# Limit groups and groups acting freely on $\mathbb{R}^{n}$-trees. 

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#### Abstract

We give a simple proof of the finite presentation of Sela's limit groups by using free actions on $\mathbb{R}^{n}$-trees. We first prove that Sela's limit groups do have a free action on an $\mathbb{R}^{n}$-tree. We then prove that a finitely generated group having a free action on an $\mathbb{R}^{n}$ tree can be obtained from free abelian groups and surface groups by a finite sequence of free products and amalgamations over cyclic groups. As a corollary, such a group is finitely presented, has a finite classifying space, its abelian subgroups are finitely generated and contains only finitely many conjugacy classes of non-cyclic maximal abelian subgroups.


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## 1 Introduction

Limit groups have been introduced by Z. Sela in the first paper of his solution of Tarski's problem [Sel01]. These groups appeared to coincide with the long-studied class of finitely generated fully residually free groups (see [Bau67], [Bau62], [KM98a, KM98b], [Chi95] and references).

A limit group is a limit of free groups in the space of marked groups. More precisely, if $n$ is a fixed integer, a marked group is a group together with an ordered generating family $S=\left(s_{1}, \ldots, s_{n}\right)$. Two marked groups $(\Gamma, S)$ and $\left(\Gamma^{\prime}, S^{\prime}\right)$ are close to each other in this topology if for some large $R,(\Gamma, S)$ and $\left(\Gamma^{\prime}, S^{\prime}\right)$ have exactly the same relations of length at most $R$ (see section 2.1).

Limit groups have several equivalent characterizations: a finitely generated group $G$ is a limit group if and only if it is fully residually free, if and only if it has the same universal theory as a free group, if and only if it is a subgroup of a non-standard free group ([Rem89, CG]).

One of the main results about limit groups is a structure theorem due to KharlampovichMyasnikov, Pfander and Sela ([KM98a, Pfa97, Sel01]). This theorem claims that a limit group can be inductively obtained from free abelian groups and surface groups by taking free products and amalgamations over $\mathbb{Z}$ (see Th. 7.1 below). This structure theorem implies that a limit group is finitely presented, and that its abelian subgroups are finitely generated. The goal of the paper is to give a simpler proof of this result in the broader context of groups acting freely on $\mathbb{R}^{n}$-trees.

Let's recall briefly the definition of a $\Lambda$-tree. Given a totally ordered abelian group $\Lambda$, there is a natural notion of $\Lambda$-metric space where the distance function takes its values in $\Lambda$. If $\Lambda$ is archimedean, then $\Lambda$ is isomorphic to a subgroup of $\mathbb{R}$ and we have a metric in the usual sense. When $\Lambda$ is not archimedean, there are elements which are infinitely small compared to other elements. A typical example is when $\Lambda=\mathbb{R}^{n}$ endowed with the lexicographic ordering.

A $\Lambda$-tree may be defined as a geodesic 0 -hyperbolic $\Lambda$-metric space. Roughly speaking, an $\mathbb{R}^{n}$-tree may be thought of as a kind of bundle over an $\mathbb{R}$-tree where the fibers are (infinitesimal) $\mathbb{R}^{n-1}$-trees.

In his list of research problems, Sela conjectures that a finitely generated group is a limit group if and only if it acts freely on an $\mathbb{R}^{n}$-tree ([Sel]). However, it is known that the fundamental group $\Gamma=\left\langle a, b, c \mid a^{2} b^{2} c^{2}=1\right\rangle$ of the non-orientable surface $\Sigma$ of Euler characteristic -1 is not a limit group since three elements in a free group satisfying $a^{2} b^{2} c^{2}=1$ must commute ([Lyn59], [Chi01, p.249]). But this group acts freely on a $\mathbb{Z}^{2}$-tree: $\Sigma$ can be obtained by gluing together the two boundary components of a twice punctured projective plane, so $\Gamma$ can be written as an HNN extension $F_{2} *_{\mathbb{Z}}$. The $\mathbb{Z}^{2}$-tree can be roughly described as the Bass-Serre tree of this HNN extension, but where one blows up each vertex into an infinitesimal tree corresponding to a Cayley graph of $F_{2}$ (see [Chi01, p.237] for details).

In this paper, we start by giving a proof that every limit group acts freely on an $\mathbb{R}^{n}$ tree. This is an adaptation a theorem by Remeslennikov saying that a fully residually free groups act freely on a $\Lambda$-tree where $\Lambda$ has finite $\mathbb{Q}$-rank, i. e. $\Lambda \otimes \mathbb{Q}$ is finite dimensional
([Rem92], see also [Chi01, th. 5.10]). However, Remeslennikov claims that $\Lambda$ can be chosen finitely generated, but this relies on a misquoted result about valuations (see section 3).

We actually prove that there is a closed subspace of the space of marked groups consisting of groups acting freely on $\mathbb{R}^{n}$-trees. In the following statement, an action of a group $\Gamma$ on a Bruhat-Tits tree is the action on the Bruhat-Tits tree of $S L_{2}(K)$ induced by a morphism $j: \Gamma \rightarrow S L_{2}(K)$ where $K$ is a valuation field. Note that $K$ may vary with $\Gamma$.

Theorem 3.3 (Acting freely on Bruhat-Tits trees is closed, see also [Rem92]). Let $\mathcal{B T} \subset \mathcal{G}_{n}$ be the set of marked groups $(\Gamma, S)$ having a free action on a Bruhat-Tits tree.

Then $\mathcal{B T}$ is closed in $\mathcal{G}_{n}$, and $\mathcal{B T}$ consists in groups acting freely on $\Lambda$-trees where $\Lambda \otimes \mathbb{Q}$ has dimension at most $3 n+1$ over $\mathbb{Q}$. In particular, $\mathcal{B T}$ consists in groups acting freely on $\mathbb{R}^{3 n+1}$-trees where $\mathbb{R}^{3 n+1}$ has the lexicographic ordering.

Corollary 3.4 ([Rem92]). A limit group has a free action on an $\mathbb{R}^{n}$-tree.
The main result of the paper is the following stucture theorem for groups acting freely on $\mathbb{R}^{n}$-trees (see theorem 7.2 for a more detailed version). In view of the previous corollary, this theorem applies to limit groups.

Theorem 7.1 (Dévissage theorem, simple version). Consider a finitely generated, freely indecomposable group $\Gamma$ having a free action on an $\mathbb{R}^{n}$-tree. Then $\Gamma$ can be written as the fundamental group of a finite graph of groups with cyclic edge groups and where each vertex group is finitely generated and has a free action on an $\mathbb{R}^{n-1}$-tree.

For $n=1$, Rips theorem says that $\Gamma$ (which is supposed to be freely indecomposable) is either a free abelian group, or a surface group (see [GLP94, BF95]). Hence, a limit group can be obtained from abelian and surface groups by a finite sequence of free products and amalgamations over $\mathbb{Z}$. It is therefore easy to deduce the following result:

Corollary 7.3. Let $\Gamma$ be a finitely generated group having a free action on an $\mathbb{R}^{n}$-tree. Then

- $\Gamma$ is finitely presented;
- if $\Gamma$ is not cyclic, then its first Betti number is at least 2;
- there are finitely many conjugacy classes of non-cyclic maximal abelian subgroups in $\Gamma$, and abelian subgroups of $\Gamma$ are finitely generated. More precisely, one has the following bound on the ranks of maximal abelian subgroups:

$$
\sum_{A}(\operatorname{Rk} A-1) \leq b_{1}(\Gamma)-1
$$

where the sum is taken over the set of conjugacy classes of non-cyclic maximal abelian subgroups of $\Gamma$, and where $b_{1}(\Gamma)$ denotes the first Betti number of $\Gamma$;

- $\Gamma$ has a finite classifying space, and the cohomological dimension of $\Gamma$ is at most $\max (2, r)$ where $r$ is the maximal rank of an abelian subgroup of $\Gamma$.

Remark. A combination theorem by Dahmani also shows that $\Gamma$ is hyperbolic relative to its non-cyclic abelian subgroups.

Corollary ([Sel01, KM98a, KM98b, Pfa97]). A limit group is finitely presented, its abelian subgroups are finitely generated, it has only finitely many conjugacy classes of maximal non-cyclic abelian subgroups, and it has a finite classifying space.

Finally, we can also easily derive from the dévissage theorem the existence of a principal splitting, a major step in Sela's proof of the finite presentation of limit groups (see corollary 7.4 and [Sel01, Th.3.2]).

Unlike Sela's proof, the proof we give doesn't need any JSJ theory, and does not use the shortening argument. The proof is also much shorter than the one by KharlampovichMyasnikov in [KM98a, KM98b] using algebraic geometry over groups, and the study of equations in free groups.

The paper is organized as follows: after some premilinaries in section 2, section 3 is devoted to the proof of the fact that limit groups act freely on $\mathbb{R}^{n}$-trees. Section 4 sets up some preliminary work on graph of actions on $\Lambda$-trees, which encode how to glue equivariantly some $\Lambda$-trees to get a new $\Lambda$-tree. In section 5, starting with a free action of a group $\Gamma$ on an $\mathbb{R}^{n}$-tree $T$, we study the action on the $\mathbb{R}$-tree $\bar{T}$ obtained by identifying points at infinitesimal distance, and we deduce a weaker version of the dévissage Theorem where we obtain a graph of groups over (maybe non-finitely generated) abelian groups. Section 6 contains the core of the argument: starting with a free action of $\Gamma$ on an $\mathbb{R}^{n}$-tree $T$, we build a free action on an $\mathbb{R}^{n}$-tree $T^{\prime}$ such that the $\mathbb{R}$-tree $\bar{T}^{\prime}$ has cyclic arc stabilizers. The dévissage theorem and its corollaries will then follow immediately, as shown in section 7.

After completing this work, the author learnt about the unpublished thesis of Shalom Gross, a student of Z. Sela, proving the finite presentation of finitely generated groups having a free action on an $\mathbb{R}^{n}$-tree. However, Shalom does not state a dévissage theorem over cyclic groups, but over finitely generated abelian groups.

## 2 Preliminaries

### 2.1 Marked groups and limit groups

Sela introduced limit groups in [Sel01]. For background about Sela's limit groups, see also $[\mathrm{CG}]$ or [Pau].

A marked group $(G, S)$ is a finitely generated group $G$ together with a finite ordered generating family $S=\left(s_{1}, \ldots, s_{n}\right)$. Note that repetitions may occur in $S$, and some generators $s_{i}$ may be the trivial element of $G$. Consider two groups $G$ and $G^{\prime}$ together with some markings of the same cardinality $S=\left(s_{1}, \ldots, s_{n}\right)$ and $S^{\prime}=\left(s_{1}^{\prime}, \ldots, s_{n}^{\prime}\right)$. A morphism of marked groups $h:(G, S) \rightarrow\left(G^{\prime}, S^{\prime}\right)$ is a homomorphism $h: G \rightarrow G^{\prime}$ sending $s_{i}$ on $s_{i}^{\prime}$ for all $i \in\{1, \ldots, n\}$. Note that there is at most one morphism between two marked groups, and that all morphisms are epimorphisms.

A relation in $(G, S)$ is an element of the kernel of the natural morphism $F_{n} \rightarrow G$ sending $a_{i}$ to $s_{i}$ where $F_{n}$ is the free group with basis $\left(a_{1}, \ldots, a_{n}\right)$. Note that two marked group are isomorphic if and only if they have the same set of relations.

Given any fixed $n$, we define $\mathcal{G}_{n}$ to be the set of isomorphism classes of marked groups. It is naturally endowed with the topology such that the sets $N_{R}(G, S)$ defined below form a neighbourhood basis of $(G, S)$. For each $(G, S) \in \mathcal{G}_{n}$ and each $R>0, N_{R}(G, S)$ is the set of marked groups $\left(G^{\prime}, S^{\prime}\right) \in \mathcal{G}_{n}$ such that $(G, S)$ and ( $G^{\prime}, S^{\prime}$ ) have exactly the same relations of length at most $R$. For this topology, $\mathcal{G}_{n}$ is a Hausdorff, compact, totally disconnected space.

Definition 2.1. A limit group $(G, S) \in \mathcal{G}_{n}$ is a marked group which is a limit of markings of free groups in $\mathcal{G}_{n}$.

Actually, being a limit group does not depend on the choice of the generating set. Moreover, limit groups have several equivalent characterizations: a finitely generated group is a limit group if and only if it is fully residually free, if and only if it has the same universal theory as a free group, if and only if it is a subgroup of a non-standard free group ([Rem89, CG]). We won't need those characterizations in this paper.

## $2.2 \Lambda$-trees

For background on $\Lambda$-trees, see [Bas91, Chi01].
Totally ordered abelian groups A totally ordered abelian group $\Lambda$ is an abelian group with a total ordering such that for all $x, y, z \in \Lambda, x \leq y \Rightarrow x+z \leq y+z$. Our favorite example will be $\mathbb{R}^{n}$, with the lexicographic ordering. In all this paper, $\mathbb{R}^{n}$ will always be endowed with its lexicographic ordering. To fix notations, we use the little endian convention: the leftmost factor will have the greatest weight. More precisely, if $\Lambda_{1}$ and $\Lambda_{2}$ are totally ordered abelian groups, the lexicographic ordering on $\Lambda_{1} \oplus \Lambda_{2}$ is defined by $\left(x_{1}, x_{2}\right) \leq\left(y_{1}, y_{2}\right)$ if $x_{1}<y_{1}$ or $\left(x_{1}=y_{1}\right.$ and $\left.x_{2} \leq y_{2}\right)$.

A morphism $\varphi: \Lambda \rightarrow \Lambda^{\prime}$ between two totally-ordered abelian groups is a non-decreasing group morphism. Given $a, b \in \Lambda$, the subset $[a, b]=\{x \in \Lambda \mid a \leq x \leq b\}$ is called the segment between $a$ and $b$. A subset $E \subset \Lambda$ is convex if for all $a, b \in E,[a, b] \subset E$. The kernel of a morphism is a convex subgroup, and if $\Lambda_{0} \subset \Lambda$ is a convex subgroup, then $\Lambda / \Lambda_{0}$ has a natural structure of totally ordered abelian group. By proper convex subgroup of $\Lambda$, we mean a convex subgroup strictly contained in $\Lambda$.

The set of convex subgroups of $\Lambda$ is totally ordered by inclusion. The height of $\Lambda$ is the (maybe infinite) number of proper convex subgroups of $\Lambda$. Thus, the height of $\mathbb{R}^{n}$ is $n$. $\Lambda$ is archimedean if its height is at most 1 . It is well known that a totally ordered abelian group is archimedean if and only if it is isomorphic to a subgroup of $\mathbb{R}$ (see for instance [Chi01, Th.1.1.2])

If $\Lambda_{0} \subset \Lambda$ is a convex subgroup, then any element $\lambda_{0} \in \Lambda_{0}$ may be thought as infinitely small compared to an element $\lambda \in \Lambda \backslash \Lambda_{0}$ since for all $n \in \mathbb{N}, n \lambda_{0} \leq \lambda$. Therefore, we will say that an element in $\mathbb{R}^{n}$ is infinitesimal if it lies in the maximal proper convex subgroup of $\mathbb{R}^{n}$, which we casually denote by $\mathbb{R}^{n-1}$. Similarly, for $p \leq n$, we will identify $\mathbb{R}^{p}$ with the corresponding convex subgroup of $\mathbb{R}^{n}$. The magnitude of an element $\lambda \in \mathbb{R}^{n}$ is the smallest $p$ such that $\lambda \in \mathbb{R}^{p}$. Thus $\lambda \in \mathbb{R}^{n}$ is infinitesimal if and only if its magnitude is at most $n-1$.

Given a totally ordered abelian group $\Lambda, \Lambda \otimes \mathbb{Q}$ has a natural structure of a totally ordered abelian group by letting $\frac{\lambda}{n} \leq \frac{\lambda^{\prime}}{n^{\prime}}$ if and only if $n^{\prime} \lambda \leq n \lambda^{\prime}$.
$\Lambda$-metric spaces and $\Lambda$-trees A $\Lambda$-metric space $(E, d)$ is a set $E$ endowed with a map $d: E \times E \rightarrow \Lambda_{\geq 0}$ satisfying the three usual axioms of a metric: separation, symmetry and triangle inequality. The set $\Lambda$ itself is a $\Lambda$-metric space for the metric $d(a, b)=|a-b|=$ $\max (a-b, b-a) \in \Lambda$. A geodesic segment in $E$ is an isometric map from a segment $[a, b] \subset \Lambda$ to a subset of $E$. A $\Lambda$-metric space is geodesic if any two points are joined by a geodesic segment. We will denote by $[x, y]$ a geodesic segment between two points in $E$ (which, in this generality, might be non-unique).

Note that even in a set $\Lambda$ like $\mathbb{R}^{n}$, the upper bound is not always defined so one cannot easily define a $\Lambda$-valued diameter (see however [Chi01, p.99] for a notion of diameter as a interval in $\Lambda$ ). Nevertheless, we will say that a subset $F$ of a $\mathbb{R}^{n}$-metric space $E$ is
infinitesimal if the distance between any two points of $F$ is infinitesimal. Similarly, we define the magnitude of $F$ as the smallest $p \leq n$ such that the distance between any two points of $F$ has magnitude at most $p$.

We give two equivalent definitions of a $\Lambda$-tree. The equivalence is proved for instance in [Chi01, lem. 2.4.3, p. 71].

Definition 2.2. $A \Lambda$-tree $T$ is a geodesic $\Lambda$-metric space such that

- $T$ is 0-hyperbolic in the following sense:

$$
\forall x, y, u, v \in T, d(x, y)+d(u, v) \leq \max \{d(x, u)+d(y, v), d(x, v)+d(y, u)\}
$$

- $\forall x, y, z \in T, d(x, y)+d(y, z)-d(x, z) \in 2 \Lambda$

Equivalently, a geodesic $\Lambda$-metric space is a $\Lambda$-tree if

- the intersection of any two geodesic segments sharing a common endpoint is a geodesic segment
- if two geodesic segments intersect in a single point, then their union is a geodesic segment.

Remark. In the first definition, the second condition is automatic if $2 \Lambda=\Lambda$, which is the case for $\Lambda=\mathbb{R}^{n}$.

It follows from the definition that there is a unique geodesic joining a given pair of points in a $\Lambda$-tree.

Clearly, $\Lambda$ itself is $\Lambda$-tree. Another simple example of a $\Lambda$-tree is the vertex set $V(S)$ of a simplicial tree $S: V(S)$ endowed with the combinatorial distance is a $\mathbb{Z}$-tree.

### 2.3 Killing infinitesimals and extension of scalars

The following two operations are usually known as the base change functor.

Killing infinitesimals. Consider $\Lambda_{0} \subset \Lambda$ a convex subgroup (a set of infinitesimals), and let $\bar{\Lambda}=\Lambda / \Lambda_{0}$. If $\Lambda=\mathbb{R}^{n}$, we will usually take $\Lambda_{0}=\mathbb{R}^{n-1}$, so that $\bar{\Lambda} \simeq \mathbb{R}$. Consider a $\Lambda$-metric space $E$. Then the relation $\sim$ defined by $x \sim y \Leftrightarrow d(x, y) \in \Lambda_{0}$ is an equivalence relation on $E$, and the $\Lambda$-metric on $E$ provides a natural $\bar{\Lambda}$-metric on $E / \sim$. We say that $\bar{E}=E / \sim$ is obtained from $E$ by killing infinitesimals. Clearly, if $T$ is a $\Lambda$-tree, then $\bar{T}$ is a $\bar{\Lambda}$-tree. Thus, killing infinitesimals in an $\mathbb{R}^{n}$-tree $T$ provides an $\mathbb{R}$-tree $\bar{T}$. By extension, we will often denote $\mathbb{R}$-trees with a bar.

Extension of scalars Consider a $\Lambda$-tree $T$, and an embedding $\Lambda \hookrightarrow \tilde{\Lambda}$ (for example, one may think of $\mathbb{Z} \subset \mathbb{R}$ ). Then $T$ may be viewed as a $\tilde{\Lambda}$-metric space, but it is not a $\tilde{\Lambda}$-tree if $\Lambda$ is not convex in $\tilde{\Lambda}$ : as a matter of fact, $T$ is not geodesic as a $\tilde{\Lambda}$-metric space (there are holes in the geodesics). However, there is a natural way to fill the holes:

Proposition 2.3 (Extension of scalars, see [Chi01, Th. 4.7,p. 75]). There exists a $\tilde{\Lambda}$-tree $\tilde{T}$ and an isometric embedding $T \hookrightarrow \tilde{T}$ which is canonical in the following sense: if $T^{\prime}$ is another $\tilde{\Lambda}$-tree with an isometric embedding $T \hookrightarrow T^{\prime}$, then there is a unique $\tilde{\Lambda}$ isometric embedding $\tilde{T} \rightarrow T^{\prime}$ commuting with the embeddings of $T$ in $\tilde{T}$ and $T^{\prime}$.

For example, take $T$ to be the $\mathbb{Z}$-tree corresponding corresponding to the set of vertices of a simplicial tree $S$. Then the embedding $\mathbb{Z} \subset \mathbb{R}$ gives an $\mathbb{R}$-tree $\tilde{T}$ which is isometric to the geometric realization of $S$.
Remark. The proposition also holds if one only assumes that $T$ is 0 -hyperbolic. In this case, taking $\tilde{\Lambda}=\Lambda$, one gets a natural $\Lambda$-tree containing $T$.

### 2.4 Subtrees

A subtree $Y$ of a $\Lambda$-tree $T$ is a convex subset of $T$, i. e. such that for all $x, y \in Y,[x, y] \subset Y$. A subtree is non-degenerate if it contains at least two points. One could think of endowing $\Lambda$, and $T$, with the order topology. However, this is usually not adapted. For instance: $\mathbb{R}^{n}$ is not connected with respect to this topology for $n>1$. This is why we need a special definition of a closed subtree. The definition coincides with the topological definition for $\mathbb{R}$-trees.

Definition 2.4 (closed subtree). A subtree $Y \subset T$ is a closed subtree if the intersection of $Y$ with a segment of $T$ is either empty or a segment of $T$.

There is a natural projection on a closed subtree. Consider a base point $y_{0} \in Y$. Then for any point $x \in T$, there is a unique point $p \in Y$ such that $\left[y_{0}, x\right] \cap Y=\left[y_{0}, p\right]$. One easily checks that $p$ does not depend on the choice of the base point $y_{0}([p, x]$ is the bridge between $x$ and $Y$, see [Chi01]). The point $p$ is called the projection of $x$ on $Y$.

Remark. The existence of a projection is actually equivalent to the fact that the subtree $Y$ is closed. Be aware that a non-trivial proper convex subgroup of $\Lambda$ is never closed in $\Lambda$. In particular, the intersection of infinitely many closed subtrees may fail to be closed.

A linear subtree of $T$ is a subtree in which any three points are contained in a segment. It is an easy exercise to prove that a maximal linear subtree of $T$ is closed in $T$. Finally, any linear subtree $L \subset T$ is isometric to a convex subset of $\Lambda$ and any two isometries $L \rightarrow \Lambda$ differ by an isometry of $\Lambda$.

### 2.5 Isometries

An isometry $g$ of a $\Lambda$-tree $T$ can be of one of the following exclusive types:

- elliptic: $g$ has a fix point in $T$
- inversion: $g$ has no fix point, but $g^{2}$ does
- hyperbolic: otherwise.

In all cases, the set $A_{g}=\left\{x \in T \mid\left[g^{-1} x, x\right] \cap[x, g \cdot x]=\{x\}\right.$ is called the characteristic set of $g$.

If $g$ is elliptic, $A_{g}$ is the set of fix points of $g$ which is a closed subtree of $T$. Moreover, for all $x \in T$, the midpoint of $[x, g \cdot x]$ exists and lies in $A_{g}$.

If $g$ is an inversion, then $A_{g}=\emptyset$. Actually, for any $x \in T, d(x, g \cdot x) \notin 2 \Lambda$ so $[x, g \cdot x]$ has no midpoint in $T$. In particular, if $2 \Lambda=\Lambda$ (which occurs for instance if $\Lambda=\mathbb{R}^{n}$ ), inversions don't exist. Moreover, one can perform the analog of barycentric subdivision for simplicial trees to get rid of inversions: consider $\tilde{\Lambda}=\frac{1}{2} \Lambda$, and let $\tilde{T}$ be the $\tilde{\Lambda}$-tree obtained by the extension of scalars $\Lambda \subset \tilde{\Lambda}$. Then the natural extension of $g$ to $\tilde{T}$ fixes a unique point in $\tilde{T}$ (in particular, $g$ is elliptic in $\tilde{T}$ ). If $g$ is elliptic or is an inversion, its translation length $l_{T}(g)$ is defined to be 0 .

If $g$ is hyperbolic, then the set $A_{g}$ is non-empty, and is a maximal linear subtree of $T$, and is thus closed in $T$. It is called the axis of $g$. Moreover, the restriction of $g$ to $A_{g}$ is conjugate to the action of a translation $\tau: a \mapsto a+l_{T}(g)$ on a $\tau$-invariant convex subset of $\Lambda$ for some positive $l_{T}(g) \in \Lambda$. The translation length of $g$ is the element $l_{T}(g) \in \Lambda_{>0}$. If $p$ is the projection of $x$ on $A_{g}$, then for $k \neq 0, d\left(x, g^{k} \cdot x\right)=2 d(x, p)+|k| l_{T}(g)$.

Note that it may happen that $A_{g}$ is not isometric to $\Lambda$. For instance, if $\Lambda=\mathbb{R}^{2}$, the axis of an element $g$ with infinitesimal translation length can be of the form $I \times \mathbb{R}$ where $I$ is any non-empty interval in $\mathbb{R}$ which can be open, semi-open or closed.

If $g$ is hyperbolic, then for all $x \in T$, the projection of $x$ on $A_{g}$ is the projection of $x$ on $\left[g^{-1} \cdot x, g \cdot x\right]$. In particular, if the midpoint of $[x, g \cdot x]$ exists, then it lies in $A_{g}$. It also follows that if $g$ is hyperbolic and if $g^{-1} \cdot x, x, g \cdot x$ are aligned (in any order) then they lie on the axis of $g$.

If an abelian group $A$ acts by isometries on $\Lambda$-tree $T$ and contains a hyperbolic element $g$, then all the hyperbolic elements of $A$ have the same axis $l, A$ contains no inversion, and all elliptic elements fix $l$. We say that $l$ is the axis of the abelian group $A$. The axis of $A$ can be characterized as the only closed $A$-invariant linear subtree of $T$, or as the only maximal $A$-invariant linear subtree of $T$.

### 2.6 Elementary properties of groups acting freely on $\Lambda$-trees

We now recall some elementary properties of groups acting freely (without inversion) on $\Lambda$-trees. They are proved for instance in [Chi01].

Lemma 2.5. Let $\Gamma$ be a group acting freely without inversion on a $\Lambda$-tree. Then

1. $\Gamma$ is torsion free;
2. two elements $g, h \in \Gamma$ commute if and only if they have the same axis. If they don't commute, the intersection of their axes is either empty or a segment ([Chi01], proof of lem. 5.1.2 p. 218 and $R k$ p.111)
3. maximal abelian subgroups of $\Gamma$ are malnormal (property $C S A$ ) and $\Gamma$ is commutative transitive: the relation of commutation on $\Gamma \backslash\{1\}$ is transitive ([Chi01, lem. 5.1.2 p.218])

Remark. Property CSA implies that $\Gamma$ is commutative transitive.
A result known as Harrison Theorem, proved by Harrison for $\mathbb{R}$-trees and by Chiswell and Urbanski-Zamboni for general $\Lambda$-trees, says that a 2 -generated group acting freely without inversion on a $\Lambda$-tree is either a free group or a free abelian group. (see [Chi94, UZ93, Har72]). We won't use this result in this paper.

## 3 A limit group acts freely on an $\mathbb{R}^{n}$-tree

The goal of this section is to prove that limit groups act freely on $\mathbb{R}^{n}$-trees. This is an adaptation of an argument by Remeslennikov concerning fully residually free groups ([Rem92], see also [Chi01, th. 5.5.10 p. 246]). Note that it is claimed in [Rem92] that finitely generated fully residually free groups act freely on a $\Lambda$-tree where $\Lambda$ is a finitely generated ordered abelian group. However, the proof is not completely correct since it relies on a misquoted result about valuations (Th. 3 in [Rem92]) to which there are known counterexamples (for any subgroup $\Lambda \subset \mathbb{Q}$, there is valuation on $\mathbb{Q}(X, Y)$, extending the trivial valuation on $\mathbb{Q}$, whose value group is $\Lambda[\mathrm{ZS} 75, \operatorname{ch} . \mathrm{VI}, \S 15$, ex.3,4] or [Kuh, Th 1.1]).

Nevertheless, Remeslennikov's argument proves the following weaker statement: a finitely generated fully residually free group acts freely on a $\Lambda$-tree where $\Lambda$ has finite $\mathbb{Q}$-rank, i. e. $\Lambda \otimes \mathbb{Q}$ is finite dimensional over $\mathbb{Q}$.

The fact that a limit group acts freely on an $\mathbb{R}^{n}$ tree will be deduced from a more general result about group acting freely on Bruhat-Tits trees. But we first state a simpler result in this spirit (see also [GS94, GS93]). Remember that $\mathcal{G}_{n}$ denotes the space of groups marked by a generating family of cardinality $n$.

Proposition 3.1 (Acting freely on $\Lambda$-trees is closed). Let $\mathcal{T}_{n} \subset \mathcal{G}_{n}$ be the set of marked groups having a free action without inversion on some $\Lambda$-tree ( $\Lambda$ may vary with the group).

Then $\mathcal{T}_{n}$ is closed in $\mathcal{G}_{n}$.
We won't give the proof of this result since this proposition is not sufficient for us as it does not give any control over $\Lambda$. This is why we rather prove the following more technical result. 1

For general information of the action of $S L_{2}(K)$ on its Bruhat-Tits $\Lambda$-tree $B T_{K}$ where $K$ a field, and $v: K \rightarrow \Lambda \cup\{\infty\}$ is a valuation, see for instance [Chi01, §4.3,p.144]. Essentially, we will only use the existence of the Bruhat-Tits $\Lambda$-tree and the formula for the translation length of a matrix $m \in S L_{2}(K): l_{B T_{K}}(m)=\max \{-2 v(\operatorname{Tr}(m)), 0\}$. Also note that the action of $S L_{2}(K)$ on its Bruhat-Tits tree has no inversion (however, there may be inversions in $G L_{2}(K)$ ).

Definition 3.2 (Action on a Bruhat-Tits tree.). By an action of $\Gamma$ on a Bruhat-Tits tree, we mean an action of $\Gamma$ on the Bruhat-Tits $\Lambda$-tree for $S L_{2}(K)$ induced by a morphism $j: \Gamma \rightarrow S L_{2}(K)$ where $K$ is a valuated field with values in $\Lambda$.

Theorem 3.3 (Acting freely on Bruhat-Tits trees is closed, see also [Rem92]). Let $\mathcal{B T} \subset \mathcal{G}_{n}$ be the set of marked groups $(\Gamma, S)$ having a free action on a Bruhat-Tits tree. Then $\mathcal{B T}$ is closed in $\mathcal{G}_{n}$, and $\mathcal{B T}$ consists in groups acting freely on $\Lambda$-trees where $\Lambda \otimes \mathbb{Q}$ has dimension at most $3 n+1$ over $\mathbb{Q}$. In particular, $\mathcal{B T}$ consists in groups acting freely on $\mathbb{R}^{3 n+1}$-trees where $\mathbb{R}^{3 n+1}$ has the lexicographic ordering.

Corollary 3.4 ([Rem92]). A limit group has a free action on an $\mathbb{R}^{n}$-tree.
Proof of the corollary. This follows from the theorem above since a free group acts freely on a Bruhat-Tits tree.

Proof of the Theorem. We first prove that $\mathcal{B T}$ is closed. Let $\left(\Gamma_{i}, S_{i}\right) \in \mathcal{B} \mathcal{T}$ be a sequence of marked groups converging to $(\Gamma, S)$. For each index $i$, consider a field $K_{i}$ and a valuation $v_{i}: K_{i} \rightarrow \Lambda_{i}$ and an embedding $j_{i}: \Gamma \rightarrow S L_{2}\left(K_{i}\right)$ such that $j_{i}\left(\Gamma_{i}\right)$ acts freely without inversions on the corresponding Bruhat-Tits tree $B T_{i}$.

Consider $\omega$ an ultrafilter on $\mathbb{N}$, i. e. a finitely additive measure of total mass 1 (a mean), defined on all subsets of $\mathbb{N}$, and with values in $\{0,1\}$, and assume that this ultrafilter is non-principal, i. e. that the mass of finite subsets is zero. Say that a property $P(k)$ depending on $k \in \mathbb{N}$ is true $\omega$-almost everywhere if $\omega(\{k \in \mathbb{N} \mid P(k)\})=1$. Note that a

[^0]property which is not true almost everywhere is false almost everywhere. Given a sequence of sets $\left(E_{i}\right)_{i \in \mathbb{N}}$, the ultraproduct $E^{*}$ of $\left(E_{i}\right)$ is the quotient $\left(\prod_{i \in \mathbb{N}} E_{i}\right) / \sim_{\omega}$ where $\sim_{\omega}$ is the natural equivalence relation on $\prod_{i \in \mathbb{N}} E_{i}$ defined by equality $\omega$-almost everywhere.

Consider $K^{*}$ the ultraproduct of the fields $K_{i}, \Gamma^{*}$ the ultraproduct of the groups $\Gamma_{i}$, and $\Lambda^{*}$ the ultraproduct of the totally ordered abelian groups $\Lambda_{i}$. As a warmup, we prove the easy fact that the natural ring structure on $K^{*}$ makes it a field: if $k^{*}=\left(k_{i}\right)_{i \in \mathbb{N}} \neq 0$ in $K^{*}$, then for almost all $i \in \mathbb{N}, k_{i} \neq 0$, and $1 / k_{i}$ is defined for almost every index $i$, and defines an inverse $\left(1 / k_{i}\right)_{i \in \mathbb{N}}$ for $k^{*}$ in $K^{*}$.

Similarly, $\Gamma^{*}$ is a group, and $\Lambda^{*}$ a totally ordered abelian group (for the total order $\left(x_{i}\right)_{i \in \mathbb{N}} \leq\left(y_{i}\right)_{i \in \mathbb{N}}$ if and only if $x_{i} \leq y_{i}$ almost everywhere). Now consider the map $v^{*}: K^{*} \rightarrow \Lambda^{*} \cup \infty$ defined by $v^{*}\left(\left(k_{i}\right)_{i \in \mathbb{N}}\right)=\left(v_{i}\left(k_{i}\right)\right)_{i \in \mathbb{N}}$, and the map $j^{*}: \Gamma^{*} \rightarrow S L_{2}\left(K^{*}\right)$ defined by $j^{*}\left(\left(g_{i}\right)_{i \in \mathbb{N}}\right)=\left(j_{i}\left(g_{i}\right)\right)_{i \in \mathbb{N}}$. Then $v^{*}$ is a valuation on $K^{*}$, and $j^{*}$ a monomorphism of groups. We denote by $B T^{*}$ the Bruhat-Tits tree of $S L_{2}\left(K^{*}\right) \cdot\left({ }^{2}\right)$

Now, given a field $K$ with a valuation $v: K \rightarrow \Lambda \cup\{\infty\}$, a subgroup $H \subset S L_{2}(K)$ acts freely without inversions on the corresponding Bruhat-Tits tree $B T$ if and only if the translation length of any element $h \in H \backslash\{1\}$ is non-zero. But the translation length of a matrix $m \in S L_{2}(K)$ can be computed in terms of the valuation of its trace by the formula $l_{B T}(m)=\max \{0,-2 v(\operatorname{Tr}(m))\}$, so the freeness (without inversion) of the action translates into $v(\operatorname{Tr}(h))<0$ for all $h \in H \backslash\{1\}$ ([Chi01, lem.4.3.5 p.148]). Therefore, since for all $i$ and all $g_{i} \in \Gamma_{i} \backslash\{1\}, \operatorname{Tr}\left(j_{i}\left(g_{i}\right)\right)$ has negative valuation, all the elements $g^{*} \in \Gamma^{*} \backslash\{1\}$ satisfy $v^{*}\left(\operatorname{Tr}\left(j^{*}\left(g^{*}\right)\right)\right)<0$, which means that $\Gamma^{*}$ acts freely without inversion on $B T^{*}$.

Finally, there remains to check that the marked group $(\Gamma, S)$ embeds into $\Gamma^{*}$ (see for instance [CG]). We use the notation $S=\left(s_{1}, \ldots, s_{n}\right)$ and $S_{i}=\left(s_{1}^{(i)}, \ldots, s_{n}^{(i)}\right)$. Consider the family $S^{*}=\left(s_{1}^{*}, \ldots, s_{n}^{*}\right)$ of elements of $\Gamma^{*}$ defined by $s_{1}^{*}=\left(s_{1}^{(i)}\right)_{i \in \mathbb{N}}, \ldots, s_{n}^{*}=\left(s_{n}^{(i)}\right)_{i \in \mathbb{N}}$. The definition of the convergence of marked groups says that if an $S$-word represents the trivial element (resp. a non-trivial element) in $\Gamma$, then for $i$ sufficiently large, the corresponding $S_{i}$-word is trivial (resp. non-trivial) in $\Gamma_{i}$. Since $\omega$ is non-principal, this implies that the corresponding $S^{*}$-word is trivial (resp. non-trivial). This means that the map sending $\left(s_{1}, \ldots, s_{n}\right)$ to $\left(s_{1}^{*}, \ldots, s_{n}^{*}\right)$ extends to an isomorphism between $\Gamma$ and $\left\langle S^{*}\right\rangle \subset \Gamma^{*}$. Therefore, $(\Gamma, S) \in \mathcal{B T}$, so $\mathcal{B T}$ is closed.

We now prove the fact that any group $(\Gamma, S)$ in $\mathcal{B} \mathcal{T}$ acts freely on a $\Lambda$-tree where $\Lambda \otimes \mathbb{Q}$ has dimension at most $3 n+1$. So consider an embedding $j: \Gamma \rightarrow S L_{2}(K)$ where $K$ has a valuation $v: K \rightarrow \Lambda \cup\{\infty\}$ such that the induced action of $\Gamma$ on the Bruhat-Tits tree for $S L_{2}(K)$ is free without inversion. Consider the subfield $L \subset K$ generated by the $4 n$ coefficient of the matrices $j\left(s_{1}\right), \ldots, j\left(s_{n}\right)$. Since the matrices have determinant $1, L$ can be written as $L=k_{0}\left(x_{1}, \ldots, x_{3 n}\right)$ where $k_{0}$ is the prime subfield of $K$. Let $\Lambda_{L}=v(L \backslash\{0\})$ be the value group of $L$. Since $\Gamma$ embeds in $S L_{2}(L), \Gamma$ acts freely on the corresponding Bruhat-Tits $\Lambda_{L}$-tree. We now quote a result about valuations which implies that $\Lambda_{L}$ has finite $\mathbb{Q}$-rank.
Theorem 3.5 ([Bou64, cor 1 in VI.10.3]). Let $L=L_{0}\left(x_{1}, \ldots, x_{p}\right)$ be a finitely generated extension of $L_{0}$, and $v: L \rightarrow \Lambda \cup\{\infty\}$ a valuation. Denote by $\Lambda_{L}=v(L \backslash\{0\})$ (resp. $\left.\Lambda_{0}=v\left(L_{0} \backslash\{0\}\right)\right)$ the corresponding value group. Then the $\mathbb{Q}$-vector space $\left(\Lambda_{L} \otimes\right.$ $\mathbb{Q}) /\left(\Lambda_{0} \otimes \mathbb{Q}\right)$ has dimension at most $p$.

Taking $L_{0}=k_{0}$, one gets that $\Lambda_{L}$ has $\mathbb{Q}$-rank at most $3 n+1$ since $\Lambda_{0}$ is either trivial

[^1]or isomorphic to $\mathbb{Z}$.

Using the extension of scalars (base change functor), there remains to prove that if a totally ordered group $\Lambda$ has finite $\mathbb{Q}$-rank, then it is isomorphic to a subgroup of $\mathbb{R}^{n}$.

Lemma 3.6. Consider $\Lambda$ a totally ordered of $\mathbb{Q}$-rank $p$. Then $\Lambda$ is isomorphic (as an ordered group) to subgroup of $\mathbb{R}^{p}$ with its lexicographic ordering.

Remark. However, $\Lambda \otimes \mathbb{Q}$ is usually not isomorphic to $\mathbb{Q}^{p}$ with its lexicographic ordering as shows an embedding of $\mathbb{Q}^{2}$ into $\mathbb{R}$.

Proof. We first check that the height of $\Lambda$ is at most $p$ (see [Bou64, prop 3 in VI.10.2]). First, $\Lambda$ embeds into $\Lambda \otimes \mathbb{Q}$, so we may replace $\Lambda$ by $\Lambda \otimes \mathbb{Q}$ and assume that $\Lambda$ is a totally ordered $\mathbb{Q}$-vector space of dimension $p$. Any convex subgroup $\Lambda_{0} \subset \Lambda$ is a $\mathbb{Q}$ vector subspace in $\Lambda$ since if $0 \leq x \in \Lambda_{0}$, for all $k \in \mathbb{N} \backslash\{0\}, \frac{1}{k} x \in \Lambda_{0}$ since $0 \leq \frac{1}{k} x \leq x$. Now the height of $\Lambda$ is at most $p$ since a chain of convex subgroups $\Lambda_{0} \varsubsetneqq \Lambda_{1} \varsubsetneqq \cdots \varsubsetneqq \Lambda_{i}$ is a chain of vector subspaces.

We now prove by induction that a totally ordered group $\Lambda$ of finite height $q$ embeds as an ordered subgroup of $\mathbb{R}^{q}$ with its lexicographic ordering. Once again, one can replace $\Lambda$ by $\Lambda \otimes \mathbb{Q}$ without loss of generality. We argue by induction on the height. If $\Lambda$ has height 1, i. e. if $\Lambda$ is archimedean, then $\Lambda$ embeds in $\mathbb{R}$ (see for instance [Chi01, Th.1.1.2]). Now consider $\Lambda_{0} \subset \Lambda$ the maximal proper convex subgroup of $\Lambda$, and let $\bar{\Lambda}=\Lambda / \Lambda_{0}$. Since $\Lambda, \Lambda_{0}$ and $\bar{\Lambda}$ are $\mathbb{Q}$ vector spaces, one has algebraically $\Lambda=\bar{\Lambda} \oplus \Lambda_{0}$.

The fact that $\Lambda_{0}$ is convex in $\Lambda$ implies that the ordering on $\Lambda$ corresponds to the lexicographic ordering on $\Lambda \oplus \Lambda_{0}$ ([Bou64, lemma 2 in VI.10.2]). Indeed, one first easily checks that any section $j: \bar{\Lambda} \rightarrow \Lambda$ is increasing. Now let's prove that the isomorphism $f: \bar{\Lambda} \times \Lambda_{0} \rightarrow \Lambda$ defined by $f\left(\bar{x}, x_{0}\right)=j(\bar{x})+x_{0}$ is increasing for the lexicographic ordering on $\bar{\Lambda} \times \Lambda_{0}$. So assume that $\left(\bar{x}, x_{0}\right) \geq 0$. If $\bar{x}=0$, then $f\left(\bar{x}, x_{0}\right)=x_{0} \geq 0$. If $\bar{x}>0$, then $f\left(\bar{x}, x_{0}\right)=j(\bar{x})+x_{0}>0$ since otherwise, one would have $0 \leq j(\bar{x}) \leq-x_{0}$, hence $j(\bar{x}) \in \Lambda_{0}$ by convexity, a contradiction.

Finally, by induction hypothesis, $\Lambda_{0}$ embeds as an ordered subgroup of $\mathbb{R}^{q-1}$ and $\bar{\Lambda}$ embeds as an ordered subgroup of $\mathbb{R}$, so $\Lambda$ embeds as an ordered subgroup of $\mathbb{R}^{q}$.

## 4 Gluing $\Lambda$-trees

The goal of this section is to define graph of actions on $\Lambda$-trees which show how to glue actions on $\Lambda$-trees along closed subtrees to get another action on a $\Lambda$-tree, and to give a criterion for the resulting action to be free. We will finally study more specifically gluings of $\mathbb{R}$-trees along points, and show that a decomposition of an $\mathbb{R}$-tree $T$ into a graph of actions on $\mathbb{R}$-trees above points correspond to a nice covering of $T$ by closed subtrees.

### 4.1 Gluing $\Lambda$-trees along points

Here, we recall that one can glue $\Lambda$ trees together along a point to get a new $\Lambda$-tree (see [Chi01, Lem. 2.1.13]).

Lemma 4.1 ([Chi01, Lemma 2.1.13]). Let $(Y, d)$ be a $\Lambda$-tree, and $\left(Y_{i}, d_{i}\right)_{i \in I}$ be a family of $\Lambda$-trees. Assume that $Y_{i} \cap Y=\left\{x_{i}\right\}$ and that for all $i, j \in I, Y_{i} \cap Y_{j}=\left\{x_{i}\right\} \cap\left\{x_{j}\right\}$. Let $X=\left(\bigcup_{i \in I} Y_{i}\right) \cup Y$ and let $\bar{d}: X \times X \rightarrow \Lambda$ defined by: $\bar{d}_{\mid Y \times Y}=d ; \bar{d}_{\mid Y_{i} \times Y_{i}}=d_{i}$; for
$x \in Y_{i}, y \in Y \bar{d}(x, y)=d\left(x, x_{i}\right)+d\left(x_{i}, y\right) ;$ for $x \in Y_{i}, y \in Y_{j} \bar{d}(x, y)=d\left(x, x_{i}\right)+d\left(x_{i}, x_{j}\right)+$ $d\left(x_{j}, y\right)$.

Then $(X, \bar{d})$ is a $\Lambda$-tree.

### 4.2 Gluing two trees along a closed subtree

The following gluing construction will be used for gluing trees along maximal linear subtrees.

Assume that we are given two $\Lambda$-trees $\left(Y_{1}, d_{1}\right),\left(Y_{2}, d_{2}\right)$, two closed subtrees $\delta_{1} \subset Y_{1}$ and $\delta_{2} \subset Y_{2}$, and an isometric $\operatorname{map} \varphi: \lambda_{1} \rightarrow \lambda_{2}$. By definition of a closed subtree, we have two orthogonal projections $p_{\lambda_{i}}: Y_{i} \rightarrow \lambda_{i}$ for $i \in\{1,2\}$.

Let $X=Y_{1} \sqcup Y_{2}$, and let $\sim$ be the equivalence relation on $X$ generated by $x \sim \varphi(x)$ for all $x \in \lambda_{1}$. The set $\left(Y_{1} \cup_{\varphi} Y_{2}\right):=X / \sim$ is now endowed with the following metric which extends $d_{i}$ on $Y_{i}$ : if $x \in Y_{1}$ and $y \in Y_{2}$, we set

$$
\begin{align*}
d(x, y) & :=d_{1}\left(x, p_{\lambda_{1}}(x)\right)+d_{2}\left(\varphi\left(p_{\lambda_{1}}(x)\right), p_{\lambda_{2}}(y)\right)+d_{2}\left(y, p_{\lambda_{2}}(y)\right)  \tag{1}\\
& =d_{1}\left(x, p_{\lambda_{1}}(x)\right)+d_{2}\left(\varphi\left(p_{\lambda_{1}}(x)\right), y\right) \\
& =\min \left\{d_{1}\left(x, x_{1}\right)+d_{2}\left(\varphi\left(x_{1}\right), y\right) \mid x_{1} \in \lambda_{1}\right\} \tag{2}
\end{align*}
$$

To prove the last equality, introduce $z_{1}=p_{\lambda_{1}}(x)$; then for any $x_{1} \in \lambda_{1}$,

$$
\begin{aligned}
d_{1}\left(x, x_{1}\right)+d_{2}\left(\varphi\left(x_{1}\right), y\right) & =d_{1}\left(x, z_{1}\right)+d_{1}\left(z_{1}, x_{1}\right)+d_{2}\left(\varphi\left(x_{1}\right), y\right) \\
& =d_{1}\left(x, z_{1}\right)+d_{1}\left(\varphi\left(z_{1}\right), \varphi\left(x_{1}\right)\right)+d_{2}\left(\varphi\left(x_{1}\right), y\right) \\
& \geq d_{1}\left(x, z_{1}\right)+d_{1}\left(\varphi\left(z_{1}\right), y\right) \\
& =d(x, y)
\end{aligned}
$$

Lemma 4.2. With the definitions above, $\left(Y_{1} \cup_{\varphi} Y_{2}, d\right)$ is a $\Lambda$-tree. Moreover, any closed subtree of $Y_{i}$ is closed in $\left(Y_{1} \cup_{\varphi} Y_{2}, d\right)$.

Proof. Let $T=Y_{1} \cup_{\varphi} Y_{2}$. Then $T$ can be viewed as the tree $L=\lambda_{1}=\lambda_{2}$ on which are glued some subtrees of $Y_{1}, Y_{2}$ at some points. More precisely, for $x \in \lambda_{1}$, let $A_{x}=\left(p_{\lambda_{1}}\right)^{-1}(x)$, and similarly, for $x \in \lambda_{2}$, let $B_{x}=\left(p_{\lambda_{2}}\right)^{-1}(x)$. Then, because of the formula (1) for the metric, $T$ is isometric to the $\Lambda$-tree obtained by gluing the trees $A_{x}$ and $B_{x}$ on $L$ along the point $x$ as in lemma 4.1. Therefore, by lemma 4.1, $(T, d)$ is an $\Lambda$-tree.

Now let $Z \subset Y_{1}$ be a closed subtree. Let's prove that $Z$ is closed in $T$. Consider $z \in Z, y \in T$, and let's prove that there exists $z_{0} \in Z$ such that $[z, y] \cap Z=\left[z, z_{0}\right]$. If $y \in Y_{1}$, then one can take $z_{0}$ to be the projection of $y$ on $Z$ by hypothesis. If $y \in Y_{2}$, let $y_{0}$ be the projection of $y$ on $\lambda_{2}$, and $z_{0}$ be the projection of $\varphi^{-1}\left(y_{0}\right)$ on $Z$. Of course, $\left[y, z_{0}\right] \subset Z$. Now $\left[y_{0}, y\right] \backslash\left\{y_{0}\right\}$ does not meet $Z$ since it is contained in $T \backslash Y_{1}$, and neither does $\left[z_{0}, y_{0}\right] \backslash\left\{z_{0}\right\}$. Thus $[z, y] \cap Z=\left[z, z_{0}\right]$ and $Z$ is closed in $T$.

### 4.3 Equivariant gluing: graphs of actions on $\Lambda$-trees.

The combinatorics of the gluing will be given by a simplicial tree $S$, endowed with an action without inversion of a group $\Gamma$. We denote by $V(S)$ and $E(S)$ the set of vertices and (oriented) edges of $S$, by $t(e)$ and $o(e)$ the origin and terminus of an (oriented) edge $e$, and by $\bar{e}$ the edge with opposite orientation as $e$.

A graph of actions on trees is usually defined as a graph of groups with some additional data like vertex trees. Here, we rather use an equivariant definition at the level of the Bass-Serre tree.

Definition 4.3 (Graph of actions on $\Lambda$-trees.). Given a group $\Gamma$, $a \Gamma$-equivariant graph of actions on $\Lambda$-trees is a triple $\left(S,\left(Y_{v}\right)_{v \in V(S)},\left(\varphi_{e}\right)_{e \in E(S)}\right)$ where

- $S$ is a simplicial tree,
- for each vertex $v \in V(S), Y_{v}$ is a $\Lambda$-tree (called vertex tree),
- for each edge $e \in E(S), \varphi_{e}: \lambda_{\bar{e}} \rightarrow \lambda_{e}$ is an isometry between closed subtrees $\lambda_{\bar{e}} \subset$ $Y_{o(e)}$ and $\lambda_{e} \subset Y_{t(e)}$ such that $\varphi_{\bar{e}}=\varphi_{e}^{-1}$. We call the subtrees $\lambda_{e}$ the edge subtrees.

This data is assumed to be $\Gamma$-equivariant in the following sense:

- $\Gamma$ acts on $S$ without inversion,
- $\Gamma$ acts on $X=\sqcup_{v \in V(S)} Y_{v}$ so that the restriction of each element of $\Gamma$ to a vertex tree is an isometry,
- the natural projection $\pi: X \rightarrow V(S)$ (sending a point in $Y_{v}$ to $v$ ) is equivariant
- the family of gluing maps is equivariant: for all $g \in \Gamma, \lambda_{g . e}=g . \lambda_{e}$, and $\varphi_{g . e}=$ $g \circ \varphi_{e} \circ g^{-1}$.

The $\Lambda$-tree dual to a graph of actions Given $\mathcal{G}$ a $\Gamma$-equivariant graph of actions on $\Lambda$-trees, we consider the smallest equivalence relation $\sim$ on $X=\sqcup_{v \in V(S)} Y_{v}$ such that for all edge $e \in E(S)$ and $x \in \lambda_{\bar{e}}, x \sim \varphi_{e}(x)$. The $\Lambda$-tree dual to $\mathcal{G}$ is the quotient space $T_{\mathcal{G}}=X / \sim$. To define the metric on $T_{\mathcal{G}}$, one can alternatively say that $T_{\mathcal{G}}$ is obtained by gluing successively the vertex trees along the edge trees according to lemma 4.2 in previous section. Formula (2) in previous section shows that the metric does not depend on the order in which the gluing are performed. Indeed, an induction shows that the distance between $x \in Y_{u}$ and $y \in Y_{v}$ can be computed as follows: let $e_{1}, \ldots, e_{n}$ the edges of the path from $u$ to $v$ in $S$, and $v_{0}=u, v_{1}, \ldots, v_{n}=v$ the corresponding vertices then

$$
d(x, y)=\min \left\{d_{Y_{u}}\left(x, x_{1}\right)+d_{Y_{v_{1}}}\left(\varphi_{e_{1}}\left(x_{1}\right), x_{2}\right)+\cdots+d_{Y_{v_{n}}}\left(\varphi_{e_{n}}\left(x_{n}\right), y\right)\right.
$$

where the minimum is taken over all $x_{i} \in \lambda_{\bar{e}_{i}}$. By finitely many applications of lemma 4.2, one gets that the gluings corresponding to finite subtrees of $S$ are $\Lambda$-trees. Now apply the fact that an increasing union of $\Lambda$-trees is a $\Lambda$-tree to get that $T$ is a $\Lambda$-tree (see [Chi01, Lem. 2.1.14]). We thus get the following lemma:

Definition 4.4 (Tree dual to a graph of actions on $\Lambda$-trees.). Consider $\mathcal{G}=\left(S,\left(Y_{v}\right),\left(\varphi_{e}\right)\right)$ $a \Gamma$-equivariant graph of actions on $\Lambda$-trees. The dual tree $T_{\mathcal{G}}$ is the set $X / \sim$ endowed with the metric d defined above. It is a $\Lambda$-tree on which $\Gamma$ acts by isometries.

We say that a $\Lambda$-tree $T$ splits as a graph of actions $\mathcal{G}$ if there is an equivariant isometry between $T$ and $T_{\mathcal{G}}$.

Remark. Consider an increasing union of trees $T_{i}$ such that $Y \subset T_{0}$ is a closed subtree of each $T_{i}$. Then $Y$ is closed in $\cup_{i} T_{i}$. Therefore, using lemma 4.2, one gets that a closed subtree of a vertex tree is closed in $T_{\mathcal{G}}$. In particular, vertex trees themselves are closed in $T_{\mathcal{G}}$.

### 4.4 Gluing free actions into free actions

We next give a general criterion saying that an action obtained by gluing is free. It is stated in terms of the equivalence relation $\sim$ on $X=\sqcup_{v \in V(S)} Y_{v}$ defined above. Each equivalence class has a natural structure of a connected graph: elements of the equivalence class are vertices, put an oriented edge between two vertices $x$ and $y$ if $y=\varphi_{e}(x)$ for some edge
$e \in E(S)$. This graph embeds into $S$ via the map $\pi: X \rightarrow S$, so this graph is a simplicial tree.

Lemma 4.5 (Criterion for a graph of free actions to be free). Consider $\mathcal{G}=\left(S, Y_{v}, \varphi_{e}\right)$ $a \Gamma$-equivariant graph of action on $\Lambda$-trees. For each vertex $v \in V(S)$, denote by $\Gamma_{v}$ its stabilizer, and assume that the action of $\Gamma_{v}$ on $Y_{v}$ is free. Assume furthermore that each equivalence class of $\sim$ has finite diameter.

Then the action of $\Gamma$ on $T_{\mathcal{G}}$ is free.
Proof. If an element $g \in \Gamma$ fixes a point in $T_{\mathcal{G}}$, then $g$ globally preserves the corresponding equivalence class in $X$. Since this equivalence class has the structure of a tree with finite diameter, $g$ must fix a vertex in this equivalence class (there are no inversions because the action on $S$ has no inversion). Hence $g$ fixes a point of $X$, which means that $g$ fixes a point in a vertex tree.

### 4.5 Nice coverings and graph of actions on $\mathbb{R}$-trees

In this section, we restrict to the case of a graph of actions on $\mathbb{R}$-trees along points. We prove that an action on an $\mathbb{R}$-tree splits as such a graph of actions if and only if it has a certain kind of covering by subtrees. The argument could in fact be generalized to graph of actions on $\Lambda$-trees along points but we won't need it.

Definition 4.6 (Nice covering). Let $T$ be an $\mathbb{R}$-tree, and $\left(Y_{u}\right)_{u \in U}$ be a family of nondegenerate closed subtrees of $T$. We say that $\left(Y_{u}\right)_{u \in U}$ is a nice covering of $T$ if

- nice intersection: whenever $Y_{u} \cap Y_{v}$ contains more than one point, $Y_{u}=Y_{v}$;
- finiteness condition: every arc of $T$ is covered by finitely many $Y_{u}$ 's.

Lemma 4.7. Consider an action of a group $\Gamma$ on an $\mathbb{R}$-tree $T$. If $T$ splits as a graph of actions on $\mathbb{R}$-trees along points $\mathcal{G}$, then the image in $T$ of non-degenerate vertex trees of $\mathcal{G}$ gives a nice covering of $T$.

Conversely, if $T$ has a $\Gamma$-invariant nice covering, then there is a natural graph of actions $\mathcal{G}$ whose non-degenerate vertex trees correspond to the subtrees of the nice covering and such that $T \simeq T_{\mathcal{G}}$.

Proof. We first check that the family of vertex trees of a graph of actions $\mathcal{G}=\left(S,\left(Y_{v}\right),\left(\varphi_{e}\right)\right)$ forms a nice covering of $T_{\mathcal{G}}$. We have already noted that vertex trees are closed in $T_{\mathcal{G}}$. The nice intersection condition follows from the fact that edge trees are points. To prove the finiteness condition, consider $x \in Y_{u}$ and $y \in Y_{v}$ and note that $[x, y]$ is covered by the trees $Y_{w}$ for $w \in[u, v]$.

To prove the converse, we need to define the simplicial tree $S$ encoding the combinatorics of the gluing.

Definition 4.8 (Skeleton of a nice covering). Consider a nice covering $\left(Y_{u}\right)_{u \in U}$ of $T$. The skeleton of this nice covering is the bipartite simplicial tree $S$ defined as follows:

- $V(S)=V_{0}(S) \cup V_{1}(S)$ where $V_{1}(S)=\left\{Y_{u} \mid u \in U\right\}$, and $V_{0}(S)$ is the set of points of $T$ which belong to a least two distinct trees $Y_{u} \neq Y_{v}$
- there is an edge between $x \in V_{0}(S)$ and $Y \in V_{1}(S)$ if and only if $x \in Y$.

The connectedness of $S$ follows from the finiteness condition (using the fact that the subtrees $Y_{u}$ are closed in $T$ ). Now let's prove the simple connectedness. Consider a path $p=x_{0}, Y_{0}, x_{1}, \ldots, x_{n-1}, Y_{n-1}, x_{n}$ in $S$, and let $\tilde{p}=\left[x_{0}, x_{1}\right] \cdot\left[x_{1}, x_{2}\right] \ldots\left[x_{n-1}, x_{n}\right]$ be the corresponding path in $T$. If $p$ does not backtrack, then $Y_{i} \cap Y_{i+1}=\left\{x_{i+1}\right\}$ so $\tilde{p}$ does not backtrack. Therefore, $x_{0} \neq x_{n}$ and $p$ is not a closed path.

Now there is a natural graph of actions $\mathcal{G}$ corresponding to $S$ : for $x \in V_{0}(S)$, the corresponding vertex tree is the point $\{x\}$, for $Y \in V_{1}(S)$, the corresponding vertex tree is $Y$, and the gluing maps $\varphi_{e}:\{x\} \rightarrow Y$ are given by inclusion. Finally, consider the natural map $\Psi: T_{\mathcal{G}} \rightarrow T$ given by the inclusion of vertex trees. This application is an isometry in restriction to vertex trees, and if $[a, b],[a, c]$ are two arcs in $T_{\mathcal{G}}$ lying in two distinct vertex trees $Y_{1}, Y_{2}$ of $T_{\mathcal{G}}$, then $\Psi([a, b]) \cap \Psi([a, c]) \subset \Psi\left(Y_{1}\right) \cap \Psi\left(Y_{2}\right)$ is reduced to one point. This implies that $\Psi$ is an isometry in restriction to each segment, and hence an isometry.

Remark. We will often prefer using a nice covering (or the graph of actions corresponding to such a covering) to a general graph of actions because of the following acylindricity property of the dual graph of actions $\mathcal{G}=\left(S,\left(Y_{v}\right)_{v \in V(S)},\left(\varphi_{e}\right)_{e \in E(S)}\right)$ : if two points $x \in Y_{v}$, and $x^{\prime} \in Y_{v^{\prime}}$ have the same image in $T_{\mathcal{G}}$, then $v, v^{\prime}$ are at distance at most 2 in $S$.

It is also worth noticing the following simple minimality result:
Lemma 4.9. Consider an $\mathbb{R}$-tree $T$ endowed with a minimal action of $\Gamma$. Consider $\left(Y_{u}\right)_{u \in U}$ an equivariant nice covering of $T$, and let $S$ be the skeleton of the nice covering.

Then the action of $\Gamma$ on $S$ is minimal.
Proof. Assume that $S^{\prime} \subset S$ is an invariant subtree. Let $T^{\prime} \subset T$ be the union of vertex trees of $S^{\prime}$. One easily checks that $T^{\prime}$ is connected using the connectedness of $S^{\prime}$. Thus, by minimality of $T$, one has $T^{\prime}=T$. Using the acylindricity remark above, $S$ is contained in the 2-neighbourhood of $S^{\prime}$. In particular, if $S^{\prime} \neq S$, then $S$ contains a terminal vertex $v$. By definition, every vertex in $V_{0}(S)$ has at least two neighbours, so $v \in V_{1}(S)$. We thus get a contradiction since $Y_{v}$ is contained in $T^{\prime}$, contradicting the nice intersection property of the nice covering.

## 5 The action modulo infinitesimals, abelian dévissage

In this section, we prove a weaker version of the cyclic dévissage theorem, where (maybe non-finitely generated) abelian groups may appear in place of cyclic groups (see prop. 5.5).

Start with a finitely generated group $\Gamma$ acting freely on an $\mathbb{R}^{n}$-tree $T$ with $n \geq 2$, and assume that $\Gamma$ is freely indecomposable. Denote by $\mathbb{R}^{n-1}$ the maximal proper convex subgroup of $\mathbb{R}^{n}$, and consider elements of $\mathbb{R}^{n-1}$ as infinitesimals. Now consider the $\mathbb{R}$-tree $\bar{T}$ obtained from $T$ by identifying points at infinitesimal distance (this is often called the base change functor in the literature, see for instance [Chi92], [JZ95], [Bas91], see also [Chi01, Th.2.4.7]). Note that the canonical projection $f: T \rightarrow \bar{T}$ preserves alignment, and that the preimage of a convex set is convex. The preimage in $T$ of a point of $\bar{T}$ is thus an infinitesimal subtree of $T$. Of course, the action of $\Gamma$ on $T$ induces an isometric action of $\Gamma$ on $\bar{T}$.

However, this action generally fails to be free. It may even happen that $\Gamma$ fixes a point $\bar{x}$ in $\bar{T}$, but in this case, the dévissage theorem holds trivially since $\Gamma$ acts freely on the $\mathbb{R}^{n-1}$-tree $f^{-1}(\bar{x})$. Therefore, we assume that $\Gamma$ acts non-trivially on $\bar{T}$, and, up to taking
a subtree of $\bar{T}$ and its preimage in $T$, we can assume that the action on $\bar{T}$ is minimal, i. e. that there is no non-empty proper invariant subtree.

We first analyze how far from free this action can be
Fact 5.1. If a group $\Gamma$ acts freely on an $\mathbb{R}^{n}$-tree $T$, then the action of $\Gamma$ on $\bar{T}$ satisfies the following:

- tripod fixators are trivial (a tripod is the convex hull of 3 points which are not aligned)
- for every pair of commuting, elliptic elements $g, h \in \Gamma \backslash\{1\}, \operatorname{Fix}_{\bar{T}} g=\mathrm{Fix}_{\bar{T}} h$; in particular, $\mathrm{Fix}_{\bar{T}} g=\mathrm{Fix}_{\bar{T}} g^{k}$ for $k \neq 0$;
- arc fixators are abelian; the global stabilizer of a line is maximal abelian if it is non-trivial;
- the action is superstable: for every non-degenerate arc $I \subset \bar{T}$ with non-trivial fixator, for every non degenerate sub-arc $J \subset I$, one has $\operatorname{Stab} I=\operatorname{Stab} J$.

Remark. This fact does not use the fact that we have an $\mathbb{R}^{n}$-tree rather than a more general $\Lambda$-tree. The statement holds for every $\Lambda$-tree $T$ with a free action of $\Gamma$ without inversion and every $\Lambda / \Lambda_{0}$-tree $\bar{T}$ obtained from $T$ by killing a convex subgroup $\Lambda_{0}$ of infinitesimals.

Proof of the fact. We start with the proof of the two first items. Consider $g \in \Gamma \backslash\{1\}$, and consider $\mathrm{Fix}_{\bar{T}} g$ its set of fix points in $\bar{T}$. The preimage of $\mathrm{Fix}_{\bar{T}} g$ is the set of points in $T$ moved by an infinitesimal amount. This set is either empty if $l_{T}(g)$ is not infinitesimal, or, it is the set of points whose distance to the axis $A_{g}$ of $g$ is infinitesimal. Therefore, if $\mathrm{Fix}_{\bar{T}} g$ is not empty, then it is the image of $A_{g}$ in $\bar{T}$ which contains no tripod since the quotient map preserves alignment. Moreover, for any element $h \in \Gamma$ commuting with $g$, $h$ globally preserves the axis of $g$, so $A_{h}=A_{g}$. Therefore, if $h$ is elliptic in $\bar{T}$ then it has the same set of fixed points as $g$.

Now we prove superstability and that arc fixators are abelian. Consider some nondegenerate arcs $\bar{J} \subset \bar{I} \subset \bar{T}$, two elements $g, h \in \Gamma \backslash\{1\}$ fixing pointwise $\bar{I}$ and $\bar{J}$ respectively. We want to prove that $h$ fixes $\bar{I}$ and commutes with $g$. By hypothesis, the translation length of $g$ and $h$ are infinitesimal in $T$, their axes $A_{g}$ and $A_{h}$ must intersect in a subset of non-infinitesimal diameter.

Now since the diameter of $A_{g} \cap A_{h}$ is much (infinitely) larger than $l_{T}(g)+l_{T}(h)$, $g h g^{-1} h^{-1}$ is elliptic in $T$ (see for instance [Chi01, Rk. p.111]). Since the action is free, this means that $g$ and $h$ commute and in particular, the fixator of $\bar{I}$ is abelian. This implies that $h\left(A_{g}\right)=A_{g}$, thus $A_{h} \supset A_{g}$ since $A_{h}$ is the maximal $h$-invariant linear subtree of $T$, and $A_{h}=A_{g}$ by symmetry of the argument. Therefore, $\operatorname{Fix}_{\bar{T}} h=\mathrm{Fix}_{\bar{T}} g$ and in particular, $h$ fixes $\bar{I}$.

Let's prove that the global stabilizer $\Gamma_{l}$ of a line $l \subset \bar{T}$ is abelian. Since Fix $g=\operatorname{Fix} g^{2}$ for all $g \in \Gamma, \Gamma_{l}$ acts on $l$ by translations. If the fixator $N_{l}$ of $l$ is trivial, then we are done. Otherwise, $N_{l}$ is a normal abelian subgroup of $\Gamma_{l}$, and let $\tilde{l}$ be its axis in $T$. Since $\Gamma_{l}$ normalizes $N_{l}, \Gamma_{l}$ preserves $\tilde{l}$, so $\Gamma_{l}$ acts freely by translations on $\tilde{l}$, so $\Gamma_{l}$ is abelian. Finally, any element normalizing $\Gamma_{l}$ must preserve $l$, so $\Gamma_{l}$ is maximal abelian.

Therefore, one can apply Sela's theorem which claims that superstable actions on $\mathbb{R}$ trees are obtained by gluing equivariantly some simpler $\mathbb{R}$-trees along points (see definition 4.4). In this statement a simplicial arc in $\bar{T}$ is an arc $[a, b]$ which contains no branch point of $\bar{T}$ except maybe at $a$ or $b$.

Theorem 5.2 (Structure theorem [Sel97],see also [Gui]). Let $(\bar{T}, \Gamma)$ be a minimal action of a finitely generated group on an $\mathbb{R}$-tree. Assume that $\Gamma$ is freely indecomposable, that tripod fixators are trivial, and that the action is super-stable. Then $\bar{T}$ can be decomposed into a graph of actions on $\mathbb{R}$-trees along points, each vertex tree being either

1. a point;
2. a simplicial arc, which is fixed pointwise by its global stabilizer;
3. a line $l$ together with an action $\Gamma_{l} \subset l$ having dense orbits, such that the image of $\Gamma_{l}$ in $\operatorname{Isom}(l)$ is finitely generated;
4. or an action on an $\mathbb{R}$-tree dual to an arational measured foliation on a 2 -orbifold (with boundary).

Remark. In [Gui], simplicial arcs are incorporated in the skeleton of the decomposition of the action (as edges of positive length) and hence do not appear in the statement of the theorem.

Since $\Gamma$ is torsion-free, the orbifold groups occuring in the structure theorem are actually surface groups.

Agglutination of simplicial arcs We now make the decomposition given in the structure theorem nicer with respect to abelian groups. In particular, we want to gather simplicial arcs having the same fixator into bigger vertex subtrees. This will imply that the stabilizer of the new corresponding vertex trees are maximal abelian. The goal is to reformulate the Structure Theorem as follows:

Theorem 5.3 (Reformulation of Structure Theorem). There is a $\Gamma$-invariant nice covering of $\bar{T}$ by a family $\left(\bar{Y}_{u}\right)_{u \in U}$ of non-degenerate closed subtrees such that, denoting by $\Gamma_{u}$ be the global stabilizer of $\bar{Y}_{u}$, one of the following holds:

- abelian-type: $\bar{Y}_{u}$ is an arc or a line, the image $\bar{\Gamma}_{u}$ of $\Gamma_{u}$ in $\operatorname{Isom}\left(\bar{Y}_{u}\right)$ is finitely generated, and $\Gamma_{u}$ is maximal abelian in $\Gamma$; moreover for any two abelian-type subtrees $\bar{Y}_{u} \neq \bar{Y}_{v}, \Gamma_{u}$ and $\Gamma_{v}$ don't commute;
- surface-type: or the action $\Gamma_{u} \subset \bar{Y}_{u}$ is dual to an arational measured foliation on a surface with boundary.
Proof. Consider the nice covering of $\bar{T}$ by the non-degenerate vertex subtrees $\left(\bar{Y}_{u}\right)_{u \in U}$ of the decomposition given by the structure theorem 5.2 (lemma 4.7). Consider the equivalence relation on $U$ generated by $u \sim u^{\prime}$ if $\bar{Y}_{u}$ and $\bar{Y}_{u^{\prime}}$ are simplicial arcs and the fixator of $\bar{Y}_{u}$ and $\bar{Y}_{u^{\prime}}$ commute (note that the fixator of these arcs are non-trivial since $\Gamma$ is freely indecomposable). The commutation of the fixators implies that those fixators coincide since commuting elliptic elements have the same set of fix points (fact 5.1).

For any equivalence class $[u]$, let $\bar{Z}_{[u]}=\bigcup_{u \in[u]} \bar{Y}_{u}$. We prove that $\left(\bar{Z}_{[u]}\right)_{u \in U / \sim}$ is the wanted nice covering. For $u$ such that $\bar{Y}_{u}$ is a simplicial arc, let $N_{[u]}$ be the common fixator of the simplicial arcs $\bar{Y}_{u}$ for $u \in[u]$. One has Fix $N_{u}=\bar{Z}_{[u]}$. As a matter of fact, $N_{u}$ cannot fix an arc in a surface type vertex tree since the fixator of an arc in a surface-type vertex tree is trivial, and $N_{u}$ cannot fix an arc in a line-type vertex tree because tripod fixators are trivial. This implies that $\bar{Z}_{[u]}$ is closed and connected, and is a linear subtree

[^2]of $\bar{T}$ since tripod fixators are trivial. Since the case of a semiline is easy to rule out, $\bar{Z}_{[u]}$ is either an arc of a line. In particular, the family of subtrees $\left(\bar{Z}_{[u]}\right)_{[u] \in U / \sim}$ is a nice covering of $\bar{T}$.

The global stabilizer $\Gamma_{[u]}$ of $\bar{Z}_{[u]}$ is maximal abelian in $\Gamma$ : this was already noted in the case where $\bar{Z}_{[u]}$ is a line; if $\bar{Z}_{[u]}$ is an arc, then $\Gamma_{[u]}$ coincides with its fixator $N_{u}$ since there can be no reflection (because Fix $g=\operatorname{Fix} g^{2}$ ) so in particular, $\Gamma_{[u]}$ is abelian. Now any element $g$ commuting with the elements of $N_{u}$ must globally preserve $\bar{Z}_{[u]}$, so $g \in \Gamma_{[u]}$. Therefore, $\Gamma_{[u]}$ is maximal abelian. If $u, v$ are such that $\Gamma_{[u]}$ and $\Gamma_{[v]}$ commute, then $N_{u}$ and $N_{v}$ commute, so $N_{u}=N_{v}$ and $[u]=[v]$.

We now focus on the skeleton $S$ of this nice covering, and we analyze the corresponding splitting of $\Gamma$. We prove that this splitting satisfies the abelian dévissage. We give a simple version before giving a more detailed statement.

Proposition 5.4 (Abelian dévissage, simple version). If a finitely generated freely indecomposable group $\Gamma$ acts freely on an $\mathbb{R}^{n}$-tree $(n \geq 2)$, then $\Gamma$ can be written as the fundamental group of a finite graph of groups where

- each edge group is abelian; more precisely, an edge group is either cyclic or fixes an arc in $\bar{T}$;
- each vertex group acts freely on an $\mathbb{R}^{n-1}$-tree;

Proposition 5.5 (Abelian dévissage, detailed version). If a finitely generated freely indecomposable group $\Gamma$ acts freely on an $\mathbb{R}^{n}$-tree, then $\Gamma$ can be written as the fundamental group of a finite graph of groups with 3 types of vertices named abelian, surface and infinitesimal, and such that the following holds:

- each edge is incident to exactly one infinitesimal vertex;
- for each abelian vertex $v, \Gamma_{v}$ is abelian maximal in $\Gamma, \Gamma_{v}=\bar{\Gamma}_{v} \oplus N_{v}$ where $\bar{\Gamma}_{v}$ is a finitely generated (maybe trivial) free abelian group, $N_{v}$ is an arc fixator, and the image in $\Gamma_{v}$ of all incident edges coincide with the (maybe infinitely generated) abelian group $N_{v}$; moreover, if $v \neq v^{\prime}$ are distinct abelian vertices, then $\Gamma_{v}$ does not commute with any conjugate of $\Gamma_{v^{\prime}}$;
- for each surface vertex $v, \Gamma_{v}$ is the fundamental group of a surface $\Sigma$ with boundary holding an arational measured foliation; there is one edge for each boundary component of $\Sigma$, and the image of its edge group in $\Gamma_{v}$ is conjugate to the fundamental group of the corresponding boundary component of $\Sigma$;
- for each infinitesimal vertex $v, \Gamma_{v}$ acts freely on an $\mathbb{R}^{n-1}$-tree; moreover, any element $g \in \Gamma \backslash\{1\}$ commuting with an element of $\Gamma_{v} \backslash\{1\}$ either belongs to $\Gamma_{v}$, or is conjugate into $\bar{\Gamma}_{w}$ where $w$ is an abelian vertex neighbouring $v$.

Finally, $\mathcal{G}$ is 4-acylindrical and any non-cyclic abelian subgroup of $\Gamma$ is conjugate into a vertex group.

Remark. A surface with empty boundary could occur in this graph of groups, but in this case, the graph of groups contains no edge, and $\Gamma$ is a surface group.

Note that the edge and vertex groups could a priori be non-finitely generated in the abelian dévissage. On the other hand, if one knew somehow4 that abelian subgroups

[^3]of $\Gamma$ were finitely generated, then the finite presentation of $\Gamma$ would follow easily: finite generation of edge groups would imply the finite generation of vertex groups (since $\Gamma$ is finitely generated), and thus vertex groups would be finitely presented by induction hypothesis.

If one knows that arc fixators of $\bar{T}$ are cyclic, then it is immediate to deduce the conclusion of the cyclic dévissage theorem from the abelian dévissage theorem. The strategy for the proof of the Cyclic Dévissage Theorem will thus consist in finding an $\mathbb{R}^{n}$-tree $T^{\prime}$ such that arc fixators of $\bar{T}^{\prime}$ are cyclic (see next section).

Proof of the simple version from the detailed version. The claim about edge groups follows from the fact that each edge is either incident on a surface vertex or on an abelian vertex. The claim about vertex groups follows from the fact that countable torsion free abelian groups and surface groups holding an arational measured foliation (which are free groups in the case where the surface have non-empty boundary) have a free action on an $\mathbb{R}$-tree.

Proof of the detailed version. Let $S$ be the skeleton of the nice covering given by the reformulation of the structure theorem (Th. 5.3). We prove that the graph of groups decomposition $\Gamma=\pi_{1}(\mathcal{G})$ induced by the action of $\Gamma$ on $S$ satisfies the abelian dévissage theorem.

Remember that $S$ is bipartite, with $V(S)=V_{0}(S) \sqcup V_{1}(S)$ where $V_{1}(S)$ is the set of non-degenerate subtrees in the nice covering, and $V_{0}(S)$ is the set of points of $\bar{T}$ which belong to at least two distinct subtrees of the nice covering. The set $V_{0}(S)$ will be the set of our infinitesimal vertices. Since the stabilizer of such a vertex fixes a point in $T$, it acts freely on an $\mathbb{R}^{n-1}$-tree. By the reformulation of the Structure Theorem, $V_{1}(S)$ is a disjoint union of abelian-type and surface type vertices $V_{1}(S)=V_{a b} \sqcup V_{s u r f}$, where $V_{a b}$ is the set of vertices corresponding to abelian-type subtrees and $V_{s u r f}$ to surface-type subtrees (excluding tori). The fact that $S$ is bipartite means that each edge of $\mathcal{G}$ is incident on exactly one infinitesimal vertex.

Let's first consider an abelian vertex $v$, and let $N_{v}$ be the fixator of the linear subtree $\bar{Y}_{v}$, and $\bar{\Gamma}_{v}$ the image of $N_{v}$ in $\operatorname{Isom}\left(\bar{Y}_{v}\right)$. The direct sum follows from the fact that $\Gamma_{v}$ is abelian and that $\bar{\Gamma}_{v}$ is a free abelian group. The only thing to check is that the image of all edge groups incident on $v$ coincide with $N_{v}$. This follows from the fact that an edge $e \in E(S)$ is a pair $\left(x, \bar{Y}_{v}\right)$ where $x \in \bar{Y}_{v}$, so the fixator of $e$ is the stabilizer of $x$ in $\Gamma_{v}$, which is $N_{v}$.

The acylindricity follows from the fact that if two edges $\left(x, \bar{Y}_{v}\right)\left(x^{\prime}, \bar{Y}_{v^{\prime}}\right)$ have commuting fixators $\Gamma_{e}, \Gamma_{e^{\prime}}$, then $\Gamma_{e}$ and $\Gamma_{e^{\prime}}$ have the same (non-empty) set of fix points in $\bar{T}$ which is either a point, or an abelian subtree. In the first case, one has $x=x^{\prime}$ so the two edges have a common endpoint at an infinitesimal vertex. In the second case, the endpoints $x$ and $x^{\prime}$ of the two edges are at distance at most 2 in $S$. The acylindricity implies that any non-cyclic abelian group $A$ is conjugate into a vertex group since otherwise, a non-trivial subgroup of $A$ would fix its axis in $S$, contradicting acylindricity.

Let's turn to a surface vertex $v$. We know that its stabilizer $\Gamma_{v}$ is the fundamental group of a surface with boundary holding an arational measured foliation. Moreover, since $\Gamma$ is freely indecomposable, edge stabilizers are non-trivial. The stabilizer of an edge $e=\left(x, \bar{Y}_{v}\right)$ is non-trivial and fixes a point in $\bar{Y}_{v}$. Since $\bar{Y}_{v}$ is dual to an arational measured foliation on a surface $\Sigma$, the elliptic elements of $\Gamma_{v}$ are exactly those which can be conjugate into the fundamental group of a boundary component of $\Sigma$, and an elliptic
element fixes exactly one point. Thus, $\Gamma_{e}$ is conjugate to a boundary component $b_{e}$ of $\Sigma$ (and not to a proper subgroup since $\Gamma_{e}$ is the whole stabilizer of $x$ in $\Gamma_{v}$ ). Moreover, if two edges $e=\left(x, \bar{Y}_{v}\right), e^{\prime}=\left(x^{\prime}, \bar{Y}_{v}\right)$ of $S$ correspond to the same boundary component $b_{e}=B_{e^{\prime}}$ of $\Sigma$, then $\Gamma_{e}$ and $g \Gamma_{e^{\prime}} g^{-1}$ for some $g \in \Gamma_{v}$, which implies that $x^{\prime}=g . x$ since $\Gamma_{e}$ fixes exactly one point in $\bar{Y}_{v}$, so $e^{\prime}=g . e$. This proves that two distinct edges of $\mathcal{G}$ incident on a surface vertex of $\mathcal{G}$ correspond to distinct boundary components of the surface. If a boundary component of $\Sigma$ does not correspond to any incident edge, it is easy to check that $\Gamma$ has a nontrivial free splitting, contradicting the hypothesis.

There remains to check the last affirmation about elements commuting with an element stabilizing an infinitesimal vertex. So let $v \in V_{0}(S), g \in \Gamma_{v} \backslash\{1\}$ and $h \in \Gamma$ commuting with $g$. If $h$ is elliptic, then $h \in \Gamma_{v}$ since two commuting elliptic elements have the same fixed points. If $h$ is hyperbolic, then $g$ must fix pointwise its axis $A_{h}$. Since surface-type subtrees have trivial arc fixators, $A_{h}$ cannot meet any surface-type subtree in more than a point. So $A_{h}$ is contained in a union of abelian subtrees. But since $g$ fixes $A_{h}, A_{h}$ is a single abelian subtree. Now $x \in A_{h}$ since $g$ fixes no tripod and the last claim follows.

## 6 Obtaining cyclic arc stabilizers

To prove the cyclic dévissage theorem, we will find an $\mathbb{R}^{n}$-tree $T^{\prime}$ such that arc fixators of the $\mathbb{R}$-tree $\overline{T^{\prime}}$ are cyclic. The cyclic dévissage theorem will then follow from the abelian dévissage theorem.

Theorem 6.1. Assume that a freely indecomposable finitely generated group $\Gamma$ acts freely on an $\mathbb{R}^{n}$-tree $T$. Then $\Gamma$ has a free action on an $\mathbb{R}^{n}$-tree $T^{\prime}$ such that the action on the $\mathbb{R}$-tree $\bar{T}^{\prime}$ obtained by killing infinitesimals has cyclic arc fixators.

This is why we define flawless actions on $\mathbb{R}^{n}$-trees as follows:
Definition 6.2 (Flawless and defective $\mathbb{R}^{n}$-trees). Let $T$ be a $\mathbb{R}^{n}$-tree endowed with an action of $\bar{\Gamma}$, and let $\bar{T}$ be the $\mathbb{R}$-tree obtained by killing infinitesimals. One says that $T$ is flawless if $\bar{T}$ has cyclic arc fixators. Otherwise, one says that $T$ is defective.

By extension, we will also say that the $\mathbb{R}$-tree $\bar{T}$ is flawless or defective accordingly.
We will construct the flawless $\mathbb{R}^{n}$-tree $T^{\prime}$ as follows: the Structure Theorem for superstable actions on $\mathbb{R}$-trees gives a decomposition of $\bar{T}$ into a graph of actions on $\mathbb{R}$-trees along points. The preimage $Y_{v}$ in $T$ of any vertex tree $\bar{Y}_{v} \subset \bar{T}$ is an $\mathbb{R}^{n}$-tree with a free action of $\Gamma_{v}$. The only defective vertex trees $\bar{Y}_{v}$ are abelian subtrees (which are lines or arcs). We are going to change the preimage of those defective trees into (flawless) infinitesimal lines, and then, we will glue equivariantly the new $\mathbb{R}^{n}$-trees along some infinitesimal lines to get a flawless action on an $\mathbb{R}^{n}$-tree.

### 6.1 Gluing flawless trees along infinitesimals is flawless

Lemma 6.3 (Gluing flawless trees is flawless). Consider a graph of flawless actions on $\mathbb{R}^{n}$-trees above infinitesimal subtrees.

Then the $\mathbb{R}^{n}$-tree dual to this graph of actions is flawless.
Proof. Let $S$ be the skeleton of the graph of actions, and denote by $Y_{v}$ the vertex $\mathbb{R}^{n}$-trees and by $\varphi_{e}: \lambda_{\bar{e}} \rightarrow \lambda_{e}$ the gluing isometries between infinitesimal closed subtrees of the corresponding vertex trees. Let $T$ be the $\mathbb{R}^{n}$ tree dual to this graph of actions, and let $\bar{T}$
be the $\mathbb{R}$-tree obtained by killing infinitesimals. The image $\bar{Y}_{v}$ of the vertex trees in $\bar{T}$ gives a nice covering of $\bar{T}$ because the gluing occurs along infinitesimal trees. Now consider an $\operatorname{arc} \bar{I} \subset \bar{T}$. Using the finiteness condition of the nice covering, up to making $\bar{I}$ smaller, one can assume that $\bar{I}$ is contained in a non-degenerate subtree $\bar{Y}_{v}$ of the nice covering. Any element fixing $\bar{I}$ must preserve $\bar{Y}_{v}$ by the nice intersection property. Since $Y_{v}$ is flawless, this implies that the fixator of $\bar{I}$ is cyclic, which means that $T$ is flawless.

### 6.2 Definition of the graph of actions

The goal of this section is to define a graph of action $\mathcal{G}=\left(S^{\prime}, T_{v}^{\prime}, \varphi_{e}\right)$ on $\mathbb{R}^{n}$-trees whose dual tree $T^{\prime}$ will be the desired flawless $\mathbb{R}^{n}$-tree in Theorem 6.1. The idea is to replace defective trees by copies of $\mathbb{R}^{n-1}$, with a suitable action of the vertex group.

We start with the nice covering $\left(\bar{Y}_{u}\right)_{u \in U}$ of $\bar{T}$ given by the reformulation of the Structure Theorem (Th. 5.3). Remember that either $\bar{Y}_{u}$ is dual to an arational measured foliation on a surface, or $\bar{Y}_{u}$ is a line or a segment. In particular, $Y_{u}$ is defective if and only if $\bar{Y}_{u}$ is an arc or a line whose fixator $N_{u}$ is non-cyclic (actions dual to arational measured foliations on surfaces have trivial arc fixators).

We first simplify our nice covering by agglutinating flawless vertex trees so that flawless subtrees have empty intersection.

Lemma 6.4 (Agglutination of flawless subtrees). There is a nice covering of the $\mathbb{R}$ tree $\bar{T}$ by closed subtrees $\left(\tilde{Y}_{v}\right)_{v \in V}$ such that

- flawless trees: if $\tilde{Y}_{u}$ and $\tilde{Y}_{v}$ are distinct flawless trees, then $\tilde{Y}_{u} \cap \tilde{Y}_{v}=\emptyset$.
- defective subtrees: if $\tilde{Y}_{u} \neq \tilde{Y}_{v}$ are two defective subtrees, then their fixators $N_{u}, N_{v}$ don't commute. In particular, $N_{u} \cap N_{v}=\{1\}$.

Proof. Start with the nice covering of $\bar{T}$ by the family of non-degenerate subtrees $\left(\bar{Y}_{u}\right)_{u \in U}$ given by the reformulation of the structure Theorem above. The second point holds in our original nice covering, and won't be affected by the agglutination of flawless subtrees.

Partition $U$ into flawless and defective indices $U=U_{F} \sqcup U_{D}: U_{F}$ consists of indices $u$ such that $\bar{Y}_{u}$ has cyclic arc fixators, and $U_{D}=U \backslash U_{F}$.

Consider the equivalence relation $\sim$ on $U_{F}$ generated by $u \sim u^{\prime}$ if $\bar{Y}_{u} \cap \bar{Y}_{u^{\prime}} \neq \emptyset$, and denote by $[u]$ the class of $U$ in $U_{F} / \sim$. Take

$$
\tilde{Y}_{[u]}=\bigcup_{u^{\prime} \in[u]} \bar{Y}_{u}
$$

Clearly, if $[u] \neq\left[u^{\prime}\right], \tilde{Y}_{[u]} \cap \tilde{Y}_{\left[u^{\prime}\right]}=\emptyset$.
Because of the finiteness property of the nice covering $\left(\bar{Y}_{u}\right), \tilde{Y}_{u}$ is closed in $\bar{T}$ and is flawless. Finally, the family $\left(\tilde{Y}_{[u]}\right)_{u \in U / \sim}$ is a nice covering since the finiteness condition is a consequence of the finiteness condition for $\left(\bar{Y}_{u}\right)_{u \in U}$.

We are going to define the skeleton $S^{\prime}$ of the desired graph of actions by a slight modification of the skeleton $S$ of the nice covering $\left(\tilde{Y}_{u}\right)_{u \in U}$ given by the agglutination lemma above. Remember that $S$ is a bipartite tree for the following partition of $V(S)$ (see section 4.5): $V_{1}(S)$ is the set of non-degenerate subtrees $\left\{\tilde{Y}_{u} \mid u \in U\right\}$, and $V_{0}(S)$ is the set of points of $\bar{T}$ contained in at least two distinct subtrees $\tilde{Y}_{u} \neq \tilde{Y}_{v}$. Then, $V_{1}(S)$ is itself partitioned into flawless and defective vertices. The edges of $S$ are the pairs $\left(x, \tilde{Y}_{u}\right)$ where $x \in V_{0}(S), \tilde{Y}_{u} \in V_{1}(S)$, and $x \in \tilde{Y}_{u}$.

We define $S^{\prime}$ as the simplicial tree obtained from $S$ by collapsing each edge incident on some flawless vertex. Since flawless vertex subtrees don't intersect, one gets $V\left(S^{\prime}\right)=$ $V_{F}\left(S^{\prime}\right) \sqcup V_{D}\left(S^{\prime}\right) \sqcup V_{0}\left(S^{\prime}\right)$ where $V_{F}\left(S^{\prime}\right)$ correspond to flawless subtrees $\tilde{Y}_{v}\left(v \in V_{1}(S)\right)$, $V_{D}\left(S^{\prime}\right)$ correspond to defective subtrees $\tilde{Y}_{v}\left(v \in V_{1}(S)\right)$, and $V_{0}\left(S^{\prime}\right)$ correspond to vertices $v \in V_{0}(S)$ whose neighbours are all defective; in other words, $V_{0}\left(S^{\prime}\right)$ correspond to points of $\bar{T}$ lying in no flawless subtree but in several defective subtrees.

We gather some simple properties about $S^{\prime}$ :
Lemma 6.5. 1. $V\left(S^{\prime}\right)=V_{0}\left(S^{\prime}\right) \sqcup V_{F}\left(S^{\prime}\right) \sqcup V_{D}\left(S^{\prime}\right)$ and this partition is equivariant;
2. any edge e of $S^{\prime}$ is incident on exactly one defective vertex in $V_{D}(S)$, and its other endpoint lies in $V_{F}\left(S^{\prime}\right) \cup V_{0}\left(S^{\prime}\right)$;
3. edge fixators are abelian and non-cyclic; and if two edge fixators commute, then those two edges are incident on a common defective vertex.
4. Let $v \in V_{D}\left(S^{\prime}\right)$. Then $\Gamma_{v}=\bar{\Gamma}_{v} \oplus N_{v}$ where $N_{v}$ coincides with the fixator of all incident edges.

Proof. The first statement is clear and statement 2 follows from the fact that $S$ was bipartite. For statement 3, consider an edge $e$, and let $v \in V_{D}\left(S^{\prime}\right)$ be its defective endpoint. Then its fixator $\Gamma_{e}$ is abelian and non-cyclic since it coincides with the stabilizer $N_{v}$ of a point in $\tilde{Y}_{v}$. If the fixators of two edges $e$ and $e^{\prime}$ commute, then $\Gamma_{v}$ commutes with $\Gamma_{v^{\prime}}$ which implies $v=v^{\prime}$. Statement 4 follows from the abelian dévissage Theorem.

### 6.2.1 The vertex $\mathbb{R}^{n}$-trees

We are now going to define the vertex $\mathbb{R}^{n}$-trees $\left(T_{v}^{\prime}\right)_{v \in V\left(S^{\prime}\right)}$ of our graph of actions. We would like to take as vertex trees the preimages in $T$ of $\tilde{Y}_{v}$, except when this preimage is defective in which case we want to replace it by a copy of $\mathbb{R}^{n-1}$. For each edge $e \in E\left(S^{\prime}\right)$, denote by $l_{e}$ the axis of $\Gamma_{e}$ in $\tilde{Y}_{o(e)}$ (resp. $l_{e}=\mathbb{R}^{n-1}$ if $t(e)$ is defective). We would next like to glue $l_{e}$ on $l_{\bar{e}}$ for each edge $e$. Unfortunately, this might not be possible as it might happen that $l_{e}$ is not isometric to $l_{\bar{e}}$.

However, for every vertex $v \in V_{0}\left(S^{\prime}\right) \cup V_{F}\left(S^{\prime}\right)$ (i. e. for $v$ non defective), and any edge $e$ incident on $v, l_{e}$ has magnitude at most $n-1$ (i. e. any two points in $l_{e}$ are at infinitesimal distance). Indeed, the non-cyclic group $\Gamma_{e}$ is elliptic in $\bar{T}$, but since $\tilde{Y}_{v}$ is not defective, $\Gamma_{e}$ fixes only one point in $\tilde{Y}_{v}$, which means that $l_{e}$ has magnitude at most $n-1$. As a remedy, we are first are going enlarge the vertex trees so that all axes of edge groups become isometric to $\mathbb{R}^{n-1}$.

In what follows, we call line in an $\mathbb{R}^{n}$-tree $T$ a maximal linear subtree of $T$.
Fact 6.6 (End completion, [Bas91, Appendix E].). If $(Z, \Gamma)$ is an action on $\mathbb{R}^{n}$ tree, and $\left(l_{e}\right)$ is an invariant family of lines in $Z$ with magnitude at most $n-1$, then there is a natural enlargement $\hat{Z}$ of $Z$ (endowed with an action of $\Gamma$ ) such that each $l_{e}$ is contained in a unique maximal line $\hat{l}_{e}$ of $\hat{Z}$, and $\hat{l}_{e}$ is isometric to $\mathbb{R}^{n-1}$.

Proof. This fact follows for instance from [Bas91, Appendix E]: take $\hat{Z}$ to be the $\mathbb{R}^{n-1}$ neighbourhood of $Z$ in the $\mathbb{R}^{n}$-fulfillment of $Z$. We give an alternative simple sketch of proof for completeness, under the assumption that any two distinct lines of the family intersect in a segment (and not a semi-line for example). This assumption is satisfied in our setting.

Fix a line $l_{e}$, choose an embedding $j_{e}$ of $l_{e}$ into $\mathbb{R}^{n-1}$, and glue $Z$ to $\mathbb{R}^{n-1}$ along the maximal line $l_{e}$ using $j_{e}$. There is actually no choice for doing this since any two
embeddings of $l_{e}$ into $\mathbb{R}^{n-1}$ differ by an isometry of $\mathbb{R}^{n-1}$. It is easily seen that the glued tree $Z \cup_{j_{e}} \mathbb{R}^{n-1}$ is an $\mathbb{R}^{n}$-tree (although $j_{e}\left(l_{e}\right)$ is generally not closed in $\mathbb{R}^{n-1}$ in the sense of $\Lambda$-trees). The additional assumption we made says that any other line $l_{e^{\prime}}$ is a maximal linear subtree in the extended tree. Therefore, we can iterate this construction, and the obtained tree does not depend on the order chosen to extend the lines. Since an increasing union of $\mathbb{R}^{n}$-trees is an $\mathbb{R}^{n}$-tree, the fact is proven.

Definition. For $v$ defective in $V\left(S^{\prime}\right)$, we take our vertex tree $T_{v}^{\prime}$ to be a copy of $\mathbb{R}^{n-1}$.
For $v \in V\left(S^{\prime}\right)$ which is not defective, we take $T_{v}^{\prime}=\hat{Z}_{v}$ to be the end completion of $Z_{v}$ given by the fact above, where $Z_{v}$ is the preimage of $\tilde{Y}_{v}$ in $T$, and $\left(l_{e}\right)$ is the family of axes in $Z_{v}$ of the groups $\Gamma_{e}$ for e ranging in the set of edges incident on $v$.

We denote by $\lambda_{e}$ the axis of $\Gamma_{e}$ in $T_{v}^{\prime}$.
Note that $\lambda_{e}$ is the unique maximal linear subtree containing $l_{e}$ in $T_{v}^{\prime}$. The end completion being canonical, the group $\Gamma$ acts naturally on the disjoint union $\sqcup_{v \in V_{0}\left(S^{\prime}\right) \cup V_{F}\left(S^{\prime}\right)} T_{v}^{\prime}$, but we still have to define an action on $\sqcup_{v \in V_{D}(S)} T_{v}^{\prime}$ (the set of copies of $\mathbb{R}^{n-1}$ ). To achieve this, we just need to define an action of $\Gamma_{v}$ on $T_{v}^{\prime}$ for one vertex $v$ of each orbit in $V_{D}\left(S^{\prime}\right) / \Gamma$, and then extend this action equivariantly. Now remember that for $v \in V_{D}\left(S^{\prime}\right)$, $\Gamma_{v}=N_{v} \oplus \bar{\Gamma}_{v}$, and $N_{v}$ comes with a natural action on its axis in $T$ (and this action is infinitesimal), so we take an action of $N_{v}$ on $T_{v}^{\prime}$ having the same translation length as in $T$. The action of $\bar{\Gamma}_{v}$ on $T_{v}^{\prime}$ will be chosen in a generic set, which will be made explicit in section 6.2.3 using the branching locus of axes.

### 6.2.2 Branching locus of axes

To be able to keep some control over the freeness of the action dual to our graph of action, we will need to take care of how axes are glued together.

Definition 6.7 (Branching locus of axes.). Let $v \in V_{0}\left(S^{\prime}\right) \cup V_{F}\left(S^{\prime}\right)$. For each edge e incident on $v$, let $\lambda_{e}$ be the axis of $\Gamma_{e}$ in $T_{v}^{\prime}$. The branching locus of axes in $T_{v}^{\prime}$ is the set

$$
B_{v}=\bigcup_{e, e^{\prime} \in E\left(S^{\prime}\right) \text { incident on } v}\left[\lambda_{e} \cap \lambda_{e^{\prime}}\right] .
$$

We are now going to prove that the branching locus is small in the following sense: the branching locus of axes is a countable union of sets of magnitude at most $n-2$. This is a consequence of the following fact with $p=n-1$. This is where the use of non-cyclicness of arc fixators shows up.

Fact 6.8 (Infinitesimal intersection of axes of non-cyclic groups). Let $\Gamma \bigcirc Y$ be $a$ free action of a group on an $\mathbb{R}^{n}$-tree. Let $H, H^{\prime}$ be two non-commuting abelian subgroups of $\Gamma$. Assume that for some $p \leq n$, the subgroups of $H$ and $H^{\prime}$ consisting of elements whose translation length is of magnitude at most $p$ are both non-cyclic.

Then the intersection of the axes of $H$ and $H^{\prime}$ has magnitude at most $p-1$.
Remark. If the subgroups of $H$ and $H^{\prime}$ are only supposed to be nontrivial (maybe cyclic), then one can get that the magnitude of the intersection of the axes is at most $p$.

Proof of the fact. This is just a consequence of the fact that if the axes of two hyperbolic elements $g, h$ intersect in a segment whose diameter is larger than the sum of the translation lengths of $g$ and $h$, then the commutator $[g, h]$ fixes a point, so that $g$ and $h$ commute.

Up to taking subgroups, one can assume that every element of $H$ and $H^{\prime}$ have translation length of magnitude at most $p$. We just need to prove that for any positive $\varepsilon \in \mathbb{R}^{p} \backslash \mathbb{R}^{p-1}, H$ (resp. $H^{\prime}$ ) contain non-trivial elements of translation length at most $\varepsilon$. This clearly holds if some element of $H \backslash\{1\}$ has a translation length of magnitude at most $p-1$. Otherwise, consider a morphism $\rho: H \rightarrow \mathbb{R}^{p}$ having the same translation length function. Composing $\rho$ by the collapse of infinitesimals in $\mathbb{R}^{p}$, we get an embedding of $H$ as a subgroup of $\mathbb{R}$. This subgroup has to be dense since $H$ is not cyclic.

### 6.2.3 Action on former defective trees and gluing maps

Now consider a defective vertex $v \in V_{D}\left(S^{\prime}\right)$. We are now going to define the action of $\bar{\Gamma}_{v}$ on $T_{v}^{\prime} \simeq \mathbb{R}^{n-1}$. For all $w \in V_{0}\left(S^{\prime}\right) \cup V_{F}\left(S^{\prime}\right)$, let $D_{w}=\left\{d\left(x, x^{\prime}\right) \mid(x, y) \in B_{w}\right\} \subset \mathbb{R}^{n}$ be the set of mutual distances between points in the branching locus, and let $D=\bigcup\left\{D_{w} \mid w \in\right.$ $\left.V_{0}\left(S^{\prime}\right) \cup V_{F}\left(S^{\prime}\right)\right\}$. The previous section shows that $D$ is a countable union of sets of magnitude at most $n-2$ in $\mathbb{R}^{n}$. We choose the action of $\bar{\Gamma}_{v}$ on $T_{v}^{\prime} \simeq \mathbb{R}^{n-1}$ so that the translation length of any non-trivial element of $\bar{\Gamma}_{v}$ lies in $\mathbb{R}^{n-1} \backslash D$.

We define $\varphi_{e}$ inductively in a generic set as follows. First, up to changing $e$ to $\bar{e}$, we can assume that $t(e) \in V_{D}\left(S^{\prime}\right)$ while $o(e) \in V_{0}\left(S^{\prime}\right) \sqcup V_{F}\left(S^{\prime}\right)$ (Lemma 6.5). For the first orbit of edges, we choose any $\Gamma_{e}$-equivariant gluing isometry $\varphi_{e}: \lambda_{\bar{e}} \rightarrow \lambda_{e}$, and we extend this choice equivariantly (remember that $\lambda_{e}$ and $\lambda_{\bar{e}}$ are the axes of $\Gamma_{e}$ in $T_{t(e)}^{\prime}$ and $\left.T_{o(e)}^{\prime}\right)$. Then, if some choices of gluing maps are already made for some other edges incident on $v$, we choose $\varphi_{e}$ so that $\varphi_{e}\left(B_{o(e)}\right)$ does not meet $\varphi_{e^{\prime}}\left(B_{o\left(e^{\prime}\right)}\right)$ for any edge $e^{\prime}$ such that $t\left(e^{\prime}\right)=t(e)$ and on which $\varphi_{e^{\prime}}$ was already defined. This is possible since one can compose $\varphi_{e}$ by any translation in $\mathbb{R}^{n-1}$, and there are only countably many classes of translations $\bmod \mathbb{R}^{n-2}$ which are prohibited. Then, we extend this choice equivariantly on the orbit of $e$.

To sum up, our generic choices with respect to the branching locus of axes ensure that the following holds:

Lemma 6.9. - For any defective vertex $v \in V_{D}\left(S^{\prime}\right)$, the translation length of any element of $\Gamma_{v} \backslash N_{v}$ in $T_{v}^{\prime}$ does not lie in $D$.

- given two edges e, $e^{\prime}$ incident on a common defective vertex $v \in V_{D}\left(S^{\prime}\right)$ such that $\varphi_{e}^{-1} B_{o(e)} \cap \varphi_{e^{\prime}}^{-1} B_{o\left(e^{\prime}\right)} \neq \emptyset$; then $e$ and $e^{\prime}$ are in the same orbit.


### 6.3 The dual action is free

In last section, we have completed the definition of our graph of actions on $\mathbb{R}^{n}$-trees $\mathcal{G}=\left(S^{\prime},\left(T_{v}^{\prime}\right),\left(\varphi_{e}\right)\right)$. Let $T^{\prime}$ be the $\mathbb{R}^{n}$-tree dual to $\mathcal{G}$. Since this is a graph of flawless actions over infinitesimal lines, $T^{\prime}$ is flawless (Lemma 6.3). Thus, Theorem 6.1 will be proved as soon as we prove that the action of $\Gamma$ on $T^{\prime}$ is free.

Lemma 6.10. Consider $T^{\prime}$ the $\mathbb{R}^{n}$-tree dual to the graph of actions $\left(S^{\prime},\left(T_{v}^{\prime}\right),\left(\varphi_{e}\right)\right)$ defined above. Then the action of $\Gamma$ on $T^{\prime}$ is free.

Proof. Remember that the glued $\mathbb{R}^{n}$-tree is obtained by quotienting $X=\sqcup_{v \in V(S)} T_{v}^{\prime}$ by the equivalence relation $\sim$ generated by $x \sim \varphi_{e}(x)$, and that each equivalence class inherits a structure of a simplicial tree by putting an edge between $x$ and $\varphi_{e}(x)$. In view of our criterion to get a free action after gluing, we have to prove that the diameter of any equivalence class is finite (lemma 4.5).

Let's first consider a point $x \in T_{v}^{\prime}$ where $v$ is not a defective vertex. We note that if $x$ is not a terminal vertex in its equivalence class, then there are two edges $e \neq e^{\prime}$ incident on $v$ such that $x \in \lambda_{e} \cap \lambda_{e^{\prime}}$. So $x$ lies in the branching locus of axes $B_{v}$.

Assume that the diameter of some equivalence class is at least 6 and argue towards a contradiction. Consider a path $p$ of length 6 in an equivalence class. Since every edge of $S^{\prime}$ joins a defective vertex to a vertex in $V_{0}\left(S^{\prime}\right) \sqcup V_{F}\left(S^{\prime}\right)$, there is a sub-path $\left(x_{1}, y, x_{2}\right)$ of $p$ such that $x_{1} \in T_{v_{1}}^{\prime}, y \in T_{w}^{\prime}, x_{2} \in T_{v_{2}}^{\prime}$ with $v_{1}, v_{2} \in V_{0} \sqcup V_{F}\left(S^{\prime}\right), w \in V_{D}(S)$, and where $x_{1}$ and $x_{2}$ are not terminal in the equivalence class. Thus for both $i=1,2, x_{i} \in B_{v_{i}}$. By the second item of lemma [6.9, the edges $e_{1}=\left[v_{1}, w\right]$ and $e_{2}=\left[v_{2}, w\right]$ are in the same orbit. So let $g \in \Gamma$ sending $e_{1}$ on $e_{2}$. Note that $g \in \Gamma_{w}$ since $w$ and $v_{i}$ are not in the same orbit. Since $N_{w}$ fixes all the edges incident on $w$ (Lemma 6.5), $g \in \Gamma_{w} \backslash N_{w}$. Now, since $x_{1} \in B_{v_{1}}, g \cdot x_{1} \in B_{v_{2}}$, and $d\left(g \cdot x_{1}, x_{2}\right) \in D_{v_{2}}$. Let $y=\varphi_{e_{1}}\left(x_{1}\right)$, so $g . y=\varphi_{e_{2}}\left(g \cdot x_{1}\right)$ so $d(y, g . y)=d\left(x_{2}, g \cdot x_{1}\right) \in D$, a contradiction with the first item of lemma 6.9.

## 7 Dévissage theorem and corollaries

Theorem 7.1 (Dévissage theorem, simple version). Consider a finitely generated, freely indecomposable group $\Gamma$ having a free action on an $\mathbb{R}^{n}$-tree. Then $\Gamma$ can be written as the fundamental group of a finite graph of groups with cyclic edge groups and where each vertex group is finitely generated and has a free action on an $\mathbb{R}^{n-1}$-tree.

This is a consequence of the following detailed version.
Theorem 7.2 (Dévissage theorem, detailed version). If a finitely generated freely indecomposable group $\Gamma$ acts freely on an $\mathbb{R}^{n}$-tree, then $\Gamma$ can be written as the fundamental group of a finite graph of groups $\mathcal{G}$ with cyclic edge groups, finitely generated vertex groups, with 3 types of vertices named abelian, surface and infinitesimal, and such that the following holds:

- each edge is incident to exactly one infinitesimal vertex;
- for each abelian vertex $v, \Gamma_{v}$ is abelian maximal in $\Gamma, \Gamma_{v}=\bar{\Gamma}_{v} \oplus N_{v}$ where $\bar{\Gamma}_{v}$ is a finitely generated (maybe trivial) free abelian group, $N_{v}$ is maximal cyclic in $G$, and the image in $\Gamma_{v}$ of all incident edges coincide with $N_{v}$; moreover, if $v \neq v^{\prime}$ are distinct abelian vertices, then $\Gamma_{v}$ does not commute with any conjugate of $\Gamma_{v^{\prime}}$;
- for each surface vertex $v, \Gamma_{v}$ is the fundamental group of a surface $\Sigma$ with boundary holding an arational measured foliation; there is one edge for each boundary component of $\Sigma$, and the image of its edge group in $\Gamma_{v}$ is conjugate to the fundamental group of the corresponding boundary component of $\Sigma$;
- for each infinitesimal vertex $v, \Gamma_{v}$ acts freely on an $\mathbb{R}^{n-1}$-tree; moreover, any element $g \in \Gamma \backslash\{1\}$ commuting with an element of $\Gamma_{v} \backslash\{1\}$ either belongs to $\Gamma_{v}$, or is conjugate into $\bar{\Gamma}_{w}$ where $w$ is an abelian vertex neighbouring $v$.

Finally, $\mathcal{G}$ is 4-acylindrical and any non-cyclic abelian subgroup of $\Gamma$ is conjugate into a vertex group.

Proof. Using Theorem 6.1, consider a free action $\Gamma \subset T^{\prime}$ such that the action on the $\mathbb{R}$ tree $\bar{T}^{\prime}$ obtained by killing infinitesimals has cyclic arc fixators. The Theorem is then a direct consequence of the abelian dévissage (Proposition 5.5): the fact that $\Gamma$ and the edge groups of $\mathcal{G}$ are finitely generated implies that vertex groups are finitely generated.

Remark. The dévissage theorem does not claim that the splitting is non-trivial. This occurs if $\Gamma$ is abelian, if $\Gamma$ is the fundamental group of a surface with empty boundary, or if $\Gamma$ acts freely on some $\mathbb{R}^{n-1}$-tree.

It follows from the commutative transitivity of $\Gamma$ that any non-cyclic maximal abelian subgroup of an infinitesimal vertex group is maximal abelian in $\Gamma$. However, some edge groups may fail to be maximal cyclic in $\Gamma$ for some edges incident on surface vertices.

The following corollary is due to Sela and Kharlampovich-Myasnikov for limit groups ([Sel01, KM98a]).

Corollary 7.3. Let $\Gamma$ be a finitely generated group having a free action on an $\mathbb{R}^{n}$-tree. Then

- $\Gamma$ is finitely presented;
- if $\Gamma$ is not cyclic, then its first Betti number is at least 2;
- there are finitely many conjugacy classes of non-cyclic maximal abelian subgroups in $\Gamma$, and abelian subgroups of $\Gamma$ are finitely generated. More precisely, one has the following bound on the ranks of maximal abelian subgroups:

$$
\sum_{A}(\operatorname{Rk} A-1) \leq b_{1}(\Gamma)-1
$$

where the sum is taken over the set of conjugacy classes of non-cyclic maximal abelian subgroups of $\Gamma$, and where $b_{1}(\Gamma)$ denotes the first Betti number of $\Gamma$;

- $\Gamma$ has a finite classifying space, and the cohomological dimension of $\Gamma$ is at most $\max (2, r)$ where $r$ is the maximal rank of an abelian subgroup of $\Gamma$.

Proof. For $n=1$, all the statements of the corollary follow from Rips theorem which claims that $\Gamma$ is a free product of finitely generated abelian groups and fundamental groups of closed surfaces (see [GLP94, BF95]).

For $n>1$, we argue by induction and assume that the corollary holds for smaller values of $n$. The conclusion of the corollary is stable under free product since any noncyclic abelian subgroup of a free product is conjugate into a vertex group. Thus one can assume that $\Gamma$ is freely indecomposable. Then the dévissage theorem says that $\Gamma$ is the fundamental group of a finite graph of groups $\mathcal{G}$ with cyclic edge groups, and vertex groups satisfy the corollary by induction hypothesis. If this splitting of $\Gamma$ is trivial, then $\Gamma$ is a vertex group and we are done.

The finite presentation of vertex groups implies that $\Gamma$ is finitely presented. Moreover, induction hypothesis shows that $\Gamma$ has a finite classifying space, and the cohomological dimension of $X$ is clearly at most $\max (2, r)$ (see for instance [Bro82, prop.VIII.2.4 and ex 8 b in VIII.6]).

We have the following bound about Betti numbers:

$$
b_{1}(\Gamma) \geq \sum_{v \in V(\mathcal{G})} b_{1}\left(\Gamma_{v}\right)+b_{1}(\mathcal{G})-\# E(\mathcal{G})
$$

where $b_{1}(\mathcal{G})$ denotes the first Betti number of the graph underlying $\mathcal{G}$. Indeed, consider the graph of groups $\mathcal{G}_{0}$ obtained from $\mathcal{G}$ by replacing edge group by a trivial group so that $\pi_{1} \mathcal{G}_{0}$ is a free product of the vertex groups and of a free group of rank $b_{1}(\mathcal{G})$. Since edge groups of $\mathcal{G}$ are cyclic, one obtains $\Gamma$ from $\pi_{1} \mathcal{G}_{0}$ by adding one relation for each edge of $\mathcal{G}$, and the inequality follows. Now since $b_{1}(\mathcal{G})-1=\# E(\mathcal{G})-\# V(\mathcal{G})$, one gets that $b_{1}(\Gamma)-1 \geq \sum_{v \in V(\mathcal{G})}\left(b_{1}\left(\Gamma_{v}\right)-1\right)$.

By induction hypothesis, each term in the sum is non-negative. In particular, $b_{1}(\Gamma) \geq$ $b_{1}\left(\Gamma_{v}\right)$ for all $v \in V(\mathcal{G})$. Thus if some vertex group is non-cyclic then $b_{1}(\Gamma) \geq 2$; but all vertex groups cannot be cyclic because of acylindricity.

The dévissage theorem claims that a non-cyclic abelian subgroup $A$ fixes a vertex $v$ in the Bass-Serre tree $S$ of $\mathcal{G}$. Let's prove that there are finitely many conjugacy classes of non-cyclic maximal abelian subgroups. Since edge stabilizers are cyclic, such a subgroup $A$ fixes exactly one point in $S$. Since there are only finitely many orbits of vertices in $S$, there remains to prove that for any vertex $v \in V(S)$, there are only finitely many $\Gamma$-conjugacy classes of abelian subgroups $A$ which fix $v$. The induction hypothesis says that there are at most finitely many such subgroups up to conjugacy in $\Gamma_{v}$, and therefore in $\Gamma$.

Denote by $\operatorname{Ab}(\Gamma)$ the set of conjugacy classes of abelian subgroups of $\Gamma$. The argument above shows that the natural map $\sqcup_{v \in V(\mathcal{G})} \mathrm{Ab}\left(\Gamma_{v}\right) \rightarrow \mathrm{Ab}(\Gamma)$ is onto. Therefore,

$$
\begin{aligned}
\sum_{A \in \mathrm{Ab}(\Gamma)}(\mathrm{Rk} A-1) & \leq \sum_{v \in V(\mathcal{G})} \sum_{A \in \mathrm{Ab}\left(\Gamma_{v}\right)}(\mathrm{Rk} A-1) \\
& \leq \sum_{v \in V(\mathcal{G})}\left(b_{1}\left(\Gamma_{v}\right)-1\right) \\
& \leq b_{1}(\Gamma)-1 .
\end{aligned}
$$

This terminates the proof of the corollary.

Corollary 7.4. Consider a freely indecomposable, non-abelian, finitely generated group having a free action on an $\mathbb{R}^{n}$-tree. Then $\Gamma$ has a non-trivial splitting which is principal in the following sense: either $\Gamma=A *_{C} B$ or $\Gamma=A *_{C}$ where $C$ is maximal abelian in $\Gamma$, or $\Gamma=A *_{C}\left(C \oplus \mathbb{Z}^{k}\right)$.

Proof. We argue by induction on $n$. The statement is clear for $n=1$. Otherwise, consider the graph of groups given by the dévissage theorem. If $\mathcal{G}$ contains a surface-type vertex, then cutting along an essential curve provides a splitting over a cyclic subgroup which is maximal abelian. If $\mathcal{G}$ contains an abelian-type vertex $v$, write $G_{v}=N_{v} \oplus \bar{\Gamma}_{v}$. If $\bar{\Gamma}_{v}$ is trivial, then $N_{v}=G_{v}$ is maximal abelian, so each of the edges of $\mathcal{G}$ incident on $v$ provides a principal splitting of $\Gamma$. If $\bar{\Gamma}_{v}$ is non-trivial, then $\Gamma=A *_{N_{v}}\left(N_{v} \oplus \bar{\Gamma}_{v}\right)$ where $A$ is the fundamental group of the graph of groups $\mathcal{G}^{\prime}$ obtained from $\mathcal{G}$ by replacing the vertex $\operatorname{group} \Gamma_{v}=N_{v} \oplus \bar{\Gamma}_{v}$ by the cyclic group $N_{v}$. If $\mathcal{G}$ has no abelian-type and no surface-type vertex, then $\mathcal{G}$ consists in a single infinitesimal vertex. This means that $\Gamma$ acts freely on an $\mathbb{R}^{n-1}$-tree.

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[^0]:    ${ }^{1}$ The proof is actually very similar to the proof of the more technical result: instead of taking ultraproducts of valuated fields, take an ultraproduct of trees to get a free action without inversion on a $\Lambda^{*}$-tree (see also [Chi01, p.239] where the behavior $\Lambda$-trees under ultrapowers is studied in terms of Lyndon length functions).

[^1]:    ${ }^{2}$ It may also be checked that $B T^{*}$ is actually the ultraproduct of the $\Lambda_{i}$-trees $B T_{i}$.

[^2]:    ${ }^{3}$ a measured foliation on a surface with boundary is arational if any non simply-connected leaf (or generalized leaf) actually has a cyclic fundamental group and contains a boundary component of $\Sigma$. Equivalently, $\mathcal{F}$ is arational if every simple closed curve having zero intersection with the measured foliation is boundary parallel.

[^3]:    ${ }^{4}$ Note that the claim of Remeslennikov that limit groups act freely on a $\Lambda$-tree with $\Lambda$ finitely generated would imply that abelian subgroup are finitely generated since they are isomorphic to subgroups of $\Lambda$ since an abelian subgroup of $\Gamma$ acts freely by translation on its axis, and is thus isomorphic to a subgroup of $\Lambda$.

