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A strong seismic velocity contrast in the shallow mantle across the Zagros collision zone (Iran)

A. Kaviani^{1,2}, A. Paul¹, E. Bourova¹, D. Hatzfeld¹, H. Pedersen¹ and M. Mokhtari²

¹Laboratoire de Géophysique Interne et Tectonophysique, CNRS & Université Joseph Fourier, P O Box 53, 38041 Grenoble, France ²International Institute of Earthquake Engineering and Seismology (IIEES), P O Box 19395/3913, Tehran, Iran

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SUMMARY

Surface wave dispersion measurements are interpreted jointly with the inversion of teleseismic P-wave traveltime residuals along a dense 620-km long temporary seismic profile across the Zagros to investigate its upper-mantle structure. The S-wave model determined from Rayleigh wave dispersion in the Zagros fold and thrust belt has high velocities from 4.5 ± 0.2 km s⁻¹ below the Moho to 4.9 ± 0.25 km s⁻¹ at 200 km depth, which are comparable to a shield-like structure. Beneath the suture region from the Main Zagros Thrust (MZT) to the Urumieh-Dokhtar volcanic arc, S-wave velocities are lower than beneath the Zagros in the top 50 km of the upper mantle, with a minimum of 4.4 ± 0.2 km s⁻¹ at 80 km depth. From 150 km and deeper, S velocities are as high as beneath the Zagros. We suggest that part of the velocity difference at shallow depth is due to higher mantle temperatures and/or higher fluid content beneath the northern half of the profile, but that velocities are too high to support the hypothesis of mantle lid delamination under the suture zone. Teleseismic P traveltime relative residuals display a long-wavelength variation along the transect, with a difference of 1.1 s between negative residuals in the Zagros Simple Folded Belt and positive residuals in Central Iran. This difference backprojects into a 6-7 per cent lateral variation of P-wave velocity in the shallow upper mantle, with higher V_P beneath Zagros and lower V_P beneath Central Iran. The main short wavelength variation of the residual is located in the suture region, with late P arrivals in the region of the MZT and early arrivals in the Sanandaj-Sirjan zone (SSZ). Using synthetic models of V_P perturbations, we show that the high velocities of the Arabian platform have to extend laterally at least to the SSZ to fit the observed P delays. This model also predicts Rayleigh wave phase velocities, which are within the error bars of the observed dispersion. It supports the model of crustal-scale overthrusting at the MZT.

Key words: lithospheric structure, surface wave dispersion, teleseismic tomography, Zagros collision belt.

INTRODUCTION

The Zagros mountain belt in southwestern Iran results from the collision of Arabia and Eurasia after the closure of the Neotethys oceanic domain in the Oligo-Micocene (Fig. 1a). This continental collision, young and of limited geographical extension, is a natural laboratory for investigating processes related to the early phases of mountain building. The role of continental subduction in the transition from oceanic subduction to continental collision (see modelling by Regard *et al.* 2003), the response of the lithospheric mantle to shortening (see modelling by Bird 1978), or the role of lithospheric delamination in the formation of the Turkish–Iranian plateau (Maggi & Priestley 2005) are still open questions. Previous studies of the Zagros region from regional data document differences in the seismic properties of the upper mantle beneath the Arabian platform and Central Iran (e.g. Maggi & Priestley 2005). However, their res-

© 2007 The Authors Journal compilation © 2007 RAS olution is too low to easily connect the observations with surface geology.

We here present the first tomography results across the Zagros belt based on a dense temporary seismic array. The 620-km long array (Fig. 1a) was installed in the area for a duration of 4 and a half months. In spite of the short duration of the experiment, and therefore the limited amount of data, we are able to give some constraints on upper-mantle structure through a joint interpretation of surface wave dispersion and teleseismic *P*-wave tomography.

Tectonic setting

The Central Iranian microcontinent is constituted of separate continental blocks that detached from Gondwana in the Permian to early-Triassic and subsequently accreted onto Eurasia along the Alborz and Kopet-Dag sutures during the late Triassic closure of the



Figure 1. Location map of the seismic array. (a) Topographic map of Iran and neighbouring regions. The small red triangles are the seismic stations used in this study. (b) Tectonic map showing the main morphotectonic units of the study area and the stations. The thick dash-dotted line is the N42 profile used to compute all cross-sections.

Palaeo-Tethys (Stöcklin 1968; Falcon 1974; Stoneley 1981). The subduction of the Neo-Tethys Ocean beneath the southern margin of the Central Iranian blocks started by the Late Jurassic (e.g. Berberian & King 1981), and the onset of the closure of the oceanic domain was marked by the obduction of ophiolites along the Main Zagros Thrust (MZT) in the Late Cretaceous (Agard *et al.* 2005). Still, it is not certain whether the calc-alkaline volcanism of the Sanandaj-Sirjan metamorphic zone (SSZ) and of the Urumieh-Dokhtar magmatic arc (UDMA) was related to subduction (see Berberian & King 1981 and references herein).

Even though evidence from different sources indicates different times of closure of the Neotethys (hereafter called Tethys), the collision has been purely continental for at least 5 Ma (Stoneley 1981; McQuarrie *et al.* 2003; Agard *et al.* 2005). The present velocity of Arabia with respect to Eurasia is approximately $22 \pm 2 \text{ mm yr}^{-1}$ in the direction N8 \pm 5°E (Vernant *et al.* 2004). This convergence is accommodated by crustal shortening by fold-and-thrust deformation in the Zagros, Alborz and Kopet-Dag and by lateral displacements of the blocks of Central Iran along major strike-slip faults.

The Zagros collision zone comprises three major subparallel tectonic elements with a general NW–SE trend. They are, from SW to NE, the Zagros fold and thrust belt (ZFTB), the SSZ, and the UDMA (Stöcklin 1968; Ricou *et al.* 1977) (Fig. 1b). The ZFTB is characterized by a sequence of Palaeozoic and Mesozoic shelf sediments deposited on the subsiding Arabian continental margin. This sequence forms a 200–300 km wide simply folded range extending about 1200 km from eastern Turkey to the Strait of Hormuz (Berberian & King 1981; Stoneley 1981). The Main Zagros Reverse Fault or MZT (Stöcklin 1968, 1974) marks the boundary between the ZFTB and the SSZ (Stöcklin 1968, 1974; Ricou *et al.* 1977; Berberian 1995). Recent geological (Agard *et al.* 2005) and geophysical (Paul *et al.* 2006) data suggest that the MZT is deeply rooted, possibly to Moho depths, and that it coincides with the suture between Arabia and the plate fragments that make up Iran. The 150–200-km wide SSZ has undergone various metamorphic episodes during the subduction of the Tethyan Ocean under the Iranian block, the obduction of ophiolites along the MZT, and the final continental collision (Stöcklin 1968; Davoudzadeh *et al.* 1997). During this latest episode, the SSZ overthrusted the Zagros sedimentary sequence along the MZT (Stöcklin 1968; Agard *et al.* 2005). To the northeast, the UDMA is often interpreted as an Andean-type, subduction-related volcanic arc (Berberian & King 1981), with volcanic and plutonic rocks ranging in age from upper Jurassic to Cenozoic. The peak volcanic activity is estimated to be of Eocene age (Berberian & King 1981; Alavi 1994).

Previous geophysical data on the lithospheric structure

No deep seismic sounding data are available in Iran besides shallow seismic reflection profiles for oil exploration. Bouguer anomalies have been used to estimate crustal thickness (Dehghani & Makris 1984; Snyder & Barazangi 1986) and, combined with geoid and topography, lithospheric thickness (Molinaro *et al.* 2005). Recent receiver function analysis by Paul *et al.* (2006) shows however that crustal thickness is strongly decorrelated with Bouguer anomalies. Based on the same field experiment as in this study, Paul *et al.* (2006) (hereafter referred to as PA06) estimate crustal thickness to be ~45 km between the Persian Gulf coast and the High Zagros after which it thickens rapidly to ~70 km within a narrow zone beneath the SSZ, before thinning to ~42 km beneath the UDMA and the southern rim of Central Iran. They propose that the localized thickening results from the overthrusting of the crust of Central Iran onto the Zagros crust along the MZT.

Studies of *Pn* velocities show high velocities in the Arabia plate including the Zagros (8.1–8.4 km s⁻¹; Al-Lazki *et al.* 2004) and normal velocities (7.9–8.1 km s⁻¹) beneath most of the Iranian plateau (Hearn & Ni 1994; Al-Lazki *et al.* 2004). The transition from high to normal velocities occurs at the MZT in the Northwestern Zagros

(Al-Lazki *et al.* 2004), and is interpreted as an indication for absent or very limited underthrusting of Arabia. In the southern Zagros the situation may be different, as the high-velocity area seems to extend 100 km north of the MZT, but their resolution in that area is too poor to draw any firm conclusions. *Sn* waves are strongly attenuated in the Iranian Plateau (Sandvol *et al.* 2001), but this attenuation is not compatible with thin, hot lithosphere as the *Pn* velocities are normal. Due to limited resolution, the *Sn* blockage is possibly limited to an area of low *Pn* velocities in Northwestern Iran (Al-Lazki *et al.* 2004).

There is still some uncertainty as to the evolution of the oceanic slab which once subducted before continental collision. Maggi *et al.* (2000) showed from waveform modelling that there is no unequivocal evidence for mantle seismicity in the Zagros or north of it, and that the deep events all belong to the Makran subduction zone.

P-wave velocities in the mantle change across the area of the MZT, with velocities being a few per cent higher beneath Arabia and Zagros than beneath Central Iran (Bijwaard et al. 1998; Piromallo & Morelli 2003). S-wave velocities have mainly been obtained by large-scale surface wave analysis with a spatial resolution of several hundreds of kilometres (e.g. Curtis et al. 1998; Villaseñor et al. 2001; Maggi & Priestley 2005) or limited to the crust and uppermost mantle (Rodgers et al. 1999). The best resolution in the top 200 km over the whole of Iran is probably obtained by Maggi & Priestley (2005) who show relatively low velocities down to 150 km beneath the Alborz, the Iranian plateau and the Zagros, whereas the South Caspian Sea and the Persian Gulf are underlain by fast mantle. They explained this velocity contrast by a thin lithosphere overlying an above-solidus temperature mantle beneath the Turkish-Iranian plateau, which would be compatible with partial delamination of the lower lithosphere.

To improve our understanding of the mantle processes beneath the Zagros belt it is now necessary to improve the lateral resolution of the velocity models. This is the scope of the present study.

Data acquisition and processing

A passive seismic experiment was carried out between November 2000 and April 2001 along a profile from Bushehr on the coast of the Persian Gulf, across the Zagros belt, to Posht-e-Badam in the southwest of Central Iran (Fig. 1; Kaviani 2004; PA06). It was coorganized by Iranian and French seismologists from IIEES, Tehran and LGIT, Grenoble. The profile was oriented N42E, almost perpendicularly to the structural strike of Zagros. The array included 66 stations equipped with digital continuously recording Agecodagis data acquisition systems with GPS time base, and various types of three-component sensors with 1–120 s cut-off period. The broad-band stations were installed in three short-aperture arrays (two triangles in the Zagros and four stations in Central Iran, see Fig. 1) to enable measurement of the incidence azimuth of the surface waves and improve the two-station dispersion studies (Cotte *et al.* 2000; Pedersen 2006).

This study proposes a joint interpretation of the results of two types of seismic data analysis with complementary advantages and disadvantages. First, Rayleigh wave dispersion curves are inverted for shear wave velocity models in two short-aperture broad-band arrays located in the ZFTB and across the MZT suture region. The lateral resolution of this surface wave study is poor since average velocity models are computed for two arrays of ~130 and ~300 km aperture. However, it gives a reliable estimate of velocity variations with depth including error bars and, more importantly,

provides absolute *S*-wave velocities that can be interpreted in terms of compositional or thermal changes with depth. Secondly, teleseismic *P*-wave relative traveltime residuals are inverted for *P*-wave velocity variations in a depth cross-section under the profile using the ACH method (Aki *et al.* 1977). It gives robust results with respect to noise in the data or initial model parametrization (Evans & Achauer 1993), with a lateral resolution of the order of a few station spacings, that is 20–30 km in our case. However, ACH also has a number of important drawbacks including the projection of velocity heterogeneities located outside the target volume (beneath the network) into it (Masson & Trampert 1997), and the impossibility to estimate vertical velocity variations as the anomalies mapped at different depths refer to different and unknown average layer velocities (Lévêque & Masson 1999).

SURFACE WAVE ANALYSIS: S-WAVE VELOCITY STRUCTURE

Data selection and pre-processing

The database for the surface wave study is composed of records of Rayleigh waves (vertical component) from teleseismic events. For this analysis we used only data from STS-2 (120-s cut-off period) and CMG-3ESP (90-s cut-off period) sensors for which we analysed 70 events with epicentral distances between 25 and 160°, magnitudes greater than 5.5, and good signal-to-noise ratios (see a location map of epicentres in Fig. 2). The seismograms were corrected for instrumental responses and subsequently frequency-time filtered (Levshin 1989) based on multiple filter analysis (Dziewonski *et al.* 1969) to minimize contamination by noise, spectral holes, higher modes and multipathing. Records with sign of mixture between the fundamental mode Rayleigh wave and other waves were rejected.

Array analysis

There are two major difficulties in surface wave analysis. First, the waves may be significantly deviated from the great-circle (e.g. Alsina & Snieder 1996; Cotte et al. 2000), and secondly the phases may be perturbed by wave interaction, which can be formalized by non-plane wave fronts (Wielandt 1993). The latter problem can be at least partly resolved by using seismic events from different epicentral areas (Pedersen 2006), however this increases the problem with great-circle deviation as it is then necessary to increase the angle that one allows for between the station profile and the eventstation great-circle. A possible compromise for these difficulties is to increase the allowed angle as suggested above, but performing a first-order, frequency dependent, correction for the great-circle deviation by array analysis (Baumont et al. 2002; Bourova et al. 2005). We have followed this procedure here. The array analysis consists of defining a small (3-5 stations) array around the target profile, and at each frequency search for the plane wave which best fits observed time-delays between pairs of stations. The frequency-azimuth thus obtained is subsequently used to correct the two-station dispersion curve.

To compare the lithospheric structure between the Arabia plate (beneath Zagros, SW of MZT) and the microblocks of Central Iran (NE of MZT), we separated the available broad-band stations in two subarrays, array AB (stations A1–A2–A3, B1–B2–B3) in the Zagros and array BCD (stations B1–B2–B3, C2, D1–D2–D3) further north (see Fig. 3a). The phase velocity measurements between stations C



Figure 2. Epicentre map of earthquakes used in the surface wave study (70 events plotted as red stars) and in the teleseismic tomography (111 events plotted as black and red stars). Azimuthal equidistant projection centred on $[30.6^{\circ}N, 53^{\circ}E]$.



Figure 3. Results of Rayleigh wave dispersion measurements. (a) Location map of the mini-arrays of broad-band stations (plotted as red stars), and stations with CMG-40 sensors (red triangles) used in the dispersion measurements. The thick line segments show the locations of subarray AB (in blue), BCD (in red) and MCD (stations M4, M5, M6, M7, M8, C2, D1, D2 and D3; in black). (b) Dispersion curves measured in subarrays AB (blue), BCD (red) and MCD (black).

and D were unstable due to small interstation distances which is why we had to add stations B1–B2–B3 to the northern array. The location map of Fig. 3(a) shows that the longest paths of subarray BCD, which are \sim 290 km long, consists of 230 km within the surface exposure of the SSZ and the UDMA, and 60 km within the ZFTB.

The phase velocity dispersion curves of the Rayleigh waves were measured between the stations of each subarray and the mean dispersion curves were calculated for arrays AB and BCD. These curves, which are plotted in Fig. 3(b), document a strong phase velocity contrast of ~4.5 per cent between 40 and 80 s period, with higher phase velocities for subarray AB. This result is consistent with previous surface wave tomographic studies in the Middle East which documented slower *S*-wave velocities at ~100 km depth beneath Central Iran than beneath the Arabian platform (Debayle *et al.* 2001; Shapiro

& Ritzwoller 2002; Maggi & Priestley 2005), but our results show that this transition is located within our study area, and most likely beneath subarray BCD, which means that it is likely to take place somewhere within the northern edge of the Arabian platform or at its contact with the Central Iranian lithosphere.

To estimate the contribution of the part of the wave paths between stations B and the surface exposure of the MZT, which definitely belongs to the Arabia plate, we added to our data set records of stations equipped with CMG-40 (60 s) sensors and located northeast of the MZT. The dispersion curves between the broad-band stations C1, D1, D2, D3 and the CMG-40 stations M4, M5, M6, M7 and M8 (see locations in Fig. 3a) were measured in the period range 20–60 s. The resulting dispersion curve, which is indicative of the crust and uppermost mantle north of the MZT, is displayed as the thin

black line with plain error bars in Fig. 3(b). It is almost identical to the dispersion curve measured for array BCD (thick plain red line) between 20 and 60 s. We conclude that at least for this period range, dispersion measurements in array BCD are representative of the lithospheric structure northeast of the surface trace of the MZT.

S-wave velocity structure

To obtain the S-wave velocity models in the lithosphere beneath subarrays AB and BCD, we applied the two-step Monte Carlo inversion technique described in Bourova et al. (2005), which is a modification of the method of Shapiro et al. (1997). In the first step, a linearized inversion of the dispersion curve is carried out using the software of Herrmann (1987) to obtain a reasonable layered starting model. Then, a stochastic Monte Carlo inversion is conducted, with the output model of the linearized inversion as starting model. In the crust, the model is parametrized by the thickness and constant velocity of each layer. To take into account the continuous velocity variation in the mantle, we consider that the mantle of the starting model consists of a few layers with a constant velocity gradient in each layer and no velocity jumps are allowed across layer interfaces. There is only one more parameter to invert for as compared to a model with constant velocity layers. At each iteration of the Monte Carlo inversion, random changes within given limits are applied to all model parameters. If the calculated dispersion curve falls within the error bars of the observations, the new model is accepted and used as the initial model for the next iteration. In the opposite case, the model is rejected and the next iteration starts from the last accepted model. To be certain of exploring most of the parameter space, we run the Monte Carlo inversion several times, with different random series of parameters.

As the starting model of the linearized inversion, we used a preliminary average S-wave velocity calculated by Maggi & Priestley (2005) for the Turkish-Iranian plateau. Even though the initial model (shown as a red dotted curve in Fig. 4) is different from the final average model (MP05) published by Maggi & Priestley (2005), it is a better starting model because it contains no developed LVZ. Moho depth in the starting model was modified accordingly to the result of the receiver function analysis by PA06. The mean Moho depths beneath arrays AB and BCD were considered to be 45 and 55 km, respectively. The crust was divided into 2 layers under subarray AB. Beneath subarray BCD, we added a third layer in the deepest 10 km of the crust to account for possible high velocities in the thickened lower crust of the SSZ, as suggested by the gravity models of PA06. In the subsequent Monte Carlo inversion, we applied 1 per cent random perturbations to S-wave velocities and 5 per cent random perturbations to interface depths at each iteration. In total, 10 000 models were tested, with 100 series of random parameters and 100 iterations for each series.

The results of the inversion are presented in Fig. 4. All models accepted in the inversion of dispersion curves of array AB are plotted in light blue, and models for array BCD in light red. The mean *S*-wave velocity models calculated for the two arrays are plotted as a thick blue line for AB, and a thick red line for BCD. Crustal velocities to 25–35 km depth are not constrained due to the lack of reliable dispersion measurements at periods shorter than 20 s. In the upper mantle, the difference in the dispersion curves measured at AB and BCD in the 40–80 s period range (Fig. 3b) results in a clear and well-resolved difference between the two sets of accepted *S*-wave velocity models in the depth range 50–170 km. The mean *S*-wave velocity structure beneath the Zagros (array AB) dis-



Figure 4. Results of the inversion of Rayleigh wave dispersion curves for *S*-wave velocity models and comparison with other models. Accepted models are plotted as thin lines, in blue for subarray AB and in red for subarray BCD. The thick lines show the average models. The dotted red line is the starting model for the inversion. The standard earth model AK135, the model measured by Bruneton *et al.* (2004) for unperturbed Proterozoic mantle in the Baltic shield, and the average shear wave velocity model MP05 measured for the Turkish–Iranian plateau by Maggi & Priestley (2005) are plotted as black lines for comparison.

plays a gentle increase from \sim 4.5 km s⁻¹ at Moho depth (45 km) to \sim 4.9 km s⁻¹ at 250 km depth, below which the resolution decreases strongly. No low-velocity zone (LVZ) is detected in the resolved depth range beneath Zagros. For subarray BCD, the minimum velocity of the average model is 4.4 km s⁻¹ at 80 km depth. The *S*-wave velocity increases again with depth between 80 and 170 km depth where it converges with the velocity model measured at array AB (Fig. 4a). The decrease in velocity immediately beneath Moho is not well resolved due to trade-off with the lower crustal velocities.

TELESEISMIC TRAVELTIME INVERSION: *P*-WAVE VELOCITY STRUCTURE

Traveltime residuals

We investigated the *P*-wave velocity variations under the array by inverting teleseismic traveltime residuals. Arrival times of *P* waves were picked on the records of 111 earthquakes with epicentral distances between 25° and 95° after correction for sensor response and subsequent bandpass filtering. The event hypocentres are shown in Fig. 2. Only *P*-wave arrival times of events with 10 or more reliable readings were kept. The average number of readings per event is 46. Traveltime residuals were calculated with respect to the IASP91 standard earth model (Kennett & Engdahl 1991), and the average for each event was subtracted from the relevant residuals. This correction yields relative residuals that are presumably sensitive only to the velocity anomalies beneath the stations. The final data set includes 5073 residuals at 66 stations.

Fig. 5(b) shows the relative residuals along a N42 profile centred at [30.6°N, 50.3°E], where x = 0 corresponds to the MZT. The time residuals observed at a given station are averaged over all available events, and the resulting mean residual and its error bar are plotted



Figure 5. Observed *P*-wave relative teleseismic traveltime residuals, and results of the ACH inversion for V_P perturbations. (a) Average elevations along the N42 profile shown in Fig. 1(b). The grey triangles correspond to seismic stations. The three vertical lines show the boundaries of the main morphotectonic units. (b) *P* traveltime relative residuals plotted for each station at the abscissa of the projection of the station onto the N42 profile. (c) Depth cross-section along the N42 profile in the 3-D model of *P*-wave velocity perturbations resulting from the inversion of residuals. The black solid line is the Moho depth profile measured by Paul *et al.* (2006) along the same transect. The vertical dotted lines bound the areas covered by surface wave dispersion measurements in subarrays AB and BCD. (d) Number of rays per block. (e) Diagonal elements of the resolution matrix. ZFTB: Zagros Fold-Thrust Belt; MZT: Main Zagros Thrust; SSZ: Sanandaj-Sirjan metamorphic Zone; UDMA: Urumieh-Dokhtar Magmatic Assemblage; CIMC: Central Iran Micro-Continent; SFB: Simple Folded Belt and KZF: Kazerun Fault.

at the abscissa of the station projected onto the N42 profile. The variations of the residuals with the backazimuth are not well resolved due to the concentration of 48 per cent of the backazimuths in the $70-120^{\circ}$ range (see Fig. 2). Moreover, the quasi-linearity or our array combines with this incomplete azimuth coverage to prevent from inverting the residuals for 3-D structure. The orientation of the profile perpendicular to the structural trend of Zagros reduces the probability that 3-D heterogeneities in the vicinity of the 2-D profile have a strong influence on the residuals. To reduce this bias even more, we could use earthquakes whose backazimuths differ by less than 30° from the average strike of the array, as done, for example, by Tilmann *et al.* (2003). However, this would leave only 26 events out of 111 and make the inversion meaningless.

The overall trend is that the residuals are negative (minimum -0.6 s) at stations located in the Simple Folded Belt (SFB) of Southern Zagros and positive (maximum 0.5 s) at stations in Central Iran. Apart from this long-wavelength variation, the most significant lateral changes are the rapid increase at stations close to the MZT

followed by a decrease to negative residuals in the SSZ, the increase from -0.5 s to null residuals between the SFB (x = -200 km) and the High Zagros (x = -100 km), and the small and spatially limited decrease at ~175 km. The difference between the most negative (at the NE end of the profile) and the most positive residual (close to the MZT) is 1.2 s.

The application of crustal corrections to teleseismic traveltimes before inversion using *a priori* information is an efficient method to attenuate smearing of crustal anomalies and increase the resolution in the mantle (e.g. Lippitsch *et al.* 2003; Martin *et al.* 2005). However, it requires a precise 3-D crustal velocity model constructed from reflection and refraction seismic data that is not available in our study region. A correction for crustal thickness variations using the Moho depth profile by PA06 and normal velocities (~6.7 km s⁻¹) for the lower crust would strongly enhance the negative residuals in the SSZ. Based on gravity observations, it is however likely that the crustal velocities are anomalous in this area. We therefore, chose not to apply crustal corrections in this study.

 Table 1. Parameters of the layered block model used in the inversion of teleseismic P residuals.

Layer number	Thickness (km)	Block size (km)
1	10	Cones
2	40	20×20
3	50	30×30
4	50	40×40
5	50	40×40
6	60	50×50

Inversion of residuals

We used the ACH damped-least-squares inversion method of Aki *et al.* (1977) to backproject the relative residuals and estimate the size and amplitude of *P*-wave velocity perturbations beneath the array. A comprehensive description of the method is given in Evans & Achauer (1993). More sophisticated iterative non-linear inversion schemes are available (e.g. Sandoval *et al.* 2004), but ACH is efficient enough to image the most significant velocity variations of interest to lithospheric exploration.

We tested the influence of block widths, layer thicknesses, and damping values, which are critical parameters for ACH inversion. The optimum parameters of the block model are given in Table 1. A damping value of 80 was selected from the trade-off curve between residual and model variances. The first layer of 10 km thickness includes cones to account for the static station corrections. To attenuate the influence of the horizontal sampling in discrete blocks, the final models were smoothed horizontally using the 'shift-andaverage' procedure of Evans & Achauer (1993).

The results of the ACH inversion of traveltime relative residuals are shown in Fig. 5. Fig. 5(c) displays velocity perturbations on a depth cross-section along the N42 profile. Two indicators of the resolution of the cross-section of Fig. 5(c) are displayed in Figs 5(d) (number of ray hits per block) and (e) (diagonal element of the resolution matrix). This final velocity perturbation model explains 85 per cent of the initial data variance. Figs 5(d) and (e) and results of synthetic tests indicate that the model is not well resolved in the crust (top 50 km, see Figs 5d and e) and at depths greater than 250 km. The hit-count cross-section (Fig. 5d) shows that the number of rays per block is larger than 60 in most mantle blocks with two peaks above 150 hits at depth of 50–150 km beneath the two sets of stations that worked best during the experiment. The diagonal elements of the resolution matrix (Fig. 5e) are very low in many blocks of the crustal layer, due to weak ray criss-crossing.

As mentioned in Section 'Introduction', the use of relative residuals implies that anomalies are computed with respect to an unknown velocity model (Lévêque & Masson 1999). Thus, it is impossible to compare velocity anomalies at different depths, and we will only discuss lateral velocity variations. The most significant large-scale feature of the depth cross-section is the contrast in the uppermost mantle between the higher P-wave velocities beneath the Zagros and the lower velocities beneath the UDMA and the southern rim of the CIMC. The maximum change in velocity perturbation between the SW and NE ends of the profile is \sim 5 per cent in the top mantle layer (50–100 km depth) and \sim 4 per cent in the 100–150 km layer. At a smaller length scale, the positive and slightly negative residuals at stations in the MZT and SSZ regions (Fig. 5b) project into a negative and positive velocity anomaly in the two shallowest layers. The increase of residual in the High Zagros (between x = -150 and 50 km) gives a negative velocity anomaly in the crustal layer. Thus, the *P*-wave tomogram displays strong anomalies both at crustal and mantle depth.

DISCUSSION

A strong lateral change in the upper-mantle velocity structure

The Rayleigh wave dispersion study shows that the phase velocity at 40–80 s period is significantly higher for paths in subarray AB than for paths in subarray BCD (Fig. 3b). Moreover, the similarity between the dispersion curves measured for BCD and the ones measured at stations located northeast of the MZT shows that, in the period range 20–60 s, dispersion measurements in BCD are representative of the mantle structure northeast of the MZT (Fig. 3). At longer periods, we have no separate estimate of the dispersion for stations on the northeastern side of the MZT, and a *S*-wave velocity difference between the Zagros and the CIMC at depths larger than 150–170 km cannot be ruled out. However, we consider it as very unlikely because such a difference would lead to different phase velocities at stations of the northern side of the MZT and at BCD even at 60 s.

The maximum difference between the mean phase velocities is 4.5 per cent at 75 s period. Furthermore, the teleseismic traveltime study shows that the ~1.1 s difference between the two ends of the profile (Fig. 5b) is projected by the ACH inversion into the crust and the uppermost mantle to a depth of 150–200 km, with higher velocities in the southwest than in the northeast (Fig. 5c). Therefore, we have two independent arguments for a strong lateral change in seismic velocities in the upper mantle beneath our profile, with relatively higher *P*- and *S*-wave velocities beneath the Zagros (Arabia plate) and lower velocities beneath UDMA and the southern rim of the CIMC (Iran microblocks). Both the surface wave analysis and the teleseismic traveltime inversion indicate that the velocity difference is likely to be limited to the uppermost mantle above 150–170 km.

The inversion of surface wave dispersion curves provides absolute shear wave velocity models that can give clues on the mineralogical composition and/or the thermal state of the mantle. However, it is difficult to predict mineralogy and temperature in the continental lithosphere from shear velocities alone. We therefore, limit our analysis to the comparison with reference global or regional S-wave velocity models. The surface wave studies of the Arabian shield and platform by Rodgers et al. (1999) and Mokhtar et al. (2001) are restricted to the crust and the very shallow upper mantle (45 and 60 s maximum period) so we focus the comparison (see Fig. 4) on the standard earth model AK135 (Kennett et al. 1995) and the mean model for the Turkish-Iranian plateau measured by Maggi & Priestley (2005), referred to as model MP05 in the following. We also compare with a model estimated for the Proterozoic Baltic shield of Finland by Bruneton et al. (2004) because it corresponds to an unperturbed mantle shield structure with a typical shield geotherm and depleted composition as estimated by a large number of seismic stations.

The upper-mantle *S*-wave velocities estimated for the Zagros region are between 0.1 and 0.6 km s⁻¹ higher than in AK135 in the depth range 70–200 km, in agreement with the smooth shear wave velocity model of Shapiro & Ritzwoller (2002) and high *Pn* velocities beneath the Arabian platform including the Zagros (Al-Lazki *et al.* 2004). The comparison with MP05 also confirms that the mantle beneath the Zagros is faster than beneath the Turkish–Iranian plateau. Its lower error bound is close to the unperturbed Proterozoic of the Baltic shield. All this indicates that the mantle beneath Zagros has a shield-type structure. It is disputed whether a continental lithosphere–asthenosphere boundary, defined as the depth at which convection replaces conduction in heat transport, would be related to a LVZ (Poupinet *et al.* 2003; Priestley & McKenzie 2006), but the consistently high velocities beneath subarray AB point towards a lithosphere at least 250 km thick. To strengthen this assertion, we used the empirical relation for $V_s(P,T)$ (*S*-wave velocity as a function of pressure and temperature) derived by Priestley & McKenzie (2006) to estimate the temperature depth profile beneath AB from the average velocity profile of Fig. 4. The temperature rises smoothly with depth between 100 and 250 km, without any rapid decrease in the temperature gradient which would mark the base of the lithosphere (Priestley & McKenzie 2006).

The low velocity zone immediately below the Moho in the mean model of subarray BCD is less than 50 km thick. It is not well resolved as it is located at the very top of the mantle where the trade-off between the crust and the mantle is significant. Moreover, velocities beneath BCD are higher than MP05 at most mantle depths and even higher than AK135 at depths greater than 130 km. Based on these observations, we believe that mantle lid delamination, as proposed by Maggi & Priestley (2005) and Molinaro *et al.* (2005), is unlikely for our study region.

Even though the hydration of mantle material can lower velocities significantly (e.g. Bruneton *et al.* 2004), the velocity contrast of almost 0.5 km s⁻¹ between the two profiles is probably too strong to be created by compositional changes only (Sobolev *et al.* 1997; Goes *et al.* 2000), and we support the idea that the uppermost mantle temperatures on average are higher beneath subarray BCD than beneath subarray AB.

The result that the mantle beneath AB has a shield-like structure qualitatively agrees with the V_P tomogram of Fig. 5(c). However, the 9 per cent V_s contrast between AB and BCD at 80 km depth is stronger than the *P*-wave velocity lateral variation. According to the V_P tomogram, BCD is located right on the transition between the high-velocity upper mantle of the Arabian platform and the lower-velocity upper mantle of Central Iran (Fig. 5c). In the following, we assume that this boundary is the suture between the two lithospheres, and we further test the influence of its location on both the dispersion curves and *P*-wave tomography to try to reconcile the two observations.

Location of the suture in the upper mantle

The analysis of receiver functions by PA06 documents a strong increase in crustal thickness beneath the SSZ (see Moho depth profile in Fig. 5c). Their modelling of the Bouguer anomaly shows that this crustal thickening has to be compensated by thicker high-density material northeast of the MZT as compared to the area southwest of the MZT. These two elements suggest a crustal origin for at least part of the low and high velocity anomalies in the shallowest two layers of the V_P tomogram beneath the MZT and the SSZ. Such crustal anomalies would leak to mantle depth in the inversion due to weak ray criss-crossing in the crustal layer, and they would blur the image of the mantle in the suture region.

Yet we can combine the different types of information available and test different lithospheric models by forward modelling, that is by comparing observed residuals with those predicted for the models. The synthetic data sets are computed using the same ray tracing scheme as in the inversion (Evans & Achauer 1993), for the same

event-station couples, and they are inverted using the same parameters (block model, damping parameter) as for the actual data set. In all the models we use the three-layer crustal geometry proposed by PA06. The second geometrical constraint is that we assume the boundary between relatively fast and slow mantle velocities is a first-order vertical discontinuity. Numerical tests showed that more complex geometries or a gradual velocity change are possible but that they cannot be resolved by our data. We chose the maximum depth of the mantle V_P anomaly (150 km) in agreement with the S-wave average velocity profiles of Fig. 4 and the P-wave velocity tomogram of Fig. 5(c). The next choice concerns the velocity contrast in the mantle lid. The V_s and V_P inversions indicate that the long-wavelength traveltime variation is due to a lateral change in the mantle velocity. Considering the thickness of the heterogeneous mantle layer, a V_P change of 6 per cent is required (+3 per cent beneath the ZFTB and -3 per cent beneath the UDMA and CIMC) to fit the difference in traveltime residual between stations located at x < -200 and >200 km.

Fig. 6(a) shows the observed and predicted residuals with a mantle boundary 135 km north of the MZT and normal crustal velocities (4.7 km s^{-1} for the sediments, 5.8 km s^{-1} for the upper crust, and 6.5 km s⁻¹ for the lower crust; model A) as proposed by Hatzfeld et al. (2003) from the inversion of arrival times of microearthquakes and receiver functions in the Ghir region. The geometry of the crustal layers induces apparent lateral velocity variations in the 50-km thick crustal block layer as shown in Fig. 6(b). The mantle velocity contrast cannot be moved more further north and still fit the observed dispersion curves within their error bars. The predicted residuals fit the long-wavelength variation however the short-wavelength variations immediately north of the MZT (x = 0-200 km) are not explained by this model. We explored a large number of mantle velocity models but there is no way of adequately explaining the short-wavelength variations north of the MZT without increasing the velocity in the lower crustal layer (6.7 km s^{-1}) and decreasing the velocity in the sediments (4.5 km s^{-1}) and upper-crustal layer (5 km s^{-1}) (model B, Fig. 7). This corresponds in practice to increasing the lateral velocity variations in the crustal block layer, as shown by Fig. 7(b). In this case, the short-wavelength residuals are fitted adequately (Fig. 7a). The velocity in the crystalline upper crust in model B is unrealistically low, but it is imposed by the geometry of the crustal model in which the positive residuals in the MZT region are explained by a thickening of the uppercrustal layer. A more reliable hypothesis is that the late P arrivals observed at stations close to the MZT are partly due to a thickening of the sediments in the accretionary wedge in front of the thrust.

The inversion of the synthetic residuals gives a tomogram (Fig. 7c) which is very similar to the result of the inversion of the observed data set (Fig. 5c). This inversion shows that the crustal structure necessary to fit the short-wavelength residual variations blurs the image of the mantle below. In spite of the blurred mantle image, it is not possible to push the vertical mantle boundary significantly towards the southwest without introducing unrealistic velocities in the crust. For example, a model with no velocity perturbation (0 per cent) in the 50-100 km layer between the MZT and the vertical boundary of Figs 6 and 7 gives a correct fit to the residual curve only with a very high velocity in the crustal root (V_P = 7.5 km s⁻¹) and an unrealistically high velocity of 6.9 km s⁻¹ in the lower crustal layer outside the crustal root. Such high velocities (and the associated densities) are difficult to reconcile with the rather strong P-to-S conversions at the Moho observed by PA06 and with the observed Bouguer anomaly.



Figure 6. Synthetic model A. The crust has the three-layer structure proposed by Paul *et al.* (2006) with velocities 4.7, 5.8 and 6.5 km s⁻¹. The velocity perturbation is 3 per cent in the upper mantle beneath the ZFTB, the MZT and the SSZ, and -3 per cent beneath the UDMA and CIMC. (a) Comparison between observed (empty squares with black error bars) and modelled (red dots) *P* traveltime residuals. (b) Synthetic lateral V_P perturbations averaged over depth in each layer of the ACH inversion (0–50, 50–100, 100–150 km). Note the strong negative anomaly (maximum: -5.9 per cent) induced in the 50–100 km layer by the crustal thickening beneath the SSZ.



Figure 7. Synthetic model B with crustal layer velocities 4.5, 5, 6.7 km s⁻¹. (a) Comparison between observed and modelled *P* traveltime residuals. Normally distributed noise with standard deviation of 0.2 s has been added to the synthetic residuals before inversion. (b). Depth-averaged synthetic lateral V_P perturbations. (c) Depth cross-section in the model of V_P perturbations resulting from the inversion of synthetic residuals.

The boundary between the two lithospheric mantles is probably not a vertical first-order discontinuity as in Fig. 7(b). We tested different other geometries, including a dipping suture and a smooth velocity transition rather than an abrupt change. However, the image resulting from the inversion is always blurred by the crustal velocity anomalies and no complementary information can be deduced from the V_P tomography.

Similarly, we have introduced the Tethyan oceanic lithosphere (modelled as 100-km thick slab with 2 per cent higher V_P than the surrounding mantle and a 45° dip towards the northeast) still attached to the Arabian margin in our synthetic models to test whether

is was detectable or not. These tests show that due to smearing of the high-velocity crustal SSZ anomaly and the poor resolution at depths larger than 250–300 km, the question of the Tethyan slab being attached to the Arabian margin or detached from it cannot be answered by the ACH tomography.

CONCLUSIONS

This first high-resolution study of the lithospheric structure across the Zagros belt documents a strong lateral change of both P- and S-wave velocities in the shallow mantle beneath the profile. The

dispersion curves of the Rayleigh fundamental mode measured in two short-aperture arrays located on each side of the MZT display clear differences. In the Zagros, the average shear wave velocity model deduced from the dispersion curve is characterized by high velocities from 4.5 \pm 0.2 km s⁻¹ below the Moho (~45 km) to 4.9 ± 0.25 km s⁻¹ at 200 km depth. The second short-aperture array (BCD) which covers the MZT region, the SSZ, the UDMA and the southern rim of the CIMC gives lower S-wave velocities in the mantle from the Moho to 150 km depth where both models converge to \sim 4.9 km s⁻¹. This average velocity model includes a rather thin (<50 km) and poorly resolved LVZ with a minimum of 4.4 \pm 0.2 km s⁻¹ at 80 km depth. The comparison of these shear wave velocity models with the standard earth model AK135, a model calculated for a Proterozoic part of the Baltic shield, and with the results of previous studies conducted in our study region (Al-Lazki et al. 2004; Maggi & Priestley 2005) indicates that the mantle of the Arabian platform beneath Zagros has a shield-like S-wave velocity structure. The 0.5 km s⁻¹ difference between the two V_s models in the shallow mantle is likely due to a compositional change (presence of hydrated minerals, for example) associated with higher temperatures beneath the MZT, the SSZ and the UDMA than beneath the Zagros. However, we believe that the absolute S-wave velocities measured in array BCD are too high to support the hypothesis of mantle lid delamination in this transition zone between Arabia and Central Iran. Teleseismic P-wave arrivals are 1.1 s earlier at stations in the Simple Folded Belt than in Central Iran, confirming the S velocity variation inferred from the dispersion measurements. Assuming that the time-shift is only due to mantle heterogeneity, it can be explained by a \sim 6 per cent difference of P-wave velocity in a 105-km thick laterally heterogeneous shallow mantle. The backprojection of traveltime shifts to P wave velocity anomalies at depth gives a maximum velocity contrast of 4-5 per cent in the two shallowest mantle layers (50-100 km; 100-150 km) between the Zagros and Central Iran. The tomogram also shows that array BCD, where we measured low phase velocities, is located right above the transition zone between the high-velocity mantle of the Arabian platform and the low-velocity upper mantle of Central Iran.

A striking result of the P traveltime study is the heterogeneity of the crust in the middle part of the transect below the High Zagros, the MZT and the SSZ. With respect to stations in the High Zagros, teleseismic P waves are ~ 0.5 s earlier in the Simple Fold Belt, \sim 0.5 s later in the MZT area, and \sim 0.2 s earlier in the middle of the SSZ. The computation of synthetic traveltimes in lithospheric models assuming the crustal geometry proposed by Paul et al. (2006) shows that a correct fit to the observed residuals requires that the pronounced crustal thickening is compensated by an extension of the upper-mantle Zagros high-velocity lid beneath the SSZ. The model of crustal overthrusting (Agard et al. 2005; Paul et al. 2006) explains at least qualitatively the short-wavelength anomalies of the relative residuals and the crustal velocity perturbations in the V_P tomogram of Fig. 5(c). The positive residuals in the MZT area and the associated low-velocity anomaly to 100 km depth could be created by the thickened crust and the thickened sediments of the accretionary wedge in the front wall of the MZT. The highvelocity anomaly beneath the SSZ would be due to the duplication of the lower crustal layer in the crustal-scale thrust in combination with high velocities in the shallow mantle to compensate for low velocities related to crustal thickening.

The inversion of *P* traveltime residuals is poorly resolved in the crustal layer due to weak ray criss-crossing. Moreover, the thickened crust induces a negative velocity perturbation in the shallowest mantle layer (50–100 km). As a result, the crustal heterogeneities leak to mantle layers and blur the tomogram, in particular in the region of the suture between the two lithospheric blocks. The location of the boundary between the high- and low-velocity regions of the upper mantle can only be estimated by trial-and-error fitting of the residual curve and the tomogram using synthetic models of V_P variations. The main argument for a boundary beneath the northern border of the SSZ is that a crustal anomaly alone cannot explain the early residuals observed in the SSZ. A model with a boundary located 135 km northeast of the MZT also gives Rayleigh wave phase



Figure 8. Proposed schematic interpretation of the lithospheric structure across Central Zagros. The Moho depth profile and the trace of the crustal-scale thrust that outcrops at the MZT and roots at Moho depth are from Paul *et al.* (2006). The results of the surface wave dispersion analysis and teleseismic *P* traveltime study are schematized as the green (high velocities) and pink (low velocities) areas in the mantle. The geometry proposed for the base of the lithosphere (dashed line) is speculative. The location of the boundary between the two lithospheres is marked by the hatched pattern. Its exact geometry remains unknown. The question mark on the dash–dotted line indicates that we have no definitive element in favour or against the presence of the Tethyan slab attached to the margin of the Arabian platform.

velocities within the error bars of the dispersion measurements for array BCD. The exact shape of the boundary remains unknown due to the smearing of crustal anomalies.

As most events used in the ACH tomography have backazimuths concentrated in the eastern quadrant (70–120°) not far from the strike of the Tethyan oceanic lithosphere (\sim 40°) if it was still attached to the Arabian margin, the influence of the associated highvelocity slab on *P*-wave residuals would combine with the effect of crustal and upper-mantle heterogeneity in the suture region, making it impossible for the ACH inversion to discriminate between the three anomalies. This is the reason why the *V*_{*P*} tomogram gives no definite answer on the presence or the absence of the Tethyan slab attached to the margin. However, other elements including the lack of high shear wave velocities at depths greater than 150 km beneath BCD array (Fig. 4) and the absence of any clear *P*-to-*S* conversion beneath the Moho at the northern end of the receiver function profile (Paul *et al.* 2006), suggest that the slab could be detached.

In Fig. 8, we present a schematic model of lithospheric structure across Central Zagros. This model assumes that the boundary between the high- and low-velocity upper-mantle lids coincides with the suture between the passive margin of the Arabian platform and the Tethyan oceanic mantle, or the upper mantle of the microblocks of Central Iran if the slab is detached. The lithosphere– asthenosphere boundary is plotted as a dotted line because we could not constrain its depth or its geometry. This hypothesis agrees with the model of crustal-scale thrust proposed by Agard *et al.* (2005) on geological arguments and by Paul *et al.* (2006) on geophysical arguments. The model implies that the upper mantle of the Arabian lithosphere extends to \sim 120 km northeast of the surface trace of the MZT assuming there is no decollement at the Moho.

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