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# Simplified Hardware Bit Correlator

Christophe Cunat, Emmanuel Boutillon<sup>\*†</sup>

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## Abstract

This letter proposes a suboptimal implementation of a binary correlator suitable for detecting a known fixed pattern in a binary stream. The theoretical performances in terms of the probability of nondetection and the probability of false alarm are evaluated. These performances show that the degradations are negligible. Compared to a proprietary core provided by FPGA vendor, this implementation allows a 15 % look-up table reduction, a 30 % register reduction and up to a 30 % higher clock frequency in a FPGA.

## 1 Introduction

Binary correlator is a common tool in digital signal processing systems used for synchronisation in a binary stream. The principle is based on the detection of a known fixed pattern in a binary stream which can be corrupted by a noise with a probability of error  $p$ . If the degree of match between the  $N$  last received bits and the  $N$  bits of the training sequence  $\text{seq}(k)_{k \in \{0, \dots, N-1\}}$  is above a given threshold, a new frame is detected. This principle is widely

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used in the context of symbol timing synchronisation for OFDM transmission [1, 2, 3].

In this letter, we propose a suboptimal algorithm which simplifies the bit-correlator hardware implementation in a FPGA. The probability of false alarm ( $P_{\text{fa}}$ ) and the probability of nondetection ( $P_{\text{nd}}$ ) for both optimal and the proposed bit correlator are given.

## 2 Bit correlation

The exact match score  $c^e(n)$  for the  $n^{\text{th}}$  bit between the training sequence  $\text{seq}(k)_{k \in \{0, \dots, N-1\}}$  and the last  $N$  received bits of the sequence  $x(k)_{k \in \mathbb{N}}$  is defined in eq. (1) as the number of common bits.

$$c^e(n) = \sum_{k=0}^{N-1} \overline{\text{seq}(k) \oplus x(n-k)} \quad (1)$$

Let's denote  $b_k(n) = \overline{\text{seq}(k) \oplus x(n-k)}$  in the following discussion. If the bit rate is equal to the clock rate (i.e., a received bit at each clock cycle), the computation of  $c^e(n)$  requires typically a shift register of size  $N$  to store the sequence  $x(k)_{k \in \{n-N+1, \dots, n\}}$  [2]. Then, the  $b_k(n)$  values can be directly computed from eq. (2).

$$b_k(n) = \begin{cases} x(n-k) & \text{when } \text{seq}(k) = 1, \\ \overline{x(n-k)} & \text{when } \text{seq}(k) = 0. \end{cases} \quad (2)$$

Finally, a pipelined addition tree performs the summation of the  $N$  partial results. The summation result is then  $c^e(n)$ .

For the sake of simplicity, the sequence length  $N$  is assumed to be a multiple of 4. In order to implement efficiently the bit correlation function

described above onto a FPGA, the internal logic structure of the FPGA is taken into account. This structure consists of a set of 4-input/1-output Look-Up Tables (LUT) [4, 5]. This structure is found within FPGAs provided by the two companies representing about 90 % of the FPGA market [6]. To fully exploit the 4 inputs of a LUT, eq. (1) can be rewritten as in eq. (3)

$$c^e(n) = \sum_{k=0}^{\frac{N}{4}-1} f_k \left( x(n-4k), x(n-4k-1), \right. \\ \left. x(n-4k-2), x(n-4k-3) \right), \quad (3)$$

with  $f_k(i_0, i_1, i_2, i_3)$  defined in eq. (4).

$$f_k(i_0, i_1, i_2, i_3) = \sum_{l=0}^3 \overline{\text{seq}(4k+l) \oplus i_l}. \quad (4)$$

It can be noticed that each  $f_k$  is the sum of 4 binary values. Thus, they take their value between 0 and 4; 3 bits ( $f_k^2, f_k^1, f_k^0$ ) are required to code a value  $f_k$ :  $f_k = 4f_k^2 + 2f_k^1 + f_k^0$ . A direct implementation of  $f_k$  can be done using 3 LUTs to generate the bit values  $f_k^2, f_k^1$  and  $f_k^0$  directly from  $(i_0, i_1, i_2, i_3)$ .

Let  $p_e$  be the channel bit error probability and  $p_b$  the probability that bit  $b_k$  equals 0. When the received sequence  $x(k)$  is synchronised, the probability that bit  $b_k$  equals 0 is  $p_b = p_e$ . Otherwise,  $p_b$  equals 0.5. In fact, when not synchronised, at least  $P$  ( $P \in [1..N]$ ) bits of the last  $N$  received bits are random data not correlated with the training sequence. If  $P < N$ ,  $N - P$  bits are non synchronized bits from the training sequence and the partial match score of these  $N - P$  bits is in average around  $\frac{N-P}{2}$  (training sequences are generally chosen to have good auto-correlation properties). This partial score is also obtained for  $p_e = 0.5$ . As  $p_b$  and  $p_e$  can be seen as

equivalent, the probability of error will be denoted as  $p$  in the following.

The probability density function (p.d.f.) for the sum of 4 binary values is  $P(f_k = a) = \binom{4}{a} p^{4-a} (1-p)^a$  i.e.  $\{p^4, 4p^3(1-p), 6p^2(1-p)^2, 4p(1-p)^3, (1-p)^4\}$ . In the system functional domain, when synchronised,  $p$  is significantly lower than 0.5, otherwise  $p$  is around 0.5. Thus, when synchronised,  $P(f_k = 1) = 4p^3(1-p)$  can be considered as negligible compared to  $P(f_k > 1)$  and it is not useful to discriminate the cases where  $f_k$  is equal to 0 or 1. The function  $f'_k$  expressed in eq. (5) is chosen for implementation.

$$f'_k(i_0, i_1, i_2, i_3) = \max(0, f_k(i_0, i_1, i_2, i_3) - 1). \quad (5)$$

The new p.d.f. of  $f'_k$  is  $P(f'_k = 0) = P(f_k = 0) + P(f_k = 1)$  and  $P(f'_k = a) = P(f_k = a + 1)$  for  $a = 1, 2, 3$ . This function takes its value between 0 and 3: 2 bits  $f'_k{}^1$  and  $f'_k{}^0$  are needed to code the result. This function can be implemented using only 2 LUTs. This represents a significant lower complexity than the optimal solution. Note that the proposed approximated match score  $c^a(n)$  takes its value between 0 and  $\frac{3}{4}N$ .

### 3 Theoretical performance for the proposed implementation

The performance can be evaluated theoretically according to the bit error probability  $p$ . In the case of the exact computation, the p.d.f. of  $c^e$  is given by  $P(c_p^e = s) = \binom{N}{s} p^{N-s} (1-p)^s$ . In the case of the approximate function, the exact expression of the p.d.f. is complex to derive. Nevertheless, it is possible, for a given error probability  $p$ , to determine numerically its p.d.f. In fact,  $c^a$  is the summation of  $N/4$  random variable (r.v.). Thus its p.d.f. function is the convolution of the p.d.f of those r.v. In practice, the p.d.f.

of  $c^e$  is also obtained with the same method. Fig. 1 shows the p.d.f. for unsynchronised and synchronised input (with  $p = 0.3$  and  $N = 64$ ) for the exact and the approximated schemes.

A detection threshold  $s_t(p)$ , an integer between 0 and  $N$  or  $\frac{3}{4}N$ , defines whether or not a detection occurs. From such a threshold, probability of false alarm  $P_{\text{fa}}$  and probability of nondetection  $P_{\text{nd}}$  are defined in eq. (6) and eq. (7), respectively. The receiver operating characteristic (R.O.C.) can be derived from these expressions: Fig. 2 presents the R.O.C. drawn (with  $p = 0.35$ ) for the two schemes. The two R.O.C. do not show any significant difference. The two curves are modified in the same manner for any variation of  $p$ .

$$P_{\text{fa}}(p) = P(c_{0.5}(n) > s_t(p)) = \sum_{k=s_t(p)+1}^N P(c_{0.5}(n) = k) \quad (6)$$

$$P_{\text{nd}}(p) = P(c_p(n) \leq s_t(p)) = \sum_{k=0}^{s_t(p)} P(c_p(n) = k) \quad (7)$$

An optimal threshold is defined as expressed in (8). It varies with  $p$  and is different for each computation scheme.

$$s_t^o(p) = \max_{s_t} (P(c_p(n) = s_t) \leq P(c_{0.5}(n) = s_t)) \quad (8)$$

Fig. 3 collects the probability  $P_d$  of correct detection ( $P_d = 1 - P_{\text{nd}}$ ) and false alarm using  $s_t^o(p)$  as a function of  $p$ . The sequence length is  $N = 64$ . Once again, Fig. 3 does not show significant differences between the two computational schemes.

## 4 Implementation results

Both the exact and approximated correlations have been implemented with a FPGA Xilinx Virtex2-2000 [4]. For realistic implementation, the pseudo-random sequence is a CHU sequence [7] using a single precision bit for quantification. This well-known sequence is a CAZAC (Constant Amplitude Zero AutoCorrelation) sequence like the ones used in [8]. Typically, over a multiple path channel [9], with a detection threshold of  $\text{SNR} = 10$  dB,  $p_b$  is around 0.3 when synchronised and 0.5 when not synchronised. Over an additive white gaussian noise channel with the same detection threshold,  $p_b$  is around 0.05 when synchronisation is achieved and 0.5 when not.

The exact correlation core of Xilinx (Bit Correlator from the CORE Generator tool [10]) is used as a state of the art design (denoted as Ref.). A generic VHDL component implementing both exact and approximated correlator has been written: the final addition can be chosen as an optimized Carry-Save Adder (CSA) or a classical tree adder [11]. Table 1 presents the place&rout results (in term of logic (LUT), registers (DFF) and clock frequency) for the exact (reference, component with and without CSA) and approximated correlators (component with and without CSA). The targeted clock frequency is 280 MHz with no other specific timing constraint given. The implementation of the approximated scheme shows about 15 % (resp. 30 %) of lower complexity in term of LUT (resp. DFF) compared to the reference design, associated with a larger clock frequency of about 30 %.

## 5 Conclusion

We have proposed a suboptimal binary correlator algorithm which simplifies FPGA implementation. The decrease of complexity (compared to a state

of the art design) is around 15 % in LUT count, 30 % in register count and a better clock frequency without any noticeable performance degradations. Note that this decrease in complexity also involves a reduction of power consumption. Moreover, this method can easily be generalized. For example, if 5-input LUTs are available, the cases when  $f_k$  equals 0, 1 and 2 can also be aggregated. Finally, this method for aggregating least significant bits can also be efficiently applied by any ASIC designers.

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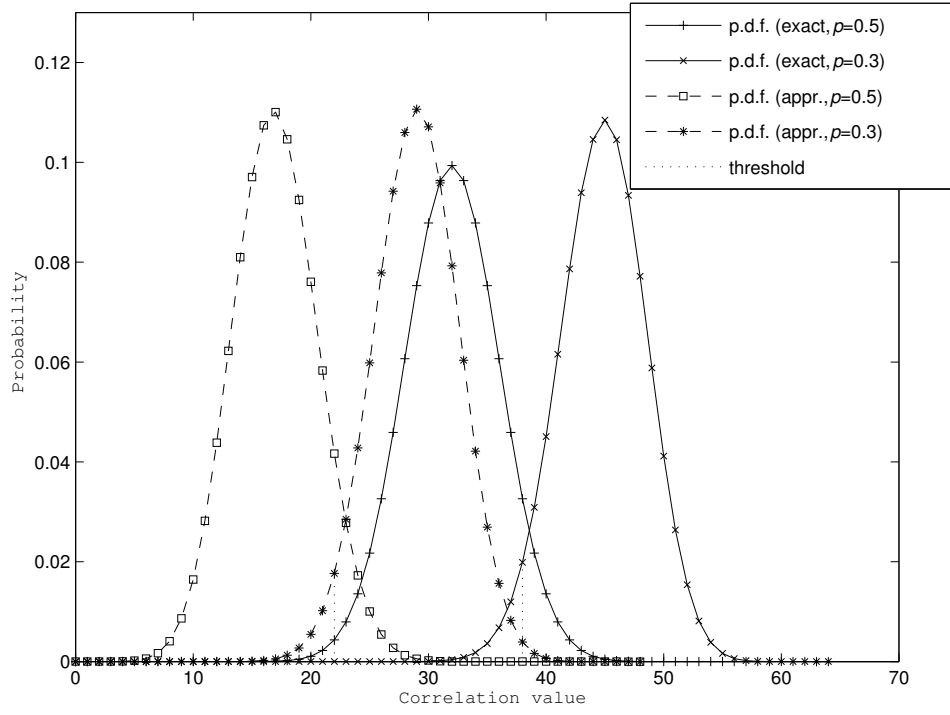


Figure 1: Probability density functions for both exact and approximated computation schemes for  $N = 64$ . P.d.f are represented for a nonsynchronised input ( $p = 0.5$ ) and a synchronised input with error probability  $p = 0.3$ . The thresholds defined in (8) are represented for the two schemes.

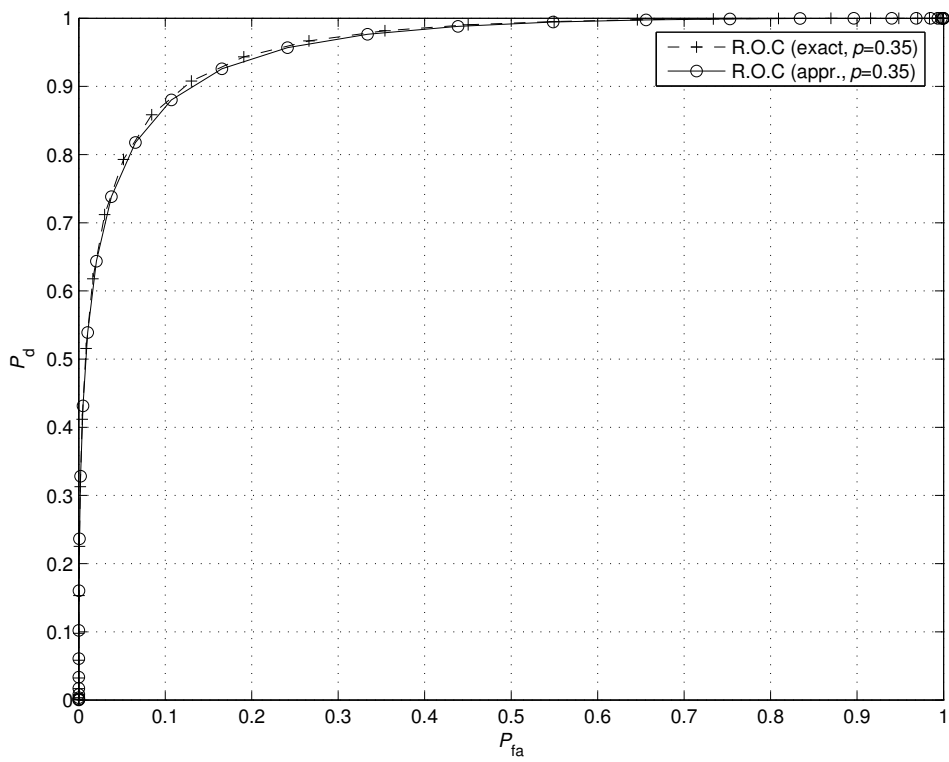


Figure 2: Receiver Operating Characteristics for the two computational schemes ( $N = 64$ ,  $p = 0.35$ ): probability of detection  $P_d = 1 - P_{nd}$  as a function of probability of false alarm.

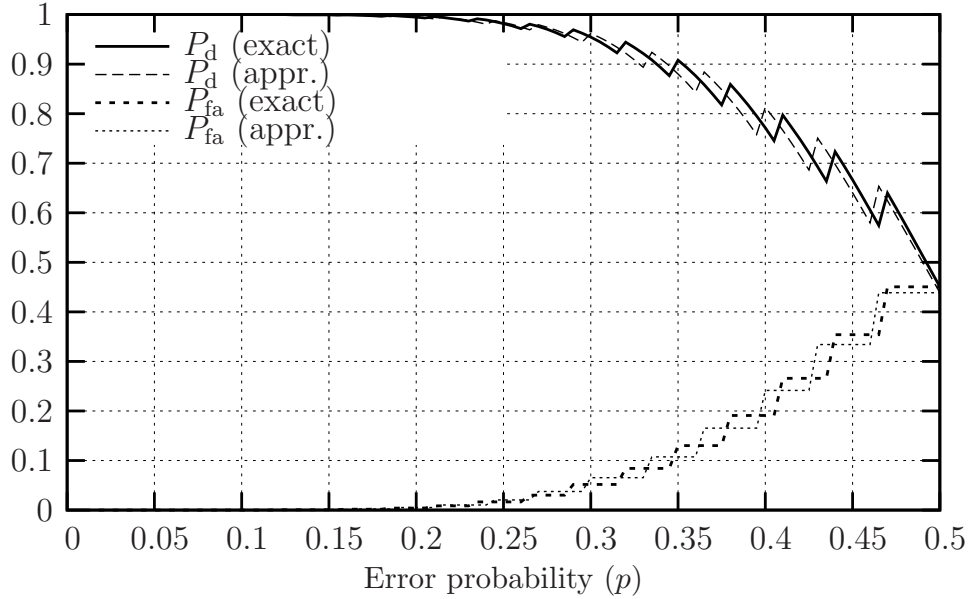


Figure 3: Probability of synchronisation as a function of the probability of error on the input sequence ( $N = 64$ ). Probabilities of correct detection ( $P_d$ ) decrease as  $p$  increases and probabilities of false alarm ( $P_{fa}$ ) increase with  $p$ .

Table 1: Implementation results on a Xilinx Virtex2-2000 for logic (LUT), registers (DFF) and clock frequency after place&route (MHz)

|           |     | Exact |      |     | appr. |     |
|-----------|-----|-------|------|-----|-------|-----|
|           |     | Ref.  | Add. | CSA | Add.  | CSA |
| $N = 256$ | LUT | 439   | 659  | 508 | 376   | 377 |
|           | DFF | 810   | 1003 | 794 | 493   | 540 |
|           | MHz | 219   | 214  | 272 | 231   | 281 |
| $N = 128$ | LUT | 216   | 325  | 252 | 185   | 185 |
|           | DFF | 396   | 493  | 397 | 239   | 271 |
|           | MHz | 219   | 210  | 281 | 253   | 281 |
| $N = 64$  | LUT | 105   | 159  | 124 | 90    | 89  |
|           | DFF | 190   | 239  | 210 | 113   | 133 |
|           | MHz | 280   | 265  | 281 | 285   | 285 |
| $N = 32$  | LUT | 50    | 76   | 60  | 43    | 42  |
|           | DFF | 88    | 113  | 103 | 51    | 63  |
|           | MHz | 286   | 280  | 283 | 283   | 287 |