Quadratic functional estimation in view of minimax goodness-of-fit testing from noisy data
Cristina Butucea

To cite this version:
Cristina Butucea. Quadratic functional estimation in view of minimax goodness-of-fit testing from noisy data. 2004. hal-00002985

HAL Id: hal-00002985
https://hal.science/hal-00002985
Preprint submitted on 30 Sep 2004
Quadratic functional estimation in view of minimax goodness-of-fit testing from noisy data

C. BUTUCEA

SEPTEMBRE 2004

Prépublication n° 936

Laboratoire de Probabilités et Modèles Aléatoires, CNRS-UMR 7599, Université Paris VI & Université Paris VII, 4, place Jussieu, Case 188, F-75252 Paris Cedex 05.

&

Modal’X, Université Paris X, 200 avenue de la République, F-92001 Nanterre Cedex.
Quadratic functional estimation in view of minimax goodness-of-fit testing from noisy data

Cristina Butucea

1 Laboratoire de Probabilités et Modèles Aléatoires (UMR CNRS 7599), Université Paris VI, 4, pl. Jussieu, Boîte courrier 188, 75252 Paris, France

2 Modal’X, Université Paris X, 200, avenue de la République 92001 Nanterre Cedex, France, e-mail: butucea@ccr.jussieu.fr

Abstract

We consider the convolution model \( Y_i = X_i + \varepsilon_i, \ i = 1, \ldots, n \) of i.i.d. random variables \( X_i \) having common unknown density \( f \) are observed with an additive i.i.d. noise, independent of \( X_i \)'s. We assume that the density \( f \) belongs to a smoothness class, has a characteristic function described either by a polynomial \(|u|^{-\beta}, \beta > 1/2 \) (Sobolev class) or by an exponential \( \exp(-\alpha|u|^r) \), \( \alpha, r > 0 \) (called supersmooth), as \( |u| \to \infty \). The noise density is supposed to be known and such that its characteristic function decays either as \(|u|^{-s}, s > 0 \) (polynomial noise) or as \( \exp(-\gamma|u|^s) \), \( s, \gamma > 0 \) (exponential noise), as \( |u| \to \infty \).

We study the problems of estimating the quadratic functional \( \int f^2 \) and use this estimator for the goodness-of-fit test in \( L_2 \) distance, from noisy observations, in all possible combinations of the previous setups.

We construct an estimator of \( \int f^2 \) based on the deconvolution kernel. When the unknown density is smoother than the noise density, we prove that this estimator is \( n^{-1/2} \) consistent, asymptotically normal and efficient (for the variance we compute). Otherwise, we give nonparametric minimax upper bounds for the same estimator. For the goodness-of-fit test, we prove minimax upper bounds for a test statistic derived from the previous estimator. Surprisingly, in the case of supersmooth densities and polynomial noise we obtain parametric \( n^{-1/2} \) minimax rate of testing.

Finally, we give an approach unifying the proof of nonparametric minimax lower bounds. We prove them for Sobolev densities and polynomial noise, for Sobolev densities and exponential noise and for supersmooth densities with exponential noise such that \( r < s \). Note that in these last two setups we obtain exact testing constants associated to the asymptotic minimax rates.

Mathematical Subject Classification 62F12, 62G05, 62G10, 62G20,

Keywords Asymptotic efficiency, convolution model, exact constant in nonparametric tests, goodness-of-fit tests, infinitely differentiable functions, quadratic functional estimation, minimax tests, Sobolev classes.
1 Introduction

We consider the convolution model,
\[ Y_i = X_i + \varepsilon_i, \; i = 1, \ldots, n \]  \hspace{1cm} (1)
where all observations are independent. We denote the common unknown density of \( X_i, \; i = 1, \ldots, n \) by \( f \), having given smoothness. Let \( \Phi(u) = \int e^{iux} f(x) dx \) denote its characteristic function. We observe only the \( Y_i, \; i = 1, \ldots, n \). The noise is supposed i.i.d. having known probability density \( g \).

We consider the following nonparametric classes for the underlying density, which is always supposed to belong to \( L_1 \cap L_2 \). A Sobolev class is defined by
\[ W(\beta, L) = \left\{ f : \mathbb{R} \to \mathbb{R}_+, C^\beta, \text{density function}, \int |\Phi(u)| |u|^\beta du < \infty, \right. \] \[ \left. \frac{1}{2\pi} \int |\Phi(u)|^2 |u|^{2\beta} du \leq L \right\}, \] (2)
with the smoothness \( \beta > 1/2 \) and radius \( L > 0 \).

A class of supersmooth densities is defined by
\[ S(\alpha, r, L) = \left\{ f : \mathbb{R} \to \mathbb{R}_+, C^\infty, \text{density function}, \int |\Phi(u)|^2 \exp(2\alpha|u|^r) du \leq L \right\}, \] for \( \alpha, r, L \) positive constants.

Classes \( S(\alpha, r, L) \) of infinitely derivable functions appeared e.g. in Lepski and Levit [24]. Note that for \( r > 1 \) these are analytic functions, for \( r = 1 \) they are analytic on a strip of size \( 2\alpha \) around the real axis.

Let the noise be i.i.d. with probability density \( g \) and characteristic function \( \Phi^g \) and the resulting observations have common density \( p = f \star g \) and characteristic function \( \Phi^p = \Phi \cdot \Phi^g \). We also consider noise having non null Fourier transform, \( \Phi^g(u) \neq 0, \forall u \in \mathbb{R} \). Typically two different behaviours are distinguished in nonparametric estimation:

- **Polynomially smooth** (or polynomial) noise
  \[ |\Phi^g(u)| \sim |u|^{-s}, \; |u| \to \infty, \; s > 1; \] (4)

- **Exponentially smooth** (or supersmooth or exponential) noise
  \[ |\Phi^g(u)| \sim \exp(-\gamma |u|^s), \; |u| \to \infty, \; \gamma, s > 0. \] (5)

We consider here nonparametric minimax goodness-of-fit tests from noisy data, that is for a given density \( f_0 \) in the smoothness class \( W(\beta, L) \), respectively \( S(\alpha, r, L) \), decide whether
\[ H_0 : f = f_0 \]
\[ H_1(C, \psi_n) : f \text{ in the smoothness class}, \|f - f_0\|^2 \geq C\psi_n^2, \]
from observations \( Y_1, \ldots, Y_n \), for some fixed \( C > 0 \) and \( \psi_n > 0 \).
**Definition 1** For a given $0 < \gamma < 1$, a test statistic $\Delta_n^*$ is said to attain the testing rate $\psi_n$ over the smoothness class if there exists $C^* > 0$ such that

$$\limsup_{n \to \infty} \left\{ P_{\theta_0}[\Delta_n^* = 1] + \sup_{f \in \mathcal{H}_1(C, \psi_n)} P_f[\Delta_n^* = 0] \right\} \leq \gamma,$$

for all $C > C^*$. The rate $\psi_n$ is called minimax rate of testing, if there exists $C_* > 0$ and

$$\liminf_{n \to \infty} \inf_{\Delta_n} \left\{ P_{\theta_0}[\Delta_n = 1] + \sup_{f \in \mathcal{H}_1(C, \psi_n)} P_f[\Delta_n = 0] \right\} \geq \gamma,$$

for all $0 < C < C_*$, where the inf is taken over all test procedures $\Delta_n$.

Moreover, if $C^* = C_*$ we call $\psi_n$ exact (or sharp) minimax rate of testing.

We recall that the usual procedure is to construct the test statistic $\Delta_n^*$ such that (6) holds, also called the upper bound of the testing rate and then prove the minimax optimality of this procedure, i.e. the lower bounds in (7). If the test procedure does not depend on the smoothness of the unknown functions (which may vary in some interval), it is called adaptive to the smoothness and $\psi_n$ is minimax adaptive rate.

In the convolution model (1), the problem of nonparametric estimation of deconvolution density $f$ was intensively studied over the past two decades. Densities belonging to Hölder or Sobolev classes are known to be estimated at reasonably fast rates when mixed with polynomial noise and logarithmic, slow rates when mixed with exponential noise (see Carroll and Hall [7], Fan [11], [12] and [13], etc.).

Classes of supersmooth densities were first considered in the convolution model by Pensky and Vidakovic [31], who computed rates of convergence, adaptive to the smoothness, of wavelets estimators and noticed that faster rates can still be expected in this problem. Comte and Taupin [8] used model selection for adaptive estimation of the deconvolution density. Rate minimax optimality of a kernel estimator and lower bounds for the pointwise risk over such classes was proven by Butucea [4] for polynomial noise (and nearly parametric rate) and optimality in the rate and in the constant in the case $r < s$, by Butucea and Tsybakov [6], for exponential noise.

In this paper, in order to surpass difficulties of estimation we address different issues and principally the goodness-of-fit test from noisy data in $L_2$ norm. To our knowledge this is the first time testing was performed from data contaminated with errors. Minimax and adaptive theory of testing was extensively developed in density model when direct observations are available, but also for regression and Gaussian white noise model. For nonparametric minimax rates in goodness-of-fit testing in different setups we refer to Ingster [19] and references therein, Ermakov [9] and [10]. Exact minimax rates were found, see e.g. Lepski and Tsybakov [26] for regression model in pointwise and sup-norm distances. First adaptive rates were given by Spokoiny [34]. For a complete review of the literature we refer to Ingster and Suslina [20].
To our knowledge, exact minimax rates of testing for supersmooth functions are known only in the Gaussian white noise model, see Pouet [32], in the case $r = 1$, with pointwise and sup-norm distances. These results are more related to pointwise estimation of the analytic function than to our results in $L_2$ distance and noisy observations hereafter.

A very original approach is the problem of goodness-of-fit to a parametric composite null hypothesis as in Pouet [33], Gayraud and Pouet [15]; composite null hypothesis plus adaptation to the smoothness in Fromont and Laurent [14] and Gayraud and Pouet [16]. Other developments concern non-asymptotic minimax rates for the mean of a sequence of Gaussian variables by Baraud [1]. In view of numerous practical applications of testing we expect the same problem in the context of data contaminated with errors to find similar extensive use in applied problems.

Here, the goodness-of-fit problem is considered in $L_2$ distance, that is, we reject the null hypothesis for densities $f$ far enough from the density $f_0$ under $H_0$, where “far” is measured by $\|f - f_0\|_2$. This distance depends on $n$ and it corresponds to the rate of testing. As we can expect, testing problem is easier than the estimation problem, i.e. the testing rates are faster as they appear in Table 2. One of the most surprising results is that minimax $L_2$ testing can be performed at parametric rate $n^{-1/2}$ for supersmooth densities and polynomial noise (though deconvolution rate is known to be less by a power of logarithm than $n^{-1/2}$).

Another remark concerns setups where densities and noise have similar smoothness properties. For Sobolev densities and polynomial noise, we have one rate of testing, slower than $n^{-1/2}$ but faster than the deconvolution estimation rate, as it was already noticed in testing problem with direct observations. On the contrary, for supersmooth densities and exponential noise a change in the rate is observed like in deconvolution density estimation (see Butucea and Tsybakov [6]).

We actually give exact minimax rates of testing in setups with densities less regular than the noise: Sobolev densities and exponential noise, supersmooth densities less smooth than the corresponding exponential noise ($r < s$).

The natural test statistic in this context is an estimator of $\int (f - f_0)^2$, where $f_0$ is given, from noisy data. Here we study also optimal estimators $d_n^2$ for $d^2 := \int f^2$, where $f$ is the deconvolution density in the model (1).

**Definition 2** An estimator $d_n^2$ of $d^2$ is said to attain the rate $\varphi_n$ over the smoothness class $W(\beta, L)$, respectively $S(\alpha, r, L)$, if there exists a constant $C > 0$ such that

$$\limsup_{n \to \infty} \sup_{f} \varphi_n^{-1} E_f[|d_n^2 - d^2|] \leq C$$

and this rate is called minimax if no other estimator attains better rates uniformly over the class

$$\liminf_{n \to \infty} \inf_{d_n^2} \sup_{f} \varphi_n^{-1} E_f[|d_n^2 - d^2|] \geq c,$$
for some $c > 0$, depending only on fixed known parameters, where the supremum is taken over all densities in the smoothness class and the infimum over all estimators $\hat{d}_n^2$.

In the case where parametric $n^{-1/2}$ rate is attained we prove the asymptotic efficiency Cramer-Rao bound of the estimator (also called efficient estimator).

**Definition 3** An estimator $\hat{d}_n^2$ of $d^2 = \int f^2$ is asymptotically normally distributed with asymptotic variance $W = W(f)$ if

$$\sqrt{n}(\hat{d}_n^2 - d^2) \xrightarrow{d} N(0, W(f)).$$

Moreover, it attains the asymptotic efficiency Cramer-Rao bound if for any $f_0$ in the Sobolev class $W(\beta, L)$, respectively in $S(\alpha, r, L)$, and a family of shrinking neighbourhoods of $f_0$: $\mathcal{V}(f_0)$

$$\inf_{\mathcal{V}(f_0)} \liminf_{n \to \infty} \sup_{f \in \mathcal{V}(f_0)} nE_f \left[ (\hat{d}_n^2 - d^2)^2 \right] \geq W(f_0),$$

for any other estimator $\hat{d}_n^2$ of $d^2$.

In direct estimation, when data $X_1, \ldots, X_n$ are available, it is well established that parametric rates could be achieved for smooth enough densities belonging e.g. to the Hölder class. Lower bounds for slower rates were found by Bickel and Ritov [2] for smoothnesses less than $1/4$. In this context, Laurent [23] gave efficient estimation at parametric rate, Birgé and Massart [3] proved nonparametric lower bounds for estimating more general quadratic functionals. The study of general functionals was completed by Kerkyacharian and Picard [21] for minimax rates and Tribouley [36] for adaptive estimation. In the context of regression model and Gaussian sequence model, Nemirovski [30] found necessary conditions for existence of asymptotically efficient estimators of less smooth functionals, one or two times continuously differentiable.

In the convolution model, linear functionals were estimated in a minimax setup by Matias and Taupin [29]. Finally, the estimator $\hat{d}_n^2$ of $\int f^2$ considered here was partly studied by Butucea [5] for proving asymptotic normality of the integrated square error (ISE) for kernel estimator in the convolution model.

In this paper, we give minimax results in the setups on the nonparametric side ("regime") and efficiency constant in the sense of the theory by Ibragimov and Khas’minskii [18] and Khoshevnik and Levit [22] for asymptotically normal, $n^{-1/2}$-consistent estimator (see Table 1).

Though we deal with both testing and quadratic functional estimation problems, these are essentially different problems. Indeed, we know in the case of direct observations that for other $L_p$ norms ($p \neq 2$) the rates for minimax testing are different from minimax rates when estimating the $L_p$ norm of a density. Compare

The structure of the paper is as follows. In Section 2 we introduce the estimator $d^2_n$ of $\int f^2$ and indicate the choice of bandwidth in order to prove either upper bounds in the minimax sense, or its asymptotic normality and efficiency, according to different setups. In Section 3 we deal with the goodness-of-fit testing problem and introduce the test statistic. For each setup, we define the tuning parameters and compute the minimax upper bounds for testing rates. Finally, in Section 4, we describe the approach unifying the proof of minimax nonparametric lower bounds from Sections 2 and 3 and prove them for nonparametric setups of Sobolev classes of densities and exponential, respectively polynomial noise, and for the bias dominated setup of supersmooth densities less smooth than the exponentially smooth noise ($r < s$). Finally, some auxiliary results appear in the Appendix.

2 Estimation of $\int f^2$ in the convolution model

In the described model, we consider the problem of estimating $d^2 = \|f\|_2^2$, from available observations $(Y_i)_{i=1,...,n}$, where the density $f$ of observations $(X_i)_{i=1,...,n}$ is unknown. Let us denote the deconvolution kernel $K_n$ defined via its Fourier transform as

$$
\Phi^{K_n}(u) = \left( \Phi^g \left( \frac{u}{h} \right) \right)^{-1} \Phi^K(u),
$$

where $K(x) = \sin(x)/(\pi x)$ is such that $\Phi^K(u) = I_{(|u|\leq 1)}$ and the bandwidth $h = h_n \to 0$, when $n \to \infty$ will be specified later.

Define $d^2_n$ a bias-reduced estimator of $d^2$ by

$$
d^2_n = \frac{1}{n(n-1)} \sum_{k \neq j=1}^{n} \int K_{n,h}(x - Y_k) \cdot K_{n,h}(x - Y_j) \, dx.
$$

In the sequel, we shall denote the $L_2$ scalar product of two functions $M$ and $N$ by $\langle M, N \rangle = \int M(x) N(x) \, dx$ and by $\overline{M}$ the complex conjugate of $M$.

**Definition 4** Let $d^2_n$ in (11) be the estimator of $d^2$, having bandwidth $h > 0$. We call the bias and the variance of this estimator, respectively:

$$
B(d_n) \triangleq |E_f[d^2_n] - d^2| \quad \text{and} \quad V(d_n) \triangleq E_f \left[ |d^2_n - E_f[d^2_n]|^2 \right].
$$

2.1 Sobolev densities and polynomial noise

We shall study in detail the case where the underlying density $f$ belongs to a Sobolev class $W(\beta, L)$, with $\beta > 1/2$, defined in (2) and the noise is $s$-polynomial as defined in (4).
Proposition 1 If $f$ is a fixed density in the Sobolev class $W(\beta, L)$, the estimator $d_n^2$ in (11) with bandwidth $h > 0$ is such that

$$B(d_n) = \frac{4\Omega_g^2(f)}{n} (1 + o(1)) + \frac{2\|p\|^2_2}{n^2h^{4s+1}} \frac{(1 + o(1))}{\pi(4s + 1)}, \quad \text{if } \beta \geq s;$$

$$V(d_n) = \frac{O(1)}{nh^{2s-\beta}} + \frac{2\|p\|^2_2}{n^2h^{4s+1}} \frac{1 + o(1)}{\pi(4s + 1)}, \quad \text{if } \beta < s.$$  

where $\Omega_g(f) \geq 0$ is defined later on, in (12), $o(1) \to 0$ and $h \to 0$, when $n \to \infty$.

In order to define $\Omega_g(f)$, let us see that for any $f$ in the Sobolev class $W(\beta, L)$ and $g$ a noise density satisfying (4), we have $\Phi/\Phi_g$ a continuous function which is absolutely and quadratically integrable (see Lemma 7). Then we can define the function

$$F(y) = \frac{1}{2\pi} \int e^{-iyu} \frac{\Phi(u)}{\Phi_g(u)} du,$$

which is uniformly continuous function, but it is not necessarily a density function. It is known (see Lukacs [28]) that if both characteristic functions $\Phi$ and $\Phi_g$ are analytic around 0 then their quotient cannot be the characteristic function of any distribution function. Nevertheless, this function is bounded and its $L_2$ norm is uniformly bounded over densities $f$ in the Sobolev class by $M^F$ depending only on $\beta, L$ and the fixed given density $g$.

Define:

$$\Omega_g^2(f) = \int |F(y)|^2 p(y) dy - \left( \int f^2(x) dx \right)^2 = E_f[|F(Y)|^2] - (E_f[F(Y)])^2. \quad (12)$$

Indeed, $E_f[F(Y)]$ is a real number, since:

$$\|f\|^2_2 = \frac{1}{2\pi} \langle \Phi, \Phi \rangle = \frac{1}{2\pi} \langle \Phi^p, \Phi_g \rangle = \langle p, F \rangle = E_f[F(Y)].$$

Remark 1 Note that (12) says that

$$4\Omega_g^2(f) = 4V(F(Y)).$$

This is heuristically similar to the results by Laurent [23] for direct estimation of $\int f^2$ where $4V(f(X)) = 4\int f^3 - 4(\int f^2)^2$ appears. Moreover, Bickel and Ritov [2] estimate with direct observation $\int (f^{(s)})^2$, where $f^{(s)}$ is the $s$-derivative of $f$ and $s$ a nonnegative integer. They note that via integration by parts, we can write $\int (f^{(s)})^2 = E_f[(-1)^s f^{(2s)}(X)]$. Then they get nonparametric rates as soon as the smoothness of the density is larger than $2s + 1/4$ and parametric rate for smoothness less than $2s + 1/4$ with asymptotic efficiency constant $4V(f^{(2s)}(X))$.

In Theorems 1 and 2 we describe the same change of "regime" when $\beta \geq s + 1/4$, respectively $\beta < s + 1/4$. Similarities between deconvolution with $s$-polynomial noise
and derivative of order \( s \) have been noticed before. Indeed, we actually estimate here
\[ f^2 = E_f[F(Y)], \]
where \( F \ast g = f \), whenever the function \( F \) exists and \( F \) replaces
the \( s \)-derivative of the function \( f \).

**Proof of Proposition 1.** Let us note that

\[
E_f[d_n^2] = E_f[(K_{n,h}(\cdot - Y_1), K_{n,h}(\cdot - Y_2))]
\]

\[
= \|K_{n,h} \ast p\|_2^2 = \|K_h \ast f\|_2^2 = \frac{1}{2\pi} \int \Phi^K(hu)|\Phi(u)|^2 du. \quad (13)
\]

By Plancherel formula in equation (13):

\[
B(d_n^2) = \frac{1}{2\pi} \left| \int (\Phi^K(hu) - 1)|\Phi(u)|^2 du \right| \leq \frac{1}{2\pi} \int_{|u| > 1/h} (h|u|)^{2\beta} |\Phi(u)|^2 du \leq Lh^{2\beta}.
\]

As for the variance let us write first:

\[
d_n^2 - E_f[d_n^2] = \frac{1}{n(n-1)} \sum_{k\neq j} \langle K_{n,h}(\cdot - Y_k) - K_h \ast f, K_{n,h}(\cdot - Y_j) - K_h \ast f \rangle
\]

\[
+ \frac{2}{n} \sum_{k=1}^{n} \langle K_{n,h}(\cdot - Y_k) - K_h \ast f, K_h \ast f \rangle = S_1 + S_2, \quad \text{say.}
\]

Variables in \( S_1 \) are uncorrelated to the variables in \( S_2 \) and all of them are centered. Thus,
\( V(d_n^2) = E_f[|S_1|^2] + E_f[|S_2|^2] \). We have

\[
E_f[|S_1|^2] = \frac{2}{n(n-1)} \left( E_f[|\langle K_{n,h}(\cdot - Y_1) - K_h \ast f, K_{n,h}(\cdot - Y_2) - K_h \ast f \rangle|^2] \right)
\]

\[
= \frac{2}{n(n-1)} \left( E_f[|\langle K_{n,h}(\cdot - Y_1), K_{n,h}(\cdot - Y_2) \rangle|^2] - \|K_h \ast f\|_2^4 \right)
\]

\[
= \frac{2\|p\|_2^2}{\pi} \left( 1 + o(1) \right) \frac{1}{n^2 h^{4s+1}}, \quad (14)
\]

where indeed, \( \|K_h \ast f\|_2^4 = \|f\|_2^4 (1 + o(1)) \) by the bias computations and this term
is negligible with respect to the first one. Similarly to Butucea [5], we have

\[
E_f[|\langle K_{n,h}(\cdot - Y_1), K_{n,h}(\cdot - Y_2) \rangle|^2]
\]

\[
= \frac{1}{h^2} \int \int \left| \int K_n \left( \frac{x-u}{h} \right) K_n \left( \frac{x-v}{h} \right) \frac{dx}{h} \right|^2 p(u)p(v)dudv
\]

\[
= \frac{1}{h} \int \int \left| \int K_n \left( \frac{z + v - u}{h} \right) K_n(z) \frac{dz}{h} \right|^2 p(u)p(v)dudv
\]

\[
= \frac{1}{h} \int \int \left| M_n \left( \frac{v - u}{h} \right) \right|^2 p(u)p(v)dudv = T, \quad \text{say.}
\]
where \( M_n(x) = \int K_n(z+x)K_n(z)dz \). Finally, use the fact that \( p \) is at least \((\beta + s - 1/2)\) - Lipschitz continuous (Lemma 6)

\[
\left| T - \frac{1}{h} \|p\|_{\mathbb{L}^2} \|M_n\|_{\mathbb{L}^2} \right| \\
\leq \frac{1}{h} \int \int \left( \frac{1}{h} \left| M_n \left( \frac{v-u}{h} \right) \right| \right)^2 p(u) - p(v) \int |M_n|^2 \, du \, dv \\
\leq \frac{1}{h} \int \int |M_n(x)|^2|p(v + hx) - p(v)| \, dx \, dv \\
\leq \frac{1}{h} \int \left( \int_{|hx| \leq \epsilon} |M_n(x)|^2 L e^{\beta + s - 1/2} \, dx + \int_{|x| \geq \epsilon} 2M^Y |M_n(x)|^2 \, dx \right) p(v) \, dv \\
\leq \frac{1}{h} \alpha(||M_n||_{\mathbb{L}^2}^2),
\]

where we chose \( \epsilon \to 0 \) such that \( \epsilon/h \to \infty \) so that

\[
T = \frac{\|p\|_{\mathbb{L}^2} \|M_n\|_{\mathbb{L}^2}}{h} (1 + o(1)). \tag{15}
\]

By Plancherel formula, \( \|M_n\|_{\mathbb{L}^2}^2 = \int |\Phi K_n(u)\Phi K_n(-u)|^2 \, du = (\pi(4s + 1) h^4 s)^{-1} (1 + o(1)). \) Note that we should again split the integration domain and evaluate the dominant term in the previous integral. Replace this in (15) in order to get (14).

On the other hand, let us deal now with:

\[
E_f[|S_2|^2] = \frac{4}{n} \left( E_f[\|K_{n,h}(\cdot \cdot \cdot Y_1), K_{h} * f\|_{\mathbb{L}^2}^4] - \|K_{h} * f\|_{\mathbb{L}^2}^4 \right) \\
= \frac{4}{n} \left( E_f \left[ \frac{1}{2\pi} \left| \int e^{iuY_1} \frac{\Phi K(hu)}{\Phi^\theta(u)} \overline{\Phi}(u) \, du \right|^2 \right] - \|f\|_{\mathbb{L}^2}^4 (1 + o(1)) \right). \tag{16}
\]

Use Lemma 7 and Lebesgue convergence theorem to see that, if \( \beta \geq s \), there exists a function

\[
F(y) = \frac{1}{2\pi} \int e^{iyu} \frac{\overline{\Phi}(u)}{\Phi^\theta(u)} \, du = \lim_{h \to 0} \frac{1}{2\pi} \int_{|u| \leq 1/h} e^{iyu} \frac{\overline{\Phi}(u)}{\Phi^\theta(u)} \, du,
\]

which is uniformly continuous, bounded such that \( \|F\|_{\mathbb{L}^2}^2 = \|\overline{\Phi}/\Phi^\theta\|_{\mathbb{L}^2}^2/(2\pi) \). Note also that \( F \) is a limit of real-valued functions. Indeed, write

\[
\frac{1}{2\pi} \int_{|u| \leq 1/h} e^{iyu} \frac{\overline{\Phi}(u)}{\Phi^\theta(u)} \, du = \frac{1}{2\pi} \int e^{iyu} \frac{\Phi K(hu)}{|\Phi^\theta(u)|^2} \overline{\Phi^\theta}(u) \, du,
\]

and note that \( \Phi K(hu)/|\Phi^\theta(u)|^2 \) is a symmetric integrable function and \( \Phi^\theta(u) \) is the Fourier transform of \( p(-y) \). Thus the integral is the convolution of two-real valued functions. The limit of real-valued functions, \( F \) is real-valued as well.
Thus, we obtain in (16):
\[
Ef||S_2||^2 = \frac{4}{n}(Ef||F(Y)||^2 - ||f||^2)(1 + o(1)) = \frac{4\Omega_g(f)}{n}(1 + o(1)).
\] (17)

Together with (14) we get the variance for the case \(s\).

In case \(\beta < s\), go back to (16):
\[
Ef\left[\frac{1}{2\pi} \left| \int e^{iuY} \Phi_K(hu) \Phi(u) du \right|^2 \right]
\leq \frac{MY}{2\pi} \left( \int_{|u| \leq 1/h} \left| \Phi(u) \right| du \right) \leq O(1) \left( \int_{M \leq |u| \leq 1/h} |u|^s \Phi(u) du \right)^2
\leq O(1)(h^{\beta - s} \int_{M \leq |u| \leq 1/h} |u|^s \Phi(u) du)^2 \leq O(1)h^{2(\beta - s)}. \]
(18)

So, from (14), (16) and (18) we get the variance for \(\beta < s\). \[\blacksquare\]

An easy consequence of Proposition 1 is that if the underlying unknown density is smoother enough than the noise (\(\beta > s + 1/4\)) our parameter can be estimated at parametric rate. We establish next asymptotic normality and a Cramer-Rao type of asymptotic efficiency bound.

**Theorem 1** If \(\beta > s + 1/4\), the estimator \(d_n^2\) defined in (11) with bandwidth \(h = h_*\) such that
\[
n^{-\frac{s+1}{s+1}} \ll h_* \ll n^{-\frac{1}{s+1}},
\]
is asymptotically normally distributed estimator of \(d^2\), i.e.
\[
\sqrt{n}(d_n^2 - d^2) \xrightarrow{d} N(0, 4\Omega_g(f)).
\]
Moreover, it attains the asymptotic efficiency Cramer-Rao bound.

**Proof.** Let us decompose the risk of the estimator as follows
\[
Ef[|d_n^2 - d^2|] \leq B(d_n) + \sqrt{V(d_n)} \leq Lh^{2\beta} + \frac{2\Omega_g(f)}{\sqrt{n}}(1 + o(1)),
\]
and then use Proposition 1. Indeed, if \(\beta > s + 1/4\) and if \(n^{-1}h^{-(4s+1)} \ll 1\) we see that
\[
4\Omega_g^2(f)/n(1 + o(1))
\]
is the dominant term in the variance. Let us take \(h = o(n^{-1/(4\beta)})\) such that the bias be infinitely smaller, \(Lh^{2\beta} \ll 2\Omega_g(f)/n\). So,
\[
\sqrt{n}(d_n^2 - d^2) = \sqrt{n}(d_n^2 - Ef[d_n^2]) + \sqrt{n}B(d_n).
\]
The second term of the sum in the right-hand side term tends to 0 and the asymptotic normality of the first term can be deduced from Butucea [5]. It is in this case a classical central limit theorem for U-statistics of order 1.
For the Cramer-Rao bound, we follow the lines of proof in Laurent [23]. Similar results were given by Bickel and Ritov [2] following the theory by Ibragimov and Hasminski [18] and Khoshevnik and Levit [22]. A first step of the proof is to compute the Fréchet derivative of the functional \( \int F \cdot p \) at likelihood \( p_0 = f_0 \ast g \):

\[
\int F \cdot p - \int F_0 \cdot p_0 = \int 2F_0(p - p_0) + \int (F - F_0)(p - p_0)
\]

and \( \int (F - F_0)(p - p_0) = o(\|p - p_0\|_2) \), when \( \|p - p_0\|_2 \to 0 \). Next, consider the space orthogonal to the square root of the likelihood \( \sqrt{p_0} \),

\[
H = \{ k : \int k \sqrt{p_0} = 0 \}
\]

and the projection operator unto this space:

\[
P_{H(p_0)}(k) = k - (\int k \sqrt{p_0}) \sqrt{p_0}.
\]

Write \( K_n = K = T'(p_0)\sqrt{p_0} = P_{H(p_0)}(k) \) as \( \langle g, k \rangle \). Then the minimal variance is given by \( \|g\|^2_2 \).

Here, \( T'(p_0)k = \int 2F_0k \), then

\[
K = \int 2F_0\sqrt{p_0}(k - (\int k \sqrt{p_0}) \sqrt{p_0})
= \int (2F_0\sqrt{p_0})k - (\int 2F_0p_0) \int \sqrt{p_0} k.
\]

So, finally,

\[
\|g\|^2_2 = 4 \int |F_0|^2 p_0 - \left( \left| \int 2F_0 p_0 \right| \right)^2 = 4V_{f_0}(F_0(Y)).
\]

In the following theorem we compute the rate on the nonparametric side (\( 1/2 < \beta \leq s + 1/4 \)). We prove in Section 3 that this rate is optimal in the minimax approach under the following additional assumption on the noise distribution.

**Assumption (P)** The distribution of the polynomial noise in (4) is such that \( \Phi^g \) is at least 3 times continuously differentiable and \( \Phi^g \) is at least 2 times continuously differentiable. Moreover there exist \( A_1, A_2 > 1, u_0, u_1, u_2 > 0 \) large enough such that

\[
|\Phi^g(u)| \geq u_0, \ \forall |u| \leq A_1 \ \text{and} \ \left| (\Phi^g)^{(k)}(u) \right| \leq \frac{u_k}{|u|^{s+k}}, \ \text{for} \ k = 1, 2, \ \forall |u| \geq A_2.
\]

**Theorem 2** If \( 1/2 < \beta \leq s + 1/4 \), the estimator \( d_n^2 \) of \( d^2 \) defined in (11) with bandwidth \( h_* \) satisfies the upper bound (8) for the rate \( \varphi_n \), where

\[
h_* = n^{-\frac{2}{4s+4s+1}}, \ \varphi_n = n^{-\frac{4s}{4s+4s+1}}.
\]

Moreover, under Assumption (P) this rate is minimax.
Proof of (8). If $1/2 < \beta \leq s + 1/4$, $\|p\|^2/(\pi(4s + 1)n^2h^{4s+1})$ is the dominant term in the variance no matter whether $\beta \geq s$ or $\beta < s$. The bandwidth $h_*$ minimizes the bias plus the variance. The upper bound of the normalized mean error is less than $C = \max\{L, \sqrt{2M}/(\pi(4s + 1)}\}$, see Lemma 6.

Remark 2 In view of Butucea [5], we get asymptotic normality of the estimator $d_n^2$ defined in (11) in the case $1/2 < \beta < s + 1/4$, for $h$ such that

$$h = o(1)n^{-\frac{1}{4s+1}} \text{ and } h = o(1)n^{-\frac{2}{4s+4s+1}}$$

(i.e. the variance tends to 0 and the bias is infinitely smaller than the variance, when $n \to \infty$),

$$nh^{2s+1/2} (d_n^2(h) - d^2) \xrightarrow{d} N\left(0, \frac{2\|p\|^2}{\pi(4s + 1)}\right).$$

We will actually use the following type of result for the testing problem

$$nh_*^{2s+1/2} (d_n^2 - E_f[d_n^2]) \xrightarrow{d} N\left(0, \frac{2\|p\|^2}{\pi(4s + 1)}\right),$$

for the optimal bandwidth $h_*$ defined in Theorem 2.

2.2 Supersmooth densities and polynomial noise

In the case of supersmooth densities, always smoother than the polynomial noise, we can always define the function $F$ as the inverse Fourier transform of $\Phi/F$. Next Theorem gives us the right choice of the bandwidth so that $d_n^2$ be an asymptotically normal and efficient estimator.

Theorem 3 The estimator $d_n^2$ defined in (11) with bandwidth $h_*$ such that

$$h_* \ll \left(\frac{\log n}{4\alpha}\right)^{-1/r}$$

is asymptotically normally distributed and it attains the asymptotic efficiency Cramer-Rao bound $4\Omega^2_y$, (see Definition 3).

Proof. In this case, the bias changes,

$$B(d_n) \leq L \exp\left(\frac{-2\alpha}{h^r}\right).$$

The variance is strongly dependent on the noise distribution, so very little is changed. In this case, the underlying density is always much more regular than the noise, so the function $F$ always exists in this setup. So, we can put together (14) and (17)

$$V(d_n) = \frac{4\Omega^2_y(f)}{n}(1 + o(1)) + \frac{2\|p\|^2}{n^2h^{4s+1}} \frac{(1 + o(1))}{\pi(4s + 1)}.$$

It is obvious that we need to choose $h_* = o(1)(\log n/(4\alpha))^{-1/r}$, in order to have the squared bias infinitely smaller than the dominant term of the variance $1/n$. ■


2.3 Sobolev densities and exponential noise

In this setup the noise is much smoother so estimation is always difficult, i.e. at nonparametric slower rates. We prove the lower bounds (9), under the following additional assumption, which is not very restrictive.

**Assumption (E)** The exponential noise distribution in (5) has a continuously differentiable Fourier transform such that

\[ |\Phi^\theta(u)| \leq O(1)|u|^A \exp(-\gamma|u|^s), \]

for large enough $|u|$ and some fixed constant $A \in \mathbb{R}$.

**Theorem 4** The estimator $d_n^2$ of $d^2$ defined in (11) with bandwidth $h_n$ satisfies the upper bound (8) for the rate $\varphi_n$, where

\[ h_n = \left( \frac{\log n}{2\gamma} - \frac{2\beta + 1}{2\gamma s} \log \frac{\log n}{2\gamma} \right)^{-1/s}, \quad \varphi_n = L \left( \frac{\log n}{2\gamma} \right)^{-\frac{2\beta}{s}}. \]

Moreover, under Assumption (E) this rate is minimax.

**Proof of (8).** In this case, the bias is the same as in Proposition 1, $B(d_n) \leq Lh^{2\beta}$. As for the variance, we can still write $V(d_n) = E_f[|S_1|^2] + E_f[|S_2|^2]$, but both terms are different now, since they are highly dependent on the noise distribution. We still have,

\[ E_f[|S_1|^2] = \frac{2 + o(1)}{n(n-1)} \frac{\|p\|^2_2}{h} \|M_n\|_2^2, \]

see (15). Now,

\[ \|M_n\|_2^2 = \frac{h}{2\pi} \int_{|u| \leq 1/h} e^{4\gamma|u|^s} du = \frac{h^s}{4\pi\gamma s} e^{4\gamma} (1 + o(1)), \]

as $h \to 0$, and then

\[ E_f[|S_1|^2] = \frac{(2 + o(1))\|p\|^2_2}{4\pi\gamma s} \frac{h^{s-1}}{n^2} e^{4\gamma}. \]

The other term, can never be of parametric order anymore, the function $F$ never exists in this setup. Indeed, recall that

\[ E_f[|S_2|^2] \leq \frac{c_1}{n} E_f \left[ \left| \int e^{inY_1} \frac{\Phi^K(hu)}{\Phi^\theta(u)} \bar{\Phi}(u) du \right|^2 \right] \]

\[ \leq \frac{c_1}{n} \left( \int \left| \frac{\Phi^K(hu)}{\Phi^\theta(u)} \bar{\Phi}(u) \right| du \right)^2 \]

13
and this integral does not check the Lebesgue convergence theorem anymore. We can compute the rate of divergence, giving a loss in the rate, via Cauchy-Schwarz
\[ \left( \int \left| \frac{\Phi^K(hu)}{\Phi^*(u)} \Phi(u) \right| du \right)^2 \leq \int |\Phi(u)|^2 |u|^{2\beta} du \int_{|u| \leq 1/h} |u|^{-2\gamma} e^{2\gamma |u|^s} du \leq c_2 h^{2\beta + s - 1} e^{2\gamma s}. \] (21)

From (19), (20) and (21), we get
\[ V(d_n^2) \leq C_1 \frac{h^{s-1}}{n^2} e^{2\gamma s} (1 + o(1)) + C_2 \frac{h^{2\beta + s - 1}}{n} e^{2\gamma s}, \] (22)
where \( c_1, c_2, C_1, C_2 > 0 \) are some constants.

As in Theorem 2 we actually select the bandwidth by minimizing an upper bound of the error:
\[ E_f[|d_n^2 - d|^2] \leq (E_f[|d_n^2 - d|^2])^{1/2} \leq (B^2(d_n) + V_f[d_n])^{1/2}. \]
The optimality of this upper bound is proven by the corresponding lower bounds. Now, we consider
\[ h_* = \arg \inf_{h > 0} \left( L^2 h^{4\beta} + c_2 \frac{h^{2\beta + s - 1}}{n} \exp \left( \frac{2\gamma}{h_s} \right) \right) \]
then \( h_* \) is a solution of the equation
\[ h_*^{2\beta + 1} = \frac{c}{n} \exp \left( \frac{2\gamma}{h_*} \right) (1 + o(1)). \] (23)
This proves that the bias is infinitely larger than the variance and gives announced \( h_* \) and rate of order of the bias \( \varphi_n \). (If we suppose that the first term on the right-hand side of (22) is dominant, we get a contradiction).

### 2.4 Supersmooth densities and exponential noise

In this setup unknown densities and noise densities are both exponentially smooth. Note that minimax rates in the nonparametric "regime" are faster than any logarithm but slower than any polynomial of \( n \).

**Theorem 5** If \( r > s \) or, if \( r = s \) and \( \alpha > \gamma \), the estimator \( d_n^2 \) defined in (11) with bandwidth \( h_* \) such that
\[ h_* \ll \left( \frac{\log n}{4\alpha} \right)^{1/r} \]
is asymptotically normally distributed and it attains the asymptotic efficiency Cramer-Rao bound \( 4\Omega^2_y \).

If \( r < s \) the same estimator \( d_n^2 \) of \( d^2 \) with bandwidth \( h_* \) satisfies the upper bounds (8) for the rate \( \varphi_n \), where
\[ h_* \text{ solution of } h_*^{r-1-(r-1)/2} \exp \left( \frac{2\alpha}{h_*} + \frac{2\gamma}{h_*} \right) = cn(1 + o(1)), \quad \varphi_n = L \exp \left( -\frac{2\alpha}{h_*} \right). \]
Moreover, unde Assumption (E) this rate is minimax.
Proof. We skip the proof of asymptotic efficiency. If \( r < s \), we know the bias is \( B(d^2_n) \leq L \exp(-2\alpha/h^r) \) and the variance writes also \( V_f[d^2_n] = E_f[|S_1|^2] + E_f[|S_2|^2] \). Furthermore, \( E_f[|S_1|^2] \) is the same as in (19).

As in (20), we need to study

\[
\int_{|u| \leq 1/h} e^{iuY_i} \frac{\bar{\Phi}(u)}{\Phi(u)} du^2.
\]

If \( r > s \) or, if \( r = s \) and \( h^s \), this integral is bounded by a constant depending only on \( \alpha, r, L \) and the noise density \( g \). So, the variance

\[
V_f[\frac{T_n}{n}^2] = E_f[|S_2|^2](1 + o(1)) = \frac{4\Omega_g^2(f)}{n}(1 + o(1)),
\]

as soon as \( h^s - 1 n^{-1} \exp(4\gamma/h^s) = o(1) \). For the bandwidth we chose in the theorem, this holds and proves this case.

If \( r < s \),

\[
\int_{|u| \leq 1/h} e^{iuY_i} \frac{\bar{\Phi}(u)}{\Phi(g)} du^2 \leq \int e^{2\alpha|u|^r} |\Phi(u)|^2 du \int_{|u| \leq 1/h} e^{-2\alpha|u|^r} e^{2\gamma|u|^s} du
\]

\[
\leq c_1 h^{s-1} \exp\left(\frac{2\gamma}{h^s} - \frac{2\alpha}{h^r}\right).
\]

Thus,

\[
V_f[d^2_n] \leq c_1 \frac{h^{s-1}}{n} \exp\left(\frac{2\gamma}{h^s} - \frac{2\alpha}{h^r}\right) + c_2 \frac{h^{s-1}}{n^2} \exp\left(\frac{4\gamma}{h^s}\right),
\]

where \( c_1, c_2, \ldots \) are some positive constants. As in Theorems 2 and 4 we find the optimal bandwidth by minimizing an upper bound of the error

\[
h_\text{*} = \arg \inf_{h > 0} \left( L^2 \exp\left(-\frac{4\alpha}{h^r}\right) + c_1 \frac{h^{s-1}}{n} \exp\left(\frac{2\gamma}{h^s} - \frac{2\alpha}{h^r}\right) + c_2 \frac{h^{s-1}}{n^2} \exp\left(\frac{4\gamma}{h^s}\right)\right).
\]

When we minimize the sum of the bias and of the first term in the variance, we find that \( h_\text{*} \) is solution of the equation

\[
h_\text{*}^{-r-1} \exp\left(\frac{2\alpha}{h_\text{*}^r} + \frac{2\gamma}{h_\text{*}^s}\right) = cn(1 + o(1)).
\]

It implies that the first term in the variance is dominant over the second, if \( r < 1 \), meaning, moreover that

\[
L^2 \exp\left(-\frac{4\alpha}{h_\text{*}^r}\right) = h_\text{*}^{-r-s} c_2 \frac{h_\text{*}^{s-1}}{n} \exp\left(\frac{2\gamma}{h_\text{*}^s} - \frac{2\alpha}{h_\text{*}^r}\right)
\]

i.e. the bias is infinitely larger than the variance for \( r < s \) for the optimal \( h_\text{*} \).
If we minimize the sum of the bias and the second term in the variance, we find that optimal bandwidth \( h_\star \) verifies
\[
h_\star^{(r-1)/2} \exp \left( \frac{2\alpha}{h_\star} + \frac{2\gamma}{h_\star} \right) = cn(1 + o(1)).
\]
The second term of the variance is dominant if \( r \geq 1 \) and in this case also the bias is dominant over the variance for \( r < s \) and the optimal \( h_\star \), respectively, the bias is of the same order as the dominant term in the variance, if \( r = s \) and \( \alpha < \gamma \). This finishes the proof of the Theorem.

**Remark 3: More upper bounds** Let us add upper bounds of the estimation risk in cases not included in the Theorem. We put them aside since we do not provide corresponding lower bounds in these cases.

In the case \( r = s \) and \( \alpha < \gamma \), the same choice of the bandwidth holds as in the case \( r < s \) of the preceding Theorem. The bias is in this case of the same order as the dominant term in the variance (not larger than the variance).

If \( r = s \) and \( \alpha = \gamma \),
\[
V_f[d_n^2] \leq \frac{c_1}{nh} + \frac{c_2 h^{s-1}}{n^2} \exp \left( \frac{4\gamma}{h^s} \right).
\]
In this case, the first term in the upper bound of the variance is always dominating over the second and when we minimize the sum of this term and of the bias we get an optimal \( h_\star \) solution of
\[
h_\star^{s-1} \exp \left( \frac{4\alpha}{h_\star^s} \right) = cn(1 + o(1)),
\]
giving a fast rate of convergence of the order of the variance:
\[
\varphi_n^2 = c_3 \frac{(\log n)^r}{n}.
\]

### 3 Goodness-of-fit tests

Let us construct a test statistic from noisy data. It is natural to suggest as a test statistic \( T_n^2 \), the square root of the optimal estimator of the quadratic functional \( \| f - f_0 \|^2_2 \):
\[
T_n^2 = \frac{1}{n(n-1)} \sum_{k \neq j} \langle K_{n,h}(\cdot - Y_k) - f_0, K_{n,h}(\cdot - Y_j) - f_0 \rangle,
\]
where \( h > 0 \), \( h \to 0 \) and \( K_{n,h} = 1/hK_n(\cdot/h) \), for the same \( K_n \) defined in (10).

Define the test procedure
\[
\Delta_n^* = \begin{cases} 
1 & T_n^2 > C^* t_n^2 \\
0 & T_n^2 \leq C^* t_n^2 
\end{cases}
\]
for a constant \( C^* > 0 \) and some threshold \( t_n > 0 \) depending on the setup.
![Table 1: Estimation rates of $d^2$ from noisy data](image)

### 3.1 Sobolev densities and polynomial noise

Though two rates were attainable in the same setup for estimating $d^2$, only one minimax rate of testing is possible. This phenomenon is similar to the case of testing with direct observations.

**Theorem 6** The test procedure $\Delta_n^*$ defined in (24) for the threshold $t_n$ attains the rate $\psi_n$ and, under Assumption (P), $\psi_n$ is a minimax rate of testing over the class $W(\beta, L)$, where

$$h = h_n = n^{-\frac{2\alpha}{\alpha + r + 1}}; \quad t_n = \psi_n = n^{-\frac{2\beta}{\beta + r + 2}}.$$

**Proof of upper bounds** (6). Let us bound from above successively the first and second type error. Note that, for a fixed density $f_0 \in W(\beta, L)$:

$$E_{f_0}[T_n^2] = \|K_h * f_0 - f_0\|_2^2 = Lh^{2\beta}o(1),$$

similarly to the proof of Proposition 1. In order to compute the variance let us write as follows

$$T_n^2 - E_{f_0}[T_n^2] = \frac{1}{n(n-1)} \sum_{k \neq j} (K_{n,h}(\cdot - Y_k) - f_0, K_{n,h}(\cdot - Y_j) - f_0) - \|K_h * f_0 - f_0\|_2^2$$

= \frac{1}{n(n-1)} \sum_{k \neq j} (K_{n,h}(\cdot - Y_k) - K_h * f_0, K_{n,h}(\cdot - Y_j) - K_h * f_0)

+ \frac{2}{n} \sum_{k=1}^{n} (K_{n,h}(\cdot - Y_k) - K_h * f_0, K_h * f_0 - f_0).$$
Note that, for all $k = 1, \ldots, n,$
\[
\langle K_{n,h}(\cdot - Y_k) - K_h * f_0, K_h * f_0 - f_0 \rangle \\
= \frac{1}{2\pi} \int (\Phi^K_n(hu)e^{iuY_k} - \Phi^K(hu)\Phi_0(u)) (\Phi^K(hu) - 1) \Phi_0(u) du \\
= \frac{1}{2\pi} \int \Phi^K(hu) (\Phi^K(hu) - 1) (e^{iuY_k}/\Phi^K(hu) - \Phi_0(u)) \Phi_0(u) du = 0,
\]
due to the support of $\Phi^K$. Finally,
\[
V_{fo}[T_n^{*2}] = E_{fo}[|S_1|^2] = \frac{S\|p_0\|^2_2}{n^2 h^{4s+1}}(1 + o(1)),
\]
where $S = 2/(\pi(4s + 1))$. So the first type error can be written as follows
\[
P_{fo}[T_n^{*2} \geq C^*t_n^2] = P_{fo}[T_n^{*2} - E_{fo}[T_n^{*2}] \geq C^*t_n^2 - c_1h^{2\beta}] \\
= O(1) \frac{n^{-2}h^{-(4s+1)}}{(C^*t_n^2 - c_1h^{2\beta})^2} \leq \frac{\alpha}{2}
\]
since, for $h = h_*$
\[
\frac{1}{nh^{2s+1/2}} \leq O(1) \max\{t_n^2, h^{2\beta}\}. \tag{25}
\]
For the second type error, consider a density $f$ in $H_1(C, \psi_n)$. Then, $E_f[T_n^{*2}] = \|K_h * f - f_0\|^2_2$. The bias can be bounded from above as follows
\[
B[T_n^{*2}] = \|K_h * f - f_0\|^2_2 - \|f - f_0\|^2_2 \\
= \|K_h * f\|^2_2 - \|f\|^2_2 - 2\langle K_h * f - f, f_0 \rangle \\
\leq \frac{1}{2\pi} \int_{|u| > 1/h} |\Phi(u)|^2 du + \frac{2}{2\pi} \int_{|u| > 1/h} |\Phi(u)| \cdot |\Phi_0(u)| du \\
\leq Lh^{2\beta}(1 + o(1)),
\]
since $\int_{|u| > 1/h} |u|^{2\beta} |\Phi_0(u)|^2 du = o(1)$, for the fixed density $f_0$. In order to evaluate the variance, let us decompose as follows
\[
T_n^{*2} - E_f[T_n^{*2}] \\
= \frac{1}{n(n - 1)} \sum_{k \neq j} \langle K_{n,h}(\cdot - Y_k) - f_0, K_{n,h}(\cdot - Y_j) - f_0 \rangle - \|K_h * f - f_0\|^2_2 \\
= \frac{1}{n(n - 1)} \sum_{k \neq j} \langle K_{n,h}(\cdot - Y_k) - K_h * f, K_{n,h}(\cdot - Y_j) - K_h * f \rangle \\
+ \frac{2}{n} \sum_{k=1}^n \langle K_{n,h}(\cdot - Y_k) - K_h * f, f - f_0 \rangle \\
= S_1(f) + S_2(f - f_0), \text{say.}
As in Proposition 1, the last two terms are uncorrelated, so \( V_f[T_n^2] = E_f[|S_1(f)|^2] + E_f[|S_2(f - f_0)|^2] \). Similar computation lead to

\[
V_f[T_n^2] \leq \frac{C_1}{n^2h^{4s+1}} + \frac{(4 + o(1))\Omega_0(f - f_0)}{n} I(\beta > s) + \frac{C_3}{nh^{2(s-\beta)}} I(\beta \leq s)
\]

\[
\leq \frac{C_1}{n^2h^{4s+1}} + \frac{C_2\|f - f_0\|^2}{n} I(\beta > s) = \text{Def } v_n^2.
\]

Indeed, let us see that whenever \( \beta > s \), we find \( M > 0 \) large enough such that

\[
\Omega_0^2(f - f_0) \leq \int (F(y) - F_0(y))^2 p(y) dy \leq \|F - f_0\|_\infty^2 \leq \frac{1}{4\pi^2} \int \left| \frac{\Phi(u) - \Phi_0(u)}{\Phi'(u)} \right|^2 du
\]

\[
\leq \int_{|u| \leq M} c_1 M^{2s}|\Phi(u) - \Phi_0(u)|^2 du + \int_{|u| > M} c_2|u|^{2s}|\Phi(u) - \Phi_0(u)|^2 du
\]

\[
\leq c_3\|f - f_0\|^2_2 + \frac{c_2}{M^{2(\beta - s)}} \int_{|u| > M} |u|^{2\beta}|\Phi(u)|^2 du \leq C\|f - f_0\|^2_2,
\]

(26)

where, \( C \) is a constant depending only on \( \beta, L \) and of the fixed noise probability density \( g \). We also use the fact that for \( h = h_\ast \),

\[
\frac{1}{n^2h^{2(s-\beta)}} \left( \frac{1}{n^2h^{4s+1}} \right) = n^{-\frac{1}{2}} = o(1).
\]

So, the second type error can be bounded as follows

\[
P_f[T_n^2 < C^*t_n^2] = P_f[T_n^2 - E_f[T_n^2] < C^*t_n^2 - E_f[T_n^2] + \|f - f_0\|^2_2 - \|f - f_0\|^2_2]
\]

\[
\leq P_f[T_n^2 - E_f[T_n^2] < -\|f - f_0\|^2_2 + C^*t_n^2 + B[T_n^2]]
\]

\[
\leq P_f \left[ \frac{T_n^2 - E_f[T_n^2]}{\sqrt{V_f[T_n^2]}} \geq \frac{-\|f - f_0\|^2_2 + C^*t_n^2 + B[T_n^2]}{v_n} \right],
\]

(27)

for \( n \) large enough. From Butucea [5] we deduce easily the asymptotic normality of center and reduced \( T_n^2 \). The proof is based on a result by Hall [17] for U-statistics of order 2 adapted for the case of noisy observations.

So the last probability in (27) is smaller than \( \alpha/2 + o(1) \) if

\[
\frac{-\|f - f_0\|^2_2 + C^*t_n^2 + B[T_n^2]}{\left( \frac{C_1}{n^2h^{4s+1}} + \frac{C_2\|f - f_0\|^2}{n} I(\beta \geq s) \right)^{1/2}} \leq -z_{1-\alpha/2},
\]

(28)

where \( z_p \) denotes the \( p \)-quantile of the standard gaussian law \( N(0, 1) \). So, either \( \beta \leq s \), then

\[
\frac{-\|f - f_0\|^2_2 + C^*t_n^2 + B[T_n^2]}{\left( \frac{C_1}{n^2h^{4s+1}} + \frac{C_2\|f - f_0\|^2}{n} I(\beta > s) \right)^{1/2}} \leq \frac{-C^*\psi_n^2 + C^*t_n^2 + B[T_n^2]}{n^{-1}h^{-(2s+1/2)}},
\]

(29)
which is smaller than \(-z_{1-\alpha/2}\) for \(\psi_n = t_n\) verifying (25). Or, \(\beta > s\), then we can solve
\[
-\|f - f_0\|^2 + C^* t_n^2 + B[T_n^2] \leq -z_{1-\alpha/2}
\]
and (use also (25)) find
\[
\|f - f_0\| \geq \frac{C_4 z_{1-\alpha/2}^2}{2\sqrt{n}} + 1 + \frac{\sqrt{C_4 z_{1-\alpha/2}^2}}{n} + 4(C^* t_n^2 + B[T_n^2])
\]
\[
\geq \max \left\{ \frac{C_5}{\sqrt{n}}, C_6 \left( \frac{C_7}{n^2 h^{4s+1}} + L h^{2\beta} \right)^{1/2} \right\} \geq C^{1/2} \psi_n,
\]
for \(C^*\) large enough, since \(h = h_s\) minimizes the risk \(C_7 n^{-2} h^{-(4s+1)} + L h^{2\beta}\). The upper bounds in (6) are proven. For the lower bounds in (7) see Section 3.

### 3.2 Supersmooth densities and polynomial noise

Very surprisingly, in this setup, we can estimate \(d^2\) at parametric rate, moreover we can also provide minimax testing at parametric \(n^{-1/2}\) rate.

**Theorem 7** The test procedure \(\Delta_n^*\) defined in (24) for the threshold \(t_n\) attains the rate \(\psi_n\) and \(\psi_n\) is a minimax rate of testing over the class \(S(\alpha, r, L)\), where
\[
h = h_s \ll \left( \frac{\log n}{4\alpha} \right)^{-1/r}, t_n = \psi_n = n^{-\frac{1}{2}}.
\]

**Proof.** We follow the lines of proof in Theorem 6, using computation from the proof of Theorem 3 in this setup. For the first type error see that
\[
E_{f_0}[T_n^2] = o(1) Le^{-2\alpha/h^r} \quad \text{and} \quad V_{f_0}[T_n^2] = \frac{S\|p_0\|^2_2}{n^2 h^{4s+1}} (1 + o(1)),
\]
where \(p_0 = f_0 \ast g\). Using Markov’s inequality
\[
P_{f_0}[T_n^2 \geq C^* t_n^2] \leq \frac{C n^{-2} h^{-(4s+1)}}{(C^* t_n^2 - o(1) \exp(-2\alpha/h^r))^2} = o(1),
\]
since \(\max\{n^{-2} h^{-(4s+1)}, \exp(-2\alpha/h^r)\} = o(t_n^2)\).

For an arbitrary density \(f \in H_1(C, \psi_n)\),
\[
B[T_n^2] = \||K_h * f - f_0\|^2 - \|f - f_0\|^2_2 \leq L \exp(-2\alpha/h^r)(1 + o(1))
\]
and \(V_{f}[T_n^2] \leq C_1 \|f - f_0\|^2_2/n \overset{\text{Def}}{=} \psi_n\). Indeed, similarly to the proof in (26), we have for some \(M > 0\) large enough
\[
2\delta_g^2(f - f_0) \leq c_1 \|f - f_0\|^2 + c_2 e^{-2\alpha M r} \int_{|u| > M} e^{2\alpha |u|^r} |\Phi(u)|^2 du \leq C_1 \|f - f_0\|^2_2,
\]
where $C_1 > 0$ depends only on $\alpha, r, L$ and the noise fixed probability density $g$. Using the asymptotic normality of this U-statistic of order 2, we get

$$P_f[T_n^2 < C^*t_n^2] \leq P_f\left[\frac{T_n^2 - E_f[T_n^2]}{\sqrt{V_f[T_n^2]}} \leq \frac{-\|f - f_0\|^2 + C^*t_n^2 + B[T_n^2]}{C_1^{1/2}\|f - f_0\|_2/\sqrt{n}}\right] \leq \frac{\alpha}{2} + o(1),$$

if

$$-C_1^{-1/2}\|f - f_0\|_2\sqrt{n} + C_1^{-1/2}\sqrt{n}(C^*t_n^2 + B[T_n^2]) \leq -z_{1-\alpha/2}.$$

We actually have

$$-C_1^{-1/2}\|f - f_0\|_2\sqrt{n} + C_1^{-1/2}\sqrt{n}(C^*t_n^2 + B[T_n^2]) \leq -(\mathcal{C}/\mathcal{C}_1)^{1/2} + o(1)$$

which is less than the needed quantile for $\mathcal{C} > C^*$ large enough.

3.3 Sobolev densities and exponential noise

**Theorem 8** The test procedure $\Delta_n$ defined in (24), for the threshold $t_n$ and for the constant $C^* = 1$, attains the rate $\psi_n$ and, under Assumption (E), $\psi_n$ is an exact minimax rate of testing over the class $W(\beta, L)$, where

$$h = h_* = \left(\frac{\log n}{2\gamma} - \frac{2\beta + 1}{2\gamma s} \log \frac{\log n}{2\gamma}\right)^{-1/s}, \quad t_n = \psi_n = \sqrt{L}\left(\frac{\log n}{2\gamma}\right)^{-\beta/s}.$$

**Proof.** Again, under the null hypothesis and $h = h_*$

$$E_f[T_n^2] = Lh^{2\beta}o(1), \quad V_f[T_n^2] = E_f[|S_1|^2] \leq c_1 \frac{h_*^{s-1}}{n^2} \exp\left(\frac{4\gamma}{h_*}\right) .$$

The first type error can be bounded then:

$$P_f[T_n^2 < C^*t_n^2] \leq \frac{c_1 h_*^{s-1}n^{-2} \exp(4\gamma/h_*)}{(C^*t_n^2 - Lh^{2\beta})^2} \leq c_2 h_*^{s+1} = o(1),$$

where we used the facts that $C^* = 1$, that $t_n^2 \leq Lh^{2\beta}$ and that $h = h_*$ is solution of (23), i.e. $n^{-2} \exp(4\gamma/h_*) = c^{-2}h^{-4\beta/2}$. Under the alternative, if $f \in H_1(\mathcal{C}, \psi_n)$:

$$B_f[T_n^2] \leq Lh^{2\beta}(1 + o(1)), \quad V_f[T_n^2] \leq c_3 \frac{h_*^{2\beta+s-1}}{n} \exp\left(\frac{2\gamma}{h_*}\right) = c_4 h_*^{4\beta+s},$$

where we used again (23). Then for $\mathcal{C} = C^*(1 + \delta) > C^*, \delta > 0$, we have

$$P_f[T_n^* < C^*t_n^2] \leq P_f\left[\frac{E_f[T_n^2] - T_n^2}{\sqrt{V_f[T_n^2]}} \geq \frac{-C^*t_n^2 - B_f[T_n^2] + \|f - f_0\|^2}{\sqrt{c_4 h_*^{2\beta+s/2}}}\right] \leq P_f\left[\frac{E_f[T_n^2] - T_n^2}{\sqrt{V_f[T_n^2]}} \geq \frac{C^*\delta t_n^2 - Lh^{2\beta}(1 + o(1))}{\sqrt{c_4 h_*^{2\beta+s/2}}}\right] \leq c_5 h_*^s = o(1),$$

for $c_5 > 0$ depending on $\delta$ and where we used Markov’s inequality.
3.4 Supersmooth densities and exponential noise

Unknown densities and noise densities are both supersmooth. Nevertheless, there is an essential difference with the case of Sobolev densities and polynomial noise from Subsection 3.1. Nonparametric minimax rates of testing are faster when \( r > s \) than in the case \( r < s \).

3.4.1 Case \( r < s \)

**Theorem 9** The test procedure \( \Delta_n^r \) defined in (24), for the threshold \( t_n \) and for the constant \( C^* = 1 \), attains the rate \( \psi_n \) and, under Assumption (E), \( \psi_n \) is an exact minimax rate of testing over the class \( S(\alpha, r, L) \), where

\[
  h = h = \text{is a solution of } h^{r-1-(r-1)/2} \exp \left( \frac{2\alpha}{h^r} + \frac{2\gamma}{h^s} \right) = n(1 + o(1)), \quad (29)
\]

\[
  t_n = \psi_n = \sqrt{L} \exp \left( -\frac{\alpha}{h^e} \right).
\]

**Proof.** Under the null hypothesis and for \( h = h \)

\[
  E_{f_0}[T_n^{*2}] = o(1) Le^{-2\alpha/h^r}, \quad V_{f_0}[T_n^{*2}] \leq c_1 \frac{h^{s-1}}{n^2} \exp \left( \frac{4\gamma}{h^s} \right). \quad (30)
\]

Then the first type error is bounded by

\[
  P_{f_0}[T_n^{*2} \geq C^*t_n^2] \leq \frac{c_1h^{s-1}n^{-2} \exp(4\gamma/h^s)}{(C^*t_n^2 - L \exp(-2\alpha/h^r))^2} \leq c_3h^{2-2r-(r-1)+s-1} = o(1),
\]

where we used the facts that \( h = h \) is defined by (29) and that \( r < s \). Under the alternative, use Theorem 7

\[
  B_f[T_n^{*2}] \leq Le^{-2\alpha/h^r}(1+o(1)), \quad V_f[T_n^{*2}] \leq c_1 \frac{h^{s-1}}{n^2} \exp \left( \frac{2\gamma}{h^s} - \frac{2\alpha}{h^r} \right) + c_2 \frac{h^{s-1}}{n^2} \exp \left( \frac{4\gamma}{h^s} \right).
\]

For \( C = C^*(1 + \delta) > C^*, \delta > 0 \), use Theorem 5 saying that, for \( h = h \) defined in (29), \( \psi_n^2 = t_n^2 \) are of the same order as \( \exp(-4\alpha/h^r) \) which is infinitely larger than \( \sqrt{V_f[T_n^{*2}]} \) to get

\[
  P_f[T_n^{*2} < C^*t_n^2] \leq P_f \left[ \frac{E_f[T_n^{*2}] - T_n^{*2}}{\sqrt{V_f[T_n^{*2}]}}, \frac{C^*t_n^2 - B_f[T_n^{*2}] + \|f - f_0\|_2^2}{\sqrt{V_f[T_n^{*2}]}}, \frac{C^*t_n^2 - L \exp(-4\alpha/h^r)(1 + o(1))}{\sqrt{V_f[T_n^{*2}]}}, \frac{V_f[T_n^{*2}]}{c_4 \exp(-4\alpha/h^r)} \right] = o(1),
\]

by Markov’s inequality.
3.4.2 Case \( r > s \)

Note that no lower bounds are provided for this setup. Nevertheless, we expect the rates to be optimal in the minimax sense.

**Theorem 10** The test procedure \( \Delta_n^* \) defined in (24) for the threshold \( t_n \) is a test procedure attaining the rate \( \psi_n \) over the class \( S(\alpha, r, L) \), (see (6)), where

\[
\begin{align*}
    h &= h_* = \text{is a solution of } h^{(r-1)/2} e^{2\alpha/h_*} = n(1 + o(1)), \\
    t_n &= \psi_n = \frac{h_*^{(s-1)/2}}{n} e^{2\gamma/h_*}.
\end{align*}
\]

**Proof.** Under the null hypothesis, (30) still holds. For \( h = h_* \) defined in (31), \( t_n \) is of the order of \( h_*^{(s-1)/2} e^{2\gamma/h_*} \) and the bias \( \exp(-2\alpha/h^*) = c_2 h^{-s} t_n = o(t_n) \). Thus, the first type error is smaller than \( \alpha/2 \) for some \( C_1 \) large enough.

Under the alternative,

\[
B_f[T_{n}^{s^2}] \leq L e^{-2\alpha/h^r} (1 + o(1)), \quad V_f[T_{n}^{s^2}] \leq \frac{4\Omega_g(f - f_0)}{n} + c_2 \frac{h_*^{s-1}}{n^2} e^{4\gamma/h_*}
\]

and we can prove as in Theorems 6 and 7 that \( 4\Omega_g(f - f_0) \leq C_1 \|f - f_0\|_2^2 \). Then the second type error is bounded by \( \alpha/2 + o(1) \) as soon as

\[
\frac{-\|f - f_0\|_2^2 + C_* t_n^2 + L \exp(-2\alpha/h^*)}{(C_1 \|f - f_0\|_2/n + c_2 h^{s-1} n^{-2} \exp(4\gamma/h^*))^{1/2}} \leq -z_{1-\alpha/2}.
\]

This is equivalent to

\[
\|f - f_0\|_2 \geq \max \left\{ \frac{1}{\sqrt{n}}, \frac{h_*^{(s-1)/2}}{n} e^{2\gamma/h_*} + L e^{-2\alpha/h^r} \right\},
\]

since \( h = h_* \) defined by (31) minimizes the sum on the right-hand side of the previous inequality. As a result

\[
\psi_n = c_3 \frac{h_*^{(s-1)/2}}{n} e^{2\gamma/h_*} = h_*^{(s-r)/2} e^{-2\alpha/h^r}
\]

which is infinitely smaller than the bias. Note that, the rate is indeed slower than any polynomial \( n^{-a} \), \( a > 0 \) but faster than any logarithmic rate.

4 Lower bounds

We show in a first part that proofs for minimax lower bounds for the estimation problem of \( d^2 \) and for the testing problem in \( L_2 \) come down to the same choice of hypotheses and checking similar conditions.

23
| Density \ Noise | Polynomial: $|u|^{-s}$ | Exponential: $\exp(-\gamma|u|^s)$ |
|----------------|-----------------|-----------------|
| $f \in W(\beta, L), \beta > 1/2$ | $O(1)n^{-\frac{2\beta}{\beta s + 1}}$ | $\sqrt{L}(\log n/(2\gamma))^{-\frac{\beta}{\gamma}}$ |
| $f \in S(\alpha, r, L)$ | $O(1)n^{-\frac{1}{4}}$ | $r < s : \sqrt{L}\exp(-\alpha/h_n^\alpha)$  |
| | | $r > s : O(1)\frac{h_n^{(\alpha-1)/2}}{n}\exp\left(\frac{2s}{h_n^2}\right)$ |

where $h_n$ is defined in (29) or (31) if $r < s$ or $r > s$, respectively.

Table 2: Testing rates in $L_2$-norm from noisy data

Let us define

$$
Rest := \inf_{d_n^2} \sup_{f \in W(\beta, L)} \varphi_n^{-1}E_f[|d_n^2 - d^2|]
$$

$$
R_{\text{test}} := \inf_{\Delta_n} \sup_{f \in W(\beta, L)} \left( P_{H_0}(\Delta_n = 1) + P_{H_1(\Delta, \psi_n)}(\Delta_n = 0) \right).
$$

**Lemma 1** Let $f_0$ and $f_1$ be two probability densities in the class $W(\beta, L)$, depending on $n$, and denote by $P_0^Y$, $E_0$ and $P_1^Y$, $E_1$ the probability measures of our data and the expected value when the true underlying parameters are $f_0$ and $f_1$, respectively. If

a) **estimation problem** densities are such that $\|f_1\|_2 - \|f_0\|_2 \geq 2\varphi_n$, for some $\varphi_n > 0$,

a') **test problem** densities are such that $\|f_1 - f_0\|_2 \geq C\psi_n$, for some $\psi_n > 0$,

b) $P_1 \ll P_0$ and there exists $0 < \gamma < 1$ such that

$$
\chi^2(P_0, P_1) := \text{Def} \int \left( \frac{dP_1}{dP_0} - 1 \right)^2 dP_0 \leq \gamma^2
$$

then

$$
Rest \geq (1 - \gamma)(1 - \sqrt{\gamma}) \quad \text{(32)}
$$

$$
R_{\text{test}} \geq (1 - \gamma)(1 - \sqrt{\gamma}). \quad \text{(33)}
$$

**Proof.** For the estimation problem we reduce the risk to two hypothesis:

$$
Rest \geq \inf_{d_n^2} \max_{i=0,1} \varphi_n^{-1}E_f[|d_n^2 - d_i^2|],
$$

and then use directly Lemma 4 from Butucea and Tsybakov [6], adapted from Tsybakov [37].
For the testing problem, we choose two hypotheses $f_0$ the density under $H_0$ and another density $f_1$ under $H_1$ (which implies that $\|f_1 - f_0\|_2 \geq C\psi_n$, for some $\psi_n > 0$). Then the risk for the test problem becomes

$$R_{test} \geq \inf_{\Delta_n} \left( P_0(\Delta_n = 1) + (1 - \sqrt{\gamma})P_0\left(\Delta_n = 0, \frac{dP_1}{dP_0} \geq 1 - \sqrt{\gamma}\right) \right)$$

$$\geq (1 - \sqrt{\gamma})P_0\left(\frac{dP_1}{dP_0} \geq 1 - \sqrt{\gamma}\right)$$

$$\geq (1 - \sqrt{\gamma}) \left( 1 - \frac{1}{\gamma}E_0 \left[ \left(\frac{dP_1}{dP_0} - 1\right)^2 \right] \right) \geq (1 - \gamma)(1 - \sqrt{\gamma}),$$

if Assumption b) holds.

We shall use in the proofs the following construction and Lemma 2. Let $0 < \delta < 1$ be small through the remaining proofs of lower bounds. Let $f_0$ be a density function in the Sobolev class $W(\beta, a(\delta)L)$, respectively, $S(\alpha, r, a(\delta)L)$, where $0 < a(\delta) < 1$ is a constant depending on $\delta$ defined for each setup, such that

$$f_0(x) \geq \frac{c_0}{1 + |x|^2}, \quad \forall x \in \mathbb{R}. \quad (34)$$

Moreover we want the Fourier transform $\Phi_0$ to have compact support included in $(-2\delta, 2\delta)$.

Let us note immediately that we have a similar property for $f_Y = f_0 * g$. Indeed, let $A > 1$ large enough be such that $\int_{-A}^A g(x)dx > 1/2$, then

$$f_Y^Y(x) \geq \int_{-A}^A f_0(x - y)g(y)dy \geq c_0^{Y} \min\left\{ \frac{1}{A^2}, \frac{1}{|x|^2} \right\}, \forall x \in \mathbb{R}, \quad (35)$$

where $c_0^{Y} > 0$.

**Lemma 2 (Lemma 1 in Butucea and Tsybakov [6])** For any $\delta > 0$ and any $D > 4\delta$ there exists a function $\Phi^G : R \rightarrow [0, 1]$ such that

(i) $\Phi^G$ is 3 times continuously differentiable on $R$ and its first 3 derivatives are uniformly bounded on $R$,

(ii) $\Phi^G$ is compactly supported on $(\delta, D - \delta)$ and

$$I_{(2\delta,D-2\delta)}(u) \leq \Phi^G(u) \leq I_{(\delta,D-\delta)}(u),$$

for all $u \in R$, where $I_A(u)$ denotes the indicator function of the interval $A$.

**Proof of the lower bounds in Theorems 4 and 8.** Here we check the assumptions in Lemma 1 and then (32) and (33) imply the needed results. Let us consider the density function $f_0$ in the class $W(\beta, a(\delta)L)$ for some small $0 < \delta < 1$ such that (34) holds.
Let $G$ be defined by Lemma 2 with $D = 1$ and the perturbation function $H$ be defined via its Fourier transform

$$
\Phi^H(u, h) = \sqrt{\pi L} h^{-\beta} \frac{\Phi^G(|u| - 1/h)}{1 + |u|^{2\beta}},
$$
where $\beta > 1/2$ and $h \to 0$ as $n \to \infty$.

Then the second hypothesis function $f_1$ is defined as follows

$$
f_1(x) = f_0(x) + H(x, h), \quad \text{for } h = \left(\frac{\log n}{2\gamma} - \frac{B}{2\gamma s} \log \frac{\log n}{2\gamma}\right)^{-1/s},
$$
for some constant $B \in \mathbb{R}$ fixed later on. Note that the characteristic functions verify $\Phi_1(u) = \Phi_0(u) + \Phi^H(u, h)$.

Let us see first that $f_1$ is a probability density function. Indeed, since $\Phi^H(\cdot, h)$ is 3 times continuously differentiable, then via integration by parts we get

$$
|H(x, h)| = \left| -\frac{1}{2\pi i x^3} \int e^{-iux} (\Phi^H)'(u) du \right| \leq \frac{C_H}{1 + |x|^{3}}, \quad (36)
$$
for all $x \in \mathbb{R}$, for some constant $C_H > 0$. Note also that

$$
\|H(\cdot, h)\|_{\infty} \leq \frac{1}{2\pi} \int |\Phi^H(u, h)| du \leq \sqrt{\frac{\pi}{\beta}} \frac{\int \frac{1}{u^2} \int_{\delta \leq |u|^{-1/h} \leq 1-\delta} \frac{du}{1 + |u|^{2\beta}}} {\frac{1}{\pi} \int_{1/h}^{1/h+1} \frac{du}{1 + u^{2\beta}}} \leq ch^\beta, \quad (37)
$$
which is $o(1)$ for $\beta > 1/2$ and $h \to 0$. Since $f_0$ is such that (34) holds, (36) and (37) show that $f_1$ is a non negative function.

Moreover, $\int f_1(x) dx = \Phi_1(0) = 1$ and $f_1$ is a probability density function.

Let us check now that it belongs to the class $W(\beta, L)$. Indeed,

$$
\frac{1}{2\pi} \int |\Phi^H(u, h)|^2 |u|^{2\beta} du \leq \frac{L}{2} h^{-2\beta} \int_{\delta \leq |u|^{-1/h} \leq 1-\delta} \frac{|u|^{2\beta} du}{(1 + |u|^{2\beta})^2} \leq Lh^{-2\beta} \int_{1/h+\delta}^{1/h+1-\delta} \frac{du}{u^{2\beta}} \leq \frac{L}{2\beta - 1} h^{-2\beta} \left[ \left( \frac{1}{h} + \delta \right)^{-2\beta + 1} - \left( \frac{1}{h} + 1 - \delta \right)^{-2\beta + 1} \right] \leq L(1 - 2\delta)(1 + o(1)) \leq L(1 - \delta),
$$
for $n$ large enough. So, $H$ belongs to $W(\beta, L(1 - \delta))$, implying that

$$
\left\| \frac{1}{2\pi} \int |\Phi_1|^2 \right\|_2 \leq \left\| \frac{1}{2\pi} \int |\Phi_0|^2 \right\|_2 + \left\| \frac{1}{2\pi} \int |\Phi^H(\cdot, h)|^2 \right\|_2 \leq \sqrt{L},
$$
26
for $a(\delta) = (1 - \sqrt{1 - \delta})^2$. Then $f_1 \in W(\beta, L)$.

Let us check a), respectively a') in Lemma 1. Note that $\Phi_0$ and $\Phi^H(\cdot, h)$ have disjoint supports for all $h > 0$ and then by Plancherel formula

$$||f_1||_2^2 - ||f_0||_2^2 = \|f_1 - f_0\|^2_2 = \frac{1}{2\pi} \int |\Phi^H(u, h)|^2 du.$$ 

Thus, it is enough to deal with

$$\|f_1 - f_0\|^2_2 = \frac{1}{2\pi} \int \frac{|\Phi^G(|u| - 1/h)|^2}{(1 + |u|^{2\beta})^2} du$$

$$\geq \frac{L}{2} \frac{h^{-2\beta}}{1/h + 1/2h} \int_{|u| \leq 1/h + 1/2h} \frac{du}{(1 + |u|^{2\beta})^2}$$

$$\geq \frac{Lh^{-2\beta}}{1/h + 1/2h} \int_{|u| \leq 1/h + 1/2h} du$$

$$\geq \frac{Lh^{-2\beta}(1 - 4\delta)(1 + o(1))}{(1 + (1/h)^{2\beta})^2} \geq Lh^{2\beta},$$

for small $0 < \delta < 1$ and large enough $n$. Note that this construction provides the right constant for testing, but not for the estimation of $d^2$.

Let us check b) of Lemma 1. Note first that $\chi^2(P_0, P_1) \leq C n \chi^2(f_0^Y, f_1^Y)$, for some constant $C > 0$, if $n \chi^2(f_0^Y, f_1^Y)$ is small. We use again the property (35) of $f_0^Y$:

$$n \chi^2(f_0^Y, f_1^Y) = n \int \frac{(f_1^Y - f_0^Y)^2(y)}{f_0^Y(y)} dy$$

$$\leq \frac{n}{c_0} \left(A^2 \int_{|y| \leq A} (H(\cdot, h) * g)^2(y) dy + \int_{|y| > A} g^2(H(\cdot, h) * g)^2(y) dy \right)$$

$$\leq \frac{n}{c_0} A^2 \|H(\cdot, h) * g\|_2^2 + \frac{n}{c_0^2} \int \left|\Phi^H(u, h) \Phi^g(u)\right|^2 du. \quad (38)$$

On the one hand, let

$$T_1 := n \|H(\cdot, h) * g\|_2^2 = \frac{n}{2\pi} \int \left|\Phi^H(u, h) \Phi^g(u)\right|^2 du$$

$$\leq O(1) nh^{-2\beta} \int_{1/h + \delta \leq |u| \leq 1/h + 1/2h} \frac{\exp(-2\gamma |u|^s)}{(1 + |u|^{2\beta})^2} du$$

$$\leq O(1) nh^{-2\beta} \int_{1/h}^\infty \frac{\exp(-2\gamma u^s)}{(1 + u^{2\beta})^2} du$$

$$\leq O(1) nh^{2\beta + s - 1} \exp \left( - \frac{2\gamma}{h^s} \right), \quad (39)$$

27
for \( h > 0 \) small enough. On the other hand, under the additional Assumption (E)

\[
T_2 := n \int |(\Phi^H(u, h)\Phi^g(u))|^2 \, du \\
\leq O(1)nh^{-2\beta} \int_{-1/h}^{1/h} |u|^{2A} e^{-2\gamma|u|} \, du \\
\leq O(1)nh^{-2\beta - 2A + s - 1} \exp\left(-\frac{2\gamma}{h^s}\right),
\]

for some fixed \( A \in \mathbb{R} \). If we choose some \( B < \min\{2\beta + s - 1, -2\beta - 2A + s - 1\} \), we conclude from (38), (39) and (40) that

\[
n^2(Y, f_Y) \leq o(1)nh^B \exp\left(-\frac{2\gamma}{h^s}\right) = o(1),
\]

by the choice of \( h \).

**Proof of the lower bounds in Theorems 5 and 9.** The proof in this case is very similar to the previous one and it can be easily adapted from Butucea and Tsybakov [6] (\( L_2 \) case). Let us choose \( f_0 \) such that (34) holds and such that the support of \( \Phi_0 \) be included in \((-2\delta, 2\delta)\). For \( \Phi^G \) defined in Lemma 2, let \( H \) be defined via its Fourier transform

\[
\Phi^H(u, h) = \sqrt{2\pi\alpha r} L(d-1)h^{(1-r)/2} e^{(d-1)\alpha/h^r} \exp(-\alpha d|u|^r) \Phi^G(|u|^r - 1/h^r),
\]

where \( d = \delta^{-1/2} \) and \( D = D(\delta) \to \infty \) as \( \delta \to 0 \), such that \( D\delta \to 0 \). We know then, that \( f_1 = f_0 + H(\cdot, h) \) belongs to \( S(\alpha, r, L) \) as soon as \( a(\delta) < (1 - e^{-\alpha(d-1)\delta})^2 \).

We can actually consider \( h \) solution of the equation

\[
n \exp\left(-\frac{2\alpha}{h^r} - \frac{2\gamma}{h^s}\right) = \exp(-(\log \log n)^2).
\]

Then,

\[
\|f_1\|_2^2 - \|f_0\|_2^2 = \|f_1-f_0\|_2^2 \geq L \exp\left(-\frac{2\alpha}{h^r}\right) (1-\sqrt{\delta})[e^{-4\alpha\sqrt{\delta}} - e^{-2\alpha(D-2\delta)/\sqrt{\delta}}](1+o(1)),
\]

as \( n \to \infty \). It is easy to prove that \( L \exp(-2\alpha/h^r) = L \exp(-2\alpha/h_*^r)(1+o(1)) \), where \( h_* \) is defined in (29). This means we checked (a) and (a*) in Lemma 1. Following the same ideas as in the previous proof, under the additional Assumption (E), there exists some \( B \in \mathbb{R} \) fixed such that (b) of Lemma 1:

\[
n^2(Y, f_Y) \leq o(1)nh^B \exp\left(-\frac{2\alpha}{h^r} - \frac{2\gamma}{h^s}\right) \leq o(1)
\]

by the choice of \( h \). Again, this proof gives exact minimax testing rates.
Proof of the lower bounds in Theorems 2 and 6. This proof is based on a large family of hypotheses. A similar reasoning proves that the same construction is valid for proving lower bounds for both quadratic functional estimation and nonparametric testing in $L_2$.

Note that this setup includes Theorem 2 for $\beta < s + 1/4$. This is not a contradiction, since the lower bounds here are much slower than the parametric $n^{-1/2}$ rate that the estimator attained, see Theorem 1.

Let $\theta_j$, $j = 1, \ldots, M$, be independent Bernoulli random variables and let $\Pi$ be the probability measure associated to them. For $h > 0$ small as $n \to \infty$ and for a function $H$ to be defined later, let

$$f_\theta(x) = f_0(x) + \sum_{j=1}^{M} \theta_j h^{\beta+s+1} H_h(x-x_j), \quad (41)$$

where $H_h(\cdot) = 1/h H(\cdot/h)$, $x_j = jh$ and $M$ is an integer such that $M/h = 1 - o(1)$, as $n \to \infty$ and $h$ small. Note that observations $Y_i$, $i = 1, \ldots, n$, when the underlying density is $f_\theta$, have density

$$f_\theta^Y(x) = f_0^Y(x) + \sum_{j=1}^{M} \theta_j h^{\beta+s+1} G_h(x-x_j), \quad (42)$$

where the function $G$ is defined in Lemma 3 and $H$ is such that

$$\Phi^G(u) = \Phi^H(u) \Phi^g \left( \frac{u}{h} \right). \quad (43)$$

Indeed,

$$(H_h(\cdot-x_j) * g)(x) = H_h * g(x-x_j) = G_h(x-x_j).$$

Using Lemmas 4 and 5, we see that the hypotheses fit into the model, i.e. $f_\theta$ are density functions for all $\theta$, belonging to the Sobolev class $W(\beta, L)$ and such that

$$\Pi \left[ \| f_\theta - f_0 \|_2^2 \right] \geq C n^{-4\beta/(4\beta + 4s+1)} \to 1,$$

as $n \to \infty$, for fixed $c > 0$.

**Lemma 3** Let the function $G : [-1, 0] \to \mathbb{R}$ be defined by

$$G(x) = \exp \left( -\frac{1}{1 - (4x+3)^2} \right) I(-1 \leq x \leq -1/2) - \exp \left( -\frac{1}{1 - (4x+1)^2} \right) I(-1/2 < x \leq 0).$$

Then $G$ is an infinitely differentiable function, such that $\int G(x) dx = 0$ and having all polynomial moments finite. Its Fourier transform is such that

$$|\Phi^G(u)| \leq C_G \exp(-a \sqrt{|u|}), \text{ as } |u| \to \infty,$$

for some positive constants $C_G$, $a > 0$. Moreover $\Phi^G$ is an infinitely differentiable, bounded function.
This construction is based on the function \( f_a \) in Lepski and Levit [24], p. 133 and the asymptotic behaviour of its Fourier transform follows from the reference therein. All other statements have classical proofs for Fourier and inverse Fourier transforms of functions in \( L_1 \) and \( L_2 \).

We stress the fact that in this setup, hypotheses functions \( f_\theta \) belong to \( H_1(C, \psi_n) \) with probability which tends to 1 when \( n \to \infty \). In order to bound from below the risk, very small modification is needed in the proof of Lemma 1 that we do not discuss in detail here. The last thing to check is that the distance between resulting models is finite:

\[
\Delta^2 := E_{f_0} \left[ \left( \prod_{i=1}^n f_\theta^Y(Y_i) / \prod_{i=1}^n f_0^Y(Y_i) \right)^2 \right] 
\]

\[
= E_{f_0} \left[ \left( \int \prod_{i=1}^n f_\theta^Y(Y_i) / f_0^Y(Y_i) \pi(d\theta) \right)^2 \right] - 1 
\]

\[
= E_{f_0} \left[ \left( \int \prod_{i=1}^n \left( 1 + \sum_{j=1}^M \theta_j h^{\beta+s+1} \frac{G_h(Y_i - x_j)}{f_0^Y(Y_i)} \right) \pi(d\theta) \right)^2 \right] - 1. 
\]

Now, call \( Y_{i,j} \) those observations \( Y_i \) belonging to the support of \( G_h(\cdot - x_j) \) and since those intervals are disjoint we write

\[
\Delta^2 = E_{f_0} \left[ \left( \prod_{i=1}^n \prod_{j=1}^M \left( 1 + \theta_j h^{\beta+s+1} \frac{G_h(Y_{i,j} - x_j)}{f_0^Y(Y_{i,j})} \right) \pi(d\theta) \right)^2 \right] - 1 
\]

\[
= \prod_{j=1}^M E_{f_0} \left[ \left( \int \prod_{i=1}^n \left( 1 + \theta_j h^{\beta+s+1} \frac{G_h(Y_{i,j} - x_j)}{f_0^Y(Y_{i,j})} \right) \pi(d\theta) \right)^2 \right] - 1 
\]

\[
\leq \prod_{j=1}^M \left\{ \frac{1}{2} \left( 1 + h^{2\beta+2s+2} E \left[ \left( \frac{G_h(Y_{1,j} - x_j)}{f_0^Y(Y_{1,j})} \right)^2 \right] \right)^n - 1 \right\} 
\]

where we used the facts that \( (a+b)^2 \leq 2a^2 + 2b^2 \) and that \( \int G = 0 \) giving

\[
E \left[ \frac{G_h(Y_{1,j} - x_j)}{f_0^Y(Y_{1,j})} \right] = 0. 
\]

Use Lemma 5 and expressions of \( M \) and \( h \) in \( n \) to get

\[
\Delta^2 \leq \left( 1 + c_3 n^2 \left( h^{2\beta+2s+2} E \left[ \left( \frac{G_h(Y_{1,j} - x_j)}{f_0^Y(Y_{1,j})} \right)^2 \right] \right)^2 \right)^M - 1 
\]

\[
\leq c_4 M n^2 h^{4\beta+4s+2} \leq c_5. 
\]
Lemma 4. For all $\theta \in \{-1, 1\}^M$ and for $h > 0$ which tends to 0 as defined Theorems 2 and 6, then

1. the functions $f^Y_\theta$ given by (42), with $G$ defined in Lemma 3 are probability density functions, i.e. non-negative functions of integral equal to 1,

2. the functions $f_\theta$ given by (41), with $H$ defined by (43) and Lemma 3 are probability density functions, given Assumption (P) and that $\Phi^\theta(u) \neq 0$ for all $u \in \mathbb{R}$.

Proof. 1. It is easy to see that $\int f^Y_\theta(x)dx = 1$, since $\int G(x)dx = 0$ and $f^Y_0$ is a probability density function, positive on $R$. We have to check that $f^Y_\theta$ is non-negative on $[0,1]$. For all $j = 1, \ldots, M$ and for $x$ in the support of the function $G_h(\cdot - x_j)$ we have $f^Y_\theta(x) = f^Y_0(x) + \theta_j h^{\beta+s+1}G_h(x - x_j)$. Then

$$f^Y_\theta(x) \geq \inf_{0 \leq s \leq 1} f^Y_0(x) - h^{\beta+s} \sup_x |G((x - x_j)/h)| \geq c^Y_1 - o(1) > 0,$$

for $n$ large enough.

2. Let us note first that $\Phi^H(0) = \Phi^G(0)/\Phi^\theta(0) = 0$, implying that $\int H(x)dx = 0$. Moreover, $\Phi^H$ is in $L_1$ and $L_2$, uniformly continuous function. Then $\int f_\theta(x)dx = 1$. In order to study its positivity, we use two methods. First, for $x$ small enough we use

$$h^{\beta+s+1}|H_h(x)| \leq h^{\beta+s+1} \frac{1}{2\pi} \int \left| \frac{\Phi^G(hu)}{\Phi^\theta(u)} \right| du$$

$$\leq h^{\beta+s+1} \frac{1}{2\pi} \left( \int_{|u| \leq A} |v_0^{-1}|\Phi^G(hu)|du + \int_{|u| > A} c_3 |u|^s |\Phi^G(hu)|du \right)$$

$$\leq c_4 h^{\beta+s} \int_{|v| \leq Ah} |\Phi^G(v)|dv + c_5 h^\beta \int_{|v| > Ah} |v|^s |\Phi^G(v)|dv \leq c_6 h^{\beta}s\text{ (44)}$$

for $A > \max\{A_1, A_2\}$ large enough (see Assumption (P)). For $x$ large, we need a sharper bound that we get using derivability and boundedness properties of $\Phi^G$

$$h^{\beta+s+1}|H_h(x)| = h^{\beta+s+1} \frac{1}{2\pi} \left| \int e^{-ixu} \frac{\Phi^G(hu)}{\Phi^\theta(u)} du \right|$$

$$= h^{\beta+s+1} \left[ \exp\left(-ixu\right) \frac{\Phi^G(hu)}{\Phi^\theta(u)} \right]_{-\infty}^{\infty} + \frac{1}{2\pi i x} \left| \int e^{-ixu} \frac{\partial \Phi^G(hu)}{\partial u} \Phi^\theta(u) du \right|$$

$$\leq h^{\beta+s+1} \frac{1}{2\pi x} \left( \int \left| \frac{\Phi^G(hu)}{\Phi^\theta(u)} \right| dv + \int \left| \frac{\Phi^G(hu)\Phi^\theta(u)'}{(\Phi^\theta(u))^2} \right| du \right).$$

We split both integrals as above and obtain

$$h \int \left| \frac{\Phi^G(hu)}{\Phi^\theta(u)} \right| dv \leq h \int_{|u| \leq A} u_0^{-1}|(\Phi^G)'(hu)|du + h \int_{|u| > A} c_7 |u|^s |\Phi^G(hu)|du$$

$$\leq c_8 + c_9 h^{-s} \leq c_9 h^{-s},$$
respectively, under Assumption (P),
\[
\int \left| \frac{\Phi^G(hu)(\Phi^G(u))'}{(\Phi^G(u))^2} \right| du \leq \int_{|u| \leq A} c_{13} |\Phi^G(hu)| du + \int_{|u| > A} c_{14} |u|^{-1} |\Phi^G(hu)| du \leq c_{13} h^{-1} + c_{14} h^{-s} \leq c_{15} h^{-s}.
\]
So, for \( x \) not equal to 0 we have \( h^{\beta+s+1} |H_h(x)| \leq (2\pi |x|)^{-1} h^{\beta+1} (c_{10} + c_{15}) \).

This bound is not sufficient, so we repeat integration by parts and, under Assumption (P), we get
\[
h^{\beta+s+1} |H_h(x)| \leq c_{16} \frac{h^{\beta+2}}{|x|^2}.
\] (45)

Let us go back to \( f_\theta \). Whenever \( x \) is in \([ (j - 1)/h, j/h ] \) for some \( j = 1, \ldots, M \), we apply (44) on the interval and on small neighbouring intervals, respectively (45) for \( x \) far enough from \( x_j \). Then
\[
|f_\theta(x)| \geq |f_0(x)| - \sum_{k \in \{j, j+1\}} h^{\beta+s+1} |H_h(x - x_k)| - \sum_{k=1, |k-j| > 1}^M h^{\beta+s+1} |H_h(x - x_k)|
\]
\[
\geq c_0^Y - 3c_6 h^\beta - \sum_{k=1, |k-j| > 1}^M \frac{c_{16} h^{\beta+2}}{|k-j|^2 h^2}
\]
\[
\geq c_0^Y - c_6 h^\beta - c_{17} h^\beta \sum_{k=1}^M \frac{1}{k^2} > 0
\]
for \( n \) large enough, since the last sum is finite. For \( x < 0 \) we use \( |x - x_j| \geq |x| \) for all \( j = 1, \ldots, M \) and
\[
|f_\theta(x)| \geq |f_0(x)| - c_{16} h^{\beta+2} \frac{M}{|x|^2} \geq |f_0(x)| - \frac{c_{18} h^{\beta+1}}{|x|^2} > 0,
\]
for \( x \) in a compact set. For large \( |x| \), we apply (35) and integration by parts up to 3rd derivatives of \( \Phi^H \) using Assumption (P), then
\[
|f_\theta(x)| \geq \frac{c_0}{1 + |x|^2} - \frac{c_{19}}{|x|^3} > 0.
\]
For \( x > 1 \) we use \( |x - x_j| \geq |x - 1| \) and a similar reasoning.

Lemma 5
1. The density functions \( f_\theta \) given by (41), with \( H \) defined by (43) and Lemma 3 are in the Sobolev class for any \( n \) large enough;

2. The density functions \( f_\theta \) are such that
\[
\Pi \left( \|f_\theta - f_0\|_2^2 \geq C n^{-\frac{4\beta}{4\beta + 4\beta + 1}} \right) \to 1, \text{ as } n \to \infty.
\]

32
3. The function $G$ defined in Lemma 4 is such that for all $j = 1, \ldots, M$

$$h^{2\beta+2s+2} E \left[ \left( \frac{G_h(Y_1 - x_j)}{f_0^3(Y_1)} \right)^2 \right] \leq O(1) h^{2\beta+2s+1} = o(1), \text{ as } n \to \infty.$$ 

**Proof.** Let us see that

$$\|f^{(\beta)}_\theta - f^{(\beta)}_0\|^2 = \sum_{j,k=1}^M \theta_j \theta_k h^{2\beta+2s+2} \int H_h^{(\beta)}(x - x_j) H_h^{(\beta)}(x - x_k) dx$$

$$= \frac{1}{2\pi} \sum_{j=1}^M h^{2\beta+2s+2} \int \Phi^H(hu) \overline{\Phi^H(hu)} |u|^{2\beta} du$$

$$+ \frac{1}{2\pi} \sum_{j \neq k}^M \theta_j \theta_k h^{2\beta+2s+2} \int \Phi^H(hu) \overline{\Phi^H(hu)} |u|^{2\beta} e^{iu(x_j-x_k)} du. \quad (46)$$

We prove that the terms in the last sum are bounded by a constant. Indeed,

$$\frac{1}{2\pi} \sum_{j=1}^M h^{2\beta+2s+2} \int \Phi^H(hu) \overline{\Phi^H(hu)} |u|^{2\beta} du$$

$$\leq c_1 h^{2\beta+2s+1} \int |u|^{2\beta} |\Phi^G(hu)|^2 \frac{|\Phi^G(u)|^2}{|\Phi^G(u)|^2} du$$

$$\leq c_2 h^{2\beta+2s+1} \int_{|u| \leq A} |u|^{2\beta} |\Phi^G(hu)|^2 du + c_3 h^{2\beta+2s+1} \int_{|u| > A} |u|^{2\beta+2s} |\Phi^G(hu)|^2 du$$

$$\leq c_4 \int |u|^{2\beta+2s} |\Phi^G(u)|^2 du (1 + c_5 h^{2s}) \leq C$$

where $A > A_{1,2}$ in Assumption (P) and this is strictly smaller than $L$ if we multiply $\Phi^G$ with a constant. Note that $\Phi^G$ multiplied by any polynomial is still integrable, which is equivalent to saying that $G$ is an infinitely differentiable function. Moreover, $\Phi^G$ and therefore $|\Phi^G|^2 = \Phi^G \overline{\Phi^G}$ are infinitely differentiable functions.

In the second term of (46), we use derivability of order 2 of $\Phi^G$ and Assump-
tion (P) as in the proof of Lemma 4, 2.,

\[
\left| \sum_{j \neq k}^{M} \theta_j \theta_k h^{2\beta+2s+2} \int \Phi^H(hu) \Phi^H(hu) |u|^{2\beta} e^{iu(x_j - x_k)} du \right|
\]

\[
\leq \sum_{j, k, j \neq k}^{M} h^{2\beta+2s+2} \left[ \frac{1}{i(x_j - x_k)} \left( \Phi^H(hu) \right)^2 |u|^{2\beta} \right]_{-\infty}^{\infty} + \frac{1}{i(x_j - x_k)} \int e^{iu(x_j - x_k)} \frac{\partial}{\partial u} \left| \Phi^G(hu) \right|^2 du
\]

\[
\leq \sum_{j, k, j \neq k}^{M} h^{2\beta+2s+2} \left| \frac{1}{|x_j - x_k|^2} \int \frac{\partial}{\partial u} \left| \Phi^G(hu) \right|^2 du \right|
\]

\[
\leq O(1) h \sum_{j, k, j \neq k}^{M} \frac{1}{|j - k|^2} = c_6 h \cdot 2 \sum_{k=1}^{M} \frac{M - k}{k^2} \leq C
\]

and we conclude that \( f_\theta \) belongs to the class \( W(\beta, L) \).

2. Similarly to the above calculations, we write

\[
\|f_\theta - f_0\|_2^2 = \frac{1}{2\pi} \sum_{j=1}^{M} h^{2\beta+2s+2} \int \left| \Phi^H(hu) \right|^2 du
\]

\[
+ \frac{1}{2\pi} \sum_{j, k, j \neq k}^{M} h^{2\beta+2s+2} \theta_j \theta_k \int \left| \Phi^H(hu) \right|^2 e^{iu(x_j - x_k)} du.
\]

Note that \( E_\Pi[\|f_\theta - f_0\|_2^2] = (2\pi)^{-1} \sum_{j=1}^{M} h^{2\beta+2s+2} \int |\Phi^H(hu)|^2 du \).

Using the same splitting technique, (4) and Assumption (P)

\[
\frac{1}{2\pi} \sum_{j=1}^{M} h^{2\beta+2s+2} \int \left| \Phi^H(hu) \right|^2 du
\]

\[
\geq c_1 M h^{2\beta+2s+2} \left( \int_{|u| > A} |u|^{2s} |\Phi^G(hu)|^2 du + \int_{|u| \leq A} |\Phi^G(hu)|^2 du \right)
\]

\[
\geq c_2 M h^{2\beta+1} \left( \int |u|^{2s} |\Phi^G(hu)|^2 du + \int |\Phi^G(hu)|^2 du \right) \geq c_n n^{-\frac{4\beta}{\beta + 1 + s}}.
\]

Now, by Chebychev inequality, for \( C = c(1 - e_n) \) and for \( e_n = (\log n)^{-1} = o(1) \), we have

\[
\Pi \left( \|f_\theta - f_0\|_2^2 \geq C\psi_n^2 \right)
\]

\[
\geq \Pi \left( \left| \sum_{j, k, j \neq k}^{M} \theta_j \theta_k h^{2\beta+2s+2} \int \left| \Phi^H(hu) \right|^2 e^{iu(x_j - x_k)} du \right| \leq c c_n \psi_n^2 \right)
\]

\[
\geq 1 - \frac{1}{c^2 c_n \psi_n^2} E_\Pi \left[ \left( \left| \sum_{j, k, j \neq k}^{M} \theta_j \theta_k h^{2\beta+2s+2} \int \left| \Phi^H(hu) \right|^2 e^{iu(x_j - x_k)} du \right| \right)^2 \right] (47)
\]

34
At last, using again derivatives of order 2 and Assumption (P)

\[ E_{\Pi} \left[ \left( \sum_{j,k,j \neq k}^{M} \theta_j \theta_k h^{2+2s+2} \left\| \Phi^H(hu) \right\| e^{iu(x_j-x_k)} du \right)^2 \right] \]

\[ \leq \sum_{j,k,j \neq k}^{M} h^{4+4s+4} \frac{c_3^2}{|x_j - x_k|^4} \left( \int \frac{\partial^2}{\partial u^2} \left| \Phi^H(hu) \right|^2 du \right)^2 \]

\[ \leq \sum_{j,k,j \neq k}^{M} h^{4+4s} \frac{c_3^2}{|j - k|^4} \left( \int \frac{\partial^2}{\partial u^2} \left| \Phi^G(hu) \right|^2 du \right)^2 \]

\[ \leq c_4 h^{4+2s+2} \sum_{k=1}^{M} \frac{M - k}{k^4} \leq c_5 h^{4+1}. \]

This last term is an $o(c^2_1 \psi^4_i)$ and together with (47) it finishes the proof.

3. Use positivity and continuity of $f^Y_0$ to get $\inf_{-1 \leq x \leq 2} f^Y_0(x) = c^Y_1 > 0$ and obtain

\[ h^{2+2s+2} E \left[ \left( \frac{G_h(Y_1 - x_j)}{f^Y_0(Y_1)} \right)^2 \right] = h^{2+2s+1} \int_{-1}^{0} \frac{G^2(z)dz}{f^Y_0(x_j + hx)} dx \]

\[ \leq (c^Y_1)^{-1} h^{2+2s+1} \int G^2(z)dz. \]

\[ \Box \]

5 Appendix

**Lemma 6** For all $f \in W(\beta, L)$, $\beta > 1/2$, $L > 0$, respectively $f \in S(\alpha, r, L)$, $\alpha, r, L > 0$, there exists a constant $M^f > 0$ depending only on the parameters of the smoothness class such that $\|f\|_2^2 \leq M^f$. Moreover, if $g$ is the density of either polynomial or exponential noise, there exists a constant $M^p > 0$ depending only on the parameters of the class and on $s$ such that

\[ \|p\|_2^2 \leq M^p, \]

and $p$ is at least $(\beta + s - 1/2)$-Lipschitz continuous.

**Proof.** It is easy to use $|\Phi| \leq 1$ and write, e.g. for $f \in W(\beta, L)$ and some $M > 0$ large enough

\[ \|f\|_2^2 = \frac{1}{2\pi} \int_{\{|u| \leq M\} \cup \{|u| > M\}} |\Phi(u)|^2 du \leq \frac{2M}{2\pi} + \frac{1}{2\pi M^{2\beta}} \int_{|u| > M} |\Phi(u)|^2 |u|^{2\beta} du \leq M^f, \]

where $M^f = M/\pi + LM^{-2\beta}$. Similar reasoning works for all other setups. It is proven in Butucea [5] that $p$ is at least $(\beta + s - 1/2)$-Lipschitz. \[ \Box \]
Lemma 7 If $\Phi, \Phi^g$ are the characteristic functions of random variables $X_1, \ldots, X_n$ and of the noise, respectively, such that $\Phi^g(u) \neq 0, \forall u \in R$, then $\Phi/\Phi^g$ is a continuous function. Moreover, $\Phi/\Phi^g$ is in $L_1$ and its $L_2$ norm is uniformly bounded in $f$, in the following setups:

1. if $f$ is in $W(\beta, L)$, see (2) and the noise is $s$-polynomial, as defined in (4), with $\beta \geq s$;

2. if $f$ is in $S(\alpha, r, L)$, see (3) and the noise is $s$-polynomial, as defined in (4);

3. if $f$ is in $S(\alpha, r, L)$, see (3) and the noise is exponential as defined in (5), with $r > s$.

Proof. Since characteristic functions are uniformly continuous (see Lukacs [28]) and $\Phi^g$ is non nul, then $\Phi/\Phi^g$ is continuous and integrable on any finite compact set $[-M, M]$, $M$ large. On the other hand, e.g. in the first setup:

$$\int_{|u| \geq M} \left| \frac{\Phi(u)}{\Phi^g(u)} \right| du \leq c \int_{|u| > M} |u|^s |\Phi(u)| du$$

and this is finite as soon as $f$ is at least $\beta$-times continuously differentiable and $\beta \geq s$.

Moreover, $\Phi/\Phi^g$ is in $L_2$ and its $L_2$ norm is uniformly bounded:

$$\|\Phi/\Phi^g\|_2^2 \leq C_1 \int_{|u| \leq M} |\Phi(u)|^2 du + C_2 \int_{|u| > M} |u|^{2\beta} |\Phi(u)|^2 du$$

$$\leq C_1(\beta, L, g) + C_2 M^{2(s-\beta)} \int_{|u| > M} |u|^{2\beta} |\Phi(u)|^2 du$$

$$\leq C_1(\beta, L, g) + \frac{C_2}{M^{2(\beta-s)}} 2\pi L = C(\beta, L, g)$$

and this constant depends only on $\beta$, $L$ and the fixed noise density $g$.

The same can be deduced in a similar way for the remaining setups. 

References


