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# Width of the analyticity strip in space variable of viscous Burgers shockwaves 

Cédric Lejard<br>Université Paris 6 - Pierre et Marie Curie<br>Institut de Mathématiques de Jussieu<br>175 rue du Chevaleret<br>F75013 PARIS, FRANCE<br>lejard@math.jussieu.fr

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#### Abstract

Analytic continuation of viscous shock solution for the generalized Burgers equation with polynomial nonlinear source term is investigated. We show that a pertubated wave recovers its analyticity in the space variable in the strip limited by the first pair of conjugate poles of the wave.


## 1 Introduction

Nonlinear parabolic evolution partial differential equations arise in various fields such as fluids mechanics, traffic flow modelling, mathematical biology and economics. Burgers' equation is one of the most popular of such type of equation, it was first introduced by Bateman [1] and deeply studied by Burgers [3] as a one-dimensional model for turbulence. It received since a constant mathematical interest from which Hopf's study [6] may be particularly outlined. Consider the Cauchy problem for generalized Burgers' equation (GBE):

$$
\begin{align*}
& \frac{\partial f(x, t)}{\partial t}+\frac{\partial \Phi(f(x, t))}{\partial x}=\nu \frac{\partial^{2} f(x, t)}{\partial x^{2}}  \tag{1}\\
& f(x, t=0)=f_{0}(x) \rightarrow \alpha_{ \pm}, x \rightarrow \alpha_{ \pm}, \alpha_{+}>\alpha_{-}
\end{align*}
$$

If $\Phi$ is a function which satisfies the Gelfand-Oleinik (cf. (7) and 12]) entropy condition :

$$
\begin{equation*}
\forall u \in\left[\alpha_{-}, \alpha_{+}\right], \quad c=\frac{\Phi\left(\alpha_{+}\right)-\Phi\left(\alpha_{-}\right)}{\alpha_{+}-\alpha_{-}}<\frac{\Phi(u)-\Phi\left(\alpha_{-}\right)}{\alpha_{+}-\alpha_{-}} \tag{2}
\end{equation*}
$$

this equation enables propagation of shockwaves $\tilde{f}(x-c t+d)$, solving the ordinary differential equation :

$$
\begin{equation*}
-c \tilde{f}(x)+\Phi(\tilde{f}(x))+k=\nu \tilde{f}^{\prime}(x), \quad \tilde{f}( \pm \infty)=\alpha_{ \pm} \tag{3}
\end{equation*}
$$

Example of such $\Phi$ are given by concave function on the interval $\left[\alpha_{-}, \alpha_{+}\right]$. If in addition, $\Phi$ satisfies the Lax condition,

$$
\begin{equation*}
\Phi^{\prime}\left(\alpha_{+}\right)<c<\Phi^{\prime}\left(\alpha_{-}\right) \tag{4}
\end{equation*}
$$

the wave is said to be characteristic, and in this case, the large time asymptotics of the Cauchy problem (1) are the shifted waves $\tilde{f}(x-c t+d)$. In our study, $\Phi$ is assumed to be polynomial. Its degree will be denoted $n$. In the particular case $\Phi(u)=-\frac{u^{2}}{2}$, which will be refered further to as the classical case, the wave has the explicit expression :

$$
\begin{equation*}
\tilde{f}(x)=c+\frac{\alpha_{+}-\alpha_{-}}{2} \tanh \left((x+d) \frac{\alpha_{+}-\alpha_{-}}{4 \nu}\right) \tag{5}
\end{equation*}
$$

the celerity $c$ and the constant $k$ being constrained by the limits $\tilde{f}( \pm \infty)=\alpha_{ \pm}$ :

$$
\begin{align*}
& c=\frac{\Phi\left(\alpha_{+}\right)-\Phi\left(\alpha_{-}\right)}{\alpha_{+}-\alpha_{-}} \\
& k=\frac{\alpha_{-} \Phi\left(\alpha_{+}\right)-\alpha_{+} \Phi\left(\alpha_{-}\right)}{\alpha_{+}-\alpha_{-}} \tag{6}
\end{align*}
$$

The shift $d$ may be assumed to be zero up to a space translation of the initial data $f_{0}$. The aim of this note is to figure out how the width of the analyticity strip of the solution $f(x, t)$ is matching the width $y_{0}\left(=\frac{2 \nu \pi}{\alpha_{+}-\alpha_{-}}\right.$for the classical case) of the analyticity strip of its asymptotic regime $\tilde{f}(x-c t)$. For NavierStokes equations, the analyticity radius of the solutions is known to increase provided that the initial data lies in a functional space that forces it to be zero at infinity. More precisely,

- Foias and Temam [4] considered space-periodic solutions and proved that the width of the analyticity strip increases like $\sqrt{t}$ provided the initial data belongs to the Sobolev space $H^{1}$ and that the $H^{1}$-norm of the solution remains uniformly bounded in time. They used Gevrey-norm estimates.
- Grujic and Kukavica [8] proved the analyticity of local-in-time solutions with initial data lying in a $L^{p}\left(\mathbb{R}^{n}\right)$-space and also estimated the growth of the width analyticity strip as $\sqrt{t}$.
- Lemarié-Rieusset 11] has also proved a $\sqrt{t}$-growth for solutions with initial data in $S^{\prime}\left(\mathbb{R}^{3}\right)$ using techniques from harmonic analysis.

Classical Burgers equation may be seen as a 1D version of Navier-Stokes equation. We stress that the width of the analyticity strip does not increase indefinitely if the overfall $\alpha_{+}-\alpha_{-}$of the shockwave does not vanish.

The author wishes to thank G. M. Henkin, his thesis supervisor, to have shared with him this quite interesting problem.

## 2 Statement of the result

Theorem. Let $f(x, t)$ be a solution of Burgers' equation with initial condition $f_{0}(x)$ such that $\left|f_{0}(x)-\tilde{f}(x)\right|={ }_{x \rightarrow \pm \infty} \mathcal{O}\left(e^{-\alpha x}\right)$ for some $\alpha>0$. For all $\left.\left.\varepsilon \in\right] 0,1\right]$, there exists $T^{*}>0$ and $M>0$ such that $f(x, t)$ extends holomorphically in variable $z=x+i y$ in the strip $|y|<\min \left(y_{0}(1-\varepsilon), M \sqrt{\nu\left(t-T^{*}\right)}\right)$ for $t>T^{*}$, where $\pm i y_{0}$ are the closest pole of the real axis of the wave $\tilde{f}$

Remark 1 : This theorem means that after a transient regime, the width of the analycity strip of a perturbation of a viscous Burgers shockwave is bounded from below by a non decreasing function of time converging monotonically to the width of the analycity strip of the wave.
Remark 2 : The proof uses Kato's contraction argument for solving NavierStokes equation [9], some elements of Sattinger's stability theory of waves 113] and estimates on the convergence rate in time of the real solution to its asymptotic wave (5], (14].
Remark 3 : At the limit $\nu=0$, the solutions develop a discontinuity called the inviscid shockwave, this phenomenon can be studied as a result of the loss of analyticity, as proposed by Bessis and Fournier in [2]. Poles are staying away from the real axis so far the viscosity does not vanish.

## 3 Analytic property of waves

The celerity $c$ may assumed to be zero, as $\Phi(u)$ may be replaced by $\Phi(u)-c u$ without loss of generality. Traveling waves are solutions of an ordinary differential equation :

$$
\begin{equation*}
\frac{\tilde{f}^{\prime}}{\Phi(\tilde{f})-\Phi\left(\alpha_{ \pm}\right)}=\frac{1}{\nu} \tag{7}
\end{equation*}
$$

which can be rewritten :

$$
\begin{equation*}
\Psi(\tilde{f}(z))=\frac{z}{\nu} \tag{8}
\end{equation*}
$$

where $\Psi(\tilde{f})=\int_{\tilde{f}(0)}^{\tilde{f}} \frac{d F}{\Phi(F)-\Phi\left(\alpha_{ \pm}\right)}$is a holomorphic primitive, which is multivalued caused to the roots $F_{j}$ of the equation $\Phi(F)=\Phi\left(\alpha_{ \pm}\right)$. Poles of $\tilde{f}$ are therefore of the form :

$$
\begin{equation*}
z_{p}=z_{0} \nu \quad \bmod \quad 2 i \pi \nu \cdot \operatorname{Res}\left(\frac{1}{\Phi(F)-\Phi\left(\alpha_{ \pm}\right)}, F=F_{j}\right) \tag{9}
\end{equation*}
$$

where $z_{0}=x_{0}+i y_{0}$ are finite limit value of $\Psi(F)$ when $F \in \mathbb{C}$ is approaching infinity. Define :

$$
\begin{align*}
w(i y) & =\exp \left(-\frac{1}{2} \int_{0}^{i y} \Phi^{\prime}(\tilde{f}(\eta)) d \eta\right)=\exp \left(-\frac{1}{2} \int_{0}^{i y} \frac{\tilde{f}^{\prime \prime}(\eta)}{\tilde{f}^{\prime}(\eta)} d \eta\right)  \tag{10}\\
& =\frac{1}{\left|\tilde{f}^{\prime}(i y)\right|^{\frac{1}{2}}}=\frac{1}{\left|\Phi(\tilde{f}(i y))-\Phi\left(\alpha_{+}\right)\right|^{\frac{1}{2}}}
\end{align*}
$$

Consequently the quantities $\left|\tilde{f}^{\prime}(i y)\right|^{1 / 2} w(i y),|\Phi(\tilde{f})|^{1 / 2} w(i y)$ and $|\tilde{f}(i y)|^{n / 2} w(i y)$ are bounded function of $y$ in the interval $|y|<y_{0}$.

## 4 Analyticity of solutions

### 4.1 Weighted norm approach

The function $f(x, t)=\tilde{f}(x)+h(x, t)$ solves (1) if $h(x, t)$ solves :

$$
\begin{equation*}
\frac{\partial h(x, t)}{\partial t}+\frac{\partial \Phi^{\prime}(\tilde{f}(x)) h(x, t)}{\partial x}-\frac{\partial^{2} h(x, t)}{\partial x^{2}}=-\frac{\partial R(\tilde{f}, h)}{\partial x} \tag{11}
\end{equation*}
$$

with initial data $h_{0}(x)=f(x)-\tilde{f}(x) . \quad R(\tilde{f}, h)=\Phi(\tilde{f}+h)-\Phi(\tilde{f})-\Phi^{\prime}(\tilde{f}) \cdot f$. The potential $H(x, t)=\int_{-\infty}^{x} h(\eta, t) d \eta$ solves the partial differential equation :

$$
\begin{equation*}
L H(x, t)=\frac{\partial H(x, t)}{\partial t}+\Phi^{\prime}(\tilde{f}(x)) \frac{\partial H(x, t)}{\partial x}-\frac{\partial^{2} H(x, t)}{\partial x^{2}}=-R\left(\tilde{f}, \frac{\partial H}{\partial \xi}\right) \tag{12}
\end{equation*}
$$

with initial data $H_{0}(x)=\int_{-\infty}^{x} h_{0}(\eta) d \eta$, yielding the integral equation :

$$
\begin{equation*}
H(x, t)=F_{0}(x, t)-\int_{0}^{t} d \tau \int_{-\infty}^{+\infty} G(x, t-\tau ; \xi) R\left(\tilde{f}, \frac{\partial H}{\partial \xi}\right) d \xi \tag{13}
\end{equation*}
$$

where $F_{0}=\int_{-\infty}^{\infty} G(x, t ; \xi) H_{0}(\xi) d \xi$ and $G(x, t ; \tau)$ is the Green function of the linearized operator $L$. Differentiating wrt $x$, we get the integral equation solved by $h(x, t)$.

$$
\begin{equation*}
h(x, t)=\partial_{x} F_{0}(x, t)-\int_{0}^{t} d \tau \int_{-\infty}^{+\infty} G(x, t-\tau ; \xi) R(\tilde{f}(\xi), h(\xi, \tau)) d \xi \tag{14}
\end{equation*}
$$

Following Sattinger [13], the Green function $G$ of the operator $L$ in the above integral equation may be expressed as :

Proposition 1. The Green function $G(x, t ; \xi)$ of the linearized operator $L$ has the expression :

$$
\begin{equation*}
G(x, t ; \xi)=\frac{w(\xi)}{w(x)} K(x, t ; \xi) \tag{15}
\end{equation*}
$$

where $w$ stands for the weight function

$$
\begin{equation*}
w(x)=\exp \left(\frac{1}{2} \int_{0}^{x} \Phi^{\prime}(\tilde{f}(\eta)) d \eta\right) \tag{16}
\end{equation*}
$$

and $K(x, t ; \xi)$ for the Green function of the operator :

$$
\begin{equation*}
\mathcal{M} u(x, t)=\frac{\partial u(x, t)}{\partial t}-\frac{\partial^{2} u(x, t)}{\partial x^{2}}-\frac{1}{2}\left(\tilde{f}^{\prime}(x) \Phi^{\prime \prime}(\tilde{f}(x))+\frac{1}{2} \Phi^{\prime}(\tilde{f})^{2}\right) u(x, t) \tag{17}
\end{equation*}
$$

Proof. direct check
Definition. Denote $m(y, t)=\operatorname{sgn}(y) \min (|y|, M \sqrt{t})$ and $\Delta_{c}=\{x+i y:|y|<c\}$. Introduce the following functional spaces :

- the weighted Hardy Space

$$
\begin{aligned}
& \mathcal{H}_{w, a, b}^{2}\left(\Delta_{c}\right)=\left\{u \in \mathcal{O}\left(\Delta_{c}\right): u(\mathbb{R}) \subset \mathbb{R}, \quad\|u\|_{\mathcal{H}_{w, a, b}^{2}\left(\Delta_{c}\right)}=\right. \\
& \left.\sup _{0 \leq y<c} \frac{|w(i y)|^{a}}{\left(\sqrt{c-|y|)}^{b}\right.}\left(\int_{-\infty}^{\infty}|w(\xi+i y)| \cdot|u(\xi+i y, t)|^{2} d \xi\right)^{1 / 2}<\infty\right\}
\end{aligned}
$$

with norm $\|\cdot\|_{\mathcal{H}_{w, a, b}^{2}\left(\Delta_{c}\right)}$.

- the Banach space $\mathcal{B}_{\varepsilon, T}$ of holomorphic functions $f(., t), 0<t \leq T$ in the strip $\left.\Delta_{m\left(y_{0}(1-\varepsilon), t\right)}\right)$ with norm $\|\cdot\|_{\varepsilon, T}$ defined as

$$
\|h\|_{\varepsilon, T}=\sup _{0<t \leq T} t^{\frac{1}{4(n-1)}}\|h(., t)\|_{\mathcal{H}_{w, a_{n}, b_{n}}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), t\right)}\right)}<\infty
$$

where,

$$
\begin{align*}
& a_{n}=\frac{2}{n}-\frac{5}{2} \\
& b_{n}=\frac{n-2}{n-1} \tag{18}
\end{align*}
$$

The forthcomming proposition is also inspired by Sattinger with some modifications:

- Estimates of the analytic continuation of the Green function $K$ in spaces variables are needed.
- These estimates are realized in a weighted $L^{2}$-Hardy norm as introduced in the previous definition and not in a first order weighted Sobolev in supremum norm as in Sattinger's work.

Proposition 2. The kernel $K(x, t ; \xi)$ is analytic in variable $x$ and $\xi$ in the strip $\Delta_{m\left(y_{0}, M \sqrt{t}\right)}$ and satisfies the following estimates :

$$
\begin{align*}
& \left\|\int_{0}^{\infty} K(x+i y, t, \xi+i \eta) w(\xi+i \eta) h(\xi+i \eta)^{2} d \xi\right\|_{L^{2}(d x)} \\
& \leq e^{\frac{(y-\eta)^{2}}{4 t}} \frac{\text { const. } e^{-\omega t}}{t^{\frac{1}{4}}}\left\|w^{\frac{1}{2}} \cdot h\right\|_{\mathcal{H}_{w, 0,0}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), t\right)}\right)} \\
& \left\|\int_{0}^{\infty} \partial_{x} K(x+i y, t, \xi+i \eta) w(\xi+i \eta) h(\xi+i \eta)^{2} d \xi\right\|_{L^{2}(d x)}  \tag{19}\\
& \leq e^{\frac{(y-\eta)^{2}}{4 t}} \frac{\text { const. } e^{-\omega t}}{t^{\frac{3}{4}}}\left\|w^{\frac{1}{2}} \cdot h\right\|_{\mathcal{H}_{w, 0,0}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), t\right)}\right)}^{2}
\end{align*}
$$

Remark: In a supremum type Hardy space $\mathcal{H}^{\infty}$ equipped with norm of the form $\|f\|_{\mathcal{H} \infty}=\sup _{|y|<\left|m\left(y_{0}, M \sqrt{t}\right)\right|} \sup _{x \in \mathbb{R}}|w(x+i y)|^{1 / 2}|f(x+i y)|$, the yielded estimates for the kernel and its derivative behave respectively as $t^{-1 / 2}$ and $t^{-1}$ as $t$ goes to zero, breaking convergence of the iterative argument for the solving of the nonlinear integral equation.

Proof. Consider the eigenfunctions equation for the ordinary linear operator $A u=u^{\prime \prime}+p(x):$

$$
\begin{equation*}
u^{\prime \prime}+p(x) u=\lambda u \tag{20}
\end{equation*}
$$

Look for a solution exhibiting the following asymptotic behaviour as $x \rightarrow \pm \infty$ :

$$
\begin{align*}
& \varphi_{+}(x, \lambda)=e^{-\gamma_{+}(\lambda) x} a_{+}(x, \lambda), \quad x \rightarrow \infty \\
& \varphi_{-}(x, \lambda)=e^{\gamma_{-}(\lambda) x} a_{-}(x, \lambda), \quad x \rightarrow-\infty \tag{21}
\end{align*}
$$

Where,

$$
\begin{align*}
& \gamma_{ \pm}(\lambda)=\sqrt{\lambda-p_{ \pm}} \\
& p_{ \pm}=\lim _{x \rightarrow \pm \infty} p(x)=\frac{1}{4} \Phi^{\prime}\left(\alpha_{ \pm}\right)^{2}  \tag{22}\\
& \bar{p}=\max \left(p_{+}, p_{-}\right)
\end{align*}
$$

Remark that for $|\arg (\lambda-\bar{p})|<\pi$,

$$
\begin{equation*}
\operatorname{Re}\left(\gamma_{ \pm}(\lambda)\right)>0 \tag{23}
\end{equation*}
$$

And consequently, the investigated $\varphi_{ \pm}$decrease exponentially as $x$ goes to $\pm \infty$. The functions $a_{+}$and $a_{-}$are analytic in $x$ and $\lambda$ and satisfy the following asymtotics :

$$
\begin{equation*}
a_{ \pm}(x+i y, \lambda)=1+\mathcal{O}\left(\frac{1}{\sqrt{|\lambda|}}\right), \quad x \rightarrow \pm \infty \tag{24}
\end{equation*}
$$

For instance, $a_{+}$is a solution as a function of $x$ of the differential equation :

$$
\begin{equation*}
a_{+}^{\prime \prime}-2 \gamma_{+} a_{+}^{\prime}+(p-\bar{p}) a_{+}=0 \tag{25}
\end{equation*}
$$

which can be reformulated as an integral equation :

$$
\begin{equation*}
a_{+}(x, \lambda)=1+\int_{x}^{\infty}\left[p\left(\frac{1-e^{2 \gamma_{+}(x-s)}}{2 \gamma_{+}}\right)-\bar{p}\right] a_{+}(s, \lambda) d s \tag{26}
\end{equation*}
$$

This equation may be readily complexified in variable $z=x+i y$ :

$$
\begin{equation*}
a_{+}(z, \lambda)=1+\int_{z}^{\infty}\left[p\left(\frac{1-e^{2 \gamma_{+}(x-s)}}{2 \gamma_{+}}\right)-\bar{p}\right] a_{+}(s+i y, \lambda) d s \tag{27}
\end{equation*}
$$

On each real line $y=$ const, the function $p-\bar{p}$ is absolutely integrable and $\int_{x}^{\infty}|p(s+i y)-\bar{p}| d s$ is uniformly bounded wrt $y$ as $x \rightarrow \infty$. The integral equation may therefore be solved, which yields a $a_{+}(z, \lambda)=1+\mathcal{O}\left(\sqrt{\frac{1}{|\lambda|}}\right)$ (and a $a_{-}$satisfying the same estimate) .

Denote $F(x, \xi, \lambda)$ the Green function of the operator $\lambda-A$, it satisfies the following estimates :

$$
\begin{align*}
& \|F(x+i y, \xi+i \eta, \lambda)\|_{L^{2}(d x)} \leq \frac{C_{1}}{|\lambda|^{3 / 4}} e^{\left(C_{2}+\left|\gamma_{+}(\lambda)\right|\right)(y-\eta)} \\
& \left\|\partial_{x} F(x+i y, \xi+i \eta, \lambda)\right\|_{L^{2}(d x)} \leq \frac{C_{3}}{|\lambda|^{1 / 4}} e^{\left(C_{2}+\left|\gamma_{+}(\lambda)\right|\right)(y-\eta)} \tag{28}
\end{align*}
$$

Classical spectral theory provides an explicit expression of $F(x, \xi, \lambda)$ :

$$
\begin{align*}
F(x, \xi, \lambda)= & \frac{1}{W(\lambda)} \varphi_{-}(\xi) \varphi_{+}(x), \quad \text { if } \xi \leq x \\
& \frac{1}{W(\lambda)} \varphi_{-}(x) \varphi_{+}(\xi), \quad \text { if } \xi \geq x \tag{29}
\end{align*}
$$

Where $W(\lambda)=-\left(\gamma_{+}(\lambda)+\gamma_{-}(\lambda)\right)+\mathcal{O}(1)$ is the wronskian of the eigenfunctions equation (cf 13]). It is independant of $x$ and $\xi$. Estimates of $\| F(x+i y, \xi+$ $i \eta, \lambda \|_{L^{2}(d \xi)}$ are now requested.

$$
\begin{align*}
& \int_{-\infty}^{\infty}|F(x+i y, \xi+i \eta, \lambda)|^{2} d \xi=\frac{1}{W(\lambda)}\left(\int_{-\infty}^{x}\left|\varphi_{-}(\xi+i \eta) \varphi_{+}(x+i y)\right|^{2} d \xi\right.  \tag{30}\\
& \left.+\int_{x}^{\infty}\left|\varphi_{-}(x+i y) \varphi_{+}(\xi+i \eta)\right|^{2} d \xi\right)
\end{align*}
$$

We now estimate the different term as in Sattinger work, using the fact that $\left\|e^{-\sqrt{\mid \lambda-x}}\right\|_{L^{2}(d x)}=\frac{1}{|\lambda|^{1 / 4}}$, which saves a factor $\frac{1}{|\lambda|^{1 / 4}}$ compared to $L^{1}$-norm. For example, consider $x>0$,

$$
\begin{gather*}
\int_{-\infty}^{x}\left|\varphi_{-}(\xi+i \eta) \varphi_{+}(x+i y)\right|^{2} d \xi \leq e^{-2 \operatorname{Re}\left(\gamma_{+}(\lambda)\right) x+2 \operatorname{Im}\left(\gamma_{+}(\lambda)\right) y}\left(\int_{\infty}^{0}\left|\varphi_{+}(\xi+i \eta, \lambda)\right|^{2} d \xi\right. \\
\left.+\int_{0}^{x}\left|\varphi_{+}(\xi+i \eta, \lambda)\right|^{2} d \xi\right) \tag{31}
\end{gather*}
$$

Where,

$$
\begin{align*}
& \int_{0}^{\infty}\left|\varphi_{+}(\xi+i \eta)\right|^{2} d \xi \leq e^{-2 \operatorname{Im}\left(\gamma_{-}\right) \eta} \int_{0}^{\infty} e^{2 \operatorname{Re}\left(\gamma_{-}\right) \xi}\left(1+\mathcal{O}\left(\frac{1}{\sqrt{|\lambda|}}\right)\right)^{2} d \xi  \tag{32}\\
& \leq \frac{1}{2 \operatorname{Re}\left(\gamma_{-}(\lambda)\right)}\left(1+\mathcal{O}\left(\frac{1}{\gamma_{-}(\lambda)}\right)\right)^{2} \leq \frac{\mathrm{const}}{\sqrt{|\lambda|}}
\end{align*}
$$

After composition with the square-root, we get the expected power in $\lambda\left(\frac{1}{W(\lambda)}\right.$ is estimated by $\frac{1}{\sqrt{|\lambda|}}$. Others terms are estimated using the same method. To estimate the norm of derivative, it is sufficient to remark that derivation wrt $x$ of $F(x, \xi, \lambda)$ gives rise to an extra $\sqrt{\lambda}$ factor. Finally, we need to prove that the kernel of the evolution operator $e^{t A}$ satisfies the expected estimates and that its $\mathcal{H}^{2}$ norm wrt $\xi+i \eta$ is uniformily bounded in $x+i y$. The kernel $K(x, t, \xi)$ is represented by the following contour integral :

$$
\begin{equation*}
K(x+i y, t, \xi+i \eta)=\frac{1}{2 i \pi} \int_{\mathcal{C}} e^{t \lambda} F(x+i y, \xi+i \eta, \lambda) d \lambda \tag{33}
\end{equation*}
$$

Where $\mathcal{C}$ is any contour avoiding the essential spectrum of $A$. Sattinger used the contour $\lambda=-\omega+\rho e^{ \pm i \delta}$, parametrized by $0 \leq \rho<\infty$. The two parameter $0<\omega<\bar{p}$ and $\pi / 2<\delta<\pi$ are chosen such that the estimates performed on $F(x, t, \xi)$ hold. The same contour will be used. Using the estimates on $F$ previously established, we get :

$$
\begin{equation*}
\|K(x+i y, t, \xi+i \eta)\|_{L^{2}(d \xi)} \leq \text { const } \int_{\mathcal{C}} \frac{\left|e^{\lambda t}\right|}{|\lambda|^{3 / 4}} e^{C \sqrt{|\lambda|}(y-\eta)}|d \lambda| \tag{34}
\end{equation*}
$$

In order to estimate the right handside, rewrite it as an integral on the parameter $\rho=|\lambda+\omega|$.

$$
\begin{align*}
\int_{\mathcal{C}} \frac{\left|e^{\lambda t}\right|}{|\lambda|^{3 / 4}} e^{C \sqrt{|\lambda|}(y-\eta)}|d \lambda| & \leq \mathrm{const} \int_{0}^{\infty} \frac{e^{-\omega t} e^{\rho t \cos \delta+\sqrt{\rho} \sin ( \pm \delta)(y-\eta)}}{\left.(\rho \cos \delta-\omega)^{2}+\rho^{2} \sin ^{2} \delta\right)^{3 / 8}} d \rho \\
& \leq e^{-\omega t} \int_{0}^{\infty} \frac{e^{\rho t \cos \delta \pm \sqrt{\rho} \sin |\delta|(y-\eta)}}{\omega^{3 / 4}+\rho^{3 / 4}|\sin \delta|^{3 / 4}} d \rho \tag{35}
\end{align*}
$$

With $\frac{\pi}{2} \leq \delta \leq \pi, \cos \delta<0$ and the convergence of the integral is assured. Remark that :

$$
\begin{align*}
\rho t \cos \delta \pm \sqrt{\rho} \sin |\delta|(y-\eta) & =\cos (\delta)\left(\sqrt{\rho t} \pm \frac{\sin |\delta|}{\cos \delta} \frac{(y-\eta)}{2 \sqrt{t}}\right)^{2}-\tan |\delta| \cos \delta \frac{(y-\eta)^{2}}{4 t} \\
& =-|\cos (\delta)|\left(\sqrt{\rho t} \pm \frac{\sin |\delta|}{\cos \delta} \frac{(y-\eta)}{2 \sqrt{t}}\right)^{2}+\sin |\delta| \frac{(y-\eta)^{2}}{4 t} \tag{36}
\end{align*}
$$

We conclude by using that $\int_{0}^{\infty} \frac{e^{-\rho t}}{\rho^{\gamma}} d \rho=\frac{\text { const }}{t^{1-\gamma}}$. The estimates are obtained with $\gamma=3 / 4$ for $K$ and $\gamma=1 / 4$ for its derivative.

### 4.2 Solving the integral equation

Proposition 3. Let $(X,\|\cdot\|)$ be a Banach Space and $B: X \rightarrow X$ a $C^{1}$ map such that $B(0)=0$ and $\sup _{\|h\|<\frac{1}{1-\alpha} \alpha}\|D B(h)\| \|<\sigma<1$. Let $a \in X$ such that $\|a\|<\alpha$. The sequence defined by the following iterative scheme :

$$
\begin{align*}
& h_{n+1}=a+B\left(h_{n}\right)  \tag{37}\\
& h_{0}=a
\end{align*}
$$

remains in a ball of center 0 and radius $\frac{1}{1-\sigma} \alpha$ and has a limit $h$ in $X$ solving the equation $h=a+B(h)$.

Proof. Assume that $\left\|h_{n}\right\| \leq \frac{1}{1-\sigma} \alpha$. The mean value inequality yields :

$$
\left\|h_{n+1}\right\| \leq \alpha+\sigma\left\|h_{n}\right\| \leq \alpha+\frac{\sigma}{1-\sigma} \alpha \leq \frac{1}{1-\sigma} \alpha
$$

The sequence $\left(h_{n}\right)$ is therefore bounded. Using the mean value inequality again, we get :

$$
\left\|h_{n+1}-h_{n}\right\| \leq \sigma\left\|h_{n}-h_{n-1}\right\|
$$

Picard's contraction theorem is enough to conclude.
Lemma. The evaluation map $\mathcal{H}_{w, a, b}^{2}\left(\Delta_{c}\right) \rightarrow \mathbb{C}$ is continuous :

$$
\begin{equation*}
|u(z)| \leq \frac{\text { const. }(c-|y|)^{\frac{b-1}{2}}}{|w(i y)|^{\frac{1}{2}+a}}\|u\|_{\mathcal{H}_{w, a, b}^{2}\left(\Delta_{c}\right)} \tag{38}
\end{equation*}
$$

Proof. Represent $w(z) u(z)^{2}$ as an integral using Cauchy's formula over the contour

$$
\mathcal{C}=\{\xi+i c: \xi \in[\infty,-\infty]\} \cup\{\xi-i c: \xi \in[-\infty, \infty]\}
$$

that is to say,

$$
\begin{equation*}
w(z) u(z)^{2}=\frac{1}{2 i \pi} \int_{\mathcal{C}} \frac{w(\zeta) u(\zeta)^{2} d \zeta}{\zeta-z} \tag{39}
\end{equation*}
$$

It provides the estimate :

$$
\begin{equation*}
|u(z)|^{2} \leq \frac{1}{\sqrt{\pi}} \frac{1}{c-|y|} \frac{1}{|w(i y)|} \int_{-\infty}^{\infty}|w(\xi+i c)| \cdot|u(\xi+i c)|^{2} d \xi \tag{40}
\end{equation*}
$$

which is the expected estimate.
Proposition 4. The nonlinear operator $B: \mathcal{B}_{\varepsilon, T} \rightarrow \mathcal{B}_{\varepsilon, T}$,

$$
\begin{align*}
& B(h)(z, t)=\int_{0}^{t} d \tau \int_{-\infty}^{\infty} \frac{\partial G}{\partial z}(x+i y, t-\tau, \xi+i m(y, \tau))  \tag{41}\\
& R(\tilde{f}(\xi+i m(y, \tau)), h(\xi+i m(y, \tau))) d \xi
\end{align*}
$$

with $R(\tilde{f}, h)=\Phi(\tilde{f}+h)-\Phi(\tilde{f})-\Phi^{\prime}(\tilde{f}) . h$, satisfies the estimate :

$$
\begin{equation*}
\sup _{\|h\|_{\varepsilon, T} \leq 2 \alpha} \mid\|D B(h)\| \| \leq C \alpha p(\alpha) \tag{42}
\end{equation*}
$$

With $C$ a constant and $p$ a polynomial of degree $\leq n-2$, both being independant of $\varepsilon$ and $T$.

Proof. Differentiating with respect to $h$ yields :

$$
\begin{align*}
& \left.D B(h)(g)(z, t)=\int_{0}^{t} d \tau \int_{-\infty}^{\infty} \frac{\partial G}{\partial z}(x+i y, \xi+i m(y, \tau)), t-\tau\right)  \tag{43}\\
& \frac{\partial R}{\partial h}(\tilde{f}(\xi+i m(y, \tau)), h(\xi+i m(y, \tau), \tau)) g(\xi+i m(y, \tau), \tau) d \xi
\end{align*}
$$

where ,

$$
\frac{\partial R}{\partial h}(\tilde{f}, h)=h \sum_{k=0}^{n-2} \frac{1}{(k+1)!} \Phi^{(k+2)}(\tilde{f}) h^{k}
$$

For $0 \leq k \leq n-2$, define the floowing operators :

$$
\begin{aligned}
A_{1}^{k}(h, g)(z, t)= & -\int_{0}^{t} \frac{d \tau}{w(z)} \int_{-\infty}^{\infty} w(\xi+i m(y, \tau)) \partial_{x} K((x+i y),(\xi+i m(y, \tau)), t-\tau) \\
& \Phi^{(k+2)}(\tilde{f}(z)) h^{k+1}(\xi+i m(y, \tau), \tau) g(\xi+i m(y, \tau), \tau) d \xi \\
A_{2}^{k}(h, g)(z, t)= & -\frac{1}{2} \int_{0}^{t} \frac{d \tau}{w(z)} \int_{-\infty}^{\infty} w(\xi+i m(y, \tau)) K(x+i y, \xi+i m(y, \tau), t-\tau) \\
& \Phi^{(k+2)}(\tilde{f}(z)) \Phi^{\prime}(\tilde{f}(z)) h^{k+1}(\xi+i m(y, \tau), \tau) g(\xi+i m(y, \tau), \tau) d \xi
\end{aligned}
$$

The expected estimates will be proved separately for each $A_{1}^{k}$ and each $A_{2}^{k}$.
Proceed first with the $A_{1}^{k}$ 's :
$\left\|\int_{-\infty}^{\infty} w(\xi+i m(y, \tau)) \partial_{x} K(x+i y, \xi+i m(y, \tau), t-\tau) \Phi^{(k+2)}(\tilde{f}(z)) h^{k} h g(\xi+i m(y, \tau), \tau) d \xi\right\|_{L^{2}(d x)} \leq I_{1}$ where,
$I_{1}=e^{M^{2} / 4} \mathrm{const}|w(i y)|^{-\frac{2}{n}(n-k-2)-\left(\frac{1}{2}+a_{n}\right) k}(t-\tau)^{-3 / 4}\left(y_{0}-|y|\right)^{k \frac{b_{n}-1}{2}}\|h\|_{\mathcal{H}_{w}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), \tau\right)}\right)}$
$\times \int_{-\infty}^{\infty}|w(\xi+i m(y, \tau))| \cdot|h(\xi+i m(y, \tau), \tau)| \cdot|g(\xi+i m(y, \tau), \tau)| d \xi$
$\leq e^{M^{2} / 4}$ const $|w(i y)|^{-\frac{2}{n}(n-k-2)-\left(\frac{1}{2}+a_{n}\right) k-2 a_{n}}(t-\tau)^{-3 / 4}\left(y_{0}-|y|\right)^{k \frac{b_{n}-1}{2}+b_{n}}$
$\times\|h\|_{\mathcal{H}_{w}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), \tau\right)}+1\right.}^{k+1}\| \|_{\mathcal{H}_{w}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), \tau\right)}\right)}$
Hence,

$$
\begin{aligned}
& \left\|\left.\left|\left|A_{1}^{k}(h, .)\right| \|_{\mathcal{L}\left(\mathcal{H}^{2}\right)} \leq e^{M^{2} / 4} \text { const }\right| w(i y)\right|^{-\frac{2}{n}(n-k-2)-\left(\frac{1}{2}+a_{n}\right) k-a_{n}-\frac{1}{2}}\right. \\
& \times\left(y_{0}-|y|\right)^{k \frac{b_{n}-1}{2}+\frac{b_{n}}{2}}\|h\|_{\varepsilon, t}^{k+1} \int_{0}^{t} \frac{e^{-\omega t} d \tau}{(t-\tau)^{\frac{3}{4}} \tau^{\frac{k+2}{4(n-1)}}}
\end{aligned}
$$

where,

$$
\int_{0}^{t} \frac{d \tau}{(t-\tau)^{\frac{3}{4}} \tau^{\frac{k+2}{4(n-1)}}}=\mathrm{const} t^{1-\left(\frac{3}{4}+\frac{k+2}{4(n-1)}\right)}=\operatorname{const} t^{\frac{n-k-3}{4(n-1)}}
$$

And finally,

$$
\begin{aligned}
\sup _{\|h\|_{\varepsilon, t} \leq 2 \alpha}\left|\left\|A_{1}^{k}(h, .) \mid\right\|_{\varepsilon, t}\right. & \leq \operatorname{const}^{\frac{M^{2}}{4}}|w(i y)|^{\left.-\frac{2}{n}(n-k-2)-\left(\frac{1}{2}+a_{n}\right) k-a_{n}-\frac{1}{2}\right)} \\
& \times\left(y_{0}-|y|\right)^{k \frac{b_{n}-1}{2}+\frac{b_{n}}{2}} e^{-\omega t} t^{\frac{n-k-2}{4(n-1)}} \alpha^{k+1} \\
& \leq \operatorname{const} \alpha^{k+1}
\end{aligned}
$$

The last inequality is obtained through the following considerations :

- The function $y \mapsto|w(i y)|$ is bounded on $\left[0, y_{0}\right]$ and $-\frac{2}{n}(n-k-2)-\left(\frac{1}{2}+\right.$ $\left.a_{n}\right) k-a_{n}-\frac{1}{2} \geq 0$, with $a_{n}=\frac{2}{n}-\frac{5}{2}$.
- The function $y \mapsto y_{0}-|y|$ is bounded and $k \frac{b_{n}-1}{2}+\frac{b_{n}}{2} \geq 0$, with $b_{n}=\frac{n-2}{n-1}$.
- For $q \geq 0, t \mapsto t^{q} e^{-\omega t}$ is bounded and $q=\frac{n-k-2}{4(n-1)} \geq 0$.

Proceed now with $A_{2}^{k}$
$\left\|\int_{-\infty}^{\infty} w(\xi+i m(y, \tau)) K(x+i y, \xi+i m(y, \tau), t-\tau) \Phi^{(k+2)}(\tilde{f}(z)) \Phi^{\prime}(\tilde{f}(z)) h^{k} h g(\xi+i m(y, \tau), \tau) d \xi\right\|_{L^{2}(d x)} \leq I_{2}$ where,

$$
\begin{aligned}
& I_{2}=e^{M^{2} / 4} \operatorname{const}|w(i y)|^{-\frac{2}{n}(2 n-k-3)-\left(\frac{1}{2}+a_{n}\right) k}(t-\tau)^{-1 / 4}\left(y_{0}-|y|\right)^{k \frac{b_{n}-1}{2}}\|h\|_{\mathcal{H}_{w}^{2}\left(\Delta_{\left.m\left(y_{0}(1-\varepsilon), \tau\right)\right)}\right.} \\
& \times \int_{-\infty}^{\infty}|w(\xi+i m(y, \tau))| \cdot|h(\xi+i m(y, \tau), \tau)| \cdot|g(\xi+i m(y, \tau), \tau)| d \xi \\
& \leq e^{M^{2} / 4} \operatorname{const}|w(i y)|^{-\frac{2}{n}(2 n-k-3)-\left(\frac{1}{2}+a_{n}\right) k-2 a_{n}}(t-\tau)^{-1 / 4}\left(y_{0}-|y|\right)^{k \frac{b_{n}-1}{2}+b_{n}} \\
& \times\|h\|_{\mathcal{H}_{w}^{2}\left(\Delta_{m\left(y_{0}(1-\varepsilon), \tau\right)} k+\right.}^{k+1}\|g\|_{\mathcal{H}_{w}^{2}\left(\Delta_{\left.m\left(y_{0}(1-\varepsilon), \tau\right)\right)}\right.}
\end{aligned}
$$

Hence,
$\left.\left|\left\|A_{2}^{k}(h, .) \mid\right\|_{\mathcal{L}\left(\mathcal{H}^{2}\right)} \leq e^{M^{2} / 4}\right.$ const $| w(i y)\right|^{-\frac{2}{n}(2 n-k-3)-\left(\frac{1}{2}+a_{n}\right) k-a_{n}-\frac{1}{2}}\|h\|_{\varepsilon, t}^{k+1} \int_{0}^{t} \frac{e^{-t} d \tau}{(t-\tau)^{\frac{1}{4}} \tau^{\frac{k+2}{4(n-1)}}}$
where,

$$
\int_{0}^{t} \frac{d \tau}{(t-\tau)^{\frac{1}{4}} \tau^{\frac{k+2}{4(n-1)}}}=\operatorname{const} t^{1-\left(\frac{1}{4}+\frac{k+2}{4(n-1)}\right)}=\operatorname{const} t^{\frac{3 n-k-5}{4(n-1)}}
$$

And finally,

$$
\begin{gathered}
\sup _{\|h\|_{\varepsilon, t} \leq 2 \alpha}\left\|\left|A_{2}^{k, k^{\prime}}(h, .)\right|\right\|_{\varepsilon, t} \leq \operatorname{const} e^{\frac{M^{2}}{4}}|w(i y)|^{-\frac{2}{n}(2 n-k-3)-\left(\frac{1}{2}+a_{n}\right) k-a_{n}-\frac{1}{2}} e^{-\omega t} t^{\frac{3 n-k-5}{4(n-1)}} \alpha^{k+1} \\
\leq \operatorname{const} \alpha^{k+1}
\end{gathered}
$$

The differential $D B(h)(g)$ being a linear superposition of the monomial operators $A_{1}^{k, k^{\prime}}(h, g)$ and $A_{2}^{k, k^{\prime}}(h, g)$, we get the required estimate.

Definition. Introduce the weighted energy $E_{H}(t)$ of a function $H(., t)$ :

$$
E_{H}(t)=\int_{-\infty}^{\infty} w(\xi)^{2}|H(x, t)|^{2} d \xi
$$

The function $H(., t)$ is said to have finite weigthed energy if $E_{H}(t)<\infty$.
Proposition 5. The Cauchy problem for perturbation of Burger's viscous traveling waves has a solution $h(x, t)$ which has a holomorphic continuation belonging to $B_{\varepsilon, t}$ for all $\left.\left.\varepsilon \in\right] 0,1\right]$ and $t>0$ provided that $E_{h}(0)$ and $E_{H}(0)$, the weighted energy of the perturbation and of its potential are sufficiently small

Proof. The following integral equation has to be complexified :

$$
\begin{equation*}
h(x, t)=\partial_{x} F_{0}(x, t)-\int_{0}^{t} d \tau \int_{-\infty}^{+\infty} G(x, t-\tau ; \xi) R(\tilde{f}(\xi), h(\xi, \tau)) d \xi \tag{44}
\end{equation*}
$$

Assuming that for each $\tau>0, h(x, \tau)$ has a holomorphic continuation in the strip $\Delta_{m\left(y_{0}(1-\varepsilon), \tau\right)}$. The integration contour in the variable $\xi$ can be shifted to the contour $\xi+\operatorname{im}(y, \tau)$. The investigated $h(z, t)$ solves the resulting integral equation :

$$
\begin{equation*}
h=\partial_{z} F_{0}+B(h) \tag{45}
\end{equation*}
$$

where $B$ has already been introduced in Proposition 2. An estimate of the linear term $\partial_{z} F_{0}$ is now required in order to get a control of its norm by some smallness condition on the initial data (here the initial weighted energies $E_{h}(0)$ and $\left.E_{H}(0)\right)$.

$$
\begin{aligned}
& \partial_{z} F_{0}(z, t)=\int_{-\infty}^{\infty} \frac{w(\xi)}{w(z)}\left(\partial_{z} K(z, t, \xi)+\frac{1}{2} \Phi^{\prime}(f(z)) \tilde{f}(z) K(z, t, \xi)\right) H_{0}(\xi) d \xi \\
& =\int_{-\infty}^{\infty} \frac{w(\xi)}{w(z)}\left(-\partial_{\xi} K(\xi, t, z)-p^{\prime}(z) K(z, t, \xi)+\frac{1}{2} \Phi^{\prime}(\tilde{f}(z)) K(z, t, \xi)\right) H_{0}(\xi) d \xi \\
& =\frac{1}{w(z)} \int_{-\infty}^{\infty}\left(\frac{1}{2} \Phi^{\prime}(\tilde{f}(\xi)) K(\xi, t, z) w(\xi) H_{0}(\xi)+K(z, t, \xi) w(\xi) h_{0}(\xi)+\right. \\
& \left.\left(\frac{1}{2} \Phi^{\prime}(\tilde{f}(z))-p^{\prime}(z)\right) K(z, t, \xi) H_{0}(\xi)\right) d \xi
\end{aligned}
$$

The wave $f \tilde{(\xi)}$ being bounded wrt $\xi \in \mathbb{R}$, using Young inequality together with the inequality :

$$
\|K(z, t, \xi)\|_{L^{1}(d \xi)} \leq \mathrm{const} e^{M^{2} / 4}
$$

we get the following estimate of $\partial_{z} F_{0}$ :

$$
\begin{equation*}
\left\|\partial_{z} F_{0}\right\|_{\varepsilon, T} \leq e^{M^{2} / 4}\left(C_{3} E_{H}(0)+C_{4} E_{h}(0)+\frac{C_{5} E_{H}(0)}{\left|w\left(i y_{0}(1-\varepsilon)\right)\right|^{\frac{6 n-5}{n}}}\right) \frac{1}{\left|w\left(i y_{0}(1-\varepsilon)\right)\right|}=\alpha \tag{46}
\end{equation*}
$$

Proposition 1 provides a solution if

$$
\begin{equation*}
C \alpha p(\alpha)<1 \tag{47}
\end{equation*}
$$

Proof of the theorem:
One can use the following a priori estimates for the weighted energy and conclude that initial data may actually be considered as always sufficiently small
Proposition 6. If $E_{H}(0)$ is finite, then $E_{H}(t)$ and $E_{h}(t)$ are finite for all $t>0$ and are bounded from above by $C_{1} \exp \left(-C_{2} t\right)$.

This statement is not well-known, but it is a variation of the result of IljinOleinik [5], its proof can be found with all details in (14]. Now, solutions of our main theorem may be constructed through the procedure : "wait"' until (47) is fullfilled denote this date $T^{*}$, and apply Proposition 3 with $h\left(x, T^{*}\right)$ as initial data.

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