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Quasi-random resamplings, with applications to rule extraction, cross-validation and (su-)bagging

Olivier Teytaud, Sylvain Gelly, Stphane Lallich, Elie Prudhomme May 17, 2006

## 1 Introduction

Resampling (typically, but not necessarily, bootstrapping) is a well-known stochastic technique for improving estimates in particular for small samples. It is known very efficient in many cases. Its drawback is that resampling leads to a compromise computational cost / stability through the number of resamplings. The computational cost is due to the study of multiple randomly drawn resamples. Intuitively, we want some more properly distributed resamples to improve the stability of resampling-based algorithms. Quasi-random numbers are a well-known technique for improving the convergence rate of data-based estimates. We here consider quasi-random version of resamplings. We apply this technique to BSFD, a data-mining algorithm for simultaneous-hypothesis-testing, to cross-validation, and to (su-)bagging, an ensemble method for learning. We present quasi-random numbers in section 2. We present bootstrap and a quasi-random version of bootstrap-sampling in section 3. We present experimental results in section 4.

## 2 Introduction to quasi-random numbers

If you are unlucky, random points can be distributed in a very non-uniform manner. Figure 1 (upper-left) is a pseudo-random independent sample (uniformly drawn in  $[0,1]^2$ ). Usually, you can not get by chance something as regular as other plots in figure 1. Therefore, in many areas of computer science, better-than-random points have been studied (integration [1], optimization [2], path planning [3], learning [4]). In order to generate and check uniform point-sets, a measure of uniformity is useful. Consider a point set  $x_1, \ldots, x_n$  in  $D = [0, 1]^d$ . An intuitive measure is  $\sup_{x \in D} \inf_{i \in [[1,n]]} d(x,x_i)$  (to be minimized), where d is some distance (e.g.  $L^{\infty}$  distance). Then, generating points as the lattice in figure 1 is easy, and it has been pointed out that for the criterion above, this is optimal for many values of the number of points ([3]). However, this point set is not satisfactory. For example, it would be nice that the projection on any axis of a good point set is a good point set. This is not the case for the

lattice in figure 1: the projection on some well-chosen axis leads to accumulations. Therefore, other criterions have been defined; the most well known is discrepancy. Among various discrepancies, the most well known is the following:  $\sup_{r\in D} \left|\frac{1}{n}Card\{i\in[[1,n]];\forall j(x_i)_j\leq r_j\} - \pi_{j\in[[1,d]]}r_j\right|$ . This formula has an immediate interpretation: it is the largest absolute difference between the area of a rectangle including 0 and the proportion of points in this rectangle. It is much more stable with respect to projection on an axis. However, it has various drawbacks (see [5]): (1) it only deals with rectangles with axis parallel to the canonical axis; (2) it only deals with rectangles; (3) it is not symmetric in the sense that the discrepancy of  $x_1, \ldots, x_n$  is not the discrepancy of  $1-x_1,\ldots,1-x_n$ ; (4) it is a worst case on r. The two first drawbacks are unclear drawbacks. Considering variables, in a non-rotation invariant manner, can be meaningful. The fourth drawback is probably the main trouble. Fortunately, extensions have already been defined. The main tool is the  $L^2$ -star-discrepancy:  $\sqrt{\int_{r\in D} \left(\frac{1}{n}Card\{i\in[[1,n]];\forall j(x_i)_j\leq r_j\}-\pi_{j\in[[1,d]]}r_j\right)^2}$ . This form of discrepancy (as well as others) verify inequalities similar to Koksma's inequality (see [5] on this topic). Many algebraic methods have been defined for generating sequences of points with low discrepancy ([1, 3, 6, 7, 8]). We here consider scrambled-Halton-sequences. We now define this quasi-random sequence. Consider p a prime number. The following sequence generates the  $n^{th}$  element  $x_{n,p} \in [0,1]$  of the Van Der Corput sequence [9] in basis p:

- write n in basis p:  $n = p_k p_{k-1} \dots p_1$ , i.e.  $n = \sum_{i=1}^k p_i p^i$  with  $p_i \in [[0, p-1]]$ ;
- $x_{n,p} = 0.p_1p_2...p_k$  in basis p, i.e.  $x_{n,p} = \sum_{i=1}^k p_i/p^i$ .

A classical improvement, termed scrambling consists in replacing this by  $x_{n,p} = 0.\pi(p_1)\pi(p_2)\dots\pi(p_k)$  where  $\pi$  is some permutation of  $0,1,\dots,p-1$ . The Halton sequence [10] generalizes the Van Der Corput sequence to dimension d. Consider  $p_i$  the  $i^{th}$  prime number. Then,  $x_n$ , the  $n^{th}$  element of a Halton sequence in dimension d, is  $x_n = (x_{n,p_1}, x_{n,p_2}, \dots, x_{n,p_d}) \in [0,1]^d$ . The scrambled-Halton sequence is the use of a randomly drawn permutation for each  $i \in [[1,d]]$ .

## 3 The applications of bootstrap in data mining and quasi-random bootstrap

Bootstrap has been first defined by Efron [11] and uniform versions appeared with the work of Giné and Zinn [12]. These works and many others are summarized in [13].

Often, we would like to know P, an unknown law of probability, but we only have a database which can be assumed i.i.d according to P. If this database is  $x_1, \ldots, x_n$ , the traditional notation is  $\hat{P}$  for the empirical measure, i.e.  $\hat{P} = \frac{1}{n} \sum_{i=1}^{n} \delta_{x_i}$ , where  $\delta_x$  is the Dirac measure located at x. A bootstrap sample consists in randomly drawing n elements, with replacement, among the  $x_i$ : for

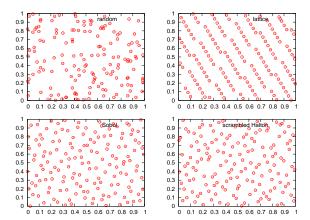


Figure 1: Random points, lattice points, Sobol points, scrambled-Halton points.  $i \in [[1, n]], x'_i$  is equal to  $x_{j_i}$ , where the  $(j_i)_{i \in [[1, n]]}$  are independent and uniform on [[1, n]]. We then note  $\widehat{\hat{P}} = \frac{1}{n} \sum_{i=1}^{n} \delta_{x'}$ .

on [[1,n]]. We then note  $\widehat{P} = \frac{1}{n} \sum_{i=1}^{n} \delta_{x_i'}$ . So, bootstrap is based on the replacement of a random variable that can not be simulated  $(\widehat{P})$ , the random part of which being the sampling) by one that can be simulated  $(\widehat{P})$ , the random part of which being the resampling). Simulating  $\widehat{P}$  is usually done in an i.i.d manner. However, there is a straightforward application of quasi-random numbers to this simulation. Precisely, we have to quasi-randomly draw the  $(x_1', \ldots, x_n')$ . Each  $x_i'$  is equal to  $x_{j_i}$  where the  $j_1, \ldots, j_n$  are i.i.d uniformly in [[1,n]]. Naively sampling the bootstrap distribution is therefore equivalent to:

- randomly draw  $z \in ]0,1]^n$ ;
- for  $i \in [[1, n]]$ , define  $x'_i = x_{i}$ , where  $j_i = [n \times z_i]$ .

With this formalism, a quasi-random version is straightforward: we only have to quasi-randomly draw the z in dimension n. Therefore, we can use a quasi-random sequence in dimension n, where n is the number of instances. Unfortunately, this naive approach does not work. The reason is that strongly redundant results can appear, as the result of the second line above is the same when ordinates of z are permuted. Well distributed z's do not lead to well distributed samples. Therefore, we define a better approach. The indices  $j_i$  are multinomially distributed. It is known that the multinomial distribution is still multinomial after the first components are observed. In algorithmic terms, this means that the following procedure works for generating correct bootstrap samples:

- randomly draw  $z \in ]0,1]^n$ ;
- set r = n (number of elements to be drawn in the database);
- for  $i \in [[1, n]]$ ,

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- define z_i' minimal such that P(binomial(r, 1/(n+1-i)) \le z_i') \ge z_i; - set r \leftarrow r - z_i'.
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• for  $i \in [[1, n]]$ , define the bootstrap sample such that  $x_i$  appears in the  $x'_j$  exactly  $z'_i$  times.

This generates independent bootstrap samples. We now just have to replace the random-drawing at the first line by a quasi-random sequence. Traditionally, the efficiency of quasi-random sequences is justified by Koksma-Hlawka's inequality. This inequality ensures a convergence in  $O(V \log(b)^n/b)$ , where n is the dimension, b is the number of quasi-random samples, and V is the total variation in the sense of Hardy & Krause. In many cases, the quasi-random method indeed works, whenever V is infinite. Here, we are in a nice case: V is finite. Let's formalize this claim:

Theorem: finiteness of the Hardy&Krause total variation Consider f any mapping  $[[0,n]]^n \to \mathbb{R}$ . Consider the following application  $\pi_f : z \mapsto f(z')$ ,  $\pi_f : [0,1]^n \to \mathbb{R}$ , where z' is defined as follows:

- set r = n (number of elements to be drawn in the database);
- $for i \in [[1, n]],$ 
  - $\ define \ z_i' \ minimal \ such \ that \ P(binomial(r,1/(n+1-i)) \leq z_i') \geq z_i;$
  - $set r \leftarrow r z_i'$ .

Then,  $\pi_f$  has finite total variation in the sense of Hardy&Krause. **Proof:**  $\pi_f$  is constant in each of finitely many hyperrectangles partitionning  $[0,1]^n$ . This is sufficient to imply the finiteness of the total variation.

Quasi-random points are often much more efficient than random points in low dimension, but quasi-random points must be adapted for huge dimension, in spite of strong improvements due in particular to scrambling. We need a dimension reduction. We perform this dimension reduction as follows for cases in which the dimensionality of the quasi-random sequence would be too high:

- group examples in the learning set in k clusters by k-means (including the label as supplementary ordinate);
- by quasi-random, choose the number of random draws in each of the k clusters,  $n_1$  examples in cluster  $1, \ldots, n_k$  examples in cluster k;
- then, randomly distribute the  $n_i$  examples among the examples in cluster i.

This method is inspired by [14] in a different context. It's likely that more sophisticated methods could be defined also. See [15] for particular cases of derandomization in huge dimension that might be helpful.

With random bootstrap-samples						
$V_0$	10	20	30	40	50	
1	0.17	0.13	0.12	0.04	0.09	
	E=0.73	E=0.55	E=0.49	E=0.53	E=0.55	
	std=0.00161	std=0.00184	std=0.00119	std=0.00121	std=0.00143	
2	0.15	0.24	0.27	0.19	0.22	
	E=1.38	E=1.79	E=1.37	E=1.61	E=1.48	
	std=0.00101	std=0.000751	std=0.000671	std=0.000958	std=0.000869	
3	0.24	0.26	0.18	0.23	0.28	
	E=1.99	E=2.85	E=2.19	E=2.47	E=2.25	
	std=0.000455	std=0.000559	std=0.000642	std=0.000610	std=0.000563	
4	0.03	0.3	0.23	0.26	0.21	
	E=2.97	E=3.99	E=3.18	E=3.46	E=3.1	
	std=0.000485	std=0.000702	std=0.000473	std=0.000350	std=0.000683	
5	0.16	0.38	0.17	0.34	0.22	
	E=3.97	E=5.14	E=4.16	E=4.44	E=3.99	
	std=0.000522	std=0.000597	std=0.000381	std=0.000468	std=0.000511	
6	0.1	0.37	0.31	0.3	0.3	
	E=4.62	E=5.95	E=5.24	E=5.63	E=4.92	
	std=0.000503	std=0.000330	std=0.000308	std=0.000281	std=0.000381	
With quasi-random bootstrap-samples						
	10	20	30	40	50	
1	0.18	0.15	0.09	0.09	0.08	
	E=0.73	E=0.66	E=0.47	E=0.65	E=0.61	
	std=0.00126	std=0.000872	std=0.000884	std=0.00102	std=0.000973	
2	0.17	0.23	0.28	0.27	0.24	
	E=1.45	E=1.73	E=1.39	E=1.77	E=1.55	
	std=0.000707	std=0.000688	std=0.000640	std=0.000653	std=0.000659	
3	0.25	0.28	0.16	0.2	0.29	
	E=2.06	E=2.89	E=2.21	E=2.43	E=2.4	
	std=0.000541	std=0.000551	std=0.000449	std=0.000433	std=0.000426	
4	0.06	0.33	0.23	0.24	0.21	
	E=2.96	E=3.97	E=3.19	E=3.44	E=3.2	
	std=0.000345	std=0.000433	std=0.000387	std=0.000333	std=0.000413	
5	0.16	0.37	0.15	0.33	0.27	
	E=4.03	E=5.16	E=4.28	E=4.59	E=4.1	
	std=0.000348	std=0.000300	std=0.000305	std=0.000296	std=0.000310	
6	0.08	0.34	0.34	0.3	0.28	
	E=4.53	E=5.86	E=5.41	E=5.63	E=5.02	
	std=0.000361	std=0.000293	std=0.000234	std=0.000240	std=0.000305	

is much lower in all but one case. Figure 2: Results of quasi-random-BSFD versus standard-BSFD. The variance

## 1 Experimental results

qrboutput.pdf. One can find there results about quasi-random-cross-validation detailed  $\operatorname{results}$ are available Ħ. http://www.lri.fr/~teytaud/

# 4.1 Results for information extraction

to be as close as possible to a risk  $\delta$  of selecting more than  $V_0$  type-I errors. based evaluation (thanks to BSFD [16]) of the selection threshold is based on 32 bootstrap-samples. The user provides  $\delta=0.25$  and  $V_0$ ; the goal of BSFD is the empirical probability of more than  $V_0$  false detections, when the bootstrap-(no detection). The table presents for each dimensionality and for 16 examples tracting variables with mean > 0; therefore the best answer is the empty answer normally distributed with variance one and mean 0. BSFD is applied for exof the tables of results, in the following setting: each variable is independent, We refer to the url above for full results; we here only present in Figure 2 one

## 4.2 Results for (su-)bagging with dimension-reduction

Bagging and subagging were applied in a setting detailed in http://www.lri.fr/~teytaud/qrboutput.pdf (18 examples, 25 bootstraps). A few results are presented in figure 3. The complete results in the url above show that QRBagging > Bagging > Weak learner, and QRSuBagging > SuBagging > Weak learner.

## 5 Conclusion

We experimented quasi-random-sequences of resamples. The standard quasi-random points in  $[[0,1]]^k$  could be used thanks to the decomposition of the multinomial law into k binomial laws. The convergence is faster and more stable, both theoretically and in various applications. As far as we know, it's the first time that quasi-random-sequences of bootstrap-samples and quasi-random-sequences of subsets are defined and applied.

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Mathad ( a standard	E			
Method (mean standard	Error rate ±			
deviation of output)	standard deviation			
199 runs, 320 examples (1/5-4/5), dim 2				
SuBaggingDecStump (0.137097)	$0.110062 \pm 0.065750$			
SuBaggingQRDecStump8 (0.123100)	$0.097637 \pm 0.048096$			
SuBaggingQRDecStump4 (0.125160)	$0.103565 \pm 0.058860$			
SuBaggingQRDecStump2 (0.125882)	$0.101170 \pm 0.054242$			
BaggingDecStump (0.079022)	$0.164514 \pm 0.121832$			
BaggingQRDecStump5 (0.074899)	$0.154719 \pm 0.123209$			
BaggingQRDecStump4 (0.073276)	$0.159332 \pm 0.122726$			
BaggingQRDecStump2 (0.073361)	$0.158154 \pm 0.119545$			
BaggingQRDecStump8 (0.074814)	$0.159293 \pm 0.121817$			
199 runs, 320 examples (1/5-4/5), dim 4				
SuBaggingDecStump (0.136094)	$0.148673 \pm 0.066784$			
SuBaggingQRDecStump8 (0.128807)	$0.136267 \pm 0.061232$			
SuBaggingQRDecStump4 (0.127693)	$0.137092 \pm 0.060400$			
SuBaggingQRDecStump2 (0.128570)	$0.140036 \pm 0.063278$			
BaggingDecStump (0.078661)	$0.164632 \pm 0.121136$			
BaggingQRDecStump5 (0.075725)	$0.158704 \pm 0.120155$			
BaggingQRDecStump4 (0.074121)	$0.159685 \pm 0.121453$			
BaggingQRDecStump2 (0.074604)	$0.165162 \pm 0.120381$			
BaggingQRDecStump8 (0.075216)	$0.161334 \pm 0.122183$			
199 runs, 1280 examples (1/5-4/5), dim 2				
SuBaggingDecStump (0.098132)	$0.034690 \pm 0.018896$			
SuBaggingQRDecStump8 (0.091579)	$0.033336 \pm 0.017868$			
SuBaggingQRDecStump4 (0.091416)	$0.031559 \pm 0.015501$			
SuBaggingQRDecStump2 (0.093533)	$0.032025 \pm 0.016090$			
BaggingDecStump (0.070920)	$0.035691 \pm 0.078878$			
BaggingQRDecStump5 (0.066053)	$0.022584 \pm 0.060712$			
BaggingQRDecStump4 (0.064879)	$0.029012 \pm 0.071060$			
BaggingQRDecStump2 (0.066117)	$0.026701 \pm 0.067174$			
BaggingQRDecStump8 (0.065024)	$0.028399 \pm 0.068832$			
199 runs, 1280 examples (1/5-4/5), dim 4				
SuBaggingDecStump (0.099501)	$0.041349 \pm 0.027841$			
SuBaggingQRDecStump8 (0.092640)	$0.038277 \pm 0.024346$			
SuBaggingQRDecStump4 (0.092366)	$0.036368 \pm 0.018317$			
SuBaggingQRDecStump2 (0.092609)	$0.036520 \pm 0.017937$			
BaggingDecStump (0.071598)	$0.030308 \pm 0.072339$			
BaggingQRDecStump5 (0.064187)	$0.025577 \pm 0.065089$			
BaggingQRDecStump4 (0.067099)	$0.029601 \pm 0.072861$			
BaggingQRDecStump2 (0.070020)	$0.024110 \pm 0.062809$			
BaggingQRDecStump8 (0.066850)	$0.025391 \pm 0.064964$			
- GG - G - Q - C - C - C - C - C - C - C - C - C				

Figure 3: Results for bagging and subagging.

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