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# THE GENERIC POINTS FOR THE HOROCYCLE FLOW ON A CLASS OF HYPERBOLIC SURFACES WITH INFINITE GENUS 

OMRI SARIG AND BARBARA SCHAPIRA


#### Abstract

A point is called generic for a flow preserving an infinite ergodic invariant Radon measure, if its orbit satisfies the conclusion of the ratio ergodic theorem for every pair of continuous functions with compact support and nonzero integrals. The generic points for horocycle flows on hyperbolic surfaces of finite genus are understood, but there are no results in infinite genus. We give such a result, by characterizing the generic points for $\mathbb{Z}^{d}$-covers.


## 1. Introduction

Generic Points. Suppose $\phi^{t}: X \rightarrow X$ is a continuous flow on a second countable locally compact metric space $X$. Let $C_{c}(X)$ denote the set of all continuous functions with compact support. A point $x \in X$ is called generic for an invariant Radon measure $m$, if
(1) $m(X)<\infty$, and for all $f \in C_{c}(X), \frac{1}{T} \int_{0}^{T} f\left(\phi^{t} x\right) d t \underset{T \rightarrow \infty}{\longrightarrow} \frac{1}{m(X)} \int f d m$,
(2) $m(X)=\infty$, and for all $f, g \in C_{c}(X)$ with non-zero integrals,

$$
\frac{\int_{0}^{T} f\left(\phi^{t} x\right) d t}{\int_{0}^{T} g\left(\phi^{t} x\right) d t} \underset{T \rightarrow \infty}{ } \frac{\int f d m}{\int g d m} .
$$

If $m$ is ergodic and conservative, then $m$-almost every $x$ is generic, because of the ratio ergodic theorem. The question is to identify this set of full measure.

Horocycle Flows. Suppose $M$ is a connected hyperbolic surface, and let $T^{1} M$ denote its unit tangent bundle (made of all tangent vectors of length one). The (stable) horocycle of $\omega \in T^{1} M$ is the set $\operatorname{Hor}(\omega)$ of all unit tangent vectors $\omega^{\prime}$ such that $d\left(g^{s} \omega^{\prime}, g^{s} \omega\right) \xrightarrow[s \rightarrow \infty]{\longrightarrow} 0$, where $g^{s}: T^{1} M \rightarrow T^{1} M$ is the geodesic flow, and $d$ is the hyperbolic metric of $T^{1} M$. This is a smooth curve. The (stable) horocycle flow is the flow $h^{t}: T^{1} M \rightarrow T^{1} M$ which moves a vector $\omega \in T^{1} M$ along $\operatorname{Hor}(\omega)$ at unit speed, in the positive direction (to determine the orientation, lift to the universal cover $\left.T^{1} \mathbb{D}, \mathbb{D}:=\{z \in \mathbb{C}:|z|<1\}\right)$.

If $M$ has finite volume, then the generic points for the horocycle flow are understood thanks to the works of Furstenberg (compact surfaces), and Dani \& Smillie DS (surfaces of finite area). Burger Bu characterized the symmetrically generic points for a large class of hyperbolic surfaces of finite genus and infinite

[^0]volume, where 'symmetrically generic' means that $\int_{0}^{T}$ is replaced by $\int_{-T}^{T}$. Schapira Scha characterized the symmetrically generic points for all hyperbolic surfaces of finite genus.

These results can be summarized as saying that all non-periodic, non-wandering horocyles are generic for the volume measure in case $\operatorname{vol}\left(T^{1} M\right)<\infty$, or symmetrically generic for a certain singular infinite Radon measure which is carried by the non-wandering set of the horocycle flow in case $\operatorname{vol}\left(T^{1} M\right)=\infty$ (see Bu, Scha] for details).

Ratner Ra generalized the part of these results pertaining to finite invariant measures to all unipotent flows, whence to all horocycle flows on all hyperbolic surfaces. One of her results is that the horocycle flow on a hyperbolic surface of infinite volume (e.g. a surface with infinite genus) does not admit finite invariant measures except possibly trivial measures on periodic horocycles encircling cusps. But there could be globally supported infinite invariant Radon measures (Babillot \& Ledrappier BL2]). The problem of describing the generic points for these measures is completely open.

The purpose of this paper is to solve this problem for the simplest possible class of hyperbolic surfaces of infinite genus: $\mathbb{Z}^{d}$-covers of compact hyperbolic surfaces.

## $\mathbb{Z}^{d}$-Covers. All surfaces in this paper are assumed to be connected.

A hyperbolic surface $M$ is called a regular $\mathbb{Z}^{d}$-cover of a compact hyperbolic surface $M_{0}$ (or just ' $\mathbb{Z}^{d}$-cover'), if there is an onto map $p: M \rightarrow M_{0}$ such that (1) every $x \in M_{0}$ has a neighborhood $V_{x}$ such that every connected component of $p^{-1}\left(V_{x}\right)$ is mapped isometrically by $p$ onto $V_{x},(2)$ the group

$$
\operatorname{Deck}(M, p):=\{D: M \rightarrow M: D \text { is an isometry s.t. } p \circ D=D\}
$$

is isomorphic to $\mathbb{Z}^{d}$ (elements of $\operatorname{Deck}(M, p)$ are called deck transformations), and (3) for every $x \in M$, there is $\widetilde{x} \in M$ such that $p^{-1}(x)=\{D(\widetilde{x}): D \in \operatorname{Deck}(M, p)\}$.

The deck transformations act on $T^{1} M$ by their differentials. We abuse notation and use the same notation for $D$ and its differential.

Choose some connected fundamental domain $\widetilde{M}_{0}$ for the action of the group of deck transformations on $T^{1} M$. Then every $\omega \in T^{1} M$ can be associated with a unique $\xi(\omega) \in \mathbb{Z}^{d}$ such that $\omega \in D_{\xi(\omega)}\left[\widetilde{M}_{0}\right]$. We call $\xi(\omega)$ the $\mathbb{Z}^{d}$-coordinate of $\omega$. It is useful to think of $T^{1} M$ as of a $\mathbb{Z}^{d}$-array of copies of $\widetilde{M}_{0}$, tagged by their $\mathbb{Z}^{d}$-coordinates.

The asymptotic cycle of a vector $\omega \in T^{1} M$ is the following limit, if it exists:

$$
\Xi(\omega):=\lim _{T \rightarrow \infty} \frac{1}{T} \xi_{T}(\omega), \text { where } \xi_{T}(\omega):=\xi\left(g^{T} \omega\right)
$$

(compare with Schw). Let

$$
\mathfrak{C}:=\overline{\operatorname{conv}}\left(\left\{\Xi(\omega): \omega \in T^{1} M \text { s.t. } \Xi(\omega) \text { exists }\right\}\right) \subset \mathbb{R}^{d}
$$

where $\overline{\text { conv }}$ denote the closure of the convex hull.
Babillot-Ledrappier Measures. The ergodic invariant Radon measures for horocycle flows on $\mathbb{Z}^{d}$-covers are known. To list them, fix a parametrization $\operatorname{Deck}(M, p)=$ $\left\{D_{\xi}: \xi \in \mathbb{Z}^{d}\right\}$ such that $D_{\xi} \circ D_{\eta}=D_{\xi+\eta}$. Then
(1) For every homomorphism $\varphi: \mathbb{Z}^{d} \rightarrow \mathbb{R}$, there exists a unique (infinite) horocycle ergodic invariant Radon measure $m_{\varphi}$ such that $m_{\varphi} \circ D_{\xi}=e^{\varphi(\xi)} m_{\varphi}$ for
all $\xi \in \mathbb{Z}^{d}$, and $m_{\varphi}\left(\widetilde{M}_{0}\right)=1$ (BL2], Theorem 1.2). We call these measures the Babillot-Ledrappier measures.
(2) There is a vector $\Xi_{\varphi} \in \mathbb{R}^{d}$ such that $\Xi(\omega)=\Xi_{\varphi} m_{\varphi}$-almost everywhere; the vector $\Xi_{\varphi}$ determines $\varphi$; and the set of all possible $\Xi_{\varphi}$ is equal to the interior of $\mathfrak{C}$, $\operatorname{int}(\mathfrak{C})$ ( $\mathbf{B L 2}$, Corollary 6.1 and $\overline{\mathbf{B L} 1}$, Proposition 1.1).
(3) Every ergodic invariant Radon measure for the horocycle flow on a $\mathbb{Z}^{d}$-cover of a compact hyperbolic surface is a constant times a Babillot-Ledrappier measure [S].
The (normalized) volume measure corresponds to $\varphi \equiv 0$, and its almost sure asymptotic cycle is $\Xi_{0}=0$.

Main Result. Suppose $M$ is a connected regular $\mathbb{Z}^{d}$-cover of a compact hyperbolic surface $M_{0}$. The purpose of the paper is to prove:

Theorem 1.1. A vector $\omega \in T^{1} M$ is generic for some horocycle ergodic invariant Radon measure $m$ iff $\Xi(\omega) \in \operatorname{int}(\mathfrak{C})$. In this case $\Xi(\omega)=\Xi_{\varphi}$ and $m=c m_{\varphi}$ for some uniquely determined homomorphism $\varphi: \mathbb{Z}^{d} \rightarrow \mathbb{R}$ and $c>0$.

The hyperbolicity of the geodesic flow makes it easy to construct geodesics without asymptotic cycles, thus there are many non-wandering horocycles which are not equidistributed with respect to any measure. This should be contrasted with the finite genus case discussed above.

It is interesting that the mere existence of an asymptotic cycle is not enough for genericity, but that the value is important as well.

The Proof. The proof that every $\omega$ with asymptotic cycle in $\operatorname{int}(\mathfrak{C})$ is generic uses harmonic analysis. It is a combination of methods from LS1 for approximating the Birkhoff integral of a function by a symbolic dynamical quantity, and techniques from BL1 (building on (L) for finding the asymptotic behavior of this quantity. A subtle difference is that the arguments of LS1] only work for almost every $\omega$, whereas we need an argument which uses explicit assumptions on $\omega$ (see the proof of lemma 4.2 for details).

The main contribution of the paper is the converse statement: every generic vector has asymptotic cycle in $\operatorname{int}(\mathfrak{C})$. We do not know how to do this using harmonic analysis, because the harmonic analytic tools we have fail for $\omega \in T^{1} M$ s.t. $\xi_{T}(\omega) / T \rightarrow \partial \mathfrak{C}$. We use a different method based on a certain built-in approximate exchangeability structure for the Lebesgue measure on horocycles.

Notational Convention. $a=b \pm c$ means $|a-b|<c$ or $\|a-b\|<c$ depending on the context. $a=e^{ \pm c} b$ means $e^{-c} \leq \frac{a}{b} \leq e^{c}$. Our error bounds $c$ are always very generous, and rarely optimal.

## 2. Preparations: Symbolic Dynamics

Generalities. A subshift of finite type with set of states $S$ and transition matrix $A=\left(t_{i j}\right)_{S \times S}\left(t_{i j} \in\{0,1\}\right)$ is the set

$$
\Sigma:=\left\{x=\left(x_{i}\right) \in S^{\mathbb{Z}}: \forall i \in \mathbb{Z}, t_{x_{i} x_{i+1}}=1\right\}
$$

together with the action of the left shift map $\sigma: \Sigma \rightarrow \Sigma, \sigma(x)_{k}=x_{k+1}$, and the metric $d(x, y)=\sum_{k \in \mathbb{Z}} \frac{1}{2^{|k|}}\left(1-\delta_{x_{k} y_{k}}\right)$. There is a one-sided version $\sigma: \Sigma^{+} \rightarrow \Sigma^{+}$ obtained by replacing $\mathbb{Z}$ by $\mathbb{N} \cup\{0\}$.

A cylinder in $\Sigma$ is a set of the form $\left[a_{-m}, \ldots, \dot{a}_{0}, \ldots, a_{n}\right]:=\left\{x \in \Sigma: x_{-m}^{n}=\right.$ $\left.a_{-m}^{n}\right\}$, where the notation $x_{-m}^{n}$ means $\left(x_{-m}, \ldots, x_{n}\right)$, and the dot designates the zeroth coordinate. Cylinders in $\Sigma^{+}$are defined similarly (with $m=0$ ). A word $\underline{a}$ is called admissible if $[\underline{a}] \neq \varnothing$. The cylinders form a basis of clopen sets for the topology of $\Sigma\left(\right.$ or $\left.\Sigma^{+}\right)$. The length of a word $\underline{a}$ is denoted by $|\underline{a}|$.

A subshift of finite type is topologically mixing iff $\exists m$ s.t. all the entries of $A^{m}$ are positive. Any topologically mixing subshift of finite type has a number $M_{b r} \in \mathbb{N}$ and a collection of admissible words of length $M_{b r} \mathfrak{B}:=\left\{\underline{w}_{a b}: a, b \in S\right\}$ such that

$$
\left[a, \underline{w}_{a b}, b\right] \neq \varnothing
$$

We fix such a collection, and refer to its elements as 'Markovian bridges'.
Suppose $F$ is a real valued function on $\Sigma$ or $\Sigma^{+}$. The Birkhoff sums of functions $F$ are denoted by $F_{n}$ :

$$
F_{n}:=F+F \circ \sigma+\cdots+F \circ \sigma^{n-1}
$$

A function $F$ is said to depend only on non-negative coordinates if $x_{0}^{\infty}=y_{0}^{\infty}$ implies $F(x)=F(y)$. The variation of such a function is

$$
\operatorname{var}(F):=\sum_{n=1}^{\infty} \sup \left\{|F(x)-F(y)|: x_{0}^{n-1}=y_{0}^{n-1}\right\} .
$$

If $F$ is Hölder continuous, then this number is finite.
Let $G$ be a group, assumed for simplicity to be abelian. The skew-product over $T: X \rightarrow X$ with the cocycle $f: X \rightarrow G$ is the map $T_{f}: X \times G \rightarrow X \times G$, $T(x, \xi):=(T(x), \xi+f(x))$.

The suspension semi-flow over $T: X \rightarrow X$ and height function $r^{*}: X \rightarrow \mathbb{R}^{+}$is the semi-flow $\varphi^{s}: X_{r^{*}} \rightarrow X_{r^{*}}$, where

$$
X_{r^{*}}:=\left\{(x, t): x \in X, 0 \leq t<r^{*}(x)\right\}
$$

and $\varphi^{s}(x, t):=\left(T^{n} x, t+s-r_{n}^{*}(x)\right)$ where $n$ is chosen s.t. $0 \leq t+s-r_{n}^{*}(x)<$ $r^{*}\left(T^{n} x\right)$. If $T$ is invertible, then this semi-flow has a unique extension to a flow. The suspension (semi)-flow can be identified with the (semi)-flow $(x, t) \mapsto(x, t+s)$ on $(X \times \mathbb{R}) / \sim\left(\right.$ respectively $\left.X \times \mathbb{R}^{+} / \sim\right)$ where $\sim$ is the orbit relation of the skew-product $T_{-r^{*}}$. Both descriptions shall be used below.

Symbolic Dynamics for the Geodesic Flow. Let $p: M \rightarrow M_{0}$ be a $\mathbb{Z}^{d}$-cover of a compact connected orientable hyperbolic surface $M_{0}$. We describe the geodesic flow on $g^{s}: T^{1} M \rightarrow T^{1} M$ as a suspension flow, whose base is a skew-product, whose base is a subshift of finite type. This description is well-known PS, PO, BL1. It can be obtained by a lifting argument from the Bowen-Series symbolic dynamics of $g^{s}: T^{1} M_{0} \rightarrow T^{1} M_{0}$ given by [BS], $\mathbf{S e 1}$, $\mathbf{S e 2}$, as in.
Lemma 2.1. Fix $i: T^{1} M_{0} \rightarrow T^{1} M 1-1$ with image $\widetilde{M}_{0}$ and s.t. $d p \circ i=i d$. There exist a topologically mixing two-sided subshift of finite type $(\Sigma, T)$, a Hölder continuous function $r: \Sigma \rightarrow \mathbb{R}$ which depends only on the non-negative coordinates, a function $f: \Sigma \rightarrow \mathbb{Z}^{d}$ s.t. $f(x)=f\left(x_{0}, x_{1}\right)$, a Hölder function $h: \Sigma \rightarrow \mathbb{R}$, and a Hölder continuous map $\pi: \Sigma \times \mathbb{Z}^{d} \times \mathbb{R} \rightarrow T^{1} M$ with the following properties:
(1) $r^{*}:=r+h-h \circ \sigma$ is non-negative, and there exists a constant $n_{0}$ such that $\inf r_{n_{0}}^{*}>0$, where $r_{n_{0}}^{*}:=\sum_{k=0}^{n_{0}-1} r^{*} \circ \sigma^{k}$.
(2) $\pi:(\Sigma \times\{0\})_{r^{*}} \rightarrow \widetilde{M}_{0}$ is a surjective two-to-one map, where

$$
(\Sigma \times\{0\})_{r^{*}}=\left\{(x, 0, t): 0 \leq t<r^{*}(x)\right\}
$$

$\pi$ is one-to-one everywhere except on a set of which maps into a countable union of geodesics in $T^{1} M$.
(3) If $Q_{\xi_{0}, t_{0}}(x, \xi, t)=\left(x, \xi+\xi_{0}, t+t_{0}\right)$, then $\pi \circ Q_{\left(\xi_{0}, t_{0}\right)}=\left[g^{\left.t_{0} \circ D_{\xi_{0}}\right] \circ \pi \text { for all }}\right.$ $\left(\xi_{0}, t_{0}\right) \in \mathbb{Z}^{d} \times \mathbb{R} ;$
(4) $\pi \circ T_{\left(f,-r^{*}\right)}=\pi$ where $T_{\left(f,-r^{*}\right)}(x, \xi, t)=\left(\sigma x, \xi+f(x), t-r^{*}(x)\right)$;
(5) Suppose $\omega=\pi(x, \xi, t), \omega^{\prime}=\pi\left(x^{\prime}, \xi^{\prime}, t^{\prime}\right)$. Then

$$
\exists p, q \geq 0 \text { s.t }\left\{\begin{array}{l}
x_{p}^{\infty}=\left(x^{\prime}\right)_{q}^{\infty} \\
t-t^{\prime}=h(x)-h\left(x^{\prime}\right)+r_{p}(x)-r_{q}\left(x^{\prime}\right) \quad \Rightarrow \exists \tau \text { s.t. } \omega^{\prime}=h^{\tau}(\omega) . \\
\xi-\xi^{\prime}=f_{q}\left(x^{\prime}\right)-f_{p}(x)
\end{array}\right.
$$

(6) For every $\omega$, there are at most countably many points on $\left\{h^{t} \omega\right\}_{t \in \mathbb{R}}$ with more than one $\pi$-preimage.
(7) Nonarithmeticity $\backslash \mathbf{S h}: \overline{\left\langle\left(-r_{n}(x), f_{n}(x)\right): T^{n} x=x, n \in \mathbb{N}\right\rangle}=\mathbb{R} \times \mathbb{Z}^{d}$. (See also (C.)

Most of lemma 2.1 extends variable curvature, except for parts (2) and it immediate corollary (6), which we only know how to prove using the the explicit nature of the Bowen-Series coding in constant negative curvature.

Symbolic Coordinates. The symbolic coordinates of $\omega \in T^{1} M$ are defined to be $(x, \xi, t)$ such that $\omega=\pi(x, \xi, t)$ and $0 \leq t<r^{*}(x)$.

We call $x=x(\omega)$ the $\Sigma$-coordinate, $\xi=\xi(\omega)$ the $\mathbb{Z}^{d}$-coordinate, and $t=t(\omega)$ the $\mathbb{R}$-coordinate (of $\omega$ ).

Some vectors have two sets of symbolic coordinates, but the collection of such vectors intersects every horocycle at a negligible, even countable, set. Therefore such vectors are of no consequence to us.

The Symbolic Description of the Babillot-Ledrappier Measures. Suppose a flow $\phi^{t}: X \rightarrow X$ has a Poincaré section $K$ with section map $T_{K}: K \rightarrow K$. If we represent the flow as a suspension over the section, then any $\phi$-invariant measure can be identified with the product of a $T_{K}$-invariant measure $\mu_{K}$ and the Lebesgue measure on $\mathbb{R}$, restricted to the suspension space. Thus any $\phi$-invariant measure is determined by the measure it induces on a Poincaré section.

The horocycle flow has a Poincaré section which can be naturally coded as $\Sigma^{+} \times$ $\mathbb{Z}^{d} \times \mathbb{R}$. We describe the Babillot-Ledrappier measures in terms of the measures they induce on this section.

Let $S$ be the set of states of $\Sigma$, and fix some $P: S \rightarrow S$ such that $(P(a), a)$ is admissible. Define $\rho^{\prime}: \Sigma^{+} \times \mathbb{Z}^{d} \times \mathbb{R} \rightarrow \Sigma \times \mathbb{Z}^{d} \times \mathbb{R}$ by $\rho^{\prime}\left(x^{+}, \xi, s\right)=(x, \xi, s+h(x))$ where $x_{0}^{\infty}=\left(x^{+}\right)_{0}^{\infty}$, and $x_{k}=P\left(x_{k+1}\right)$ for $k<0$. By BM] (see also [S])
(1) $\rho:=\pi \circ \rho^{\prime}$ maps $\Sigma^{+} \times \mathbb{Z}^{d} \times \mathbb{R}$ onto a Poincaré section for the horocycle flow on $T^{1} M$;
(2) if $\exists p, q$ s.t. $\left(x^{+}\right)_{p}^{\infty}=\left(y^{+}\right)_{q}^{\infty}, \xi-\xi^{\prime}=f_{q}\left(x^{+}\right)-f_{p}\left(y^{+}\right), s-s^{\prime}=r_{p}(x)-r_{q}\left(x^{\prime}\right)$, then $\rho\left(x^{+}, \xi, s\right)$ and $\rho\left(y^{+}, \xi^{\prime}, s^{\prime}\right)$ lie on the same horocycle.
There is a slight inconvenience in that $\rho$ is countably-to-one (because of lemma 2.1 part (4)). We shall deal with this problem by working with restrictions of $\rho$ to sets where it is one-to-one.

By (1), any measure $m$ on $T^{1} M$ can be identified (locally, on subsets of the suspension space on which $\rho$ is one-to-one) with $\mu \times d t$, where $\mu$ is some measure on $\Sigma^{+} \times \mathbb{Z}^{d} \times \mathbb{R}$. By (2), if $\mu$ is invariant for the equivalence relation

$$
\left(x^{+}, \xi, s\right) \sim\left(y^{+}, \xi^{\prime}, s^{\prime}\right) \Longleftrightarrow\left\{\begin{array}{rlr}
\left(x^{+}\right)_{p}^{\infty} & =\left(y^{+}\right)_{q}^{\infty}  \tag{2.1}\\
\xi-\xi^{\prime} & =f_{q}\left(x^{+}\right)-f_{p}\left(y^{+}\right) \\
s-s^{\prime} & =r_{p}(x)-r_{q}\left(x^{\prime}\right),
\end{array}\right.
$$

then $\mu$ is invariant for the Poincaré map of the horocycle flow ${ }^{1}$, and therefore gives rise to a flow invariant measure on $T^{1} M$ (see BL2 for details).

This was the way Babillot and Ledrappier constructed their family of infinite invariant measures for the horocycle flow: they constructed an infinite family of measures $\mu_{\varphi}$ which are invariant under the equivalence relation (2.1).

The construction uses the thermodynamic formalism. We review some necessary facts (see e.g. $\mathbf{P P}$ ). Let $\sigma: \Sigma^{+} \rightarrow \Sigma^{+}$denote the one-sided version of $\Sigma$. The topological pressure of a continuous function $\varphi: \Sigma^{+} \rightarrow \mathbb{R}$ is the number $P_{\text {top }}(\varphi):=$ $\sup \left\{h_{\mu}(\sigma)+\int \varphi d \mu\right\}$ where the supremum ranges over all shift invariant probability measures on $\Sigma^{+}$. Define $P: \mathbb{R}^{d} \rightarrow \mathbb{R}$ implicitly by $u \mapsto P(u)$ where $P(u)=P$ is the root of

$$
P_{t o p}(-\operatorname{Pr}+\langle u, f\rangle)=1
$$

This defines a $C^{\infty}$-diffeomorphism from $\mathbb{R}^{d}$ onto $\operatorname{int}(\mathfrak{C})$ BL2. This diffeomorphism can be defined canonically, and does not depend on the particular choice of the coding, see BL2.

Any homomorphism $\varphi: \mathbb{Z}^{d} \rightarrow \mathbb{R}$ can be identified with a vector $u_{\varphi} \in \mathbb{R}^{d}$ by $\varphi(\cdot)=\left\langle u_{\varphi}, \cdot\right\rangle$. Define the operator $L_{-P\left(u_{\varphi}\right), u_{\varphi}}: C\left(\Sigma^{+}\right) \rightarrow C\left(\Sigma^{+}\right)$by

$$
\left(L_{-P\left(u_{\varphi}\right), u_{\varphi}} F\right)(x)=\sum_{\sigma y=x} e^{-P\left(u_{\varphi}\right) r(y)+\left\langle u_{\varphi}, f(y)\right\rangle} F(y)
$$

Ruelle's Perron-Frobenius Theorem says that there exists a probability measure $\nu_{\varphi}$ and a positive Hölder continuous function $\Psi_{\varphi}$ on $\Sigma^{+}$such that

$$
L_{-P\left(u_{\varphi}\right), u_{\varphi}} \Psi_{\varphi}=\Psi_{\varphi}, L_{P\left(u_{\varphi}\right), u_{\varphi}}^{*} \nu_{\varphi}=\nu_{\varphi}, \text { and } \int \Psi_{\varphi} d \nu_{\varphi}=1
$$

The Babillot-Ledrappier measure $m_{\varphi}$ (on $T^{1} M$ ) is given locally by $\mu_{\varphi} \times d t$, where $\mu_{\varphi}$ (a measure on the Poincaré section) is given in symbolic coordinates by

$$
\begin{equation*}
d \mu_{\varphi}(x, \xi, s):=\text { const } e^{-P\left(u_{\varphi}\right) s+\left\langle u_{\varphi}, \xi\right\rangle} d \nu_{\varphi} d \xi d s \tag{2.2}
\end{equation*}
$$

This formula can be used to deduce the following important consequences:
(1) $m_{\varphi}$ is quasi-invariant under the geodesic flow, and $m_{\varphi} \circ g^{s}=e^{-P\left(u_{\varphi}\right) s} m_{\varphi}$;
(2) $\Xi_{\varphi}=(\nabla P)\left(u_{\varphi}\right)$ (corollary 6.1 in BL2 $) ;$
(3) $u_{\varphi}=-(\nabla H)\left(\Xi_{\varphi}\right)$, where $H(\cdot)$ is minus the Legendre transform of $P(\cdot)$.
(The double minus sign in (3) is a convention from BL2.)

[^1]Symbolic Local Manifolds. Suppose $\omega$ has symbolic coordinates ( $x, \xi, t$ ) (i.e. $\left.0 \leq s+h(x)<r^{*}(x)\right)$, and write $t=s+h(x)$. The symbolic local stable manifold of $\omega=\pi(x, \xi, s+h(x))$ is defined by

$$
W_{\mathrm{loc}}^{s s}(\omega):=\pi\left\{(y, \xi, s+h(y)): y_{0}^{\infty}=x_{0}^{\infty}\right\} .
$$

This is a subset of $\operatorname{Hor}(\omega)$, because of lemma 2.1 part (5).
If $W_{\text {loc }}^{s s}\left(\omega_{1}\right), W_{\text {loc }}^{s s}\left(\omega_{2}\right)$ intersect with positive measure, then they are equal up to sets of length zero. Indeed, for almost every $\omega$ in the intersection $\exists p$ s.t. $\omega=$ $\pi\left(x, \xi\left(\omega_{1}\right), s\left(\omega_{1}\right)+h(x)\right), x_{0}^{\infty}=x\left(\omega_{1}\right)_{0}^{\infty}$ and $\omega=\pi\left(\sigma^{p} x, \xi\left(\omega_{2}\right), s\left(\omega_{2}\right)+h\left(\sigma^{p} x\right)\right)$, $x_{p}^{\infty}=x\left(\omega_{2}\right)_{0}^{\infty}$. This forces $x\left(\omega_{1}\right)_{p}^{\infty}=x\left(\omega_{2}\right)_{0}^{\infty}, \xi\left(\omega_{2}\right)=\xi\left(\omega_{1}\right)+f_{p}\left(x\left(\omega_{1}\right)\right), s\left(\omega_{2}\right)=$ $s\left(\omega_{1}\right)-r_{p}\left(x\left(\omega_{1}\right)\right)$ (lemma 2.1 part (1)). It follows from lemma 2.1 parts (4) and (1) that $W_{\text {loc }}^{s s}\left(\omega_{1}\right)=W_{\text {loc }}^{s s}\left(\omega_{2}\right)$ up to sets of measure zero.

Lemma 2.2. BL2, prop. 4.5] Let $\ell_{\omega}$ denote the hyperbolic length measure on the horocycle of $\omega$. If $\omega=\pi(x, \xi, s+h(x))$, then $\ell_{\omega}\left[W_{\text {loc }}^{s s}(\omega)\right]=e^{-s} \psi\left(x_{0}, x_{1}, \ldots\right)$ where $\psi: \Sigma^{+} \rightarrow \mathbb{R}$ is Hölder continuous and positive. (In fact $\psi=\Psi_{0}$.)

## 3. Proof that a Generic Vector has Asymptotic Cycle in $\operatorname{int}(\mathfrak{C})$

In this section we prove
Proposition 3.1. Let $M$ be a $\mathbb{Z}^{d}$-cover of a compact hyperbolic surface. If $\omega_{0}$ is generic for some horocycle invariant Radon measure $m$, then there exists a homomorphism $\varphi: \mathbb{Z}^{d} \rightarrow \mathbb{R}$ and $c>0$ such that $m=c m_{\varphi}$ and $\Xi(\omega)=\Xi_{\varphi}$.

The proof is as follows. Suppose $\omega_{0}$ is generic for some horocycle ergodic invariant Radon measure $m$. By [ $\mathbf{S}]$, there is a homomorphism $\varphi: \mathbb{Z}^{d} \rightarrow \mathbb{R}$ and $c>0$ such that $m=c m_{\varphi}$. Of course if $\omega_{0}$ is generic for $c m_{\varphi}$, then it is generic for $m_{\varphi}$, therefore we may assume w.l.o.g. that $m=m_{\varphi}$. We saw above that $\Xi(\omega)=\Xi_{\varphi} m_{\varphi}$-a.e., for some $\Xi_{\varphi} \in \operatorname{int}(\mathfrak{C})$. We aim at showing that $\Xi\left(\omega_{0}\right)=\Xi_{\varphi}$.

Recall that $\widetilde{M}_{0} \subset T^{1} M$ is the set of vectors whose $\mathbb{Z}^{d}$-coordinate is equal to zero, and define the following objects:

$$
\begin{align*}
A_{T} & :=\left\{h^{t}\left(\omega_{0}\right): 0 \leq t \leq T\right\} \\
\lambda_{T} & :=\text { the normalized length measure on } A_{T} \cap \widetilde{M}_{0}  \tag{3.1}\\
& =\frac{1}{\int_{0}^{T} 1_{\widetilde{M}_{0}}\left(h^{t}\left(\omega_{0}\right)\right) d t} \int_{0}^{T} 1_{\widetilde{M}_{0}}\left(h^{t} \omega_{0}\right) \delta_{h^{t}\left(\omega_{0}\right)} d t \quad\left(\delta_{x}:=\text { Dirac at } x\right) \\
\Lambda_{n}\left(N, \varepsilon_{0}\right) & :=\left\{\omega \in \widetilde{M}_{0}: \omega=\pi(x, \underline{,}, s) \text { and }\left\|\frac{f_{N}\left(\sigma^{n N} x\right)}{r_{N}^{*}\left(\sigma^{n N} x\right)}-\Xi_{\varphi}\right\|<\varepsilon_{0}\right\} . \tag{3.2}
\end{align*}
$$

Recall that $n_{0}$ is a constant such that $\min r_{n_{0}}^{*}>0$ (lemma 2.1 part (1)). The key to the proof of proposition 3.1 is the following lemma:

Lemma 3.2 (Key Lemma). There are $C_{0}, T_{0}>0$ such that for every $\varepsilon_{0}>0$ there are constants $N\left(\varepsilon_{0}\right)>n_{0}, K\left(\varepsilon_{0}\right)>0$, and $\tau\left(\varepsilon_{0}\right)$ such that for all $T>\tau\left(\varepsilon_{0}\right)$

$$
\begin{equation*}
\sup _{n} \lambda_{T}\left\{\omega: r_{n N\left(\varepsilon_{0}\right)}^{*}(x(\omega))<\ln \frac{T}{T_{0}}-K\left(\varepsilon_{0}\right) \text { and } \omega \notin \Lambda_{n}\left(N\left(\varepsilon_{0}\right), \varepsilon_{0}\right)\right\} \leq C_{0} \varepsilon_{0} . \tag{3.3}
\end{equation*}
$$

The proof is somewhat technical, so we postpone it, and first explain how to use the lemma to prove proposition 3.1.

Fix $\varepsilon_{0}$ and set $N=N\left(\varepsilon_{0}\right), K=K\left(\varepsilon_{0}\right), \Lambda_{n}:=\Lambda_{n}\left(N\left(\varepsilon_{0}\right), \varepsilon_{0}\right)$, and $T^{*}:=$ $\ln \left(T / T_{0}\right)$. Abbreviate $\left\{r_{n N}^{*}<T^{*}-K\right\}:=\left\{\omega \in T^{1} M: r_{n N}^{*}(x(\omega))<T^{*}-K\right\}$.

Working in the symbolic model for $T^{1} M$, define the following functions, which we view as random variables on $A_{T}: A_{k}:=f_{N} \circ \sigma^{k N} 1_{\left\{r_{k N}^{*}<T^{*}-K\right\}}$ and $B_{k}:=$ $r_{N}^{*} \circ \sigma^{k N} 1_{\left\{r_{k N}^{*}<T^{*}-K\right\}}$. Then for all $T$ large enough

$$
\begin{aligned}
& \mathbb{E}_{\lambda_{T}}\left(\frac{\sum_{i} A_{i}}{\sum_{i} B_{i}}\right)=\mathbb{E}_{\lambda_{T}}\left(\sum_{i} \frac{B_{i}}{\sum_{j} B_{j}}\left[\left(\frac{A_{i}}{B_{i}}-\Xi_{\varphi}\right) 1_{\left\{r_{i N}^{*}<T^{*}-K\right\}}\right]\right)+\Xi_{\varphi} \\
& =\Xi_{\varphi} \pm \sum_{i}\left\|\frac{B_{i}}{\sum_{j} B_{j}}\right\|_{\infty}\left\|\left(\frac{A_{i}}{B_{i}}-\Xi_{\varphi}\right) 1_{\left\{r_{i N}^{*}<T^{*}-K\right\}}\right\|_{1} \\
& =\Xi_{\varphi} \pm \sum_{i=1}^{\left[\left(T^{*} / \min r_{n_{0}}^{*}\right)+n_{0}\right] / N}\left(\frac{N \max r^{*}}{T^{*}-K-N \max r^{*}}\right)\left\|\left(\frac{A_{i}}{B_{i}}-\Xi_{\varphi}\right) 1_{\left\{r_{i N}^{*}<T^{*}-K\right\}}\right\|_{1} .
\end{aligned}
$$

We estimate the $L^{1}$-norm by breaking the support of $\lambda_{T}$ into $\widetilde{M}_{0} \cap \Lambda_{i}$ and $\widetilde{M}_{0} \backslash \Lambda_{i}$ :

$$
\begin{aligned}
& \left\|\left(\frac{A_{i}}{B_{i}}-\Xi_{\varphi}\right) 1_{\left\{r_{i N}^{*}<T^{*}-K\right\}}\right\|_{1} \\
& \quad \leq \varepsilon_{0} \lambda_{T}\left(\widetilde{M}_{0} \cap \Lambda_{i}\right)+\left(\frac{N \max \|f\|_{\infty}}{\left\lfloor N / n_{0}\right\rfloor \min r_{n_{0}}^{*}}+\left\|\Xi_{\varphi}\right\|\right) \lambda_{T}\left(\widetilde{M}_{0} \cap\left\{r_{i N}^{*}<T^{*}-K\right\} \backslash \Lambda_{i}\right) \\
& \quad \leq \varepsilon_{0}+\left(\frac{N \max \|f\|_{\infty}}{\left\lfloor N / n_{0}\right\rfloor \min r_{n_{0}}^{*}}+\left\|\Xi_{\varphi}\right\|\right) \sup _{i} \lambda_{T}\left(\widetilde{M}_{0} \cap\left\{r_{i N}^{*}<T^{*}-K\right\} \backslash \Lambda_{i}\right)
\end{aligned}
$$

Thus, the key lemma implies that for all $T$ large enough

$$
\begin{equation*}
\left\|\mathbb{E}_{\lambda_{T}}\left(\frac{\sum_{i} A_{i}}{\sum_{i} B_{i}}\right)-\Xi_{\varphi}\right\| \leq \operatorname{const} \varepsilon_{0} \tag{3.4}
\end{equation*}
$$

with the constant independent of $T$ and $\varepsilon_{0}$.
But the quotient whose expectation we are calculating is nearly constant! For every $\omega \in\left\{h^{t}\left(\omega_{0}\right): 0<t<T\right\}, \sum_{i} B_{i}=T^{*} \pm\left(K+N \max r^{*}\right)$, and

$$
\begin{aligned}
\sum_{i} A_{i} & =\xi\left(g^{T^{*}} \omega\right) \pm(K+N) n_{0} \frac{\max \|f\|}{\min r_{n_{0}}^{*}} \\
& =\xi\left(g^{T^{*}} \omega_{0}\right) \pm\left[(K+N) n_{0} \frac{\max \|f\|}{\min r_{n_{0}}^{*}}+\left\|\xi\left(g^{T^{*}} \omega\right)-\xi\left(g^{T^{*}} \omega_{0}\right)\right\|\right]
\end{aligned}
$$

Now $\operatorname{dist}\left(g^{T^{*}}(\omega), g^{T^{*}}\left(\omega_{0}\right)\right) \leq e^{-T^{*}} T=T_{0}$, so $\left\|\xi\left(g^{T^{*}} \omega\right)-\xi\left(g^{T^{*}} \omega_{0}\right)\right\|$ is bounded by some constant independent of $T^{*}$. Thus we obtain $\sum_{i} A_{i}=\xi\left(g^{T^{*}} \omega_{0}\right) \pm$ const, where the constant is independent of $T^{*}$.

We see that

$$
\mathbb{E}_{\lambda_{T}}\left(\frac{\sum_{i} A_{i}}{\sum_{i} B_{i}}\right)=\frac{\xi\left(g^{T^{*}} \omega_{0}\right) \pm \mathrm{const}}{T^{*} \pm \mathrm{const}}=[1+o(1)] \frac{1}{T^{*}} \xi\left(g^{T^{*}} \omega_{0}\right)+o(1)
$$

Comparing this with (3.4), we see that for $T$ large, $\left\|\frac{1}{T^{*}} \xi\left(g^{T^{*}} \omega_{0}\right)-\Xi_{\varphi}\right\|<$ const $\varepsilon_{0}$, with the constant independent of $\varepsilon_{0}$. Since $\varepsilon_{0}$ was arbitrary, $\omega_{0}$ has asymptotic cycle $\Xi_{\varphi}$, and proposition 3.1 is proved (assuming lemma 3.2).

The remainder of the section contains the proof of lemma 3.2. The proof requires the construction of certain self maps of horocycles. These are constructed and studied in the next subsections.

Preparations I: Distortion Estimates. We find uniform bounds on the RadonNikodym derivative of certain maps between local symbolic stable manifolds, equipped with the hyperbolic length measure.

Define an equivalence relation on $\Sigma$ via

$$
x \sim y \Leftrightarrow \exists p, q \text { s.t. } x_{p}^{\infty}=y_{q}^{\infty}
$$

(the equivalence class of $x$ can be viewed as the weak stable "manifold" of $x$ for the action of the shift). If $x, y$ are non-eventually periodic, then the following are independent of the choice of $p, q$ :

$$
\begin{align*}
R^{+}(x, y) & :=r_{q}(y)-r_{p}(x) \\
R(x, y) & :=r_{q}(y)-r_{p}(x)+h(y)-h(x)=\lim _{n \rightarrow \infty}\left[r_{q+n}^{*}(y)-r_{p+n}^{*}(x)\right]  \tag{3.5}\\
F(x, y) & :=f_{p}(x)-f_{q}(y)=\lim _{n \rightarrow \infty}\left[f_{p+n}(x)-f_{q+n}(y)\right] .
\end{align*}
$$

These are minus the functions appearing in lemma 2.1, part 5 . Note that $R^{+}(x, y)$ and $F(x, y)$ only depend on $x_{0}^{\infty}, y_{0}^{\infty}$.

Fix some admissible sequence $x_{0}^{\infty}$ and two words $\underline{a}, \underline{b}$ (not necessarily of the same length) such that $\left(\underline{a}, x_{0}\right),\left(\underline{b}, x_{0}\right)$ are admissible and such that $a_{0}=b_{0}$. Define

$$
\kappa^{*}:\left\{w \in \Sigma: w_{-|\underline{a}|}^{\infty}=\underline{a} x_{0}^{\infty}\right\} \rightarrow\left\{w \in \Sigma: w_{-|\underline{b}|}^{\infty}=\underline{b} x_{0}^{\infty}\right\}
$$

by

$$
\kappa^{*}(w)= \begin{cases}\left(w_{-}^{-|a|-1}, \underline{b}, \dot{x}_{0}^{\infty}\right) & w=\left(w_{-}^{-|a|-1}, \underline{a}, \dot{x}_{0}^{\infty}\right) \\ \left(w_{-\infty}^{|-|b|-1}, \underline{a}, \dot{x}_{0}^{\infty}\right) & w=\left(w_{-}^{-| | b-1}, \underline{b}, \dot{x}_{0}^{\infty}\right) \\ w & \text { otherwise, }\end{cases}
$$

where the zero coordinate is at the beginning of the dotted word. This induces the following self-map of $W^{s s}(\pi(x, \xi, s+h(x))$ :

$$
\kappa[\pi(w, \xi, s+h(w))]=\pi\left(\kappa^{*}(w), \xi, s+h\left(\kappa^{*}(w)\right)\right)
$$

This map is well-defined and one-to-one on $W_{\text {loc }}^{s s}(\pi(x, \xi, s+h(x)))$ minus a countable set (Lemma 2.1, part 2).

Lemma 3.3. $\kappa: W_{\text {loc }}^{s s}(\pi(x, \xi, s+h(x))) \rightarrow W_{\text {loc }}^{s s}(\pi(x, \xi, s+h(x)))$ is absolutely continuous with respect to the hyperbolic length measure $\ell$, and there is some constant $D^{\prime}>1$, independent of $x_{0}^{\infty}, \underline{a}$, and $\underline{b}$ such that

$$
\left(D^{\prime}\right)^{-1} \exp \left[-\left|R^{+}\left(\underline{a} x_{0}^{\infty}, \underline{b} x_{0}^{\infty}\right)\right|\right] \leq \frac{d \ell \circ \kappa}{d \ell} \leq D^{\prime} \exp \left[\left|R^{+}\left(\underline{a} x_{0}^{\infty}, \underline{b} x_{0}^{\infty}\right)\right|\right]
$$

Proof. Split the domain of $\kappa$ into three parts: $A$, where it flips $\underline{a}$ to $\underline{b}, B$ where it flips $\underline{b}$ to $\underline{a}$, and $C$, where $\kappa=i d$.

We estimate the derivative on $A$. Fix $n$ and a word $\left(x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}\right)$ such that $\left(x_{-|\underline{a}|}^{\prime}, \ldots, x_{-1}^{\prime}\right)=\underline{a}$. We study the distortion in the length of the horocycle piece $K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}:=\left\{\pi(w, \xi, s+h(w)): w_{-n}^{\infty}=\left(\left(x^{\prime}\right)_{-n}^{-1}, x_{0}^{\infty}\right)\right\}:$

$$
\begin{aligned}
\ell & {\left[K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}\right]=\ell\left[\left\{\pi(w, \xi, s+h(w)): w_{-n}^{\infty}=\left(\left(x^{\prime}\right)_{-n}^{-1}, x_{0}^{\infty}\right)\right\}\right] } \\
& =\ell\left[\left\{\pi\left(\sigma^{-n} w, \xi-f_{n}\left(\sigma^{-n} w\right), s+h(w)+r_{n}^{*}\left(\sigma^{-n} w\right)\right): w_{-n}^{\infty}=\left(\left(x^{\prime}\right)_{-n}^{-1}, x_{0}^{\infty}\right)\right\}\right] \\
& =\ell\left[\left\{\pi\left(w^{\prime}, \xi, s+h\left(\sigma^{n} w^{\prime}\right)+r_{n}^{*}\left(w^{\prime}\right)\right):\left(w^{\prime}\right)_{0}^{\infty}=\left(\left(x^{\prime}\right)_{-n}^{-1}, x_{0}^{\infty}\right)\right\}\right] \quad\left(\because \ell \circ D_{f_{n}}=\ell\right) \\
& =\ell\left[\left\{\pi\left(w^{\prime}, \xi, s+h\left(w^{\prime}\right)+r_{n}\left(w^{\prime}\right)\right):\left(w^{\prime}\right)_{0}^{\infty}=\left(\left(x^{\prime}\right)_{-n}^{-1}, x_{0}^{\infty}\right)\right\}\right] \\
& =e^{-r_{n}\left(x_{-n}^{\prime}, \ldots x_{-1}^{\prime}, x_{0}^{\infty}\right)} \psi\left(x_{-n}^{\prime}, \ldots x_{-1}^{\prime}, x_{0}^{\infty}\right) \quad\left(\because \ell \circ g^{s}=e^{-s} \ell\right) .
\end{aligned}
$$

A similar calculation shows that

$$
(\ell \circ \kappa)\left[K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}\right]=e^{-r_{n+|\underline{\underline{b}}|-|\underline{\underline{a}}|}\left(x_{-n}^{\prime}, \ldots x_{\left.-\mid \underline{\underline{a} \mid-1}, \underline{b}, x_{0}^{\infty}\right)}^{\prime}\right.} \psi\left(x_{-n}^{\prime}, \ldots x_{-|\underline{a}|-1}^{\prime}, \underline{b}, x_{0}^{\infty}\right) .
$$

Dividing, we see that

$$
\begin{aligned}
\frac{(\ell \circ \kappa)\left[K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}\right]}{\ell\left[K_{\left.x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}\right]}\right]}= & \frac{\exp \left[r_{n}\left(x_{-n}^{\prime}, \ldots x_{-1}^{\prime}, x_{0}^{\infty}\right)\right]}{\exp \left[r_{n+|\underline{b}|-|\underline{a}|}\left(x_{-n}^{\prime}, \ldots x_{-|\underline{a}|-1}^{\prime}, \underline{b}, x_{0}^{\infty}\right)\right]} \\
& \times \frac{\psi\left(x_{-n}^{\prime}, \ldots x_{-|\underline{a}|-1}^{\prime}, \underline{b}, x_{0}^{\infty}\right)}{\psi\left(x_{-n}^{\prime}, \ldots, x_{-1}^{\prime} x_{0}^{\infty}\right)} \\
\leq & \left(\frac{\max \psi}{\min \psi}\right) e^{\left|R^{+}\left(\underline{a} x_{0}^{\infty}, \underline{b} x_{0}^{\infty}\right)\right|+\operatorname{var}(r)} .
\end{aligned}
$$

Thus, for a global constant $D^{\prime}$ independent of $x, \underline{a}$, and $\underline{b}$,

$$
\frac{(\ell \circ \kappa)\left[K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}\right]}{\ell\left[K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}\right]} \leq D^{\prime} \exp \left[\left|R\left(\underline{a} x_{0}^{\infty}, \underline{b} x_{0}^{\infty}\right)\right|\right]
$$

Since this estimate holds for all $n>|\underline{a}|$, and since $\left\{K_{x_{-n}^{\prime}, \ldots, x_{-1}^{\prime}}\right\}$ generate the Borel sigma-algebra of $A$, we get that $\left.\ell \circ \kappa\right|_{A} \ll \ell$, and $d \ell \circ \kappa / d \ell \leq D^{\prime} \exp \left[\left|R\left(\underline{a} x_{0}^{\infty}, \underline{b} x_{0}^{\infty}\right)\right|\right]$. The lower bound on the derivative is obtained in exactly the same manner, as do the estimates for the distortion of $\kappa$ on $B$.

We turn to discuss a different class of maps between local symbolic manifolds. Fix two admissible sequences $x_{0}^{\infty}, y_{0}^{\infty}$ and define

$$
\vartheta^{*}:\left\{w \in \Sigma: w_{0}^{\infty}=x_{0}^{\infty}\right\} \rightarrow\left\{w \in \Sigma: w_{0}^{\infty}=y_{0}^{\infty}\right\}
$$

by $\vartheta^{*}(w)=\left(w_{-\infty}^{-1}, \underline{w}_{w_{-1} y_{0}}, \dot{y}_{0}^{\infty}\right)$, where $\underline{w}_{w_{-1} y_{0}}$ is a bridge word out of the (fixed) collection $\mathfrak{B}$, and where the zero coordinate is the first symbol of the dotted word.

This induces the map from $W_{\text {loc }}^{s s}\left(\pi(x, \xi, s+h(x))\right.$ into $W_{\mathrm{loc}}^{s s}(\pi(y, \xi, s+h(y))$

$$
\vartheta[\pi(w, \xi, s+h(w))]=\pi\left(\vartheta^{*}(w), \xi, s+h\left(\vartheta^{*}(w)\right)\right)
$$

As before, $\vartheta$ is well-defined and one-to-one on $W_{\text {loc }}^{s s}(\pi(x, \xi, s+h(x)))$ minus a countable set. But we can not claim it is surjective (because of the insertion of a fixed bridge word).

Lemma 3.4. $\vartheta: W_{\mathrm{loc}}^{s s}(\pi(x, \xi, s+h(x))) \rightarrow W_{\text {loc }}^{s s}(\pi(y, \xi, s+h(y)))$ is absolutely continuous with respect to the hyperbolic length measure $\ell$, and there is some constant $D^{\prime \prime}>1$, independent of $x_{0}^{\infty}$ and $y_{0}^{\infty}$ such that $D^{\prime \prime-1} \leq d \ell \circ \vartheta / d \ell \leq D^{\prime \prime}$.
Proof. Fix $n$ and a word $\left(w_{-n}, \ldots, w_{-1}\right)$ such that $\left[w_{-1}, x_{0}\right] \neq \varnothing$, and set

$$
K_{w_{-n}, \ldots, w_{-1}}:=\left\{\pi\left(w^{\prime}, \xi, s+h\left(w^{\prime}\right)\right):\left(w^{\prime}\right)_{-n}^{\infty}=\left(w_{-n}^{-1}, x_{0}^{\infty}\right)\right\}
$$

The same calculation as in the previous lemma shows that

$$
\begin{aligned}
& \frac{(\ell \circ \vartheta)\left[K_{w_{-n}, \ldots, w_{-1}}\right]}{\ell\left[K_{w_{-n}, \ldots, w_{-1}}\right]}= \frac{\exp \left[r_{n}\left(w_{-n}, \ldots w_{-1}, x_{0}^{\infty}\right)\right]}{\left.\exp \left[r_{n+\left|\underline{w}_{w_{-1} y_{0}}\right|} \mid w_{-n}, \ldots w_{-1}, \underline{w}_{w_{-1} y_{0}}, y_{0}^{\infty}\right)\right]} \\
& \times \frac{\psi\left(w_{-n}, \ldots w_{-1}, \underline{w}_{w_{-1} y_{0}}, y_{0}^{\infty}\right)}{\psi\left(w_{-n}, \ldots, w_{-1} x_{0}^{\infty}\right)} \\
& \leq\left(\frac{\max \psi}{\min \psi}\right) \times \exp [\operatorname{var}(r)] \times \max _{\underline{w} \in \mathfrak{B}}\left[\exp \max _{x \in[\underline{w}]}\left|r_{M_{b r}}(x)\right|\right] .
\end{aligned}
$$

As in the proof of the previous lemma, this implies that for some constant $D_{1}^{\prime \prime}>1$, independent of $x$ and $y, d \ell \circ \vartheta / d \ell \leq D_{1}^{\prime \prime}$. A uniform lower bound $D_{2}^{\prime \prime}$ can be obtained in exactly the same manner.

Preparations II: Permuting Points on a Horocycle. We use the transformations discussed above to construct certain maps which 'permute' points on a given horocycle. These bijections are defined symbolically in terms of the coding $\pi(x, \xi, s)$. They take the form

$$
\begin{aligned}
\theta[\pi(x, \xi, s+h(x))] & =\pi\left(\theta^{*}(x), \xi+F\left(x, \theta^{*}(x)\right), s+h(x)+R\left(x, \theta^{*}(x)\right)\right) \\
& =\pi\left(\theta^{*}(x), \xi+F\left(x, \theta^{*}(x)\right), s+h\left(\theta^{*} x\right)+R^{+}\left(x, \theta^{*}(x)\right)\right)
\end{aligned}
$$

where $\theta^{*}$ will be defined below, and $F(\cdot, \cdot), R(\cdot, \cdot), R^{+}(\cdot, \cdot)$, given by (3.5), are designed to ensure that $\theta[\pi(x, \xi, s)]$ stays on the horocycle of $\pi(x, \xi, s)$. Definitions of this form make sense everywhere on the horocycle where $\pi$ is injective, therefore everywhere except a countable set.

The maps $\theta^{*}(x)$ we need fall into two groups (precise definitions and explanation of notation follow):
(1) maps $\theta^{*}=\kappa_{n, N}^{*}$ which exchange the positions of two $N$-blocks in $x$,
(2) maps $\theta^{*}=\vartheta_{T^{*}, \omega_{1}, \omega_{2}}^{*}$ which exchange some suffix of $x$ by another suffix.

Exchanging blocks: $\kappa_{n, N}$. Fix $n, N \in \mathbb{N}$. Define $\kappa_{n, N}^{*}$ on $\Sigma$ by exchanging the places of the $N$-blocks $(x)_{0}^{N-1},(x)_{n N}^{n N+N-1}$, and then inserting bridge words (see $\left.\S 2\right)$ at the right places to ensure admissibility:

$$
\begin{aligned}
\kappa_{n, N}^{*}(x):=\left(x_{-\infty}^{-1}, w_{x_{-1} x_{n N}},\right. & , \dot{x}_{n N}^{n N+N-1}, w_{x_{n N+N-1}, x_{N}} \\
& \left.x_{N}^{n N-1}, w_{x_{n N-1}, x_{0}}, x_{0}^{N-1}, w_{x_{N-1}, x_{(n+1)}}, x_{(n+1) N}^{\infty}\right)
\end{aligned}
$$

The zero coordinate is at the first symbol of the dotted word, and the boxed blocks are those that were switched. This gives rise to the following self-map of the horocycle $\operatorname{Hor}(\pi(x, s, h(x))$ :
$\kappa_{n, N}(\pi(x, \underline{\xi}, s+h(x))):=\pi\left(\kappa_{n, N}^{*} x, \xi+F\left(x, \kappa_{n, N}^{*} x\right), s+h\left(\kappa_{n, N}^{*} x\right)+R^{+}\left(x, \kappa_{n, N}^{*} x\right)\right)$.
Lemma 3.5. The map $\kappa_{n, N}$ is absolutely continuous and injective on a subset of full $\ell$-measure of $\operatorname{Hor}(\pi(x, \xi, s+h(x)))$, and there exist constants $C_{r}^{\prime} \geq 1, E^{\prime}$, and $L^{\prime}$ independent of $n, N$ and $x$ such that
(1) $\left(C_{r}^{\prime}\right)^{-1} \leq d \ell \circ \kappa_{n, N} / d \ell \leq C_{r}^{\prime}$,
(2) the $\Sigma$-coordinate of $\kappa_{n, N}(\pi(x, \xi, t))$ is $\sigma^{l}\left(\kappa_{n, N}^{*}(x)\right)$ for some $|l| \leq L^{\prime}$,
(3) $\operatorname{dist}\left(\omega, \kappa_{n, N}(\omega)\right) \leq E^{\prime}\left(\operatorname{dist}=\operatorname{dist}_{T^{1} M}\right)$.

Proof. The map $\kappa_{n, N}^{*}$ can be thought of locally as the map which exchanges the word $\underline{a}$ by $\underline{b}$, where

$$
\begin{aligned}
\underline{a} & =\left(x_{0}, \ldots, x_{(n+1) N-1}\right) \\
\underline{b} & =\left(w_{x_{-1} x_{N n}}, x_{N n}^{(n+1) N-1}, w_{x_{N(n+1)-1}, x_{N}}, x_{N}^{N n-1}, w_{x_{N n-1}, x_{0}}, x_{0}^{N-1}, w_{x_{N-1}, x_{(n+1) N}}\right)
\end{aligned}
$$

Note that $|\underline{a}|=(n+1) N$, and $|\underline{b}|=(n+1) N+4 M_{b r}$, where $M_{b r}$ is the length of the bridge words in $\mathfrak{B}$.

The distortion of such maps was found in Lemma 3.3. A direct calculation using the boundedness and Hölder continuity of $r$ shows that there exist a constant
$E_{R}^{\prime}$, which only depends on $\max r, M_{b r}$ and $\operatorname{var}(r)$ (but not on $N, n$ ), such that $\left|R^{+}\left(\underline{a} x_{(n+1) N}^{\infty}, \underline{b} x_{(n+1) N}^{\infty}\right)\right|<E_{R}^{\prime}$. Part (1) follows from lemma 3.3.

Next we study the $\Sigma$-coordinate of $\kappa_{n, N}(\pi(x, \xi, s+h(x)))$. This must be $\sigma^{l}\left(\kappa_{n, N}^{*} x\right)$ with $l$ such that either $l \geq 0$ and

$$
0 \leq s+h\left(\kappa_{n, N}^{*} x\right)+R^{+}\left(x, \kappa_{n, N}^{*} x\right)-r_{l}^{*}\left(\sigma^{l} \kappa_{n, N}^{*} x\right)<r^{*}\left(\sigma^{l} \kappa_{n, N}^{*} x\right)
$$

or $l<0$ and $0 \leq s+h\left(\kappa_{n, N}^{*} x\right)+R^{+}\left(x, \kappa_{n, N}^{*} x\right)+r_{-l}^{*}\left(\sigma^{l} \kappa_{n, N}^{*} x\right)<r^{*}\left(\sigma^{l} \kappa_{n, N}^{*} x\right)$. We have seen that $\left|R^{+}\left(x, \kappa_{n, N}^{*} x\right)\right| \leq E_{R}^{\prime}$. Since $h$ is bounded and $\inf r_{n_{0}}^{*}>0, l$ must be bounded by some constant $L^{\prime}=L^{\prime}\left(\max |h|, E_{r}^{\prime}, \min r_{n_{0}}^{*}\right)$. Part (2) follows.

Finally we study the $\mathbb{Z}^{d}$-coordinate of $\omega^{\prime}:=\kappa_{n, N}(\pi(x, \xi, s+h(x)))$. If $l$ is as above, then the symbolic coordinates of $\omega^{\prime}$ are (assuming for simplicity that $l>0$ )

$$
\left(\sigma^{l}\left(\kappa_{n, N}^{*}(x)\right), \xi+F\left(\underline{a} x_{(n+1) N}^{\infty}, \underline{b} x_{(n+1) N}^{\infty}\right)+f_{l}\left(\kappa_{n, N}^{*}(x)\right), \text { something }\right) .
$$

It is routine to check that $\|F(\underline{a} x, \underline{b} x)\|$ is uniformly bounded by some constant $E_{F}^{\prime}$ which only depends on max $\|f\|$ and $M_{b r}$. This means that the difference in $\mathbb{Z}^{d}$-coordinates is no more than $\left\|F\left(\underline{a}_{(n+1) N}^{\infty}, \underline{b} x_{(n+1) N}^{\infty}\right)+f_{l}\left(\kappa_{n, N}^{*}(x)\right)\right\| \leq E_{F}^{\prime}+$ $L^{\prime}$ max $\|f\|$.

Thus $\omega, \omega^{\prime}$ lie in two copies of $\widetilde{M}_{0} \subset T^{1} M$ which differ by a deck transformation whose $\mathbb{Z}^{d}$-index is bounded. Since the diameter of $\widetilde{M}_{0}$ is finite, this implies that $\operatorname{dist}\left(\omega, \omega^{\prime}\right)$ is uniformly bounded, whence part (3).
Changing suffices: $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}$. Fix $T^{*}>0$ and two vectors $\omega_{1}, \omega_{2}$ on the same horocycle $\operatorname{Hor}(\omega)$. We define a map $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}: g^{-T^{*}}\left[W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{1}\right)\right] \rightarrow g^{-T^{*}}\left[W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{2}\right)\right]$ as follows: write $\omega_{i}^{*}:=g^{T^{*}}\left(\omega_{i}\right)=\pi\left(x_{i}^{*}, \xi_{i}^{*}, s_{i}^{*}+h\left(x_{i}^{*}\right)\right)(i=1,2)$, and define
(1) $\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}:\left\{z^{*} \in \Sigma:\left(z^{*}\right)_{0}^{\infty}=\left(x_{1}^{*}\right)_{0}^{\infty}\right\} \rightarrow\left\{x^{*} \in \Sigma:\left(x^{*}\right)_{0}^{\infty}=\left(x_{2}^{*}\right)_{0}^{\infty}\right\}$ by

$$
\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}(z)=\left(z_{-\infty}^{-1}, w_{z_{-1},\left(x_{2}^{*}\right)_{0}},\left(\dot{x}_{2}^{*}\right)_{0}^{\infty}\right) ;
$$

(2) $\widetilde{\vartheta}_{\omega_{1}, \omega_{2}}: W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{1}\right) \rightarrow W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{2}\right)$ by

$$
\widetilde{\vartheta}_{\omega_{1}, \omega_{2}}\left(\pi\left(z, \xi_{1}^{*}, s_{1}^{*}+h(z)\right)\right)=\pi\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*} z, \xi_{2}^{*}, s_{2}^{*}+h\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*} z\right)\right) ;
$$

(3) The map $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}: g^{-T^{*}}\left[W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{1}\right)\right] \rightarrow g^{-T^{*}}\left[W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{2}\right)\right]$ is

$$
\vartheta_{T^{*}, \omega_{1}, \omega_{2}}:=g^{-T^{*}} \circ \widetilde{\vartheta}_{\omega_{1}, \omega_{2}} \circ g^{T^{*}} .
$$

Lemma 3.6. Suppose $\operatorname{dist}\left(g^{T^{*}} \omega_{1}, g^{T^{*}} \omega_{2}\right) \leq T_{0}$. The map $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}$ is an absolutely continuous injective map from a subset of full $\ell$-measure of $g^{-T^{*}}\left[W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{1}\right)\right]$ into $g^{-T^{*}}\left[W_{\mathrm{loc}}^{s s}\left(g^{T^{*}} \omega_{2}\right)\right]$, and there exist constants $C_{r}^{\prime \prime} \geq 1, E^{\prime \prime}$ and $L^{\prime \prime}$ which only depend on $T_{0}$ such that
(1) $\left(C_{r}^{\prime \prime}\right)^{-1} \leq d \ell \circ \vartheta_{T^{*}, \omega_{1}, \omega_{2}} / d \ell \leq C_{r}^{\prime \prime}$,
(2) the $\Sigma$-coordinate of $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}(\pi(x, \xi, T))$ is $\sigma^{-m}\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*} \sigma^{n} x\right)$ with $n \geq 0$ such that $\left|r_{n}^{*}(x)-T^{*}\right| \leq 5\left(\max r^{*}+\max |h|\right)$ and $|m-n| \leq L^{\prime \prime}$,
(3) $\operatorname{dist}\left(\omega, \vartheta_{T^{*}, \omega_{1}, \omega_{2}} \omega\right) \leq E^{\prime \prime}\left(\right.$ dist $\left.=\operatorname{dist}_{T^{1} M}\right)$.

Proof. Lemma 3.4 implies that $\widetilde{\vartheta}_{\omega_{1}, \omega_{2}}$ is absolutely continuous and that

$$
\frac{1}{D^{\prime \prime}} \leq \frac{d \ell \circ \widetilde{\vartheta}_{\omega_{1}, \omega_{2}}}{d \ell} \leq D^{\prime \prime}
$$

with $D^{\prime \prime}$ independent of $\omega_{i}$. Since the geodesic flow contracts the length of horocycles uniformly, part (1) follows with $C_{r}^{\prime \prime}:=D^{\prime \prime}$.

To compare the symbolic coordinates of $\omega$ and $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}(\omega)$, write $\omega=\pi(x, \xi, t)$ with $0 \leq t<r^{*}(x)$. Since $\omega \in g^{-T^{*}} W_{\text {loc }}^{s s}\left(\omega_{1}^{*}\right)$, there is some $n$ s.t.

$$
g^{T^{*}}(\omega)=\pi\left(\sigma^{n}(x), \xi+f_{n}(x), t+T^{*}-r_{n}^{*}(x)\right)
$$

where $\sigma^{n}(x)_{0}^{\infty}=\left(x_{1}^{*}\right)_{0}^{\infty}, \xi+f_{n}(x)=\xi_{1}^{*}, t+T^{*}-r_{n}^{*}(x)=s_{1}^{*}+h\left(\sigma^{n}(x)\right)$. Thus

$$
\begin{aligned}
\vartheta_{T^{*}, \omega_{1}, \omega_{2}}(\omega) & =g^{-T^{*}} \pi\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right), \xi_{2}^{*}, s_{2}^{*}+h\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)\right) \\
& =\pi\left(\begin{array}{c}
\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right) \\
\xi_{2}^{*}-f_{m}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right) \\
s_{2}^{*}+h\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)-T^{*}+r_{m}^{*}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)
\end{array}\right)
\end{aligned}
$$

with $m$ s.t.

$$
0 \leq s_{2}^{*}+h\left(\vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)-T^{*}+r_{m}^{*}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)<r^{*}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)
$$

The obvious bounds $\left|s_{2}^{*}\right| \leq \max r^{*}+\max |h|,\left|r_{m}^{*}-r_{m}\right| \leq 2 \max |h|$, and the double inequality above imply that

$$
\left|r_{m}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)-T^{*}\right| \leq 5\left(\max r^{*}+\max |h|\right)
$$

The identity $t+T^{*}-r_{n}^{*}(x)=s_{1}^{*}+h\left(\sigma^{n}(x)\right)$ means that

$$
\left|r_{n}^{*}(x)-T^{*}\right|,\left|r_{n}(x)-T^{*}\right| \leq 5\left(\max r^{*}+\max |h|\right)
$$

We see that $\left|r_{n}(x)-r_{m}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)\right| \leq 10\left(\max r^{*}+\max |h|\right)$. By construction,

$$
\begin{equation*}
\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)_{0}^{\infty}=\left(x_{n-m+M_{b r}}, \ldots, x_{n-1}, w_{x_{n-1}\left(x_{2}^{*}\right)_{0}},\left(x_{2}^{*}\right)_{0}^{\infty}\right) \tag{3.6}
\end{equation*}
$$

This allows us to estimate $|m-n|$ :

$$
\begin{aligned}
10\left(\max r^{*}+\max |h|\right) & \geq\left|r_{n}(x)-r_{m}\left(\sigma^{-m} \vartheta_{x_{1}^{*}, x_{2}^{*}}^{*}\left(\sigma^{n} x\right)\right)\right| \\
& \geq \inf \left|r_{\left|n-m+M_{b r}\right|}\right|-2 M_{b r} \max |r|-2 \operatorname{var}(r) \\
& \geq \inf r_{\left|n-m+M_{b r}\right|}^{*}-2 \max |h|-2 M_{b r} \max |r|-2 \operatorname{var}(r) \\
& \geq\left\lfloor\frac{|n-m|}{n_{0}}\right\rfloor \inf r_{n_{0}}^{*}-2 \max |h|-3 M_{b r} \max |r|-2 \operatorname{var}(r) .
\end{aligned}
$$

Since $\inf r_{n_{0}}^{*}>0$, we see that $|m-n| \leq L^{\prime \prime}$, with $L^{\prime \prime}=L^{\prime \prime}\left(r, r^{*}, M_{b r}, h, n_{0}\right)$ with $L^{\prime \prime}$ independent of $\omega_{1}, \omega_{2}$ and $T^{*}$.

We can now estimate the difference between the $\mathbb{Z}^{d}$ and $\mathbb{R}$ coordinates of $\omega=$ $\pi(x, \xi, t)$ and $\omega^{\prime}:=\vartheta_{T^{*}, \omega_{1}, \omega_{2}}(\omega)$ which we write as $\omega^{\prime}=\pi\left(x^{\prime}, \xi^{\prime}, t^{\prime}\right)$.

We saw above that $\xi=\xi_{1}^{*}-f_{n}(x)$. Comparing this to the symbolic coordinates of $\omega^{\prime}$ found above, and recalling that $f(x)=f\left(x_{0}, x_{1}\right)$, we see that

$$
\begin{aligned}
\left\|\xi^{\prime}-\xi\right\| & \leq\left\|\xi_{1}^{*}-\xi_{2}^{*}\right\|+\left\|f_{m}\left(x^{\prime}\right)-f_{n}(x)\right\| \\
& \leq\left\|\xi_{1}^{*}-\xi_{2}^{*}\right\|+\left(L^{\prime \prime}+M_{b r}\right) \max \|f\|(\because(3.6)) .
\end{aligned}
$$

Since by assumption $\operatorname{dist}\left(\omega_{1}^{*}, \omega_{2}^{*}\right) \leq T_{0},\left\|\xi_{1}^{*}-\xi_{2}^{*}\right\|$ is bounded by a constant which only depends on $T_{0}$ and the geometry of $\widetilde{M}_{0}$. This implies that $\left\|\xi^{\prime}-\xi\right\|$ is bounded above by some constant which only depends on $T_{0}, L^{\prime \prime}$ and $\max \|f\|$.

The upper bound on the difference between $\mathbb{Z}^{d}$-coordinates implies a uniform upper bound $E^{\prime \prime}$ on the distance between $\omega$ and $\omega^{\prime}$ in $T^{1} M$, whence part (3).

Proof of the Key Lemma. Define once and for all the following constants:

- $\ell_{\min }:=\inf _{\omega^{\prime} \in T^{1} M} \ell\left(W_{\text {loc }}^{s s}\left(\omega^{\prime}\right)\right)=\min \psi, d_{\max }:=\sup _{\omega^{\prime} \in T^{1} M} \operatorname{diam}\left[W_{\text {loc }}^{s s}\left(\omega^{\prime}\right)\right]$ (with the diameter measured using the intrinsic horocycle metric);
- $T_{0}:=100 d_{\text {max }}$;
- $C_{r}:=\max \left\{C_{r}^{\prime}, C_{r}^{\prime \prime}\right\}$, where $C_{r}^{\prime}, C_{r}^{\prime \prime}$ are as in lemmas 3.5 and 3.6 (with $T_{0}$ as above);
- $L:=\max \left\{L^{\prime}, L^{\prime \prime}\right\}$ where $L^{\prime}, L^{\prime \prime}$ are as in lemmas 3.5 and 3.6 (with $T_{0}$ as above);
- $E:=\max \left\{E^{\prime}, E^{\prime \prime}\right\}$ where $E^{\prime}, E^{\prime \prime}$ are as in lemmas 3.5 and 3.6 (with $T_{0}$ as above);
- $K^{*}:=100 L\left(\max r^{*}+\max |h|+\max |r|+\max \|f\|+\operatorname{var}(r)\right)$, where $r, r^{*}, f$ are as in lemma 2.1, $L$ as in lemma 3.3;
- Recall that $\widetilde{M}_{0} \subset T^{1} M$ is a fundamental domain for the action of the covering group on $T^{1} M$. Fix $C=C\left(\widetilde{M}_{0}, E\right)$ so large that

$$
\operatorname{dist}\left(\omega, \widetilde{M}_{0}\right)<10 E \Longrightarrow \omega \in \bigcup_{\|a\|<C} D_{\underline{a}}\left(\widetilde{M}_{0}\right)=: \widetilde{M}_{0}(C)
$$

where $\left\{D_{\xi}: \xi \in \mathbb{Z}^{d}\right\}$ are the deck transformations of the cover.
Finally, fix some arbitrarily small $\varepsilon_{0}>0$.
Step 1. Application of Egoroff's theorem, and choice of $N\left(\varepsilon_{0}\right)$.
Recall that $\frac{1}{T} \xi\left(g^{T} \omega\right) \rightarrow \Xi_{\varphi}$ as $T \rightarrow \infty m_{\varphi}$-almost everywhere. Symbolically, this means that

$$
\frac{f_{n}(x)}{r_{n}^{*}(x)} \underset{n \rightarrow \infty}{ } \Xi_{\varphi} \text { for } m_{\varphi} \text {-a.e. } \omega=\pi(x, \xi, t)
$$

The reason is that this fraction is asymptotic to $\frac{1}{T_{n}}\left[\xi\left(g^{T_{n}} \omega\right)-\xi(\omega)\right]$, where $T_{n}=$ is the $n$-th hitting time to the Poincaré section.

We construct a large set $\Lambda$ where the limit is nearly achieved in finite time. There exists an $N=N\left(\varepsilon_{0}\right)$ s.t. $m_{\varphi}\left\{\omega \in \widetilde{M}_{0}(C): \omega=\pi(x, \xi, s),\left\|\frac{f_{N}(x)}{r_{N}^{*}(x)}-\Xi_{\varphi}\right\| \geq \varepsilon_{0}\right\}<\varepsilon_{0}$. Better yet, since $r_{n}^{*} \geq\left\lfloor n / n_{0}\right\rfloor \inf r_{n_{0}}^{*}$ tends to infinity uniformly and $f$ is bounded, we can take $N=N\left(\varepsilon_{0}, K^{*}\right)$ so large that the set

$$
\Lambda\left(\varepsilon_{0}\right):=\left\{\omega=\pi(x, \xi, s) \in T^{1} M:\left\|\frac{f_{N}(x)+e_{f}}{r_{N}^{*}(x)+e_{r}}-\Xi_{\varphi}\right\|<\varepsilon_{0} \text { for all }\left|e_{r}\right|,\left\|e_{f}\right\|<K^{*}\right\}
$$

satisfies $m_{\varphi}\left[\Lambda\left(\varepsilon_{0}\right) \cap \widetilde{M}_{0}(C)\right]>\left(1-\varepsilon_{0}\right) m_{\varphi}\left[\widetilde{M}_{0}(C)\right]$ and $m_{\varphi}\left(\Lambda\left(\varepsilon_{0}\right) \cap \widetilde{M}_{0}\right)>1-\varepsilon_{0}$. This completes step 1.

We know that $\Lambda\left(\varepsilon_{0}\right)$ is large with respect to $m_{\varphi}$. The next step is to study the size of the intersection of $\Lambda\left(\varepsilon_{0}\right)$ with the horocycle of $\omega_{0}$. Recall from (3.1) the definition of $A_{T}$ and $\lambda_{T}$, and define $\lambda_{T}^{C}$ to be the length measure on $A_{T} \cap \widetilde{M}_{0}(C)$, normalized s.t. $\lambda_{T}^{C}\left[\widetilde{M}_{0}\right]=1$ :

$$
\lambda_{T}^{C}:=\frac{1}{\int_{0}^{T} 1_{\widetilde{M}_{0}}\left(h^{t}\left(\omega_{0}\right)\right) d t} \int_{0}^{T} 1_{\widetilde{M}_{0}(C)}\left(h^{t} \omega_{0}\right) \delta_{h^{t}\left(\omega_{0}\right)} d t .
$$

Note that $\lambda_{T}$ is a probability measure, but $\lambda_{T}^{C}$ is not.
Step 2. If $\omega_{0}$ is generic for $m_{\varphi}$, then there exists $\tau=\tau\left(\varepsilon_{0}\right)$ such that for all $T \geq \tau$, $\lambda_{T}\left(\widetilde{M}_{0} \backslash \Lambda\left(\varepsilon_{0}\right)\right) \leq \lambda_{T}^{C}\left(\widetilde{M}_{0}(C) \backslash \Lambda\left(\varepsilon_{0}\right)\right)<2 \varepsilon_{0}$.

Proof. Set $\Lambda=\Lambda\left(\varepsilon_{0}\right), N=N\left(\varepsilon_{0}\right)$. The discontinuities of the map $\omega \mapsto \frac{f_{N}(x(\omega))}{r_{N}^{*}(x(\omega))}$ are contained in the union of the boundaries of all sets of the form $\pi\{(x, \xi, t): x \in$ $\left.\left[a_{0}, \ldots, a_{N-1}\right], \xi \in \mathbb{Z}^{d}, 0 \leq t<r^{*}(x)\right\}$. The Bowen-Series coding of Se1, Se2] has the property that these boundaries are geodesics arcs. Therefore, $m_{\varphi}$ assigns to this set measure zero.

Thus for every $\varepsilon>0$, we can construct sets $F_{\varepsilon} \subset U_{\varepsilon} \subset \Lambda \cap \widetilde{M}_{0}(C)$ such that $F_{\varepsilon}$ is compact, $U_{\varepsilon}$ is open, and $m_{\varphi}\left[\Lambda \cap \widetilde{M}_{0}(C) \backslash F_{\varepsilon}\right]<\varepsilon$. Urysohn's lemma provides a continuous function $0 \leq \rho_{\varepsilon}(\cdot) \leq 1$ such that $\rho_{\varepsilon}=1$ on $F_{\varepsilon}$ and $\rho_{\varepsilon}=0$ outside $U_{\varepsilon}$ (whence outside $\Lambda$ ). This function has compact support, and

$$
\int \rho_{\varepsilon} d m_{\varphi}>m_{\varphi}\left(\Lambda \cap \widetilde{M}_{0}(C)\right)-\varepsilon>1-\left(\varepsilon_{0}+\varepsilon\right)
$$

Next construct a continuous function with compact support $\theta_{\varepsilon}(\cdot)$ which approximates the indicator function of $\widetilde{M}_{0}$ from above in the sense that $0 \leq \theta_{\varepsilon} \leq 1, \theta_{\varepsilon}=1$ on the closure of $\widetilde{M}_{0}$, and $1<\int \theta_{\varepsilon} d m_{\varphi}<1+\varepsilon$.

By construction, and since $\omega_{0}$ is assumed to be $m_{\varphi}-$ generic,

$$
\lambda_{T}^{C}(\Lambda)=\frac{\int_{0}^{T} 1_{\Lambda \cap \widetilde{M}_{0}(C)}\left(h^{t} \omega_{0}\right) d t}{\int_{0}^{T} 1_{\widetilde{M}_{0}}\left(h^{t} \omega_{0}\right) d t} \geq \frac{\int_{0}^{T} \rho_{\varepsilon}\left(h^{t} \omega_{0}\right) d t}{\int_{0}^{T} \theta_{\varepsilon}\left(h^{t} \omega_{0}\right) d t} \xrightarrow[T \rightarrow \infty]{ } \frac{\int \rho_{\varepsilon} d m_{\varphi}}{\int \theta_{\varepsilon} d m_{\varphi}}>\frac{1-\left(\varepsilon_{0}+\varepsilon\right)}{1+\varepsilon}
$$

Thus there exists $\tau_{\varepsilon}$ such that for all $T>\tau_{\varepsilon}, \lambda_{T}^{C}(\Lambda)>\left[1-\left(\varepsilon_{0}+\varepsilon\right)\right] /(1+\varepsilon)$. Choosing $\varepsilon$ sufficiently small, we get that $\lambda_{T}^{C}(\Lambda)>1-2 \varepsilon_{0}$ for all $T>\tau_{\varepsilon}$ sufficiently large. Equivalently, $\lambda_{T}^{C}\left(\widetilde{M}_{0}(C) \backslash \Lambda\right)<2 \varepsilon_{0}$ for all $T>\tau_{\varepsilon}$. Note that $\tau_{\varepsilon}$ is a function of $\varepsilon_{0}$. This finishes the proof of the second step.

The key lemma calls for the estimation of $\lambda_{T}\left(\widetilde{M}_{0} \cap\left\{r_{n N}^{*}<\ln T^{*}-K\right\} \backslash \Lambda_{n}\right)$ for suitable choice of $K=K\left(\varepsilon_{0}\right)$, where here and throughout $N=N\left(\varepsilon_{0}\right), \Lambda=\Lambda\left(\varepsilon_{0}\right)$, $\Lambda_{n}=\Lambda_{n}\left(N\left(\varepsilon_{0}\right), \varepsilon_{0}\right), T^{*}:=\ln \left(T / T_{0}\right)$ (with $T_{0}$ as above), and

$$
\left\{r_{n N}^{*}<T^{*}-K\right\}:=\left\{\omega \in T^{1} M: r_{n N}^{*}(x(\omega))<T^{*}-K\right\} .
$$

Our choice for $K$ is $K=K\left(\varepsilon_{0}\right):=10(N+L) \max r^{*}$. We estimate the $\lambda_{T^{-}}$ measure of $\widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \backslash \Lambda_{n}$ by partitioning $\widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \backslash \Lambda_{n}\left(\varepsilon_{0}\right)$ into two pieces, which we then treat separately. Define for this purpose
$\mathcal{W}(\mathrm{I}):=\bigcup W_{\text {loc }}^{s s}\left(\omega^{\prime}\right)$, where the union is over all $\omega^{\prime}$ s.t. $W_{\text {loc }}^{s s}\left(\omega^{\prime}\right) \subseteq g^{T^{*}}\left[A_{T}\right]$,
$\mathcal{W}(\mathrm{II}):=\bigcup W_{\mathrm{loc}}^{s s}\left(\omega^{\prime}\right)$, where the union is over all $\omega^{\prime}$ s.t. $W_{\mathrm{loc}}^{s s}\left(\omega^{\prime}\right) \nsubseteq g^{T^{*}}\left[A_{T}\right]$, but $\mathcal{W}_{\text {loc }}^{s s}\left(\omega^{\prime}\right) \cap g^{T^{*}}\left[A_{T}\right]$ has positive length.
Note that $\mathcal{W}(\mathrm{I})$ and $\mathcal{W}(\mathrm{II})$ are unions of local stable manifolds. Let $\mathcal{N}(\mathrm{I}), \mathcal{N}(\mathrm{II})$ be the minimal number of local stable manifolds needed to cover these sets, up to sets of length zero. Next define

$$
\begin{aligned}
A_{T}(\mathrm{I}) & :=A_{T} \cap \widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \cap g^{-T^{*}}[\mathcal{W}(\mathrm{I})] \\
A_{T}(\mathrm{II}) & :=A_{T} \cap \widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \cap g^{-T^{*}}[\mathcal{W}(\mathrm{II})] .
\end{aligned}
$$

Clearly $A_{T} \backslash \Lambda_{n}=\left[A_{T}(\mathrm{I}) \cup A_{T}(\mathrm{II})\right] \backslash \Lambda_{n}$. The plan is to fix $n$, and estimate $\lambda_{T}\left[A_{T}(\mathrm{I}) \backslash \Lambda_{n}\right]$ and $\lambda_{T}\left[A_{T}(\mathrm{II}) \backslash \Lambda_{n}\right]$.
Step 3. $\sup _{n} \lambda_{T}\left[A_{T}(\mathrm{I}) \backslash \Lambda_{n}\right] \leq 2 C_{r} \varepsilon_{0}$ for all $T>\tau\left(\varepsilon_{0}\right)$.

Proof. We use the holonomy $\kappa_{n, N}$ which exchanges the first and $n$-th blocks of $N$ symbols in $x$, see lemma 3.5 above. The idea is to show that

$$
\begin{equation*}
\kappa_{n, N}\left(A_{T}(\mathrm{I}) \backslash \Lambda_{n}\right) \subset A_{T} \cap\left(\widetilde{M}_{0}(C) \backslash \Lambda\right) \tag{3.7}
\end{equation*}
$$

which implies by Lemma 3.5 and the definition of $C_{r}$ that

$$
\begin{aligned}
\lambda_{T}\left[A_{T}(\mathrm{I}) \backslash \Lambda_{n}\right] & =\frac{\ell\left[A_{T}(\mathrm{I}) \backslash \Lambda_{n}\right]}{\ell\left[A_{T} \cap \widetilde{M}_{0}\right]} \leq C_{r} \frac{\ell \circ \kappa_{n, N}\left[A_{T}(\mathrm{I}) \backslash \Lambda_{n}\right]}{\ell\left[A_{T} \cap \widetilde{M}_{0}\right]} \\
& \leq C_{r} \frac{\ell\left[A_{T} \cap \widetilde{M}_{0}(C) \backslash \Lambda\right]}{\ell\left[A_{T} \cap \widetilde{M}_{0}\right]} \quad \because(3.7) \\
& =C_{r} \lambda_{T}^{C}\left(\widetilde{M}_{0}(C) \backslash \Lambda\right)<2 C_{r} \varepsilon_{0} \quad(\text { step } 2),
\end{aligned}
$$

which proves the step.
We prove (3.7). Suppose $\omega=\pi(x, \xi, s+h(x)) \in A_{T}(\mathrm{I}) \backslash \Lambda_{n}$, and let $\omega^{\prime}:=\kappa_{n, N}(\omega)$.
(1) $\omega^{\prime} \in A_{T}$ : The choice of $K$ is such that $\omega \in\left\{r_{n N}^{*}<T^{*}-K\right\}$ forces

$$
r_{(n+1) N+L}^{*}(\omega) \leq r_{n N}^{*}(\omega)+(N+L) \max r^{*}<T^{*}
$$

This implies that $x\left(g^{T^{*}} \omega\right)_{0}^{\infty}=x_{p}^{\infty}$ for $p>(n+1) N+L$.
There exists some $m>0$ such that $\left(\kappa_{n, N}^{*}(x)\right)_{m}^{\infty}=x_{(n+1) N}^{\infty}$. By lemma $3.5, x\left(\omega^{\prime}\right)=\sigma^{l}\left(\kappa_{n, N}^{*}(x)\right)$ with $|l|<L$, so there must exist some $k \geq 0$ such that $x\left(\omega^{\prime}\right)_{k}^{\infty}=x_{(n+1) N+L}^{\infty}$, whence $\exists q>0$ such that $x\left(\omega^{\prime}\right)_{q}^{\infty}=x_{p}^{\infty}=$ $x\left(g^{T^{*}} \omega\right)_{0}^{\infty}$. It is not difficult to see that this entails the existence of $T^{\#}>0$ s.t.

$$
g^{T^{\#}}\left(\omega^{\prime}\right) \in W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega\right) \subset \mathcal{W}(\mathrm{I}) \subset g^{T^{*}}\left[A_{T}\right]
$$

Thus $\omega^{\prime} \in g^{T^{*}-T^{\#}}\left(A_{T}\right)$. But image of $\kappa_{n, N}$ is always in $\operatorname{Hor}\left(\omega_{0}\right)$, so we must have $T^{\#}=T^{*}$, and $\omega^{\prime} \in A_{T}$.
(2) $\omega^{\prime} \in \widetilde{M}_{0}(C)$ : See lemma 3.5 part 3 , and the choice of $E$ and $C$.
(3) $\omega^{\prime} \notin \Lambda$ : By construction, the first $N$-block of $x\left(\omega^{\prime}\right)$ differs from the $n$-th $N$-block of $x(\omega)$ by at most $2|l|<2 L$ symbols. This means that

$$
\begin{aligned}
\left\|f_{N}\left(x\left(\omega^{\prime}\right)\right)-f_{N}\left(\sigma^{N n} x(\omega)\right)\right\| & \leq 2 L \max \|f\|<K^{*} \\
\left|r_{N}^{*}\left(x\left(\omega^{\prime}\right)\right)-r_{N}^{*}\left(\sigma^{N n} x(\omega)\right)\right| & \leq\left|r_{N}\left(x\left(\omega^{\prime}\right)\right)-r_{N}(x(\omega))\right|+4 \max |h| \\
& \leq 2 L \max |r|+\operatorname{var}(r)+4 \max |h|<K^{*} .
\end{aligned}
$$

Had $\omega^{\prime}$ been in $\Lambda$, then it would have followed from these estimates that $\left\|\frac{f_{N}\left(\sigma^{N n} x(\omega)\right)}{r_{N}^{*}\left(\sigma^{N n} x(\omega)\right)}-\Xi_{\varphi}\right\|<\varepsilon_{0}$, contrary to the assumption that $\omega \notin \Lambda_{n}$.
This finishes the proof of (3.7), and completes the step.
Step 4. $\sup _{n} \lambda_{T}\left[A_{T}(\mathrm{II}) \backslash \Lambda_{n}\right] \leq \frac{4 C_{r}^{2} d_{\max }}{\ell_{\min }} \varepsilon_{0}$ for all $T>\tau\left(\varepsilon_{0}\right)$.
Proof. Fix $W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{1}\right) \subset \mathcal{W}(\mathrm{II})$ and $W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{2}\right) \subset \mathcal{W}(\mathrm{I})$. We use $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}$ to $\operatorname{map} g^{-T^{*}} W_{\mathrm{loc}}^{\text {ss }}\left(g^{T^{*}} \omega_{1}\right)$ into $g^{-T^{*}} W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{2}\right) \in g^{-T^{*}}[\mathcal{W}(\mathrm{I})] \subset A_{T}$, and then apply $\kappa_{N, n}$ to claim that

$$
\begin{align*}
\kappa_{n, N} \circ \vartheta_{T^{*}, \omega_{1}, \omega_{2}}\left(g^{-T^{*}} W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{1}\right) \cap \widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \backslash \Lambda_{n}\right) \\
\subset A_{T} \cap \widetilde{M}_{0}(C) \backslash \Lambda . \tag{3.8}
\end{align*}
$$

Suppose this were proved. Using the bounds on the Radon-Nikodym derivatives of $\kappa_{n, N}$ and $\vartheta_{T^{*}, \omega_{1}, \omega_{2}}$, we can then deduce that
$\lambda_{T}\left(g^{-T^{*}} W_{\mathrm{loc}}^{s s}\left(g^{T^{*}} \omega_{1}\right) \cap \widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \backslash \Lambda_{n}\right) \leq C_{r}^{2} \lambda_{T}^{C}\left(\widetilde{M}_{0}(C) \backslash \Lambda\right)<2 C_{r}^{2} \varepsilon_{0}$.
Fixing $W_{\text {loc }}^{s s}\left(\omega_{2}\right)$, and summing over all $W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{1}\right)$ needed to cover $\mathcal{W}$ (II) up to sets of length zero, we get $\lambda_{T}\left(A_{T}(\mathrm{II}) \backslash \Lambda_{n}\right) \leq 2 C_{r}^{2} \mathcal{N}(\mathrm{II}) \varepsilon_{0}$.

We claim that $\mathcal{N}(\mathrm{II}) \leq 2 d_{\max } / \ell_{\min }$. To see this note that every local stable manifold in $\mathcal{W}$ (II) has length at least min $\psi$, and is located at most $d_{\text {max }}$ units of distance away from the endpoints of $g^{T^{*}}\left(A_{T}\right)$ (otherwise it would be contained in $g^{T^{*}}\left(A_{T}\right)$, which it is not). Since local stable manifolds are either equal or disjoint up to sets of length zero, this means that $\mathcal{N}(\mathrm{II}) \leq 2 d_{\max } / \ell_{\min }$.

The step follows from this. Thus it is enough to prove (3.8).
The argument is similar to the one we used in step 3. Fix $\omega \in g^{-T^{*}} W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{1}\right) \cap$ $\widetilde{M}_{0} \cap\left\{r_{n N}^{*}<T^{*}-K\right\} \backslash \Lambda_{n}$ and set $\omega^{\prime}:=\left(\kappa_{n, N} \circ \vartheta_{T^{*}, \omega_{1}, \omega_{2}}\right)(\omega)$.
(1) $\omega^{\prime} \in A_{T}$ : Set $\omega^{\prime \prime}:=\vartheta_{T^{*}, \omega_{1}, \omega_{2}}(\omega)$. Then $\omega^{\prime \prime} \in g^{-T^{*}} W_{\text {loc }}^{s s}\left(g^{T^{*}} \omega_{2}\right)$, and $\exists k>0, l \in[-L, L]$ such that $\left|r_{k}^{*}(x(\omega))-T^{*}\right|<5\left(\max r^{*}+\max |h|\right)$, $x\left(\omega^{\prime \prime}\right)_{k+M_{b r}+l}^{\infty}=x\left(\omega_{2}\right)_{k}^{\infty}$, and $x\left(\omega^{\prime \prime}\right)_{l}^{k+l}=x(\omega)_{0}^{k}$ (lemma 3.6). This $k$ is larger than $(n+1) N+2 L$, because by choice of $K$,

$$
\begin{aligned}
r_{(n+1) N+2 L}^{*}(x(\omega)) & \leq r_{n N}^{*}(x(\omega))+(N+2 L) \max r^{*} \\
& <T^{*}-5\left(\max r^{*}+\max |h|\right),
\end{aligned}
$$

and $r_{k}^{*}(x(\omega))>T^{*}-5\left(\max r^{*}+\max |h|\right)$. Thus the tail $x\left(\omega_{2}\right)_{k}^{\infty}$ survives $\kappa_{n, N}$, which means that $x\left(\omega_{2}\right)_{k}^{\infty}$ appears as some tail of $x\left(\omega^{\prime}\right)$. This means that there exists $T^{\#}>0$ such that $g^{T^{\#}}\left(\omega^{\prime}\right) \in W_{\operatorname{loc}}^{s s}\left(g^{T^{*}} \omega_{2}\right) \subset g^{T^{*}}\left(A_{T}\right)$. As before $T^{\#}$ must be equal to $T^{*}$, whence $\omega^{\prime} \in A_{T}$.
(2) $\omega^{\prime} \in \widetilde{M}_{0}: \vartheta_{T^{*}, \omega_{1}, \omega_{2}}$ moves points at most $E^{\prime \prime}$ units of distance. $\kappa_{n, N}$ moves points at most $E^{\prime}$ units of distance. In total we move at most $2 E$ units of distance from $\widetilde{M}_{0}$, which still leaves us well inside $\widetilde{M}_{0}(C)$.
(3) $\omega^{\prime} \notin \Lambda$ : By construction, the first $N$-block of $x\left(\omega^{\prime}\right)$ differs from the $n$-th $N$-block of $x$ by at most $4 L$ coordinates (the edge effects of two shifts by at most $L$ units). Similar considerations to those used above show that had $\omega^{\prime}$ belonged to $\Lambda$, then $\omega$ would have had to belong to $\Lambda_{n}$, a contradiction.
(3.8) is proved and step 4 is done.

Steps 3 and 4 imply the key lemma, with $C_{0}:=2 C_{r}+4 C_{r}^{2} d_{\max } / \ell_{\min }$, and $K\left(\varepsilon_{0}\right), T_{0}, N\left(\varepsilon_{0}\right), \tau\left(\varepsilon_{0}\right)$ as above.

## 4. Proof that a vector with asymptotic cycle in $\operatorname{int}(\mathfrak{C})$ is generic

The purpose of this section is to prove
Proposition 4.1. For every $\varepsilon>0$ there is a compact neighborhood $K_{\varphi}(\varepsilon) \ni \Xi_{\varphi}$ in $\mathbb{R}^{d}$ s.t. for all non-negative, non-identically zero continuous functions $f, g$, if $T$ is large enough then

$$
\begin{equation*}
\frac{\xi_{\ln T}(\omega)}{\ln T} \in K_{\varphi}(\varepsilon) \Longrightarrow e^{-\varepsilon} \frac{\int f d m_{\varphi}}{\int g d m_{\varphi}} \leq \frac{\int_{0}^{T} f\left(h^{t} \omega\right) d t}{\int_{0}^{T} g\left(h^{t} \omega\right) d t} \leq e^{\varepsilon} \frac{\int f d m_{\varphi}}{\int g d m_{\varphi}} \tag{4.1}
\end{equation*}
$$

Thus every vector with asymptotic cycle $\Xi_{\varphi}$ is generic for $m_{\varphi}$. Indeed we have the stronger statement that if there is a sequence $T_{n} \rightarrow \infty$ such that $\xi_{T_{n}}(\omega) / T_{n} \rightarrow \Xi_{\varphi}$, then $\int_{0}^{e^{T_{n}}} f\left(h^{t} \omega\right) d t / \int_{0}^{e^{T_{n}}} g\left(h^{t} \omega\right) d t \rightarrow \int f d m_{\varphi} / \int g d m_{\varphi}$ for all $f, g$ as above.

Another way of looking at this is to say that if $\xi_{T}(\omega) / T$ has more than one accumulation point in $\operatorname{int}(\mathfrak{C})$ then $\int_{0}^{T} f\left(h^{t} \omega\right) d t / \int_{0}^{T} g\left(h^{t} \omega\right) d t$ oscillates without converging, and therefore cannot be generic for any measure. This agrees with proposition 3.1, but it does not prove it, because of the lack of information on $\omega$ 's such that $\xi_{T}(\omega) / T \rightarrow \partial \mathfrak{C}$.

In what follows, we fix $\varepsilon>0$ and look for $K_{\varphi}(\varepsilon)$ as above.
Modification of the Coding. Fix some small $\varepsilon^{*}=\varepsilon^{*}(\varepsilon)>0$, to be determined later. Recall the symbolic coding of section 2, in particular the definitions of $\psi$ and $\Psi_{\varphi}$. Let $d_{\text {max }}$ denote the maximal diameter of a symbolic local stable manifold, measured in the intrinsic metric of the horocycle which contains it.

We claim that we can change the coding to ensure that the new roof function and symbolic strong stable manifolds satisfy

$$
\begin{aligned}
\max r_{\text {new }}^{*} & <\varepsilon^{*} \\
\max \left|h_{\text {new }}\right| & <\varepsilon^{*} \\
\left(d_{\text {max }}\right)_{\text {new }} & <\varepsilon^{*} \\
\max \psi_{\text {new }} & <\varepsilon^{*}
\end{aligned}
$$

$$
\operatorname{diam}\left(\pi_{\text {new }}\left\{(x, \xi, s): x_{0}=a_{0}, \xi=\xi_{0}, 0 \leq s<r_{\text {new }}^{*}(x)\right\}\right)<\varepsilon^{*} \text { for all } a_{0}, \xi_{0}
$$

Moreover, we claim that this modification can be done in such a way that

$$
\frac{\max \psi_{\text {new }}}{\min \psi_{\text {new }}}, \frac{\max \left(\Psi_{\varphi}\right)_{\text {new }}}{\min \left(\Psi_{\varphi}\right)_{\text {new }}}<C_{\varphi}
$$

where $C_{\varphi}$ does not depend on $\varepsilon^{*}$ or $\varepsilon$.
Here is how to do this.
The coding in lemma 2.1 is based on finding a Poincaré section for the geodesic flow, with a Markov section map $T$. Take a power $\alpha_{L}:=\bigvee_{i=-L}^{L} T^{-i} \alpha$ of the Markov partition $\alpha$ of this section, with $L$ so large that

$$
V(L):=\sum_{k=L}^{\infty} \sup \left\{|r(x)-r(y)|: x_{-k}^{k}=y_{-k}^{k}\right\}<\frac{1}{2} \varepsilon^{*}
$$

Such $L$ exist because $r$ is Hölder continuous.
Increase the Poincaré section by adding to it the sets

$$
g^{k \varepsilon^{*} / 2}(A), \text { for } A \in \alpha_{L} \text { and all } k=1, \ldots,\left\lfloor 2 \min _{A} r / \varepsilon^{*}\right\rfloor
$$

This is again a Poincaré section for the geodesic flow. It can be used to code the geodesic flow as a special flow over a (new) subshift of finite type with roof function $r_{\text {new }}^{*}$ such that max $r_{\text {new }}^{*} \leq \varepsilon^{*} / 2<\varepsilon^{*}$ and $\operatorname{var}\left(r_{\text {new }}^{*}\right) \leq V(L)<\varepsilon^{*}$.

Recall that $h_{\text {new }}$ is (any) Hölder continuous function such that $r_{\text {new }}:=r_{\text {new }}^{*}+$ $h_{\text {new }} \circ \sigma_{\text {new }}-h_{\text {new }}$ only depends on the non-negative coordinates (w.r.t $\Sigma_{\text {new }}$ ). There are explicit constructions of such functions which lead to functions $h_{\text {new }}$ such that $\left|h_{\text {new }}\right| \leq \operatorname{var}\left(r_{\text {new }}^{*}\right)$, see for example the proof of lemma 1.6 in Bo2. Since $\operatorname{var}\left(r^{*}\right)<\varepsilon^{*}$, this gives $h_{\text {new }}$ with $\left|h_{\text {new }}\right|<\varepsilon^{*}$.

We claim that if $L$ is large enough, then the diameter and length of all symbolic manifolds in the new coding are less than $\varepsilon^{*} / 2$, whence $\left(d_{\text {max }}\right)_{\text {new }}, \max \left(\psi_{\text {new }}\right)<\varepsilon^{*}$.

To see this observe that for every $x$, the sets $\pi\left\{(y, \xi, s+h(y)): y_{-L}^{L}=x_{-L}^{L}\right\}$ decrease to $\{\pi(x, \xi, s+h(x))\}$ as $L \rightarrow \infty$. Thus for every $x$ there exists $L(x)$ such that the length and diameter of

$$
\pi\left(\left\{(y, \xi, s): y_{-L(x)}^{L(x)}=x_{-L(x)}^{L(x)}, \xi=\xi_{0}, 0<s<\varepsilon^{*} / 2\right\}\right)
$$

are less than $\varepsilon^{*}$. (This $L(x)$ does not depend on $\xi_{0}$, because the deck transformations are isometries.) A compactness argument shows that $L(x)$ can be chosen to be uniform in $x$.

We check that the ratio of the maxima and minima of $\psi_{\text {new }}$ and $\left(\Psi_{\varphi}\right)_{\text {new }}$ remains bounded by a constant independent of $L, \varepsilon^{*}$ and $\varepsilon$.

First note that our modification of the coding does not change the value of $P\left(u_{\varphi}\right)$, because as mentioned above the diffeomorphism $P(\cdot)$ does not depend on the coding (it can be described by a 'section-free' formula, see BL2).

Unfortunately $\left(\Psi_{\varphi}\right)_{\text {new }}: \Sigma_{\text {new }}^{+} \rightarrow \mathbb{R}$ is affected by the coding, because it is defined to be the normalized eigenfunction of $L_{-P\left(u_{\varphi}\right), u_{\varphi}}^{\text {new }}: C\left(\Sigma_{\text {new }}^{+}\right) \rightarrow C\left(\Sigma_{\text {new }}^{+}\right)$ and $r_{\text {new }}, f_{\text {new }}$ and $\Sigma_{\text {new }}^{+}$are different from $r, f$ and $\Sigma^{+}$.

The first observation is that any change which is solely due to refining the Markov partition does not affect the minimum of maximum of $\Psi_{\varphi}$, because the subshift of finite type it generates is conjugate to the original subshift. It is therefore enough to focus on changes in the roof function $r$ and the Poincaré section.

The modified Poincaré section can be coded using a subshift of finite type $\Sigma_{\text {new }}^{+}$ with two types of states: the old set of states $S$ of $\Sigma^{+}$, and a new set of states $S^{\prime}$ each of which has a unique predecessor (i.e. a state which can lead to it). It is easy to see that $\max r_{\text {new }} \leq \max r$, and $\max \left\|f_{\text {new }}\right\| \leq \max \|f\|$ (in fact $f_{\text {new }}=0$ except perhaps on states which lead to $S$ ).

One can recover $\Sigma^{+}$from $\Sigma_{\text {new }}^{+}$by inducing: If one induces the shift $\sigma_{\text {new }}$ : $\Sigma_{\text {new }}^{+} \rightarrow \Sigma_{\text {new }}^{+}$on the union of the states in $S$, then one gets a dynamical system isomorphic to $\sigma: \Sigma^{+} \rightarrow \Sigma^{+}$. The same induction procedure can be used to recover $L_{-P\left(u_{\varphi}\right), u_{\varphi}}$ from $L_{-P\left(u_{\varphi}\right), u_{\varphi}}^{\text {new }}$ : If $\tau$ is the first return time to the states in $S$, then $L_{-P\left(u_{\varphi}\right), u_{\varphi}}$ is conjugate to the operator $F \mapsto\left[\left(L_{-P\left(u_{\varphi}\right), u_{\varphi}}^{\text {new }}\right)^{\tau(x)} F\right](x)$ on $C\left(\Sigma_{\text {new }}^{+}\right)$. Standard results on inducing Ruelle operators imply that this conjugacy maps $\left(\Psi_{\varphi}\right)_{\text {new }} \mid \cup S$ to $\Psi_{\varphi}$. It follows that

$$
\left.\max \left(\Psi_{\varphi}\right)_{\text {new }}\right|_{S}=\max \Psi_{\varphi} \text { and }\left.\min \left(\Psi_{\varphi}\right)_{\text {new }}\right|_{\cup S}=\min \Psi_{\varphi}
$$

Consider now points $x \in[a] \subset \bigcup S^{\prime}$. Let $k$ be the minimal natural number such that $x=\sigma^{k}(y)$ and $y \in \bigcup S$. Since every state in $S^{\prime}$ has exactly one predecessor, and since $\Psi_{\varphi}=L_{-P\left(u_{\varphi}\right), u_{\varphi}} \Psi_{\varphi}$,

$$
\Psi_{\varphi}(x)=e^{-P\left(u_{\varphi}\right)\left(r_{\text {new }}\right)_{k}(y)+\left\langle u_{\varphi},\left(f_{\text {new }}\right)_{k}(y)\right\rangle} \Psi_{\varphi}(y) .
$$

It is easy to verify that $\left|\left(r_{\text {new }}\right)_{k}(y)\right| \leq\left|r^{*}(y)\right|+2 \max |h|$ and that $\left(f_{\text {new }}\right)_{k}(y)$ is either equal to zero or to $f(y)$. We conclude that

$$
\begin{aligned}
& \Psi_{\varphi}(x) \leq e^{\left|P\left(u_{\varphi}\right)\right|\left(\max r^{*}+2 \max |h|\right)+\left\|u_{\varphi}\right\| \max \|f\|} \max \left(\Psi_{\varphi}\right)_{\text {new }} \mid \cup S \\
& \Psi_{\varphi}(x) \geq e^{-\left|P\left(u_{\varphi}\right)\right|\left(\max r^{*}+2 \max |h|\right)-\left\|u_{\varphi}\right\| \max \|f\|} \min \left(\Psi_{\varphi}\right)_{\text {new }} \mid \cup S
\end{aligned}
$$

It follows that

$$
\frac{\max \left(\Psi_{\varphi}\right)_{\text {new }}}{\min \left(\Psi_{\varphi}\right)_{\text {new }}} \leq \text { const } \times \frac{\max \Psi_{\varphi}}{\min \Psi_{\varphi}}
$$

where the constant is independent of $\varepsilon^{*}, \varepsilon$.

The bound on $\max \psi_{\text {new }} / \min \psi_{\text {new }}$ can be obtained in exactly the same way. Indeed, $\psi_{\text {new }}=\left(\Psi_{0}\right)_{\text {new }}$ where 0 is the trivial homomorphism, see proposition 4.5 in BL2.

This shows that the new coding is as required. Henceforth we work with this coding, and drop the decorations by 'new'.
Basic Sets. Working with $\varepsilon, \varepsilon^{*}$ and the symbolic coding of the previous section, we consider the following sets, which we name $\varepsilon^{*}$-basic sets, (or just 'basic sets'):

$$
E=\pi\left\{(x, \xi, s+h(x)): x \in[\underline{a}]:=\left[\dot{a}_{0}, \ldots, a_{n-1}\right], \alpha \leq s<\beta\right\} \subset \Sigma \times \mathbb{Z}^{d} \times \mathbb{R},
$$

where $0 \leq \alpha \leq \beta \leq \inf _{[\underline{a}]} r^{*}$. We call $\beta-\alpha$ the width of $E$.
Note that $\operatorname{diam}(E)<\varepsilon^{*}$, and that

$$
m_{\varphi}(E)=\operatorname{const} e^{\left\langle u_{\varphi}, \xi\right\rangle} \int_{\alpha}^{\beta} e^{-P\left(u_{\varphi}\right) s} d s \int_{[\underline{a}]} \psi d \nu_{\varphi}
$$

with the constant independent of $\varepsilon^{*}, \varepsilon$.
Lemma 4.2. If $\varepsilon^{*}$ is sufficiently small, then there is a compact neighborhood $K_{\varphi} \ni$ $\Xi_{\varphi}$ in $\mathbb{R}^{d}$ s.t. for any two $\varepsilon^{*}$-basic sets $E_{1}, E_{2}$, if $T$ is large enough

$$
\frac{\xi_{\ln T}(\omega)}{\ln T} \in K_{\varphi} \Longrightarrow e^{-\varepsilon} \frac{m_{\varphi}\left(E_{1}\right)}{m_{\varphi}\left(E_{2}\right)} \leq \frac{\int_{0}^{T} 1_{E_{1}}\left(h^{t} \omega\right) d t}{\int_{0}^{T} 1_{E_{2}}\left(h^{t} \omega\right) d t} \leq e^{\varepsilon} \frac{m_{\varphi}\left(E_{1}\right)}{m_{\varphi}\left(E_{2}\right)}
$$

Proof. Lemma 4.2 is proved by finding the asymptotic behavior of $I_{T}(\omega, E):=$ $\int_{0}^{T} 1_{E}\left(h^{t} \omega\right) d t$ as $T \rightarrow \infty$. Such asymptotics can be derived for almost every $\omega$ when $\varphi \equiv 0$ from the main lemma of LS1. Here we describe the necessary modifications to cover $\varphi \not \equiv 0$, and to replace the quantification ' $m_{\varphi}$-almost everywhere' by a condition on $\xi\left(g^{\ln T} \omega\right) / \ln T$.

In what follows we assume without loss of generality that $\omega \in \widetilde{M}_{0}$, and denote $A_{T}(\omega):=\left\{h^{t}(\omega): 0 \leq t \leq T\right\}$ and $T^{*}:=\ln T$.
Step 1. For all $\omega$ and $T>1, \exists N^{+}, N^{-} \in \mathbb{N}$ and $\exists \omega_{i}^{*} \in g^{T^{*}}\left(A_{T}(\omega)\right)=A_{1}\left(g^{T^{*}} \omega\right)$ $\left(i=0, \ldots, N^{+}\right)$s.t. if $J_{T^{*}}\left(\omega_{i}^{*}, E\right):=\ell\left[E \cap g^{-T^{*}} W_{\text {loc }}^{s s}\left(\omega_{i}^{*}\right)\right]$, then

$$
\sum_{i=0}^{N^{-}} J_{T^{*}}\left(\omega_{i}^{*}, E\right) \leq I_{T}(\omega, E) \leq \sum_{i=0}^{N^{+}} J_{T^{*}}\left(\omega_{i}^{*}, E\right) \text { and } 0<\frac{N^{+}-N^{-}}{N^{-}}<\frac{4 C_{\varphi} \varepsilon^{*}}{1-2 \varepsilon^{*}}
$$

Proof. This is the same as in step 1 in lemma 1 of LS1], except for the fact that we work in constant negative curvature, and this allows us to argue for all $\omega$, and not just almost all $\omega$. We explain why.

We view $I_{T}(\omega, E)$ as an integral on the horocyclic arc $A_{T}(\omega)$ with respect to its hyperbolic length measure $\ell=\ell_{\omega}$ :

$$
I_{T}(\omega, E)=\int_{0}^{T} 1_{E}\left(h^{t} \omega\right) d t=\ell_{\omega}\left[E \cap A_{T}(\omega)\right]=\ell_{\omega}\left[E \cap g^{-T^{*}} A_{1}\left(g^{T^{*}} \omega\right)\right]
$$

where the last equality is because of the commutation relation between the geodesic and horocycle flows.

Let $W_{\text {loc }}^{s s}\left(\omega_{i}^{*}\right)\left(i=1, \ldots, N^{-}\right)$be the symbolic local stable manifolds contained in $A_{1}\left(g^{T^{*}} \omega\right)$. Add to the list the $W_{\text {loc }}^{s s}\left(\omega_{i}^{*}\right)\left(i=N^{-}+1, \ldots, N^{+}\right)$which intersect $A_{1}\left(g^{T^{*}}(\omega)\right)$ with positive measure without being contained in it.

In constant negative curvature, for every $\omega$, any two symbolic local stable manifolds are either equal or disjoint up to sets of length zero (lemma 2.1, part 2). Therefore, $I_{T}(\omega, E)$ can be sandwiched between $\sum_{i=0}^{N^{ \pm}} J_{T^{*}}\left(\omega_{i}^{*}, E\right)$ as above.

The $N^{+}-N^{-}$symbolic local stable manifolds which intersect $A_{1}\left(g^{T} \omega\right)$ without being contained in it must be contained in a $d_{\max }$-neighborhood of the endpoints of $A_{1}\left(g^{T} \omega\right)$, thus $N^{+}-N^{-}<4 d_{\max } / \min \psi$ and $N^{-}>\left(1-2 d_{\max }\right) / \max \psi$. Since $\max \psi / \min \psi<C_{\varphi}, 0<\frac{N^{+}-N^{-}}{N^{-}}<\frac{4 C_{\varphi} d_{\max }}{1-2 d_{\max }}<\frac{4 C_{\varphi} \varepsilon^{*}}{1-2 \varepsilon^{*}}$.
Step 2. Suppose $\omega$, $\omega_{i}^{*}$ have symbolic coordinates $(x, 0, t+h(x)),\left(x_{i}^{*}, \xi_{i}^{*}, t_{i}^{*}+h\left(x_{i}^{*}\right)\right)$, and assume $T>e^{\varepsilon^{*}}$. Set $T_{i}^{\#}:=T^{*}-t_{i}^{*}$. Then for every $\varepsilon^{*}$-basic set $E$,

$$
\begin{equation*}
J_{T^{*}}\left(\omega_{i}^{*}, E\right)=e^{ \pm|\beta-\alpha|} \sum_{n=0}^{\infty} \sum_{\sigma^{n}(y)=\left(x_{i}^{*}\right)_{0}^{\infty}} 1_{[\alpha, \beta]}\left(r_{n}(y)-T_{i}^{\#}\right) \delta_{\xi_{i}^{*}, \xi+f_{n}(y)} 1_{[\underline{a}]}(y) \psi(y), \tag{4.3}
\end{equation*}
$$

where the sum ranges over the one-sided subshift of finite type $\Sigma^{+}$.
Proof. See step 2 in lemma 1 of LS1.
We note for future reference that $\left|T_{i}^{\#}-T^{*}\right|=\left|t_{i}^{*}\right|<\max r^{*}+\max |h|<2 \varepsilon^{*}$, and that $|\beta-\alpha| \leq \max r^{*}<\varepsilon^{*}$.
Step 3 BL2. For every $\varepsilon^{*}$-basic set $E$, there exists a compact neighborhood $K_{\varphi}^{0}$ of $\Xi_{\varphi}$ and $T_{0}>0$ such that for all $T \geq T_{0}$,

$$
\frac{\xi_{i}^{*}}{T^{*}} \in K_{\varphi}^{0} \Rightarrow J_{T^{*}}\left(\omega_{i}^{*}, E\right)=\operatorname{const} e^{ \pm C_{\varphi} \varepsilon^{*}} m_{\varphi}(E) e^{ \pm \varepsilon} \frac{e^{T_{i}^{\#} H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)}}{(\ln T)^{d / 2}} \Psi_{\varphi}\left(x_{i}^{*}\right),
$$

where $H(\cdot)$ is the minus the Legendre transform of $P(\cdot)$, and $H(\cdot)$, the constant in front of the expression, $C_{\varphi}$, and $K_{\varphi}$ do not depend on $\varepsilon, \varepsilon^{*}, E$ or $\omega$.
Proof. This is done by estimating the sum (4.3) using an elaboration of Lalley's method [L], as in Babillot \& Ledrappier [BL1] or [BL2]. ${ }^{2}$
Step 4. There is a function $F_{\varphi}\left(\varepsilon, \varepsilon^{*}\right) \xrightarrow[\varepsilon, \varepsilon^{*} \rightarrow 0^{+}]{\longrightarrow}$, s.t. for all $\varepsilon^{*}$-basic sets $E_{1}$, $E_{2}$, there is a compact neighborhood $K_{\varphi} \subset K_{\varphi}^{0}$ of $\Xi_{\varphi}$ and $T_{1}>0$ such that for all $\omega \in T^{1} M$ and $T \geq T_{1}$ with $\frac{\xi_{T^{*}}(\omega)}{T^{*}} \in K_{\varphi}$,

$$
\frac{1}{F_{\varphi}\left(\varepsilon, \varepsilon^{*}\right)} \frac{m_{\varphi}\left(E_{1}\right)}{m_{\varphi}\left(E_{2}\right)} \leq \frac{I_{T}\left(\omega, E_{1}\right)}{I_{T}\left(\omega, E_{2}\right)} \leq F_{\varphi}\left(\varepsilon, \varepsilon^{*}\right) \frac{m_{\varphi}\left(E_{1}\right)}{m_{\varphi}\left(E_{2}\right)} .
$$

Proof. It is enough to prove the inequality on the right. By the previous steps,

$$
\begin{equation*}
\frac{I_{T}\left(\omega, E_{1}\right)}{I_{T}\left(\omega, E_{2}\right)} \leq e^{2 C_{\varphi} \varepsilon^{*}} e^{2 \varepsilon} \frac{m_{\varphi}\left(E_{1}\right)}{m_{\varphi}\left(E_{2}\right)}\left[1+\frac{\sum_{i=N^{-}+1}^{N^{+}} e^{T_{i}^{\#} H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)} \Psi_{\varphi}\left(x_{i}^{*}\right)}{\sum_{i=1}^{N^{-}} e^{T_{i}^{\#} H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)} \Psi_{\varphi}\left(x_{i}^{*}\right)}\right] \tag{4.4}
\end{equation*}
$$

Fix some small compact neighborhood $K_{\varphi} \subset K_{\varphi}^{0}$ of $\Xi_{\varphi}$ (we shall see later how small), and assume $\frac{\xi_{T^{*}}(\omega)}{T^{*}} \in K_{\varphi}$.

[^2]By construction all the $\omega_{i}^{*}$ belong to a $d_{\max }-$ neighborhood of $A_{1}\left(g^{T^{*}} \omega\right)$, a horocyclic arc of length 1 . Thus their $\mathbb{Z}^{d}$-coordinates $\xi_{i}^{*}$ are within a bounded distance $D$ from each other. Since $\left|T_{i}^{\#}-T^{*}\right|<2 \varepsilon^{*}$, for all $T$ large enough, $\left\|\frac{\xi_{i}^{*}}{T_{i}^{\#}}-\Xi_{\varphi}\right\|<$ 2 diam $K_{\varphi}$. Thus, if diam $K_{\varphi}$ is small enough, then

$$
\begin{aligned}
\left\lvert\, T_{i}^{\#} H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)\right. & \left.-T^{*} H\left(\frac{\xi_{T^{*}}(\omega)}{T^{*}}\right) \right\rvert\, \leq \\
& \leq\left|T_{i}^{\#}-T^{*}\right| \cdot\left|H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)\right|+T^{*}\left|H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)-H\left(\frac{\xi_{T^{*}}(\omega)}{T^{*}}\right)\right| \\
& \leq 2 \varepsilon^{*}\left[H\left(\Xi_{\varphi}\right)+\varepsilon^{*}\right]+\left(\left\|(\nabla H)\left(\Xi_{\varphi}\right)\right\|+\varepsilon^{*}\right) T^{*}\left\|\frac{\xi_{i}^{*}}{T_{i}^{\#}}-\frac{\xi_{T^{*}}(\omega)}{T^{*}}\right\| .
\end{aligned}
$$

Now, for $T$ large enough so that $\left\|\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right\|<2 \operatorname{diam} K_{\varphi}+\left\|\Xi_{\varphi}\right\|$, we have

$$
\begin{aligned}
T^{*}\left\|\frac{\xi_{i}^{*}}{T_{i}^{\#}}-\frac{\xi_{T^{*}}(\omega)}{T^{*}}\right\| & \leq T^{*}\left\|\frac{\xi_{i}^{*}}{T_{i}^{\#}}-\frac{\xi_{i}^{*}}{T^{*}}\right\|+T^{*}\left\|\frac{\xi_{i}^{*}}{T^{*}}-\frac{\xi_{T^{*}}(\omega)}{T^{*}}\right\| \\
& \leq T^{*}\left\|\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right\|\left|1-\frac{T_{i}^{\#}}{T^{*}}\right|+D \\
& \leq\left(2 \operatorname{diam} K_{\varphi}+\left\|\Xi_{\varphi}\right\|\right) \cdot 2 \varepsilon^{*}+D
\end{aligned}
$$

Consequently, there is a constant $k_{\varphi}^{\prime}$ which only depends on $\varphi$ such that for all $T$ large enough, if $\frac{\xi\left(g^{T^{*}} \omega\right)}{T^{*}} \in K_{\varphi}$, then

$$
\exp \left(\left|T_{i}^{\#} H\left(\frac{\xi_{i}^{*}}{T_{i}^{\#}}\right)-T^{*} H\left(\frac{\xi_{T^{*}}(\omega)}{T^{*}}\right)\right|\right) \leq \exp \left(k_{\varphi}^{\prime} \varepsilon^{*}+D\left\|\nabla H\left(\Xi_{\varphi}\right)\right\|\right)=: k_{\varphi}\left(\varepsilon^{*}\right)
$$

Thus the term in the brackets in (4.4) can be estimated by

$$
1+k_{\varphi}\left(\varepsilon^{*}\right)^{2} \frac{\max \Psi_{\varphi}}{\min \Psi_{\varphi}}\left(\frac{N^{+}-N^{-}}{N^{-}}\right) \leq 1+\frac{4 \varepsilon^{*} C_{\varphi}^{2} k_{\varphi}\left(\varepsilon^{*}\right)^{2}}{1-2 \varepsilon^{*}}
$$

and so $I_{T}(\omega, E) / I_{T}\left(\omega, E_{0}\right) \leq e^{2 C_{\varphi} \varepsilon^{*}} e^{2 \varepsilon} \frac{m_{\varphi}(E)}{m_{\varphi}\left(E_{0}\right)} F_{\varphi}\left(\varepsilon_{0}, \varepsilon^{*}\right)$ where

$$
F_{\varphi}\left(\varepsilon, \varepsilon^{*}\right):=e^{2 C_{\varphi} \varepsilon^{*}+2 \varepsilon}\left(1+\frac{4 \varepsilon^{*} C_{\varphi} k_{\varphi}\left(\varepsilon^{*}\right)^{2}}{1-2 \varepsilon^{*}}\right)
$$

The lower bound is obtained in the same way, and the step is proved.
We can now prove the lemma. Fix $\widetilde{\varepsilon}$. Choose $\varepsilon, \varepsilon^{*}$ so small that $e^{-\widetilde{\varepsilon}}<F\left(\varepsilon, \varepsilon^{*}\right)<$ $e^{\widetilde{\varepsilon}}$. Then the lemma follows with $\widetilde{\varepsilon}$ instead of $\varepsilon$.

Proof of Proposition 4.1. Take $\varepsilon$ and $K_{\varphi}(\varepsilon)$ as in the previous section, and fix $\varepsilon^{*}$ as in lemma 4.2. Call a function an $\varepsilon^{*}$-step function if it is a finite linear combination of indicators of $\varepsilon^{*}$-basic sets. Lemma 4.2 clearly implies (4.1) for any pair of $\varepsilon^{*}$-step functions with non-zero integrals.

We also have (4.1) for all non-negative non-identically zero continuous functions $f, g$ with compact supports which do not intersect the section: Such functions can be sandwiched between $\varepsilon^{*}$-step functions with almost the same integrals, and $\varepsilon^{*}$ and the width of the basic sets can be chosen arbitrarily small.

We claim that there is an open neighborhood $V$ of the section such that for all non-negative, non-identically zero, continuous functions $f, g$ supported inside $V$, if $T$ is large enough and $\xi_{\ln T}(\omega) / \ln T \in \operatorname{int}\left(K_{\varphi}\right)$, then

$$
e^{-3 \varepsilon} \frac{\int f d m_{\varphi}}{\int g d m_{\varphi}} \leq \frac{\int_{0}^{T} f\left(h^{t} \omega\right) d t}{\int_{0}^{T} g\left(h^{t} \omega\right) d t} \leq e^{3 \varepsilon} \frac{\int f d m_{\varphi}}{\int g d m_{\varphi}} .
$$

Every point $\widetilde{\omega}$ in the section has a precompact open neighborhood $V_{\widetilde{\omega}}$ and a constant $0<s(\widetilde{\omega})<\varepsilon^{*}<\varepsilon$ such that the closure of $g^{s(\widetilde{\omega})}\left[V_{\widetilde{\omega}}\right]$ does not intersect the section. Suppose $f_{1}, f_{2}$ are non-negative, non-identically zero, continuous functions with compact support in $V_{\widetilde{\omega}}$; then $\widetilde{f}_{i}:=f_{i} \circ g^{-s(\widetilde{\omega})}$ are uniformly continuous functions with compact supports which do not intersect the section. Thus they satisfy (4.1) for all $T$ large enough.

The commutation relation between the geodesic flow and the horocycle flow implies $\int_{0}^{T} f_{i}\left(h^{t} \omega\right) d t=e^{s(\widetilde{\omega})} \int_{0}^{T e^{-s(\widetilde{\omega})}} \tilde{f}_{i}\left(h^{\tau} g^{-s(\widetilde{\omega})} \omega\right) d \tau$. If $\frac{\xi_{\ln T}(\omega)}{\ln T} \in \operatorname{int}\left(K_{\varphi}\right)$, then for $T$ large enough $\frac{\left.\xi_{\ln T} T g^{s(\tilde{\omega})} \omega\right)}{\ln T} \in \operatorname{int}\left(K_{\varphi}\right)$. For such $T, \int_{0}^{T} f_{1}\left(h^{t} \omega\right) d t / \int_{0}^{T} f_{2}\left(h^{t} \omega\right) d t=$ $\int_{0}^{T e^{-s(\tilde{\omega})}} \tilde{f}_{1}\left(h^{\tau} g^{-s(\widetilde{\omega})} \omega\right) d \tau / \int_{0}^{T e^{-s(\tilde{\omega})}} \widetilde{f}_{2}\left(h^{\tau} g^{-s(\widetilde{\omega})} \omega\right) d \tau=e^{ \pm \varepsilon} \int \widetilde{f}_{1} / \int \widetilde{f}_{2}$. The integral ratio is equal to $\int f_{1} / \int f_{2}$, because $m_{\varphi} \circ g^{\tau}=e^{-P\left(u_{\varphi}\right) \tau} m_{\varphi}$.

Thus (4.1) holds for all $f_{1}, f_{2}$ supported inside $V_{\widetilde{\omega}}$.
Now suppose supp $f_{1} \subset V_{\widetilde{\omega}_{1}}$ and $\operatorname{supp} f_{2} \subset V_{\widetilde{\omega}_{2}}$ where $\widetilde{\omega}_{1} \neq \widetilde{\omega}_{2}$. Choose nonnegative non-identically zero continuous $g_{i}$ with compact support in $V_{\widetilde{\omega}_{i}} \backslash$ section. Writing

$$
\frac{\int_{0}^{T} f_{1} \circ h^{t} d t}{\int_{0}^{T} f_{2} \circ h^{t} d t}=\frac{\int_{0}^{T} f_{1} \circ h^{t} d t}{\int_{0}^{T} g_{1} \circ h^{t} d t} \cdot \frac{\int_{0}^{T} g_{1} \circ h^{t} d t}{\int_{0}^{T} g_{2} \circ h^{t} d t} \cdot \frac{\int_{0}^{T} g_{2} \circ h^{t} d t}{\int_{0}^{T} f_{2} \circ h^{t} d t},
$$

we see that for all $T$ large enough, if $\xi_{\ln T}(\omega) / \ln T \in \operatorname{int}\left(K_{\varphi}\right)$ then

$$
e^{-3 \varepsilon} \frac{\int f_{1} d m_{\varphi}}{\int f_{2} d m_{\varphi}} \leq \frac{\int_{0}^{T} f_{1}\left(h^{t} \omega\right) d t}{\int_{0}^{T} f_{2}\left(h^{t} \omega\right) d t} \leq e^{3 \varepsilon} \frac{\int f_{1} d m_{\varphi}}{\int f_{2} d m_{\varphi}}
$$

Let $V$ be the union of $V_{\widetilde{\omega}}$ where $\widetilde{\omega}$ ranges over the section. Every non-negative continuous function with compact support in $V$ is the sum of finitely many nonnegative continuous functions supported inside $V_{\widetilde{\omega}}$. Thus proposition 4.1 holds for all $f, g$ non-negative, non-identically zero, continuous functions supported inside $V$.

Now set $\mathcal{U}$ to be the family of all non-negative non-identically zero continuous functions with compact support, whose support does not intersect the section. Define $\mathcal{V}$ to be the family of all non-negative non-identically zero continuous functions supported inside $V$.

We saw that proposition 4.1 holds for all pairs of functions in $\mathcal{U}$, and for all pairs of functions in $\mathcal{V}$. Since $\mathcal{U} \cap \mathcal{V} \neq \varnothing$, proposition 4.1 holds for all pairs of functions in $\mathcal{U} \cup \mathcal{V}$. Since any non-negative continuous function of compact support is the sum of a function from $\mathcal{U}$ and a function from $\mathcal{V}$, proposition 4.1 holds for all non-negative continuous functions of compact support.

## 5. A Question

The obvious question is what happens for other hyperbolic surfaces of infinite genus. Theorem 1.1 does not make sense for such surfaces, because the notion of asymptotic cycle is specific to $\mathbb{Z}^{d}$-covers.

It is desirable to find another criterion which does make sense in general.
The following observation is perhaps a step in this direction. Let $\Delta$ denote the Laplace-Beltrami operator on the hyperbolic surface $M$. A positive eigenfunction $F: M \rightarrow \mathbb{R}$ is called minimal, if it defines an extremal ray in the cone of positive eigenfunctions with the same eigenvalue. The minimal positive eigenfunctions are known for $\mathbb{Z}^{d}$-covers $\mathbf{C G}$, $\left.\mathbf{L P}\right]$ : they form a list $\left\{c F_{\varphi}: c>0, \varphi: \mathbb{Z}^{d} \rightarrow\right.$ $\mathbb{R}$ a homomorphism $\}$, where $F_{\varphi}$ satisfies $F_{\varphi} \circ D_{\xi}=e^{\varphi(\xi)} F_{\varphi}$ for all deck transformations $D_{\xi}, \xi \in \mathbb{Z}^{d}$. The similarity with the collection of Babillot-Ledrappier measures is not a coincidence, see LS2.

Extend $F_{\varphi}: M \rightarrow \mathbb{R}$ to $F_{\varphi}: T^{1} M \rightarrow \mathbb{R}$ by setting $F_{\varphi}(\omega)=F_{\varphi}$ (base point of $\omega$ ). It is easy to see using the precompactness of $\widetilde{M}_{0}$ and the continuity of $F_{\varphi}$ that for all homomorphisms $\varphi$,

$$
\varphi(\Xi(\omega))=\lim _{T \rightarrow \infty} \frac{1}{T} \ln F_{\varphi}\left(g^{T} \omega\right)
$$

Thus $\Xi(\omega)$ is completely determined by the logarithmic growth of the minimal positive eigenfunctions of $\Delta$ along the forward geodesic ray of $\omega$.

In particular, we get the following corollary of theorem 1.1: Suppose $M$ is a $\mathbb{Z}^{d}$-cover of a compact hyperbolic surface, then $\omega$ is generic for the horocycle flow with respect to the volume measure iff

$$
\lim _{T \rightarrow \infty} \frac{1}{T} \ln F\left(g^{T} \omega\right)=0
$$

for every positive minimal eigenfunction $F$ of the Laplace-Beltrami operator of $M$.
Question: Does the above extend to other, perhaps all, hyperbolic surfaces with the Liouville property?
We remind the reader that a hyperbolic surface is called Liouville if all its bounded harmonic functions are constant. We need to assume the Liouville property, because of Kaimanovich's theorem [K], which says that the volume measure is ergodic for the horocycle flow on a hyperbolic surface, iff this surface is Liouville.

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[^1]:    ${ }^{1}$ Here we use the general fact that a measure is invariant for a transformation if and only if it is invariant for the corresponding orbit relation. (A Borel measure $m$ is invariant for a Borel equivalence relation $\sim$, if $\left.m \circ \kappa\right|_{\operatorname{dom}(\kappa)}=\left.m\right|_{\text {image }(\kappa)}$ for all partial Borel isomorphisms $\kappa: \operatorname{dom}(\kappa) \rightarrow$ image $(\kappa)$ such that $\kappa(x) \sim x$ for all $x \in \operatorname{dom}(\kappa)$.)

[^2]:    ${ }^{2}$ For a detailed account of the calculation in the particular case $\varphi \equiv 0$, see the appendix of LS1]. The modifications needed to treat general $\varphi$ 's are routine.

