Pc4 pulsations and broad-band activity during geomagnetic storms. On two days, namely 1989 days 3 and 4, there was almost continuous Pc4 pulsation activity during local daytime at Hermanus. Scanning these two days with the ANN-S100 identified 41 events as Pi2s. Visual inspection of the pulsation data revealed a few of these events to be enhancements in amplitude of pre-existing Pc4 pulsations. Some of these enhancements were correlated with simultaneous Pi2 signatures at Kakioka in the nightside hemisphere; these were regarded to be Pi2s. However, eleven of these amplitude enhancements were not correlated with clear Pi2 signatures; these can be regarded as falsely reported Pi2s. All of these false reports were for events which occurred between 09 and 16 LT. We thus conclude that the ANN will occasionally falsely identify enhancements in the amplitude of Pc4s, which are typically daytime pulsations, as being Pi2 pulsations. If the ANN is used only for scanning data from the night-time hemisphere, this problem will be avoided. During large geomagnetic storms induction magnetometers record broad-band oscillations for much of the storm's duration. The ANN-S100 was used to scan two days of data where the K indices were all 5 or greater. For many hours the output of the neural

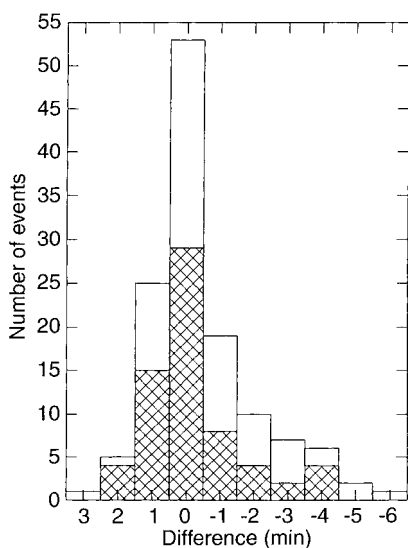
network was a sequence of +1s. We thus conclude that during large geomagnetic storms, the ANN fails as a means of identifying Pi2s. However, we point out that at such times it is also not possible visually to identify Pi2 signatures.

We next consider the timing accuracy of the ANN Pi2 identification method. In order to do this the difference between the onset times of Pi2s determined by visual inspection and by the ANN were noted. The time differences for the first two data sets are presented in Fig. 8 in the form of a histogram. It is seen that in the majority of cases the onset times determined by visual inspection and ANN scanning corresponded. In those cases where there was a difference, the majority differed only by 1 min. In a number of cases the ANN scanned onset times were four or more minutes later than those determined by visual inspection. Investigation of the cause revealed that timing errors may occur in cases where the Pi2 amplitude is very small, where the amplitude increases gradually rather than being impulsive, or when Pi2s overlap. It is in these cases that an experienced observer also has difficulty in determining an accurate onset time.

## 5 Applications

The neural-network-based process which has been developed to identify Pi2 pulsations in magnetometer data has been shown to work extremely well. It could thus serve as a useful and powerful tool in substorm research. We now briefly discuss some of the potential applications:

1. This process can be implemented in real time to identify Pi2 pulsations, and consequently substorm onsets and enhancements, as they occur. Many years ago Saito et al. (1976) proposed that by continuously



**Fig. 8.** Histogram showing the differences in onset times of Pi2 signatures determined visually and by the ANN; the signs are in the sense of visual minus ANN timing. The *cross hatched* and *plain* regions represent the differences for data sets 1 and 2, respectively

monitoring Pi2 pulsations from three low-latitude ground stations evenly spaced in longitude, the onset of most substorms could be identified. Although this suggestion had significant merit, the technology at the time was not adequate to implement easily the idea in practice. Since that time, however, significant developments have taken place. Geomagnetic data are continuously recorded in digital form at many observatories. The means exist to distribute data in near real time. More sophisticated data processing techniques have been developed. Consequently, we suggest that the idea of continuously monitoring the occurrence of substorms by utilising observations of low-latitude Pi2 pulsations could be implemented relatively easily.

2. The HMO regularly receives requests from researchers world-wide to scan its induction magnetometer data for Pi2s. Generally, the purpose of such requests is either to determine or confirm the occurrence of substorms during a specified interval of time, or to determine or confirm the onset time of a specific substorm. In the past this has been done by plotting and visually inspecting the data, which, when there are a large number of events, can be time consuming. The new process will enable this task to be done rapidly and objectively. It will be particularly useful where the identification of a large number of events from archived data, for example for statistical studies, is required.

3. The ANN process might be used to search for substorms with, or classify substorms according to, certain characteristics which are related to specific Pi2 parameters. The ANN-S100 utilised in this paper was trained to identify Pi2s with a broad range of frequencies, amplitudes, durations and shapes. However, an ANN might be trained where one or more of these parameters allow for only a narrow range of values; for example, ANN-S4 selected only large-amplitude Pi2s. An ANN might also be trained to classify Pi2s into one or more groups, for example, according to frequency. The ability to make an automated search for Pi2s with periods exceeding 100 s would have been particularly useful to Sutcliffe and Nielsen (1990) in their search for Pi2 signatures in STARE data. Because of the limited 20-s time resolution of STARE data, Sutcliffe and Nielsen (1990) first visually scanned Hermanus induction magnetometer data for Pi2s with periods exceeding 100-s. This was a time-consuming process which could have been speeded up significantly using the ANN pattern recognition method.

## 6 Conclusion

We have used the pattern recognition capabilities of artificial neural networks to develop a technique to identify Pi2 pulsations by the automated scanning of digital magnetometer data. Since low-latitude Pi2 pulsations are among the clearest indicators of magnetospheric substorm onsets and enhancements, the procedure is ideally suited to substorm onset and enhancement identification. We have shown the procedure to be extremely reliable and pointed out a number



of applications. In future work we plan to train ANNs to identify Pi2 pulsations with specific parameters and then to evaluate this as a procedure for the characterisation of substorms.

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