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# HILBERT DOMAINS QUASI-ISOMETRIC TO NORMED VECTOR SPACES 

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#### Abstract

We prove that a Hilbert domain which is quasi-isometric to a normed vector space is actually a convex polytope.


## 1. Introduction

A Hilbert domain in $\mathbf{R}^{m}$ is a metric space $\left(\mathcal{C}, d_{\mathcal{C}}\right)$, where $\mathcal{C}$ is an open bounded convex set in $\mathbf{R}^{m}$ and $d_{\mathcal{C}}$ is the distance function on $\mathcal{C}$ - called the Hilbert metric - defined as follows.
Given two distinct points $p$ and $q$ in $\mathcal{C}$, let $a$ and $b$ be the intersection points of the straight line defined by $p$ and $q$ with $\partial \mathcal{C}$ so that $p=(1-s) a+s b$ and $q=(1-t) a+t b$ with $0<s<t<1$. Then

$$
d_{\mathcal{C}}(p, q):=\frac{1}{2} \ln [a, p, q, b],
$$

where

$$
[a, p, q, b]:=\frac{1-s}{s} \times \frac{t}{1-t}>1
$$

is the cross ratio of the 4 -tuple of ordered collinear points $(a, p, q, b)$.
We complete the definition by setting $d_{\mathcal{C}}(p, p):=0$.


The metric space $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ thus obtained is a complete non-compact geodesic metric space whose topology is the one induced by the canonical topology of $\mathbf{R}^{m}$ and in which the affine open segments joining two points of the boundary $\partial \mathcal{C}$ are geodesics that are isometric to $(\mathbf{R},|\cdot|)$.

For further information about Hilbert geometry, we refer to [3, 6, 8, (10] and the excellent introduction [14] by Socié-Méthou.

The two fundamental examples of Hilbert domains $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ in $\mathbf{R}^{m}$ correspond to the case when $\mathcal{C}$ is an ellipsoid, which gives the Klein model of $m$-dimensional hyperbolic geometry (see for

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example [14, first chapter]), and the case when $\overline{\mathcal{C}}$ is a $m$-simplex, for which there exists a norm $\|\cdot\|_{\mathcal{C}}$ on $\mathbf{R}^{m}$ such that $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ is isometric to the normed vector space $\left(\mathbf{R}^{m},\|\cdot\|_{\mathcal{C}}\right)$ (see [7, pages 110-113] or [13, pages 22-23]).

Much has been done to study the similarities between Hilbert and hyperbolic geometries (see for example [6], [15] or [1]), but little literature deals with the question of knowing to what extend a Hilbert geometry is close to that of a normed vector space. So let us mention two results in this latter direction which are relevant for our present work.
Theorem 1.1 ([9], Theorem 2). A Hilbert domain $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ in $\mathbf{R}^{m}$ is isometric to a normed vector space if and only if $\mathcal{C}$ is the interior of a m-simplex.

Theorem 1.2 ([5], Theorem 3.1). If $\mathcal{C}$ is an open bounded convex polygonal set in $\mathbf{R}^{2}$, then $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ is Lipschitz equivalent to Euclidean plane.

In light of these two results, it is natural to ask whether the converse of Theorem 1.2 holds. In other words, if a Hilbert domain $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ in $\mathbf{R}^{m}$ is quasi-isometric to a normed vector space, what can be said about $\mathcal{C}$ ? Here, by quasi-isometric we mean the following (see [2]):

Definition 1.1. Given real numbers $A \geqslant 1$ and $B \geqslant 0$, a metric space $(S, d)$ is said to be $(A, B)$ -quasi-isometric to a normed vector space $(V,\|\cdot\|)$ if and only if there exists a map $f: S \longrightarrow V$ such that

$$
\frac{1}{A} d(p, q)-B \leqslant\|f(p)-f(q)\| \leqslant A d(p, q)+B
$$

for all $p, q \in S$.

Recalling that a convex polytope in $\mathbf{R}^{m}$ is the convex hull of a finite set of points whose linear span is the whole space $\mathbf{R}^{m}$, we then show

Theorem 1.3. If a Hilbert domain $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ in $\mathbf{R}^{m}$ is $(A, B)$-quasi-isometric to a normed vector space $(V,\|\cdot\|)$ for some real constants $A \geqslant 1$ and $B \geqslant 0$, then $\mathcal{C}$ is the interior of a convex polytope.

## 2. Proof of Theorem 1.3

The proof of Theorem 1.3 is based on an idea developed by Förtsch and Karlsson in their paper (9].

It needs the following fact due to Karlsson and Noskov:
Theorem 2.1 ( $\mathbb{1 1 ]}$, Theorem 5.2). Let $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ be a Hilbert domain in $\mathbf{R}^{m}$ and $x, y \in \partial \mathcal{C}$ such that $[x, y] \nsubseteq \partial \mathcal{C}$. Then, given a point $p_{0} \in \mathcal{C}$, there exists a constant $K=K\left(p_{0}, x, y\right)>0$ satisfying

$$
d_{\mathcal{C}}\left(x_{n}, y_{n}\right) \geqslant d_{\mathcal{C}}\left(x_{n}, p_{0}\right)+d_{\mathcal{C}}\left(x_{n}, p_{0}\right)-K
$$

for all sequences $\left(x_{n}\right)_{n \in \mathbf{N}}$ and $\left(y_{n}\right)_{n \in \mathbf{N}}$ in $\mathcal{C}$ that converge respectively to $x$ and $y$ in $\mathbf{R}^{m}$.

Now, here is the key result which gives the proof of Theorem 1.3:

Proposition 2.1. Let $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ be a Hilbert domain in $\mathbf{R}^{m}$ which is $(A, B)$-quasi-isometric to a normed vector space $(V,\|\cdot\|)$ for some real constants $A \geqslant 1$ and $B \geqslant 0$.
Then, if $N=N(A,\|\cdot\|)$ denotes the maximum number of points in the ball $\{v \in V \mid\|v\| \leqslant 2 A\}$ whose pairwise distances with respect to $\|\cdot\|$ are greater than or equal to $1 /(2 A)$, and if $X \subseteq \partial \mathcal{C}$ is such that $[x, y] \nsubseteq \partial \mathcal{C}$ for all $x, y \in X$ with $x \neq y$, we have

$$
\operatorname{card}(X) \leqslant N .
$$

Proof.
Let $f: \mathcal{C} \longrightarrow V$ such that

$$
\begin{equation*}
\frac{1}{A} d_{\mathcal{C}}(p, q)-B \leqslant\|f(p)-f(q)\| \leqslant A d_{\mathcal{C}}(p, q)+B \tag{2.1}
\end{equation*}
$$

for all $p, q \in \mathcal{C}$.
First of all, up to translations, we may assume that $0 \in \mathcal{C}$ and $f(0)=0$.
Then suppose that there exists a subset $X$ of the boundary $\partial \mathcal{C}$ such that $[x, y] \nsubseteq \partial \mathcal{C}$ for all $x, y \in X$ with $x \neq y$ and $\operatorname{card}(X) \geqslant N+1$. So, pick $N+1$ distinct points $x_{1}, \ldots, x_{N+1}$ in $X$, and for each $k \in\{1, \ldots, N+1\}$, let $\gamma_{k}:[0,+\infty) \longrightarrow \mathcal{C}$ be a geodesic of $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ that satisfies $\gamma_{k}(0)=0, \lim _{t \rightarrow+\infty} \gamma_{k}(t)=x_{k}$ in $\mathbf{R}^{m}$ and $d_{\mathcal{C}}\left(0, \gamma_{k}(t)\right)=t$ for all $t \geqslant 0$.
This implies that for all integers $n \geqslant 1$ and every $k \in\{1, \ldots, N+1\}$, we have

$$
\begin{equation*}
\left\|\frac{f\left(\gamma_{k}(n)\right)}{n}\right\| \leqslant A+\frac{B}{n} \tag{2.2}
\end{equation*}
$$

from the second inequality in Equation 2.1 with $p=\gamma_{k}(n)$ and $q=0$.
On the other hand, Theorem 2.1 yields

$$
d_{\mathcal{C}}\left(\gamma_{i}(n), \gamma_{j}(n)\right) \geqslant 2 n-K\left(0, x_{i}, x_{j}\right)
$$

for all integers $n \geqslant 1$ and every $i, j \in\{1, \ldots, N+1\}$ with $i \neq j$, and hence

$$
\begin{equation*}
\left\|\frac{f\left(\gamma_{i}(n)\right)}{n}-\frac{f\left(\gamma_{j}(n)\right)}{n}\right\| \geqslant \frac{2}{A}-\frac{1}{n}\left(\frac{K\left(0, x_{i}, x_{j}\right)}{A}-B\right) \tag{2.3}
\end{equation*}
$$

from the first inequality in Equation 2.1 with $p=\gamma_{i}(n)$ and $q=\gamma_{j}(n)$.
Now, fixing an integer $n \geqslant \max \left\{B / A, K\left(0, x_{i}, x_{j}\right)-B / A\right\}$, we get

$$
\left\|\frac{f\left(\gamma_{k}(n)\right)}{n}\right\| \leqslant 2 A
$$

for all $k \in\{1, \ldots, N+1\}$ by Equation 2.2 together with

$$
\left\|\frac{f\left(\gamma_{i}(n)\right)}{n}-\frac{f\left(\gamma_{j}(n)\right)}{n}\right\| \geqslant \frac{1}{2 A}
$$

for all $i, j \in\{1, \ldots, N+1\}$ with $i \neq j$ by Equation 2.3.
But this contradicts the definition of $N=N(A,\|\cdot\|)$.
Therefore, Proposition 2.1 is proved.

Remark. Given $v \in V$ such that $\|v\|=2 A$, we have $\|-v\|=2 A$ and $\|v-(-v)\|=2\|v\|=$ $4 A \geqslant 1 /(2 A)$, which proves that $N \geqslant 2$.

The second ingredient we will need for the proof of Theorem 1.3 is the following:
Proposition 2.2. Let $\mathcal{C}$ be an open bounded convex set in $\mathbf{R}^{2}$.
If there exists a nonempty finite subset $Y$ of the boundary $\partial \mathcal{C}$ such that for every $x \in \partial \mathcal{C}$ one can find $y \in Y$ with $[x, y] \subseteq \partial \mathcal{C}$, then $\overline{\mathcal{C}}$ is a polygon.

Proof.
Assume $0 \in \mathcal{C}$ and let us consider the continuous map $\pi: \mathbf{R} \longrightarrow \partial \mathcal{C}$ which assigns to each $\theta \in \mathbf{R}$ the unique intersection point $\pi(\theta)$ of $\partial \mathcal{C}$ with the half-line $\mathbf{R}_{+}^{*}(\cos \theta, \sin \theta)$.
For each pair $\left(x_{1}, x_{2}\right) \in \partial \mathcal{C} \times \partial \mathcal{C}$, denote by $A\left(x_{1}, x_{2}\right) \subseteq \partial \mathcal{C}$ the arc segment defined by $A\left(x_{1}, x_{2}\right)=\pi\left(\left[\theta_{1}, \theta_{2}\right]\right)$, where $\theta_{1}$ and $\theta_{2}$ are the unique real numbers such that $\pi\left(\theta_{1}\right)=x_{1}$ with $\theta_{1} \in[0,2 \pi)$ and $\pi\left(\theta_{2}\right)=x_{2}$ with $\theta_{1} \leqslant \theta_{2}<\theta_{1}+2 \pi$.
We shall prove Proposition 2.2 by induction on $n:=\operatorname{card}(Y) \geqslant 1$.
Before doing this, notice that adding a point of $\partial \mathcal{C}$ to $Y$ does not change $Y$ 's property, and therefore we may assume that $n \geqslant 2$.
If $n=2$, writting $Y=\left\{x_{1}, x_{2}\right\}$, we have that for all $x \in \partial \mathcal{C},\left[x, x_{1}\right] \subseteq \partial \mathcal{C}$ or $\left[x, x_{2}\right] \subseteq \partial \mathcal{C}$.
Let $\theta_{1} \in[0,2 \pi)$ and $\theta_{2} \in\left[\theta_{1}, \theta_{1}+2 \pi\right)$ such that $\pi\left(\theta_{1}\right)=x_{1}$ and $\pi\left(\theta_{2}\right)=x_{2}$, and define $\alpha_{0}:=\max \left\{\theta \in\left[\theta_{1}, \theta_{2}\right] \mid\left[x_{1}, \pi(\theta)\right] \subseteq \partial \mathcal{C}\right\}$.
Then $A\left(x_{1}, x_{2}\right)=\left[x_{1}, \pi\left(\alpha_{0}\right)\right] \cup\left[\pi\left(\alpha_{0}\right), x_{2}\right]$. Hence, $A\left(x_{1}, x_{2}\right)$ is the union of two affine segments, and the same holds for $A\left(x_{2}, x_{1}\right)$.
Since $\partial \mathcal{C}=A\left(x_{1}, x_{2}\right) \cup A\left(x_{2}, x_{1}\right)$, this implies that $\partial \mathcal{C}$ is a union of four affine segments in $\mathbf{R}^{2}$, and therefore $\overline{\mathcal{C}}$ is a polygon (quadrilateral or triangle).
Now, assume Proposition 2.2 is true for some $n \geqslant 2$, and let $Y$ such that $\operatorname{card}(Y)=n+1$.
Write $Y=\left\{x_{1}, \ldots, x_{n+1}\right\}$ with $x_{1}=\pi\left(\theta_{1}\right), x_{2}=\pi\left(\theta_{2}\right), \ldots, x_{n+1}=\pi\left(\theta_{n+1}\right)$, where $\theta_{1} \in[0,2 \pi)$ and $\theta_{1}<\theta_{2}<\cdots<\theta_{n+1}<\theta_{n+2}=\theta_{1}+2 \pi$.
Then, defining $x_{n+2}:=\pi\left(\theta_{n+2}\right)=x_{1}$, we shall consider two cases.

- Case 1: Suppose for every $k \in\{1, \ldots, n+1\}$ and all $x \in A\left(x_{k}, x_{k+1}\right)$, we have $\left[x, x_{k}\right] \subseteq \partial \mathcal{C}$ or $\left[x, x_{k+1}\right] \subseteq \partial \mathcal{C}$.
Considering $\alpha_{k}:=\max \left\{\theta \in\left[\theta_{k}, \theta_{k+1}\right] \mid\left[x_{k}, \pi(\theta)\right] \subseteq \partial \mathcal{C}\right\}$, then we get $A\left(x_{k}, x_{k+1}\right)=\left[x_{k}, \pi\left(\alpha_{k}\right)\right] \cup$ $\left[\pi\left(\alpha_{k}\right), x_{k+1}\right]$.
Since $\partial \mathcal{C}=\bigcup_{k=1}^{n+1} A\left(x_{k}, x_{k+1}\right)$, this implies that $\partial \mathcal{C}$ is a finite union of affine segments in $\mathbf{R}^{2}$, and thus $\overline{\mathcal{C}}$ is a polygon.
- Case 2: Suppose there exist $k \in\{1, \ldots, n+1\}$ - we may assume to be equal to $n+1$ up to permutations - and $x_{0} \in A\left(x_{k}, x_{k+1}\right)=A\left(x_{n+1}, x_{1}\right)$ such that $x_{0} \notin\left\{x_{1}, x_{n+1}\right\}$ and $\left[x_{0}, x_{i}\right] \subseteq \partial \mathcal{C}$ for some $i \in\{2, \ldots, n\}$.
Then $\mathcal{C}$ is contained in one of the two open half-planes in $\mathbf{R}^{2}$ bounded by the line passing through the points $x_{0}$ and $x_{i}$, and hence either $A\left(x_{0}, x_{i}\right)=\left[x_{0}, x_{i}\right]$, or $A\left(x_{i}, x_{0}\right)=\left[x_{0}, x_{i}\right]$.
But $x_{1} \in A\left(x_{0}, x_{i}\right)$ and $x_{n+1} \in A\left(x_{i}, x_{0}\right)$, so we get either $x_{1} \in\left[x_{0}, x_{i}\right] \subseteq \partial \mathcal{C}$, or $x_{n+1} \in\left[x_{0}, x_{i}\right] \subseteq$ $\partial \mathcal{C}$. And this implies that $Y$ can be replaced by $Y \backslash\left\{x_{1}\right\}$ or $Y \backslash\left\{x_{n+1}\right\}$ in the hypothesis of Proposition 2.2.
Since $\operatorname{card}\left(Y \backslash\left\{x_{1}\right\}\right)=\operatorname{card}\left(Y \backslash\left\{x_{n+1}\right\}\right)=n$, we get that Proposition 2.2 is true for $n+1$.
This finishes the proof of Proposition 2.2 by induction.

Before proving Theorem 1.3, let us recall the following useful result, where a convex polyhedron in $\mathbf{R}^{m}$ is the intersection of a finite number of closed half-spaces:
Theorem 2.2 ([1]2], Theorem 4.7). Let $K$ be a convex set in $\mathbf{R}^{m}$ and $p \in \stackrel{\circ}{K}$.
Then $K$ is a convex polyhedron if and only if all its plane sections containing $p$ are convex polyhedra.

## Proof of Theorem 1.3 .

Let $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ be a nonempty Hilbert domain in $\mathbf{R}^{m}$ that is $(A, B)$-quasi-isometric to a normed vector space $(V,\|\cdot\|)$ for some real constants $A \geqslant 1$ and $B \geqslant 0$.
According to Theorem 2.2, it suffices to prove Theorem 1.3 for $m=2$ since any plane section of $\mathcal{C}$ gives rise to a 2-dimensional Hilbert domain which is also $(A, B)$-quasi-isometric to $(V,\|\cdot\|)$. So, let $m=2$, and consider the set $\mathcal{E}:=\{X \subseteq \partial \mathcal{C} \mid[x, y] \nsubseteq \partial \mathcal{C}$ for all $x, y \in X$ with $x \neq y\}$.
It is not empty since $\{x, y\} \in \mathcal{E}$ for some $x, y \in \partial \mathcal{C}$ with $x \neq y$ (indeed, $\mathcal{C}$ is a nonempty open set in $\mathbf{R}^{2}$ ), which implies together with Proposition 2.1 that $n: \max \{\operatorname{card}(X) \mid X \in \mathcal{E}\}$ does exist and satisfies $2 \leqslant n \leqslant N$ (recall that $N \geqslant 2$ ).
Then pick $Y \in \mathcal{E}$ such that $\operatorname{card}(Y)=n$, write $Y=\left\{x_{1}, \ldots, x_{n}\right\}$, and prove that for every $x \in \partial \mathcal{C}$ one can find $k \in\{1, \ldots, n\}$ such that $\left[x, x_{k}\right] \subseteq \partial \mathcal{C}$.
Owing to Proposition 2.2, this will show that $\overline{\mathcal{C}}$ is a polygon.
So, suppose that there exists $x_{0} \in \partial \mathcal{C}$ satisfying $\left[x_{0}, x_{k}\right] \nsubseteq \partial \mathcal{C}$ for all $k \in\{1, \ldots, n\}$, and let us find a contradiction by considering $Z:=Y \cup\left\{x_{0}\right\}$.
First, since $x_{0} \neq x_{k}$ for all $k \in\{1, \ldots, n\}$ (if not, we would get an index $k \in\{1, \ldots, n\}$ such that $\left[x_{0}, x_{k}\right]=\left\{x_{0}\right\} \subseteq \partial \mathcal{C}$, which is false), we have $x_{0} \notin Y$. Hence $\operatorname{card}(Z)=n+1$.
Next, since $Y \in \mathcal{E}$ and $\left[x_{0}, x_{k}\right] \nsubseteq \partial \mathcal{C}$ for all $k \in\{1, \ldots, n\}$, we have $Z \in \mathcal{E}$.
Therefore, the assumption of the existence of $x_{0}$ yields a set $Z \in \mathcal{E}$ whose cardinality is greater than that of $Y$, which contradicts the very definition of $Y$.
Conclusion: $\overline{\mathcal{C}}$ is a polygon, and this proves Theorem 1.3.
Let us conclude by a natural question: Considering Theorem 1.1 by Förtsch and Karlsson, we may conjecture that if the quasi-isometry in Theorem 1.3 is close to an isometry, then $\mathcal{C}$ is the interior of a $m$-simplex. More precisely, does there exist a sufficiently small constant $A_{0}=A_{0}(m) \geqslant 1$ such that if a Hilbert domain $\left(\mathcal{C}, d_{\mathcal{C}}\right)$ in $\mathbf{R}^{m}$ is $(A, B)$-quasi-isometric to a normed vector space for some constants $A=A(m, \mathcal{C}) \in\left[1, A_{0}\right]$ and $B=B(m, \mathcal{C}) \geqslant 0$, then $\mathcal{C}$ is the interior of a $m$-simplex?

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