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A FULLY DISTRIBUTED PRIME NUMBERS GENERATION USING THE WHEEL SIEVE

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ABSTRACT

This article presents a new distributed approach for generating all prime numbers up to a given limit. From Eratosthenes, who elaborated the first prime sieve (more than 2000 years ago), to the advances of the parallel computers (which have permitted to reach large limits or to obtain the previous results in a shorter time), prime numbers generation still represents an attractive domain of research. Nowadays, prime numbers play a central role in cryptography and their interest has been increased by the very recent proof that primality testing is in P. In this work, we propose a new distributed algorithm which generates all prime numbers in a given finite interval $[2, ..., n]$, based on the wheel sieve. As far as we know, this paper designs the first fully distributed wheel sieve algorithm.

KEY WORDS

Distributed algorithms, prime numbers generation, wheel sieve, broadcast and leader election.

1 Introduction

We address the generation of prime numbers smaller than a given limit n, by using the *wheel* sieve in a distributed way. *Wheel* sieve algorithms can be very efficient to determine the primality of integers which belong to a given finite interval, for sufficiently large values of n and when the test of primality is carried out on all numbers of the interval.

The main purpose of parallelization of such a kind of algorithms is to increase the limits of the sequential generation of prime numbers, or to reach the previous limits in a lower execution time. The first parallelization of a sieve algorithm was realized in 1987 [1]. In this latter work, the reason to employ the Eratosthenes'sieve was to test a new parallel machine (the Flex/32). In fact, this challenging algorithm is relevant as a benchmark to test the performance of any new proposed architecture, mainly due to its intensive use of resources. This way, the proposed performances of the new architecture can be validated.

The sieve of Eratosthenes was the first sieve algorithm and it consists in eliminating all non prime numbers in the interval $[2, ..., n]$. To start, the algorithm takes the first number of the interval and generates all its multiples (by adding its own value to itself), which are eliminated. The next number (i.e., the first number that has not been eliminated) is the next prime which will sieve again the same interval, and so on until obtaining a prime number $> \sqrt{n}$. We can find another parallelization of this algorithm in [2], that was implemented in a distributed way, in a "master/slave" framework where each slave executes in a symmetrical manner (the same code [3]) on an interval of data to be sieved, and where these intervals are distributed by the master process. The way the parallelization was made in this case is similar to the implementation of [1], that was realized on a parallel machine (Flex/32) and not on a distributed system (distributed memory).

In any case, the main drawback of the practical sieve of Eratosthenes is clearly the fact that it imposes to go through all the entries of the multiples of each number during the sieving process. For instance, if the current entry corresponds to p , then any entry at locations $2p$, $3p$, $4p$ is changed to zero, and so on, until we reach the criterion of stop, i.e., $p^2 > n$. The basic sieve of Eratosthenes proceeds in the same way on any other entry. We can easily see that some numbers will be generated more than once, for example 6 is "generated" twice (from 2 and 3), and so is 12 (from 2 and 3). The entries that are already zeros are left unchanged. Nevertheless, each entry must be checked throughout the sieving process. Figure 1 illustrates this flaw.

Thus, the main idea of the algorithm consists in trying to prevent all numbers from being sieved "too many times". Sieving the multiples of any given number more than once must be avoided, as much as possible. All efficient sieving algorithms are based on similar techniques. The complexity (in steps) $O(n \ln \ln n)$ of the sieve of Eratosthenes may be somewhat reduced exploiting several clever arguments that are carried out by the above methods. Such sieve algorithms improve the complexity of Eratosthenes and achieve a linear [4, 5, 6] or even a sublinear (step) complexity [5, 7]. So far, the best algorithm known is the "wheel sieve", designed in 1981 [7, 8]. It requires only $O(n/\log \log n)$ steps to find the set of primes in the interval $[2, ..., n]$ (with $n > 4$). Basically, the algorithm relies on the central result about the number of primes in arithmetic progressions. More precisely, Dirichlet's theorem states that if a, b are coprime integers $((a, b) = 1)$ and $b > 0$, then the arithmetic progression $\{a, a+b, a+2b, \ldots\} = \{a \mod (b)\}\)$ contains infinite primes (see [9, Thm. 15]). See [10] for more details on the analysis of the "wheel sieve" algorithm.

Figure 1. Example of some numbers being eliminated more than once.

The present paper introduces a new distributed algorithm that finds all primes by sieving a given interval [1, ..., n], using the properties of the *wheel* sieve [8]. Some other distributed algorithms to generate all prime numbers can be found in [11, 12], which are based on the properties of the Dirichlet's theorem. In our work we employ the wheel sieve, as like in [2], where we proceeded to the first distribution of the *wheel sieve*, using a master process in order to coordinate the iterations of the remaining processes. This first distribution was implemented using a message passaging interface specification *lam-mpi library* [13] and the results (runtime execution) were compared with a sequential implementation of the *wheel sieve* and with a distributed and a sequential implementations of the Eratosthenes's sieve [2]. The main contribution of the new distribution of the *wheel sieve* algorithm presented here, is the fact that we elaborated a completely distributed version (without coordinator process), using the leader election algorithm at each iterations. In [14] we can find another kind of distributed prime numbers generation, based on the scheduling by multiple edge reverse framework [15], that is a completely new kind of generation of prime numbers and employs just comparisons and reversals of arcs on the multigraph used by the algorithm.

This article is organized as follows: in the next section we introduce the *wheel* sieve, section 3 is devoted to the design of our distributed algorithm and the final section draws a short conclusion and offers some perspectives.

2 Wheel Sieve

The *wheel* sieve algorithm was derived from a previous algorithm [7], and consists basically in generating a set of numbers that are not multiple of the first k prime numbers, this is the idea of the *wheels* [8] and was employed by computational number theorists for some time as in the trialdivision routines [16]. The sieve (applied on the resulting set from the wheel) eliminates the non prime numbers that remain in the set.

We define by Π_k , the multiplication of the first k prime numbers, and by W_k the k-th *wheel*. W_k is defined as $\mathcal{R}(\Pi_k)$, where $\mathcal{R}(x) = \{x \mid 1 \leq y \leq x \text{ and gcd }$ $(y, x) = 1$, where gcd stands for greatest common divisor. The sieve introduced by the *wheel* sieve consists basically, after having generated the next *wheel* W_{k+1} , in using the prime number $k + 1$ to sieve the new *wheel*, generating all its multiples and removing them from W_{k+1} , for purposes of clarity we will call this new set as S_{k+1} . It is clear that after that we obtained the S_{k+1} we will proceed to another sieving process, to eliminate the remaining composite numbers.

We can see that *wheels* are patterns that are repeated every Π_k times. In figure 2, we use $\Pi_2 = p_1 \cdot p_2 = 6$, that corresponds to the multiplication of the two first prime numbers, 2 and 3 (Π_k is the length of the current *wheel* W_2). We can, using Π_2 , generate all "quasi-prime" numbers (numbers that are not multiples of the first k prime numbers.), between 1 and the new limit Π_3 . Firstly, we proceed to obtain the next Π_k , that is $\Pi_3 = \Pi_2 \cdot p_3 = 30$, this is the new limit of the new wheel ($\mathcal{W}_3 = \mathcal{R}(30)$, represented by the big circle in figure 2). The next prime is the first number obtained after the number 1, which belongs to the interval being sieved. So, in the second wheel (that's used to generate the third wheel), the next prime number (p_{k+1}) has now a value equals to 5 [8].

Figure 2. Example of the generation of a *wheel* (W_{k+1}) starting from the precedent *wheel*. (W_k)

We have
$$
\mathcal{W}_{k+1} = \mathcal{W}_k \cup \{x \cdot \Pi_k + y | x \in
$$

 $\{1, ..., p_{k+1}-1\}$ and $y \in W_k$ [8]. We can see in figure 3, using the small *wheel*, the generation of all "quasi-prime" numbers of the big wheel, that will result in the new wheel, a set composed by $\{1, 5, 7, 11, 13, 17, 19, 23, 25, 29\}$. In figure 4 the procedure of generation of the big *wheel* goes on and the number 7 is generated from the number 1 of the small *wheel*. We can interpret this (in a geometrical abstraction) as if we were "rolling" the small circle inside the big one. Starting from a wheel W_k , we can generate the next one (W_{k+1}) in a graphical way. The points where the elements of the *wheel* W_k touch the W_{k+1} circle are the new "pseudo-primes". In figure 4 we can see the moment where the number 7 is included in the new *wheel* from the number 1 of the precedent *wheel* (W_2) [8].

Figure 3. Generation of the new "quasi-prime" numbers.

Figure 4. Here we can see another new "quasi-prime" number (number 7 been generated from the precedent wheel).

The figure 5 shows the final phase of the wheel sieve, where the multiples of the previous p_{k+1} (in this example, the number 5) are eliminated from $\mathcal{R}(\Pi_3)$ set. Using the precedent definition of W_{k+1} , we define S_{k+1} = $\mathcal{W}_k \cup \{x \cdot \Pi_k + y \mid, x \in \{1, ..., p_{k+1} - 1\} \text{ and } y \in \mathcal{W}_k\}$ ${p_{k+1}.y \mid y \in \mathcal{W}_k}$. In [8] (using its geometrical abstraction), the previous wheel (W_k) is put in the middle of the new wheel (their centers coincide) (\mathcal{W}_{k+1}) – See figure 5. Afterwards, drawing a radius from the center of the small circle passing on each "pseudo-prime" number of this circle, their prolongation will touch the big circle at every "pseudo-prime" that will be eliminated in the new wheel \mathcal{W}_{k+1} .

Figure 5. The sieve being applied on the new wheel (W_{k+1}) to generate the S_{k+1} .

In [2] we present the first distributed version of the wheel sieve, that was implemented using a message passaging interface specification (*lam-mpi 7.0.6 library*[13]), the computation times are compared between a sequential and a distributed implementation of the wheel sieve and with a sequential and a distributed implementation of the Eratosthenes's Sieve. This distributed algorithm is quite different from the one of the next section, in the sense that the previous distributed implementation of the wheel sieve uses a master process which coordinates the activities of the others processes, this is due (in part), because it was the solution found to obtain the next prime (p_{k+1}) number among each process sieving the interval. Each process (or "slave"), after having generated all its new "quasi-prime" numbers (employing for that, just additions – with the value of Π_k), sends its lower number to the coordinator, that sorts the numbers received (in a decreasing order) and generates all multiples $<\Pi_{k+1}$ of p_{k+1} .

In the implementation [2], we start with 8 processes, each of them being associated with a number of the set $W_3 = \{1, 7, 11, 13, 17, 19, 23, 29\}$. In a first step, the master process sends the Π_k , $p_{k+1} = 7$ (for this configuration) and the new limit $(\prod_{k+1}$ or n) to each slave. Each process receiving these values, proceeds to the generation of the next "quasi-primes" numbers (the next wheel W_{k+1}), and transmits its multiples (of p_{k+1} less than or equal to a given limit n or Π_k) to the master process, which is responsible of the transmission of these numbers to the "slave" processes. Each process (apart the master process) proceeds to the elimination of these multiples of their sets of "quasiprimes" numbers. Finally, they transmit their first number of their local list of "quasi-prime" numbers to the "master" process (except the process which has the value 1 which transmit the second value of his set), which sort all values to determine the next prime number (p_{k+1}) , which is sent to the remainder processes which generate the next limit of the new wheel (Π_{k+1} of the W_{k+1}). The "master process" is also charged of finalizing the execution of the algorithm.

The research of a completely (fully) distributed version of the wheel sieve brings us to a completely new proposal of distribution of this algorithm, that will be introduced in the next section.

3 The Distributed Wheel Sieve Algorithm

To create a fully distributed version of the wheel sieve algorithm, we suppose that the procedure that is introduced below (named Distributed-Wheel-Sieve) is designed for any process, i.e., it is executed in a symmetrical way [3, 17]. This procedure uses some local variables that are defined more precisely as follows:

- $PseudoPrime$ denotes the number that the processor (or process) has been attributed, which is initially set to an exclusive value in {1, 7, 11, 13, 17, 19, 23, 29}, for example, if we employ the third wheel \mathcal{W}_3 as first wheel in the algorithm.
- $Neigh_{PseudoPrime}$ denotes the set of neighbors of every PseudoPrime, which consists in all others processes (if we represent the processes by the nodes of a graph, this graph would be a complete graph).
- $NextPrime$ is the value in the current set of numbers being sieving, which will corresponds to the next prime. It will be used to generate the value of the NewLimit variable, which represents the bound of generation of the $PseudoPrime$ numbers, by each element (process) of the wheel sieve, its first value attributed is 7.
- Every new created process will attribute to the $Child$ variable, the value of its $PseudoPrime$ plus the value of the Π_k variable.
- Every member of the *wheel* sieve generates its multiple (Multiple) and broadcasts its value for each one of its neighbors (members $\in Neigh_{PseudoPrime}$ set).

We employed in the algorithm described here, two pseudo-commands (**Fork** and **Self termination**), that consist for the first one in the creation of a new process with $PseudoPrime$ value = $Child + \Pi$ and that inherits all others values from the father process. The second one is used when a process notes that it has as value $(PseudoPrime)$ the same one that it had received, and for this reason, it stops its participation in the algorithm.

The other local variables have their functionality selfexplaining in the procedure.

```
Procedure Distributed-Wheel-Sieve(n)
var
    \Pi = 30:
    End: boolean init false;
    NextPrime = 7;NewLimit = 0;Child = 0;Multiple = 0;PseudoPrime<sub>Neigh</sub> = 0;Begin
    While not End
         NewLimit = \Pi \times NextPrime;If NewLimit > n Then
              NewLimit = n;EndIf
         GeneratingChildren(Child,NewLimit);
         Multiple = PseudoPrime \times NextPrime;If Multiple ≤ NewLimit Then
              Broadcast Multiple to
                   Neigh_{PseudoPrime};EndIf
         receive Multiple from Neigh_{PseudoPrime};
         If Multiple = PseudoPrime Then
              Self termination;
         EndIf
         NewPrimeElection(PseudoPrime);
         receive PseudoPrime
              from Neigh_{PseudoPrime};If NextPrime^2 > n Then
              End = true;EndIf
    EndWhile
end.
```

```
GeneratingChildren(Child,NewLimit)
```
While $Child \leq NewLimit$ **Fork**(Child); $Child = \Pi + PseudoPrime;$ **EndWhile**

NewPrimeElection(PseudoPrime)

If $PseudoPrime \neq 1$ **Then Broadcast** PseudoPrime **to** $Neigh_{PseudoPrime};$ **receive** $PseudoPrime$ **from** $Neigh_{PseudoPrime}$; **If** $PseudoPrime < (all)PseudoPrime_{Neigh}$ **Then** $NextPrime = PseudoPrime;$ **Broadcast** NextPrime **to** $Neigh_{PseudoPrime};$

EndIf

EndIf

As said above, initially there are eight processes which have as values the numbers

 $\{1, 7, 11, 13, 17, 19, 23, 29\}.$ These values represent the "quasi-prime" numbers of the third *wheel*. Beginning with these values (we consider that at the beginning, each process knows its identity – $PseudoPrime$.), each process generates the new "pseudo-prime" numbers, adding the value of the Π_k variable to its $PseudoPrime$ variable. Each new generated "quasi-prime" number is attributed to a new process, by the command **Fork**.

The next step consists in generating the multiples of the "next prime (p_{k+1}) " number, denoted by the variable $NextPrime$. Each process multiplies its value (*P seudoPrime*) by the p_{k+1} , the generated multiple (which verifies $Multiple \leq \prod_k$) is broadcasted to the others processes, which compare the received value to their own value ($PseudoPrime$). If they have the same value, they stop their participation in the algorithm (what we call "**Self termination**").

The last step of the main loop is a leader election, where the winner process is the one which has the lower value greater than one, which will be the "next prime" (p_{k+1}) number. The process which has this value, broadcasts the same to all processes participating of the *wheel* sieve. To complete, every process will test if the variable $NextPrime > \sqrt{n}$ (this value is received after the leader election); if the result of this comparison is true, the process proceeds to its termination, attributing the value true to its End variable.We can easily verify that at this point, all processes will finish their participation in the *wheel* sieve algorithm.

As an example, suppose that we start with two processes, with values equal to $\{1, 5\}$ (values of the "quasiprime" numbers) in the second *wheel*). As we can see, the variable $NextPrime$ will have affected the value 5, which represents the next prime number. The NewLimit value will be equal to 30 ($\Pi_k \cdot p_{k+1}$); with these values, each process can start the generation of its children, by a call to the procedure **GeneratingChildren()**. Each new generated process will inherits all values from its father process, Π_k , $NewLimit$ and p_{k+1} . In figure 6, we can see the values generated by each process of the *wheel* W_2 . In the next step, each process will generate its multiple $(< n)$ and broadcast the same for all its neighbors. We can consider here that if a process doesn't have a value less than n , it can broadcast the value equals to *NULL*, for example and by this way, we'll have a synchronization where each process will receive a message, and if the element received has the same value that its $PseudoPrime$ variable, its participation to the algorithm will be end.

We suppose that every new process will start its execution just after its creation; then, the next step is a call of the procedure **NewPrimeElection()**, where the least value (bigger than 1) will be the next prime number (p_{k+1}) ; once again, if the process has as value the number 1, it can send a message with a *NULL* value, for example. The process that has this value will broadcast the same to all elements \in $Neigh_{PseudoPrime}$, and test the termination of the algorithm (when $NextPrime^2 > n$). At this point, all pro-

Figure 6. Generation of the children of every process.

cesses will have their participation on the algorithm ended, and the list with all prime numbers $\leq n$ will be returned as output.

4 Conclusion

We have presented a new distributed algorithm to sieve a set of integers, resulting in the set of all prime numbers less than a given value n . It is the first fully distribution of the wheel sieve algorithm, and it uses an election leader distributed algorithm to this end. The proposed algorithm was implemented using *lam-mpi* [13] on a cluster of computers, and we expect briefly to investigate more experiments to validate the efficiency of this new distributed algorithm, compared to the precedent implementation of the *wheel* sieve algorithm (sequential and distributed) [2].

Another fundamental point to be investigated, is the analysis of this distributed algorithm, with respect to the number of messages, required memory spaces and steps. By this way, we will be able to establish, in a theoretical approach, what are the exact differences between the sequential and the proposed algorithms.

One direction in which the research described in this paper can be extended would be the search of some intrinsics properties of prime numbers theory to try to derive a new prime numbers generator with some refinements.

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